

Area Control Simulator Program Volume 3: Program Listing

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Research Project 1048-4

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Prepared by

PHILADELPHIA ELECTRIC COMPANY
Research and Testing Division
2301 Market Street
Philadelphia, Pennsylvania 19101

Principal Investigators
L. M. Smith
J. H. Spare

Prepared for

Electric Power Research Institute
3412 Hillview Avenue
Palo Alto, California 94304

EPRI Project Manager
C. J. Frank

Power Systems Planning and Operation Program
Electrical Systems Division

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Prepared by
Philadelphia Electric Company
Philadelphia, Pennsylvania

ABSTRACT

The purpose of this EPRI-sponsored study was to develop a digital computer simulation program for a single-area power system, and to hold a Workshop at which this simulation package would be presented. This and the companion volumes present our philosophy of modeling a power system and demonstrate the simulation capabilities of the Area Control Simulator. The results of this research study have been the development of the Area Control Simulator, the Area Control Simulator Workshop held May 1-3, 1979 and the creation of the Technical Manual (Volume 1), the Programming Manual (Volume 2), and the Program Listing (Volume 3).

The above-mentioned three volumes in addition to a fourth volume covering a multi-area model development serve as a final report for this project.



EPRI PERSPECTIVE

PROJECT DESCRIPTION

Over the past 50 years, all electric utilities have increased their interconnections with each other. In fact, there are currently just three groups of interconnected networks of utilities for all the power generated in the United States and Canada. Historically, area control of generation was accomplished manually. Then, analog computer generation control was developed to reduce manual control requirements. More recently, direct digital computer control systems have been installed, which provide the potential for improved control.

The growth of the interconnected networks has placed increasing demands on our ability to analyze and control each generator's performance. This has stimulated a need to mathematically simulate the control system in the interconnected networks both to evaluate current control strategies and to develop improved strategies.

PROJECT OBJECTIVES

This project under RP1048-1 had two objectives:

1. To develop a digital computer, two-area control simulator program for use by EPRI member utilities to evaluate and improve their current control strategies. This program was also being developed for use in a companion project, RP1048-1, where interconnected control performance was being analyzed by Control Data Corporation (CDC).
2. To develop a multiarea control simulator program for use by CDC on RP1048-1.

PROJECT RESULTS

The simulator programs that were developed during this project were based on a digital computer program developed by Philadelphia Electric Company (PECO) to analyze control strategies in the Pennsylvania-Maryland-New Jersey (PJM) Power Pool. The simulator program developed for EPRI can be used to analyze control actions of generators in one control area (usually a single utility) that is part of a larger interconnected network. The simulator has two features not available in other simulators currently in use:

1. It includes mathematical models and representative data for most types of generators commonly used in the United States and Canada (fossil, hydro, gas turbine, and boiling water nuclear reactor).

2. It is based on generation models that were already developed and extensively field-tested by PECO and PJM prior to the EPRI contract.

The area control simulators developed in this project were successfully used by CDC while performing the research on RP1048-1. Two versions of the area control simulator were supplied to CDC. The first used two control areas: one for the control area to be analyzed and one for the remaining interconnected utilities. The second allowed up to 10 control areas to be analyzed simultaneously. The CDC research showed that the first version was preferable for analyzing control strategies. A copy of this first version of the simulator is available from the Electric Power Software Center.

The computer program developed for this project might be classified as an engineering-grade program. This means it has been tested thoroughly as to the integrity of the programming and the accuracy of the results. However, several limitations in the use of the simulator should be pointed out:

1. The data input requires a user with good knowledge of the models.
2. The input is not user-oriented for entering large amounts of data.
3. Many of the models and their data are imbedded in the computer program and limit the flexibility of the simulator usage.

If EPRI finds there is sufficient demand by users of the area control simulator program, a production-grade version of the simulator could be developed which overcomes the above limitations. In the production-grade development, the simulator data requirements would be coordinated with the data requirements of the long-term dynamics program being developed in RP1469.

Charles J. Frank, Project Manager
Electrical Systems Division

SUMMARY

This research project has resulted in the development of two power system models that are similar. The first is a single-area power system simulation, the Area Control Simulator, the second is a multi-area power system simulation that was used in a companion research project. Both computer programs are FORTRAN stand-alone structures that offer such user-oriented features as print and plot options, load data or available space for a load model, optional external area power systems to be tied into the system under study, optional statistical variations to the load data (sine wave, random noise, frequency feedback) and functions designed to simulate dynamic behavior (limits, deadspaces, delays, etc.). One workshop has been given to date on the Area Control Simulator with the material in Volumes 1, 2 and 3 serving as User's Manuals, detailing design features. These simulation programs are available through EPRI and provide an engineering-grade tool to quantitatively and qualitatively analyze new control structures and strategies. They provide a test bed on which repeatable case studies can be analyzed and system sensitivities can be determined.

These simulators are designed to have new or existing automatic generation control algorithms as their input and basis of analysis. The algorithms included with these programs are merely intended to make the simulation whole and operable and should be replaced or restructured by the user.

This volume presents the computer listing of the Area Control Simulator. The user can refer to the Programming Manual, Volume 2, to gain an understanding of program changes and their effect on the simulator program. The Technical Manual, Volume 1, covers the dynamics that are simulated in this listing. Both of the previous volumes refer to specific sections of the simulator listing by subroutine, function or data set name. In this simulator listing, all data sets are grouped at the beginning, followed by the subroutines then functions. There are comments and instructions throughout the listing.

INTRODUCTION

The Program Listing, (Volume 3), is a self-contained digital computer program of the Area Control Simulator. It is a FORTRAN stand-alone program and the listing includes both instructions and comments to the user. The time-sharing version of this program (80 character width for CRT display) has prompting messages to help specify the most used (or changed) system variables. There is a duplicate version for batch running (132 character width for printout paper). The simulator requires, as an input, either load data from a disk file (as in this version) or a load model (to be programmed by the user and added to the listing). The output is in the form of printout and plots. The plot information requires a second disk file (temporary data set) to store the plot information between computation and plot printout.

The listing has been arranged to include the data sets at the beginning of the program, followed by the subroutines then the functions. The data sets include input and output data in addition to the system variable storage areas. There is a cross-reference in the first page of the listing that shows where each data set or common area is used throughout the program. The block data sets are then sequenced, explained, and listed. All of the parameters are dimensioned in these explanations, some of the unitless variables are left undimensioned. The subroutines are developed in the Technical Manual, Volume 1, and the Programming Manual, Volume 2, of this report. There are further descriptions given throughout the subroutine and function listings. The subsections of each subroutine are separated and titled for easier reference.

[illegible]

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C -----
C *      1      COMMON / CURVAL /      *
C -----
C
C COMMON /CURVAL/ CONTAINS INITIAL CONDITIONS AND CONSTANTS
C FOR THE INERTIA, EXTERNAL AREA, DISPATCH OFFICE, AND
C LOADER MODELS
C
C THE FOLLOWING SUBROUTINES PASS COMMON /CURVAL/ IN ITS
C ENTIRETY:      MAIN      INERTA      LOADER      EXTERNL      LDD
C
C THE REMAINING SUBROUTINES USING COMMON /CURVAL/ GENERALLY
C PASS ONLY TIME, DELT, AND KEEP
C
C BLOCK DATA
COMMON / CURVAL / TIME , DELT , KEEP , NUNIT , GOTIME, N ,
1      FREQHZ, PM(20), OMEGA , TM , PMSYS , PMTOT ,
2      PELSY , PACCEL, LOAD , LDDTOT, H , PTINET ,
3      PMEXT , LODEXT, DUTE02, SPIEX , DUTIE3, DUTIE4,
4      DUTIE5, DUTIE6, DEDIEX, CEXT01, CEXT02, CEXT03,
5      CEXT04, CEXT05, CEXT06, CEXT07, CEXT08, CEXT09,
6      CEXT10, CEXT11, ACEEXT, DUTE03, DUTE04, DUTE05,
7      PDROP , DEEXT, PGJVE, SPEXT , CTIMR , CBIAS ,
8      CADD , CKCR , KLR , DUM , CLSUP , KLP ,
9      CSKEDF, INADV , LAM , SKDTI , TIMBS , FRQBS ,
A      ACE , AR , MWNEW , LNEW , PEC(20) ,
B      SP(20), PEB(20) , UCE(20) , UCE1 ,
C      PMS(20) , FINTIM, KEXTRN, PFREQ , AMPLTD,
D      WAVEON, WAVEFR, WAVEPH, PNOISE, NSEED , MU ,
E      SIGMA
C
C REAL*4      LOAD , LDDTOT, LODEXT, KLR , KLP , INADV , LAM ,
1      MWNEW , LNEW , MU
C
C -----
C INERTIA MODEL
C INITIAL CONDITIONS AND CONSTANTS
C -----
C
C DATA TIME,DELT,KEEP,NUNIT,GOTIME,N/0.,1.,0,8,39668.2,1/

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EXTERNAL AREA
INITIAL CONDITIONS AND CONSTANTS

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COMM1120
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COMM1180
COMM1190
COMM1200

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PMEXT	MECHANICAL POWER FOR THE EXTERNAL AREA	-- MW
LOADEXT	EXTERNAL SYSTEM LOAD	-- MW
OUTE02	OUTPUT OF A.G.C. TIME LAG	-- MW
SPIEX	INITIAL CONDITION OF GOVERNOR	-- MW
OUTIE3	INITIAL CONDITION OF BOILER LAG	-- MW
OUTIE4	INITIAL CONDITION OF INTEGRAL CONTROLLER	-- MW
OUTIE5	INITIAL CONDITION OF FIRING LAG	-- MW
OUTIE6	INITIAL CONDITION OF TURBINE REHEAT LAG	-- MW
DEDIEX	INITIAL CONDITION OF GOVERNOR DEADBAND	-- MW
CEXT01	FREQUENCY BIAS	-- MW/.1HZ
CEXT02	ACE GAIN	
CEXT03	DEADBAND	-- MW
CEXT04	BOILER PRESSURE DROP FACTOR	
CEXT05	BOILER LAG	-- SEC
CEXT06	FIRING LAG	-- SEC
CEXT07	BOILER PROPORTIONAL CONTROL GAIN	
CEXT08	BOILER INTEGRAL CONTROL GAIN	
CEXT09	NONREHEAT PORTION OF TURBINE	
CEXT10	TURBINE REHEAT LAG	-- SEC
CEXT11	SPEED DROOP FACTOR	
ACEEXT	AREA CONTROL ERROR	-- MW
OUTE03	OUTPUT OF BOILER LAG	-- MW
OUTE04	OUTPUT OF INTEGRAL CONTRL	-- MW
OUTE05	OUTPUT OF FIRING LAG	-- MW
PDROP	SUM OF BOILER STATE AND PRESSURE DROP FACTOR	
		-- MW
DEDEXT	GOVERNOR DEADBAND OUTPUT	-- MW
PGOVEX	INPUT TO GOVERNOR DEADBAND	-- MW
SPEXT	GOVERNOR SET POINT	-- MW

-5-

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C

DISPATCH OFFICE
INITIAL CONDITIONS AND CONSTANTS

```
DATA CTIMR,CBIAS,CADD,CKCR/-19.4,-97.,0.,.15/  
DATA KLR,DUM,CLSUP,KLP/.0441,0.,0.,.1/  
DATA CSKEDF,INADV,LAM/60.,0.,0./  
DATA SKDTI,TIMBS,FRQBS,ACE,AR,MWNEW/6*0./  
DATA LNEW,PEC,SP,PEB,UCE,UCE1/82*0./  
DATA PMS/20*0./
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 . NOMENCLATURE

CTIMR	SYSTEM TIME ERROR BIAS	-- MW/SEC	COMM1800
CBIAS	SYSTEM FREQUENCY BIAS	-- MW/.1HZ	COMM1810
CADD	AGC MANUAL ADD	-- MW	COMM1820
CKCR	ACE TO AR FILTER CONSTANT		COMM1830
KLR	LAMBDA RESET		COMM1840
DUM	DUMMY		COMM1850
CLSUP	MANUAL ADD TO SYSTEM COST	-- MILS/KWH	COMM1860
KLP	PROPORTIONAL GAIN FOR SYSTEM COST		COMM1870
CSKEDF	SCHEDULED FREQUENCY	-- HZ	COMM1880
INADV	INADVERTANT INTERCHANGE OF POWER	-- MW	COMM1890
LAM	SYSTEM COST	-- MILS/KWH	COMM1900
SKDTI	SCHEDULED TIE LINE FLOW	-- MW	COMM1910
TIMBS	TIME ERROR BIAS	-- MW/SEC	COMM1920
FRQBS	FREQUENCY ERROR BIAS	-- MW/.1HZ	COMM1930
ACE	AREA CONTROL ERROR	-- MW	COMM1940
AR	AUTOMATIC REGULATION	-- MW	COMM1950
MWNEW	SYSTEM MW DEMAND	-- MW	COMM1960
LNEW	RESULT OF TABULAR LOOKUP ON AR LAMBDA CURVE		COMM1970
PEC	ECONOMIC POWER DEMAND FOR EACH UNIT	-- MILS/KWH	COMM1980
SP	GOVERNOR SET POINT	-- MW	COMM1990
PB	PRESSURE ERROR BIAS BOILER COORDINATED CONTROLS	-- MW	COMM2000
PB	PRESSURE ERROR BIAS BOILER COORDINATED CONTROLS		COMM2010

C			-- MW/P.U.	COMM2020
C	UCE	UNIT CONTROL ERROR	-- MW	COMM2030
C	UCE1	UCE	-- MW	COMM2040
C	PMS	TELEMETERED UNIT OUTPUT POWER	-- MW	COMM2050
C				COMM2060
C				COMM2070
C	PEC, SP, PEB, UCE, AND PMS ARE DIMENSIONED BY THE MAXIMUM			COMM2080
C	NUMBER OF UNITS			COMM2090
C				COMM2100
C				COMM2110
C		-----		COMM2120
C		LOADER MODEL PARAMETERS		COMM2130
C		-----		COMM2140
C				COMM2150
	DATA PFREQ/0./			COMM2160
	DATA AMPLTD,WAVEON,WAVEFR,WAVEPH/0.,0.,0.,0./			COMM2170
	DATA PNOISE,NSEED,MU,SIGMA/0.0,7,0.,1./			COMM2180
C				COMM2190
C				COMM2200
C		. NOMENCLATURE .		COMM2210
C				COMM2220
C				COMM2230
C	PFREQ	FREQUENCY FEEDBACK GAIN IN LOADER VARIATIONS		COMM2240
C	AMPLTD	AMPLITUDE OF SINUSOIDAL WAVE	-- MW	COMM2250
C	WAVEON	INITIATION TIME OF SINUSOIDAL WAVE	-- SEC	COMM2260
C	WAVEFR	FREQUENCY OF SINUSOIDAL WAVE	-- RAD/SEC	COMM2270
C	WAVEPH	PHASE SHIFT OF SINUSOIDAL WAVE	-- RAD	COMM2280
C	PNOISE	NOISE AMPLITUDE	-- MW	COMM2290
C	NSEED	ANY ODD INTEGER (SEED FOR NOISE GENERATOR)		COMM2300
C	MU	MEAN OF NORMAL GAUSSIAN DISTRIBUTION (NOISE GENER-		COMM2310
C		ATOR)		COMM2320
C	SIGMA	STANDARD DEVIATION OF NORMAL GAUSS. DIST.		COMM2330
C				COMM2340
C				COMM2350
	END			COMM2360

C	-----	COMM0010
C	* 2 COMMON / CONST1 / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /CONST1/ CONTAINS CONSTANTS THAT WILL BE FOUND IN THE	COMM0050
C	LDD OFFICE	COMM0060
C		COMM0070
	BLOCK DATA	COMM0080
	COMMON / CONST1 / CLDD(4) , C01(20) , C02(20)	COMM0090
1	C03(20) , C04(20) , C05(20)	COMM0100
	DATA CLDD/2.,60.,1.,2./	COMM0110
	DATA C01/0.25,0.38,0.13,0.15,0.067,0.067,0.833,1.0,12#0./	COMM0120
	DATA C02/0.,0.37,0.17,0.16,0.,0.30,14#0./	COMM0130
	DATA C03/1.,1.,1.,1.,1.,1.,1.,1.,12#0./	COMM0140
	DATA C04/1.,.0094,0.1,.0094,0.1,0.095,1.,1.,12#0./	COMM0150
	DATA C05/20#0./	COMM0160
C		COMM0170
C		COMM0180
C	. NOMENCLATURE .	COMM0190
C		COMM0200
C		COMM0210
C	CLDD CONSTANTS FOR CALCULATION OF AR AND LAM	COMM0220
C	C01 GOVERNOR RATE LIMITS -- MW/SEC	COMM0230
C	C02 UNIT PARTICIPATION IN AR -- %	COMM0240
C	C03 TELEMETRY TIME DELAY -- SEC	COMM0250
C	C04 GOV. CONTROLLER PROPORTIONAL GAIN	COMM0260
C	C05 GOV. CONTROLLER RESET GAIN	COMM0270
C		COMM0280
C		COMM0290
C		COMM0300
C	THE CONSTANT ARRAYS C01 THROUGH C05 ARE DIMENSIONED BY THE	COMM0310
C	THE MAXIMUM NUMBER OF UNITS	COMM0320
C		COMM0330
C		COMM0340
C	END	COMM0350

C	-----	COMM0010
C	* 3 COMMON / INITIAL / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /INITAL/ CONTAINS THE INITIAL MW SETTING OF EACH PRIME	COMM0050
C	MOVER, THE MWR OF EACH UNIT, AND THE UNIT TYPE FOR EACH	COMM0060
C	UNIT	COMM0070
C		COMM0080
C	MAIN PROGRAM AND SUBROUTINE LDJ USE COMMON /INITAL/ IN	COMM0090
C	ITS ENTIRETY	COMM0100
C		COMM0110
C	SUBROUTINES BOILER, HYDRO, GASTUB, AND NUCLER USE	COMM0120
C	COMMON /INITAL/ TO PASS MWR	COMM0130
C		COMM0140
C	BLOCK DATA	COMM0150
C	REAL*4 MWR , INITIAL	COMM0160
C	COMMON / INITIAL / PI(20), UNTYPE(20) , MWR(20)	COMM0170
C	DATA PI/1550.,1620.,330.,500.,175.,538.,310.,301.,12*0./	COMM0180
C	DATA UNTYPE/1.,7.,8.,7.,8.,2.,6.,6.,12*0./	COMM0190
C	DATA MWR/1550.,1749.,346.,516.,190.,550.,654.,690.,12*0./	COMM0200
C		COMM0210
C		COMM0220
C	. Nomenclature .	COMM0230
C		COMM0240
C	PI(N) INITIAL SETTINGS FOR THE PRIMEMOVERS-- MW	COMM0250
C	UNTYPE(N) ARRAY USED TO DISTINGUISH THE TYPE OF UNIT	COMM0260
C	MWR(N) MEGAWATT RATING OF THE UNIT -- MW	COMM0270
C	N UNIT SEQUENTIAL NUMBER	COMM0280
C		COMM0290
C		COMM0300
C		COMM0310
C	----- KEY TO UNIT TYPE -----	COMM0320
C		COMM0330
C	UNTYPE(N)= 1---NUCLEAR UNIT	COMM0340
C	2---BOILER, SUPERCRITICAL ONCE THROUGH UNIT	COMM0350
C	3---BOILER, SUBCRITICAL ONCE THROUGH .	COMM0360
C	4---BOILER, DRUM TYPE UNIT,OIL	COMM0370
C	5---HYDRO UNIT	COMM0380
C	6---GASTURBINE UNIT	COMM0390
C	7---BOILER, DRUM TYPE UNIT,COAL	COMM0400

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C

8---BOILER, NON-REHEAT DRUM TYPE UNIT

PI, UNTYPE, AND MWR ARE DIMENSIONED BY THE MAXIMUM NUMBER
OF UNITS

END

COMM0410
COMM0420
COMM0430
COMM0440
COMM0450
COMM0460
COMM0470
COMM0480

