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MIXED-MODE INTERFACIAL FRACTURE TESTING USING DUAL ACTUATOR TEST FRAME

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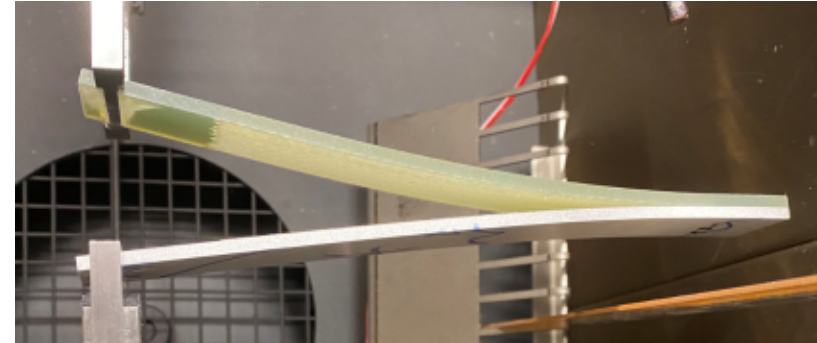
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INTERFACIAL FRACTURE

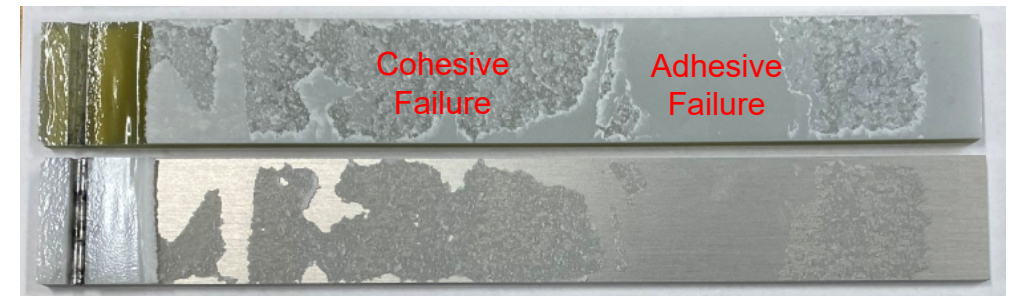
- Manufacturing defects or in-service damage can lead to fracture based failure
- Isotropic materials fracture under Mode I
- Laminated materials activate more energetic fracture modes
 - Anisotropy
 - Preferential fracture paths
- Bonded joints tend to fail either at the interface (adhesive failure) or within the adhesive (cohesive failure)
- Rarely are any failures pure Mode I or pure Mode II



Mode I – DCB experiment with co-bonded GFRP to Aluminum



Mode II – ENF experiment with co-cured GFRP to CFRP

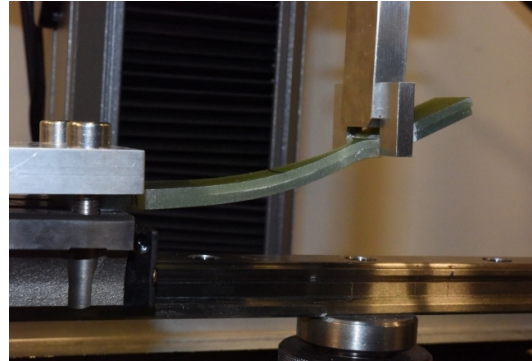


Failure surface of Mode I DCB with GFRP secondarily bonded to Aluminum with epoxy, mixture of adhesive and cohesive failure

FRACTURE TESTING



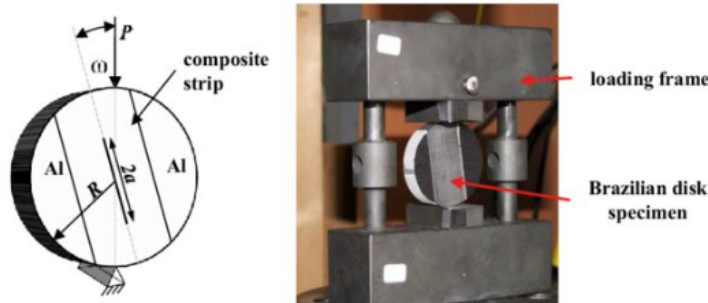
- Mode I
 - Double cantilever beam (DCB)
 - Wedge insertion
 - Compact tension
 - Single edge notched bending
- Mode II
 - End notched flexure (ENF)
 - End loaded split (ELS)
- Mixed mode I/II
 - Mixed mode bending (MMB)
 - Asymmetric DCB
 - Single leg bending
 - Brazilian disc
 - **Dual actuator loading**
- Many others



