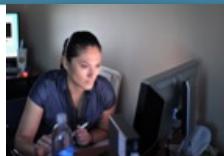




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An optimization-based coupling of reduced order models with efficient reduced adjoint basis generation approach



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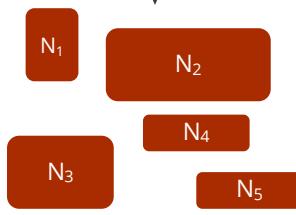
Heterogeneous Numerical Methods



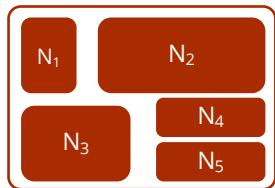
Model



Numerical parts



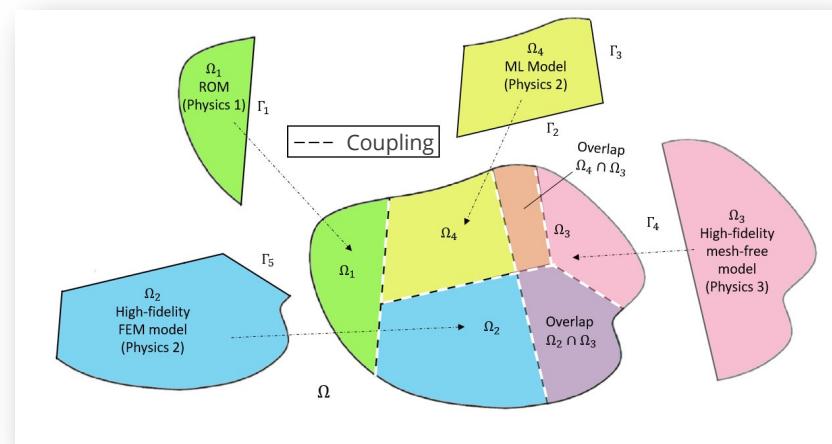
HNM



DOE applications require
diverse “mathematical parts”:
PDEs, integral equations, classical
DFT, potential-based atomistic...

Diverse math. models require
diverse “numerical parts”:
mesh based (FE, FV, FD),
meshless (SPH, MLS), implicit,
explicit, Eulerian, Lagrangian...

HNM = Collection of **diverse**
numerical parts from multiple
disciplines functioning together
as a **unified simulation tool**



Exemplar – Advection-Diffusion



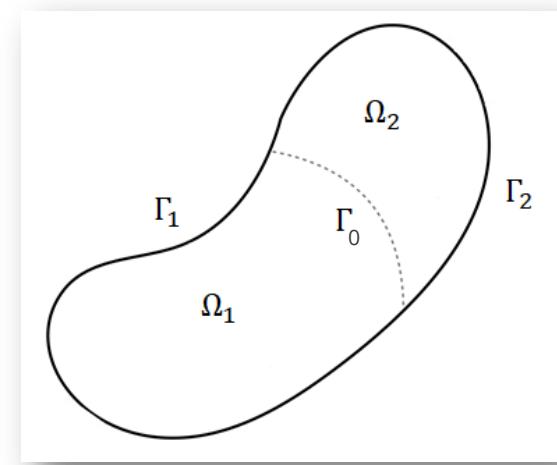
Coupled problem with "matching" interface conditions:

$$u_{i,t} - \nabla \cdot \sigma_i(u_i) = f_i \text{ in } \Omega_i$$

$$u_i = 0 \text{ on } \Gamma_i$$

$$u_1 = u_2 \text{ on } \Gamma_0$$

$$\sigma_1(u_1) \cdot n_1 = -\sigma_2(u_2) \cdot n_2 \text{ on } \Gamma_0$$



Non-overlapping DD of $\Omega = \Omega_1 \cup \Omega_2$.

