

FEEDBACK-BASED CALIBRATION FOR TUNING AND DRIFT CONTROL OF A TRAPPED-ION QUANTUM PROCESSOR

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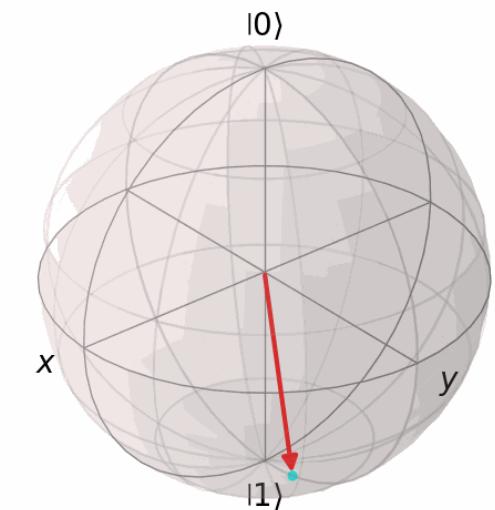
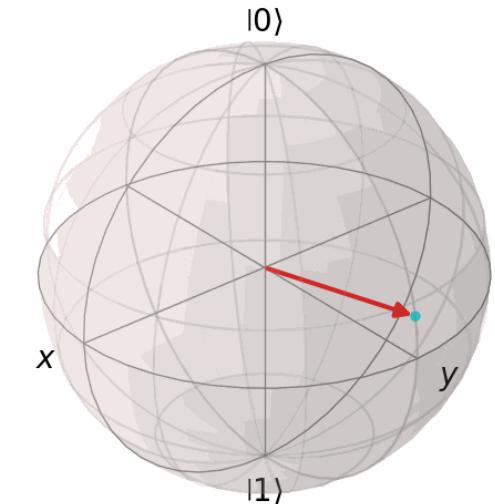
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FORMULATING THE PROBLEM



- The accuracy of quantum gates depends on many parameters, and we want to tune them shot-by-shot to rapidly calibrate for random variation and drift.
- We look at two classes of circuits with some over or under rotation angle δ caused by some control parameter η which is out of tune:
 - Indefinite outcome circuits with linear noise response (i.e. a $\pi/2$ rotation gate)
 - Definite outcome circuits with quadratic noise response (i.e. a π rotation gate)
- This work demonstrates a rapid, online method for tuning and drift control which is able to respond to drift and SPAM and is implementable in any quantum processor. We will also demonstrate control hardware considerations and progress towards calibration of Sandia's trapped ion processors.



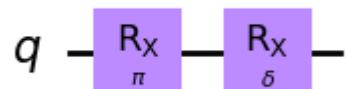
SENSITIVITY TUNING VIA COHERENT NOISE AMPLIFICATION



- We can coherently amplify the noise in a circuit by repeating the gates, effectively increasing sensitivity to changes in η
 - Calibrating a $\mathcal{G}_x\left(\frac{\pi}{2}\right)$ gate, we can repeat by $r = 4n + 1$ with n an integer, $s \propto r$
 - Calibrating a $\mathcal{G}_x(\pi)$ gate, we can repeat by $r = 2n + 1$ with n an integer, $s \propto r$

- Example: $\mathcal{G}_x(\pi + \delta)$

(a) A single noisy $\mathcal{G}_x(\pi)$ gate

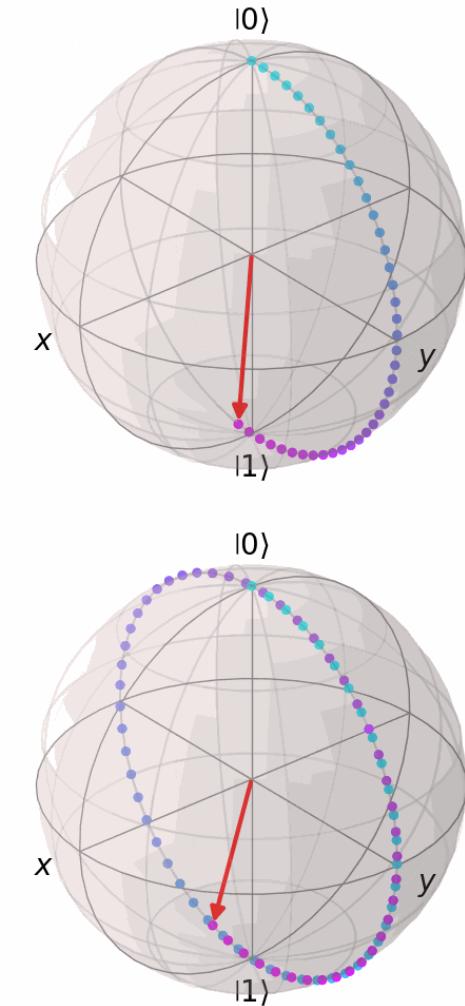
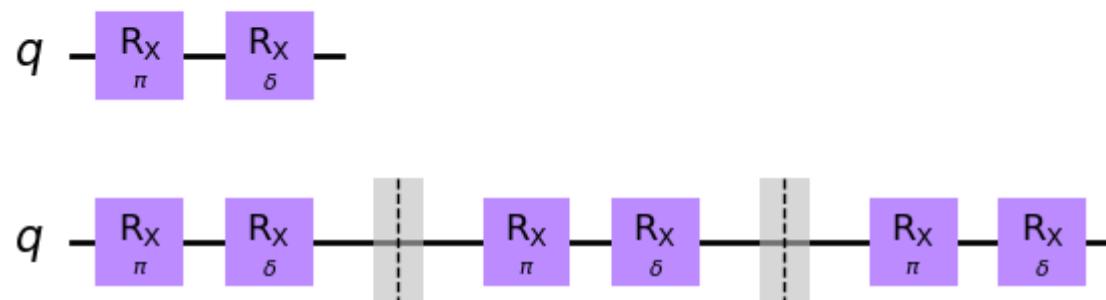


SENSITIVITY TUNING VIA COHERENT NOISE AMPLIFICATION (CONT.)



