

A FRAMEWORK TO DESIGN AND OPTIMIZE CHEMICAL FLOODING PROCESSES

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ABSTRACT

The goal of this proposed research is to provide an efficient and user friendly simulation framework for screening and optimizing chemical/microbial enhanced oil recovery processes. The framework will include (1) a user friendly interface to identify the variables that have the most impact on oil recovery using the concept of experimental design and response surface maps, (2) UTCHEM reservoir simulator to perform the numerical simulations, and (3) an economic model that automatically imports the simulation production data to evaluate the profitability of a particular design. Such a reservoir simulation framework is not currently available to the oil industry.

The objectives of Task 1 are to develop three primary modules representing reservoir, chemical, and well data. The modules will be interfaced with an already available experimental design model. The objective of the Task 2 is to incorporate UTCHEM reservoir simulator and the modules with the strategic variables and developing the response surface maps to identify the significant variables from each module. The objective of the Task 3 is to develop the economic model designed specifically for the chemical processes targeted in this proposal and interface the economic model with UTCHEM production output. Task 4 is on the validation of the framework and performing simulations of oil reservoirs to screen, design and optimize the chemical processes.

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INTRODUCTION

In this report, we detail our progress on Tasks 1 through 4 for the second year of the project. We have continued our development of the framework with modules for uncertainty and optimization of reservoir properties, well placement, chemical data, and economics. We have performed several surfactant flooding simulations with different permeability and permeability heterogeneities, surfactant concentration and slug size to identify the key variables that control the project life and oil recovery using the experimental design and a simple discounted cash flow analysis.

The experimental design module was then used to design the simulations varying the primary variables such as reservoir permeability and heterogeneity, surfactant and polymer concentration and slug size and the provided range for each.

EXECUTIVE SUMMARY

An efficient approach to obtain the optimum design under uncertainty for a wide range of reservoir simulation applications has been developed and successfully implemented. The approach discussed here significantly reduces the time required to evaluate optimum designs for improved oil recovery (IOR) processes.

Determining the optimum combination of design variables for an IOR process is a complex problem that depends on the crude oil price, reservoir and fluid properties, process performance, and well specifications. Due to the large number of design variables, numerical simulation is often the most appropriate tool to evaluate the feasibility of such a process. However, because of the economical and geological

uncertainties, the optimum design should be expressed as a distribution to gauge the uncertainties.

Our innovative simulation approach has the capability to determine an economically optimum design that includes the following variables for surfactant/polymer flooding projects.

- The duration of water injection prior to the surfactant flooding
- Surfactant concentration and slug size
- Polymer concentration injected with the surfactant
- The concentration and duration of the polymer drive
- The electrolytes concentration in different stages of the flood

The uncertain parameters considered in this study were Dykstra-Parsons coefficient as a measure of formation heterogeneity, average reservoir permeability, horizontal correlation length, ratio of horizontal to vertical correlation lengths, vertical to horizontal permeability ratio, residual oil saturation, surfactant adsorption, price of crude oil and chemicals, and discount rate.

In order to efficiently perform these complex design processes efficiently, a platform that distributes multiple simulations on a cluster of computer processors has been developed. The platform integrates several oil reservoir simulators, an economic model, an experimental design and response surface methodology, and a Monte Carlo algorithm with a global optimization search engine to identify the optimum design under conditions of uncertainty.

The technique incorporates the following steps:

- Factorial design to find the most influential design and uncertain factors.

- Response surface methodology (RSM) design over those most influential factors to fit a response surface using net present value (NPV) as the objective function.
- Monte Carlo simulation over the response surface to maximize the mean of the net present value and search for the optimum combination of the design variables at the same time.

This approach is applied to a field-scale surfactant/polymer flood using the UTCHEM simulator to find the optimal values of design variables that will maximize the NPV.

The objectives of Task 1 are to develop three primary modules representing reservoir, chemical, and well data. The modules are interfaced with an already available experimental design model. The objective of the Task 2 is to incorporate UTCHEM reservoir simulator and the modules with the strategic variables and developing the response surface maps to identify the significant variables from each module. The objective of Task 3 is to incorporate an economic model that automatically imports the simulation production data to evaluate the profitability of a particular design. The objective of the Task 4 is to perform a certain number of flow simulations using UTCHEM in order to determine the "response surface" of the simulator in the space of predominant uncertain parameters. The simulation results will then be analyzed and recovery data as a function of designed variables will be stored. These simulation results will then be ported to Design-Expert software to plot the responses versus each parameter.

Here we report on our continuing development and efforts on Tasks 1 through Task 4 during the second year of the project. A platform called Integrated Reservoir Simulation Platform (IRSP) is designed and developed that is a combination of several softwares and hardwares to solve various oil reservoir engineering problems. Several window based commercial packages are used to analyze the results by IRSP.

EXPERIMENTAL

This project does not include an experimental component.

RESULTS AND DISCUSSION

A user-friendly framework is designed and in the process of development to perform and optimize chemical flooding simulations in a reasonable time frame by automating the simulation input data generation. Several key simulation output results are generated automatically and plotted using Excel. For a surfactant flood, the uncertain parameters are from the reservoir and fluid properties and crude oil price. Under these uncertainties, an optimal combination of the decision variables is obtained in order to make project decisions. Table 1 summarizes the previous published work (Brown *et al.*, 1984; Gittler *et al.*, 1985; Barua *et al.*, 1986; Jakobson *et al.*, 1994; Wu *et al.*, 1996; Qu *et al.*, 1998; Zerpa *et al.*, 2004) on surfactant flood design and optimization.

As indicated in Table 1, this is the first time that a systematic design and optimization of surfactant flooding is studies taking into account the uncertainties due to reservoir properties and crude oil and chemical prices. None of the previous work has taken all these uncertainties into account at the same time. They also suffered either with lack of an economical model or no consideration of uncertainties. Majority of these

sensitivity studies were done by varying one design parameter at the time. Therefore, the interactions between the factors were ignored. The simulations were run sequentially and the results were analyzed manually. This made the study cumbersome and inefficient.

Here we present a practical, systematic, and efficient approach to design and optimize a surfactant flood taking into account technical and economical uncertainties. The platform integrates UTCHEM chemical flooding reservoir simulator (Delshad *et al.*, 2002), a discounted cash flow model, an experimental design and response surface methodology, and a Monte Carlo algorithm with a global optimization search engine to identify the optimum design under uncertainty (Zhang *et al.*, 2005). The platform distributes the multiple simulations on a cluster of computer processors to run simultaneously. The post-processing utilities minimize the human involvement for analysis of voluminous simulation output. The automated and user-friendly working environment of the platform greatly increases the efficiency and accuracy for reservoir simulation design and optimization studies.

These results will be fed to the economic package. Our progress on Tasks 1 through 4 is reported as discussed below.

Task 1: Development of Uncertainty Modules and Experimental Design Model

Integrated reservoir simulation system (IRSS) is a compilation of software and hardware on a single processor running Linux or a cluster of processors to solve numerous oil reservoir problems where multiple reservoir simulations are simultaneously performed, either in sequential, distributed or parallel mode. The applications include well placement, design, optimization, and economic analysis of chemical flooding

projects, sensitivity studies to rank the important factors and stochastic simulation to gauge the uncertainties. The reservoir simulators incorporated are UTCHEM, ECLIPSE from Geoquest, (Schlumberger) and VIP from Landmark (Landmark), Matrix Decomposition Method (Yang, 1990), and Sequential Gaussian Simulation module of GSLIB (Geostatistical Software Library) (Deutsch and Journel, 1998) are part of the framework to generate stochastic distributions of reservoir properties. The framework uses two different job schedulers to submit the jobs either in sequential, distributed or parallel mode. The two job schedulers are Portable Batch System (PBS) (Altair Grid Technologies) and Load Sharing Facility (LSF) (Platform Computing Corporation).

