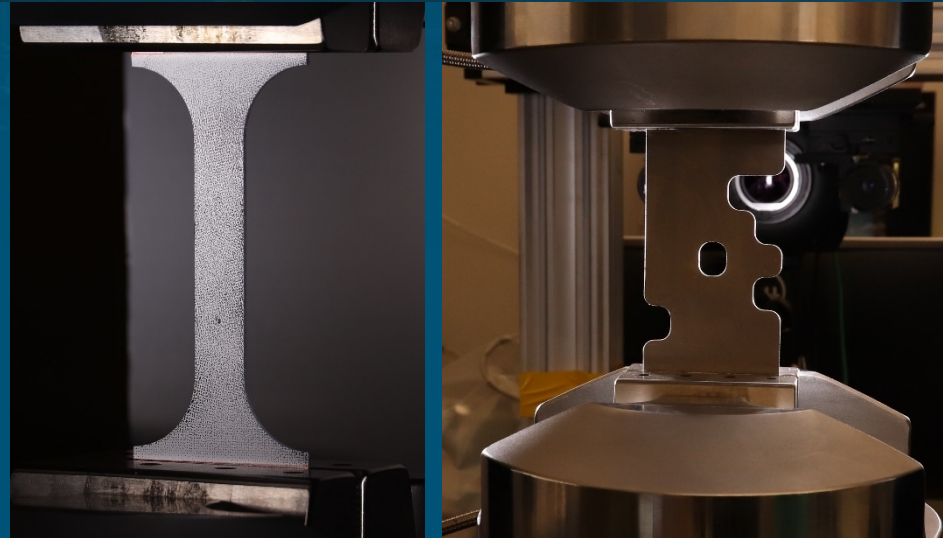


<https://sem.org/dic-challenge>



# Stereo-DIC Challenge 2.0

## The Tensile Experience - Update



PRESENTED BY

Phillip Reu, Waqas Ahmad, Amanda Jones, Elizabeth Jones, Sven Bossuyt, and Mark Iadicola

Special Thanks to Dave Johnson for experimental support



Sandia National Laboratories is a multimission laboratory managed and operated by National Technology & Engineering Solutions of Sandia, LLC, a wholly owned subsidiary of Honeywell International Inc., for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-NA0003525.



# Mission of the DIC Challenge: Improve DIC methods

**Mission:** advance the practice of DIC through collective efforts that point to optimum methodologies

Comprised of industry, government, and academic researchers

Meets twice annually, in sync with Society for Experimental Mechanics annual conference in the summer and the International DIC Society meeting in the fall

## 2023 Challenge Board

Will LePage (U. Tulsa) – Co-chair

Benoît Blaysat (U. Clermont Auvergne) – Co-Chair

Jin Yang (U. Austin) – Secretary

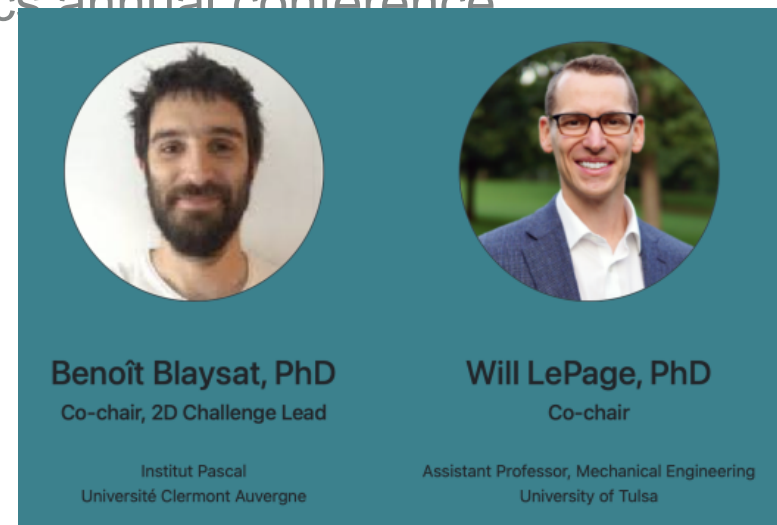
Hugh Bruck, Jeff Helm, Mark Iadicola – Advisors at Large

Evelyne Toussaint, Elizabeth Jones – Results analysis

Helena Jin (Sandia) – DVC Lead

Phillip Reu (Sandia) – Stereo-DIC Challenges

Victoria Tucker (U Tulsa) – SEM Lead

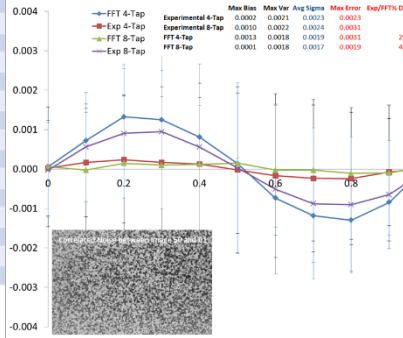


Challenge image sets should be used for all publications claiming improvements in DIC algorithms.



# History of the DIC Challenge

Description	Set Name	Method <sup>1</sup>	Contrast	Subset Size <sup>2</sup>	Noise $\sigma$ (GL)	Shift (pixels)	# Images
TexGen Shift X,Y	Sample1	FFT 4-Tap					
TexGen Shift X,Y	Sample2	Exp 4-Tap					
FFT Shift X,Y	Sample3	FFT 4-Tap					
FFT Step Shift	Sample3b	Exp 8-Tap					
FFT Shift x and y	Sample4	FFT 4-Tap					
FFT Shift x and y	Sample5	Exp 4-Tap					
Prosilica Bin	Sample6	FFT 4-Tap					
Prosilica Bin	Sample7	Exp 4-Tap					
Rotation TexGen	Sample8	FFT 4-Tap					
Rotation FFT	Sample9	Exp 4-Tap					
Strain Gradient	Sample10	FFT 4-Tap					
Strain Gradient	Sample11	Exp 4-Tap					
Ex1 - Plate Hole	Sample12	FFT 4-Tap					
Ex2 - Weld	Sample13	Exp 4-Tap					



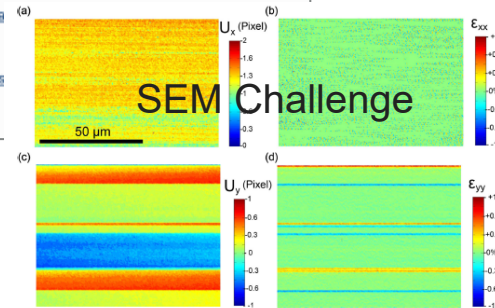
Published: 11 December 2017

## DIC Challenge: Developing Images and Guidelines for Evaluating Accuracy and Resolution of 2D Analyses

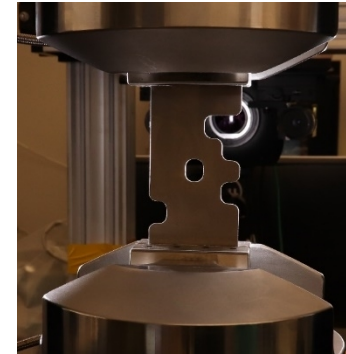
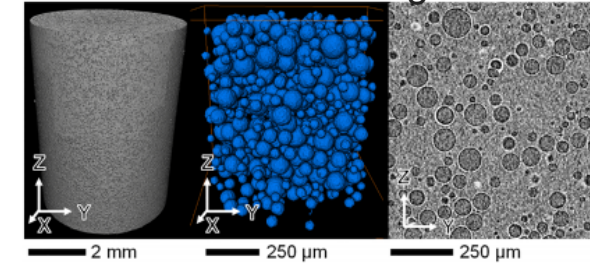
P. L. Reu, E. Toussaint, E. Jones, H. A. Bruck, M. Iadicola & M. Simonsen

*Experimental Mechanics* 58, 1067–1099 (2018) | [Cite this](#)

4118 Accesses | 76 Citations | [Metrics](#)



## DVC Challenge



## Stereo-DIC Challenge

2.0

2023

2012

2D-DIC Challenge

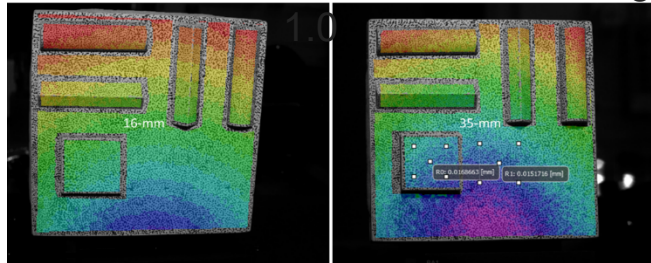
2015

2018

2021

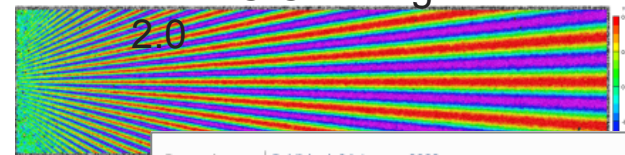
1.0

## Stereo-DIC Challenge



## 2D-DIC Challenge

2.0



Research paper | Published: 04 January 2022

## DIC Challenge 2.0: Developing Images and Guidelines for Evaluating Accuracy and Resolution of 2D Analyses

Focus on the Metrological Efficiency Indicator

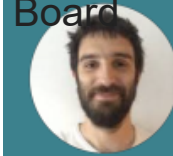
P. L. Reu, B. Blaysat, E. Andó, K. Bhattacharya, C. Couture, V. Couty, D. Deb, S. S. Fayad, M. A. Iadicola, S. Jaminon, M. Klein, A. K. Landauer, P. Lava, M. Liu, L. K. Luan, S. N. Olufsen, J. Réthoré, E. Roubin, D. T. Seidl, T. Siebert, O. Stamati, E. Toussaint, D. Turner, C. S. R. Vemulapati, T. Weikert, J. F. Witz, O. Witzel & J. Yang

*Experimental Mechanics* 62, 639–654 (2022) | [Cite this article](#)

1983 Accesses | 16 Citations | 1 Altmetric | [Metrics](#)

## 2020 New DIC Challenge

Board



Benoît Blaysat, PhD  
Co-chair, 2D Challenge Lead



Will LePage, PhD  
Co-chair

Institut Pascal  
Université Clermont Auvergne

Assistant Professor, Mechanical Engineering  
University of Tulsa

## Current Challenges

- 2-D DIC Challenge 1.0 and 2.0 (Phillip Reu)
- Digital Volume Correlation (DVC) Round Robin 1.0 and 2.0 (Helena Jin)
- Discontinuity DIC Challenge (J.C. Stinville)
- Stereo DIC Challenge 1.0 and 2.0 (Phillip Reu)
- Huge Strain Challenge (Benoît Blaysat)
- Scanning Electron Microscope DIC (SEM-DIC) Round Robin (Will LePage)

## DIC Challenge Board ca 2017

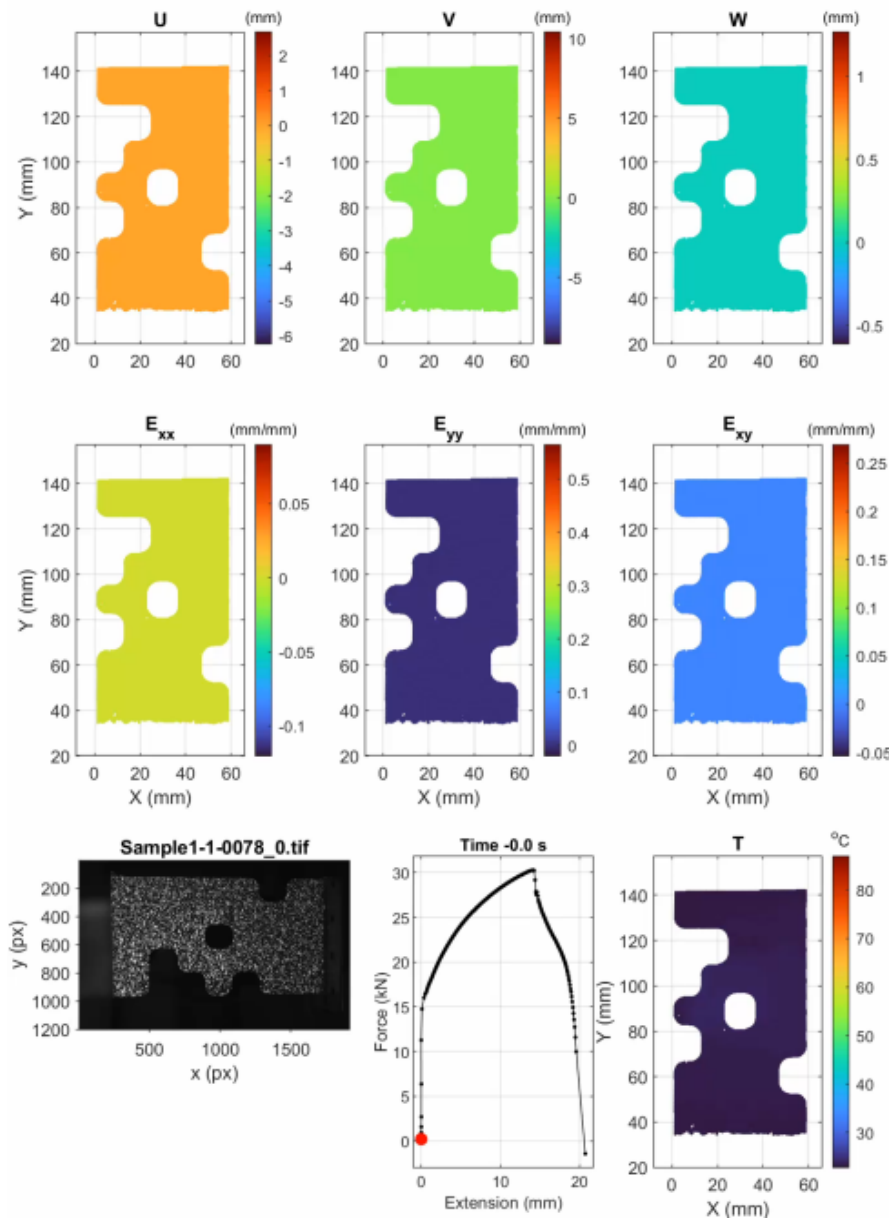
- Phillip Reu – Chairman (US – FFT Shifting)
- Mark Iadicola (NIST) – co-chair
- Will LePage (Univ. Mich.) – SEM challenge Lead
- Helena Jin (Sandia) – DVC challenge Lead
- Elizabeth Jones (Sandia) – Results analysis
- Evelyne Toussaint (University Clermont Auvergne, France)
- Ruben Balcaen (PhD Student KU Leuven)
- Hugh Bruck (University of Maryland)
- In memoriam – Laurent Robert

## Founded about 2012 DIC Challenge Board

Phillip Reu (Chair – US)  
Mark Iadicola (Co-Chair)  
Bertrand Wattrisse (EU)  
Wei-Chung Wang (Asia)  
Laurent Robert (EU)



# A thorough data set of DIC+IR full field data for 304L stainless steel sheet metal is publicly available in support of Material Testing 2.0.



