

FLANGE: A Computer Program for
the Analysis of Flanged Joints
with Ring-Type Gaskets

E. C. Rodabaugh
F. M. O'Hara, Jr.
S. E. Moore

MASTER



OAK RIDGE NATIONAL LABORATORY

OPERATED BY UNION CARBIDE CORPORATION • FOR THE U.S. ATOMIC ENERGY COMMISSION

DISCLAIMER

This report was prepared as an account of work sponsored by an agency of the United States Government. Neither the United States Government nor any agency thereof, nor any of their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States Government or any agency thereof. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States Government or any agency thereof.

DISCLAIMER

Portions of this document may be illegible in electronic image products. Images are produced from the best available original document.

Printed in the United States of America. Available from
National Technical Information Service
U.S. Department of Commerce
5285 Port Royal Road, Springfield, Virginia 22161
Price: Printed Copy \$7.75; Microfiche \$2.25

This report was prepared as an account of work sponsored by the United States Government. Neither the United States nor the Energy Research and Development Administration, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness or usefulness of any information, apparatus, product or process disclosed, or represents that its use would not infringe privately owned rights.

ORNL-5035

NRC-1, -5

Contract No. W-7405-eng-26

Reactor Division

FLANGE: A COMPUTER PROGRAM FOR THE ANALYSIS
OF FLANGED JOINTS WITH RING-TYPE GASKETS

E. C. Rodabaugh
Battelle-Columbus Laboratories

F. M. O'Hara, Jr. S. E. Moore
Oak Ridge National Laboratory

Work funded by the Nuclear Regulatory Commission
under Interagency Agreement 40-495-75

JANUARY 1976

Subcontract No. 2913

for

OAK RIDGE NATIONAL LABORATORY
Oak Ridge, Tennessee 37830

Operated by
UNION CARBIDE CORPORATION
for the

U.S. ENERGY RESEARCH AND DEVELOPMENT ADMINISTRATION

—NOTICE—
This report was prepared as an account of work sponsored by the United States Government. Neither the United States nor the United States Energy Research and Development Administration, nor any of their employees, nor any of their contractors, subcontractors, or their employees, makes any warranty, express or implied, or assumes any legal liability or responsibility for the accuracy, completeness or usefulness of any information, apparatus, product or process disclosed, or represents that its use would not infringe privately owned rights.

DISTRIBUTION OF THIS DOCUMENT IS UNLIMITED

fug

CONTENTS

	<u>Page</u>
FOREWORD	v
1. INTRODUCTION	1
Purpose and Scope	1
Nomenclature	2
2. GENERAL DESCRIPTION OF THE ANALYSIS	4
3. FLANGE WITH A TAPERED-WALL HUB	7
Equations for the Annular Ring	7
Equations for the Tapered Hub	8
Equations for the Pipe	11
Boundary Conditions	11
Boundary Equations	12
Stresses	15
Displacements	15
4. FLANGE WITH A STRAIGHT HUB	17
5. BLIND FLANGES	20
Analysis Method	20
Stresses	24
Displacements	25
6. THERMAL GRADIENTS	26
7. CHANGE IN BOLT LOAD WITH PRESSURE, TEMPERATURE, AND EXTERNAL MOMENTS	27
Analysis	28
External Moment Loading	36
8. COMPUTER PROGRAM	37
Option Control Data Card	37
Input for Code-Compliance Calculations	39
Output from Code-Compliance Calculations	41
Input for General Purpose Calculations	43
Output from General Purpose Calculations	47

	<u>Page</u>
ACKNOWLEDGMENT	52
REFERENCES	52
APPENDIX A. Examples of Application of Computer Program FLANGE	53
APPENDIX B. Flowcharts and Listing of Computer Program FLANGE and Attendant Subroutines	97

FOREWORD

The work reported here was performed at Oak Ridge National Laboratory and at Battelle-Columbus Laboratories under Union Carbide Corp., Nuclear Division, Subcontract No. 2913 as part of the ORNL Design Criteria for Piping and Nozzles Program, S. E. Moore, Manager. This program is funded by the Division of Reactor Safety Research (RSR) of the U.S. Nuclear Regulatory Commission as part of a cooperative effort with industry to develop and verify analytical methods for assessing the safety of pressure-vessel and piping-system design. The cognizant RSR project engineer is E. K. Lynn. The cooperative effort is coordinated through the Pressure Vessel Research Committee of the Welding Research Council under the Subcommittee on Piping, Pumps, and Valves.

The study described in this report was conducted under the general direction of W. L. Greenstreet and S. E. Moore, Solid Mechanics Department, Reactor Division, ORNL, and is a continuation of work supported in prior years by the Division of Reactor Research and Development, U.S. Energy Research and Development Administration (formerly the USAEC).

Prior reports and open-literature publications in this series are:

1. W. L. Greenstreet, S. E. Moore, and E. C. Rodabaugh, "Investigations of Piping Components, Valves, and Pumps to Provide Information for Code Writing Bodies," ASME Paper 68-WA/PTC-6, American Society of Mechanical Engineers, New York, Dec. 2, 1968.
2. W. L. Greenstreet, S. E. Moore, and R. C. Gwaltney, *Progress Report on Studies in Applied Solid Mechanics*, ORNL-TM-4576 (August 1970).
3. E. C. Rodabaugh, *Phase Report No. 115-1 on Stress Indices for Small Branch Connections with External Loadings*, ORNL-TM-3014 (August 1970).
4. E. C. Rodabaugh and A. G. Pickett, *Survey Report on Structural Design of Piping Systems and Components*, TID-25553 (December 1970).
5. E. C. Rodabaugh, *Phase Report No. 115-8, Stresses in Out-of-Round Pipe Due to Internal Pressure*, ORNL-TM-3244 (January 1971).
6. S. E. Bolt and W. L. Greenstreet, "Experimental Determination of Plastic Collapse Loads for Pipe Elbows," ASME Paper 71-PVP-37, American Society of Mechanical Engineers, New York May 1971.

7. G. H. Powell, R. W. Clough, and A. N. Gantayat, "Stress Analysis of B16.9 Tees by the Finite Element Method," ASME Paper 71-PVP-40, American Society of Mechanical Engineers, New York, May 1971.
8. J. K. Hayes and B. Roberts, "Experimental Stress Analysis of 24-Inch Tees," ASME Paper 71-PVP-28, American Society of Mechanical Engineers, New York, May 1971.
9. J. M. Corum et al., "Experimental and Finite Element Stress Analysis of a Thin-Shell Cylinder-to-Cylinder Model," ASME Paper 71-PVP-36, American Society of Mechanical Engineers, New York, May 1971.
10. W. L. Greenstreet, S. E. Moore, and J. P. Callahan, *Second Annual Progress Report on Studies in Applied Solid Mechanics (Nuclear Safety)*, ORNL-4693 (July 1971).
11. J. M. Corum and W. L. Greenstreet, "Experimental Elastic Stress Analysis of Cylinder-to-Cylinder Shell Models and Comparisons with Theoretical Predictions," Paper No. G2/5, First International Conference on Structural Mechanics in Reactor Technology, Berlin, Germany, Sept. 20-24, 1971.
12. R. W. Clough, G. H. Powell, and A. N. Gantayat, "Stress Analysis of B16.9 Tees by the Finite Element Method," Paper No. F4/7, First International Conference on Structural Mechanics in Reactor Technology, Berlin, Germany, Sept. 20-24, 1971.
13. R. L. Johnson, *Photoelastic Determination of Stresses in ASA B16.9 Tees*, Research Report 71-9E7-PHOTO-R2, Westinghouse Research Laboratory (November 1971).
14. E. C. Rodabaugh and S. E. Moore, *Phase Report No. 115-10 on Comparisons of Test Data with Code Methods for Fatigue Evaluations*, ORNL-TM-3520 (November 1971).
15. W. G. Dodge and S. E. Moore, *Stress Indices and Flexibility Factors for Moment Loadings on Elbows and Curved Pipe*, ORNL-TM-3658 (March 1972).
16. J. E. Brock, *Elastic Buckling of Heated, Straight-Line Piping Configurations*, ORNL-TM-3607 (March 1972).
17. J. M. Corum et al., *Theoretical and Experimental Stress Analysis of ORNL Thin-Shell Cylinder-to-Cylinder Model No. 1*, ORNL-4553 (October 1972).
18. W. G. Dodge and J. E. Smith, *A Diagnostic Procedure for the Evaluation of Strain Data from a Linear Elastic Test*, ORNL-TM-3415 (November 1972).

19. W. G. Dodge and S. E. Moore, "Stress Indices and Flexibility Factors for Moment Loadings on Elbows and Curved Pipe," *Welding Research Council Bulletin 179*, December 1972.
20. W. L. Greenstreet, S. E. Moore, and J. P. Callahan, *Third Annual Progress Report on Studies in Applied Solid Mechanics (Nuclear Safety)*, ORNL-4821 (December 1972).
21. W. G. Dodge and S. E. Moore, *ELBØW: A Fortran Program for the Calculation of Stresses, Stress Indices, and Flexibility Factors for Elbows and Curved Pipe*, ORNL-TM-4098 (April 1973).
22. W. G. Dodge, *Secondary Stress Indices for Integral Structural Attachments to Straight Pipe*, ORNL-TM-3476 (June 1973). Also in *Welding Research Council Bulletin 198*, September 1974.
23. E. C. Rodabaugh, W. G. Dodge, and S. E. Moore, *Stress Indices at Lug Supports on Piping Systems*, ORNL-TM-4211 (May 1974). Also in *Welding Research Council Bulletin 198*, September 1974.
24. W. L. Greenstreet, S. E. Moore, and J. P. Callahan, *Fourth Annual Progress Report on Studies in Applied Solid Mechanics (Pressure Vessels and Piping System Components)*, ORNL-4925 (July 1974).
25. G. H. Powell, *Finite Element Analysis of Elastic-Plastic Tee Joints*, ORNL-Sub-3193-2 (UC-SESM 74-14), College of Engineering, University of California, Berkeley (September 1974).
26. R. C. Gwaltney, *CURT-II - A Computer Program for Analyzing Curved Tubes or Elbows and Attached Pipes with Symmetric and Unsymmetric Loadings*, ORNL-TM-4646 (October 1974).
27. E. C. Rodabaugh and S. E. Moore, *Stress Indices and Flexibility Factors for Concentric Reducers*, ORNL-TM-3795 (February 1975).
28. D. R. Henley, *Test Report on Experimental Stress Analysis of a 24 Inch Diameter Tee (ORNL T-13)*, ORNL-Sub-3310-3 (CENC 1189), Combustion Engineering, Inc. (March 1975).
29. D. R. Henley, *Test Report on Experimental Stress Analysis of a 24 Inch Diameter Tee (ORNL T-12)*, ORNL-Sub-3310-4 (CENC 1237), Combustion Engineering, Inc. (April 1975).
30. D. R. Henley, *Test Report on Experimental Stress Analysis of a 24 Inch Diameter Tee (ORNL T-16)*, ORNL-Sub-3310-5 (CENC 1239), Combustion Engineering, Inc. (June 1975).
31. R. C. Gwaltney, S. E. Bolt, and J. W. Bryson, *Theoretical and Experimental Stress Analysis of ORNL Thin-Shell Cylinder-to-Cylinder Model 4*, ORNL-5019 (June 1975).

32. R. C. Gwaltney, S. E. Bolt, J. M. Corum, and J. W. Bryson, *Theoretical and Experimental Stress Analysis of ORNL Thin-Shell Cylinder-to-Cylinder Model 3*, ORNL-5020 (June 1975).
33. E. C. Rodabaugh and S. E. Moore, *Stress Indices for ANSI B16.11 Standard Socket-Welding Fittings*, ORNL-TM-4929 (August 1975).
34. R. C. Gwaltney, J. W. Bryson, and S. E. Bolt, *Experimental and Finite-Element Analysis of ORNL Thin-Shell Model No. 2*, ORNL-5021 (October 1975).

1. INTRODUCTION

Purpose and Scope

The *ASME Boiler and Pressure Vessel Code*¹ gives rules for designing bolted flange connections with ring-type gaskets based on a stress analysis developed by Waters et al.² These rules give formulas and graphs for calculating stresses due to a moment applied to the flange ring. The Code rules, however, do not require that stresses due to internal pressure be taken into account, although Ref. 2 briefly discusses such stresses.

The computer program FLANGE was written to calculate not only the stresses due to moment loads on the flange ring but also stresses due to internal pressure; stresses due to a temperature difference between the hub and ring; and stresses due to the variations in bolt load that result from pressure, hub-ring temperature gradient, and/or bolt-ring temperature difference. The program FLANGE is applicable to tapered-hub, straight, and blind flanges. The analysis method is based on the differential equations for thin plates and shells rather than on the strain-energy method used by Waters et al.² The stresses due to moment loading calculated by the two methods are essentially identical for identical boundary conditions. The analysis provided herein also includes a different, and perhaps more realistic, set of boundary conditions than those used in Ref. 2.

The nomenclature used in this report is identified in the remainder of this chapter. In Chapter 2 a description of the general model of flanges used in the theoretical development of the computer code is provided. The actual mathematical expressions for calculating stresses and displacements due to moment and pressure loads are derived in Chapters 3, 4, and 5 for tapered-hub, straight hub, and blind flanges, respectively. In Chapters 6 and 7, these expressions are extended to include the effects of thermal gradients and variations in bolt loads. The computer program FLANGE is described in the last chapter of this report. Example calculations, listings, and flowcharts of the program and its subroutines are included as appendices.

Nomenclature

a = outside radius of ring
 A = $2a$ = outside diameter of ring
 A_b = cross-sectional bolt area
 A_g = gasket area
 b = inside radius of ring and mean radius of pipe
 B = $2b$ = inside diameter of ring
 b_n = Bessel function of n
 c = bolt-circle radius
 C = $2c$ = bolt-circle diameter
 C_i = constant of integration
 C'_i = C_i/b
 D = $E t^3 / 12(1 - \nu^2)$
 D_{ij} = constants of integration (blind-flange analysis)
 E = E_f = modulus of elasticity of flange material
 E_b = modulus of elasticity of bolt material
 E_g = modulus of elasticity of gasket material
 f = ASME Code design parameter
 F = ASME Code design parameter
 g_0 = wall thickness of pipe
 g_1 = wall thickness of hub at intersection with ring
 g = gasket centerline radius
 G = $2g$ = gasket centerline diameter
 h = length of tapered-wall hub
 K = $a/b = A/B$
 l_0 = bolt length
 M = total moment applied to ring, in.-lb
 M_i or M_{ij} = moment resultants, in.-lb/in.
 p = internal pressure
 P_i = shear resultants, lb/in.
 $P^* = \frac{[1 - (\nu/2)]bp}{g_0 E}$ = nondimensional pressure parameter
 r = radial coordinate, ring

t = ring thickness
 t_x = hub thickness
 u = radial displacement, hub
 u_1 = radial displacement, pipe
 u_r = radial displacement, ring
 V = ASME Code design parameter
 v_0 = undeformed gasket thickness
 w = axial displacement, ring
 W_1 = initial bolt load, lb
 W_2 = residual bolt load, lb
 x = axial coordinate, hub
 x_1 = axial coordinate, pipe
 $\alpha = (g_1 - g_0)/g_0 = \rho - 1$ = nondimensional wall-thickness parameter
 $\beta = [3(1 - \nu^2)/b^2 g_0^2]^{1/4}$ = dimensional parameter used in the analysis
 $\gamma = [12(1 - \nu^2)/b^2 g_0^2]^{1/4}(h)$ = dimensional parameter used in the analysis
 Δ = temperature difference between hub/pipe and ring
 δ_i = axial displacement of ring
 ϵ_f = coefficient of thermal expansion, flange material
 ϵ_b = coefficient of thermal expansion, bolt material
 ϵ_g = coefficient of thermal expansion, gasket material
 $\eta = 2\gamma(\psi/\alpha)^{1/2}$ = nondimensional argument of the modified Bessel functions
 ν = Poisson's ratio (0.3 used herein)
 $\xi = x/h$ = nondimensional distance parameter
 $\rho = g_1/g_0$ = nondimensional wall-thickness parameter
 σ = stress, with subscripts:
 l = longitudinal (pipe or hub)
 c = circumferential (pipe or hub)
 t = tangential (ring)
 r = radial (ring)
 b = bending
 m = membrane
 o = outside surface of the pipe or hub on the hub side of ring
 i = inside surface of the pipe or hub on the gasket-face side of ring
 $\psi = \xi + (1/\alpha)$ = nondimensional parameter

2. GENERAL DESCRIPTION OF THE ANALYSIS

The model used for the analysis of tapered-hub flanges is shown in Fig. 1. The three parts involved are the pipe, hub, and ring, respectively. The analysis presented here is based on the theory of thin plates and shells. The pipe is considered to be a uniform-wall-thickness cylindrical shell with midsurface radius b . The hub is considered to be a linearly variable-wall-thickness cylindrical shell with midsurface radius b . The ring is considered to be a flat annular plate with constant thickness t , inside radius b , and outside radius a . The effects of the bolt holes are neglected.

Three different types of loadings on bolted flanges are considered:

1. Bolt load, represented by W in Fig. 1. In application, the moment M applied to the flange ring is converted into an equivalent bolt load by the relationship $W(a - b) = M$. This is the same approach used in the ASME Code calculation method.¹

2. Internal pressure, acting radially on the pipe, hub, and ring and axially on an (assumed remote) end closure on the pipe.

3. A temperature difference between the pipe and the ring. The pipe and the hub are assumed to be at the same uniform temperature. The ring is also assumed to be at a uniform temperature, which may be different from that of the pipe or hub.

Upon integration of the shell and plate differential equations, algebraic equations in terms of dimensions, materials properties and loadings, and 12 integration constants are obtained, 4 for each part. These constants are evaluated by the usual discontinuity analysis method of writing continuity equations at the junctures of the parts and at the boundaries. After numerical values are determined for the constants, the algebraic equations provide the means for computing the stresses and deflections. In the development of the equations for stresses, the assumption is made that the bolt load W does not change with pressure or temperature. Later the analysis is modified to include changes in W as a function of these loadings. Because the relations are linear, it is possible to determine the stresses (or stress range) due to combinations

ORNL-DWG 75-4299

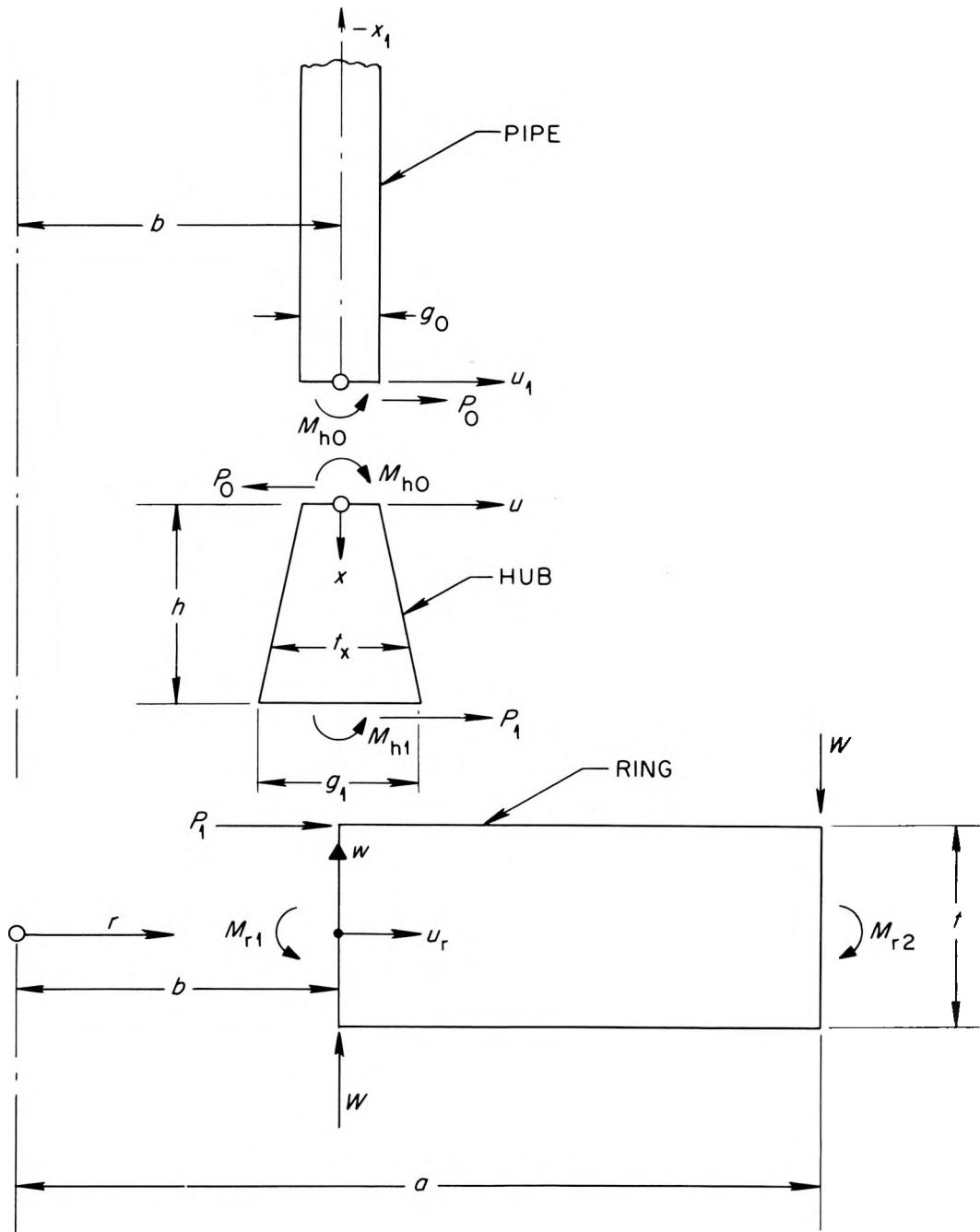


Fig. 1. Analysis model of a tapered-hub flange.

of initial bolt loading, pressure, and temperature change. The model used for straight-hub flanges is a simplification of the tapered-hub case in that only two parts are involved, the pipe and the ring.

In common with all shell-type analyses, the analysis gives anomalous results at points of abrupt thickness change or meridional direction change. In particular, the stresses at the juncture of the hub to the ring represent only the gross loading effect; detailed local stresses are not determined by the theory. Displacements, however, are represented fairly accurately.

3. FLANGE WITH A TAPERED-WALL HUB

The first step in deriving the stress equations is to state the basic shell/plate equations for the ring, the hub, and the pipe. We then inspect the boundary conditions, compute the constants, and calculate the stresses and displacements.

Equations for the Annular Ring

The basic differential equation for the displacement w of a circular plate given by Timoshenko³ is

$$\frac{1}{r} \frac{d}{dr} \left\{ r \frac{d}{dr} \left[\frac{1}{r} \frac{d}{dr} \left(r \frac{dw}{dr} \right) \right] \right\} = \frac{q}{D}, \quad (1)$$

where the coordinate r and displacement w are illustrated in Fig. 1 and q = a uniformly distributed lateral load on the plate, $D = Et^3/12(1 - \nu^2)$ = the flexural rigidity of the plate, E = modulus of elasticity of the flange material, t = plate thickness, and ν = Poisson's ratio. Equation (1) can be integrated to give a relation for the displacement in terms of arbitrary constants:

$$w = C_7 r^2 \ln r + C_8 r^2 + C_9 \ln r + C_{10} + \frac{r^4 q}{64D}, \quad (2)$$

where numerical values for the constants C_7, \dots, C_{10} are established from boundary conditions. Derivatives of w , required in the subsequent analysis, are:

$$\frac{dw}{dr} = C_7(2r \ln r + r) + 2C_8r + \frac{C_9}{r} + \frac{r^3 q}{16D}, \quad (3)$$

$$\frac{d^2w}{dr^2} = C_7(2 \ln r + 3) + 2C_8 - \frac{C_9}{r^2} + \frac{3r^2 q}{16D}, \quad (4)$$

and

$$\frac{d^3w}{dr^3} = C_7 \left(\frac{2}{r} \right) + \frac{2C_9}{r^3} + \frac{3rq}{8D} . \quad (5)$$

In the subsequent analysis the distributed load q is taken as zero.

The radial and tangential moments are given³ by the equations:

$$M_r = -D \left(\frac{d^2w}{dr^2} + \nu \frac{dw}{dr} \right) \quad (6)$$

and

$$M_t = -D \left(\frac{1}{r} \frac{dw}{dr} + \nu \frac{d^2w}{dr^2} \right) . \quad (7)$$

Using Eqs. (3) and (4), these moments can be expressed as

$$M_r = -D \left\{ C_7[2(1 + \nu) \ln r + (3 + \nu)] + C_8[2(1 + \nu)] - C_9 \left(\frac{1 - \nu}{r^2} \right) \right\} \quad (8)$$

and

$$M_t = -D \left\{ C_7[2(1 + \nu) \ln r + (1 + 3\nu)] + C_8[2(1 + \nu)] + C_9 \left(\frac{1 - \nu}{r^2} \right) \right\} . \quad (9)$$

Equations for the Tapered Hub

The basic differential equation for the radial displacement u of a cylindrical shell with a linearly variable wall thickness t_x is given by Timoshenko³ as

$$\frac{d^2}{dx^2} \left(t_x^3 \frac{d^2 u}{dx^2} \right) + \frac{12(1 - v^2)t_x u}{b^2} - \frac{12(1 - v^2)[1 - (v/2)]p}{E} = 0. \quad (10)$$

The solution of Eq. (10) can be shown* to be:

$$u = \frac{b}{\psi^{1/2}} (C_1 b_1 + C_2 b_2 + C_3 b_3 + C_4 b_4) + \frac{b P^*}{1 + \alpha \xi}, \quad (11)$$

where $P^* = [1 - (v/2)]bp/g_0E$. Derivatives of u , required in the subsequent analysis, are

$$u' = \frac{du}{dx} = \frac{b}{2\psi^{3/2}h} (C_1 b_5 + C_2 b_6 + C_3 b_7 + C_4 b_8) - \frac{b\alpha P^*}{h(1 + \alpha \xi)^2}, \quad (12)$$

$$u''' = \frac{d^2u}{dx^2} = \frac{b}{4\psi^{5/2}h^2} (C_1 b_9 + C_2 b_{10} + C_3 b_{11} + C_4 b_{12}) + \frac{2b\alpha^2 P^*}{h^2(1 + \alpha \xi)^3}, \quad (13)$$

and

$$u'''' = \frac{d^3u}{dx^3} = \frac{b}{8\psi^{7/2}h^3} (C_1 b_{13} + C_2 b_{14} + C_3 b_{15} + C_4 b_{16}) - \frac{6r\alpha^2 P^*}{h^3(1 + \alpha \xi)^4}. \quad (14)$$

The b_n 's used in Eqs. (11) through (14) are modified Bessel functions of argument $n = 2\gamma(\psi/\alpha)^{1/2}$ defined in Table 1, which gives equations for $n = 1$ through 20; ψ , α , and ξ are defined in the nomenclature.

* A solution to an equation that is essentially the same as Eq. (10) is given by Timoshenko,³ who credits the original solution to G. Kirchoff in 1879.

Table 1. Modified Bessel functions of argument η^α

$b_1 = \text{ber}' \eta$
$b_2 = \text{bei}' \eta$
$b_3 = \text{ker}' \eta$
$b_4 = \text{kei}' \eta$
$b_5 = -\eta \text{ bei } \eta - 2 \text{ ber}' \eta$
$b_6 = \eta \text{ ber } \eta - 2 \text{ bei}' \eta$
$b_7 = -\eta \text{ kei } \eta - 2 \text{ ker}' \eta$
$b_8 = \eta \text{ ker } \eta - 2 \text{ kei}' \eta$
$b_9 = 4\eta \text{ bei } \eta + 8 \text{ ber}' \eta - \eta^2 \text{ bei}' \eta$
$b_{10} = -4\eta \text{ ber } \eta + 8 \text{ bei}' \eta + \eta^2 \text{ ber}' \eta$
$b_{11} = 4\eta \text{ kei } \eta + 8 \text{ ker}' \eta - \eta^2 \text{ kei}' \eta$
$b_{12} = -4\eta \text{ ker } \eta + 8 \text{ kei}' \eta + \eta^2 \text{ ker}' \eta$
$b_{13} = -\eta^3 \text{ ber } \eta - 24\eta \text{ bei } \eta - 48 \text{ ber}' \eta + 8\eta^2 \text{ bei}' \eta$
$b_{14} = -\eta^3 \text{ bei } \eta + 24\eta \text{ ber } \eta - 48 \text{ bei}' \eta - 8\eta^2 \text{ ber}' \eta$
$b_{15} = -\eta^3 \text{ ker } \eta - 24\eta \text{ kei } \eta - 48 \text{ ker}' \eta + 8\eta^2 \text{ kei}' \eta$
$b_{16} = -\eta^3 \text{ kei } \eta + 24\eta \text{ ker } \eta - 48 \text{ kei}' \eta - 8\eta^2 \text{ ker}' \eta$
$b_{17} = -\eta \text{ ber } \eta + 2 \text{ bei}' \eta$
$b_{18} = -\eta \text{ bei } \eta - 2 \text{ ber}' \eta$
$b_{19} = -\eta \text{ ker } \eta + 2 \text{ kei}' \eta$
$b_{20} = -\eta \text{ kei } \eta - 2 \text{ ker}' \eta$

^aThe argument $\eta = 2\gamma(\psi/\alpha)^{1/2}$, where $\gamma = [12(1 - v^2)/b^2 g_0^2]^{1/4}(h)$, $\psi = \xi + (1/\alpha)$, $\xi = x/h$, and $\alpha = (g_1 - g_0)/g_0$.

Equations for the Pipe

The basic differential equation for the radial displacement u_1 of a cylindrical shell with uniform wall thickness is:

$$g_0^3 \frac{d^4 u_1}{dx_1^4} + \frac{12(1 - \nu^2)g_0}{b^2} u_1 - \frac{12(1 - \nu^2)[1 - (\nu/2)]p}{E} = 0 . \quad (15)$$

The solution of Eq. (15) is:

$$u_1 = e^{-\beta x_1} (C_{11} \sin \beta x_1 + C_{12} \cos \beta x_1) + e^{\beta x_1} (C_5 \sin \beta x_1 + C_6 \cos \beta x_1) + bP^* . \quad (16)$$

For large negative values of x_1 , $u_1 = bP^*$. Hence, $C_{11} = C_{12} = 0$.

Derivatives of u_1 needed in the subsequent analysis are

$$u_1' = \frac{du_1}{dx_1} = \beta e^{\beta x_1} [C_5 (\sin \beta x_1 + \cos \beta x_1) + C_6 (\cos \beta x_1 - \sin \beta x_1)] , \quad (17)$$

$$u_1'' = \frac{d^2 u_1}{dx_1^2} = 2\beta^2 e^{\beta x_1} [C_5 \cos \beta x_1 - C_6 \sin \beta x_1] , \quad (18)$$

and

$$u_1''' = \frac{d^3 u_1}{dx_1^3} = -2\beta^3 e^{\beta x_1} [C_5 (\sin \beta x_1 - \cos \beta x_1) + C_6 (\sin \beta x_1 + \cos \beta x_1)] . \quad (19)$$

Boundary Conditions

The equations listed above involve ten unknown constants: C_1, C_2, \dots, C_{10} . These can be determined from the ten boundary-condition

equations shown in Table 2 [Eq. (20)]. The ASME Code stress-calculation method¹ is based on the assumption that the radial displacement at the hub-to-ring juncture is zero. A more realistic assumption (particularly for internal pressure loading) is that the displacement of the hub equals the displacement of the surface of the ring where it joins the hub. Boundary-condition equations for both of these alternatives are provided in Table 2. [See Eqs. (20-5).] In Eq. (20-5b) a positive dw/dr gives a negative radial displacement at the surface of the ring adjacent to the hub. Also in Eq. (20-5b), u_r is the radial expansion of the ring due to internal pressure as given by Lame's equation:

$$u_r = -\frac{b}{E} \left[\frac{(1 + \nu)k^2 + (1 - \nu)}{k^2 - 1} \right] \left(p - \frac{P_1}{t} \right), \quad (21)$$

where $k = a/b$. In this expression, it is assumed that in addition to internal pressure p , the shear resultant P_1 is uniformly distributed around the inner edge of the ring.

Boundary Equations

When the equations in Table 2 are satisfied simultaneously, they establish the values of the ten constants (C_1, C_2, \dots, C_{10}) in terms of the dimensions, Poisson's ratio, and the loads (total bolt load W and internal pressure p). After algebraic manipulation, the equations are reduced to the forms shown in Table 3. This table provides the elements for the matrix equation $[A] |C| + |B| = 0$, where the terms in the coefficient matrix $[A]$ are given under the headings of the corresponding constants in the column matrix $|C|$. The loading parameters constitute the column matrix $|B|$.

To derive numerical values for the constants, three items should be noted.

1. It is convenient to define two new constants, $C'_5 = C_5/b$ and $C'_6 = C_6/b$.
2. The radial expansion of the ring u_r is defined in Eq. (21).

Table 2. Equations for the boundary conditions for a tapered-hub flange

Hub-to-pipe juncture			Hub-to-ring juncture			Ring		
	Equation	Eq. No.		Equation	Eq. No.		Equation	Eq. No.
Displacements ^a	$(u)_{x=0} = (u_1)_{x_1=0}$	(20-1)		$(u)_{x=h} = 0$	(20-5a)		$(w)_{r=b} = 0$	(20-8)
	$(u)_{x=h} = (u_r - \frac{t}{2} \frac{dw}{dr})_{r=b}$	(20-5b)					(Footnote b)	
Rotations	$(u')_{x=0} = (u'_1)_{x_1=0}$	(20-2)		$(u')_{x=h} = \left(\frac{dw}{dr} \right)_{r=b}$	(20-6)			
Moments ^c	$(u'')_{x=0} = (u''_1)_{x_1=0}$	(20-3)		$M_{h1} = -M_{r1} + \frac{1}{2} P_1 t$	(20-7)	$M_{r2} = 0$		(20-9)
Shears	$\left(\frac{3a}{h} u''' + u'''' \right)_{x=0} = (u''''_1)_{x_1=0}$	(20-4)		$Q = - \frac{dM_r}{dr} + \frac{M_t - M_r}{r} = \frac{W}{2\pi r}$	(20-10)			

^aRadial for hub-to-pipe and hub-to-ring junctures and axial for the ring.^bSetting $(w)_{r=b}$ equal to zero provides a reference point for all other axial displacements.^cRadial for ring.^dThe assumption is that the shear P_1 of the hub on the ring produces an additional moment on the ring.

Table 3. Matrix coefficients of the discontinuity equations^a for a flange with a tapered-wall hub

Eq. No.	C_1	C_2	C_3	C_4	C_5^t	C_6^t	C_7	C_8	C_9	C_{10}	Loading parameters
(20-1) ^b	b_1^0	b_2^0	b_3^0	b_4^0	0	$-\psi_0^{1/2}$	0	0	0	0	0
(20-2)	b_5^0	b_6^0	b_7^0	b_8^0	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	0	0	0	0	$-2\psi_0^{1/2} p^*$
(20-3)	b_9^0	b_{10}^0	b_{11}^0	b_{12}^0	$-\eta_0^2 \psi_0^{1/2}$	0	0	0	0	0	$8\psi_0^{1/2} p^*$
(20-4)	b_{17}^0	b_{18}^0	b_{19}^0	b_{20}^0	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	$-\frac{\eta_0 \psi_0^{1/2}}{\sqrt{2}}$	0	0	0	0	0
(20-5a) ^c	b_1^t	b_2^t	b_3^t	b_4^t	0	0	0	0	0	0	$(\psi_1^{1/2}/b)(bP^*/\rho)$
(20-5b) ^d	$b_1^t + U_1 b_5^t - b_2^t + U_1 b_6^t - b_3^t + U_1 b_7^t - b_4^t + U_1 b_8^t - U_2 U_3 b_{17}^t$	$U_2 U_3 b_{18}^t$	$U_2 U_3 b_{19}^t$	$U_2 U_3 b_{20}^t$	0	0	0	0	0	0	$(\psi_1^{1/2}/b)(bP^*/\rho - U_3 p + U_4)$
(20-6)	b_5^t	b_6^t	b_7^t	b_8^t	0	0	$-2\psi_1^{3/2} h \times$ ($2 \ln b + 1$)	$-4\psi_1^{3/2} h$	$-2\psi_1^{3/2} h/b^2$	0	$-2\psi_1^{1/2} p^*/\rho$
(20-7) ^d	$b_9^t + U_5 b_{17}^t$	$b_{10}^t + U_5 b_{18}^t$	$b_{11}^t + U_5 b_{19}^t$	$b_{12}^t + U_5 b_{20}^t$	0	0	$U_6 [2(1+v) \ln b + (3+v)]$	$-U_6 \frac{(1-v^2)}{b^2}$	0	0	$8\psi_1^{1/2} p^*/\rho$
(20-8)	0	0	0	0	0	0	$b^2 \ln b$	b^2	$\ln b$	1.0	0
(20-9)	0	0	0	0	0	0	$2(1-v) \ln a + (3+v)$	$2(1+v)$	$-(1-v)/a^2$	0	0
(20-10)	0	0	0	0	0	0	1.0	0	0	0	$-\frac{3(1-v^2)M}{2\pi Et^3(a-b)}$

^aThese equations are in the form $[A]|C| + |B| = 0$, where $[A]$ is the coefficient matrix, $|C|$ is the column matrix of unknown constants, and $|B|$ is the column matrix of loading parameters.

^bA superscript "0" on the b 's indicates that the Bessel function is to be evaluated at $x = 0$, $\eta = 2\gamma/a$.

^cA prime ('') on the b 's indicates that the Bessel function is to be evaluated at $x = h$, $\eta = 2\gamma p^{1/2}/a$.

^d $U_1 = t/4\psi_1 h$; $U_2 = \eta_1^2 E g_1^3 / 96 t \psi_1^3 h^3 (1-v^2)$; $U_3 = (b/E) \left[\frac{(1+v)K^2 + (1-v)}{K^2 - 1} \right]$, where $K = a/b$; $U_4 = tbaP^*/2h(1+\alpha)^2$; $U_5 = \gamma^2 t/h\alpha$; $U_6 = -4\psi_1^{5/2} h^2 t^3 / b g_1^3$.

3. The ASME Code stress-calculation method uses a moment M , applied to the flange ring, rather than a bolt load W , where the correlation between M and W is $M = W(a - b)$. In the present analysis, however, Eq. (20-10) from Table 2 is used with the loading parameter M , rather than W .

