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# Automatic Performance Tuning for Albany Land-Ice

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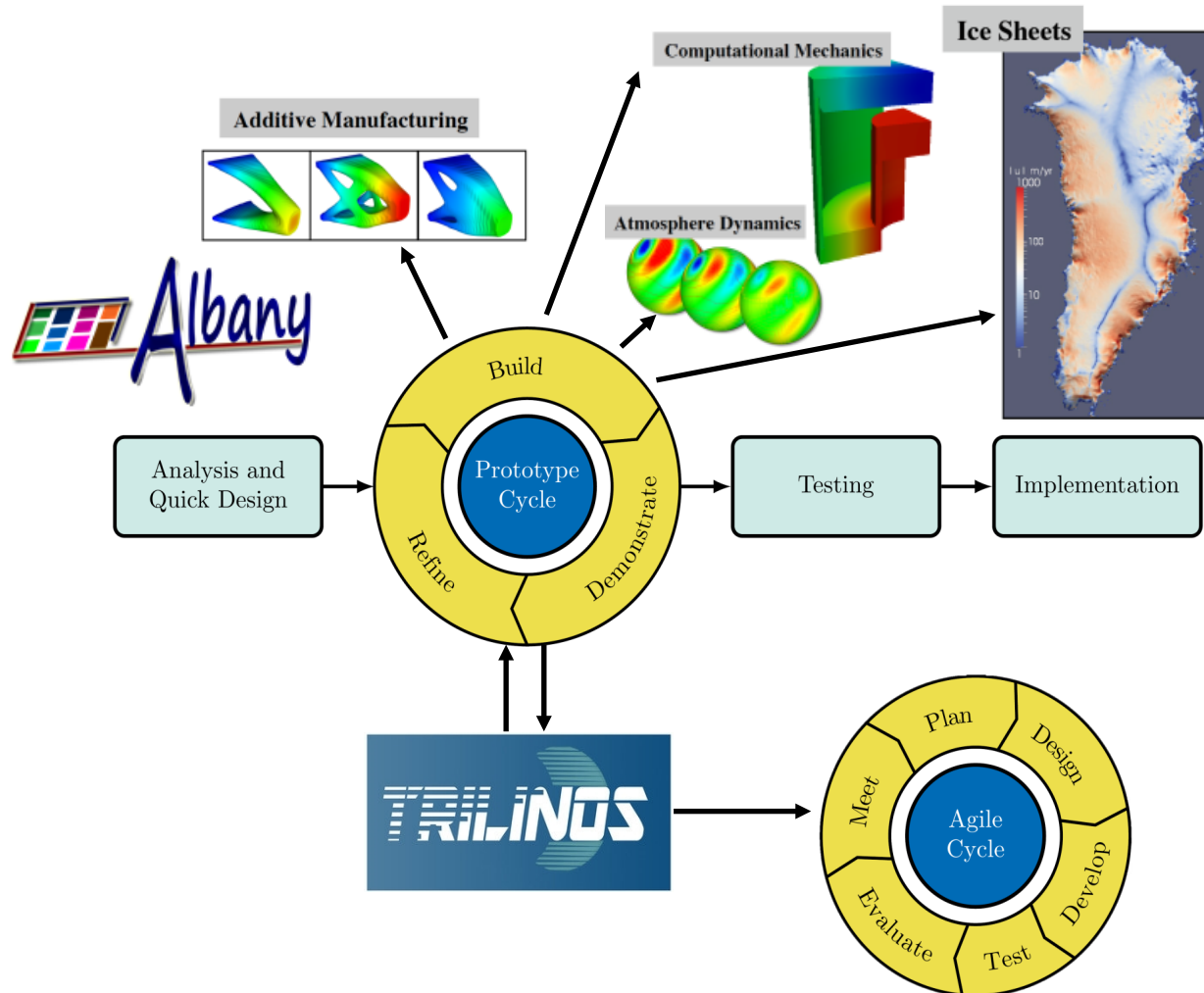
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# The Albany Code Base

**Albany:** open-source<sup>1</sup> parallel C++ unstructured-grid multi-physics finite element code built for rapid application development from Trilinos<sup>2</sup> Agile Components



## Distinguishing features of Albany:

- Designed to facilitate prototyping of scientific models and analysis tools
- Albany-Land Ice is a model that evolved from prototype to full-fledged production software
- Close collaboration with Trilinos developers facilitates efforts to maintain Albany's **scalability** and **portability**