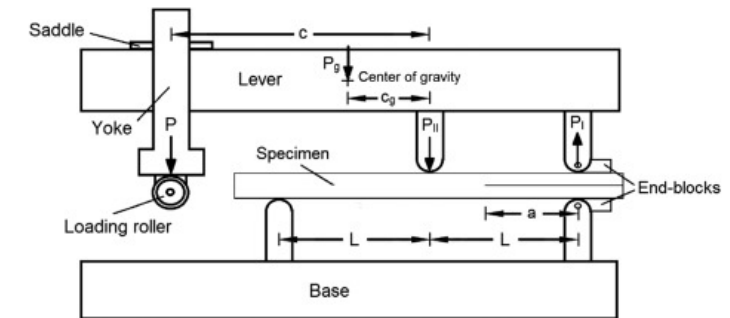
End loaded split (ELS)



End notched flexure (ENF)



Brazilian disc test¹



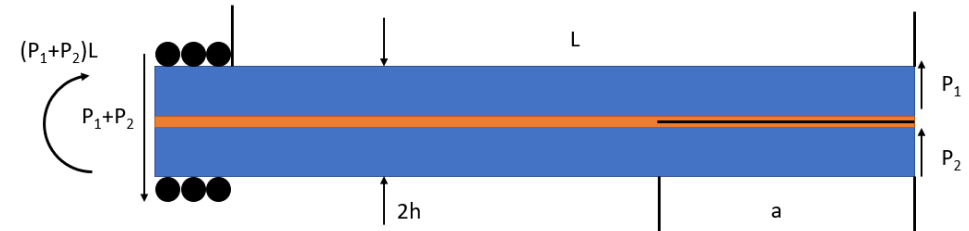
Mixed mode bending (MMB)²

¹Mega, Mor & Banks-Sills, Leslie. (2018). Testing of Brazilian Disk Specimens With a Delamination Between a Transversely Isotropic and a Tetragonal Composite Ply. *Procedia Structural Integrity*. 13. 123-130. 10.1016/j.prostr.2018.12.021.

²Bamber Blackman, et.al, 17 - Understanding fracture mode-mixity and its effects on bond performance, Editor(s): David A. Dillard, In Woodhead Publishing in Materials, *Advances in Structural Adhesive Bonding (Second Edition)*, Woodhead Publishing, 2023, Pages 579-613

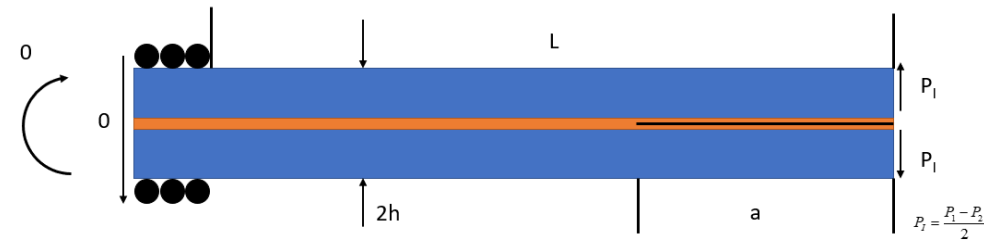
DUAL ACTUATOR TESTING

- Developed by Dillard et al.
- Current work by Liechti et al.
- Independent loading of each adherend
 - Superposition of DCB and ELS
 - Displacement, load, or moment control
- Assumptions in this work (ongoing)
 - Linear elastic
 - Plane strain
 - Slender beams – no shear contribution
 - Small deformations/rotations
- Current testing is displacement controlled
- Simple beam theory and two J-integral based data reduction schemes investigated



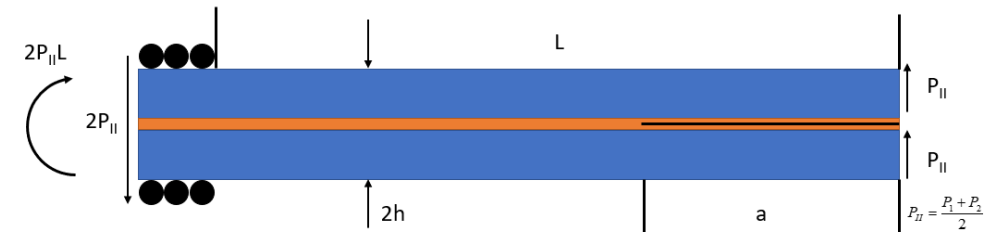
General Test

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Mode I (DCB)