- We can coherently amplify the noise in a circuit by repeating the gates, effectively increasing sensitivity to changes in η
 - Calibrating a $\mathcal{G}_x\left(\frac{\pi}{2}\right)$ gate, we can repeat by $r = 4n + 1$ with n an integer, $s \propto r$
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- Example: $\mathcal{G}_x(\pi + \delta)$

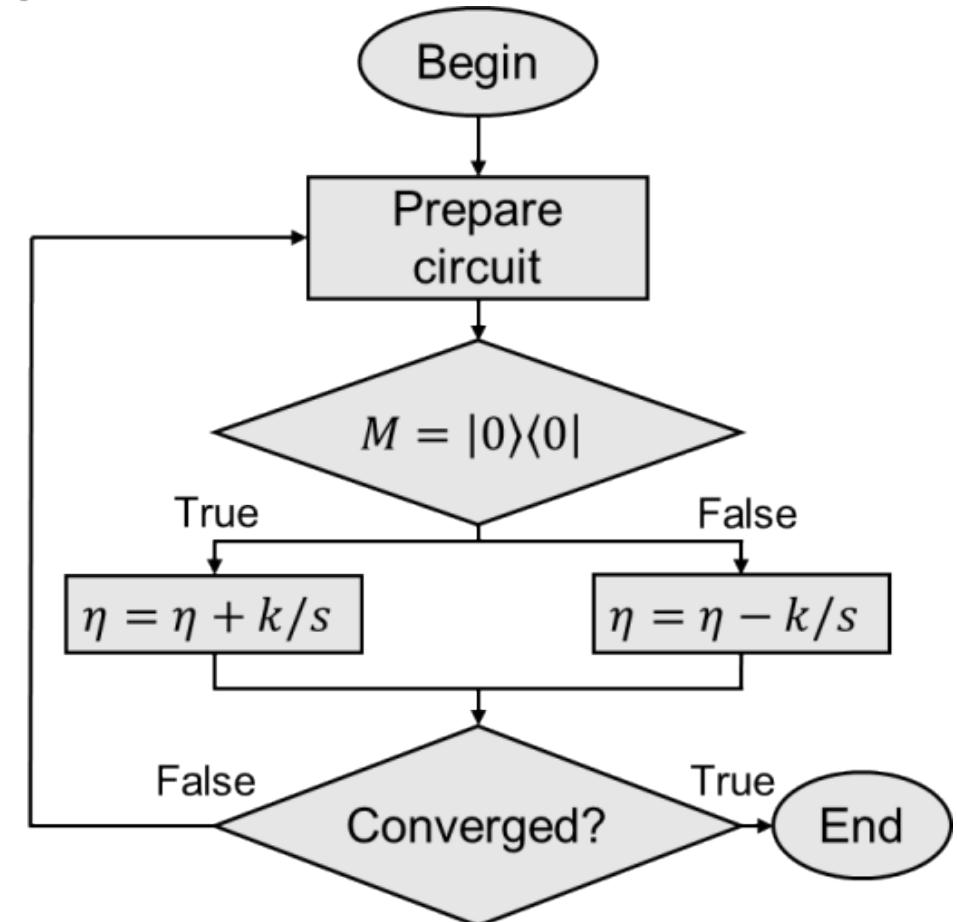
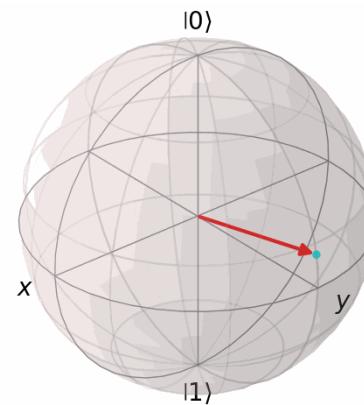
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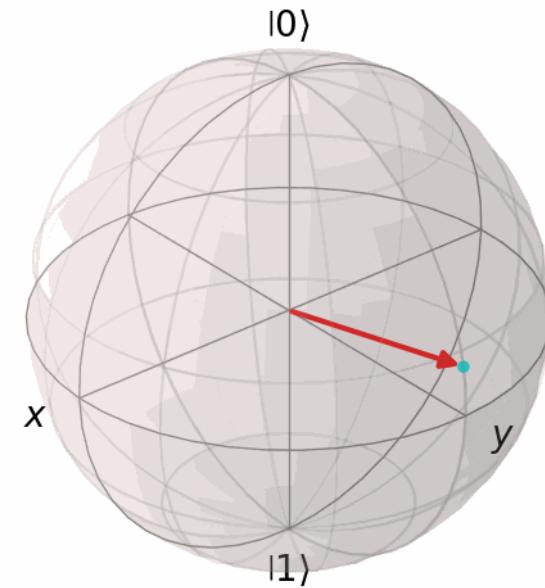
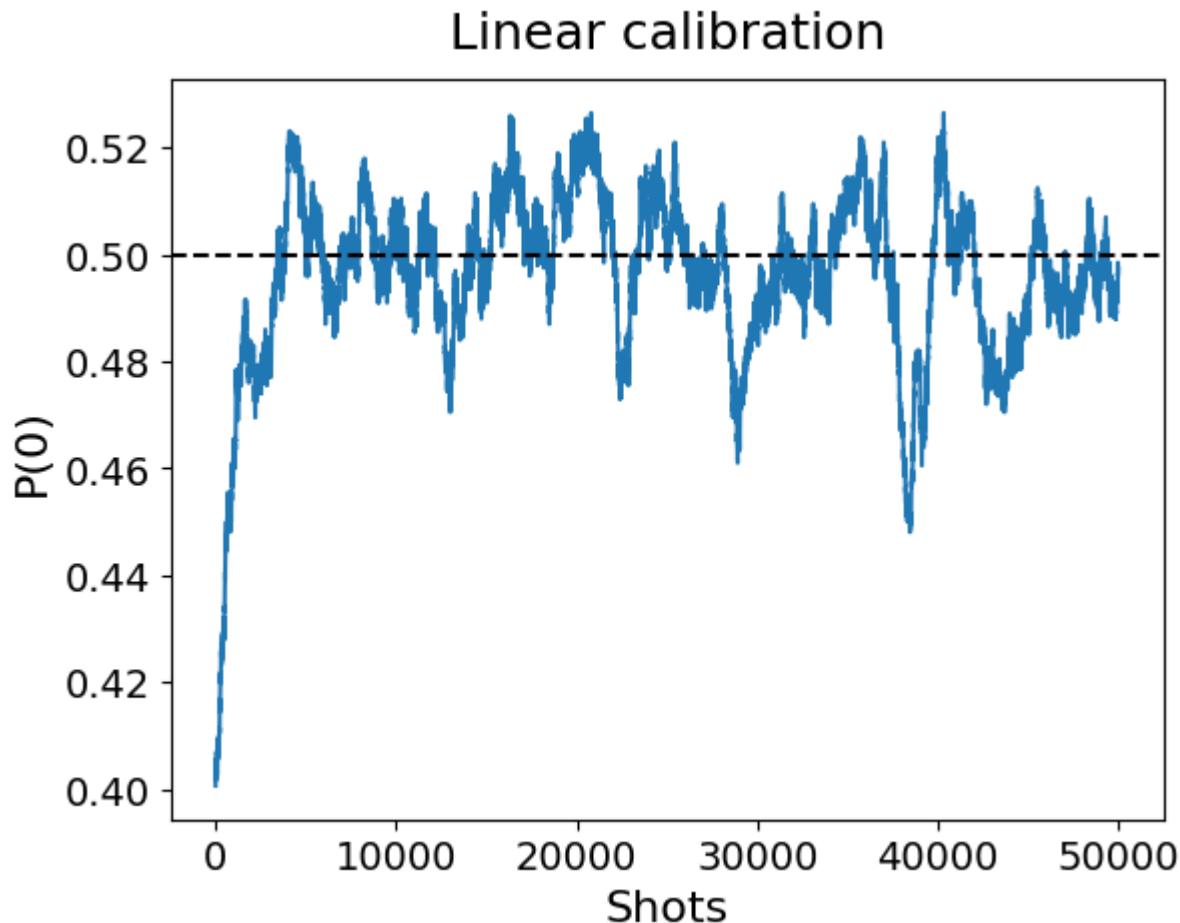
METHODS: INDEFINITE CIRCUITS (LINEAR CALIBRATION)



