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Schwarz-based Domain Decomposition Solutions for Data-Driven and Physics-Informed Models

SIAM UQ 2024

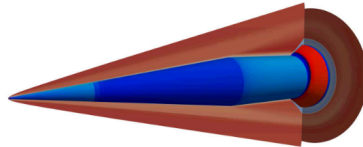
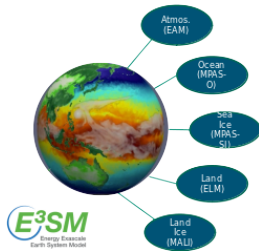
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Joshua Barnett, Irina Tezaur

February 28, 2024

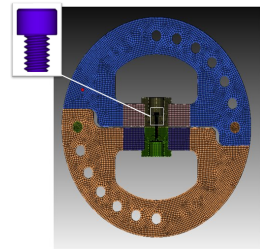
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Multiscale, multiphysics systems

- Practical physical system solvers composed from subsystem modules
 - Governing equations (fluid, solid, multi-phase, radiation)
 - Mesh type, refinement (quad/hex, tri/tet, geodesic)
 - Time integrators, time step (implicit, explicit, IMEX)
- Coupling is labor-intensive, often reliant on empirical models



Blonigan *et al.*, 2022



Murugesen *et al.*, 2020



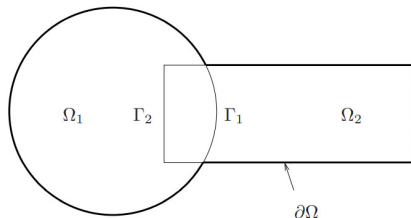
Overview

- The Schwarz alternating method
- Projection-based reduced-order models
- 2D shallow water equations – Gaussian pulse
 - Additive Schwarz parallelism
 - “Non-overlapping” finite-volume Schwarz
 - Hyper-reduction with domain decomposition
- Conclusions and outlook

The Schwarz alternating method^{1,2}

■ Monolithic (non-linear) ODE

$$\frac{d\mathbf{q}}{dt} = \mathbf{f}(\mathbf{q}, t, \boldsymbol{\mu}) \quad \text{in } \Omega, \quad \mathbf{q} \in \mathbb{R}^N$$



■ Decompose solution on **overlapping** Ω_1, Ω_2

$$\left\{ \begin{array}{ll} \frac{d\mathbf{q}_1^{k+1}}{dt} = \mathbf{f}(\mathbf{q}_1^{k+1}, t, \boldsymbol{\mu}_1) & \text{in } \Omega_1 \\ \mathbf{q}_1^{k+1} = \mathbf{f}_b(\mathbf{q}_1^{k+1}) & \text{on } \partial\Omega_1 \setminus \Gamma_1 \\ \mathbf{q}_1^{k+1} = \mathbf{q}_2^k & \text{on } \Gamma_1 \end{array} \right. \quad \left\{ \begin{array}{ll} \frac{d\mathbf{q}_2^{k+1}}{dt} = \mathbf{f}(\mathbf{q}_2^{k+1}, t, \boldsymbol{\mu}_2) & \text{in } \Omega_2 \\ \mathbf{q}_2^{k+1} = \mathbf{f}_b(\mathbf{q}_2^{k+1}) & \text{on } \partial\Omega_2 \setminus \Gamma_2 \\ \mathbf{q}_2^{k+1} = \mathbf{q}_1^{k+1} & \text{on } \Gamma_2 \end{array} \right.$$

¹Schwarz, H.A., *Vierteljahrsschrift der Naturforschenden Gesellschaft in Zürich*, Vol. 15, 1870.

²Gander, *Electron. Trans. Numer. Anal.*, Vol. 31, 2008.



Additive Schwarz

- Multiplicative Schwarz is strictly **serial**
- Additive: advance independently, communicate afterward

$$\begin{aligned}\frac{d\mathbf{q}_i^{k+1}}{dt} &= \mathbf{f}\left(\mathbf{q}_i^{k+1}, t, \boldsymbol{\mu}_i\right) && \text{in } \Omega_i \\ \mathbf{q}_i^{k+1} &= \mathbf{f}_b\left(\mathbf{q}_i^{k+1}\right) && \text{on } \partial\Omega_i \setminus \Gamma_i \\ \mathbf{q}_i^{k+1} &= \mathbf{q}_j^k && \text{on } \Gamma_i\end{aligned}$$

- Empirically observed to slow convergence, no loss of accuracy

All results in this presentation use the **additive** Schwarz algorithm.
Parallelism helps balance additional cost due to Schwarz iterations.