Stresses

After having solved the set of equations in Table 3 for the constants C_1, \dots, C_{10} , the stresses can be obtained anywhere in the structure. The equations for these stresses, used in other reports^{4,5} in this series, are given in Table 4 [Eqs. (22)–(45)] for the same locations as those given by the ASME Code stress-calculation method; these are (1) at the hub-to-pipe juncture, (2) in the hub at the hub-to-ring juncture, and (3) at the inside edge of the ring ($r = b$).

Displacements

In Chapter 7 the displacements w of the flange ring are used. The equations for these displacements (with w arbitrarily set to zero at $r = b$) are:

$$w_g = C_7g^2 \ln g + C_8g^2 + C_9 \ln g + C_{10} \quad (46)$$

at the gasket centerline radius, $g = G/2$; and

$$w_c = C_7c^2 \ln c + C_8c^2 + C_9 \ln c + C_{10} \quad (47)$$

at the bolt-circle radius, $c = C/2$.

Table 4. Equations for the stresses in a tapered-hub flange

Type	Hub-to-pipe-juncture, longitudinal and circumferential		Hub-to-ring juncture, longitudinal and circumferential		Inside edges of ring, tangential and radial	
	Equation	Eq. No.	Equation	Eq. No.	Equation	Eq. No.
Longitudinal or tangential						
Bending	$(\sigma_{\ell})_b = \pm \frac{Eg_0}{2(1 - v^2)} (2b^2) C_5^t b$	(22)	$(\sigma_{\ell})_b = \pm \frac{Eg_1}{2(1 - v^2)} \left[\frac{b}{4\psi_1^5/2h^2} (C_1 b_9^t + C_2 b_{10}^t) + C_3 b_{11}^t + C_4 b_{12}^t \right] + \frac{2ba^2 P^*}{h^2(1 + \alpha)^3}$	(30)	$(\sigma_t)_b = \pm (6/t^2) (M_t)_{r=b} = \pm [Et/2(1 - v^2)] \times [C_7(2.6 \ln b + 1.9) + 2.6C_8 + 0.7C_9/b^2]$	(38)
Membrane	$(\sigma_{\ell})_m = pb/2g_0$	(23)	$(\sigma_{\ell})_m = pb/2g_1$	(31)	$(\sigma_t)_m = \frac{K^2 + 1}{K^2 - 1} \left(p - \frac{p_1}{t} \right)$	(39) ^a
Outside	$(\sigma_{\ell})_o = pb/2g_0 - 1.816C_5^t$	(24)	$(\sigma_{\ell})_o = pb/2g_1 - (\sigma_{\ell})_b$	(32)	$(\sigma_t)_o = (\sigma_t)_m + (\sigma_t)_b$	(40) ^b
Inside	$(\sigma_{\ell})_i = pb/2g_0 + 1.816C_5^t$	(25)	$(\sigma_{\ell})_i = pb/2g_1 + (\sigma_{\ell})_b$	(33)	$(\sigma_t)_i = (\sigma_t)_m - (\sigma_t)_b$	(41) ^c
Circumferential or radial						
Bending	$\pm(\sigma_c)_b = \pm v(\sigma_{\ell})_b$	(26)	$\pm(\sigma_c)_b = \pm(\sigma_{\ell})_b$	(34)	$(\sigma_r)_b = \pm \frac{6M_r t}{t^2} = \pm \frac{Et}{2(1 - v^2)} \times [C_7(2.6 \ln b + 3.3) + 2.6C_8 - 0.7C_9/b^2]$	(42)
Membrane	$(\sigma_c)_m = (Eu_0/b) + v(pb/2g_0)$	(27) ^d	$(\sigma_c)_m = (Eu_h/b) + v(pb/2g_1)$	(35) ^e	$(\sigma_r)_m = -p + p_1/t$	(43)
Outside	$(\sigma_c)_o = (Eu_0/b) + v(\sigma_{\ell})_o$	(28)	$(\sigma_c)_o = (Eu_h/b) + v(\sigma_{\ell})_o$	(36)	$(\sigma_r)_o = (\sigma_r)_m + (\sigma_t)_b$	(44) ^b
Inside	$(\sigma_c)_i = (Eu_0/b) + v(\sigma_{\ell})_i$	(29)	$(\sigma_c)_i = (Eu_h/b) + v(\sigma_{\ell})_i$	(37)	$(\sigma_r)_i = (\sigma_r)_m - (\sigma_t)_b$	(45) ^c

^aHere, $K = a/b$, and $\frac{p_1}{t} = - \frac{Eg_1^3}{(1 - v^2)} \frac{bn_1^2}{8h^3\psi_1^{7/2}} (C_1 b_{17}^t + C_2 b_{18}^t + C_3 b_{19}^t + C_4 b_{20}^t)$.

^bHub-side surface of ring.

^cGasket-side surface of ring.

^d $u_o = b(C_6^t + P^*)$.

^e $u_h = \frac{b}{\psi_1^{1/2}} (C_1 b_1^t + C_2 b_2^t + C_3 b_3^t + C_4 b_4^t) + bP^*/(1 + \alpha)$.

4. FLANGE WITH A STRAIGHT HUB

Although the mathematical expressions for the straight hub can be obtained by letting $g_0 = g_1$, this would result in indeterminate quantities in the computer program. Therefore, the direct solution to the ring with a straight hub was obtained by using the previously given basic equations for only the pipe and the ring. There are six constants of integration to be established; the boundary-condition equations are displayed in Table 5 [Eq. (48)].

After algebraic manipulation, the equations displayed in Table 5 are reduced to the matrix-equation form $[A]|C| + |B| = 0$, where the terms in the coefficient matrix $[A]$ are given in Table 6 under the headings of the corresponding constants in the column matrix $|C|$. Solving this set of equations for the six constants ($C_5^1, C_6^1, C_7, C_8, C_9$, and C_{10}) allows calculation of the stresses in the structure. The equations for the stresses in the pipe at the pipe-to-ring juncture and in the ring at the inner edge ($r = b$) are analogous to those previously derived for the flange with a tapered hub (see Table 4).

One can calculate the displacements w_g and w_c for a straight-hub flange from Eqs. (46) and (47), respectively, using the constants C_7, \dots, C_{10} , identified in Table 6.

Table 5. Equations for the boundary conditions for a straight-hub flange

	Hub-to-ring juncture		Ring	
	Equation	Eq. No.	Equation	Eq. No.
Displacements	$(u_1)_{x_1=0} = 0$	(48-1a) ^{a,b}	$(w)_{r=b} = 0$	(48-4) ^c
	$(u_1)_{x_1=0} = \left(u_r - \frac{t}{2} \frac{dw}{dr} \right)_{r=b}$	(48-1b) ^{a,b}		
Rotations	$(u'_1)_{x_1=0} = \left(\frac{dw}{dr} \right)_{r=b}$	(48-2)		
Moments	$M_{r1} = -M_{ho} + \frac{1}{2} P_0 t$	(48-3)	$M_{r2} = 0$	(48-5) ^d
Shear along radius r			$Q = - \frac{dM_r}{dr} + \frac{M_t - M_r}{r} = \frac{W}{2\pi r}$	(48-6)

^aRadial displacements.

^bFor an ASME-type calculation, Eq. (48-1a) is used.

^cAxial displacements; $(w)_{r=b} = 0$ is the reference point for all other axial displacements.

^dRadial moment at outside edge of ring ($r = a$).

Table 6. Matrix coefficients of the discontinuity equations^a for a flange with a straight hub

Eq. No.	Coefficients of C_n						Loading parameters
	C_5	C_6	C_7	C_8	C_9	C_{10}	
(48-1a)	0	1.0	0	0	0	0	$bP^* + b\varepsilon_f^\Delta - U_3 P$
(48-1b) ^b	$U_{34} - U_{33}$	$1 + U_{34} + U_{33}$	0	0	0	0	0
(48-2)	β	β	$-(2b \ln b + b)$	$-2b$	0	0	0
(48-3)	$2\beta^2 + 2\beta^3 t/2$	$-2\beta_1^3 t/2$	$-(2.6 \ln b + 3.3) \times (t/g_0)^3$	$-2.6(t/g_0)^3$	$(0.7/b^2)(t/g_0)^3$	0	0
(48-4)	0	0	$b^2 \ln b$	b^2	$\ln b$	1.0	0
(48-5)	0	0	$2.6 \ln a + 3.3$	2.6	$-0.7/a^2$	0	0
(48-6)	0	0	1.0	0	0	0	$\frac{-3(1 - v^2)M}{2\pi Et^3(a - b)}$

^aThese equations are in the form $[a]|C| + |B| = 0$, where $[A]$ is the coefficient matrix, $|C|$ is the column matrix of unknown constants, $|B|$ is the column matrix of loading parameters.

$$b_{U_3} = (b/E) \left[\frac{(1 + v)K^2 + (1 - v)}{K^2 - 1} \right], \text{ where } K = a/b; U_{33} = \frac{2U_3 E g_0^3 \beta^3}{12(1 - v^2)t}; U_{34} = t\beta/2.$$

5. BLIND FLANGES

Analysis Method

Blind flanges (or flat heads) are modeled as shown in Fig. 2. The general equations for a circular flat plate are:³

$$w = D_1 r^2 \ln r + D_2 r^2 + D_3 \ln r + D_4 + r^4 p / 64D , \quad (49)$$

$$\frac{dw}{dr} = D_1 (2r \ln r + r) + D_2 (2r) + D_3/r + r^3 p / 16D , \quad (50)$$

$$\frac{d^2w}{dr^2} = D_1 (2 \ln r + 3) + D_2 (2) - D_3/r^2 + 3r^2 p / 16D , \quad (51)$$

and

$$\frac{d^3w}{dr^3} = D_1 (2/r) + D_3 (2/r^3) + 3rp / 8D . \quad (52)$$

The radial and tangential moments M_r and M_t (see Fig. 2) are given by

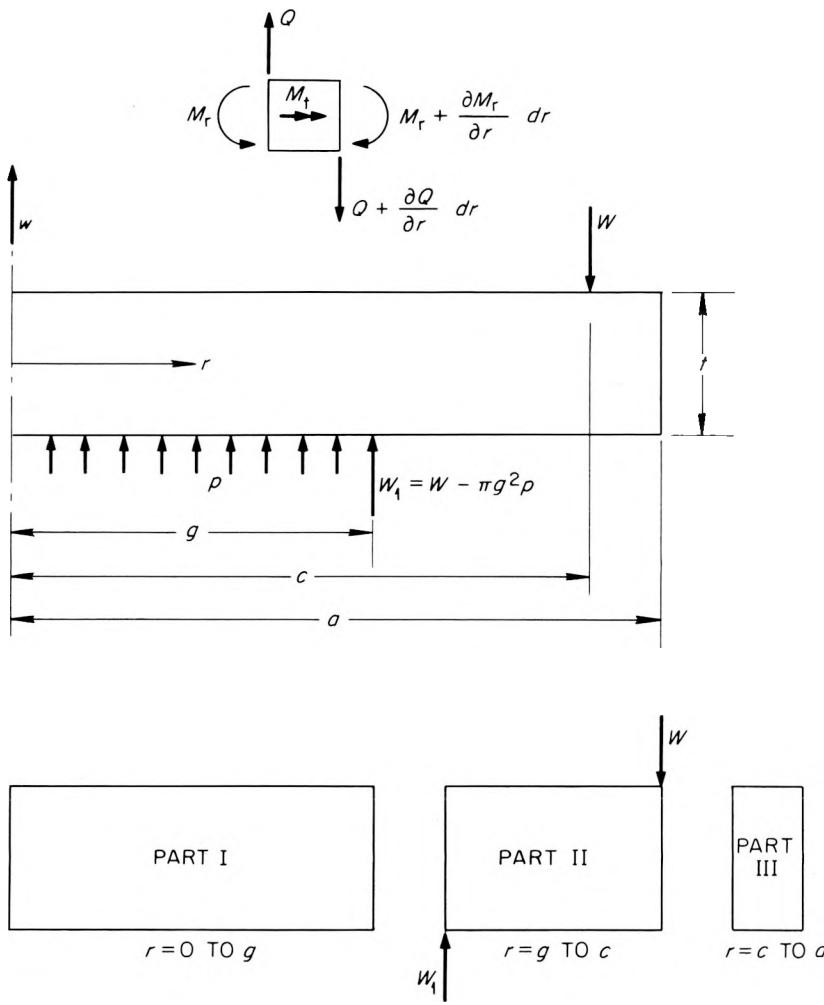
$$M_r = -D \left(\frac{d^2w}{dr^2} + \nu \frac{dw}{dr} \right) \quad (53)$$

and

$$M_t = -D \left(\frac{1}{r} \frac{dw}{dr} + \nu \frac{d^2w}{dr^2} \right) ; \quad (54)$$

and the shear is given by

$$Q = - \frac{dM_r}{dr} + \frac{M_t - M_r}{r} . \quad (55)$$



CONSTANTS:
 $D_{11}, D_{12}, D_{13}, D_{14}$ $D_{21}, D_{22}, D_{23}, D_{24}$ $D_{31}, D_{32}, D_{33}, D_{34}$

Fig. 2. Flat-plate analysis model of a blind flange or cover plate.

The moments and shears, in terms of the integration constants D_1 through D_4 , are:

$$\begin{aligned}
 M_r = & -D \{ D_1 [2(1 + \nu) \ln r + (3 + \nu)] + D_2 [2(1 + \nu)] - D_3 [(1 - \nu)/r^2] \} \\
 & - r^2 p/16(3 + \nu) , \quad (56)
 \end{aligned}$$

$$M_t = -D\{D_1[2(1 + v) \ln r + (1 + 3v)] + D_2[2(1 + v)] + D_3[(1 - v)/r^2]\} - r^2 p/16(1 + 3v) , \quad (57)$$

and

$$Q = D \left(\frac{4D_1}{r} \right) + \frac{rp}{2} . \quad (58)$$

For analysis, the plate is divided into three parts as shown in Fig. 2. There are four integration constants for each segment. The boundary-condition equations used to evaluate these constants are shown in Table 7. These boundary conditions show that 3 of the 12 constants are zero. The set of simultaneous equations to be solved to establish the remaining 9 constants is shown in Table 8. Again, this table presents the elements of the matrix equation $[A][C] + [B] = 0$.

Table 7. Boundary condition equations used for blind-flange analysis

Equation No.	Boundary condition
1	$2\pi r Q = \pi r^2 p$ for all of Part I. This gives $D_{11} = 0$.
2	$(dw/dr)_I = 0$ at $r = 0$. This gives $D_{13} = 0$.
3	$(w)_I = 0$ at $r = g$
4	$(dw/dr)_I = (dw/dr)_{II}$ at $r = g$
5	$(Q)_{II} = (W/2\pi r) - (\pi g^2 p/2\pi g)$ at $r = g$. This gives $D_{21} = W/8\pi D - g^2 p/8D$. (For pressure loading, $W = \pi g^2 p$; hence $D_{21} = 0$.)
6	$(w)_{II} = 0$ at $r = g$
7	$(M_r)_I = (M_r)_{II}$ at $r = g$
8	$(dw/dr)_I = (dw/dr)_{II}$ at $r = g$
9	$(Q)_{III} = 0$. This gives $D_{31} = 0$.
10	$(M_r)_{II} = (M_r)_{III}$ at $r = c$
11	$(M_r)_{III} = 0$ at $r = a$
12	$(w)_{II} = (w)_{III}$ at $r = c$

Table 8. Boundary equations^a for a blind flange

No. ^b	Coefficients of D_{ij}								Loading parameter
	D_{12}	D_{14}	D_{21}	D_{22}	D_{23}	D_{24}	D_{32}	D_{33}	
3	g^2	1.0	0	0	0	0	0	0	$g^4 p / 64D$
4	-2g	0	$2g \ln g + g$	2g	$1/g$	0	0	0	$-g^3 p / 16D$
5	0	0	1.0	0	0	0	0	0	$-W / 8\pi D$
6	0	0	$g^2 \ln g$	g^2	$\ln g$	1.0	0	0	0
7	-2.6	0	$2.6 \ln g + 3.3$	2.6	$-0.7/g^2$	0	0	0	$-3.3g^2 p / 16D$
8	0	0	$2c \ln c + c$	2c	$1/c$	0	-2c	-1/c	0
10	0	0	$2.6 \ln c + 3.3$	2.6	$-0.7/c^2$	0	-2.6	$0.7/c^2$	0
11	0	0	0	0	0	0	2.6	$-0.7/a^2$	0
12	0	0	$c^2 \ln c$	c^2	$\ln c$	1.0	$-c^2$	$-\ln c$	-1.0

^aThese equations are in the form $[A]|C| + |B| = 0$, where $[A]$ is the coefficient matrix, $|C|$ is the column matrix of unknown constants, and $|B|$ is the column matrix of loading parameters.

^bBoundary condition number from Table 4.

Stresses

After having established values for the integration constants, the stresses at any point in the blind flange can be readily obtained. Equations for stresses at the center of the flange and at $r = g$ and $r = c$ are given by

$$\sigma_t = \pm 6M_t/t^2 = \pm EtM_t/[2(1 - v^2)]D \quad (59a)$$

and

$$\sigma_r = \pm 6M_r/t^2 = \pm EtM_r/[2(1 - v^2)]D. \quad (59b)$$

At the center of the flange ($r = 0$),

$$M_t = M_r = -D\{D_{12}[2(1 + v)]\}. \quad (60)$$

At the gasket ($r = g$),

$$M_r = -D\{D_{12}[2(1 + v)] + g^2p(3 + v)/16D\}, \quad (61)$$

and

$$M_t = -D\{D_{12}[2(1 + v)] + g^2p(1 + 3v)/16D\}. \quad (62)$$

At the bolt circle ($r = c$),

$$M_r = -D\{D_{32}[2(1 + v)] - D_{33}(1 - v)/c^2\}, \quad (63)$$

and

$$M_t = -D\{D_{32}[2(1 + v)] + D_{33}(1 - v)/c^2\}. \quad (64)$$

In all of the above, a positive moment produces a tensile stress on the back of the flange (positive w side of Fig. 2).

Displacements

In the third and sixth boundary conditions listed in Table 7, the axial displacement at the gasket has been arbitrarily set equal to zero. The relative displacement of the bolt circle to the gasket is therefore

$$w_c = D_{32}c^2 + D_{33} \ln c + D_{34} . \quad (65)$$

6. THERMAL GRADIENTS

Two kinds of thermal gradients are included in the analysis: (1) a constant temperature in the pipe and hub that may be different from the assumed constant temperature in the ring and (2) a constant temperature in the bolts that may be different from the assumed constant temperature in the ring.

The significance of the bolt-to-ring thermal gradients is dependent upon the dimensional and material characteristics of the flanged joint and is covered later in Chapter 7.

The pipe/hub-to-ring temperature gradient is included in the analysis by an appropriate change in the "loading parameters" shown in Table 3. We define Δ as the difference in temperature between the pipe/hub and the ring; Δ is positive if the pipe/hub is hotter than the ring. The radial expansion of the tapered hub at its juncture with the ring is then:

$$u = \frac{b}{\sqrt{\psi_1}} (C_1 b'_1 + C_2 b'_2 + C_3 b'_3 + C_4 b'_4) + b \epsilon_f \Delta , \quad (66)$$

where b is the pipe radius; b'_i terms are the Bessel functions defined in Table 1 evaluated at $x = h$, $\eta = 2\gamma\rho^{1/2}/\alpha$, as indicated in footnote *c* of Table 3; and ϵ_f is the coefficient of thermal expansion of the flange material.

The effects of such a thermal gradient are taken into account by adding $(\sqrt{\psi_1}/b)(b \epsilon_f \Delta)$ to the existing terms in the loading-parameter column in Table 3 [Eqs. (20-5a) and (20-5b)]. The analogous term is already included in Table 6.

7. CHANGE IN BOLT LOAD WITH PRESSURE, TEMPERATURE, AND EXTERNAL MOMENTS

A flanged joint is a statically indeterminate structure. Thus, in order to determine the residual bolt load in the joint, it is necessary to calculate the relative displacements of the parts when the joint is subjected to (1) initial bolt loading, (2) moment loading, (3) internal pressure, and (4) thermal gradients.

The object of the analysis is to determine the residual bolt load W_2 in terms of (1) the loadings W_1 , p , Δ , and Δ' ; (2) the component temperatures T_b , T_g , T_f , and T'_f ; (3) the flanged-joint dimensions; and (4) the material properties.

The basic analysis is given by Wesstrom and Bergh,⁶ and we follow their nomenclature, with additions as necessary. Reference 6 covers only the effect of initial bolt loading and part of the influence of internal pressure; the remaining influence from the internal pressure is discussed by Rodabaugh.⁷ The extension of the analysis to cover thermal gradients is relatively simple and is covered below.

The nomenclature used in this development is:

A = cross-sectional area of bolts or gasket

B = inside diameter of ring

C = bolt-circle diameter

E = modulus of elasticity

g_0 = wall thickness of pipe

G = gasket centerline diameter

ℓ = bolt length

p = internal pressure

p^* = equivalent pressure for external moment loading

q = elastic deformation coefficients

t = ring thickness

T = final-state temperature (initial-state temperature is defined as zero)

v = gasket thickness

W = bolt load

δ = relative axial displacement between the gasket centerline and the bolt circle

ϵ = coefficient of thermal expansion

Δ = temperature between hub/pipe and ring

The subscripts 0, 1, and 2 refer to the undeformed, initial deformed, and final deformed states, respectively; subscripts b, g, and f refer to the bolts, gasket, and flange, respectively. Quantities with a prime (') are for one of the flanges in a pair (e.g., T_f' refers to the temperature of the right-hand flange in Fig. 3); quantities without a prime are for the other flange.

Analysis

Figure 3 shows a schematic illustration of the general case of two dissimilar flanges and their mode of deformation. When the bolts are initially tightened to make up the joint, the resulting initial deformed bolt length is

$$l_1 = v_1 + t_1 + t_1' - \delta_1 - \delta_1'. \quad (67)$$

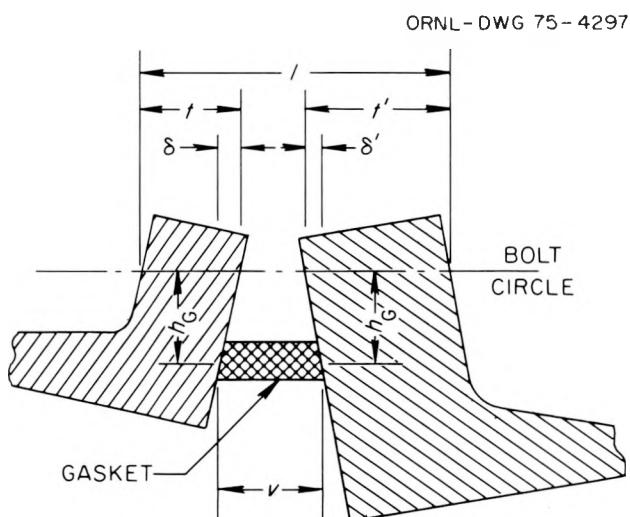


Fig. 3. General case of two dissimilar flanges and their mode of deformation.

After application of loadings, the bolt length becomes

$$l_2 = v_2 + t_2 + t'_2 - \delta_2 - \delta'_2 . \quad (68)$$

The basic displacement relationship is thus

$$\begin{aligned} l_2 - l_1 &= (v_2 - v_1) + (t_2 - t_1) + (t'_2 - t'_1) \\ &\quad - (\delta_2 - \delta_1) - (\delta'_2 - \delta'_1) . \end{aligned} \quad (69)$$

We also use the following relationships:

$$l_2 = l_0 + T_b \varepsilon_b l_0 + q_{b2} W_2 , \quad (a)$$

$$v_2 = v_0 + T_g \varepsilon_g v_0 - q_{g2} (W_2 - H_{D2} - H_{T2}) , \quad (b)$$

$$t_2 = t_0 + T_f \varepsilon_f t_0 , \quad (c)$$

$$t'_2 = t'_0 + T'_f \varepsilon'_f t'_0 , \quad (d)$$

$$\delta_2 = q_{f2} M_2 h_G + q_p p h_G + q_t \Delta h_g , \quad (e)$$

$$\delta'_2 = q'_{f2} M'_2 h_G + q'_p p h_G + q'_t \Delta' h_G , \quad (f)$$

$$l_1 = l_0 + q_{b1} W_1 , \quad (g) \quad (70)$$

$$v_1 = v_0 - q_{g1} W_1 , \quad (h)$$

$$t_1 = t_0 , \quad (i)$$

$$t'_1 = t'_0 , \quad (j)$$

$$\delta_1 = q_{f1} M_1 h_G , \quad (k)$$

$$\delta'_1 = q'_{f1} M'_1 h_G . \quad (l)$$

The elastic deformation coefficients q_{b1} , q_{g1} , q_{b2} , and q_{g2} in Eqs. (70a- ℓ) are further defined as

$$q_{b1} = \frac{\lambda_0}{A_b E_{b1}}, \quad (71a)$$

$$q_{g1} = \frac{v_0}{A_g E_{g1}}, \quad (71b)$$

$$q_{b2} = \frac{\lambda_0}{A_b E_{b2}}, \quad (71c)$$

$$q_{g2} = \frac{v_0}{A_g E_{g2}}. \quad (71d)$$

In Eqs. (70a- ℓ), the term q_{f1} is a rotation of the flange due to a unit moment load, q_p is a rotation of the flange due to a unit internal pressure, and q_t is a rotation of the flange due to a unit temperature gradient between the hub and the ring. The quantities q_{f1} , q_p , and q_t are obtained from the functional expression

$$q(L) = \frac{-w_c(L) + w_g(L)}{h_G}, \quad (72)$$

where $h_G = (C - G)/2$, C is the bolt-circle diameter, and G is the gasket-centerline diameter. Values for the displacements $w_c(L)$ and $w_g(L)$ are obtained from Eqs. (46) and (47) with the appropriate unit values for the loads Δ , P , and M .

For q_{f1} the modulus of elasticity used is that for the initial condition. For q_p and q_t , the moduli used are those for the final condition. The term q_{f2} is obtained from q_{f1} and the ratio of the initial and final elastic moduli; thus:

$$q_{f2} = q_{f1} \frac{E_1}{E_2}.$$

The moments and loads are defined by Eqs. (73a-n). The nomenclature used in these equations is analogous to that used in the ASME Code.¹ The symbol H represents a load, h represents a lever arm, and M represents a moment. The term H_D is the hydrostatic end force (in pounds) on the area inside the flange, H_G is the gasket load in pounds, H_T is the difference between the total hydrostatic end force and the hydrostatic end force on the area inside the flange, h_D is the radial distance in inches from the bolt circle to the circle on which H_D acts (as prescribed in Table UA-50 of the Code), h_G is the radial distance in inches from the gasket-load reaction to the bolt circle, and h_T is the radial distance in inches from the bolt circle to the circle on which H_T acts (as prescribed in Table UA-50). Symbols, C , B , G , g_0 , and p are defined earlier in this chapter. Again, a subscript 1 refers to the initial deformed state, a subscript 2 refers to the final deformed state, and primed quantities refer to the mating flange.

$$h_D = (C - B - g_0)/2 , \quad (a)$$

$$h'_D = (C' - B' - g'_0)/2 , \quad (b)$$

$$h_T = [C - (G + B)/2]/2 , \quad (c)$$

$$h'_T = [C' - (G' + B')/2]/2 , \quad (d)$$

$$h_G = (C - G)/2 , \quad (e)$$

$$H_{D2} = \frac{\pi}{4} B^2 p , \quad (f)$$

$$H'_{D2} = \frac{\pi}{4} (B')^2 p , \quad (g) \quad (73)$$

$$H_{T2} = \frac{\pi}{4} (G^2 - B^2)p , \quad (h)$$

$$H'_{T2} = \frac{\pi}{4} [G^2 - (B')^2]p , \quad (i)$$

$$H_{G2} = W_2 - H_{D2} - H_{T2} , \quad (j)$$

$$H'_{G2} = W_2 - H'_{D2} - H'_{T2} , \quad (k)$$

$$M_1 = W_1 h_G = H_{G1} h_G , \quad (\ell)$$

$$M_2 = H_{D2} h_D + H_{T2} h_T + H_{G2} h_G , \quad (m)$$

and

$$M'_2 = H'_{D2} h'_D + H'_{T2} h'_T + H'_{G2} h'_G . \quad (n)$$

Substituting Eqs. (70a- ℓ) into Eq. (69) gives

$$\begin{aligned} T_b \varepsilon_b \ell_0 + q_{b2} W_2 - q_{b1} W_1 &= T_g \varepsilon_g v_0 - q_{g2} (W_2 - H_{D2} - H_{T2}) \\ &+ q_{g1} W_1 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - h_G (q_{f2} M_2 + q_p p + q_t \Delta - q_{f1} M_1) \\ &- h_G (q'_{f2} M'_2 + q'_p p + q'_t \Delta' - q'_{f1} M'_1) . \quad (74) \end{aligned}$$

In order to eliminate M_1 and M_2 from Eq. (74), Eqs. (73 ℓ and m) are used; the sixth term on the right-hand side of Eq. (74) then becomes

$$-h_G \{ q_{f2} [H_{D2} h_D + H_{T2} h_T + (W_2 - H_{D2} - H_{T2}) h_G] + q_p p + q_t \Delta - q_{f1} W_1 h_G \} .$$

The last term in Eq. (74) is treated similarly. Collecting terms containing W_2 on the left gives:

$$\begin{aligned} (q_{b2} + q_{g2} + h_G^2 q_{f2} + h_G^2 q'_{f2}) W_2 &= (q_{b1} + q_{g1} + h_G^2 q_{f1} + h_G^2 q'_{f1}) W_1 \\ &+ T_g \varepsilon_g v_0 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - T_b \varepsilon_b \ell_0 + q_{g2} (H_{D2} + H_{T2}) \\ &- h_G q_{f2} [H_{D2} (h_D - h_G) + H_{T2} (h_T - h_G)] \\ &- h_G q'_{f2} [H'_{D2} (h'_D - h'_G) + H'_{T2} (h'_T - h'_G)] \\ &- h_G (q_p + q'_p) p - h_G (q_t \Delta + q'_t \Delta') . \quad (75) \end{aligned}$$

Defining

$$Q_1 = q_{b1} + q_{g1} + h_G^2 q_{f1} + h_G^2 q'_{f1}$$

and

$$Q_2 = q_{b2} + q_{g2} + h_G^2 q_{f2} + h_G^2 q'_{f2}$$

and using the given definitions of H_D , H'_D , H_T , and H'_T , Eq. (75) becomes

$$\begin{aligned} W_2 &= \frac{Q_1}{Q_2} W_1 + \frac{1}{Q_2} (T_g \varepsilon_g v_0 + T_f \varepsilon_f t_0 + T'_f \varepsilon'_f t'_0 - T_b \varepsilon_b \ell_0) \\ &+ \frac{\pi h_G}{4Q_2} \left\{ \left[\frac{q_{g2}}{h_G} - q_{f2}(h_T - h_G) - q'_{f2}(h_T - h_G) - q'_{f2}(h'_T - h_G) \right] G^2 \right. \\ &\quad \left. - [q_{f2} B^2 (h_D - h_T) + q'_{f2} (B')^2 (h'_D - h'_T)] \right\} p \\ &- \frac{h_G}{Q_2} (q_p + q'_p) p - \frac{h_G}{Q_2} (q_t^\Delta + q_t'^\Delta) . \quad (76) \end{aligned}$$

In order to compute the flange stresses under the various loading conditions, it is necessary to compute the flange moment M_2 or M'_2 . From Eq. (73m) and the definitions in Eqs. (73a-k),

$$M_2 = \frac{\pi}{4} p [B^2 h_D + (G^2 - B^2) h_T - G^2 h_G] + W_2 h_G . \quad (77a)$$

And similarly for the mating flange,

$$M'_2 = \frac{\pi}{4} p \left\{ (B')^2 h'_D + [G^2 - (B')^2] h'_T - G^2 h_G \right\} + W_2 h_G . \quad (77b)$$

The computer program was written to separately evaluate the various effects involved in bolt-load changes. The residual bolt load due to

temperature differences that produce differential axial strain is

$$W_{2a} = W_1 + \frac{1}{Q_1} (T_g \epsilon_g v_0 + T_f \epsilon_f t_0 + T'_f \epsilon'_f t'_0 - T_b \epsilon_b \ell_0) . \quad (78)$$

The residual bolt load, after internal pressure (acting in an axial direction) has transferred the bolt load on the gasket to a tensile load on the attached pipes due to a shift in lever arms, is given by:

$$W_{2b} = W_1 + \frac{\pi}{4} \frac{h_G}{Q_1} \left\{ \left[\frac{q_{g1}}{h_G} - q_{f1}(h_T - h_G) - q'_{f1}(h'_T - h_G) \right] G^2 - [q_{f1} B^2 (h_D - h_T) + q'_{f1} (B')^2 (h'_D - h'_T)] \right\} p . \quad (79)$$

The total effect of internal pressure due to both the shift in the lever arms and the radial effect of pressure acting on the integral flange(s) and/or on the inside surface of a blind flange is given by:

$$W_{2c} = W_{2b} - \frac{h_G}{Q_1} (q_p + q'_p) p . \quad (80)$$

The residual bolt load due to a temperature difference between the hub and the ring is given by:

$$W_{2d} = W_1 - \frac{h_G}{Q_1} (q_t \Delta + q'_t \Delta') . \quad (81)$$

A slight modification of the above is required for the case of a blind flange. If we designate the blind flange as that with the "primed" nomenclature, then all* of Eqs. (70a- ℓ) are valid except Eqs. (70f and ℓ) for δ'_1 and δ'_2 .

* For v_2 it should be noted that $H_{D2} - H_{T2} = \pi G^2 p / 4$; hence, this equation is valid for blind flanges.

For blind flanges, W is used rather than M as the loading parameter because the relationship $M = W(a - b)$ is not valid for the blind-flange analysis. For blind-flange analysis, Eq. (65) gives a value of w_c ; here $-w_c$ is the equivalent of $-w_c + w_g$ in Eq. (72) because $w_g \equiv 0$ in the blind-flange analysis. For blind flanges we define

$$q'_f = \frac{(-w_c)W}{h_G^2}, \quad (82)$$

where $(-w_c)W$ is the axial displacement per unit total bolt load W . The equation for W_2 for a blind flanged joint is then:

$$\begin{aligned} W_2 = & \frac{Q_1}{Q_2} W_1 + \frac{1}{Q_2} (T_g \epsilon_g v_0 + T_f \epsilon_f t_0 + T'_f \epsilon'_f t'_0 - T_b \epsilon_b \ell_0) \\ & + \frac{\pi h_G}{4 Q_2} \left\{ \frac{-q_{g2}}{h_G} - q_{f2} (h_T - h_G) \right\} G^2 - q_{f2} B^2 (h_D - h_T) \} p \\ & - \frac{h_G}{Q_2} (q_p + q'_p) p - \frac{h_G}{Q_2} q_t \Delta. \end{aligned} \quad (83)$$

In Eq. (83) the primed values refer to properties of the blind flange.

After the internal pressure has transferred the bolt load on the gasket to a tensile load on the attached pipe due to a shift in the lever arms, the residual bolt load for the case where a blind flange is used is

$$W_{2b} = W_1 + \frac{\pi h_G}{4 Q_1} \left\{ \frac{-q_{g1}}{h_G} - q_{f1} (h_T - h_G) \right\} G^2 - q_{f1} B^2 (h_D - h_T) \} p. \quad (84)$$

It should be noted that $q_t \Delta$ does not exist for an integral flange mated to a blind flange.

The combined effect of all of the above is also obtained from the computer program by calculating W_2 from Eqs. (76) and (83).

External Moment Loading

Up to this point, all loads considered have been axisymmetric. For flanged joints in pipe lines, there is one other significant loading; that is, the bending moment imposed on the flanged joint by the attached pipe. To distinguish this from the local moments applied to the flange ring, the bending moment will be designated as an "external" moment. The external moment can be represented by a distributed axial edge force acting on the attached pipe:

$$F_M(\theta) = F_m \cos \theta , \quad (85)$$

where θ = angle around the circumference ($\theta = 0$ at the point of maximum tensile stress in the pipe due to the external moment). Since this report deals only with cases in which all contact occurs within the bolt-hole circle, a reasonably good first approximation for the effects of the external moment loading can be obtained by replacing the distributed axial force $F_M(\theta)$ with the axisymmetric tensile force $F_m = F_M(\max)$. Then, since F_m is axisymmetric, there is some pressure p^* that will produce the same axial force in the pipe; or alternately, there is an equivalent pressure p^* that will produce an axial stress in the pipe which is equal to the maximum tensile stress S_b produced by an external moment. The relation between p^* and S_b is given by

$$p^* = 4S_b g_0 / D_o , \quad (86)$$

where S_b is the bending stress in the attached pipe due to the external moment. The change in bolt load W_{2b} is then obtained by replacing p with $p + p^*$ in Eqs. (79) and (84). It should be noted that this equivalent pressure is included only in Eqs. (79) and (84) and not in Eq. (80).

8. COMPUTER PROGRAM

A Fortran computer program named FLANGE has been written to carry out the calculations according to the analyses described in this report. The program calculates appropriate loads, stresses, and displacements for the flanges, bolts, and gaskets when the flanged joint is subjected to internal pressure, moment, and/or thermal gradient loadings; thus, the program is much more general than that needed only to determine compliance with the ASME Boiler and Pressure Vessel Code. The program also has the advantage of internally computing the values of the Code variables F , V , and f that must otherwise be extracted manually from the curves given in Code Figs. UA-51.2, UA-51.3, and UA-51.6. Loose hubbed flanges, which are covered by the Code, however, are not covered by the computer program.

The main function of this chapter is to describe the input and output for the various computational options available to the user. For more detailed information, the reader is urged to carefully study the examples given in Appendix A where a flanged joint, selected from API Standard 605 (Ref. 8), is analyzed. Several sample problems are worked, and the data input and program output are given for the various program options along with a discussion of the results. Flowcharts and listings of the program and its subroutines are given in Appendix B. In the following sections, the input data for option control and the input data and program output for Code compliance calculations and for more general calculations are discussed.

Option Control Data Card

The first card of each data set, herein called the option control card, contains control information for execution of the various program options. It contains information specifying the type of flange being analyzed, the boundary condition placed on the displacement $(u_r)_{x=h}$, the stresses and other variables to be calculated, and the joint configuration and which flange (of the pair) is to be analyzed. These specifications are under control of the four variables ITYPE, IBOND,

ICØDE, and MATE. The admissible values and their significance are as follows.