<sup>1</sup> <https://github.com/sandialabs/Albany>

<sup>2</sup> <https://github.com/trilinos/Trilinos>

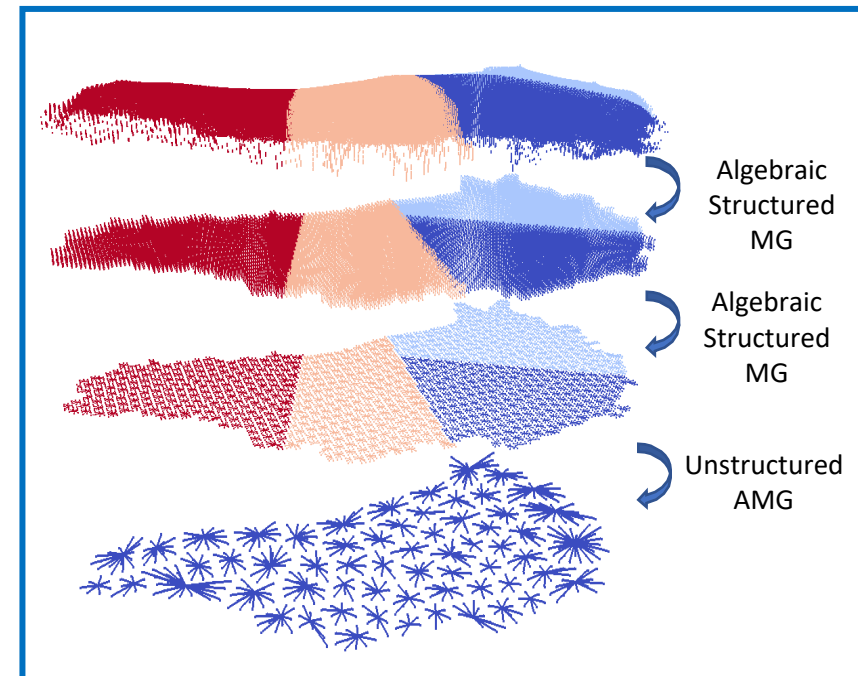
# Motivation - Automated Performance Tuning

## Problem Description

- Find a **robust** set of parameters for optimal **performance** and **accuracy**
- Often many runtime parameters to choose from (e.g. discretization, solver)
- Optimal parameters are not necessarily unique across architectures or problem inputs
  - Optimal parameters can also shift in time due to code changes, algorithmic optimization, and deployment on new compilers or architectures

## Putting Automated Performance Tuning to Work

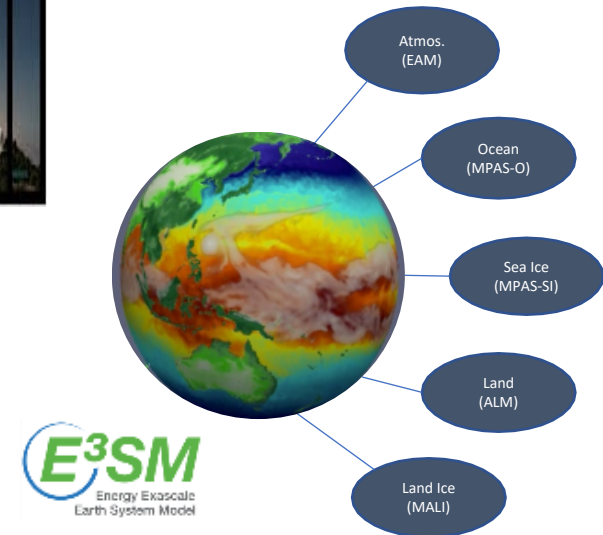
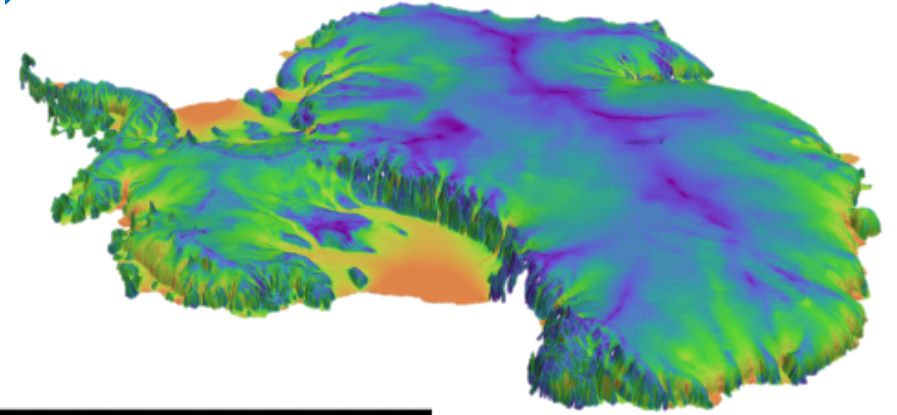
- We consider the production-level land-ice simulation software **Albany Land-Ice (ALI)**
- Effort is ongoing towards improving the performance portability of **ALI** for use on current and next-gen computing platforms
- Current targets for performance improvements include multigrid preconditioner with many runtime parameters



# MPAS-Albany Land Ice (MALI)

## What is MALI?

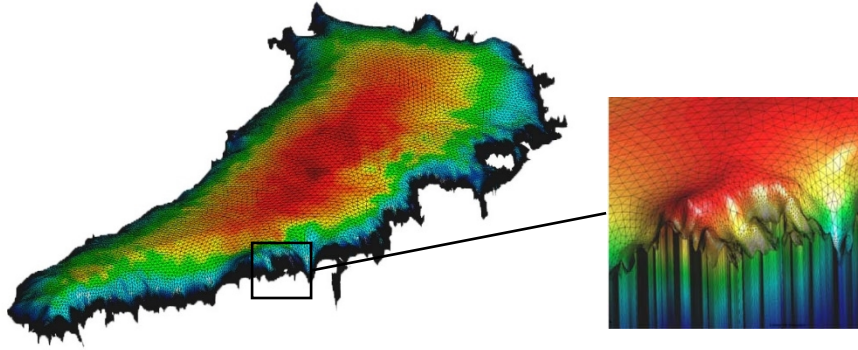
- U.S. DOE SciDAC-funded project land-ice modeling project, **FAnSSIE (Framework for Antarctic System Science in E3SM, FY23-FY27)**
- Albany Land Ice is the velocity solver of **MALI (MPAS-Albany Land Ice)**, the land-ice component of the U.S. DOE's Energy Exascale Earth System Model (E3SM)
- Portable performance is critical to target new and upcoming computing platforms such as NERSC's **Perlmutter** supercomputer