where $\sigma_i(u) = \nu_i \nabla u - \mathbf{a}_i u$

Review - Decomposition with Optimization-Based Coupling



$$J_\delta(u_1^n, u_2^n, g^n) := \frac{1}{2} \| \color{red} u_1^n - u_2^n \|_{\Gamma_0}^2 + \frac{1}{2} \delta \| g^n \|_{\Gamma_0}^2$$

$$\min_{g^n} \quad J_\delta(u_1^n, u_2^n, g^n)$$

s.t. finding $u_i^n \in X_i$ satisfying

$$\frac{1}{\Delta t} (u_i^n - u_i^{n-1}, v) + (\sigma_i(u_i^n), \nabla v) = (f_i^n, v) + (-1)^i (\color{blue} g^n, v)_{\Gamma_0} \quad \forall v \in V_i$$

where $X_i = \{u \in H^1(\Omega_i) | u = 0 \text{ on } \Gamma_i\}$, $V_i = \{v \in H^1(\Omega_i) : v = 0 \text{ on } \Gamma_i\}$

Review - Relaxation with Lagrangian



We next introduce a Lagrangian in order to relax the constrained minimization problem,

$$\mathcal{L}(u_1^n, u_2^n, g^n, \mu_1, \mu_2) := J_\delta(u_1^n, u_2^n, g^n) + \sum_{i=1}^2 \left[\frac{1}{\Delta t} (u_i^n - u_i^{n-1}, \mu_i) + (\sigma_i(u_i^n), \nabla \mu_i) - (f_i^n, \mu_i) + (-1)^{i+1} (\mathbf{g}^n, \mu_i)_{\Gamma_0} \right]$$

and we solve for its stationary points.

$$\begin{aligned} \frac{\partial \mathcal{L}(u_1^n, u_2^n, g^n, \mu_1, \mu_2)}{\partial \mu_i} = 0 & \quad (\text{State, primal problem}) & \frac{1}{\Delta t} (u_i^n - u_i^{n-1}, v) + (\sigma_i(u_i^n), \nabla v) = (f_i^n, v) + (-1)^i (\mathbf{g}^n, v)_{\Gamma_0} \quad \forall v \in V_i \\ \frac{\partial \mathcal{L}(u_1^n, u_2^n, g^n, \mu_1, \mu_2)}{\partial u_i^n} = 0 & \quad (\text{Adjoint problem}) & \frac{1}{\Delta t} (\mu_i, \eta) + (\nu_i \nabla \mu_i + \mathbf{a}_i \mu_i, \nabla \eta) = (-1)^i (\mathbf{u}_1^n - \mathbf{u}_2^n, \eta)_{\Gamma_0} \quad \forall \eta \in X_i^n \\ \frac{\partial \mathcal{L}(u_1^n, u_2^n, g^n, \mu_1, \mu_2)}{\partial g^n} = 0 & \quad (\text{Informs update to control}) & \delta(\psi, g^n)_{\Gamma_0} = -(\psi, \mu_1 - \mu_2)_{\Gamma_0} \quad \forall \psi \in L^2(\Gamma_0) \end{aligned}$$

Gradient Descent $g^{n,(k)} = (1 - \alpha \delta) g^{n,(k-1)} - \alpha (\mu_1^{(k)} - \mu_2^{(k)})|_{\Gamma_0}$