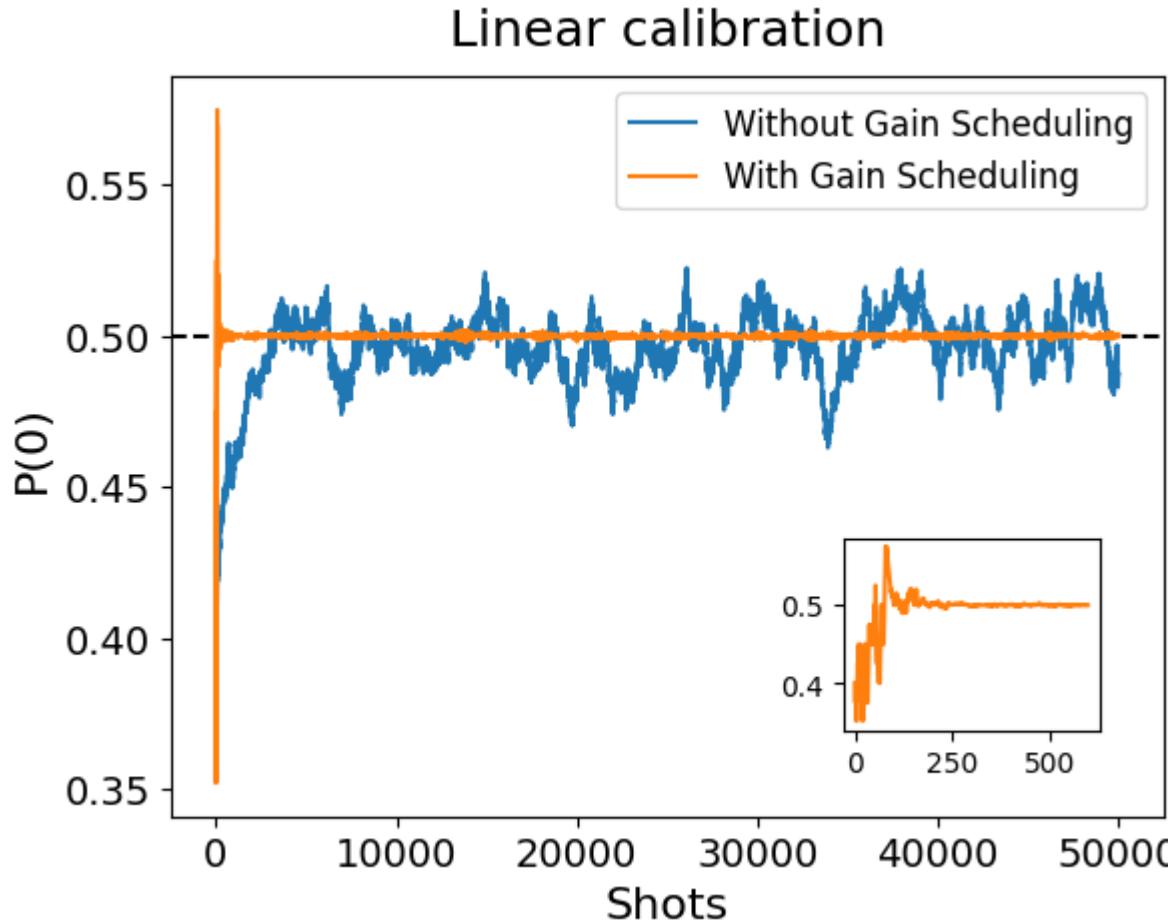
- Circuits with an unbiased, indefinite outcome (i.e. a $\pi/2$ gate) have an approximately linear response in their output to a noise parameter $\delta = s(\eta - \eta_{opt})$, $s \propto 4n + 1$
- Shot-by-shot:
 - If we measure $|0\rangle$, rotate towards $|1\rangle$ by $\eta += k/s$
 - If we measure $|1\rangle$, rotate towards $|0\rangle$ by $\eta -= k/s$
- Goal: $\eta \rightarrow \eta_{opt}$ s.t. $P(z = \pm 1|\delta) \approx \frac{1}{2}(1 + z\delta) \rightarrow \frac{1}{2}$