Upon successful completion of the simulations, UT_IRSP will summarize the results and generates statistical summary files and statistical map files according to the purpose of the study. Figure 1 shows the structure and the components of IRSS.

There are many Window-based softwares listed for data post-processing in Figure 1. Design-Expert and Crystal Ball are the most critical components of the platform. Surfer is used to generate variogram for the 3D geostatistical data. Tecplot RS is used to plot the 3D map files from UTCHEM and ECLIPSE.

The framework is designed using the object-oriented concept and is written in C⁺⁺. Ideally, it works on a cluster of computers with LINUX as the operating system. The framework can be divided into three modules. Figure 2 shows the UML class diagram of the framework.

- Main program works as the frontend to the framework. Once the framework is launched, the user needs to provide the study name and select the numerical model of interest.

- Pre-processing group contains ten classes. This section of the code reads the instruction and/or stochastic files first. Multiple simulation input files are then generated according to the user's specification. All the simulation jobs are then submitted to the processors either as sequential (one simulation at a time), distributed (multiple simulations to a cluster of PCs) or parallel mode. The simulation output files are saved hierarchically on a storage device. The instruction file contains the following data as (1) the number of the simulations, (2) the run number, (3) the execution mode, and (4) the factors that are under investigation and as how these factors are varied for each simulation. The stochastic input file is also needed to generate the single or spatial stochastic fields from the distributions. Sequential Gaussian (sgsim) model from GSLIB (Deutsch and Journel, 1998) is one of the two geostatistical modules available in the framework.
- Post-processing module contains eight classes. The output of the simulations will be collected and summarized either for further data manipulation or graphical presentations.

Task 2: Reservoir Simulation and Response Surface Model

Design of Experiments (DOE) is a method to select simulations to maximize the information gained from each simulation and to evaluate statistically the significance of the different factors. An experimental design study is used to generate response surfaces that identify the various factors that cause changes in the responses and also predicting these variations in a simple mathematical form. The purpose of Response Surface

Methodology (RSM) (Myers and Montgomery, 1995) is to approximate a process over a region of interest, often called operating region. The components of the operating region include objectives, requirements, state parameters (with or without uncertainty), decision variables, and constraints. An objective is the statement of the goal, and requirement can be imposed. State parameters are those that cannot be controlled and most of the times have uncertainties associated with them. They can be discrete or continuous. Discrete parameters are also referred to as “scenarios”. Decision variables are those that are controllable and are usually choices available to the decision-maker. Constraints are boundary conditions, which restrict values available for the decision variables.

Engineers define objectives of the process called responses as the output and the settings for the state parameters and decision variables as input. RSM provides tools for (1) identifying the variables that influence the responses (screening) and (2) building regression models relating the responses to the strategic variables (modeling). The final models are used to make predictions of the process over the domain.

In order to compute the regression model, the process has to be sampled over the operating region through experimentation. Design of Experiment is the use of mathematical and statistical methods to determine the number and the location of the experiments in order to get most information at the lowest experimental cost.

We will not describe the detailed mathematical and statistical theories behind response surface and experimental design. More detailed information can be found in related literature (Myers and Montgomery, 1995). A flowchart showing the integration of Design of Experiment and Response Surface in the framework is given in Figure 3. A

commercial package, Design-Expert from Stat-Ease, Inc., is used for performing experimental design analysis.

The steps to perform RSM and DOE in conjunction with our framework are listed as the following:

- Select the response and identify the settings for the state parameters and decision variables.
- Select the corresponding method of DOE according to the study objective.
- Include the experimental plan from DOE in the instruction and/or stochastic and/or economic file.
- Run the numerical simulations using the framework. The simulations are executed sequentially, distributed or in a parallel mode.
- Export the results of the response to the DOE and perform statistical analysis.
- Use the response model results to screen the factors and/or to perform further optimization as discussed in the next section.

Traditional search methods work well when finding local solutions around a given starting point with model data that are precisely known. These methods fail, however, when searching for solutions to real world problems that contain significant level of uncertainty. Recent developments in optimization have produced efficient search methods capable of finding optimal solutions to complex problems involving elements of uncertainty.

The optimization algorithm incorporates metaheuristics to guide its search algorithm toward better solutions. The approach uses a form of adaptive memory to store

which solutions worked well before and recombines them into new improved solutions. Since this technique does not use the hill-climbing approach of ordinary solvers, it does not get trapped in local solutions, and it does not get thrown off course by noisy (uncertain) model data. Scatter and tabu searches are used to globally search the solution space. Neural network is used as a predictive model to help the system accelerate the search by screening the reference points that are likely to have inferior objective function values. The optimizer is described in detail in the references (April *et al.*, 2003).

OptQuest from OptTek Systems, Inc. is the commercial optimizer that implements the above stated optimization algorithm and has been integrated in Crystal Ball, a risk analysis software package from Decisioneering, Inc. We use Crystal Ball and OptQuest to perform the optimization under uncertainty. Figure 4 shows the workflow of OptQuest in the Crystal Ball environment.

Task 3: Economic Analysis

A simple discounted cash flow model is implemented in the framework (Vaskas, 1996). The discounted cash flow (DCF) method of economic analysis allows individual projects to be evaluated and/or compared with other projects. DCF analysis gives less weight to future incomes by applying a discount rate to the predicted cash flows, thereby taking into account the time value of money. The model defines economic limit (project life) as the time when the cumulative discounted cash flow (net present value, NPV) reaches a maximum as shown in Figure 5.

Task 4: Validation and Field Scale Studies

Our approach is applied to an actual onshore U.S. dolomite reservoir. The reservoir is a potential candidate for surfactant flooding since it has already been waterflooded to near its economic limit and is otherwise subject to abandonment. The quarter-symmetry element of a 40-acre five-spot pattern is modeled. The quarter-five-spot is 660 ft in both x and y directions with a thickness of 30 ft.

The simulation grid is $11 \times 11 \times 5$ with an injector located at grid (1, 1) and a producer at (11, 11). Both injection and production wells are completed over the entire reservoir thickness with a constant injection pressure of 2500 psi and producing bottomhole pressure of 300 psi. The permeability field is generated by matrix decomposition method (Yang, 1990). A spherical variogram and a log-normal permeability distribution are assumed. A Dykstra-Parsons coefficient of 0.75, a mean permeability of 80 md, a correlation length of 200 ft in x and y directions and a correlation length of 25 ft in z-direction are used to generate the permeability field for the base case. The permeability distribution is isotropic with a vertical to horizontal permeability ratio of 0.1 in the base case. Figure 6 shows an example of the permeability field used in the simulations.

A constant porosity of 0.16 and a constant initial water saturation of 0.293 were used. The reservoir pressure is about 1975 psi corresponding to a depth of about 4700 ft. The reservoir temperature is 100^0F . Water and oil viscosities are 0.7 and 5 cp respectively. Based on the water analysis of the formation water, the initial electrolytes are about 1.026 meq/ml of total anion (32,600 mg/l of Cl^-) and 0.070 meq/ml of total divalent cations (2100 mg/l of Ca^{++}).

In each simulation, first water was injected to reach a certain WOR and then a chemical slug containing different concentrations of surfactant and polymer was injected followed by a polymer drive with different polymer concentration. The salinity was at optimum during the chemical slug at 0.445 meq/ml and was reduced to below optimum during the polymer drive and subsequent water injection. Based on our own laboratory data, a blend of 2% surfactant, 4% alcohol with the reservoir crude oil at the reservoir temperature of 100⁰F yielded a solubilization ratio of about 20 at the optimum salinity of 1.5 wt% NaCl.