```

C -----
C *      4      COMMON / COST /      *
C -----
C
C COMMON /COST/ CONTAINS COST CURVES FOR EACH UNIT FOLLOWED BY
C OTHER FUNCTION GENERATOR CURVES
C
C COMMON /COST/ IS FOUND IN THE AFGEN FUNCTION SUBROUTINE
C
C THE AFGEN FUNCTION SUBROUTINE IS CALLED FROM:
C -- EXTRNL TO COMPUTE SKEDTX
C -- LDD TO COMPUTE SKDTI, M41, AND PEC
C
C BLOCK DATA
C COMMON / COST / UNIT1(20) , UNIT2(20) , UNIT3(20) ,
1 UNIT4(20) , UNIT5(20) , UNIT6(20) ,
2 UNIT7(20) , UNIT8(20) , SKEDTX(20) ,
3 SKDTI(20)
C DATA UNIT1/ 0., 500., 4.4, 500., 4.5, 1100., 4.6, 1550.,
1 60., 1550., 10*0./
C DATA UNIT2/ 0., 200., 5.5, 200., 5.9, 800., 6.2, 1128.,
1 6.3, 1230., 6.7, 1490., 6.9, 1620., 60., 1620.,
2 4*0./
C DATA UNIT3/ 0., 10., 7.0, 10., 8.0, 57., 8.6, 154.,
1 9.1, 240., 9.5, 294., 10.3, 330., 60., 330.,
2 4*0./
C DATA UNIT4/ 0., 15., 7.8, 15., 7.9, 52., 8.3, 139.,
1 8.5, 203., 8.8, 413., 9.2, 482., 9.4, 500.,
2 60., 500., 2*0./
C DATA UNIT5/ 0., 10., 9.8, 10., 11.1, 70., 12.4, 100.,
1 13.3, 135., 16.3, 171., 33.7, 181., 46.5, 190.,
2 60., 190., 2*0./
C DATA UNIT6/ 0., 20., 7.5, 20., 7.6, 325., 7.9, 400.,
1 8.3, 475., 8.6, 538., 60., 538., 6*0./
C DATA UNIT7/ 0., 60., 21.0, 60., 22.9, 214., 24., 310.,
1 25.8, 480., 60., 480., 8*0./
C DATA UNIT8/ 0., 40., 19.9, 40., 23.8, 278., 26.0, 534.,
1 31.2, 690., 60., 690., 8*0./
C
C COMM0010
C COMM0020
C COMM0030
C COMM0040
C COMM0050
C COMM0060
C COMM0070
C COMM0080
C COMM0090
C COMM0100
C COMM0110
C COMM0120
C COMM0130
C COMM0140
C COMM0150
C COMM0160
C COMM0170
C COMM0180
C COMM0190
C COMM0200
C COMM0210
C COMM0220
C COMM0230
C COMM0240
C COMM0250
C COMM0260
C COMM0270
C COMM0280
C COMM0290
C COMM0300
C COMM0310
C COMM0320
C COMM0330
C COMM0340
C COMM0350
C COMM0360
C COMM0370
C COMM0380
C COMM0390
C COMM0400

```

C
C
C
C
C

THIS SPACE RESERVED FOR FUTURE UNITS

DATA SKEDTX/0.,0.,3600.,0.,16*0./
DATA SKDTI /0.,0.,3600.,0.,16*0./

C
C

COMM0410
COMM0420
COMM0430
COMM0440
COMM0450
COMM0460
COMM0470
COMM0480
COMM0490

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C

.....
. NUMENCLATURE .
.....

SKEDTX EXTERNAL TIE FLOW -- MW
SKDTI SCHEDULED TIE LINE FLOW -- MW

THE ARRAYS ABOVE ARE DIMENSIONED FOR TEN SETS OF DATA PAIRS
FOR A TOTAL OF 20 STORAGE LOCATIONS. ANY MODIFICATION
OF THIS DIMENSIONING WILL REQUIRE NEW CODING IN THE AFGEN
FUNCTION SUBROUTINE.

COST CURVES FOR ADDITIONAL UNITS SHOULD BE PLACED IN THE
SPACE RESERVED ABOVE. SPECIFICALLY, THEY MUST BE PLACED
BEFORE ANY OTHER FUNCTION GENERATOR CURVES. THE ADDED
COST CURVES SHOULD HAVE PRECISELY TEN DATA PAIRS.

END

COMM0500
COMM0510
COMM0520
COMM0530
COMM0540
COMM0550
COMM0560
COMM0570
COMM0580
COMM0590
COMM0600
COMM0610
COMM0620
COMM0630
COMM0640
COMM0650
COMM0660
COMM0670
COMM0680

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C -----
C *      5              COMMON / BOILRS /      *
C -----
C
C COMMON /BOILRS/ CONTAINS THE PARAMETERS FOR EACH OF THE 5 TYPES
C OF BOILER UNITS USED IN SUBROUTINE BOILER
C
C BLOCK DATA
C COMMON / BOILRS / HUNT1(150)
C DIMENSION HUNT2(30)      , HUNT3(30)      , HUNT4(30)
C DIMENSION HUNT5(30)      , HUNT6(30)
C EQUIVALENCE(HUNT1(1),HUNT2(1))
C EQUIVALENCE(HUNT1(31),HUNT3(1))
C EQUIVALENCE(HUNT1(61),HUNT4(1))
C EQUIVALENCE(HUNT1(91),HUNT5(1))
C EQUIVALENCE(HUNT1(121),HUNT6(1))
C
C -----
C SUPERCRITICAL ONCE THROUGH
C
C DATA HUNT2/20.00      ,
C 1      10.      ,1.0      ,1.0      ,00.85      ,0.0      ,
C 210.00      ,0.025      ,0.10      ,8.00      ,0.28      ,1.0      ,
C 33.877115      ,1.062857      ,6.59378      ,13.25411      ,1.76      ,0.115      ,
C 40.0      ,0.0      ,9.0      ,0.9881      ,0.0214      ,20.00      ,
C 56.00      ,44.00      ,0.514      ,1.0      ,0.006      ,745.      /
C -----
C SUBCRITICAL ONCE THROUGH
C
C DATA HUNT3/20.00      ,
C 1      3.0      ,1.0      ,1.0      ,00.85      ,0.0      ,
C 210.00      ,00.025      ,00.10      ,8.00      ,00.28      ,1.00      ,
C 36.041757      ,1.076923      ,27.04244      ,10.91322      ,4.50      ,00.03      ,
C 40.0      ,0.0      ,9.00      ,0.9881      ,0.0214      ,20.00      ,
C 56.00      ,44.00      ,0.0382      , 3.926      ,0.004      ,191.      /
C -----
C OIL FIRED DRUM
C
C DATA HUNT4/20.00      ,

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COMM0010
COMM0020
COMM0030
COMM0040
COMM0050
COMM0060
COMM0070
COMM0080
COMM0090
COMM0100
COMM0110
COMM0120
COMM0130
COMM0140
COMM0150
COMM0160
COMM0170
COMM0180
COMM0190
COMM0200
COMM0210
COMM0220
COMM0230
COMM0240
COMM0250
COMM0260
COMM0270
COMM0280
COMM0290
COMM0300
COMM0310
COMM0320
COMM0330
COMM0340
COMM0350
COMM0360
COMM0370
COMM0380
COMM0390
COMM0400

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1	4.0	,1.0	,1.0	,00.85	,0.0	,	COMM0410
210.00	,00.025	,00.10	,8.00	,00.28	,1.00	,	COMM0420
311.178	,1.060606	,25.634	,11.39730	,00.9	,00.015	,	COMM0430
40.0	,1.00	,9.00	,1.00	,00.5	,25.00	,	COMM0440
56.00	,40.0	,0.0	,0.0	,0.0	,225.	/	COMM0450
-----							COMM0460
COAL FIRED DRUM							COMM0470
							COMM0480
DATA HUNT5/20.00,							COMM0490
1	4.0	,1.0	,1.0	,.85	,0.0	,	COMM0500
210.0	,.025	,.10	,8.0	,.28	,1.0	,	COMM0510
311.178	,1.060606	,25.634	,11.39730	,.9	,.015	,	COMM0520
40.0	,1.	,30.	,1.0	,.5	,25.0	,	COMM0530
525.0	,40.	,0.0	,0.0	,0.0	,225.	/	COMM0540
-----							COMM0550
NON-REHEAT DRUM							COMM0560
							COMM0570
DATA HUNT6/20.00,							COMM0580
1	1.0	,1.0	,1.0	,00.85	,0.0	,	COMM0590
210.0	,.0222	,.0222	,1.0	,1.0	,1.0	,	COMM0600
34.15835	,1.064189	,16.20734	,5.37715	,2.0	,.04	,	COMM0610
40.0	,1.0	,3.0	,1.0	,5.0	,25.	,	COMM0620
52.0	,7.	,0.	,0.	,0.	,80.	/	COMM0630
							COMM0640
							COMM0650
.....							COMM0660
. NOMENCLATURE .							COMM0670
.....							COMM0680
							COMM0690
HUNT1(1)=CYS02	SPEED DROOP (1/REGULATION)						COMM0700
HUNT1(2)=CYS03	DEADBAND						COMM0710
HUNT1(3)=CYS04	K1, INDICATES FIRST STAGE PRESSURE FEEDBACK						COMM0720
HUNT1(4)=CYS05	PRESSURE SET POINT -- P.U.						COMM0730
HUNT1(5)=CYS06	INITIAL PRESSURE LIMITER SET POINT-- P.U.						COMM0740
HUNT1(6)=	DUMMY						COMM0750
HUNT1(7)=CYS07	INITIAL PRESSURE LIMITER GAIN						COMM0760
HUNT1(8)=CYS09	VALVE OPENING TRAVEL TIME -- SEC						COMM0770
HUNT1(9)=CYS10	VALVE CLOSING TRAVEL TIME -- SEC						COMM0780
HUNT1(10)=CYS02	REHEATER TIME CONSTANT -- SEC						COMM0790

C	HUNT1(11)=CYS11	F, POWER DEVELOPED BEFORE REHEATER	COMM0800
C	HUNT1(12)=PT	THROTTLE PRESSURE	COMM0810
C	HUNT1(13)=C(2)	CAPACITY OF SECONDARY SUPERHEATER	COMM0820
C	HUNT1(14)=PD	DRUM OR PRIMARY SUPERHEATER PRESSURE	COMM0830
C	HUNT1(15)=C(1)	CAPACITY OF DRUM+PSH OR TRANSITION ZONE+PSH	COMM0840
C	HUNT1(16)=K'	BOILER PRESSURE/FLOW CONSTANT	COMM0850
C	HUNT1(17)=KP	BOILER PRESSURE CONTROL PROPORTIONAL GAIN	COMM0860
C	HUNT1(18)=KI	BOILER PRESSURE CONTROL INTEGRAL GAIN	COMM0870
C	HUNT1(19)=	DUMMY	COMM0880
C	HUNT1(20)=K	FUEL SYSTEM GAIN	COMM0890
C	HUNT1(21)=TF	FUEL SYSTEM TIME CONSTANT -- SEC	COMM0900
C	HUNT1(22)=K1	FEEDWATER SYSTEM PROPORTIONAL GAIN	COMM0910
C	HUNT1(23)=K2	FEEDWATER SYSTEM INTEGRAL GAIN	COMM0920
C	HUNT1(24)=M	FEEDWATER SYSTEM TIME CONSTANT -- SEC	COMM0930
C	HUNT1(25)=CYF03	FUEL SYSTEM FIRING DELAY -- SEC	COMM0940
C	HUNT1(26)=KD	BOILER PRESSURE CONTROL DERIVATIVE GAIN	COMM0950
C	HUNT1(27)=MWBYX	COORDINATED CONTRL SYSTEM MEGAWATT BIAS	COMM0960
C	HUNT1(28)=PEBYXX	COORDINATED CONTRL SYSTEM PRESS. ERROR BIAS	COMM0970
C	HUNT1(29)=PEB0B	COORDINATED CONTRL PRESSURE ERROR DEADBAND	COMM0980
C	HUNT1(30)=CYS01	BASE MW VALUE OF UNIT SIMULATED -- MW	COMM0990
C			COMM1000
C			COMM1010
C	HUNT1 IS DIMENSIONED FOR 5 TYPES OF BOILER UNITS AT 30		COMM1020
C	VARIABLES PER UNIT. NOT TO BE CHANGED.		COMM1030
C			COMM1040
C			COMM1050
C			COMM1060

END

C	-----	COMM0010
C	* 6 COMMON / WATT / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /WATT/ CONTAINS THE PARAMETERS USED FOR THE HYDRO UNITS	COMM0050
C	IN SUBROUTINE HYDRO	COMM0060
C		COMM0070
	BLUCK DATA	COMM0080
	COMMON / WATT / WATER1(36)	COMM0090
	DATA WATER1/0.05, 0.125, 1.0, 8.0, 43.33, 2.0,	COMM0100
1	0.05, 0.125, 1.0, 8.0, 43.33, 2.0,	COMM0110
2	0.05, 0.125, 1.0, 8.0, 43.33, 2.0,	COMM0120
3	0.05, 0.125, 1.0, 8.0, 43.33, 2.0,	COMM0130
4	0.05, 0.125, 1.0, 8.0, 43.33, 2.0,	COMM0140
5	0.05, 0.125, 1.0, 8.0, 43.33, 2.0/	COMM0150
C		COMM0160
C		COMM0170
C		COMM0180
C	. NOMENCLATURE .	COMM0190
C		COMM0200
C		COMM0210
C	WATER1(1)= REGULATION I.E. 5%	COMM0220
C	WATER1(2)= REGULATION/TRANSIENT REGULATION	COMM0230
C	WATER1(3)= DEADBAND -- MW	COMM0240
C	WATER1(4)=TK TRANSIENT DROP TIME CONSTANT	COMM0250
C	WATER1(5)= RATE OF GATE LIMIT -- MW/SEC	COMM0260
C	WATER1(6)= WATER STARTING TIME -- SEC	COMM0270
C		COMM0280
C		COMM0290
C	WATER1 IS DIMENSIONED FOR 6 UNITS AT 6 VARIABLES PER UNIT.	COMM0300
C		COMM0310
C		COMM0320
C	END	COMM0330

C	-----	COMM0010
C	* 7 COMMON / GAS / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /GAS/ CONTAINS THE PARAMETERS USED FOR THE GAS TURBINES	COMM0050
C	IN SUBROUTINE GASTUB	COMM0060
C		COMM0070
	BLOCK DATA	COMM0080
	COMMON / GAS / GASS1(60)	COMM0090
	DATA GASS1/1.0, 0.05, 54.,	COMM0100
1	1.0, 0.05, 54.,	COMM0110
2	1.0, 0.05, 54.,	COMM0120
3	1.0, 0.05, 54.,	COMM0130
4	1.0, 0.05, 54.,	COMM0140
5	1.0, 0.05, 54.,	COMM0150
6	1.0, 0.05, 54.,	COMM0160
7	1.0, 0.05, 54.,	COMM0170
8	1.0, 0.05, 54.,	COMM0180
9	1.0, 0.05, 54.,	COMM0190
A	1.0, 0.05, 54.,	COMM0200
B	1.0, 0.05, 54.,	COMM0210
C	1.0, 0.05, 54.,	COMM0220
D	1.0, 0.05, 54.,	COMM0230
E	1.0, 0.05, 54.,	COMM0240
F	1.0, 0.05, 54.,	COMM0250
G	1.0, 0.05, 54.,	COMM0260
H	1.0, 0.05, 54.,	COMM0270
I	1.0, 0.05, 54.,	COMM0280
J	1.0, 0.05, 54./	COMM0290
C		COMM0300
C		COMM0310
C	. NOMENCLATURE .	COMM0320
C		COMM0330
C		COMM0340
C		COMM0350
C	GASS1(1)= DEADBAND -- MW	COMM0360
C	GASS1(2)= REGULATION E.G. 14.2% -- %	COMM0370
C	GASS1(3)= AMBIENT TEMPERATURE DEGREES C E.G. 29.5 FOR	COMM0380
C	WINTER	COMM0390
C	GASS1 IS DIMENSIONED FOR 20 UNITS AT 3 VARIABLES PER UNIT.	COMM0420
C		COMM0430
C		COMM0440
C		COMM0450
	END	

C	-----	COMM0010
C	* 8 COMMON / ATOM / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /ATOM/ CONTAINS THE PARAMETERS USED FOR THE NUCLEAR	COMM0050
C	UNITS IN SUBROUTINE NUCLER	COMM0060
C		COMM0070
	BLOCK DATA	COMM0080
	COMMON / ATOM / ATOM1(110)	COMM0090
	DATA ATOM1/0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0100
1	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0110
2	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0120
3	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0130
4	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0140
5	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0150
6	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0160
7	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0170
8	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50,	COMM0180
9	0.0,7.0,0.15,1.0,0.1,0.6,2.0,5.0,0.3,4.5,.50/	COMM0190
		COMM0200
C		COMM0210
C		COMM0220
C	. NOMENCLATURE .	COMM0230
C		COMM0240
C		COMM0250
C	ATOM1(1)=CYB02 PROPORTIONAL PART OF RECIRCULATION CONTROL	COMM0260
C	ATOM1(2)=CYB03 IN-CORE THERMAL TIME CONSTANT -- SEC	COMM0270
C	ATOM1(3)=CYB04 INTEGRAL PART OF RECIRCULATION CONTROL	COMM0280
C	ATOM1(4)=CYB05 POWER CORRESPONDING TO FULL RECIRCULATION	COMM0290
C	FLOW IN STEADY STATE -- MW	COMM0300
C	ATOM1(5)=CYB06 PRESSURE REGULATOR LIMIT	COMM0310
C	ATOM1(6)=CYB07 PRESSURE REGULATOR GAIN	COMM0320
C	ATOM1(7)=CYB08 PRESSURE REGULATOR TIME CONSTANT T1	COMM0330
C	-- SEC	COMM0340
C	ATOM1(8)=CYB09 PRESSURE REGULATOR TIME CONSTANT T2	COMM0350
C	-- SEC	COMM0360
C	ATOM1(9)=CYB10 TURBINE POWER BEFORE CROSSOVER AND MOISTURE	COMM0370
C	SEPARATOR -- MW	COMM0380
C	ATOM1(10)=CYB11 TIME CONSTANT OF STEAM FLOW IN MOISTURE	COMM0390
C	SEPARATOR AND CROSSOVER -- SEC	COMM0400

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C

ATOM1(11)=CYB12 REGULATION

-- %

ATOM1 IS DIMENSIONED FOR 10 UNITS AT 11 VARIABLES PER UNIT.

END

COMM0410
COMM0420
COMM0430
COMM0440
COMM0450
COMM0460
COMM0470

C	-----	COMM0010
C	* 9 COMMON / PRTCNL / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /PRTCNL/ CONTAINS PARAMETERS USED TO CONTROL VARIOUS	COMM0050
C	OUTPUT ROUTINES	COMM0060
C		COMM0070
C	COMMON /PRTCNL/ IS UTILIZED IN MAIN PROGRAM AND THE	COMM0080
C	SUBROUTINES PRINT, OUTPUT, AND PAGEHD	COMM0090
C		COMM0100
C	COMMON /PRTCNL/ IS PRESENTLY NOT USED IN SUBROUTINES	COMM0110
C	BOILER, HYDRO, GASTUB, AND NUCLER, BUT IS PLACED IN THESE	COMM0120
C	ROUTINES TO PERMIT THE USER TO PRINT ANY VARIABLE USED	COMM0130
C	WITHIN THESE ROUTINES	COMM0140
C		COMM0150
C	BLOCK DATA	COMM0160
C	REAL*4 VALUE(44)	COMM0170
C	REAL*8 SYMBOL(44)	COMM0180
C	COMMON / PRTCNL / ICOUNT, TLAST, SYMBOL, VALUE, LINES, IPAGES,	COMM0190
C	1 CURPRT, PRNTIM	COMM0200
C		COMM0210
C	DATA ICOUNT,TLAST,SYMBOL,VALUE,LINES,IPAGES/0,0.0,44*0.,44*0.,	COMM0220
C	1 0,1/	COMM0230
C	DATA CURPRT,PRNTIM/0.0,10.0 /	COMM0240
C		COMM0250
C		COMM0260
C		COMM0270
C	. NOMENCLATURE .	COMM0280
C		COMM0290
C		COMM0300
C	ICOUNT INDEX USED TO LOCATE PRINT VARIABLES IN THE	COMM0310
C	ARRAYS SYMBOL AND VALUE	COMM0320
C	TLAST STORES TIME OF LAST PRINT	COMM0330
C	SYMBOL ARRAY TO STORE PRINT VARIABLE NAMES	COMM0340
C	VALUE ARRAY TO STORE PRINT VARIABLE VALUES	COMM0350
C	LINES LINE COUNTER	COMM0360
C	IPAGES PAGE COUNTER	COMM0370
C	CURPRT CURRENT PRINT TIME	COMM0380
C	PRNTIM PRINT INTERVAL	COMM0390
C		COMM0410
C	END	COMM0420

C	-----	COMM0010
C	* 10 COMMON / PLOTT / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /PLOTT/ CONTAINS THE PRINT SYMBOLS AS WELL AS THE DATA	COMM0050
C	USED TO INITIALIZE PLOT SCALES AND LIMITS USED IN	COMM0060
C	SUBROUTINES PLOT AND DOODLE	COMM0070
C		COMM0080
C	THE MAXIMUM NUMBER OF VARIABLES THAT CAN BE PLOTTED IS 14	COMM0090
C		COMM0100
	BLUCK DATA	COMM0110
	COMMON / PLOTT / XOUT(15) , AMAX(15) , AMIN(15) ,	COMM0120
1	POINT(15) , INT , ITIC , NPLVAR, ACR ,	COMM0130
2	UP , BLANK , PLUS , BPP(60) ,	COMM0140
3	D(1,60) , APP(5), NWRITE, NEGATE, AFFIRM	COMM0150
C		COMM0160
	REAL*4 NEGATE	COMM0170
C		COMM0180
	DATA AMAX/0.,100.,5500.,50500.,60.05,100.,5500.,100.,7#0./	COMM0190
	DATA AMIN/0.,-100.,4500.,49500.,59.95,-200.,5200.,-100.,7#0./	COMM0200
	DATA POINT/' ','A','M','X','F','T','L','R',7#0./	COMM0210
	DATA INT,ITIC/1,5/	COMM0220
	DATA NPLVAR/7/	COMM0230
	DATA ACR,UP,BLANK,PLUS/'-',' ',' ','+'/	COMM0240
	DATA NWRITE/0/	COMM0250
	DATA NEGATE,AFFIRM/'N','Y'/	COMM0260
C		COMM0270
C		COMM0280
C		COMM0290
C	. NOMENCLATURE .	COMM0300
C		COMM0310
C		COMM0320
C	XOUT VALUES READ FROM DISK TO BE PLOTTED	COMM0330
C	AMAX UPPER GRAPH LIMIT	COMM0340
C	AMIN LOWER GRAPH LIMIT	COMM0350
C	POINT SYMBOLS USED IN PLOTS OF SIMULATION VARIABLES	COMM0360
C	INT PLOT INTERVAL DESIRED IN SECONDS	COMM0370
C	ITIC TIME TIC MARK IN SECONDS	COMM0380
C	NPLVAR TOTAL NUMBER OF VARIABLES TO BE PLOTTED	COMM0390
C	ACR USED TO PRINT - >	COMM0400
C	UP USED TO PRINT I > USED PRIMARILY TO PRINT	COMM0410

C	BLANK	USED TO PRINT A BLANK > AXES AND REFERENCE POINTS	COMM0420
C	PLUS	USED TO PRINT + >	COMM0430
C	BPP	PRINTS LEFT MARGIN OF GRAPH	COMM0440
C	D	PLOTS LINE OF DATA	COMM0450
C	APP	PRINTS SCALE HEADINGS OF VARIABLES	COMM0460
C	NWRITE	NUMBER OF TIMES LINE OF DATA IS WRITTEN TO UNIT 11	COMM0470
C	NEGATE	READS ANSWER OF N (NO) IN RESPONSE TO PROMPT	COMM0480
C	AFFIRM	READS ANSWER OF Y (YES) IN RESPONSE TO PROMPT	COMM0490

C			COMM0500
C			COMM0510
C	SET UP THE SCALE (AMAX, AMIN) DESIRED FOR EACH VARIABLE TO BE		COMM0520
C	PLOTTED IN THE SAME ORDER AS THEY APPEAR ON THE PREPAR		COMM0530
C	CARD (I.E., THE WRITE (11) STATEMENT IN MAIN). THE FIRST		COMM0540
C	DATA SET ENTRY FOR AMAX AND AMIN IS RESERVED FOR THE		COMM0550
C	INDEPENDENT VARIABLE, IN THIS PROGRAM THIS SCALE IS		COMM0560
C	NOT USED.		COMM0570
C			COMM0580
C	SET UP THE POINT CONFIGURATION (SYMBOL TO BE USED TO PLOT		COMM0590
C	VARIABLE) DESIRED FOR EACH VARIABLE, MAINTAINING THE		COMM0600
C	SAME ORDER AS THEY APPEAR ON THE PREPAR CARD. THE FIRST		COMM0610
C	DATA ENTRY IN THE ARRAY POINT IS ALSO A DUMMY ENTRY.		COMM0620
C			COMM0630
C			COMM0640
C	END		COMM0650

C	-----	COMM0010
C	* 11 COMMON / DELAY / *	COMM0020
C	-----	COMM0030
C		COMM0040
C	COMMON /DELAY/ CONTAINS THE STORAGE VARIABLES FOR THE DELAY	COMM0050
C	FUNCTION. THE COMMON AREA IS DISPLAYED BELOW FOR	COMM0060
C	NOMENCLATURE PURPOSES ONLY. NO INITIALIZATION OCCURS.	COMM0070
C		COMM0080
C	COMMON /DELAY/ C(1000),DLAY(8,21,6)	COMM0090
C		COMM0100
C		COMM0110
C		COMM0120
C	. NOMENCLATURE .	COMM0130
C		COMM0140
C		COMM0150
C	C ARRAY TO STORE DELAY POINTS	COMM0160
C	DLAY WORK AREA FOR TEMPORARY STORAGE OF DELAY POINTS	COMM0170
C	DLAY IS DIMENSIONED AS DLAY(X,Y,Z) WHERE:	COMM0180
C	X= TOTAL NUMBER OF INDEXED SUBROUTINES	COMM0190
C	Y= MAXIMUM NUMBER OF UNITS PLUS 1	COMM0200
C	Z= GREATER THAN OR EQUAL TO THE GREATEST	COMM0210
C	NUMBER OF DELAY FUNCTIONS CALLED IN	COMM0220
C	ANY SUBROUTINE	COMM0230
C		COMM0240
C		COMM0250
C		COMM0260
C	-----	COMM0270
C	* 12 COMMON / PASSES / *	COMM0280
C	-----	COMM0290
C		COMM0300
C	COMMON /PASSES/ CONTAINS THE COUNTERS USED TO CONTROL THE	COMM0310
C	PASSES THROUGH THE BOILER SUBROUTINE. THE COMMON AREA	COMM0320
C	IS DISPLAYED BELOW FOR NOMENCLATURE PURPOSES ONLY.	COMM0330
C	NO INITIALIZATION OCCURS.	COMM0340
C		COMM0350
C	COMMON /PASSES/ KONT,AEEP	COMM0360
C		COMM0370
C		COMM0380
C		COMM0390
C	. NOMENCLATURE .	COMM0400


