



Sandia
National
Laboratories



User-Level Threading for HPC Applications

CEA-NNSA Meeting – June 19-22, 2023

Jan Ciesko, SNL

Adrien Roussel, CEA/DAM

Outline

1.ULT for HPC Applications

2.Qthreads and MPC

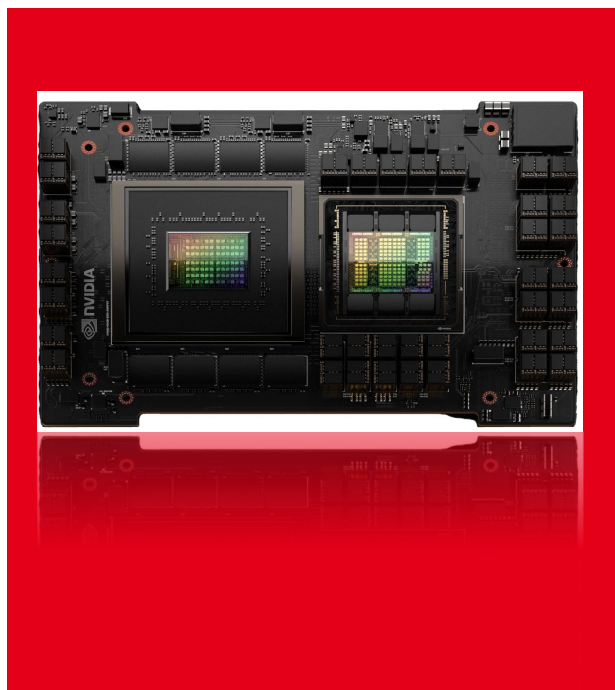
3.Projects

4.Conclusion

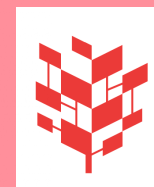
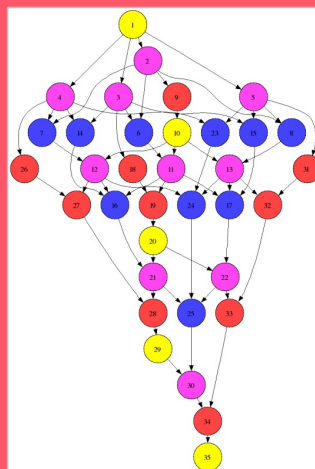


ULT for HPC Applications

The opportunity:



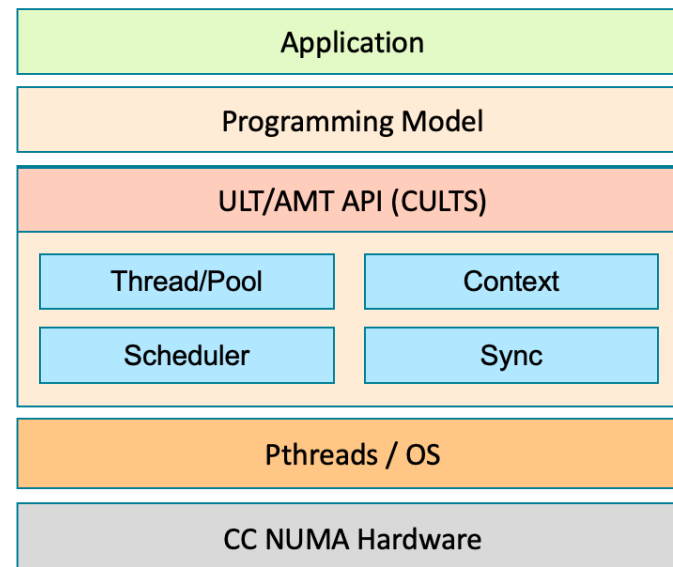
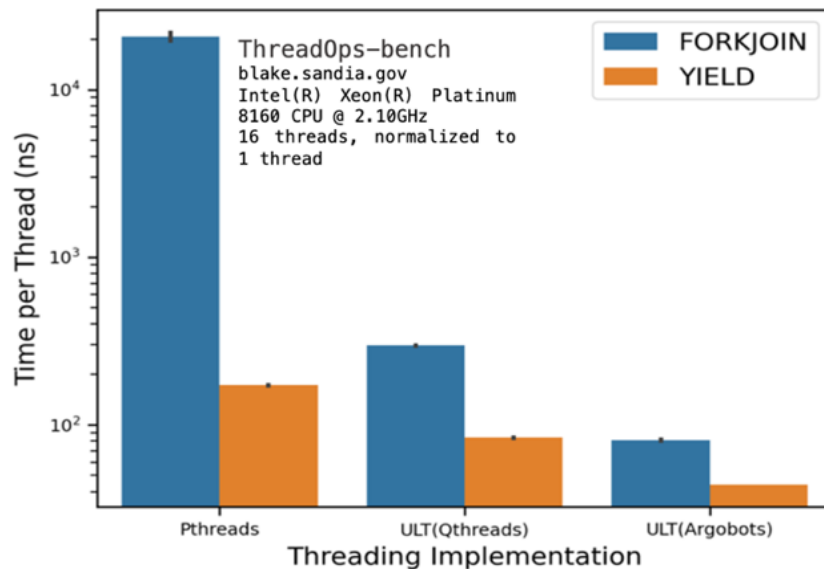
Matrix factorization (ILU, LU, CHOL), Direct Solvers, MD, Graph algorithms



ULT for HPC Applications

Asyncs, jthreads, processes, futures, coroutines, pthreads, tasks, fibers, kernels, agents, actors, executors, senders-receivers

- We need domain-specific interfaces that target abstract machine models (a la Kokkos)
- Important: task-parallelism benefits from light-weight units of work (task)





2. Multi-Processor Computing (MPC)

Qthreads

FunHPC:
Functional HPC Programming

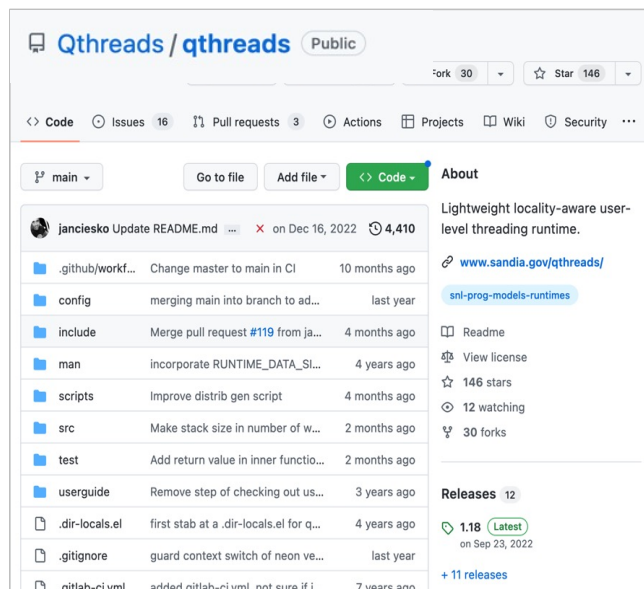


MPICH



OPEN MPI

“An API for Programing with Millions of Lightweight Threads”