<https://github.com/MALI-Dev/E3SM>

# ALI's Multigrid Preconditioner

**Problem:** Ice sheet meshes are thin with high aspect ratios



**Solution:** Matrix dependent semi-coarsening algebraic multigrid (MDSC-AMG)<sup>1</sup>

- First, apply algebraic **structured** multigrid to coarsen vertically
- Second, apply **SA-AMG** on single layer

Performance of multigrid preconditioners depend on many **run-time parameters**

## Run-time parameters:

- Number of levels in the multigrid hierarchy
- Types of smoothing algorithms at fine/coarse levels:
  - **Multi-threaded Gauss-Seidel**
  - **Two-stage Gauss-Seidel**
  - **Chebyshev**
  - **Damped Block-Jacobi**
- Smoother-specific parameters such as:
  - **Multi-threaded/Two-stage Gauss-Seidel:**
    - Number of sweeps
    - Damping factor
  - **Damped Block-Jacobi:**
    - Number of sweeps
    - Damping factor
  - **Chebyshev:**
    - Eigenvalue ratio
    - Chebyshev expansion degree
    - Maximum number of iterations
- Aggregation parameters
- ...and more!



# Approach to Performance Tuning

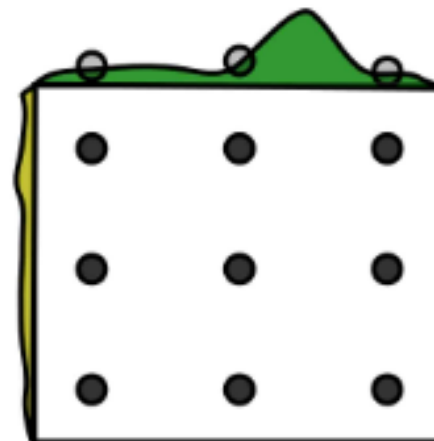
**Goal:** We want to find the optimal parameters to **minimize** solve time of ALI

- Gradient is not available for this optimization problem, treated as **blackbox optimization**
- Naïve methods for **blackbox optimization**: exhaustive/grid search and random search
- **Bayesian** search works by fitting a Gaussian model to performance data to allow for a more directed approach to exploring parameter space

## Offline vs Online Performance Tuning

- **Online** tuning evaluates candidate parameters on-the-fly during practical execution
- **Offline** tuning evaluates candidate parameters via trial execution and then optimal parameters are used for practical execution

Grid Search

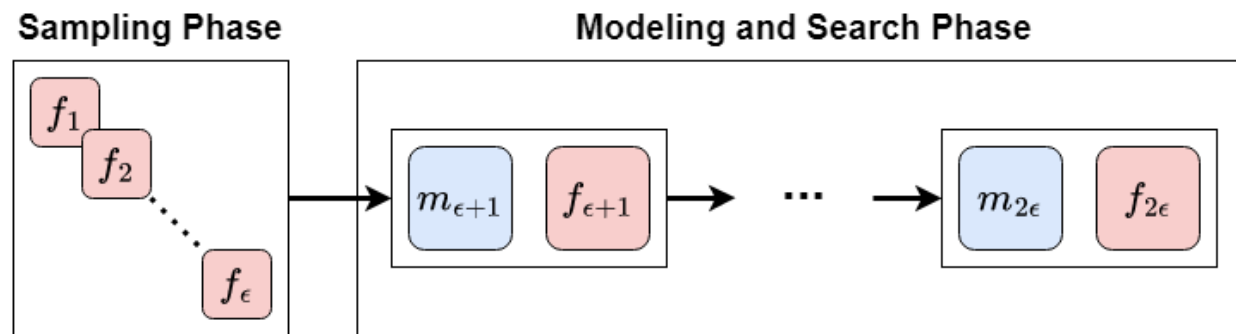


Random Search



# Approach to Performance Tuning (GPTune)

- **GPTune** is an autotuning software library with a Python interface that relies on multitask and transfer learning using Bayesian optimization methodologies for blackbox optimization.
- Provides a **reverse communication interface** for Bayesian optimization
  - Noninvasive, no instrumentation of Albany required
- Supports **transfer learning** for leveraging available performance data to potentially lower cost of future/larger tuning tasks



# Workflow Management: Automated Tuning

Tasks are assigned to running jobs on a computing cluster, minimizing time jobs have to wait in queue