```

3          PMEXT , LOEXT, OUTE02, SPIEX , OUTIE3, OUTIE4, MAIN0100
4          OUTIE5, OUTIE6, DEDIEX, CEXT01, CEXT02, CEXT03, MAIN0110
5          CEXT04, CEXT05, CEXT06, CEXT07, CEXT08, CEXT09, MAIN0120
6          CEXT10, CEXT11, ACEEXT, OUTE03, OUTE04, OUTE05, MAIN0130
7          PDROP , DEEXT, PGOVEX, SPEXT , CTIMR , CBIAS , MAIN0140
8          CADD , CKCR , KLR , DUM , CLSUP , KLP , MAIN0150
9          CSKEDF, INADV , LAM , SKDT1 , TIMBS , FRQBS , MAIN0160
A          ACE , AR , MWNEW , LNEW , PEC(20) , MAIN0170
B          SP(20), PEB(20) , UCE(20) , UCE1 , MAIN0180
C          PMS(20) , FINTIM, KEXTRN, PFREQ , AMPLTD, MAIN0190
D          WAVEDN, WAVEFR, WAVEPH, PNOISE, NSEED , MU , MAIN0200
E          SIGMA , MAIN0210
COMMON / COST / UNIT1(20) , MAIN0220
COMMON / INITAL / PI(20), UNTYPE(20) , MWR(20) , MAIN0230
COMMON / PRTCNL / ICDJNT, TLAST , SYMBOL, VALUE , LINES , IPAGES, MAIN0240
1          CURPRT, PRNTIM , MAIN0250
COMMON / PLOTT / XOUT(15) , AMAX(15) , AMIN(15) , MAIN0260
1          POINT(15) , INT , ITIC , NPLVAR, ACR , MAIN0270

2          UP , BLANK , PLUS , BPP(60) , MAIN0280
3          D(1,60) , APP(5), NWRITE, NEGATE, AFFIRM , MAIN0290
COMMON / NALARM / IERR , MAIN0300
C          , MAIN0310
REAL#4 VALUE(44) , MAIN0320
REAL#8 SYMBOL(44) , MAIN0330
REAL#4 LOAD , LODTOT, LOEXT, KLR , KLP , INADV , LAM , MAIN0340
1          MWNEW , LNEW , INITAL, MWR , NEGATE, NOLOAD, NSCALE , MAIN0350
C          , MAIN0360
C          , MAIN0370
C          , MAIN0380
C          , MAIN0390
C          , MAIN0400
C          , MAIN0410
C          , MAIN0420
C          , MAIN0430
C          , MAIN0440
C          , MAIN0450
C          , MAIN0460
C          , MAIN0470
C          , MAIN0480
C          , MAIN0490

-----
INITIALIZATION
-----

WRITE(6,10)
10 FORMAT(' ENTER FINISH TIME IN SECONDS' )
READ(5,20) FINTIM
20 FORMAT(E14.7)
WRITE(6,30)
30 FORMAT(' DO YOU WISH TO ADD VARIATIONS IN LOAD? ')
READ(5,40) NOLOAD

```

```

40 FORMAT(A1)
   IF(NOLoad .EQ. NEGATE) GO TO 130
   WRITE(6,50)
50 FORMAT(' ENTER FREQUENCY FEEDBACK GAIN ')
   READ(5,20) PFREQ
   WRITE(6,60)
60 FORMAT(' ENTER SINUSOIDAL WAVE AMPLITUDE ')
   READ(5,20) AMPLTD
   IF(AMPLTD .EQ. 0.) GO TO 100
   WRITE(6,70)
70 FORMAT(' ENTER INITIATION TIME OF WAVE IN SECONDS ')
   READ(5,20) WAVEDN
   WRITE(6,80)
80 FORMAT(' ENTER WAVE FREQUENCY IN RADIAN PER SECOND ')
   READ(5,20) WAVEFR
   WRITE(6,90)
90 FORMAT(' ENTER PHASE SHIFT OF WAVE IN RADIAN ')
   READ(5,20) WAVEPH
100 WRITE(6,110)
110 FORMAT(' ENTER AMPLITUDE GAIN OF NOISE GENERATOR ')
   READ(5,20) PNOISE
   IF(PNOISE .EQ. 0.) GO TO 130
   WRITE(6, 120)
120 FORMAT(' ENTER AN ODD INTEGER ')
   READ(5,40) NSEED
130 CONTINUE
   WRITE(6,140)

```

```

MAIN0500
MAIN0510
MAIN0520
MAIN0530
MAIN0540
MAIN0550
MAIN0560
MAIN0570
MAIN0580
MAIN0590
MAIN0600
MAIN0610
MAIN0620
MAIN0630
MAIN0640
MAIN0650
MAIN0660
MAIN0670
MAIN0680
MAIN0690
MAIN0700
MAIN0710
MAIN0720
MAIN0730
MAIN0740
MAIN0750
MAIN0760

```

140	FORMAT(' DO YOU WISH TO MODIFY ANY OF THE SCALES FOR THE PLOT VARIMAINO770	
	TABLES?')	MAIN0780
	READ(5,40) NSCALE	MAIN0790
	IF(NSCALE .EQ. NEGATE) GO TO 150	MAIN0800
	CALL PLOTMD	MAIN0810
150	WRITE(6,270) BLANK	MAIN0820
	WRITE(6,160)	MAIN0830
160	FORMAT(' CLEAR THE SCREEN AND HIT ENTER TO START PRINT ROUTINE')	MAIN0840
	READ(5,260) DUMM3	MAIN0850
	IF(TIME .LT. DELT) GO TO 170	MAIN0860
	GO TO 190	MAIN0870
170	CONTINUE	MAIN0880
	DO 180 L=1,NUNIT	MAIN0890
	PM(L)=PI(L)	MAIN0900
	SP(L)=PI(L)	MAIN0910
180	PMS(L)=PI(L)	MAIN0920
190	CONTINUE	MAIN0930
C		MAIN0940
C		MAIN0950
C	-----	MAIN0960
C	SIMULATION	MAIN0970
C	-----	MAIN0980
200	CALL INERTA	MAIN0990
C		MAIN1000
C	-----	MAIN1010
C	* IF EXTERNAL AREA IS TO BE USED, SET KEXTRN=1 IN COMMON /CURVAL/	MAIN1020
C	*	MAIN1030
C		MAIN1040
	IF(KEXTRN .EQ. 1) CALL EXTRNL	MAIN1050
C		MAIN1060
C	-----	MAIN1070
C	* NUNIT IS THE TOTAL NUMBER OF UNITS IN THE MODEL	MAIN1080
C	*	MAIN1090
		MAIN1100
	DO 210 N=1,NUNIT	MAIN1110
	CALL LDD	MAIN1120
210	CONTINUE	MAIN1130
	IF(KEEP .NE. 1) GO TO 220	MAIN1140
C		MAIN1150
C	-----	MAIN1160
C	* WRITE(11) IS USED TO WRITE DATA ON DISK TO BE PLOTTED LATER	

C	*	IT IS REFERRED TO AS THE 'PREPAR' CARD IN COMMON /PLOTT/	MAIN1170
C	*		MAIN1180
C			MAIN1190
		WRITE(11) TIME,ACE,PMSYS,PMEXT,FREQHZ,PTINET,LOAD,AR	MAIN1200
		NWRITE=NWRITE+1	MAIN1210
220		CONTINUE	MAIN1220
		IF(KEEP .EQ. 0) GO TO 230	MAIN1230
		IF(TIME .LT. CURPRT) GO TO 230	MAIN1240
C			MAIN1250
C	*	-----	MAIN1260
C	*	THE PRINT VARIABLES ARE ENTERED AS PAIRS:	MAIN1270
C	*	VARIABLE NAME,VARIABLE VALUE	MAIN1280
C	*	PRECISELY SIX PRINT VARIABLES MUST BE CODED PER PRINT CALL.	MAIN1290
C	*	THE LAST VARIABLE TO BE PRINTED IS FOLLOWED BY A BLANK.	MAIN1300
C	*	NO VARIABLE NAME MAY EXCEED EIGHT CHARACTERS.	MAIN1310
C	*		MAIN1320
C			MAIN1330
		CALL PRINT('LOAD ', LOAD , 'PMSYS ', PMSYS ,	MAIN1340
1		'LODEXT ', LODEXT , 'PMEXT ', PMEXT ,	MAIN1350
2		'PACCEL ', PACCEL , 'FREQHZ ', FREQHZ)	MAIN1360
		CALL PRINT('PTINET ', PTINET , 'ACEEXT ', ACEEXT ,	MAIN1370
1		'SKDTI ', SKDTI , 'ACE ', ACE ,	MAIN1380
2		'AR ', AR , 'LAM ', LAM)	MAIN1390
		CALL PRINT('PM(1) ', PM(1) , 'PM(2) ', PM(2) ,	MAIN1400
1		'PM(3) ', PM(3) , 'PM(4) ', PM(4) ,	MAIN1410
2		'PM(5) ', PM(5) , 'PM(6) ', PM(6))	MAIN1420
		CALL PRINT('PM(7) ', PM(7) , 'PM(8) ', PM(8) ,	MAIN1430
1		' ', , 'B ', B ,	MAIN1440
2		'C ', C , 'D ', D)	MAIN1450
C			MAIN1460
C	*	-----	MAIN1470
C	*	CALL OUTPUT WRITES THE PRINT VARIABLES	MAIN1480
C	*		MAIN1490
C			MAIN1500
		CALL OUTPUT	MAIN1510
		CURPRT=CURPRT+PRNTIM	MAIN1520
230		CONTINUE	MAIN1530
		IF(TIME .LE. FINTIM) GO TO 290	MAIN1540
240		WRITE(6,270) BLANK	MAIN1550
		WRITE(6,250)	MAIN1560

250	FORMAT(' CLEAR SCREEN AND HIT ENTER TO START PLOT ROUTINE')	MAIN1570
	READ(5,260) DUMM3	MAIN1580
260	FORMAT(1A5)	MAIN1590
	CALL PLOT	MAIN1600
	WRITE(6,270) BLANK	MAIN1610
270	FORMAT(2A1)	MAIN1620
	WRITE(6,280)	MAIN1630
280	FORMAT(' DO YOU WISH TO MODIFY ANY OF THE SCALES FOR THE PLOT VARIMAIN1640	
	IABLES AND SEE THE PLOT AGAIN?')	MAIN1650
	READ(5,40) NSCALE	MAIN1660
	IF(NSCALE .EQ. NEGATE) GO TO 320	MAIN1670
	CALL PLOTMD	MAIN1680
	GO TO 240	MAIN1690
290	CONTINUE	MAIN1700
	IF(KEEP .EQ. 1) KEEP=-1	MAIN1710
	KEEP=KEEP+1	MAIN1720
	IF(TIME .GT. FINTIM) GO TO 320	MAIN1730
	IF(KEEP .EQ. 0)TIME=TIME+DELT	MAIN1740
	IF (IERR .EQ. 1) GO TO 300	MAIN1750
	GO TO 200	MAIN1760
300	WRITE(6,310)	MAIN1770
310	FORMAT(' SIMULATION TERMINATES DUE TO ERROR')	MAIN1780
320	WRITE(6,270) BLANK	MAIN1790
	WRITE(6,330)	MAIN1800
330	FORMAT(' END OF PROGRAM')	MAIN1810
	STOP	MAIN1820
	END	MAIN1830

```

C ----- INER0010
INERTA C * * INER0020
C * INER0030
C * INER0040
C * INER0050
C ----- INER0060
C INER0070
C SUBROUTINE INERTA INER0080
C INER0090
COMMON / CURVAL / TIME , DELT , KEEP , NUNIT , GTIME, N , INER0100
1 FREQH2, PM(20), OMEGA , TM , PMSYS , PMTOT , INER0110
2 PELS , PACCEL, LOAD , LODTOT, H , PTINET, INER0120
3 PMEXT , LOEXT, OUTE02, SPIEX , OUTIE3, OUTIE4, INER0130
4 OUTIE5, OUTIE6, DEDIEX, CEXT01, CEXT02, CEXT03, INER0140
5 CEXT04, CEXT05, CEXT06, CEXT07, CEXT08, CEXT09, INER0150
6 CEXT10, CEXT11, ACEEXT, OUTE03, OUTE04, OUTE05, INER0160
7 PDROP , DEEXT, PGVEX, SPEXT , CTMR , CBIAS , INER0170
8 CADD , CKCR , KLR , DUM , CLSUP , KLP , INER0180
9 CSKEDF, INADV , LAM , SKDTI , TIMBS , FRQBS , INER0190
A ACE , AR , MWNEW , LNEW , PEC(20) , INER0200
B SP(20), PEB(20) , UCE(20) , UCE1 , INER0210
C PMS(20) , FINTIM, KEXTRN INER0220
C INER0230
REAL*4 INITIAL, INADV , INTGRL, KLP , KLR , LAM , LNEW , INER0240
1 LOAD , LOEXT, LODTOT, MWNEW INER0250
C INER0260
ISUB=1 INER0270
C INER0280
C * ----- INER0290
C * ISUB IS A SUBROUTINE INDEX NUMBER. EVERY SUBROUTINE THAT INER0300
C * USES EITHER A DELAY OR AN INTGRL FUNCTION MUST HAVE A INER0310
C * UNIQUE SUBROUTINE INDEX NUMBER. THIS NUMBER IS USED INER0320
C * FOR INDEXING THE DELAY AND INTGRL FUNCTIONS. SEE COMMENTS INER0330
C * IN EITHER THE DELAY OR INTGRL FUNCTION SUBROUTINES FOR INER0340
C * FURTHER DETAILS. INER0350
C * INER0360
C * INER0370
C * INER0380
C * INER0390
C * INER0400
C * INER0410

HTOT=0.
IF(KEXTRN .EQ. 1) HTOT=340000.

```

```

PMSYS=0.
HTOT=HTOT+H
DO 10 L=1,NUNIT
10 PMSYS=PMSYS+PM(L)
CALL LOADER
PACCEL=PMSYS-LOAD+PMEXT-LODEXT
IF (TIME .LT. DELT) OMEGAD=OMEGA
OMEGA=INTGRL(ISUB,0,1,OMEGAD,PACCEL/(OMEGA*2.*HTOT),OMEGA)

```

```

INER0420
INER0430
INER0440
INER0450
INER0460
INER0470
INER0480
INER0490

```

```

C
C *-----
C * THE CALLING FORMAT FOR THE INTGRL FUNCTION SUBROUTINE IS:
C *   INTGRL(ISUB,KUNIT,KINGRL,INITIAL CONDITION,INPUT,OUTPUT)
C * SEE COMMENTS IN THE INTGRL FUNCTION SUBROUTINE FOR FURTHER
C *   DETAILS.
C *
C
C
FREQHZ=60.*OMEGA
PELSY=PMSYS-PACCEL*H/HTOT
PTINET=PELSY-LOAD
RETURN
END

```

```

INER0500
INER0510
INER0520
INER0530
INER0540
INER0550
INER0560
INER0570
INER0580
INER0590
INER0600
INER0610
INER0620

```

```

LOADER C ----- LOAD0010
C * * LOAD0020
C * * LOAD0030
C * * LOAD0040
C * * LOAD0050
C * * LOAD0060
C * * LOAD0070
C ----- LOAD0080
C LOAD0090
C SUBROUTINE LOADER LOAD0100
C LOAD0110
COMMON / CURVAL / TIME , DELT , KEEP , NUNIT , GOTIME, N , LOAD0120
1 FREQHZ, PM(20), OMEGA , TM , PMSYS , PMTOT , LOAD0130
2 PELS , PACCEL, LOAD , LODTOT, H , PTINET, LOAD0140
3 PMEXT , LOEXT, OUTE02, SPIEX , OUTIE3, OUTIE4, LOAD0150
4 OUTIE5, OUTIE6, DEDIEX, CEXT01, CEXT02, CEXT03, LOAD0160
5 CEXT04, CEXT05, CEXT06, CEXT07, CEXT08, CEXT09, LOAD0170
6 CEXT10, CEXT11, ACEEXT, OUTE03, OUTE04, OUTE05, LOAD0180
7 PDROP , DEEXT, PGOVEX, SPEXT , CTIMR , CBIAS , LOAD0190
8 CADD , CKCR , KLR , DUM , CLSUP , KLP , LOAD0200
9 CSKEDF, INADV , LAM , SKDTI , TIMBS , FRQBS , LOAD0210
A ACE , AR , MWNEW , LNEW , PEC(20) , LOAD0220
B SP(20), PEB(20) , UCE(20) , UCE1 , LOAD0230
C PMS(20) , FINTIM, KEXTRN, PFREQ , AMPLTD, LOAD0240
D WAVEDN, WAVEFR, WAVEPH, PNOISE, NSEED , MU , LOAD0250
E SIGMA LOAD0260
C LOAD0270
REAL*4 MIN , LOAD , MU , NOISE LOAD0280
C LOAD0290
DATA JUMP1/0/ LOAD0300
C LOAD0310
ISUB=2 LOAD0320
C LOAD0330
C LOAD0340
C LOAD0350
IF(KEEP .EQ. 0 .AND. TIME .GE. TM) GO TO 10 LOAD0360
GO TO 40 LOAD0370
10 CONTINUE LOAD0380
BLOAD=ALOAD LOAD0390
20 READ(10) HR,MIN,SEC,ALOAD LOAD0400
TM=HR*3600.+MIN*60.+SEC-GOTIME LOAD0410

```

IF(JUMP1.NE.0) GO TO 30	LOAD0420
BLOAD=ALOAD	LOAD0430
JUMP1=1	LOAD0440
30 CONTINUE	LOAD0450
IF(TM.LE.0.) GO TO 20	LOAD0460
40 IF(KEEP.NE.0) GO TO 50	LOAD0470
LOAD=BLOAD	LOAD0480
C	LOAD0490

C * SKIP THE VARIATIONS IN LOAD IF NO FREQUENCY FEEDBACK, NOISE,	LOAD0500
C * OR SINUSOIDAL WAVES ARE USED.	LOAD0510
C *	LOAD0520
C *	LOAD0530
C	LOAD0540
IF(PFREQ.EQ.0. .AND. AMPLTD.EQ.0. .AND. PNOISE.EQ.0.) GO TO 50	LOAD0550
C	LOAD0560
C *****	LOAD0570
C *	LOAD0580
C * VARIATIONS IN LOAD SHOULD BE ADDED TO THE FOLLOWING LINE *	LOAD0590
C * BY ADJUSTING LOADER MODEL PARAMETERS IN COMMON /CURVAL/ *	LOAD0600
C *	LOAD0610
C *****	LOAD0620
C	LOAD0630
LOAD=BLOAD*(1.+PFREQ*(FREQHZ-CSKEDF))+AMPLTD*SINE(WAVEON,WAVEFR,	LOAD0640
1 WAVEPH)+PNOISE*NOISE(NSEED,MU,SIGMA)	LOAD0650
50 RETURN	LOAD0660
END	LOAD0670