LINEAR CALIBRATION – BASELINE



LINEAR CALIBRATION – GAIN AND SENSITIVITY SCHEDULING

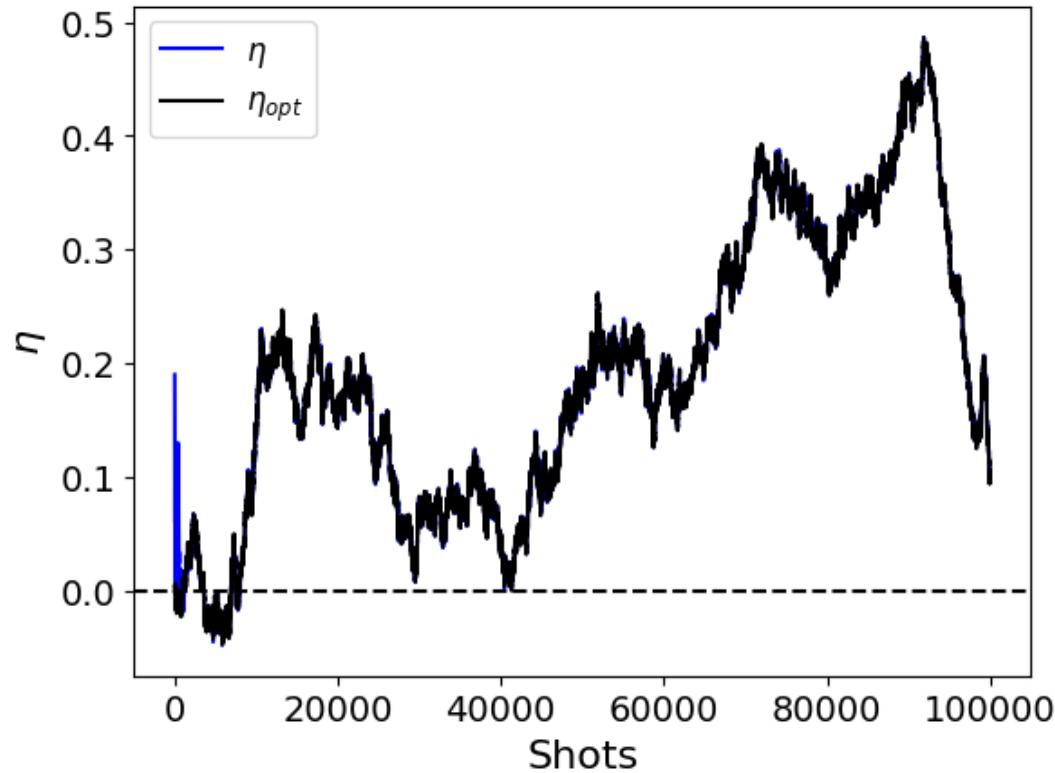


1. Start with a high gain and a single gate ($s = 1$), increase s and reduce k as $k = 1/s$ every $4/k$ shots
2. Beyond a sensitivity cap, set $k = ls$ (here $l = 0.001$, cap s at 250)
3. Tweak l based on measurement history
 - a) If measurements are uncorrelated, reduce k to reduce stationary variance
 - b) If measurements are correlated, increase k to correct for errors quicker

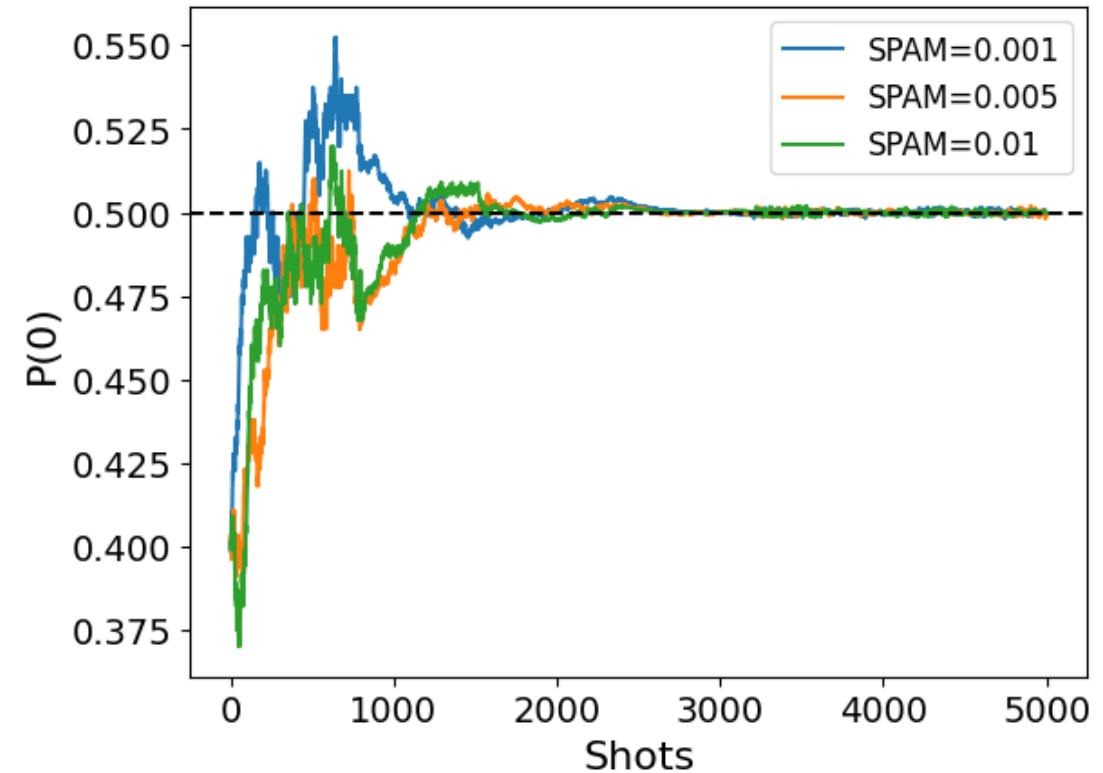
LINEAR CALIBRATION – DRIFT AND SPAM



Linear calibration with drift, gain scheduling



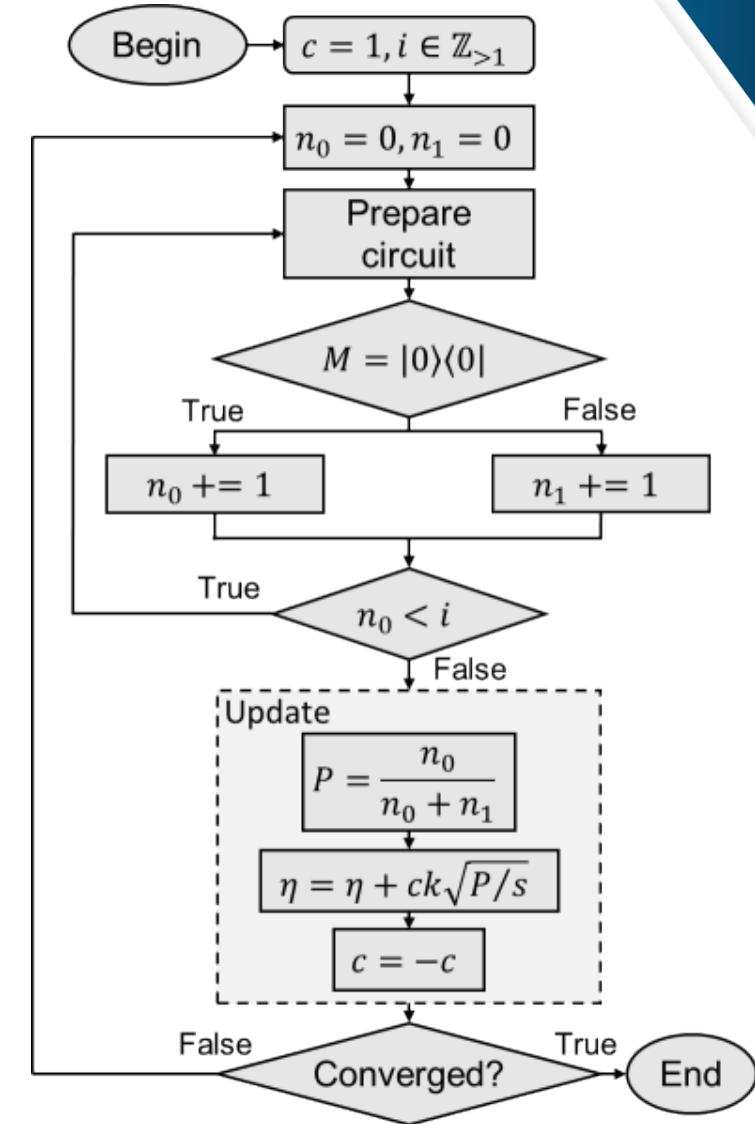
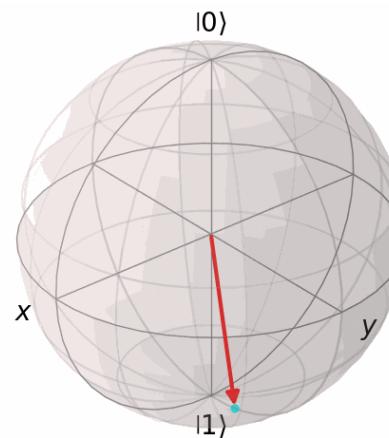
Linear calibration with SPAM, gain scheduling