ITYPE (indicates the type of flange being analyzed)

- 1 for a tapered-hub flange
- 2 for a straight-hub flange
- 3 for a blind hub

IBØND (specifies the displacement u_r at $x = h$)

- 0 for $(u_r)_{x=h} = 0$ to conform with the ASME Code basis
- 1 (see footnote)*
- 2 for $(u_r)_{x=h} \neq 0$ [see Eq. (20-6) of this report]

ICØDE (controls the amount of output data)

- 0 for a wide variety of stresses, moments, and loads for specified moment, pressure, and ΔT
- 1 (see footnote)*
- 2 for a select list for checking Code compliance in accordance with Section VIII, Div. 1 of the ASME Code

MATE (specifies the joint configuration and the flange to be analyzed)

- 1 for only one flange to be analyzed (This is the situation for ASME-Code related calculations.)
- 2 for two identical flanges mated together
- 3 for the first of two flanges that are not identical, neither of which is a blind flange
- 4 for the second of two flanges that are not identical, neither of which is a blind flange
- 5 for a blind flange
- 6 for a flange that is mated with a blind flange.

The data card with the above information is followed by other data cards containing physical-property data, etc., for the particular flange being analyzed. Since the program can be used to analyze any number of flanges

* In the original conception of the program, IBØND and ICØDE were envisioned as controlling additional calculations that were not implemented in the present version. As it is now written, the program does not distinguish between values of 0 or 1 nor between 2 and numbers greater than 2 for either IBØND or ICØDE.

or flanged joints sequentially (as done in the examples of Appendix A), the data card set for each flange must start with an option-control data card.

Different types of flanges and different types of calculations have different input data requirements. These data and their formats are discussed in the following sections.

Input for Code-Compliance Calculations

Since the ASME Code calculation procedures consider only one flange at a time, the input data requirements for the computer program are quite simple and straightforward. Input data are completely prescribed by the three data cards illustrated in Table 9. The nomenclature is the same as that used in the Code.

The first card is the option control card discussed in the previous sections. The first variable ITYPE may be equal to 1, 2, or 3, depending on the type of flange being analyzed. The next variable IBØND will always be 0, in which case the displacement u_r will be equal to zero at $x = h$, as specified by the Code. The third variable ICØDE will always be 2 and will therefore cause the program to compute the stresses in accordance with Code paragraph UA-50 for straight or tapered-hub flanges or paragraph UG-34(c)(2) for blind flanges. The last variable MATE will always be 1 for Code-compliance calculations. This variable essentially controls the bolt-load-change calculations made by the program. Since the ASME Code does not consider bolt-load changes in determining compliance, when MATE = 1 these calculations are not performed.

The second card in the data set enters the physical dimensions of the flange being analyzed, as shown in Table 9. These dimensions are the outside and inside diameters of the flange ring A and B, the ring thickness t , the pipe-wall thickness g_0 , the hub thickness at the hub-to-ring juncture g_1 , the hub length h , the bolt-circle diameter C, and the internal pressure. All dimensions are expressed in inches; the pressure is in pounds per square inch.

Table 9. Input data for ASME bolt and flange stress calculation, using symbols defined in ASME Code, Section VIII, Division 1, Appendix II

Option-Control Card (Read-in in FLANGE)

Column number	5	10	15	20
Variable	ITYPE ^a	IBOND	ICODE	MATE
Value	1, 2, or 3	0	2	1

Second Card (Read-in in TAPHUB, STHUB, or BLIND)^{b,c}

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70	71-80
Quantity	Flange outer diameter A	Flange inner diameter B	Ring thickness t	Pipe-wall thickness g_0	Hub thickness g_1	Hub length h	Bolt-circle diameter c	Pressure p
Variable	XA	XB	TH	G0	G1	HL	C	PRESS

Third Card (Read-in in ASMEIN)^d

Column number	0-10	11-20	21-30	31-40 ^d	41-50	51-60	61-70 ^e	72 ^d	73-80 ^d
Quantity	Gasket factor m	Minimum design seating stress y	Gasket outer diameter G_o	Gasket inner diameter G_i	Allowable bolt stress at design temperature S_b	Allowable bolt stress at atmospheric temperature S_a	Bolt cross-sectional area A_b	Option I	Basic gasket seat width b_o
Variable	XM	Y	GOUT	GIN	SB	SA	AB	INBO	BO

^aWhen ITYPE = 2 for a ring flange, g_0 , on the second card, should be a suitably small value, but not zero (e.g., 0.01).

^bSubroutines TAPHUB and STHUB call both ASMEIN and FLGDW; BLIND calls ASMEIN.

^cFor ITYPE = 2, g_0 must be entered; g_1 and h are not used. For ITYPE = 3, B, g_0 , g_1 , and h are not used.

^dIf I (Column 72) is 0, the program computes b, b_o , and G for the particular case of $b_o = N/2 = 1/2(G_o - G_i)/2$ as defined in Table UA-49.2 sketches (1a) and (1b) of the Code. Columns 73-80 may then be left blank. For other values of b_o , enter I = 2. In this case, the value of G_i is not used and thus columns 31-40 may be left blank.

^eColumn 71 is blank.

The third card inputs other physical data, including the gasket factor m , the minimum-design seating stress y , the outside diameter of the gasket G_o , the inside diameter of the gasket G_i , the allowable bolt stress at design temperature S_b , the allowable bolt stress at ambient temperature S_a , the total cross-sectional area of the bolts A_b , an option-selecting variable I , and the basic gasket-seating width b_o . The option variable I controls the calculation of b and G .

Output for Code-Compliance Calculations

For Code-compliance calculations, all of the output for each flange being analyzed is printed on a single page (e.g., see examples 1 and 2 of Appendix A). The program prints the input data followed by the effective gasket seating width b_o and the loads, bolt stresses, and moments identified under the headings shown in Table 10. For compliance with Code criteria, the value of $SB1$ must not exceed the allowable bolt stress at design temperature, and the value of $SB2$ must not exceed the allowable bolt stress at atmospheric* temperature.

Immediately below, the program prints the flange stresses needed for comparison with the ASME Code criteria. For tapered-hub and straight-hub flanges (ITYPE = 1 or 2), the program prints five stresses under the two headings "ASME FLANGE STRESSES AT OPERATING MOMENT, MOP" and "ASME FLANGE STRESSES AT GASKET SEATING MOMENT." The stresses are identified as follows:

2/3(SH) = two-thirds of the longitudinal stress on the outside surface at the small end of the hub,

ST = the tangential stress on the hub side of the ring,

SR = the radial stress on the hub side of the ring,

(SH + ST)/2 = the average of SH and ST, and

(SR + ST)/2 = the average of SR and ST.

* Although "ambient" would probably be a better term here, the word "atmospheric" is used as it is used in the Code.

Table 10. Output data identification, ICODE = 2,
(ASME Code stresses)

ASME Code symbol ^a	Program symbol	Description ^a
b_o	BO	See ASME Code, Table UA-49.2. (This will be input data for I = 2.) ^b
H	WM11	$\pi G^2 p/4$
	WM12	$2\pi b G p$
W_{m1}	WM1	$\pi G^2 p/4 + 2\pi b G p$
	SB1	Bolt stress, W_{m1}/A_b
W_{m2}	WM2	$\pi b G y$
	SB2	Bolt stress, W_{m2}/A_b
(c)	MOP	$H_G h_G + H_T h_T + H_D h_D$
(d)	MGS	$[(A_m + A_b) S_a/2] \times [(C - G)/2]$ Except for ITYPE = 3 (Blind flanges)
	MGS1	$W_{m2} \times [(C - G)/2]$

^aAll symbols are defined in the ASME Boiler Code, Section VIII, Div. 1 (1971), Appendix II.

^bSee Footnote d of Table 9.

^cMOP is the operating moment as defined by the ASME Code.

^dMGS is the gasket seating moment as defined by the ASME Code.

For compliance with the Code Criteria, each of the above values printed under the first heading must not exceed the allowable stress for the flange material at the design temperature. The values printed under the second heading must not exceed the allowable stress for the flange material at atmospheric temperature.

For blind flanges (ITYPE = 3), the program prints the following five quantities under the heading "ASME CODE STRESSES FOR BLIND FLANGE":

SP = the stress due to pressure loading only,

SW1 = the stress due to the bolt load W_{m1} only, where $W_{m1} = \pi G^2 p/4 + 2\pi b G p$,

SOP = the stress at operating conditions,

SW₂ = the stress due to the bolt load W_{m2} , where $W_{m2} = \pi b G y$, and
SGS = the stress at gasket-seating conditions.

For Code compliance, SOP must not exceed the allowable stress for the flange material at design temperature, and SGS must not exceed the allowable stress at atmospheric temperature.

Input for General Purpose Calculations

When the computer program is used for general purpose calculations, (i.e., when it is used for calculating displacements and stresses other than those needed specifically for checking Code compliance), the user may select almost any combination of admissible values for the four variables ITYPE, IB_{OND}, IC_{ODE}, and MATE coded in the option control data card. The only specific requirement is that the variable IC_{ODE} must be less than two for other than Code-compliance calculations. In this case the input data are structured somewhat differently than those described in the previous section.

When IC_{ODE} = 0 and MATE = 1, (i.e., only one flange is to be analyzed and the user does not wish to obtain bolt load changes), three data cards are needed as shown in Table 11. These are the option-control card (for which ITYPE may be 1, 2, or 3 and IB_{OND} may be 0 or 2) and two physical-property data cards.

When IC_{ODE} = 0 and MATE = 2, 3, ... 6, the program will analyze a pair of flanges mated together and give bolt load changes. If MATE = 2, the program performs the calculations for a pair of identical flanges mated together. The input data requirements include the data cards shown in Table 11 plus the three cards shown in Table 12. These last three cards contain data on the physical properties of the bolts and gasket, supplemental data on the initial and final state of the flange, and other conditions. For this case, the six cards listed below complete the input data set when MATE = 2.

Table 11. Input data for the general purpose analysis of a single flange
and partial data for paired flanges

Option-Control Card: [FØRMAT (415) read-in in FLANGE]

Column number	5	10	15	20
Variable	ITYPE ^{a,b}	IBØND	ICØDE	MATE ^c
Value	1, 2, or 3	0 to 2	0	1 or (2)

Second Card: [FØRMAT (8E10.5); read-in in TAPHUB, STHUB, or BLIND]

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70	71-80
Quantity	Flange outer diameter A	Flange inner diameter B	Ring thickness t	Pipe-wall thickness g_0	Hub thickness g_1	Hub length h	Bolt-circle diameter C	Pressure p
Variable	XA	XB ^b	TH	G0 ^{a,b}	G1 ^{a,b}	HL ^{a,b}	C	PRESS

Third Card: [FØRMAT (5E10.5); read-in in TAPHUB, STHUB, or BLIND]

Column number	0-10	11-20	21-30	31-40	41-50
Quantity	Moment applied to flange ring M	Coefficient of thermal expansion ϵ_f	Thermal gradient pipe or hub to ring Δ	Modulus of elasticity flange E	Gasket centerline diameter $2g$
Variable	XMOA ^b	EF ^b	DELTA ^b	YM	G

^aWhen ITYPE = 2, G0 must be entered; G1 and HL are not used.

^bWhen ITYPE = 3, XB, G0, G1, HL, EF, and DELTA are not used; the value for XMOA is the total bolt load W.

^cWhen MATE = 2, additional data as described in Table 12 are also required.

Table 12. Last three input data cards for the general purpose analysis of paired flanges

Card No. 4 or 7:^a [FORMAT (7E10.5); read-in in FLGDW]

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70
Quantity	Nominal bolt diameter	Initial state; bolt modulus of elasticity E_b	Bolt coefficient of thermal expansion ϵ_b	Final state; bolt temperature T_b	Outside diameter of gasket	Inside diameter of gasket	Cross-sectional root area of all bolts
Variable	BSIZE ^b	YB	EB	TB	XG0 ^c	XGI ^c	AB

Card No. 5 or 8:^a [FORMAT (6E10.5); read-in in FLGDW]

Column number	0-10	11-20	21-30	31-40	41-50	51-60
Quantity	Gasket thickness v_o	Initial state; gasket modulus of elasticity E_g	Gasket coefficient of thermal expansion ϵ_g	Final state; gasket temperature T_g	A free bolt length variable	Equivalent pressure see Eq. (86) of text p^*
Variable	VO	YG	EG	TG ^d	FACE ^b	PBE

Card No. 6 or 9:^a [FORMAT (7E10.5); read-in in FLGDW]

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70
Quantity	Initial bolt load w_1	Final state temperature of flange, side one T_{f2}	Final state temperature of flange, side two T'_{f2}	Final state flange modulus of elasticity, side one E_{f2}	Final state flange modulus of elasticity, side two E'_{f2}	Final state bolt modulus of elasticity E_{b2}	Final state gasket modulus of elasticity E_{g2}
Variable	W1	TF ^d	TFP ^d	YF2	YFP2	YB2	YG2

^aFirst card number applies when MATE = 2; second number applies when MATE = 3 and 4 or 5 and 6.

^bThe effective bolt load is calculated as $\lambda_0 = XLB = TH + THP + VO + BSIZE + FACE$.

^cValues for G_1 and A_g are calculated using input variables XG0 and XGI.

^dInitial-state temperatures are defined as zero.

<u>Card No.</u>	<u>Identification</u>
1	Option control card with MATE = 2
2}	Data cards per Table 11
3}	
4}	Data cards per Table 12
5}	
6}	

When IC \emptyset DE = 0 and MATE = 3, the program performs the calculations for a pair of nonidentical flanges, neither of which, however, is blind (i.e., ITYPE = 1 or 2 \neq 3 on the option-control card). Data for the first flange of the pair follows the option-control card. Data for the second flange in the pair will follow an option-control card with MATE = 4. The three cards described in Table 12 will then complete the data requirements. The complete input data set for analyzing a pair of nonidentical flanges (neither of which is blind) consists of the following nine cards.

<u>Card No.</u>	<u>Identification</u>
1	Option-control card, ITYPE \neq 3, IC \emptyset DE = 0, MATE = 3
2}	Data cards per Table 11 for first flange of pair
3}	
4	Option-control card, ITYPE \neq 3, IC \emptyset DE = 0, MATE = 4
5}	Data cards per Table 11 for second flange of pair
6}	
7}	
8}	Data cards per Table 12
9}	

When IC \emptyset DE = 0 and MATE = 5, the program performs the calculations for a flanged joint that is closed with a blind flange. For this option,

the blind flange is designated as the first flange and the mating flange is designated as the second with MATE = 6. As before, the input data set is completed by using the data cards described in Table 12. The complete input data set for this case consists of the following nine cards.

<u>Card No.</u>	<u>Identification</u>
1	Option-control card, ITYPE = 3, ICØDE = 0, MATE = 5
2 }	Data cards per Table 11 for blind flange
3 }	
4	Option-control card, ITYPE = 1 or 2, ICØDE = 0, MATE = 6
5 }	Data cards per Table 11 for second flange
6 }	
7 }	
8 }	Data cards per Table 12
9 }	

Output from General Purpose Calculations

The amount and format of the data printed out are determined predominantly by the number and types of flanges being analyzed, which in turn are determined by the value of the option-control variable MATE. When MATE = 1, the output consists of one page of printout, which gives (1) the input data; (2) the three sets of stresses for moment loading only (the bolt load for blind flanges), pressure loading only, and temperature-gradient (hub to ring) loading only (except for blind flanges); and (3) the displacements produced by the calculated stresses. The symbols used on the printout are explained in Tables 13 and 14.

When MATE = 2, the output consists of three pages of printout. The first page gives (1) the input data and (2) the parameters involved in the bolt-load-change calculations. The second page gives (1) the loadings, (2) the residual bolt loads, and (3) the initial and residual moments. The symbols used in the first and second page of printout are explained in Tables 15 and 16. The third page gives the stresses and

Table 13. Output data identification, stresses, displacements, and rotation

Theory Symbol	Program symbol	Description
$(\sigma_\ell)_o$	SLSO ^a	Stress, longitudinal, small end of hub, outside surface
$(\sigma_\ell)_i$	SLSI ^a	Stress longitudinal, small end of hub, inside surface
$(\sigma_c)_o$	SCSO ^a	Stress, circumferential, small end of hub, outside surface
$(\sigma_c)_i$	SCSI ^a	Stress, circumferential, small end of hub, inside surface
$(\sigma_\ell)_o$	SLLO	Stress, longitudinal, large end of hub, outside surface
$(\sigma_\ell)_i$	SLLI	Stress, longitudinal, large end of hub, inside surface
$(\sigma_c)_o$	SCLO	Stress, circumferential, large end of hub, outside surface
$(\sigma_c)_i$	SCLI	Stress, circumferential, large end of hub, inside surface
$(\sigma_t)_o$	STH	Stress, tangential, hub side of ring, at $r = b$
$(\sigma_t)_i$	STF	Stress, tangential, face side of ring, at $r = b$
$(\sigma_r)_o$	SRH	Stress, radial, hub side of ring, at $r = b$
$(\sigma_r)_i$	SRF	Stress, radial, face side of ring, at $r = b$
δ_g	ZG	Axial displacement at $r = g$
δ_c	ZC	Axial displacement at $r = c$
$q_f^h G$	QFHG	$-\delta_c + \delta_g$
y_0	YO	Radial displacement, small end of hub
y_1	Y1	Radial displacement, large end of hub
	THETA	Rotation of ring at $r = b$
		<u>For blind flanges^b</u>
$\sigma_r, \sigma_t, r = o$	SORT	Stress, $r = o$, radial and tangential
$\sigma_r, r = g$	SGR	Stress, $r = g$ radial
$\sigma_t, r = g$	SGT	Stress, $r = g$, tangential
$\sigma_r, r = c$	SCR	Stress, $r = c$, radial
$\sigma_t, r = c$	SCT	Stress, $r = c$, tangential
$\sigma_t, r = a$	SAT	Stress, $r = a$, tangential
δ_c	ZC	Axial displacement at $r = c$ ($\delta \equiv 0$ at $r = g$)

^aFor "Straight Hub Flange," these are at juncture of hub with ring.

^bAll stresses are for the side of the flange opposite the pressure-bearing side. Stresses on the pressurized side of the flange have reversed signs.

Table 14. Output data identification when MATE = 2, 3 and 4, or 5 and 6

Theory symbol	Program symbol	Description
$q_{f1} h_G$	QFHG	Axial displacement from C to G, unit moment load
$q_{p1} h_G$	QPHG	Axial displacement from C to G, unit pressure load
$q_{t1} h_G$	QTHG ^a	Axial displacement from C to G, unit DELTA
2b	XB ^{a,b}	Inside diameter
g_0	GO ^{a,b}	Pipe wall thickness
t	TH	Ring thickness
E_{f1}	YM ^b	Modulus of elasticity of flange material, initial state
E_{f2}	YF2 ^c	Modulus of elasticity of flange material, final state
ϵ_f	EF ^b	Coefficient of thermal expansion of flange material
()'	()P	The above nine symbols with a prime mark (') on the theory symbols are for the mating flange. The program symbol has the added final letter "P."

^aFor blind flanges, these values are not significant; an artificial value of -1.0000 is printed out.

^bThese values are input data for flange side one, input cards 2 and 3 (see Table 11). For MATE = 2, these values, along with calculated values of QFHG, QPHG, and QTHG, are used for side one and side two (i.e., an identical pair). If MATE = 3 or 5, the primed values are stored; the unprimed values are read in by input cards 5 and 6, and values of QFHGP, QPHGP, and QTHGP are calculated.

^cInput from card 6 for MATE = 2, card 9 for MATE = 3 and 4 or 5 and 6 (see Table 11).

Table 15. Output data identification, MATE = 2, 3 and 4,
or 5 and 6, bolts, gasket, and loadings data

Theory symbol	Program symbol	Description ^a
l	XLB	Effective bolt length
A_b	AB	Cross-sectional root area of all bolts
C	C	Bolt-circle diameter
E_{b1}	YB	Modulus of elasticity, bolts, initial state
E_{b2}	YB2	Modulus of elasticity, bolts, final state
ϵ_b	EB	Coefficient of thermal expansion, bolts
v_0	VO	Gasket thickness
	XGO	Outside diameter of gasket
	XGI	Inside diameter of gasket
E_{g1}	YG	Modulus of elasticity of gasket, initial state
E_{g2}	YG2	Modulus of elasticity of gasket, final state
ϵ_g	EG	Coefficient of thermal expansion, gaskets
W_1	W1	Initial total bolt load
T_b	TB	Temperature of bolts, final state
T_{f2}	TF	Temperature of flange ring, side one, final state
T'_{f2}	TFP	Temperature of flange ring, side two, final state
T_g	TG	Temperature of gasket, final state
Δ	DELTA	Thermal gradient, pipe/hub to ring, side one
Δ'	DELTAP	Thermal gradient, pipe/hub to ring, side two
P	PRESS	Internal pressure

^aAll values are input data, except XLB which is calculated by the equation: $XLB = TH + THP + VO + BSIZE + FACE$.

Table 16. Output data identification, MATE 2, 3 and 4, or 5 and 6, residual bolt loads and moments

Theory symbol	Program ^a symbol	Effect included
W_{2a}	W2A	Relative change in temperature of bolts, gasket, flange (AXIAL THERMAL)
W_{2b}	W2B	Change in moment arms (MOMENT SHIFT)
W_{2c}	W2C	Total pressure
W_{2d}	W2D	Thermal gradient, pipe/hub to ring (DELTA THERMAL)
W_2	W2	All of the above, plus change in modulus of elasticity (COMBINED)

^aThe change in bolt load (e.g., $W_1 - W_{2A}$) and ratio of residual to initial bolt load (e.g., W_{2A}/W_1) are also printed out, along with the corresponding values of the initial moment (M_1) and residual moments, M_{2A}, \dots, M_{2P} . The residual moment identifiers with final letter P (for prime) are for the first entered of a pair of nonidentical flanges. If the pair of flanges are identical, then $M_{2B} = M_{2BP}$, etc. The residual moment values are not significant for blind flanges, ITYPE = 3; therefore, residual bolt loads are used for blind flanges.

displacements as for the case when MATE = 1 plus the stresses and displacements for combined loading. The heading includes the value of the residual moments $M_2 = M_{2P}$ used for the combined-loading calculations.

When MATE = 3 and 4 or 5 and 6, the output consists of four pages of printout. The first two pages have the same format as for the case when MATE = 2, except input data for both of the (nonidentical) flanges are printed. The residual moments on the last line of page 2 apply to flange one; those on the preceding line apply to flange two. The last two pages of printout are for flange one and flange two, respectively, and are identical in format to the third page of the printout for the case when MATE = 2.

Acknowledgment

The authors gratefully acknowledge the assistance of O. W. Russ of the Computer Sciences Division for converting the CDC 7700 Fortran program written at Battelle-Columbus Laboratories to double precision for operation on the ORNL IBM 360 computers.

References

1. *ASME Boiler and Pressure Vessel Code*, Section VIII-1971, "Nuclear Power Plant Components," American Society of Mechanical Engineers, New York, July 1, 1971.
2. E. O. Waters et al., "Formulas for Stresses in Bolted Flanged Connections," *Trans. ASME* 59, 161-69 (1937).
3. S. Timoshenko, *Theory of Plates and Shells*, 1st ed., McGraw-Hill, New York, 1940.
4. E. C. Rodabaugh, F. M. O'Hara, Jr., and S. E. Moore, *Analysis of Flanged Joints with Ring-Type Gaskets* (in preparation).
5. E. C. Rodabaugh, F. M. O'Hara, Jr., and S. E. Moore, *Stresses in the Bolting and Flanges of B16.5 Flanged Joints with Metal-to-Metal Contact Outside the Bolt Circle* (in preparation).
6. D. B. Wesstrom and S. E. Bergh, "Effect of Internal Pressure on Stresses and Strains in Bolted-Flanged Connections," *Trans ASME* 73, 553-68 (1951).
7. E. C. Rodabaugh, Discussion Section of Ref. 6.
8. *Large-Diameter Carbon Steel Flanges (Size: 26 Inches to 30 Inches, Inclusive, Nominal Pressure Rating: 75, 150, and 300 lb)*, API Standard 605, 1st Ed., American Petroleum Institute, New York, 1967.

APPENDIX A

EXAMPLES OF APPLICATION OF COMPUTER PROGRAM FLANGE

APPENDIX A

CONTENTS

	<u>Page</u>
INTRODUCTION	57
DETAILS OF THE FLANGE USED IN THE EXAMPLES	59
ASME CODE CALCULATIONS, EXAMPLES 1 AND 2	62
BLIND-TO-TAPERED-HUB FLANGED JOINT, EXAMPLES 3(a) and 3(b)	67
Input Data	67
Output Data	70
Residual Bolt Loads	70
Blind Flange Stresses, Example 3(a)	80
Tapered-Hub Flange Stresses, Example 3(a)	81
Blind and Tapered-Hub Stresses, Example 3(b)	83
Displacements	83
IDENTICAL PAIR OF TAPERED-HUB FLANGES, EXAMPLES 4(a) AND 4(b)	84
Input Data	84
Output Data	84
Residual Bolt Loads	84
Flange Stresses	93
Displacements	94
COMPUTER TIME	96

INTRODUCTION

Several examples have been selected to illustrate the input/output data of the computer program FLANGE and the significance of the results. The flange selected for analysis is one included in API Standard 605.* The particular size and rating selected was the 60-in., 300-lb tapered-hub flange. This particular flange represents a design in which the bolt stresses and flange stresses are close to the upper limits set in API-605.

Six examples are included:

1. A Code stress calculation is performed for a tapered-hub flange at its rated pressure of 720 psi at 100°F. The results show that this particular flange does indeed meet the criteria given in API-605 at 720 psi and 100°F.
2. A Code stress calculation is performed for a blind flange to match the 60-in., 300-lb API-605 tapered-hub flange. The thickness of the blind flange was selected so that its maximum stress was the allowable flange stress of 17,500 psi used in API-605.
3. A blind flange bolted to a tapered-hub flange under pressure loading only is analyzed.
 - (a) For an initial bolt stress equal to the API-605 allowable stress for the bolting material of 20,000 psi, the results indicate that the flanged joint will probably leak at its rated pressure of 720 psi at 100°F.
 - (b) For an initial bolt stress of 44,300 psi, the results indicate that the flanged joint will pass a hydrostatic test of 1.5×720 psi at ambient temperature.
4. A tapered-hub flange bolted to an identical tapered-hub flange with an initial bolt stress of 46,100 psi is analyzed.

* *Large-Diameter Carbon Steel Flanges (Size: 26 Inches to 30 Inches, Inclusive, Nominal Pressure Rating: 75, 150, and 300 lb)*, API Standard 605, 1st Ed., American Petroleum Inst., New York, 1967.

- (a) For pressure loading only, the results indicate that the flanged joint will hold a hydrostatic test pressure of 1.5×720 psi.
- (b) For pressure loading of 300 psi (API-605 rated pressure at 850°F) plus an external bending moment that produces an axial stress in the attached pipe of 7500 psi, the results indicate that the flanged joint is adequate to carry these loads.

DETAILS OF THE FLANGE USED IN THE EXAMPLES

A sketch of the tapered-hub flange is shown in Fig. A.1. The dimensions are as specified in API-605. The inside diameter and dimensions B (and therefore g_0 and g_1) are not specified in API-605. For the purpose of checking ratings, the following equation given in API-605 was used to establish B:

$$B = D_o - 2t_p , \quad (A.1)$$

where

D_o = nominal outside diameter of pipe, in.;

t_p = $p_1 D_o / 2(0.875)S$ (but not less than 0.25), in.;

p_1 = rated pressure at 100°F, psi;

0.875 = assumed pipe-wall tolerance; and

S = 20,000 psi, the allowable stress at 100°F.

The definition of t_p , with $D_o = 60$ in. and $p_1 = 720$ psi, leads to $t_p = g_0 = 1.2343$ in. Equation (A.1) gives $B = 57.5314$ in. and $g_1 = (X-B)/2 = 2.7030$ in.

For the purpose of checking ratings, the hub length h was calculated by the equation given in API-605:

$$h = Y - t + 0.176g_0 + 0.469 .$$

Dimensions Y and t are shown in Fig. A.1. For this flange:

$$h = 10.6875 - 5.9375 + 0.176(1.2343) + 0.469 = 5.4362 \text{ in.}$$

The API-605 standard states that flange ratings were based on use of a 1/16-in.-thick, compressed-asbestos, flat ring-shaped gasket, with an inside diameter 1/4 in. larger than the outside diameter of the pipe and with an outside diameter equal to the raised-face diameter. For the 60-in., 300-lb flange, the gasket inside diameter is 60.25 in.; its

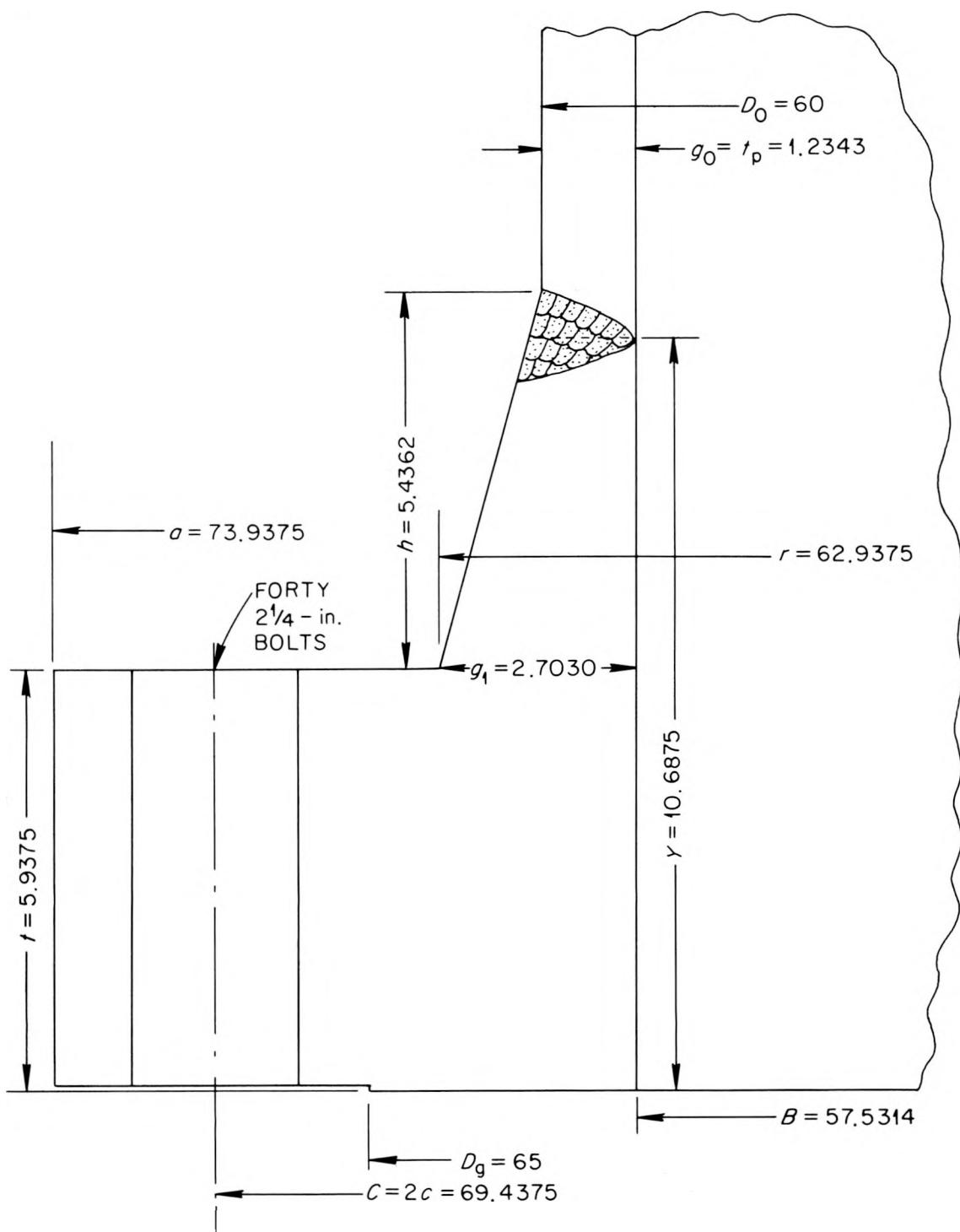


Fig. A.1. Dimensions (in inches) of 60-in., 300-lb API-605 tapered-hub flange. The terms B , R , C , D_o , X , and A are diameters expressed in inches.

outside diameter is 65 in. According to the ASME Code, for a 1/16-in.-thick asbestos gasket, $m = 2.75$, and $y = 3700$ psi.

The 60-in., 300-1b flange has forty 2-1/4-in.-diam. bolts. For an 8-pitch thread, the root area per bolt is 3.423 in.², giving a total bolt root area of 136.92 in.².

ASME CODE CALCULATIONS, EXAMPLES 1 AND 2

The input data for examples 1 and 2 are shown in Table A.1. The source of all input for Cards 2 and 3 are contained in the previous section on flange details, except that the thickness of the blind flange was selected* so that the controlling flange stress is 17,500 psi. Note that Card 2 is identical for examples 1 and 2 except for the value of t ; however, B , g_0 , g_1 , and h are not used for example 2 (blind flange), and any number (including zero) can be entered for these dimensions.

Example 1 is a Code stress calculation for the 60-in., 300-lb API-605 tapered-hub flange at its rated pressure of 720 psi at 100°F. The output data are shown in Table A.2. The value of $SB1 = 20,033$ psi is the controlling bolt stress, which essentially meets the API criterion value of a bolt stress not greater than 20,000 psi. The value of $(SH + ST)/2 = 17,293$ psi under the heading "ASME FLANGE STRESSES AT OPERATING MOMENT, MOP" is the controlling flange stress and meets the API-605 criterion of a controlling flange stress not greater than 17,500 psi. The results, therefore, confirm that the 60-in., 300-lb API-605 tapered-hub flange meets the stated criteria.

The reader who is accustomed to using hand calculations for checking flange designs according to Code rules will note that the program input does not require either the factors T , U , Y , Z from Code Fig. UA-51.1, or F , V , and f from Code Figs. UA-51.2, UA-51.3, and UA-51.6, respectively. These factors are calculated by the computer program. In addition to simplifying the input, the program accurately calculates F , V , and f values for any values of h/h_0 and g_1/g_0 , including those beyond the range of the Code figures.

Example 2 is a Code stress calculation for a blind flange to match the 60-in., 300-lb API-605 tapered-hub flange. The calculation method is that given in UG-34 [Eq. (2)], with $C = 0.3$. The output data are shown in Table A.3. The controlling flange stress is $SOP = 17,500$ psi;

* API-605 does not give blind-flange thicknesses.

Table A.1. Input data for ASME Code stress calculations, examples 1 and 2

First card

Column number	5	10	15	20
Variable	ITYPE	IBOND	ICODE	MATE
Example 1	1	0	2	1
Example 2	3	0	2	1

Second card

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70	71-80
Variable	A	B	t	g_0	g_1	h	C	P
Example 1	73.9375	57.5314	5.9375	1.2343	2.7030	5.4362	69.4375	720.
Example 2	73.9375	57.5314 ^a	7.9044	1.2343 ^a	2.7030 ^a	5.4362 ^a	69.4375	720.

Third card

Column number	0-10	11-20	21-30	31-40	41-50	51-60	61-70 ^b	72	73-80
Variable	m	y	G_o	G_i	S_b	S_a	A_b	I	b_o
Example 1	2.75	3700.	65.	60.25	20000.	20000.	136.92	0	0
Example 2	2.75	3700.	65.	60.25	20000.	20000.	136.92	0	0

^aNot used in calculations for a blind flange.

^bColumn 71 is blank.

Table A.2. Output data for example 1, ASME Code analysis of a tapered-hub flange

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, G0	HUB AT BASE, G1	HUB LENGTH, H	ECLT CIRCLE, C	PRESSURE, P
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	720.000
M	Y	GOUT	GIN	SB	SA	AB	
2.75000	3700.00000	65.00000	60.25000	20000.00000	20000.00000	136.92000	
BO	WM11	WM12	WM1	SB1	WM2	SB2	
1.1875D 00	2.3097D 06	4.3322D 05	2.7430D 06	2.0033D 04	4.0477D 05	2.9563D 03	
MOP	MGS	MGS1					
1.1719D 07	7.5742D 06	1.1186D 06					

ASME FLANGE STRESSES AT OPERATING MOMENT, MOP

$$(2/3) * SH = 1.5608D 04 \quad ST = 1.1174D 04 \quad SR = 8.4442D 03 \quad (SH+ST)/2 = 1.7293D 04 \quad (SH+SR)/2 = 1.5928D 04$$

ASME FLANGE STRESSES AT GASKET SEATING MOMENT, MGS

$$(2/3) * SH = 1.0087D 04 \quad ST = 7.2216D 03 \quad SR = 5.4576D 03 \quad (SH+ST)/2 = 1.1176D 04 \quad (SH+SR)/2 = 1.0294D 04$$

Table A.3. Output data for example 2, ASME Code analysis of a blind flange

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, G0	HUB AT BASE, G1	HUB LENGTH, H	BCLT CIRCLE, C	PRESSURE, P
73.93750	0.0	7.90440	0.0	0.0	0.0	69.43750	720.000
M	Y	GOUT	GIN	SB	SA	AB	
2.75000	3700.00000	65.00000	60.25000	20000.00000	20000.00000	136.92000	5
BO	WM11	WM12	WM1	SB1	WM2	SB2	
1.1875D 00	2.3097D 06	4.3322D 05	2.7430D 06	2.0033D 04	4.0477D 05	2.9563D 03	
ASME CODE STRESSES FOR BLIND FLANGE							
SP	SW1	SOP	SW2	SGS			
1.4121D 04	3.3792D 03	1.7500D 04	4.9865D 02	3.3763D 03			

the flange thickness of 7.9044 in. was selected to obtain this result. This example was included to illustrate that a blind flange may have to be considerably thicker than a mating flange in order for both to meet the Code stress limitations.

BLIND-TO-TAPERED-HUB FLANGED JOINT, EXAMPLES 3(a) AND 3(b)

Input Data

The input data for examples 3(a) and 3(b) are shown in Table A.4. In addition to the basic purpose of illustrating input/output data for the program FLANGE, this pair of examples was selected to show how the program can be used to estimate required initial bolt stresses. In addition, example 3(a) shows how the general purpose option (ICODE \neq 2) gives stresses as obtained from Code calculations plus deformation data and additonal stresses.

Examples 3(a) and (b) do not involve temperature gradients or temperatures other than ambient; hence, the modulus of elasticity is the same for the initial and final states. Values of temperatures for the flanges, bolts, and gaskets in the final state have been entered as zero. The initial-state reference temperature is zero; hence, a zero in the final state denotes a zero thermal gradient. However, the value of DELTA (the hub-to-ring thermal gradient) cannot be entered as zero without causing a divide-check error, so a value of 0.01 was used. A smaller value could be used (e.g., 0.001 or 0.0001), but the output data shows that $\text{DELTA} = 0.01$ is sufficiently small so that its influence is negligible. A coefficient of thermal expansion of 6×10^{-6} has been entered but is not significant in these examples.