```

EXTRNL C ----- EXTR0010
C * * EXTR0020
C * EXTRNL- AN EXTERNAL AREA MODEL * EXTR0030
C * ONE LUMPED (50000 MW) AGC CONTROLLED * EXTR0040
C * BOILER-TURBINE-GENERATOR * EXTR0050
C * * EXTR0060
C ----- EXTR0070
C EXTR0080
C SUBROUTINE EXTRNL EXTR0090
C EXTR0100
C COMMON / CURVAL / TIME , DELT , KEEP , NUNIT , GOTIME, N , EXTR0110
1 FREQHZ, PM(20), OMEGA , TM , PMSYS , PMTOT , EXTR0120
2 PELS , PACCEL, LOAD , LODTOT, H , PTINET, EXTR0130
3 PMEXT , LOEXT, OUTE02, SPIEX , OUTIE3, OUTIE4, EXTR0140
4 OUTIE5, OUTIE6, DEDIEX, CEXT01, CEXT02, CEXT03, EXTR0150
5 CEXT04, CEXT05, CEXT06, CEXT07, CEXT08, CEXT09, EXTR0160
6 CEXT10, CEXT11, ACEEXT, OUTE03, OUTE04, OUTE05, EXTR0170
7 PDROP , DEEXT, PGOVEX, SPEXT , CTIMR , CBIAS , EXTR0180
8 CADD , CKCR , KLR , DUM , CLSUP , KLP , EXTR0190
9 CSKEDF, INADV , LAM , SKDT1 , TIMBS , FRQBS , EXTR0200
A ACE , AR , MWNEW , LNEW , PEC(20) , EXTR0210
B SP(20), PEB(20) , UCE(20) , UCE1 , EXTR0220
C PMS(20) , FINTIM, KEXTRN EXTR0230
C EXTR0240
C REAL*4 INADV , INTGRL, KLP , KLR , LAM , LNEW , LOAD , EXTR0250
1 LOEXT, LODTOT, MWNEW EXTR0260
C EXTR0270
C ISUB=3 EXTR0280
C EXTR0290
C EXTR0300
C EXTR0310
C PTIE=-1.*PTINET EXTR0320
C EXTR0330
C * ----- EXTR0340
C * PTIE IS THE EXTERNAL TIE FLOW EXTR0350
C * SIGN CONVENTION: -- INTO EXTERNAL SYSTEM IS - EXTR0360
C * -- OUT OF EXTERNAL SYSTEM IS + EXTR0370
C * EXTR0380
C EXTR0390
C SKEDTX=AFGEN(TIME,NUNIT*1) EXTR0400

```

ACEEXT=PTIE-SKEDTA-CEXT01*10.*(FREQHZ-CSKEDF)	EXTR0410
IF(KEEP .EQ. 0 .AND. TIME .EQ. 0.) OUTE02=ACEEXT	EXTR0420
OUTE02=ACEEXT*(DELT/(DELT+3.))+ (3./(DELT+3.))*	EXTR0430
1 DELAY (ISUB,0,1,1,DELT,OUTE02)	EXTR0440
C	EXTR0450
C *-----	EXTR0460
C * THE CALLING FORMAT FOR THE DELAY FUNCTION SUBROUTINE IS:	EXTR0470
C * DELAY (ISUB,KUNIT,IDLAY,# SAMPLED POINTS,DELAY TIME,INPUT)	EXTR0480
C * SEE COMMENTS IN THE DELAY FUNCTION SUBROUTINE FOR FURTHER	EXTR0490
C * DETAILS.	EXTR0500
C *	EXTR0510
C	EXTR0520
SPEXT=INTGRL (ISUB,0,1,SPIEX,CEXT02*OUTE02,SPEXT)	EXTR0530
PGOVEX=SPEXT-(CEXT11/60.)*(FREQHZ-CSKEDF)	EXTR0540
IF(KEEP .EQ. 0) GO TO 60	EXTR0550
A=PGOVEX-DEDIEX	EXTR0560
IF (TIME .GE. DELT) GO TO 10	EXTR0570
T1=CEXT03	EXTR0580
T2=CEXT03	EXTR0590
CDBEXT=T1+T2	EXTR0600
10 IF(A-T1) 20, 50, 40	EXTR0610
20 IF(A-T2) 30, 50, 50	EXTR0620
30 T2=A	EXTR0630
T3=A+CDBEXT/2.	EXTR0640
T1=A+CDBEXT	EXTR0650
GO TO 50	EXTR0660
40 T1=A	EXTR0670
T2=A-CDBEXT	EXTR0680
T3=A-CDBEXT/2.	EXTR0690
50 A=T3	EXTR0700
DEDEXT=A+DEDIEX	EXTR0710
60 CONTINUE	EXTR0720
PDRUP=- (CEXT04*DEDEXT+OUTE03)	EXTR0730
OUTE04=INTGRL (ISUB,0,2,OUTIE4,CEXT08*PDRUP,OUTE04)	EXTR0740
OUTE05=INTGRL (ISUB,0,3,OUTIE5,((CEXT07*PDRUP+OUTE04)-OUTE05)/	EXTR0750
1 CEXT06,OUTE05)	EXTR0760
OUTE03=INTGRL (ISUB,0,4,OUTIE3,((1.-CEXT04)*(DEDEXT+OUTE05)	EXTR0770
1 -OUTE03)/CEXT05,OUTE03)	EXTR0780
OUTE07=DEDEXT+PDRUP	EXTR0790

```
PMEXT1=INTGRL(1SUB,0,5,OUT IE6,(1./CEXT10)*QUTE07-PMEXT),PMEXT1) EXTR0800
PMEXT=CEXT09*QUTE07+PMEXT1 EXTR0810
RETURN EXTR0820
END EXTR0830
```

LDD