Publications

To cite Qthreads:

- [Qthreads: An API for Programming with Millions of Lightweight Threads](#) . Kyle Wheeler, Richard Murphy, Douglas Thain. In *Proceedings of the 22nd IEEE International Parallel & Distributed Processing Symposium Workshops (IPDPS '08, in the MTAAP '08 workshop)*, IEEE Press, 2008.

Related Papers:

- [Scheduling Chapel Tasks with Qthreads on Manycore: A Tale of Two Schedulers](#) . Noah Evans, Stephen Olivier, Richard Barrett, George, Stelle. In *Proceedings of the 7th International Workshop on Runtime and Operating Systems for Supercomputers (ROSS 2017)*, ACM Press, 2017.
- [Kokkos/Qthreads task-parallel approach to linear algebra based graph analytics](#) . Michael Wolf, H. Carter Edwards and Stephen Olivier. In *Proceedings of the 2016 IEEE High Performance Extreme Computing Conference (HPEC 2016)*, IEEE Press, 2016.
- [Early Experiences Co-Scheduling Work and Communication Tasks for Hybrid MPI+X Applications](#) . D. T. Stark, R. F. Barrett, R. E. Grant, S. L. Olivier, K. T. Pedretti and C. T. Vaughan. In *2014 Workshop on Exascale MPI (ExaMPI 2014) at SC14*, IEEE Press, 2014.
- [Scheduling Task Parallelism on Multi-Socket Multicore Systems](#) . Stephen Olivier, Allan Porterfield, Kyle Wheeler, and Jan Prins. In *Proceedings of the 25th International Conference on Supercomputing (ICS'11, in the ROSS'11 workshop)*, ACM Press, 2011.
- [Implementing a Portable Multi-threaded Graph Library: the MTGL on Qthreads](#) . Brian Barrett, Jonathan Berry, Richard Murphy, Kyle Wheeler. In *Proceedings of the 23rd IEEE International Parallel & Distributed Processing Symposium (IPDPS '09, in the MTAAP '09 workshop)*, IEEE Press, 2009.

- 182 functions in 16 areas



- 6 concepts
 - Qthreads
 - Locality
 - FEB
 - Schedulers
 - Blocking Action
 - Context Swap

[1] <https://github.com/Qthreads/qthreads>

[2] <https://join.slack.com/t/qthreads/>

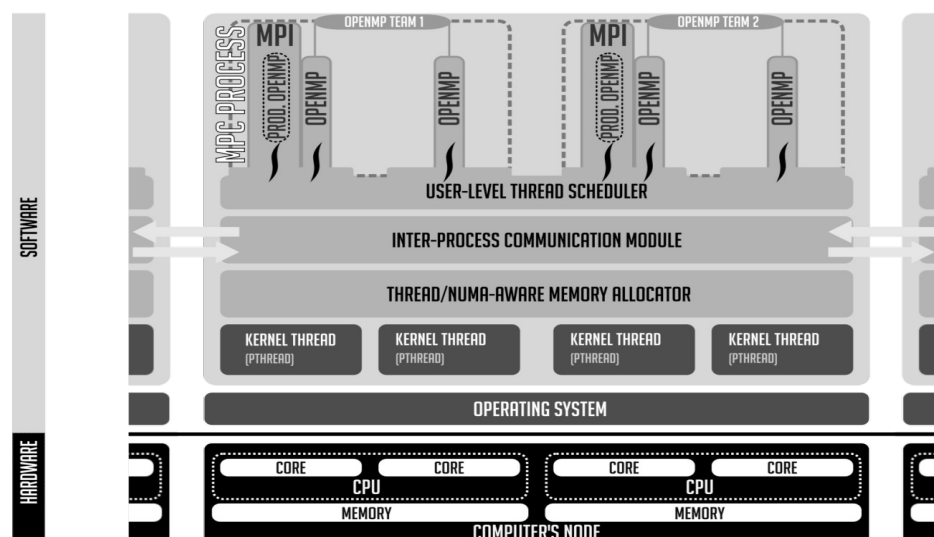


Multi-Processor Computing

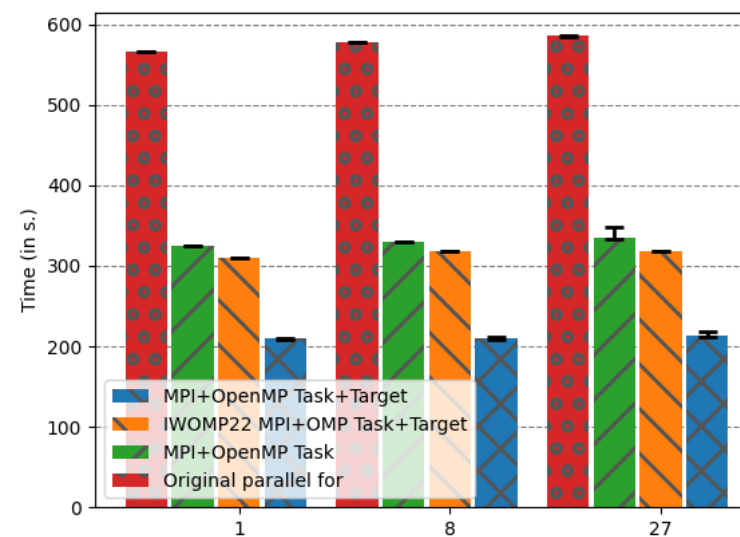
MPC Framework

- MPC (Multi Processor Computing)
 - **Features MPI & OpenMP** Implementation
 - **Implements user-level threading scheduler** and interoperability

- Architecture



- Lulesh (weak scaling)