The value of FACE, which is intended to permit use of a bolt length other than $\ell_0 = \text{TH} + \text{THP} + \text{VO} + \text{BSIZE}$, was entered as zero. The modulus of elasticity for both the flanges and the bolts was assumed to be 3×10^7 psi. The modulus of elasticity for the 1/16-in.-thick asbestos gasket was assumed to be 3×10^6 psi.

Some comments on the use of a modulus of elasticity of 3×10^6 for a 1/16-in. asbestos gasket may be appropriate. The stress-strain relationship for such a gasket, which is confined between the two rigid flange faces, is highly nonlinear and both time and history dependent. Starting out with a new gasket, the first increment of bolt stress to produce a gasket stress of 1000 psi might decrease the gasket thickness

Table A.4. Input data for blind-to-tapered-hub flanged joint, examples^a 3a and 3b

Card No.	Variables and numerical values							Read format
1	ITYPE	IBOND	ICODE	MATE				
	3	0	0	5				415
2	A	B	t	g ₀	g ₁	h	C	p
	73.9375	57.5314	7.9044	1.2343	2.7030	5.4362	69.4375	720. 8E10.5
								(1080.)
3	XMOA ^b	EF	DELTA ^c	YM	G			
	2.7430D+6	6. D-6	.01	3. D+7	62.625			5E10.5
	(6.0656D+6)							
4	ITYPE	IBOND	ICODE	MATE				
	1	0	0	6				415
5	A	B	t	g ₀	g ₁	h	C	p
	73.9375	57.5314	5.9375	1.2343	2.7030	5.4362	69.4375	720. 8E10.5
								(1080.)
6	XMOA	EF	DELTA ^c	YM	G			
	1.1719D+7	6. D-6	.01	3. D+7	62.625			5E10.5
	(2.0661D+7)							
7	BSIZE	YB	EB	TB	XGO	XGI	AB	
	2.25	3. D+7	6. D-6	0	65.	60.25	136.92	7E10.5
8	VO	YG	EG	TG	FACE	PBE		
	.0625	3. D+6	6. D-6	0	0	0		6E10.5
9	W1	TF	TFB	YF2	YFP2	YB2	YG2	
	2.7430D+6	0	0	3. D+7	3. D+7	3. D+7	3. D+6	7E10.5
	(6.0656D+6)							

^aValues in parentheses are for example 3b.^bInitial bolt load is used here since ITYPE = 3; see footnote ^b to Table 11 in the text.^cSince DELTA cannot be entered as zero, 0.01 was used as a satisfactorily small value.

by 20%, so that the modulus would be $1000/(0.2 \times 0.0625) = 8 \times 10^4$ psi. Crude observations indicate that, at a bolt stress that produces a gasket stress of 40,000 psi, the gasket thickness is about one-half of its original thickness, so that the average modulus up to this stress is $40,000/0.03125 = 1.28 \times 10^6$ psi. These numbers are dependent upon the ratio of width to thickness of the gasket and the time under stress, particularly for low gasket stress. However, for the flanged-joint analysis, we are not interested in the gasket stress-strain characteristics when the bolt load is applied but rather in the gasket stress-strain characteristics when the gasket stress is decreased after the gasket has been under bolt load for several days or many months. No data on the "spring-back" of asbestos gaskets are available, but in most flanged joints using 1/16-in.-thick asbestos gaskets, the assumed modulus of elasticity of the gasket is not very significant provided it is not unrealistically low. This can be shown for example 3 by noting that the change in the bolt load depends upon the sum of the load-displacement characteristics of the bolts, the flanges, and the gasket. The displacements for a unit bolt load are —

$$\text{for bolts: } \frac{\lambda_0}{A_b E_b} = \frac{16.15}{136.92 \times 3 \times 10^7} = 3.93 \times 10^{-9} ,$$

$$\text{for flanges: } 2 \times QFHG = 2(1.197 \times 10^{-9}) = 2.40 \times 10^{-9} ,$$

and

$$\text{for gasket: } \frac{V_0}{A_G E_G} = \frac{0.0625}{467.26 \times E_G} = \frac{1.34 \times 10^{-4}}{E_G} .$$

As E_G varies from 10^5 to 10^7 , the sum of these three displacements varies as follows:

E_G	10^5	3×10^5	10^6	3×10^6	10^7
Sum of displacements ($\times 10^9$ in.)	7.67	6.78	6.46	6.37	6.34

From the above, it can be seen that changing the gasket modulus by two orders of magnitude changes the sum of the displacement by only 17%.

The initial bolt stress used in example 3(a) is 20,033 psi, giving an initial bolt load of $W_1 = S_b A_b = 20,033 \times 136.92 = 2.743 \times 10^6$ lb; W_1 is entered in place of XMOA on card 6 (see footnote *b* to Table 11 of text). The initial moment, XMOA, used in example 3(a) is 1.1719×10^7 in.-lb. The initial bolt stress used in example 3(b) is 44,300 psi, giving an initial bolt load of $W_1 = 6.0656 \times 10^6$ lb. The initial moment, XMOA, used in example 3(b) is 2.0661×10^7 in.-lb. The reasons for using these particular values of W_1 and XMOA are discussed in connection with the output data for these examples.

Output Data

Residual Bolt Loads

The output data for example 3(a) are shown in Table A.5. The output starts with a printout of all input data on the first page (Table A.5a).* The parameters involved in the bolt-load-change calculations are then printed, followed by residual bolt loads and moments, all on the second page (Table A.5b). The initial bolt load under "LOADINGS" is 2.743×10^6 lb; the residual bolt load after application of the pressure of 720 psi is given following "COMBINED" as $W_2 = 1.0948 \times 10^6$ lb. The loss in bolt load is given by $W_1 - W_2 = 1.6482 \times 10^6$ lb, and the ratio of residual to initial bolt load is given by $W_2/W_1 = 0.39911$. Calculated stresses for the blind flange and for the tapered-hub flange are printed on the third and fourth pages (Tables A.5c and A.5d, respectively). These are discussed later.

* For convenience in referring to specific pages of multipage tables, we have used alphabetic suffixes on table numbers. For example, the first page of Table A.5 is designated Table A.5a; the second page is Table A.5b, the third is Table A.5c, etc.

Table A.5a. Output data for example 3(a), blind flange bolted to a tapered-hub flange, with initial bolt stress = 20,033 psi*

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, GO	HUB AT BASE, G1	HUB LENGTH, H	BCLT CIRCLE, C	PRESSURE, P
73.93750	57.53140	7.90440	1.23430	2.70300	5.43620	69.43750	720.000
BOLT LOAD 2.743D 06	COEFF. OF THERMAL EXP. 6.000D-06	DELTA ELASTICITY 1.000D-02	MOD. OF MEAN DIAMETER 3.000D 07	GASKET 6.263D 01	ITYPE 3	IECND 0	ICODE 0
FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, GO	HUB AT BASE, G1	HUB LENGTH, H	BCLT CIRCLE, C	PRESSURE, P
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	720.000
MOMENT THERMAL EXP. 1.172D 07	COEFF. OF DELTA 6.000D-06	MOD. OF MEAN ELASTICITY 1.000D-02	GASKET 3.000D 07	ITYPE 1	IECND 0	ICODE 0	MATE 6
BSIZE 2.2500D 00	YB 3.0000D 07	EB 6.0000D-06	TB 0.0	XGO 6.5000D 01	XGI 6.0250D 01	AB 1.3692D 02	
VO 6.2500D-02	YG 3.0000D 06	EG 6.0000D-06	TG 0.0	FACE 0.0	PBE 0.0		
W1 2.7430D 06	TF 0.0	TFP 0.0	YF2 3.0000D 07	YFP2 3.0000D 07	YB2 3.0000D 07	YG2 3.0000D 06	
FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, BLIND TO INTEGER PAIR							
FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)							
QFHG= 9.4994D-10	QPHG= 6.5350D-06	QTHG= -1.0000D 00	XB = -1.0000D 00	GO= -1.0000D 00	TH = 7.9044D 00		
YM = 3.0000D 07	YF2 = 3.0000D 07	EF = 6.0000D-06					
FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)							
QFHG= 1.1968D-09	QPHG= 8.0422D-06	QTHG= 9.5590D-05	XB = 5.7531D 01	GO= 1.2343D 00	TH = 5.9375D 00		
YM = 3.0000D 07	YF2 = 3.0000D 07	EF = 6.0000D-06					
BOLTING							
BOLT LENGTH= 1.6154D 01	BCLT AREA= 1.3692D 02	BCLT CIRCLE= 6.9438D 01					
YB = 3.0000D 07	YB2 = 3.0000D 07	EB = 6.0000D-06					
GASKET							
VO = 6.2500D-02	XGO = 6.5000D 01	XGI = 6.0250D 01					
YG = 3.0000D 06	YG2 = 3.0000D 06	EG = 6.0000D-06					

*For the convenience of the user, the first page of Table A.5 is designated Table A.5a, the second page is Table A.5b, the third is Table A.5c, etc. This convention is also used in the following tables.

Table A.5b (continued)

LOADINGS

INITIAL BOLT LOAD= 2.7430D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAE= 1.0000D-02 PRESSURE= 7.2000D 02

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 2.7430D 06 MOMENT SHIFT,W2B= 2.2294D 06

TOTAL PRESSURE,W2C= 1.0949D 06 DELTA THERMAL,W2D= 2.7429D 06

COMBINED,W2= 1.0948D 06

W1-W2A= 0.0 W1-W2B= 5.1359D 05 W1-W2C= 1.6481D 06 W1-W2D= 1.0333D 02 W1-W2= 1.6482D 06

W2A/W1= 1.0000D 00 W2B/W1= 8.1276D-01 W2C/W1= 3.9915D-01 W2D/W1= 9.9996D-01 W2/W1= 3.9911D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 9.3433D 06 M2A= 9.3433D 06 M2B= 1.1646D 07 M2C= 7.7818D 06 M2D= 9.3430D 06 M2= 7.7814D 06

M2BP= 4.2880D 07 M2CP= 3.9015D 07 M2P= 3.9015D 07

Table A.5c (continued)

BLIND FLANGE

CALCULATIONS FOR BOLT LOADING

SORT= 4.0213D 03 SGR= 4.0213D 03 SGT= 4.0213D 03 SCR= -1.6157D 02 SCT= 2.5764D 03 SAT= 2.4148D 03
ZC= -2.6057D-03

CALCULATIONS FOR PRESSURE LOADING

SORT= 1.3144D 04 SGR= -8.3815D 02 SGT= 5.0937D 03 SCR= -2.8472D 02 SCT= 4.5403D 03 SAT= 4.2555D 03
ZC= -4.7052D-03

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FCR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.0948D 06

SORT= 1.4749D 04 SGR= 7.6681D 02 SGT= 6.6987D 03 SCR= -3.4921D 02 SCT= 5.5685D 03 SAT= 5.2193D 03
ZC= -5.7452D-03

Table A.5d (continued)

TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

```

SLSO= 2.3042D 04  SLSI= -2.3042D 04  SCSO= 1.9763D 04  SCSI= 5.9379D 03
SLLO= 2.3411D 04  SLLI= -2.3411D 04  SCLO= 7.0234D 03  SCLI= -7.0234D 03
STH= 1.1173D 04  STF= -1.8482D 04  SRH= 8.4441D 03  SRF= -6.6480D 03
ZG= -1.0421D-02  ZC= -2.4446D-02  QFHG= 1.4026D-02  Y0= 1.2322D-02  Y1= 1.0058D-18  THETA= -4.0579D-03

```

CALCULATIONS FOR PRESSURE LOADING

```

SLSO= 1.4194D 04  SLSI= 2.5863D 03  SCSO= 1.4398D 04  SCSI= 1.0915D 04
SLLO= 1.8645D 03  SLLI= 5.7979D 03  SCLO= 5.5935D 02  SCLI= 1.7394D 03
STH= 9.3311D 03  STF= -1.1002D 03  SRH= -2.2932D 03  SRF= 2.7038D 02
ZG= -4.5114D-03  ZC= -1.0302D-02  QFHG= 5.7904D-03  Y0= 9.7224D-03  Y1= 6.0715D-18  THETA= -1.8088D-03

```

CALCULATIONS FOR TEMPERATURE LOADING

```

SLSO= 1.2228D 00  SLSI= -1.2228D 00  SCSO= 1.0649D-01  SCSI= -6.2722D-01
SLLO= -1.3977D-01  SLLI= 1.3977D-01  SCLO= -1.8419D 00  SCLI= -1.7581D 00
STH= 1.1087D 00  STF= -6.1330D-01  SRH= -2.7247D-01  SRF= 1.5072D-01
ZG= -7.4476D-07  ZC= -1.7007D-06  QFHG= 9.5590D-07  Y0= -2.4965D-07  Y1= -1.7259D-06  THETA= -2.9860D-07

```

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 7.7814D 06

```

SLSO= 3.3385D 04  SLSI= -1.6605D 04  SCSO= 3.0857D 04  SCSI= 1.5860D 04
SLLO= 2.1362D 04  SLLI= -1.3700D 04  SCLO= 6.4068D 03  SCLI= -4.1117D 03
STH= 1.8638D 04  STF= -1.6493D 04  SRH= 4.7391D 03  SRF= -5.2661D 03
ZG= -1.3191D-02  ZC= -3.0663D-02  QFHG= 1.7472D-02  Y0= 1.9984D-02  Y1= -1.7259D-06  THETA= -5.1886D-03

```

To avoid leakage,* the residual bolt load must not be less than the critical value W_c , which may be obtained from simple equilibrium considerations; thus,

$$W_c = \frac{\pi}{4} G_0^2 p, \quad (A.2)$$

where

W_c = "critical" bolt load,

G_0 = outside diameter of gasket (65 in. in this example), and

p = pressure (720 psi in this example).

In this example, the value of W_c is

$$W_c = \frac{\pi}{4} \times 65^2 \times 720 = 2.389 \times 10^6 \text{ lb.}$$

Because W_c is significantly greater than $W_2 = 1.0948 \times 10^6$ lb, the results for example 3(a) indicate that the joint will leak at the rated pressure with the initial bolt stress of 20,033 psi. The results illustrate an aspect of ASME-designed flanges that is well known to many users; that is, the joints often cannot be made leaktight (especially in order to pass the hydrostatic test) by applying an initial bolt stress equal to the Code-allowable bolt stress.

The output data for example 3(b) are shown in Table A.6. Example 3(b) is the same as 3(a), except that the initial bolt stress has been increased from 20,033 psi to 44,300 psi (W_1 input under XMOA increased to 2.0661×10^7); the initial moment has been correspondingly increased; and the pressure has been increased from 720 psi to 1080 psi, the latter being the hydrostatic-test pressure of 1.5 times the cold rating pressure. It can be seen in Table A.6 (on the second page, Table A.6b) that the

* Leakage is defined as the gross type of leakage that occurs when the load on the gasket is reduced to zero. Slow, diffusion-type leakage may occur at lower pressures.

Table A.6a. Output data for example 3(b), blind flange bolted to a tapered-hub flange, with initial bolt stress = 44,300 psi

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, G0	HUB AT BASE, G1	HUB LENGTH, H	BOLT CIRCLE, C	PRESSURE, P
73.93750	57.53140	7.90440	1.23430	2.70300	5.43620	69.43750	1080.000
BOLT COEFF. OF DELTA MOD. OF MEAN GASKET ITYPE IBOND ICODE MATE							
LOAD THERMAL EXP. ELASTICITY DIAMETER							
6.066D 06	6.000D-06	1.000D-02	3.000D 07	6.263D 01	3	0	0 5
FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, G0	HUB AT BASE, G1	HUB LENGTH, H	BOLT CIRCLE, C	PRESSURE, P
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	1080.000
MOMENT COEFF. OF DELTA MOD. OF MEAN GASKET ITYPE IBOND ICODE MATE							
THERMAL EXP. ELASTICITY DIAMETER							
2.066D 07	6.000D-06	1.000D-02	3.000D 07	6.263D 01	1	0	0 6
BSIZE VO	YB YG	EB EG	TB TG	XGO FACE	XGI PBE	AB	
2.2500D 00 6.2500D-02	3.0000D 07 3.0000D 06	6.0000D-06 6.0000D-06	0.0 0.0	6.5000D 01 0.0	6.0250D 01 0.0	1.3692D 02	
W1 6.0656D 06	TF	YF2	YFP2	YB2	YG2		
	0.0	0.0	3.0000D 07	3.0000D 07	3.0000D 07	3.0000D 06	

FLANGE JCINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, BLIND TO INTEGER PAIR

FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)

QFHG= 9.4994D-10 QPHG= 6.5350D-06 QTHG= -1.0000D 00 XB = -1.0000D 00 GO= -1.0000D 00 TH = 7.9044D 00
YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)

QFHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00
YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

BOLTING

BOLT LENGTH= 1.6154D 01 BOLT AREA= 1.3692D 02 BOLT CIRCLE= 6.9438D 01
YB = 3.0000D 07 YB2 = 3.0000D 07 EB = 6.0000D-06

GASKET

VO = 6.2500D-02 XGO = 6.5000D 01 XGI = 6.0250D 01
YG = 3.0000D 06 YG2 = 3.0000D 06 EG = 6.0000D-06

Table A.6b (continued)

LOADINGS

INITIAL BOLT LOAD= 6.0656D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAP= 1.0000D-02 PRESSURE= 1.0800D 03

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 6.0656D 06 MOMENT SHIFT,W2E= 5.2952D 06

TOTAL PRESSURE,W2C= 3.5934D 06 DELTA THERMAL,W2D= 6.0655D 06

COMBINED,W2= 3.5933D 06

W1-W2A= 0.0 W1-W2B= 7.7038D 05 W1-W2C= 2.4722D 06 W1-W2D= 1.0333D 02 W1-W2= 2.4723D 06

W2A/W1= 1.0000D 00 W2B/W1= 8.7299D-01 W2C/W1= 5.9242D-01 W2D/W1= 9.9998D-01 W2/W1= 5.9240D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 2.0661D 07 M2A= 2.0661D 07 M2B= 2.4115D 07 M2C= 1.8319D 07 M2D= 2.0661D 07 M2= 1.8318D 07

M2BP= 7.0966D 07 M2CP= 6.5169D 07 M2P= 6.5168D 07

Table A.6c (continued)

BLIND FLANGE

CALCULATIONS FOR BOLT LOADING

SORT= 8.8924D 03 SGR= 8.8924D 03 SGT= 8.8924D 03 SCR= -3.5727D 02 SCT= 5.6971D 03 SAT= 5.3399D 03
ZC= -5.7620D-03

CALCULATIONS FOR PRESSURE LOADING

SORT= 1.9716D 04 SGR= -1.2572D 03 SGT= 7.6405D 03 SCR= -4.2709D 02 SCT= 6.8104D 03 SAT= 6.3833D 03
ZC= -7.0578D-03

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 3.5933D 06

SORT= 2.4984D 04 SGR= 4.0107D 03 SGT= 1.2908D 04 SCR= -6.3873D 02 SCT= 1.0185D 04 SAT= 9.5467D 03
ZC= -1.0471D-02

Table A.6d (continued)

TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

```

SLS0= 4.0624D 04  SLSI= -4.0624D 04  SCS0= 3.4843D 04  SCSI= 1.0469D 04
SLLO= 4.1275D 04  SLLI= -4.1275D 04  SCLO= 1.2382D 04  SCLI= -1.2382D 04
STH= 1.9699D 04  STF= -3.2584D 04  SRH= 1.4887D 04  SRF= -1.1721D 04
ZG= -1.8372D-02  ZC= -4.3100D-02  QFHG= 2.4728D-02  Y0= 2.1724D-02  Y1= 2.1553D-19  THETA= -7.1542D-03

```

CALCULATIONS FOR PRESSURE LOADING

```

SLS0= 2.1290D 04  SLSI= 3.8794D 03  SCS0= 2.1596D 04  SCSI= 1.6373D 04
SLLO= 2.7967D 03  SLLI= 8.6968D 03  SCLO= 8.3902D 02  SCLI= 2.6090D 03
STH= 1.3997D 04  STF= -1.6503D 03  SRH= -3.4397D 03  SRF= 4.0556D 02
ZG= -6.7671D-03  ZC= -1.5453D-02  QFHG= 8.6856D-03  Y0= 1.4584D-02  Y1= 6.0715D-18  THETA= -2.7132D-03

```

CALCULATIONS FOR TEMPERATURE LOADING

```

SLS0= 1.2228D 00  SLSI= -1.2228D 00  SCS0= 1.0649D-01  SCSI= -6.2722D-01
SLLO= -1.3977D-01  SLLI= 1.3977D-01  SCLO= -1.8419D 00  SCLI= -1.7581D 00
STH= 1.1087D 00  STF= -6.1330D-01  SRH= -2.7247D-01  SRF= 1.5072D-01
ZG= -7.4476D-07  ZC= -1.7007D-06  QFHG= 9.5590D-07  Y0= -2.4965D-07  Y1= -1.7259D-06  THETA= -2.9860D-07

```

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.8318D 07

```

SLS0= 5.7309D 04  SLSI= -3.2139D 04  SCS0= 5.2489D 04  SCSI= 2.5654D 04
SLLO= 3.9392D 04  SLLI= -2.7898D 04  SCLO= 1.1816D 04  SCLI= -8.3712D 03
STH= 3.1463D 04  STF= -3.0541D 04  SRH= 9.7592D 03  SRF= -9.9860D 03
ZG= -2.3057D-02  ZC= -5.3667D-02  QFHG= 3.0610D-02  Y0= 3.3844D-02  Y1= -1.7259D-06  THETA= -9.0565D-03

```

residual bolt load after application of a pressure of 1080 psi is $W_2 = 3.5933 \times 10^6$ lb. The value of the critical bolt load to prevent gross leakage is

$$W_c = \frac{\pi}{4} \times 65^2 \times 1080 = 3.584 \times 10^6 \text{ lb} .$$

With an initial bolt stress of 44,300 psi, the residual bolt load is now greater than W_c . Accordingly, the results of example 3(b) indicate that an initial bolt stress of 44,300 psi is sufficient for the joint to pass a hydrostatic test to 1080 psi, albeit with no margin of safety. As the reader may have surmised, the initial bolt stress of 44,300 psi was preselected for example 3(b) to achieve this final result. It is pertinent to note that, because of the linear nature of the calculations, it is not necessary to iterate in order to find a value for the initial bolt stress that would make $W_2 = W_c$. Note that $(W_1 - W_2) = 1.648 \times 10^6$ in example 3(a) and that $(W_1 - W_2)$ varies linearly with pressure. To find the required value of W_1 to make $W_2 = W_c$ at an arbitrary pressure p , we need only solve the equation:

$$W_1 = \frac{\pi}{4} G_0^2 p + \frac{p}{720} (1.648 \times 10^6) . \quad (\text{A.3})$$

For $p = 1080$, Eq. (A.3) gives $W_1 = 6.056 \times 10^6$, and the corresponding initial bolt stress is $W_1/A_b = 6.056 \times 10^6 / 136.92 = 44,228$ psi, which was rounded off to 44,300 psi for Example 3(b).

Blind Flange Stresses, Example 3(a)

Example 3(a) was run with an initial bolt stress of 20,033 psi to permit direct comparison of the blind-flange stresses with the stresses calculated in example 2, where the controlling bolt stress was $SB_1 = 20,033$ psi.

Stresses for the blind flange are shown in Table A.5c. The maximum stress due to initial bolt loading only is $SORT = 4021.3$ psi. A comparable stress from the Code calculation (Table A.3), is $SGS = 3376.3$ psi.

This also represents a stress at the center of the blind flange due to bolt loading only. The maximum stress due to pressure loading only of the blind flange (Table A.5c) is SORT = 13,144 psi. A Comparable stress from the Code calculation (Table A.3) is SP = 14,121 psi.

The maximum stress due to combined bolt loading and pressure loading (Table A.5c) is SORT = 14,749 psi. Note that this combined stress is not the sum of the stress due to the initial bolt load and the stress due to pressure. Rather, the program recognizes that the pressure changes the bolt load — in this example, from 2.743×10^6 lb down to 1.0948×10^6 (Table A.5b). Stresses for combined loadings are related to stresses for initial bolt loading only and pressure only by the equation

$$\sigma_c = \sigma_b \cdot \frac{W_2}{W_1} + \sigma_p , \quad (A.4)$$

where σ_c = combined stress, σ_b = stress due to initial bolt load only, W_2 = bolt load at pressure, W_1 = initial bolt load, and σ_p = stress due to pressure only.

The Code equation for combined stresses [i.e., $S = (d/t)^2(0.3p + 1.78W_h G)$ from paragraph UG-34 and Figs. UG-34 (j) and (k)] can be derived by assuming that the blind flange is a flat circular plate of outside diameter equal to the effective gasket diameter d . The metal outside the diameter d is ignored. The plate is simply supported along d and loaded by edge moment $W_h G$ and pressure p . $W_h G$ is either the operating moment or the gasket-seating moment, as obtained in Appendix II of the Code. The method used in this report is theoretically more accurate than that used in the Code, and the relatively good agreement between stresses in Table A.5c and those in Table A.3 is, in part, coincidental. Large differences can exist, particularly when there is a significant amount of flange material outside the gasket diameter d .

Tapered-Hub Flange Stresses, Example 3(a)

Example 3(a) was run with an initial moment of 1.1719×10^7 in.-lb to permit direct comparison with the stresses given for example 1 in

Table A.2 under the heading "ASME FLANGE STRESSES AT OPERATING MOMENT, MOP." In example 1, the value for MOP was determined to be 1.1719×10^7 in.-lb. To be consistent with the Code calculations in this example [3(a)], we chose $IBOND = 0$.

Calculated stresses for the tapered-hub flange are shown in Table A.5d. The Code method covers only moment loading. The stresses in Table A.5d for initial moment loading only are the same as those in Table A.2 for operating moment, MOP:

Stress values from Table A.5d	Stress values from Table A.2
SLLO = 23,411 psi	SH = 23,412 psi
STH = 11,173 psi	ST = 11,174 psi
SRH = 8,444 psi	SR = 8,444 psi

The Code method gives stresses at the small end of the hub if the Code factor f is greater than 1.0; otherwise, it gives stresses for the large end of the hub. The Code method calculates radial and tangential stresses on the hub side of the flange only. Usually these are higher than the corresponding stresses on the face side of the flange, but in this example, $STH = 11,173$ psi is less than $STF = -18,482$ psi in absolute magnitude. The Code method does not give circumferential stresses in the hub.

Stresses for pressure loading only, temperature loading only, and combined loadings are shown as the 2nd, 3rd, and 4th groups of stresses in Table A.5d. The small values under the heading "CALCULATIONS FOR TEMPERATURE LOADINGS" come from using $\Delta = 0.01$, since $\Delta = 0$ is not a permissible input value.

Combined stresses are not the sum of the stresses due to the three individual loads. Rather, the program recognizes that pressure and temperature change the moment from $M_1 = 9.3433 \times 10^6$ in.-lb to $M_2 = 7.7814 \times 10^6$ in.-lb in this example* (Table A.5b). The maximum stress

* It should be noted that M_1 is not the same as the input moment XMOA. The program will accept any value for calculating stresses but, for calculating bolt load changes, it assumes that the moment is equal to $W(C-G)/2$.

under combined loads (in this example, residual moment and pressure) is SLS0 = 33,385 psi. Under initial moment only, the maximum stress is SLLO = 23,411 psi.

Blind and Tapered-Hub Flange Stresses, Example 3(b)

Stresses are shown in Table A.6c and A.6d for blind and tapered-hub flanges, respectively. It can be seen that maximum stresses are quite high for the realistic initial bolt stress of 44,300 psi needed to pass the hydrostatic test pressure of 1080 psi [i.e., SORT = 24,984 psi for the blind flange (Table A.6c) and SLS0 = 57,309 psi for the tapered-hub flange (Table A.6d)]. Comments on the significance of these high calculated stresses are included later in the discussion of examples 4a and 4b.

Displacements

Tables A.5 and A.6 include, along with stresses, the displacements ZC for the blind flange or ZG, ZC, QFHG, Y0, Y1, and THETA for the tapered-hub flange. One potential application for these displacements is discussed later in connection with examples 4(a) and 4(b).

IDENTICAL PAIR OF TAPERED-HUB FLANGES, EXAMPLES 4(a) AND 4(b)

Input Data

The input data for Examples 4(a) and 4(b) are shown in Table A.7. The initial bolt stress of 46,100 psi and corresponding $W_1 = 6.312 \times 10^6$ lb were selected by a preliminary calculation so that W_2 would equal W_c at the hydrostatic-test pressure of 1080 psi. The value of $W_1 = 6.312 \times 10^6$ lb leads to initial moment $XMOA = W_1(C-G)/2 = 2.1500 \times 10^7$ in.-lb. Example 4(a) is for hydrostatic test conditions at atmospheric temperature. Example 4(b) is for steady-state operating conditions at the rated pressure of 300 psi and corresponding API-605 temperature of 850°F.

The modulus of elasticity of the flange, bolt, and gasket materials was assumed to be 2.25×10^7 psi at 800°F, as compared with 3.0×10^7 at atmospheric temperature. It is assumed that at steady-state operating conditions there is an external bending moment such that the axial stress in the attached pipe is 7500 psi. This axial stress gives 617 psi as the input value for PBE for example 4(b), as shown below:

$$PBE = 4 S_b g_0 / D_o = 4 \times 7500 \times 1.2343/60 = 617 \text{ psi} .$$

Output DataResidual Bolt Loads

The output data for example 4(a) are shown in Table A.8. The output data starts with a printout of all input data. The parameters involved in the bolt-load-change calculations are then printed, followed by residual bolt loads and moments (Table A.8b).

The residual bolt load is given by $W_2 = 3.585 \times 10^6$ lb. The critical bolt load, derived from Eq. (A.2), is $W_c = \pi G_0^2 p/4 = 3.584 \times 10^6$ lb. Accordingly, the results of example 4(a) indicate that an initial bolt stress of 46,100 psi is sufficient for the joint to pass a hydrostatic test to 1080 psi, albeit with no margin of safety.

Table A.7. Input data for tapered-hub-to-tapered-hub flanged joint, examples^a 4a and 4b

Card No.	Variables and numerical values								Read format
1	ITYPE	IBOND	ICODE	MATE					
	1	0	0	2					4I5
2	A	B	t	g ₀	g ₁	h	C	P	
	73.9375	57.5314	5.9375	1.2343	2.7030	5.4362	69.4375	1080.	8E10.5
									(300.)
3	XMOA	EF	DELTA ^b	YM	G				
	2.1500D+7	6. D-6	.01	3. D+7	62.625				5E10.5
4	BSIZE	YB	EB	TB	XGO	XGI	AB		8
	2.25	3. D+7	6. D-6	0	65.	60.25	136.92		7E10.5
5	VO	YG	EG	TG	FACE	PBE			
	.0625	3. D+6	6. D-6	0	0	0			6E10.5
									(617.)
6	W1	TF	TFP	YF2	YFP2	YB2	YG2		
	6.3120D+6	0	0	3. D+7	3. D+7	3. D+7	3. D+6		7E10.5
				(2.25D+7)	(2.25D+7)	(2.25D+7)	(2.25D+6)		

^aValues in parentheses are for example 4b.

^bSince DELTA cannot be entered as zero, 0.01 was used as a satisfactorily small value.

Table A.8a. Output data for example 4(a), identical pair of tapered-hub flanges, with initial bolt stress of 46,100 psi

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, GO	HUB AT BASE, GI	HUB LENGTH, H	BOLT CIRCLE, C	PRESSURE, P
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	1080.000
MOMENT COEFF. OF DELTA MOD. OF MEAN GASKET ITYPE IBOND ICODE MATE							
THERMAL EXP. ELASTICITY DIAMETER							
2.150D 07	6.000D-06	1.000D-02	3.000D 07	6.263D 01	1	0	0 2
BSIZE VO	YB YG	EB EG	TB TG	XGO FACE	XGI PBE	AB	
2.2500D 00	3.0000D 07	6.0000D-06	0.0	6.5000D 01	6.0250D 01	1.3692D 02	
6.2500D-02	3.0000D 06	6.0000D-06	0.0	0.0	0.0		
W1	TF	TFP	YF2	YFP2	YB2	YG2	
6.3120D 06	0.0	0.0	3.0000D 07	3.0000D 07	3.0000D 07	3.0000D 06	

FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, IDENTICAL PAIR

98

FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)

QFHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00
YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)

QFHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00
YM = 3.0000D 07 YF2 = 3.0000D 07 EF = 6.0000D-06

BOLTING

BOLT LENGTH= 1.4188D 01 BOLT AREA= 1.3692D 02 BOLT CIRCLE= 6.9438D 01
YB = 3.0000D 07 YB2 = 3.0000D 07 EB = 6.0000D-06

GASKET

VO = 6.2500D-02 XGO = 6.5000D 01 XGI = 6.0250D 01
YG = 3.0000D 06 YG2 = 3.0000D 06 EG = 6.0000D-06

Table A.8b (continued)

LOADINGS

INITIAL BOLT LOAD= 6.3120D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAP= 1.0000D-02 PRESSURE= 1.0800D 03

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 6.3120D 06 MOMENT SHIFT,W2B= 5.0760D 06

TOTAL PRESSURE,W2C= 3.5852D 06 DELTA THERMAL,W2D= 6.3118D 06

COMBINED,W2= 3.5850D 06

W1-W2A= 0.0 W1-W2B= 1.2360D 06 W1-W2C= 2.7268D 06 W1-W2D= 1.6408D 02 W1-W2= 2.7270D 06

W2A/W1= 1.0000D 00 W2B/W1= 8.0418D-01 W2C/W1= 5.6799D-01 W2D/W1= 9.9997D-01 W2/W1= 5.6796D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 2.1500D 07 M2A= 2.1500D 07 M2B= 2.3369D 07 M2C= 1.8291D 07 M2D= 2.1500D 07 M2= 1.8290D 07

M2BP= 2.3369D 07 M2CP= 1.8291D 07 M2P= 1.8290D 07

Table A.8c (continued)

TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

SLS0= 4.2273D 04 SLSI= -4.2273D 04 SCS0= 3.6258D 04 SCSI= 1.0894D 04
SLLO= 4.2951D 04 SLLI= -4.2951D 04 SCLO= 1.2885D 04 SCLI= -1.2885D 04
STH= 2.0499D 04 STF= -3.3907D 04 SRH= 1.5492D 04 SRF= -1.2197D 04
ZG= -1.9118D-02 ZC= -4.4850D-02 QFHG= 2.5732D-02 Y0= 2.2606D-02 Y1= 1.6524D-18 THETA= -7.4448D-03

CALCULATIONS FOR PRESSURE LOADING

SLS0= 2.1290D 04 SLSI= 3.8794D 03 SCS0= 2.1596D 04 SCSI= 1.6373D 04
SLLO= 2.7967D 03 SLLI= 8.6968D 03 SCLO= 8.3902D 02 SCLI= 2.6090D 03
STH= 1.3997D 04 STF= -1.6503D 03 SRH= -3.4397D 03 SRF= 4.0556D 02
ZG= -6.7671D-03 ZC= -1.5453D-02 QFHG= 8.6856D-03 Y0= 1.4584D-02 Y1= 6.0715D-18 THETA= -2.7132D-03

88

CALCULATIONS FOR TEMPERATURE LOADING

SLS0= 1.2228D 00 SLSI= -1.2228D 00 SCS0= 1.0649D-01 SCSI= -6.2722D-01
SLLO= -1.3977D-01 SLLI= 1.3977D-01 SCLO= -1.8419D 00 SCLI= -1.7581D 00
STH= 1.1087D 00 STF= -6.1330D-01 SRH= -2.7247D-01 SRF= 1.5072D-01
ZG= -7.4476D-07 ZC= -1.7007D-06 QFHG= 9.5590D-07 Y0= -2.4965D-07 Y1= -1.7259D-06 THETA= -2.9860D-07

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.8290D 07

SLS0= 5.7253D 04 SLSI= -3.2083D 04 SCS0= 5.2441D 04 SCSI= 2.5640D 04
SLLO= 3.9335D 04 SLLI= -2.7841D 04 SCLO= 1.1799D 04 SCLI= -8.3541D 03
STH= 3.1436D 04 STF= -3.0496D 04 SRH= 9.7386D 03 SRF= -9.9698D 03
ZG= -2.3032D-02 ZC= -5.3608D-02 QFHG= 3.0576D-02 Y0= 3.3814D-02 Y1= -1.7259D-06 THETA= -9.0466D-03

2

The output data for example 4(b) are shown in Table A.9, which is identical in format to Table A.8 for example 4(a). The residual bolt load for example 4(b) is given by $W_2 = 3.2718 \times 10^6$ lb. The pressure is lower in example 4(b) than in 4(a), but there is a modulus-of-elasticity decrease which, by itself, makes $W_2 = W_1 \times 2.25 \times 10^7 / (3 \times 10^7)$ and makes the effect of the equivalent pressure correspond to the external moment PBE. We can check to see if the residual bolt load is sufficient to prevent leakage by an extension of the concept of the initial bolt load W_c , which was discussed in the previous section. We made the conservative assumption that the maximum tensile stress due to the external bending moment (which exists only at one point on the pipe circumference) acts around the complete circumference of the pipe. The value of W_c , the critical bolt load to prevent gross leakage, is then the sum of Eq. (A.2) and the axial load due to the bending moment; thus

$$W_c = \frac{\pi}{4} G_0^2 p + A_p S_b , \quad (A.5)$$

where

$A_p = \pi(B + g_0)$ g_0 = cross-sectional area of attached pipe, and

S_b = axial stress in attached pipe due to an external moment.

For example 4(b), Eq. (A.5) gives:

$$\begin{aligned} W_c &= \left(\frac{\pi}{4} \times 65^2 \times 300 \right) + (\pi \times 58.7657 \times 1.2343 \times 7500) \\ &= 2.7045 \times 10^6 \text{ lb} . \end{aligned}$$

Because $W_2 = 3.2718 \times 10^6$ lb is greater than $W_c = 2.7045 \times 10^6$ lb, the results indicate that the flanged joint with an initial bolt stress of 46,100 psi can carry, at least for a short time at 850°F, an external moment giving both an axial bending stress of 7500 psi in the attached pipe of 1.2343-in. wall thickness and an internal pressure of 300 psi.

