

270
11/10/79
HCP/MS-4209

DR. 2092

MASTER

Electric/Hybrid Vehicle Simulation Program (ELVEC) User's Manual

July 1978

Prepared for:
U.S. Department of Energy
Assistant Secretary for Conservation
and Solar Applications
Division of Transportation Energy Conservation

Under Interagency Agreement EM-78-I-01-4209

Electric/Hybrid Vehicle Simulation Program (ELVEC) User's Manual

July 1978

Prepared by:
Jet Propulsion Laboratory
Pasadena, California

Prepared for:
U.S. Department of Energy
Assistant Secretary for Conservation
and Solar Applications
Division of Transportation Energy Conservation
Washington, D.C. 20545

Under Interagency Agreement EM-78-I-01-4209

NOTICE
This report was prepared as an account of work sponsored by the United States Government. Neither the United States nor the United States Department of Energy, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness or usefulness of any information, apparatus, product or process disclosed, or represents that its use would not infringe privately owned rights.

NOTICE

This report was prepared as an account of work sponsored by the United States Government. Neither the United States nor the United States Department of Energy, nor any of their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, mark, manufacturer, or otherwise, does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.

DISCLAIMER

This report was prepared as an account of work sponsored by an agency of the United States Government. Neither the United States Government nor any agency thereof, nor any of their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.

DISCLAIMER

Portions of this document may be illegible in electronic image products. Images are produced from the best available original document.

ACKNOWLEDGMENT

I wish to thank General Research Corporation of Santa Barbara, and in particular, John Brenmand (the creator of this simulator) for his hard work and long hours in making this version of ELVEC a reality. Special appreciation must be extended to the Jet Propulsion Laboratory Vehicle Systems Modeling Task Area Team for their work in putting ELVEC on the JPL 1108 computer and in the preparation of this document. In particular, I wish to thank Ron Slusser who helped write this manual and who generated the program used to produce the heat engine tables and maps in Appendix C. Special thanks must be extended to Jose Miranda of JPL and Jim Baltes of General Research Corporation for solving the problems of working on three computer systems of completely different architecture (IBM, Control Data, Univac). And last, my special thanks to Larry Mak and Ray Vaughn of the JPL Documentation Section who prepared this document for publication.

Phil Chapman
June 1978



FOREWORD

The User's Manual provides the user with enough information to allow him to use the program which resides on National CSS Timeshare. Detailed information is conveyed by the use of several simulation examples and an explanation of the results of these examples (on a line-by-line basis) as required.

Except for a brief description of the road load equations, this User's Manual does not include descriptions of the math models.

A complete report of the ELVEC simulator is being prepared by the Vehicle Systems Modeling Task Area Team of the Electric and Hybrid Vehicle System Research and Development Project at the Jet Propulsion Laboratory. This report should be available to those wishing a complete program description by October, 1978. However, it is not necessary to possess this information in order to conduct electric and hybrid vehicle performance simulations using ELVEC. Flow charts and source listings are available for those wishing to review the coding. This information should be requested through T.A. Barber, Project Manager, Electric and Hybrid Vehicle System Research and Development Project, Jet Propulsion Laboratory, 4800 Oak Grove Drive, Pasadena, CA 91103.



CONTENTS

I.	PROGRAM ACCESS	1-1
A.	GENERAL	1-1
B.	USING THE NCSS TIMESHARE NETWORK	1-1
C.	TIMESHARE ARRANGEMENTS AND COSTS	1-2
D.	GENERAL TYPING CONVENTIONS	1-2
E.	TIMESHARE SIGN-ON	1-3
F.	ESCAPE FROM AN EXECUTING PROGRAM	1-3
G.	NORMAL EXIT	1-4
II.	SIMULATION EXAMPLES	2-1
A.	GENERAL	2-1
B.	EXAMPLE 1. DRIVING CYCLE SIMULATION, ALL-ELECTRIC	2-1
C.	EXAMPLE 2. DETAIL OUTPUT	2-3
D.	EXAMPLE 3. ALL-ELECTRIC CONSTANT SPEED	2-3
E.	EXAMPLE 4. FXOP HYBRID CONFIGURATION	2-4
F.	EXAMPLE 5. CBTOUT HYBRID CONFIGURATION	2-6
G.	EXAMPLE 6. FORDB HYBRID CONFIGURATION	2-9
H.	EXAMPLE 7. ALL-HEAT ENGINE VEHICLE	2-11
I.	EXAMPLE 8. MAXIMUM ACCELERATION AND PASSING	2-11

APPENDICES

A.	PROGRAM VARIABLE DICTIONARY	A-1
B.	OUTPUT VARIABLES DESCRIPTION	B-1
C.	DATA STORED FOR HEAT ENGINES	C-1
D.	ROAD LOAD MODEL	D-1
E.	PHONE LIST	E-1

TABLES

1-1	Terminal Speed and Designator	1-2
2-1	FXOP Special User-Defined Variables	2-5
2-2	CBTOUT Special User-Defined Variables	2-7
2-3	FORDB Special User-Defined Variables	2-10
2-4	Wide-Open Throttle and Passing - Special User Defined Variables	2-12
A-1	Vehicle-Unique Parameters	A-4

B-1	Definition of Variables	B-6
C-1	Heat Engine Map Choices	C-3
C-2	Tabulation of Heat Engine Data	C-4
C-3	Kathe - The Heat Engine Catalog	C-5

ILLUSTRATIONS

1-1	Accessing the Network	1-5
2-1	Driving Cycle Simulation, All Electric	2-13
2-2	Detail Output, Driving Cycle Simulation, All Electric	2-14
2-3	Constant Speed Simulation, All Electric	2-16
2-4	FXOP Series Hybrid Configuration	2-17
2-5A	FXOP Series Hybrid Simulation, J227D	2-18
2-5B	FXOP Series Hybrid Simulation, J227D	2-19
2-5C	FXOP Series Hybrid Simulation, J227D	2-20
2-5D	FXOP Series Hybrid Simulation, J227B, BTSMIN = 0.999.	2-21
2-5E	FXOP Series Hybrid Simulation, J227B, BTSMIN = 0.999.	2-22
2-5F	FXOP Series Hybrid Simulation, J227B, BTSMIN = 0.999.	2-23
2-5G	FXOP Series Hybrid Simulation, 35 mph Constant Speed	2-24
2-5H	FXOP Series Hybrid Simulation, 35 mph Constant Speed	2-25
2-6	CBTOUT and FORDB Parallel Hybrid Configurations	2-26
2-7	CBTOUT Hybrid Strategy	2-27
2-8	FORDB Hybrid Strategy, J227D, Detail during 10th Cycle	2-34
2-9	All Heat Engine Example, J227D	2-38
2-10A	Variable Selection for Wide Open Throttle, PDMAX = 0	2-40
2-10B	All Heat Engine Wide Open Throttle	2-41
2-10C	Passing-Time and Distance - All Heat Engine	2-42
2-10D	Passing Time and Distance - Hybrid Mode	2-43
2-10E	Zero to 30 mph Hybrid Mode	2-44
2-10F	Zero to 30 mph, Heat Engine Only	2-45
A1	Variable Dictionary	A-5
A-2	Output from "List"	A-10
B-1	Output Variable Definitions	B-7
C-1	Output from "Helist"	C-6
C-2	Engine: Honda CVCC	C-7

C-3	Engine Map, Briggs & Stratton - BS400	C-8
C-4	Engine Map, Onan - ON782	C-10
C-5	Engine Map, General Motors - GM5735	C-12
C-6	Engine Map, Honda - HN1600	C-14
C-7	Engine Map, General Motors - GMVEGA140	C-16
C-8	Engine Map, Triumph, TR7	C-18
C-9	Engine Map, Volkswagen - TURBODSL	C-20
C-10	Engine Map, Volkswagen - NADSL	C-22
C-11	Engine Map, British Leyland Rover - IDIDSL	C-24
C-12	Engine Map, Curtis Wright - CWSTRATROT	C-26
C-13	Engine Map, NSU/AUDI - NSUAUDIROT	C-28

SECTION I

PROGRAM ACCESS

A. GENERAL

ELVEC is a general-purpose electric and hybrid vehicle simulation program which resides on the NCSS Timeshare system. As such, it can be accessed by a local call in most major U.S. cities. ELVEC was designed as a tool for detailed parametric studies of electric and hybrid vehicles. The simulator can be used interactively and can guide the user in a manner which requires only an elementary knowledge of computer simulation programs. This simulator can also be used in the batch mode, although not easily on the Timeshare network.

The reader will find simulation examples in Section II; Variable Dictionary List, Appendix A; Output Variables Description, Appendix B; Data Stored for Heat Engines, Appendix C; Road Load Model, Appendix D; NCSS Timeshare Phone List, Appendix E.

The remainder of this section provides the user with the information and procedures required to access the simulator.

B. USING THE NCSS TIMESHARE NETWORK

To access the network, the user needs to know:

- 1) The NCSS local telephone number
- 2) His demand terminal speed
- 3) The NCSS computer hostname
- 4) A user ID
- 5) A user password

Appendix E is a nationwide listing of phone numbers the user may use, depending on his geographical location. For example, from the Los Angeles area, the user dials 277-7942 (a Century City phone number), although the computer used is located in Sunnyvale, CA.

Demand terminals normally operate at the speeds indicated in Table 1-1. After dialing the phone number, obtaining the high frequency tone, and placing the telephone handset in the acoustic coupler, the user types the keyboard character that designates the speed of the terminal and the "return" key. The correct keyboard character is indicated next to the speed in Table 1-1. See Appendix E for autospeed and fixed speed phone numbers.

C. TIMESHARE ARRANGEMENTS AND COSTS

Information regarding the use of the Timeshare network can be obtained by writing or phoning the corporate headquarters of:

National CSS, Inc.
 187 Danbury Drive
 Wilton, CT 06897
 (203) 853-7200

Arrangements can be made with the Department of Energy and the Jet Propulsion Laboratory to transfer the ELVEC object code to a prospective user's NCSS account. This can be accomplished in a matter of minutes, after the user has arranged for an account on the network. Typical costs, including connect charges, storage charges, fixed charges, and actual CPU charges should not exceed 67 dollars an hour. Approximately 15 to 20 simulations can be performed in an hour's time.

D. GENERAL TYPING CONVENTIONS

Each input line must end with a carriage return, which allows the current line to be transmitted. When the line has been accepted by

Table 1-1. Terminal Speed and Designator

Speed		Designator
Character/sec	Baud Rate	
10	110	S (Letter)
30	300	O (Letter)
120	1200	< (Back Arrow)

the system, the input prompt ">" is printed, indicating that the system is ready to accept further input.

To correct typographical input errors (before the carriage return), use either the character-delete symbol "@" or the line-delete symbol "[". A "@" deletes the preceding character in the input line plus itself. Five consecutive @'s (@@@@@) delete the five characters immediately preceding the @'s and the @'s themselves. A "[" deletes the entire current input line and itself.

E. TIMESHARE SIGN-ON

System and user responses are indicated in Figure 1-1. A line-by-line description is given below: (Note that user response is shown in lower case letters in all examples.)

The user types the letter 0, designating a 300-Baud (30 characters per second) terminal, then types a return. The system responds as indicated on line 2. The user types line 3, where L SUNY is the computer hostname. The particular computer on which ELVEC is resident is located in Sunnyvale, CA. GRCUSER is the user identification (USER ID). The system prints lines 4 and 5. At the end of line 5, the system does a carriage return, but no line feed. This allows the user to type the password on top of line 5. This is done to prevent non-authorized personnel from determining the password should they obtain a copy of the output. The system asks for accounting information on line 6. The user types the initial letter of his first name and his last name in full.

F. ESCAPE FROM AN EXECUTING PROGRAM

If, for some reason, the user desires to terminate execution of the program before the appropriate place to type QUIT, he can use the method outlined below:

- 1) Push the BREAK key - machine will echo VP, return, > (prompt)
- 2) Push the BREAK key again - machine will echo another >

- 3) Type KX following the prompt - machine will type KILLED! and then reinitialize the system. Then it will type the standard CSS prompt with the time, XX.XX.XX >
- 4) The user can then restart the program or log off.

If the user inadvertently pushes the BREAK key, the machine will stop execution and enter the VP mode as above. To restart the program with only a line or so of output lost, follow the above procedure, only type RT instead of KX.

G. NORMAL EXIT

To exit from ELVEC after a simulation run, type QUIT or STOP. To exit from the timeshare network after a normal exit from ELVEC, type LOGOUT.

```

1  o
2  CSS ONLINE - LA2
3  >I suny grcuser
4  password:
5  #####
6  A/C INFO:
7  >p.chapman
   SUNY READY AT 09.09.54 ON 23JUNE78.
   CSS.302 01MAY78
   09.10.07 SET CORE 440
   CSS.302 01MAY78
   09.10.10 SET CORE 440
   ( 448 )P 58% (000313 LEFT)

   ELVEC CAN ACCESS A NUMBER OF SETS OF VEHICLE PARAMETERS. TO USE
   ONE OF THESE, TYPE THE KEYWORD BEFORE THE VEHICLE NAME:

   ELVRIPP ... RIPP ELECTRIC (ALL ELECTRIC)
   ELVGE .... GENERAL ELECTRIC VEHICLE (ALL ELECTRIC)
   ELVAIR ... GARRETT/AIRESEARCH VEHICLE (ELECTRIC - FLYWHEEL)
   ELVCHLD ... CHILD'S VAN (FIXED OPERATING POINT HYBRID)

20 09.10.30 >elvrripp
21 EXECUTION:

   GRC ELECTRIC VEHICLE/BATTERY SIMULATION. VERSION3.2A  8/MAY/78 -

23 SPECIFY DESIRED OUTPUT UNITS - METRIC OR ENGLISH . . .
24 >e
25 INITIATING BULK READ-
   FEDERAL CYCLE. 1372 VALUES READ.
   HIWAY CYCLE. 766 VALUES READ.

28 CHANGES FOR THIS AND FOLLOWING RUNS-

29 WB=1300LB WT=3288LB ACLFAC=1.0 EFFCB=1 CDA=9.68FT2
   ATIREF=1.2 EFFBC=.85 EFFCT=.9,.9,.9,.9
31 EFFCM=0.82 EFFCD=.75 MANCYC=J227D NREGEN=2
   GEAR=3.757,2.169,1.404,1.0 RATIO=.29,3.9,1
   VELSCD=5.81,10.28,14.75 EFFCFW=0.622
35 CH=3.178,-0.7279,-0.05863
34 NCELLS=60 PWRHEN=7500. PDMAX=150. EFFALT=.75
36 END DATA
37 WARNING . . .THE VARIABLE DICTIONARY HAS BEEN CHANGED FOR THIS VERSION
38 (VERSION 3.2 10/MAR/78) OF ELVEC. A NEW DRIVING CYCLE IS AVAILABLE--
   MAXACL (MAXIMUM ACCELERATION BEGINNING AT SPEED VINIT). ALSO FOUR TYPES
   OF CLUTCHES ARE AVAILABLE--DIRECT COUPLING, MANUAL, TORQUE CONVERTER,
   AND CVRT. THE BATTERY STATE LIMITS CAN NOW BE SPECIFIED (BTSMIN AND
   BTSMAX).
   NAMES OF AVAILABLE HEAT-ENGINE MAPS . . .
44 BS400 ON782 GM5735 HN1600 GHVEGA140 TR7
45 TURBODSL NADSL IDIBSL CWSTRATROT NSUAUDIROT
46 BULK READ COMPLETE-
47 INPUT CHANGES FOR NEXT RUN-
48 >run
   INPUT COMPLETE FOR THIS CASE
   INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
51 >example 1.....driving cycle simulation, all electric

```

Figure 1-1. Accessing the Network

SECTION II

SIMULATION EXAMPLES

A. GENERAL

This section of the User's Manual provides eight examples of simulation runs. The actual computer printout is annotated with line numbers to clarify the explanations. These examples are just that. The components, values of variables chosen, and strategies selected are for illustrative purposes only to help the user understand how to use this simulator. One must be careful not to come to any conclusions with regard to the results of the examples.

B. EXAMPLE 1. DRIVING CYCLE SIMULATION, ALL-ELECTRIC (Figures 1-1, 2-1)

Figure 1-1 indicates how to access the network (described in detail in Section I). In order to start the program (start execution), one of four codes is used: ELVRIPP, ELVGE, ELVAIR, or ELVCHLD. These differ only in the stored default data parameters (see Table A-1, Appendix A). ELVRIPP starts the program with the Ripp electric parameters; ELVGE starts the program with the General Electric vehicle parameters; ELVAIR starts the program with the Garret AiResearch vehicle parameters; and ELVCHLD starts the program with the Energy Research & Development Corporation (Child's) van parameters. Use of line 20 indicates that the Ripp electric vehicle parameters were selected. Line 21 indicates that execution is commencing on the ELVEC program. The first question asked of the user is on line 23. In this case, the user requested English units, "E", on line 24. An "M" would have initiated the use of metric units.

On line 25, the "bulk read" process is begun. It is in this file that all the bulk data resides. First, the values of speeds for the EPA urban and highway driving cycles are read. On line 28, ELVEC prints "changes for this and following runs," indicating that this is the section of the program where the user can make changes. First, however, the rest of the bulk data is printed (the vehicle parameters - the Ripp electric vehicle in this example). Line 36 indicates that the vehicle data part of the bulk data file has been read. Lines 37 through 45 are reserved for messages to the user about the current version of

the program. This section can vary in length according to how many lines are necessary to print the message. Line 46 indicates that the bulk data file reading operation has been completed by ELVEC.

Line 47 indicates that ELVEC is now ready to accept user changes to the data, and the user types RUN, without changing any of the bulk data values.

ELVEC responds on line 49, indicating that it is now starting the run and asks for the run title, which the user inputs on line 51.

Figure 2-1 shows the output for this run, starting with the title on line 1. (A complete description of ELVEC output is contained in Appendix B.) Lines 2 and 3 show the date and time of this run for record-keeping purposes.

Lines 4 through 7 are data concerning one cycle of the particular driving schedule selected by default from the bulk data file: The SAE J227a/D schedule. Information printed includes the cycle length in time and distance, road energy required without and with regenerative braking, and the maximum road power required on this cycle.

Lines 8 through 11 show the apportionment of the energy required from one cycle, in watt-hours and as a percentage of the total for the simulated vehicle on the selected driving cycle. Note that in this example no energy goes into the brakes due to regenerative braking

Lines 12 through 15 summarize the energy required from and returned to the battery and the maximum power density required from and returned to the battery.

Finally, lines 16 through 19 print the cumulative data for the simulated vehicle, running repeated cycles of the selected driving schedule until the battery is discharged. The line of asterisks indicates the completed run.

C. EXAMPLE 2. DETAILED OUTPUT (Figures 2-1, 2-2A, 2-2B)

ELVEC requests parameter changes for the next run on line 21. On line 22, the user has changed the printing flag for a detailed printout (i.e., DETAIL = 1) and the ending time of the detailed printout to 97 seconds (i.e., TFTRC = 97). (Appendix A contains the definitions of all-user selectable variables). The starting time for the detailed printout remains at the default value of zero. Then, the user types two spaces and RUN to initiate the run with this data. Note that the vehicle data has not been changed, only the detail of output was changed. Also, ELVEC always uses the most recent values of an input parameter. Previous, bulk data or default values are not restored at the end of a simulation run.

The response on line 23 indicates that ELVEC is now ready to start the run as soon as the user types a title on line 25. After the user types this line, ELVEC spaces down a few lines and, on line 26, starts the output.

Figures 2-2A and 2-2B show the detailed printing output. The left-hand column shows the time (in one-second intervals throughout the J227/D schedule) followed by the vehicle speed at that time. Next, is the acceleration of the vehicle in feet per second per second. This is followed (to the right) by the transmission gear in use (in this case, a four-speed transmission) and the road load power, which is zero during coast or idle and negative during braking. The next two columns show the output and speed of the electric motor, followed by three columns indicating the output, speed, and fuel flow of the heat engine. The final column shows the battery state. In the all-electric mode, the heat engine and battery state columns remain unchanged. Road load power is defined as the power required at the drive wheels to move the vehicle in the prescribed manner specified by the particular driving schedule selected.

D. EXAMPLE 3. ALL ELECTRIC CONSTANT SPEED (Figure 2-3)

Example 3 (Figure 2-3) shows the changes made to turn off detailed printing and initiate a constant speed run. The same vehicle parameters are being used with a constant speed of 35 mi/hr. Note that line 12

shows a 60-second "driving cycle". The energy summary on line 15 shows no energy going into the brakes because braking did not occur. Likewise, the battery parameters on line 20 indicate that no energy is returned to the battery because braking is not used during constant speed.

E. EXAMPLE 4. FXOP HYBRID CONFIGURATION
(Figures 2-4, 2-5A through 2-5H)

The hybrid series configuration is called FXOP (Fixed Operating Point). In this configuration, the motor propels the vehicle and an auxiliary engine drives an alternator (or generator) which can charge the batteries. The engine can either be on or off during the simulation, depending upon the user-specified battery state variables.

The special user-defined variables particular to this configuration are indicated in Table 2-1. Other variables associated with the physical vehicle can be changed as required, as previously illustrated in this section and in Appendix A. The FXOP block diagram is illustrated in Figure 2-4.

Example 4 (FXOP Series Hybrid Simulation) is shown in Figures 2-5A thru 2-5H and is described below.

The first part of Figure 2-5A shows the new variable values for this series hybrid case. Line 10 is the means by which heat engines are scaled. The user types CHGENG, and the system prints line 11. The engine to be scaled is the BS400 (a Briggs and Stratton 400-cc displacement engine).

The horsepower in this case (element 11 of the Kathe array) is to be scaled from 13 hp to 16 hp, as seen on lines 13 thru 16. The elements of the Kathe array are defined in Appendix C, Table C-3.

Lines 26 through 37 indicate the energy distribution parameters for one J227a/D cycle. These parameters are defined in Appendix B. The user has the option of simulating additional cycles, as indicated on lines 38 thru 41. In this example, he chooses two additional cycles.

Table 2-1. FXOP Special User-Defined Variables

Variable	Description
BTSMAX	The maximum fraction above which the battery will not be charged by the heat engine/generator $BTSMAX \leq 1.0$ The default value of BTSMAX is 0.8
BTSMIN	The battery will start to be charged by the heat engine/generator when the battery state reaches or falls below this fraction: $BTSMIN \leq 0.999$. The default value of BTSMIN is 0.
NAMCLC	Name of clutch. For example, for a manually operated clutch, NAMCLC = MANUAL.
NAMHE	Name of the heat engine to be selected to drive the alternator or generator (see Table C-1).
NAMHYB	Name of this hybrid configuration. NAMHYB = FXOP
PWRHEN	The normal output in watts of the engine driving the generator (or alternator) which charges the batteries under charge conditions. For example, PWRHEN = 9740 (13 hp).
SPDHE	Speed (in radians/s) of the fixed operating point of the heat engine. If specified in rpm, include units. For example SPDHE = 3600RPM.
EFFALT	The efficiency of the generator (or alternator) expressed as a fraction ≤ 1.0 . For example, EFFALT = 0.77 implies that in order to supply 7500 watts to the batteries, it would require the heat engine to develop 13 hp, if the efficiency of the generator is 77%.

Figure 2-5B illustrates detailed output from the simulator, starting at the 265th second and ending after the 300th second in the third J227a/D cycle. Note that on the 280th second of the simulation, the heat engine turned on to charge the batteries, since the battery state dropped below 0.8 BTSMIN. Starting in Column 8 (counting from the left), the heat engine power, speed, and fuel flow are indicated, unlike an all-electric simulation. The last column of the detailed output indicates battery state. The fraction 0.794 means that 79.4% of the

battery remains for use. After the brief detail output, the user requests an additional 20 J227a/D cycles, making a total of $1 + 2 + 20$, or 23 cycles.

Figure 2-5C indicates that the test (simulation) was terminated when the battery was depleted in the 20th J227D cycle. The effective fuel consumption was 23.0 mi/gal.

Figure 2-5D shows that the user selected a different driving schedule (the J227B); in addition, the variable BTSMIN was set at 0.999, effectively forcing the heat engine to stay on most of the time. One J227B cycle is run, and the user requests 49 additional cycles, as seen on lines 21 thru 24.

The detailed output is seen in Figures 2-5E and 2-5F in the 50th J227B cycle between the 3529th and 3580th second. The heat engine was cycling on and off, as the battery state fell below 0.999 and rose to 1.0. At the 3540th second, the heat engine came on to charge the batteries. The output in Figure 2-5F captures the heat engine shutting down after the 3577th second. Note that there are two values at 3576 seconds. This is true for all J227-type schedules which have discontinuous power requirements at the beginning of the cruise, coast, and braking phases.

Figures 2-5G and 2-5H illustrate an FXOP constant-speed simulation, with detailed printout from the 50th through the 60th second. Normally, only 60 seconds of constant speed are simulated. In the case of hybrid vehicles, however, the user may wish to "drive" additional cycles in order to observe the changes in battery state. A cycle in this case refers to 60 seconds at constant speed.

F. EXAMPLE 5. CBTOUT HYBRID CONFIGURATION
(Figures 2-6, 2-7A, through 2-7G)

ELVEC implements a constant-battery-output parallel hybrid configuration as illustrated in Figure 2-6, and shown as examples in Figures 2-7A thru 2-7G. This strategy is such that the heat engine will come on if:

- 1) The required battery power density exceeds the user-specified PDMAX, the maximum allowable battery specific power density, or
- 2) The battery state drops below the user-specified BTSMIN, the minimum battery state allowed prior to charging.

If the heat engine is on, it will turn off if:

- 1) The battery state exceeds the maximum allowable state, BTSMAX.
- 2) The specific power density of the battery during regeneration exceeds the maximum allowable specific power density, PDMAX.

In essence, the heat engine does the load-leveling. When the motor and battery are unable to provide the necessary power, the heat engine supplies it. When the vehicle stops, there is no way to charge the battery with the engine, as in the FXOP hybrid strategy, because the motor is coupled directly to the wheels. Table 2-2 indicates the special user-defined variables for this strategy.

Table 2-2. CBTOUT Special User-Defined Variables

Variable	Description
BTSMAX	(See Table 2-1)
BTSMIN	(See Table 2-1)
FRCHEP	Fraction of maximum power at which engine is to operate when battery is being charged. Default value is 0.6. However, the engine can operate at any power load up to its maximum if required by the driving schedule.
NAMCLC	(See Table 2-1)
NAMHE	(See Table 2-1 and Table C-2)
NAMHYB	Name of this hybrid configuration NAMHYB = CBTOUT
PDMAX	Maximum allowable battery specific power density for either discharge or charge.