- Seven unique geometries (including the one from the stereo DIC Challenge 2.0)
- Full-field DIC+IR data, plus force, global extension, and time
  - Two nominal grip velocities for rate-dependence characterization
  - Three material orientations (transverse, rolling, diagonal) for anisotropy characterization
  - Infrared (IR) temperature measurements for temperature-dependence characterization
- Both post-processed data AND raw images included (so you can either immediately use spatially and temporally synchronized data, or reanalyze with your own software)
- Tensile dog bone stress-strain data also included
- EMC Jones, PL Reu, SLB Kramer, AR Jones, JD Carroll, KN Karlson, DT Seidl, DZ Turner. “Digital Image Correlation and Infrared Thermography Data for Seven Unique Geometries of 304L Stainless Steel”, submitted to *Scientific Data*, April 2024.
- Data will be hosted on Figshare+ repository, <https://doi.org/10.25452/figshare.plus.25483534>

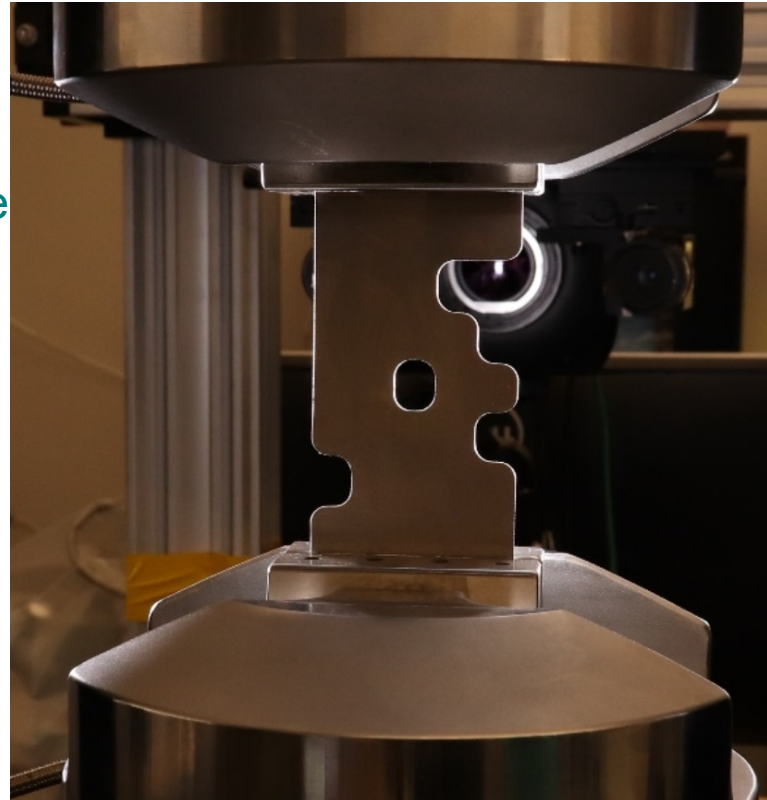


# Stereo-DIC Challenge 2.0: The Tensile Experience

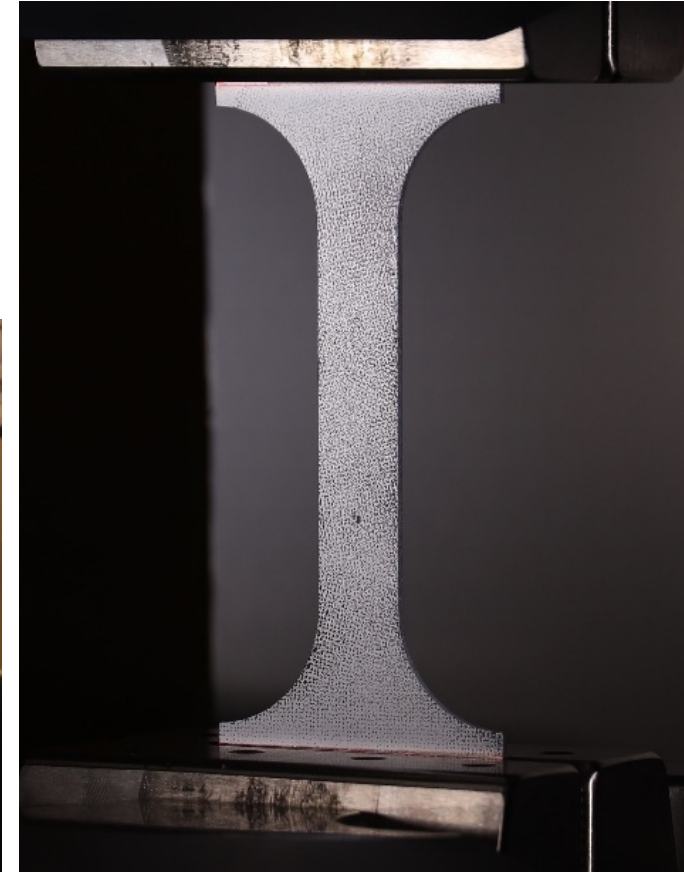
## Why a Stereo-DIC Challenge 2.0? Strain!

- Comparison of strain calculations – there are multiple paths to calculation of strain that vary greatly between codes.
- Comparison of strain spatial resolution vs noise
- Complex specimen geometry
- Standard tensile specimen
- Use data for the Good Practices Guides
- Possible extension to a material property challenge

Bespoke Specimen ×1



Standard Tensile Specimen ×2





# Experimental Setup: Very stable throughout the day

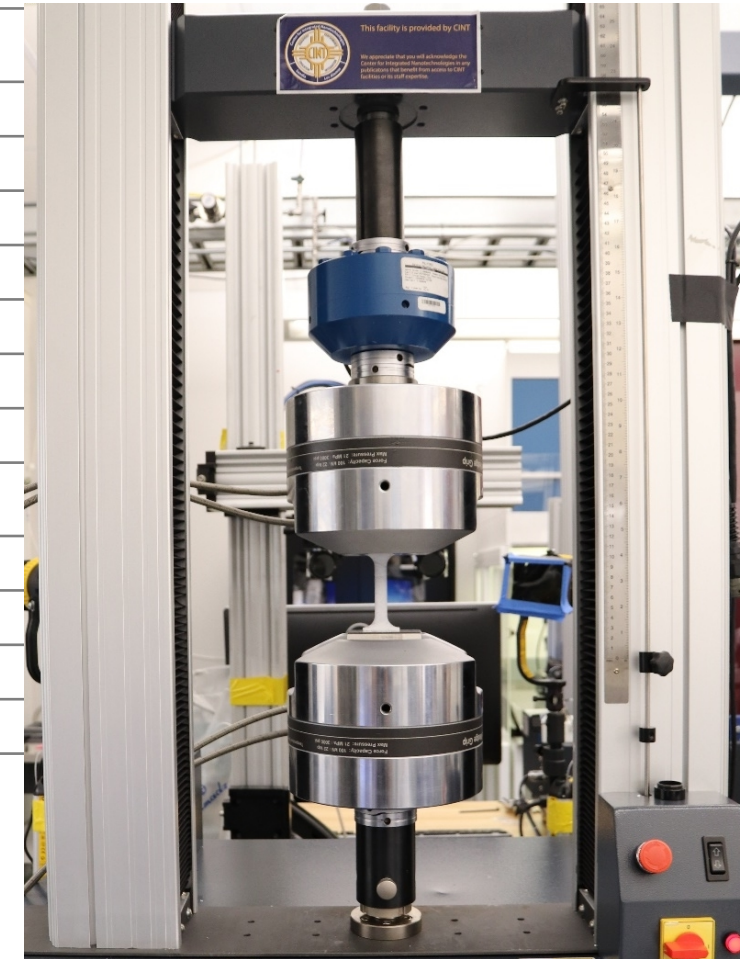
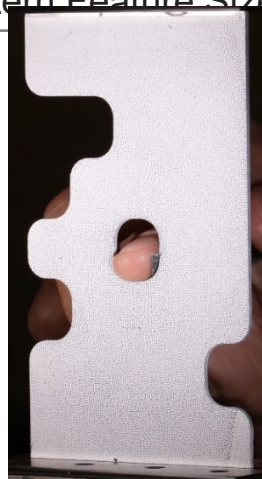


Camera	Grasshopper 2 (Gras-50S5M)
Image Size	2448×2048 pixels
Aperture	$\approx f/8$
Field-of-view	$\approx 125$ mm
Focal Length	35-mm
Image Scale	19.7 px/mm
Stereo-Angle	$19.4^\circ$
Stand-off Distance	600 mm
Image Acquisition Rate	1 Hz
Exposure Time	< 2 ms
Paint	Rust-oleum flat enamel
Patterning Technique	Roller 0.007-inch pattern
Pattern Feature Size	$\approx 7$ pixels

## Ideal Experimental Setup

- Low distortion 35-mm lens
- Cross-polarized lighting to remove glare
- Minimal heat waves
- Rigid camera mounting – stable stereo-rig

Test Conducted  
June 2023



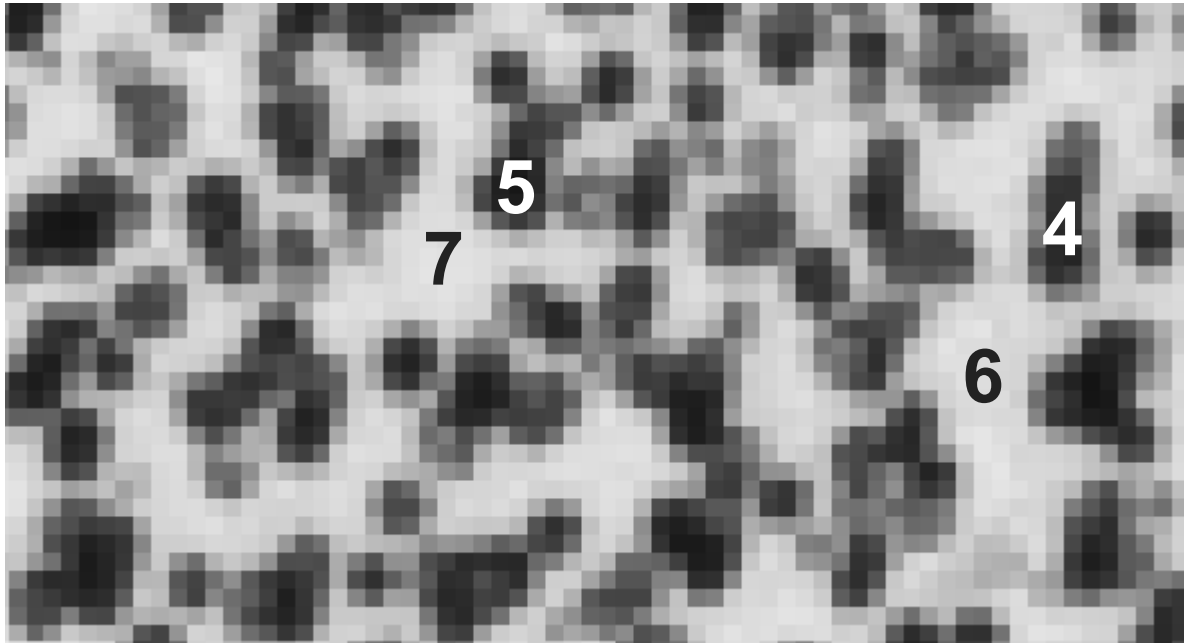
Load Frame	313 Series Frame, 313XHD
Load Cell	12.5 kip, 1020ACK-12.5k-B

# Speckle Pattern nearly ideal using a multi-pass roller on white base-coat

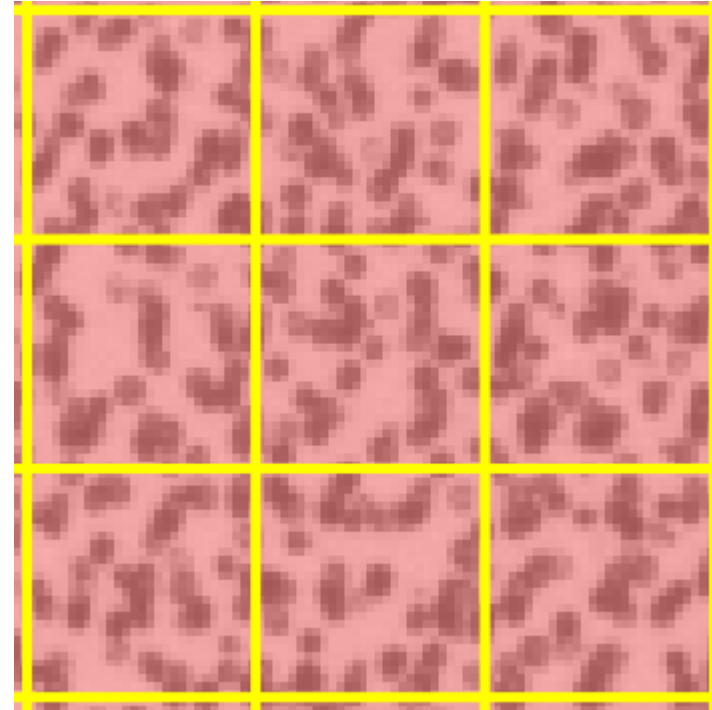


## Ideal Speckle pattern

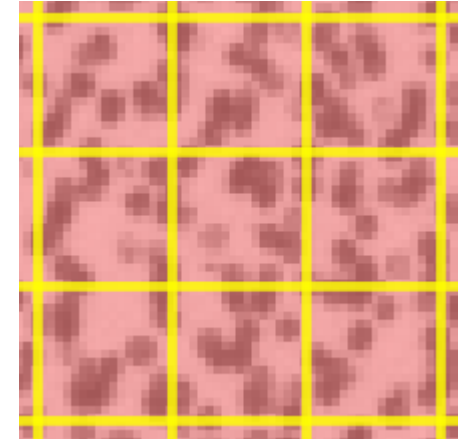
- White base coat (no evidence of failure)
- Black ink roller with multiple passes
- Very uniform pattern with approximately 5-pixel speckles
- Should support subset sizes down to 17 or maybe 15



Subset 29×29



Subset 17×17



### DIC Analysis

- Subset 29 pixels
- Step 1 pixel
- SW = 15
- Affine shape
- ZNSSD
- 8-tap interpolant

VSG = 43 pixels



# Virtual Strain Gage (VSG) and Examples of Strain Gage Calculation Methods

## Sec. 5.3.1 and Sec. 5.3.2

### VSG size:

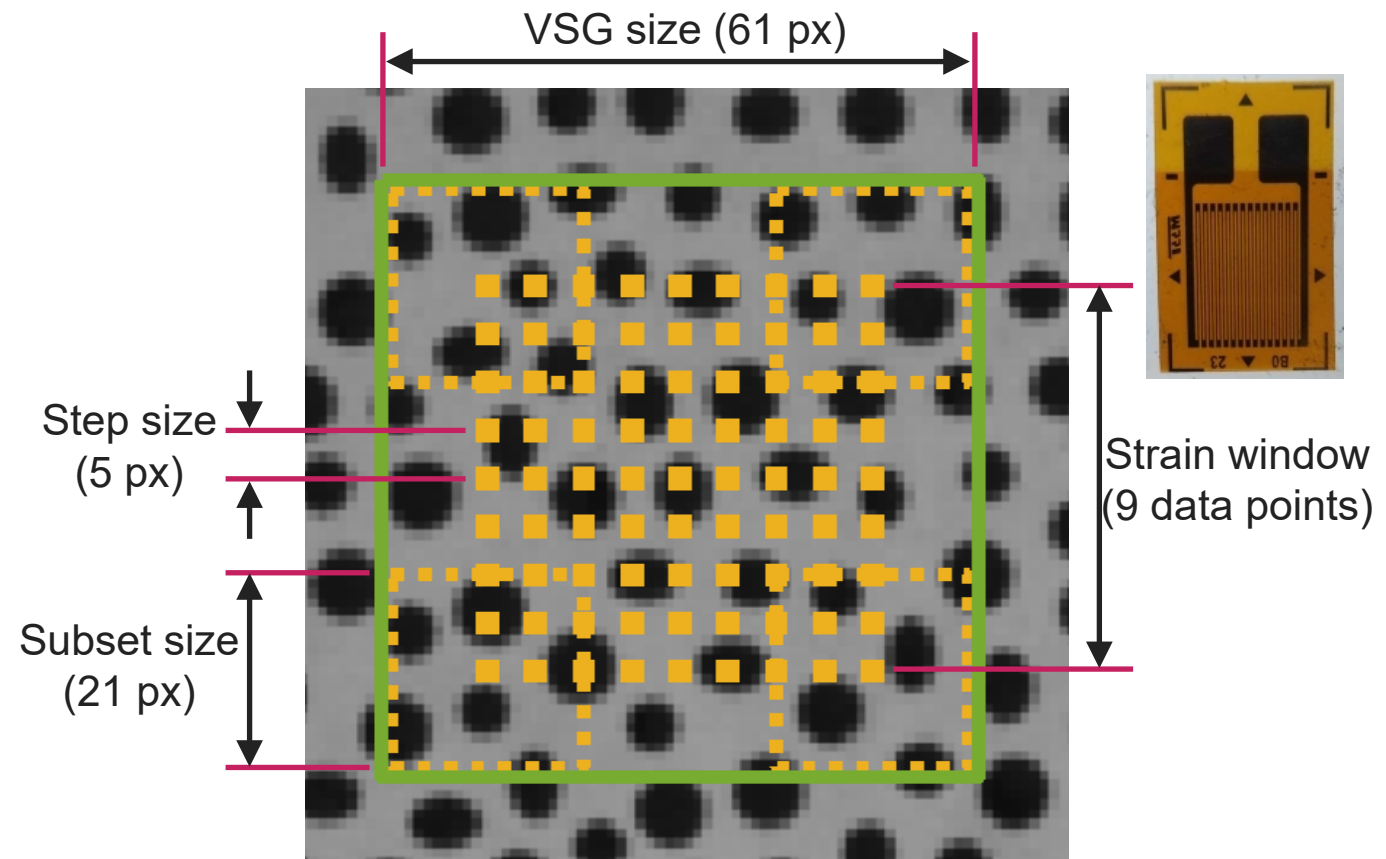
- ▶ Local region of the image that is used for strain calculation at a given location
- ▶ Analogous to, but not exactly, the size of a physical strain gage
- ▶ Participants submitted VSG sizes of 23, 33, 43, 53, and 63 pixels