## Problem:

- A single evaluation of the objective function requires solving a problem at scale with Albany Land-Ice
- Samples of the performance model can be evaluated in parallel
- Need to take advantage of as much computing power as is available

## Solution:

- Using the Python workflow management tool **Parsl**, the tuning workflow can be automated with **parallel efficiency** in mind



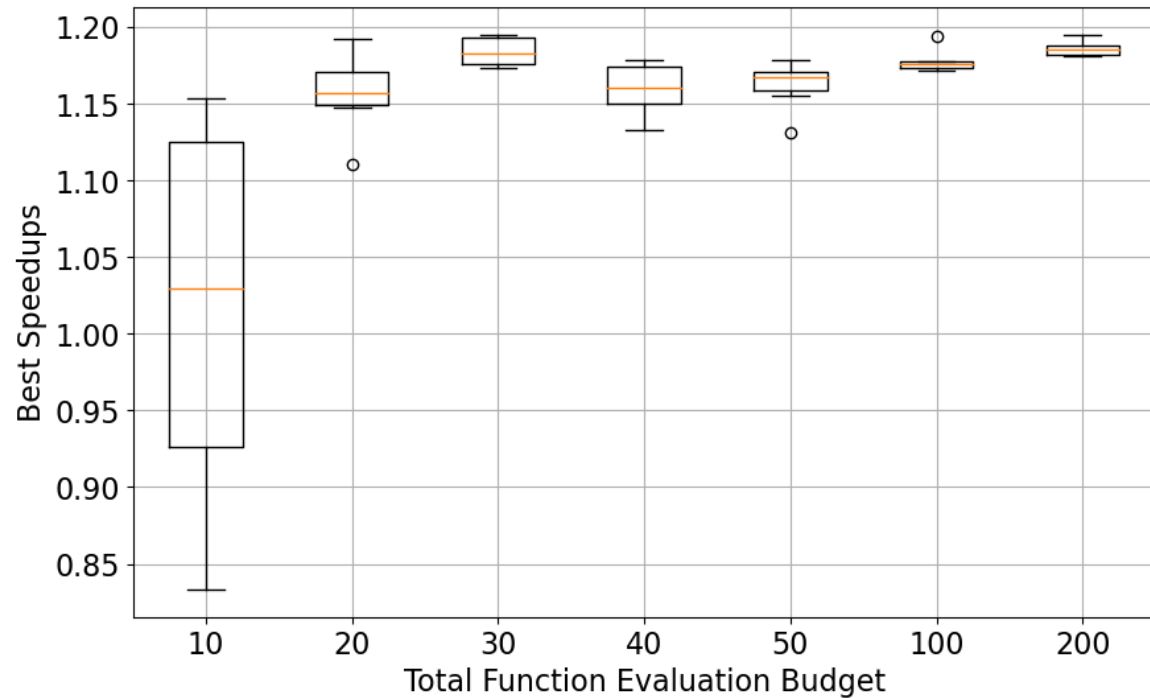
With a single Python script, we can ensure parallel efficiency for a variety of automated performance tuning tasks

```
1 # 1) get number of function evaluations
2 requested_num_evals = get_num_function_evals(...)
3 num_func_evals = requested_num_evals.result()
4
5 while num_func_evals > 0:
6
7     # 2) create function evaluation configuration files
8     requested_eval_configs = get_function_eval_configs(...)
9
10    # 3) do function evaluations
11    function_evaluated = []
12    for k in range(num_func_evals):
13        function_evaluated.append(evaluate_function(...))
14
15    # 4) get function evaluations
16    evaluation_results = []
17    for k in range(num_func_evals):
18        evaluation_results.append(get_evaluation_result(...))
19
20    # 5) write function evaluations to database
21    database_updated = update_database(...)
22
23    # 6) get remaining number of function evaluations
24    requested_num_evals = get_num_function_evals(...)
25    num_func_evals = requested_num_evals.result()
```