```

C ----- LDD000010
C * * LDD000020
C * LDD- LOAD DISPATCH OFFICE MODELS * LDD000030
C * * LDD000040
C ----- LDD000050
C LDD000060
C SUBROUTINE LDD LDD000070
C LDD000080
COMMON / CURVAL / TIME , DELT , KEEP , NUNIT , GOTIME, N , LDD000090
1 FREQHZ, PM(20), OMEGA , TM , PMSYS , PMTOT , LDD000100
2 PELS , PACCEL, LOAD , LDDTOT, H , PTINET, LDD000110
3 PMEXT , LODEXT, DUTE02, SPIEX , OUTIE3, OUTIE4, LDD000120
4 OUTIE5, OUTIE6, DEDIEX, CEXT01, CEXT02, CEXT03, LDD000130
5 CEXT04, CEXT05, CEXT06, CEXT07, CEXT08, CEXT09, LDD000140
6 CEXT10, CEXT11, ACEEXT, DUTE03, DUTE04, DUTE05, LDD000150
7 PDROP , DEDEXT, PGDEVX, SPEXT , CTIMR , CBIAS , LDD000160
8 CADD , CKCR , KLR , DUM , CLSUP , KLP , LDD000170
9 CSKEDF, INADV , LAM , SKDTI , TIMBS , FRQBS , LDD000180
A ACE , AR , MWNEW , LNEW , PEC(20) , LDD000190
B SP(20), PEB(20) , UCE(20) , UCE1 , LDD000200
C PMS(20) , FINIM, KEXTRN LDD000210
COMMON / INITAL / PI(20), UNTYPE(20) , MWR(20) LDD000220
COMMON / CONST1 / CLDD(4) , CO1(20) , CO2(20) , LDD000230
1 CO3(20) , CO4(20) , CO5(20) LDD000240
C LDD000250
DIMENSION C2MOD(20) , C2MOD0(20) , SPR1(20) , LDD000260
1 SPR2(20) , NUMBER(20) LDD000270
C LDD000280
REAL*4 INADV , INITAL, INTGRL, KLP , KLR , LAM , LCHNG1, LDD000290
1 LIMIT , LL101 , LL102 , LNEW , LOAD , LODEXT, LDDTOT, LDD000300
2 LOLD1 , LRSET1, LRSET , MW , MWNEW , MWOLD1, MWR , LDD000310
3 MW1 LDD000320
C LDD000330
DATA JUMP/0/ LDD000340
C LDD000350
ISUB=4 LDD000360
C LDD000370
C LDD000380
C LDD000390
C ----- LDD000400

```

C	INITIALIZATION	L0000410
C	-----	L0000420
C		L0000430
	IF(JUMP .EQ. 1) GO TO 20	L0000440
	N1=0	L0000450
	N2=0	L0000460
	N3=0	L0000470
	N4=0	L0000480
	DO 10 M=1,NUNIT	L0000490
	PEB(M)=0.	L0000500
	C2MOD(M)=0.	L0000510
	C2MOD0(M)=0.	L0000520
	IF(UNTYPE(M) .EQ. 1.) N1=N1+1	L0000530
	IF(UNTYPE(M) .EQ. 1.) NUMBER(M)=N1	L0000540
	IF(UNTYPE(M) .EQ. 2.) N2=N2+1	L0000550
	IF(UNTYPE(M) .EQ. 2.) NUMBER(M)=N2	L0000560
	IF(UNTYPE(M) .EQ. 3.) N2=N2+1	L0000570
	IF(UNTYPE(M) .EQ. 3.) NUMBER(M)=N2	L0000580
	IF(UNTYPE(M) .EQ. 4.) N2=N2+1	L0000590
	IF(UNTYPE(M) .EQ. 4.) NUMBER(M)=N2	L0000600
	IF(UNTYPE(M) .EQ. 5.) N3=N3+1	L0000610
	IF(UNTYPE(M) .EQ. 5.) NUMBER(M)=N3	L0000620
	IF(UNTYPE(M) .EQ. 6.) N4=N4+1	L0000630
	IF(UNTYPE(M) .EQ. 6.) NUMBER(M)=N4	L0000640
	IF(UNTYPE(M) .EQ. 7.) N2=N2+1	L0000650
	IF(UNTYPE(M) .EQ. 7.) NUMBER(M)=N2	L0000660
	IF(UNTYPE(M) .EQ. 8.) N2=N2+1	L0000670
	IF(UNTYPE(M) .EQ. 8.) NUMBER(M)=N2	L0000680
	10 JUMP=1	L0000690
	20 CONTINUE	L0000700
C		L0000710
C	*-----	L0000720
C	* UNTYPE(M) IS THE ACRONYM FOR THE UNIT TYPE OF UNIT M	L0000730
C	* NUMBER(M) IS THE SEQUENTIAL NUMBER FOR UNIT M WITHIN A GIVEN	L0000740
C	* UNIT TYPE (NUCLEAR, BOILER, HYDRD, GAS TURBINE)	L0000750
C	* N1= THE TOTAL NUMBER OF NUCLEAR UNITS	L0000760
C	* N2= THE TOTAL NUMBER OF BOILER UNITS	L0000770
C	* N3= THE TOTAL NUMBER OF HYDRO UNITS	L0000780
C	* N4= THE TOTAL NUMBER OF GAS TURBINES	L0000790
C	*	L0000800

C		L0000810
C		L0000820
C	*-----*	L0000830
C	* CALCULATION OF THE REGULATION SIGNAL (AR) AND COST SIGNAL (LAM)	L0000840
C	* IS PERFORMED ONLY DURING THE FIRST PASS FOR THE FIRST UNIT	L0000850
C	* (N EQUAL 1) FOR EACH TIME STEP	L0000860
C	*	L0000870
C		L0000880
C		L0000890
C	-----	L0000900
C	CALCULATION OF AR	L0000910
C	-----	L0000920
C		L0000930
	IF(N.NE.1) GO TO 140	L0000940
	IF(KEEP.EQ. 1) GO TO 30	L0000950
	TIOLD1=PTITM	L0000960
	IF(TIME.LE.DELT) TIOLD1=PTINET	L0000970
30	PTITM=(DELT/(DELT+CLDD(4)))*PTINET+(CLDD(4)/(DELT+CLDD(4)))*	L0000980
1	TIOLD1	
	SKDTI=AFGEN(TIME,NUNIT+2)	L0000990
	DTFLD=PTITM-SKDTI	L0001000
	TIMER=INTGRL (ISUB,0,1,0.,(FREQHZ-CSKEDF)/60.,TIMER)	L0001010
	TIMBS=0.	L0001020
C		L0001030
C	*-----*	L0001040
C	* INADV IS THE INADVERTANT INTERCHANGE OF ENERGY. IT ACTS AS A	L0001050
C	* SWITCH AND IF EXCEEDED THE ALGORITHM CALCULATES THE TIME	L0001060
C	* BIAS (TIMBS)	L0001070
C	*	L0001080
C		L0001090
	IF(TIMER.GT.0..AND.INADV.LT.0.) GO TO 40	L0001100
	IF(TIMER.LT.0..AND.INADV.GT.0.) GO TO 40	L0001110
	GO TO 50	L0001120
40	TIMBS=CTIMR*TIMER	L0001130
50	FRQBS=CBIAS*10.*(FREQHZ-CSKEDF)	L0001140
C		L0001150
C	*-----*	L0001160
C	* - ACE MEANS UNDERGENERATION	L0001170
C	* + ACE MEANS OVERGENERATION	L0001180
C	*	L0001190
C		L0001200

ACE=DTFLO-FRQBS+CADD-TIMBS	L0001210
IF(KEEP .EQ. 1) GO TO 60	L0001220
FDBAK1=AR	L0001230
60 AR=LIMIT(-75.,75.,ACE*CKCR+(1.-CKCR)*FDBAK1)	L0001240
IF(KEEP .EQ. 1) GO TO 70	L0001250
MWOLD1=MWNEW	L0001260
IF(TIME.LT.DELT) MWOLD1=PMSYS	L0001270
70 MWNEW=MWOLD1-AR	L0001280
IF(TIME.LT.DELT) LOLD1=LNEW	L0001290
IF(KEEP .EQ. 1) GO TO 80	L0001300
LOLD1=LNEW	L0001310
C	L0001320
C *-----	L0001330
C * SLOPE OF 650. MW/MIL FOR STEAM GENERATION	L0001340
C *	L0001350
C	L0001360
80 LNEW=MWNEW/650.	L0001370
C	L0001380
C	L0001390
C	L0001400
C	L0001410
C	L0001420
C	L0001430
C *-----	L0001440
C * CALCULATION OF COMPANY STARTING COST SIGNAL (LAM) BASED ON	L0001450
C *	L0001460
C *	L0001470
C	L0001480
IF(TIME .EQ. 0. .AND. KEEP .EQ. 0) GO TO 90	L0001490
GO TO 120	L0001500
90 CONTINUE	L0001510
MW=0.	L0001520
LAM=1.	L0001530
100 MW=0.	L0001540
DO 110 M=1,NUNIT	L0001550
MW1=AFGEN(LAM,M)	L0001560
110 MW=MW+MW1	L0001570
IF(MW.GE.PELSY) GO TO 120	L0001580
LAM=LAM+I.	L0001590
GO TO 100	L0001600

0074	120	CONTINUE	L0001610
0075		LCHNG1=LNEW-LGLD1	L0001620
0076		IF (TIME .LT. DELT) LCHNG1=0.	L0001630
0077		IF (KEEP .EQ. 1) GO TO 130	L0001640
0078		LRSET1=LRSET	L0001650
0079		IF (TIME .LT. DELT) LRSET1=LAM	L0001660
0080	130	LRSET=LRSET1+KLR*LCHNG1+CL SUP	L0001670
0081		LAM=LRSET+KLP*LCHNG1	L0001680
0082		LL101=DELAY (ISUB,0,1,1,DELT,LAM)	L0001690
0083		LL102=LIMIT (-CLD0 (3),CLD0 (3),LAM-LL101)	L0001700
0084		LAM=LIMIT (CLD0 (1),CLD0 (2),LL102+LL101)	L0001710
	C		L0001720
	C		L0001730
	C	-----	L0001740
	C	GOVERNOR CONTROLLER	L0001750
	C	-----	L0001760
	C		L0001770
0085	140	PEC (N)=AFGEN (LAM,N)	L0001780
0086		PMS (N)=PM (N)* (DELT / (DELT+CO3 (N))) + (CO3 (N) / (DELT+CO3 (N))) *	L0001790
	1	DELAY (ISUB,N,2,1,DELT,PMS (N))	L0001800
0087		UCE (N)=PEC (N)-CO2 (N)*AR-PMS (N)	L0001810
0088		UCE1=UCE (N)	L0001820
0089		IF (UNTYPE (N) .EQ. 2. .OR. UNTYPE (N) .EQ. 3.) UCE (N)=UCE (N)-PEB (N)	L0001830
0090		C2MOD (N)=INTGRL (ISUB,N,2,C2MOD0 (N),UCE (N),C2MOD (N))	L0001840
0091		SPR1 (N)=CO4 (N)*UCE (N)+CO5 (N)*C2MOD (N)	L0001850
0092		SPR2 (N)=LIMIT (-CO1 (N),CO1 (N),SPR1 (N))	L0001860
	C		L0001870
	C	***** UNIT GENERATION CHANGE *****	L0001880
	C	# THIS SPACE ALLOCATED FOR SPECIFYING TURBINE TRIPS OR #	L0001890
	C	# PRIME MOVERS COMING ON LINE #	L0001900
	C	*****	L0001910
	C		L0001920
0093		SP (N)=INTGRL (ISUB,N,3,PI (N),SPR2 (N),SP (N))	L0001930
0094		IF (SP (N) .LT. 0.) SP (N)=0.	L0001940
0095		IF (SP (N) .GE. MWR (N)) SP (N)=MWR (N)	L0001950
	C		L0001960
	C	*-----	L0001970
	C	* PI (N) INITIAL POWER FROM UNIT N	L0001980
	C	* SP (N) THE GOVERNOR SET POINT FOR UNIT N	L0001990
	C	* PM (N) THE MECHANICAL POWER FROM UNIT N	L0002000
	C	* PEB (N) THE PRESSURE ERROR BIAS SETTING USED WITH ONCE-THROUGH	

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C *      UNITS THAT HAVE AN INTEGRATED BOILER-TURBINE CONTROLLER L0002010
C * PMS(N)      SENSED MECHANICAL POWER(TELEMETERED) FOR UNIT N      L0002020
C * C2MOD(N)    OUTPUT OF THE DIAT (THREE MODE CONTROLLER) INTEGRATOR L0002030
C *           FOR UNITS THAT HAVE THESE CONTROLLERS                  L0002040
C * C2MODD(N)   INITIAL CONDITION OF THE DIAT INTEGRATOR FOR UNIT N   L0002050
C * SPR2(N)     GOVERNOR SET POINT RATE (INPUT TO GOVERNOR MOTOR) FOR L0002060
C *           UNIT N                                                  L0002070
C * SPLAST(N)   LAST VALUE OF THE GOVERNOR MOTOR SET POINT FOR UNIT N L0002080
C * SPR1(N)     OUTPUT OF THE CONTROLLER (E.G. A DIAT IF USED) FOR     L0002090
C *           UNIT N. IT COULD BE 1.*UCE(N) IN THE ABSENCE OF A        L0002100
C *           CONTROLLER.                                              L0002110
C * PEC(N)      POWER REQUIREMENT THAT RESULTS FROM THE ECONOMIC CURVE L0002120
C *           FOR UNIT N                                              L0002130
C * UCE(N)      UNIT CONTROL ERROR FOR UNIT N. UCE= PEC+AR-PMS        L0002140
C *                                                    L0002150
C                                                    L0002160
C                                                    L0002170
C          -----
C          GO TO PRIME MOVER MODEL
C          -----
C                                                    L0002180
C                                                    L0002190
C                                                    L0002200
C          ITYPE=UNTYPE(N)                                           L0002210
C          GO TO ( 150, 160, 160, 150, 170, 180, 160, 160 ), ITYPE   L0002220
150 CALL NUCLER(CSKEDF,OMEGA,SP(N),PM(N),NUMBER(N),N)                 L0002230
C          GO TO 190                                                  L0002240
160 IF(KEEP .NE. 1) GO TO 190                                         L0002250
C          CALL BOILER(CSKEDF,OMEGA,SP(N),PM(N),NUMBER(N),ITYPE,      L0002260
1      UCE(N),N,PEB(N),UCE1)                                           L0002270
C          GO TO 190                                                  L0002280
170 CALL HYDRO(CSKEDF,OMEGA,SP(N),PM(N),NUMBER(N),N)                 L0002290
C          GO TO 190                                                  L0002300
180 CALL GASTUB(CSKEDF,OMEGA,SP(N),PM(N),NUMBER(N),N)                 L0002310
190 CONTINUE                                                         L0002320
C                                                                    L0002330
C *-----
C * ITYPE IS UNIT TYPE
C *
C * 1---NUCLEAR UNIT
C * 2,3,4,7,8---BOILER UNITS
C *           2---SUPERCRITICAL ONCE THROUGH UNIT
C *           3---SUBCRITICAL ONCE THROUGH UNIT
C                                                                    L0002340
C                                                                    L0002350
C                                                                    L0002360
C                                                                    L0002370
C                                                                    L0002380
C                                                                    L0002390
C                                                                    L0002400

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C * 4---DRUM TYPE UNIT, OIL FIRED
C * 7---DRUM TYPE UNIT, COAL FIRED
C * 8---DRUM TYPE UNIT, NON-REHEAT
C * 5---HYDRO UNIT
C * 6---GAS TURBINE UNIT
C
RETURN
END

L0002410
L0002420
L0002430
L0002440
L0002450
L0002460
L0002470
L0002480

BOILER	C	-----	BOIL0010
	C	*	BOIL0020
	C	* SUBROUTINE BOILER	BOIL0030
	C	*	BOIL0040
	C	-----	BOIL0050
	C		BOIL0060
		SUBROUTINE BOILER(CSKEDF,OMEGA,SPYS,PMYS,NUMBER,ITYPE,UCE,	BOIL0070
	1	N,PEB,UCE1)	BOIL0080
	C		BOIL0090
		COMMON / CURVAL / TIME , DELT , KEEP	BOIL0100
		COMMON / BOILKS / HUNT1(150)	BOIL0110
		COMMON / PASSES / KUNT , AEEP	BOIL0120
		COMMON / INITAL / DUMMY(40) , MWR(20)	BOIL0130
		COMMON / PRICNL / ICOUNT, TLAST , SYMBOL, VALUE , LINES , IPAGES	BOIL0140
	C		BOIL0150
		DIMENSION HUNT(1340)	BOIL0160
	C		BOIL0170
		REAL*4 INTGRL, LIMIT , LOODEM, MWR	BOIL0180
		REAL*4 VALUE(44)	BOIL0190
		REAL*8 SYMBOL(44)	BOIL0200
	C		BOIL0210
		ISUB=5	BOIL0220
	C		BOIL0230
	C		BOIL0240
	C		BOIL0250
	C	THE ARRAY HUNT1 IS THE DATA STORAGE AREA USED TO STORE THE	BOIL0260
	C	PARAMETERS FOR THE 5 TYPES OF BOILER UNITS. IT IS	BOIL0270
	C	DIMENSIONED FOR 5 TYPES OF UNITS AT 30 VARIABLES PER	BOIL0280
	C	UNIT. NOT TO BE CHANGED.	BOIL0290
	C		BOIL0300
	C	THE ARRAY HUNT IS THE WORKING AREA REPRESENTING THE DYNAMIC	BOIL0310
	C	EQUATIONS FOR EACH BOILER UNIT. IT IS DIMENSIONED FOR	BOIL0320
	C	20 UNITS AT 67 VARIABLES PER UNIT.	BOIL0330
	C		BOIL0340
	C	SUBROUTINE BOILER IS DESIGNED TO REPRESENT 5 TYPES OF BOILER	BOIL0350
	C	UNITS. THE TYPE OF UNIT IS TRIGGERED BY ITYPE WHICH IS	BOIL0360
	C	EQUIVALENT TO UNTYPE.	BOIL0370
	C		BOIL0380
	C	----- KEY TO ITYPE -----	BOIL0390
	C		BOIL0400

C	ITYPE= 2	SUPERCRITICAL ONCE THROUGH		BOILO410
C	3	SUBCRITICAL ONCE THROUGH		BOILO420
C	4	OIL FIRED DRUM		BOILO430
C	7	COAL FIRED DRUM		BOILO440
C	8	NONREHEAT DRUM		BOILO450
C				BOILO460
C	THIS SUBROUTINE IS ON A HALF SECOND INTEGRATION STEP FOR			BOILO470
C	NUMERICAL STABILITY. THE FUNCTION SUBROUTINE INTGR			BOILO480
C	AUTOMATICALLY USES A .5 SECOND INTEGRATION STEP SIZE			BOILO490
C	BY CHECKING THE VALUE OF ISUB TO DETERMINE WHEN INTEGRALS			BOILO500
C	FROM BOILER ARE BEING UPDATED. THE COUNTER KONT CONTROLS			BOILO510
C	THE NUMBER OF PASSES THROUGH BOILER AND THEREBY ENSURES			BOILO520
C	THAT BOILER INTEGRALS ARE PROPERLY UPDATED.			BOILO530
C				BOILO540
C				BOILO550
C	HUNT(L)=T1SY	DEADBAND UPPER VALUE	-- MW	BOILO560
C	HUNT(L+1)=T2SY	DEADBAND LOWER VALUE	-- MW	BOILO570
C	HUNT(L+2)=T3SY	OUTPUT OF DEADBAND	-- MW	BOILO580
C	HUNT(L+3)=CYS01	UNIT MW RATING	-- MW	BOILO590
C	HUNT(L+4)=CYS02	SPEED DROOP	-- MW/HZ	BOILO600
C	HUNT(L+5)=CYS03	DEADBAND WIDTH	-- MW	BOILO610
C	HUNT(L+6)=	OUTPUT OF DEADBAND	-- MW	BOILO620
C	HUNT(L+7)=CYS04	K, FIRST STAGE PRESSURE FEEDBACK		BOILO630
C	HUNT(L+8)=XLAST			BOILO640
C	HUNT(L+9)=STMFL0	STEAM FLOW	-- P.U.	BOILO650
C	HUNT(L+10)=CYS05	PRESSURE SETPOINT (THROTTLE)	-- P.U.	BOILO660
C	HUNT(L+11)=CYS06	INITIAL PRESSURE LIMITER SETPOINT	-- P.U.	BOILO670
C	HUNT(L+12)=	BOILER CONTROLLER COMPENSATION RATIO		BOILO680
C	HUNT(L+13)=K(IPL)	CYS07, INITIAL PRESSURE LIMITER CONSTANT		BOILO690
C	HUNT(L+14)=CYS08	LOAD LIMIT	-- MW	BOILO700
C	HUNT(L+15)=CVDEM	CONTROL VALVE DEMAND		BOILO710
C	HUNT(L+16)=	LEG CONTAINING K(IPL), INPUT TO LOW VALVE GATE		BOILO720
C	HUNT(L+17)=	INPUT AND OUTPUT TO RATE LIMIT		BOILO730
C	HUNT(L+18)=CVAREA	CONTROL VALVE AREA		BOILO740
C	HUNT(L+19)=CYS09	YALLOW, VALVE OPENING TRAVEL TIME INVERSE		BOILO750
C	HUNT(L+20)=CYS10	BALLOW, VALVE CLOSING TRAVEL TIME INVERSE		BOILO760
C	HUNT(L+21)=T(RH)	CYS12		BOILO770
C	HUNT(L+22)=F	CYS11, PERCENT POWER FROM NON-REHEAT TURBINE		BOILO780
C	HUNT(L+23)=TMYS	TURBINE OUTPUT	-- P.U.	BOILO790
C	HUNT(L+24)=	OUTPUT OF REHEAT TURBINE INTEGRATOR		BOILO800

C	HUNT(L+25)=	INITIAL CONDITION FOR INTEGRATOR NO. 1	BOIL0810
C	HUNT(L+26)=PMYS	MECHANICAL POWER OUTPUT	BOIL0820
C	HUNT(L+27)=W	FEEDWATER FLOW -- P.U.	BOIL0830
C	HUNT(L+28)=	OUTPUT OF SQUARE ROOT IN BOILER REPRESENTATION	BOIL0840
C	HUNT(L+29)=P(T)	THROTTLE PRESSURE -- P.U.	BOIL0850
C	HUNT(L+30)=	INITIAL CONDITION FOR INTEGRATOR NO. 2	BOIL0860
C	HUNT(L+31)=C(2)	SECONDARY SUPERHEATER STEAM CAPACITY	BOIL0870
C	HUNT(L+32)=P(D)	DRUM PRESSURE OR PRIMARY SUPERHEATER OUTLET	BOIL0880
C		PRESSURE	BOIL0890
C	HUNT(L+33)=	INITIAL CONDITION FOR INTEGRATOR NO. 3	BOIL0900
C	HUNT(L+34)=C(1)	DRUM OR WATERWALL STEAM CAPACITY	BOIL0910
C	HUNT(L+35)=K'		BOIL0920
C	HUNT(L+36)=KP	PROPORTIONAL BOILER CONTROL CONSTANT	BOIL0930
C	HUNT(L+37)=KI	RESET BOILER CONTROL CONSTANT	BOIL0940
C	HUNT(L+38)=	OUTPUT OF THE FIRST SUM BLOCK IN THE BOILER	BOIL0950
C		CONTROLS	BOIL0960
C	HUNT(L+39)=	INITIAL CONDITION FOR INTEGRATOR NO. 4	BOIL0970
C	HUNT(L+40)=T(R)	BOILER CONTROL TIME CONSTANT.	BOIL0980
C	HUNT(L+41)=	OUTPUT OF Z-FORM IN BOILER CONTROLS	BOIL0990
C	HUNT(L+42)=	Z-SEC. DELAY OF HUNT(L+41)	BOIL1000
C	HUNT(L+43)=	OUTPUT OF BOILER CONTROLS	BOIL1010
C	HUNT(L+44)=	OUTPUT OF LIMITER BEFORE FUEL AND FEEDWATER	BOIL1020
C		SYSTEMS	BOIL1030
C	HUNT(L+45)=K	FUEL SYSTEM GAIN	BOIL1040
C	HUNT(L+46)=T(F)	FUEL SYSTEM TIME CONSTANT -- SEC	BOIL1050
C	HUNT(L+47)=	OUTPUT OF D-DELAY IN FUEL SYSTEM	BOIL1060
C	HUNT(L+48)=	INITIAL CONDITION FOR INTEGRATOR NO. 5--DRUM	BOIL1070
C		TYPE UNITS	BOIL1080
C	HUNT(L+49)=	OUTPUT OF FUEL SYSTEM	BOIL1090
C	HUNT(L+50)=K(1)	GAIN IN FEEDWATER SYSTEM	BOIL1100
C	HUNT(L+51)=K(2)	GAIN IN FEEDWATER SYSTEM	BOIL1110
C	HUNT(L+52)=M	FEEDWATER SYSTEM TIME CONSTANT -- SEC	BOIL1120
C	HUNT(L+53)=	OUTPUT OF FEEDWATER INTEGRATOR(7) IN FEED	BOIL1130
C		FORWARD LOOP	BOIL1140
C	HUNT(L+54)=	INITIAL CONDITION FOR INTEGRATOR NO. 5 (ONCE	BOIL1150
C		THROUGH UNITS)	BOIL1160
C	HUNT(L+55)=	OUTPUT OF SECOND FEEDWATER INTEGRATOR(7) (ONCE	BOIL1170
C		THROUGH UNITS)	BOIL1180
C	HUNT(L+56)=	INITIAL CONDITION FOR INTEGRATOR NO. 7 (ONCE	BOIL1190
C		THROUGH UNITS)	BOIL1200
C	HUNT(L+57)=	OUTPUT OF INTEGRATOR NO. 4	BOIL1210

C	HUNT(L+58)=CLOCK	BOIL1220
C	HUNT(L+59)=D-DELAY CYF03	BOIL1230
C	HUNT(L+60)= INPUT TO BOILER CONTROLS	BOIL1240
C	HUNT(L+61)= VALUE OF HUNT(L+60) AT LAST TIME STEP	BOIL1250
C	HUNT(L+62)= OUTPUT OF DERIVATIVE CONTROL	BOIL1260
C	HUNT(L+63)= DERIVATIVE BOILER CONTROL CONSTANT	BOIL1270
C	HUNT(L+64)= MW BIAS -- MW	BOIL1280
C	HUNT(L+65)= PRESSURE FEEDBACK BIAS	BOIL1290
C	HUNT(L+66)= DEADBAND WITH IN THE PRESSURE FEEDBACK CIRCUIT	BOIL1300
C		BOIL1310
C		BOIL1320
C		BOIL1330
C		BOIL1340
C	-----	BOIL1350
C	INITIALIZATION	BOIL1360
C	-----	BOIL1370
C	*-----*	BOIL1380
C	* INITIALIZATION ROUTINE FOR EACH BOILER AT TIME LESS THAN	BOIL1390
C	* DELT, THE SYSTEM INTEGRATION STEP.	BOIL1400
C	*-----*	BOIL1410
C	* VALUES WHICH DEPEND ON THE UNIT RATING ARE CALCULATED USING MWR,	BOIL1420
C	* PMYS, AND SPYS. MWR IS THE MEGAWATT RATING OF THE UNIT.	BOIL1430
C	* PMYS AND SPYS ARE ANALOGOUS TO PM(N) AND SP(N) WHICH ARE	BOIL1440
C	* INITIALIZED IN INITAL. SCALING IS USED TO ALLOW US TO BE	BOIL1450
C	* ABLE TO USE ONE SET OF DATA TO TAKE CARE OF ALL UNITS OF THE	BOIL1460
C	* SAME TYPE. THIS IS ACCOMPLISHED BY SCALING DOWN SPYS AND	BOIL1470
C	*-----*	BOIL1480
C	* PMYS WITH RESPECT TO THE RATING OF THE UNIT REPRESENTED BY	BOIL1490
C	* THE DATA.	BOIL1500
C	*-----*	BOIL1510
C	* HUNT IS INITIALIZED BY THE DATA SET HUNT1 AND HAS 67 LOCATIONS	BOIL1520
C	* RESERVED FOR EACH BOILER.	BOIL1530
C	*-----*	BOIL1540
C		BOIL1550
C		BOIL1560
C		BOIL1570
C	KONT=1	BOIL1580
C	DELT0=.5	BOIL1590
C	AEEP=0.	BOIL1600
C	ICALC=NUMBER*67	BOIL1610
C	L=ICALC-66	

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C *-----
C * L IS USED TO INDEX TO THE APPROPRIATE LOCATION IN HUNT FOR THE
C * UNIT PRESENTLY BEING UPDATED.
C *
C
      IF(MWR(N) .LT. 1.) GO TO 130
      IF(TIME .LT. DELT) GO TO 10
      GO TO 20
10  IITYPE=ITYPE
      IF(ITYPE .EQ. 7) IITYPE=5
      IF(ITYPE .EQ. 8) IITYPE=6
      LL=(IITYPE-2)*30
C
C *-----
C * LL IS USED TO INDEX HUNT1 TO THE PROPER UNIT TYPE
C *
C
      HUNT(L+3)=HUNT1(LL+30)
      PMYS=PMYS/MWR(N)*HUNT(L+3)
      HUNT(L)=PMYS+HUNT1(LL+2)/2.
      HUNT(L+1)=PMYS-HUNT1(LL+2)/2.
      HUNT(L+2)=PMYS
      HUNT(L+4)=HUNT1(LL+1)
      HUNT(L+5)=HUNT1(LL+2)
      HUNT(L+6)=PMYS
      HUNT(L+7)=HUNT1(LL+3)
      HUNT(L+8)=HUNT(L+2)/HUNT(L+3)
      HUNT(L+9)=HUNT(L+8)
      HUNT(L+10)=HUNT1(LL+4)
      HUNT(L+11)=HUNT1(LL+5)
      HUNT(L+12)=HUNT1(LL+6)
      HUNT(L+13)=HUNT1(LL+7)
      HUNT(L+14)=HUNT(L+3)
      HUNT(L+15)=HUNT(L+8)

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BOIL1620
BOIL1630
BOIL1640
BOIL1650
BOIL1660
BOIL1670
BOIL1680
BOIL1690
BOIL1700
BOIL1710
BOIL1720
BOIL1730
BOIL1740
BOIL1750
BOIL1760
BOIL1770
BOIL1780
BOIL1790
BOIL1800
BOIL1810
BOIL1820
BOIL1830
BOIL1840
BOIL1850
BOIL1860
BOIL1870
BOIL1880
BOIL1890
BOIL1900
BOIL1910
BOIL1920
BOIL1930
BOIL1940
BOIL1950
BOIL1960

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HUNT(L+17)=HUNT(L+8)
HUNT(L+18)=HUNT(L+8)
HUNT(L+19)=HUNT1(LL+8)
HUNT(L+20)=HUNT1(LL+9)
HUNT(L+21)=HUNT1(LL+10)
HUNT(L+22)=HUNT1(LL+11)
HUNT(L+23)=HUNT(L+8)
HUNT(L+24)=HUNT(L+8)*(1.-HUNT(L+22))
HUNT(L+25)=HUNT(L+24)
HUNT(L+26)=PMYS
HUNT(L+27)=HUNT(L+8)
HUNT(L+28)=HUNT(L+8)
HUNT(L+29)=HUNT1(LL+12)
HUNT(L+30)=HUNT(L+29)
HUNT(L+31)=HUNT1(LL+13)
HUNT(L+32)=HUNT1(LL+14)
HUNT(L+33)=HUNT(L+32)
HUNT(L+34)=HUNT1(LL+15)
HUNT(L+35)=(HUNT(L+9)**2)/(HUNT(L+32)-HUNT(L+29))
HUNT(L+36)=HUNT1(LL+17)
HUNT(L+37)=HUNT1(LL+18)
HUNT(L+38)=HUNT(L+8)
HUNT(L+39)=HUNT(L+8)
HUNT(L+40)=HUNT1(LL+19)
HUNT(L+41)=HUNT(L+8)
HUNT(L+42)=HUNT(L+8)
HUNT(L+43)=HUNT(L+8)
HUNT(L+44)=HUNT(L+8)
HUNT(L+45)=HUNT1(LL+20)
HUNT(L+46)=HUNT1(LL+21)
HUNT(L+47)=HUNT(L+8)
HUNT(L+48)=HUNT(L+8)
HUNT(L+49)=HUNT(L+8)
HUNT(L+50)=HUNT1(LL+22)
HUNT(L+51)=HUNT1(LL+23)
HUNT(L+52)=HUNT1(LL+24)
HUNT(L+53)=HUNT(L+8)
HUNT(L+54)=HUNT(L+8)
HUNT(L+55)=HUNT(L+8)
HUNT(L+56)=HUNT(L+8)

BOIL1970
BOIL1980
BOIL1990
BOIL2000
BOIL2010
BOIL2020
BOIL2030
BOIL2040
BOIL2050
BOIL2060
BOIL2070
BOIL2080
BOIL2090
BOIL2100
BOIL2110
BOIL2120
BOIL2130
BOIL2140
BOIL2150
BOIL2160
BOIL2170
BOIL2180
BOIL2190
BOIL2200
BOIL2210
BOIL2220
BOIL2230
BOIL2240
BOIL2250
BOIL2260
BOIL2270
BOIL2280
BOIL2290
BOIL2300
BOIL2310
BOIL2320
BOIL2330
BOIL2340
BOIL2350
BOIL2360

HUNT(L+57)=HUNT(L+8)	BOIL2370
HUNT(L+58)=HUNT(L+8)	BOIL2380
HUNT(L+59)=HUNT1(LL+25)	BOIL2390
HUNT(L+60)=0.0	BOIL2400
HUNT(L+61)=0.0	BOIL2410
HUNT(L+62)=0.0	BOIL2420
HUNT(L+63)=HUNT1(LL+26)	BOIL2430
HUNT(L+64)=HUNT1(LL+27)	BOIL2440
HUNT(L+65)=HUNT1(LL+28)	BOIL2450
HUNT(L+66)=HUNT1(LL+29)	BOIL2460
PMYS=PMYS/HUNT(L+3)*MWR(N)	BOIL2470
20 CONTINUE	BOIL2480
C	BOIL2490
C	BOIL2500
C	BOIL2510
C	BOIL2520
C	BOIL2530
	BOIL2540
PMYS=PMYS/MWR(N)*HUNT(L+3)	BOIL2550
SPYS=SPYS/MWR(N)*HUNT(L+3)	BOIL2560
30 HUNT(L+27)=HUNT(L+55)	BOIL2570
IF(HUNT(L+45).EQ.1.)HUNT(L+27)=HUNT(L+49)	BOIL2580
HUNT(L+29)=INTGRL(ISUB,N,1,HUNT(L+30),(HUNT(L+28)-HUNT(L+9))	BOIL2590
1 /HUNT(L+31),HUNT(L+29))	BOIL2600
HUNT(L+32)=INTGRL(ISUB,N,2,HUNT(L+33),(HUNT(L+27)-HUNT(L+28))	BOIL2610
1 /HUNT(L+34),HUNT(L+32))	BOIL2620
B=HUNT(L+32)-HUNT(L+29)	BOIL2630
IF(B.LE.0.)B=0.	BOIL2640
HUNT(L+28)=SQRT(ABS(B)*HUNT(L+35))	BOIL2650
C	BOIL2660
C	BOIL2670
C	BOIL2680
C	BOIL2690
	BOIL2700
A2=0.0	BOIL2710
IF(HUNT(L+10)-HUNT(L+29).GE.HUNT(L+66)/2.)A2=HUNT(L+10)-	BOIL2720
1 HUNT(L+29)-HUNT(L+66)/2.	BOIL2730
IF(HUNT(L+10)-HUNT(L+29).LE.-HUNT(L+66)/2.)A2=HUNT(L+10)-	BOIL2740
1 HUNT(L+29)+HUNT(L+66)/2.	BOIL2750
PEB=MWR(N)*HUNT(L+65)*A2	BOIL2760
HUNT(L+60)=HUNT(L+10)-HUNT(L+29)	BOIL2770
IF(ITYPE.EQ.2.OR.ITYPE.EQ.3)GO TO 40	
GO TO 50	

40	HUNT(L+60)=HUNT(L+60)+UCE1*HUNT(L+64)/MWR(N)	BOIL2780
50	CONTINUE	BOIL2790
	IF(AEEP.EQ.0.)GO TO 60	BOIL2800
	HUNT(L+62)=(HUNT(L+60)-HUNT(L+61))/DELTD)*HUNT(L+63)	BOIL2810
	HUNT(L+61)=HUNT(L+60)	BOIL2820
60	CONTINUE	BOIL2830
	HUNT(L+57)=INTGRL(ISUB,N,3,HUNT(L+39),(HUNT(L+60))*HUNT(L+37),	BOIL2840
	1 HUNT(L+57))	BOIL2850
	HUNT(L+38)=(HUNT(L+60))*HUNT(L+36)+HUNT(L+57)+HUNT(L+62)	BOIL2860
	HUNT(L+44)=LIMIT(0.,1.,HUNT(L+38))	BOIL2870
C		BOIL2880
C		BOIL2890
C	FUEL SYSTEM	BOIL2900
C		BOIL2910
C		BOIL2920
C	*-----	BOIL2930
C	* FUEL SYSTEM DYNAMICS ARE REPRESENTED IN THE DRUM TYPE UNITS ONLY	BOIL2940
C	*	BOIL2950
C		BOIL2960
	IF(HUNT(L+45).EQ.0.) GO TO 80	BOIL2970
	NN=IFIX(2.*HUNT(L+59))	BOIL2980
C		BOIL2990
C	*-----	BOIL3000
C	* DELAY FUNCTIONS IN BOILER MUST BE CODED SO THAT THEY ARE ONLY	BOIL3010
C	* COMPUTED IF KONT EQUALS 4. IF ANY DELAY FUNCTIONS ARE	BOIL3020
C	* ADDED IN THE BOILER SUBROUTINE, THIS PROVISION MUST BE	BOIL3030
C	* MADE.	BOIL3040
C	*	BOIL3050
C		BOIL3060
	IF(KONT.NE.4) GO TO 70	BOIL3070
	HUNT(L+47)=DELAY(ISUB,N,1,NN,HUNT(L+59),HUNT(L+44))	BOIL3080
70	HUNT(L+49)=INTGRL(ISUB,N,4,HUNT(L+48),	BOIL3090
	1 (HUNT(L+47)-HUNT(L+49))/HUNT(L+46),HUNT(L+49))	BOIL3100
80	CONTINUE	BOIL3110
C		BOIL3120
C		BOIL3130
C	FEEDWATER SYSTEM	BOIL3140
C		BOIL3150
C		BOIL3160

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C *-----BOIL3170
C * FEEDWATER DYNAMICS ARE REPRESENTED ON THE ONCE-THROUGH UNITS ONLY BOIL3180
C * BOIL3190
C BOIL3200
C IF (HUNT(L+45).EQ.1.) GO TO 90 BOIL3210
C HUNT(L+53)=INTGRL (ISUB,N,5,HUNT(L+54),(HUNT(L+44) BOIL3220
C 1 -HUNT(L+55))*HUNT(L+51),HUNT(L+53)) BOIL3230
C HUNT(L+55)=INTGRL (ISUB,N,6,HUNT(L+56),(HUNT(L+53)+(HUNT(L+44) BOIL3240
C 1 -HUNT(L+55))*HUNT(L+50)-HUNT(L+55))/HUNT(L+52),HUNT(L+55)) BOIL3250
C 90 CONTINUE BOIL3260
C BOIL3270
C A=SPYS-(HUNT(L+3)*HUNT(L+4))*(OMEGA-CSKEDF/60.) BOIL3280
C BOIL3290
C BOIL3300
C -----BOIL3310
C DEADBAND BOIL3320
C -----BOIL3330
C BOIL3340
C *-----BOIL3350
C * DEADBAND REPRESENTS THE STATISTICS OF LUMPED UNITS BOIL3360
C * BOIL3370
C BOIL3380
C IF (TIME .LT. DELT) HUNT(L+6)=A BOIL3390
C HUNT(L)=(A-HUNT(L+6))/1.)*3.1212/HUNT(L+5) BOIL3400
C HUNT(L+1)=LIMIT(-1.5606,1.5606,HUNT(L)) BOIL3410
C HUNT(L+2)=TAN(HUNT(L+1)) BOIL3420
C HUNT(L+6)=INTGRL (ISUB,N,7,A,.0213*HUNT(L+2),HUNT(L+6)) BOIL3430
C BOIL3440
C -----BOIL3450
C VALVE AREA OF BOILER BOIL3460
C -----BOIL3470
C BOIL3480
C HUNT(L+15)=HUNT(L+6)*HUNT(L+7)/HUNT(L+3)-HUNT(L+9)*(HUNT(L+7)-1.) BOIL3490
C IF (HUNT(L+14)/HUNT(L+3) .LT. HUNT(L+15))HUNT(L+15)=HUNT(L+14)/ BOIL3500
C 1 HUNT(L+3) BOIL3510
C HUNT(L+16)=(HUNT(L+29)-HUNT(L+11)*HUNT(L+10))*HUNT(L+13) BOIL3520
C IF (HUNT(L+16) .LT. HUNT(L+15)) HUNT(L+15)=HUNT(L+16) BOIL3530
C HUNT(L+17)=LIMIT(0.,1.,HUNT(L+15)) BOIL3540
C IF (HUNT(L+17)-HUNT(L+8) .LT. 0.) GO TO 100 BOIL3550
C IF (HUNT(L+17)-HUNT(L+8) .GT. HUNT(L+19)*DELTD)HUNT(L+17)=HUNT(L+8)+ BOIL3560
C 1 HUNT(L+19)*DELTD BOIL3570

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HUNT(L+8)=HUNT(L+17)	80IL3580
GO TO 110	80IL3590
100 IF (HUNT(L+8)-HUNT(L+17) .GT. HUNT(L+20)*DELTD) HUNT(L+17)=HUNT(L+8)-	80IL3600
1 HUNT(L+20)*DELTD	80IL3610
HUNT(L+8)=HUNT(L+17)	80IL3620
110 CONTINUE	80IL3630
HUNT(L+18)=HUNT(L+17)	80IL3640
HUNT(L+9)=HUNT(L+18)*HUNT(L+29)	80IL3650
STMFLO=HUNT(L+9)	80IL3660
C	80IL3670
C	80IL3680
C	80IL3690
C	80IL3700
C	80IL3710
HUNT(L+24)=INTGR(1 SUB, N, 8, HUNT(L+25), (HUNT(L+9)*(1.-HUNT(L+22))	80IL3720
1 -HUNT(L+24))*1./HUNT(L+21), HUNT(L+24))	80IL3730
HUNT(L+23)=HUNT(L+24)+HUNT(L+9)*HUNT(L+22)	80IL3740
HUNT(L+26)=HUNT(L+23)*HUNT(L+3)	80IL3750
PMYS=HUNT(L+26)	80IL3760
C	80IL3770
C	80IL3780
C *	80IL3790
C * THE COUNTER KONT ACCUMULATES FOUR PASSES THROUGH BOILER EACH	80IL3800
C * TIME SUBROUTINE BOILER IS ENTERED. BEING A TWO STEP	80IL3810
C * TRAPEZOIDAL INTEGRATION ROUTINE THERE ARE TWO PASSES FOR	80IL3820
C * EACH .5 SECOND BOILER INTEGRATION INTERVAL AND TWO .5	80IL3830
C * SECOND INTERVALS FOR EACH 1. SECOND SYSTEM MODES INTEGRA-	80IL3840
C * TION STEP.	80IL3850
C *	80IL3860
C	80IL3870
IF(AEEP .EQ. 1.) AEEP=-1.	80IL3880
AEEP=AEEP+1.	80IL3890
KONT=KONT+1	80IL3900
IF(KONT .EQ. 5) GO TO 120	80IL3910
GO TO 30	80IL3920
120 CONTINUE	80IL3930
C	80IL3940
C *	80IL3950
C * PMYS (MECHANICAL POWER OUTPUT) AND SPYS (GOVERNOR SET POINT)	80IL3960
C * ARE RESCALED FROM THE UNIT SIZE OF WHICHEVER OF THE SIX	80IL3970
C * BASIC TYPES OF BOILER UNITS USED TO THE SIZE OF THE UNIT	

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C *      REPRESENTED IN THE SYSTEM MODEL.  FOR EXAMPLE:
C *      PMYS=PMYS*MEGAWATT RATING/ 191.0 MW
C *      FOR THE SUBCRITICAL ONCE-THROUGH UNIT (ITYPE=3)
C *
C
      PMYS=PMYS/HUNT(L+3)*MWR(N)
      SPYS=SPYS/HUNT(L+3)*MWR(N)
130 CONTINUE
      IF (MWR(N) .LT. 1.) PMYS=0.
      RETURN
      END

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BOIL3980
BOIL3990
BOIL4000
BOIL4010
BOIL4020
BOIL4030
BOIL4040
BOIL4050
BOIL4060
BOIL4070
BOIL4080

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C	-----	HYDR0010
C	*	* HYDR0020
C	*	* HYDR0030
C	*	* HYDR0040
C	-----	HYDR0050
C		HYDR0060
C	SUBROUTINE HYDRO(CSKEDF,OMEGA,SPYP,PMYP,NUMBER,N)	HYDR0070
C		HYDR0080
C		HYDR0090
	COMMON / CURVAL / TIME , DELT , KEEP	HYDR0100
	COMMON / WATT / WATER1(36)	HYDR0110
	COMMON / INITIAL / DUMMY(40) , MWR(20)	HYDR0120
	COMMON / PRICNL / ICDUNT, ILAST , SYMBOL, VALUE , LINES , IPAGES	HYDR0130
C		HYDR0140
C	DIMENSION WATER(132)	HYDR0150
C		HYDR0160
	REAL*4 LIMIT , INTGRL, MWR	HYDR0170
	REAL*4 VALUE(44)	HYDR0180
	REAL*8 SYMBOL(44)	HYDR0190
C		HYDR0200
	ISUB=6	HYDR0210
C		HYDR0220
C		HYDR0230
C		HYDR0240
C	THIS SUBROUTINE REPRESENTS HIGH AND LOW HEAD HYDRO UNITS.	HYDR0250
C		HYDR0260
C	THE ARRAY WATER1 IS THE DATA STORAGE AREA USED TO STORE THE	HYDR0270
C	PARAMETERS AND INITIALIZATION DATA FOR EACH HYDRO UNIT.	HYDR0280
C	WATER1 IS DIMENSIONED FOR 6 UNITS AT 6 VARIABLES PER UNIT.	HYDR0290
C		HYDR0300
C	THE ARRAY WATER IS THE WORKING AREA REPRESENTING THE DYNAMIC	HYDR0310
C	EQUATIONS FOR EACH HYDRO UNIT. WATER IS DIMENSIONED FOR	HYDR0320
C	6 UNITS AT 22 VARIABLES PER UNIT.	HYDR0330
C		HYDR0340
C	WATER(L)=TH1Y DEADBAND UPPER VALJE	HYDR0350
C	WATER(L+1)=TH2Y DEADBAND LOWER VALJE	HYDR0360
C	WATER(L+2)=TH3Y DEADBAND OUTPUT	HYDR0370
C	WATER(L+3)=CYP01 SPEED DROOP (1/R)	HYDR0380
C	WATER(L+4)=CYP02 TRANSIENT REGULATION (R/R)	HYDR0390
C	WATER(L+5)=CYP03 DEADBAND (T(R))	HYDR0400

C	WATER(L+6)=CYP04	TRANSIENT DROOP TIME CONSTANT	HYDR0410
C	WATER(L+7)=CYR05	RATE OF GATE LIMIT (MW/SEC)	HYDR0420
C	WATER(L+8)=CYP06	GATE UPPER LIMIT	HYDR0430
C	WATER(L+9)=CYP07	GATE LOWER LIMIT	HYDR0440
C	WATER(L+10)=CYP08	TW, WATER STARTING TIME	HYDR0450
C	WATER(L+11)=T3PY	DEADBAND INPUT	HYDR0460
C	WATER(L+12)=S1PY	GOVERNOR STATE	HYDR0470
C	WATER(L+13)=SPYP	GOVERNOR SETPOINT	HYDR0480
C	WATER(L+14)=PMYP	MECHANICAL POWER OUTPUT	HYDR0490
C	WATER(L+15)=HY1		HYDR0500
C	WATER(L+16)=P0	INITIALIZED TO T3PY, WATER(L+11)	HYDR0510
C	WATER(L+17)=HY2	INITIALIZED TO HY1	HYDR0520
C	WATER(L+18)=HY3	INITIALIZED TO P0	HYDR0530
C	WATER(L+19)=G	OUTPUT OF GATE	HYDR0540
C	WATER(L+20)=DL1	INITIALIZE TO 3.*P0	HYDR0550
C	WATER(L+21)=S2PY	HYDRAULIC TURBINE STATE	HYDR0560
C			HYDR0570
C			HYDR0580
C		-----	HYDR0590
C		INITIALIZATION	HYDR0600
C		-----	HYDR0610
C			HYDR0620
C	*-----*		HYDR0630
C	* INITIALIZATION ROUTINE FOR EACH HYDRO UNIT AT TIME LESS THAN		HYDR0640
C	* DELT, THE SYSTEM INTEGRATION STEP.		HYDR0650
C	*-----*		HYDR0660
C	* WATER IS INITIALIZED BY THE DATA SET WATER1 AND HAS 22 LOCATIONS		HYDR0670
C	* RESERVED FOR EACH HYDRO UNIT.		HYDR0680
C	*-----*		HYDR0690
C			HYDR0700
C	ICALC=NUMBER*22		HYDR0710
C	L=ICALC-21		HYDR0720
C			HYDR0730
C	*-----*		HYDR0740
C	* L IS USED TO INDEX TO THE APPROPRIATE LOCATION IN WATER FOR		HYDR0750
C	* THE UNIT PRESENTLY BEING UPDATED.		HYDR0760
C	*-----*		HYDR0770
C			HYDR0780
C	IF(TIME .LT. DELT)GO TO 10		HYDR0790
C	GO TO 20		HYDR0800
C	10 LLLCALC=NUMBER*6		HYDR0810

	LL=LLCALC-5	HYDR0820
C		HYDR0830
C	*-----*	HYDR0840
C	* LL INDEXES WATER1 TO THE PROPER LOCATION FOR THE CURRENT UNIT'S	HYDR0850
C	* PARAMETERS.	HYDR0860
C	*-----*	HYDR0870
C		HYDR0880
	WATER(L)=PMYP+WATER1(LL+2)/2.	HYDR0890
	WATER(L+1)=PMYP-WATER1(LL+2)/2.	HYDR0900
	WATER(L+2)=PMYP	HYDR0910
	WATER(L+3)=MWR(N)*1./WATER1(LL)	HYDR0920
	WATER(L+4)=WATER1(LL+1)	HYDR0930
	WATER(L+5)=WATER1(LL+2)	HYDR0940
	WATER(L+6)=WATER1(LL+3)	HYDR0950
	WATER(L+7)=WATER1(LL+4)	HYDR0960
	WATER(L+8)=MWR(N)	HYDR0970
	WATER(L+9)=.10*MWR(N)	HYDR0980
	WATER(L+10)=WATER1(LL+5)	HYDR0990
	WATER(L+11)=PMYP	HYDR1000
	WATER(L+12)=PMYP*(1.-WATER1(LL+1))	HYDR1010
	WATER(L+13)=SPYP	HYDR1020
	WATER(L+14)=PMYP	HYDR1030
	WATER(L+15)=PMYP	HYDR1040
	WATER(L+16)=PMYP	HYDR1050
	WATER(L+17)=PMYP	HYDR1060
	WATER(L+18)=PMYP	HYDR1070
	WATER(L+19)=PMYP	HYDR1080
	WATER(L+20)=3.*PMYP	HYDR1090
	WATER(L+21)=3.*PMYP	HYDR1100
20	CONTINUE	HYDR1110
C		HYDR1120
C		HYDR1130
C	-----	HYDR1140
C	DYNAMICS	HYDR1150
C	-----	HYDR1160
	IF (SPYP .LT. .5) GO TO 80	HYDR1170
	WATER(L+13)=SPYP	HYDR1180
	WATER(L+11)=WATER(L+13)-WATER(L+3)*(OMEGA-CSKEDF/60.)	HYDR1190
C		HYDR1200
C	-----	HYDR1210

C
C
C

DEADBAND

IF (WATER(L+11)-WATER(L)) 30, 60, 50
30 IF (WATER(L+11)-WATER(L+1)) 40, 60, 60
40 WATER(L+1)=WATER(L+11)
WATER(L+2)=WATER(L+11)+WATER(L+5)/2.
WATER(L)=WATER(L+11)+WATER(L+5)
GO TO 60
50 WATER(L)=WATER(L+11)
WATER(L+1)=WATER(L+11)-WATER(L+5)
WATER(L+2)=WATER(L+11)-WATER(L+5)/2.
60 WATER(L+11)=WATER(L+2)
CONTINUE

C
C
C
C
C

GATE RATE AND TRAVEL NON-WINDUP LIMITS

WATER(L+12)=INTGR1 (ISUB,N,1,WATER(L+15)*(1.-WATER(L+4)),
1 LIMIT(-WATER(L+7)*(1.-WATER(L+4)),WATER(L+7)*(1.-WATER(L+4))),
2 (1./WATER(L+6))*(WATER(L+11)-WATER(L+15))),WATER(L+12))
IF (WATER(L+12) .GT. (1.-WATER(L+4))*WATER(L+8)) WATER(L+12)=
1 (1.-WATER(L+4))*WATER(L+8)
IF (WATER(L+12) .LT. (1.-WATER(L+4))*WATER(L+9)) WATER(L+12)=
1 (1.-WATER(L+4))*WATER(L+9)
WATER(L+15)=WATER(L+12)+WATER(L+11)*WATER(L+4)
IF (KEEP .NE. 1.) GO TO 70
WATER(L+17)=WATER(L+15)
IF (ABS(WATER(L+15)-WATER(L+18)) .GT. WATER(L+7)*DELT) WATER(L+17)
1 =WATER(L+18)+WATER(L+7)*DELT*SIGN(1.,WATER(L+15)-WATER(L+18))
WATER(L+18)=WATER(L+17)
70 CONTINUE
WATER(L+19)=LIMIT (WATER(L+9),WATER(L+8),WATER(L+17))

C
C
C
C
C

TURBINE

WATER(L+20)=DELAY (ISUB,N,1,1,DELT,WATER(L+21))
WATER(L+21)=WATER(L+19)*3.*1./(1.+WATER(L+10)/(2.*DELT))+(1.-1./

HYDR1220
HYDR1230
HYDR1240
HYDR1250
HYDR1260
HYDR1270
HYDR1280
HYDR1290
HYDR1300
HYDR1310
HYDR1320
HYDR1330
HYDR1340
HYDR1350
HYDR1360
HYDR1370
HYDR1380
HYDR1390
HYDR1400
HYDR1410
HYDR1420
HYDR1430
HYDR1440
HYDR1450
HYDR1460
HYDR1470
HYDR1480
HYDR1490
HYDR1500
HYDR1510
HYDR1520
HYDR1530
HYDR1540
HYDR1550
HYDR1560
HYDR1570
HYDR1580
HYDR1590
HYDR1600
HYDR1610
HYDR1620