Application of Finite Element Method to OBC



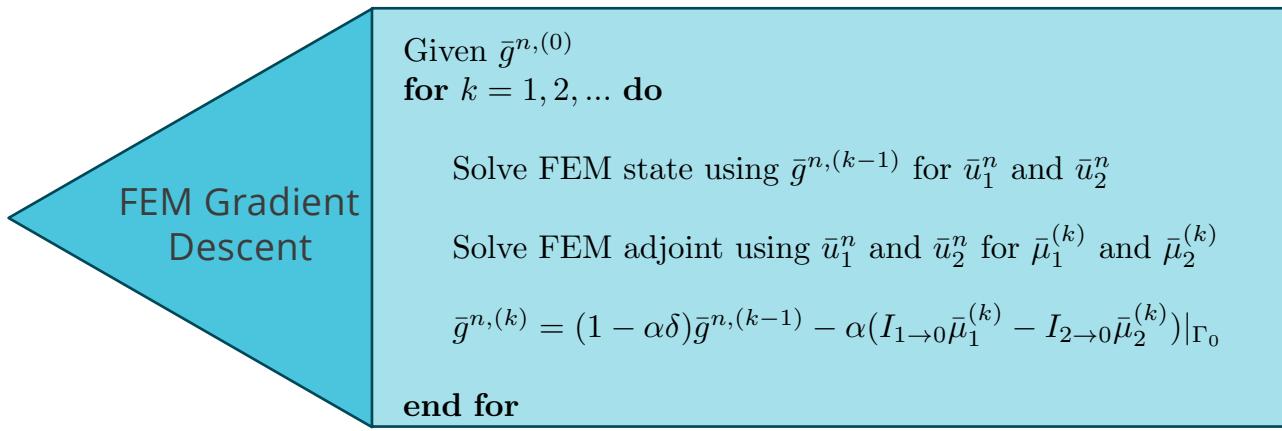
Find $\bar{u}_i^n \in \mathbb{R}^{N_i}$ satisfying

$$\frac{1}{\Delta t} M_i \bar{u}_i^n + (\nu_i K_i - A_i) \bar{u}_i^n = \bar{f}_i^n + (-1)^i M_{\Gamma_0, i} \bar{g}^n + \frac{1}{\Delta t} M_i \bar{u}_i^{n-1} \quad (\text{FEM State})$$

Find $\bar{\mu}_i \in \mathbb{R}^{N_i}$ satisfying

$$\frac{1}{\Delta t} M_i \bar{\mu}_i + (\nu_i K_i + A_i^T) \bar{\mu}_i = (-1)^i M_{\Gamma_0, i} (\bar{u}_1 - \bar{u}_2) \quad (\text{FEM Adjoint})$$

where $(M_i)_{k,j} := (\phi_{i,k}, \phi_{i,j})$, $(K_i)_{k,j} := (\nabla \phi_{i,k}, \nabla \phi_{i,j})$, $(A_i)_{k,j} := (\mathbf{a} \phi_{i,k}, \nabla \phi_{i,j})$, $(\bar{f}_i^n)_k := (f_i^n, \phi_{i,k})$, and $(M_{\Gamma_0, i})_{k,j} := (\xi_{\Gamma_0, j}, \xi_{i,k})$



Adaptation to ROM-ROM Coupling



Find $\hat{u}_i^n \in \mathbb{R}^{N_{u_i,r}}$ satisfying

$$\frac{1}{\Delta t} \hat{M}_i \hat{u}_i^n + (\nu_i \hat{K}_i - \hat{A}_i) \hat{u}_i^n = \hat{f}_i^n + (-1)^i M_{\Gamma_0,i} \bar{g} + \frac{1}{\Delta t} \hat{M}_i \hat{u}_i^{n-1} \quad (\text{ROM State})$$

Find $\hat{\mu}_i \in \mathbb{R}^{N_{\mu_i,r}}$ satisfying

$$\frac{1}{\Delta t} \tilde{M}_i \hat{\mu}_i + (\nu_i \tilde{K}_i + \tilde{A}_i^T) \hat{\mu}_i = (-1)^i (\Psi_{\mu,i}^T M_{\Gamma_0,i} (\Psi_{u,1} \hat{u}_1^n - \Psi_{u,2} \hat{u}_2^n) + \Psi_{u,i}^T (\bar{\beta}_1^n - \bar{\beta}_2^n)) \quad (\text{ROM Adjoint})$$

where $\hat{M}_i := \Psi_{\mu,i}^T M_i \Psi_{\mu,i}$, $\hat{K}_i = \Psi_{\mu,i}^T K_i \Psi_{\mu,i}$, $\hat{A}_i := \Psi_{\mu,i}^T A_i \Psi_{u,i}$

with ROM change of basis:

$$\Psi_{u,i} \hat{u}_i^n + \bar{\beta}_i^n = \bar{u}_i^n; \quad \hat{u}_i \in \mathbb{R}^{N_{u_i,r}}$$

$$\Psi_{\mu,i} \hat{\mu}_i = \bar{\mu}_i; \quad \hat{\mu}_i \in \mathbb{R}^{N_{\mu_i,r}}$$

How is the adjoint reduced basis $\Psi_{\mu,i}$ generated?