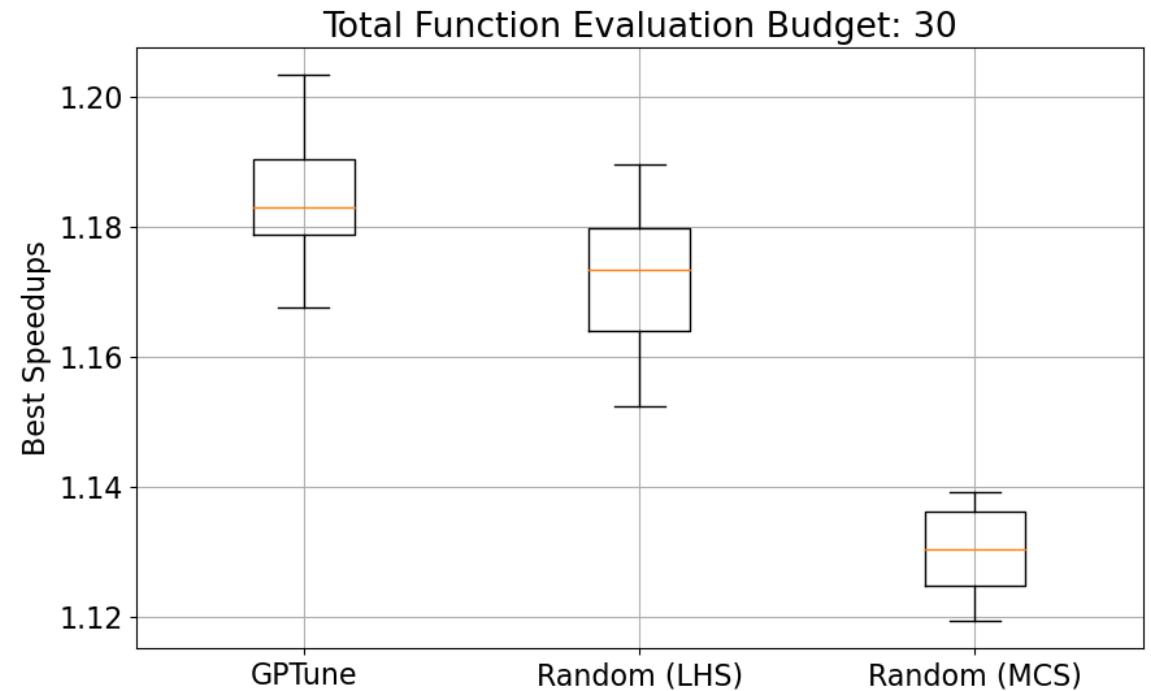
# GPtune Pre-tuning Analysis

Total function evaluation budget refers to the number of times ALI is allowed to run during the tuning process

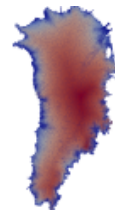


Good parameters can be found in relatively few runs of Albany

Extreme outliers can be found rarely with speedups up to 1.5x



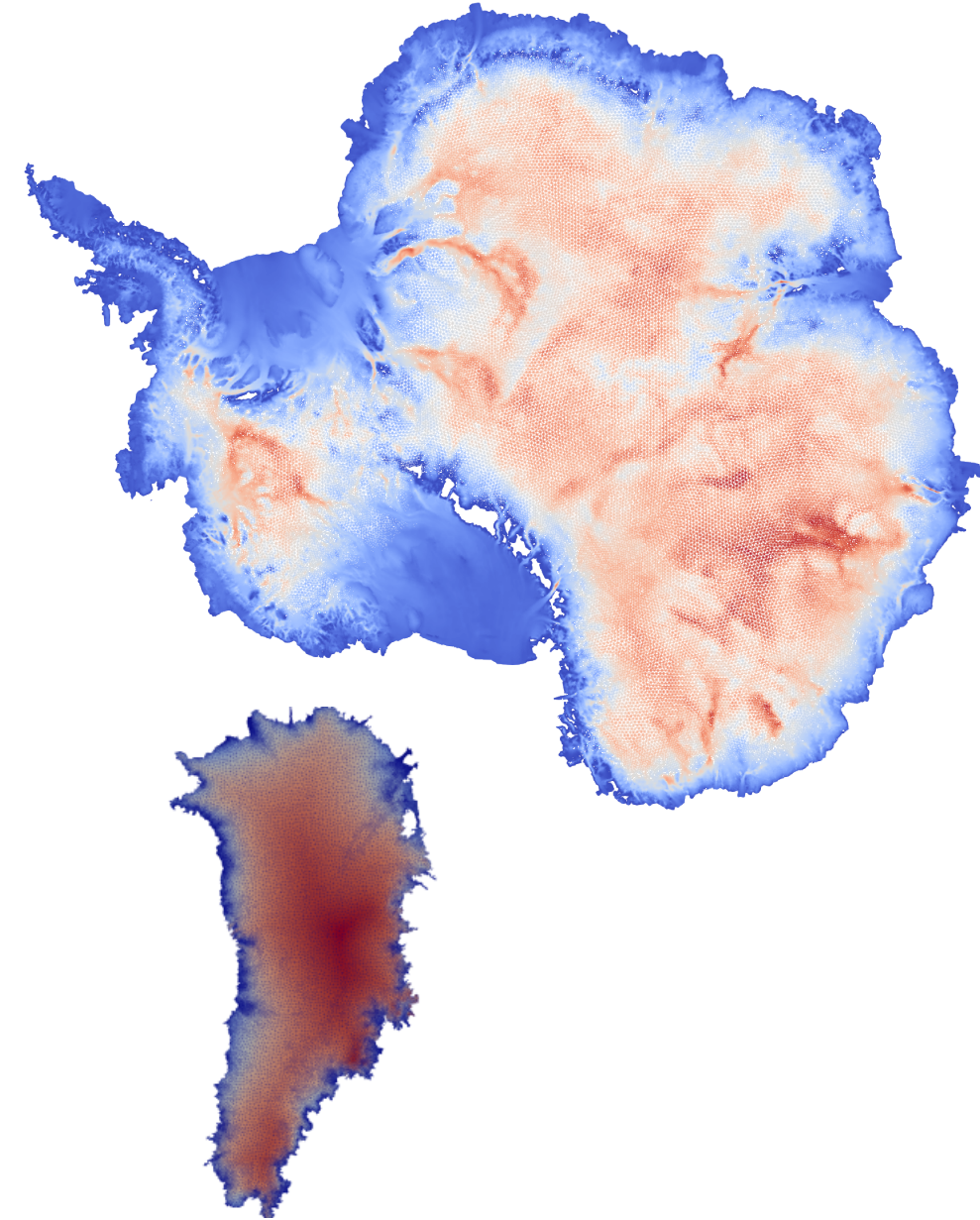
GPtune more reliably produces optimal parameters over random search