- Problem size: 264^3 elements, 128 iterations



3. Projects

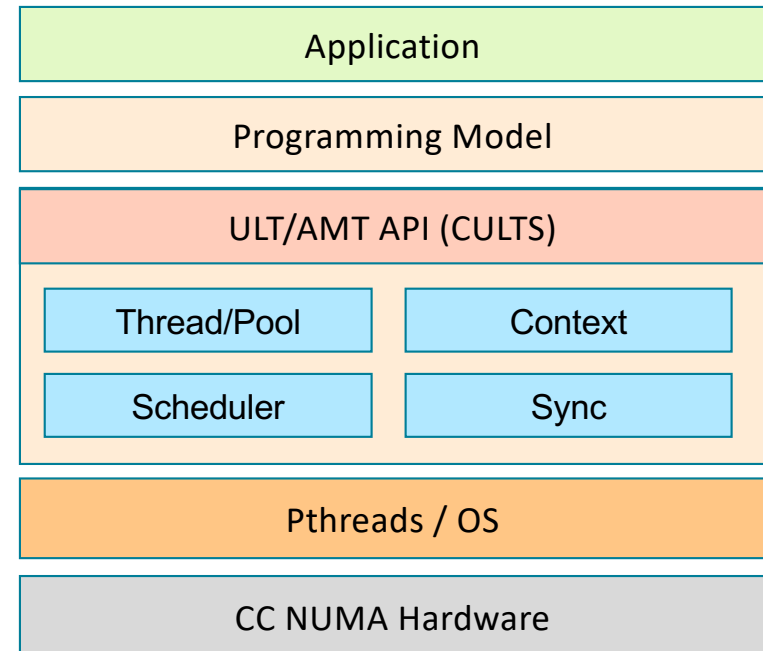


Better code: Common ULT Substrate (CULTS)

1/5

Many common building blocks among ULT/AMT libraries

- Externalize common functionality like context swap
- Improve code quality
- Develop towards common prog model frontends (C++ stdlib, HPX, Chapel)



Collaborators:





Better interop: LIBULT and MPI_TASK_MULTIPLE

2/5

OpenMPI and MPICH support ULT/AMT libs

- Qthreads and Argobots are supported
- Configure options
- Developer needs matching MPI for this app
- Pulls in ULT/AMT lib specific codes

Develop libult as a generic ULT/AMT interface so MPI can be configured for ULT support (vs. Pthreads)

- Which particular ULT is used is determined at application compile time
- Potentially add **MPI_TASK_MULTIPLE**

Collaborators:



Sandia
National
Laboratories



Others:



THE UNIVERSITY OF
TENNESSEE
KNOXVILLE



```
--with-thread-package=package MPICH
--with-argobots=[PATH]
--with-argobots-include=PATH
--with-argobots-lib=PATH
```

Open MPI

```
--with-threads=TYPE Specify thread TYPE to use. default:pthreads. Other
options are qthreads and argobots.
--with-argobots=DIR Specify location of argobots installation. Error:
argobots support cannot be found.
--with-argobots-libdir=DIR Search for argobots libraries in DIR
--with-qthreads=DIR Specify location of qthreads installation. Error:
qthreads support cannot be found.
--with-qthreads-libdir=DIR Search for qthreads libraries in DIR
```

Note: Use *ompi_info --config* to see your MPI configuration



Event-orientation in MPI: MPI Continuations

Chapter 16

Allows to attach callback functions to MPI operations

- Spec proposal to be voted on in 2023. [1][2]
- Makes OpenMP interop work (sort of)
- MPI Cont' can replace task offload to communication threads in HPX and others
- Polling vs callback in interop?

Collaborators:



ECP Deliverable 2022

<https://github.com/devreal/ompi/tree/mpi-continue-master>

<https://github.com/mpiwg-hybrid/hybrid-issues/issues/6>

Completion Continuations

Some applications may need to handle large numbers of requests or require fast reaction to the completion or cancellation of an MPI operation. The reaction to the completion of an operation can be expressed as a **continuation** application that is invoked by MPI once completion alleviates the need for the application to manage fast reaction to state changes.

Continuations are **attached** to either a **shared** request or a **persistent** request. A continuation request is used to test or wait for the completion of a request. Once all continuations registered with the request complete, the continuation request is completed. How at any time.

Continuation requests are used to test or wait for the completion of a request. A continuation request is used to test or wait for the completion of a request. A continuation request is used to test or wait for the completion of a request.

In general, continuation requests are used to test or wait for the completion of a request. A continuation request is used to test or wait for the completion of a request. A continuation request is used to test or wait for the completion of a request.

When attaching a continuation request to a request, the continuation request will be filled before the request is completed. By using MPI_STATUS_IGNORE, the continuation request will be filled before the request is completed.

Example 16.1

A continuation is a request that is used to test or wait for the completion of a request. A continuation request is used to test or wait for the completion of a request. A continuation request is used to test or wait for the completion of a request.

#include <mpi.h>

```
1 int callback(int rc, void *data) {
2   omp_event_handle_t event = (omp_event_handle_t) data;
3   omp_fulfill_event(event);
4   return MPI_SUCCESS;
5 }
6
7 MPI_Request cont_req;
8 MPIX_Continue_init(MPI_UNDEFINED, 0, MPI_INFO_NULL, &cont_req);
9 MPI_Start(&cont_req);
10
11 #pragma omp task depend(out:value) \
12   shared(value, comm_started_flag) detach(event) producer
13 {
14   MPI_Request req;
15   MPI_Irecv(&value, 1, MPI_INT, 1, 0, MPI_COMM_WORLD, &req);
16   MPIX_Continue(&req, &callback, (void *) event, \
17     MPIX_CONT_PERSISTENT, MPI_STATUS_IGNORE, cont_req);
18   comm_started_flag = 1;
19 }
20
21 #pragma omp task depend(in:value) consumer
22 {
23   assert(value == REF);
24 }
25
26 #pragma omp task shared(comm_started_flag) polling
27 {
28   int flag = 0;
29   do {
30     if (comm_started_flag) {
31       MPI_Test(&cont_req, &flag, MPI_STATUS_IGNORE);
32     }
33     #pragma omp taskyield /*potentially noops*/
34     while(!flag);
35   }
36 }
37
38 #pragma omp taskwait
39 MPI_Request free (&cont_req);
```

Some applications may need asynchronous reaction to the completion of an operation function provided by the application.

Continuations are attached to a request and registered with a continuation request that has to be initialized. The completion of all registered continuations registered with the request has to be started to enable the request to be registered with a valid continuation request.