### Strain computation methods:

- ▶ Many methods, such as:
  - ▶ Subset Shape Function
  - ▶ Finite Element Shape Function
  - ▶ Strain Shape Function
  - ▶ Spline Fit
- ▶ See software manual for details

**For subset based codes – This is the definition of VSG size**

$$L_{VSG} = (L_{window} - 1)L_{step} + L_{subset}$$



# Participants joined via online meeting to approve the calibrations



## Live Event Participants

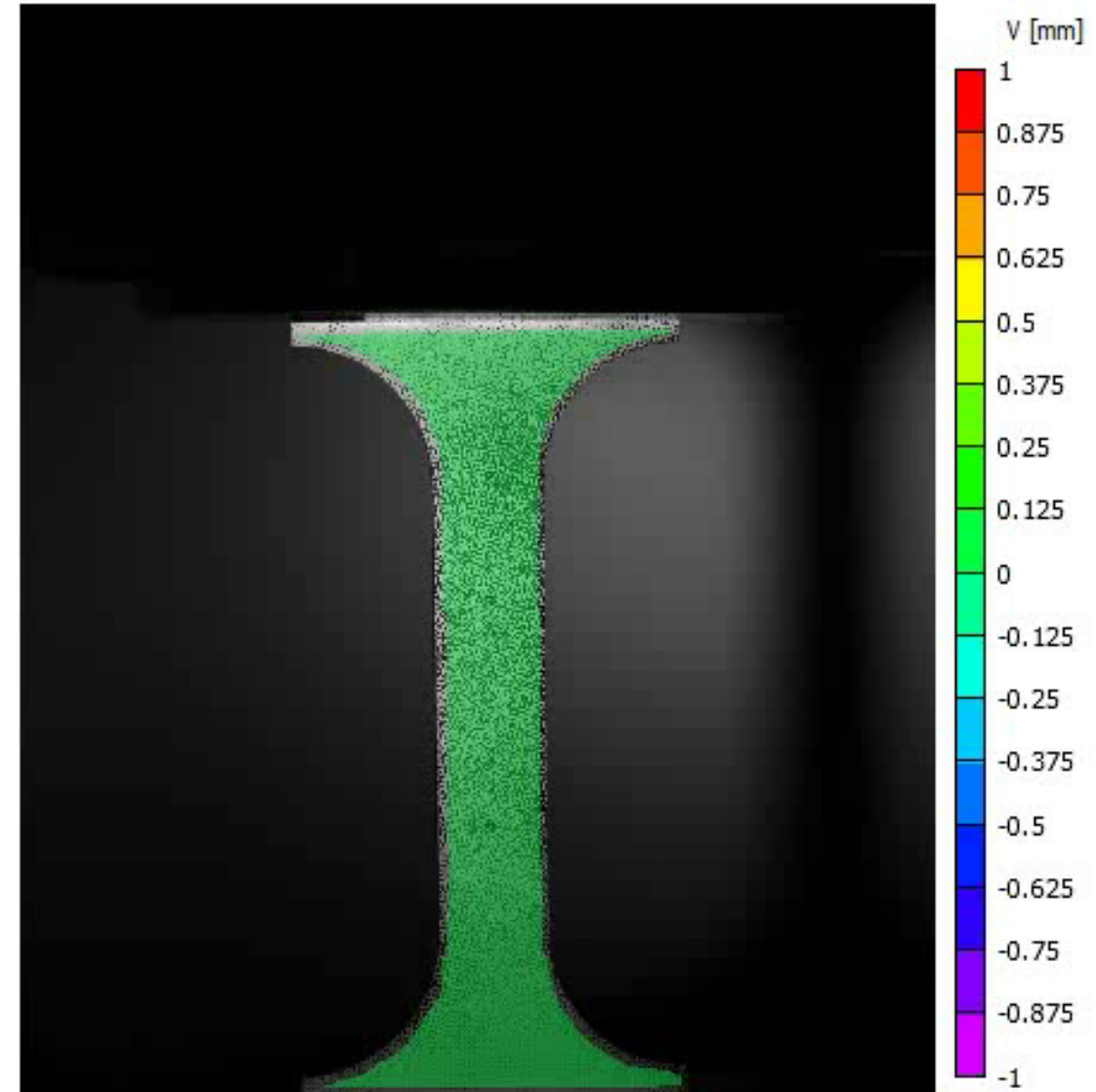
- Dantec,
- LaVision,
- DICe,
- Eikosim,
- MatchID
- Correlated Solutions

## Invited to Participate

- GOM
- Image Systems,
- CorreliSTC,
- ALDIC.

## Participation during experiment to validate setup

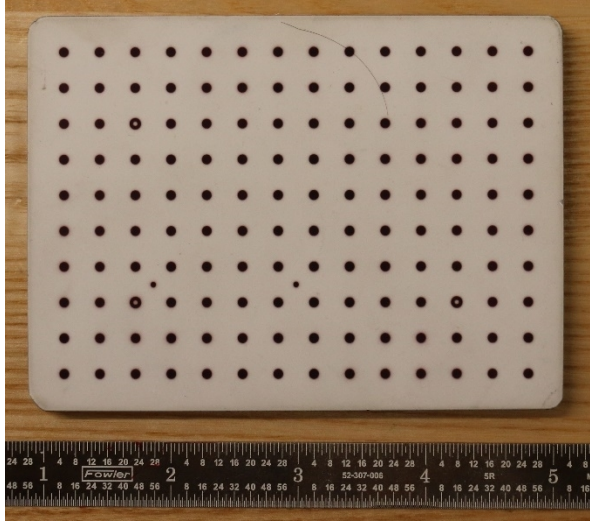
- Nearly all vendors participated in the live calibration event. Feedback was provided until all participants happy with calibration
- Data collected immediately after calibration. Projection error remained small the remainder of the day
- Data available to all participants by invitation to the Google Drive. Email: [plreu@sandia.gov](mailto:plreu@sandia.gov)



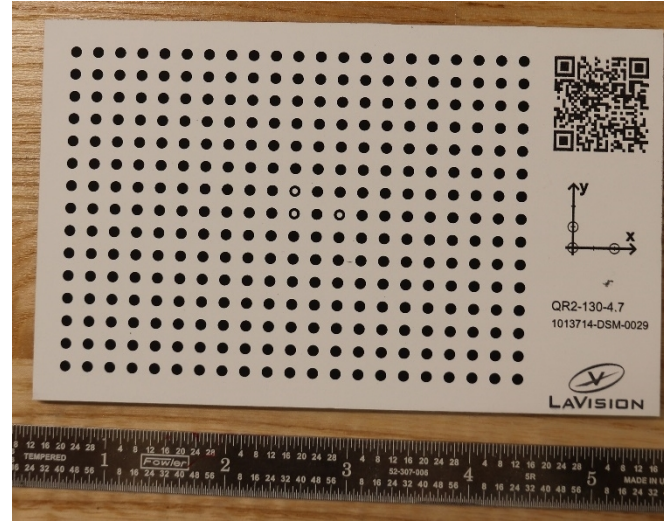


# Calibration targets: Something for everyone.

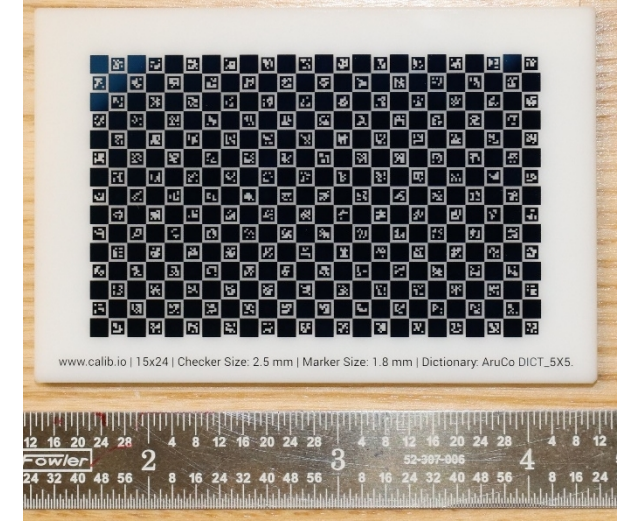
CSI 7mm Dot Grid (H95-00-04)  
113 Images



LaVision Dot Grid (QR2-130-4.7)  
169 Images



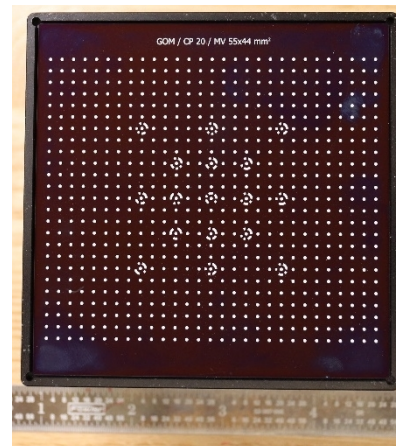
Eikosim OpenCV 15×24 Checker =2.5mm  
Marker=1.8mm 188 Images



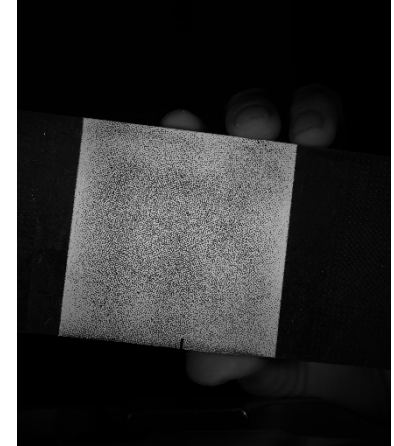
Dantec 8-mm Grid (AI-08-BMB-9×9\_1811)  
125 Images



GOM 55×44 mm<sup>2</sup> (CP20)  
201 Images



Rigid Plate  
78 Images

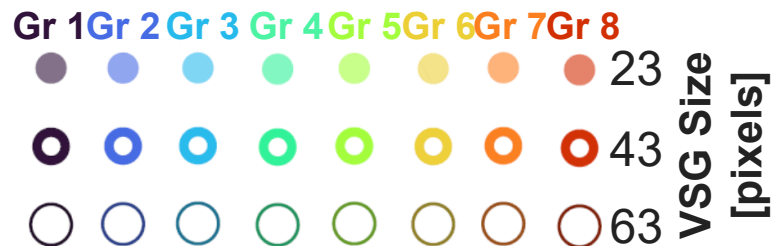






# Participants to the DIC Challenge Analysis

Participant	Type of Code	Strain Description
DICe	Subset Based	
LaVision	Subset Based	Provided
Dantec Dynamics	Subset Based	Provided
Correlated Solutions	Subset Based	
Eikosim	Global Code	
MatchID	Subset Based	
ALDIC	Subset/Global Hybrid	Provided
CorreliSTC	Global Code	
Your Name Here		



## Missing Codes from the Challenge

- GOM
- Image Systems
- SeptD
- IIT

## Why participate in the challenge?

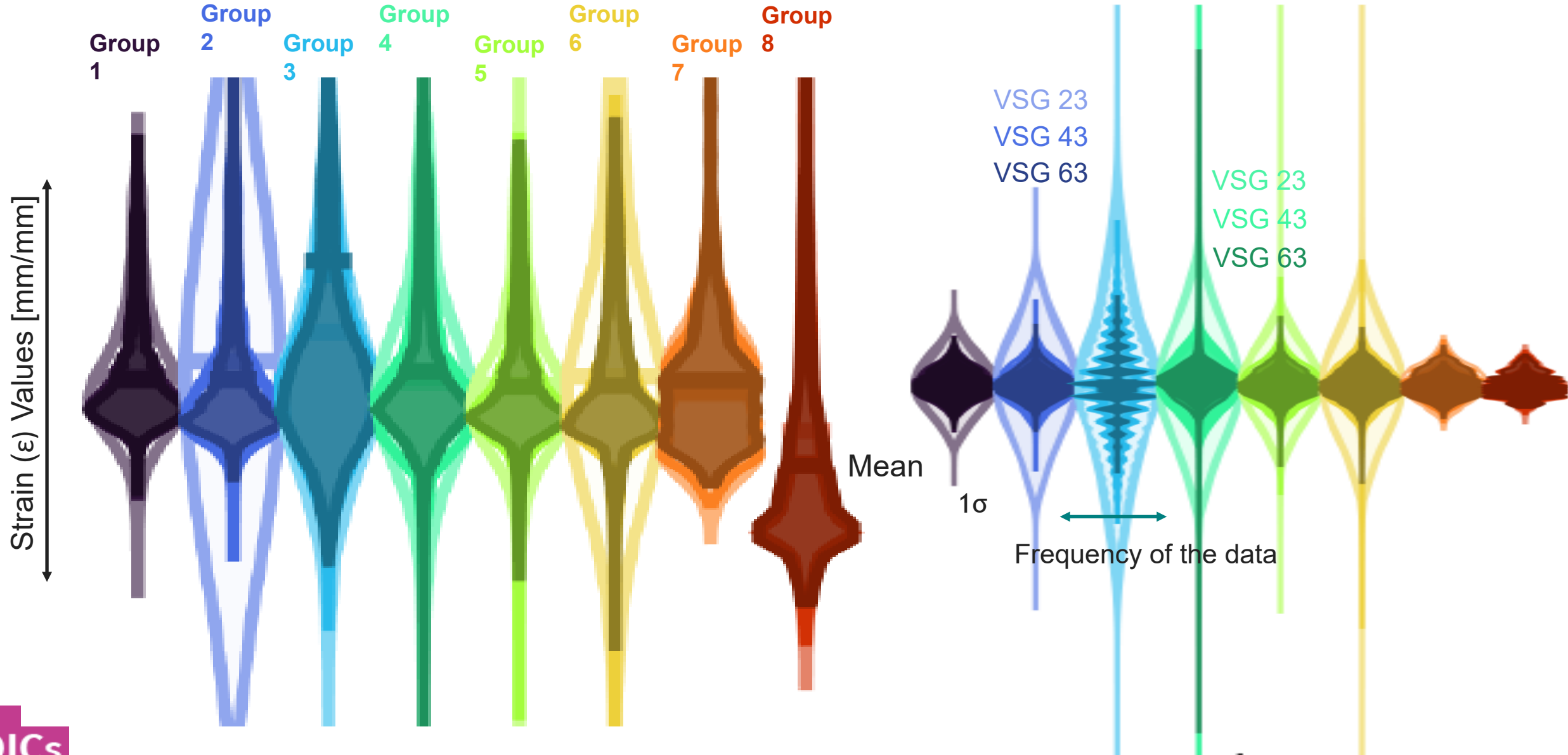
- Benchmark your code against others
- Ensure that DIC results are reliable industry wide
- Validate your code against the best available experimental data

## Strain Calculation Methods are needed

- Error estimates for the lens distortions
- Need to provide calibration parameters for the calibration
- May need to resubmit results to correct coordinate systems
- We are looking for a way to check if everyone is in the same coordinate system