Non-overlapping Schwarz

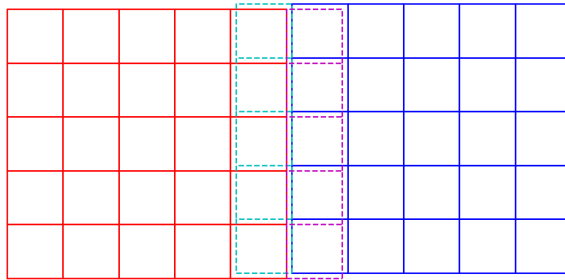
- Overlapping interfaces are uncommon in the physical world
 - Mechanical assemblies, multi-physics systems
- Non-overlapping Dirichlet–Dirichlet condition has no convergence guarantees
- **Dirichlet–Neumann** conditions resolve this issue

$$\left\{ \begin{array}{ll} \frac{d\mathbf{q}_1^{k+1}}{dt} = \mathbf{f}(\mathbf{q}_1^{k+1}, t, \boldsymbol{\mu}_1) & \text{in } \Omega_1 \\ \mathbf{q}_1^{k+1} = \mathbf{f}_b(\mathbf{q}_1^{k+1}) & \text{on } \partial\Omega_1 \setminus \Gamma_1 \\ \mathbf{q}_1^{k+1} = \mathbf{q}_2^k & \text{on } \Gamma_1 \end{array} \right. \quad \left\{ \begin{array}{ll} \frac{d\mathbf{q}_2^{k+1}}{dt} = \mathbf{f}(\mathbf{q}_2^{k+1}, t, \boldsymbol{\mu}_2) & \text{in } \Omega_2 \\ \mathbf{q}_2^{k+1} = \mathbf{f}_b(\mathbf{q}_2^{k+1}) & \text{on } \partial\Omega_2 \setminus \Gamma_2 \\ \frac{\partial \mathbf{q}_2^{k+1}}{\partial \mathbf{n}} = \frac{\partial \mathbf{q}_1^{k+1}}{\partial \mathbf{n}} & \text{on } \Gamma_2 \end{array} \right.$$

- Robin–Robin also converges, but rare in production codes

A note on finite volume methods

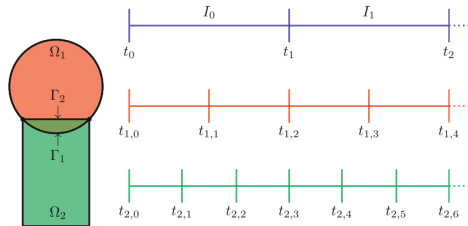
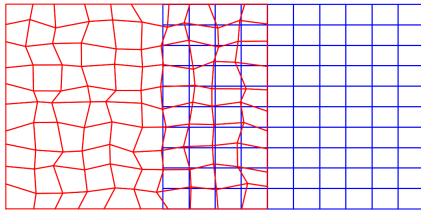
- Today's results use **cell-centered** FVM with **ghost cell** boundary conditions
 - BCs are enforced **approximately** by fictitious ghost cell state
- Can't apply Dirichlet–Neumann or Robin–Robin without significant effort
- Some literature suggests Dirichlet–Dirichlet works for hyperbolic problems³
- **Not truly non-overlapping**, but non-physical cells suggest interesting possibilities



³Dolean et al., *SIAM J Sci Comput*, 2009

Not covered in this talk

- Non-conformal meshes
 - Interpolation/projection of transmission condition⁴
- Non-uniform time steps
 - “Controller” time-step concept⁵
- Physics-informed neural network (PINN) coupling⁶
 - Didn't work as well as we hoped