# Tuning Case Overview

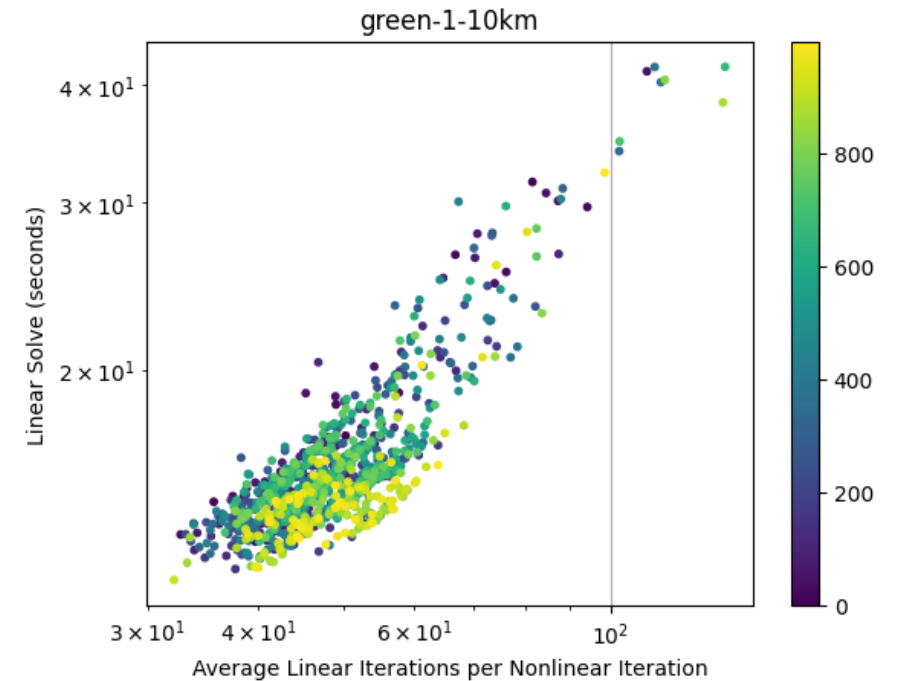
## Cases:

- Tuned on a variety of typical land ice meshes:
  - Antarctic Ice Sheet (AIS)
  - Greenland Ice Sheet (GIS)
- Variety of mesh resolutions
  - AIS: 2-10km resolution
  - AIS: 4-20km resolution
  - GIS: 1-10km resolution
- For 4-20km Antarctica mesh, tuned on a single node and on 8 GPU nodes to see impacts of strong scaling



# Chebyshev Smoother Tuning

- Followup tuning after tuning on smoother choice
- Tuning resulted in good speedup on top of the speedup from smoother selection tuning
- Optimal parameters resulted in best runtime AND convergence
- Optimal parameters for Antarctica meshes/setup are largely the same