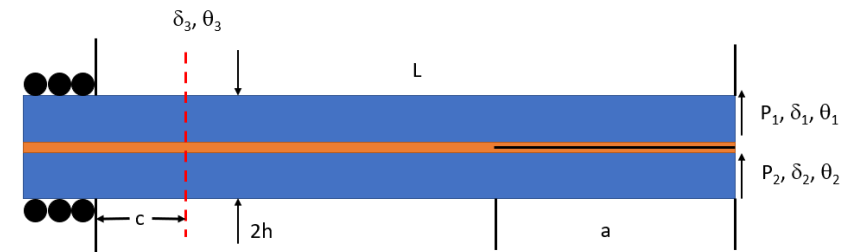
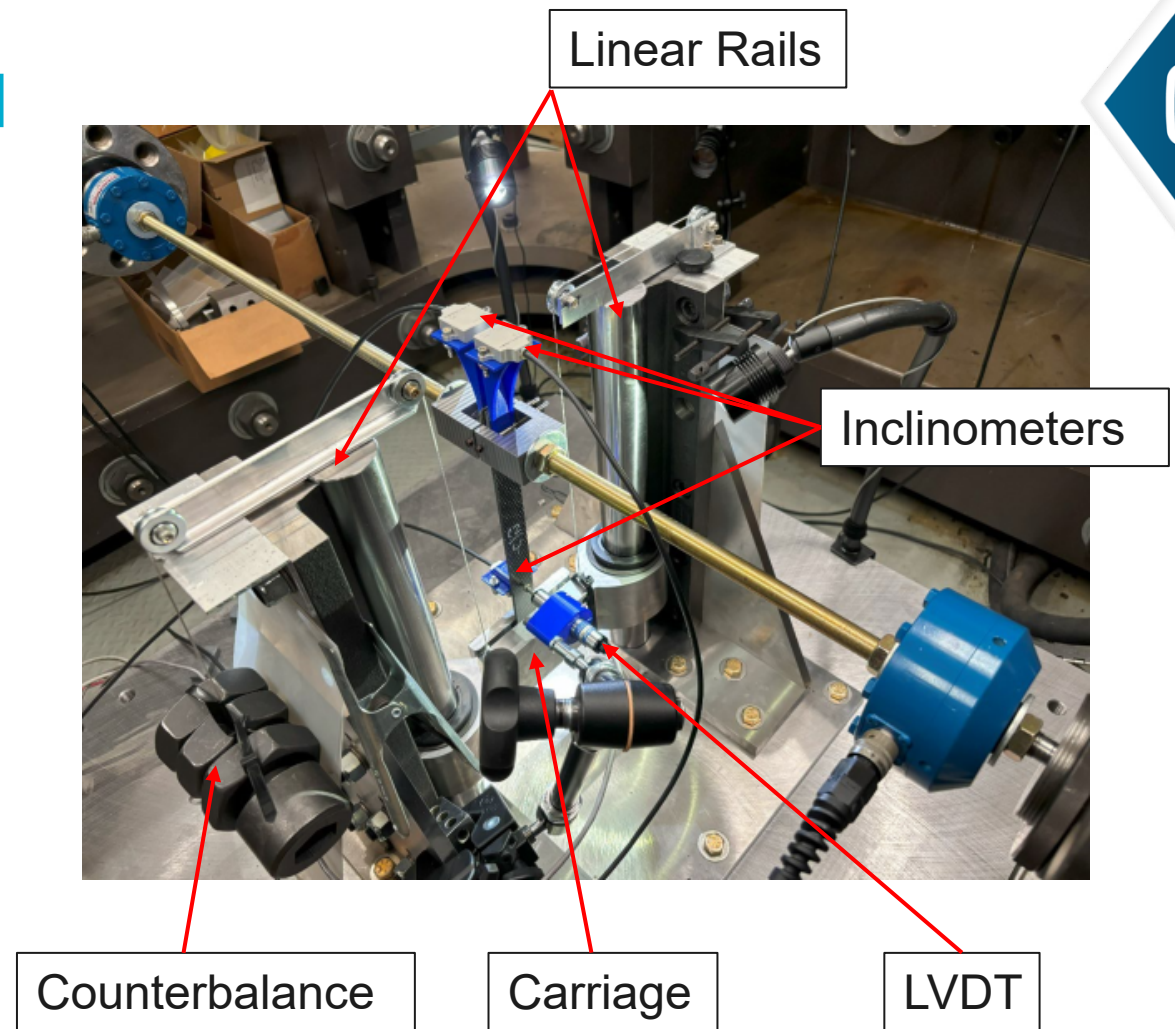
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Mode II (ELS)