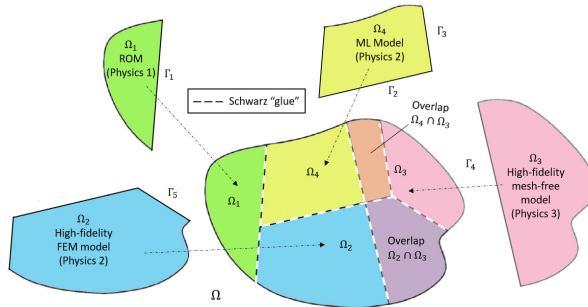
⁴ Mota et al., *arXiv:2311.05643*, 2023

⁵ Mota et al., *Int J Numer Meth Eng*, Vol. 123, 2022

⁶ Snyder et al., *CSRI Summer Proceedings*, 2023

Data-driven methods

- Accelerate workflows for **many-query problems**
- Coupling traditional numerical methods with
 - Projection-based ROMs (PROMs)
 - Operator inference ROMs
 - Neural network surrogates
- Schwarz lends to “plug-and-play” architectures



Projection-based reduced-order models (PROMs)

- Recall governing (non-linear) ODE

$$\frac{d\mathbf{q}}{dt} = \mathbf{f}(\mathbf{q}, t, \boldsymbol{\mu}), \quad \mathbf{q} \in \mathbb{R}^N$$

- Low-dimensional affine representation ($K \ll N$)

$$\mathbf{q}(t) \approx \tilde{\mathbf{q}}(t) = \bar{\mathbf{q}} + \boldsymbol{\Phi} \hat{\mathbf{q}}(t)$$

$$\hat{\mathbf{q}} \in \mathbb{R}^K, \quad \boldsymbol{\Phi} \in \mathbb{R}^{N \times K}$$

- The proper orthogonal decomposition

$$\boldsymbol{\Phi} = \underset{\mathbf{A} \in \mathbb{R}^{N \times K}}{\operatorname{argmin}} \left\| \mathbf{Q} - \mathbf{A} \mathbf{A}^\top \mathbf{Q} \right\|_2^2$$

$$\mathbf{Q} = \mathbf{U} \boldsymbol{\Sigma} \mathbf{V}^\top, \quad \boldsymbol{\Phi} \leftarrow \mathbf{U}[:, :K]$$



Least-squares Petrov–Galerkin⁷

- No dimension reduction yet, project by test basis $\Psi \in \mathbb{R}^{N \times K}$ and rearrange

$$\frac{d\hat{\mathbf{q}}}{dt} = \left[\Psi^\top \Phi \right]^{-1} \Psi^\top \mathbf{f}(\bar{\mathbf{q}} + \Phi \hat{\mathbf{q}})$$

- For fully-discrete residual (e.g. BDF1)

$$\mathbf{r}(\hat{\mathbf{q}}^n) = \Phi(\hat{\mathbf{q}}^n - \hat{\mathbf{q}}^{n-1}) - \Delta t \mathbf{f}(\bar{\mathbf{q}} + \Phi \hat{\mathbf{q}}^n) = \mathbf{0}$$

- Minimize with Gauss–Newton

$$\delta \hat{\mathbf{q}}^n = \underset{\mathbf{y} \in \mathbb{R}^K}{\operatorname{argmin}} \left\| \frac{\partial \mathbf{r}(\mathbf{y})}{\partial \mathbf{y}} \mathbf{y} + \mathbf{r}(\mathbf{y}) \right\|_2^2$$

- Equivalent to Petrov–Galerkin projection with test basis

$$\Psi = \frac{\partial \mathbf{r}(\hat{\mathbf{q}})}{\partial \mathbf{q}} \Phi$$

⁷ Carlberg et al., *Int J Numer Meth Eng*, Vol. 86, 2011.

Hyper-reduction

- Non-linear residual still scales with full dimension N
- Collocation: minimize residual at **small subset** of DOFs, $N_s \ll N$

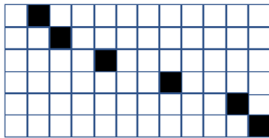
$$\hat{\mathbf{q}}^n = \underset{\mathbf{y} \in \mathbb{R}^K}{\operatorname{argmin}} \|\mathbf{S} \mathbf{r}(\mathbf{y})\|_2^2$$