Continuation requests themselves are not persistent. All continuations registered with a request have been executed. Attaching a continuation to a non-persistent request returns ownership of that request to MPI, i.e., the request may not be used to test or wait for the completion of the respective operation. The ownership of persistent requests is returned to the application at the start of the execution of the continuation callback. The outcome of attaching more than one continuation to a request is undefined.

Continuations can be executed by any thread calling into MPI or by a restricted set of threads belonging to the application and testing or waiting on the associated continuation request (see Section 16.1.1). When attaching a continuation to a request, a status object may be provided, which will be filled before the continuation is invoked. The application may pass MPI_STATUS_IGNORE instead of a status object or status objects.

3/5

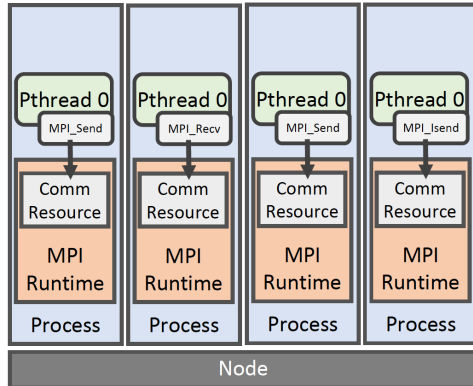
OpenMF



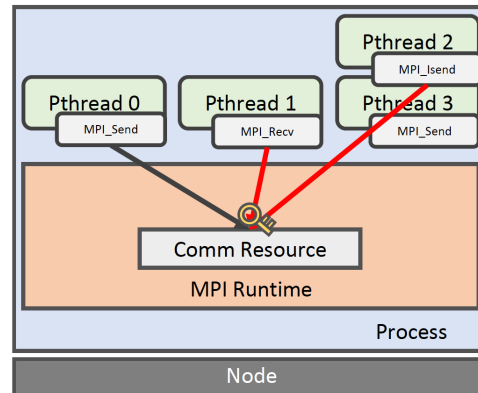
VCI-(Resource-)Aware Task-scheduling

4/5

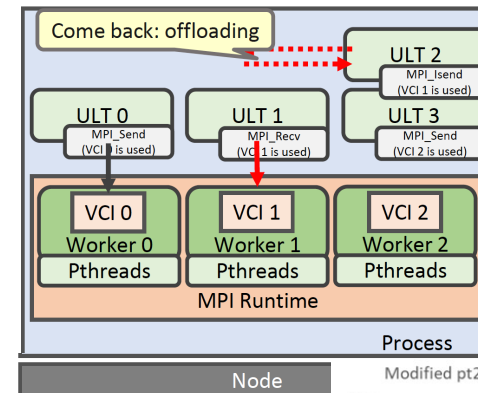
Match performance of MPI-everywhere if scheduler serialize contending tasks on VCI



MPI Everywhere (MPI_THREAD_SINGLE)

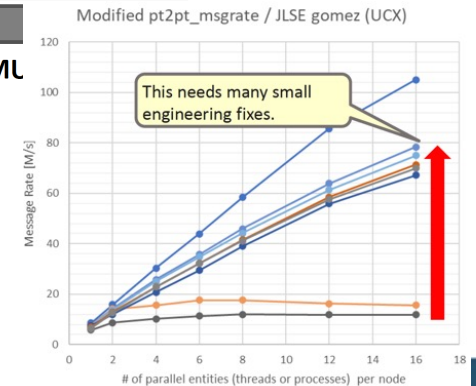
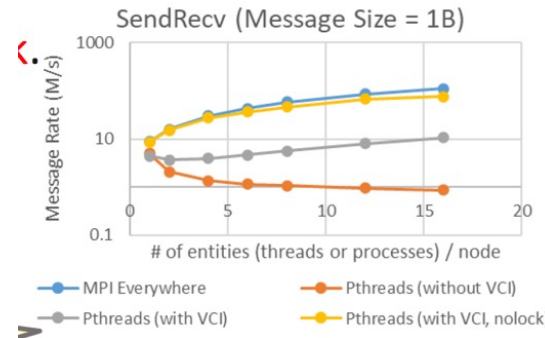


MPI_THREAD MULTIPLE



MPI_THREAD_MULTIPLE

Collaborators:



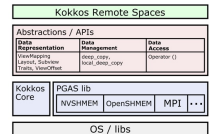


Device-initiated Communication

5/5

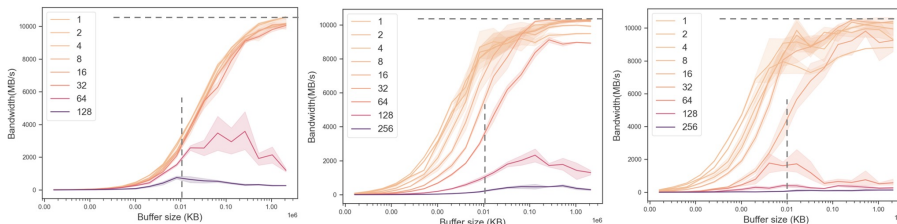
Two APIs: RMA or Partitioned Communication

- What is the usage model in a kernel?



User-level threading (ULT) + Partitioned Communication (Basic)

- MPI Partix: "Bench1", 16KB-2GB buffer size, 1:1 partitions to task mapping



Blake, x86, UCX, OMPI 5.0.X, Pthreads, 1-128 partitions, 1:1 P2T

Blake, x86, UCX, OMPI 5.0.X, Qthreads, 1-256 partitions, 1:1 P2T

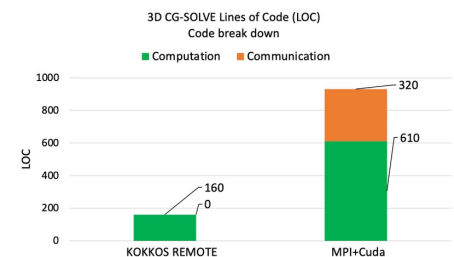
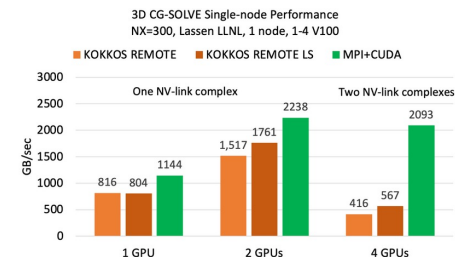
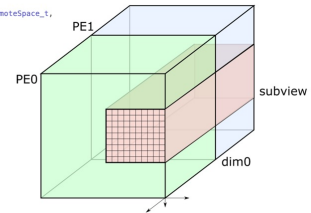
Blake, x86, UCX, OMPI 5.0.X, OMP Task, 1-256 partitions, 1:1 P2T