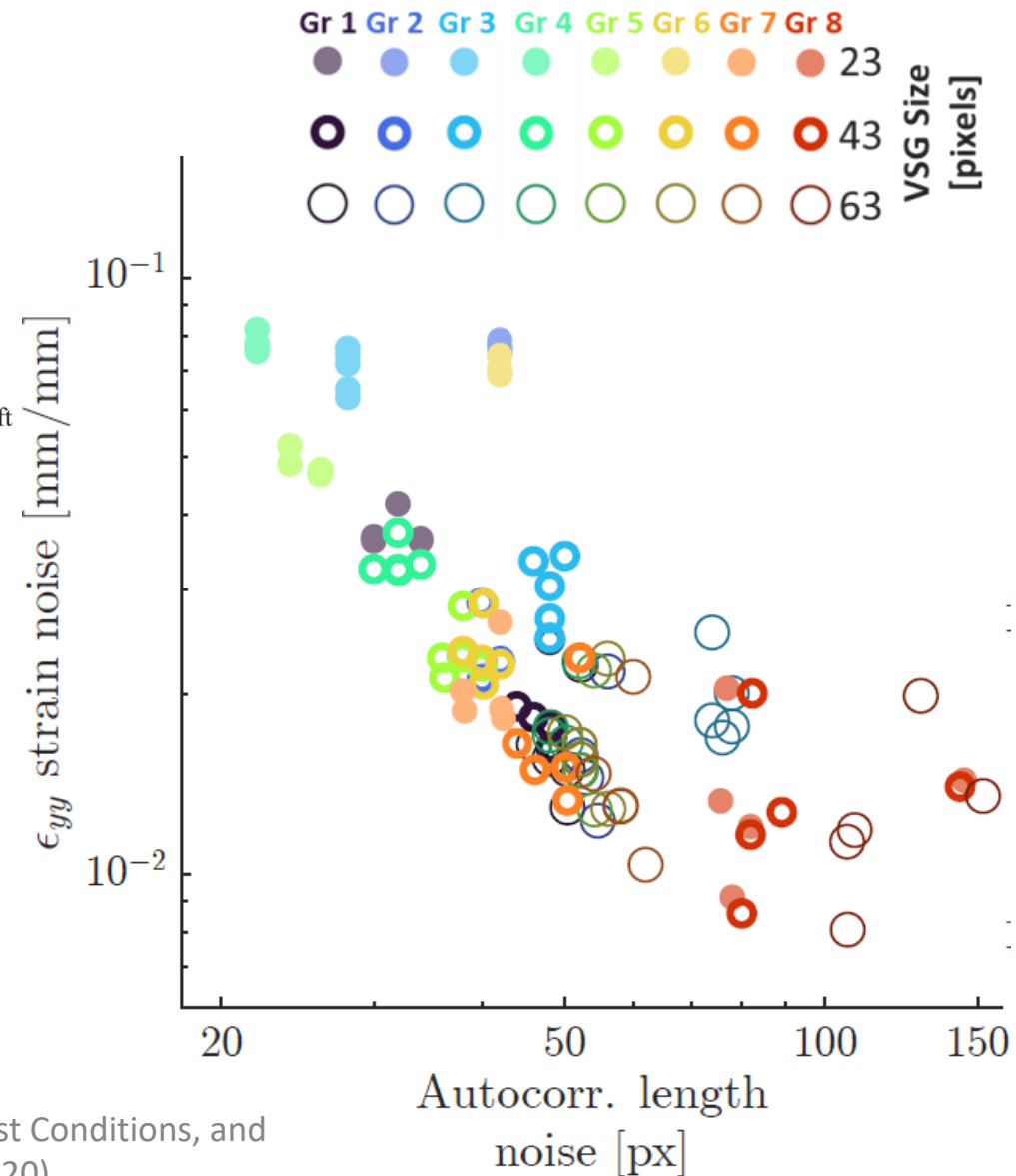
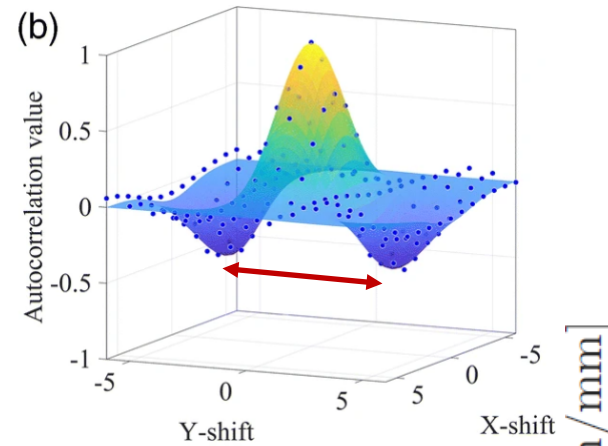
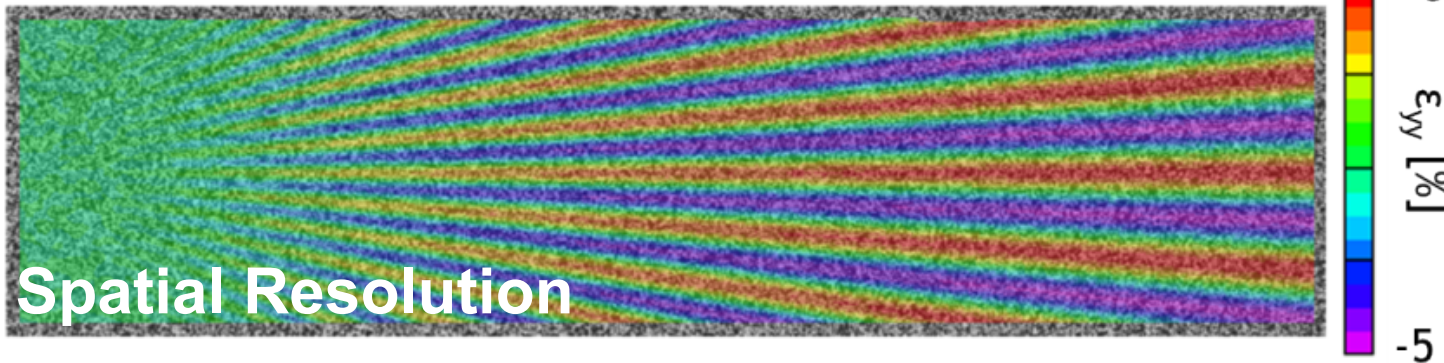
# Data plotting description – Violin Plots



# First Item: Static Noise Floor: Noise vs Spatial Resolution ( $\epsilon_{yy}$ shown here)

## Notes

- Spatial resolution is a measure of the maximum gradient DIC can measure
- Autocorrelation length used to estimate the strain resolution
- Distance between the peaks estimates the spatial resolution
- All 8 Groups plotted
- Note the log/log scaling
- Some data is hidden but all is plotted.



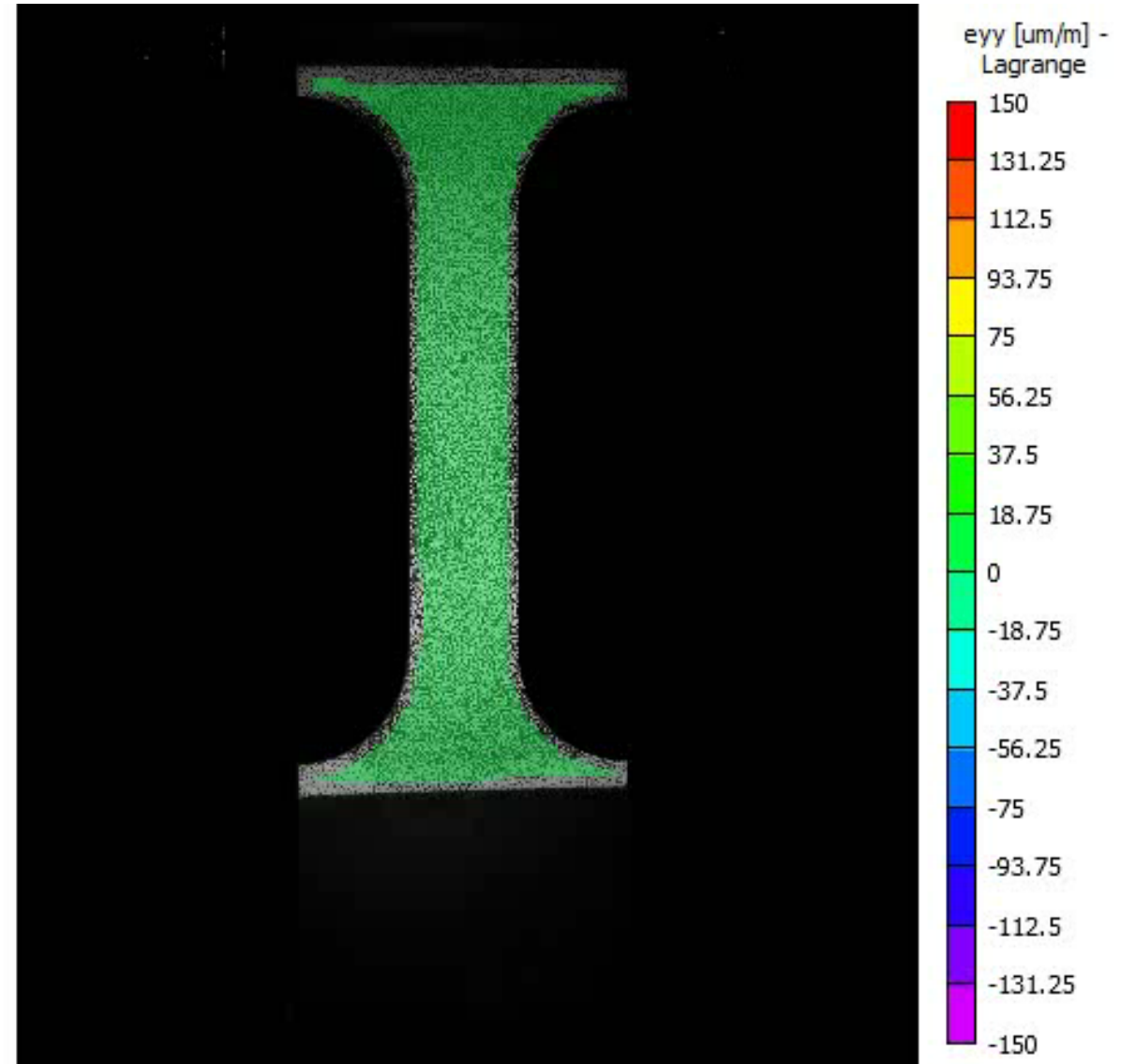
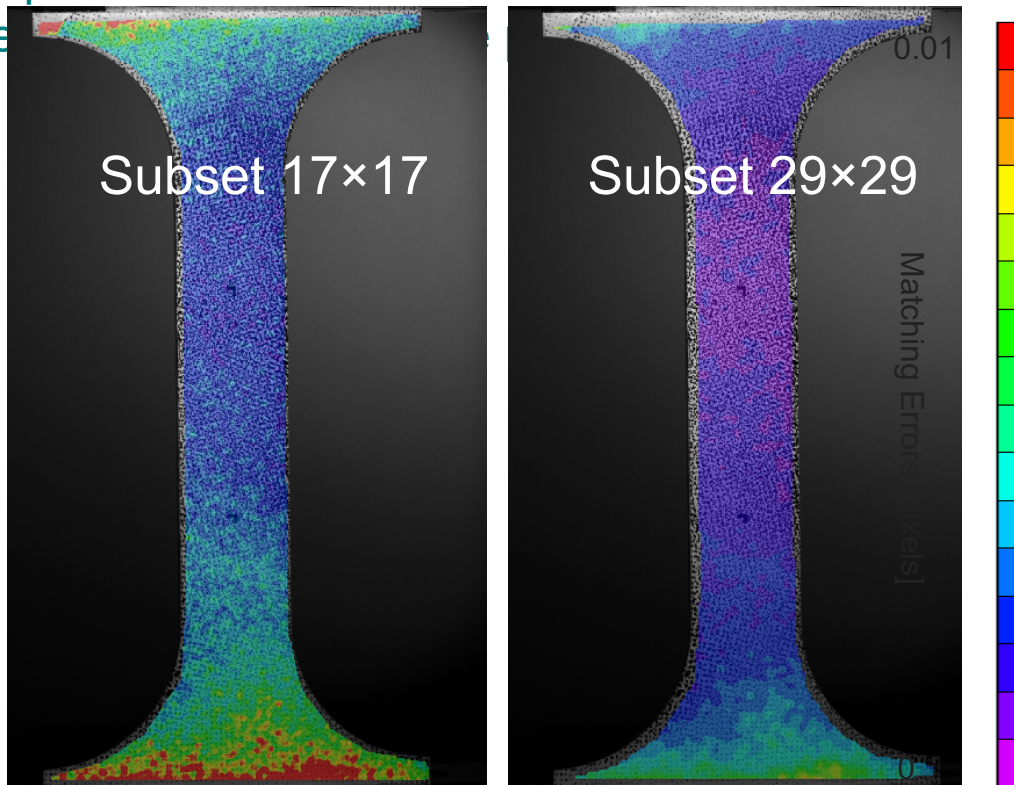




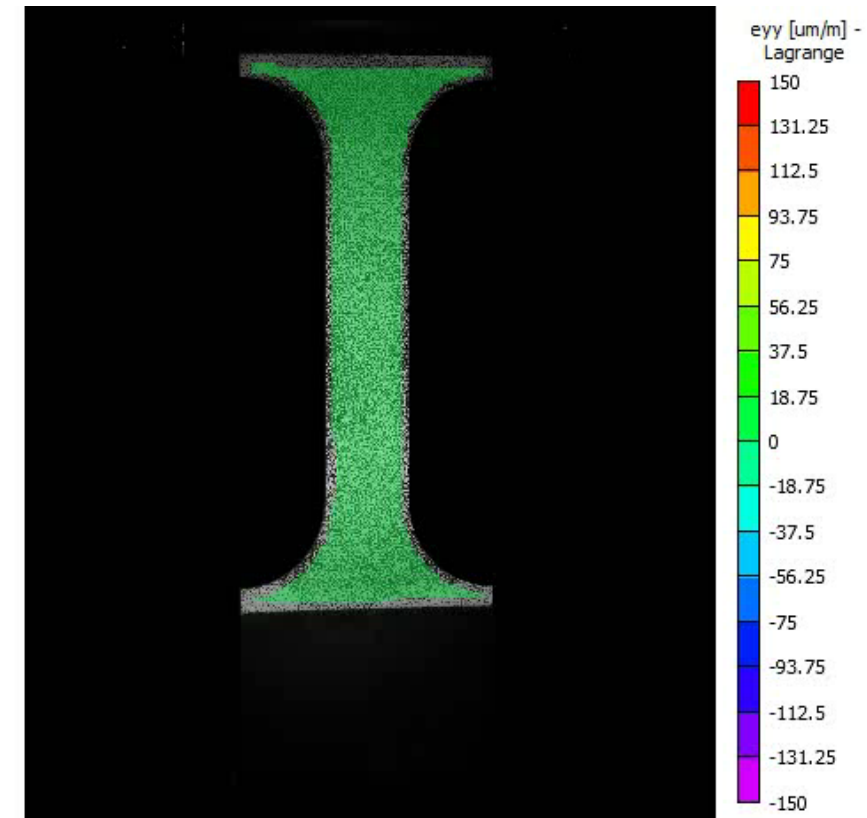
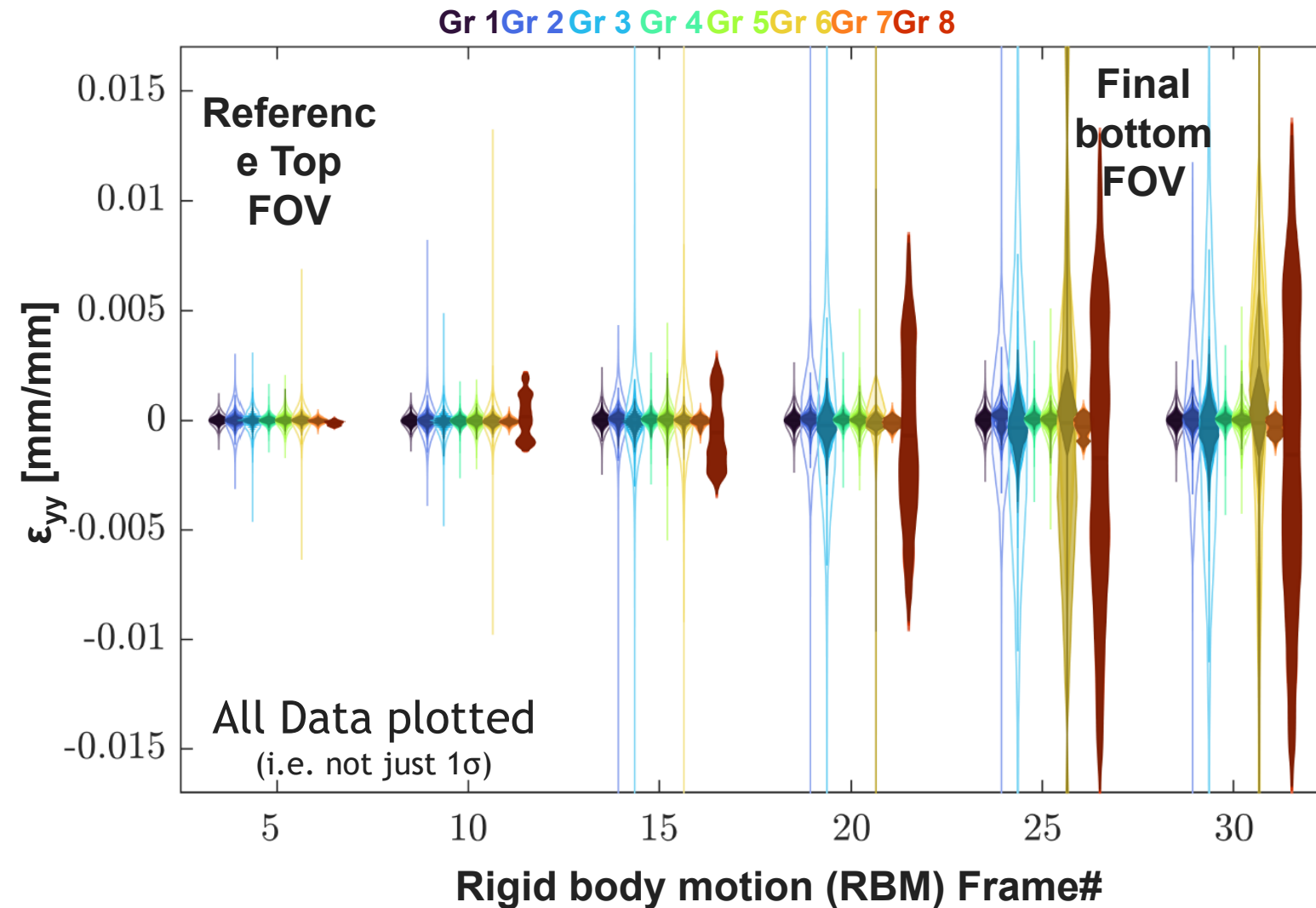
# Better uncertainty estimate is the: Rigid-body zero-value test