Figure 2-7A indicates that the user sets PDMAX to 95 watts/kg (a no-units indication always defaults to metric), selects a 50-hp naturally aspirated diesel engine (Table C-1, Appendix C), selects the CBTOUT hybrid strategy, and sets BTSMIN (the minimum battery state before charging occurs) to 0.75. This is indicated in lines 2 and 3 of Figure 2-7A. The entire 50th J227D cycle was also selected for detailed printout (Detail = 1, previously set, start of trace TSTRC = 6100 seconds, trace final TFTRC = 6222). Lines 10 thru 21 are the energy summary data based upon one J227D cycle. The user is asked if he wishes to drive additional cycles, and requests 49 more (line 25).

If the vehicle had gone the full 50 cycles, the detailed printout (the trace) would have appeared after line 25. However, the battery state fell to zero during the 32nd cycle, as seen by the note on lines 30 and 35. Therefore, the heat engine summary appears after line 25.

A detailed output of the first cycle is shown in Figures 2-7B, C, and D, through the 98th second. Note that the heat engine starts on the 20th second of the simulation because the power density required of the battery exceeds PDMAX. This is apparent in that the battery state was 0.981 at 20 seconds, and BTSMIN was previously set to 0.75. As can be seen from the 20th thru the 28th second, the motor power stays constant at 46.88 hp, and the heat engine provides the remainder of the required road load power to meet the acceleration portion of the driving schedule. In the cruise portion of the cycle, the road load requires 18.17 hp. The heat engine supplies 24.33 hp, of which 4.14 hp is used to drive the motor as a generator, 18.17 hp is used to meet the road load requirements, and the remainder is lost due to the efficiency factors. The battery state increases a small amount during the cruise and the coast phases. At 78 seconds when the coast phase begins, the entire engine output is used to drive the motor as a generator and 24.33 hp, less losses, is returned to the battery, as no power from either the motor or heat engine is required to move the vehicle. During braking, however, the specific power density returned to the battery exceeds PDMAX, and the engine shuts off.

Figures 2-7E and 2-7F show that during the 31st J227D cycle the battery is about depleted, and during the 31st cycle the batteries are depleted, giving an effective 26.5 mi/gal.

Figure 2-7G illustrates the simulator output for 10 seconds during a constant speed run at 35 mph. The motor is able to supply the road load power below the battery maximum allowed specific power density. Therefore, since the battery state had not dropped below 0.75 (BTSMIN = 0.75), the heat engine is off during this time period. Eventually, the battery state would drop below 0.75, and the heat engine would come on, supplying the required power to move the vehicle at 35 mph and the additional power to charge the batteries.

G. EXAMPLE 6. FORDB HYBRID CONFIGURATION
(Figures 2-8A thru 2-8D and 2-6)

ELVEC is able to simulate a modified version of the Ford Motor Company "Ford B" parallel hybrid strategy.* In this configuration (see Figure 2-6), the battery/motor provides initial vehicle acceleration. The Ford B strategy uses a direct coupling between the engine and motor. The engine valves are closed when the engine is not operating to avoid pumping losses. When the engine speed reaches a user-specified rpm, the heat engine starts. At that point, the motor may or may not stay on, depending on the following logic.

If the battery state < BTSMIN and JBTCHG = 1, the motor is operated as a generator; or if the road load requirement > than the heat engine can supply, then the motor supplements the heat engine.

The above logic is dependent on the user specified values of FRCHEP, JBTCHG, KATHE(14) and BTSMIN.

*"Hybrid Vehicle for Fuel Economy", L.E. Unnewehr, J.E. Auiler, L.R. Foote, D.F. Moyer, and H.L. Stadler, Society of Automotive Engineers, No. 760121, 1976.

Figures 2-8A through 2-8D illustrate the FORDB strategy and are described below; Table 2-3 defines the special variable.

Lines 2, 3, and 4 of Figure 2-8A indicate the special user-defined parameters necessary for this parallel hybrid configuration. The user selects a turbocharged Volkswagen, 70-hp diesel engine. The vehicle parameters are those of the vehicle used to illustrate the FXOP and CBTOUT strategies. Note that for this run, ACLFAC has been set to a value of less than 1 to allow non-linear acceleration.

Lines 11 through 22 indicate the energy summary based upon one J227D cycle. The user requests 9 additional cycles at line 26; Figures 2-8B through 2-8D show the detailed output of the 10th J227D cycle.

Table 2-3. FORDB Special User-Defined Variables

Variable	Description
BTSMAX	(See Table 2-1)
BTSMIN	(See Table 2-1)
FRCHEP	(See Table 2-2)
JBTCHEG	Flag set to 1 if engine is allowed to recharge battery, or to 0 (zero) if recharge comes during regenerative braking. JBTCHEG = 1 (default)
KATHE (14)	Minimum engine speed, rpm. Engine will turn on at this speed. Default is specified in the heat engine catalog array, element 14, for each engine. See Table C3.
NAMCLC	NAMCLC = DRCOUP only
NAMHYB	NAMHYB = FORDB for this strategy
NAMHE	(See Table 2-1 and Tables C-1 and C-2)

The heat engine starts during the third second of the simulation when the engine speed reaches 800 rpm (KATHE (14) = 800). The motor and engine move the vehicle up the acceleration ramp. Just before cruise (1126th second), the road load requirement drops to the point where the motor is not required and so shuts off. The vehicle is propelled by the heat engine, consuming diesel fuel at the rate of 1.31 gallons per hour. During braking, energy is returned to the battery through regenerative braking (NREGEN = 2), and the heat engine turns off (BTSMAX = 1). The effective mileage is 33.4 mpg in this configuration.

H. EXAMPLE 7. ALL-HEAT ENGINE VEHICLE
(Figures 2-9A, 2-9B)

ELVEC is able to simulate an all-heat engine vehicle by setting PDMAX = 0 and NAMHYB = CBTOUT. An engine and clutch must also be selected.

Figures 2-9A and 2-9B illustrate this capability. In this example, the constant battery output strategy was chosen with a turbocharged normally aspirated Volkswagen engine with an automatic transmission. Note automatic scaling of the torque converter to match the selected engine (lines 10 - 15).

I. EXAMPLE 8. MAXIMUM ACCELERATION AND PASSING
(Figures 2-10A through 2-10F)

Wide-open throttle and passing time and distance are features of the ELVEC simulator. Table 2-4 indicates the special user-defined variables for these simulation modes. Figures 2-10A through 2-10F indicate the implementation procedures.

Figures 2-10A and 2-10B indicate the input parameters and results of simulating wide-open throttle performance of a Datsun 1200 chassis with a Triumph TR7, 4-cylinder, 86-hp engine and 20-hp electric motor. The user specifies 0 to 60-mph performance, using the heat engine only (PDMAX = 0), shifting at 15, 30, and 50 mph. Figure 2-10B shows the results. The column headings are self-explanatory. For best results, the time step has been set to 0.1 seconds (DELTA = 0.1) and the printing step set to 10 (NPRINT = 10). This gives one-second spacing in the output, but better calculation resolution.

Table 2-4. Wide-Open Throttle and Passing - Special User Defined Variables

Variable	Description
BTSMAX	(See Table 2-1)
BTSMIN	(See Table 2-1)
DELTA	Integration time step. 0.1 s recommended
DTSHFT	Time delay to shift gears. Default = 0.2 s
NAMCLC	(See Table 2-1)
NAMCYC	NAMCYC = MAXACL for wide-open throttle
NAMHE	Any engine
NAMHYB	Any configuration
NPRINT	Number of time steps between printing. Default is 1. 10 recommended if DELTA = 0.1
PDMAX	PDMAX = 0 for all-heat engine only
SPEED	Final speed*
VINIT	Initial speed*

*For 0 to 30, VINIT = 0, SPEED = 30 mph. For passing, 30 to 48 mph, VINIT = 30 mph, SPEED = 48 mph.

Figure 2-10C is a passing-time and distance example, where the user wishes to know the time and distance to pass another vehicle (or accelerate), starting at 20.7 mph and ending at 35.2 mph. Again, this is an all-heat engine case, since PDMAX was previously set to zero.

In Figure 2-10D, the motor is allowed to work by setting PDMAX to 150 watts/kg. In Figure 2-10E, the user asks for acceleration performance from 0 to 30 mph, using both the motor and the engine. This can be compared to Figure 2-10F, where only the heat engine is allowed to work over the same range of acceleration speeds.

```

1  EXAMPLE 1.....DRIVING CYCLE SIMULATION, ALL ELECTRIC
2  DATE    06/23/78
3  TIME    09.18.04

4  TIME/  RANGE/  ROAD ENERGY  MAX ROAD  DRIVING
5  CYC   CYCLE  W/O RGN  W RGN  POWER  SCHEDULE
6  SEC   MI      WH/MI      KW
7  122   0.961  226.3  163.6  29.9   J227D

8  ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
9  AERO  TIRES  BRAKES  DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG  BATT SYS
10 WH-    81    75    0    30    62    0    0    0    142
11 PRCNT 20.8  19.2  0.0  7.7  16.0  0.0  0.0  0.0  36.3

12 -----BATTERY-----
13 ENR OUT ENR IN PD OUT MX PD IN MX
14 WH/MI      W/LB
15 306.7    46.3    31.1    26.5

16 TOTAL      ELECT CONSM      ELECT COST      FINAL STATE
17 RANGE      AT WALL      (AT 4.0C/KWH)  BATT STR DEV
18 MI         WH/MI WH/MI*TON    C/MI           WH
19 49.1       408    248    1.63          0.0    1000.

20 *****
21 INPUT CHANGES FOR NEXT RUN-
22 >detail 1 tftrc 97 run
23 INPUT COMPLETE FOR THIS CASE
24 INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
25 >example 2.....detail output of example 1

26 EXAMPLE 2.....DETAIL OUTPUT OF EXAMPLE 1
   DATE    06/23/78
   TIME    09.19.36

```

Figure 2-1. Driving Cycle Simulation, all Electric

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	---MOTOR---		---HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
0	0.0	2.3	1	0.0	0.0	0	0.0	0	0.0	1.000
1	1.6	2.3	1	1.22	1.35	344	0.0	0	0.0	1.000
2	3.2	2.3	1	2.44	2.71	689	0.0	0	0.0	1.000
3	4.8	2.3	1	3.66	4.07	1033	0.0	0	0.0	1.000
4	6.4	2.3	1	4.89	5.44	1378	0.0	0	0.0	1.000
5	8.0	2.3	1	6.13	6.81	1723	0.0	0	0.0	1.000
6	9.6	2.3	1	7.37	8.19	2067	0.0	0	0.0	1.000
7	11.2	2.3	1	8.63	9.58	2412	0.0	0	0.0	1.000
8	12.8	2.3	1	9.89	10.99	2757	0.0	0	0.0	1.000
9	14.4	2.3	2	11.17	12.41	1790	0.0	0	0.0	1.000
10	16.0	2.3	2	12.46	13.85	1989	0.0	0	0.0	1.000
11	17.6	2.3	2	13.77	15.30	2188	0.0	0	0.0	1.000
12	19.2	2.3	2	15.09	16.77	2387	0.0	0	0.0	1.000
13	20.8	2.3	2	16.44	18.27	2586	0.0	0	0.0	1.000
14	22.4	2.3	2	17.81	19.79	2785	0.0	0	0.0	1.000
15	24.0	2.3	3	19.20	21.33	1931	0.0	0	0.0	1.000
16	25.6	2.3	3	20.61	22.90	2060	0.0	0	0.0	1.000
17	27.2	2.3	3	22.05	24.50	2189	0.0	0	0.0	1.000
18	28.8	2.3	3	23.51	26.13	2318	0.0	0	0.0	1.000
19	30.4	2.3	3	25.01	27.79	2446	0.0	0	0.0	1.000
20	32.0	2.3	3	26.54	29.48	2575	0.0	0	0.0	1.000
21	33.6	2.3	4	28.09	31.22	1926	0.0	0	0.0	1.000
22	35.2	2.3	4	29.69	32.99	2018	0.0	0	0.0	1.000
23	36.7	2.3	4	31.32	34.80	2109	0.0	0	0.0	1.000
24	38.3	2.3	4	32.98	36.65	2201	0.0	0	0.0	1.000
25	39.9	2.3	4	34.68	38.54	2293	0.0	0	0.0	1.000
26	41.5	2.3	4	36.43	40.48	2384	0.0	0	0.0	1.000
27	43.1	2.3	4	38.22	42.46	2476	0.0	0	0.0	1.000
28	44.7	2.3	4	40.05	44.49	2568	0.0	0	0.0	1.000
28	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
29	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
30	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
31	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
32	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
33	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
34	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
35	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
36	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
37	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
38	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
39	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
40	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
41	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
42	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
43	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
44	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
45	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
46	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
47	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
48	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
49	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
50	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000

Figure 2-2A. Detail Output, Driving Cycle Simulation, all Electric

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
51	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
52	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
53	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
54	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
55	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
56	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
57	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
58	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
59	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
60	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
61	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
62	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
63	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
64	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
65	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
66	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
67	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
68	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
69	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
70	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
71	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
72	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
73	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
74	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
75	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
76	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
77	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
78	44.7	0.0	4	10.62	11.80	2568	0.0	0	0.0	1.000
78	44.7	-0.8	4	0.0	0.0	2568	0.0	0	0.0	1.000
79	44.2	-0.8	4	0.0	0.0	2535	0.0	0	0.0	1.000
80	43.6	-0.8	4	0.0	0.0	2503	0.0	0	0.0	1.000
81	43.0	-0.8	4	0.0	0.0	2471	0.0	0	0.0	1.000
82	42.5	-0.8	4	0.0	0.0	2439	0.0	0	0.0	1.000
83	42.0	-0.8	4	0.0	0.0	2408	0.0	0	0.0	1.000
84	41.4	-0.8	4	0.0	0.0	2377	0.0	0	0.0	1.000
85	40.9	-0.8	4	0.0	0.0	2347	0.0	0	0.0	1.000
86	40.4	-0.8	4	0.0	0.0	2317	0.0	0	0.0	1.000
87	39.9	-0.7	4	0.0	0.0	2288	0.0	0	0.0	1.000
88	39.4	-0.7	4	0.00	0.00	2259	0.0	0	0.0	1.000
88	39.4	-6.4	4	-62.68	-56.41	2259	0.0	0	0.0	1.000
89	35.0	-6.4	4	-56.46	-50.82	2008	0.0	0	0.0	1.000
90	30.6	-6.4	3	-49.98	-44.99	2467	0.0	0	0.0	1.000
91	26.2	-6.4	3	-43.27	-38.95	2114	0.0	0	0.0	1.000
92	21.9	-6.4	2	-36.36	-32.73	2722	0.0	0	0.0	1.000
93	17.5	-6.4	2	-29.29	-26.36	2177	0.0	0	0.0	1.000
94	13.1	-6.4	2	-22.08	-19.88	1633	0.0	0	0.0	1.000
95	8.7	-6.4	1	-14.78	-13.30	1886	0.0	0	0.0	1.000
96	4.4	-6.4	1	-7.41	-6.66	943	0.0	0	0.0	1.000
97	0.0	-6.4	1	-0.00	-0.00	0	0.0	0	0.0	1.000
97	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	1.000

Figure 2-2B. Detail Output, Driving Cycle Simulation, all Electric (Cont'd)

INPUT CHANGES FOR NEXT RUN-
 >detail 0 namcyc conspd speed 35mph run
 INPUT COMPLETE FOR THIS CASE
 INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
 >example 3.....constant speed simulation using vehicle from example 1

EXAMPLE 3.....CONSTANT SPEED SIMULATION USING VEHICLE FROM EXAMPLE 1
 DATE 06/23/78
 TIME 09.27.30

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE	
12	60	0.583	173.4	173.4	4.9	CONSPD

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
 AERD TIRES BRAKES DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG BATT SYS

15	WH-	43	57	0	11	24	0	0	0	77
16	PRCNT	20.4	26.6	0.0	5.2	11.5	0.0	0.0	0.0	36.2

-----BATTERY-----
 ENR OUT ENR IN PD OUT MX PD IN MX
 WH/MI W/LB

20	235.0	0.0	5.1	0.0
----	-------	-----	-----	-----

TOTAL RANGE MI	ELECT CONSM AT WALL WH/MI	ELECT COST (AT 4.0C/KWH) C/MI	FINAL STATE BATT STR DEV WH
92.8	368	224	1.47
			0.0 1000.

Figure 2-3. Constant Speed Simulation, all Electric

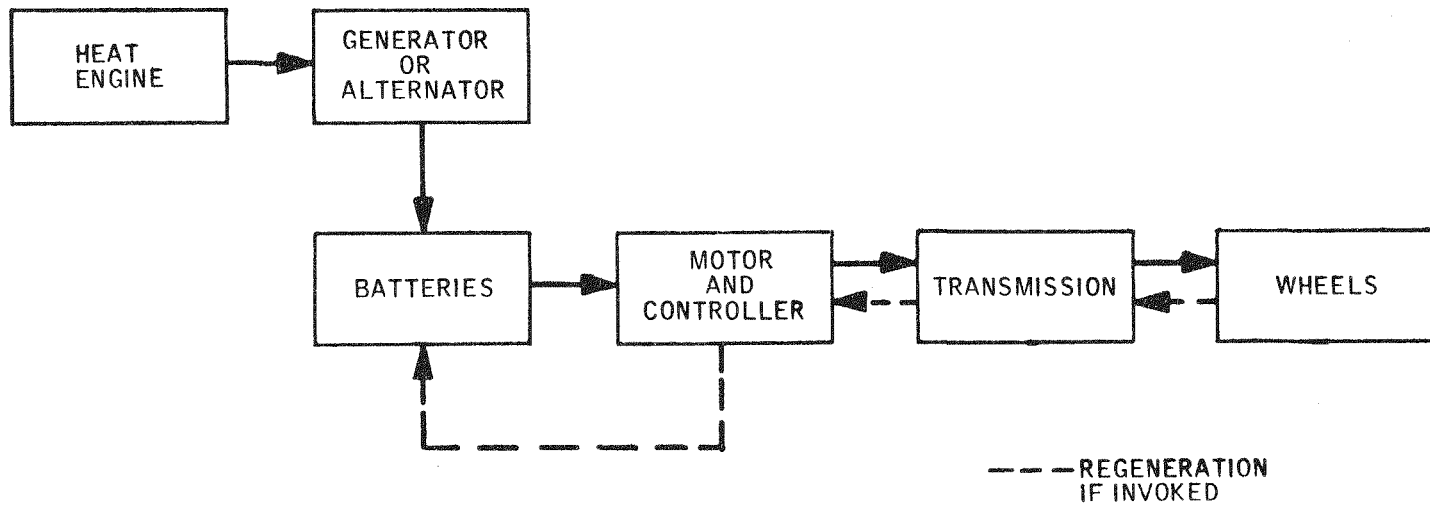


Figure 2-4. FXOP Series Hybrid Configuration

```

1 INPUT CHANGES FOR NEXT RUN-
>wb 10401b wt 51301b atiref 1.4 cda 15.73ft2 effcm .78
>btsmax 1.0 btsmin 0.8 effalt .77 nregen 1
>namhe bs400 namhyb fxop namclc manual spdhe 3600rpm
>gear 3.80,2.06,1.22,0.82
>ratio 0.33,4.125,0.0
>velscd 10mph,20mph,30mph
>purhen 9740 detail 1 tstop 10000
>tstrc 265 tftrc 274
10 >chgeng
    WHICH ENGINE(TYPE =NONE= IF FINISHED)-
    >bs400
    WHICH ELEMENT OF KATHE ARRAY TO BE CHANGED (1-18)-
    >11
    INPUT NEW VALUE FOR KATHE(11, 1)
    >16
    WHICH ENGINE(TYPE =NONE= IF FINISHED)-
    >none
    >run
20 INPUT COMPLETE FOR THIS CASE
    INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
    >fxop series hybrid simulation, j227-d driving cycle.....

```

```

FXOP SERIES HYBRID SIMULATION, J227-D DRIVING CYCLE.....
DATE 06/23/78
25 TIME 09.40.18

```

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE
122	0.950	379.3	284.0	47.8	J227D

```

30 ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
    AERO TIRES BRAKES DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG BATT SYS
WH- 132 137 90 49 112 0 27 0 291
PRCNT 15.8 16.3 10.8 5.8 13.4 0.0 3.2 0.0 34.7

```

```

-----BATTERY-----
35 ENR OUT ENR IN PD OUT MX PD IN MX
    WH/MI W/LB
    540.2 0.0 65.5 0.0
    DO YOU WANT TO CONTINUE WITH MORE CYCLES...
    >yes
40 HOW MANY MORE CYCLES...
    >2

```

Figure 2-5A. FXOP Series Hybrid Simulation, J227D

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
265	33.6	2.3	4	44.91	49.90	1468	0.0	0	0.0	0.841
266	35.2	2.3	4	47.47	52.74	1538	0.0	0	0.0	0.838
267	36.7	2.3	4	50.08	55.64	1608	0.0	0	0.0	0.834
268	38.3	2.3	4	52.75	58.61	1677	0.0	0	0.0	0.829
269	39.9	2.3	4	55.48	61.65	1747	0.0	0	0.0	0.824
270	41.5	2.3	4	58.28	64.76	1817	0.0	0	0.0	0.818
271	43.1	2.3	4	61.15	67.94	1887	0.0	0	0.0	0.812
272	44.7	2.3	4	64.09	71.21	1957	0.0	0	0.0	0.804
273	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.804
273	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.803
274	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.803
275	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.802
276	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.802
277	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.801
278	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.800
279	44.7	0.0	4	18.17	20.19	1957	0.0	0	0.0	0.800
280	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.799
281	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.799
282	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.799
283	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.798
284	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.798
285	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.798
286	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.798
287	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.797
288	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.797
289	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.797

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
290	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.796
291	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.796
292	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.796
293	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.795
294	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.795
295	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.795
296	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.795
297	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.794
298	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.794
299	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.794
300	44.7	0.0	4	18.17	20.19	1957	13.06	3600	1.39	0.793

DO YOU WANT TO CONTINUE WITH MORE CYCLES...

>yes

HOW MANY MORE CYCLES...

>20

Figure 2-5B. FXOP Series Hybrid Simulation, J227D (cont'd)

```

-----HEAT ENGINE-----
  FUEL  PWR OUT,HP  AVE EFF  ENGINE  HYBRID
MI/GAL  AVER  PEAK  PERCENT  NAME  STRATEGY
 23.0   11.5  13.1   18.7  BS400   FXOP

```

TEST TERMINATED...BATTERY CHARGE TOO LOW

```

TOTAL      ELECT CONSM      ELECT COST      FINAL STATE
RANGE      AT WALL      (AT 4.0C/KWH)  BATT STR DEV
  MI       WH/MI  WH/MI*TON      C/MI              WH
 0.0       471     183      1.89      -0.000  1000.

```

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 20 CYCLES

Figure 2-5C. FXOP Series Hybrid Simulation, J227D (Cont'd)

INPUT CHANGES FOR NEXT RUN-
2 >namcyc j227b btmin .999 tstrc 3529 tftrc 3580 run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>fxop series hybrid simulation, j227b, min battery .999

FXOP SERIES HYBRID SIMULATION, J227B, MIN BATTERY .999

DATE	06/27/78
TIME	14.08.47

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE
72	0.187	283.2	172.9	13.4	J227B

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-

	AERO	TIRES	BRAKES	DRVLNE	MTR/CNTR	STR DEV	CLUTCH	HT ENG	BATT SYS
WH-	4	27	20	7	16	0	8	427	0
PRCNT	1.0	5.3	4.0	1.5	3.2	0.0	1.6	83.3	0.0

-----BATTERY-----
ENR OUT ENR IN PD OUT MX PD IN MX
WH/MI W/LB

169.1 189.3 11.2 7.2
21 DO YOU WANT TO CONTINUE WITH MORE CYCLES...
>yes
HOW MANY MORE CYCLES...
24 >49

Figure 2-5D. Series Hybrid Simulation, J227B, BTSMIN = 0.999

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
3529	1.0	1.5	1	0.90	1.00	212	0.0	0	0.0	1.000
3530	2.1	1.5	1	1.81	2.01	424	0.0	0	0.0	1.000
3531	3.1	1.5	1	2.71	3.02	636	0.0	0	0.0	1.000
3532	4.2	1.5	1	3.62	4.03	848	0.0	0	0.0	1.000
3533	5.2	1.5	1	4.53	5.04	1060	0.0	0	0.0	1.000
3534	6.3	1.5	1	5.45	6.05	1273	0.0	0	0.0	1.000
3535	7.3	1.5	1	6.37	7.08	1485	0.0	0	0.0	1.000
3536	8.4	1.5	1	7.29	8.10	1697	0.0	0	0.0	0.999
3537	9.4	1.5	1	8.22	9.14	1909	0.0	0	0.0	0.999
3538	10.5	1.5	2	9.16	10.18	1150	0.0	0	0.0	0.999
3539	11.5	1.5	2	10.10	11.23	1265	0.0	0	0.0	0.999
3540	12.6	1.5	2	11.06	12.29	1380	13.06	3600	1.43	0.999
3541	13.6	1.5	2	12.02	13.35	1495	13.06	3600	1.43	0.999
3542	14.7	1.5	2	12.99	14.43	1610	13.06	3600	1.43	0.998
3543	15.7	1.5	2	13.97	15.52	1725	13.06	3600	1.43	0.998
3544	16.7	1.5	2	14.96	16.63	1840	13.06	3600	1.42	0.998
3545	17.8	1.5	2	15.97	17.74	1955	13.06	3600	1.39	0.998
3546	18.8	1.5	2	16.98	18.87	2070	13.06	3600	1.36	0.998
3547	19.9	1.5	2	18.01	20.02	2185	13.06	3600	1.35	0.997
3548	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.997
3548	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3549	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3550	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3551	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3552	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3553	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998

Figure 2-5E. FXOP Series Hybrid Simulation, J227B, BTSMIN = 0.99 (Cont'd)

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
3554	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3555	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3556	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3557	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3558	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3559	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3560	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3561	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3562	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3563	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3564	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3565	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3566	19.9	0.0	2	4.65	5.17	2185	13.06	3600	1.35	0.998
3567	19.5	-0.5	2	0.0	0.0	2145	13.06	3600	1.35	0.998
3567	19.5	-0.5	2	0.0	0.0	2145	13.06	3600	1.35	0.999
3568	19.2	-0.5	2	0.0	0.0	2106	13.06	3600	1.35	0.999
3569	18.8	-0.5	2	-0.00	0.0	2066	13.06	3600	1.35	0.999
3570	18.4	-0.5	2	0.0	0.0	2027	13.06	3600	1.35	0.999
3571	14.8	-5.4	2	-31.80	0.0	1622	13.06	3600	1.35	0.999
3571	14.8	-5.4	2	-31.80	0.0	1622	13.06	3600	1.35	0.999
3572	11.1	-5.4	2	-23.96	0.0	1216	13.06	3600	1.35	0.999
3573	7.4	-5.4	1	-16.03	0.0	1496	13.06	3600	1.35	0.999
3574	3.7	-5.4	1	-8.03	0.0	748	13.06	3600	1.35	1.000
3575	0.0	-5.4	1	-0.00	0.0	0	13.06	3600	1.35	1.000
3576	0.0	0.0	1	0.0	0.0	0	13.06	3600	1.35	1.000
3576	0.0	0.0	1	0.0	0.0	0	13.06	3600	1.35	1.000
3577	0.0	0.0	1	0.0	0.0	0	13.06	3600	1.35	1.000
3578	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	1.000
3579	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	1.000
3580	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	1.000

DO YOU WANT TO CONTINUE WITH MORE CYCLES...