ROM Gradient Descent

Given $\bar{g}^{n,(0)}$
for $k = 1, 2, \dots$ do

Solve ROM state using $\bar{g}^{n,(k-1)}$ for \hat{u}_1^n and \hat{u}_2^n

Solve ROM adjoint using \hat{u}_1^n , and \hat{u}_2^n for $\hat{\mu}_1^{(k)}$ and $\hat{\mu}_2^{(k)}$

$$\bar{g}^{n,(k)} = (1 - \alpha\delta) \bar{g}^{n,(k-1)} - \alpha (I_{1 \rightarrow 0} \Psi_{\mu,1} \hat{\mu}_1^{(k)} - I_{2 \rightarrow 0} \Psi_{\mu,2} \hat{\mu}_2^{(k)})|_{\Gamma_0}$$

end for

Adaptation to ROM-ROM Coupling



How do we most appropriately/efficiently generate snapshots for a suitable ROM basis for the adjoint system?

- Collecting snapshots of the state problem is well understood
- We make the assumption that the state snapshots are still available at the time of generating adjoint snapshots
- Below are several obvious ways to collect snapshots (**a,b**) and another way proposed by our group and investigated in this presentation (**c**):
 - a) Use state snapshots to form a reduced basis for the adjoint
 - b) Sequentially solve the FOM-FOM coupled problem with an OBC approach, storing all iterations at all timesteps
 - c) A modified version of b) that uses state snapshots to decouple timesteps and a fixed number of gradient descent iterations per timestep to reduce the adjoint snapshot size

Adaptation to ROM-ROM Coupling



Gradient Descent m for Reduced Adjoint

Given $\bar{g}^{n,(0)}$

for $k = 1, 2, \dots$ **do**

Solve FEM state using \bar{u}_1^{n-1} , \bar{u}_2^{n-1} , and $\bar{g}^{n,(k-1)}$ for \bar{u}_1^n and \bar{u}_2^n

Solve FEM adjoint using \bar{u}_1^n and \bar{u}_2^n for $\bar{\mu}_1^{(k)}$ and $\bar{\mu}_2^{(k)}$

$\bar{g}^{n,(k)} = (1 - \alpha\delta)\bar{g}^{n,(k-1)} - \alpha(I_{1 \rightarrow 0}\bar{\mu}_1^{(k)} - I_{2 \rightarrow 0}\bar{\mu}_2^{(k)})|_{\Gamma_0}$

end for

With traditional gradient descent, the solution at timestep (n-1) is needed and must be highly accurate (very tight tolerance for OBC)

Modified Gradient Descent m for Reduced Adjoint

Given $\bar{g}^{n,(0)}$

for $k = 1, 2, \dots$ **do**

Solve FEM state using $\bar{u}_{SNAP,1}^{n-1}$, $\bar{u}_{SNAP,2}^{n-1}$, and $\bar{g}^{n,(k-1)}$ for \bar{u}_1^n and \bar{u}_2^n

Solve FEM adjoint using \bar{u}_1^n and \bar{u}_2^n for $\bar{\mu}_1^{(k)}$ and $\bar{\mu}_2^{(k)}$

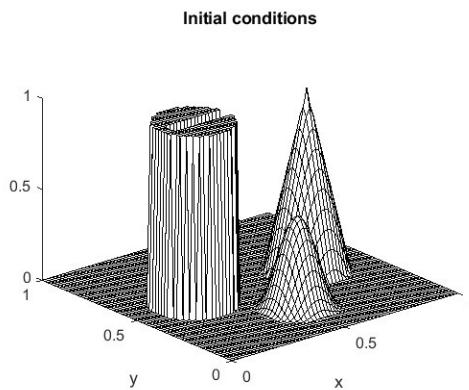
$\bar{g}^{n,(k)} = (1 - \alpha\delta)\bar{g}^{n,(k-1)} - \alpha(I_{1 \rightarrow 0}\bar{\mu}_1^{(k)} - I_{2 \rightarrow 0}\bar{\mu}_2^{(k)})|_{\Gamma_0}$