<https://github.com/sandialabs/MPI-Partix>

Kokkos + RMA/PC (Kokkos Remote Spaces Project)

- CGSolve

```
1 ...
2 using ViewRemote_3D_t = Kokkos::View<Data_t, Dim3, DefaultRemoteSpace_t,
3 Kokkos::MemoryTraits<Kokkos::atomic_v>
4 ViewRemote_3D_t view =
5 ViewRemote_3D_t("RemoteView", 20, 20, 20);
6
7 auto range0 = Kokkos::All();
8 std::pair<int, int> range1 = std::make_pair(10, 20);
9 std::pair<int, int> range2 = std::make_pair(5, 15);
10
11 auto sub_view =
12 Kokkos::subview(view, range0, range1, range2);
13
14 ...
15
16 Kokkos::parallel_for("Increment", sub_view.extent(0),
17 Kokkos::LAMBDA<const int>() {
18   for (int i = 0; i < sub_view.extent(1); ++i)
19     for (int l = 0; l < sub_view.extent(2); ++l) {
20       sub_view(i, i, l)++;
21     }
22   });
23 ...
```



<https://github.com/kokkos/kokkos-remote-spaces>

Collaborators:



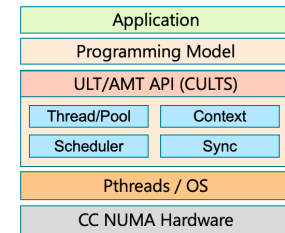


4. Conclusion & Future Works



Conclusion (brief)

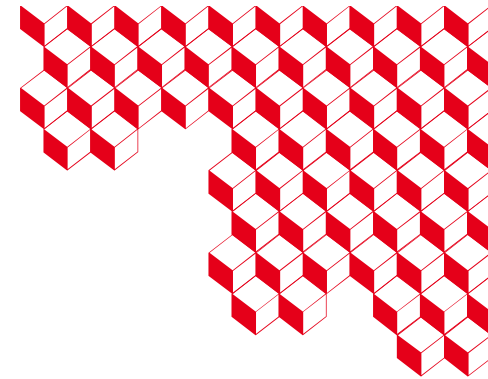
- Roadmap ULT/AMT libs @ NNSA and CEA
 - Increase code quality and reduce maintenance
 - Common ULT Substrate (CULTS)
 - No API lock-in
 - Expose through established interfaces (OpenMP, Chapel, HPX, stdlib)
 - Play nice with others
 - Interoperability with MPI and non-cooperative APIs
 - Be relevant
 - Work on GPU stuff (RMA and PartCom on GPUs)
 - Could constrained task-execution (aka dataflow) be a thing?
 - 144 CCNUMA Cores on GH – how to use that?



Contact:

adrien.roussel@cea.fr, jciesko@sandia.gov





Thank you for your attention

Questions?

Adrien Roussel, PhD

adrien.roussel@cea.fr

jciesko@sandia.gov

MPC Team



Backup



Qthreads

“An API for Programing with Millions of Lightweight Threads”

The screenshot shows the GitHub repository for Qthreads. At the top, it says 'Qthreads / qthreads' with a 'Public' label. Below this are buttons for 'Edit Pins', 'Unwatch' (12), 'Fork' (30), and 'Star' (146). A navigation bar includes links for 'Code', 'Issues' (16), 'Pull requests' (3), 'Actions', 'Projects', 'Wiki', 'Security', and a menu icon. Below the navigation bar, there's a 'main' branch selector, 'Go to file', 'Add file', and a 'Code' button. The 'About' section describes it as a 'Lightweight locality-aware user-level threading runtime' and provides a link to 'www.sandia.gov/qthreads/'. It also lists 'snl-prog-models-runtimes'. The 'Releases' section shows version '1.18' as the 'Latest' release, dated 'on Sep 23, 2022', with '+ 11 releases'. The 'Files' section lists various directories and files with their last update times: '.github/workf...' (10 months ago), 'config' (last year), 'include' (4 months ago), 'man' (4 years ago), 'scripts' (4 months ago), 'src' (2 months ago), 'test' (2 months ago), 'userguide' (3 years ago), '.dir-locals.el' (4 years ago), '.gitignore' (last year), and '.aitlab-ci.vml' (7 years ago).

Publications

To cite Qthreads:

- [Qthreads: An API for Programming with Millions of Lightweight Threads](#) . Kyle Wheeler, Richard Murphy, Douglas Thain. In *Proceedings of the 22nd IEEE International Parallel & Distributed Processing Symposium Workshops (IPDPS '08, in the MTAAP '08 workshop)*, IEEE Press, 2008.

Related Papers:

- [Scheduling Chapel Tasks with Qthreads on Manycore: A Tale of Two Schedulers](#) . Noah Evans, Stephen Olivier, Richard Barrett, George, Stelle. In *Proceedings of the 7th International Workshop on Runtime and Operating Systems for Supercomputers (ROSS 2017)*, ACM Press, 2017.
- [Kokkos/Qthreads task-parallel approach to linear algebra based graph analytics](#) . Michael Wolf, H. Carter Edwards and Stephen Olivier. In *Proceedings of the 2016 IEEE High Performance Extreme Computing Conference (HPEC 2016)*, IEEE Press, 2016.
- [Early Experiences Co-Scheduling Work and Communication Tasks for Hybrid MPI+X Applications](#) . D. T. Stark, R. F. Barrett, R. E. Grant, S. L. Olivier, K. T. Pedretti and C. T. Vaughan. In *2014 Workshop on Exascale MPI (ExaMPI 2014) at SC14*, IEEE Press, 2014.
- [Scheduling Task Parallelism on Multi-Socket Multicore Systems](#) . Stephen Olivier, Allan Porterfield, Kyle Wheeler, and Jan Prins. In *Proceedings of the 25th International Conference on Supercomputing (ICS'11, in the ROSS'11 workshop)*, ACM Press, 2011.
- [Implementing a Portable Multi-threaded Graph Library: the MTGL on Qthreads](#) . Brian Barrett, Jonathan Berry, Richard Murphy, Kyle Wheeler. In *Proceedings of the 23rd IEEE International Parallel & Distributed Processing Symposium (IPDPS '09, in the MTAAP '09 workshop)*, IEEE Press, 2009.