At 850°F, the carbon-steel flanges and bolts would be expected to undergo significant relaxation due to creep in the flanges and bolts,

Table A.9a. Output data for example 4(b), identical pair of tapered-hub flanges, steady-state operation at 300 psi and 850°F

FLANGE O.D., A	FLANGE I.D., B	FLANGE THICK., T	PIPE WALL, G0	HUB AT BASE, G1	HUB LENGTH, H	BCLT CIRCLE, C	PRESSURE, P	
73.93750	57.53140	5.93750	1.23430	2.70300	5.43620	69.43750	300.000	
MOMENT	COEFF. OF THERMAL EXP.	DELTA	MOD. OF ELASTICITY	MEAN GASKET DIAMETER	ITYPE	IBOND	ICODE	MATE
2.150D 07	6.000D-06	1.000D-02	3.000D 07	6.263D 01	1	0	0	2
BSIZE 2.2500D 00	YB 3.0000D 07	EB 6.0000D-06	TB 0.0	XGO 6.5000D 01	XGI 6.0250D 01	AB PBE	1.3692D 02	
VO 6.2500D-02	YG 3.0000D 06	EG 6.0000D-06	TG 0.0	FACE	6.1700D 02			
W1 6.3120D 06	TF 0.0	TFP 0.0	YF2 2.2500D 07	YFP2 2.2500D 07	YB2 2.2500D 07	TG2 2.2500D 07	2.2500D 07	

FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADS, IDENTICAL PAIR

FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)

QFHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00
YM = 3.0000D 07 YF2 = 2.2500D 07 EF = 6.0000D-06

FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)

QFHG= 1.1968D-09 QPHG= 8.0422D-06 QTHG= 9.5590D-05 XB = 5.7531D 01 GO= 1.2343D 00 TH = 5.9375D 00
YM = 3.0000D 07 YF2 = 2.2500D 07 EF = 6.0000D-06

BOLTING

BOLT LENGTH= 1.4188D 01 BOLT AREA= 1.3692D 02 BOLT CIRCLE= 6.9438D 01
YB = 3.0000D 07 YB2 = 2.2500D 07 EB = 6.0000D-06

GASKET

VO = 6.2500D-02 XGO = 6.5000D 01 XGI = 6.0250D 01
YG = 3.0000D 06 YG2 = 2.2500D 07 EG = 6.0000D-06

Table A.9b (continued)

LOADINGS

INITIAL BOLT LOAD= 6.3120D 06 BOLT TEMP.= 0.0 FLANGE ONE TEMP.= 0.0 FLANGE TWO TEMP.= 0.0
GASKET TEMP.= 0.0 DELTA= 1.0000D-02 DELTAE= 1.0000D-02 PRESSURE= 3.0000D 02

RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS

AXIAL THERMAL,W2A= 6.3120D 06 MOMENT SHIFT,W2B= 5.2625D 06

TOTAL PRESSURE,W2C= 4.8484D 06 DELTA THERMAL,W2D= 6.3118D 06

COMBINED,W2= 3.2718D 06

W1-W2A= 0.0 W1-W2B= 1.0495D 06 W1-W2C= 1.4636D 06 W1-W2D= 1.6408D 02 W1-W2= 3.0402D 06

W2A/W1= 1.0000D 00 W2B/W1= 8.3374D-01 W2C/W1= 7.6813D-01 W2D/W1= 9.9997D-01 W2/W1= 5.1835D-01

INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE LOADS.

M1= 2.1500D 07 M2A= 2.1500D 07 M2B= 1.9614D 07 M2C= 1.8203D 07 M2D= 2.1500D 07 M2= 1.2833D 07

M2BP= 1.9614D 07 M2CP= 1.8203D 07 M2P= 1.2833D 07

Table A.9c (continued)

TAPERED HUB FLANGE

CALCULATIONS FOR MOMENT LOADING

SLS0= 4.2273D 04 SLSI= -4.2273D 04 SCS0= 3.6258D 04 SCSI= 1.0894D 04
SLLO= 4.2951D 04 SLLI= -4.2951D 04 SCLO= 1.2885D 04 SCLI= -1.2885D 04
STH= 2.0499D 04 STF= -3.3907D 04 SRH= 1.5492D 04 SRF= -1.2197D 04
ZG= -1.9118D-02 ZC= -4.4850D-02 QPHG= 2.5732D-02 Y0= 2.2606D-02 Y1= 1.6524D-18 THETA= -7.4448D-03

CALCULATIONS FOR PRESSURE LOADING

SLS0= 5.9140D 03 SLSI= 1.0776D 03 SCS0= 5.9990D 03 SCSI= 4.5481D 03
SLLO= 7.7687D 02 SLLI= 2.4158D 03 SCLO= 2.3306D 02 SCLI= 7.2473D 02
STH= 3.8880D 03 STF= -4.5841D 02 SRH= -9.5549D 02 SRF= 1.1266D 02
ZG= -1.8798D-03 ZC= -4.2924D-03 QPHG= 2.4127D-03 Y0= 4.0510D-03 Y1= 8.6736D-19 THETA= -7.5365D-04

CALCULATIONS FOR TEMPERATURE LOADING

SLS0= 1.2228D 00 SLSI= -1.2228D 00 SCS0= 1.0649D-01 SCSI= -6.2722D-01
SLLO= -1.3977D-01 SLLI= 1.3977D-01 SCLO= -1.8419D 00 SCLI= -1.7581D 00
STH= 1.1087D 00 STF= -6.1330D-01 SRH= -2.7247D-01 SRF= 1.5072D-01
ZG= -7.4476D-07 ZC= -1.7007D-06 QPHG= 9.5590D-07 Y0= -2.4965D-07 Y1= -1.7259D-06 THETA= -2.9860D-07

CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITYPE=1 OR 2, W2 FOR ITYPE=3, = 1.2833D 07

SLS0= 3.1147D 04 SLSI= -2.4156D 04 SCS0= 2.7641D 04 SCSI= 1.1050D 04
SLLO= 2.6413D 04 SLLI= -2.3221D 04 SCLO= 7.9222D 03 SCLI= -6.9680D 03
STH= 1.6125D 04 STF= -2.0698D 04 SRH= 8.2910D 03 SRF= -7.1671D 03
ZG= -1.3292D-02 ZC= -3.1064D-02 QPHG= 1.7772D-02 Y0= 1.7544D-02 Y1= -1.7259D-06 THETA= -5.1976D-03

particularly with the high bolt stresses and flange stresses involved in example 4(b). For long-term service (many years) at 850°F, one might expect the flanges and/or bolts to creep so that a residual bolt stress of around 20,000 psi would exist, at which time $W_2 = 2000 \times 136.92 = 2.7384 \times 10^6$ lb. Because this is larger than $W_c = 2.7045 \times 10^6$ lb obtained from Eq. (A.5), indications are that the flanged joint could still carry the external moment and pressure, albeit with almost no margin of safety.

It should be noted that, if bolts relax in high-temperature service, then the bolt load does not return to its initial value upon returning to initial conditions. The permanent loss in bolt load would be $W_2 - S_{br}A_b$, where S_{br} = relaxed bolt stress, assumed here to be 20,000 psi. The permanent loss in bolt load, in this example, is $3.2718 \times 10^6 - 20,000 \times 136.92 = 533,400$ lb. The load is theoretically not sufficient to pass a hydrotest of 1080 psi, but it is extremely unlikely such a hydrotest would be required for a system operating at 300 psi and 850°F.

Flange Stresses

Tables A.8c and A.9c show the flange stresses for examples 4(a) and 4(b), respectively. The maximum calculated stress occurs in example 4(a) where $SLS_0 = 57,253$ psi for combined loadings. Note that this is not the sum of the stresses due to initial moment loading only plus pressure loading only (first two groups of stresses), but rather it is the stress due to the moment as changed by pressure, $M_2 = M_2P = 1.829 \times 10^7$ in.-lb, plus the stress due to pressure only.

The question arises as to whether the flanges in the flanged joint are strong enough to pass the hydrostatic test. To pursue this question, it is appropriate to tabulate the tangential and radial stresses at initial and pressurized conditions:

Condition	STH	STF	SRH	SRF
Initial	20,499	-33,907	15,492	-12,197
Pressurized	31,436	-30,496	9,739	-9,970

It should be noted that the stresses are, in large part, bending stresses. Before large plastic deformations occur, these stresses must reach about $1.5S_y$, where S_y is the yield strength of the flange material. Further, high stresses in the hub will not lead to large plastic deformations if there is reserve strength in the flange ring as indicated by relatively low tangential and radial stresses. If the capability for calculating these stresses has been attained, the next logical step is to conduct an extensive study to develop suitable design criteria for stress limits in flanged joints. Until such a study is conducted, however, the following limits are suggested as appropriate for stresses under hydrostatic test conditions:

Stress	Limit
Longitudinal hub stresses	$\leq 1.5S_y$
Radial stress or tangential stress	$\leq S_y$
Averages of radial or tangential stress and longitudinal hub stress	$\leq S_y$

The above criterion makes the average of SLSO and STH under pressurized conditions [i.e., $1/2(5.7253 \times 10^4 + 3.1436 \times 10^4) = 44,344$ psi] the controlling stress and infers that the flanged joint is acceptable, provided the flange-material yield strength is not less than 44,344 psi.

Displacements

In tightening the bolts to 46,100 psi, the question arises as to whether the flanges will rotate so that contact occurs on the outer edge. Table A.8c shows values of THETA, the rotation of the ring at the mean radius of the pipe wall. An estimate* of the displacement of the ring edge with respect to the gasket centerline can be obtained by

* The deformation of the ring is not exactly linear across the ring, but in this example it is sufficiently close to linear.

multiplying THETA by $(A-G)/2$, the radial distance between the ring edge and gasket centerline. In example 4(a), $A = 73,9375$, $G = 62.625$, and $THETA = -9.0466 \times 10^{-3}$ under combined loading; the minus sign means that the rotation is such that clearance is reduced at the outer edge. The displacement of A with respect to C is $9.0466 \times 10^{-3} \times (73.9375 - 62.625)/2 = 0.0512$ in. Because API-605 flanges have 1/16-in. raised faces, the outer edges of the flanges will not contact each other. The clearance will then be $(0.0625 - 0.0512) \times 2 = 0.0056$ in. plus the thickness of the gasket.

COMPUTER TIME

The six examples discussed in this appendix were run on Battelle's CDC 6400 computer and also on ORNL's IBM 360/91. The IBM FORTRAN source deck (converted to double precision for use on the IBM machine) has 1583 cards. The total length of the program is 80K bytes (10,240 actual words), and it needs no auxiliary storage devices except standard read and write units. The program requires 270K bytes for compilation and has a compilation time of 19.4 sec. The total execution time for the six examples was 1.15 sec.

APPENDIX B

FLOWCHARTS AND LISTING OF COMPUTER PROGRAM FLANGE
AND ATTENDANT SUBROUTINES

APPENDIX B

CONTENTS

	<u>Page</u>
1. Flowcharts of Program FLANGE and Attendant Subroutines	101
2. Listing of Program FLANGE and Attendant Subroutines	114

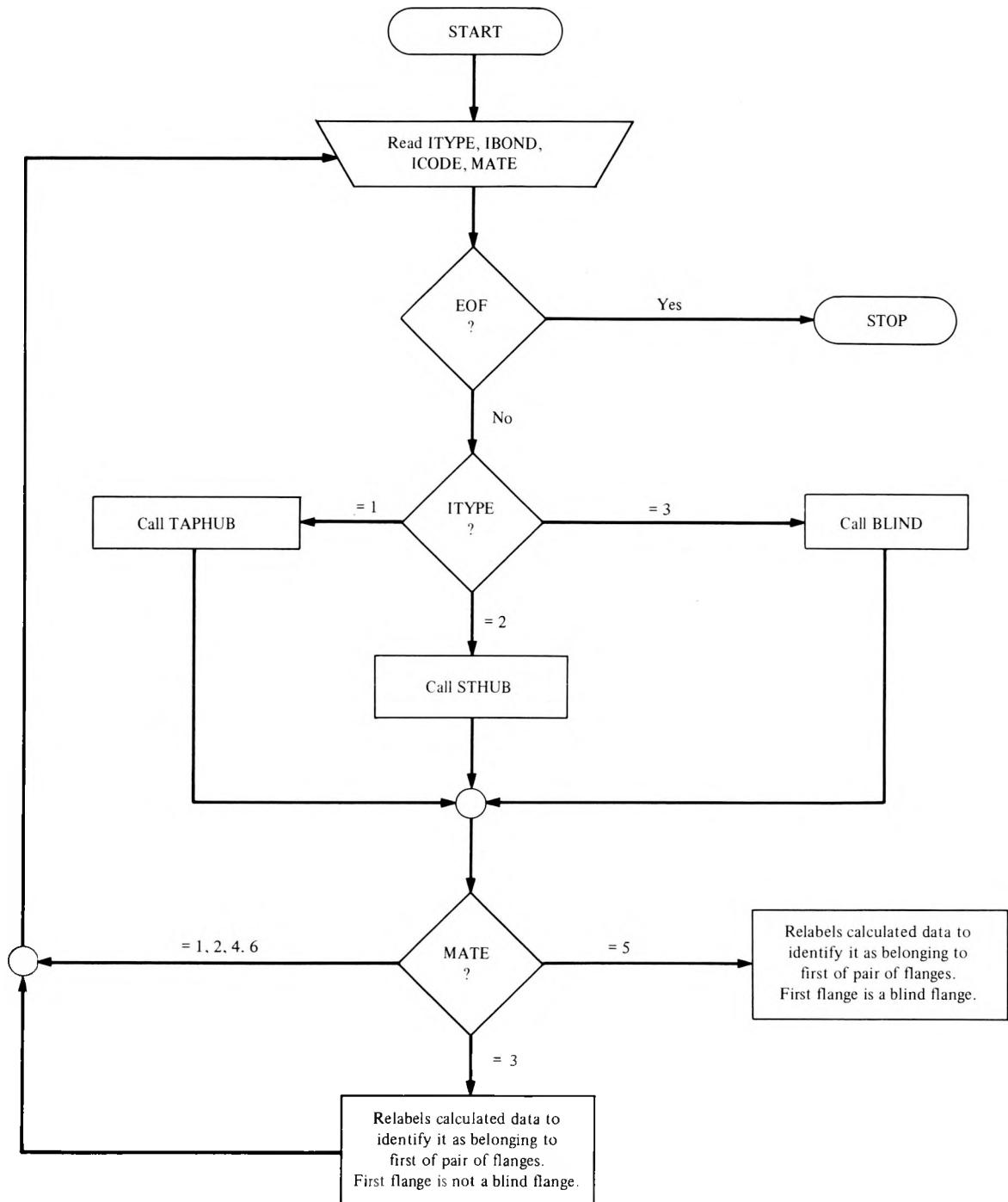


Fig. B.1. Program FLANGE.

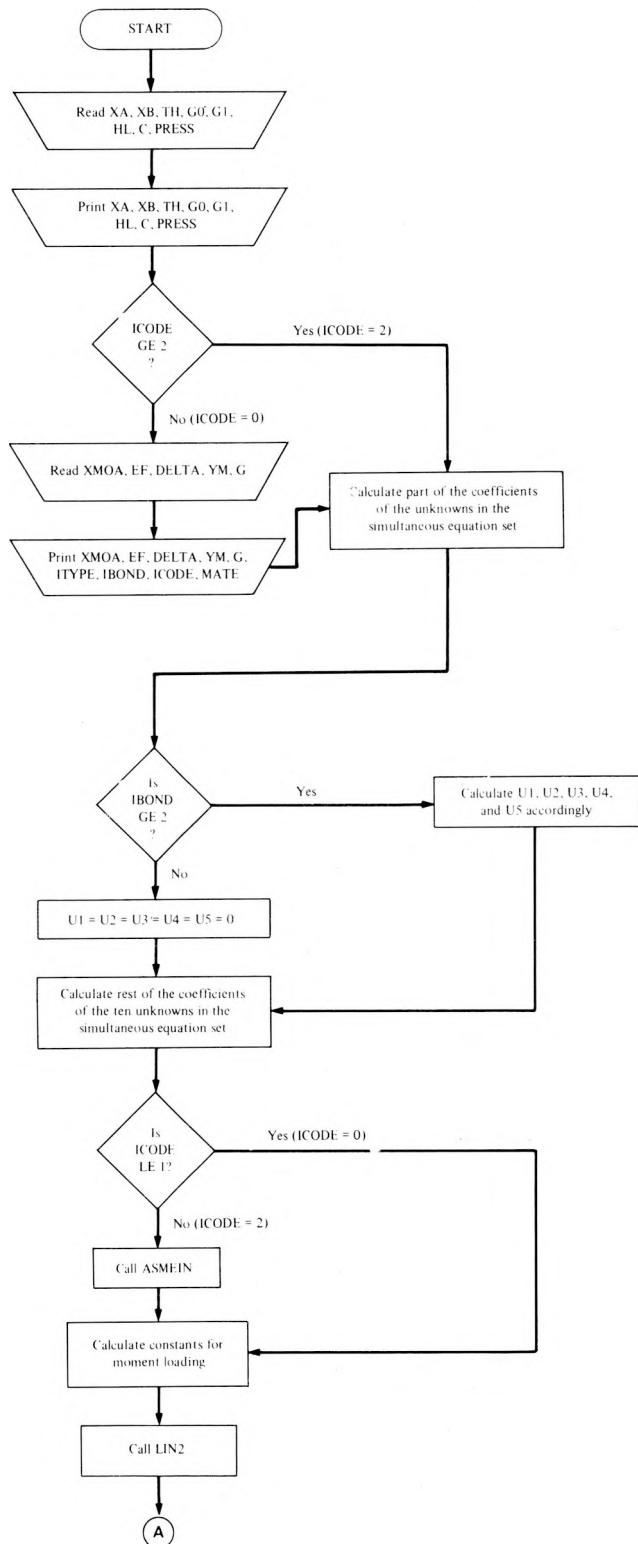


Fig. B.2. Subroutine TAPHUB (Part 1).

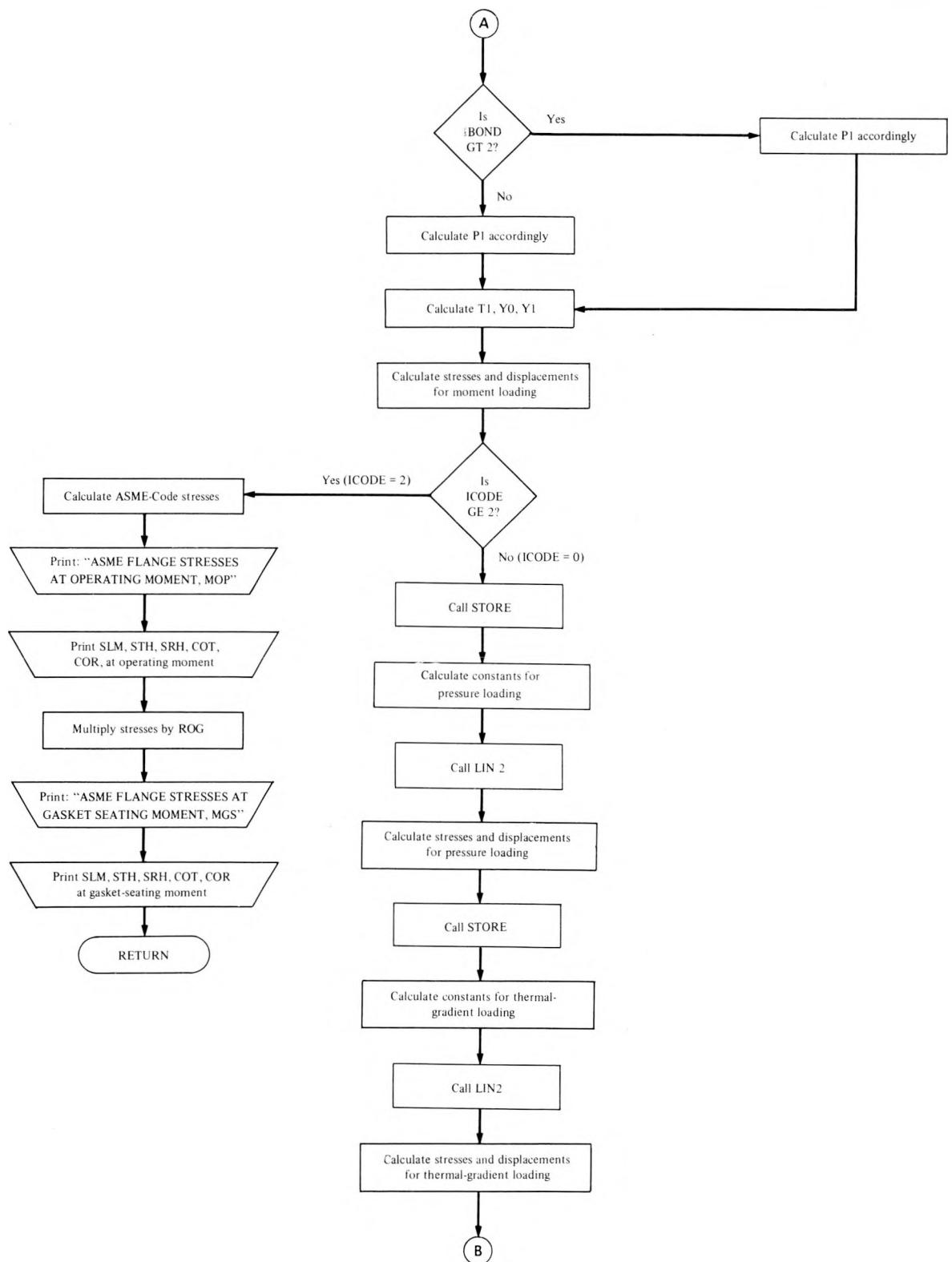


Fig. B.2. Subroutine TAPHUB (Part 2).

ORNL-DWG 75-4303R

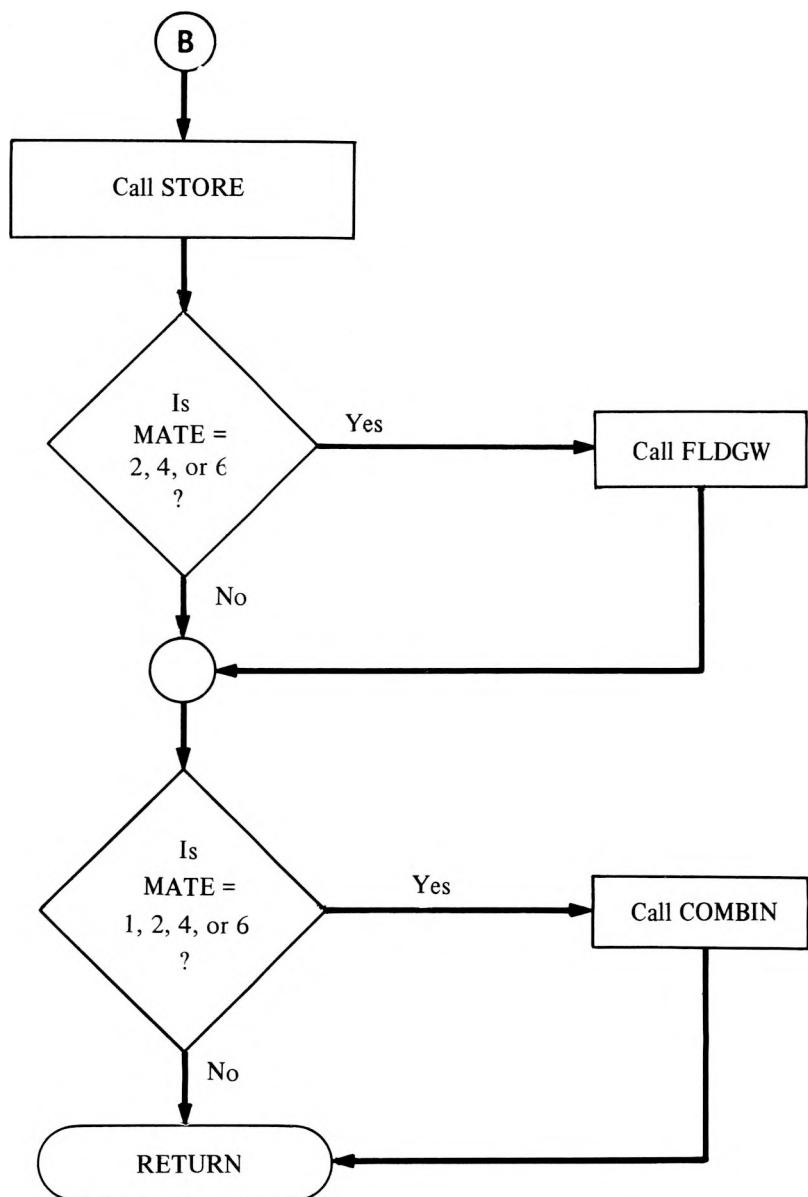


Fig. B.2. Subroutine TAPHUB (Part 3).

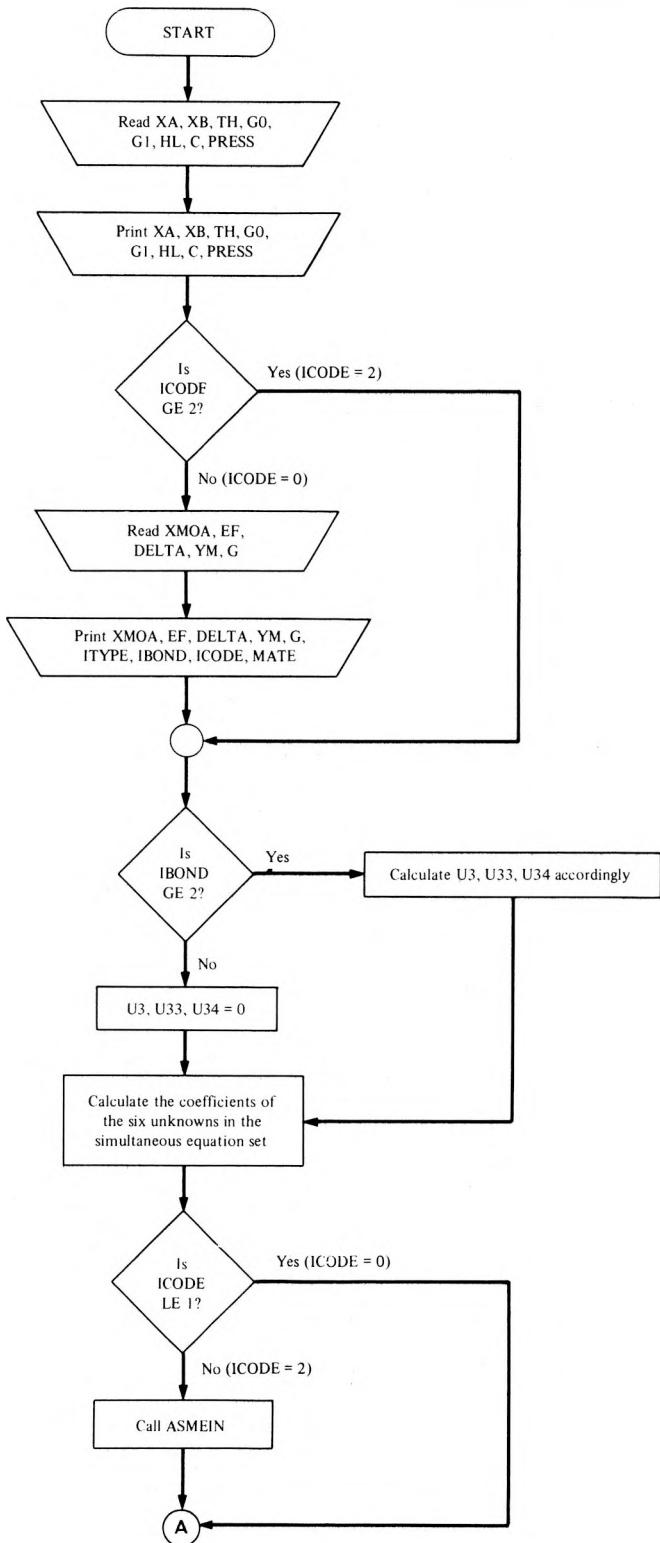


Fig. B.3. Subroutine STHUB (Part 1).

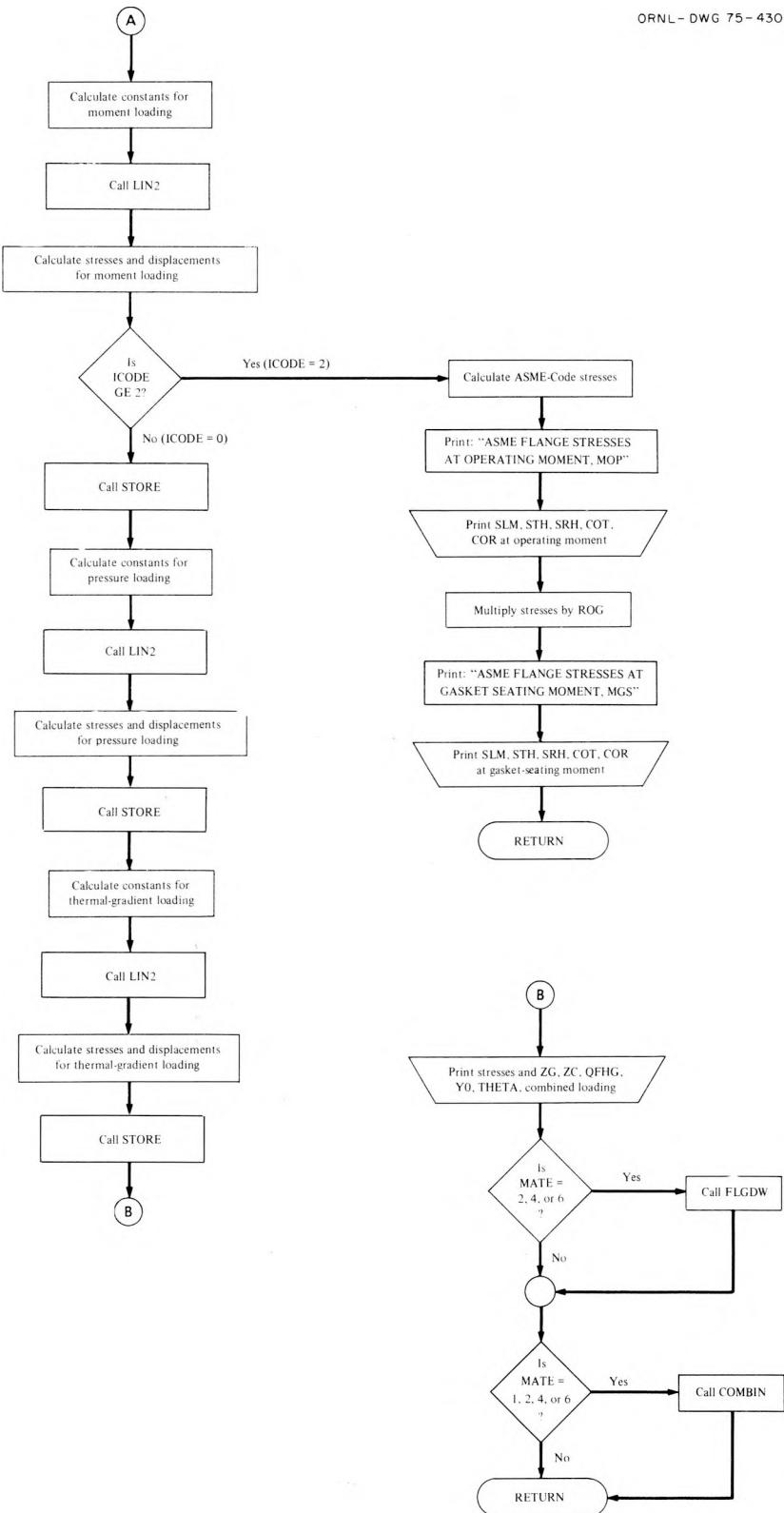


Fig. B.3. Subroutine STHUB (Part 2).

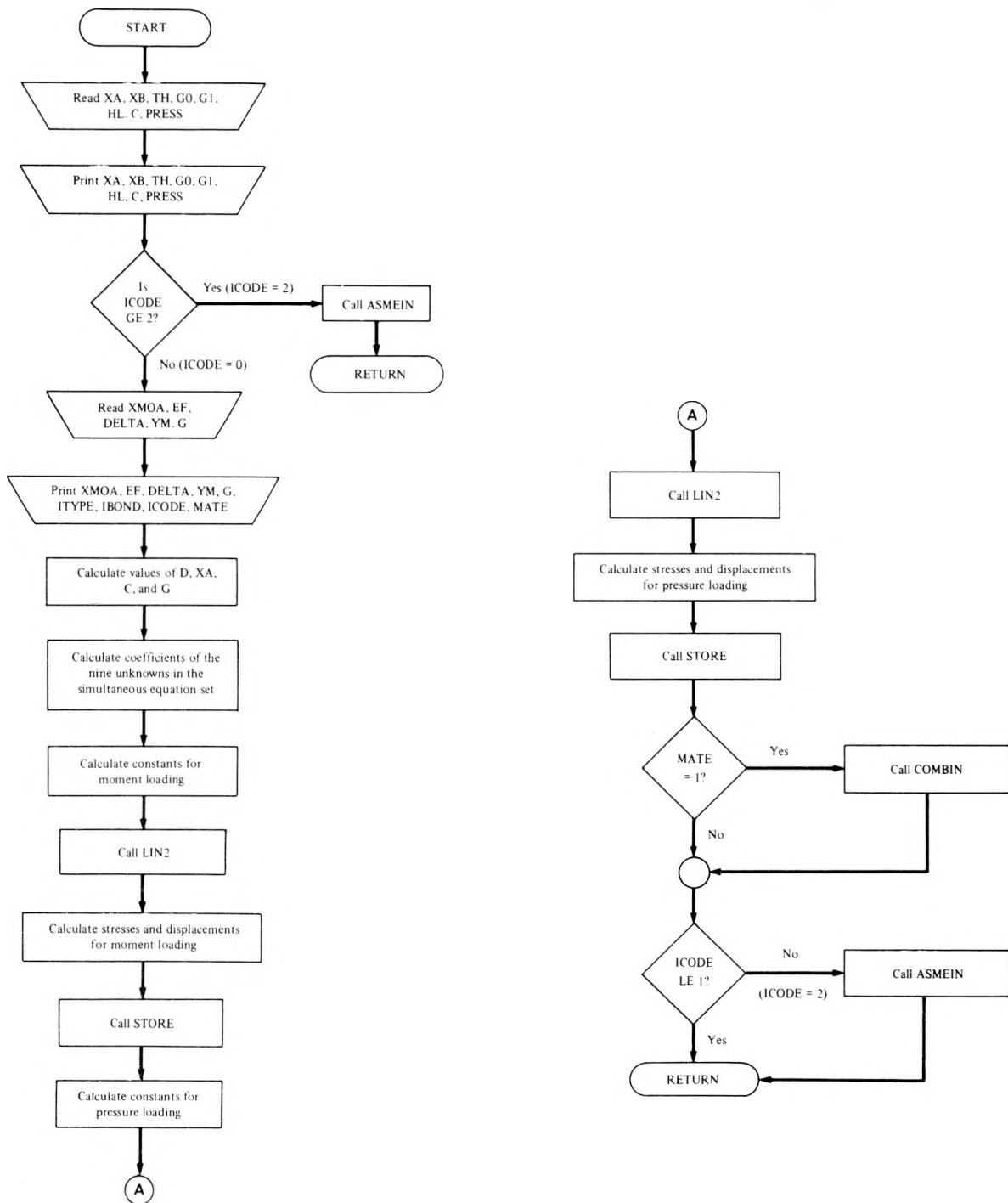


Fig. B.4. Subroutine BLIND.

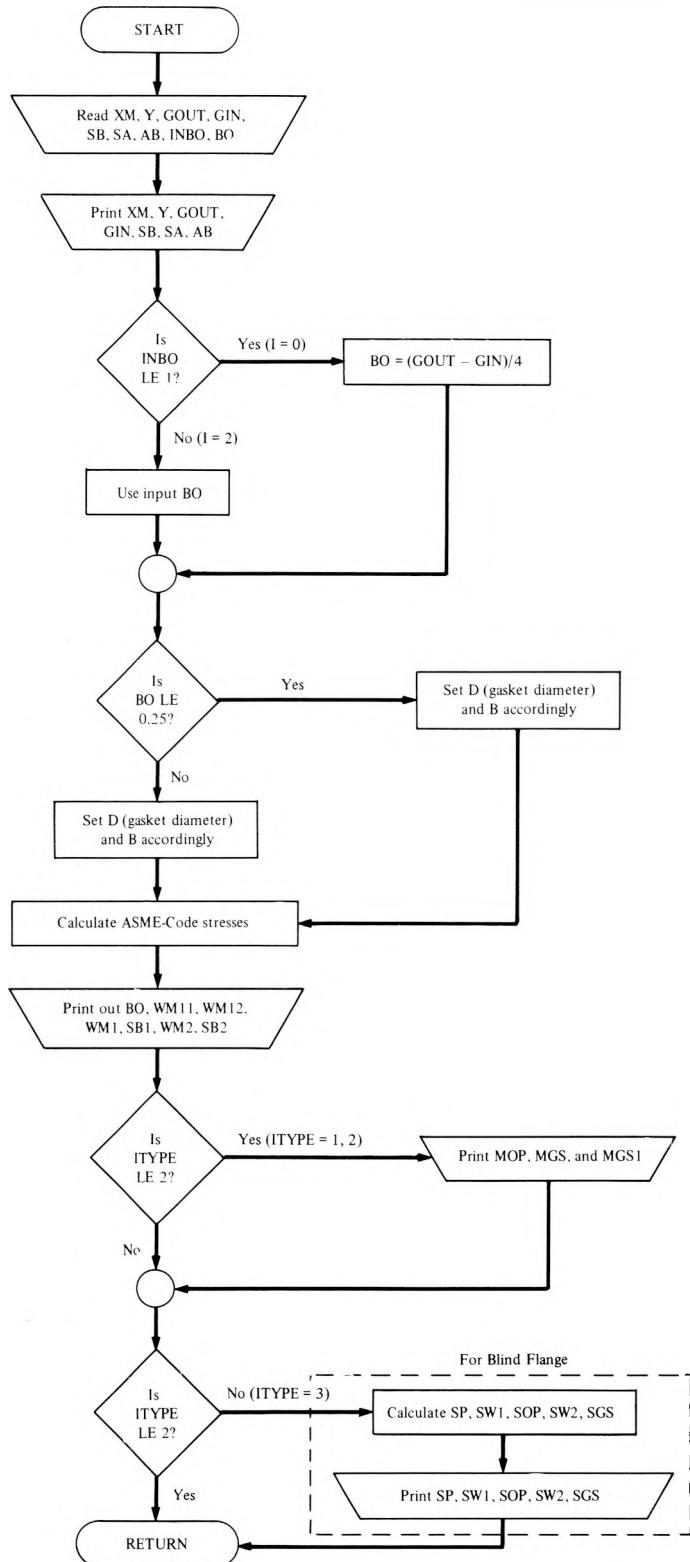


Fig. B.5. Subroutine ASMEIN.