## Rigid-body zero-value – Tensile specimen

- Test sample used and translated unloaded through FOV
- Some hints of air turbulence (SS = 29)
- No drop-outs with even a subset = 17
- Subse



# RBM Strain Results – The errors are growing!



## Notes

- All 8 Groups plotted
- VSG 23, 43 and 63 plotted in different shades
- All groups had more noise
- Group 2 and Group 7 Performed badly

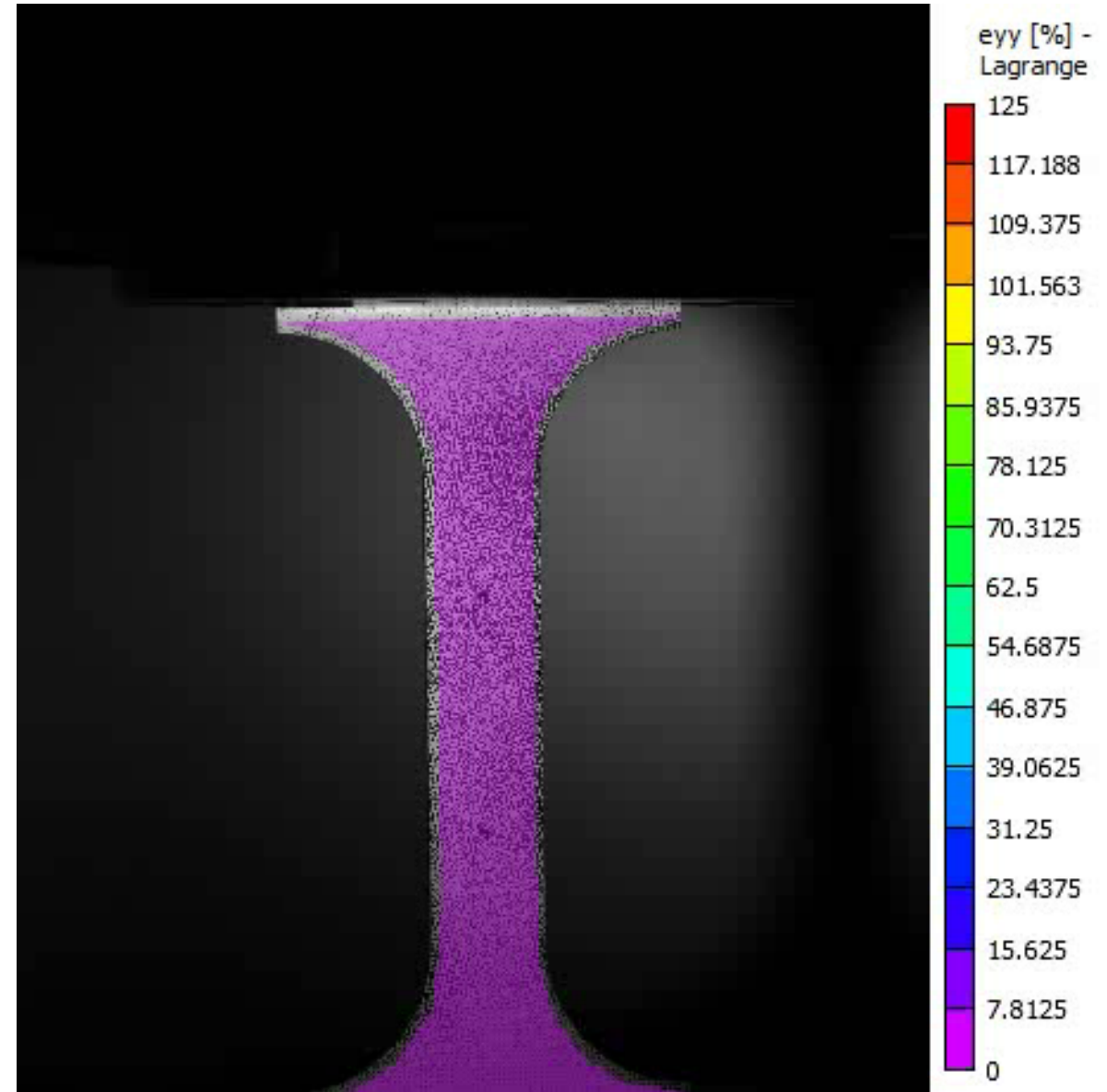
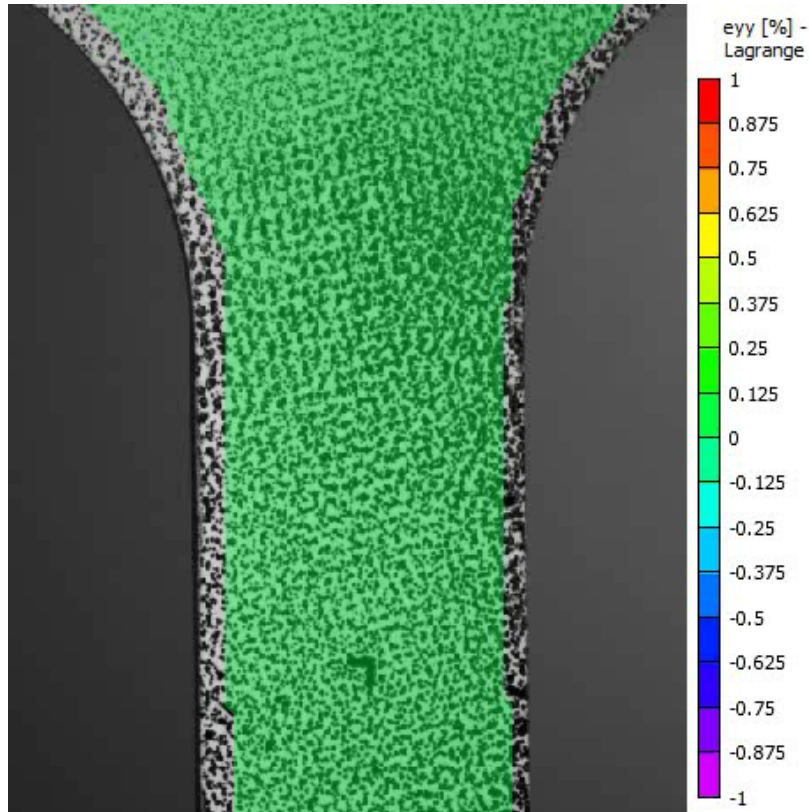
What do the growing errors (for some codes) indicate?



# Tensile data provides a rich data set to explore DIC code implementations

## Tensile Specimen goes to failure

- Paint held up well.
- Pattern is ideal.
- Very clean experimental data set.

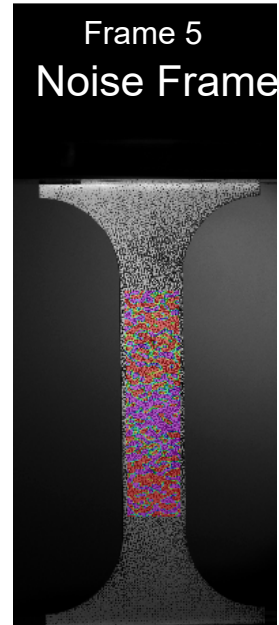
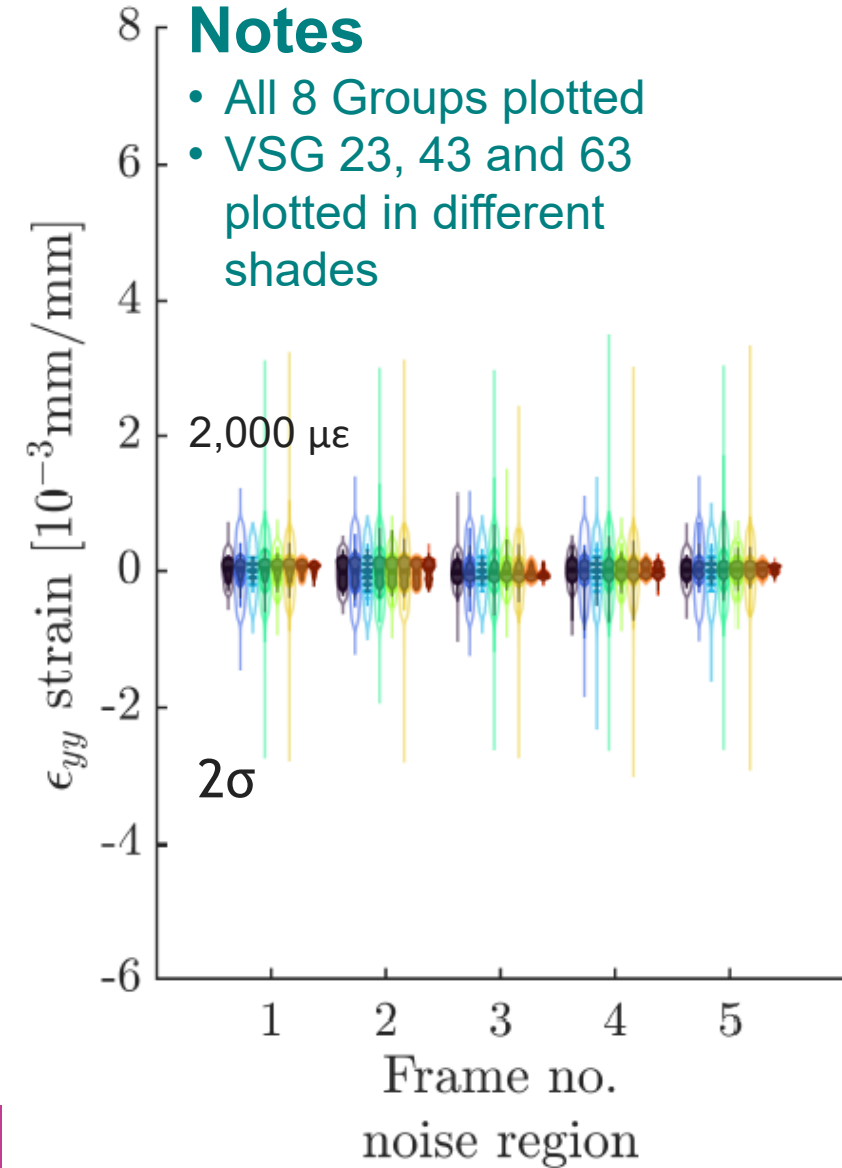




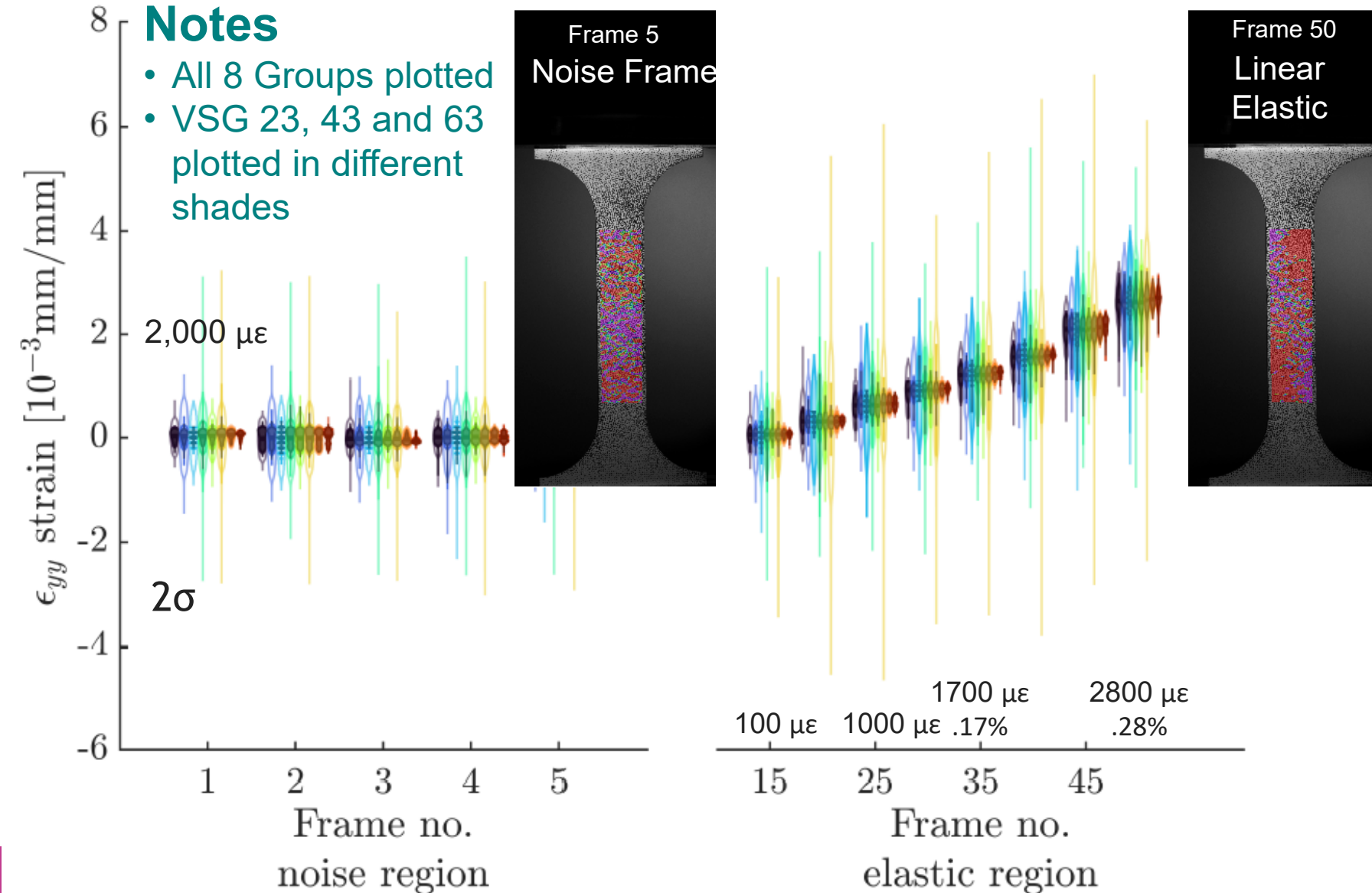
# Overview of the strain for the region before localization $\epsilon_{yy}$