>no

-----HEAT ENGINE-----					
FUEL MI/GAL	PWR AVER	OUT,HP PEAK	AVE EFF PERCENT	ENGINE NAME	HYBRID STRATEGY
13.6	6.8	13.1	19.4	BS400	FXOP

TOTAL RANGE MI	ELECT CONSM AT WALL WH/MI	ELECT COST (AT 4.0C/KWH) C/MI	FINAL STATE BATT STR DEV WH
0.0	0	0	1.000 1000.

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 50 CYCLES

Figure 2-5F. FXOP Series Hybrid Simulation, J227B, BTSMIN = 0.999 (Cont'd)

INPUT CHANGES FOR NEXT RUN-
 >namcyc conspd speed 35mph tstrc 50 tftrc 60 run
 INPUT COMPLETE FOR THIS CASE
 INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
 >fxop series hybrid simulation, 35 mi/hr constant speed.....

FXOP SERIES HYBRID SIMULATION, 35 MI/HR CONSTANT SPEED.....
 DATE 06/27/78
 TIME 14.18.38

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD	----MOTOR----		----HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
50	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
51	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
52	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
53	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
54	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
55	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
56	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
57	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
58	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.992
59	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.991
60	35.0	0.0	4	11.30	12.56	1647	13.06	3600	1.43	0.991

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE
60	0.865	242.1	242.1	8.4	CONSPD

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
 AERO TIRES BRAKES DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG BATT SYS

WH-	85	124	0	23	65	0	21	1023	68
PRCNT	6.0	8.8	0.0	1.6	4.6	0.0	1.5	72.5	4.8

-----BATTERY-----
 ENR OUT ENR IN PD OUT MX PD IN MX
 WH/MI W/LB

139.1 0.0 11.5 0.0
 DO YOU WANT TO CONTINUE WITH MORE CYCLES...
 >no

Figure 2-5G. FXOP Series Hybrid Simulation, 35 mph Constant Speed

```

-----HEAT ENGINE-----
FUEL  PWR OUT,HP  AVE EFF  ENGINE  HYBRID
MI/GAL  AVER  PEAK  PERCENT  NAME  STRATEGY

25.4   18.6  13.1   18.4  BS400  FXOP

```

```

TOTAL      ELECT CONSM      ELECT COST      FINAL STATE
RANGE      AT WALL      (AT 4.0C/KWH)  BATT STR DEV
MI         WH/MI  WH/MI*TON      C/MI         WH

0.0       218     85      0.87      0.991  1000.

```

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 1 CYCLES

Figure 2-5H. FXOP Series Hybrid Simulation, 35 mph Constant Speed (Cont'd)

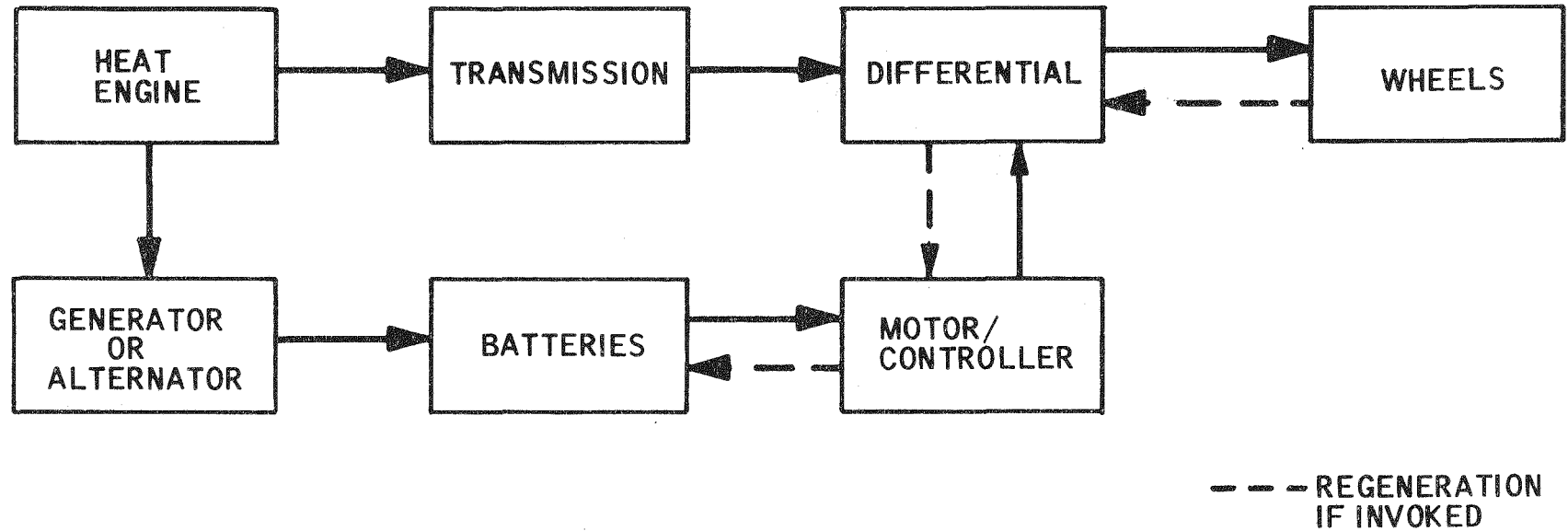


Figure 2-6. CBTOUT and FORDB Parallel Hybrid Configurations

```

1 INPUT CHANGES FOR NEXT RUN-
2 >pdmax 95 namhe nads1 namhyb cbtout tstop 10000 nancyc j227d
3 >tstrc 6100 tftrc 6222 btmin .75 run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>constant battery output (cbtout) strategy, j227-d cycle.....

```

CONSTANT BATTERY OUTPUT (CBTOUT) STRATEGY, J227-D CYCLE.....

DATE 07/07/78
TIME 15.02.58

```

10 TIME/ RANGE/ ROAD ENERGY MAX ROAD DRIVING
CYC CYCLE W/O RGN W RGN POWER SCHEDULE
SEC MI WH/MI KW
122 0.950 379.1 283.8 47.8 J227D

```

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
AERO TIRES BRAKES DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG BATT SYS

```

WH- 132 137 90 49 69 0 0 1012 84
PRCNT 8.4 8.7 5.7 3.1 4.4 0.0 0.1 64.3 5.3

```

-----BATTERY-----
ENR OUT ENR IN PD OUT MX PD IN MX
WH/MI W/LB

```

21 232.1 76.6 43.1 13.6
DO YOU WANT TO CONTINUE WITH MORE CYCLES...
>yes
HOW MANY MORE CYCLES...
25 >49

```

-----HEAT ENGINE-----
FUEL PWR OUT,HP AVE EFF ENGINE HYBRID
MI/GAL AVER PEAK PERCENT NAME STRATEGY
26.6 13.8 24.3 23.8 NADSL CBTOUT

30 TEST TERMINATED...BATTERY CHARGE TOO LOW

```

TOTAL ELECT CONSM ELECT COST FINAL STATE
RANGE AT WALL (AT 4.0C/KWH) BATT STR DEV
MI WH/MI WH/MI*TON C/MI WH
0.0 217 84 0.87 -0.003 1000.

```

35 NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 32 CYCLES

Figure 2-7A. CBTOUT Hybrid Strategy, J227D

INPUT CHANGES FOR NEXT RUN-
>tstrc 0 tfrtc 98 run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>cbtout hybrid strategy, j227-d first cycle.....

CBTOUT HYBRID STRATEGY, J227-D FIRST CYCLE.....
DATE 07/07/78
TIME 15.06.41

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
0	0.0	2.3	1	0.0	0.0	0	0.0	0	0.0	1.000
1	1.6	2.3	1	1.95	2.16	323	0.0	0	0.0	1.000
2	3.2	2.3	1	3.90	4.33	647	0.0	0	0.0	1.000
3	4.8	2.3	1	5.85	6.50	971	0.0	0	0.0	1.000
4	6.4	2.3	1	7.81	8.68	1295	0.0	0	0.0	1.000
5	8.0	2.3	1	9.78	10.87	1619	0.0	0	0.0	0.999
6	9.6	2.3	1	11.77	13.08	1943	0.0	0	0.0	0.999
7	11.2	2.3	2	13.77	15.30	1229	0.0	0	0.0	0.999
8	12.8	2.3	2	15.79	17.55	1405	0.0	0	0.0	0.998
9	14.4	2.3	2	17.83	19.81	1580	0.0	0	0.0	0.998
10	16.0	2.3	2	19.90	22.11	1756	0.0	0	0.0	0.997
11	17.6	2.3	2	21.99	24.43	1932	0.0	0	0.0	0.996
12	19.2	2.3	2	24.11	26.78	2107	0.0	0	0.0	0.996
13	20.8	2.3	3	26.26	29.17	1352	0.0	0	0.0	0.994
14	22.4	2.3	3	28.44	31.60	1456	0.0	0	0.0	0.993
15	24.0	2.3	3	30.66	34.07	1560	0.0	0	0.0	0.992
16	25.6	2.3	3	32.93	36.58	1664	0.0	0	0.0	0.990
17	27.2	2.3	3	35.23	39.14	1768	0.0	0	0.0	0.988
18	28.8	2.3	3	37.58	41.75	1872	0.0	0	0.0	0.986
19	30.4	2.3	4	39.97	44.41	1328	0.0	0	0.0	0.984
20	32.0	2.3	4	42.42	46.88	1398	0.25	1398	0.07	0.981
21	33.6	2.3	4	44.91	46.88	1468	3.03	1468	0.38	0.978
22	35.2	2.3	4	47.47	46.88	1538	5.87	1538	0.50	0.976
23	36.7	2.3	4	50.08	46.88	1608	8.77	1608	0.67	0.973
24	38.3	2.3	4	52.75	46.88	1677	11.73	1677	0.81	0.970
25	39.9	2.3	4	55.48	46.88	1747	14.77	1747	1.01	0.967
26	41.5	2.3	4	58.28	46.88	1817	17.88	1817	1.26	0.964
27	43.1	2.3	4	61.15	46.88	1887	21.07	1887	1.54	0.961
28	44.7	2.3	4	64.09	46.88	1957	24.33	1957	1.87	0.959
29	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
29	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
30	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
31	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
32	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
33	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
34	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959

Figure 2-7B. CBTOUT Hybrid Strategy, J227D, First Cycle

35	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
36	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
37	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
38	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
39	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
40	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
41	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
42	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
43	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
44	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
45	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
46	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
47	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
48	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.959
49	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
50	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	-----MOTOR----- PW,HP SPD,RPM	-----HEAT ENGINE----- PW,HP RPM FL,GPH	BATTERY STATE
51	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
52	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
53	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
54	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
55	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
56	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
57	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
58	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
59	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960
60	44.7	0.0	4	18.17	-4.14	1957 24.33	1957 1.87 0.960

Figure 2-7C. CBTOUT Hybrid Strategy J227D, First Cycle (Cont'd)

61	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
62	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
63	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
64	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
65	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
66	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
67	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
68	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
69	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
70	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
71	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.960
72	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
73	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
74	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
75	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
76	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
77	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
78	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.961
79	44.1	-0.9	4	0.0	-24.33	1930	24.33	1930	1.87	0.961
79	44.1	-0.9	4	0.0	-24.33	1930	24.33	1930	1.87	0.961
80	43.5	-0.9	4	0.0	-24.33	1903	24.33	1903	1.86	0.962
81	42.9	-0.9	4	0.0	-24.33	1876	24.33	1876	1.86	0.962
82	42.3	-0.9	4	0.0	-24.33	1850	24.33	1850	1.85	0.962
83	41.7	-0.9	4	0.00	-24.33	1824	24.33	1824	1.84	0.963
84	41.1	-0.9	4	0.00	-24.33	1798	24.33	1798	1.84	0.963
85	40.5	-0.8	4	0.0	-24.33	1773	24.33	1773	1.83	0.963
86	40.0	-0.8	4	0.00	-24.33	1748	24.33	1748	1.82	0.964
87	39.4	-0.8	4	0.00	-24.33	1723	24.33	1723	1.81	0.964
88	38.8	-0.8	4	0.00	-24.33	1699	24.33	1699	1.80	0.965
89	38.8	-6.3	4	-93.96	7.43	1699	0.0	1699	0.0	0.965
89	34.5	-6.3	4	-84.70	0.0	1510	0.0	0	0.0	0.965
90	30.2	-6.3	4	-75.01	0.0	1322	0.0	0	0.0	0.965
91	25.9	-6.3	3	-64.97	0.0	1685	0.0	0	0.0	0.965
92	21.6	-6.3	3	-54.62	0.0	1404	0.0	0	0.0	0.965
93	17.3	-6.3	2	-44.00	0.0	1897	0.0	0	0.0	0.965
94	12.9	-6.3	2	-33.18	0.0	1423	0.0	0	0.0	0.965
95	8.6	-6.3	1	-22.21	0.0	1750	0.0	0	0.0	0.965
96	4.3	-6.3	1	-11.13	0.0	875	0.0	0	0.0	0.965
97	0.0	-6.3	1	-0.00	0.0	0	0.0	0	0.0	0.965
98	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	0.965
98	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	0.965

Figure 2-7D. CBTOUT Hybrid Strategy, J227D, First Cycle (Cont'd)

```

INPUT CHANGES FOR NEXT RUN-
>tstrc 3661  tftrc 3689  run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>cbtout hybrid strategy, j227-d cycle, 30th cycle.....

```

```

CBTOUT HYBRID STRATEGY, J227-D CYCLE, 30TH CYCLE.....
DATE    07/07/78
TIME    15.21.22

```

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/D RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE
122	0.950	379.1	283.8	47.8	J227D

```

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
AERO  TIRES  BRAKES  DRVLNE MTR/CNTR  STR DEV CLUTCH  HT ENG  BATT SYS
WH-    132    137    90    49    69    0    0    1012    84
PRCNT  8.4    8.7    5.7    3.1    4.4    0.0    0.1    64.3    5.3

```

```

-----BATTERY-----
ENR OUT ENR IN PD OUT MX PD IN MX
      WH/MI                W/LB
232.1    76.6    43.1    13.6
DO YOU WANT TO CONTINUE WITH MORE CYCLES...
>yes
HOW MANY MORE CYCLES...
>30

```

Figure 2-7E. CBTOUT Hybrid Strategy J227D, Detail During 30th Cycle

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
3661	1.6	2.3	1	1.95	-2.92	323	5.08	800	0.42	0.050
3662	3.2	2.3	1	3.90	-0.67	647	5.00	800	0.42	0.050
3663	4.8	2.3	1	5.85	1.50	971	5.00	971	0.42	0.050
3664	6.4	2.3	1	7.81	3.68	1295	5.00	1295	0.44	0.050
3665	8.0	2.3	1	9.78	5.87	1619	5.00	1619	0.46	0.049
3666	9.6	2.3	1	11.77	8.08	1943	5.00	1943	0.47	0.049
3667	11.2	2.3	2	13.77	10.30	1229	5.00	1229	0.43	0.049
3668	12.8	2.3	2	15.79	12.54	1405	5.00	1405	0.45	0.049
3669	14.4	2.3	2	17.83	14.81	1580	5.00	1580	0.46	0.049
3670	16.0	2.3	2	19.90	17.11	1756	5.00	1756	0.46	0.048
3671	17.6	2.3	2	21.99	19.43	1932	5.00	1932	0.47	0.048
3672	19.2	2.3	2	24.11	21.78	2107	5.00	2107	0.49	0.047
3673	20.8	2.3	3	26.26	24.17	1352	5.00	1352	0.45	0.046
3674	22.4	2.3	3	28.44	26.60	1456	5.00	1456	0.46	0.045
3675	24.0	2.3	3	30.66	29.07	1560	5.00	1560	0.45	0.044
3676	25.6	2.3	3	32.93	31.58	1664	5.00	1664	0.46	0.043
3677	27.2	2.3	3	35.23	34.14	1768	5.00	1768	0.46	0.042
3678	28.8	2.3	3	37.58	36.75	1872	5.00	1872	0.47	0.040
3679	30.4	2.3	4	39.97	39.41	1328	5.00	1328	0.45	0.038
3680	32.0	2.3	4	42.42	46.88	1398	0.25	1398	0.07	0.036
3681	33.6	2.3	4	44.91	46.88	1468	3.03	1468	0.38	0.033
3682	35.2	2.3	4	47.47	46.88	1538	5.87	1538	0.50	0.030
3683	36.7	2.3	4	50.08	46.88	1608	8.77	1608	0.67	0.027
3684	38.3	2.3	4	52.75	46.88	1677	11.73	1677	0.81	0.024
3685	39.9	2.3	4	55.48	46.88	1747	14.77	1747	1.01	0.022
3686	41.5	2.3	4	58.28	46.88	1817	17.88	1817	1.26	0.019

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
3687	43.1	2.3	4	61.15	46.88	1887	21.07	1887	1.54	0.016
3688	44.7	2.3	4	64.09	46.88	1957	24.33	1957	1.87	0.013
3689	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.013
3689	44.7	0.0	4	18.17	-4.14	1957	24.33	1957	1.87	0.013

DO YOU WANT TO CONTINUE WITH MORE CYCLES...

>no

-----HEAT ENGINE-----					
FUEL MI/GAL	PWR AVER	OUT,HP PEAK	AVE EFF PERCENT	ENGINE NAME	HYBRID STRATEGY
26.5	13.8	24.3	23.8	NADSL	CBTOUT

TOTAL RANGE MI	ELECT CONSM AT WALL WH/MI	ELECT COST (AT 4.0C/KWH) C/MI	FINAL STATE BATT STR DEV WH
0.0	211	82	0.85 0.020 1000.

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 31 CYCLES

Figure 2-7F. CBTOUT Hybrid Strategy J227D, Detail During 30th Cycle (Cont'd)

INPUT CHANGES FOR NEXT RUN-
 >namcyc conspd speed 35mph tstrc 50 tftrc 60 run
 INPUT COMPLETE FOR THIS CASE
 INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
 >cbtout hybrid strategy, constant speed at 35 mi/hr.....

CBTOUT HYBRID STRATEGY, CONSTANT SPEED AT 35 MI/HR.....
 DATE 07/07/78
 TIME 15.26.05

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
50	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.976
51	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.975
52	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.975
53	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.975
54	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.975
55	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.974
56	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.974
57	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.974
58	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.973
59	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.973
60	35.0	0.0	4	11.30	12.56	1531	0.0	0	0.0	0.973

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE
60	0.875	242.1	242.1	8.4	CONSPD

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-

	AERO	TIRES	BRAKES	DRVLNE	MTR/CNTR	STR DEV	CLUTCH	HT ENG	BATT SYS
WH-	86	125	0	23	66	0	0	0	171
PRCNT	18.2	26.5	0.0	5.0	14.0	0.0	0.0	0.0	36.3

-----BATTERY-----
 ENR OUT ENR IN PD OUT HX PD IN HX
 WH/MI W/LB
 344.9 0.0 11.5 0.0
 DO YOU WANT TO CONTINUE WITH MORE CYCLES...
 >no

TOTAL RANGE MI	ELECT CONSM AT WALL WH/MI WH/MI*TON	ELECT COST (AT 4.0C/KWH) C/MI	FINAL STATE BATT STR DEV WH
0.9	541	210	2.16 0.973 1000.

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 1 CYCLES

Figure 2-7G. CBTOUT Hybrid Strategy, Constant Speed at 35 mph

```

INPUT CHANGES FOR NEXT RUN-
2 >namhyb fordb namhe turbodsl namclc drcoup acifac .7 namcyc j227d
3 >frchep .6 nregen 2 jbtchg 1 btmax 1 btmin .8
4 >detail 1 tstrc 1098 tftrc 1195 tstop 10000 run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>ford-b hybrid strategy, j227-d cycle, 10th cycle.....

```

```

FORD-B HYBRID STRATEGY, J227-D CYCLE, 10TH CYCLE.....
DATE 07/07/78
TIME 15.29.59

```

```

11 TIME/ RANGE/ ROAD ENERGY MAX ROAD DRIVING
    CYC CYCLE W/O RGN W RGN POWER SCHEDULE
    SEC MI WH/MI KW
    122 0.991 389.1 297.8 40.1 J227D

```

```

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
AERO TIRES BRAKES DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG BATT SYS
WH- 139 142 81 51 46 0 0 888 52
PRCNT 9.9 10.2 5.8 3.7 3.3 0.0 0.0 63.4 3.7

```

```

-----BATTERY-----
ENR OUT ENR IN PD OUT MX PD IN MX
WH/MI W/LB

```

```

22 145.8 53.3 31.5 38.6
DO YOU WANT TO CONTINUE WITH MORE CYCLES...
>yes
HOW MANY MORE CYCLES...
26 >9

```

Figure 2-8A. FORDB Hybrid Strategy J227D, Detail During Cycle

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
1098	0.0	0.0	1	0.0	0.0	0	0.0	0	0.0	1.002
1099	2.2	3.1	1	3.41	5.31	440	0.0	440	0.0	1.002
1100	4.3	3.1	1	6.60	0.0	870	7.34	870	0.57	1.002
1101	6.4	3.0	1	9.60	0.0	1289	10.66	1289	0.75	1.002
1102	8.4	2.9	1	12.41	0.0	1699	13.79	1699	0.89	1.002
1103	10.4	2.9	2	15.05	0.21	1137	16.51	1137	1.17	1.002
1104	12.3	2.8	2	17.54	0.39	1349	19.10	1349	1.35	1.002
1105	14.2	2.7	2	19.89	0.78	1556	21.33	1556	1.51	1.002
1106	16.0	2.7	2	22.11	1.64	1757	22.92	1757	1.63	1.002
1107	17.8	2.6	2	24.21	2.41	1954	24.48	1954	1.74	1.002
1108	19.5	2.5	2	26.20	3.10	2146	26.01	2146	1.84	1.002
1109	21.2	2.5	3	28.08	11.59	1382	19.61	1382	1.39	1.002
1110	22.9	2.4	3	29.87	12.27	1490	20.93	1490	1.49	1.001
1111	24.5	2.4	3	31.58	13.31	1596	21.77	1596	1.55	1.001
1112	26.1	2.3	3	33.21	14.30	1699	22.60	1699	1.61	1.001
1113	27.7	2.2	3	34.76	15.21	1800	23.41	1800	1.66	1.000
1114	29.2	2.2	3	36.24	16.08	1899	24.19	1899	1.72	1.000
1115	30.6	2.1	4	37.67	22.70	1341	19.16	1341	1.36	0.999
1116	32.1	2.1	4	39.03	23.43	1404	19.94	1404	1.42	0.998
1117	33.5	2.0	4	40.34	24.13	1465	20.70	1465	1.47	0.998
1118	34.9	2.0	4	41.61	24.97	1525	21.26	1525	1.51	0.997
1119	36.2	1.9	4	42.82	25.85	1584	21.73	1584	1.55	0.996
1120	37.5	1.9	4	44.00	26.69	1641	22.19	1641	1.58	0.995
1121	38.8	1.9	4	45.14	27.51	1697	22.64	1697	1.61	0.994
1122	40.0	1.8	4	46.23	28.29	1752	23.08	1752	1.64	0.993
1123	41.3	1.8	4	47.30	29.04	1805	23.51	1805	1.67	0.992

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE---			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
1124	42.4	1.7	4	48.33	29.77	1857	23.93	1857	1.70	0.991
1125	43.6	1.7	4	49.34	30.48	1908	24.34	1908	1.73	0.990
1126	44.7	1.6	4	50.31	31.17	1957	24.74	1957	1.76	0.988
1127	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1127	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1128	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1129	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1130	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1131	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1132	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1133	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988

Figure 2-8B. FORDB Hybrid Strategy, J227D, Detail During 10th Cycle (Cont'd)

1134	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1135	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1136	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1137	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1138	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1139	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1140	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1141	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1142	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1143	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1144	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1145	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1146	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1147	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1148	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1149	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1150	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1151	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1152	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1153	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1154	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1155	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1156	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1157	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1158	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1159	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1160	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1161	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1162	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1163	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1164	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1165	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1166	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1167	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1168	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1169	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1170	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1171	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1172	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1173	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1174	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988

Figure 2-8C. FORDB Hybrid Strategy, J227D, Detail During 10th Cycle (Cont'd)

TIME SEC	SPEED MI/H	ACCL FT/S2	GEAR	ROAD LD HP	----MOTOR-----		----HEAT ENGINE----			BATTERY STATE
					PW,HP	SPD,RPM	PW,HP	RPM	FL,GPH	
1175	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1176	44.7	0.0	4	18.17	0.0	1957	20.19	1957	1.31	0.988
1177	44.1	-0.9	4	0.0	11.78	1930	0.0	1930	0.0	0.988
1177	44.1	-0.9	4	0.0	11.78	1930	0.0	1930	0.0	0.988
1178	43.5	-0.9	4	0.0	11.44	1903	0.0	1903	0.0	0.988
1179	42.9	-0.9	4	0.0	11.12	1876	0.0	1876	0.0	0.988
1180	42.3	-0.9	4	0.0	10.81	1850	0.0	1850	0.0	0.987
1181	41.7	-0.9	4	0.00	0.0	1824	0.00	1824	0.00	0.987
1182	41.1	-0.9	4	0.00	0.0	1798	0.00	1798	0.00	0.987
1183	40.5	-0.8	4	0.0	9.92	1773	0.0	1773	0.0	0.987
1184	40.0	-0.8	4	0.00	0.0	1748	0.00	1748	0.00	0.987
1185	39.4	-0.8	4	0.00	0.0	1723	0.00	1723	0.00	0.987
1186	38.8	-0.8	4	0.00	0.0	1699	0.00	1699	0.00	0.987
1187	34.5	-6.3	4	-84.70	-91.54	1510	0.82	1510	0.18	0.987
1187	34.5	-6.3	4	-84.70	-91.54	1510	0.82	1510	0.18	0.991
1188	30.2	-6.3	4	-75.01	-82.83	1322	9.53	1322	0.70	0.995
1189	25.9	-6.3	3	-64.97	-77.05	1685	13.95	1685	0.90	0.998
1190	21.6	-6.3	3	-54.62	-77.05	1404	12.32	1404	0.82	1.001
1191	17.3	-6.3	2	-44.00	11.38	1897	0.0	1897	0.0	1.001
1192	12.9	-6.3	2	-33.18	6.35	1423	0.0	1423	0.0	1.001
1193	8.6	-6.3	1	-22.21	9.66	1750	0.0	1750	0.0	1.001
1194	4.3	-6.3	1	-11.13	3.02	875	0.0	875	0.0	1.001
1195	0.0	-6.3	1	-0.00	0.00	0	0.0	0	0.0	1.001

DO YOU WANT TO CONTINUE WITH MORE CYCLES...