EXPERIMENTAL FIXTURE DESIGN

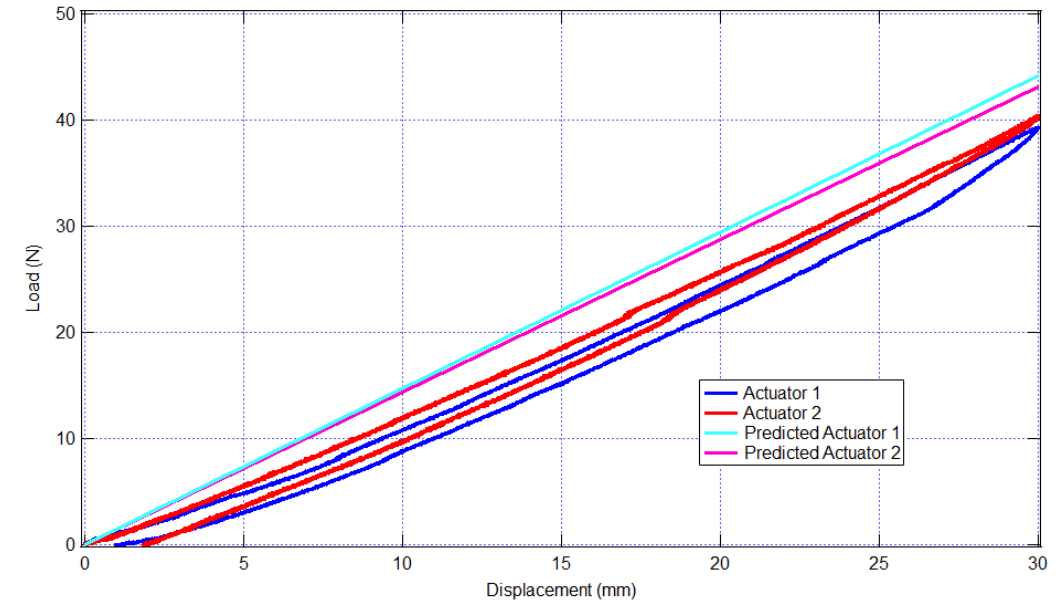
- Selected use of existing MTS servo-hydraulic bi-axial load frame
 - Four horizontal 550-kip actuators placed 90 degrees apart
 - One pair used for this testing
 - Unlike other setups, actuators are fixed and cannot pivot, possibility for actuator to impart a moment on pull rods
 - Approx. 180cm of space between actuators
- Steel work table supports fixturing
- Two linear rails support clamping carriage
 - Counterbalanced
 - Block easy view for DIC along length of specimen
 - Extension rods at hinge points can have speckled flags for DIC
- Two 1-kip load cells are used in series
- Pull/push rods are steel 5/8"-18 all-thread
- Inclinometers used to measure specimen rotations



Monitored signals during test

COMPLIANCE CHECK

- 6061 Aluminum bar (225mmx25mmx3.175mm) clamped in carriage
- Loaded with a single actuator – only in tension (need to check compression)
- Stroke compared to predicted beam deflection
- Nonlinearity in beginning of loading
- Some hysteresis, relief of slack in system
- Produces similar terminal compliance at higher force
- Initial nonlinearity produces around 10% error
- Can be corrected with compliance correction
 - Laser displacement sensors or LVDTs can be used to improve displacement accuracy
 - Required for effective crack length determination
 - J-integral approaches do not rely on displacements



DATA REDUCTION

- Mode I/II partitioning
- Crack length measurement
 - Difficult for Mode II
 - DIC methods, not used here
 - Simple beam theory calculation