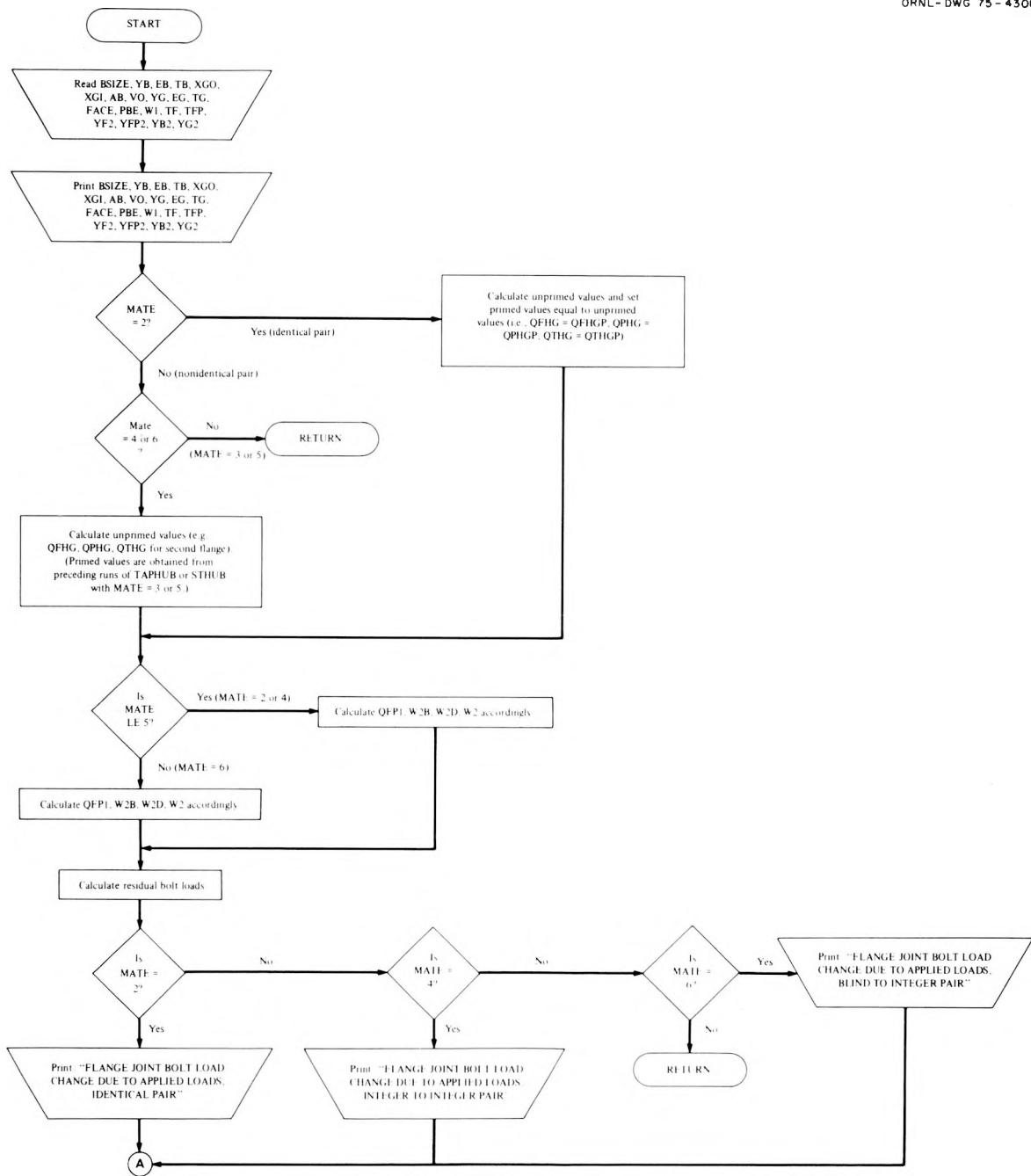


Fig. B.6. Subroutine FLGDW (Part 1).

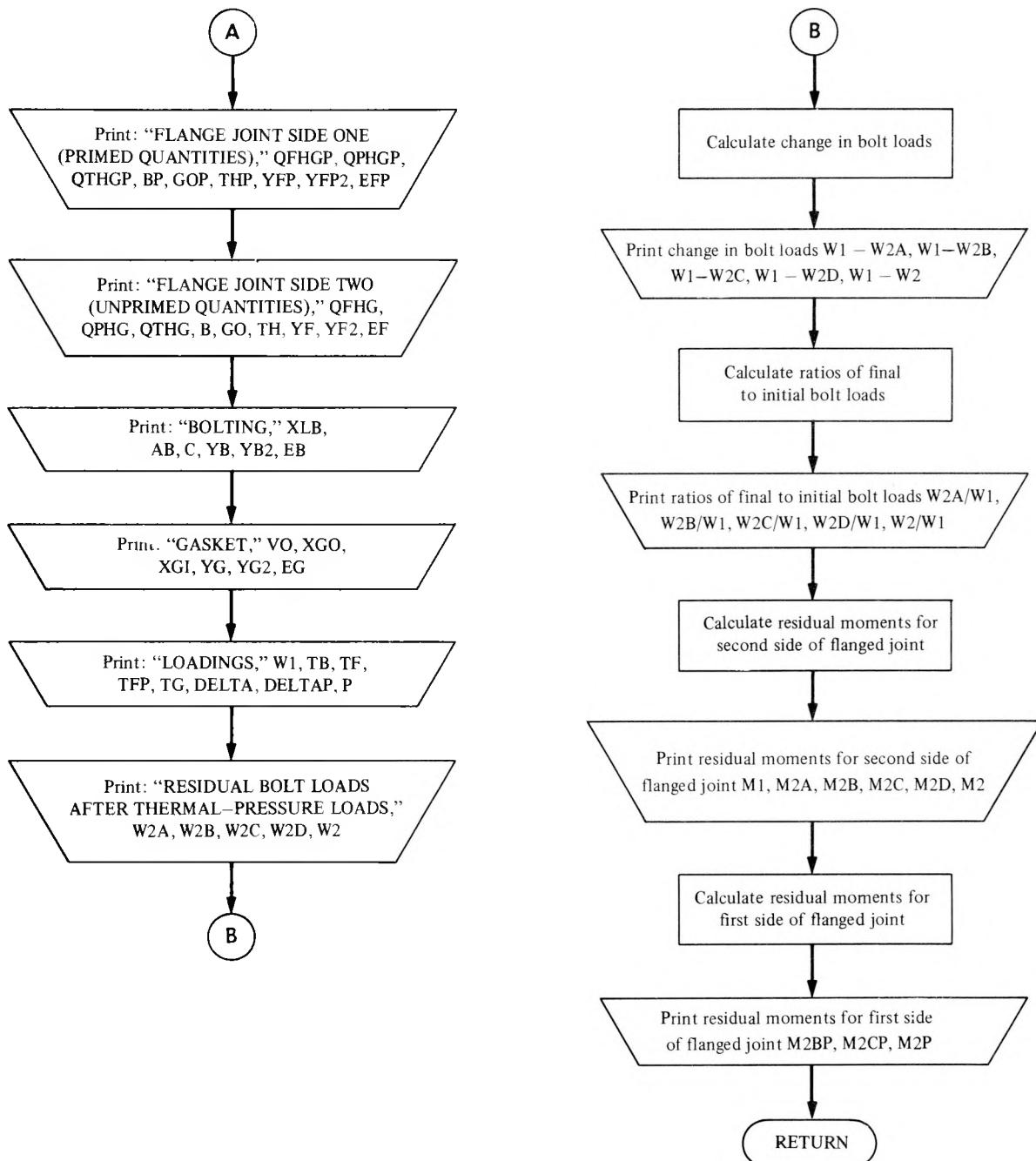


Fig. B.6. Subroutine FLGDW (Part 2).

ORNL-DWG 75-14884

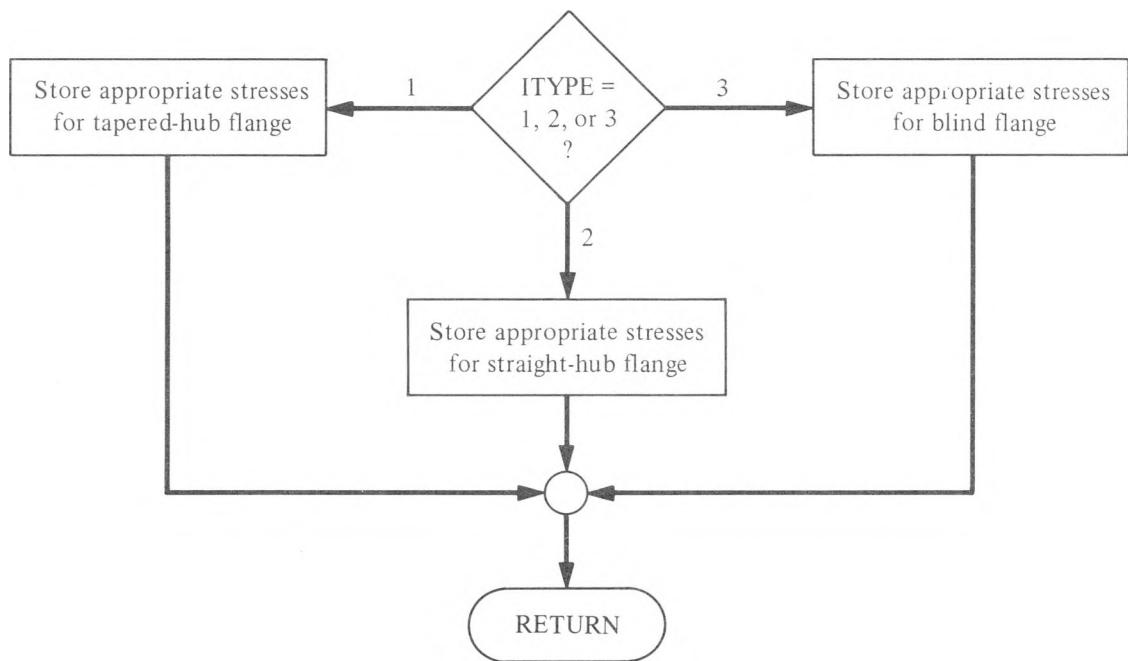


Fig. B.7. Subroutine STORE.

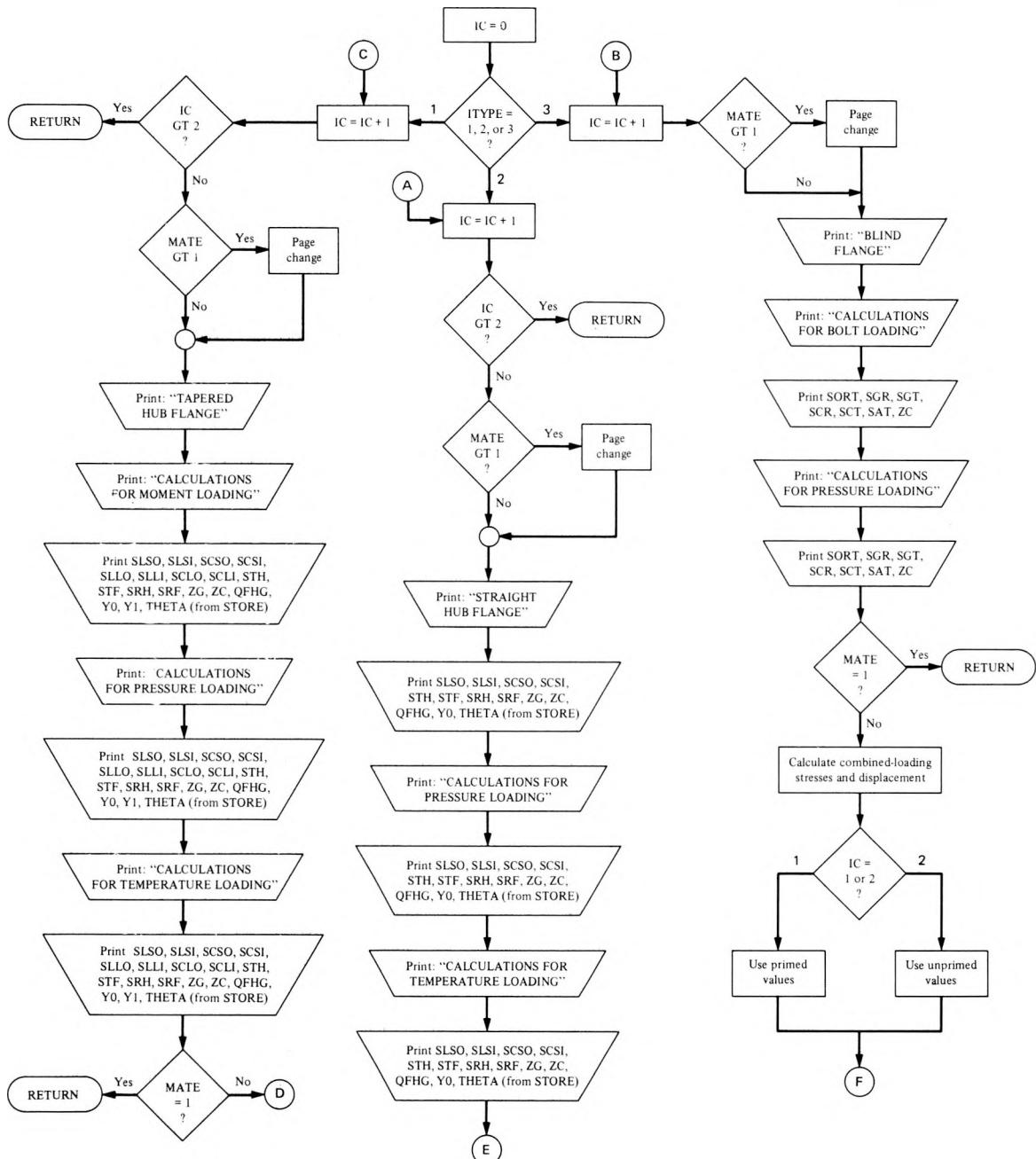


Fig. B.8. Subroutine COMBIN (Part 1).

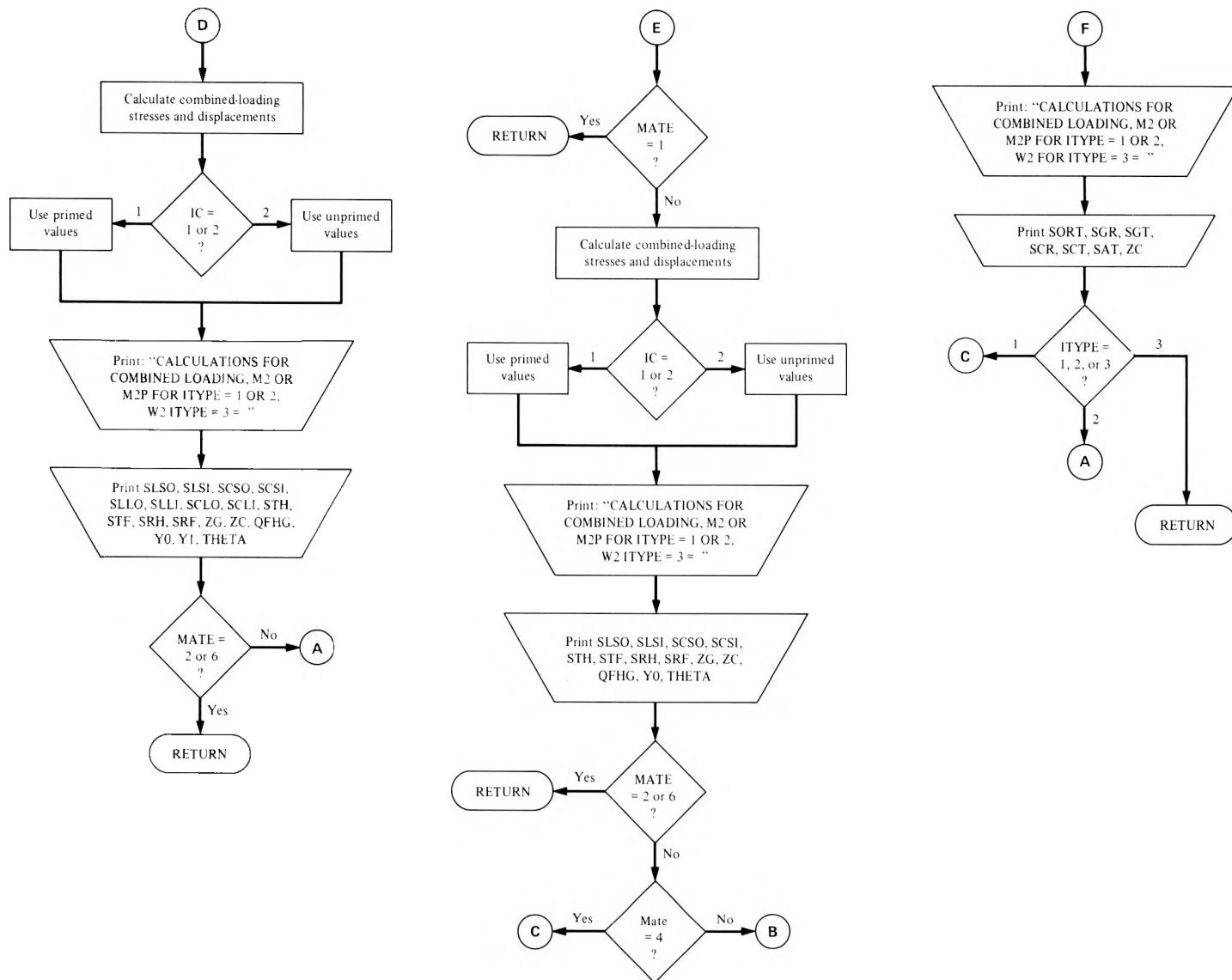


Fig. B.8. Subroutine COMBIN (Part 2).

LISTING OF PROGRAM FLANGE AND ATTENDANT SUBROUTINES

COMPILER OPTIONS - NAME= MAIN, OEF=02, LINECNT=60, SIZ F=0000K,
 SOURCE, EBCDIC, NOLIST, NODECK, LOAD, MAP, NOEDIT, NOID, NOXREF

C PROGRAM FLANGE (INPUT,OUT PUT,TAPE60=INPUT) PLA 1
 C REV ISID 6/21/74 PLA 2
 C CONVERTED TO IBM/360 W/STANDARD INPUT = 5, OUTPUT = 6. 01-22-75
 C FLANGE PROGRAM CHANGES TO FLANK COMMON, 02-19-75. PLA
 C ** MODIF. TO FLANGE PROGRAMS, 09-17-75.
 IMPLICIT REAL*8 (A-H,C-Z) 01-28-75
 DIMENSION A(10,10), B(10), LTEMP(10), LPA(10), LPC(10), AM(10,10) PLA 3
 DIMENSION SB(6,18),SC(18) PLA 3A
 COMMON ITYPE,IBOND,ICODE,MATE,XA,XB,G,C,PRESS,XGS,AOP,G1,GC,Th,YM,PLA 4
 TAB,QPHG(4),AL,DELTA,XMO,QFHPG,QPHGP,QTHGP,BP,GOP,THP,YFP,EFP,PLA 5
 2DELTA,ROUT,G1K,RCG PLA 6
 3,SLSO,SLSI,SCSO,SCSI,SLIO,SLII,SCLO,SCLI,SLR PLA 6A
 4,SPF,SPH,SPF,ZG,ZC,QFHG,YC,YI,T1,THETA,SOFT,SGR,SG1,SCR,SCI,SAT PLA 6B
 5,W2,W1,SB,MA,II,XM1,XM2,XM2P,IT2 PLA 6C

C ITYPE = 1 TAPERED HUB PLA 7
 C ITYPE = 2 STRAIGHT HUB PLA 8
 C ITYPE = 3 BLIND PLA 9
 C IBOND = 0 BOUNDARY PER ASME CODE, Y(X=H) EQUAL ZERO PLA 10
 C IBOND = 2 BOUNDARY Y(X=H) NOT EQUAL TO ZFO PLA 11
 C IBOND = 3 INCLUDES EFFECT OF OUTWARD TAPER, TAPERED HUB FLANGE PLA 12
 C ICODE = 0 CALCULATES STRESSES FOR INPUT XMOA, PRESS, DELTA AND COFLA 13
 C ICODE = 2 CALCULATES STRESSES FOR KSMF OPERATING MOMENT PLA 14
 C MATE = 1 DOES NOT CALCULATE LOAD CHANGES PLA 15
 C MATE = 2 CALCULATES LOAD CHANGES FOR IDENTICAL PAIR PLA 16
 C MATE = 3 CALCULATES LOAD CHANGES FOR INTEGER TO INTEGER PLA 17
 C MATE = 4 CALCULATES LOAD CHANGES FOR INTEGER TO INTEGER PLA 18
 C MATE = 5 CALCULATES LOAD CHANGES FOR BLIND TO INTEGER PLA 19
 C MATE = 6 CALCULATES LOAD CHANGES FOR BLIND TO INTEGER PLA 20

C PRINT 11 PLA 21A
 1 READ 12, ITYPE,IBOND,ICODE,MATE PLA 22
 C IF (LOF,60) 10,2 PLA 23
 2 IT2=ITYPE
 1 READ(5,12,END=10) ITYPE,IBOND,ICODE,MATE 01-22-75
 C IF (ITYPE-2) 3,4,5 PLA 24
 3 CALL TAPHUB PLA 25
 GO TO 6 PLA 26
 4 CALL SINUB PLA 27
 GO TO 6 PLA 28
 5 CALL BLIND PLA 29
 GO TO 6 PLA 30
 6 GO TO (7,7,8,7,9,7), MATE PLA 31
 7 GO TO 1 PLA 32
 8 QFHGP=QFHG(1)/XMOA PLA 33
 QPHGP=QPHG(2)/PRESS PLA 34
 QTHGP=QTHG(3)/DELTA PLA 35
 BP=XB*2.
 G0P=G0 PLA 36
 THP=TH PLA 37
 YFP=YM PLA 38
 EFP=AL PLA 39
 DELTA=DELTA PLA 40
 II = ITYPE PLA 41
 GO TO 1 PLA 41A
 9 QFHGP=-QFHG(1)/XMOA PLA 42
 QPHGP=-QPHG(2)/PRESS PLA 43
 QTHGP=-1.
 BP=-1.
 G0P=-1.
 THP=TH PLA 44
 YFP=YM PLA 45
 EFP=AL PLA 46
 GO TO 1 PLA 47
 10 QFHGP=QFHG(1)/XMOA PLA 48
 QPHGP=QPHG(2)/PRESS PLA 49
 QTHGP=QTHG(3)/DELTA PLA 50

```

      DELTAP=DELTAA          FLA  51
      IT = ITYPE             FLA  51A
      GO TO 1                FLA  52
10  RETURN                01-27-75
C
11  FORMAT (1H1)           FLA  54
12  FORMAT (4I5)           FLA  55
      END                    FLA  56
                                         FLA  57

```

```

C SUBROUTINE TAIFHUB          TAP  2
  THIS CALCULATION IS FOR ITYPE = 1, TAPERED HUB FLANGES      TAP  4
  IMPLICIT REAL*8 (A-H,C-Z)          01-28-75
  DIMENSION A(10,10), B(10), LTEMP(10), LPR(10), AM(10,10)  TAP  6
  DIMENSION SB(6,18),SC(18)           TAP  7A
  COMMON ITYPE,IBCNE,ICCDE,MATE,XA,XB,G,C,PRESS,XGS,XDP,G1,GO,TH,YM,TAP  8
  1AB,QFHG(4),AL,DELTAA,XMOA,QFHGP,QPHGP,QTHGP,BE,BOP,THP,YFP,EFP,TAP 10
  2DELTAP,GOUT,GIN,FCG              TAP  12
  3,SLSO,SLSI,SCSC,SCSI,SLIO,SILI,SCLO,SCLI,SPH            TAP  7A
  4,STF,SPH,SPF,ZG,ZC,QFHG,Y0,Y1,T1,THETA,SORT,SGR,SGI,SCR,SCT,SAT  TAP  7B
  5,W2,W1,SB,MA,IT,XM1,XM2,XM2E          TAP  7C
  DATA A/100*0./,B/10*0./,LTEMP/10*0./,LPR/10*0./,AM/100*0./
C
1  READ 48, XA,XB,TH,GO,G1,HL,C,PRESS          TAP  14
  PRINT 49                                     TAP  16
  PRINT 50, XA,XB,TH,GO,G1,HL,C,PRESS          TAP  18
  G=1.                                         TAP  20
  YM=1.                                         TAP  22
  IF (ICODE.GE.2) GO TO 2          TAP  24
  READ 51, XMOA,EF,DELTAA,YM,G          TAP  26
  PRINT 52                                     TAP  28
  AL=EF                                     TAP  30
  PRINT 53, XMOA,EF,DELTAA,YM,G,ITYPE,IBONE,ICODE,MATE  TAP  32
2  HHO = HL/DSQRT(XB*GO)          TAP  34A
  XA=XA/2.                                     TAP  36
  XB=XB/2.                                     TAP  38
  G=G/2.                                       TAP  40
  C=C/2.                                       TAP  42
  RHO=G1/GO          TAP  44
  ALPHA=RHO-1          TAP  46
  GAMMA = (10.92**0.25)*HL/DSQRT(XB*GO)  TAP  48A
  PHI0=1./ALPHA          TAP  50
  PHI1=RHO/ALPHA          TAP  52
  ETA0=2.*GAMMA/ALPHA          TAP  54
  ETA1=(RHO**.5)*ETA0          TAP  56
  XK=XA/XB          TAP  58
  J=1.                                         TAP  60
  X=ETA0          TAP  62
  PS=(.85*XB/(YM*GO))*PRESS          TAP  64
3  CONTINUE          TAP  66
  IF (X-10.0) 4,4,5          TAP  68
4  T=X/10.0          TAP  70
  C3 = DLOG(X/2.0)          TAP  72A
  T2=T*T          TAP  74
  T3=T2*T          TAP  76
  T4=T3*T          TAP  78
  T8=T4*T4          TAP  80
  T12=T8*T4          TAP  82
  T16=T12*T4          TAP  84
  TZ0=T16*T4          TAP  86

```

T 24=T 20*T 4	TAP	88
T 28=T 24*T 4	TAP	90
T 32=T 28*T 4	TAP	92
C *** CORR. TO CARDS TAP 54-149 OF SUBR. TAPHUB, 02-27-75.		
BERX=.9999999999974D0-156.249999995701D0*T4+678.1684027663091D0*TAP	94 A	
18-4 70.9502795889968D0*T12+93.8596692971726D0*T16-7.2422567278207D0*TAP	96 A	
2*T20+.2597773C007D0*T24-.0048987125727D0*T28+.0000516070465D0*T32 TAP	98 A	
BEIX=-T2*(-24.999999999998D0+434.027777777748D0*T4-678.1684027769TAP	100 A	
1807D0*T8+240.2807549442574DC*T12-28.9690338786499D0*T16+1.49633427TAP	102 A	
249742DC*T20-.0384288282734DC*T24+.0005444243175D0*T28-.44913D-5*T3TAP	104 A	
42) TAP 105 A		
DBERX=T 3*(-62.4999999999999D0+542.534722222147D0*T4-565.140335647TAP	106 A	
19486D0*T8+150.1754718432278D0*T12-14.4845169498403D0*T16+.62347263TAP	108 A	
248243D0*T20-.013724603619D0*T24+.1701453451D-3*T28-.12506046D-5*T3TAP	110 A	
32) TAP 111 A		
DBEIX=-T*(-4.9999999999993D0+260.416666665533D0*T4-678.1684027747TAP	112 A	
1539D0*T8+336.3930569023651D0*T12-52.1442608975905D0*T16+3.29193521TAP	114 A	
208579D0*T20-.0999147064932D0*T24+.0016331100837D0*T28-.00001522698TAP	116 A	
384D0*T32) TAP 117 A		
R1X=T2*(24.9999999999993D0-795.7175925924866D0*T4+1548.48451967309TAP	118 A	
192D0*T8-623.0136717405201D0*T12+81.95247716062D0*T16-4.51874591326TAP	120 A	
239D0*T20+.1222087382192D0*T24-.0018064777860D0*T28+.154363047D-4*TAP	122 A	
3T32) TAP 123 A		
R2X=T4*(234.375-1412.8508391203636D0*T4+1153.8281852814561D0*T8-25TAP	124 A	
15.0971742710479D0*T12+21.2123451660231D0*T16-.8061529027876D0*T20+TAP	126 A	
2.0159380149705D0*T24-.001797627986D0*T28+.0000012161109D0*T32) TAP 128 A		
DR1X=I*(4.9999999999975D0-477.4305555551536D0*T4+1548.484519665203TAP	130 A	
15D0*T8-872.2191403672455D0*T12+147.514458591337D0*T16-9.941240320TAP	132 A	
29725D0*T20+.3177418434686D0*T24-.0054188558408D0*T28+.000052329431TAP	134 A	
34D0*T32) TAP 135 A		
DR2X=T 3*(93.749999999998D0-1130.2806712962694D0*T4+1384.593822337TAP	136 A	
12452D0*T8-408.1554788292578D0*T12+42.4246903131088D0*T16-1.9347669TAP	138 A	
2229237D0*T20+.0446263862145D0*T24-.0005752042283D0*T28+.0000043682TAP	140 A	
3053D0*T32) TAP 141 A		
CEIX=-.78539816439745D0*BERX+R1X- (.5772156649D0+C3)*BEIX TAP 142 A		
CERX=+.78539816439745D0*BEIX-R2X- (.5772156649D0+C3)*BERX TAP 144 A		
DKERX=+.78539816439745D0*DBEIX-DR2X- (EERX/X)- (.5772156649D0+C3)*DBI TAP 146 A		
1ERX TAP 147 A		
DKEIX=-.78539816439745D0*DBERX+DR1X- (BEIX/X)- (.5772156649D0+C3)*DBI TAP 148 A		
1EIX TAP 149 A		
GO TO 6 TAP 150		
5 T=10.0/X TAP 152		
C1=(DEXP(+X/1.414213562371D0)/DSQRT(6.2831E503718D0*X)) TAP 154 B		
C2=(DEXP(-X/1.414213562371D0)*DSQRT(1.57079632679D0/X)) TAP 156 B		
SIN1=DSIN((X/1.414213562371D0)+(.392699081699D0)) TAP 158 B		
SIN2=DSIN((X/1.414213562371D0)-(.392699081699D0)) TAP 160 B		
COS1=DCOS((X/1.414213562371D0)+(.392699081699D0)) TAP 162 B		
COS2=DCOS((X/1.414213562371D0)-(.392699081699D0)) TAP 164 B		
T2=T*T TAP 166		
T3=T2*T TAP 168		
T4=T3*T TAP 170		
T5=T4*T TAP 172		
T6=T5*T TAP 174		
T7=T6*T TAP 176		
T8=T7*T TAP 178		
S=1+.0088388346D0*T+.7D-9*T2-.0000517869D0*T3-.0000112207D0*T4-.0TAP 180 A		
1000016192D0*T5+.135D-8*T6+.1452D-6*T7+.492D-7*T8 TAP 182 A		
TT=-.0088388340D0*T-.00C07031241D0*T2-.0000518006D0*T3-.72D-8*T4+.1TAP 184 A		
164310D-5*T5+.59291E-6*T6+.750D-7*T7-.243D-7*T8 TAP 186 A		
U=1.-.0265165C40DC*T-.8D-9*T2+.725024D-4*T3+.144255D-4*T4+.19780D-TAP 188 A		
15*T5-.147D-7*T6-.1671D-6*T7-.563D-7*T8 TAP 190 A		
V=+.0265165034D0*T+.0011718740D0*T2+.725179D-4*T3+.79D-8*T4-.20042TAP 192 A		
1D-5*T5-.6992D-6*T6-.8E3D-6*T7+.269D-8*T8 TAP 194 A		
BERX=C1*((S*COS2)-(T*T*SIN2)) TAP 196		
BEIX=C1*((TT*COS2)+(S*SIN2)) TAP 198		
DBERX=C1*((U*COS1)-(V*SIN1)) TAP 200		
DBEIX=C1*((V*CCS1)+(U*SIN1)) TAP 202		
T=-T TAP 204		
T2=T*T TAP 206		
T3=T2*T TAP 208		

```

T4=T3*T                               T AP 210
T5=T4*T                               T AP 212
T6=T5*T                               T AP 214
T7=T6*T                               T AP 216
T8=T7*T                               T AP 218
S=1.+.0088388346D(*T+.7D-.9*T2-.517869D-4*T3-.112207D-4*T4-.16192D-T AP 220 A
15*T5+.135D-8*T6+.1452D-6*T7+.492D-7*T8                               T AP 222A
T T=-.8838834D-2*T1-.7031241D-3*T2-.518006D-4*T3-.72D-8*T4+.16431D-5T AP 224A
1*T5+.5929D-6*T6+.75CD-7*T7-.243D-7*T8                               T AP 226 A
U=1.+.026516504D0*T-.8D-9*T2+.725024D-4*T3+.144255D-4*T4+.1978D-5*T AP 228A
1T5-.147D-7*T6-.1671D-6*T7-.563D-7*T8                               T AP 230A
V=+.0265165034D0*T+.1171874D-2*T2+.725179D-4*T3+.79D-8*T4-.20042D-T AP 232 A
15*T5-.6992D-6*T6-.883D-6*T7+.269D-8*T8                               T AP 234A
CERX=C2*((S*COS1)+(T*T*SIN1))                               T AP 236
CEIX=C2*((TT*CCS1)-(S*SIN1))                               T AP 238
DKERX=-C2*((U*COS2)+(V*SIN2))                               T AP 240
DKEIX=-C2*((V*COS2)-(U*SIN2))                               T AP 242
6 CONTINUE                               T AP 244
IF (J-1) 7,7,8                               T AP 246
7 PO=(1.)/(RHO-1.)) **.5                               T AP 248
J=J+1                               T AP 250
A (1,1)=DBERX                               T AP 252
A (1,2)=DBEI X                               T AP 254
A (1,3)=DK ERX                               T AP 256
A (1,4)=DKEIX                               T AP 258
A (1,5)=0.                               T AP 260
A (1,6)=-PO                               T AP 262
A (1,7)=0.                               T AP 264
A (1,8)=0.                               T AP 266
A (1,9)=0.                               T AP 268
A (1,10)=0.                               T AP 270
A (2,1)=-X*BEIX-2.*DBERX                               T AP 272
A (2,2)=X*BERX-2.*IBERX                               T AP 274
A (2,3)=-X*CEIX-2.*DKEIX                               T AP 276
A (2,4)=X*CERX-2.*DKERX                               T AP 278
A (2,5)=-(X*PO/(2.**.5))                               T AP 280
A (2,6)=A (2,5)                               T AP 282
A (2,7)=0.                               T AP 284
A (2,8)=0.                               T AP 286
A (2,9)=0.                               T AP 288
A (2,10)=0.                               T AP 290
A (3,1)=4.*X*BEIX+8.*DBERX-X*X*DBEI X                               T AP 292
A (3,2)=-4.*X*EI FX+8.*DBEI X+X*X*DBERX                               T AP 294
A (3,3)=4.*X*CEIX+E.*DKEFX-X*X*DKEIX                               T AP 296
A (3,4)=-4.*X*CEBX+8.*DKEIX+X*X*X*DKEIX                               T AP 298
A (3,5)=-X*X*PO                               T AP 300
A (3,6)=0.                               T AP 302
A (3,7)=0.                               T AP 304
A (3,8)=0.                               T AP 306
A (3,9)=0.                               T AP 308
A (3,10)=0.                               T AP 310
A (4,1)=(-X*BERX+2.*DBEI X)                               T AP 312
A (4,2)=(-X*BEIX-2.*DBERX)                               T AP 314
A (4,3)=(-X*CERX+2.*DKEIX)                               T AP 316
A (4,4)=(-X*CEIX-2.*DKERX)                               T AP 318
A (4,5)=A (2,5)                               T AP 320
A (4,6)=-A (2,5)                               T AP 322
A (4,7)=0.                               T AP 324
A (4,8)=0.                               T AP 326
A (4,9)=0.                               T AP 328
A (4,10)=0.                               T AP 330
X=X*RHO**.5                               T AP 332
GO TO 3                               T AP 334
8 PO=(RHO/(RHO-1.)) **.5                               T AP 336
IF (IBOND-1) 9,10,10                               T AP 338
9 IF 1=0.                               T AP 340
U2=0.                               T AP 342
U3=0.                               T AP 344
U4=0.                               T AP 346
U5=0.                               T AP 348

```

```

GO TO 11
10 PHI 1=PO*PO
P=PRESS
XK2=XK*XX
U1=TH/(4.*PHI 1*HL)
U2=X*YM*G1**3/(87.36*TH*(PHI1*HL)**3)
U3=(XB/YM)*((1.3*XK2+.7)/(XK2-1.))
U4=-TH*X*B*ALPHA*FS/(2.*HL*(1.+ALPHA)**2)
U5=ALPHA*GO*X E*P/(4.*HL*TH)

11 AA11=DEERX
AA12=DBEIX
AA13=DKERX
AA14=DKEIX
AA21=-X*BEIX-2.*DEERX
AA22=X*BERX-2.*DBEIX
AA23=-X*CEIX-2.*DKERX
AA24=X*CERX-2.*DKEIX
AA41=(-X*EERX+2.*IBEIX)
AA42=(-X*BEIX-2.*IBERX)
AA43=(-X*CERX+2.*IKEIX)
AA44=(-X*CEIX-2.*IKERX)
A(5,1)=AA11+U1*AA21-U2*U3*AA41
A(5,2)=AA12+U1*AA22-U2*U3*AA42
A(5,3)=AA13+U1*AA23-U2*U3*AA43
A(5,4)=AA14+U1*AA24-U2*U3*AA44
A(5,5)=0.
A(5,6)=0.
A(5,7)=0.
A(5,8)=0.
A(5,9)=0.
A(5,10)=0.
A(6,1)=-X*BEIX-2.*DBEIX
A(6,2)=X*BERX-2.*IBEIX
A(6,3)=-X*CEIX-2.*DKERX
A(6,4)=X*CERX-2.*DKEIX
A(6,5)=0.
A(6,6)=0.
A(6,7)=-2.0*PHI 1**1.5*HL*(2.0*DLOG(XB)+1.0)
A(6,8)=-4.*PHI 1**1.5*HL
A(6,9)=-2.*PHI 1**1.5*HL/(XB*XB)
A(6,10)=0.
A(7,1)=4.*X*BEIX+8.*DBERX-X*X*DBEIX+((GAMMA**2.*TH)/(HL*ALPHA))*(-
1*X*BERX+2.*DBEIX)
A(7,2)=-4.*X*BERX+8.*DBEIX+X*X*DBERX+((GAMMA**2.*TH)/(HL*ALPHA))*(
1-X*BEIX-2.*DBERX)
A(7,3)=4.*X*CEIX+8.*DKERX-X*X*DKEIX+((GAMMA**2.*TH)/(HL*ALPHA))*(-
1*X*CERX+2.*DKEIX)
A(7,4)=-4.*X*CERX+8.*DKEIX+X*X*DKERX+((GAMMA**2.*TH)/(HL*ALPHA))*(
1-X*CEIX-2.*DKERX)
A(7,5)=0.
A(7,6)=0.
TEMP=-4.*PHI 1**2.5*HL*H1*TH**3./((G1**3.)*XB)
A(7,7)=TEMP*(2.*DLOG(XB)+3.3)
A(7,8)=TEMP*2.6
A(7,9)=-TEMP*0.7/(XB*XB)
A(7,10)=0.
A(8,1)=0.
A(8,2)=0.
A(8,3)=0.
A(8,4)=0.
A(8,5)=0.
A(8,6)=0.
A(8,7)=XB*XB*DLCG(XB)
A(8,8)=XB*X
A(8,9)=DLOG(XB)
A(8,10)=1.0
A(9,1)=0.
A(9,2)=0.
A(9,3)=0.
A(9,4)=0.