end for

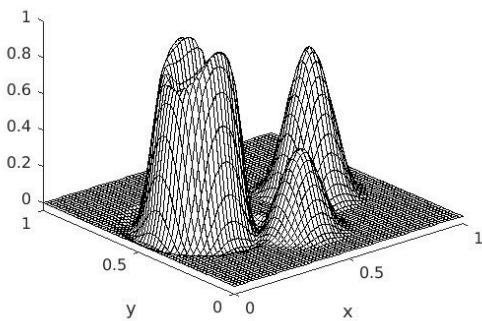
Observation: Replace solution at previous timestep (n-1) with solution corresponding to that time in state snapshot matrix (breaks connection between timesteps [parallel] and allows GD tolerance to be loosened [cheaper])

Leaves open the choice of what to choose for $\bar{g}^{n,(0)}$ at each timestep. We choose $\bar{g}^{n,(0)} = \vec{0}$.

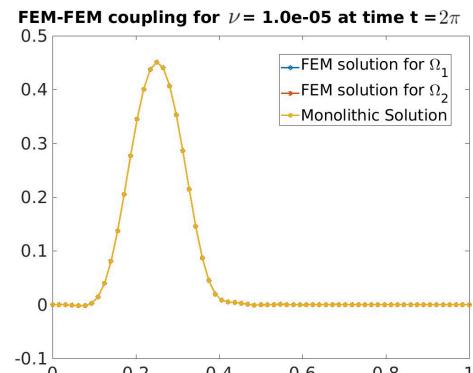
Numerical Result – OBC FOM-FOM Coupled Problem



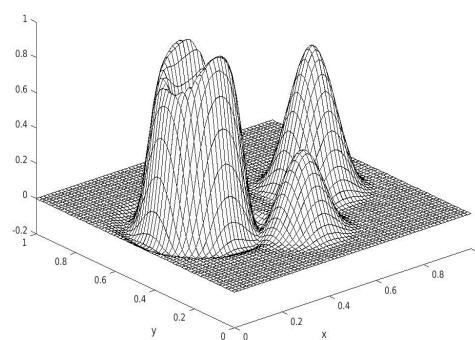
Monolithic FEM solution for $\nu = 1e - 5$ at time $t=2\pi$



$$\Delta t = 1.122398e - 3 \quad h = \frac{1}{64} \quad \nu = 1e - 5$$



FEM-FEM coupling for $\nu = 1e - 5$ at time $t=2\pi$

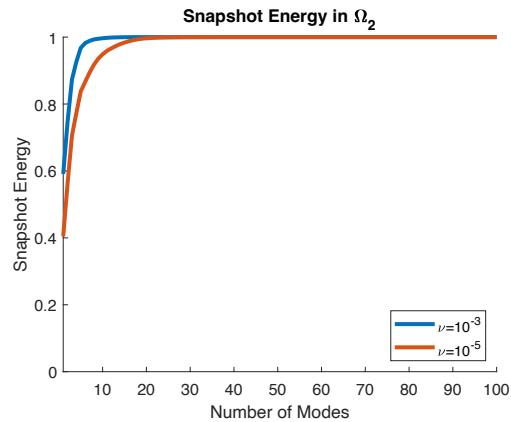
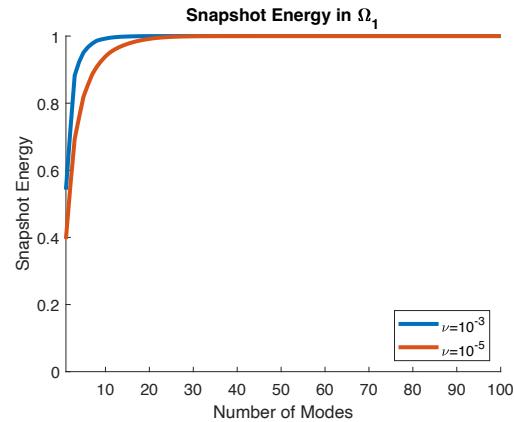