METHODS: DEFINITE CIRCUITS (QUADRATIC CALIBRATION)



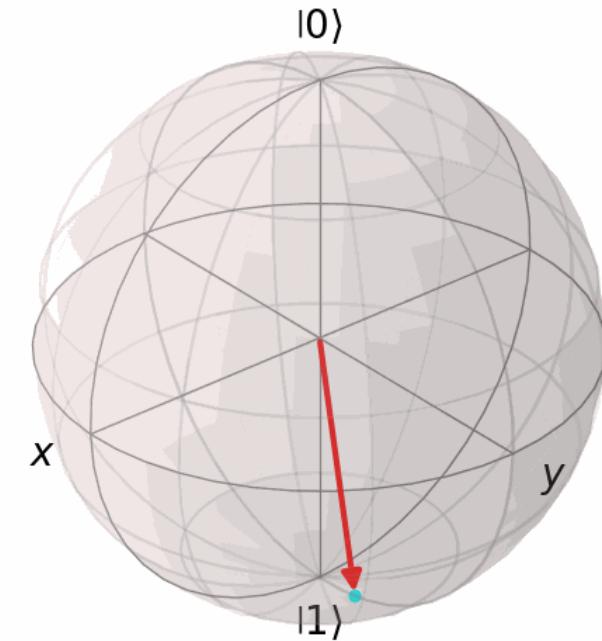
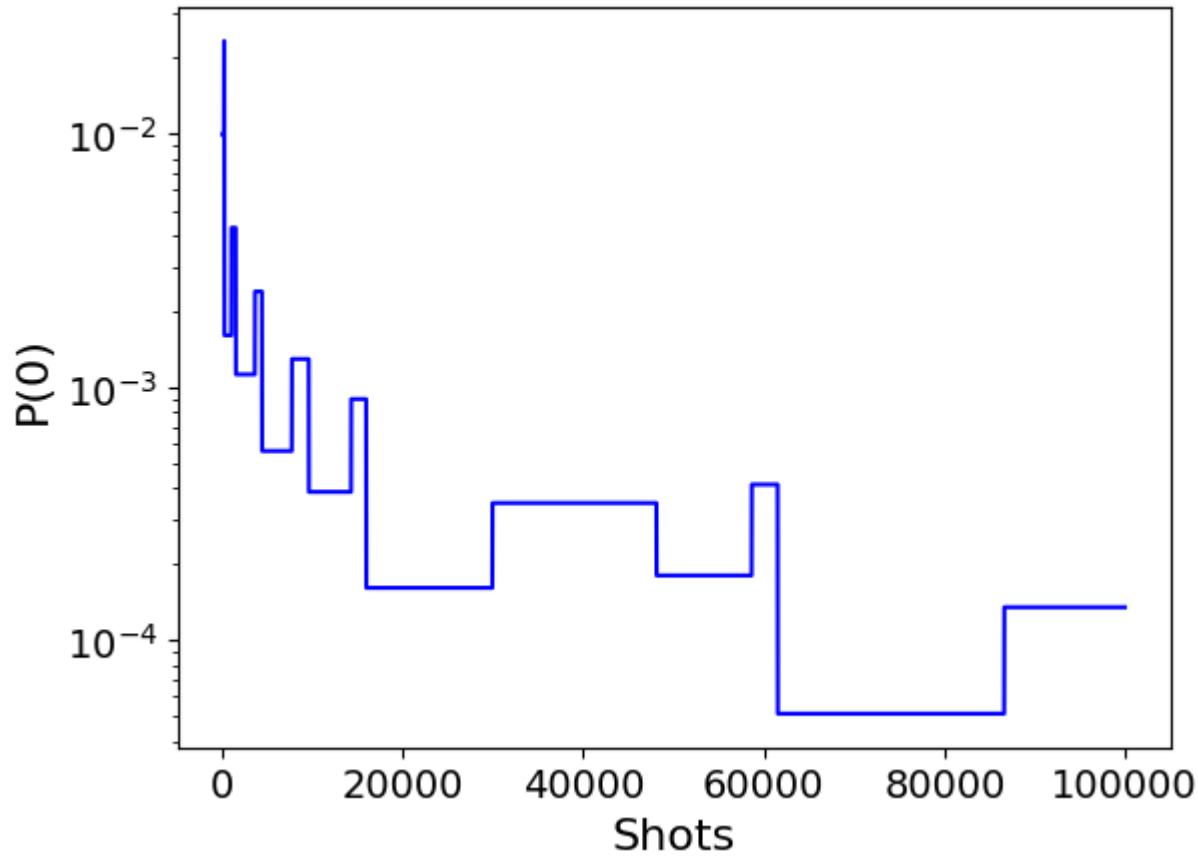
- Circuits with an ideally definite outcome (i.e. a π gate) have a probability of measuring an undesired result which is approximately quadratic with respect to the noise parameter $\delta = s(\eta - \eta_{opt})$, $s \propto 2n + 1$
- Measure until a certain number of errors are seen
 - The maximum likelihood estimator is $\hat{p} = \frac{n_0}{n_0+n_1}$
 - Update η as $\eta += ck\sqrt{P/s}$
- Goal: $\eta \rightarrow \eta_{opt}$ s.t. $P(z = 1) \rightarrow 1$