```
1      (1.+WATER(L+10)/(2.*DELT)))*WATER(L+20)
      PMYP=WATER(L+21)-2.*WATER(L+19)
80 CONTINUE
      RETURN
      END
```

```
HYDR1630
HYDR1640
HYDR1650
HYDR1660
HYDR1670
```

C	-----	GAST0010
C	*	* GAST0020
C	*	* GAST0030
C	*	* GAST0040
C	-----	GAST0050
C		GAST0060
C	SUBROUTINE GASTUB(CSKEDF,OMEGA,SPYT,P4YT,NUMBER,N)	GAST0070
C		GAST0080
	COMMON / CURVAL / TIME , DELT , KEEP	GAST0090
	COMMON / GAS / GASS1(60)	GAST0100
	COMMON / INITIAL / DUMMY(40) , MWR(20)	GAST0110
C	COMMON / PRTCNL / ICOUNT, ILAST , SYMBOL, VALUE , LINES , IPAGES	GAST0120
		GAST0130
	REAL*4 LIMIT , MWR	GAST0140
	REAL*4 VALUE(44)	GAST0150
	REAL*8 SYMBOL(44)	GAST0160
C		GAST0170
	DIMENSION GASS(140)	GAST0180
C		GAST0190
	ISUB=7	GAST0200
C		GAST0210
C		GAST0220
C		GAST0230
C	SUBROUTINE GASTUB IS THE GAS TURBINE MODEL USED IN THE SYSTEM	GAST0240
C	MODEL	GAST0250
C		GAST0260
C	THE ARRAY GASS1 IS THE DATA STORAGE AREA WHERE THE PARAMETERS	GAST0270
C	AND INITIALIZATION DATA FOR EACH GAS TURBINE UNIT ARE	GAST0280
C	STORED. GASS1 IS DIMENSIONED FOR 20 UNITS AT 3 VARIABLES	GAST0290
C	PER UNIT.	GAST0300
C		GAST0310
C	THE ARRAY GASS IS THE WORKING AREA REPRESENTING THE DYNAMIC	GAST0320
C	EQUATIONS FOR EACH GAS TURBINE. GASS IS DIMENSIONED FOR	GAST0330
C	20 UNITS AT 7 VARIABLES PER UNIT.	GAST0340
C		GAST0350
C		GAST0360
C	GASS(L)=TG1Y DEADBAND UPPER LIMIT	GAST0370
C	GASS(L+1)=TG2Y DEADBAND LOWER LIMIT	GAST0380
C	GASS(L+2)=TG3Y DEADBAND OUTPUT	GAST0390
C	GASS(L+3)=T3TY DEADBAND INPUT	GAST0400

C	GASS(L+4)=CDBYT DEADBAND WIDTH	GAST0410
C	GASS(L+5)=CYT01 SPEEDDROOP (1/R)	GAST0420
C	GASS(L+6)=CYT02 EXHAUST TEMPERATURE POWER LIMIT	GAST0430
C		GAST0440
C		GAST0450
C		GAST0460
C		GAST0470
C		GAST0480
C	-----	GAST0490
C	INITIALIZATION	GAST0500
C	-----	GAST0510
	ICALC=NUMBER*7	GAST0520
	L=ICALC-6	GAST0530
C		GAST0540
C	*-----	GAST0550
C	* L IS USED TO INDEX TO THE APPROPRIATE LOCATION IN GASS FOR THE	GAST0560
C	* UNIT PRESENTLY BEING UPDATED.	GAST0570
C	*	GAST0580
C		GAST0590
	IF (TIME .LT. DELT) GO TO 10	GAST0600
	GO TO 20	GAST0610
	10 LLCALC=NUMBER*3	GAST0620
	LL=LLCALC-2	GAST0630
C		GAST0640
C	*-----	GAST0650
C	* LL INDEXES GASS1 TO THE PROPER LOCATION FOR THE CURRENT UNIT'S	GAST0660
C	* PARAMETERS.	GAST0670
C	*	GAST0680
C		GAST0690
	GASS(L)=PMYT+GASS1(LL)/2.	GAST0700
	GASS(L+1)=PMYT-GASS1(LL)/2.	GAST0710
	GASS(L+2)=PMYT	GAST0720
	GASS(L+3)=PMYT	GAST0730
	GASS(L+4)=GASS1(LL)	GAST0740
	GASS(L+5)=MWR(N)*1./GASS1(LL+1)	GAST0750
C		GAST0760
C	*-----	GAST0770
C	* 29.5 IS AMBIENT TEMPERATURE IN WINTER (DEGRESS F)	GAST0780
C	*	GAST0790
C		GAST0800
	GASS(L+6)=(1.23-(.23/59.)*GASS1(LL+2))*MWR(N)	

```

20 CONTINUE
C
C
C
C
C
      GASS(L+3)=SPYT-GASS(L+5)*(OMEGA-1.)
      IF(KEEP .EQ. 0.) GO TO 70
      IF(GASS(L+3)-GASS(L)) 30, 60, 50
30  IF(GASS(L+3)-GASS(L+1)) 40, 60, 60
40  GASS(L+1)=GASS(L+3)
      GASS(L+2)=GASS(L+3)+GASS(L+4)/2.
      GASS(L)=GASS(L+3)+GASS(L+4)
      GO TO 60
50  GASS(L)=GASS(L+3)
      GASS(L+1)=GASS(L+3)-GASS(L+4)
      GASS(L+2)=GASS(L+3)-GASS(L+4)/2.
60  GASS(L+3)=GASS(L+2)
70  CONTINUE
      PMYT=DELAY(1SUB,N,1,2,2.,LIMIT(0.,GASS(L+6),GASS(L+3)))
      RETURN
      END

```

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GAST0810
GAST0820
GAST0830
GAST0840
GAST0850
GAST0860
GAST0870
GAST0880
GAST0890
GAST0900
GAST0910
GAST0920
GAST0930
GAST0940
GAST0950
GAST0960
GAST0970
GAST0980
GAST0990
GAST1000
GAST1010
GAST1020

```

C	-----	NUCL0010
C	*	* NUCL0020
C	*	* NUCL0030
C	*	* NUCL0040
C	-----	NUCL0050
C		NUCL0060
C	SUBROUTINE NUCLER(CSKEDF,OMEGA,SPYB,P4YB,NUMBER,N)	NUCL0070
C		NUCL0080
	COMMON / CURVAL / TIME , DELT , KEEP	NUCL0090
	COMMON / ATOM / ATOM1(110)	NUCL0100
	COMMON / INITAL / DUMMY(40) , MWR(20)	NUCL0110
C	COMMON / PRICNL / ICOUNT, TLAST , SYMBOL, VALUE , LINES , IPAGES	NUCL0120
		NUCL0130
	REAL*8 SYMBOL(44)	NUCL0140
	REAL*4 VALUE(44)	NUCL0150
	REAL*4 INITAL, INTGRL, LIMIT , MWR	NUCL0160
C		NUCL0170
	DIMENSION ATOM(310)	NUCL0180
C		NUCL0190
	ISUB=8	NUCL0200
C		NUCL0210
C		NUCL0220
C		NUCL0230
C	SUBROUTINE NUCLER REPRESENTS THE BOILING WATER NUCLEAR REACTOR	NUCL0240
C	UNITS ON THE SYSTEM.	NUCL0250
C		NUCL0260
C	THE ARRAY ATOM1 IS THE DATA STORAGE AREA WHERE THE PARAMETERS AND	NUCL0270
C	INITIALIZATION DATA FOR EACH NUCLEAR UNIT ARE STORED. IT IS	NUCL0280
C	DIMENSIONED FOR 10 UNITS AT 11 VARIABLES PER UNIT.	NUCL0290
C		NUCL0300
C	THE ARRAY ATOM IS THE WORKING AREA REPRESENTING THE DYNAMIC	NUCL0310
C	EQUATIONS FOR EACH UNIT. IT IS DIMENSIONED FOR 10 UNITS	NUCL0320
C	AT 31 VARIABLES PER UNIT.	NUCL0330
C		NUCL0340
C		NUCL0350
C	ATOM(L)=CYB01 UNIT MW RATING	NUCL0360
C	ATOM(L+1)=CYB02 PROPORTIONAL PART OF RECIRCULATION CONTROL	NUCL0370
C	ATOM(L+2)=CYB03 IN-CORE THERMAL TIME CONSTANT	NUCL0380
C	ATOM(L+3)=CYB04 INTEGRAL PART OF RECIRCULATION CONTROL	NUCL0390
C	ATOM(L+4)=CYB05 POWER CORRESPONDING TO RECIRCULATION CONTROL	NUCL0400