## Notes

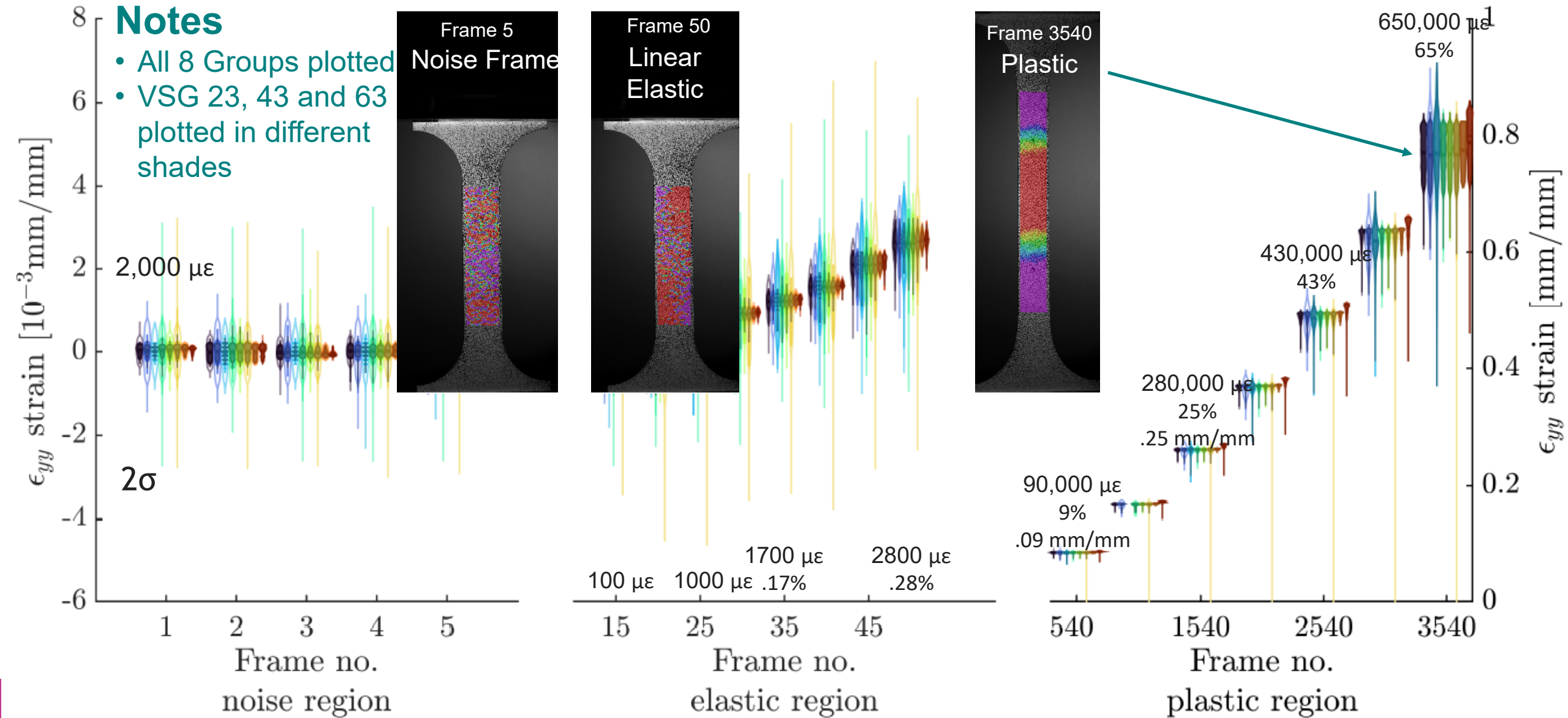
- All 8 Groups plotted
- VSG 23, 43 and 63 plotted in different shades



# Overview of the strain for the region before localization $\epsilon_{yy}$

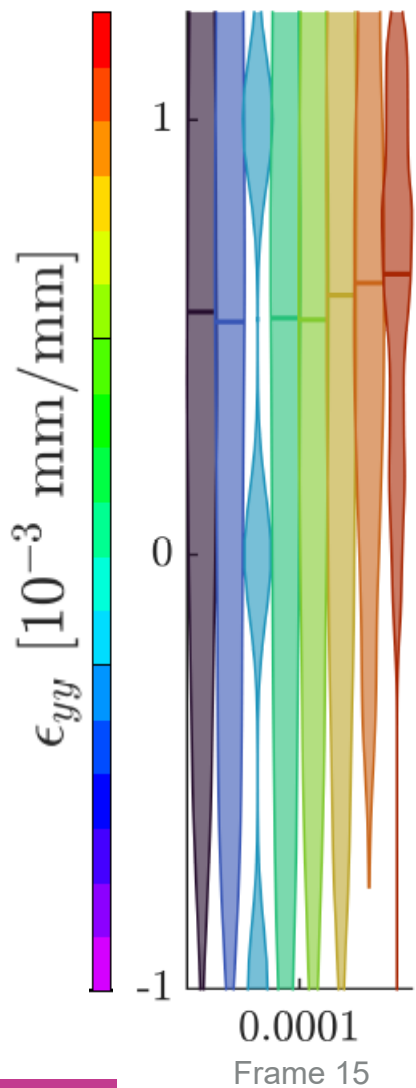


# Overview of the strain for the region before localization $\epsilon_{yy}$

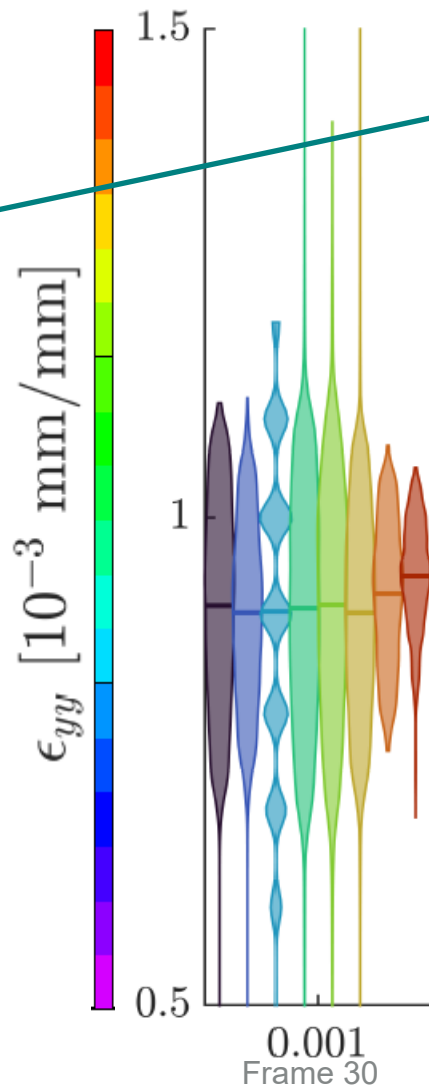
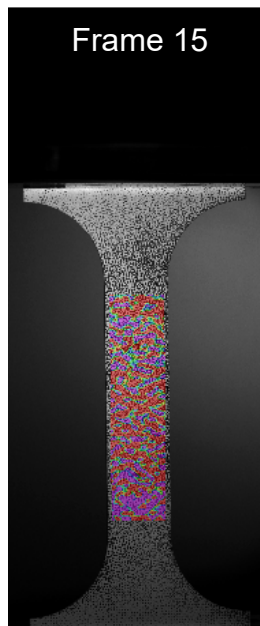




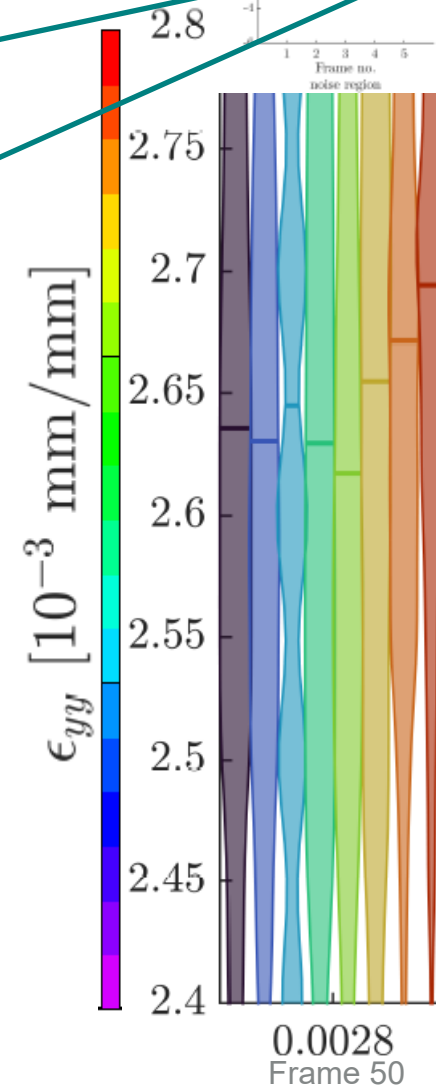
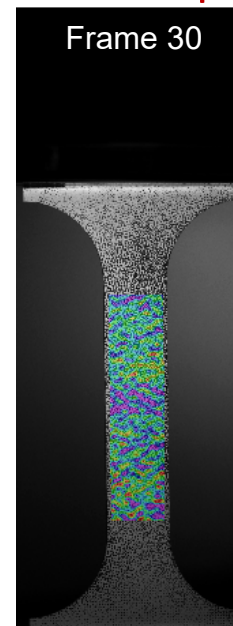
# A closer look at the differences between the codes for $\epsilon_{yy}$ (VSG =



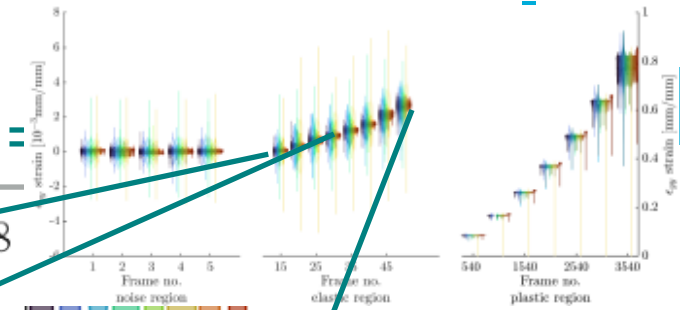
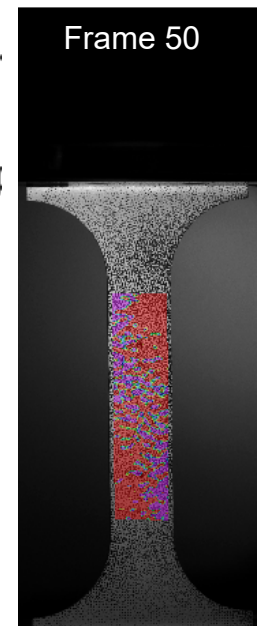
Gr 1-6  
 $\Delta = 36 \mu\epsilon$   
 $\mu = 48 \mu\epsilon$   
 $1\sigma = 251 \mu\epsilon$



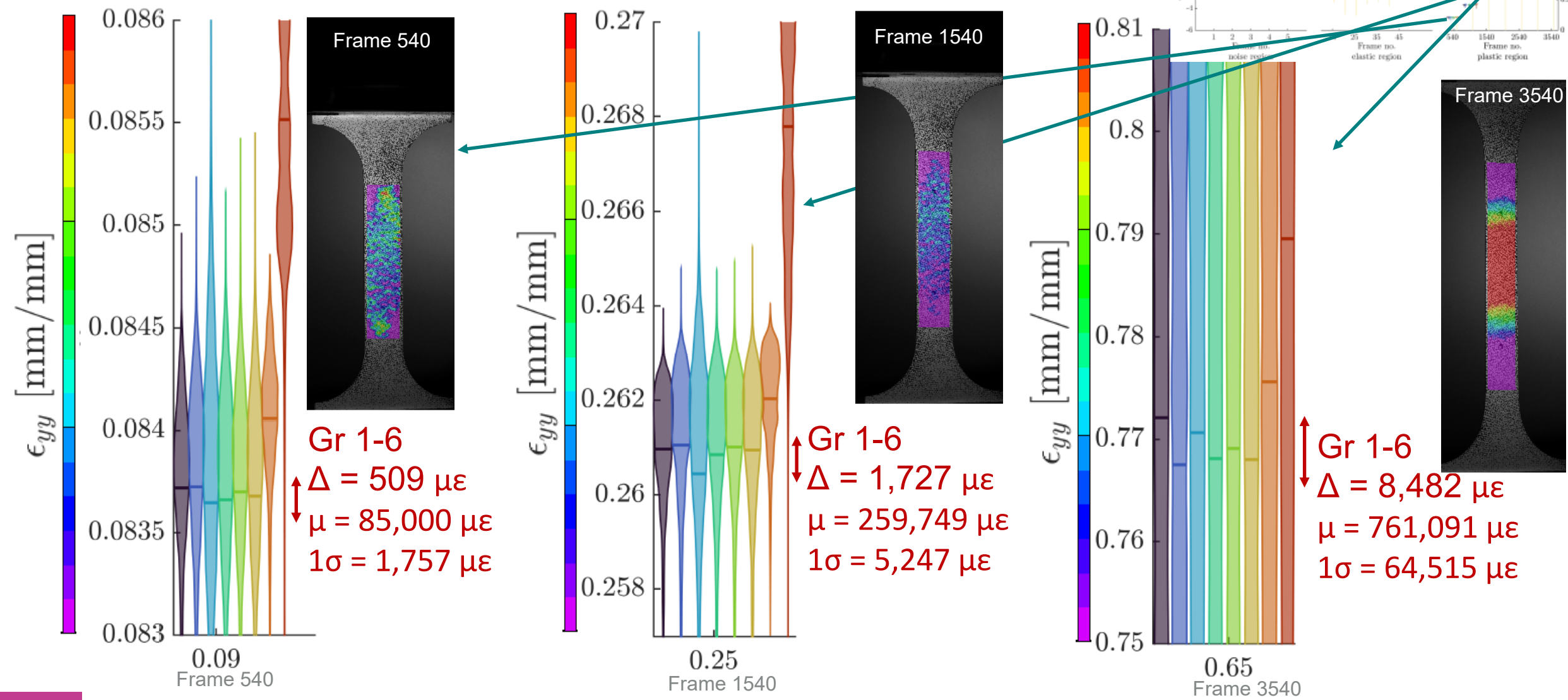
Gr 1,2,3,5,6  
 $\Delta = 4 \mu\epsilon$   
 $\mu = 901 \mu\epsilon$   
 $1\sigma = 390 \mu\epsilon$



Gr 1-6  
 $\Delta = 57 \mu\epsilon$   
 $\mu = 2,673 \mu\epsilon$   
 $1\sigma = 508 \mu\epsilon$



# A closer look at the differences between the codes for $\epsilon_{yy}$ (VSG =



# Verification and classification of extensometer systems ASTM E83 and ISO 9513

## Where does DIC fit into this standard?

### Notes

- ASTM E83/ISO9513 Extensometer verification
- Checks the extensometer against a special caliper
- Three classes of accuracy are allowed, A, B-1 and B-2
- We are going to do a similar calculation. but using the displacement from I displacement

MTS 1  $\mu\text{m}$   
ASTM B2  
Standard?