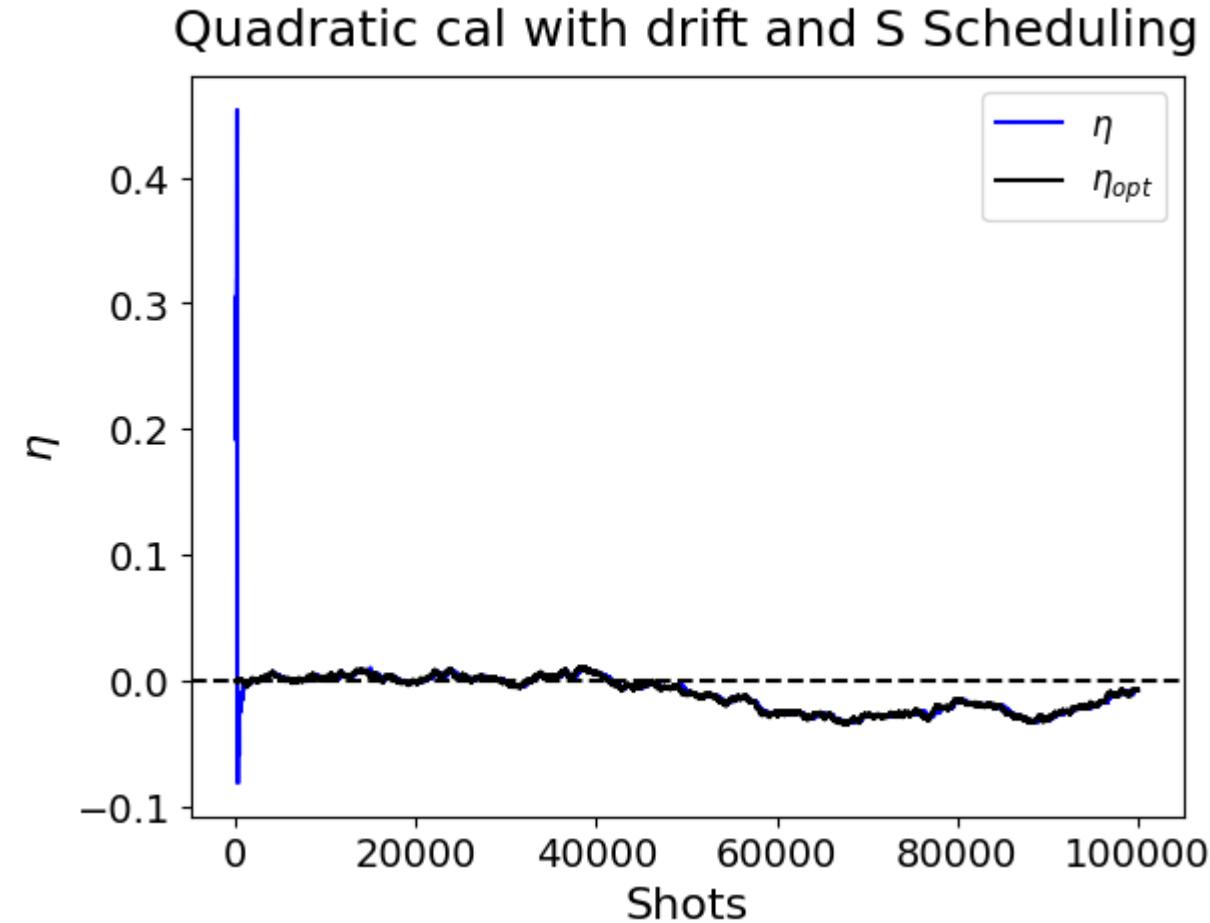
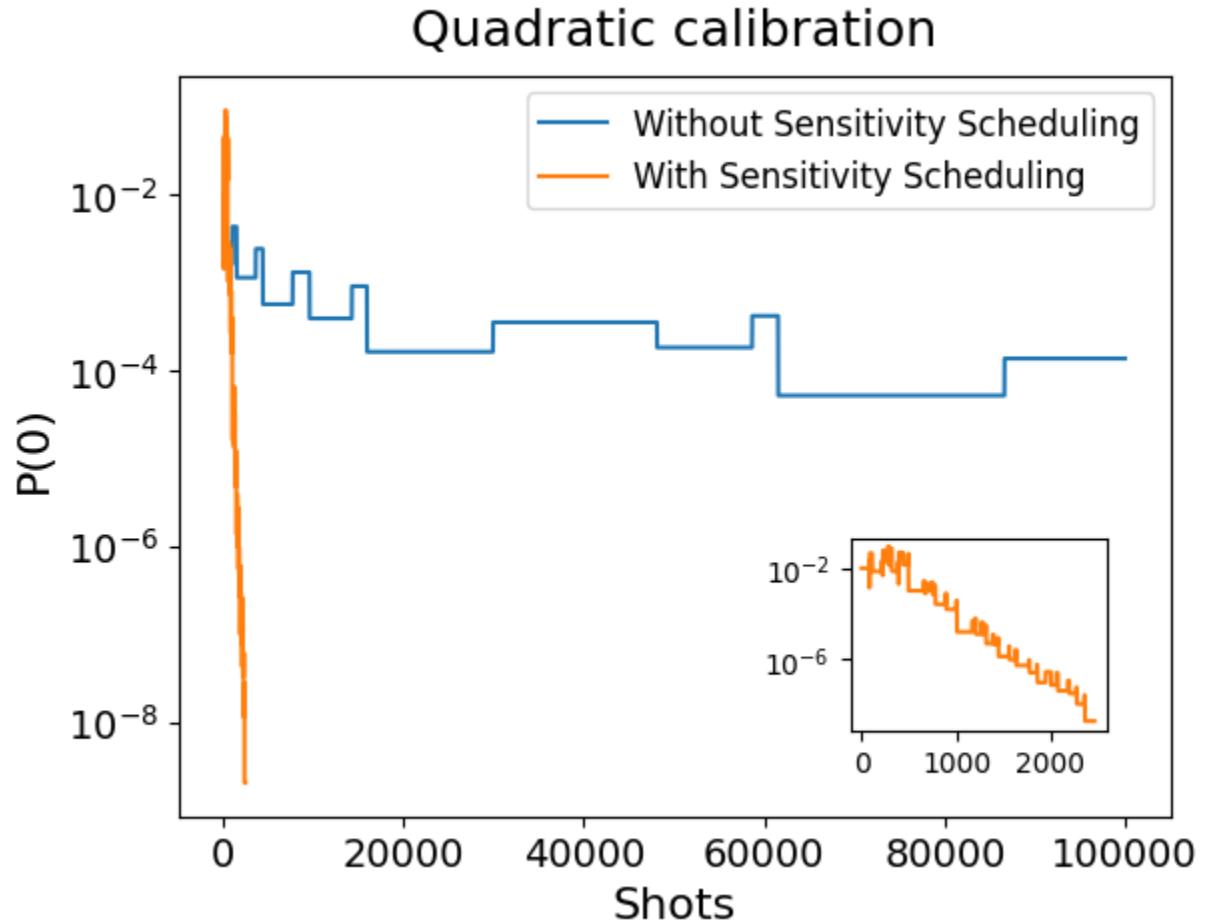
QUADRATIC CALIBRATION – BASELINE