>no

-----HEAT ENGINE-----					
FUEL MI/GAL	PWR OUT,HP AVER	AVE EFF PEAK	AVE EFF PERCENT	ENGINE NAME	HYBRID STRATEGY
33.4	13.1	26.0	27.7	TURBODSL	FORDB

TOTAL RANGE MI	ELECT CONSM AT WALL WH/MI	ELECT COST (AT 4.0C/KWH) C/MI	FINAL STATE BATT STR DEV WH
0.0	90	35	1.001 1000.

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 10 CYCLES

Figure 2-8D. FORDB Hybrid Strategy J227D, Detail During 10th Cycle (Cont'd)

```

INPUT CHANGES FOR NEXT RUN-
>nanhe turbodsl  nanhyb cbtout  namclc trqcnv
>pdmax 0  run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>all heat engine example, j227-d cycle.....

```

```

ALL HEAT ENGINE EXAMPLE, J227-D CYCLE.....
DATE 07/07/78
TIME 15.39.49

```

```

10 NOTE-TORQUE CONVERTER DIAMETER HAS BEEN SCALED FROM 10.0 IN. TO 7.1 IN. TO
MATCH ENGINE POWER OF 69 HP AT A MAXIMUM SPEED OF 4999 RPM. IF YOU DO NOT
WANT TO HAVE AUTOMATIC SCALING OCCUR TYPE NO AND CARRIAGE RETURN. OTHERWISE
TYPE YES
AUTOMATIC SCALING...
15 >yes

```

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN WH/MI	MAX ROAD POWER KW	DRIVING SCHEDULE
122	0.991	389.1	297.8	40.1	J227D

```

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-
AERO TIRES BRAKES DRVLNE MTR/CNTR STR DEV CLUTCH HT ENG BATT SYS
UH- 139 142 90 51 2 0 170 1942 6
PRCNT 5.5 5.6 3.6 2.0 0.1 0.0 6.7 76.3 0.3

```

```

-----BATTERY-----
ENR OUT ENR IN PD OUT MX PD IN MX
WH/MI W/LB
11.9 0.0 9.7 0.0
DO YOU WANT TO CONTINUE WITH MORE CYCLES...
>yes
HOW MANY MORE CYCLES...
>9

```

Figure 2-9A. All Heat Engine Example, J227D

DO YOU WANT TO CONTINUE WITH MORE CYCLES...
 >no

```

-----HEAT ENGINE-----
  FUEL  PWR OUT,HP  AVE EFF  ENGINE  HYBRID
MI/GAL  AVER  PEAK  PERCENT  NAME  STRATEGY
  17.7   21.9  85.6   24.4  TURBODSL  CBTOUT
  
```

```

TOTAL      ELECT CONSM      ELECT COST      FINAL STATE
RANGE      AT WALL      (AT 4.0C/KWH)  BATT STR DEV
  MI      WH/MI  WH/MI*TON      C/MI      WH
  0.0      18      7      0.08      0.991  1000.
  
```

NOTE-RANGE NOT MEANINGFUL FOR HYBRID VEHICLE. ABOVE FIGURES BASED ON 10 CYCLES

Figure 2-9B. All Heat Engine Example, J227D (cont'd)

14.31.49 Delvripp
EXECUTION:

GRC ELECTRIC VEHICLE/BATTERY SIMULATION. VERSION3.2A 8/MAY/78 -

SPECIFY DESIRED OUTPUT UNITS - METRIC OR ENGLISH . . .

>e

INITIATING BULK READ-

FEDRAL CYCLE. 1372 VALUES READ.

HIWAY CYCLE. 766 VALUES READ.

CHANGES FOR THIS AND FOLLOWING RUNS-

WB=1300LB WT=3288LB ACLFAC=1.0 EFFCB=1 CDA=9.68FT2

ATIREF=1.2 EFFBC=.85 EFFCT=.9,.9,.9,.9

EFFCM=0.82 EFFCD=.75 NAMCYC=J227D NREGEN=2

GEAR=3.757,2.169,1.404,1.0 RATIO=.29,3.9,1

VELSCD=5.81,10.28,14.75 EFFCFW=0.622

CH=3.178,-0.7279,-0.05863

NCELLS=60 PWRHEN=7500. PDMAX=150. EFFALT=.75

END DATA

WARNING . . .THE VARIABLE DICTIONARY HAS BEEN CHANGED FOR THIS VERSION
(VERSION 3.2 10/MAR/78) OF ELVEC. A NEW DRIVING CYCLE IS AVAILABLE--
MAXACL (MAXIMUM ACCELERATION BEGINNING AT SPEED VINIT). ALSO FOUR TYPES
OF CLUTCHES ARE AVAILABLE--DIRECT COUPLING, MANUAL, TORQUE CONVERTER,
AND CVRT. THE BATTERY STATE LIMITS CAN NOW BE SPECIFIED (BTSMIN AND
BTSMAX).

NAMES OF AVAILABLE HEAT-ENGINE MAPS . . .

BS400 ON782 GM5735 HN1600 GMVEGA140 TR7

TURBODSL NADSL IDIDSL CWSTRATROT NSUAUDIROT

BULK READ COMPLETE-

INPUT CHANGES FOR NEXT RUN-

>namhyb cbtout namhe tr7 namclic manual namcyc maxacl delt 0.1

>vinit 0 speed 60mph velscd 15mph,30mph,50mph pdmax 0 nprint 10

>run

INPUT COMPLETE FOR THIS CASE

INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-

>wide open throttle example.....

WIDE OPEN THROTTLE EXAMPLE.....

DATE 06/26/78

TIME 14.34.32

Figure 2-10A. Variable Selection for Wide Open Throttle, PDMAX = 0

-----WIDE OPEN THROTTLE PERFORMANCE-----

TIME S	DIST FT	SPEED MI/HR	ACCEL GEES	LIMIT MECHNSM	BATTERY STATE	ENGINE OUTPT KW	ENGINE OUTPT HP	FLYWHL OUTPT HP	ROAD POWER HP
0.0	0	0.0	0.0		1.00	0.0	0.0	0.0	0.0
1.00	4	6.3	0.27	ENGINE	1.00	0.0	17.8	0.0	16.0
2.00	18	11.8	0.23	ENGINE	1.00	0.0	29.2	0.0	26.3
2.64	30	15.0	0.23	ENGINE	1.00	0.0	36.3	0.0	32.6
2.84	35	14.9	-0.01	COAST	1.00	0.0	0.0	0.0	0.0
2.84	35	14.9	0.14	ENGINE	1.00	0.0	22.6	0.0	20.3
3.00	38	15.4	0.14	ENGINE	1.00	0.0	23.2	0.0	20.9
4.00	63	18.4	0.13	ENGINE	1.00	0.0	26.8	0.0	24.1
5.00	92	21.2	0.13	ENGINE	1.00	0.0	30.3	0.0	27.3
6.00	125	24.0	0.12	ENGINE	1.00	0.0	33.8	0.0	30.4
7.00	162	26.7	0.12	ENGINE	1.00	0.0	37.2	0.0	33.5
8.00	203	29.3	0.12	ENGINE	1.00	0.0	40.6	0.0	36.6
8.26	214	30.0	0.12	ENGINE	1.00	0.0	41.5	0.0	37.3
8.46	223	29.9	-0.02	COAST	1.00	0.0	0.0	0.0	0.0
8.46	223	29.9	0.07	ENGINE	1.00	0.0	27.9	0.0	25.1
9.00	247	30.8	0.07	ENGINE	1.00	0.0	28.7	0.0	25.8
10.00	294	32.4	0.07	ENGINE	1.00	0.0	30.1	0.0	27.1
11.00	342	34.0	0.07	ENGINE	1.00	0.0	31.4	0.0	28.2
12.00	393	35.6	0.07	ENGINE	1.00	0.0	32.6	0.0	29.4
13.00	447	37.1	0.07	ENGINE	1.00	0.0	33.9	0.0	30.5
14.00	502	38.6	0.07	ENGINE	1.00	0.0	35.1	0.0	31.6
15.00	560	40.1	0.07	ENGINE	1.00	0.0	36.3	0.0	32.7
16.00	620	41.5	0.07	ENGINE	1.00	0.0	37.5	0.0	33.8
17.00	682	43.0	0.06	ENGINE	1.00	0.0	38.7	0.0	34.8
18.00	746	44.4	0.06	ENGINE	1.00	0.0	39.9	0.0	35.9
19.00	812	45.7	0.06	ENGINE	1.00	0.0	41.0	0.0	36.9
20.00	880	47.1	0.06	ENGINE	1.00	0.0	42.2	0.0	37.9
21.00	950	48.4	0.06	ENGINE	1.00	0.0	43.3	0.0	38.9
22.00	1022	49.7	0.06	ENGINE	1.00	0.0	44.4	0.0	39.9
22.20	1037	50.0	0.06	ENGINE	1.00	0.0	44.6	0.0	40.1
22.40	1051	49.9	-0.03	COAST	1.00	0.0	0.0	0.0	0.0
22.40	1051	49.9	0.04	ENGINE	1.00	0.0	32.5	0.0	29.2
23.00	1095	50.3	0.03	ENGINE	1.00	0.0	32.9	0.0	29.6
24.00	1170	51.1	0.03	ENGINE	1.00	0.0	33.3	0.0	30.0
25.00	1245	51.8	0.03	ENGINE	1.00	0.0	33.7	0.0	30.3
26.00	1322	52.6	0.03	ENGINE	1.00	0.0	34.1	0.0	30.7
27.00	1399	53.3	0.03	ENGINE	1.00	0.0	34.5	0.0	31.1
28.00	1478	54.0	0.03	ENGINE	1.00	0.0	35.0	0.0	31.5
29.00	1558	54.7	0.03	ENGINE	1.00	0.0	35.4	0.0	31.8
30.00	1638	55.3	0.03	ENGINE	1.00	0.0	35.7	0.0	32.2
31.00	1720	56.0	0.03	ENGINE	1.00	0.0	36.1	0.0	32.5
32.00	1803	56.6	0.03	ENGINE	1.00	0.0	36.5	0.0	32.9
33.00	1886	57.3	0.03	ENGINE	1.00	0.0	36.9	0.0	33.2
34.00	1971	57.9	0.03	ENGINE	1.00	0.0	37.3	0.0	33.5
35.00	2056	58.5	0.03	ENGINE	1.00	0.0	37.6	0.0	33.9
36.00	2142	59.1	0.03	ENGINE	1.00	0.0	38.0	0.0	34.2
37.00	2229	59.7	0.03	ENGINE	1.00	0.0	38.3	0.0	34.5
37.58	2280	60.0	0.03	ENGINE	1.00	0.0	38.5	0.0	34.6

Figure 2-10B. All Heat Engine Wide Open Throttle

INPUT CHANGES FOR NEXT RUN-
>vinit 20.7mph speed 35.2mph run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>passing performance example.....

PASSING PERFORMANCE EXAMPLE.....
DATE 06/26/78
TIME 14.40.04

-----WIDE OPEN THROTTLE PERFORMANCE-----

TIME	DIST	SPEED	ACCEL	LIMIT	BATTERY	ENGINE	FLYWHL	ROAD
S	FT	MI/HR	GEES	MECHNSM	STATE	OUTPT	OUTPT	POWER
						KW	HP	HP
0.0	0	20.7	0.0		1.00	0.0	3.1	2.8
1.00	32	23.5	0.12	ENGINE	1.00	0.0	33.2	29.9
2.00	68	26.2	0.12	ENGINE	1.00	0.0	36.6	33.0
3.00	109	28.9	0.12	ENGINE	1.00	0.0	40.0	36.0
3.43	127	30.0	0.12	ENGINE	1.00	0.0	41.4	37.3
3.63	136	29.9	-0.02	COAST	1.00	0.0	0.0	0.0
3.63	136	29.9	0.07	ENGINE	1.00	0.0	27.9	25.1
4.00	152	30.5	0.07	ENGINE	1.00	0.0	28.5	25.6
5.00	198	32.1	0.07	ENGINE	1.00	0.0	29.8	26.9
6.00	247	33.7	0.07	ENGINE	1.00	0.0	31.1	28.0
6.94	294	35.2	0.07	ENGINE	1.00	0.0	32.2	29.0

Figure 2-10C. Passing-Time and Distance-All Heat Engine

INPUT CHANGES FOR NEXT RUN-
 >pdmax 150 run
 INPUT COMPLETE FOR THIS CASE
 INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
 >hybrid wide open throttle example.....

HYBRID WIDE OPEN THROTTLE EXAMPLE.....
 DATE 06/26/78
 TIME 14.41.35

-----WIDE OPEN THROTTLE PERFORMANCE-----

TIME S	DIST FT	SPEED MI/HR	ACCEL GEES	LIMIT MECHNSM	BATTERY STATE	ENGINE OUTPT KW	FLYWHL OUTPT HP	ROAD POWER HP
0.0	0	20.7	0.0		1.00	2.8	0.0	2.8
0.88	32	30.0	0.44	ENGINE	0.99	88.5	41.5	124.9
1.08	41	29.9	-0.02	COAST	0.99	0.0	0.0	0.0
1.08	41	29.9	0.40	ENGINE	0.99	88.5	27.9	112.7
1.74	72	35.2	0.35	ENGINE	0.99	88.5	32.5	116.8

Figure 2-10D. Passing Time and Distance - Hybrid Mode

```

INPUT CHANGES FOR NEXT RUN-
>vinit 0 speed 35mph run
INPUT COMPLETE FOR THIS CASE
INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
>hybrid wide open throttle example .....

```

```

HYBRID WIDE OPEN THROTTLE EXAMPLE .....
DATE    06/26/78
TIME    14.42.54

```

-----WIDE OPEN THROTTLE PERFORMANCE-----

TIME S	DIST FT	SPEED MI/HR	ACCEL GEES	LIMIT MECHNSM	BATTERY STATE	BATTERY OUTPT KW	ENGINE OUTPT HP	FLYWHL OUTPT HP	ROAD POWER HP
0.0	0	0.0	0.0		1.00	0.0	0.0	0.0	0.0
1.00	8	11.0	0.50	SLIP	1.00	51.3	0.0	0.0	50.8
1.37	15	15.0	0.50	SLIP	1.00	70.3	0.0	0.0	69.5
1.57	19	14.9	-0.01	COAST	1.00	0.0	0.0	0.0	0.0
1.57	19	14.9	0.50	SLIP	1.00	70.0	0.0	0.0	69.3
2.00	30	19.7	0.50	SLIP	0.99	88.5	4.4	0.0	91.5
2.97	65	30.0	0.44	ENGINE	0.99	88.5	41.5	0.0	124.9
3.17	74	29.9	-0.02	COAST	0.99	0.0	0.0	0.0	0.0
3.17	74	29.9	0.40	ENGINE	0.99	88.5	27.9	0.0	112.7
3.80	104	35.0	0.35	ENGINE	0.98	88.5	32.2	0.0	116.5

Figure 2-10E. Zero to 30 mph Hybrid Mode

INPUT CHANGES FOR NEXT RUN-
 >pdmax 0 run
 INPUT COMPLETE FOR THIS CASE
 INPUT A 1-78 CHARACTER TITLE FOR THIS CASE-
 >all heat engine wide open throttle example.....

ALL HEAT ENGINE WIDE OPEN THROTTLE EXAMPLE.....
 DATE 06/26/78
 TIME 14.44.15

-----WIDE OPEN THROTTLE PERFORMANCE-----

TIME S	DIST FT	SPEED MI/HR	ACCEL GEES	LIMIT MECHNSM	BATTERY STATE	ENGINE OUTPT KW	FLYWHL OUTPT HP	ROAD POWER HP
0.0	0	0.0	0.0		1.00	0.0	0.0	0.0
1.00	4	6.3	0.27	ENGINE	1.00	0.0	17.8	16.0
2.00	18	11.8	0.23	ENGINE	1.00	0.0	29.2	26.3
2.64	30	15.0	0.23	ENGINE	1.00	0.0	36.3	32.6
2.84	35	14.9	-0.01	COAST	1.00	0.0	0.0	0.0
2.84	35	14.9	0.14	ENGINE	1.00	0.0	22.6	20.3
3.00	38	15.4	0.14	ENGINE	1.00	0.0	23.2	20.9
4.00	63	18.4	0.13	ENGINE	1.00	0.0	26.8	24.1
5.00	92	21.2	0.13	ENGINE	1.00	0.0	30.3	27.3
6.00	125	24.0	0.12	ENGINE	1.00	0.0	33.8	30.4
7.00	162	26.7	0.12	ENGINE	1.00	0.0	37.2	33.5
8.00	203	29.3	0.12	ENGINE	1.00	0.0	40.6	36.6
8.26	214	30.0	0.12	ENGINE	1.00	0.0	41.5	37.3
8.46	223	29.9	-0.02	COAST	1.00	0.0	0.0	0.0
8.46	223	29.9	0.07	ENGINE	1.00	0.0	27.9	25.1
9.00	247	30.8	0.07	ENGINE	1.00	0.0	28.7	25.8
10.00	294	32.4	0.07	ENGINE	1.00	0.0	30.1	27.1
11.00	342	34.0	0.07	ENGINE	1.00	0.0	31.4	28.2
11.63	374	35.0	0.07	ENGINE	1.00	0.0	32.1	28.9

Figure 2-10F. Zero to 30 mph, Heat Engine Only

APPENDIX A

THE VARIABLE DICTIONARY

Figures A1-A through A1-E list the simulation variables (as defined for ELVEC) which are available for the user to change. Table A-1 lists the vehicle dependent values for the Ripp and GE electrics, and the Garrett electric/flywheel vehicles.

All calculations are performed in ELVEC using the metric units defined in the right-hand column of Figure A1-A, lines 32 through 46. The user can specify different units when changing variables, but the variable units and unit format are restricted to those given in the left-hand column in the same figure. For example, if the user wishes to input a new drag coefficient-frontal area product in English units, he can type the following, where $\text{\textcircled{cr}}$ is the symbol for the "return" key (carriage return) on the terminal:

CDA 8FT2 $\text{\textcircled{cr}}$

This value of 8.0 ft^2 is converted by the program to 0.743224 m^2 , using the scale factor indicated on line 35 of Figure A1-A. Note that a space must be placed between the last character of the variable name and the first number of the variable value. A space between the last number of the variable value and the first letter of the unit name is optional.

If the user wishes to input several variable changes, he can either use the return key after each selection, or he can concatenate several variables on the same line. For example, the user can designate changes for the drag coefficient-frontal area product, vehicle weight, battery model, heat engine, and hybrid strategy by listing each change separately;

CDA 8FT2
WT 1270.06
MDLBAT FRCTUT
NAMHE TR7
NAMHYB FXOP

cr
cr
cr
cr
cr

or the user can effect the same changes by:

CDA 8FT2, WT 1270.06, MDLBAT FRCTUT, NAMHE TR7, NAMHYB FXOP

cr

Note that no units were designated for the vehicle weight (WT), indicating that the default unit is implied, i.e., kilograms. The user could have specified 2800LB. Also note that each variable is delimited by a comma. There is no limit to the number of variable changes or the number of lines. When the user is finished specifying the changes for the next run, he types:

RUN

cr

This is indicated on line 26 of Figure A1-A.

If the user wishes to reinstate all of the bulk data values, he can type:

RESTART

cr

as indicated on line 25. After the user specifies the desired variable changes, and either prior to typing RUN or immediately after the simulation, he may obtain a list of the variable values for the particular simulation by typing:

LIST

cr

An example of such a list is illustrated in Figure A-2.

When the user wishes to terminate the simulation session, he types:

QUIT

(cr)

or STOP

(cr)

and can then log off the network as previously indicated in Section I.

Figures A1-B through A1-E list all the variables and arrays, with their definitions. Any or all of these parameters can be changed by the user. The default values of the single variables (Non-array variables) are listed in the far right-hand columns of the figures.

Table A-1. Vehicle-Unique Parameters

Variable Name	Vehicle		
	Ripp Electric ELVRIPP	General Electric ELVGE	Garrett AiResearch ELVAIR
ACLFAC	1.0	1.0	1.0
ATIREF	1.2	1.11	1.11
CDA	9.68 ft ²	5.8 ft ²	8.0 ft ²
EFFCFW	---	---	0.622
NREGEN	2	2	3
WB	1300 lb	1092 lb	1040 lb
WFW	---	---	126 kg
WT	3288 lb	3708 lb	3466 lb
EFFCT	0.9, 0.9, 0.9, 0.9	0.9, 0.9, 0.9, 0.9	0.96, 0.96, 0.96, 0.96
GEAR	{ 3.757, 2.169, 1.404, 1.0	1.0, 1.0, 1.0, 1.0	1.0, 1.0, 1.0, 1.0
RATIO	0.290, 3.90, 1.0	0.281, 5.48, 0.0	0.281, 5.48, 0.0
VELSCD	5.81, 10.28, 14.75	100., 100., 100.	100., 100., 100.
EFFCM	0.82	0.82	1.0
CH	{ 3.178, -0.7279, -0.05863	3.3282, -0.68459, -0.021946	3.337, -0.57519, -0.064065

14.46.33 >print vardir data

ELVEC VERSION 3.2A

08 MAY 78

THIS VERSION INCORPORATES THE HYBRID MODEL UTILIZING HEAT-ENGINE MAPS READ FROM THE BULK DATA FILE. THE BULK DATA FILE NOW INCLUDES ALL OF THE AVAILABLE HEAT-ENGINES. THE HYBRID MODELS ARE INVOLVED BY SETTING THE NEW INPUT VARIABLE =NAMHYB= TO ONE OF THREE STRATEGIES---

CBTOUT CONSTANT BATTERY OUTPUT (HEAT ENGINE PEAKING)
FORDB MODIFIED FORD B
FXOP FIXED OPERATING POINT (BATTERY PEAKING)

AS IN VERSIONS 2.0 - 2.3 A HEAT ENGINE MUST BE INVOLVED WITH THE HYBRID OPTIONS BY SETTING THE VARIABLE =NAHHE= TO ONE OF THE HEAT ENGINES AVAILABLE (PRINTED AT THE BEGINNING OF THE RUN).

14 DICTIONARY OF KEYWORDS AND OPTIONAL UNIT-NAMES - ELVEC VERSION 3.2

15 KEYWORD PROGRAM ACTION

17 CHGENG CHANGE ONE OF THE KATHE ARRAY VALUES FOR A HEAT ENGINE
END EXECUTE CASE WITH CURRENT DATA
END DATA EXECUTE CASE WITH CURRENT DATA
20 HELIST LIST HEAT-ENGINE DATA FOR ALL HEAT-ENGINE MAPS AVAILABLE
(VALUES PRINTED FOR EACH ENGINE ARE SAME VALUES AND IN
SAME SEQUENCE AS READ FROM BULK DATA FILE)
23 LIST LIST ALL PROGRAM VARIABLES AND ARRAYS AND THEIR VALUES
24 QUIT TERMINATE EXECUTION
25 RESTART IMMEDIATELY RE-INITIALIZE AND RESTART PROGRAM FROM BEGINNING
26 RUN EXECUTE CASE WITH CURRENT DATA
STOP TERMINATE EXECUTION
UNITNAME (FOLLOWED BY 1-4 CHAR. UNIT-NAME FOLLOWED BY ASSOCIATED
SCALING FACTOR) DEFINES (OR RE-DEFINES) A UNIT-NAME

30	UNIT-NAME	MEANING	SCALING FACTOR	TO CONVERT TO INTERNAL UNIT
	DEG	DEGREES	0.017453	RADIANS
	FT	FEET	0.3048	METERS
	FTLB	FEET-POUNDS	1.355866	NEWTON-METERS
35	FT2	FEET-SQUARED	0.092903	METERS-SQUARED
	HP	HORSEPOWER	746.0	WATTS
	KG	KILOGRAMS	1.	KILOGRAMS
	KPH	KILOMETERS/HOUR	0.277777	METERS/SECOND
	KM	KILOMETERS	1000.	METERS
	LB	POUNDS	0.453592	KILOGRAMS
	M	METERS	1.0	METERS
	NM	NEWTON-METERS	1.0	NEWTON-METERS
	MPH	MILES/HOUR	0.44704	METERS/SECOND
	PSF	POUNDS/SQ.FEET	4.882428	KILOGRAMS/SQ.METER
	RPM	REVS/MINUTE	0.104720	RADIANS/SEC
46	SEC	SECONDS	1.0	SECONDS

USER MAY DEFINE NEW UNIT-NAMES OR RE-DEFINE OLD ONES USING THE =UNITNAME= KEYWORD. A MAXIMUM OF 16 NEW NAMES IS PERMITTED.