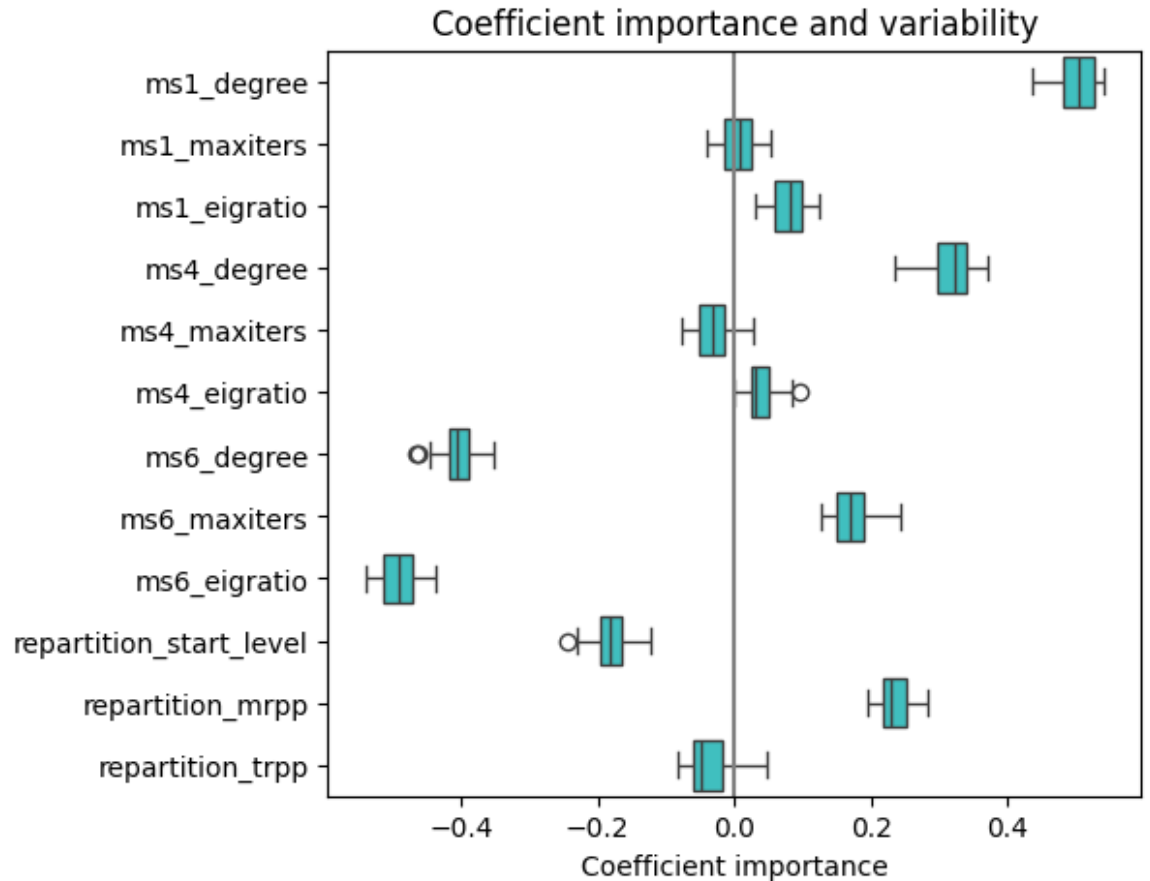


Case Name	Preconditioner Construction	Linear Solve	Total Solve	Tuning Speedup
green-1-10km	15.76s	12.37s	38.24s	~23% speedup
ant-4-20km-1node	7.39s	5.71s	18.13s	~25% speedup
ant-4-20km-8node	4.19s	3.99s	9.05s	~36% speedup
ant-2-10km-2node	15.6s	17.69s	43.9s	~29% speedup

# Chebyshev Smoother Tuning

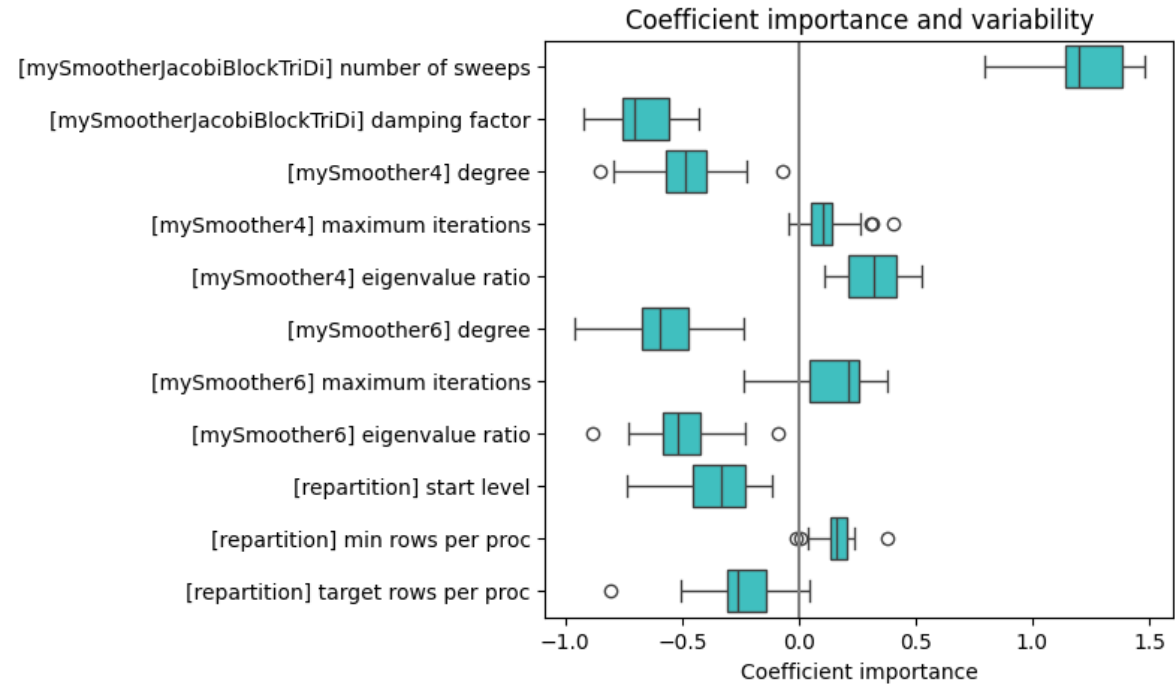
## Lessons learned:

- Low polynomial degree should be used for fine smoother and high polynomial degree for coarsest smoother
- Optimal parameters for polynomial degree landed at the extremes of the search space
- Number of levels in multigrid hierarchy has huge impact on solve time and convergence



# Block Jacobi Smoother Tuning

- Tuning offered very little speedup for this case
- Linear solve times and convergence are better but preconditioner construction is bottleneck
- Tuning data given to solver developers and solution has been identified