Quadratic calibration without sensitivity scheduling



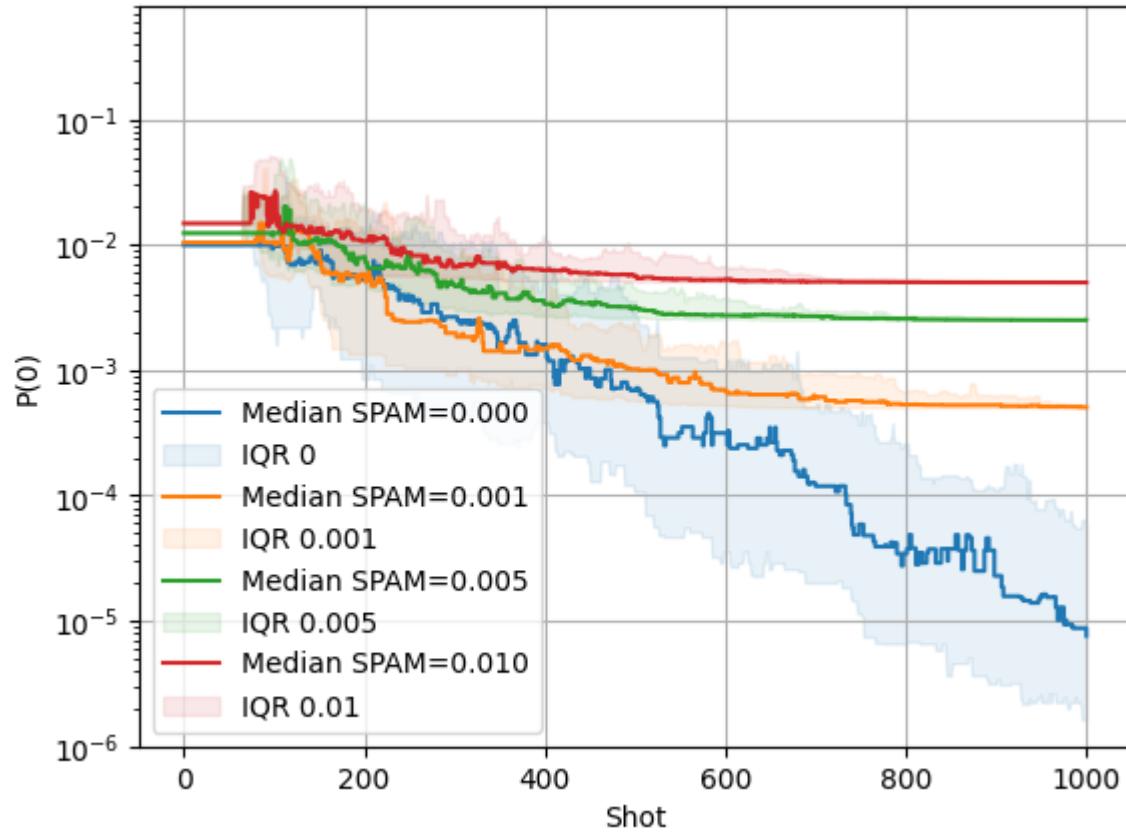
QUADRATIC CALIBRATION – SENSITIVITY SCHEDULING



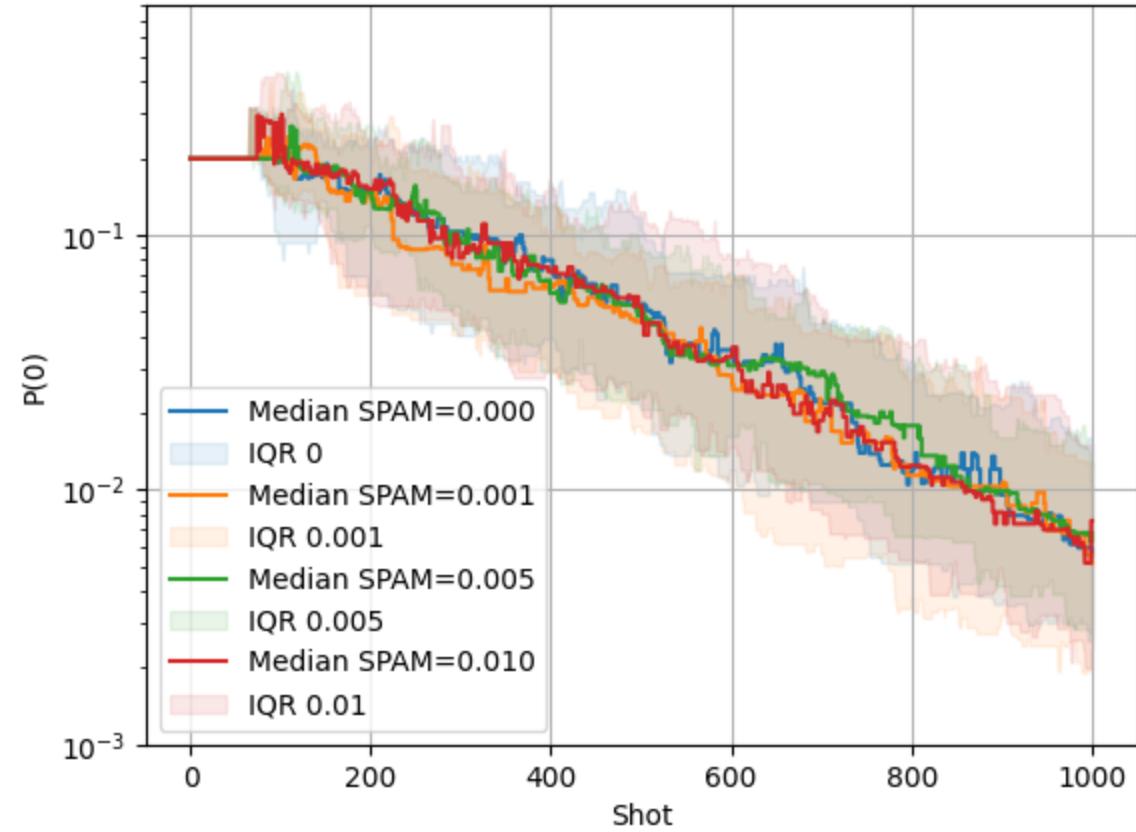
QUADRATIC CALIBRATION – SPAM



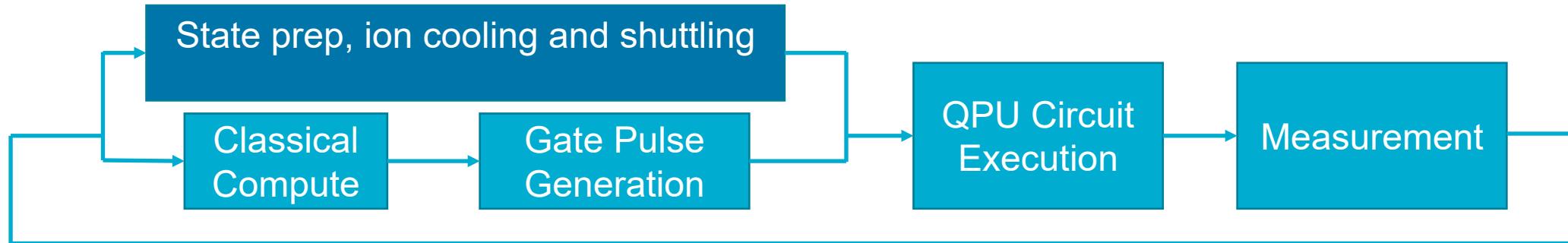
Quad Cal $P(0)$ with SPAM, 50 Trajectories



Quad Cal $|\eta|$ with SPAM, 50 Trajectories



REAL TIME CALIBRATION OF TRAPPED ION PROCESSORS



- Sandia's Octet pulse compiler has multiple options for fast tuning of gate pulses
 - Continuously modulated spline generation using parameters input to a direct digital synthesis (DDS) module which requires less data than an AWG
 - Alternatively, more basic pulses can be generated from registered parameter values from a DMA engine in less time
- We can perform updates of gate pulses from measurement data in parallel with cooling and shuttling of ions in the trap, allowing for faster response to drift



Photo: Craig Fritz, SNL

REAL TIME CALIBRATION OF A ROTATION GATE



- Using QSCOUT's API, we can control registered parameters of pulse sequences to implement calibration of a simple rotation gate.
 - In the rotation gate code below, we can modify the length of the gate pulse without full recompilation in order to perform rapid tuning.
 - Additional modifiable parameters include pulse amplitude, frequency and phase