Figure A1-A. Variable Dictionary

DICTIONARY OF INPUT VARIABLES - ELVEC VERSION 3.2

VARIABLE NAME	DESCRIPTION	DEFAULT VALUE
ACLFAC	RATIO OF FINAL TO AVERAGE VALUE FOR EXPONENTIALLY DECREASING ACCELERATION PROFILE	1.
AH20	20-HR AMP-HOUR RATING OF BATTERY *	21.54 A-H
AKCK	FACTOR USED IN KLECKNER MODEL *	4.713
ATIREF	TIRE FRICTION COEFFICIENT (PERCENT)	1.3 PERCENT
BTSMAX	MAXIMUM ALLOWABLE BATTERY STATE - BASED ON FRACTIONAL AMOUNT OF BATTERY WEIGHT REMAINING (HOXIE AND FRACTIONAL UTILIZATION MODELS). FRACTIONAL CHARGE REMAINING (KLECKNER MODEL, BASED ON 20 H RATE).	0.8
BTSMIN	MINIMUM ALLOWABLE BATTERY STATE - (SEE BTSMAX)	0.
CDA	DRAG-AREA PRODUCT	0.8993 M2
DELT	DRIVING CYCLE TIME-STEP	1. S
DETAIL	OUTPUT CONTROL (0=MINIMUM OUTPUT,1=INCLUDE TRACE OUTPUT) DEFAULT IS 0	0.
DTSHFT	TIME DELAY TO SHIFT GEARS DURING IN MAX. ACCEL RUNS	0.2 S
ECHO	FLAG (=ON= OR =OFF=) INDICATING WHETHER PROGRAM SHOULD REPEAT PRINT OF USER INPUTS.	OFF
EFCVRT	EFFICIENCY OF CONTINUOUSLY VARIABLE RATIO TRANSMISSION	0.8
EFFALT	EFFICIENCY(FRACTIONAL) OF ALTERNATOR/RECTIFIER USED WITH FXOP STRATEGY	0.75
EFFBC	EFFICIENCY OF BATTERY CHARGER(FRACTIONAL)	0.85
EFFCB	CHARGE-DISCHARGE EFFICIENCY OF BATTERY WHEN REGENERATIVE BRAKING IS USED	1.0
EFFCD	CHARGE-DISCHARGE EFFICIENCY OF BATTERY DURING NORMAL CHARGE-DISCHARGE CYCLES	0.75
EFFCFW	EFFICIENCY OF TRANSMISSION COUPLING FLYWHEEL WITH VEHICLE DRIVELINE	0.622
EFFCM	EFFICIENCY OF MOTOR(IF SET TO ZERO, THE MOTOR EFFICIENCY IS CALCULATED AT EACH TIME STEP. THIS REQUIRES THAT A DETAILED MOTOR MODEL BE PRESENT.)	0.
EK	FACTOR USED IN KLECKNER MODEL *	0.892
ENFWHL	USEABLE ENERGY IN FLYWHEEL FOR CONST. SPEED RUNS	3.6E6 JOULES
FRCHP	FRACTION OF MAXIMUM POWER AT WHICH ENGINE IS TO OPERATE WHEN BATTERY IS BEING CHARGED (FORDB AND CBTOUT STRATEGIES)	0.6
GRADE	ROADWAY GRADIENT(TANGENT OF SLOPE ANGLE, PERCENT)	0.
INFORM	FLAG (=CARD= FOR CARD-FORMAT INPUT, =FREE= FOR FREE-FORMAT INPUT)	FREE
ITTY	INTERACTIVE MODE FLAG(0=NON-INTERACTIVE, 1=INTERACTIVE)	1
JBTCHG	FLAG SET TO 1 IF ENGINE IS ALLOWED TO RECHARGE BATTERY IN FORDB STRATEGY (OTHERWISE ALL BATTERY RECHARGE COMES DURING REGENERATIVE BRAKING)	1
MDLBAT	FLAG (=FRCTUT= FOR FRACTIONAL UTILIZATION BATTERY DISCHARGE MODEL, =HOXIE= FOR HOXIE BATTERY DISCHARGE MODEL, OTHER FOR KLECKNER MODEL)	HOXIE
MDLMOT	=GESPEX= FOR G E SEPARATELY EXCITED MOTOR =AIRMOT= FOR AIR RESEARCH SEPARATELY EXCITED MOTOR	GESPEX
MOTYP	FLAG (=SERIES= FOR SERIES MOTOR, =SHUNT= FOR SEPARATELY EXCITED MOTOR)	SHUNT

Figure A1-B. Variable Dictionary (Cont'd)

NAMCLC	NAME OF CLUTCH...VALID NAMES ARE-	
	DRCOUP DIRECT COUPLING	
	MANUAL MANUALLY ACTUATED	
	TROCNV TORQUE CONVERTER	
	CVRT CONTINUOUSLY VARIABLE RATIO TRANSMISSION	
NAMCYC	DRIVING SCHEDULE . . .	J227B
	=J227A=,=J227B=,=J227C=,=J227D= (NEW SAE)	
	=MAXACL FOR MAXIMUM ACCELERATION RUNS	
	=SAERES=,=SAEMET= (OLD SAE)	
	=FEDRAL= (EPA URBAN)	
	=CONSPD= (CONSTANT SPEED)	
	=HTWAY= (EPA HIGHWAY)	
NAMHE	NAME OF HEAT-ENGINE TO USE (USED ONLY IF NAMHYB IS SET TO ONE OF THE ALLOWABLE OPTIONS). MUST CORRESPOND TO ONE OF THE HEAT ENGINES READ FROM THE BULK DATA FILE.	
NAMHYB	FLAG FOR HYBRID STRATEGY-	
	= FOR ELECTRIC OR FLYWHEEL ASSISTED VEHICLES	
	= FORDB FOR MODIFIED FORDB STRATEGY	
	= CBTOUT FOR CONSTANT BATTERY OUTPUT	
	= FXOP FOR FIXED OPERATING POINT	
NCELLS	NUMBER OF BATTERY CELLS *	60
NKLINE	NUMBER OF CHARACTERS/OUTPUT-LINE (PROGRAM RECOGNIZES 79 AND 131)	79
NPPFC	NUMBER OF POSITIVE PLATES/BATTERY-CELL *	9
NPRINT	NUMBER OF TIME STEPS BETWEEN OUTPUTS FOR DETAIL=1	1
NREGEN	REGENERATION FLAG (1= NO REGENERATIVE BRAKING, 2= REGENERATIVE BRAKING, 3= FLYWHEEL SYSTEM)	1
PMAX	MAXIMUM ALLOWABLE BATTERY SPECIFIC POWER DENSITY FOR EITHER DISCHARGE OR CHARGE (DURING VARIOUS HYBRID MODES).	150. W/KG
PMX2	POWER LEVEL OF BATTERY OUTPUT FOR NREGEN = 3 OPTION (IF UNKNOWN, THE PROGRAM ITERATES TO FIND PMX2, BUT THE COMPUTATION TAKES LONGER).	1. W
PROMPT	PROMPTING SYMBOL USED BY PROGRAM (UNLESS OVER-RIDDEN BY SYSTEM PROMPTING)	
PRHEN	HEAT ENGINE OUTPUT POWER SETTING FOR FXOP STRATEGY	7.5 KW
RF	MOTOR FIELD RESISTANCE	0.0164 OHMS
RI	BATTERY INTERNAL RESISTANCE/POSITIVE PLATE	0.009 OHMS
SPDHE	HEAT ENGINE SPEED SETTING FOR FXOP STRATEGY	3000. RPM
SPEED	SPEED FOR =CONSPD= DRIVING SCHEDULE	13.41 M/S
YCIN1	TORQUE CONVERTER INPUT INERTIA	0.108 KG-M2
YCIN2	TORQUE CONVERTER OUTPUT INERTIA	0.0203 KG-M2
YFTRC	TIME TO TERMINATE DETAILED (DETAIL=1) OUTPUT	1500. S
YD	TORQUE LOSS IN DIFFERENTIAL	0. N-M
YSTOP	MAXIMUM TIME TO TERMINATE COMPUTATION	1500. S
YSTRC	TIME TO BEGIN DETAILED (DETAIL=1) OUTPUT	0. S
VFWD	VOLTAGE DROP ACROSS FREE-WHEELING DIODE PARALLELING MOTOR (NOT PRESENTLY USED)	1. V
VINIT	INITIAL SPEED FOR MAX. ACCELERATION RUNS	0. M/S
VMINRG	MINIMUM SPEED AT WHICH REGENERATIVE BRAKING CAN OCCUR	0. M/S
VOC	BATTERY OPEN-CIRCUIT VOLTAGE PER CELL *	1.084 V
VSCR	VOLTAGE DROP ACROSS SILICON-CONTROLLED RECTIFIER IN CHOPPER-CONTROLLER (NOT PRESENTLY USED)	1.2 V
UTMIN	MINIMUM BATTERY VOLTAGE PER CELL	1.75 V
UB	BATTERY MASS	589.68 KG
UFW	MASS OF FLYWHEEL ENERGY STORAGE SYSTEM (USED ONLY TO COMPUTE POWER DENSITIES)	100. KG
WT	GROSS VEHICLE MASS (AS TESTED)	1191.44 KG
WRAT	RATIO OF EFFECTIVE TO STATIC MASS FOR VEHICLE	1.03

***** * - USED ONLY IN THE * E * * * * MODEL

Figure A1-C. Variable Dictionary (Cont'd)

DICTIONARY OF INPUT ARRAYS - ELVEC VERSION 3.2

ARRAY NAME	DESCRIPTION	DIMEN.
AF2I	COEFFICIENTS USED FOR DETAILED SIMULATION OF SERIES MOTOR TO CALCULATE THE CURRENT (I,AMPS) REQUIRED TO PRODUCE TORQUE (T,NEWTON-METERS) . . . $I = AF2I(1) + T*(AF2I(2) + T*(AF2I(3) + T*AF2I(4)))$ (NEEDED ONLY IF EFFCM IS ZERO)	(4)
ARES	COEFFICIENTS USED TO CALCULATE THE EQUIVALENT FIELD AND ARMATURE RESISTANCE (R,OHMS) FOR A GIVEN MOTOR SPEED (S,RADIANS/SEC) AND CURRENT (I,AMPS) . . . $R = ARES(1) + S*(ARES(2) + ARES(3)*(S/I)**2) + ARES(4)*(S/I)**2$ (NEEDED ONLY IF EFFCM IS ZERO)	(5)
CFI	COEFFICIENTS GIVING CAPACITY FACTOR FOR TORQUE CONVERTER. (HP/(RPM**3)) CFI(1) IS CAPACITY FACTOR AT ZERO TORQUE RATIO (STALL) CFI(2),TR(2), AND SRI(1) GO TOGETHER. CFI(3) IS THE CAPACITY FACTOR AT THE COUPLING POINT CFI(4) IS THE CAPACITY FACTOR AT SRI(3)(ABOUT HALF WAY BETWEEN SRI(2) AND UNITY)	(4)
CH	COEFFICIENTS USED TO CALCULATE THE BATTERY SPECIFIC POWER DENSITY (PD,WATTS/KG) WHICH A BATTERY CAN MAINTAIN FOR TIME (T,SEC) . . . $PD = EXP(CH(1) + CH(2)*ALOG(T/3600) + CH(3)*ALOG(T/3600)**2)$	(3)
DENS	DENS(1)=GASOLINE SPECIFIC GRAVITY DENS(2)=DIESEL FUEL SPECIFIC GRAVITY	(2)
EFFCT	EFFICIENCY OF TRANSMISSION FOR EACH GEAR SPEED (FRACTION)	(4)
FEEQV	FEEQV(1)=GASOLINE ENERGY EQUIVALENT(DEFAULT=46.7E6 J/KG) FEEQV(2)=DIESEL FUEL ENERGY EQUIVALENT(DEFAULT=45.6E6 J/KG)	(2)
GEAR	TRANSMISSION GEAR RATIO FOR EACH SPEED)	(4)
GECON	CONSTANTS NEEDED TO MODEL THE GENERAL ELECTRIC MOTOR (SEE SUBROUTINES CNTRLR AND GEMOT FOR THE MANNER IN WHICH THE CONSTANTS ARE USED)	(14)
RATIO	RATIO(1)=DRIVING WHEEL RADIUS, METERS RATIO(2)=DIFFERENTIAL RATIO, INPUT-SPEED/OUTPUT-SPEED RATIO(3)=NOT CURRENTLY USED	(3)

Figure A1-D. Variable Dictionary (Cont'd)

SRI	SPEED RATIO ARRAY FOR CFI AND TRI INPUTS SRI(1) CORRESPONDS TO CFI(2) AND TRI(2) SRI(2) IS THE SPEED RATIO AT THE COUPLING POINT SRI(3) CORRESPONDS TO CFI(4)	(3)
TOT	TORQUE LOSS IN TRANSMISSION(FOR EACH GEAR)	(4)
TRI	TORQUE RATIO ARRAY FOR TORQUE CONVERTER TRI(1) IS THE STALL TORQUE RATIO TRI(2) CORRESPONDS TO SRI(1) (NEAR THE SPEED RATIO FOR MAXIMUM CAPACITY FACTOR) TRI(3) IS THE COUPLING POINT TORQUE RATIO TRI(4) IS THE TORQUE RATIO AT UNITY SPEED RATIO	(4)
VELSCD	SPEED AT WHICH 2ND, 3RD, AND 4TH GEARS ARE ENGAGED(M/S)	(3)

Figure A1-E. Variable Dictionary (Cont'd)

List

SCALED VARIABLES FOR THIS RUN-

ACLFAC	1.000000	AH20	21.539993	AKCK	4.713000
ATIREF	1.200000	BTSMAX	0.800000	BTSMIN	0.0
CDA	0.899301	DELT	1.000000	DETAIL	0.0
BTSHFT	0.200000	ECHO	OFF	EFCVRT	0.800000
EFFALT	0.750000	EFFBC	0.850000	EFFCB	1.000000
EFFCD	0.750000	EFFCFW	0.622000	EFFCH	0.820000
EK	0.892000	ENFWHL	0.360000E+07	FRCHEP	0.600000
GRADE	0.0	INFORM	FREE	ITTY	1
JRTCHG	1	MDLBAT	FRCTUT	MDLHDT	GESPEX
MOTYP	SHUNT	NAMCLC	DRCOUP	NAMCYC	J227D
NAMHE		NAMHYB		NCELLS	60
NKLINE	79	NPPPC	9	NPRINT	1
NREGEN	2	PDMAX	150.000000	PMMX2	1.000000
PROMPT		PWRHEN	7500.00000	RF	0.164000E-01
RI	0.900000E-02	SPDHE	314.159912	SPEED	13.410000
TCIN1	0.108480	TCIN2	0.203400E-01	TFTRC	1500.00000
TDB	0.0	TSTOP	1500.00000	TSTRC	0.0
VFWD	1.000000	VINIT	0.0	VMINRG	0.0
VDC	2.064000	VSCR	1.200000	VTMIN	1.750000
WB	589.669434	WFW	126.000000	WT	1491.41040
XHRAT	1.030000				
AF2I	0.776461E+01		-0.561570E-01		0.229324E-03
	0.0				
ARES	0.797000E-01		0.0		0.0
	0.0		0.0		
CFI	0.297192E-02		0.275950E-02		0.195205E-02
	0.102572E-02				
CH	0.317800E+01		-0.727900E+00		-0.586300E-01
DENS	0.750000E+00		0.840000E+00		
EFFCT	0.900000E+00		0.900000E+00		0.900000E+00
	0.900000E+00				
FEEQV	0.467000E+08		0.456000E+08		
GEAR	0.375700E+01		0.216900E+01		0.140400E+01
	0.100000E+01				
GECON	0.414000E+00		0.170000E-02		0.730000E-01
	0.330000E-01		0.254000E-01		0.600000E-02
	0.276000E+01		0.356300E+02		0.314159E+03
	0.149200E+05		0.500500E+02		0.900600E+02
	0.412300E+01		0.488300E+01		
RATIO	0.290000E+00		0.390000E+01		0.100000E+01
SRI	0.472000E+00		0.842000E+00		0.920000E+00
TOT	0.0		0.0		0.0
	0.0				
TRI	0.245000E+01		0.155500E+01		0.998000E+00
	0.998000E+00				
VELSCD	0.581000E+01		0.102800E+02		0.147500E+02
XJ	0.0		0.0		0.0

Figure A-2. Output from "List"

APPENDIX B

OUTPUT VARIABLE DESCRIPTION

This appendix describes how the output from an all-electric simulation is calculated. Please refer to the sample output, Figure B-1. The different energies will be described mathematically, and the energy data from the sample output will be derived. Remember that all calculations are performed in the metric system, but that the output is scaled to give customary metric or English units. The variables described in this appendix are summarized in Table B-1.

1. Road energy without regeneration, E_{NRGN}

$$E_{NRGN} = \frac{C_1}{R} \int (P_{AERO} + P_{BRAKES} + P_{TIRES}) dt \quad \text{W.hr/mi} \quad (B1.1)$$

where

R = range covered during one cycle of the driving schedule, mi

P_{AERO} = power required to overcome aerodynamic drag, watts

P_{BRAKES} = power dissipated in the brakes

P_{TIRE} = power required to overcome rolling resistance, watts

C_1 = dimensional constant

From the sample output and output from the case where NREGEN = 1,

$$E_{NRGN} = (AERO + BRAKES + TIRES)/R \quad \text{W.hr/mi} \quad (B1.2)$$

where $E_{NRGN} = (81 + 60 + 75)/0.961 \quad \text{W.hr/mi}$

$= 224.8 \quad \text{W.hr/mi}$

NOTE: $P_{BRAKES} = 60 \text{ W.hr}$ when NREGEN = 1, otherwise $P_{BRAKES} = 0$

The difference between the computer output of 226.3 W.hr/mi (using equation [B1.1] and the hand calculation (equation [B1.2] of 224.8 W.hr/mi, a difference of 0.67% is due to the roundoff of quantities AERO, BRAKES and TIRES before they are printed.

2. Road energy with regeneration, E_{RGN}

$$E_{\text{RGN}} = \frac{C_1}{R} \int P_{\text{ROAD}} dt \quad (\text{B2.1})$$

where

$$P_{\text{ROAD}} = \text{Road load power}$$

From the sample output,

$$E_{\text{RGN}} = E_{\text{NRGN}} - \left[\frac{E_{\text{BATIN}}}{(\text{EFFCM} * \text{EFFCT})} \right] \quad \text{W.hr/mi} \quad (\text{B2.2})$$

where

$$\begin{aligned} E_{\text{NRGN}} &= \text{road energy without regeneration} \\ &= 226.3 \text{ W.hr/mi} \end{aligned}$$

$$\begin{aligned} E_{\text{BATIN}} &= \text{energy back to battery from regeneration} \\ &= 46.3 \text{ W.hr/mi} \end{aligned}$$

$$\begin{aligned} \text{EFFCM} &= \text{motor efficiency} \\ &= 0.82 \end{aligned}$$

$$\begin{aligned} \text{EFFCT} &= \text{transmission efficiency} \\ &= 0.9 \end{aligned}$$

$$\begin{aligned} E_{\text{RGN}} &= 226.3 - [46.3 / (0.82)(0.9)] \quad \text{W.hr/mi} \\ &= 163.6 \text{ W.hr/mi} \end{aligned}$$

3. Energy consumption at the wall, E_{WALL}

$$E_{\text{WALL}} = \frac{E_{\text{MC}} - \text{EFFCB} * E_{\text{IN}}}{R * \text{EFFBC} * \text{EFFCD}} \quad \text{W.hr/mi} \quad (\text{B3.1})$$

where

E_{MC} = energy taken from the battery to motor/controller, W.hr

EFFBC = battery charger efficiency
= 0.85

EFFCD = battery charge/discharge efficiency
= 0.75

EFFCB = charge efficiency during regeneration
= 1.0

E_{IN} = energy returned to battery from regeneration, W.hr

From the sample output,

$$E_{WALL} = \frac{E_o - \text{EFFCB} * E_{BATIN}}{\text{EFFBC} * \text{EFFCD}} \quad \text{W.hr/mi} \quad (\text{B3.2})$$

where

$E_o = E_{MC}/R \quad \text{W.hr/mi}$

and

$E_{BATIN} = E_{IN}/R \quad \text{W.hr/mi}$

Therefore,

$$\begin{aligned} E_{WALL} &= \frac{306.7 - (1.0)(46.3)}{(0.85)(0.75)} \quad \text{W.hr/mi} \\ &= 408 \quad \text{W.hr/mi} \end{aligned}$$

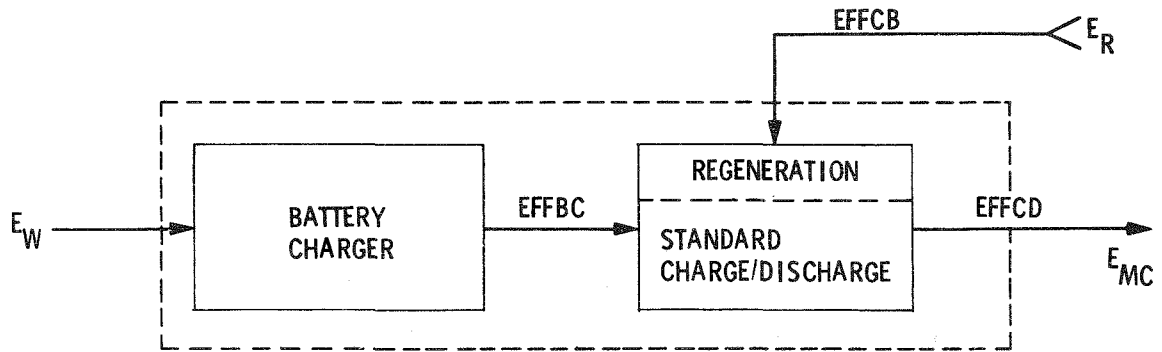
4. Energy cost, E_{COST}

$$E_{COST} = E_{WALL} \quad 4\text{¢}/1000 \quad \text{W.hr} \quad \text{¢/mi} \quad (\text{B.4.1})$$

From the sample output,

$$\begin{aligned} E_{COST} &= 408 * 4\text{¢}/1000 \\ &= 1.63 \text{ ¢/mi} \end{aligned}$$

5. Battery System losses energy, E_{BSL}
Refer to the diagram below:



$$E_W = (E_{WALL}) (\text{CYCLE RANGE}) = 392 \text{ W.hr}$$

EFFBC
EFFCD
EFFCB } Efficiencies as described in Appendix A

$$E_R = \text{regeneration energy, W.hr}$$

$$= (E_{BATIN}) (\text{cycle range}) = 44.5 \text{ W.hr}$$

$$E_{MC} = \text{energy to motor-controller, W.hr}$$

$$\text{Also, } E_{MC} = (E_R) (\text{EFFCB}) + (E_W) (\text{EFFBC}) (\text{EFFCD})$$

The battery system loss is

$$E_{BSL} = E_W + E_R - E_{MC} \quad \text{W.hr} \quad (\text{B5.1})$$

or

$$E_{BSL} = E_W + E_R - (E_R * \text{EFFCB} + E_W * \text{EFFBC} * \text{EFFCD}) \quad (\text{B5.2})$$

or

$$E_{BSL} = E_W (1 - \text{EFFBC} * \text{EFFCD}) + E_R (1 - \text{EFFCB}) \quad \text{W.hr} \quad (\text{B5.3})$$

$$= \frac{E_{MC} - E_R * \text{EFFCB}}{\text{EFFBC} * \text{EFFCD}} * (1 - \text{EFFBC} * \text{EFFCD})$$

$$+ E_R (1 - \text{EFFCB}) \quad \text{W.hr} \quad (\text{B5.4})$$

$$\begin{aligned}
&= E_{MC} \left(\frac{1}{\text{EFFBC} * \text{EFFCD}} - 1 \right) + E_R \\
&* \left(1 - \text{EFFCB} - \frac{\text{EFFCB}}{\text{EFFBC} * \text{EFFCD}} + \text{EFFCB} \right) \quad (\text{B5.5})
\end{aligned}$$

and finally,

$$\begin{aligned}
E_{BSL} &= E_{MC} \left(\frac{1}{\text{EFFBC} * \text{EFFCD}} - 1 \right) + E_R \\
&* \left(1 - \frac{\text{EFFCB}}{\text{EFFBC} * \text{EFFCD}} \right) \text{ W.hr} \quad (\text{B5.6})
\end{aligned}$$

From the example then,

$$\begin{aligned}
E_{BSL} &= (306.7) (0.961) \left(\frac{1}{(0.85)(0.75)} - 1 \right) \\
&+ (46.3) (0.961) \left(1 - \frac{1}{(0.85)(0.75)} \right) \text{ W.hr}
\end{aligned}$$

$$E_{BSL} = 142.4 \text{ W.h}$$

6. Battery output energy, E_{MC} , E_R

$$E_{MC} = C_2/R \int \text{MAX} [0, P_{BAT}] dt \quad \text{W.hr} \quad (\text{B6.1})$$

$$E_R = -C_2/R \int \text{MIN} [0, P_{BAT}] dt \quad \text{W.hr} \quad (\text{B6.2})$$

where

E_{MC} = energy furnished by the battery to the motor-controller, W.hr

E_R = energy furnished by the motor-controller (or alternator-rectifier) to the battery, W.hr

C_2 = dimension constant

P_{BAT} = instantaneous battery output power, watts

Table B-1. DEFINITION OF VARIABLES

AERO	Energy loss due to drag, W.hr
C_1	Constant to adjust units
C_2	Constant to adjust units
CYCLE RANGE	Driving schedule range (see R below), mi
E_o	Energy to motor-controller = E_{MC}/R W.hr/mi
E_{BATIN}	Energy back to battery from regeneration, W.hr/mi
E_{BSL}	Battery system energy losses, W.hr
E_{COST}	Energy cost at wall plug, ¢/mi
EFFBC	Battery charger efficiency, fraction
EFFCB	Charger efficiency, fraction
EFFCD	Battery charge/discharge efficiency, fraction
EFFCM	Motor efficiency, fraction
EFFCT	Transmission efficiency, fraction
E_{IN}	Energy returned to battery (CHARGER + REGEN), W.hr
E_{MC}	Energy to motor-controller, W.hr
E_{NRGN}	Road energy loss per cycle, without regeneration, W.hr
E_R	Regeneration energy, W.hr
E_{RGN}	Road energy loss per cycle with regeneration, W.hr
E_W	Energy wall cost, $E_W = (E_{WALL}) (R)$, W.hr
E_{WALL}	Energy consumption at wall plug, W.hr/mi
P_{AERO}	Power required to overcome aero drag, watts
P_{BAT}	Instantaneous battery power, watts
P_{BRAKES}	Power dissipated in the brakes, watts
P_{ROAD}	Power back into battery (regeneration), watts
P_{TIRES}	Power required to overcome rolling resistance, watts
R	Driving schedule range for one cycle, mi
TIRES	Energy loss due to rolling resistance, W.hr

OUTPUT VARIABLE DEFINITIONS.....

DATE 07/24/78
 TIME 10.05.37

TIME/ CYC SEC	RANGE/ CYCLE MI	ROAD ENERGY W/O RGN WH/MI	W RGN	MAX ROAD POWER KW	DRIVING SCHEDULE
122	0.961	226.3	163.6	29.9	J227D

ENERGY SUMMARY BASED ON INPUT TO CHARGER AND FUEL TANK USING FRCTUT MODEL-

	AERO	TIRES	BRAKES	DRVLNE	MTR/CNTR	STR DEV	CLUTCH	HT ENG	BATT SYS
WH- PRCNT	81 20.8	75 19.2	0 0.0	30 7.7	62 16.0	0 0.0	0 0.0	0 0.0	142 36.3

-----BATTERY-----

ENR OUT WH/MI	ENR IN	PD OUT HX W/LB	PD IN HX
306.7	46.3	31.1	26.5

TOTAL RANGE MI	ELECT CONSM AT WALL WH/MI	ELECT COST (AT 4.0C/KWH) C/MI	FINAL STATE BATT STR DEV WH
49.1	408	248	1.63
			0.0 1000.

Figure B-1. Output Variable Definitions

APPENDIX C

DATA STORED FOR HEAT ENGINES

There are eleven heat engines available for use by ELVEC. The operating data for these are summarized in the following figures. Any one of these can be used when a hybrid simulation is selected.