The net present value (NPV) is chosen as our objective function (response) and our goal is to find an optimal combination of design variables under uncertainties from the state parameters to maximizing the NPV.

Table 2 lists the eleven state parameters along with their low, base, and high value settings based on our experience and judgment. The first four parameters are used to generate permeability fields and the last four are for economic analysis. Based on our experience, vertical to horizontal permeability ratio, waterflood residual oil saturation, and surfactant adsorption are also among the most influential factors affecting a chemical flood design and optimization.

The design variables are listed in Table 3. Eventhough the reservoir has been waterflooded to about 98-99% water cut, the duration of pre-water flood is still included as one design variable in order to investigate its significance in a case of a reservoir at early stage of waterflooding. Since the produced reservoir water is re-injected, the salinity of the pre-water flooding is as the initial formation water salinity. The salinity of surfactant slug is at the optimum salinity of 0.445 meq/ml.

Table 4 lists the economic factors that UT_IRSP takes into account. For this case we perform a discounted cash flow calculation before tax and we assume there is no initial capital cost.

The Plackett-Burman design was chosen to investigate the effects of the 19 factors (11 state parameters and 8 design variables). Twenty reservoir simulations were designed using the Plackett-Burman design which is a two level design where the number of runs is a multiple of four.

Figure 7 shows the results where the effect on the x axis represents the change in the average response when a factor varies from its low to high value. The Design-Expert identifies the top ten influential factors as given in Fig. 7. For the design factors and the reservoir conditions studied, the order from most to least influential factors are the crude oil price, the duration of water flooding prior to the chemical injection, salinity in the polymer drive, correlation length in the x direction for permeability distribution, surfactant slug size, formation heterogeneity (Dykstra-Parsons coefficient), price of polymer, waterflood residual oil saturation, surfactant adsorption and average reservoir permeability. These ten factors are then used to generate the quadratic model for the process optimization. It should be noted that Design-Expert can only handle maximum of ten continuous factors in its response surface designs. The remaining nine factors are set to their base values.

The central composite design (CCD) is used to generate the response model and 158 simulations are performed. The CCD is the most common RSM design. It is divided into three parts:

- Two-level full or fractional design (the core)

- Axial points (outside the core)
- Center points

The two-level factorial consists of all possible combinations of the +1 or -1 levels of the factors. Axial points, often represented by stars, emanate from the center point, with all but one of the factors set to zero.

Figure 8 shows the response surface generated for the surfactant slug size in PV and surfactant adsorption in mg/g rock. The highest NPV is obtained when surfactant adsorption is at the minimum and when the surfactant slug size is 0.1 PV with the surfactant concentration of 0.02 volume fraction.

The NPV at the economic limit for all the 158 simulations is shown in Fig. 9. The corresponding economic limit is given in Fig. 10. The simulations with no bar associated with them represent those that were not economical. We chose the seven cases with NPV greater than 4 million dollars and plot their cumulative oil recovery and NPV in Figures 11 and 12. The results emphasize the importance of coupling economic calculations to the optimization process for the chemical flooding projects. Table 5 summarizes the design variables for the seven best cases. Figure 13 compares the chemical oil recovery to that of a continuous waterflood for simulation Case 134 which yielded the highest NPV.

Table 6 shows the results for a simulation in which the oil price is assumed to be roughly the current oil price of \$50/bbls. For this case all the uncertain parameters are set to the base values and the three design variables are set to more favorable values. In order to get a statistical quantification of the profitability under uncertainties, the following optimization step is performed.

A crystal ball model is developed based on the quadratic model found from the RSM analysis. The triangular distributions are then assigned to all the state parameters with their base value as the most likely value. The ranges for all the decision variables were also specified. The optimizer, OptQuest, is launched with a goal of maximizing the mean NPV. After about 400 Monte Carlo simulations, the optimal combination of the decision variables is found under uncertainties. This is for a case where surfactant slug size is 0.1 PV, the initial water flood duration is 1.0 PV, and salt concentration added to the polymer drive is the same as that in the surfactant slug.

The NPV probability distribution is generated by Crystal Ball, with a minimum value of \$240,000 and maximum of \$4,480,000 with an average value of \$2,000,000. The coefficient of variability is 0.38 (Fig. 14). With seven uncertain parameters in which five of them are reservoir properties or reservoir fluids and two are based on the economics, the most likely NPV is about \$2,000,000.

CONCLUSIONS

We have developed a user-friendly and efficient platform that integrates an oil reservoir simulator to perform the flow simulations, an economic model for discounted cash flow analysis, an experimental design and response surface methodology, and a Monte Carlo algorithm with a global optimization search engine to identify the optimum design under conditions of uncertainty. This approach was applied to a field-scale surfactant/polymer flood to find the optimal values of design variables that will maximize the NPV. Based on the work presented, the following can be summarizes:

The proposed approach is practical and can greatly increase the efficiency and productivity for reservoir simulation studies.

- UT_IRSP in conjunction with Design-Expert and Crystal Ball can systematically and efficiently solve sensitivity and optimization under uncertainties.
- An integrated cost analysis model is crucial to design and optimize surfactant floods.
- With optimal design variables for the case studied, the mean NPV is \$2 million with the coefficient of variability of 0.38. This is with the oil price of \$30/bbls to \$70/bbls.
- For the case and reservoir conditions we studied, the most critical factors that affect the surfactant/polymer floods are: (1) oil Price, (2) duration of waterflood prior to the chemical injection, (3) salt concentration in the polymer drive, and (4) the horizontal correlation length.

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Table 1—Summary of Previous Work on the Design and Optimization of Surfactant Flood

Authors	Parameter	Surfactant Flood Mathematical Model		Sensitivity and RSM Study		Optimization		Objective Function	
		Simulator	Simplified Model	Manual	Systematic	Manual	Automatic	Oil Recovery	Econ. Model
Brown <i>et al.</i> (1984)	Residual oil saturation to water and surfactant; Surfactant adsorption; Surfactant relative permeability		✓	✓ with some uncertainty				✓	
Gittler <i>et al.</i> (1985)	Oil Recovery; Oil Price; Facility cost; Chemical cost	✓ CEES			✓ with some economic uncertainty				✓
Barua <i>et al.</i> (1986)	Surfactant concentration, slug size; Polymer slug size; Number of infill wells; Dykstra-Parsons coefficient; IFT; Oil price; Surfactant cost		✓ CFPM	✓			✓ with some uncertainty		✓
Jakobseen <i>et al.</i> (1994)	Surfactant concentration, slug size; IFT; Surfactant adsorption; Critical capillary number; Oil price; Surfactant cost; Discount rate; Operating cost; Well pattern	✓ ECLIPSE		✓ with some uncertainty					✓
Wu <i>et al.</i> (1996)	Chemical concentration, slug size; Polymer concentration; Vertical to horizontal permeability ratio; Permeability realizations; Oil, surfactant and polymer price; Discount rate; Operating cost	✓ UTCHEM		✓ with economic uncertainty		✓			✓ external Excel model
Qu <i>et al.</i> (1998)	Chemical concentration and slug size; Chemical flood starting time	✓ UTCHEM		✓					✓
Zerpa <i>et al.</i> (2004)	Chemical concentration, slug size	✓ UTCHEM				✓		✓	
Zhang <i>et al.</i> (present work)	Surfactant concentration and slug size; Polymer concentration in surfactant drive and concentration and slug size in polymer drive; Salt concentration in every stage of the flood; Surfactant flood starting time; Dykstra-Parsons coefficient; Mean permeability; X-correlation length; Ratio of X to Z correlation length; Vertical to horizontal permeability ratio; Residual oil saturation; Surfactant adsorption; Prices of oil, surfactant and polymer; Discount rate	✓ UTCHEM			✓ with reservoir, fluid and economic uncertainty		✓ with reservoir, fluid and economic uncertainty		✓ internal C++ model