Qthreads API

- 182 functions in 16 areas
- 6 concepts
 - Qthreads
 - Locality
 - FEB
 - Schedulers
 - Blocking Action
 - Context Swap

Feature	API	Description
Array	1 qarray_create	allocate a runtime distributed array
	2 qarray_create_configured	allocate a runtime distributed array
	3 qarray_create_light	allocate a runtime distributed array
	4 qarray_destroy	deallocate a distributed array
	5 qarray_dist_like	redistribute a qarray to match another qarray
	6 qarray_elem	return a pointer to a distributed array element
	7 qarray_elem_migrate	return a pointer to a distributed array element
	8 qarray_elem_nomigrate	return a pointer to a distributed array element
	9 qarray_iter	iterate through a distributed array
	10 qarray_iter_constitop	iterate through a distributed array
	11 qarray_iter_loop	iterate through a distributed array
	12 qarray_iter_loop_nb	iterate through a distributed array
	13 qarray_iter_loopacum	iterate through a distributed array
	14 qarray_set_shepof	locate a distributed array element
	15 qarray_shepof	locate a distributed array element
Array Ops	16 qt_double_max	find the maximum value within an array in parallel
	17 qt_double_min	find the minimum value within an array in parallel
	18 qt_double_prod	multiplies an array in parallel
	19 qt_double_sum	add up an array in parallel
	20 qt_int_max	find the maximum value within an array in parallel
	21 qt_int_min	find the minimum value within an array in parallel
	22 qt_int_prod	multiplies an array in parallel
	23 qt_int_sum	add up an array in parallel
	24 qutil_double_max	find the maximum value within an array in parallel
Utils	25 qutil_double_min	find the minimum value within an array in parallel
	26 qutil_double_mult	multiply an array in parallel
	27 qutil_double_sum	add up an array in parallel
	28 qutil_int_max	find the maximum value within an array in parallel
	29 qutil_int_min	find the minimum value within an array in parallel
	30 qutil_int_mult	multiply an array in parallel
	31 qutil_int_sum	add up an array in parallel
	32 qutil_mergesort	sorts an array of doubles in parallel
	33 qutil_qsort	sorts an array of doubles in parallel
	34 qutil_uint_max	find the maximum value within an array in parallel
	35 qutil_uint_min	find the minimum value within an array in parallel
	36 qutil_uint_mult	multiply an array in parallel
	37 qutil_uint_sum	add up an array in parallel
	38 qthmad_dincr	atomically increment a value
	39 qst_allpairs	computes a given function over all pairs of the input data
Queue	40 qdqueue_create	allocate a distributed queue
	41 qdqueue_dequeue	remove an element from a distributed queue
	42 qdqueue_destroy	deallocate a distributed queue
	43 qdqueue_empty	test whether a distributed queue is empty
	44 qdqueue_enqueue	append an element to a distributed queue
	45 qdqueue_enqueue_there	append an element to a distributed queue
	46 qlfqueue_create	allocate a lock-free queue
	47 qlfqueue_dequeue	remove an element from a lock-free queue
	48 qlfqueue_destroy	deallocate a lock-free queue
	49 qlfqueue_empty	test whether a lock-free queue is empty
Mem pool	50 qlfqueue_enqueue	append an element to a lock-free queue
	51 qpool_alloc	allocate memory from a distributed memory pool
	52 qpool_create	allocate a distributed memory pool
	53 qpool_create_aligned	allocate a distributed memory pool
	54 qpool_destroy	deallocate a distributed memory pool
	55 qpool_free	return a memory block to its distributed memory pool
Memmap	56 qalloc_checkpoint	locks an address, and may block
	57 qalloc_cleanup	unmaps all memory maps
	58 qalloc_dynfree	return an allocated block to the map
	59 qalloc_dynmalloc	allocates memory from the specified map
	60 qalloc_free	return an allocated block to the map
	61 qalloc_loadmap	creates or loads a map file
	62 qalloc_makemap	creates or loads a map file
	63 qalloc_makemap	creates or loads a map file
	64 qalloc_malloc	allocates memory from the specified map
	65 qalloc_statfree	return an allocated block to the map
Sys call	66 qalloc_statmalloc	allocates memory from the specified map
	67 qt_accept	accept a connection
	68 qt_connect	connect to a server
	69 qt_system	pass a command to the shell
	70 qt_block_blocking_action	indicate blocking operations to the runtime
	71 qt_end_blocking_action	indicate blocking operations to the runtime
	72 qt_wait	wait for process termination
	73 qt_dictionary_create	allocate a concurrent dictionary
	74 qt_dictionary_delete	remove a key/value pair from the dictionary
	75 qt_dictionary_destroy	deallocate a concurrent dictionary
Dictionary	76 qt_dictionary_end	create an iterator pointing to the end of the dictionary
	77 qt_dictionary_get	retrieve a value from the dictionary
	78 qt_dictionary_iterator_create	duplicate an iterator
	79 qt_dictionary_iterator_create	allocate a concurrent dictionary iterator
	80 qt_dictionary_iterator_destroy	deallocate a qt_dictionary_iterator
	81 qt_dictionary_iterator_equals	compare two iterators
	82 qt_dictionary_iterator_get	retrieve the indicated entry in the dictionary
	83 qt_dictionary_iterator_next	retrieve the current value and advance the iterator
	84 qt_dictionary_put	retrieve the current value and advance the iterator
	85 qt_dictionary_put_if_absent	insert a key/value pair into a dictionary
Timer	86 qtimer_create	allocate a qtimer
	87 qtimer_destroy	deallocate a qtimer
	88 qtimer_generate	generate a quick random number based on the high-resolution timer
	89 qtimer_secs	calculate the elapsed time in seconds
	90 qtimer_start	start/stop a qtimer timing
	91 qtimer_stop	start/stop a qtimer timing
	92 qt_sinc_create	allocate and/or initialize a sinc
	93 qt_sinc_destroy	deallocate and clean-up a sinc
	94 qt_sinc_expect	increase the number of expected submissions