```

```

A(9,5)=0                                     TAP 490
A(9,6)=0                                     TAP 492
A(9,7)=2.6*DLCG(XA)+3.3                     TAP 494A
A(9,8)=2.6                                     TAP 496
A(9,9)=-0.7/(XA*XA)                         TAP 498
A(9,10)=0.                                    TAP 500
A(10,1)=0.                                    TAP 502
A(10,2)=0.                                    TAP 504
A(10,3)=0.                                    TAP 506
A(10,4)=0.                                    TAP 508
A(10,5)=0.                                    TAP 510
A(10,6)=0.                                    TAP 512
A(10,7)=1.0                                   TAP 514
A(10,8)=0.                                    TAP 516
A(10,9)=0.                                    TAP 518
A(10,10)=0.                                 TAP 520
C   PRINT 3,B(1), B(2), B(3), E(4), B(5), B(6), B(7), B(8), B(9), B(10) TAP 522
DO 13 I=1,10                                 TAP 524
DO 12 J=1,10                                 TAP 526
AM(I,J)=A(I,J)                            TAP 528
12 CONTINUE                                 TAP 530
13 CONTINUE                                 TAP 532
C   CALCULATIONS FOR MOMENT LOADING, TAPERED HUB
P=0.                                         TAP 534
PS=0.                                         TAP 536
DELT=0.                                         TAP 538
IF (ICODE-1) 14,14,15                         TAP 540
14 XMO=XMOA                                 TAP 542
GO TO 16                                 TAP 544
15 CALL ASMEIN                               TAP 546
XMO=XOP                                     TAP 548
G=(GOUT+GIN)/2.                            TAP 550
16 PRINT 54                                 TAP 552
16 CONTINUE                                 TAP 554A
DO 17 I=1,10                                 TAP 554B
B(I)=0.                                     TAP 556
17 CONTINUE                                 TAP 558
B(10)=-(2.73/(6.2832*YM*TH**3.* (XA-XB)))*XMO TAP 560
CALL LIN2 (A,10,1C,0.,B,1,1C,LTEMP,IERR,DET,NEIV,ELV,LPA,LPC) TAP 562
B17=(-X*BERX+2.*DEEIX)                      TAP 564
B18=(-X*BEIX-2.*DEERX)                      TAP 566
B19=(-X*CERX+2.*DKEIX)                      TAP 568
B20=(-X*CEIX-2.*DKERX)                      TAP 570
P1=(-YM*G1**3.*XB*ETA1**2.)/(87.36*PHI1**3.5*HL**3.)*(B17*B(1)+B18*B(2)) TAP 572
1*B(2)+B19*B(3)+B20*B(4))                  TAP 574
B9=-X*BEIX+8.*DEERX-X*DEEIX                  TAP 576
B10=-4.*X*BERX+8.*DCEIX+X*X*DBERX          TAP 578
B11=4.*X*CEIX+8.*DKEIX-X*X*DKEIX          TAP 580
B12=-4.*X*CERX+8.*DKERX+X*X*DKERX          TAP 582
A1=(1./(4.*PHI1**2.5))*(B9*B(1)+B10*B(2)+B11*B(3)+B12*B(4))+2.*ALP TAP 584
1*H**2*PS/((1.+ALPHA)**3)                   TAP 586
T1=B(7)*(2.0*XB*DLOG(XB)+XB)+2.0*B(8)*XB+B(9)/XB TAP 590A
P1A1=P1/A1                                 TAP 592
COF=-(YM*G0*H1*HL**3.)/(XE**2.73**.25*GAMMA**3.) TAP 594
F=P1A1/COF                                 TAP 596
T1A1=T1/A1                                 TAP 598
COV=(XB**2.73**.25*RHO**3.)/(HL*GAMMA)      TAP 600
V=T1A1/COV                                 TAP 602
C-----01-17-75
C   IF (IBOND-1) 18,18,19
C   18 CONTINUE
C-----01-17-75
19 IP=0                                     TAP 604
MA=1                                         TAP 606
20 SLBS=1.816*YM*B(5)                      TAP 608
IF (IBOND-2) 21,21,22                      TAP 610
21 P1=(-YM*G1**3.*XB*ETA1**2.)/(87.36*PHI1**3.5*HL**3.)*(B17*B(1)+B18*B(2)) TAP 612
12)+B19*B(3)+B20*B(4))                  TAP 614
GO TO 23                                 TAP 618
22 P1=(-YM*G1**3.*XB*ETA1**2.)/(87.36*PHI1**3.5*HL**3.)*(B17*B(1)+B18*B(2)) TAP 620
                                            TAP 622

```

```

12) +E19*B(3) +B20*B(4)) +ALPHA*G0*XB*P/(4.*HL) TAP 624
23 T1 = B(7) + (2.0*XB*DLOG(XB)+XB) + 2.0*B(8)*XB+B(9)/XB TAP 626A
Y0=XB*(8.6+PS) TAP 628
Y1=(XB/PO)*(DEERX*B(1)+DBLIX*B(2)+DKERX*B(3)+DKETX*B(4))+XB*PS/RHOTAP 630
SLSO=-SIBS+P*XB/(2.*G0) TAP 632
SLSI=SLS+P*XE/(2.*G0) TAP 634
SCSO=.3*SLS0+Y1*Y0/XB TAP 636
SCSI=.3*SLSI+Y1*Y0/XB TAP 638
SLBL=(YM*G1/1.82)*((XB/(4.*PH1**2.5*HL*HL))* (B9*B(1)+B10*B(2)+B11) TAP 640
1*B(3)+B12*B(4))+2.*XB*ALPHA**2*PS/(HL*HL*(1.+ALPHA)**3)) TAP 642
SLL0=-SLBL+P*XE/(2.*G1) TAP 644
SLLI=SLBL+P*XE/(2.*G1) TAP 646
SCLO=.3*SILO+YM*Y1/XB TAP 648
SCLI=.3*SLLI+YM*Y1/XB TAP 650
STB = -(YM*TH/1.82)*((2.6*DLOG(XB)+1.9)*B(7)+2.6*B(8)+ (0.7/(XB*XB)) TAP 652A
1*B(9)) TAP 654A
STM=((XK*XK+1.)/(XK*XK-1.))*(P-P1/TH) TAP 656
STH=STB+STM TAP 658
STF=-STB+STM TAP 660
SRB = -(YM*TH/1.82)*((2.6*DLOG(XB)+3.3)*B(7)+2.6*B(8)-0.7*B(9)/(XB TAP 662A
1*XB)) TAP 664A
SRH=SRE-P+P1/TH TAP 666
SFF=-SAB-P+P1/TH TAP 668
FR=SLSO/SLL0 TAP 670
ZG = B(7)*G*DLOG(G)+B(8)*G*G+B(9)*DLOG(G)+B(10) TAP 672A
ZC = B(7)*C*C*DLOG(C)+B(8)*C*C+B(9)*DLOG(C)+B(10) TAP 674A
QFHG=-ZC+ZG TAP 676
QFHR(MA)=QFHG TAP 678
IF (ICODE-2) 24,25,25 TAP 680
24 CALL STORE TAP 681A
C 24 PRINT 55, ETC, ETC. TAP 682A
C 1,ETC, ETC. TAP 684A
GO TO 26 TAP 686
25 SLMAX = DMAX1(DAES(SLSO),DABS(SLL0)) TAP 688A
SLM=.66667*SLMAX TAP 690
COT=(SLMAX+STH)/2. TAP 692
COR=(SLMAX+SRH)/2. TAP 694
PRINT 56 TAP 696
PRINT 57, SLM,STH,SRH,COT,COR TAP 698
PRINT 58 TAP 700
SLM=SLM*ROG TAP 702
STH=STH*ROG TAP 704
SRH=SRH*ROG TAP 706
COT=COT*ROG TAP 708
COR=COR*ROG TAP 710
PRINT 57, SLM,STH,SRH,COT,COR TAP 712
PRINT 62 TAP 714
GO TO 47 TAP 716
26 IP=IP+1 TAP 718
C GO TO( 27,36,40,44 ),IP TAP 720A
GO TO( 27,36,40 ),IP TAP 721A
C CALCULATION FOR PRESSURE LOADING, TAPERED HUB TAP 722
27 XM0=0. TAP 724
P=PRESS TAP 726
DLT=0. TAP 728
PS=(.85*XB/(YM*G0))*P TAP 730
C PRINT 59 TAP 732A
DO 28 I=1,10 TAP 734
B(I)=0. TAP 736
28 CONTINUE TAP 738
PO=(1.0/(RHO-1.0))**.5 TAP 740
E(2)=-2.*PO*PS TAP 742
E(3)=8.*PO*PS TAP 744
-----01-17-75
C ** THESE TWO STATEMENTS NO LONGER COMMENTS, 09-17-75.
IF( IBOND-2 ) 30,30,29 TAP 746A
29 B(4) = -1.944*E*PS TAP 748A
C-----01-17-75
30 E0=(RHO/(RHO-1.0))**.5 TAP 750
IF( IBOND-2 ) 31,31,32 TAP 752

```

```

31 B(5) = (PO/XB)*(XB*PS/(1.+ALPHA))-U3*P+U4*XB*AL*DELT)      TAP 754
  B(7) = 8.*PO*PS/(RHC)                                         TAP 756
  GO TO 33                                         TAP 758
32 B(5) = (PO/XB)*(XB*PS/(1.+ALPHA))-U3*P+U4*U3*U5*XB*AL*DELT)  TAP 760
  B(7) = 8.*PO*PS/(RHC)-5.4*TH*H1*P/(GJ*GO*RPO**.5*ALPHA**1.5*YM) TAP 762
33 B(6) = -2.*PO*PS/(1.+ALPHA)                                     TAP 764
  DO 35 I=1,10                                         TAP 766
  DO 34 J=1,10                                         TAP 768
  A(I,J) = AM(I,J)                                     TAP 770
34 CONTINUE                                         TAP 772
35 CONTINUE                                         TAP 774
  CALL LIN2 (A,10,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC) TAP 776
  MA=2                                         TAP 778
  GO TO 20                                         TAP 780
C  CALCULATION FOR DELTA TEMPERATURE, TAPERED HUB
36 P=0.                                         TAP 782
  PS=0.                                         TAP 784
  DELT=DELT
C  PRINT 60                                         TAP 786
  DO 37 I=1,10                                         TAP 788
  B(I)=0.                                         TAP 790A
37 CONTINUE                                         TAP 792
  B(5) = (PO/XB)*(XB*AL*DELT)                         TAP 794
  DO 39 I=1,10                                         TAP 796
  DO 38 J=1,10                                         TAP 798
  A(I,J) = AM(I,J)                                     TAP 800
38 CONTINUE                                         TAP 802
39 CONTINUE                                         TAP 804
  CALL LIN2 (A,10,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC) TAP 806
  MA=3                                         TAP 808
  GO TO 20                                         TAP 810
C ** CARDS TAP816-864 DELETED 09-19-75.
C 44 PRINT 62                                         TAP 812
  40 CONTINUE                                         TAP 814
  GO TO (46,45,46,45), MATE
45 CALL FLGDW                                         TAP 866A
46 CONTINUE                                         TAP 866B
  GO TO (70,70,71,70,71,70), MATE
70 CALL COMBIN                                         TAP 866C
71 CONTINUE                                         TAP 868
72 RETURN                                         TAP 870
C
48 FORMAT (8E10.5)                                         TAP 872
49 FORMAT (84H FLANGE    FLANGE    FLANGE    PIPE    HUB A.    HUB AP 886
  1B      BOLT    PRESSURE, /84H O. D.,H    I. D.,S    THICK.,T    WATAP 888
  2LL,GO  BASE, G1    LENGTH, H    CIRCLE,C    P    )  TAP 884
50 FORMAT (7F10.5,1F10.3/)                                         TAP 886
51 FORMAT (5E10.5)                                         TAP 888
52 FORMAT (98H MOMENT COEFF. OF DELTA    MOD. OF MEAN GASKET ITTAP 890
  1YPE    1BOND  1CODE    MATE    /51H    THERMAL ETAP 892
  2XF.    ELASTICITY DIAMETER )  TAP 894
53 FORMAT (1P5L10.3,16,3I10//)
54 FORMAT (52H CALCULATIONS FOR MOMENT LOADING, TAPERED HUB FLANGE//) TAP 896
55 FORMAT (7H SLSU=1PE12.4,7H SLLI=1E12.4,7H SCSO=E12.4,7H SCSI=E1TAP 898
  12.4//7H SLLO=E12.4,7H SLLI=E12.4,7H SCLO=E12.4,7H SCLO=E12.4//TAP 900
  27H STH=E12.4,7H STF=E12.4,7H SAH=E12.4,7H SAH=E12.4//5H 2TAP 902
  3G=E12.4,5H ZG=E12.4,7H QFHG=E12.4,5H YC=E12.4,5H Y1=E12.4,8H TAP 904
  4THETA=E12.4//)                                         TAP 906
56 FORMAT (49H ASME FLANGE STRESSES AT OPERATING MOMENT, MOP //) TAP 908
57 FORMAT (11H (2/3)*SH=,1PE12.4,6H ST=,E12.4,6H SA=,E12.4,13H TAP 910
  1(SH+ST)/2=,E12.4,13H (SH+SR)/2=,E12.4//)  TAP 912
58 FORMAT (55H ASME FLANGE STRESSES AT GASKET SEATING MOMENT, MGS TAP 914
  1//)                                         TAP 916
59 FORMAT (34H CALCULATIONS FOR PRESSURE LOADING//) TAP 918
60 FORMAT (37H CALCULATIONS FOR TEMPERATURE LOADING//) TAP 920
61 FORMAT (34H CALCULATIONS FOR COMBINED LOADING//) TAP 922
62 FORMAT (1n1)                                         TAP 924
  END                                         TAP 926
                                         TAP 928

```

```

SUBROUTINE STHUB          S TH   2
C THIS CALCULATION IS FOR ITYPE = 2, STRAIGHT HUB FLANGES      S TH   4
IMPLICIT REAL*8 (A-H,C-Z)          01-28-75
DIMENSION A(10,10), B(10), ITEMP(10), LPR(10), AM(10,10) S TH   6
DIMENSION SB(6,18), SC(18)          S TH   6A
COMMON ITYPE,IBONL,ICCDE,MATE,XA,XB,G,C,PRESS,XGS,XOP,G1,GO,TH,YM,STH
1AE,QFHG(4),AL,DELT,AM,XMOA,QFHGP,QPHGP,THGP,BE,GO,THP,YPP,EPP,STH  8
2DELTAE,GOUT,GIN,RCG          S TH   10
3,SLSO,SLSI,SCSC,SCSI,SLIO,SILI,SCLO,SCLI,STH          S TH   12
4,STF,SRH,SEF,ZG,ZC,QFHG,YC,Y1,T1,THETA,SOFT,SGR,SGT,SCR,SCF,SAT  S TH   8A
5,W2,W1,SB,MA,IT,XM1,XM2,XM2F          S TH   8B
DATA A/100*0./,B/10*0./,ITEMP/10*0./,LPR/10*0./,AM/100*0./,STH   8C

C
1 READ 32, XA,XE,TH,GO,G1,HL,C,PRESS          S TH   14
PPINT 33          S TH   16
PRINT 34, XA,XB,TH,GO,G1,HL,C,PRESS          S TH   18
G=1.          S TH   20
YM=1.          S TH   22
IF (ICODE.GE.2) GO TO 2          S TH   24
READ 35, XMOA,EF,DELT,YM,G,ITYPE,IBONL,ICODE,MATE          S TH   26
PRINT 36          S TH   28
AL=EF          S TH   30
PRINT 37, XMOA,EF,DELT,YM,G,ITYPE,IBONL,ICODE,MATE          S TH   32
2 XA=XA/2.          S TH   34
XB=XB/2.          S TH   36
XK=AH/XB          S TH   38
XK2=XK*XK          S TH   40
G=G/2.          S TH   42
C=C/2.          S TH   44
BETA = 2.73**C.25/DSQRT(XB*GO)          S TH   46A
IF (IBOND-1) 3,4,4          S TH   48
3 U3=0.          S TH   50
U33=0.          S TH   52
U34=0.          S TH   54
GO TO 5          S TH   56
4 U3=(XB/YM)*((1.3*XK2+.7)/(XK2-1.))          S TH   58
U33=2.*U3*YM*(GO*BETA)**3/(TH*10.92)          S TH   60
U34=TH*BETA/2.          S TH   62
5 XT1=U34-U33          S TH   64
XT2=1.+U34+U33          S TH   66
PS=(.85*XB/(YM*GO))*PRESS          S TH   68
A(1,1)=XT1          S TH   70
A(1,2)=XT2          S TH   72
A(1,3)=0.          S TH   74
A(1,4)=0.          S TH   76
A(1,5)=0.          S TH   78
A(1,6)=0.          S TH   80
A(2,1)=BETA          S TH   82
A(2,2)=BETA          S TH   84
A(2,3) = -(2.0*XB*DLOG(XB)+XB)          S TH   86A
A(2,4)=-2.*XB          S TH   88
A(2,5)=-1./XB          S TH   90
A(2,6)=0.          S TH   92
A(3,1)=2.*BETA**2*(1.+BETA*TH/2.)          S TH   94
A(3,2)=-2.*BETA**3*TH/2.          S TH   96
A(3,3) = -(2.6*DLOG(XB)+3.3)*(TH/GO)**3          S TH   98A
A(3,4)=-2.6*(TH/GO)**3          S TH   100
A(3,5)=(.7/(XE*XB))*(TH/GO)**3          S TH   102
A(3,6)=0.          S TH   104
A(4,1)=0.          S TH   106
A(4,2)=0.          S TH   108
A(4,3) = XB*XB*DLOG(XB)          S TH   110A
A(4,4)=XB-XB          S TH   112
A(4,5) = DLOG(XB)          S TH   114A
A(4,6)=1.          S TH   116
A(5,1)=0.          S TH   118
A(5,2)=0.          S TH   120
A(5,3) = 2.6*DLOG(XA)+3.3          S TH   122A
A(5,4)=2.6          S TH   124

```

```

A (5,5)=-.7/(XA*XA)          S TH 126
A (5,6)=0.                     S TH 128
A (6,1)=0.                     S TH 130
A (6,2)=0.                     S TH 132
A (6,3)=1.                     S TH 134
A (6,4)=0.                     S TH 136
A (6,5)=0.                     S TH 138
A (6,6)=0.                     S TH 140
DO 7 I=1,6                     S TH 142
DO 6 J=1,6                     S TH 144
AM(I,J)=A(I,J)               S TH 146
o CONTINUE                      S TH 148
7 CONTINUE                      S TH 150
C CALCULATIONS FOR MOMENT LOADING, STRAIGHT HUB      S TH 152
P=0.                           S TH 154
PS=0.                          S TH 156
DLT=0.                         S TH 158
IF (ICODE-1) 8,8,9             S TH 160
8 XMO=XMOZ                     S TH 162
GO TO 10                        S TH 164
9 CALL ASMEIN                   S TH 166
XMO=XOP                        S TH 168
C 10 PRINT 38                   S TH 170A
10 CONTINUE                      S TH 170B
DO 11 I=1,6                     S TH 172
B(I)=0.                         S TH 174
11 CONTINUE                      S TH 176
B(6)=-2.73*XMC/(6.2832*YM*TH**3*(XA-XB))          S TH 178
CALL LIN2 (A,6,10,0.,B,1,10,LTEMP,IBLK,DET,NPIV,PIV,LPC,LPC) S TH 180
IP=0.                           S TH 182
MA=1.                           S TH 184
12 C5=B(1)                      S TH 186
C6=B(2)                        S TH 188
D1=B(3)                        S TH 190
D2=B(4)                        S TH 192
D3=B(5)                        S TH 194
D4=B(6)                        S TH 196
THETA=BT*B*(C5+C6)             S TH 198
THETA1=D1*(2.0*X*B*DLOG(XB)+XB)+2.0*EZ*X*B+D3/XB      S TH 200A
XHO=YM*(G0**3)*(BT*B**2)*C5/5.46                      S TH 202
PO=YM*G0**3*B*(C5+C6)/5.46                      S TH 204
YO=C6+X*B*PS                      S TH 206
SLSB=6.*XHO/(G0*G0)                      S TH 208
SLSO=-SLSB*P*X3/(2.*G0)                      S TH 210
SLSI=SLSO+P*X/E/(2.*G0)                      S TH 212
SCSO=.3*SLSO+YM*YO/XB                      S TH 214
SCSI=.3*SLSI+YM*YC/XB                      S TH 216
STM=-(YM*TH/1.82)*(2.0*EZ+0.7*D3/(XB*X*B)+D1*(2.6*DLOG(XB)+1.9)) S TH 218A
STM=((XK*XK+1.)/(XK*XK-1.))*(P-PO/TH)          S TH 220
S TH=STM+STM                      S TH 222
STM=-STM+STM                      S TH 224
SRB=-(YM*TH/1.82)*(2.0*EZ+0.7*D3/(XB*X*B)+D1*(2.6*DLOG(XB)+3.3)) S TH 226A
SRH=SRB-P*PC/TH                      S TH 228
SFR=-SRB-P*PC/TH                      S TH 230
ZG=D2*G*G+D3*DLOG(G)+D4*D1*(G*G*DLOG(G))          S TH 232A
ZC=D2*C*C+D3*DLOG(C)+D4*D1*(C*C*DLOG(C))          S TH 234A
QFHG=-ZC*ZG                      S TH 236
QFHG(MA)=QFHG                      S TH 238
IF (ICCL=2) 13,14,14                      S TH 240
C 13 PRINT 39, ETC, ETC.                  S TH 242A
13 CALL STORE                      S TH 242B
GO TO 15                        S TH 244
14 SLM=.66667*SLSO                  S TH 246
COT=(SLSO+STH)/2.                  S TH 248
COR=(SLSO+SRH)/2.                  S TH 250
PAINT 40                        S TH 252
PAINT 41, SLM,STH,SRH,COT,CCR      S TH 254
PAINT 42                        S TH 256
SLM=SLSO*RCG                      S TH 258
STH=STH*RCG                      S TH 260

```

S RH=S RH*ROG	STH	262
COT=C OT*ROG	STH	264
COR=CR*ROG	STH.	266
PRINT 41, SLM,STH,SRH,COT,COR	STH	268
PRINT 46	STH	270
GO TO 31	STH	272
15 IP=IP+1	STH	274
C GO TO (16,20,24,28),IP	STH	276A
C GO TO (16,20,24),IP	STH	276 B
C CALCULATIONS FOR PRESSURE ICADING, STRAIGHT HUB	STH	278
16 XMO=0.	STH	280
DELT=0.	STH	282
P=PRESS	STH	284
PS=(.85*XB/(YM*GO))*P	STH	286
C PRINT 43	STH	288A
DO 17 I=1,6	STH	290
B(I)=0.	STH	292
17 CONTINUE	STH	294
B(1)=+XB*PS+XE*AL*DELT-U3*PRESS	STH	296
DO 19 I=1,6	STH	298
DO 18 J=1,6	STH	300
A(I,J)=AM(I,J)	STH	302
18 CONTINUE	STH	304
19 CONTINUE	STH	306
CALL LIN2 (A,6,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC)	STH	308
MA=2	STH	310
GO TO 12	STH	312
C CALCULATIONS FOR DELTA TEMPERATURE LOADING, STRAIGHT HUB	STH	314
20 P=0.	STH	316
PS=0.	STH	318
DELT=DELTA	STH	320
C PRINT 44	STH	322A
DO 21 I=1,6	STH	324
B(I)=0.	STH	326
21 CONTINUE	STH	328
B(1)=XB*A I*DELT	STH	330
DO 23 I=1,6	STH	332
DO 22 J=1,6	STH	334
A(I,J)=AM(I,J)	STH	336
22 CONTINUE	STH	338
23 CONTINUE	STH	340
CALL LIN2 (A,6,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPA,LPC)	STH	342
MA=3	STH	344
GO TO 12	STH	346
C ** DELETED CARDS STH348-384 OF SUBR. STHUE 09-19-75.		
C 28 PRINT 46	STH	386A
24 CONTINUE	STH	386 B
GO TO (30,29,30,29,30,29), MATE	STH	388
29 CALL FLGDW	STH	390
30 CONTINUE	STH	392
GO TO (70,70,71,70,71,70),MATE	STH	392A
70 CALL COMBIN	STH	392B
71 CONTINUE	STH	392C
31 RETURN	STH	394
C	STH	396
32 FORMAT (8E10.5)	STH	398
33 FORMAT (84H FLANGE FLANGE FLANGE PIPE HUB AT HUSTH	STH	400
1B BOLT PRESSURE, /84H O. E., A I. D., B THICK., T WASTH	STH	402
2LL, GO BASE, G1 LENGTH, H CIRCLE, C P)	STH	404
34 FORMAT (7F10.5, 1F10.3/)	STH	406
35 FORMAT (5E10.5)	STH	408
36 FORMAT (98H MOMENT COEFF. OF DELTA MOD. OF MEAN GASKET ITS TH	STH	410
1TYPE IBOND ICODE MATE /51H THERMAL ESTH	STH	412
2XP. ELASTICITY DIAMETER)	STH	414
37 FORMAT (1P5E10.3, 16,3I10//)	STH	416
38 FORMAT (53H CALCULATIONS FCF MOMENT LOADING, STRAIGHT HUB FLANGE//STH	STH	418
1)	STH	420
39 FORMAT (7H SLSO=1PE12.4, 7H SLSI=E12.4, 7H SCSO=E12.4, 7H SCSI=E1STH	STH	422
12.4//7H STH=E12.4, 7H STF=E12.4, 7H SRH=E12.4, 7H SRF=E12.4//STH	STH	424
25H ZG=E12.4, 5H ZC=E12.4, 7H QPHG=E12.4, 5H YO=E12.4, 8H THETA=E1STH	STH	426

32.4/)

40 FORMAT (49H ASM E FLANGE STRESSES AT OPERATING MOMENT, MOP //) S TH 428
 41 FORMAT (11H (2/3)*SH=, E12.4,6H ST =, E12.4,6H SR =, E12.4,13H S TH 430
 1(SH+ST)/2=, E12.4,13H (SH+SR)/2=, E12.4///) S TH 432
 42 FORMAT (55H ASM E FLANGE STRESSES AT GASKET SEATING MOMENT, MGS S TH 434
 1//) S TH 436
 43 FORMAT (34H CALCULATIONS FOR PRESSURE LOADING//) S TH 438
 44 FORMAT (37H CALCULATIONS FOR TEMPERATURE LOADING//) S TH 440
 45 FORMAT (34H CALCULATIONS FOR COMBINED LOADING//) S TH 442
 46 FORMAT (1H1) S TH 444
 END S TH 446
 S TH 448

C SUBROUTINE BLIND BLI 2
 THIS CALCULATION IS FOR ITYPE = 3, BLIND FLANGES BLI 4
 IMPLICIT REAL*8 (A-B,O-Z) 0- 28-75
 DIMENSION A(10,10), B(10), LTEMP(10), LPR(10), LPC(10), AM(10,10) BII 6
 DIMENSION SB(6,18), SC(18) BLI 6A
 COMMON ITYPE, ICOND, ICODE, MATE, XA, XB, G, C, PRESS, XGS, XOP, G1, GO, TH, YM, BII 8
 TAB, QFHGP(4), AL, DELTA, XMO, XMCA, QFHGP, QFEGP, QTHGP, BP, GUP, THP, YFP, EFP, BII 10
 2DELTAP, GOUT, GIN, FCG BII 12
 3, SLSO, SLSI, SCSO, SCSI, SLL0, SLL1, SCLO, SCLI, STH BII 12A
 4, STF, STH, SFF, ZG, ZC, QFHGP, Y0, Y1, F1, THETA, SOFT, SGR, SGT, SCR, SCT, SAT BII 12B
 5, W2, W1, SB, MA, IT, XM1, XM2, XM2P BII 12C
 DATA A/100*0./, B/10*0./, LTEMP/10*0./, LPR/10*0./, LPC/10*0./, AM/100*0./

C

1 READ 17, XA, XB, TH, GO, G1, HL, C, PRESS BLI 14
 PRINT 18 BLI 16
 PRINT 19, XA, XB, TH, GO, G1, HL, C, PRESS BLI 18
 G=1. BLI 20
 YM=1. BLI 22
 IF (ICODE.GE. 2) GO TO 15 BLI 24
 READ 20, XMCA, EF, DELTA, YM, G BLI 26
 PRINT 21 BLI 28
 AL=EF BLI 30
 PRINT 22, XMOA, EF, DELTA, YM, G, ITYPE, ICOND, ICODE, MATE BLI 32
 D=YM*TH**3/10.92 BLI 34
 XA=XA/2. BLI 36
 C=C/2. BLI 38
 G=G/2. BLI 40
 A(1,1)=G*G BLI 42
 A(1,2)=1. BLI 44
 A(1,3)=0. BLI 46
 A(1,4)=0. BLI 48
 A(1,5)=0. BLI 50
 A(1,6)=0. BLI 52
 A(1,7)=0. BLI 54
 A(1,8)=0. BLI 56
 A(1,9)=0. BLI 58
 A(2,1)=-2.*G BLI 60
 A(2,2)=0. BLI 62
 A(2,3) = 2.0*G*DLCG(G)+G BLI 64A
 A(2,4)=2.*G BLI 66
 A(2,5)=1./G BLI 68
 A(2,6)=0. BLI 70
 A(2,7)=0. BLI 72
 A(2,8)=0. BLI 74
 A(2,9)=0. BLI 76
 A(3,1)=0. BLI 78
 A(3,2)=0. BLI 80

A (3,3) = 1.	BLI	82
A (3,4) = 0.	BLI	84
A (3,5) = 0.	BLI	86
A (3,6) = 0.	BLI	88
A (3,7) = 0.	BLI	90
A (3,8) = 0.	BLI	92
A (3,9) = 0.	BLI	94
A (4,1) = 0.	BLI	96
A (4,2) = 0.	BLI	98
A (4,3) = G* G*DLOG (G)	BLI	100A
A (4,4) = G* G	BLI	102
A (4,5) = DLOG (G)	BLI	104A
A (4,6) = 1.	BLI	106
A (4,7) = 0.	BLI	108
A (4,8) = 0.	BLI	110
A (4,9) = 0.	BLI	112
A (5,1) = -2.6	BLI	114
A (5,2) = 0.	BLI	116
A (5,3) = 2.6*DLOG (G) + 3.3	BLI	118A
A (5,4) = 2.6	BLI	120
A (5,5) = -7/(G*G)	BLI	122
A (5,6) = 0.	BLI	124
A (5,7) = 0.	BLI	126
A (5,8) = 0.	BLI	128
A (5,9) = 0.	BLI	130
A (6,1) = 0.	BLI	132
A (6,2) = 0.	BLI	134
A (6,3) = 2.0*C*DLOG (C) + C	BLI	136A
A (6,4) = 2.*C	BLI	138
A (6,5) = 1./C	BLI	140
A (6,6) = 0.	BLI	142
A (6,7) = -2.*C	BLI	144
A (6,8) = -1./C	BLI	146
A (7,4) = 2.6	BLI	156
A (7,8) = -7/(C*C)	BLI	164
A (6,9) = 0.	BLI	148
A (7,1) = 0.	BLI	150
A (7,2) = 0.	BLI	152
A (7,3) = 2.6*DLOG (C) + 3.3	BLI	154A
A (7,5) = -7/(C*C)	BLI	158
A (7,6) = 0.	BLI	160
A (7,7) = -2.6	BLI	162
A (7,9) = 0.	BLI	166
A (8,1) = 0.	BLI	168
A (8,2) = 0.	BLI	170
A (8,3) = 0.	BLI	172
A (8,4) = 0.	BLI	174
A (8,5) = 0.	BLI	176
A (8,6) = 0.	BLI	178
A (8,7) = 2.6	BLI	180
A (8,8) = -7/(X A*X A)	BLI	182
A (8,9) = 0.	BLI	184
A (9,1) = 0.	BLI	186
A (9,2) = 0.	BLI	188
A (9,3) = C*C*DLOG (C)	BLI	190A
A (9,4) = C*C	BLI	192
A (9,5) = DLOG (C)	BLI	194A
A (9,6) = 1.	BLI	196
A (9,7) = -C*C	BLI	198
A (9,8) = -DLOG (C)	BLI	200A
A (9,9) = -1.	BLI	202
DO 3 I=1,9	BLI	204
DO 2 J=1,9	BLI	206
AM(I,J)=A(I,J)	BLI	208
2 CONTINUE	BLI	210
3 CONTINUE	BLI	212
C CALCULATION FOR MOMENT LOADING, BLINE FLANGES	BLI	214
MA = 1	BLI	215A
P=0.	BLI	216
W=XMOA	BLI	218

```

C PRINT 23
DO 4 I=1,9
B(I)=0.
4 CONTINUE
B(3)=-W/(25.1328*I)
CALL LIN2 (A,9,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPR,LPC)
IP=0
5 ZC = C*C*B(7) +DLOG(C)*B(8)+B(9)
QFHR(IP+1)=ZC
SORT=-(YM*TH/1.82)*2.6*B(1)
SGR=-(YM*TH/1.82)*(2.6*B(1)+G*G*2*3.3/(16.*D))
SGT=-(YM*TH/1.82)*(2.6*B(1)+G*G*1.9*P/(16.*D))
SCR=-(YM*TH/1.82)*(2.6*B(7)-.7*B(8)/(C*C))
SCT=-(YM*TH/1.82)*(2.6*B(7)+.7*B(8)/(C*C))
SAT=-(YM*TH/1.82)*(2.6*B(7)+.7*B(8)/(XA*X A))
C PRINT 24, FTC, FTC.
IP=IP+1
CALL STCPE
C GO TO ( 6,10,14 ),IP
GO TO ( 6,10 ),IP
C CALCULATION FOR PRESSURE LOADING, BLIND FLANGES
6 P=PRESS
MA = 2
W=0.
C PRINT 25
DO 7 I=1,9
B(I)=0.
7 CONTINUE
B(1)=G**4*P/(64.*I)
B(2)=-G**3*P/(16.*D)
B(5)=-G*G*P*3.3/(16.*D)
DO 9 I=1,9
DO 8 J=1,9
A(I,J)=AM(I,J)
8 CONTINUE
9 CONTINUE
CALL LIN2 (A,9,10,0.,B,1,10,LTEMP,IERR,DET,NPIV,PIV,LPR,LPC)
GO TO 5
C ** DELETED CARDS EL1290-322 OF SUBR. ELINE, 09-19-75.
C 14 CONTINUE
10 CONTINUE
IF( MATE.EQ.1 ) CALL COMBIN
IF( CODE=1 ) 16,16,15
15 C=C/2.
CALL ASMEIN
C FLGDW IS CALLED THRU TAPHUE OR STHUB, 2ND TIME THRU
PRINT 27
16 CONTINUE
RETURN
C
17 FORMAT (8E10.5)
18 FORMAT (84H FLANGE FLANGE FLANGE PIPE HUB AT HUBLI 342
18 BOLT PRESSURE, /84H O.D.,A I.D.,B THICK.,T WABLI 344
2LL,GO BASE,G1 LENGTH,H CIRCLE,C P )
19 FORMAT (7F10.5,1F10.3/)
20 FORMAT (5E10.5)
21 FORMAT (98H EOLT COEFF. OF DELTA MOD. OF MEAN GASKET ITBLI 352
1TYPE IBOND ICCDE MATE /
2 51H LOAD THERMAL EXP. ELASTICITY DIAMETER )BLI 356
22 FORMAT (1F5E10.3,16,3I10//)
23 FORMAT (46H CALCULATIONS FOR BOLT LOADING, ELINE FLANGE//)
24 FORMAT (7H SORT=1F12.4,7H SGA=E12.4,7H SGT=E12.4,7H SCR=E1BLI 362
12.4,7H SCT=E12.4,7H SAT=E12.4//9H ZC=E12.4//)
25 FORMAT (34H CALCULATIONS FOR PRESSURE LOADING//)
26 FORMAT (34H CALCULATIONS FOR COMBINED LOADING//)
27 FORMAT (1H1)
END