Table 2—State Parameters with Uncertainty

Parameters		Base Value	Low	High
Permeability Field Generation	Dykstra-Parsons Coeff	0.75	0.6	0.8
	Mean Permeability (md)	80	40	100
	X-Correlation Length (ft)	200	130	320
	X/Z Correlation Length	8	1	10
Vertical to Horizontal Permeability Ratio		0.1	0.01	0.5
Residual Oil Saturation		0.33	0.25	0.4
Surfactant Adsorption (mg/g)		0.3	0.1	1
Factors for	Crude Oil Price (\$/bbl)	50	30	70

	Surfactant Price (\$/lb)	1.5	1	2
	Polymer Price (\$/lb)	1.5	1	2
	Discount Rate (%)	15	10	20

Table 3—Design Variables

Variables	Base	Low	High
Pre-Water Flood Duration (PV)	1.8	1	2
Surfactant Slug Size (PV)	0.25	0.1	2
Surfactant Concentration (vol. fraction)	0.02	0.005	0.04
Polymer Drive Slug (PV)	0.5	0	2
Polymer Slug Concentration (wt %)	0.075	0	0.1
Polymer Drive Concentration (wt %)	0.075	0	0.1
Polymer Drive Salinity (meq/ml)	0.34	0.2	0.44
Post-Water Flush Salinity (meq/ml)	0.04	0.04	0.44

Table 4—Other Economic Factors for Discounted Cash Flow Calculation

Economical Variables		Suggested Value
Operating Cost	Water-flood Operating Cost (\$/month)	21250
	Chemical Slug Injection Cost (\$/bbl)	0.2
	Polymer Drive Injection Cost (\$/bbl)	0.1
	Produced Water Cost (\$/bbl)	0.03
	Oil Treatment Cost (\$/bbl)	0.5
	Overhead Cost Rate (%)	15
Tax and Economical Rates	Royalty Rate (%)	12
	Tax Rate (%)	0
	Inflation Rate (%)	2
	Oil Price Escalation (%)	3
	Chemical Price Escalation (%)	0
	Operating Cost Escalation (%)	2
Capital Cost	Work-over Cost (\$)	0
	Development Drilling Cost (\$)	0
	Facility and Equipment Cost (\$)	0
	Leasehold Cost (\$)	0
	Intangible Drilling Cost (\$)	0

**Table 5—The Design Variables of Seven Highest NPV runs
(Oil Price = \$70/bbls; Pre-Waterflood = 1.0 PV; Surfactant Slug = 0.1 PV)**

Sim No	Poly Drive Salt (meq/ml)	X-Correl Length (ft)	DP Coeff	Polymer Price (\$/lb)	Sor	Surf Adsorp (mg/g rock)	Mean Perm (md)
7	0.2	320	0.6	1	0.25	0.1	100
9	0.2	320	0.8	1	0.25	0.1	40
85	0.44	130	0.6	2	0.25	0.1	100
121	0.44	320	0.8	2	0.25	1	100
129	0.2	320	0.8	2	0.4	0.1	40
133	0.2	320	0.6	2	0.4	0.1	100
134	0.44	130	0.6	1	0.4	0.1	100

**Table 6—Profitability for Barrel Oil Produced
(Oil Price = \$50/bbl)**

Profitability/bbl	No discount (\$/bbl)	With discount (\$/bbl)
Revenue	50	50
Royalty	6	6
Capital Cost	0	0
Operating Cost	12.1027	11.3593
Chemical Cost	10.7745	13.3975
Taxes	0	0
Profit	21.1228	19.2432

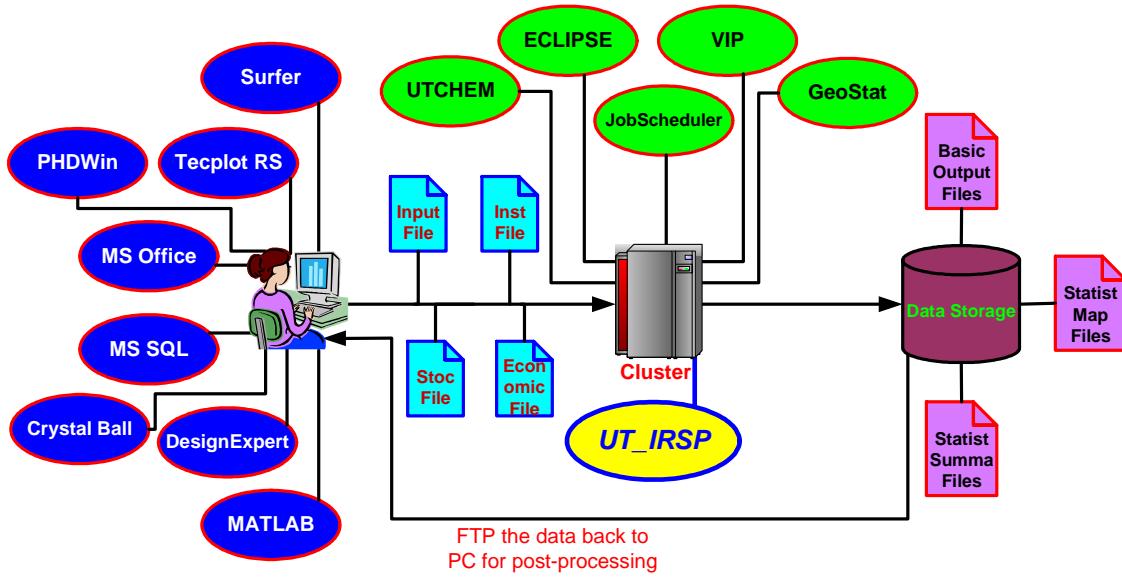


Fig. 1—IRSS - integrated reservoir simulation system.

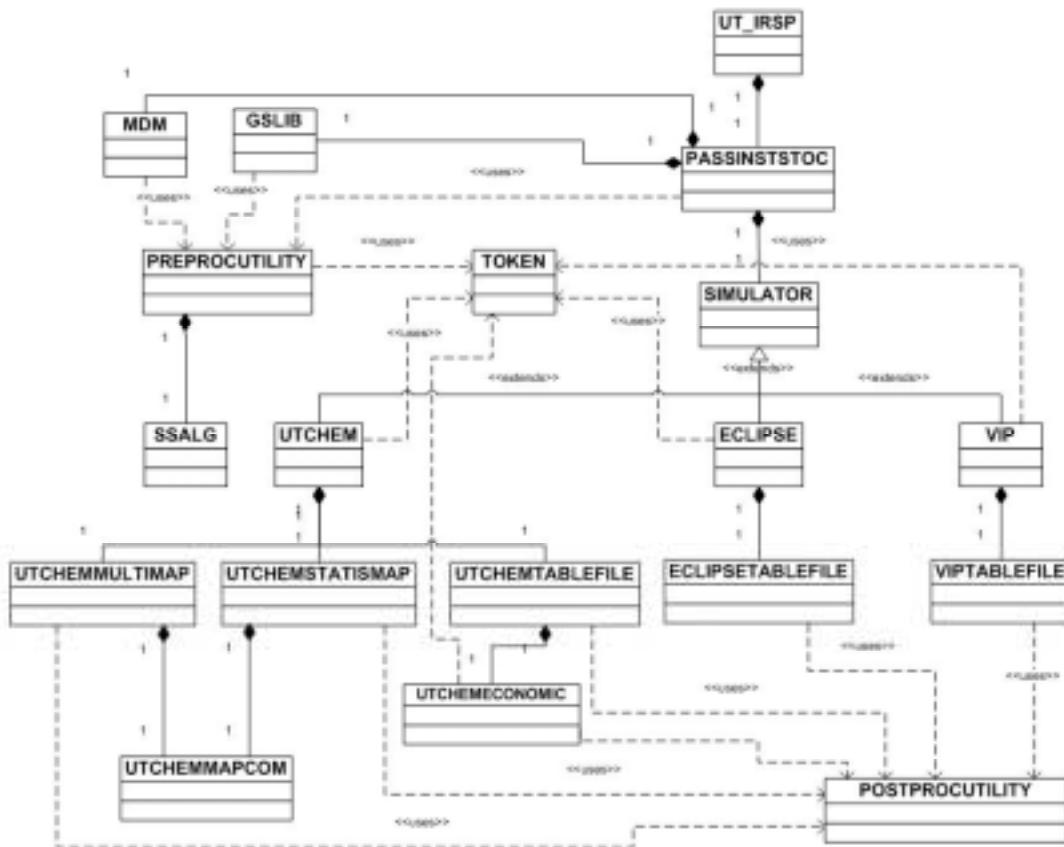


Fig. 2—UML class diagram of framework - UT_IRSP.