	95 qt_sinc_fini	deallocate and clean-up a sinc
Reductions	96 qt_sinc_init	allocate and/or initialize a sinc
	97 qt_sinc_restart	restarts a sinc
	98 qt_sinc_submit	submit to a sinc
	99 qt_sinc_wait	block caller until all expected submissions are submitted
	100 qt_poll	synchronous I/O multiplexing
	101 qt_read	read input
	102 qt_write	write output
	103 qt_read	read input
	104 qt_wait	synchronous I/O multiplexing
	105 qt_loop	implementation of a threaded loop
Loop	106 qt_loop_balance	implementation of a threaded loop that returns values
	107 qt_loop_balance_simple	implementation of a threaded loop
	108 qt_loop_queue_addworker	adds a worker to an ongoing loop
	109 qt_loop_queue_create	allocate a loop queue handle
	110 qt_loop_queue_run	allocate a loop queue handle
	111 qt_loop_queue_run_there	implementation of a threaded loop
	112 qt_loop_queue_setchunk	a function to specify a loop chunk size
	113 qt_loop_stop	implementation of a threaded loop
	114 qt_loopqueue_balance	implementation of a threaded loop that returns values
	115 qt_team_critical_section	marks a region of code that must not be interrupted by a cureka
Team	116 qt_team_eureka	signals a eureka moment
	117 qt_team_id	returns the current team's unique ID number
	118 qt_team_parent_id	returns the current team's parent's unique ID number
Thread	119 qt_thread_create	create a thread
	120 qt_thread_finalize	terminate all qthreads and free library data structures
	121 qt_thread_disable_shepherd	enable or disable a shepherd for thread scheduling
	122 qt_thread_disable_worker	enable or disable a worker for thread scheduling
	123 qt_thread_distance	returns the distance between shepherds
	124 qt_thread_getlevel	returns status information from the runtime
	125 qt_thread_cache_line	returns the cache line size
	126 qt_thread_init	initialize the qthread library
	127 qt_thread_initialize	initialize the qthread library
	128 qt_thread_migrate_to	relocate a qthread to the target shepherd
FEB	129 qt_thread_num_shepherds	returns the number of shepherds
	130 qt_thread_num_workers	returns the number of workers
	131 qt_thread_pass	pass a command to the shell
	132 qt_thread_yield	release the CPU, allow other qthreads to run
	133 qt_thread_worker	returns the qthread's current worker's task ID
	134 qt_thread_worker_unique	returns the qthread's current worker ID
	135 qt_thread_stackleft	returns the amount of space left in the thread's allocated stack
	136 qt_thread_spawn	spawn a qthread (task)
	137 qt_thread_status	returns status information from the runtime
	138 qt_thread_return	returns pointer to qthread's return location
Queue	139 qt_thread_shepherd	returns the qthread's shepherd ID
	140 qt_thread_shepherd_id	check on whether a thread's shepherd is disabled
	141 qt_thread_size_tactical	returns the number of bytes allocated for task-local data
	142 qt_thread_shepherd_id	returns a list of other shepherds, sorted by their distance
	143 qt_thread_shepherd_id	returns a list of other shepherds, sorted by their distance
	144 qt_thread_spawn	spawn a qthread
	145 qt_thread_fork	spawn a qthread
	146 qt_thread_fork_precond	spawn a qthread
	147 qt_thread_fork_precond_to	spawn a qthread
	148 qt_thread_fork_syncvar	spawn a qthread
Queue	149 qt_thread_fork_syncvar_to	spawn a qthread
	150 qt_thread_fork_to	spawn a qthread
	151 qt_thread_enable_shepherd	enable or disable a shepherd for thread scheduling
	152 qt_thread_disable_worker	enable or disable a worker for thread scheduling
	153 qt_thread_fill	sets the given address to either "empty" or "full"
	154 qt_thread_readff	waits for the source to be full, then copies it
	155 qt_thread_readff	waits for the source to be full, then copies it
	156 qt_thread_waitff	waits for the dest to be empty, then fills it
	157 qt_thread_waitff_const	waits for the dest to be empty, then fills it
	158 qt_thread_waitff	fills an address with data
Queue	159 qt_thread_waitff_const	fills an address with data
	160 qt_thread_syncvar_fill	sets the given syncvar to either "empty" or "full"
	161 qt_thread_syncvar_fill	sets the given syncvar to either "empty" or "full"
	162 qt_thread_syncvar_readff	waits for the syncvar to be full, then copies its data and empties
	163 qt_thread_syncvar_readff	waits for the syncvar to be full, then copies its data
	164 qt_thread_syncvar_status	returns the full/empty status of a syncvar
	165 qt_thread_syncvar_waitff	waits for the dest syncvar to be empty, then fills it
	166 qt_thread_syncvar_waitff_const	waits for the dest syncvar to be empty, then fills it
	167 qt_thread_syncvar_waitff	fills a syncvar with data
	168 qt_thread_syncvar_waitff_const	fills a syncvar with data
Queue	169 qt_thread_feb_barrier_create	manipulates FEB-based barriers
	170 qt_thread_feb_barrier_destroy	manipulates FEB-based barriers
	171 qt_thread_feb_barrier_grow	manipulates FEB-based barriers
	172 qt_thread_feb_barrier_shrink	manipulates FEB-based barriers
	173 qt_thread_feb_status	manipulates FEB-based barriers
	174 qt_thread_lock	lock or unlock an address
	175 qt_thread_unlock	lock or unlock an address
	176 qt_thread_cas	atomically compare-and-swap a value
	177 qt_thread_cas_ptr	atomically compare-and-swap a value
	178 qt_thread_empty	sets the given address to either "empty" or "full"
Queue	179 qt_thread_queue_create	allocate and/or initialize a synchronization queue
	180 qt_thread_queue_destroy	deallocate a synchronization queue
	181 qt_thread_queue_join	enter a queue and block until the queue is released
	182 qt_thread_queue_length	return the length of the queue
Queue	183 qt_thread_queue_release	activate the tasks in the queue for scheduling and execution
	184 qt_thread_queue_release_one	activate the tasks in the queue for scheduling and execution