Coupled FEM-FEM results with $\delta = 1e - 16$ and tolerance of $1e - 14$ results in:

$$\frac{\|u_c - u_m\|_{L^2}}{\|u_m\|_{L^2}} = 7.8e - 8$$

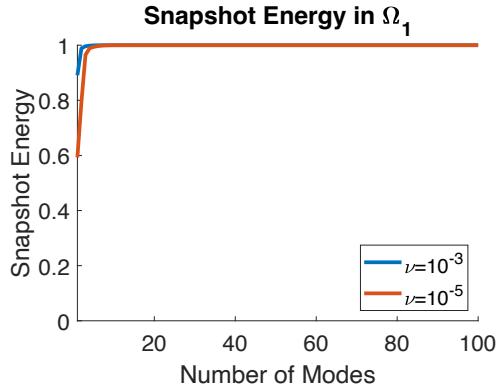
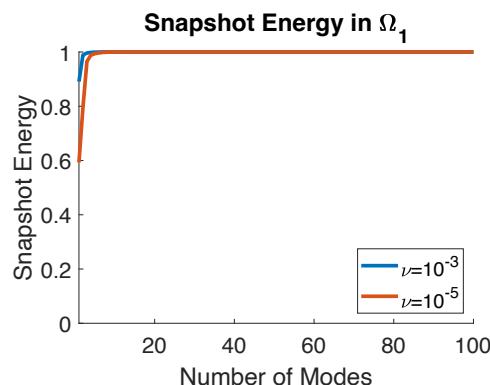
Balance of mismatched states and penalty term for the control indicates error should be roughly $\sqrt{\text{tolerance}}$

Numerical Result – Applicability of P-ROM



Snapshot energy in state solutions as a function of modes

Quick decay of snapshot energies w.r.t. # of modes



Snapshot energy in adjoint solutions as a function of modes

Numerical Result – Comparison Using Different Reduced Spaces for the Adjoint



RS - Reduced state

FS - FOM state

SRA - State solution-based reduced adjoint

MGD1RA - Modified gradient descent - 1 iteration

FA - FOM adjoint

Takeaway #1: State solutions used to produce reduced basis for adjoint doesn't work until ~ 1500 modes retained. Replacing SRA with FA has significant impact. Can we do better?

RS-FA		
Modes	Error	Iters.
50	10^{-4}	*
100	10^{-7}	50.1
250	10^{-7}	36.9
500	10^{-7}	21.4
1000	10^{-7}	9.8
1500	10^{-8}	4.4
1600	10^{-8}	4.4
1700	10^{-8}	4.4
1800	10^{-8}	4.4
2016	10^{-8}	3

RS-SRA			FS-SRA	
Modes	Error	Iters.	Error	Iters.
50	10^{-3}	*	10^{-4}	*
100	10^{-3}	*	10^{-4}	*
250	10^{-5}	*	10^{-4}	*
500	10^{-6}	*	10^{-5}	*
1000	10^{-7}	*	10^{-6}	*
1500	10^{-7}	506.7	10^{-8}	139.8
1600	10^{-8}	68.6	10^{-8}	48.2
1700	10^{-8}	21.1	10^{-8}	11.9
1800	10^{-8}	14.8	10^{-8}	9
2016	10^{-8}	3	10^{-8}	3

RS-MGD1RA			FS-MGD1RA	
Modes	Error	Iters.	Error	Iters.
50	10^{-4}	*	10^{-7}	*
100	10^{-5}	2342.8	10^{-8}	4.2
250	10^{-6}	401.5	10^{-8}	4
500	10^{-7}	102.8	10^{-8}	3.7
1000	10^{-7}	35.2	10^{-8}	3.7
1500	10^{-8}	7.8	10^{-8}	3.7
1600	10^{-8}	6.6	10^{-8}	3.7
1700	10^{-8}	6.5	10^{-8}	3.7
1800	10^{-8}	6.5	10^{-8}	3.7
2016	10^{-8}	3	10^{-8}	3