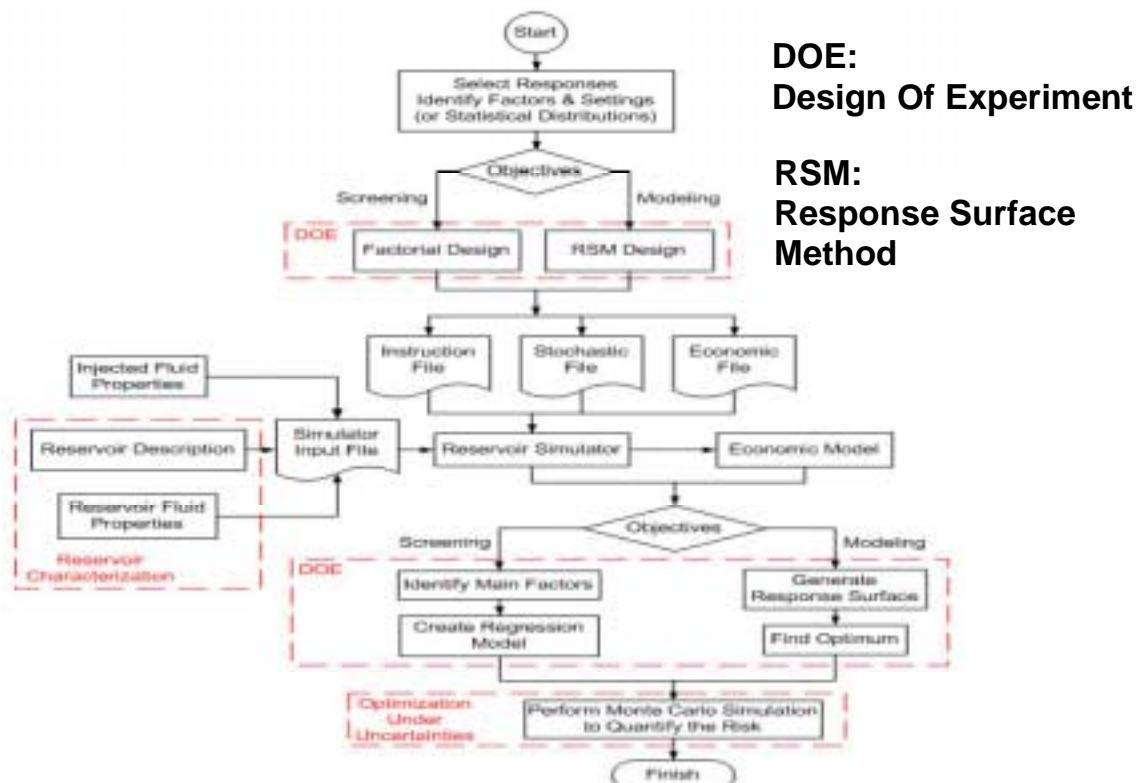


Fig. 3—Experimental design and optimization flowchart.

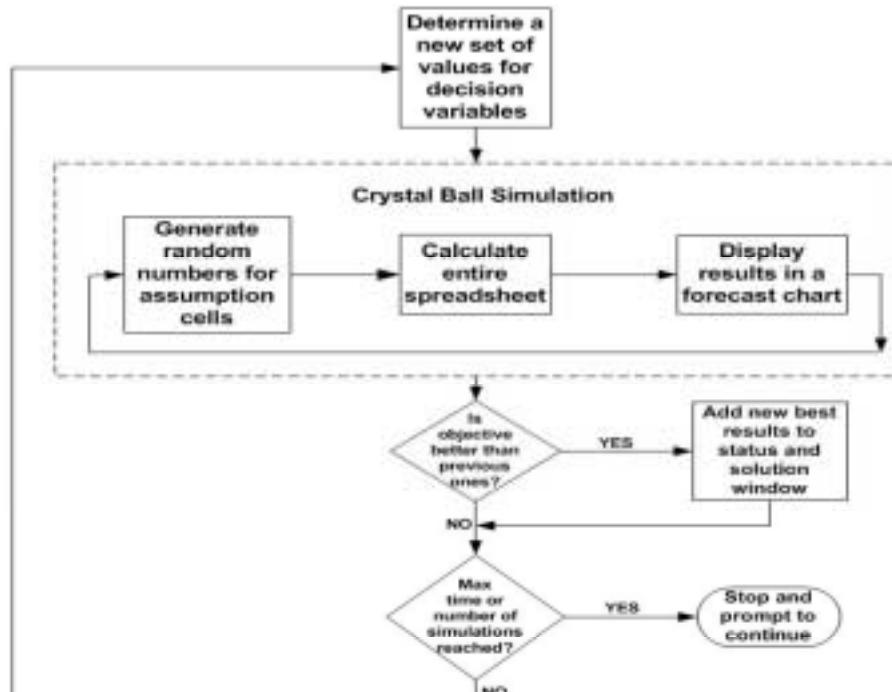


Fig. 4—OptQuest flowchart.

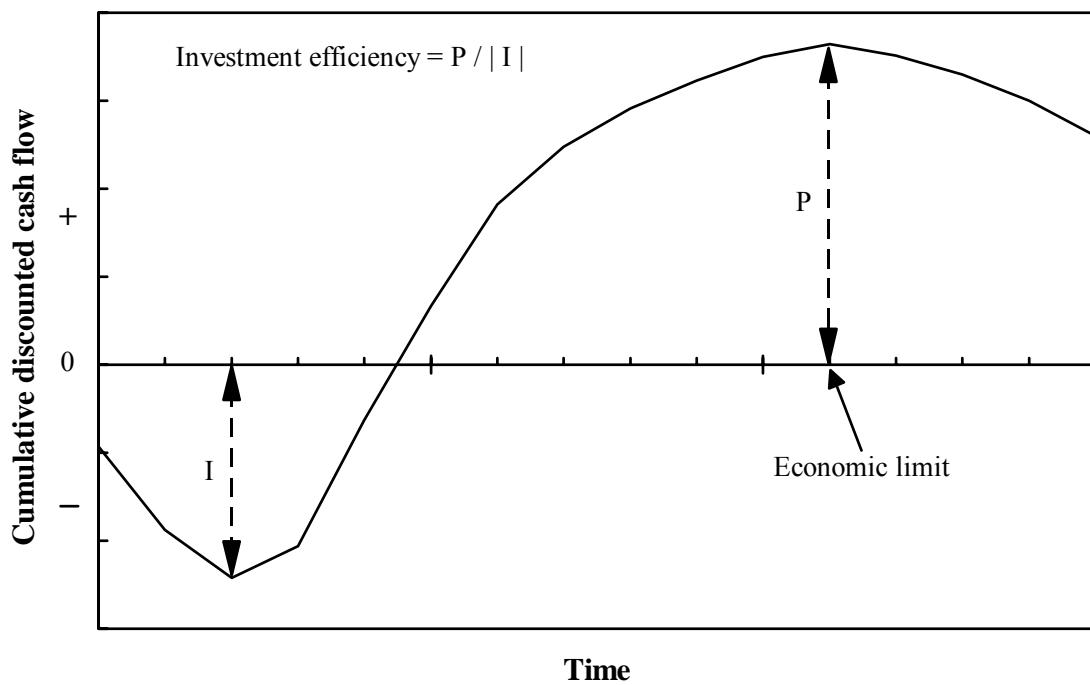


Fig. 5—Definition of economic limit and investment efficiency.