$\mathbf{S} \mathbf{r}(\mathbf{y})$

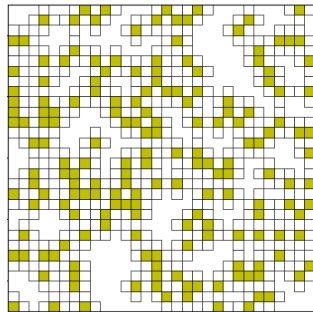


=

$\mathbf{S}$



$\mathbf{r}(\mathbf{y})$



Yellow: residual cells, White: stencil cells



Open-source software

- Projection-based ROM interface provided by **pressio**

<https://github.com/Pressio/pressio>

- Experiments run with **pressio-demoapps**

<https://github.com/Pressio/pressio-demoapps>

- Schwarz coupling for **pressio-demoapps**

<https://github.com/cwentland0/pressio-demoapps-schwarz>



Rizzi, F. *et al.*, “Pressio: Enabling Projection-based Model Reduction for Large-scale Nonlinear Dynamical Systems,” arXiv:2003.07798v3, 2021.

2D shallow water equations: Gaussian pulse

$$\frac{\partial h}{\partial t} + \frac{\partial(hu)}{\partial x} + \frac{\partial(hv)}{\partial y} = 0$$

$$\frac{\partial(hu)}{\partial t} + \frac{\partial}{\partial x} \left(hu^2 + \frac{1}{2}gh^2 \right) + \frac{\partial}{\partial y} (huv) = -\mu v$$

$$\frac{\partial(hv)}{\partial t} + \frac{\partial}{\partial x} (huv) + \frac{\partial}{\partial y} \left(hv^2 + \frac{1}{2}gh^2 \right) = \mu u$$

- Uniform 300×300 Cartesian grid
- First-order in space and time
- Vary “Coriolis” parameter μ
 - $\mu_{\text{train}} \in [-4.0, -3.0, -2.0, -1.0, 0.0]$
 - $\mu_{\text{test}} \in [-3.5, -2.5, -1.5, -0.5]$
- $T = 10.0, \Delta t = 0.01$

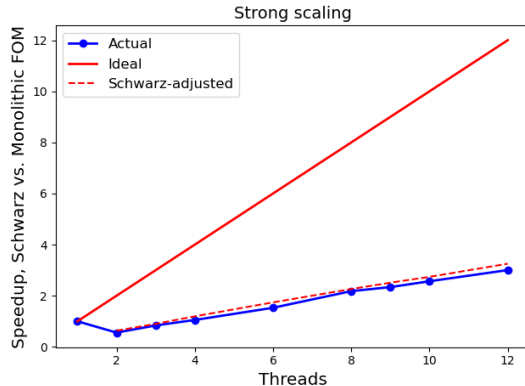


2D SWE: Parallelism

- Straightforward OpenMP parallelism, one thread per subdomain
- Schwarz iterations incur significant costs ($n_t \approx 3.5$ iterations on average here)
- Adjusting ideal scaling by Schwarz iterations shows parallelism works as intended

$$\text{Adjusted} = \frac{\# \text{ threads}}{\frac{1}{N_t} \sum_{i=1}^{N_t} n_{t,i}}$$

$n_t := \# \text{ Schwarz iterations}$





2D SWE: PROMs

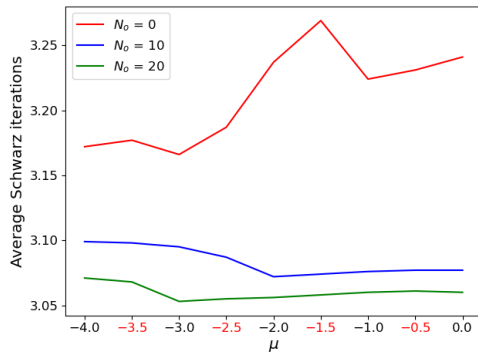
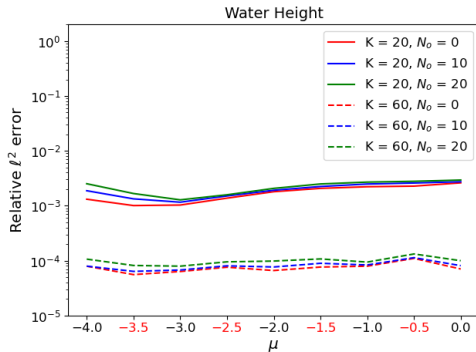
- $N_o :=$ cell width of overlap region (not including ghost cells)
- “Non-overlapping” Dirichlet–Dirichlet FVM performs well, no convergence issues