$$P_I = \frac{P_1 - P_2}{2}$$

$$P_{II} = \frac{P_1 + P_2}{2}$$

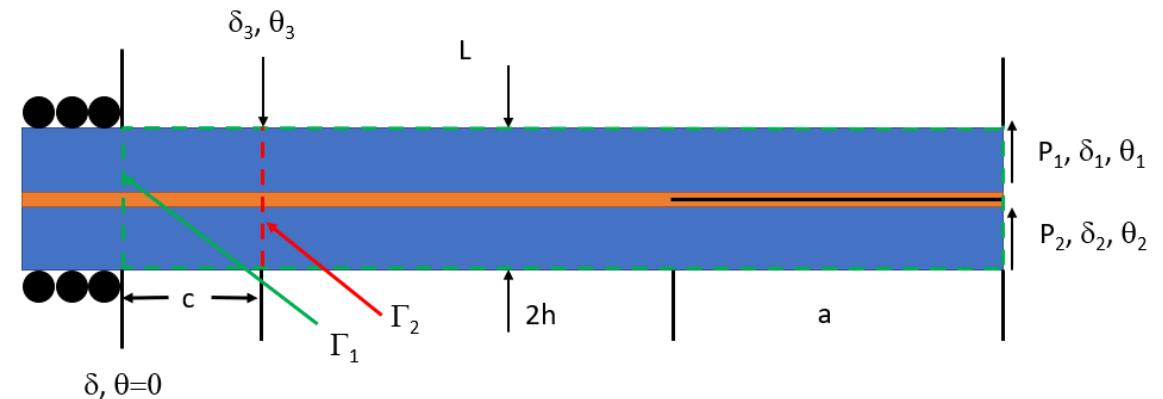
$$\delta_I = \delta_1 - \delta_2$$

$$\delta_{II} = \frac{\delta_1 + \delta_2}{2}$$

$$\theta_I = \frac{\theta_1 - \theta_2}{2}$$

$$\theta_{II} = \frac{\theta_1 + \theta_2}{2}$$

$$\alpha_I^{eff} = \left[\frac{Ebh^3 (\delta_1 - \delta_2)}{4(P_1 - P_2)} \right]^{\frac{1}{3}} \quad \alpha_{II}^{eff} = \left[\frac{Ebh^3 (\delta_1 - \delta_2)}{3(P_1 + P_2)} - \frac{L^3}{3} \right]^{\frac{1}{3}}$$

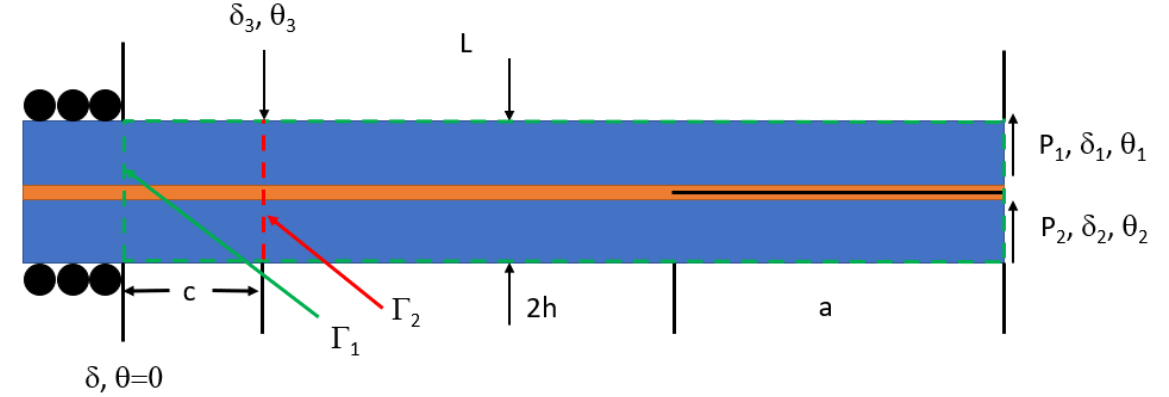


Measurements Used	Simple Beam Theory	J-Integral (\$\Gamma_1\$)	J-Integral (\$\Gamma_2\$)
\$\delta_1, \delta_2\$	X	-	-
\$P_1, P_2\$	X	X	X
\$\theta_1, \theta_2\$	-	X	X
\$\theta_3\$	-	-	X

DATA REDUCTION



- Strain Energy Release Rates, G_I , G_{II} , G_{total}



$$a_I^{eff} = \left[\frac{Eb h^3 (\delta_1 - \delta_2)}{4(P_1 - P_2)} \right]^{\frac{1}{3}} \quad a_{II}^{eff} = \left[\frac{Eb h^3 (\delta_1 - \delta_2)}{3(P_1 + P_2)} - \frac{L^3}{3} \right]^{\frac{1}{3}}$$

Method	G_I	G_{II}	G_{total}
Simple Beam Theory	$\frac{3(P_1 - P_2)^2 a_I^2}{Eb^2 h^3}$	$\frac{9(P_1 + P_2)^2 a_{II}^2}{4Eb^2 h^3}$	$\frac{3}{4Eb^2 h^3} \left(4(P_1 - P_2)^2 a_I^2 + 3(P_1 + P_2)^2 a_{II}^2 \right)$
J-Integral (Γ_1)	$\frac{(P_1 - P_2)}{2b} (\theta_1 - \theta_2)$	$-\frac{3(P_1 + P_2)^2 L^2}{4Eb^2 h^3} + \frac{P_1 + P_2}{2b} (\theta_1 + \theta_2)$	$\frac{(P_1 - P_2)}{2b} (\theta_1 - \theta_2) - \frac{3(P_1 + P_2)^2 L^2}{4Eb^2 h^3} + \frac{(P_1 + P_2)}{2b} (\theta_1 + \theta_2)$
J-Integral (Γ_2)	$\frac{(P_1 - P_2)}{2b} (\theta_1 - \theta_2)$	$-\frac{3(P_1 + P_2)^2 (L - c)^2}{4Eb^2 h^3} - \frac{P_1 + P_2}{2b} (2\theta_3 - \theta_1 - \theta_2)$	$\frac{(P_1 - P_2)}{2b} (\theta_1 - \theta_2) - \frac{3(P_1 + P_2)^2 (L - c)^2}{4Eb^2 h^3} - \frac{P_1 + P_2}{2b} (2\theta_3 - \theta_1 - \theta_2)$