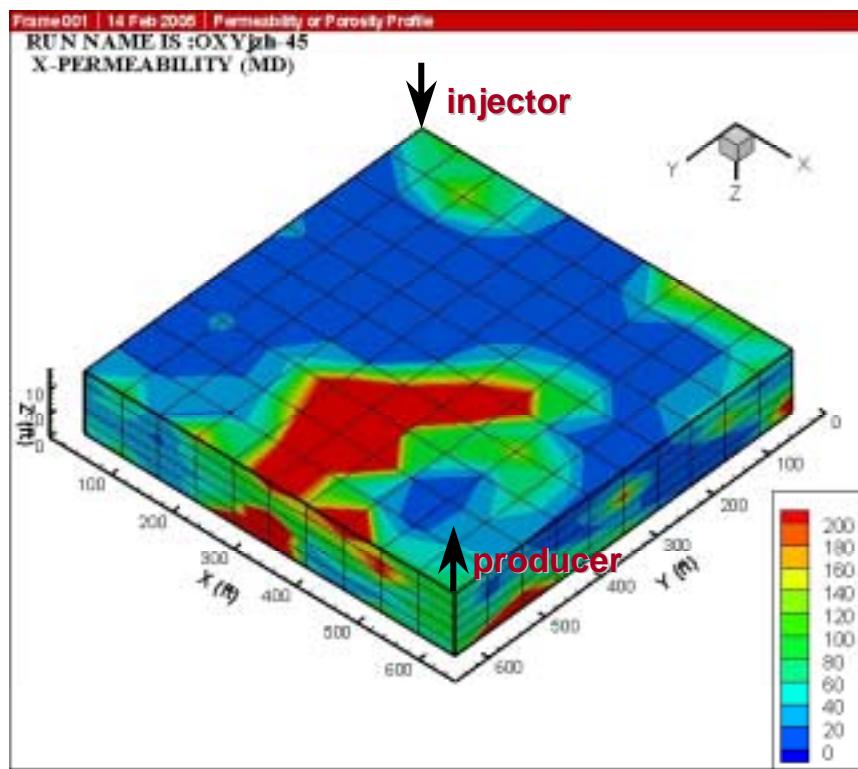


Fig. 6—An example of the permeability realization.

DESIGN-EXPERT Plot
NPV

- 6 A: DP Coeff
- 10 B: Mean Perm
- 4 C: X-Col Length
- D: X-Col/Z-Col
- E: Pz/Px
- 8 F: Sor
- 9 G: Surf Adsorp
- 1 H: Oil Price
- J: Surf Price
- 7 K: Poly Price
- L: Discount Rate
- 2 M: PreWaterPV
- 5 N: SurfSlugPV
- O: SurfConc
- P: PolyDrivePV
- Q: PolySlugConc
- R: PolyDriveConc
- 3 S: PolyDriveSalt
- T: PostWaterSalt

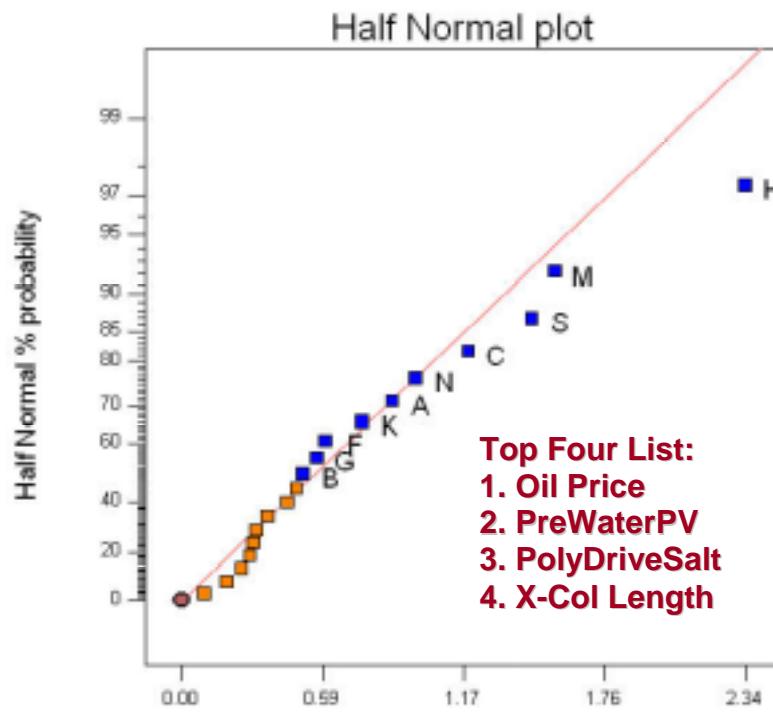


Fig. 7—Screening of nineteen factors with Plackett-Burman design.

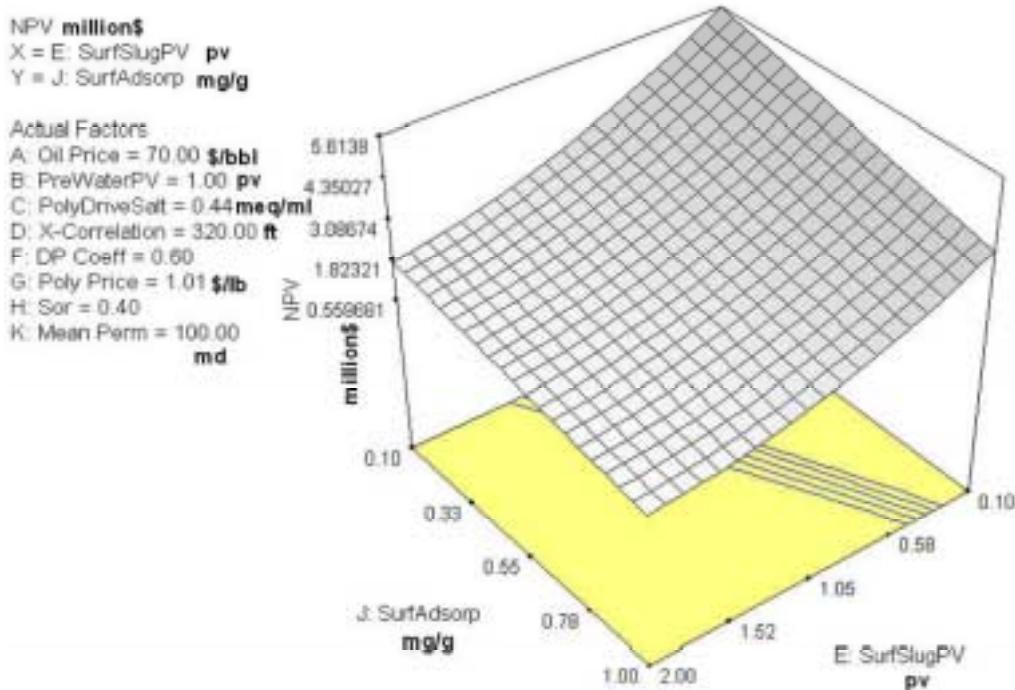


Fig. 8—Response surface for surfactant concentration and adsorption.