C	ATOM(L+5)=CYB06	PRESSURE REGULATOR LIMIT	NUCL0410
C	ATOM(L+6)=CYB07	PRESSURE REGULATOR GAIN	NUCL0420
C	ATOM(L+7)=CYB08	TIME CONSTANT PRESSURE REGULATOR OFFSET	NUCL0430
C	ATOM(L+8)=CYB09	TIME CONSTANT PRESSURE REGULATOR OFFSET	NUCL0440
C	ATOM(L+9)=CYB10	TURBINE POWER BEFORE MOISTURE SEPARATOR	NUCL0450
C	ATOM(L+10)=CYB11	MOISTURE SEPARATOR STEAM FLOW TIME CONSTANT	NUCL0460
C	ATOM(L+11)=CYB12		NUCL0470
C	ATOM(L+12)=S1BY	TURBINE INTEGRATOR	NUCL0480
C	ATOM(L+13)=S2BY	CORE THERMAL STORAGE INTEGRATOR	NUCL0490
C	ATOM(L+14)=S3BY	PRESSURE REGULATOR OFFSET INTEGRATOR	NUCL0500
C	ATOM(L+15)=S4BY	PRESSURE REGULATOR OFFSET INTEGRATOR	NUCL0510
C	ATOM(L+16)=S5BY	PRESSURE REGULATOR OFFSET INTEGRATOR	NUCL0520
C	ATOM(L+17)=PFLOW	INPUT TO TURBINE	NUCL0530
C	ATOM(L+18)=LODEM	LOAD DEMAND	NUCL0540
C	ATOM(L+19)=LDERR	LOAD DEMAND ERROR	NUCL0550
C	ATOM(L+20)=THRESH	PRESSURE REGULATOR THRESHOLD	NUCL0560
C	ATOM(L+21)=THRES1		NUCL0570
C	ATOM(L+22)=THRES2		NUCL0580
C	ATOM(L+23)=P1PR	OUTPUT OF PRESSURE REGULATOR	NUCL0590
C	ATOM(L+24)=RECIR1		NUCL0600
C	ATOM(L+25)=RECIR2		NUCL0610
C	ATOM(L+26)=RECFLW	RECIRCULATION FLOW	NUCL0620
C	ATOM(L+27)=PGEN	POWER CORRESPONDING TO RECIRCULATION FLOW	NUCL0630
C	ATOM(L+28)=PG DEL	PGEN DELIVERED	NUCL0640
C	ATOM(L+29)=MSEPC	TURBINE POWER BEFORE MOISTURE SEPARATOR	NUCL0650
C	ATOM(L+30)=DUMMY		NUCL0660
C			NUCL0670
C			NUCL0680
C			NUCL0690
C		-----	NUCL0700
C		INITIALIZATION	NUCL0710
C		-----	NUCL0720
C			NUCL0730
C	ICALC=NUMBER*31		NUCL0740
C	L=ICALC-30		NUCL0750
C			NUCL0760
C	*-----*		NUCL0770
C	* L INDEXES TO THE PROPER LOCATION IN ATOM FOR THE UNIT PRESENTLY		NUCL0780
C	* BEING UPDATED		NUCL0790
C	*		NUCL0800
C			NUCL0810

IF(MWR(N) .LT. 1.) GO TO 30	NUCL0820
IF(TIME .LT. DELT) GO TO 10	NUCL0830
GO TO 20	NUCL0840
10 LLCALC=NUMBER*11	NUCL0850
LL=LLCALC-10	NUCL0860
C	NUCL0870
C *-----	NUCL0880
C * LL INDEXES ATOM1 TO THE PROPER LOCATIONS FOR THE CURRENT UNIT'S	NUCL0890
C * PARAMETERS.	NUCL0900
C *	NUCL0910
C	NUCL0920
ATOM(L)=MWR(N)	NUCL0930
ATOM(L+1)=ATOM1(LL)	NUCL0940
ATOM(L+2)=ATOM1(LL+1)	NUCL0950
ATOM(L+3)=ATOM1(LL+2)	NUCL0960
ATOM(L+4)=ATOM1(LL+3)	NUCL0970
ATOM(L+5)=ATOM1(LL+4)	NUCL0980
ATOM(L+6)=ATOM1(LL+5)	NUCL0990
ATOM(L+7)=ATOM1(LL+6)	NUCL1000
ATOM(L+8)=ATOM1(LL+7)	NUCL1010
ATOM(L+9)=ATOM1(LL+8)	NUCL1020
ATOM(L+10)=ATOM1(LL+9)	NUCL1030
ATOM(L+11)=ATOM1(LL+10)	NUCL1040
ATOM(L+13)=PMYB/ATOM(L)	NUCL1050
C	NUCL1060
C *-----	NUCL1070
C * PU=PMYB/CYB01 = S2BY = ATOM(L+13)	NUCL1080
C *	NUCL1090
C	NUCL1100
ATOM(L+12)= (1.-ATOM(L+9))*ATOM(L+13)	NUCL1110
ATOM(L+14)=(1.3*ATOM(L+13)/ATOM(L+4))- .3	NUCL1120
ATOM(L+15)=0.0	NUCL1130
ATOM(L+16)=0.0	NUCL1140
ATOM(L+17)=ATOM(L+16)+ATOM(L+13)	NUCL1150
ATOM(L+22)=ATOM(L+15)	NUCL1160
ATOM(L+23)=ATOM(L+16)	NUCL1170
ATOM(L+28)=ATOM(L+13)	NUCL1180
ATOM(L+30)=ATOM(L+12)	NUCL1190
20 CONTINUE	NUCL1200

C
C
C
C
C

DYNAMICS

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ATOM(L+18)=(SPYB/ATOM(L))- (OMEGA-CSKEDF/60.)/ATOM(L+11)
ATOM(L+19)=ATOM(L+18)-ATOM(L+17)
ATOM(L+20)=LIMIT(-ATOM(L+5),ATOM(L+5),ATOM(L+19))
ATOM(L+21)=ATOM(L+6)*ATOM(L+20)
ATOM(L+22)=INTGRL (ISUB,N,1,ATOM(L+15), (ATOM(L+21)-ATOM(
1      L+22))/ATOM(L+7),ATOM(L+22))
ATOM(L+23)=INTGRL (ISUB,N,2,ATOM(L+16), (ATOM(L+21)-ATOM(
1      L+22)-ATOM(L+23))/ATOM(L+8),ATOM(L+23))
ATOM(L+24)=ATOM(L+19)*ATOM(L+1)
ATOM(L+25)=INTGRL (ISUB,N,3,ATOM(L+14),ATOM(L+19)*
1      ATOM(L+3),ATOM(L+25))
ATOM(L+26)=LIMIT(0.50,1.05,ATOM(L+25)+ATOM(L+24))
ATOM(L+27)=(ATOM(L+26)+0.3)*(ATOM(L+4)/1.30)
ATOM(L+28)=INTGRL (ISUB,N,4,ATOM(L+13), (ATOM(L+27)-ATOM(
1      L+28))/ATOM(L+2),ATOM(L+28))
ATOM(L+17)=ATOM(L+23)+ATOM(L+28)
ATOM(L+29)=ATOM(L+9)*ATOM(L+17)
ATOM(L+30)=INTGRL (ISUB,N,5,ATOM(L+12), ((ATOM(L+17)-ATOM(
1      L+29))-ATOM(L+30))/ATOM(L+10),ATOM(L+30))
PMYB=(ATOM(L+29)+ATOM(L+30))*ATOM(L)
30 CONTINUE
RETURN
END

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NUCL1210
NUCL1220
NUCL1230
NUCL1240
NUCL1250
NUCL1260
NUCL1270
NUCL1280
NUCL1290
NUCL1300
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NUCL1410
NUCL1420
NUCL1430
NUCL1440
NUCL1450
NUCL1460
NUCL1470
NUCL1480

C	*****	AFGE0010
C	*	* AFGE0020
C	*	* AFGE0030
C	*	* AFGE0040
C	*****	AFGE0050
C		AFGE0060
	FUNCTION AFGEN(ANPUT,N)	AFGE0070
C		AFGE0080
	COMMON / CURVAL / TIME , DELT	AFGE0090
	COMMON / COST / CURVE(1)	AFGE0100
C		AFGE0110
	DIMENSION LOC(100)	AFGE0120
	DATA LOC/100*1/	AFGE0130
C		AFGE0140
C		AFGE0150
C		AFGE0160
	M=20*(N-1)	AFGE0170
	I1=LOC(N)	AFGE0180
	DO 10 I=I1,19,2	AFGE0190
	IF(CURVE(I+M) .GT. ANPUT) GO TO 20	AFGE0200
10	CONTINUE	AFGE0210
20	I2=I-1	AFGE0220
	DO 30 K=2,12,2	AFGE0230
	IF(CURVE(I-K+M) .LT. ANPUT) GO TO 40	AFGE0240
30	CONTINUE	AFGE0250
40	LOC(N)=I-K	AFGE0260
	I=LOC(N)+2	AFGE0270
	SLOPE=(CURVE(I+1+M)-CURVE(I-1+M))/(CURVE(I+M)-CURVE(I-2+M))	AFGE0280
	AFGEN=CURVE(I-1+M)+SLOPE*(ANPUT-CURVE(I-2+M))	AFGE0290
	RETURN	AFGE0300
	END	AFGE0310

C		DEAD0010
C	*****	DEAD0020
C	*	* DEAD0030
C	*	* DEAD0040
C	*	* DEAD0050
C	*****	DEAD0060
C		DEAD0070
	FUNCTION DEADSP(P1, P2, X)	DEAD0080
C		DEAD0090
	IF(X .GT. P2) GO TO 10	DEAD0100
	IF(X .LT. P1) GO TO 20	DEAD0110
	DEADSP = 0.0	DEAD0120
	RETURN	DEAD0130
	10 DEADSP = X - P2	DEAD0140
	RETURN	DEAD0150
	20 DEADSP = X - P1	DEAD0160
	RETURN	DEAD0170
	END	DEAD0180

C	ROUTINE. THIS NUMBER IS CODED IN THE KINGRL SPOT OF THE	DELA0420
C	CALLING ARGUMENTS. SIMILARLY NUMBER THE DELAYS IN THE	DELA0430
C	SUBROUTINE FROM 1 TO M WHERE M IS THE MAXIMUM NUMBER OF	DELA0440
C	DELAYS USED IN THE SUBROUTINE. THIS NUMBER IS CODED IN	DELA0450
C	THE IDLAY SPOT OF THE CALLING ARGUMENTS.	DELA0460
C		DELA0470
C	4) BE SURE THAT DLAY, SD, AND PD ARE DIMENSIONED ADEQUATELY.	DELA0480
C	(SEE COMMENTS IN COMMON /DELLAY/ ABOVE AND IN FUNCTION	DELA0490
C	INTGRL BELOW)	DELA0500
C		DELA0510
C	5) IF A DELAY FUNCTION IS ADDED IN THE BOILER SUBROUTINE,	DELA0520
C	A BRANCHING STATEMENT MUST BE PROVIDED SO THAT THE DELAY	DELA0530
C	IS ONLY COMPUTED WHEN KONT EQUALS 4. IF KONT DOES NOT	DELA0540
C	EQUAL 4, THE DELAY FUNCTION MUST BE SKIPPED.	DELA0550
C		DELA0560
	COMMON / CURVAL / TIME , DELT , KEEP	DELA0570
	COMMON / DELLAY / C(1000) , DLAY(8,21,6)	DELA0580
	COMMON / PASSES / KONT	DELA0590
	COMMON / NALARM / IERR	DELA0600
C		DELA0610
	INTEGER*4 KC(1)	DELA0620
C		DELA0630
	EQUIVALENCE (C(1),KC(1))	DELA0640
C		DELA0650
	DATA K1/3/	DELA0660
C		DELA0670
C		DELA0680
C		DELA0690
	IF (ISUB.GT.8 .OR. KUNIT.GT.21 .OR. IDLAY.GT.6) GO TO 140	DELA0700
	IF (TIME .EQ. 0.) GO TO 10	DELA0710
	K=DLAY(ISUB,KUNIT+1,IDLAY)	DELA0720
	GO TO 40	DELA0730
10	IF (KEEP .EQ. 0 .OR. KONT .EQ. 4) GO TO 20	DELA0740
	GO TO 30	DELA0750
20	DLAY(ISUB,KUNIT+1,IDLAY)=K1	DELA0760
	K1=K1+2*NUM+2	DELA0770
30	CONTINUE	DELA0780
	K=DLAY(ISUB,KUNIT+1,IDLAY)	DELA0790
	IF (K.GT.999) GO TO 170	DELA0800
	IF (TIME .GT. 0.0) GO TO 40	DELA0810

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      KC(K-1)=K
      KC(K-2)=K+2*(NUM-1)
      C(K)=0.0
      C(K+1)=X
      DELAY=X
      RETURN
C    TEST IF TIME FOR OUTPUT
40   TIMEX=TIME-P
      IF(TIMEX .GE. 0.0) GO TO 50
      DELAY=X
      GO TO 120
50   INDEX=KC(K-1)
      IF(C(K) .LE. 0.0) GO TO 70
      KEND=KC(K-2)
      IF(INDEX .EQ. KEND) GO TO 70
      INDEX2=INDEX+2
      DO 60 I1=INDEX2,KEND,2
      I=I1
      IF(TIMEX-C(I)) 100, 110, 60
60   CONTINUE
70   DO 80 I1=K,INDEX,2
      I=I1
      IF(TIMEX-C(I)) 100, 110, 80
80   CONTINUE
      WRITE(6,90) NUM,P
90   FORMAT('O DELAY BLOCK NEEDS MORE THAN THE ',15,
1     'POINTS PROVIDED FOR DELAY OF',E12.5/)
      GO TO 200
100  I=I-2
      IF(I .LT. K) I=KEND
110  DELAY=C(I+1)
C    TEST IF TIME TO STORE INPUT
120  IF(KEEP .LE. 0) RETURN
      INDEX=KC(K-1)+2
      IF(INDEX .LE. KC(K-2)) GO TO 130
      INDEX=K
130  KC(K-1)=INDEX
      C(INDEX)=TIME
      C(INDEX+1)=X
      GO TO 210

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DELA0820
DELA0830
DELA0840
DELA0850
DELA0860
DELA0870
DELA0880
DELA0890
DELA0900
DELA0910
DELA0920
DELA0930
DELA0940
DELA0950
DELA0960
DELA0970
DELA0980
DELA0990
DELA1000
DELA1010
DELA1020
DELA1030
DELA1040
DELA1050
DELA1060
DELA1070
DELA1080
DELA1090
DELA1100
DELA1110
DELA1120
DELA1130
DELA1140
DELA1150
DELA1160
DELA1170
DELA1180
DELA1190
DELA1200
DELA1210

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140 WRITE(6,150)	DELA1220
WRITE(6,160) ISUB,KUNIT,IDLAY	DELA1230
150 FORMAT('0 A DLAY INDEX HAS EXCEEDED A MAXIMUM. USER MUST INCREASE	DELA1240
IE THE DIMENSION OF DLAY(8,21,6)')	DELA1250
160 FORMAT(' THE ATTEMPTED INDICES WERE: ISUB=',I5,' KUNIT=',	DELA1260
I15,' IDLAY=',I5/)	DELA1270
GO TO 200	DELA1280
170 WRITE(6,180)	DELA1290
180 FORMAT(1H0,' MORE THAN 1000 STORAGE SPACES REQUIRED, USER MUST INC	DELA1300
REASE DIMENSION OF C(1000).')	DELA1310
WRITE(6,190) K	DELA1320
190 FORMAT(' THE ATTEMPTED INDEX WAS: K=',I5/)	DELA1330
GO TO 200	DELA1340
200 IERR=1	DELA1350
210 CONTINUE	DELA1360
RETURN	DELA1370
END	DELA1380

C		INTG0010
C	*****	INTG0020
C	*	INTG0030
C	* INTGRL- TRAPIZOIDAL INTEGRATION ROUTINE	INTG0040
C	*	INTG0050
C	*****	INTG0060
C		INTG0070
	REAL FUNCTION INTGRL(ISUB,KUNIT,KINGRL,B,C,Y)	INTG0080
C		INTG0090
C	ISUB --- SUBROUTINE INDEX NUMBER	INTG0100
C	KUNIT -- SEQUENTIAL UNIT NUMBER (0 OR N)	INTG0110
C	KINGRL - INDEX OF THE INTGRL FUNCTION WITHIN THE SUBROUTINE	INTG0120
C	B ----- INITIAL CONDITION OF INTEGRATOR	INTG0130
C	C ----- INPUT	INTG0140
C	Y ----- OUTPUT FROM LAST TIME STEP	INTG0150
C		INTG0160
	COMMON / CURVAL / TIME , DELT , KEEP	INTG0170
	COMMON / PASSES / KONT , AEEP	INTG0180
	COMMON / NALARM / IERR	INTG0190
C		INTG0200
	DIMENSION SD(8,21,10) , PD(8,21,10)	INTG0210
C		INTG0220
C	SD AND PD ARE DIMENSIONED AS SD(X,Y,Z) , PD(X,Y,Z) WHERE:	INTG0230
C	X= TOTAL NUMBER OF INDEXED SUBROUTINES	INTG0240
C	Y= MAXIMUM NUMBER OF UNITS PLUS ONE	INTG0250
C	Z= GREATER THAN OR EQUAL TO THE GREATEST NUMBER OF	INTG0260
C	INTEGRATORS USED IN ANY SUBROUTINE	INTG0270
C		INTG0280
C	SEE FURTHER COMMENTS IN FUNCTION DELAY	INTG0290
C		INTG0300
C		INTG0310
C		INTG0320
C		INTG0330
C	*-----	INTG0340
C	* IF THIS IS AN INTEGRATOR FROM THE BOILER SUBROUTINE, CHANGE	INTG0350
C	* THE INTEGRATION INTERVAL TO 0.5 SECONDS (FOR NUMERICAL	INTG0360
C	* STABILITY)	INTG0370
C	*	INTG0380
C		INTG0390
	IF(ISUB .EQ. 5) DELT=0.5	INTG0400
	IF(ISUB.GT.8 .OR. KUNIT.GT.21 .OR. KINGRL.GT.8) GO TO 30	INTG0410

IF(ISUB .NE. 5 .AND. KEEP .EQ. 1 .AND. TIME .NE. 0.) GO TO 10	INTG0420
IF(ISUB .EQ. 5 .AND. AEEP .EQ. 1 .AND. TIME .NE. 0.) GO TO 10	INTG0430
PD(ISUB,KUNIT+1,KINGRL)=C	INTG0440
SD(ISUB,KUNIT+1,KINGRL)=Y	INTG0450
IF(TIME .EQ. 0.) GO TO 20	INTG0460
INTGRL=SD(ISUB,KUNIT+1,KINGRL)+DELT*C	INTG0470
GO TO 70	INTG0480
10 INTGRL=SD(ISUB,KUNIT+1,KINGRL)+.5*DELT*(PD(ISUB,KUNIT+1,KINGRL)+C)	INTG0490
GO TO 70	INTG0500
20 SD(ISUB,KUNIT+1,KINGRL)=B	INTG0510
INTGRL=SD(ISUB,KUNIT+1,KINGRL)	INTG0520
GO TO 70	INTG0530
30 WRITE(6,40)	INTG0540
WRITE(6,50) ISUB,KUNIT,KINGRL	INTG0550
40 FORMAT('O AN INTEGRATOR INDEX HAS EXCEEDED A MAXIMUM. USER	INTG0560
IMUST INCREASE THE DIMENSION OF PD(8,21,10) AND SD(8,21,10)')	INTG0570
50 FORMAT(' THE ATTEMPTED INDICES WERE: ISUB=',I5,' KUNIT=',	INTG0580
I15,' KINGRL=',I5/)	INTG0590
GO TO 60	INTG0600
60 IERR=1	INTG0610
70 CONTINUE	INTG0620
C	INTG0630
C *-----	INTG0640
C * BE SURE DELT IS AT ITS ORIGINAL VALUE BEFORE RETURNING	INTG0650
C *	INTG0660
C	INTG0670
DELT=1.0	INTG0680
RETURN	INTG0690
END	INTG0700

C		LIMI0010
C	*****	LIMI0020
C	*	LIMI0030
C	LIMIT --- LIMITER FUNCTION	LIMI0040
C	*	LIMI0050
C	*****	LIMI0060
C		LIMI0070
	REAL FUNCTION LIMIT(P1, P2, X)	LIMI0080
C		LIMI0090
	LIMIT = X	LIMI0100
	IF(X .LT. P1) LIMIT=P1	LIMI0110
	IF(X .GT. P2) LIMIT = P2	LIMI0120
	RETURN	LIMI0130
	END	LIMI0140

C		NOIS0010
C	*****	NOIS0020
C	*	NOIS0030
C	* NOISE --- NOISE GENERATOR	NOIS0040
C	*	NOIS0050
C	*****	NOIS0060
C		NOIS0070
	REAL FUNCTION NOISE(P1, P2, P3)	NOIS0080
C		NOIS0090
	INTEGER*4 P1	NOIS0100
C		NOIS0110
C	A NORMAL GAUSSIAN DISTRIBUTION AROUND THE MEAN 'P2' WITH STANDARD	NOIS0120
C	DEVIATION 'P3'. 'P1' IS ANY ODD INTEGER (SEED)	NOIS0130
C		NOIS0140
	IY=P1*65539	NOIS0150
	IF(IY .LT. 0) IY=IY+2147483647+1	NOIS0160
	P1=IY	NOIS0170
	UNZRP1=IY*0.4656613E-09	NOIS0180
	NOISE=P3*SQRT(-2.0*ALOG (UNZRP1))*COS(UNZRP1*6.283185)+P2	NOIS0190
	RETURN	NOIS0200
	END	NOIS0210

C *****	SINE0010
C *	SINE0020
C * SINE --- SINUSOIDAL GENERATOR	SINE0030
C *	SINE0040
C *****	SINE0050
C	SINE0060
FUNCTION SINE(P1,P2,P3)	SINE0070
C	SINE0080
COMMON / CURVAL / TIME , DELT	SINE0090
C	SINE0100
P1 INITIATION TIME OF WAVE IN SECONDS	SINE0110
C	SINE0120
P2 FREQUENCY OF WAVE IN RADIANS PER SECOND	SINE0130
C	SINE0140
P3 PHASE SHIFT OF WAVE IN RADIANS	SINE0150
C	SINE0160
IF P1<T , Y=0	SINE0170
C	SINE0180
IF P1>T , Y=SIN(P2*(T-P1)+P3)	SINE0190
C	SINE0200
X=TIME-P1	SINE0210
IF(X+0.5*DELT .GE. 0.0) GO TO 10	SINE0220
SINE=0.0	SINE0230
RETURN	SINE0240
10 SINE=SIN(P2*X+P3)	
RETURN	
END	