$$\mu = -0.5, K = 80$$



2D SWE: PROMs, domain overlap

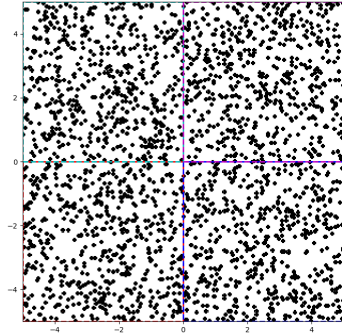
- Decreasing overlap has no effect or improves solution
 - Minimizing residual on trial space **does not guarantee matching** in overlap region
- Schwarz iterations decrease (very roughly) with $N_o^{0.25}$, but $\mathbf{r}(\mathbf{q})$ scales with N_o^2



Black μ : training set, Red μ : testing set

2D SWE: Hyper-reduced PROMs (HPROMs)

- Naive random sampling invariably results in an unstable solution
- Sparsely-sampled boundary fails to transmit strong gradients

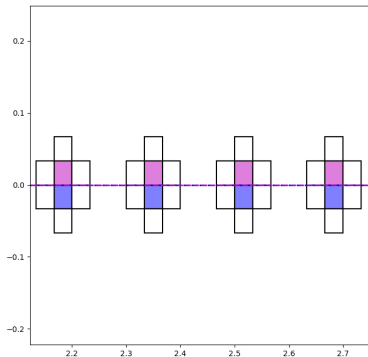


$$N_s = 2.5\% \times N$$

$$\mu = -0.5, K = 100$$

2D SWE: Hyper-reduced PROM boundary sampling

- Sample boundaries at fixed interval N_b
- For fixed budget N_s , boundary samples draw points away from interior



$N_b = 5$, boundary zoom view



2D SWE: Hyper-reduced PROM boundary sampling

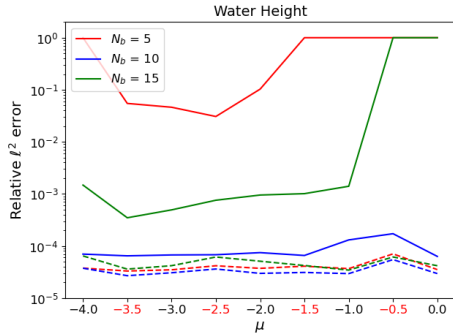
- Can often get away with $< 10\%$ boundary sampling

$$\mu = -0.5, K = 100, N_s = 0.5\% \times N$$

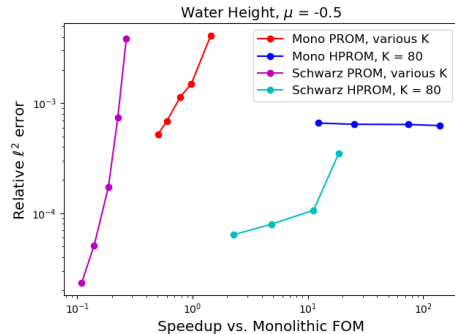


2D SWE: Hyper-reduced PROM performance

- Balancing act between capturing dynamics and boundary transmission
- Noticeable cost savings **relative to monolithic FOM**
- For fixed PROM dimension K , Schwarz delivers lower error and comparable cost



Solid: $N_s = 0.5\% \times N$, Dash: $N_s = 1.0\% \times N$



Lower-right is better



Conclusions

- Schwarz provides a flexible framework for coupling disparate models
 - Difficult to recover traditional parallel performance due to Schwarz iterations
- “Non-overlapping” Dirichlet–Dirichlet FVM treatment performs well
 - Requires extension and verification for non-conformal meshes
- Schwarz HPROMs require special attention to boundary treatment
 - Fixed-interval boundary sampling method works, but is not cost-effective
- Ongoing work
 - “Optimal” spatial decomposition
 - Online multi-fidelity modeling adaptivity
 - Extensions to production Sandia applications

Acknowledgements



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