EXPERIMENTS

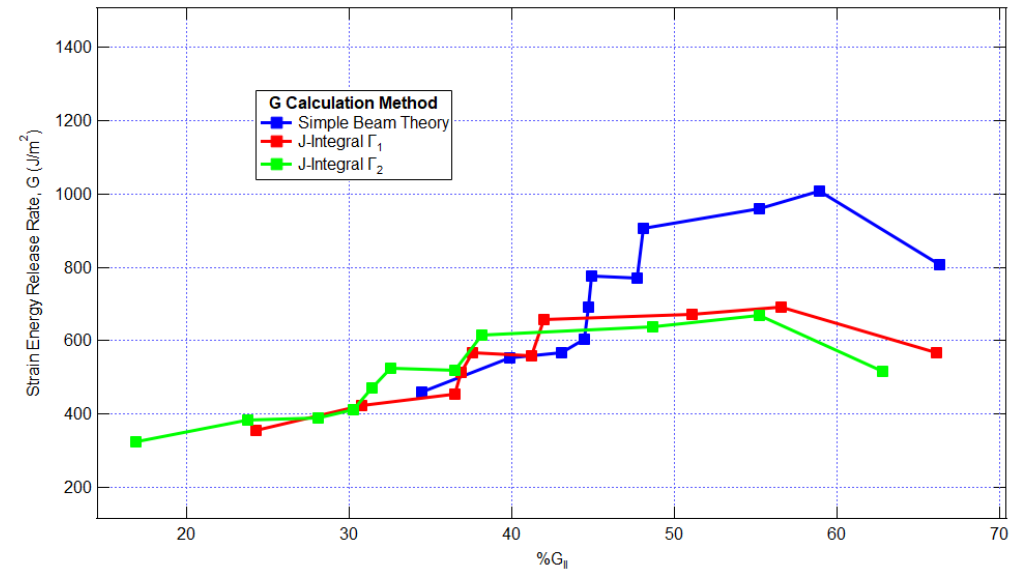
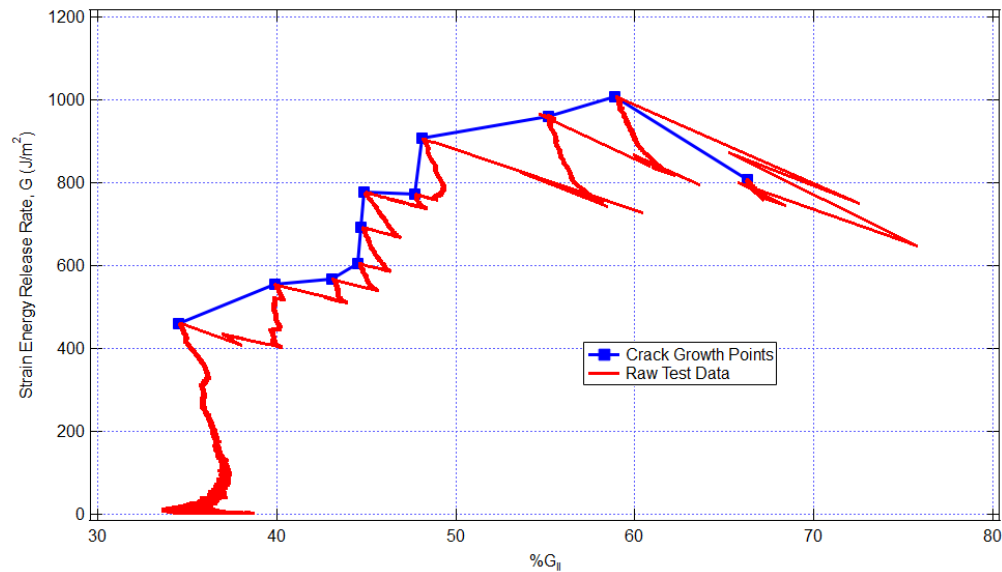