$\delta = 1e-16$ and tolerance of $1e-14$, $\nu = 1e-5$

Numerical Result – Comparison Using Different Reduced Spaces for the Adjoint



RS - Reduced state
FS - FOM state

SRA - State solution-based reduced adjoint
MGD1RA - Modified gradient descent – 1 iteration
FA - FOM adjoint

Takeaway #2: MGD1RA outperforms SRA and doesn't require many modes (# of state modes kept is more important)

RS-FA		
Modes	Error	Iters.
50	10^{-4}	*
100	10^{-7}	50.1
250	10^{-7}	36.9
500	10^{-7}	21.4
1000	10^{-7}	9.8
1500	10^{-8}	4.4
1600	10^{-8}	4.4
1700	10^{-8}	4.4
1800	10^{-8}	4.4
2016	10^{-8}	3

RS-SRA			FS-SRA	
Modes	Error	Iters.	Error	Iters.
50	10^{-3}	*	10^{-4}	*
100	10^{-3}	*	10^{-4}	*
250	10^{-5}	*	10^{-4}	*
500	10^{-6}	*	10^{-5}	*
1000	10^{-7}	*	10^{-6}	*
1500	10^{-7}	506.7	10^{-8}	139.8
1600	10^{-8}	68.6	10^{-8}	48.2
1700	10^{-8}	21.1	10^{-8}	11.9
1800	10^{-8}	14.8	10^{-8}	9
2016	10^{-8}	3	10^{-8}	3

RS-MGD1RA			FS-MGD1RA	
Modes	Error	Iters.	Error	Iters.
50	10^{-4}	*	10^{-7}	*
100	10^{-5}	2342.8	10^{-8}	4.2
250	10^{-6}	401.5	10^{-8}	4
500	10^{-7}	102.8	10^{-8}	3.7
1000	10^{-7}	35.2	10^{-8}	3.7
1500	10^{-8}	7.8	10^{-8}	3.7
1600	10^{-8}	6.6	10^{-8}	3.7
1700	10^{-8}	6.5	10^{-8}	3.7
1800	10^{-8}	6.5	10^{-8}	3.7
2016	10^{-8}	3	10^{-8}	3

$\delta = 1e-16$ and tolerance of $1e-14$, $\nu = 1e-5$

Numerical Result – Projection Errors (State and Adjoint)



Modes	RS	
	$\mathcal{E}(u_1, \Psi_{u,1})$	$\mathcal{E}(u_2, \Psi_{u,2})$
50	10^{-3}	10^{-3}
100	10^{-8}	10^{-7}
250	10^{-9}	10^{-8}
500	10^{-9}	10^{-8}
1000	10^{-9}	10^{-8}
1500	10^{-9}	10^{-8}
2016	10^{-15}	10^{-15}

Projection of state solutions onto reduced basis generated from state solution snapshots

Modes	SRA	
	$\mathcal{E}(\mu_1, \Psi_{u,1})$	$\mathcal{E}(\mu_2, \Psi_{u,2})$
50	10^{-1}	10^{-1}
2000	10^{-1}	10^{-1}
2001	10^{-2}	10^{-2}
2014	10^{-2}	10^{-2}
2015	10^{-3}	10^{-3}
2016	10^{-15}	10^{-15}

Takeaway #3: State solutions should not be used to generate reduced basis for adjoint

Projection of adjoint solutions onto reduced basis generated from state solution snapshots