The heat engine maps are stored as arrays within the data files of the ELVEC program. To print these arrays, the user selects the engine of interest from Table C-1. The user types HELIST, as indicated in line 1 of Figure C-1. The system asks which engine, and the user types the appropriate choice, using the proper name indicated in Table C-1. Figure C-1 (the engine map for the Honda HN1600 engine) is used as an example to describe the engine map array and associated parameters.

Line 4 indicates the engine name. In line 5, the number 197 is an index number in the array named HETAB, and indicates where the data begins for this heat engine. The next number in the row (moving to the right) indicates that there are 10 limit boundary pairs. This can be seen in Figure C-2, where the data from Figure C-1 has been rearranged into a more conventional configuration. The next number in the row indicates that there are 9 fractional rpm rows within the actual map. Again, this can be seen in Figure C-2. The next number to the right in line 5 of Figure C-1 (the number 10) indicates the number of fractional power columns in the map. The next number (to the right) is a fuel flag: 1 for gasoline, 2 for diesel.

Moving down to the next row (line 6 of Figure C-1), the 5500 indicates the maximum rpm of the engine. The following numbers are defined for this row of Figure C-1:

<u>Number</u>	<u>Definition</u>
5500	Max rpm
50	Max power
1.05	Idle Fuel consumption
1.00	Torque multiplier
1000	FORDB cut-in engine rpm
0.0117	Fuel to start engine

<u>Number</u>	<u>Definition</u>
0.0400	Engine inertia
800.0	Idle rpm
0.0	Not used

Figure C-2 gives the units in the rearranged configuration.

Starting on line 7, the numbers appearing in each row are the specific fuel consumption for this particular engine and can be correlated with the rearranged array of Figure C-2.

Each engine map is stored in this manner, and computer rearrangements are illustrated in Figures C-3A through C-13B for user information.

Certain properties of the engines can be scaled, including maximum horsepower and maximum rpm. Other properties can be changed by the user. Table C-3 lists the elements of the heat engine catalog. Any element in this list may be changed, with the exception of element No. 5, which is locked out to the user. To change an element in KATHE (Table C-3), type "CHGENG." The program will guide the user.

Table C-1. Heat Engine Map Choices

Simulator Mfg/Designation	Displacement (cm ³)	HP at MAX RPM	Description
1. Briggs & Stratton BS400	400	11 at 3600	1 Cyl Horizontal
2. Onan ON782	782	14 at 3600	2 Cyl Opposed
3. General Motors GM5735	5736 (350 CID)	150 at 3800	V8 (1975)
4. Honda HN1600	1600	50 at 5500	Honda CVCC
5. General Motors GMVEGA140	2294	80 at 4000	GM VEGA, 140 CID, (1975)
6. Triumph TR7	2000	86 at 6000	Slant 4 Cyl
7. Volkswagen TURBODSL	1471	70 at 5000	VW Rabbit Diesel, Turbocharged
8. Volkswagen NADSL	1471	50 at 5000	VW Rabbit, Diesel, Naturally Aspirated
9. British Leyland IDIDSL (Rover)	2300	60 at 4000	Indirect Injection Diesel
10. Curtis Wright CWSTRATROT	983	75 at 4500	Stratified Charge Single Rotor Rotary
11. NSU/AUDI NSUAUDIROT	750/Rotor (1500 Total)	170 at 6500	2 Rotor Rotary

Table C-2. Tabulation of Heat Engine Data

Engine	HP	CID/ℓ	Idle		Fuel	
			RPM	Fuel Flow (lb/hr)	LB/GAL	Heat Value (Btu/lb)
Briggs & Stratton	11	0.4ℓ	1800	1.04-1.6	6.1	18900
Onan	14.4	48	1200	1.5-2.0	6.1	18900
GM 350 CID	150	350	800	4.9	6.1	18900
Honda CVCC	50	1.6ℓ	800	0.9-1.2	6.1	18900
GM 140 CID	95	140	850	2.2-2.7	6.1	18900
VW Rabbit Diesel TC	70	90	650	0.6	7.42	18390
VW Rabbit Diesel NA	50	90	650	0.6	7.42	18390
Rover Diesel	60	2.3ℓ	650	1.0	7.42	18390
C-W Stratified Rotary	75	60	500	1.0*	6.1	18900
NSU Rotary	170	3ℓ	700	3.0	6.1	18900
TR-7 Slant 4	86	122	950	2.3	6.1	18900

*Add 0.4 lb/hr for accessory, e.g., air conditioning

Table C-3. Kathe - The Heat Engine Catalog

Kathe Array Element	Type	Description
1 - 3	HOLLERITH	Name of the Ith engine (up to 10 characters)
4	HOLLERITH	Not used
5	INTEGER	Location of start-of-data for Ith engine (not available for user change)
6	INTEGER	Number of fractional peak horsepower/fractional rpm pairs in the engine map
7	INTEGER	Number of fractional rpm grid points in the engine map
8	INTEGER	Number of fractional horsepower grid points in the engine map
9	INTEGER	Fuel type (1 = gasoline, 2 = diesel)
10	REAL	Maximum rpm
11	REAL	Peak horsepower
12	REAL	Idle fuel consumption (gal/hr)
13	REAL	Factor for torque required to turn nonrunning engine (FORDB only), ft-lb
14	REAL	Speed at which the engine starts (FORDB only), rpm
15	REAL	Fuel to start engine, lb
16	REAL	Engine inertia, ft-lb-s ²
17	REAL	Engine idle speed, rpm
18	REAL	Not Used

1	HELIST									
2	WHICH ENGINE-									
3	>HM1600									
4	HM1600									
5	KATHE (5-18, 4) 197 10 9 10 1									
6	5500.0	50.0	1.05	1.06	1000.0	0.0117	0.0400	800.0	0.0	
7	0.2400	0.3700	0.5100	0.6500	0.7800	0.8700	0.9500	1.0000	0.9900	
	0.9600	0.1820	0.2730	0.3640	0.4550	0.5450	0.6360	0.7270	0.8180	
9	0.9090	1.0000	0.1820	0.3640	0.4550	0.5450	0.6360	0.7270	0.8180	
	0.9090	1.0000	0.1000	0.2000	0.3000	0.4000	0.5000	0.6000	0.7000	
11	0.2000	0.9000	1.0000	1.7000	1.9000	1.5000	1.9000	2.0000	2.0000	
	2.0000	2.0000	1.9600	0.9600	0.9500	0.8550	0.9750	1.0300	1.1200	
13	1.1400	1.4000	1.7000	0.8600	0.7900	0.6970	0.7950	0.7850	0.8650	
	0.8100	0.9750	1.4700	0.7600	0.7100	0.6100	0.6870	0.6590	0.7200	
15	0.6550	0.8250	1.2700	0.6550	0.6550	0.5540	0.6200	0.5810	0.6200	
	0.5850	0.7250	1.0900	0.5720	0.5470	0.5080	0.5600	0.5400	0.5500	
17	0.5840	0.6650	0.9420	0.5250	0.4910	0.4680	0.5100	0.5160	0.5160	
	0.5350	0.6250	0.8210	0.4990	0.4410	0.4400	0.4700	0.5050	0.5050	
19	0.5250	0.6250	0.7290	0.4890	0.4430	0.4400	0.4700	0.5000	0.5060	
	0.5250	0.6250	0.6640	0.4830	0.4850	0.4900	0.5500	0.5000	0.5000	
21	0.5250	0.6250	0.6270							

Figure C-1. Output from "Helist"

LIMIT BOUNDARY		FRACTIONAL POWER vs SPECIFIC FUEL CONSUMPTION									
hp/MAX hp	rpm/MAX rpm	.10	.20	.30	.40	.50	.60	.70	.80	.90	1.0
.24	.182	1.7	.98	.86	.76	.655	.572	.525	.499	.489	.483
.37	.273	-	-	-	-	-	-	-	-	-	-
.51	.364	1.9	.95	.79	.71	.655	.547	.491	.441	.443	.495
.65	.455	1.5	.855	.697	.61	.554	.508	.468	.44	.44	.49
.76	.545	1.9	.975	.795	.687	.62	.56	.51	.47	.47	.55
.87	.636	2.0	1.03	.785	.659	.581	.54	.516	.505	.5	.5
.95	.727	2.0	1.12	.865	.72	.62	.55	.516	.505	.506	.5
1.0	.818	2.0	1.14	.81	.655	.585	.554	.535	.525	.525	.525
.99	.909	2.0	1.4	.975	.825	.725	.665	.625	.625	.625	.625
.96	1.00	1.96	1.7	1.47	1.27	1.09	.942	.821	.729	.664	.627

ENGINE DISPLACEMENT	1600 cc
HETAB INDEX	197
OF LIMIT BOUNDARY PAIRS	10
FRACTIONAL SPEED ROWS	9
FRACTIONAL POWER COLUMNS	10
FUEL FLAG (1 = GASOLINE; 2 DIESEL)	1

MAX rpm	5500
MAX hp	50
IDLE FUEL CONSUMPTION	1.05 lb/hr
TORQUE MULTIPLIER	1.0
MIN rpm	1000
STARTUP FUEL	0.0117 lb
ENGINE INERTIA	0.0400 ft-s ²
IDLE rpm	800

Figure C-2. Engine: Honda CVCC (Rearranged Data from Figure C-1)

ENGINE: BS400

MAXIMUM POWER: 11.0 HP

MAXIMUM RPM: 3600.0

MINIMUM RPM: 1000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
1800.	5.	.5000	.4590
2098.	6.	.5830	.5730
2397.	7.	.6660	.6780
2700.	8.	.7500	.7920
2998.	9.	.8330	.8680
3301.	10.	.9170	.9410
3600.	11.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	2./ .250	POWER, 5./ .500	VALUE/ 8./ .750	FRACTION 11./ 1.000
1800./ .500	1.6700	1.0700	.9280	.8520
2098./ .583	1.5900	1.0900	.8900	.7940
2397./ .666	1.5100	1.0400	.8340	.7400
2700./ .750	1.4100	.9240	.7520	.6890
2998./ .833	1.3900	.8970	.7400	.6700
3301./ .917	1.3600	.8810	.7370	.6570
3600./ 1.000	1.4100	.9050	.7950	.6540

Figure C-3A. Engine Map, Briggs & Stratton - BS400

10
9
8
7
6
5
4
3
2
1
0
0.0

FUEL CONSUMPTION (LB/HP/HR)

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE BS400
NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

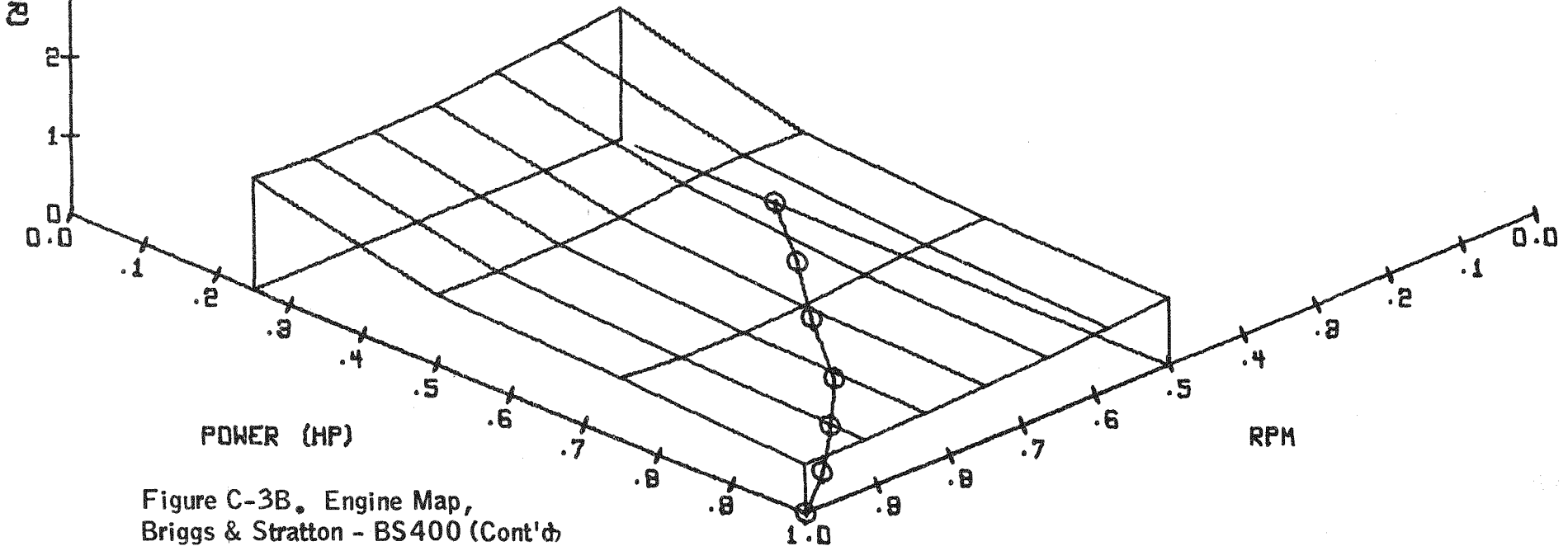


Figure C-3B. Engine Map,
Briggs & Stratton - BS400 (Cont'd)

ENGINE: ON782

MAXIMUM POWER: 14.4 HP

MAXIMUM RPM: 3600.0

MINIMUM RPM: 1000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
1598.	8.	.4440	.5680
1998.	9.	.5550	.6420
2199.	10.	.6110	.7100
2397.	11.	.6660	.7770
2599.	12.	.7220	.8410
2797.	12.	.7770	.8990
2998.	13.	.8330	.9390
3196.	14.	.8880	.9730
3398.	14.	.9440	.9930
3600.	14.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, VALUE/FRACTION	4./ .333	7./ .500	10./ .750	14./ 1.000
1598./ .444	1.0500	.9300	.8000	.7300	
1998./ .555	1.1500	.9500	.7850	.7000	
2397./ .666	1.1700	.9300	.7700	.7000	
2797./ .777	1.2000	.9250	.7700	.7000	
3196./ .888	1.2500	.9650	.8150	.7300	
3600./ 1.000	1.3600	1.0800	.8950	.7600	

Figure C-4A. Engine Map, Onan - ON782

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE ON782
 NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
 UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

C-11

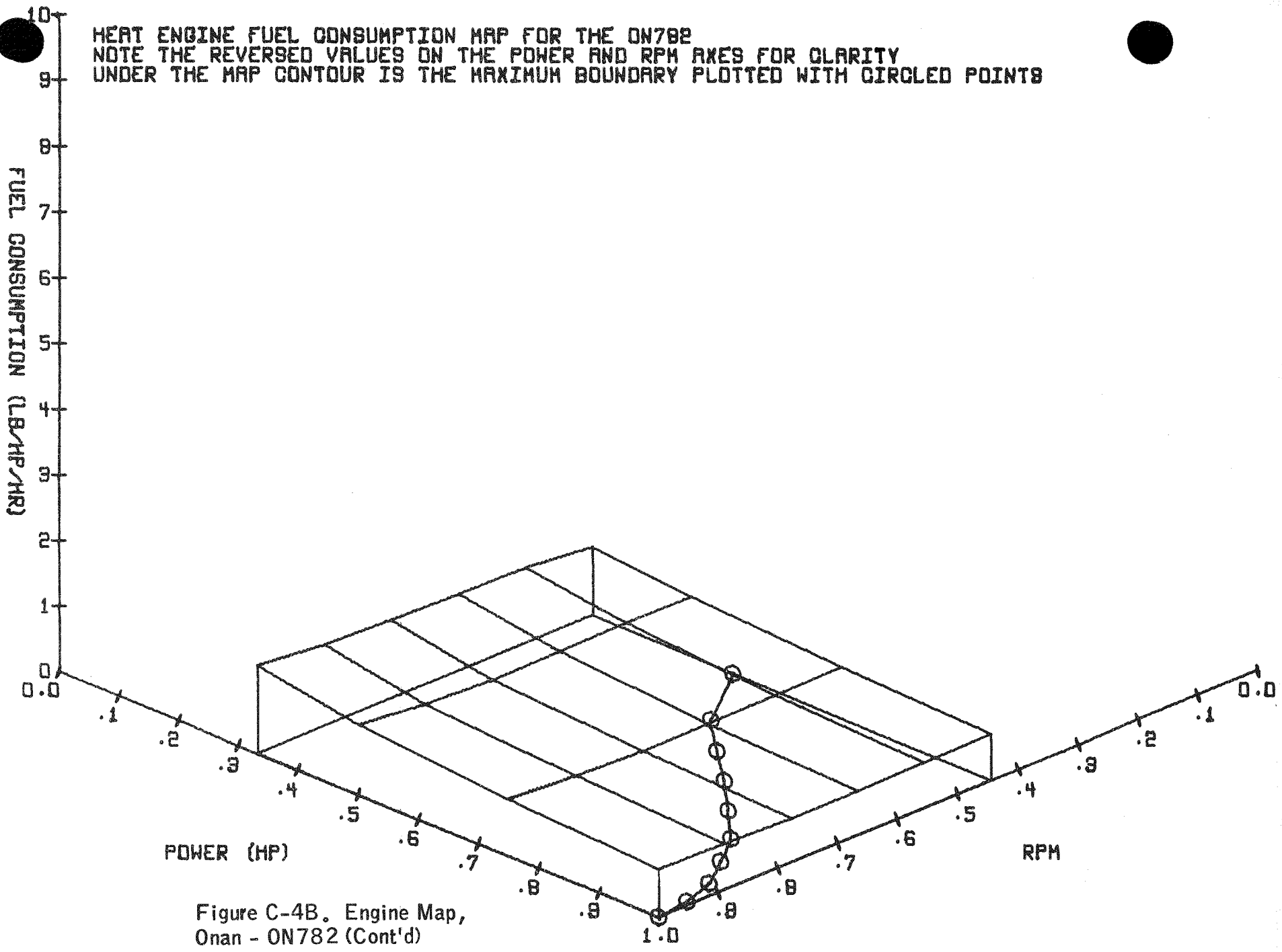


Figure C-4B. Engine Map,
 Onan - ON782 (Cont'd)

ENGINE: GM5735

MAXIMUM POWER: 150.0 HP

MAXIMUM RPM: 3800.0

MINIMUM RPM: 1000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
190.	4.	.0500	.0300
999.	42.	.2630	.2840
1299.	58.	.3420	.3900
1497.	72.	.3940	.4800
1900.	96.	.5000	.6440
2200.	111.	.5790	.7410
2800.	132.	.7370	.8810
3298.	144.	.8680	.9600
3800.	150.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, VALUE/FRACTION	15./	37./	60./	90./	112./	150./
4./	15./						
.030	.100	.250	.400	.600	.750	1.000	
999./	3.4100	.9540	.8330	.5690	.5420	.5230	.5480
.263	5.3000	1.4800	.6980	.5420	.4770	.4630	.5380
1299./	3.6800	1.3100	.7910	.5120	.5260	.5440	.4420
.342	3.9200	1.3600	.7150	.5520	.5000	.5110	.5060
1497./	3.5600	1.3300	.7160	.5300	.5380	.4930	.4970
.394	5.0800	1.5700	.8220	.5250	.5270	.5320	.5110
1900./	4.0700	1.5400	.8830	.6940	.5860	.5450	.5360
.500	5.5500	1.7600	.8040	.6920	.6290	.6180	.5610
2200./							
.579							
2800./							
.737							
3298./							
.868							
3800./							
1.000							

Figure C-5A. Engine Map, General Motors - GM5735

C-13

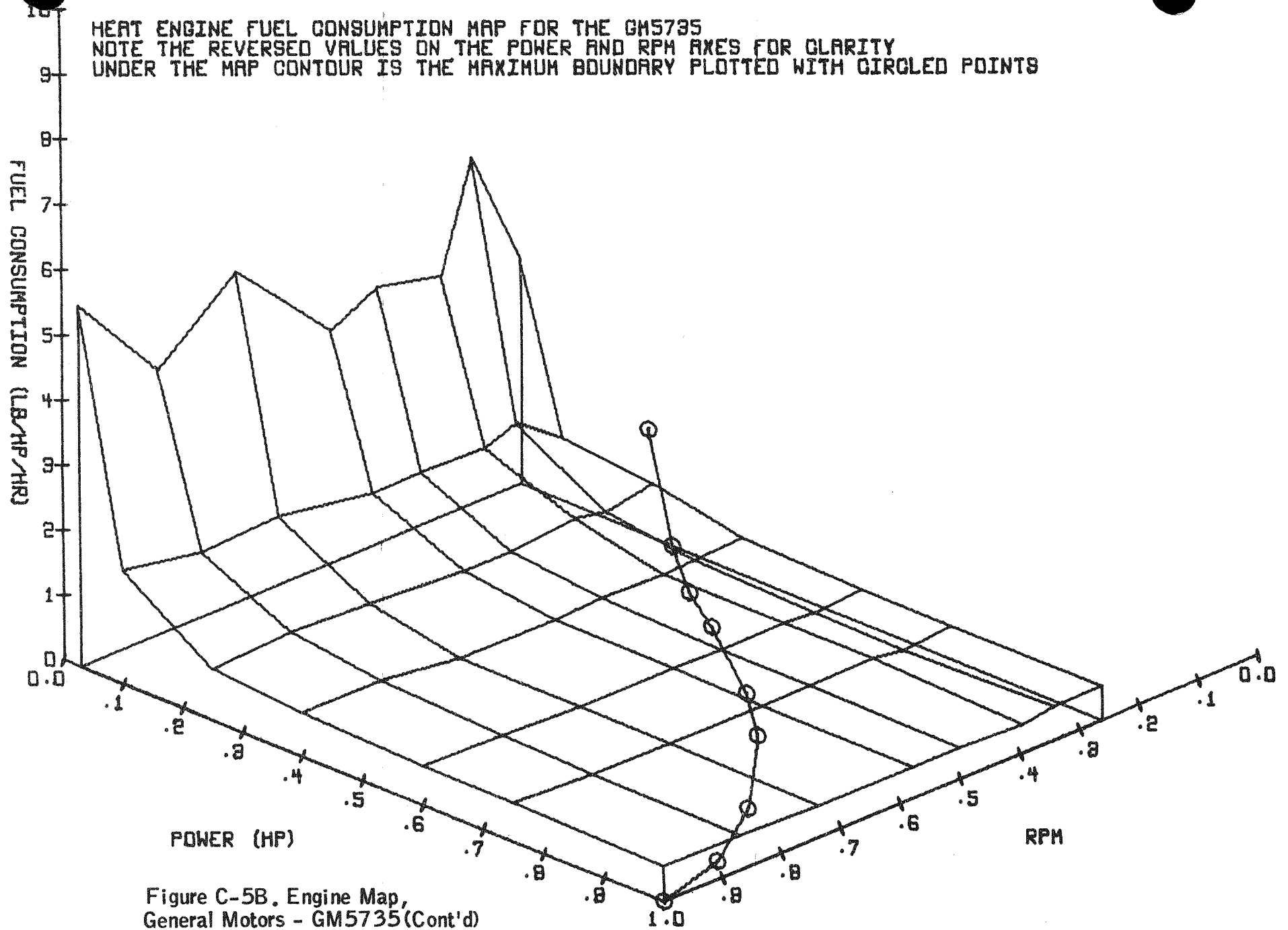


Figure C-5B. Engine Map,
General Motors - GM5735 (Cont'd)

ENGINE: HN1600

MAXIMUM POWER: 50.0 HP

MAXIMUM RPM: 5500.0

MINIMUM RPM: 1000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
1001.	12.	.1820	.2400
1501.	18.	.2730	.3700
2002.	25.	.3640	.5100
2502.	32.	.4550	.6500
2997.	38.	.5450	.7600
3498.	43.	.6360	.8700
3998.	47.	.7270	.9500
4499.	50.	.8180	1.0000
4999.	49.	.9090	.9900
5500.	48.	1.0000	.9600

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	5./ .100	10./ .200	15./ .300	20./ .400	25./ .500	30./ .600	35./ .700	40./ .800	45./ .900	50./ 1.000
1001./ .182	1.7000	.9800	.8600	.7600	.6550	.5720	.5250	.4990	.4890	.4830
2002./ .364	1.9000	.9500	.7900	.7100	.6550	.5470	.4910	.4410	.4430	.4950
2502./ .455	1.5000	.8550	.6970	.6100	.5540	.5080	.4680	.4400	.4400	.4900
3003./ .546	1.9000	.9750	.7950	.6870	.6200	.5600	.5100	.4700	.4700	.5500
3498./ .636	2.0000	1.0300	.7850	.6590	.5810	.5400	.5160	.5050	.5000	.5000
3998./ .727	2.0000	1.1200	.8650	.7200	.6200	.5500	.5160	.5050	.5060	.5000
4499./ .818	2.0000	1.1400	.8100	.6550	.5850	.5540	.5350	.5250	.5250	.5250
4999./ .909	2.0000	1.4000	.9750	.8250	.7250	.6650	.6250	.6250	.6250	.6250
5500./ 1.000	1.9600	1.7000	1.4700	1.2700	1.0900	.9420	.8210	.7290	.6640	.6270

Figure C-6A. Engine Map, Honda - HN1600

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE HN1600
NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