C	-----	PLOT0010
C	*	* PLOT0020
C	* SUBROUTINE PLOT	* PLOT0030
C	*	* PLOT0040
C	-----	PLOT0050
	SUBROUTINE PLOT	PLOT0060
C	COMMON / PLOTT / XOUT(15) , AMAX(15) , AMIN(15) ,	PLOT0070
	1 POINT(15) , INT , ITIC , NPLVAR, ACR ,	PLOT0080
	2 UP , BLANK , PLUS , BPP(60) ,	PLOT0090
	3 D(1,60) , APP(5), NWRITE	PLOT0100
		PLOT0110
C		PLOT0120
C		PLOT0130
C		PLOT0140
C	THE MAXIMUM NUMBER OF VARIABLES THAT CAN BE PLOTTED IS 14.	PLOT0150
C		PLOT0160
C	INT IS THE PLOT INTERVAL DESIRED IN SECONDS	PLOT0170
C		PLOT0180
C	ITIC IS THE TIME TIC MARK IN SECONDS	PLOT0190
C		PLOT0200
C	NPLVAR IS THE TOTAL NUMBER OF VARIABLES TO BE PLOTTED.	PLOT0210
C		PLOT0220
C		PLOT0230
C		PLOT0240
	REWIND 11	PLOT0250
	NCOUNT=NPLVAR+1	PLOT0260
	READ(11) (XOUT(I),I=1,NCOUNT)	PLOT0270
	NREAD=NWRITE-1	PLOT0280
	TIME=XOUT(1)	PLOT0290
	DO 20 IT=1,22	PLOT0300
	WRITE(6,10) BLANK	PLOT0310
10	FORMAT(23A1)	PLOT0320
20	CONTINUE	PLOT0330
30	LINCHK=NCOUNT+1	PLOT0340
	ICALC=0	PLOT0350
	JAN=1	PLOT0360
	DO 60 L=2,NCOUNT	PLOT0370
	DO 40 K=10,50,10	PLOT0380
	I=K/10	PLOT0390
	PP=K	PLOT0400
	IF(K .EQ.K/10*10) APP(1)=AMIN(L)+PP/(60./(ABS(AMAX(L)-AMIN(L))))	PLOT0410

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40 CONTINUE
   WRITE(6,50) POINT(L),(APP(I),I=1,5,2)
50 FORMAT(1X,A4,1X,3(F10.3,10X))
60 CONTINUE
   DO 70 K=1,60
     BPP(K)=ACR
     IF(K.EQ. K/10*10) BPP(K)=UP
70 CONTINUE
   START=UP
   WRITE(6,80)START, (BPP(I),I=1,60)
80 FORMAT(2X,61A1)
90 CONTINUE
   IF(LINCHK.EQ. 24) GO TO 30
   DO 100 J=1,60
100 D(1,J)=BLANK
     D(1,60)=UP
     ITIME=TIME
     ATIME=ITIME
     IF(ATIME-TIME.NE. 0.) ICALC=1
     IF(ITIME.NE. ITIME/ITIC*ITIC) GO TO 120
     DO 110 J=10,50,10
110 D(1,J)=PLUS
120 CONTINUE
     START=UP
     DO 130 J=2,NCCUNT
       A=(XOUT(J)-AMIN(J))*{60./(ABS(AMAX(J)-AMIN(J)))}
       L=A
       DIF=A-FLOAT(L)
       IF(DIF.GE. .51) L=L+1
       IF(L.LT. 1) START=POINT(J)
       IF(L.LT. 1) GO TO 130
       IF(L.GT. 60) L=60
       D(1,L)=POINT(J)
130 CONTINUE
       IF(ICALC.EQ. 1) GO TO 140
       IF(ITIME.EQ. ITIME/ITIC*ITIC) GO TO 170
       GO TO 150
140 IF(JAN.EQ. JAN/ITIC*ITIC) GO TO 170
150 WRITE(6,160) START,(D(1,J),J=1,60)
160 FORMAT(2X,61A1)

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PLOT0420
PLOT0430
PLOT0440
PLOT0450
PLOT0460
PLOT0470
PLOT0480
PLOT0490
PLOT0500
PLOT0510
PLOT0520
PLOT0530
PLOT0540
PLOT0550
PLOT0560
PLOT0570
PLOT0580
PLOT0590
PLOT0600
PLOT0610
PLOT0620
PLOT0630
PLOT0640
PLOT0650
PLOT0660
PLOT0670
PLOT0680
PLOT0690
PLOT0700
PLOT0710
PLOT0720
PLOT0730
PLOT0740
PLOT0750
PLOT0760
PLOT0770
PLOT0780
PLOT0790
PLOT0800
PLOT0810

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      GO TO 190
170  WRITE(6,180) START,(D(1,J),J=1,60),TIME
180  FORMAT(2X,61A1,2X,F8.2)
      JAN=JAN+1
190  CONTINUE
      LINCHK=LINCHK+1
      DO 200 J=1,INT
      IF (NREAD .EQ. 0) GO TO 210
200  READ(11) (XOUT(I),I=1,NCOUNT)
      NREAD=NREAD-1
      TIME=XOUT(1)
      GO TO 90
210  RETURN
      END

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PLOT0820
PLOT0830
PLOT0840
PLOT0850
PLOT0860
PLOT0870
PLOT0880
PLOT0890
PLOT0900
PLOT0910
PLOT0920
PLOT0930
PLOT0940
PLOT0950

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C	-----	PRIN0010
C	*	PRIN0020
C	* PRINT- A SUBROUTINE THAT SPECIFIES OUTPUT	PRIN0030
C	*	PRIN0040
C	-----	PRIN0050
C		PRIN0060
C	SUBROUTINE PRINT(SYM1, VAL1, SYM2, VAL2, SYM3, VAL3,	PRIN0070
	1 SYM4, VAL4, SYM5, VAL5, SYM6, VAL6)	PRIN0080
C		PRIN0090
	REAL*4 BLANKS/ ' ', VALUE(44)	PRIN0100
	REAL*8 SYMBOL(44) , SYM , SYM1 , SYM2 , SYM3 , SYM4 ,	PRIN0110
	1 SYM5 , SYM6	PRIN0120
C		PRIN0130
	EQUIVALENCE (FIRST4,SYM)	PRIN0140
C		PRIN0150
	COMMON / CURVAL / TIME , DELT	PRIN0160
	COMMON / PRICNL / ICDUNT, TLAST , SYM30L, VALUE , LINES , IPAGES	PRIN0170
C		PRIN0180
C		PRIN0190
C		PRIN0200
C	*-----	PRIN0210
C	* RESET THE COUNTER IF TIME HAS CHANGED	PRIN0220
C	*	PRIN0230
C		PRIN0240
	IF(TIME .EQ. TLAST) GO TO 10	PRIN0250
	ICDUNT = 0	PRIN0260
	TLAST = TIME	PRIN0270
	10 CONTINUE	PRIN0280
C		PRIN0290
C	*-----	PRIN0300
C	* NOW START SAVING THE SYMBOLS AND VALUES	PRIN0310
C	*	PRIN0320
C		PRIN0330
	SYM = SYM1	PRIN0340
	VAL = VAL1	PRIN0350
	DO 70 I = 1, 6	PRIN0360
C		PRIN0370
C	*-----	PRIN0380
C	* GO AWAY IF THERE IS A BLANK SYMBOL PASSED OR IF THE ARRAY IS FULL.	PRIN0390
C	*	PRIN0400
C		PRIN0410

	IF(FIRST4 .EQ. BLANKS .OR. ICDUNT .GT. 44) GO TO 80	PRIN0420
C		PRIN0430
C	*-----	PRIN0440
C	* DUMP THE SYMBOLS AND VALUES INTO THE APPROPRIATE SPOTS IN THE	PRIN0450
C	* TABLES	PRIN0460
C	*	PRIN0470
C		PRIN0480
	ICDUNT = ICDUNT + 1	PRIN0490
	SYMBOL(ICDUNT) = SYM	PRIN0500
	VALUE(ICDUNT) = VAL	PRIN0510
	GO TO (20, 30, 40, 50, 60, 70), I	PRIN0520
20	SYM = SYM2	PRIN0530
	VAL = VAL2	PRIN0540
	GO TO 70	PRIN0550
30	SYM = SYM3	PRIN0560
	VAL = VAL3	PRIN0570
	GO TO 70	PRIN0580
40	SYM = SYM4	PRIN0590
	VAL = VAL4	PRIN0600
	GO TO 70	PRIN0610
50	SYM = SYM5	PRIN0620
	VAL = VAL5	PRIN0630
	GO TO 70	PRIN0640
60	SYM = SYM6	PRIN0650
	VAL = VAL6	PRIN0660
70	CONTINUE	PRIN0670
80	RETURN	PRIN0680
	END	PRIN0690

C	-----	PLOT0010
C *		* PLOT0020
C *	PLOTMD- A SUBROUTINE THAT MODIFIES PLOT SCALES	* PLOT0030
C *		* PLOT0040
C	-----	PLOT0050
C		PLOT0060
	SUBROUTINE PLOTMD	PLOT0070
C		PLOT0080
	COMMON / PLOT / XOUT(15) , AMAX(15) , AMIN(15) ,	PLOT0090
1	POINT(15) , INT , ITIC , NPLVAR, ACR ,	PLOT0100
2	UP , BLANK , PLUS	PLOT0110
C		PLOT0120
	DIMENSION PID(14)	PLOT0130
C		PLOT0140
C		PLOT0150
C		PLOT0160
	WRITE(6,10) BLANK	PLOT0170
10	FORMAT(2A1)	PLOT0180
	WRITE(6,20)	PLOT0190
20	FORMAT(' CLEAR SCREEN AND HIT ENTER TO START PLOT CHANGES')	PLOT0200
	READ(5,30) DUMM3	PLOT0210
30	FORMAT(1A5)	PLOT0220
	WRITE(6,40)	PLOT0230
40	FORMAT(' THE PLOT SCALES USED ARE SHOWN BELOW')	PLOT0240
	WRITE(6,50)	PLOT0250
50	FORMAT(' VARIABLE MINIMUM MAXIMUM')	PLOT0260
	L=NPLVAR+1	PLOT0270
	DO 70 N=2,L	PLOT0280
	WRITE(6,60) POINT(N),AMIN(N),AMAX(N)	PLOT0290
60	FORMAT(5X,A1,5X,F10.3,3X,F10.3)	PLOT0300
70	CONTINUE	PLOT0310
	WRITE(6,80)	PLOT0320
80	FORMAT(' AFTER EACH PROMPT ENTER A PLOT SYMBOL WHOSE SCALE YOU WIS	PLOT0330
	IN TO CHANGE. ENTER A BLANK WHEN DONE.')	PLOT0340
	LINCHK=5+NPLVAR	PLOT0350
	DO 150 N=1,NPLVAR	PLOT0360
	WRITE(6,90)	PLOT0370
90	FORMAT(' ?')	PLOT0380
	READ(5,100) PID(N)	PLOT0390
100	FORMAT(A1)	PLOT0400
	LINCHK=LINCHK+2	PLOT0410

IF(LINCHK .LE. 21) GO TO 140	PLOT0420
IF(LINCHK .EQ. 22) WRITE(6,100) BLANK	PLOT0430
WRITE(6,100) BLANK	PLOT0440
CONTINUE	PLOT0450
IF(PID(N) .EQ. BLANK) GO TO 160	PLOT0460
WRITE(6,50)	PLOT0470
LINCHK=2+NPLVAR	PLOT0480
L=NPLVAR+1	PLOT0490
DO 130 I=2,L	PLOT0500
DO 110 J=1,NPLVAR	PLOT0510
IF(PID(J) .EQ. POINT(I)) GO TO 120	PLOT0520
110 CONTINUE	PLOT0530
WRITE(6,60) POINT(I),AMIN(I),AMAX(I)	PLOT0540
GO TO 130	PLOT0550
120 LINCHK=LINCHK-1	PLOT0560
130 CONTINUE	PLOT0570
140 IF(PID(N) .EQ. BLANK) GO TO 160	PLOT0580
150 CONTINUE	PLOT0590
160 IF(PID(1) .EQ. BLANK) GO TO 320	PLOT0600
IF (LINCHK .GE. 23) GO TO 180	PLOT0610
M=24-LINCHK	PLOT0620
DO 170 I=1,M	PLOT0630
WRITE(6,100) BLANK	PLOT0640
170 CONTINUE	PLOT0650
180 WRITE(6,190)	PLOT0660
190 FORMAT(' ALONG WITH THE PLOT VARIABLES WHOSE SCALES YOU WANTED CHAP	PLOT0670
INGED, YOU WILL BE SHOWN THE PRESENT SCALE VALUES.')	PLOT0680
WRITE(6,200)	PLOT0690
200 FORMAT(' ', ' ENTER THE NEW MINIMUM AND MAXIMUM SCALE VALUES DESIRE	PLOT0700
10 AFTER EACH DISPLAY.')	PLOT0710
LINCHK=4	PLOT0720
DO 310 J=1,NPLVAR	PLOT0730
IF(PID(J) .EQ. BLANK) GO TO 320	PLOT0740
L=NPLVAR+1	PLOT0750
DO 210 N=2,L	PLOT0760
IF(PID(J) .EQ. POINT(N)) GO TO 220	PLOT0770
210 CONTINUE	PLOT0780
220 WRITE(6,100) BLANK	PLOT0790
WRITE(6,230) POINT(N),AMIN(N),AMAX(N)	PLOT0800
230 FORMAT(5X,A1,6X,' MIN=',F10.3,2X,' MAX=',F10.3/)	PLOT0810

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        WRITE(6,240) POINT(N)
240  FORMAT(' ENTER NEW MINIMUM FOR ',A1/)
        READ(5,260) AMIN(N)
        WRITE(6,250) POINT(N)
250  FORMAT(' ENTER NEW MAXIMUM FOR ',A1/)
        READ(5,260) AMAX(N)
260  FORMAT(F10.3)
        LINCHK=LINCHK+9
        IF(LINCHK .EQ. 22) GO TO 270
        IF(LINCHK .EQ. 23) GO TO 280
        IF(LINCHK .EQ. 24) GO TO 290
        GO TO 310
270  WRITE(6,100) BLANK
280  WRITE(6,100) BLANK
290  LINCHK=4
        WRITE(6,300) BLANK
300  FORMAT(4A1)

310  CONTINUE
320  RETURN
      END

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PLOT0820
PLOT0830
PLOT0840
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PLOT0890
PLOT0900
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PLOT0960
PLOT0970
PLOT0980
PLOT0990
PLOT1000
PLOT1010

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OUTPUT	C	-----	OUTP0010
	C	*	OUTP0020
	C	* OUTPUT- A SUBROUTINE THAT PRINTS THE OUTPUT	* OUTP0030
	C	*	* OUTP0040
	C	-----	OUTP0050
	C		OUTP0060
		SUBROUTINE OUTPUT	OUTP0070
	C		OUTP0080
		REAL*4 VALUE(44)	OUTP0090
		REAL*8 SYMBOL(44)	OUTP0100
	C		OUTP0110
		COMMON / CURVAL / TIME , DELT	OUTP0120
		COMMON / PRTCNL / ICOUNT, TLAST , SYMBOL, VALUE , LINES , IPAGES	OUTP0130
	C		OUTP0140
	C		OUTP0150
	C		OUTP0160
		LINCHK=LINES	OUTP0170
		IF(IPAGES .EQ. 1) LINCHK=LINES+1	OUTP0180
		IPAGES=IPAGES+1	OUTP0190
	10	LINES=LINCHK+(ICOUNT+1)/2+1	OUTP0200
		IF(LINES .GE. 24) GO TO 30	OUTP0210
		WRITE(6,20) TIME, (SYMBOL(I), VALUE(I), I = 1 , ICOUNT)	OUTP0220
	20	FORMAT(' TIME = ', E12.4, 2(4X, A8, '= ', E12.4), /;	OUTP0230
	1	22(25X, A8, '= ', E12.4, 4X, A8, '= ', E12.4, /), //)	OUTP0240
		RETURN	OUTP0250
	30	IF(LINCHK .GE. 23) GO TO 60	OUTP0260
		M=23-LINCHK	OUTP0270
		DO 50 I=1,M	OUTP0280
		WRITE(6,40)	OUTP0290
	40	FORMAT(' ')	OUTP0300
	50	CONTINUE	OUTP0310
	60	LINES=0	OUTP0320
		LINCHK=0	OUTP0330
		GO TO 10	OUTP0340
		END	OUTP0350

TIME = 0.0	LOAD = 0.5324E 04	PMSYS = 0.5324E 04	LODEXT = 0.5007E 05	PMEXT = 0.5005E 05
	PACCEL = -0.6965E 02	FREQHZ = 0.6000E 02	PTINET = 0.7180E 01	ACEEXT = -0.7180E 01
	SKDTI = 0.0	ACE = 0.7180E 01	AR = 0.1077E 01	LAM = 0.2500E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1620E 04	PM(3) = 0.3300E 03	PM(4) = 0.5000E 03
	PM(5) = 0.1750E 03	PM(6) = 0.5380E 03	PM(7) = 0.3100E 03	PM(8) = 0.3010E 03
TIME = 0.1000E 02	LOAD = 0.5329E 04	PMSYS = 0.5340E 04	LODEXT = 0.5007E 05	PMEXT = 0.5008E 05
	PACCEL = 0.1712E 02	FREQHZ = 0.6000E 02	PTINET = 0.9336E 01	ACEEXT = -0.2621E 02
	SKDTI = 0.0	ACE = 0.5219E 01	AR = 0.9283E 00	LAM = 0.2500E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1620E 04	PM(3) = 0.3301E 03	PM(4) = 0.5000E 03
	PM(5) = 0.1753E 03	PM(6) = 0.5381E 03	PM(7) = 0.3170E 03	PM(8) = 0.3094E 03
TIME = 0.2000E 02	LOAD = 0.5335E 04	PMSYS = 0.5352E 04	LODEXT = 0.5007E 05	PMEXT = 0.5005E 05
	PACCEL = -0.3438E 00	FREQHZ = 0.6001E 02	PTINET = 0.1743E 02	ACEEXT = 0.5406E 02
	SKDTI = 0.0	ACE = 0.2300E 02	AR = 0.1543E 02	LAM = 0.2497E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1620E 04	PM(3) = 0.3294E 03	PM(4) = 0.5000E 03
	PM(5) = 0.1754E 03	PM(6) = 0.5375E 03	PM(7) = 0.3229E 03	PM(8) = 0.3168E 03
TIME = 0.3000E 02	LOAD = 0.5329E 04	PMSYS = 0.5368E 04	LODEXT = 0.5007E 05	PMEXT = 0.5003E 05
	PACCEL = 0.2375E 01	FREQHZ = 0.6001E 02	PTINET = 0.3851E 02	ACEEXT = 0.3298E 02
	SKDTI = 0.0	ACE = 0.4100E 02	AR = 0.2995E 02	LAM = 0.2493E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1619E 04	PM(3) = 0.3285E 03	PM(4) = 0.4998E 03
	PM(5) = 0.1757E 03	PM(6) = 0.5364E 03	PM(7) = 0.3313E 03	PM(8) = 0.3269E 03
TIME = 0.4000E 02	LOAD = 0.5326E 04	PMSYS = 0.5383E 04	LODEXT = 0.5007E 05	PMEXT = 0.5001E 05
	PACCEL = 0.1926E 01	FREQHZ = 0.6001E 02	PTINET = 0.5629E 02	ACEEXT = 0.2023E 02
	SKDTI = 0.0	ACE = 0.6014E 02	AR = 0.4900E 02	LAM = 0.2488E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1619E 04	PM(3) = 0.3275E 03	PM(4) = 0.4996E 03
	PM(5) = 0.1759E 03	PM(6) = 0.5348E 03	PM(7) = 0.3395E 03	PM(8) = 0.3367E 03
TIME = 0.5000E 02	LOAD = 0.5326E 04	PMSYS = 0.5397E 04	LODEXT = 0.5007E 05	PMEXT = 0.5000E 05
	PACCEL = 0.1980E 01	FREQHZ = 0.6001E 02	PTINET = 0.7069E 02	ACEEXT = 0.1087E 02
	SKDTI = 0.0	ACE = 0.7612E 02	AR = 0.6730E 02	LAM = 0.2481E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1618E 04	PM(3) = 0.3264E 03	PM(4) = 0.4994E 03
	PM(5) = 0.1760E 03	PM(6) = 0.5329E 03	PM(7) = 0.3477E 03	PM(8) = 0.3466E 03
TIME = 0.6000E 02	LOAD = 0.5324E 04	PMSYS = 0.5411E 04	LODEXT = 0.5007E 05	PMEXT = 0.4999E 05
	PACCEL = 0.4422E 01	FREQHZ = 0.6001E 02	PTINET = 0.8701E 02	ACEEXT = 0.1112E 02
	SKDTI = 0.0	ACE = 0.9280E 02	AR = 0.7500E 02	LAM = 0.2475E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1618E 04	PM(3) = 0.3253E 03	PM(4) = 0.4991E 03
	PM(5) = 0.1760E 03	PM(6) = 0.5311E 03	PM(7) = 0.3557E 03	PM(8) = 0.3563E 03
TIME = 0.7000E 02	LOAD = 0.5324E 04	PMSYS = 0.5425E 04	LODEXT = 0.5007E 05	PMEXT = 0.4997E 05
	PACCEL = 0.4219E 01	FREQHZ = 0.6001E 02	PTINET = 0.1006E 03	ACEEXT = 0.9767E 01
	SKDTI = 0.0	ACE = 0.1080E 03	AR = 0.7500E 02	LAM = 0.2469E 02
	PM(1) = 0.1550E 04	PM(2) = 0.1616E 04	PM(3) = 0.3241E 03	PM(4) = 0.4986E 03
	PM(5) = 0.1760E 03	PM(6) = 0.5299E 03	PM(7) = 0.3638E 03	PM(8) = 0.3660E 03
TIME = 0.8000E 02	LOAD = 0.5329E 04	PMSYS = 0.5438E 04	LODEXT = 0.5007E 05	PMEXT = 0.4996E 05
	PACCEL = -0.1785E 01	FREQHZ = 0.6001E 02	PTINET = 0.1090E 03	ACEEXT = 0.7496E 01
	SKDTI = 0.0	ACE = 0.1202E 03	AR = 0.7500E 02	LAM = 0.2464E 02
	PM(1) = 0.1549E 04	PM(2) = 0.1615E 04	PM(3) = 0.3229E 03	PM(4) = 0.4980E 03
	PM(5) = 0.1759E 03	PM(6) = 0.5289E 03	PM(7) = 0.3717E 03	PM(8) = 0.3756E 03

A	-400.000	-300.000	-200.000	-100.000	0.0	100.000	200.000	300.000	400.000
M	4200.000	4400.000	4600.000	4800.000	5000.000	5200.000	5400.000	5600.000	5800.000
X	49600.000	49700.000	49800.000	49900.000	50000.000	50100.000	50200.000	50300.000	50400.000
F	59.920	59.940	59.960	59.980	60.000	60.020	60.040	60.060	60.080
T	-40.000	20.000	80.000	140.000	200.000	260.000	320.000	380.000	440.000
L	5230.000	5260.000	5290.000	5320.000	5350.000	5380.000	5410.000	5440.000	5470.000
R	-80.000	-60.000	-40.000	-20.000	0.0	20.000	40.000	60.000	80.000

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