Modes	GDRA		MGD1RA	
	$\mathcal{E}(\mu_1, \Psi_{\mu,1})$	$\mathcal{E}(\mu_2, \Psi_{\mu,2})$	$\mathcal{E}(\mu_1, \Psi_{\mu,1})$	$\mathcal{E}(\mu_2, \Psi_{\mu,2})$
50	$10^{-4} - 10^{-3}$	$10^{-6} - 10^{-5}$	$10^{-4} - 10^{-3}$	$10^{-6} - 10^{-5}$
100	$10^{-15} - 10^{-14}$	10^{-15}	$10^{-15} - 10^{-14}$	10^{-15}
500	$10^{-15} - 10^{-14}$	10^{-15}	$10^{-15} - 10^{-14}$	10^{-15}
1500	$10^{-15} - 10^{-14}$	10^{-15}	$10^{-15} - 10^{-14}$	10^{-15}
2016	10^{-15}	10^{-15}	10^{-15}	10^{-15}

Projection of adjoint solutions onto reduced basis generated from GDRA and MGD1RA

Numerical Result – Interplay of state and adjoint ROM modes



State/Adjoint Reduced Space Modal Size Comparison

RS Modes	50		100		250	
MGD1RA Modes	Avg. Iters.	Error	Avg. Iters.	Error	Avg. Iters.	Error
25	*	10^{-4}	4498.8	10^{-6}	*	10^{-4}
50	*	10^{-4}	761.5	10^{-6}	2119.8	10^{-6}
100	*	10^{-4}	2342.8	10^{-5}	536.9	10^{-6}

$\delta = 1e - 16$ and tolerance of $1e - 14$, $\nu = 1e - 5$

RS Modes	50		100		250	
MGD1RA Modes	Avg. Iters.	Error	Avg. Iters.	Error	Avg. Iters.	Error
25	*	10^{-4}	349	10^{-5}	4246.4	10^{-6}
50	*	10^{-4}	170.7	10^{-5}	312.4	10^{-6}
100	*	10^{-4}	150.4	10^{-5}	129.5	10^{-5}

$\delta = 1e - 14$ and tolerance of $1e - 12$, $\nu = 1e - 5$

RS Modes	50		100		250	
MGD1RA Modes	Avg. Iters.	Error	Avg. Iters.	Error	Avg. Iters.	Error
25	15.2	10^{-3}	9.3	10^{-4}	15.6	10^{-4}
50	18.9	10^{-3}	11.4	10^{-4}	8.8	10^{-4}
100	12.7	10^{-3}	8.4	10^{-4}	6.2	10^{-4}

$\delta = 1e - 10$ and tolerance of $1e - 8$, $\nu = 1e - 5$

Takeaway #4:
 Important to balance reduced space state and reduced space adjoint number of modes.
 Also, loosening tolerance and increasing penalty increases rate of convergence.

Numerical Result – MGDMRA vs. GDRA

What is lost from limiting ourselves to m iterations?



Takeaway #5: Similar iterations and runtimes for GDRA and MGD1RA; both beating the FOM-FOM coupled problem

Average Iteration Comparison

RS Modes	100		250		
MGD1RA Modes	Avg. Iters.	Error	Avg. Iters.	Error	
50	170.7	10^{-5}	312.4	10^{-6}	
100	150.4	10^{-5}	129.5	10^{-5}	
GDRA Modes					
50	170.7	10^{-5}	371.2	10^{-6}	
100	242.1	10^{-5}	143.2	10^{-5}	

$$\nu = 1e - 5$$

Runtime Comparison

$\nu = 10^{-5}$			$\nu = 10^{-3}$		
FOM	MGD1RA ROM	GDRA ROM	FOM	MGD1RA ROM	GDRA ROM
86 sec	33 sec	32 sec	131 sec	76 sec	76 sec

Conclusions

- Introduced a snapshot collection technique (MGDmRA) for producing a reduced basis for the adjoint of a ROM-ROM OBC problem
 - Broke the connection between timesteps by using state snapshot data
 - Fixed memory / computational footprint by selecting a fixed subset of gradient descent iterations per timestep
- Numerical experiments indicate:
 - State snapshots are not effective for producing a reduced basis for the adjoint
 - MGDmRA produces a basis that is competitive with the reduced basis generated by gradient descent (run sequentially with a tight tolerance) in iteration counts, projection errors, and computational time (with reduced offline cost).

Future Work

- Explore FOM-ROM combinations
- Improved optimization algorithms (far fewer iterations)

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