C-15

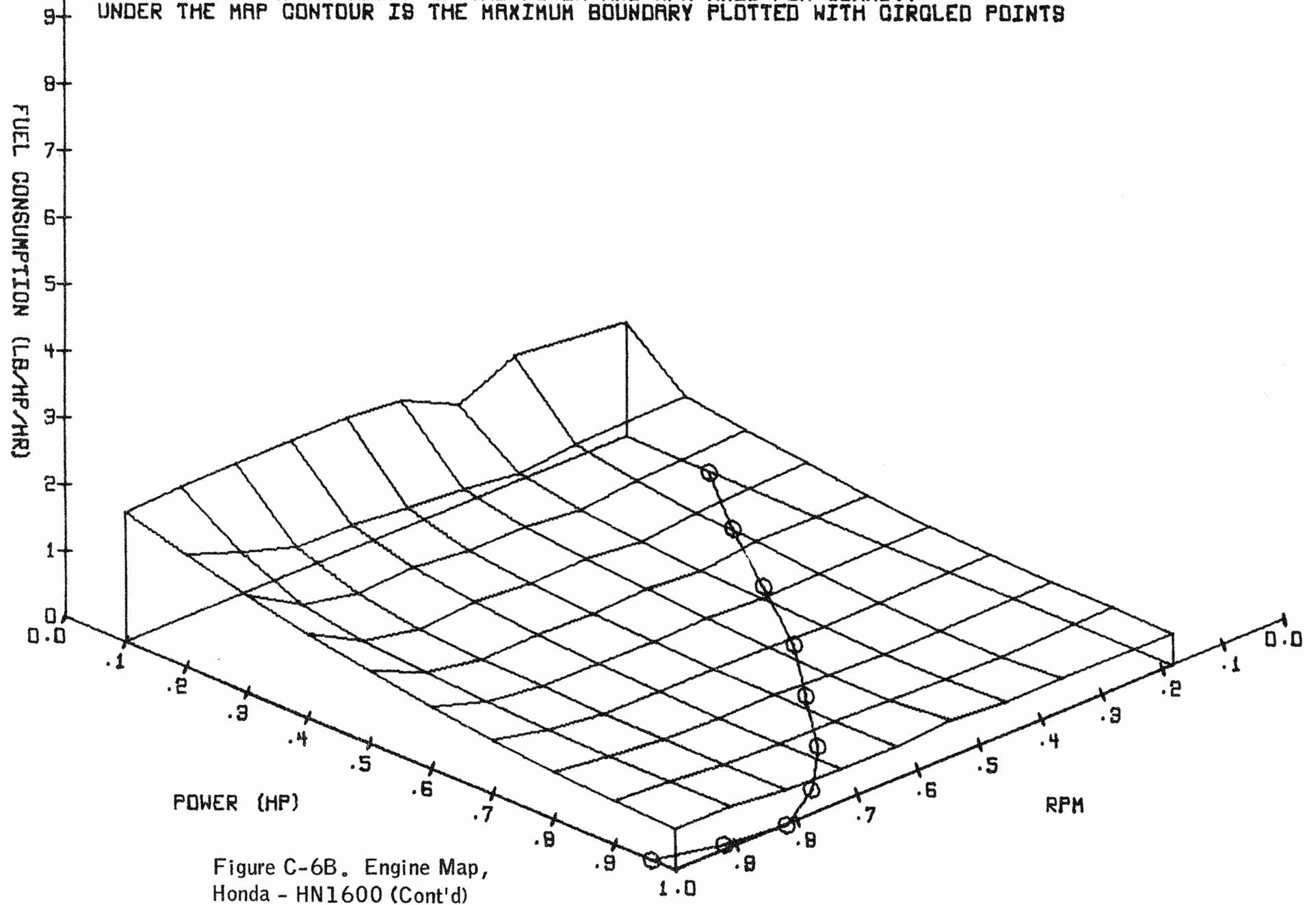


Figure C-6B. Engine Map,
Honda - HN1600 (Cont'd)

ENGINE: GMVEGA140

MAXIMUM POWER: 80.0 HP

MAXIMUM RPM: 4000.0

MINIMUM RPM: 1000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
200.	2.	.0500	.0300
908.	19.	.2270	.2400
1364.	28.	.3410	.3600
1820.	40.	.4550	.5000
2544.	56.	.6360	.7000
3272.	68.	.8180	.8600
4000.	80.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, 4./	8./	12./	20./	40./	60./	80./
	.050	.100	.150	.250	.500	.750	1.000
908./							
.227	2.8000	1.9500	1.3200	.9790	.5960	.4610	.5850
1364./							
.341	3.6000	1.8400	1.4500	1.0400	.6310	.5000	.6310
1820./							
.455	2.8100	1.5200	1.1100	.7760	.5260	.4880	.5760
2544./							
.636	2.8500	1.4500	1.0300	.7300	.5250	.4970	.5280
3272./							
.818	2.6800	1.4900	1.1200	.6400	.6170	.5230	.5420
4000./							
1.000	2.7000	1.6400	1.1700	.8730	.6060	.5530	.5170

Figure C-7A. Engine Map, General Motors - GMVEGA140

C-17

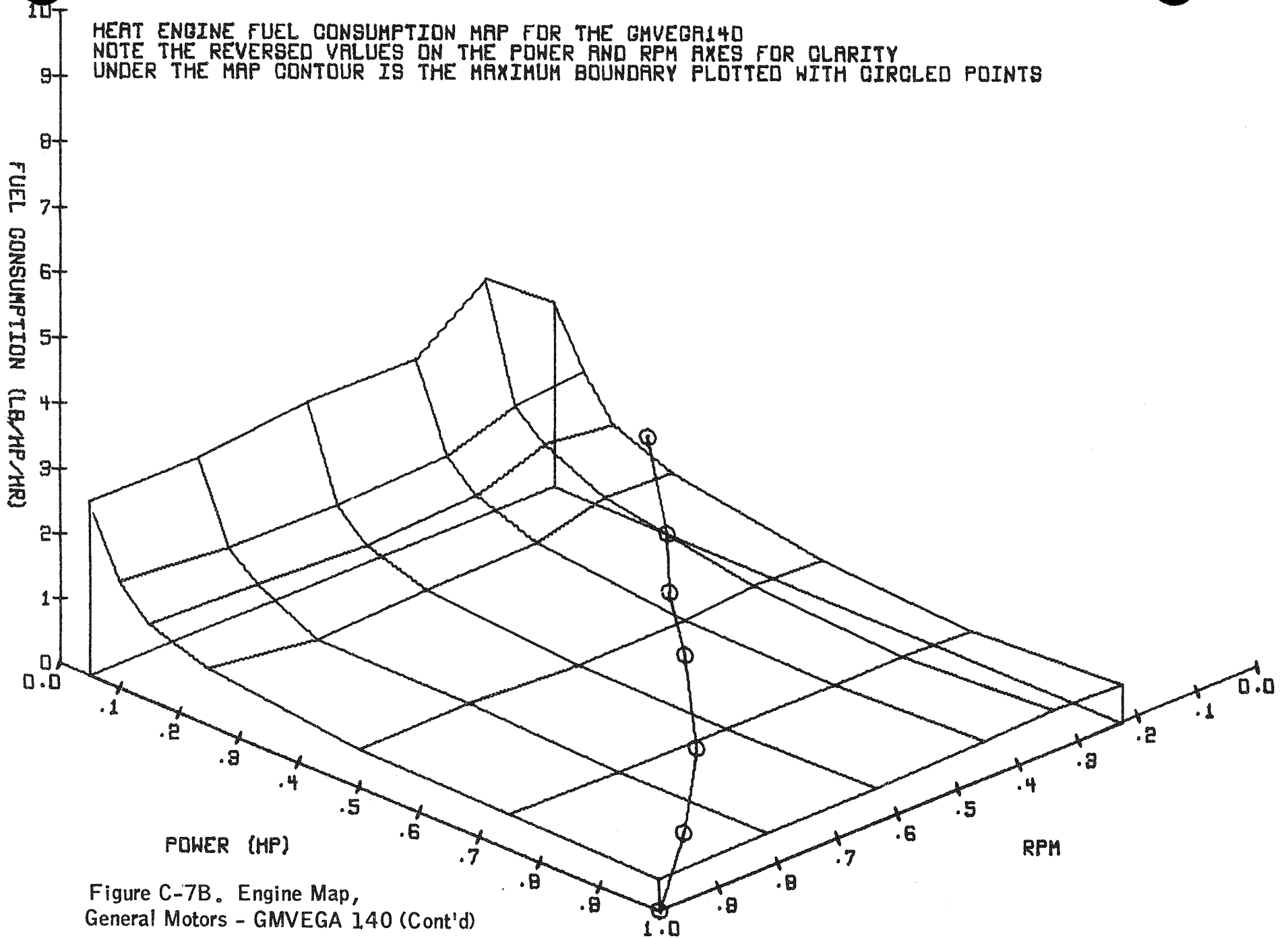


Figure C-7B. Engine Map,
General Motors - GMVEGA 140 (Cont'd)

ENGINE: TR7

MAXIMUM POWER: 86.0 HP

MAXIMUM RPM: 6000.0

MINIMUM RPM: 1000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
996.	14.	.1660	.1670
1500.	25.	.2500	.2920
1998.	35.	.3330	.4140
2502.	45.	.4170	.5330
3000.	55.	.5000	.6480
3498.	65.	.5830	.7630
4002.	74.	.6670	.8650
4500.	81.	.7500	.9530
4998.	85.	.8330	.9970
5496.	83.	.9160	.9710
6000.	80.	1.0000	.9360

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, VALUE/FRACTION	8./ .100	12./ .150	21./ .250	30./ .350	43./ .500	51./ .600	64./ .750	77./ .900	86./ 1.000
996./ .166	1.4000	1.2000	.8500	.7000	.6000	.5600	.5200	.5000	.5100	.5100
1500./ .250	1.3200	1.0000	.7500	.6400	.5500	.5200	.4950	.4900	.5100	.5100
1998./ .333	1.3000	.9700	.7050	.6050	.5250	.5150	.4850	.4800	.5100	.5100
2502./ .417	1.3000	.9350	.6950	.5950	.5250	.5050	.4760	.4700	.5100	.5100
3000./ .500	1.3000	.9100	.6900	.5900	.5300	.5000	.4730	.4700	.5100	.5100
3498./ .583	1.3000	.9000	.6900	.5900	.5250	.4950	.4720	.4700	.5100	.5100
4002./ .667	1.3000	1.0000	.7000	.5850	.5250	.5000	.4800	.4700	.5100	.5100
4500./ .750	1.3500	1.1500	.7200	.6200	.5400	.5200	.4900	.4850	.5100	.5100
4998./ .833	1.5000	1.3000	.7900	.6600	.5600	.5350	.5150	.5000	.5300	.5300
5496./ .916	1.7000	1.5000	1.1500	.8000	.6500	.6000	.5500	.5500	.5800	.5800
6000./ 1.000	2.0000	1.7000	1.4000	1.3000	1.2000	1.0000	.8000	.7000	.6500	.6500

C-18

Figure C-8A. Engine Map, Triumph, TR7

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE TR7
 NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
 UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

FUEL CONSUMPTION (LB/HP/HR)

C-19

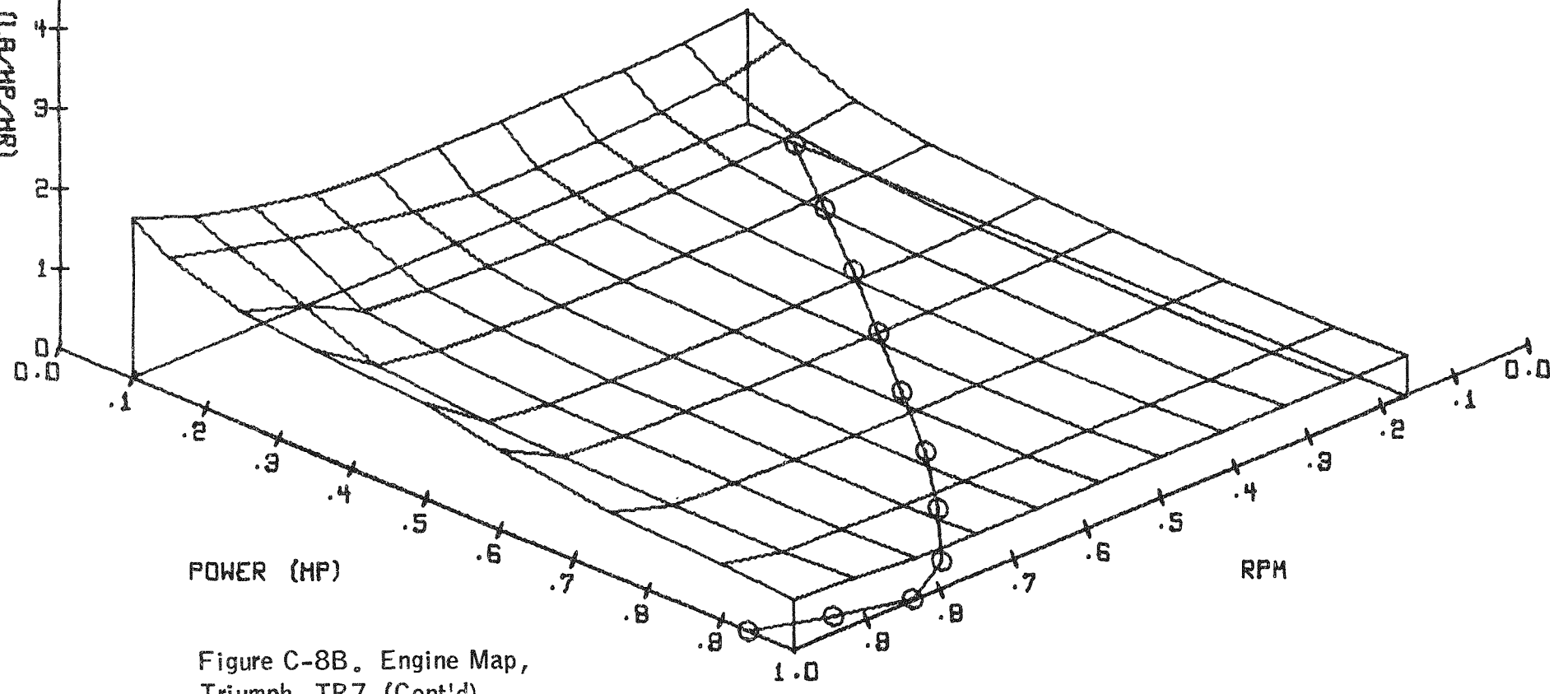


Figure C-8B. Engine Map,
 Triumph, TR7 (Cont'd)

ENGINE: TURBODSL

MAXIMUM POWER: 70.0 HP

MAXIMUM RPM: 5000.0

MINIMUM RPM: 700.0

FUEL TYPE: DIESEL

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
500.	5.	.1000	.0820
1000.	12.	.2000	.1840
1500.	20.	.3000	.2970
2000.	32.	.4000	.4710
2500.	43.	.5000	.6250
3000.	53.	.6000	.7680
3500.	61.	.7000	.8810
4000.	67.	.8000	.9630
4500.	69.	.9000	.9900
5000.	70.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, 3./ .050	POWER, 7./ .100	POWER, 17./ .250	POWER, 28./ .400	POWER, 42./ .600	POWER, 52./ .750	POWER, 70./ 1.000
1000./ .200	1.7600	1.3900	.8600	.6100	.5100	.4950	.4950
1500./ .300	1.4500	1.2000	.7100	.5300	.4600	.4400	.5000
2000./ .400	1.5600	1.1500	.6100	.4600	.4400	.4400	.5000
2500./ .500	1.6500	1.1500	.6100	.4600	.4400	.4400	.5000
3000./ .600	1.9000	1.2200	.5900	.4600	.4300	.4300	.5000
3500./ .700	2.1400	1.7300	.6300	.4600	.4300	.4300	.5000
4000./ .800	2.4700	1.4000	.7100	.5300	.4400	.4600	.5400
5000./ 1.000	2.4000	1.7300	1.0900	.7600	.5900	.5400	.5800

Figure C-9A. Engine Map, Volkswagen - TURBODSL

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE TURBODSL
 NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
 UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

C-21

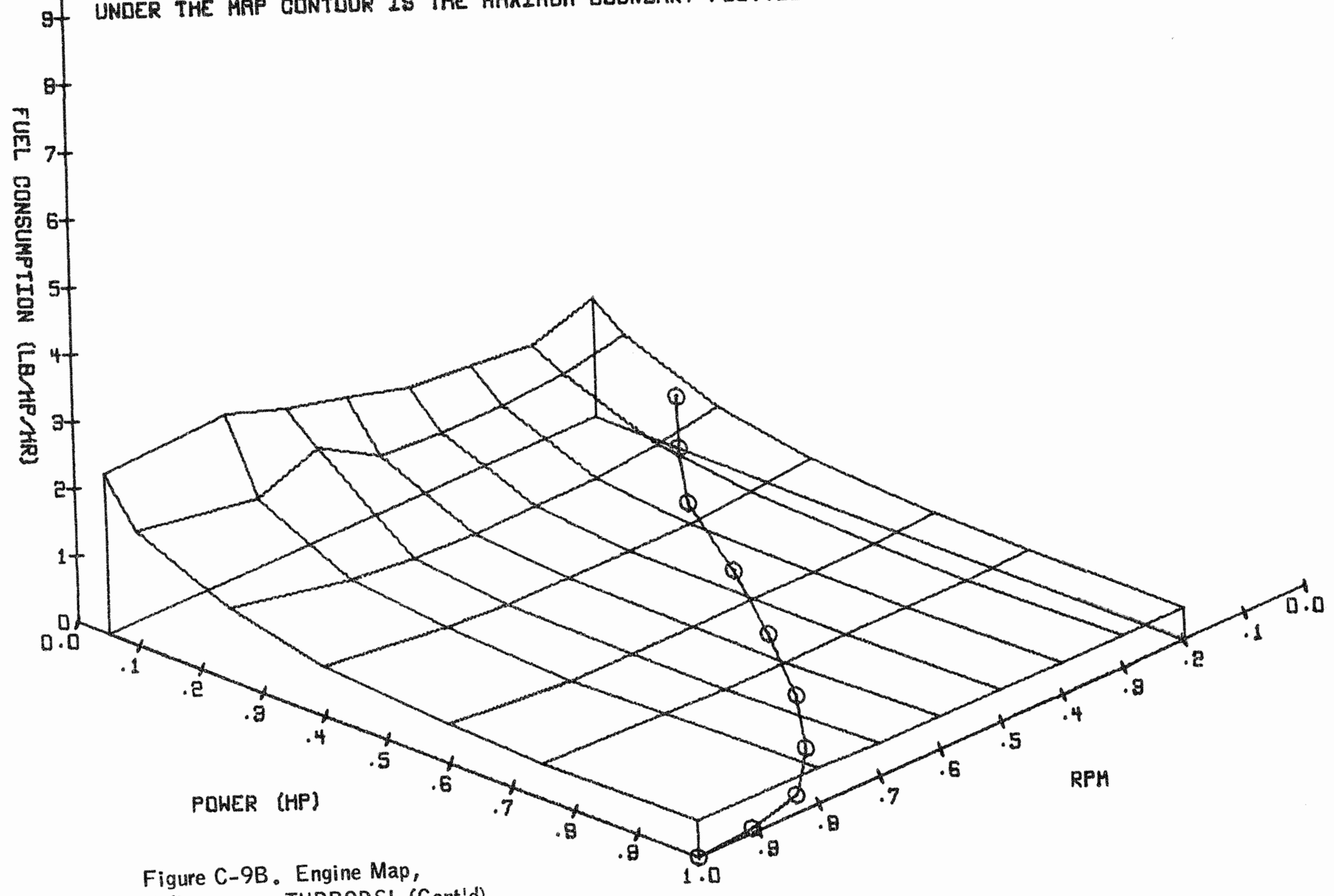


Figure C-9B. Engine Map,
 Volkswagen - TURBODSL (Cont'd)

ENGINE: NADSL

MAXIMUM POWER: 50.0 HP

MAXIMUM RPM: 5000.0

MINIMUM RPM: 700.0

FUEL TYPE: DIESEL

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
500.	2.	.1000	.0560
1000.	10.	.2000	.2000
1500.	14.	.3000	.2870
2000.	22.	.4000	.4530
2500.	28.	.5000	.5600
3000.	35.	.6000	.7070
3500.	40.	.7000	.8130
4000.	45.	.8000	.9070
4500.	48.	.9000	.9680
5000.	50.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM,	POWER, VALUE/FRACTION						
VALUE/ FRACTION	2./ .050	5./ .100	12./ .250	20./ .400	30./ .600	37./ .750	50./ 1.000
1000./ .200	1.7000	1.3800	.8400	.6100	.5700	.4700	.4900
1500./ .300	1.6700	1.2300	.6900	.5800	.5400	.4900	.4900
2000./ .400	1.7300	1.2500	.6900	.5300	.4400	.4500	.4900
2500./ .500	1.7300	1.2400	.7200	.5400	.4500	.4300	.4900
3000./ .600	1.7300	1.2500	.7300	.5400	.4700	.4400	.4900
3500./ .700	1.8100	1.4000	.7600	.5400	.4600	.4500	.4900
4000./ .800	2.3100	1.6900	.8500	.6000	.4900	.4700	.4900
4500./ .900	1.8600	1.6500	1.0000	.6800	.5500	.5300	.5400
5000./ 1.000	2.5600	2.1800	1.1100	.7800	.5900	.5400	.5400

Figure C-10A. Engine Map, Volkswagen - NADSL

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE NADSL
NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

FUEL CONSUMPTION (LB/HP/HR)

C-23

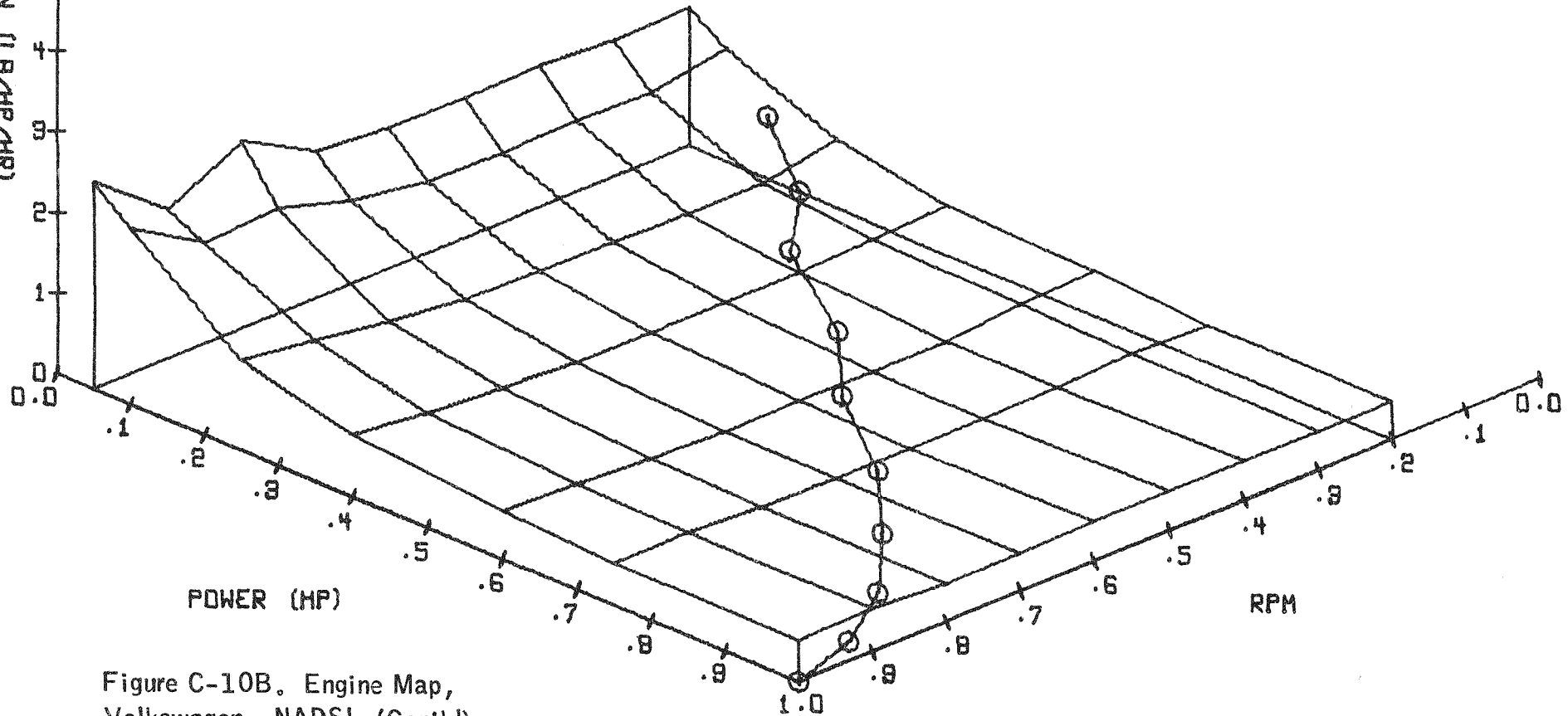


Figure C-10B. Engine Map,
Volkswagen - NADSL (Cont'd)

ENGINE: IDIDSL

MAXIMUM POWER: 60.0 HP

MAXIMUM RPM: 4000.0

MINIMUM RPM: 700.0

FUEL TYPE: DIESEL

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
1000.	18.	.2500	.3100
1500.	28.	.3750	.4700
2000.	36.	.5000	.6100
2500.	45.	.6250	.7500
3000.	51.	.7500	.8500
3500.	55.	.8750	.9300
4000.	60.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, 6./ .100	POWER, 9./ .150	POWER, 15./ .250	POWER, 21./ .350	POWER, 30./ .500	POWER, 36./ .600	POWER, 45./ .750	POWER, 54./ .900	POWER, 60./ 1.000
1000./ .250	1.2000	1.0000	.7150	.5800	.5300	.4790	.4390	.4360	.4400
1500./ .375	1.0000	.9000	.6500	.5600	.4780	.4410	.4250	.4310	.4400
2000./ .500	1.1000	.9000	.6600	.5450	.4700	.4370	.4220	.4300	.4400
2500./ .625	1.1000	.9000	.6700	.5600	.4790	.4500	.4320	.4250	.4400
3000./ .750	1.1300	.9500	.7000	.5750	.5150	.4790	.4570	.4470	.4550
3500./ .875	1.1500	1.0000	.8000	.6500	.5550	.5200	.4820	.4710	.4750
4000./ 1.000	1.2000	1.0500	.9000	.6750	.6100	.5700	.5300	.5000	.5000

Figure C-11A. Engine Map, British Leyland Rover - IDIDSL

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE IDIDSL
NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