```

```

SUBROUTINE ASPEIN
IMPLICIT REAL*8 (A-H,O-Z)
DIMENSION SS(6,18),SI(18)
COMMON ITYPE,IBCNL,ICCDL,MATE,XA,XB,G,C,PRESS,XGS,XOP,G1,G0,TH,YM,ASM
1AE,QFHG(4),AL,DELT,A,XMO,XMOA,QPHGP,QPHGF,QTHGP,BP,GOP,THP,YFP,EFP,ASM
2DELTAP,GOUT,GIN,RCG
3,SLSO,SLSI,SCSO,SCSI,SLLO,SLLI,SCLO,SCLI,STH
4,STF,SRH,SFF,2G,ZC,QPHG,Y0,Y1,T1,THTA,SOF,SGP,SGP,SGT,SGT,SAT
5,W2,W1,SS,MA,IP,XM1,XM2,XM2P
C
      READ 10, XM,Y,GOUT,GIN,SB,SA,AB,INBO,BO
      PRINT 11
      PRINT 12
      PRINT 13, XM,Y,GOUT,GIN,SB,SA,AB
      XA=XA*2.
      XB=XB*2.
      C=C*2.
      IF (INBO-1) 1,1,2
1  BO=(GOUT-GIN)/4.
2  IF (BO-.25) 3,3,4
      D = GASKET DIAMETER IN THIS SUBROUTINE
3  D=(GOUT+GIN)/2.
      B=BO
      GO TO 5
4  B = DSQR2(B0)/2.0
      D=GOUT-2.*B
5  P=PRESS
      WM11=.7854*D*D*E
      WM12=6.2832*B*D*X*B*2
      WM1=.7854*D*D*P+6.2832*B*D*XM*P
      SB1=WM1/AB
      WM2=3.1416*B*D*Y
      SB2=WM2/AB
      AM1=WM1/SB
      AM2=WM2/SB
      AM = DMAX1(AM1,AM2)
      WGS=(AM+AB)*SA/2.
      XGS=WGS*(C-D)/2.
      XGS1=WM2*(C-D)/2.
      R=(C-XE)/2.-G1
      H=WM11
      HD=.7854*XB*XB*E
      HT=H-HD
      HG=WM1-H
      XD=(R+.5*G1)*HD
      XT=((R+G1+(C-D)/2.)/2.)*HT
      XG=((C-D)/2.)*HG
      XOP=XD+XT+XG
      ROG=XGS/XOP
      PRINT 14
      PRINT 15, BO,WM11,WM12,WM1,SB1,WM2,SB2
      IF (ITYPE-2) 6,6,7
6  PRINT 16
      PRINT 17, XOP,XGS,XGS1
      IN PBINI OUT, MCP=XOP, MGS=XGS, MGS1=XGS1
C
7  IF (ITYPE-2) 9,9,8
8  SP=((D/TH)**2)*(3*E)
      SW1=((D/TH)**2)*(1.78*WM1*(C-D)/2.)/(D**3)
      SOP=SP+SW1
      SW2=((D/TH)**2)*(1.78*WM2*(C-D)/2.)/(D**3)
      SGS=((D/TH)**2)*(1.78*WGS*(C-D)/2.)/(D**3)
      PRINT 18
      PRINT 19
      PRINT 20, SP,SW1,SOP,SW2,SGS
9  XA=XA/2.
      XB=XB/2.
      C=C/2.
      RETURN
C
10 FORMAT (7E10.5,112,1E8.5)

```

11	FORMAT (1H0)					ASM	130
12	FORMAT (108H)	M	Y	GOUT)	A SM	132
13	1 GIN	SB	SA	AB)	A SM	134
14	FORMAT (7F15.5//)	BC	WM11	WM12)	ASM	136
15	FORMAT (1I7E15.4//)	SB1	WM2	SB2)	WA SM	138
16	FORMAT (50H)	MOE	MGS	MGS1)	A SM	140
17	FORMAT (1P3E15.4//)					ASM	142
18	FORMAT (+7H)	ASME	CCDE STRESSES FOR BLIND FLANGE //)			A SM	148
19	FORMAT (100H)	SP	SW1	SOP)	SA SM	150
20	1W2	SGS				A SM	152
	FORMAT (1P5E15.4//)	END				A SM	154
						A SM	156

SUBROUTINE FLGDW		FLG	2
C	THIS SUBROUTINE IS CALLED ONLY IF MATE = 2,4,6	FLG	4
	IMPLICIT REAL*8 (A-H,C-Z)	0 1-28-75	
	DIMENSION SB(6,18),SC(18)	FLG	4A
	COMMON ITYPE, IONL, ICODE, MATE, XA, XB, G, C, PRESS, XGS, AOP, G1, G2, TH, YM, FLG	FLG	6
	1AB, QFHP(4), A1, DELTA, XMCA, QFHGP, QFEGP, QT HGP, BF, G0P, THP, YFP, ZFP	FLG	8
	2DELTAP, GOUT, GIN, RCG	FLG	10A
	3, SLSO, SLSI, SCSO, SCSI, SLL0, SLL1, SCLO, SCLI, STH	FLG	10B
	4, STF, SH, SRF, ZG, ZC, QFHG, Y0, Y1, T1, THETA, SOFT, SGA, SGP, SCR, SCT, SAT	FLG	10C
	5, W2, W1, SB, MA, IT, XM1, XM2, XM2P	FLG	10D
C	R FAD 21, BSIZE, YB, EB, TB, XGO, XGI, AB, VO, YG, EG, TG, FACE, PSE, W1, IF, TFP, FIG	FLG	12
	1YF2, YFP2, YB2, YG2	FLG	14
	PRINT 22	FLG	16
	PRINT 25, BSIZE, YB, TB, XGO, XGI, AB	FLG	18
	PRINT 23	FLG	20
	PRINT 26, VO, YG, EG, TG, FACE, PSE	FLG	22
	PRINT 24	FLG	24
	PRINT 27, W1, IF, TFP, YF2, YFP2, YB2, YG2	FLG	26
	C=2.*C	FLG	28
	GO TO (1,1,20,2,20,2), MATE	FLG	30
1	QFHR(1)=QFHR(1)/XPCA	FLG	32
	QFHR(2)=QFHR(2)/PRESS	FLG	34
	QFHR(3)=QFHR(3)/DELT	FLG	36
	QFHGP=QFHR(1)	FLG	38
	QFHG=QFHGP	FLG	40
	QPHGP=QFHR(2)	FLG	42
	QFHG=QPHGP	FLG	44
	QTHGP=QFHR(3)	FLG	46
	QTHG=QTHGP	FLG	48
	BP=XB*2.	FLG	50
	B=BP	FLG	52
	G0P=G0	FLG	54
	THP=TH	FLG	56
	YFP=YM	FLG	58
	YF=YFP	FLG	60
	EFP=AL	FLG	62
	EF=EFP	FLG	64
	DELTAP=DELT	FLG	66
	XLB=2.*TH+VO+FACE+BSIZE	FLG	68
	TFP=TF	FLG	70
	YFP2=YF2	FLG	72
	GO TO 3	FLG	74
2	QFHG=QFHR(1)/XMCA	FLG	76

```

QPHG=QFHP (2) / ERESS          FLG  78
QTHG=QFHG (3) / DELTA          FLG  80
3 =XB*2.                         FLG  82
Y F=YM                           FLG  84
3F=AL                           FLG  86
XLB=THE+TH+VC+FAC E+BSIZE     FLG  88
3 P=PESS                          FLG  90
QB1=XLB/(AB*YB)                 FLG  92
QB2=XLE/(AB*Y E2)               FLG  94
G=(XGO+XGI)/2.                  FLG  96
AG=(XGO-XGI)*1.5708*G          FLG  98
QG1=VO/(AG*YG)                 FLG 100
QG2=VO/(AG*YG2)                 FLG 102
HG=(C-G)/2.                      FLG 104
QF1=QFHG/HG                      FLG 106
QF2=QF1*(YF/YF2)                 FLG 108
IF (MATE-5) 5,5,4                FLG 110
4 QFP1=QFHG/(HG*HG)              FLG 112
GO TO 6                           FLG 114
5 QFP1=QFHG P/HG                 FLG 116
6 QFP2=QF1*(YFF/YFF2)            FLG 118
Q1=QB1+QG1+HG*HG*(QF1+QFP1)      FLG 120
Q2=QB2+QG2+HG*HG*(QF2+QFP2)      FLG 122
HT=(C-(G+B)/2.)/2.                FLG 124
HTP=(C-(G+B P)/2.)/2.              FLG 126
HD=(C-B-G 0)/2.                  FLG 128
HDP=(C-EP-G0P)/2.                 FLG 130
COFAL=.7854*HG/C1                 FLG 132
W2A=W1+(1./Q1)*(-TB*EE*XLB+TG*EG*VC+TF*FF*TH+TFP*EFP*TDP)  FLG 134
IF (MATE-5) 8,8,7                FLG 136
7 W2B=W1+COFAL*((QG1/HG-QF1*(HT-HG))*G*G-QF1*B*B*(HD-HT))*P  FLG 138
GO TO 9                           FLG 140
8 W2B=W1+COFAL*((QG1/HG-QF1*(HT-HG)-QFP1*(HTP-HG))*G*G-(QF1*B*B*(HD-FLG 142
1HT)+QF1*B*BP*(HIE-HTP)))*(P+PBE)  FLG 144
9 W2C=W2B-(QPHG/HG+QPHGP/HG)*P*HG/Q1  FLG 146
IF (MATE-5) 11,11,10               FLG 148
10 W2D=W1-(QTHG/HG)*DELT A*HG/C1  FLG 150
GO TO 12                           FLG 152
11 W2D=W1-(QTHG*DELT A+QTHGP*DELT AP)/C1  FLG 154
12 IF (MATE-5) 14,14,13               FLG 156
13 W2=(Q1/Q2)*W1+(1./Q2)*(-TB*EB*XLB+IG*EG*VC+TF*EF*TH+TFP*EFP*TDP)+(FLG 158
1Q1/Q2)*COFAL*((QG2/HG-QF2*(HT-HG))*G*G-QF2*B*B*(HD-FLG 160
2G)*(YF/YF2)+(QPHGP/HG)*(YFP/YFP2))*P*HG/Q2-(QTHG/HG)*(YF/YF2)*DELTFLG 162
3A*HG/Q2                           FLG 164
GO TO 15                           FLG 166
14 W2=(Q1/Q2)*W1+(1./Q2)*(-TB*EB*XLB+IG*EG*VC+TF*EF*TH+TFP*EFP*TDP)+(FLG 168
1Q1/Q2)*COFAL*((QG2/HG-QF2*(HT-HG)-QFP2*(HTP-HG))*G*G-(QF2*B*B*(HD-FLG 170
2HT)+QF2*BP*BP*(HIE-HTP)))*(P+PBE)-((QPHG/HG)*(YF/YF2)+(QPHGP/HG)*P*FLG 172
3(YFP/YFP2))*P*HG/Q2-(QTHG*DELT A*(YF/YF2)+QTHGP*DELTAP*(YF/YF2))/FLG 174
4Q2                                FLG 176
15 GO TO (20,16,20,17,20,18), MATE  FLG 178
16 PRINT 28                          FLG 180
GO TO 19                           FLG 182
17 PRINT 29                          FLG 184
GO TO 19                           FLG 186
18 PRINT 30                          FLG 188
19 PRINT 31                          FLG 190
PRINT 32, QPHG, QHGE, QTHGP, BP, GO P, THP, YFF, YFP2, EFP  FLG 192
PRINT 33                          FLG 194
PRINT 32, QFHG, QF1, QTHG, E, GO, TH, YF, YF2, EF  FLG 196
PRINT 34                          FLG 198
PRINT 35, XLB, AB, C, YB, YF2, EB  FLG 200
PRINT 36                          FLG 202
PRINT 37, VO, XGO, XGI, YG, YG2, EG  FLG 204
PRINT 46                          FLG 204A
PRINT 38                          FLG 206
PRINT 39, W1, IB, TF, TFP, TG, DELTA, DELTAP, P  FLG 208
PRINT 40                          FLG 210
PRINT 41, W2A, W2B, W2C, W2D, W2  FLG 212
DWA=W1-W2A                         FLG 214

```

```

DWB=W1-W2B          FLG 216
DWC=W1-W2C          FLG 218
DWD=W1-W2D          FLG 220
DWCO=W1-W2          FLG 222
PRINT 42, DWA,DWB,DWC,DWD,EWCO  FLG 224
RA=W2A/W1            FLG 226
RB=W2B/W1            FLG 228
RC=W2C/W1            FLG 230
RD=W2D/W1            FLG 232
RCO=W2/W1            FLG 234
PRINT 43, RA,FB,AC,RD,RCC  FLG 236
PRINT 47            FLG 236A
47 FORMAT(//6X,'INITIAL AND RESIDUAL MOMENTS AFTER THERMAL PRESSURE',FLG 236B
F,' LOADS.' /)      FLG 236C
XM1=W1*HG            FLG 238
XM2A=W2A*HG          FLG 240
XM2B=W2B*HG+.7854*P*(B*B*HD+(G*G-B*B)*HT-G*G*HG)  FLG 242
XM2C=W2C*HG+.7854*P*(B*B*HD+(G*G-B*B)*HT-G*G*HG)  FLG 244
XM2D=W2D*HG          FLG 246
XM2=W2*HG+.7854*P*(B*B*HD+(G*G-B*B)*HT-G*G*HG)  FLG 248
PRINT 44, XM1,XM2A,XM2B,XM2C,XM2D,XM2  FLG 250
XM2BP=W2B*HG+.7854*P*(B*BP*HP+(G*G-EP*BP)*HTP-G*G*HG)  FLG 252
XM2CP=W2C*HG+.7854*P*(B*BP*HP+(G*G-EP*BP)*HTP-G*G*HG)  FLG 254
XM2P=W2*HG+.7854*P*(B*BP*HP+(G*G-EP*BP)*HTP-G*G*HG)  FLG 256
PRINT 45, XM2EP,XM2CP,XM2P  FLG 258
C PRINT 30,QE1,QE2,G,AG,QG1,QG2,HG,QF1,QF2,QFP1,QFP2,Q1,Q2,  FLG 260
C 1 HT, HTP, HD, HP, CCFAL  FLG 262
C 30 FORMAT(//10E12.4//8E12.4)  FLG 264
C 20 PRINT 46            FLG 266A
C 20 CONTINUE          FLG 266B
C RETURN              FLG 268
C
21 FORMAT(7E10.5/6E10.5/7E10.5)  FLG 270
22 FORMAT(106H      BSIZE      Y3      EB      )  TFLG 274
 1B      XGO      XGI      AB      )  FLG 276
23 FORMAT(106H      VO      YG      EG      )  TFLG 278
 1G      FACE      FBE      )  FLG 280
24 FORMAT(106H      W1      TF      TFP      )  YFFLG 282
 12      YFP2      YB2      YG2      )  FLG 284
25 FORMAT(1P7E15.4)  FLG 286
26 FORMAT(1E6E15.4)  FLG 288
27 FORMAT(1P7E15.4//)  FLG 290
28 FORMAT(80H      FLANGE JCINT BOLT LOAD CHANGE DUE TO APPLIED LOADFLG 292
 1S, IDENTICAL PAIR //)  FLG 294
29 FORMAT(82H      FLANGE JCINT BOLT LOAD CHANGE DUE TO APPLIED LOADFLG 296
 1S, INTEGER TO INTEGER PAIR //)  FLG 298
30 FORMAT(80H      FLANGE JOINT BOLT LOAD CHANGE DUE TO APPLIED LOADFLG 300
 1S, BLIND TO INTEGER PAIR //)  FLG 302
31 FORMAT(54H      FLANGE JOINT SIDE ONE (PRIMED QUANTITIES)  /FLG 304
 1)  FLG 306
32 FORMAT(7H      QFHG=1PE12.4,7H      QPHG=E12.4,7H      XB =E1FLG 308
 12.4,9H      GO=E12.4,12H      TH =E12.4/12H      YM =E12.4,14HFLG 310
 2      YF2 =E12.4,8H      FF =E12.4/)  FLG 312
33 FORMAT(54H      FLANGE JOINT SIDE TWO (UNPRIMED QUANTITIES)  /FLG 314
 1)  FLG 316
34 FORMAT(17H      ECLTING/)  FLG 318
35 FORMAT(14H      BOLT LENGTH=1PE12.4,12H      BOLT AREA=E12.4,14H      BOLT CIFLG 320
 1ECL=12.4/12H      YB =E12.4,13H      YB2 =E12.4,8H      EB =E1FLG 322
 22.4/)  FLG 324
36 FORMAT(16H      GASKET/)  FLG 326
37 FORMAT(9H      VC =1PE12.4,7H      XGO =E12.4,7H      XGI =E12.4/12H  FLG 328
 1      YG =E12.4,13H      YG2 =E12.4,8H      EG =E12.4/)  FLG 330
38 FORMAT(18H      ICADINGS/)  FLG 332
39 FORMAT(20H      INITIAL BOLT LOAD=1PE12.4,13H      BOLT TEMP.=E12.4,20H  FLG 334
 1      FLANGE ONE TEMP.=E12.4,20H      FLANGE TWO TEMP.=E12.4/15H      GASKET TFLG 336
 2      TEMP.=E12.4,9H      DELTA=E12.4,10H      DELTAT=E12.4,11H      PRESSURE=E12.4FLG 338
 3/)  FLG 340
40 FORMAT(53H      RESIDUAL BOLT LOADS AFTER THERMAL-PRESSURE LOADS/)FLG 342
41 FORMAT(20H      AXIAL THERMAL,W2A=1PE12.4,19H      MOMENT SHIFT,W2B=E12.4FLG 344
 1//21H      TOTAL PRESSURE,W2C=E12.4,21H      DELTA THERMAL,W2D=E12.4//14HFLG 346

```

```

2 COMBINED, W2=E12.4) F LG 348
42 FORMAT (//9H W1-W2A=1PE12.4,9H W1-W2B=E12.4,9H W1-W2C=E12.4,9H F LG 350
1 W1-W2D=E12.4,9H W1-W2= E12.4) F LG 352
43 FORMAT (//9H W2A/W1=1EE12.4,9H W2B/W1=E12.4,9H W2C/W1=E12.4,9H F LG 354
1W2D/W1=E12.4,,8F W2/W1=E12.4) F LG 356
44 FORMAT (//5H F1=1EE12.4,6H M2A=E12.4,6H M2B=E12.4,6H M2C=E12.4, F LG 358
16H M2D=E12.4,5H M2=E12.4) F LG 360
45 FORMAT (//7H M2BP=1PE12.4,7H M2CP=E12.4,6H M2D=E12.4) F LG 362
46 FORMAT (1H1) F LG 364
END F LG 366

```

```

SUBROUTINE LIN2(A,N,NN,EPS,B,M,MM,LTEMP,IERR,NPIV,PIV,LPR, 3 046 A00 1
1 LIC) 8 046 A00 2
IMPLICIT REAL*8 (A-H,O-Z) LIN2 02A
DIMENSION A(NN,N),B(MM,M) 3 046 A00 3
DIMENSION LTEMP(1),LPR(1),IEC(1) 8 C46A C04
C 8 046 A00 5
C SUBROUTINE LIN2 3 046 A00 6
C DECK 8046A 8 C46A C07
C 8 046 A00 8
C SUBROUTINES CALLED - NCNE 8 C46A C09
C 8 046 A010
C THIS ROUTINE SOLVES THE MATRIX EQUATION AX+B=C OVERWRITING B WITH THE 3 046 A011
C SOLUTION MATRIX X. A MUST BE SQUARE AND NON-SINGULAR. B MUST 8 046 A012
C HAVE THE SAME NUMBER OF ROWS AS A. THE DETERMINANT OF A IS 3 046 A013
C COMPUTED. BOTH A AND E ARE DESTROYED. 8 046 A014
8 C46A C15
C THIS ROUTINE IS RECOMMENDED FOR THE SOLUTION OF SIMULTANEOUS LINEAR 3 046 A016
C EQUATIONS. 8 046 A017
8 046 A018
C THE METHOD CONSISTS OF GAUSSIAN ELIMINATION FOLLOWED BY BACK 3 046 A019
C SUBSTITUTIONS. THIS IS MORE EFFICIENT THAN SOLUTION BY MATRIX 8 C46A C020
C INVERSION REGARDLESS OF THE NUMBER OF COLUMNS IN B. BOTH ROWS AND 3 046 A021
C COLUMNS ARE SEARCHED FOR MAXIMAL PIVOTS. INTERCHANGING OF ROWS OR 8 046 A022
C COLUMNS OF A IS AVOIDED. CHAPTER 1 OF E.L. STIEFLE, INTRODUCTION TO 8 C46A C23
C NUMERICAL MATHEMATICS, ACADEMIC PRESS, N.Y., 1963, SHOULD BE HELPFUL IN 8 046 A024
C FOLLOWING THE CODE. 8 046 A025
8 046 A026
C THE CALLING PROGRAM MUST SET A,N,NN,EPS,B,M,MM,LTEMP TO- 3 046 A027
C 8 046 A028
C A-THE COEFFICIENT MATRIX 3 046 A029
C 8 046 A030
C N-THE ORDER OF A 3 046 A031
C 8 046 A032
C NN-THE NUMBER OF WORDS OF STORAGE PROVIDED FOR EACH COLUMN OF 3 046 A033
C A IN THE CALLING PROGRAM 3 046 A034
8 C46A C35
C EPS-A NON-NEGATIVE NUMBER WHICH EACH PIVOT IN THE ELIMINATION 3 046 A036
C PROCESS IS REQUIRED TO EXCEED IN ABSOLUTE VALUE (CUSTOMARILY 8 046 A037
C ZERO) 8 C46A C38
8 046 A039
C B-THE CONSTANT TERM MATRIX 3 046 A040
C 8 046 A041
C M-THE NUMBER OF COLUMNS OF B 3 046 A042
C 8 046 A043
C B IN THE CALLING PROGRAM 3 046 A044
C MM-THE NUMBER OF WORDS OF STORAGE PROVIDED FOR EACH COLUMN OF 3 046 A045
C 8 C46A C46
C LTEMP-A BLOCK OF AT LEAST N WORDS OF TEMPORARY INTEGER STORAGE 3 046 A047

```

```

C IN ADDITION TO OVERWRITING B WITH THE SOLUTION MATRIX X, THE ROUTINE
C SETS IERR,DET,NPIV,PIV,LPC, AND LPIV TO
C
C IERR= 2 IF NO COLUMNS OF X ARE FOUND, THE ELIMINATION PROCESS
C BEING HALTED BECAUSE THE CURRENT PIVOT FAILS TO EXCEED
C EPS IN MAGNITUDE
C
C IF ALL COLUMNS OF X ARE FOUND, NO TROUBLE BEING DETECTED
C
C DET=PLUS OF MINUS THE PRODUCT OF THE CURRENT AND ALL PRECEDING
C PIVOTS
C
C NPIV=THE NUMBER OF THE CURRENT PIVOT (FIRST,SECOND,ETC.)
C
C PIV=THE CURRENT PIVOT
C
C LPR=THE FIRST NPIV POSITIONS LIST THE PIVOT ROW INDICES IN ORDER
C OF USE, A VECTOR OF LENGTH N
C
C LPC=THE FIRST NPIV POSITIONS LIST THE PIVOT COLUMN INDICES IN
C ORDER OF USE, A VECTOR OF LENGTH N
C
C IF THE ELIMINATION PROCESS IS HALTED PREMATURELY (IERR NEGATIVE), THEN
C THE DATA NPIV,PIV,LPR,LPC, MAY BE HELPFUL IN DIAGNOSING THE UNDERLYING
C CAUSE OF THE TROUBLE. IF THE PROCESS GOES TO COMPLETION THEN NPIV=N,
C DET SHOULD BE THE DETERMINANT OF A, PIV WILL BE THE NTH PIVOT, AND LPR
C AND LPC LIST ALL PIVOT POSITIONS.
C
C DO INITIALIZATIONS
C
1 IERR=0
DET=1.
DO 2 I=1,N
LPR(I)=I
2 LPC(I)=I
C
C BEGIN ELIMINATION PROCESS
C
DO 18 NP=1,N
NPIV=NP
C
C SELECT PIVOT
C
PIV=0.
DO 4 K=NP,N
I=LPR(K)
DO 4 L=NP,N
J=LPC(L)
IF( DABS(A(I,J))-DABS(PIV) ) 4,3,3
3 KPIV=K
LPIV=L
IPIV=I
JPIV=J
PIV=A(I,J)
4 CONTINUE
C
C UPDATE DETERMINANT AND PIVOT ROW AND COLUMN LISTS
C
DET=DET*PIV
ITEMP=LPR(NP)
LPR(NP)=LPR(KPIV)
LPR(KPIV)=ITEMP
ITEMP=LPC(NP)
LPC(NP)=LPC(LPIV)
LPC(LPIV)=ITEMP
C
C EXIT IF PIVOT TOO SMALL
C
IF( EPS-DABS(PIV) ) 8,7,7
8046A048
8046A049
8046A050
8046A051
8046A052
8046A053
8046A054
8046A055
8046A056
8046A057
8046A058
8046A059
8046A060
8046A061
8046A062
8046A063
8046A064
8046A065
8046A066
8046A067
8046A068
8046A069
8046A070
8046A071
8046A072
8046A073
8046A074
8046A075
8046A076
8046A077
8046A078
8046A079
8046A080
8046A081
8046A082
8046A083
8046A084
8046A085
8046A086
8046A087
8046A088
8046A089
8046A090
8046A091
8046A092
8046A093
8046A094
8046A095
8046A096
LIN2 97A
8046A098
8046A099
8046A100
8046A101
8046A102
8046A103
8046A104
8046A105
8046A106
8046A107
8046A108
8046A109
8046A110
8046A111
8046A112
8046A113
8046A114
8046A115
8046A116
LIN2 117A

```

```

7 IERR= 2
    RETURN
C
C MCDIFY PIVOT ROW OF A AND B (ELEMENTS IN PRESENT OR PREVIOUS PIVOT
C   COLUMNS OF A ARE SKIPPED)
C
8 IF (NP-N) 9, 11, 9
9 NNP=NP+1
  DO 10 L=NNP,N
    J=LPC (L)
10 A (IPIV,J)=-A (IPIV,J)/PIV
11 DO 12 J=1,M
12 B (IPIV,J)=-B (IPIV,J)/PIV
C
C MODIFY NON-PIVOT RCWS OF A AND B (ELEMENTS IN PRESENT OR PREVIOUS
C   PIVOT RCWS OR COLUMNS ARE SKIPPED)
C
13 IF (NP-N)13,18,13
14 DO 15 I=NNP,N
  J=LPC (L)
15 A (I,J)=A (I,J) +A (IPIV,J) *TEMP
  DO 16 J=1,M
16 B (I,J)=B (I,J) +B (IPIV,J) *TEMP
17 CONTINUE
18 CONTINUE
C
C END ELIMINATION PROCESS
C
C DO BACK SUBSTITUTIONS
C
19 DO 23 J=1,M
20 DO 21 K=2,N
  KK=N-K+1
  I=LPR (KK)
21 DO 22 I=2,K
  LL=N-L+2
  II=LPR (LL)
  JJ=LPC (LL)
22 B (I,J)=B (I,J) +B (II,J)*A (I,JJ)
23 CONTINUE
C
C UNSCRAMBLE ROWS OF SOLUTION MATRIX AND ADJUST SIGN OF DETERMINANT
C
24 DO 24 I=1,N
  L=LPR (I)
25 LTEMP (I)=LPC (I)
  DO 28 I=1,N
26 K=LTEMP (I)
  IF (I-K)26,28,26
27 DET=-DET
  DO 27 J=1,M
    TEMP=B (I,J)
    B (I,J)=B (K,J)
    B (K,J)=TEMP
  LTEMP (I)=LTEMP (K)
  LTEMP (K)=K
  GO TO 25
28 CONTINUE
    RETURN
  END

```

8 046A 118
 8 046A 119
 8 046A 120
 8 046A 121
 8 046A 122
 8 046A 123
 8 046A 124
 8 046A 125
 8 046A 126
 8 046A 127
 8 046A 128
 8 046A 129
 8 046A 130
 8 046A 131
 8 046A 132
 8 046A 133
 8 046A 134
 8 046A 135
 8 046A 136
 8 046A 137
 8 046A 138
 8 046A 139
 8 046A 140
 8 046A 141
 8 046A 142
 8 046A 143
 8 046A 144
 8 046A 145
 8 046A 146
 8 046A 147
 8 046A 148
 8 046A 149
 8 046A 150
 8 046A 151
 8 046A 152
 8 046A 153
 8 046A 154
 8 046A 155
 8 046A 156
 8 046A 157
 8 046A 158
 8 046A 159
 8 046A 160
 8 046A 161
 8 046A 162
 8 046A 163
 8 046A 164
 8 046A 165
 8 046A 166
 8 046A 167
 8 046A 168
 8 046A 169
 8 046A 170
 8 046A 171
 8 046A 172
 8 046A 173
 8 046A 174
 8 046A 175
 8 046A 176
 8 046A 177
 8 046A 178
 8 046A 179
 8 046A 180
 8 046A 181

```

SUBROUTINE COMBIN
  IMPLICIT REAL*8 (A-H,O-Z)                               COMBIN
  DIMENSION S(6,18), SC(18)                               COMBIN
  DATA SC/18*0.0/                                         COMBIN
  COMMON ITYPE, IONE, ICODE, MATE, XA, XB, G, C, PRESS, XGS, XOP, G1, GU, TH, YM, FLA      4
  TAB, QFHR(4), AL, DELTA, XMO, XMC, QFHGE, QPHGE, QTHGP, BP, GOP, THP, YPP, EPP, FLA      5
  2DELTAP, GJUT, GIN, ROG, SLSO, SLSI, SCSI, SILO, SLLI, SCLU, SCLI, STH,
  3 STP, SRH, SRF, ZG, ZC, QFHG, Y0, Y1, T1, THETA, SCRT, SGF, SGT, SCR, SCT, SAT,
  4 W2, W1, S, MA, IT, XM1, XM2, XM2P, IT2

C
  IC = 0
  IF(MATE.LE.2) IT=ITYPE
  GO TO( 1,2,3 ),IT                                     COMBIN
  1 IC = IC + 1
  IF(IC.GT.2) GO TO 99
  IF(MATE.GT.1) PRINT 49
  PRINT 50
  NN = 18
  DO 4 MA = 1,3
  GO TO( 5,6,7 ),MA                                     COMBIN
  5 PRINT 53
  GO TO 8
  6 PRINT 54
  GO TO 8
  7 PRINT 55
  8 GO TO( 12,13 ),IC                                 COMBIN
  12 PRINT 60, (S (MA,I), I=1,NN)
  GO TO 4
  13 PRINT 60, (S (MA+3,I), I=1,NN)
  4 CONTINUE
  IF(MATE.EQ.1) GC TO 99
  DO 9 I=1,NN
  GO TO( 10,11 ),IC                                     COMBIN
  10 SC(I) = S(1,I)*XM2P/XM1+S(2,I) + S(3,I)
  GO TO 9
  11 SC(I) = S(4,I)*XM2/XM1+ S(5,I) + S(6,I)
  9 CONTINUE
  GO TO( 40,41 ),IC                                     COMBIN
  40 PRINT 56, XM2P
  GO TO 42
  41 PRINT 56, XM2
  42 PRINT 60, (SC(I), I=1,NN)
  IF(MATE.EQ.2) GC TO 99
  IF(IT.EQ.IT2) GO TO 1
  IF(MATE.EQ.4) GC TO 2
  IF(MATE.EQ.6) GO TO 99
  2 IC = IC + 1
  IF(IC.GT.2) GO TO 99
  IF(MATE.GT.1) PRINT 49
  PRINT 51
  NN = 13
  DO14 MA = 1,3
  GO TO( 15,16,17 ),MA                                 COMBIN
  15 PRINT 53
  GO TO 18
  16 PPINT 54
  GO TO 18
  17 PRINT 55
  18 GO TO( 22,23 ),IC                                 COMBIN
  22 PRINT 61, (S (MA,I), I=1,NN)
  GO TO14
  23 PRINT 61, (S (MA+3,I), I=1,NN)
  14 CONTINUE
  IF(MATE.EQ.1) GC TO 99
  DO19 I=1,NN
  GO TO( 20,21 ),IC                                     COMBIN
  20 SC(I) = S(1,I)*XM2P/XM1+S(2,I) + S(3,I)
  GO TO19
  21 SC(I) = S(4,I)*XM2/XM1+ S(5,I) + S(6,I)
  19 CONTINUE
  GO TO( 43,44 ),IC                                 COMBIN

```

```

43 PRINT 56, XM2P
  GO TO 45
44 PRINT 56, XM2
45 PRINT 61, (SC(I), I=1,NN)
  IF(MATE.EQ.2) GC 1C 99
  IF(IT.EQ.IT2) GO TO 2
  IF(MATE.EQ.4) GC 1C 1
  IF(MATE.EQ.6) GO TO 99
3  IC = IC + 1
  IF(MATE.GT.1) PRINT 49
  PRINT 52
  NN = 7
  DO 24 MA=1,2
  GO TO( 25,26 ),MA
25 PRINT 57
  GO TO 28
26 PRINT 54
28 PRINT 62, (S (MA, I), I=1,NN)
24 CONTINUE
  IF(MATE.EQ.1) GC 1C 99
  DO 29 I=1,NN
  SC(I) = S(1,I)*W2/W1 + S(2,I)
29 CONTINUE
  PRINT 50, W2
  PRINT 62, (SC(I), I=1,NN)
  GO TO( 1,2 ),ITYPE
99 PRINT 49
  RETURN
49 FORMAT (1H1)
50 FORMAT (/50H           TAPERED HUB FLANGE          /)
51 FORMAT (/50H           STRAIGHT HUB FLANGE         /)
52 FORMAT (/50H           BLIND FLANGE             /)
53 FORMAT (50H           CALCULATIONS FOR MOMENT LOADING  //)
54 FORMAT (50H           CALCULATIONS FOR PRESSURE LOADING //)
55 FORMAT (50H           CALCULATIONS FOR TEMPERATURE LOADING //)
56 FORMAT (36H           CALCULATIONS FOR COMBINED LOADING, M2 OR M2P FOR ITY
  1PE=1 OR 2, W2 FOR ITYPE=3, = 1PE12.4 //)
57 FORMAT (50H           CALCULATIONS FOR BOLT LOADING    //)
60 FORMAT (7H  SLSO=E12.4,7H  SLSI=E12.4,7H  SCZO=E12.4,7H  SCSI=E1TAP  900
  12.4//7H  SLLO=E12.4,7H  SLLI=E12.4,7H  SCIO=E12.4,7H  SCLI=E12.4//TAP 902
  27H  STH=E12.4,7H  STF=E12.4,7H  SRH=E12.4,7H  SRF=E12.4//5H  ZTAP 904
  3G=E12.4,5H  ZC=E12.4,7H  QFHG=E12.4,5H  YO=E12.4,5H  Y1=E12.4,8H  TAP 906
  4THETA=E12.4/)  TAP 908
61 FORMAT (7H  SISC=1PE12.4,7H  SLSI=E12.4,7H  SCZO=E12.4,7H  SCSI=E1STH 422
  12.4//7H  STH=E12.4,7H  STF=E12.4,7H  SFH=E12.4,7H  SRF=E12.4//STH 424
  25H  ZG=E12.4,5H  ZC=E12.4,7H  QFHG=E12.4,5H  YO=E12.4,8H  THETA=E1STH 426
  32.4/)  STH 428
62 FORMAT (7H  SORT=1PE12.4,7H  SGR=E12.4,7H  SGT=E12.4,7H  SCR=E1BLI 362
  12.4,7H  SCT=E12.4,7H  SAT=E12.4//9H  ZC=E12.4//)  BLI 364
  END

```

```

SUBROUTINE STORE
IMPLICIT REAL*8 (A-H,C-Z)
DIMENSION S(6,18), SC(18)
COMMON ITYPE,IBOND,ICODE,MATE,XA,XB,G,C,PRESS,XGS,XOP,G1,G0,Th,YM,FLA
1AB,QFHR(4),AL,DELTA,XMO,XPCA,QFHGE,QFHGI,CHGEP,BP,GOP,THP,YFP,EFP,FLA
2DELTAP,GOUT,GIN,RCG,SLSO,SLSI,SCZO,SCSI,SILO,SLLI,SCLO,SCLI,S1H,
3  S1F,SCM,SCF,ZG,ZC,QFHG,YO,Y1,T1,THETA,SCRT,SGR,SGT,SCR,SCT,SAT,
4  W2, W1, S, MA, IT, XM1, XM2, XM2P

```

```

GO TO ( 4, 4, 4, 5, 4, 5 ), MA TE      STORE
5 MA = MA + 3
4 GO TO ( 1, 2, 3 ), ITYPE      STORE
1 S(MA,1) = S1SC
  S(MA,2) = S1SI
  S(MA,3) = SCSO
  S(MA,4) = SCSE
  S(MA,5) = SLLO
  S(MA,6) = S1II
  S(MA,7) = SCLO
  S(MA,8) = SCII
  S(MA,9) = STH
  S(MA,10) = S1F
  S(MA,11) = SRF
  S(MA,12) = SRF
  S(MA,13) = ZG
  S(MA,14) = ZC
  S(MA,15) = QFHG
  S(MA,16) = Y0
  S(MA,17) = Y1
  S(MA,18) = I1
  GO TO 50
2 S(MA,1) = S1SC
  S(MA,2) = SLSI
  S(MA,3) = SCSC
  S(MA,4) = SCSE
  S(MA,5) = STH
  S(MA,6) = S1F
  S(MA,7) = SRF
  S(MA,8) = SFF
  S(MA,9) = ZG
  S(MA,10) = ZC
  S(MA,11) = QFHG
  S(MA,12) = Y0
  S(MA,13) = THETA
  GO TO 50
3 S(MA,1) = SCFT
  S(MA,2) = SGR
  S(MA,3) = SG1
  S(MA,4) = SCR
  S(MA,5) = SCT
  S(MA,6) = SAT
  S(MA,7) = ZC
50 RETURN
END

```


INTERNAL DISTRIBUTION

1. R. L. Battiste	32. R. E. MacPherson
2. M. Bender	33. S. S. Manson (consultant)
3. J. J. Blass	34. W. J. McAfee
4. S. E. Bolt	35. W. J. McCarthy, Jr.
5. R. H. Bryan	36. H. C. McCurdy
6. J. W. Bryson	37. J. G. Merkle
7. J. H. Butler	38-52. S. E. Moore
8. J. P. Callahan	53-54. F. M. O'Hara (consultant)
9. C. J. Claffey	55. T. W. Pickel
10. J. A. Clinard	56. H. Postma
11. C. W. Collins	57. C. E. Pugh
12-13. J. M. Corum	58. M. Richardson
14. W. B. Cottrell	59. D. N. Robinson
15. F. L. Culler	60. R. A. Schmidt
16. R. W. Derby	61. M. R. Sheldon
17. W. G. Dodge	62. J. E. Smith
18. G. G. Fee	63. I. Spiewak
19. M. H. Fontana	64. W. C. T. Stoddart
20. W. R. Gall	65. R. E. Textor
21. R. H. Gallagher (consultant)	66. J. J. Taylor
22. M. J. Goglia	67. D. B. Trauger
23-24. W. L. Greenstreet	68. G. D. Whitman
25. R. C. Gwaltney	69. W. J. Wilcox
26. W. O. Harms	70. G. T. Yahr
27. R. F. Hibbs	71. ORNL Patent Office
28. H. W. Hoffman	72-74. Central Research Library
29. P. R. Kasten	75. Document Reference Section
30. K. C. Liu	76-81. Laboratory Records Department
31. R. N. Lyon	82. Laboratory Records, ORNL RC

Subcontractors

83-87. E. C. Rodabaugh, Battelle-Columbus Laboratories, Columbus, OH
43201

88-89. N. E. Johnson, Mechanics Research Inc., Oak Ridge, TN 37830

EXTERNAL DISTRIBUTION

90-97. Director, Office of Nuclear Regulatory Research, NRC, Washington, DC 20555
98. Director, Reactor Division, ERDA, ORO
99. Research and Technical Support Division, ERDA, ORO
100-180. Design Criteria for Piping and Nozzles Program Distribution
181-440. Given distribution as shown under categories NRC-1 and NRC-5 (25 copies - NTIS)