Instron 0.1  $\mu\text{m}$   
ASTM B1 Standard

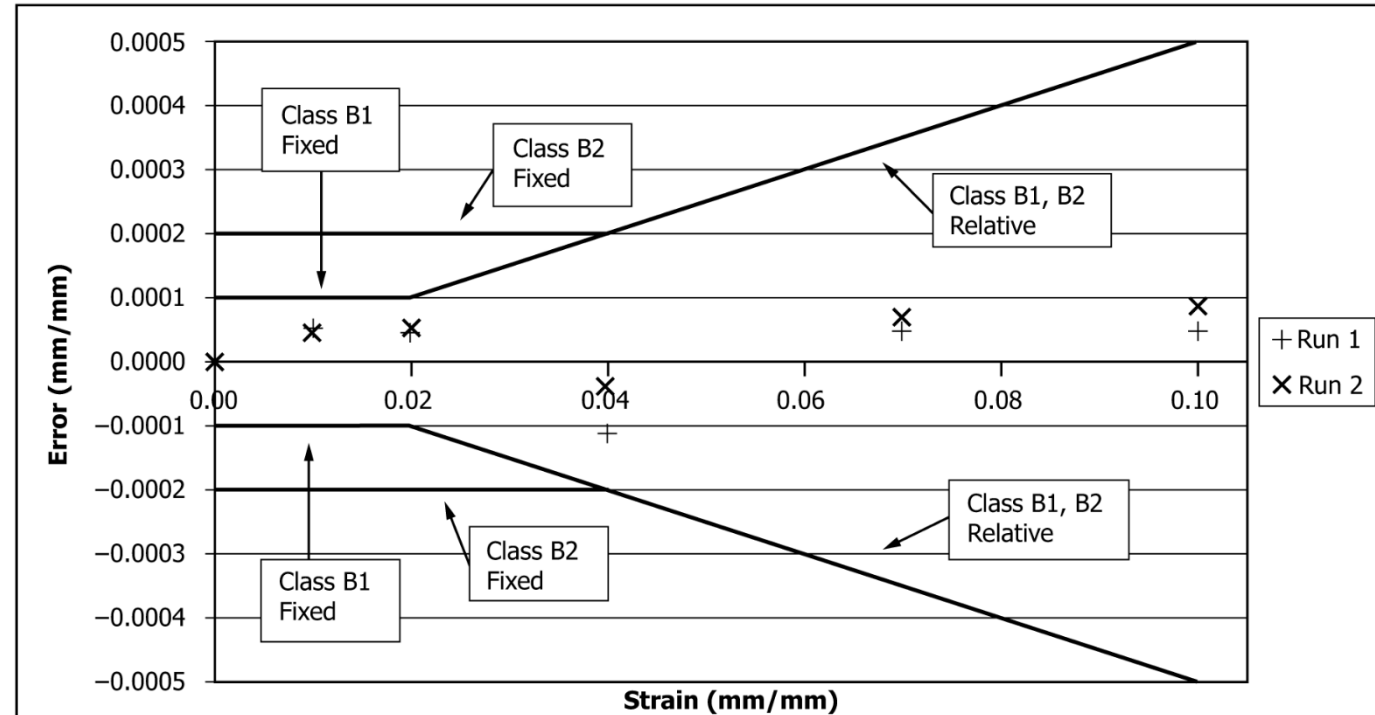


FIG. X1.4 Extensometer Errors and Specifications 25 mm, 100% Extensometer (10% Range, Fig. X1.2)

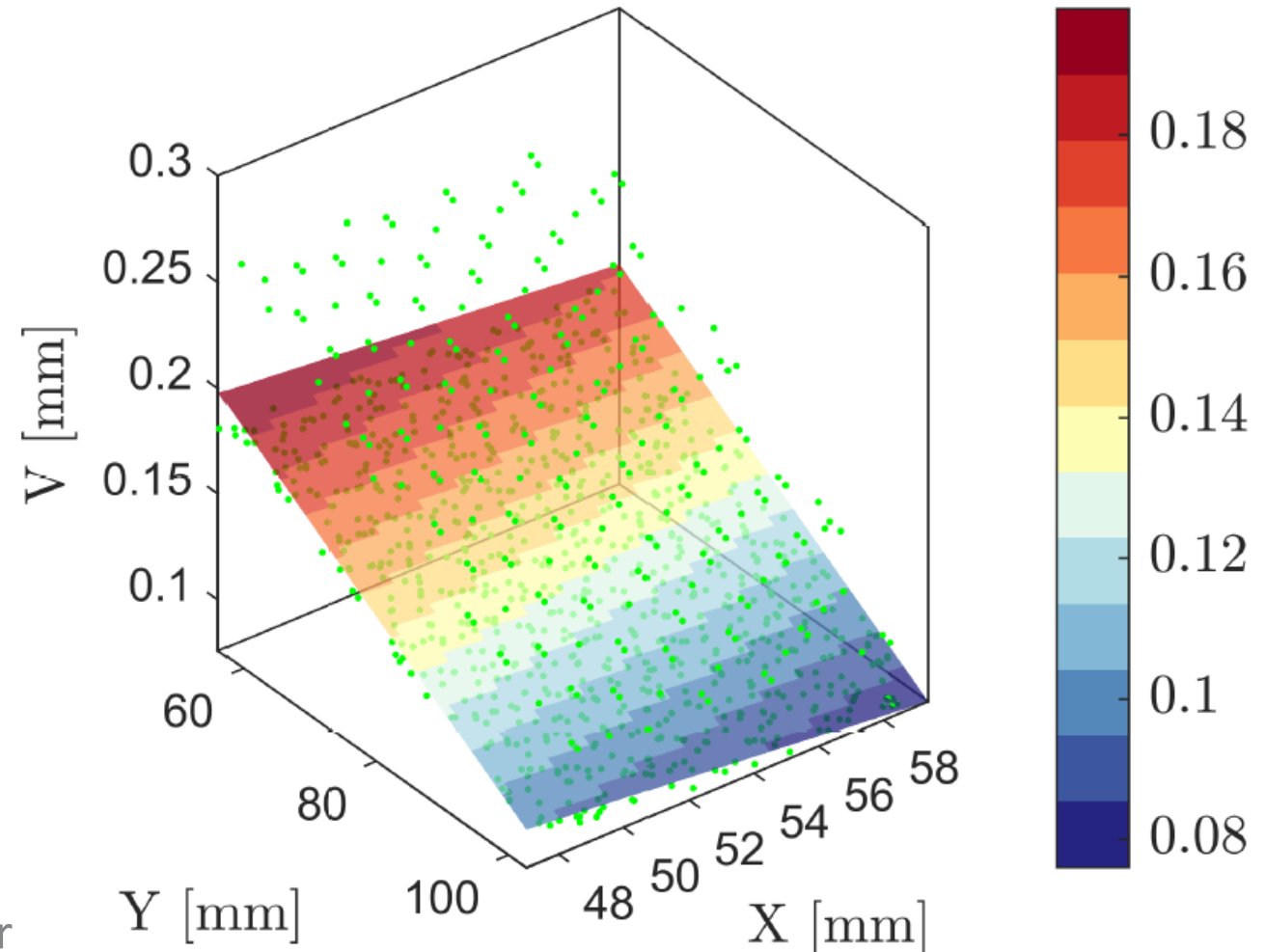


# Calculation of the strain for the ASTM E83 comparison

## Notes

- Method is still in process of being developed
- 3 Groups had coordinate system errors and were not used for calculating the displacement/strain
- Pixel locations rather than X,Y locations used and then scaled (again due to coordinate issues)
- 5 Groups & 5 VSG sizes with a weighted average were combined together to get U, V and W planes. May have had the same subset size. Weights were determined from noise floor images.
- Displacement fields were then fit with a plane to calculate the  $\epsilon_{xx}$ ,  $\epsilon_{yy}$ , and  $\epsilon_{xy}$
- The average strains were then subtracted as the “ground truth” for the following “ASTM” plots.
- Errors may grow in the plastic regions, but are thought to be small at this point.

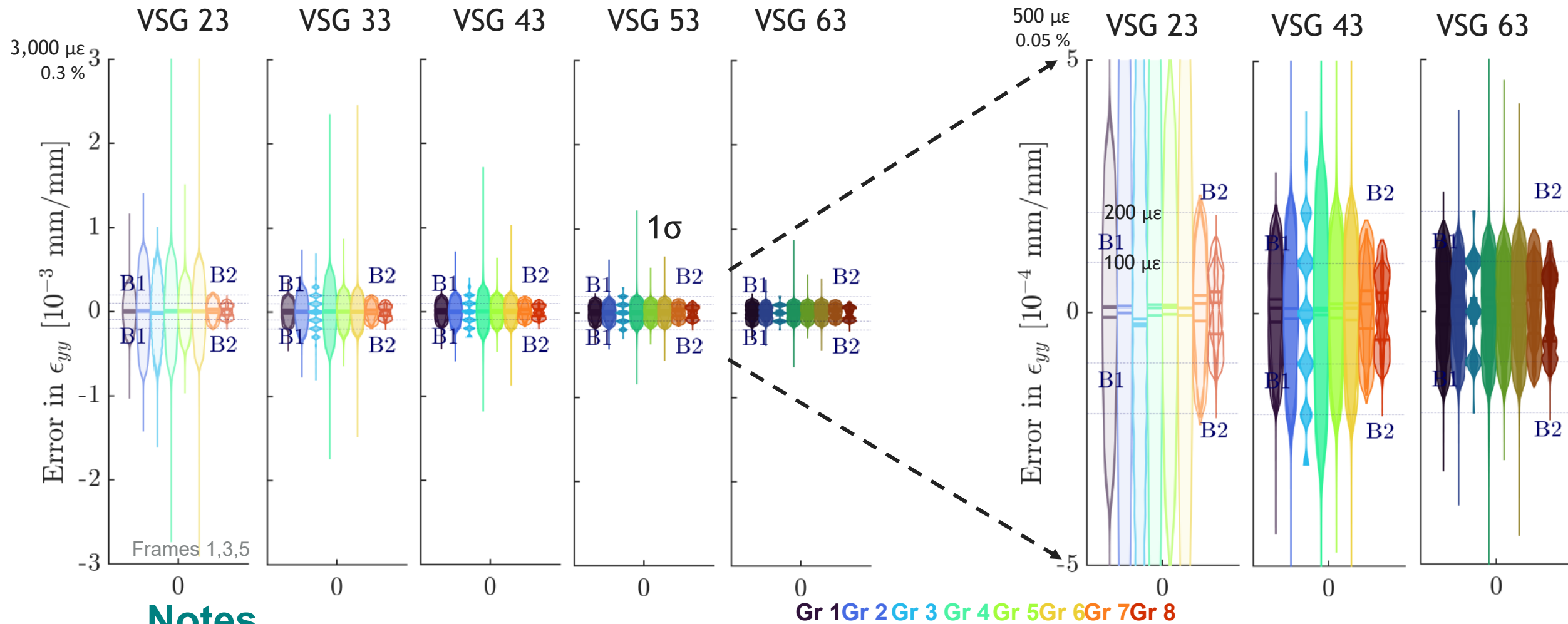
V- Displacement field (Data and average plane)



Verification and classification of extensometer systems ASTM E83 and ISO 9513



# ASTM Noise floor image comparisons $\epsilon_{yy}$

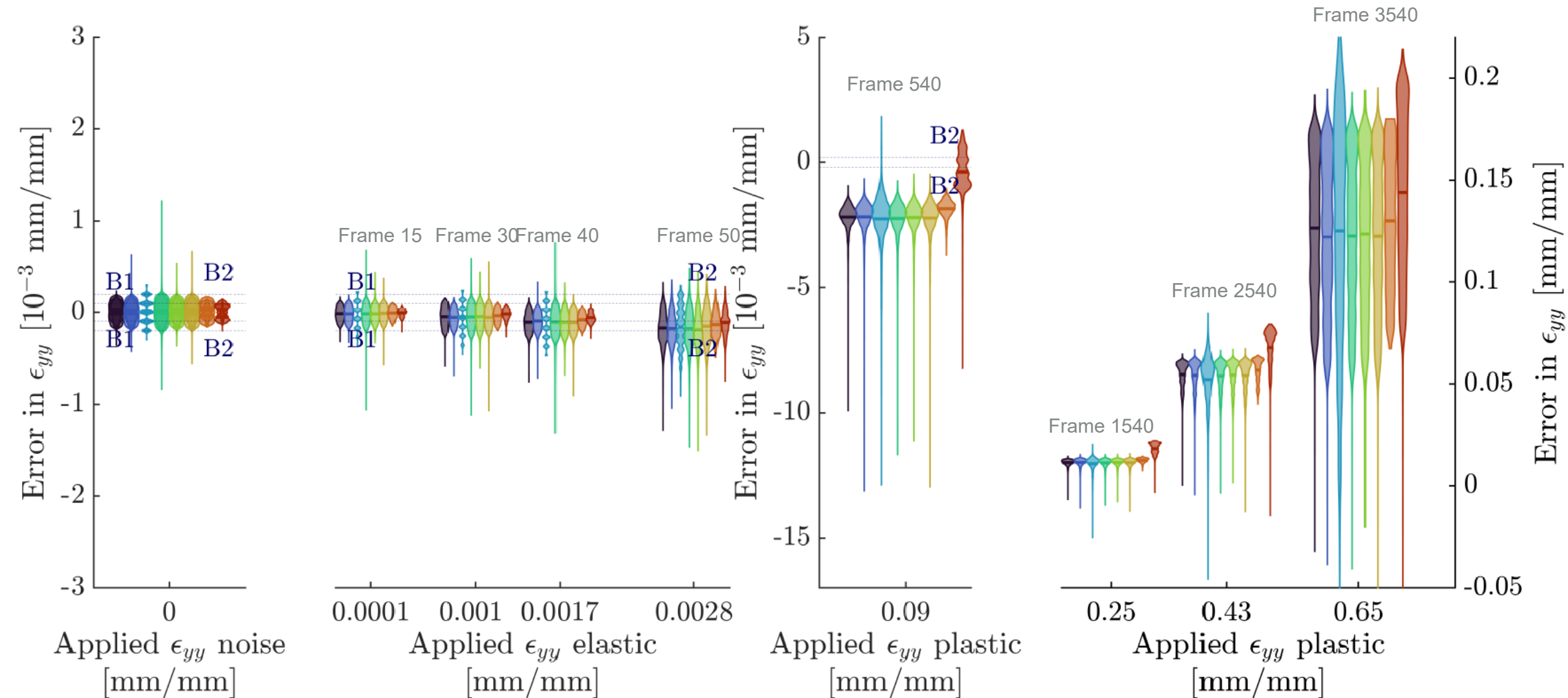


## Notes

- VSG 43 seems to be the optimum size
- In the noise region we meet the ASTM B1 standards



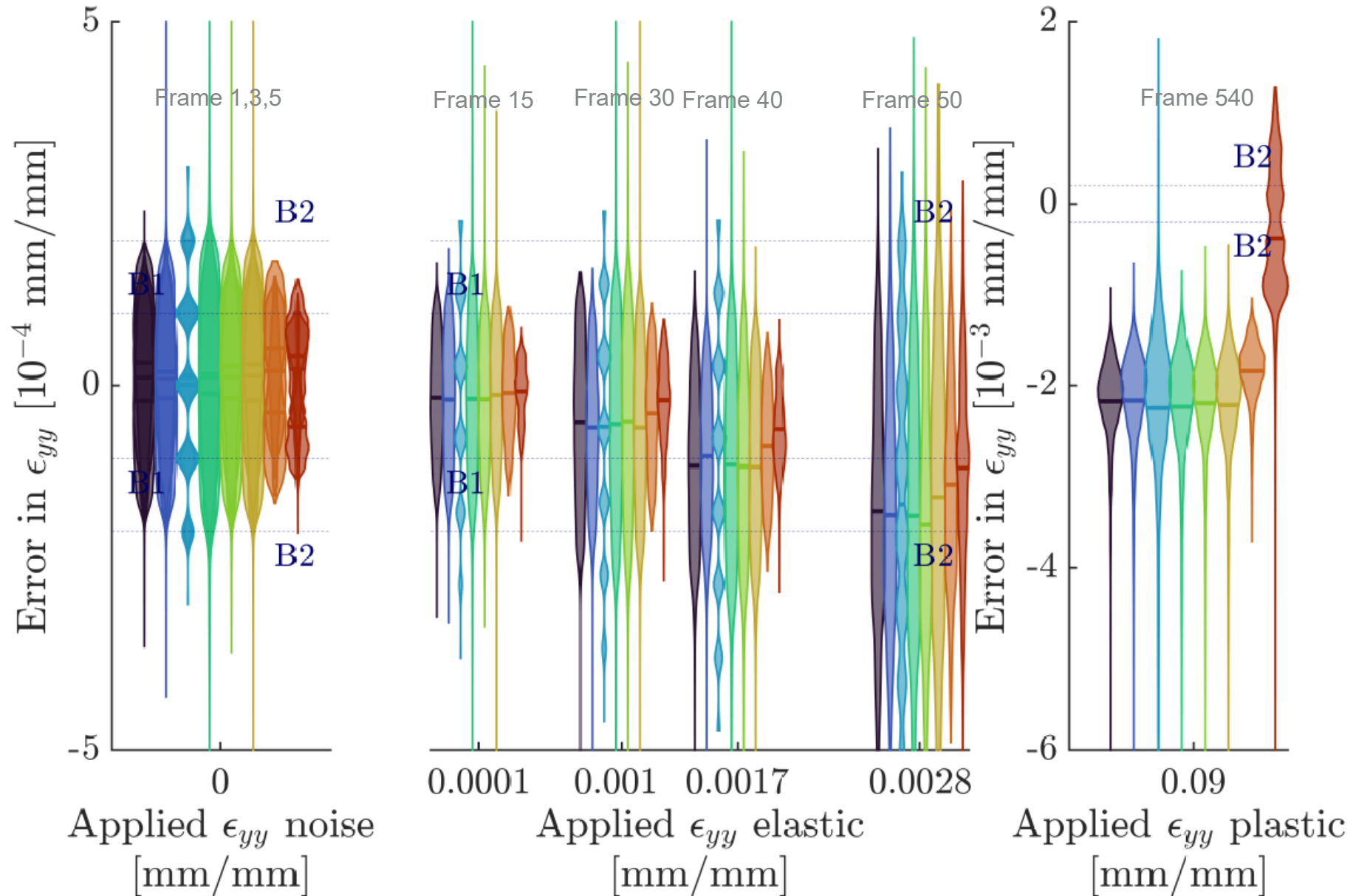
# ASTM Comparisons $\epsilon_{yy}$ – All Frames VSG=43