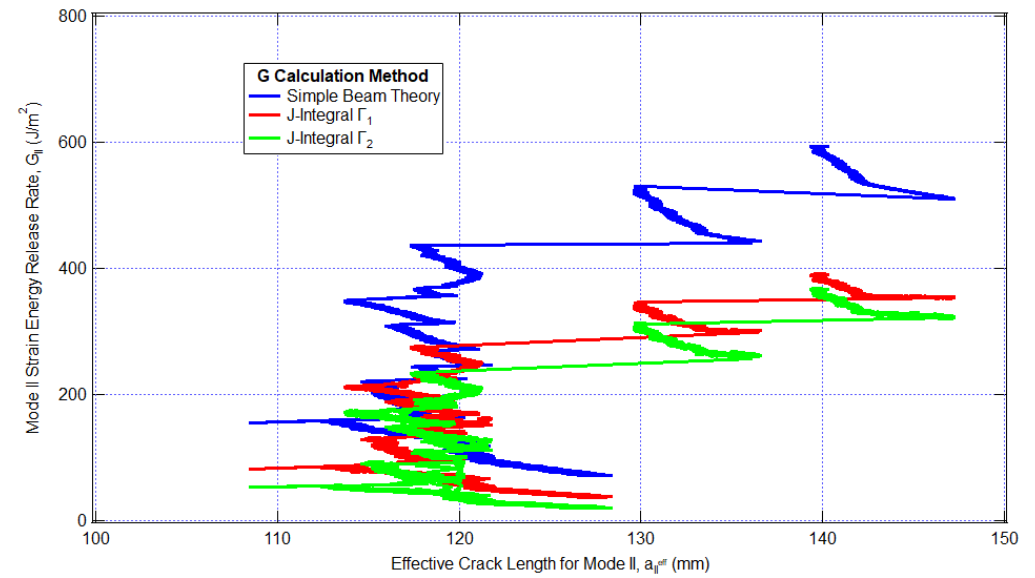
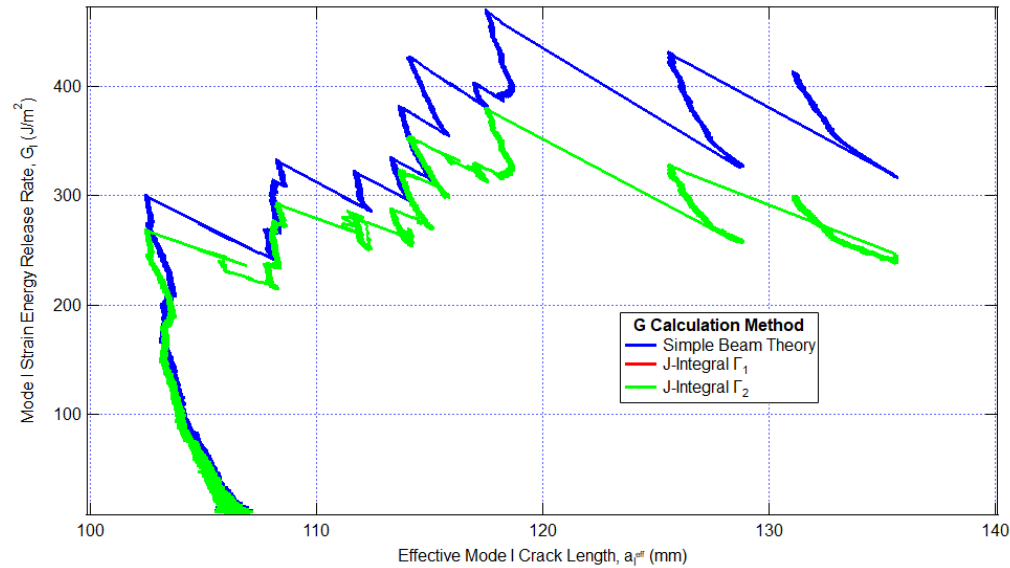