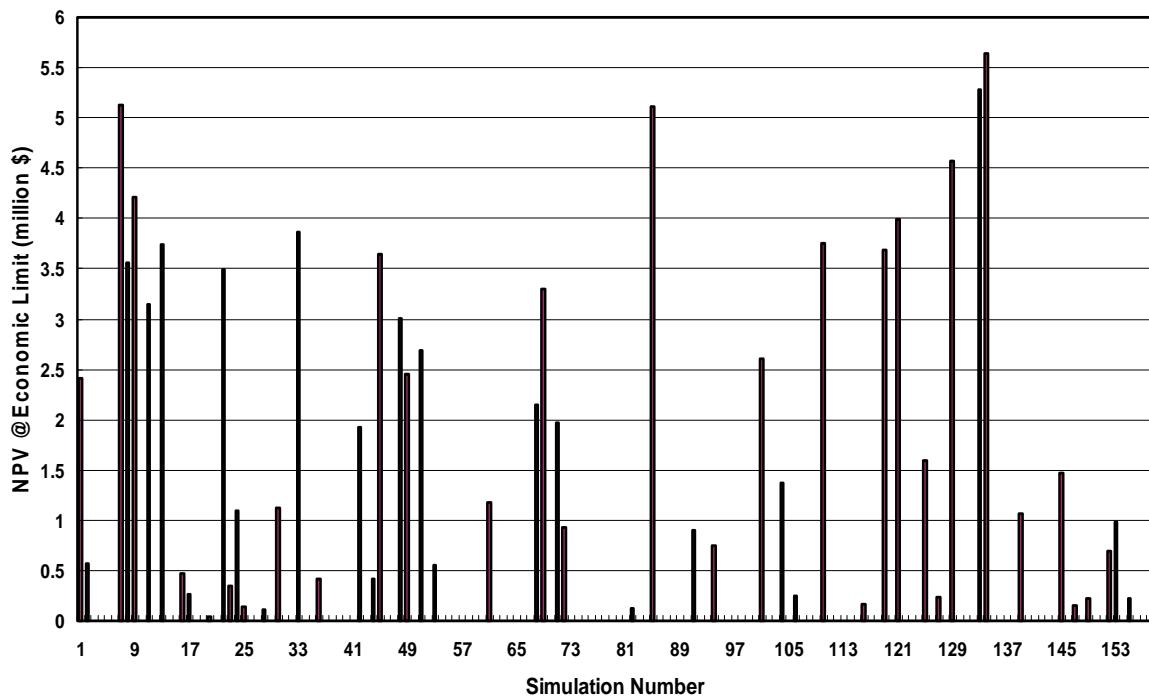


Fig. 9—Net present value at the economic limit for 158 simulations from CCD.

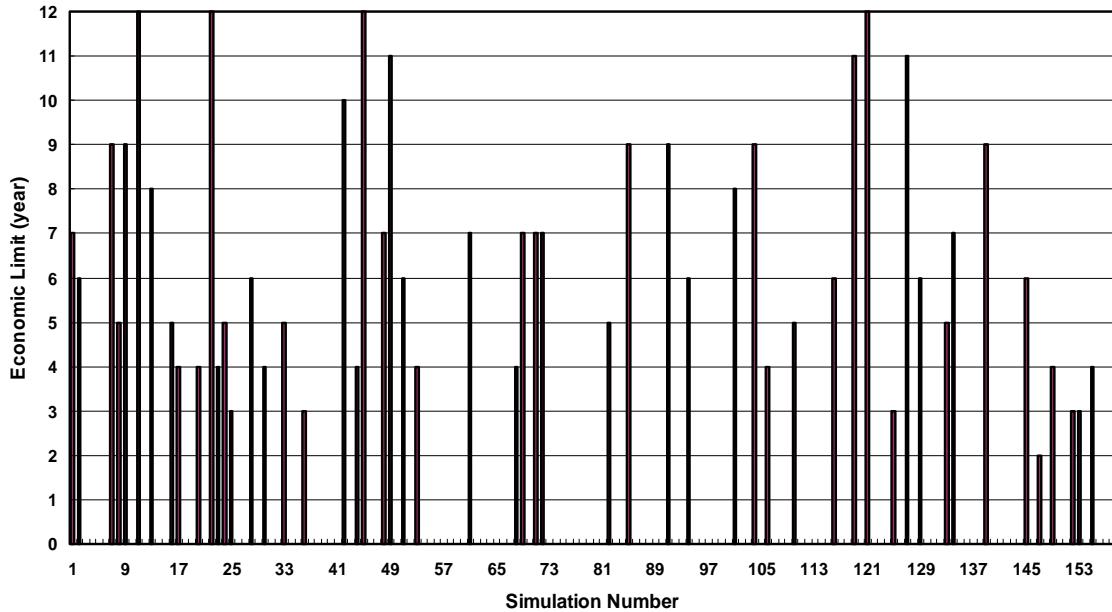


Fig. 10—Economic limit for 158 simulations from CCD.

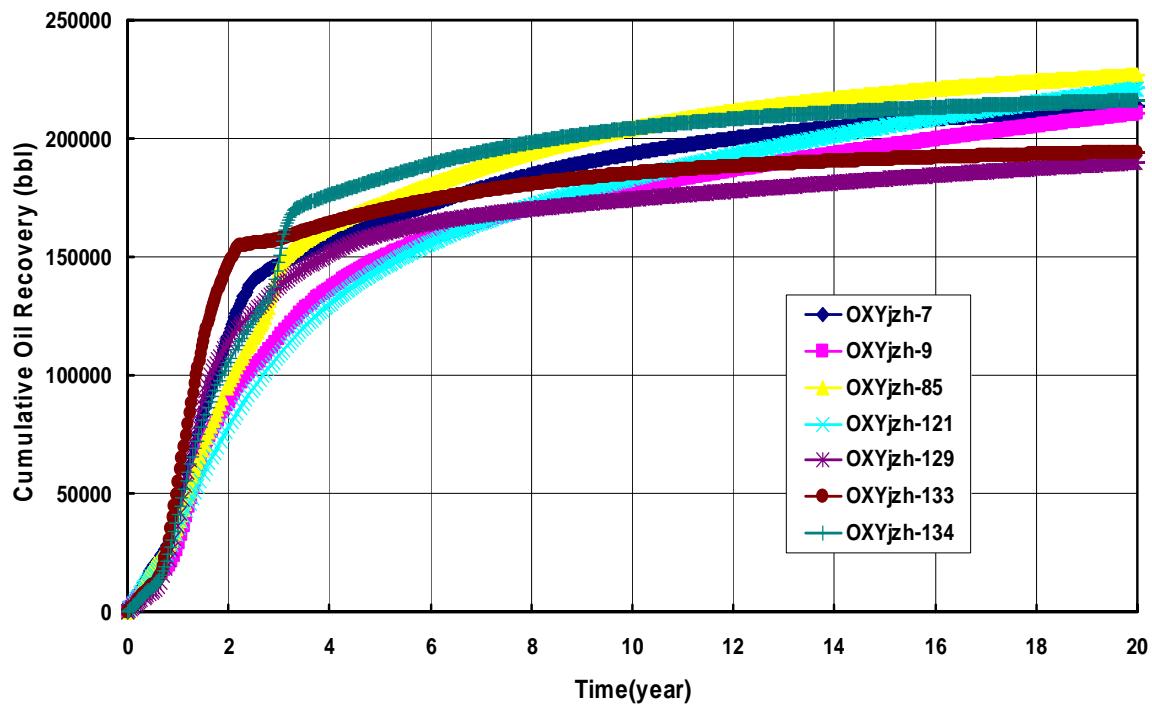


Fig. 11—Cumulative oil recovery of the 7 runs from 158 CCD simulations.