- An initial implementation in the on-board real time processing unit (RPU) is in progress, with goals of implementing logic in the control system's FPGA fabric for lower latency.

```
function gate_R_custom(pi(parameters::Dict{String,Any},qubit::Float64, theta::Float64, args3::Float64)
    calibrated_pi_time=get(parameters, "calibrated_pi_time", 20e-6)
    Gate(PulseData(remap_qubit(parameters, qubit), calibrated_pi_time*abs(theta)/pi;
        amp0=Discrete([9.5]),
        amp1=Discrete([98.5]),
        freq0=Discrete([200e6]),
        freq1=Discrete([230e6]),
        phase0=Discrete([args3]),
        framerot0=Discrete([10.0]),
        ForwardFrame0Tone0=true,
        )))
    # return
end
```





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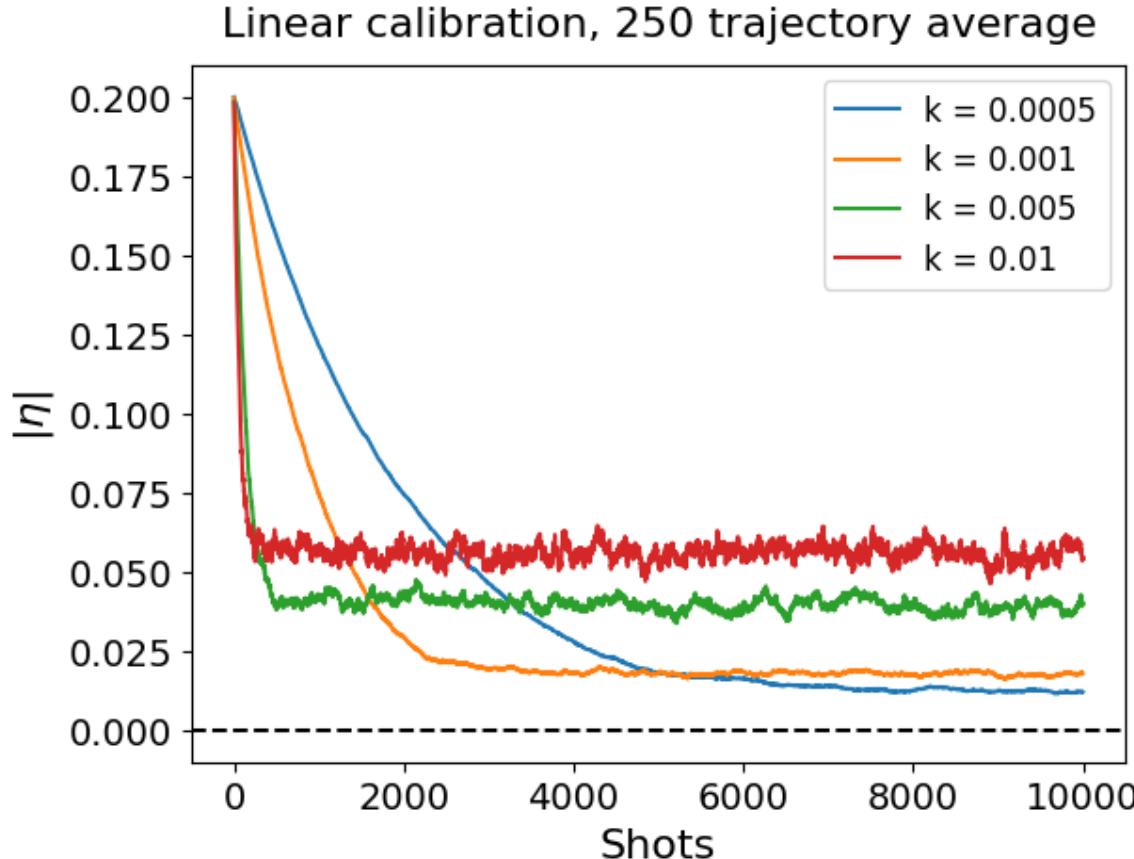
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QUESTIONS?

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LINEAR CALIBRATION CONVERGENCE



Gain	Mean of $ \eta $	σ^2 of $ \eta $
0.0005	0.01259	2.575e-7
0.001	0.01794	3.550e-7
0.005	0.03975	4.274e-6
0.01	0.05608	7.268e-6

Large gains converge quickly but poorly. This motivates gain and sensitivity scheduling, for fast convergence and reduced mean and stationary variance of η .

MORE QUADRATIC SPAM EXPERIMENTS