- Material
 - AS4/3362-100 8HS woven carbon composite
 - Layup: 12 plies - $[(0/90)_{3s}]_s$
 - 300mm x 300mm panel
 - Autoclave cured
 - 50mm Teflon precrack (125 μ m thickness)
 - Specimens approx. 25mm x 300mm, tile saw cut
 - Bonded piano hinges, pin loaded
 - Crack extended in Mode I to around 115mm
 - Clamped length – approx. 50mm
- Test Matrix
 - Varied displacement rate for two actuators
 - Pure Mode I to near pure Mode II loading

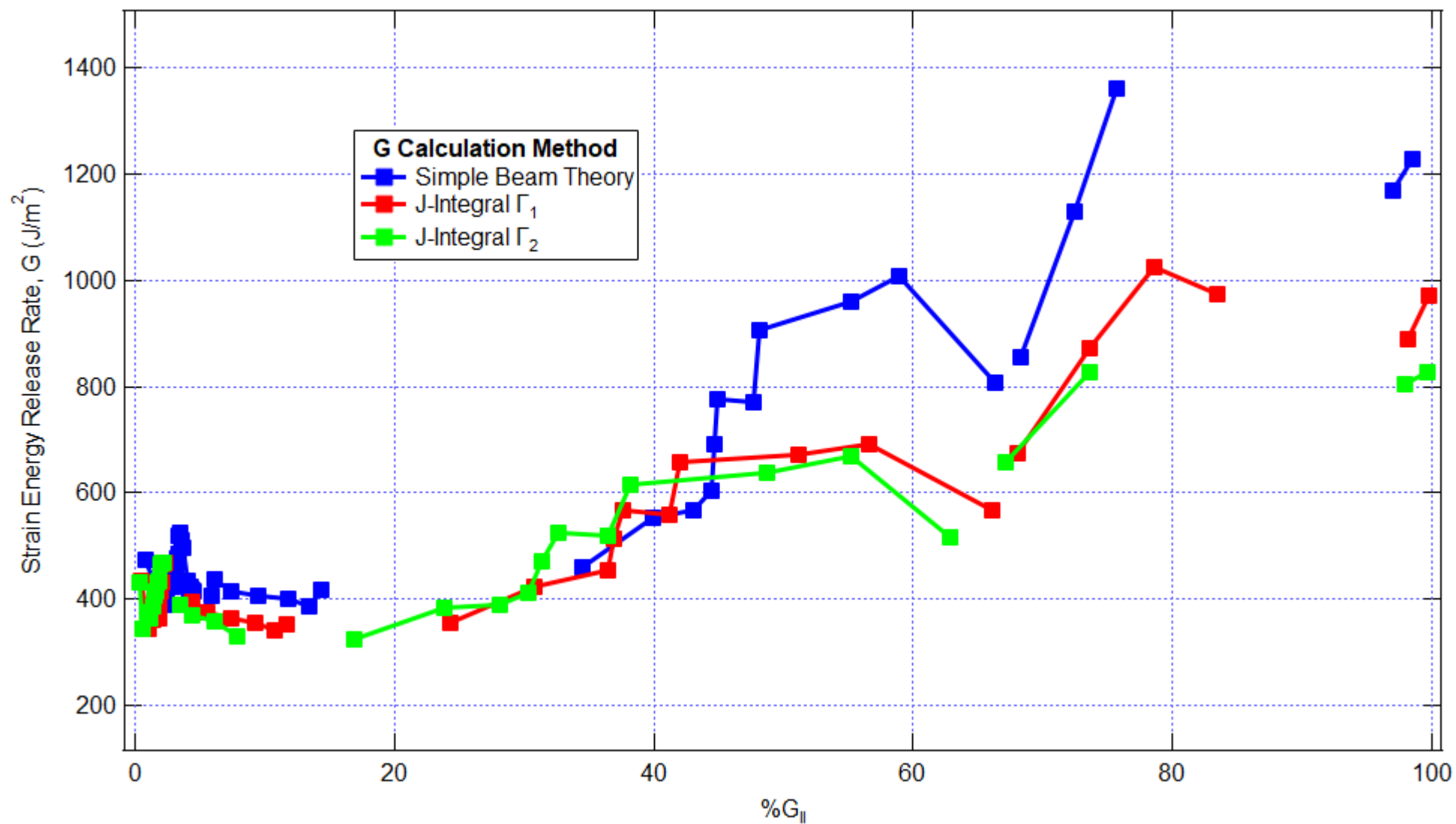
Test Run	V_1 (mm/min)	V_2 (mm/min)
1	2.54	2.54
2	2.54	1.27
3	2.54	0
4	2.54	-1.27
5	2.54	-1.905
6	2.54	-2.49

Positive displacement rate is tension

TYPICAL RESULTS ($V_1=2.54$ MM/MIN, $V_2=-1.27$ MM/MIN)



INITIAL RESULTS



FURTHER CHECKS/IMPROVEMENTS



- Improve load/displacement measurements
 - Laser displacement sensor
 - Check compliance in compression
 - Add 6-axis load cell
 - Stiffen push rod
 - Smaller load cell for more compliant specimens
- Add shear contributions (Timoshenko beam theory)
- Decompose load components into normal and shear
- Try with more stable crack growth fabric (GFRP)

ACKNOWLEDGEMENTS

- LWSL for laying up and curing the panels (Brian McKay, Gus Nungaray)
- Danielle Oteri for extending the cracks using standard DCB test techniques
- Ethan Dike for performing 3-pt bend tests to verify the bending modulus and helping run the experiments