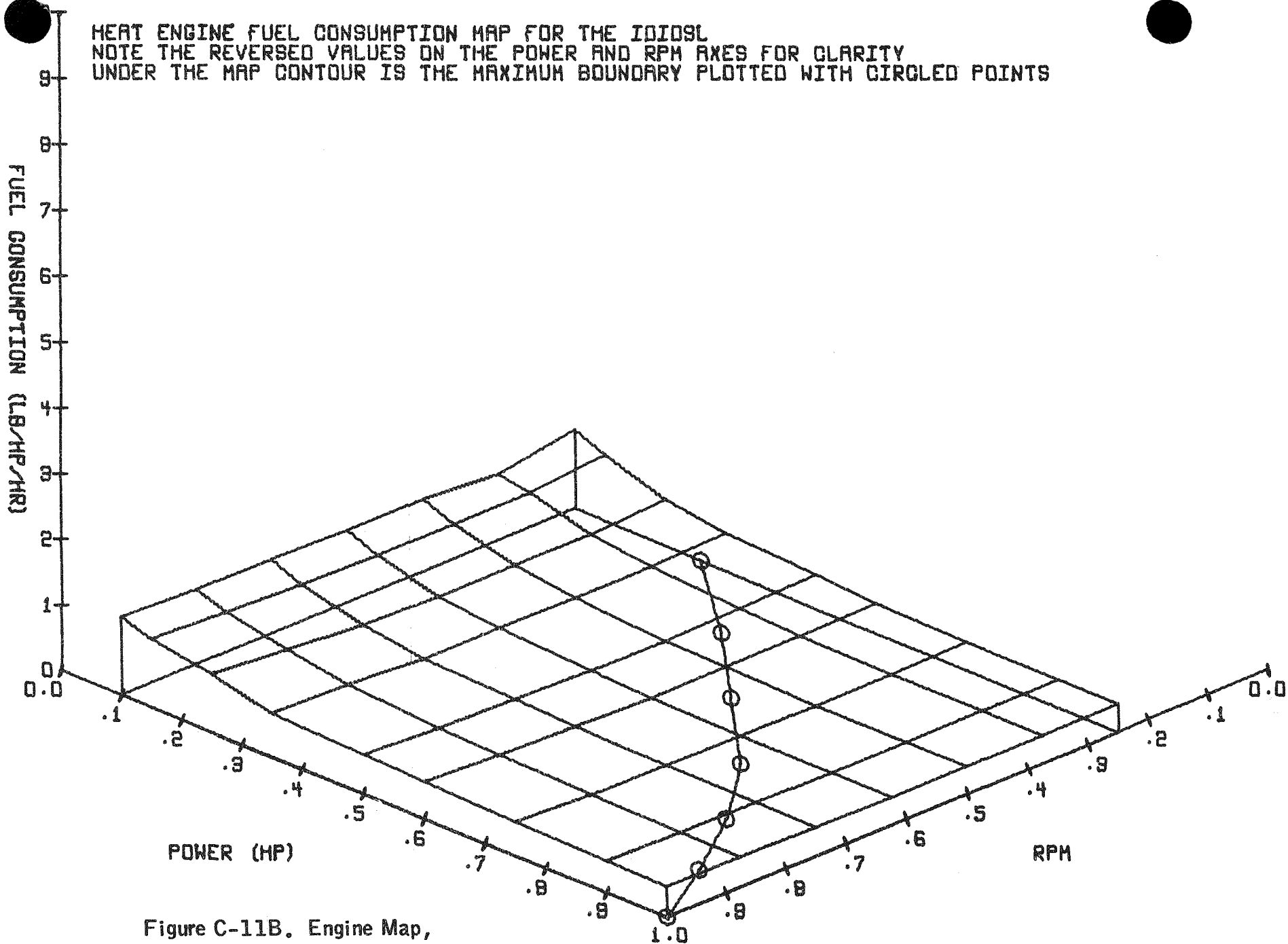


Figure C-11B. Engine Map,
British Leyland Rover - IDIDSL

ENGINE: CWSTRATROT

MAXIMUM POWER: 75.0 HP

MAXIMUM RPM: 4500.0

MINIMUM RPM: 1200.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
1197.	15.	.2660	.2050
1498.	22.	.3330	.3030
1800.	30.	.4000	.4060
1998.	35.	.4440	.4770
2497.	48.	.5550	.6500
3001.	60.	.6670	.8060
3496.	69.	.7770	.9330
3996.	75.	.8880	1.0000
4500.	70.	1.0000	.9360

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, VALUE/ FRACTION	11./ .150	18./ .250	26./ .350	37./ .500	45./ .600	56./ .750	67./ .900	75./ 1.000
1197./ .266	1.5000	1.2000	.9000	.7200	.6100	.5800	.5500	.5500	.5500
1498./ .333	1.3500	1.0500	.7600	.6200	.5400	.5300	.5000	.5250	.5500
1998./ .444	1.2000	.9500	.7400	.6000	.5300	.5000	.4900	.5000	.5500
2497./ .555	1.2000	.9000	.6950	.5900	.5300	.5000	.4870	.4950	.5500
3001./ .667	1.2500	.9000	.6800	.5850	.5300	.4970	.4800	.4920	.5500
3496./ .777	1.3000	.9000	.7100	.6000	.5300	.4970	.4920	.5200	.5500
3996./ .888	1.3500	1.0500	.7600	.6250	.5400	.5200	.5200	.5250	.5500
4500./ 1.000	1.4500	1.2000	.8500	.6850	.5700	.5500	.5400	.5400	.5500

Figure C-12A. Engine Map, Curtis Wright - CWSTRATROT

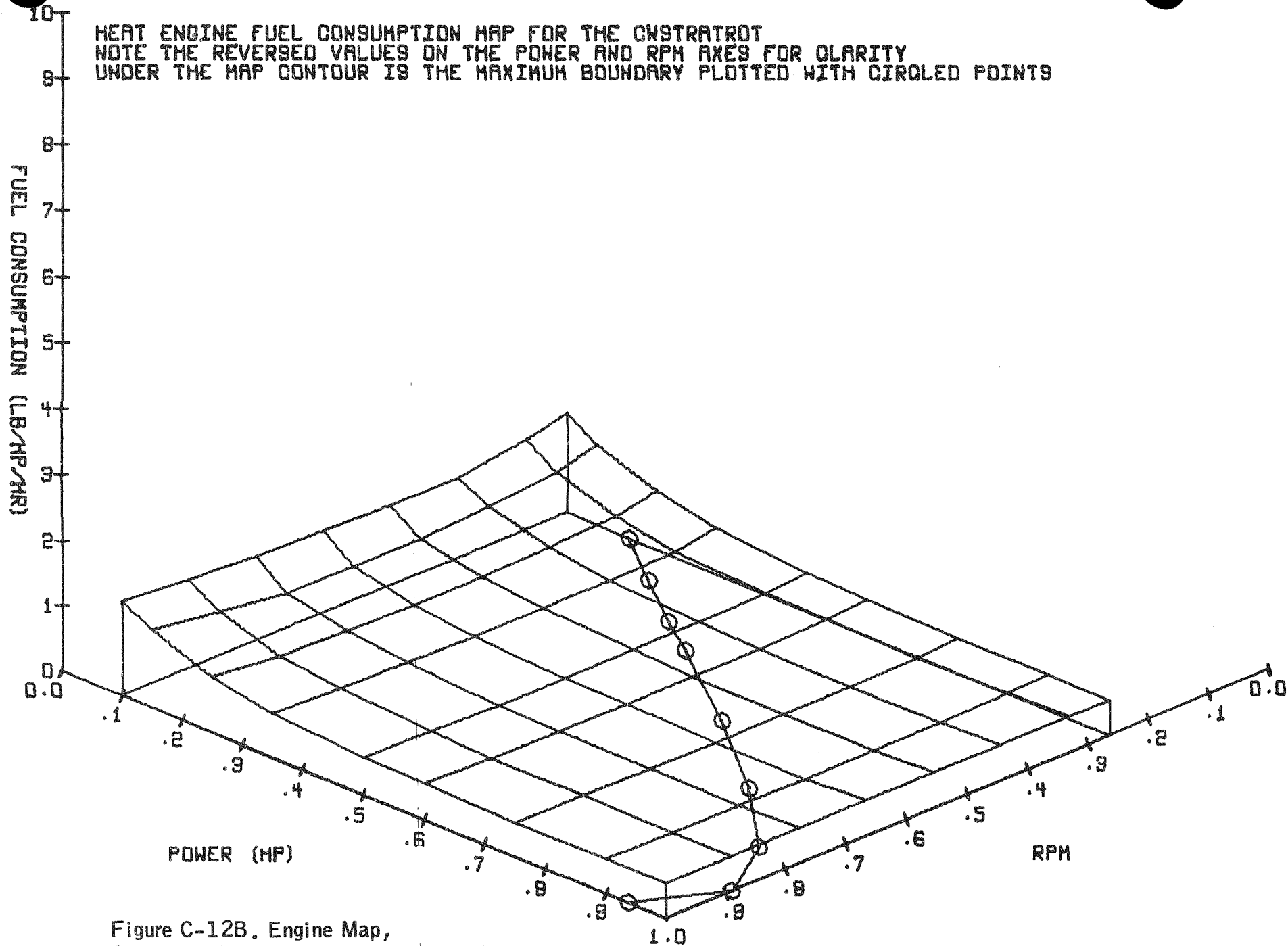


Figure C-12B. Engine Map,
Curtis Wright - CWSTRATROT (Cont'd)

ENGINE: NSUAUDIROT

MAXIMUM POWER: 170.0 HP

MAXIMUM RPM: 6500.0

MINIMUM RPM: 2000.0

FUEL TYPE: GASOLINE

ENGINE MAXIMUM OPERATING BOUNDARY -

RPM	POWER	FRACT RPM	FRACT POWER
1501.	36.	.2310	.2130
2002.	54.	.3080	.3200
2502.	70.	.3850	.4130
3003.	88.	.4620	.5190
3503.	105.	.5390	.6230
3997.	123.	.6150	.7290
4498.	137.	.6920	.8070
4998.	150.	.7690	.8840
5499.	161.	.8460	.9500
5999.	168.	.9230	.9910
6500.	170.	1.0000	1.0000

FUEL CONSUMPTION - (LB/HP/HR)

RPM, VALUE/ FRACTION	POWER, VALUE/ FRACTION	17./ .100	25./ .150	42./ .250	59./ .350	85./ .500	102./ .600	127./ .750	153./ .900	170./ 1.000
1501./ .231	1.0000	.8800	.7500	.6400	.5370	.5200	.4970	.4840	.4840	.4840
2002./ .308	1.0000	.8600	.7080	.5940	.5190	.4950	.4730	.4620	.4620	.4730
3003./ .462	1.0000	.8600	.6450	.5500	.4950	.4660	.4520	.4400	.4400	.4620
3997./ .615	1.0400	.8470	.6500	.5500	.4980	.4730	.4510	.4490	.4490	.4620
4998./ .769	1.2100	1.0000	.6600	.6050	.5280	.5060	.4840	.4800	.4800	.4840
5999./ .923	1.4000	1.2000	.9350	.6490	.5830	.5410	.5240	.5190	.5190	.5150
6500./ 1.000	1.7000	1.4000	1.1000	.9100	.6400	.5900	.5500	.5400	.5400	.5300

Figure C-13A. Engine Map, NSU/AUDI - NSUAUDIROT

HEAT ENGINE FUEL CONSUMPTION MAP FOR THE NSUAUDIROT
NOTE THE REVERSED VALUES ON THE POWER AND RPM AXES FOR CLARITY
UNDER THE MAP CONTOUR IS THE MAXIMUM BOUNDARY PLOTTED WITH CIRCLED POINTS

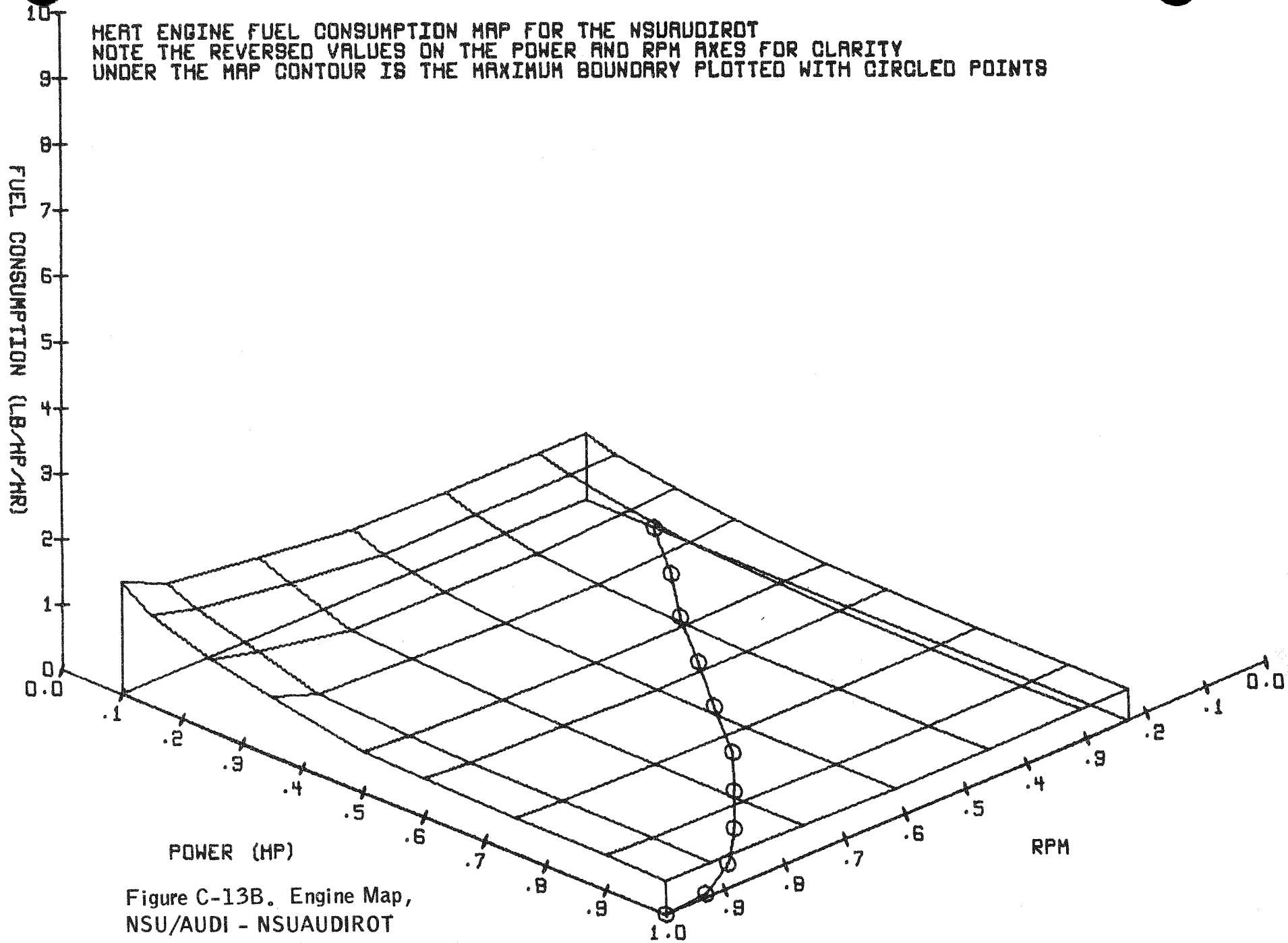


Figure C-13B. Engine Map,
NSU/AUDI - NSUAUDIROT

APPENDIX D

ROAD LOAD MODEL

The calculations described in this appendix are for the road load model in ELVEC. This is intended as a summary of how the road load parameters are calculated in this simulator.

ROAD LOAD AND ITS COMPONENTS

The basic equation used to compute road load is

$$P_R = (F_A + F_T + M_V G_F + F_2 \dot{V}) V$$

where

P_R = road load (includes acceleration), W

F_A = aerodynamic drag, N

F_T = tire friction, N

M_V = vehicle mass, kg

G_F = gradient factor, N/kg

F_2 = vehicle effective mass, kg

\dot{V} = acceleration, m/s²

V = speed, m/s

Aerodynamic drag is calculated, using

$$F_A = 0.6125 * CDA * V * V$$

where

0.6125 = standard air density/2, kg/m³

CDA = aerodynamic drag-area product, m²

V = speed, m/s

Note that the resulting units are $\text{kg} \cdot \text{m/s}^2$, which is equivalent to Newtons (N). The power lost in aerodynamic drag is calculated from $\text{PLAERO} = \text{FA} * \text{V}$.

Tire friction is calculated, using

$$\text{FTR} = \text{ATIREF}/100 * 9.807 * \text{WT}$$

where

ATIREF = tire friction coefficient, percent

9.807 = acceleration due to gravity, m/s^2

WT = vehicle mass, kg

The default value of ATIREF is 1.2 percent. The power lost in the tires is

$$\text{PLTIRE} = \text{FTR} * \text{V}$$

The gradient factor is equal to

$$G_F = \sin[\tan^{-1}(\theta/100)] * 9.808$$

where

θ = road gradient, percent

Note that G_F is set to zero for all driving schedules except constant speed and maximum acceleration.

The vehicle effective mass is calculated from

$$F_2 = M_{Ve} + \beta_3^2 I_3$$

where

$M_{Ve} = X_m M_V$, if the wheel, driveline, and motor inertias are set to zero; in this case X_m should be set to about 1.03

$$= M_V + \beta_1^2 I_1 + \beta_2^2 I_2, \text{ if } I_1 \neq 0$$

where

$$\beta_1 = 1/\text{driving wheel radius [BETA(1)]}, m^2$$

$$\beta_2 = \beta_1 * r_1 \text{ (} r_1 \text{ is differential ratio)}$$

$$I_1 = \text{inertial of wheels [XJ(1)]}, kg-m^2$$

$$I_2 = \text{inertial of driveline (not including motor)}, kg-m^2$$

The term $\beta_3^2 I_3$ is the reflected (to the wheels) mass of the rotating motor. Here

$$\beta_3 = \beta_2 * r_2 \text{ (} r_2 \text{ is transmission gear ratio)}$$

$$I_3 = \text{rotating inertia of motor}, kg - m^2$$

APPENDIX E

PHONE LIST

***** PHONLIST

THIS DIRECTORY INCLUDES ALL VOICE AND DATA NUMBERS FOR ALL
NCSS FACILITIES. ASTERISKS IN THE FAR RIGHT COLUMN DENOTE RECENT
CHANGES OR ADDITIONS.

PLEASE TYPE INFO PHONES FOR FURTHER INFORMATION.

--- ARIZONA

PHOENIX (602) 264-5490

110: 264-2718 134.5: 264-9172 300: 264-1891

TUCSON (602) 264-5490

300: 623-0318

--- CALIFORNIA

LOS ANGELES (213) 277-7511

AUTOSPEED: 277-7942 1200: 553-4271 2000: 553-7271

1200 VADIC FULL DUPLEX: 552-1674

MODESTO (408) 739-6271

AREA CODE 209 AUTOSPEED: 529-5050

MOUNTAIN VIEW (408) 739-6271

AUTOSPEED: 965-9500

NEWPORT BEACH (714) 833-8370

110: 833-0531 134.5: 833-1740 300: 752-1162

2000: 752-0630

PALO ALTO (408) 739-6271

AREA CODE 415 AUTOSPEED: 321-7011

RANCHO BERNARDO (714) 297-5870

300: 484-2900

SACRAMENTO (415) 989-3930

AREA CODE 916 110: 485-1048 134.5: 481-3618

300: 481-3617

SAN DIEGO (714) 297-5870

110: 297-8252 134.5: 297-6730 300: 297-9260

SAN FRANCISCO (415) 989-3930

AUTOSPEED: 788-6800 1200: 982-2191

SAN MATEO (408) 739-6271

AREA CODE 415 AUTOSPEED: 341-7405

SANTA BARBARA (213) 277-7511
AREA CODE 805 AUTOSPEED: 963-6633

SUNNYVALE (408) 739-6271 SUNY
AUTOSPEED: 245-6051
1200: 732-9791 1200 VADIC FULL DUPLEX: 733-3420
1200 BELL 212 FULL DUPLEX: 732-1092
2000: 739-3632 2400: 735-8968 4800: 733-4870
VOICE RESPONSE: 737-2733

VENTURA (213) 277-7511
AREA CODE 805 AUTOSPEED: 643-5779

--- CANADA
MONTREAL (203) 327-9100
AREA CODE 514 AUTOSPEED: 875-5318

TORONTO (203) 327-9100
AREA CODE 416 300: 862-7511

--- COLORADO
COLORADO SPRINGS (303) 534-2720
AUTOSPEED: 598-8327

DENVER (303) 534-2720
110: 573-1427 134.5: 573-1270 300: 573-1116

--- CONNECTICUT
BRIDGEPORT (203) 327-9100
AUTOSPEED: 367-8451

DANBURY (203) 327-9100
AUTOSPEED: 792-6616

HARTFORD (203) 561-3730
110: 561-2624 134.5: 561-3376 300: 561-3780

NEW HAVEN (203) 327-9100
AUTOSPEED: 772-2490

NEW MILFORD (203) 327-9100
AUTOSPEED: 354-9430

NORWALK (203) 327-9100
AUTOSPEED: 853-7915

STAMFORD (203) 327-9100 HSYS
AUTOSPEED: 327-3204 1200: 359-2801 2000: 327-9910
2400: 327-7971
1200 VADIC FULL DUPLEX: 327-9014 4800: 327-9280
VOICE RESPONSE: 327-7610

STAMFORD (203) 327-9100 M168
AUTOSPEED: 327-7100 1200: 327-2080 2000: 327-2020
2400: 327-7972 4800: 359-3428
VOICE RESPONSE: 327-7874

WATERBURY (203) 327-9100
AUTOSPEED: 574-5848

--- DISTRICT OF COLUMBIA

WASHINGTON, D.C. (703) 524-1500
AUTOSPEED: 243-8500 1200: 525-4884
AREA CODE 202 4800: 554-7734

--- DELAWARE

WILMINGTON (215) 665-1566
AREA CODE 302 AUTOSPEED: 478-4486

--- EUROPE

LONDON, ENGLAND 01-834-2223
110: 01-828-9090 134.5: 01-828-9000 300: 01-834-1288

PARIS, FRANCE 261-56-35
110: 260-43-02 134.5: 260-21-25 300: 260-25-13

--- FLORIDA

MELBOURNE (404) 659-1600
AREA CODE 305 110: 723-0091
134.5: 723-0092 300: 724-6770

--- GEORGIA

ATLANTA (404) 659-1600
110: 659-0840 134.5: 659-0990 300: 659-0860
1200: 577-4628

--- ILLINOIS

CHICAGO (312) 751-2200
AUTOSPEED: 266-1790 1200: 787-7694

--- INDIANA

ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

--- IOWA

ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

CEDAR RAPIDS (312) 751-2200
AREA CODE 319 AUTOSPEED: 393-4813

COUNCIL BLUFFS (312) 751-2200
AREA CODE 712 300: 322-7885

--- KENTUCKY
 ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
 AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

--- MAINE
 PORTLAND (617) 868-2950
 AREA CODE 207 AUTOSPEED: 774-0374

--- MARYLAND
 BALTIMORE (703) 524-1500
 AREA CODE 301 AUTOSPEED: 837-5929

--- MASSACHUSETTS
 CAMBRIDGE (617) 868-2950
 AUTOSPEED: 661-8000 1200: 492-4442 4800: 547-8379
 SPRINGFIELD (617) 868-2950
 AREA CODE 413 AUTOSPEED: 739-4726

--- MICHIGAN
 ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
 AUTOSPEED: 621-8229 AUTOSPEED: 621-8228
 ANN ARBOR (313) 559-7766
 300: 995-5722
 DETROIT (313) 559-7766
 110: 559-7612 134.5: 559-7904 300: 559-7965

--- MINNESOTA
 ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
 AUTOSPEED: 621-8229 AUTOSPEED: 621-8228
 MINNEAPOLIS (612) 339-4801
 110: 338-4803 134.5: 338-3005 300: 338-6217

--- MISSOURI
 ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
 AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

--- NEW HAMPSHIRE
 NASHUA (617) 868-2950
 AREA CODE 603 AUTOSPEED: 883-9095

--- NEW JERSEY
 CAMDEN (215) 665-1566
 AREA CODE 609 AUTOSPEED: 962-6266
 ELIZABETH (201) 965-2250
 AUTOSPEED: 353-3600 1200: 355-1677

PRINCETON (201) 965-2250
AREA CODE 609 110: 799-3285 134.5: 799-2775
300: 799-3490

--- NEW MEXICO
ALBUQUERQUE (408) 739-6271
AREA CODE 505 300: 843-9652

--- NEW YORK
ALBANY (203) 327-9100 HSYS
AREA CODE 518 1200 (DATASPEED ONLY): 449-8793

ALBANY (203) 327-9100 M168
AREA CODE 518 AUTOSPEED: 462-5686

BINGHAMTON (203) 327-9100
AREA CODE 607 AUTOSPEED: 772-1915

BUFFALO (203) 327-9100
AREA CODE 716 300: 847-1710

HEMPSTEAD (212) 754-1700
AREA CODE 516 AUTOSPEED: 489-8746

NEW YORK (212) 754-1700
AUTOSPEED: 350-0900 1200: 755-9470 2000: 757-6957
1200 VADIC FULL DUPLEX: 688-6349 VOICE RESPONSE: 751-5392

POUGHKEEPSIE (203) 327-9100
AREA CODE 914 AUTOSPEED: 454-7920

ROCHESTER (716) 924-9303
110: 924-3037 134.5: 924-7175 300: 924-9338

WHITE PLAINS (203) 327-9100
AREA CODE 914 AUTOSPEED: 428-8010 1200: 428-7759
1200 VADIC FULL DUPLEX: 948-1408

--- NORTH CAROLINA
JAMESTOWN (703) 524-1500
AREA CODE 919 300: 886-4968

--- OHIO
ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

AKRON (216) 771-5550
300: 434-8181

CLEVELAND (216) 771-5550
 110: 696-5778 134.5: 696-0366 300: 696-5141

COLUMBUS (216) 771-5550
 AREA CODE 614 300: 224-6897

DAYTON (216) 771-5550
 AREA CODE 513 300: 224-8505

--- OKLAHOMA
 TULSA (214) 661-3688
 AREA CODE 918 300: 582-3203

--- OREGON
 PORTLAND (503) 223-7255
 110: 226-2395 134.5: 226-2390 300: 226-1351

--- PENNSYLVANIA
 BETHLEHEM (215) 691-3616
 AUTOSPEED: 691-5600

CARLISLE (215) 665-1566
 AREA CODE 717 AUTOSPEED: 243-1063

PHILADELPHIA (215) 665-1566
 AUTOSPEED: 665-8920 1200: 564-5961

PITTSBURGH (412) 281-6111
 110: 281-6842 300: 281-6127

--- RHODE ISLAND
 PROVIDENCE (617) 868-2950
 AREA CODE 401 AUTOSPEED: 521-5487

--- TENNESSEE
 ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
 AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

MEMPHIS (404) 659-1600
 AREA CODE 901 300: 725-1210

--- TELEX AND TMX
 TELEX: 965806 TMX 110: 710-474-3540

--- TEXAS
 DALLAS (214) 661-3688
 110: 661-9291 134.5: 661-9274 300: 661-9257

FT. WORTH (214) 661-3688
 300: 263-2113

HOUSTON (713) 621-9231
110: 741-1660 134.5: 741-2800 300: 741-2200
2000: 627-3565 1200 VADIC FULL DUPLEX: 621-1397

SAN ANTONIO (713) 621-9231
AREA CODE 512 300: 225-7424

--- UTAH
SALT LAKE CITY (303) 534-2720
AREA CODE 801 300: 364-2720

--- VIRGINIA
ARLINGTON (703) 524-1500
AUTOSPEED: 243-8500 1200: 525-4884

NORFOLK (703) 524-1500
AREA CODE 804 AUTOSPEED: 627-7423

RICHMOND (703) 524-1500
AREA CODE 804 AUTOSPEED: 644-0637

--- WASHINGTON
SEATTLE (509) 223-7255
AREA CODE 206 300: 623-4741

--- WISCONSIN
ZONE 2 WATS: AREA CODE 800 AUTOSPEED: 621-8223
AUTOSPEED: 621-8229 AUTOSPEED: 621-8228

APPLETON (312) 751-2200
AREA CODE 414 AUTOSPEED: 731-6566

MILWAUKEE (312) 751-2200
AREA CODE 414 300: 475-6818