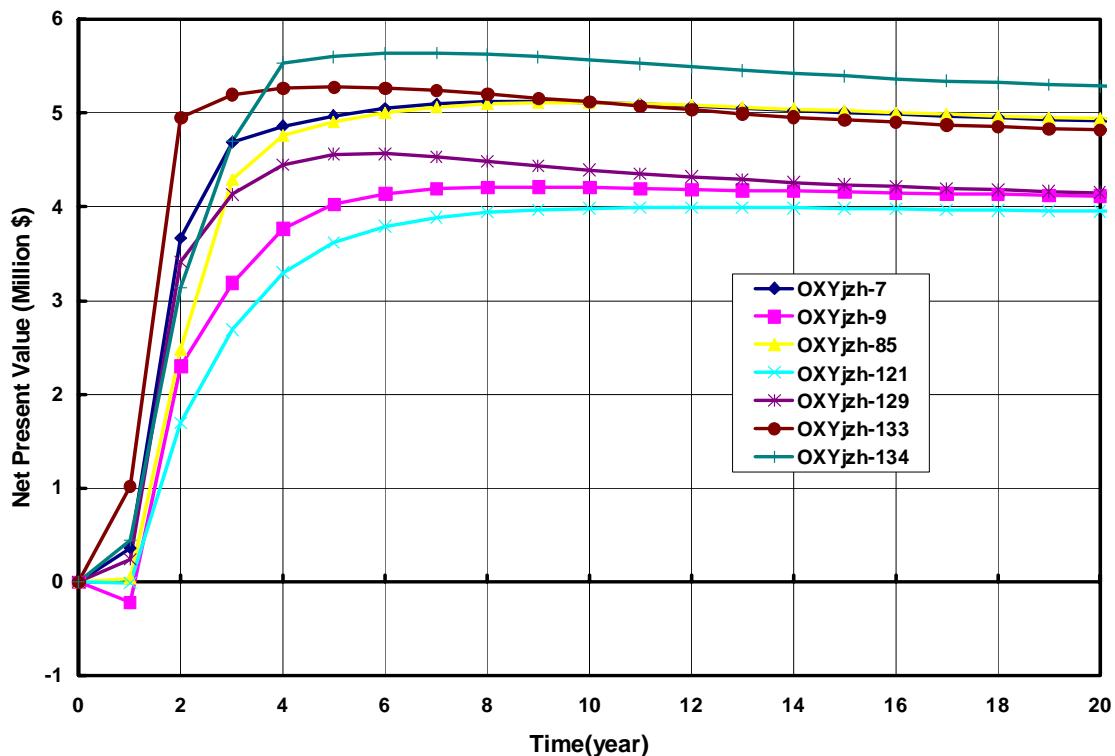


Fig. 12—NPV of the best 7 among 158 CCD simulations.

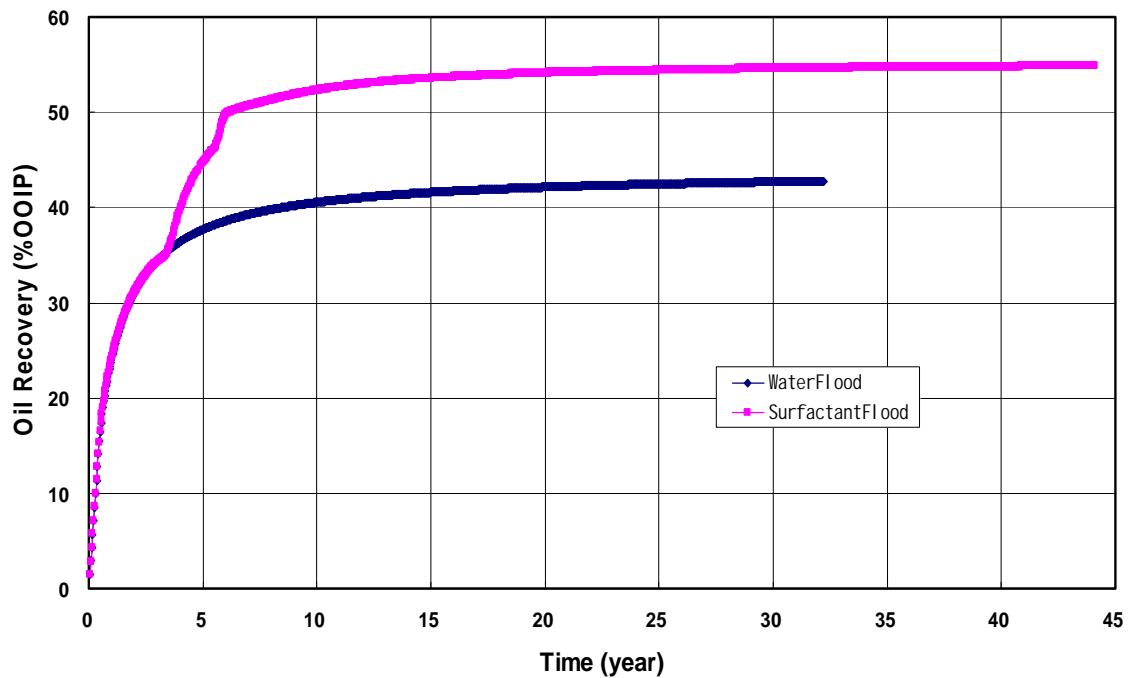


Fig. 13—Comparison of water flood and surfactant flood oil recovery for Run 134.

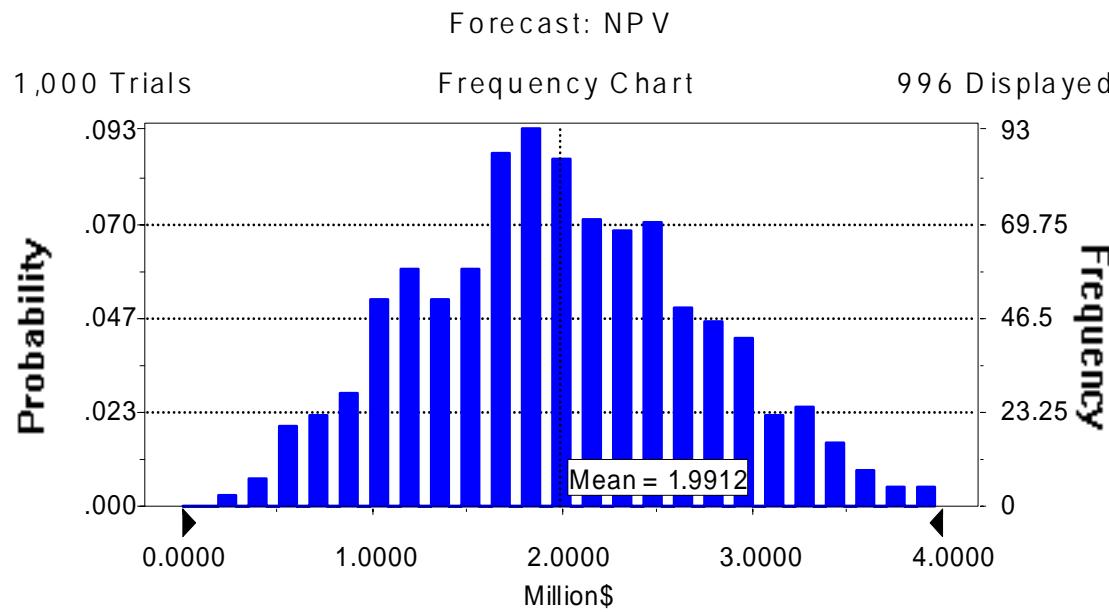


Fig. 14—Probability distribution for net present value in million dollars.