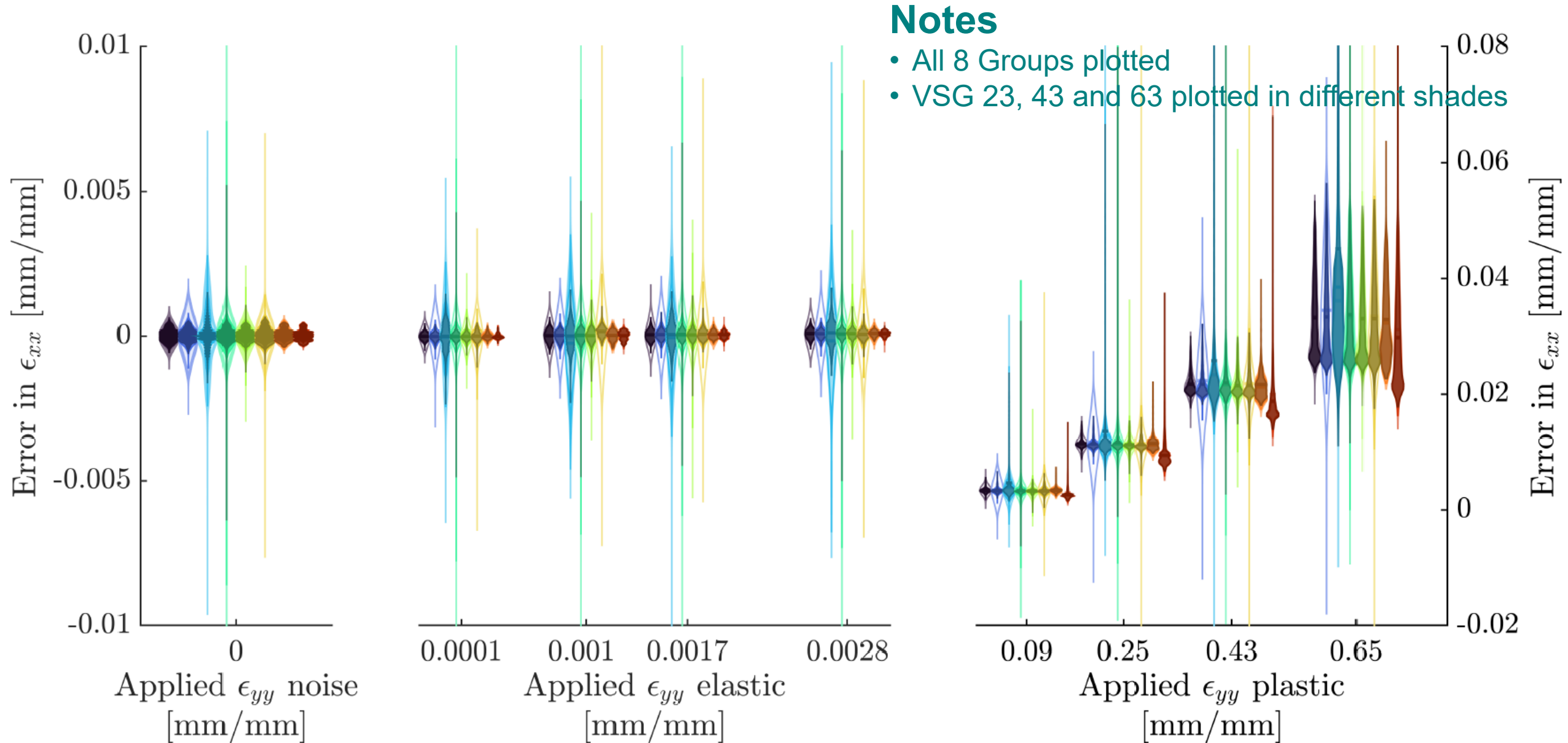


# ASTM Comparisons $\epsilon_{yy}$ – All Frames VSG=43





# ASTM Comparisons (zoomed) $\epsilon_{xx}$

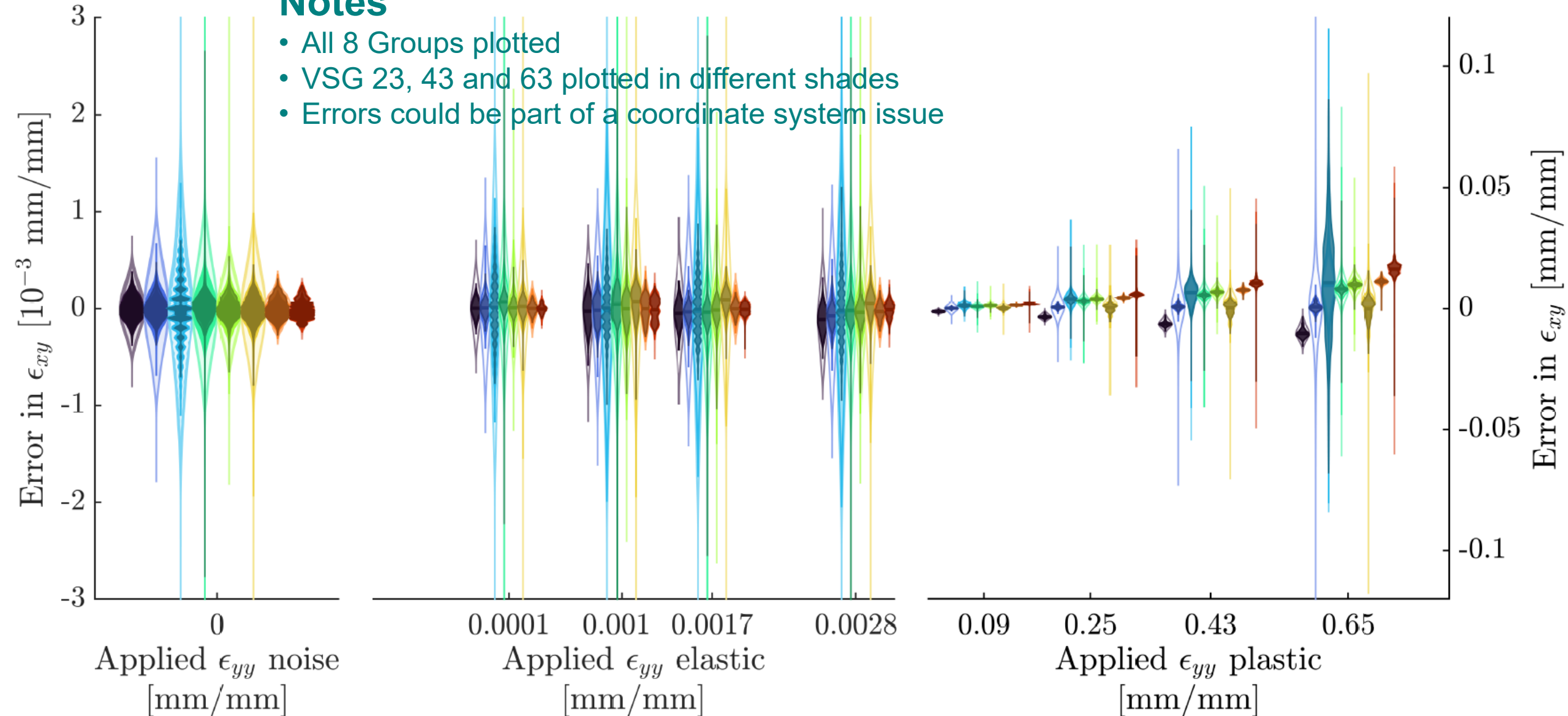




# ASTM Comparisons (zoomed) $\epsilon_{xy}$

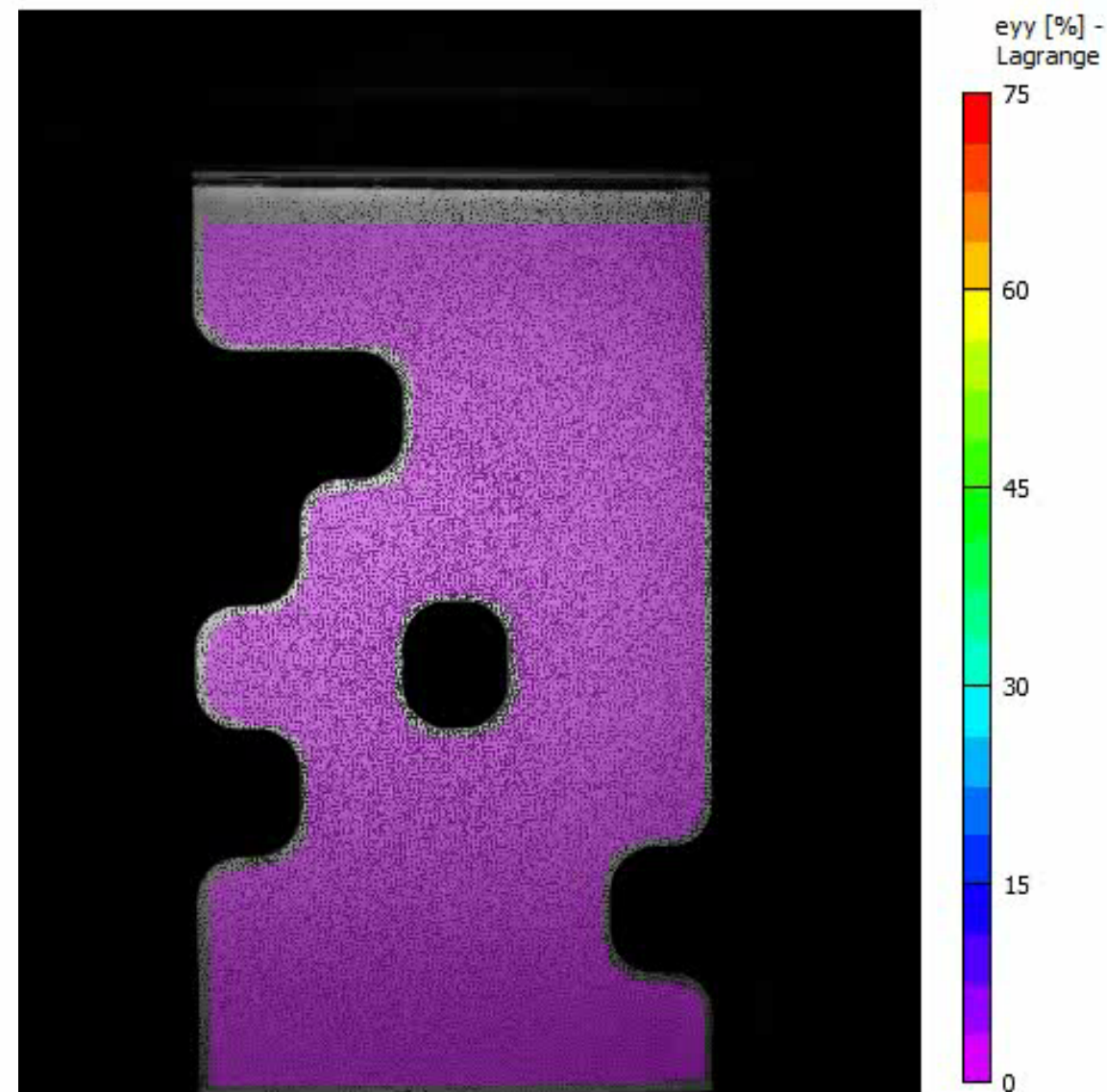
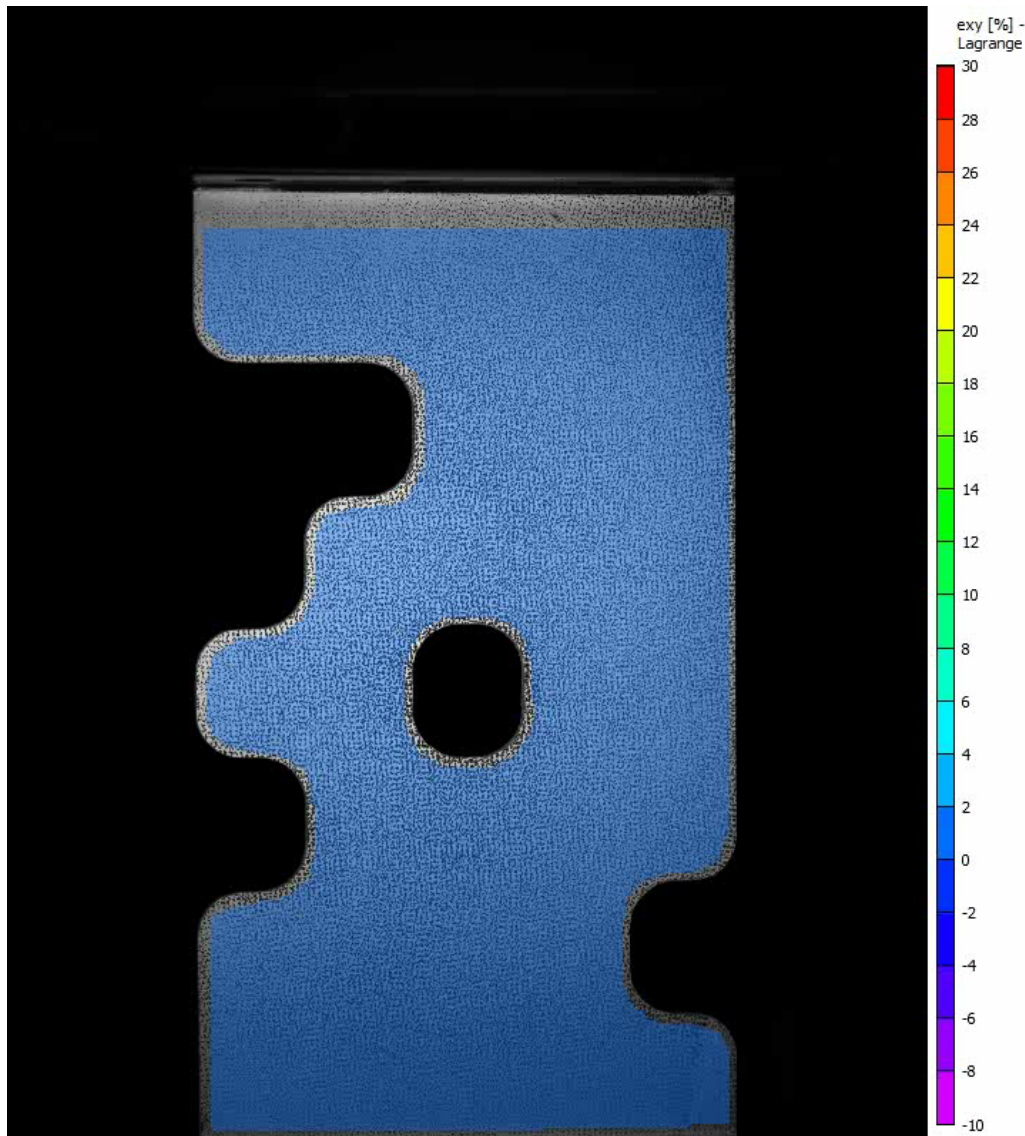
## Notes

- All 8 Groups plotted
- VSG 23, 43 and 63 plotted in different shades
- Errors could be part of a coordinate system issue





## Example data for the bespoke specimen





# Invitation to help with the analysis

Participant	Type of Code	Strain Method
DICe	Subset Based	
LaVision	Subset Based	Provided
Dantec Dynamics	Subset Based	Provided
Correlated Solutions	Subset Based	
Eikosim	Global Code	
MatchID	Subset Based	
ALDIC	Subset/Global Hybrid	Provided
CorreliSTC	Global Code	
Your Name Here		

## Missing Codes from the Challenge

- GOM
- Image Systems
- SeptD
- IIT

## Future Analysis Ideas (There are multiple papers in this data)

- A participant to run the “missing” codes and submit results
- A study of the effect lens distortion correction on the results
- Improvement on the ASTM analysis
- A comparison of the **displacement** fields for each code
- Bespoke sample data comparisons
- Material 2.0 comparisons

# iDICs 2024 is in France – come join us October 29<sup>th</sup>

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## Classes

- DIC201 – Updated and new full day

In association with Photomechanics