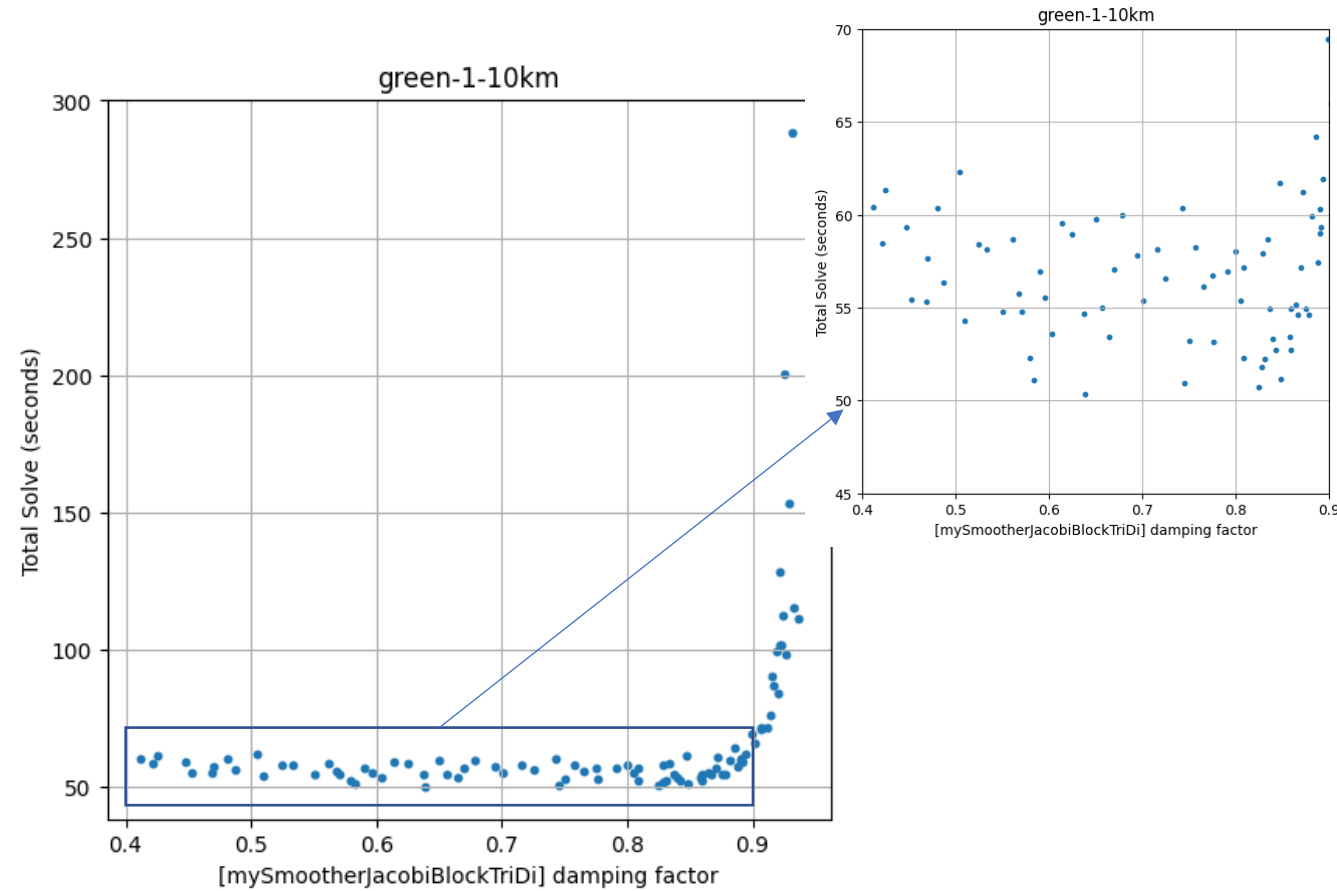
Case Name	Preconditioner Construction	Linear Solve	Total Solve	Tuning Speedup
green-1-10km	<b>32.2s</b>	8.2s	50.35s	~1% speedup
ant-4-20km-1node	<b>13.72s</b>	4.47s	23.16s	~1% speedup
ant-4-20km-8node	<b>5.53s</b>	3.37s	9.99s	~1% speedup
ant-2-10km-4node	<b>18.47s</b>	9.61s	33.59s	~2% speedup

Preconditioner construction time dominates total solve time but linear solve is a large improvement over the all-Chebyshev case

# Block Jacobi - Damping Factor

## Lessons Learned:

- Total solve time has a major bottleneck in preconditioner construction that tuning can't solve
- Solve time depends primarily on block-Jacobi fine smoother, less so on Chebyshev coarse smoothers
- Tuning data is helpful to pass on to solver developers



Optimal damping factor is around 0.63



# Looking ahead

## Takeaways:

- Automated performance tuning is capable of producing good multigrid parameters for a given problem in relatively few runs of Albany Land-Ice
- Bayesian optimization consistently produces better parameters than random search but could be improved

## Future work:

- Integrate with kokkos-tools to enable online tuning of MALI due to ice sheet instabilities over time
- Connect automated tuning framework with nightly performance testing to run tuning tasks when performance changepoints are detected
- Use **transfer learning** to leverage tuning results for small problems (such as Greenland ice sheet) to reduce cost of tuning large problems (such as Antarctica ice sheet)