Qthreads Usage

- Supported on most platforms
- One sub release per year (v1.18 latest)
- 10 papers published
- GitHub Repo [1]: 146 Stars, 30 clones pM, 100 views pM
- Package includes man pages, unit tests, examples and benchmarks,
- Slack channel [2]

Prominent use cases:



[1] <https://github.com/Qthreads/qthreads>

[2] <https://join.slack.com/t/qthreads/>

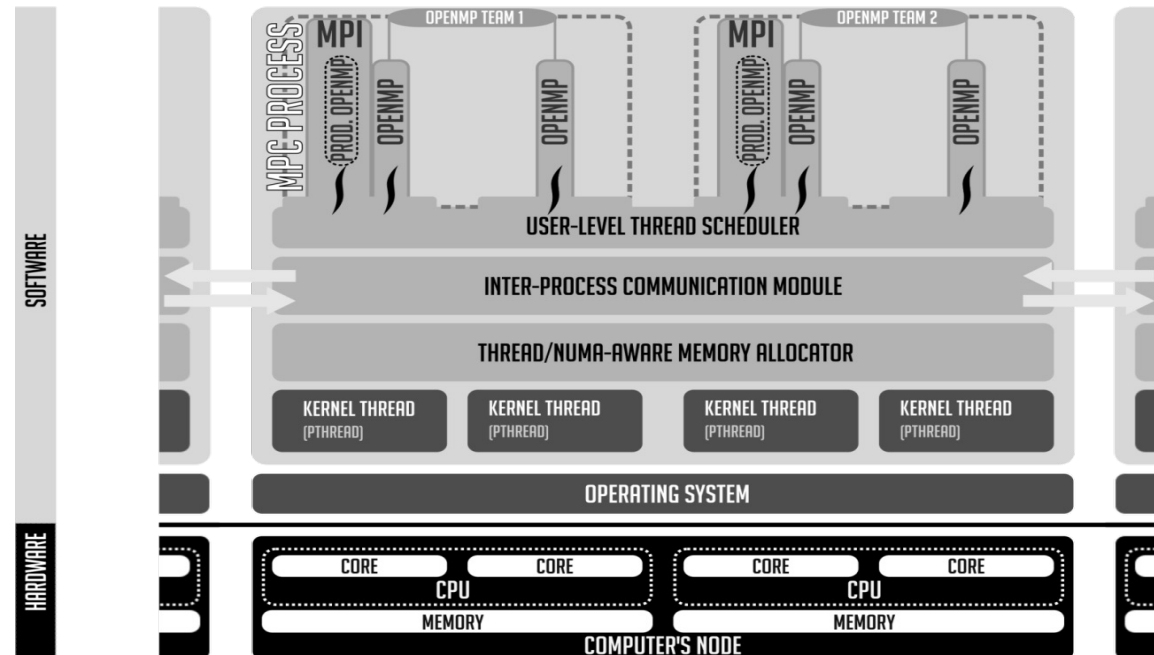


MPC Framework

- MPC (Multi Processor Computing)
 - Features **MPI** & **OpenMP** Implementation
 - Implements user-level threading scheduler and interoperability
- Task-based parallelism
 - Low overhead
 - Better interoperability
 - MPI
 - GPU
 - Scheduling flexibility



Multi-Processor Computing





Code Example: LULESH

- MPI+OpenMP Implementation
 - MPI Encapsulated within OpenMP Tasks
 - CPU $\leftrightarrow$ GPU Transfers through “target data update”
- Cooperative Communication Progression
 - Task switching until communication is completed
 - Avoid busy waiting in tasks

```
1 # pragma omp task depend(inout: x)
2 {
3     /* some work that may write x */
4     MPI_Isend(x, ..., req);
5     /* some work independent from x */
6     MPI_Wait(req);
7     /* some work that may write x */
8 }
9
10 # pragma omp task
11 { /* some independent work */ }
```

```
/* Internal MPI request progression */
int MPIX_Progress(MPI_Request * request)
{
    int completed;
    MPI_Test(request, &completed);
    if (completed)
    {
        omp_fulfill_event(request->omp_event);
    }
}

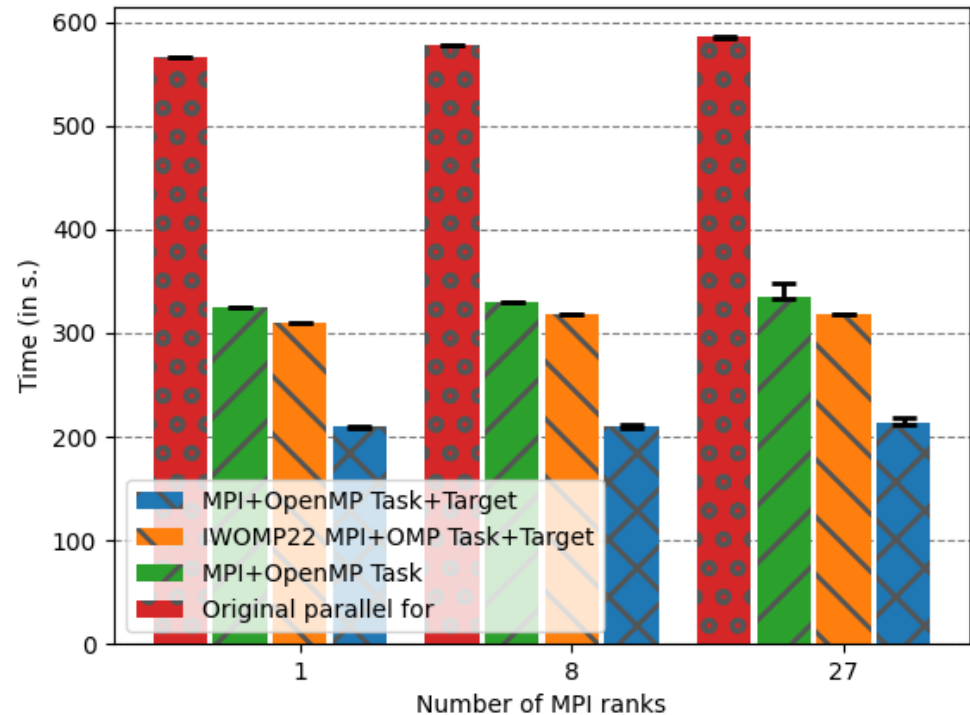
int MPI_Wait(MPI_Request * request, MPI_Status * status)
{
    if (omp_in_explicit_task())
    {
        /* notifies OMP that we are within a send-task */
        omp_in_send_task();

        /* block current task until the event is fulfilled */
        omp_task_block(request->omp_event);
    }
    else
    {
        /* Standard MPI_Wait implementation */
        [...]
    }
}
```



LULESH Performance Evaluation

- Problem size
 - 264^3 elements
 - 80% of the NUMA domain memory capacity
 - 20% of the GPU memory capacity
 - 128 iterations
- Software environment
 - MPC-OpenMP with LLVM 16.x for GPU offloading + OpenMPI 4.0.5
- Placement
 - 16 cores + 1 GPU per MPI rank
- Weak scaling
 - Median runtime of 10 runs
 - Each version scale very well
 - OpenMP tasks version significantly improves performances due to cache reuse
 - Significant performance gain with GPU



ranks	Median time (in s.)			
	parallel-for	no offloading	IWOMP22	offloading
1	565.84	325.02	309.14	209.31
8	572.45	331.09	317.91	209.43
27	581.26	333.98	318.83	212.78