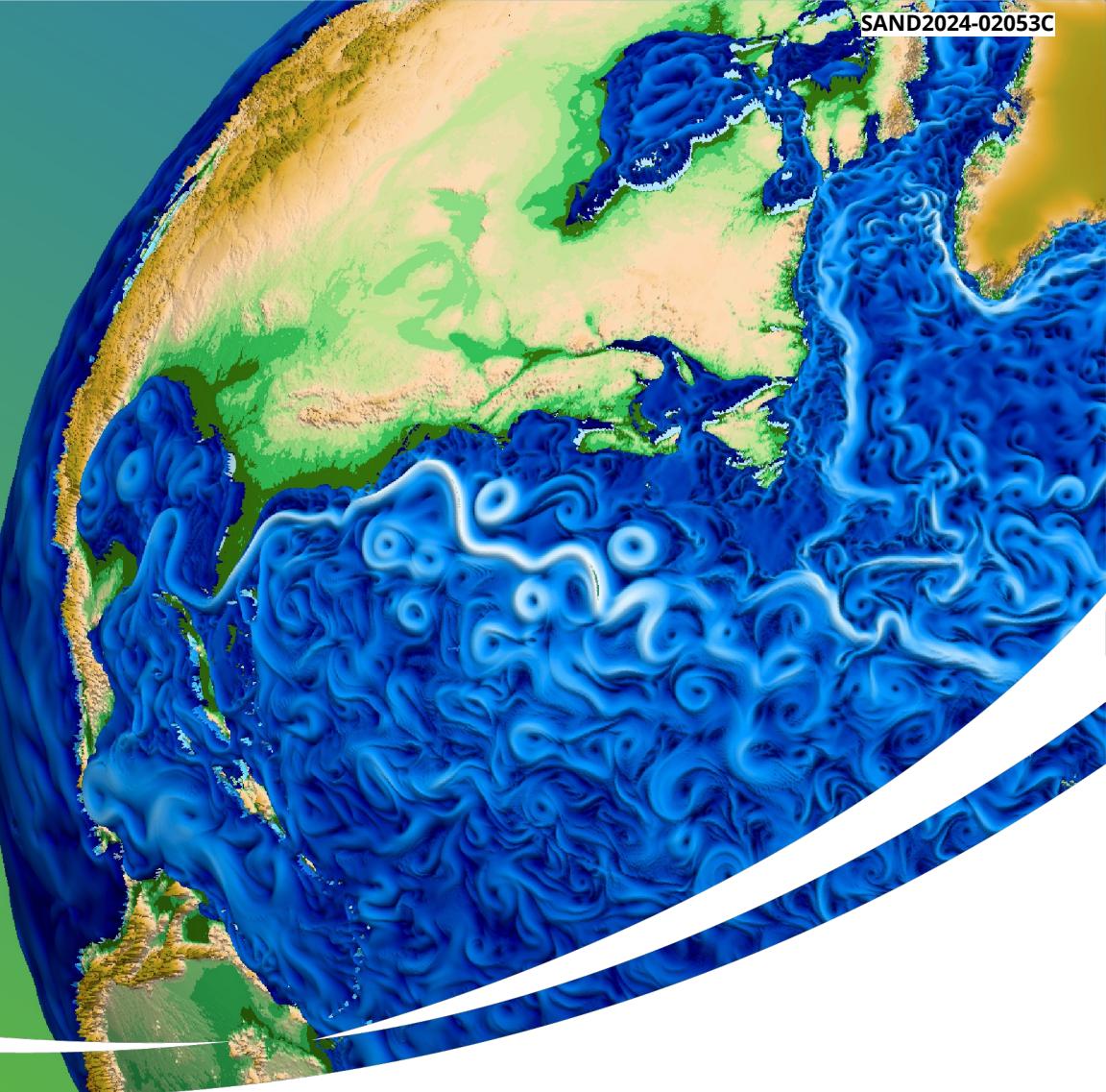


Reduced-Dimensional Neural Network Surrogate Construction for the E3SM Land Model

Khachik Sargsyan (SNL), Daniel Ricciuto (ORNL)

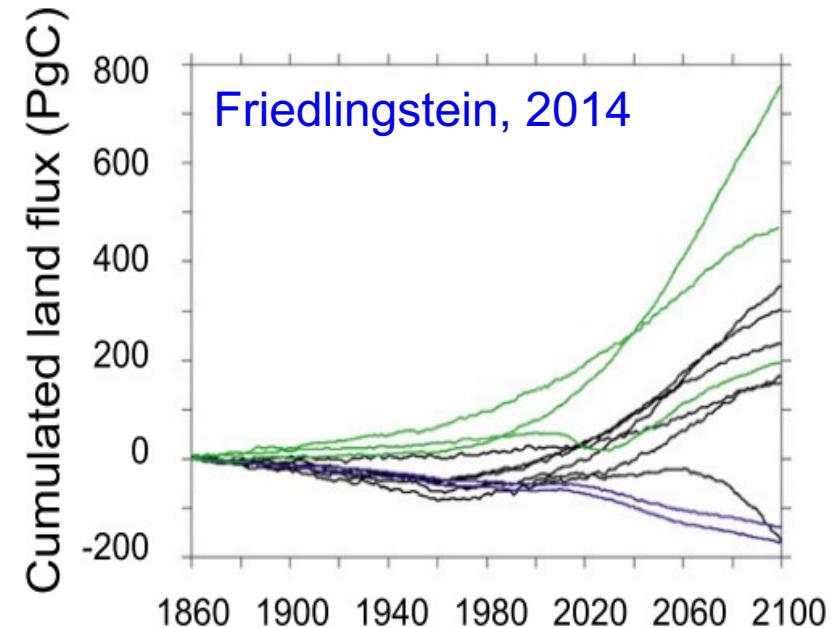


SIAM UQ
Trieste, Italy
March 1, 2024

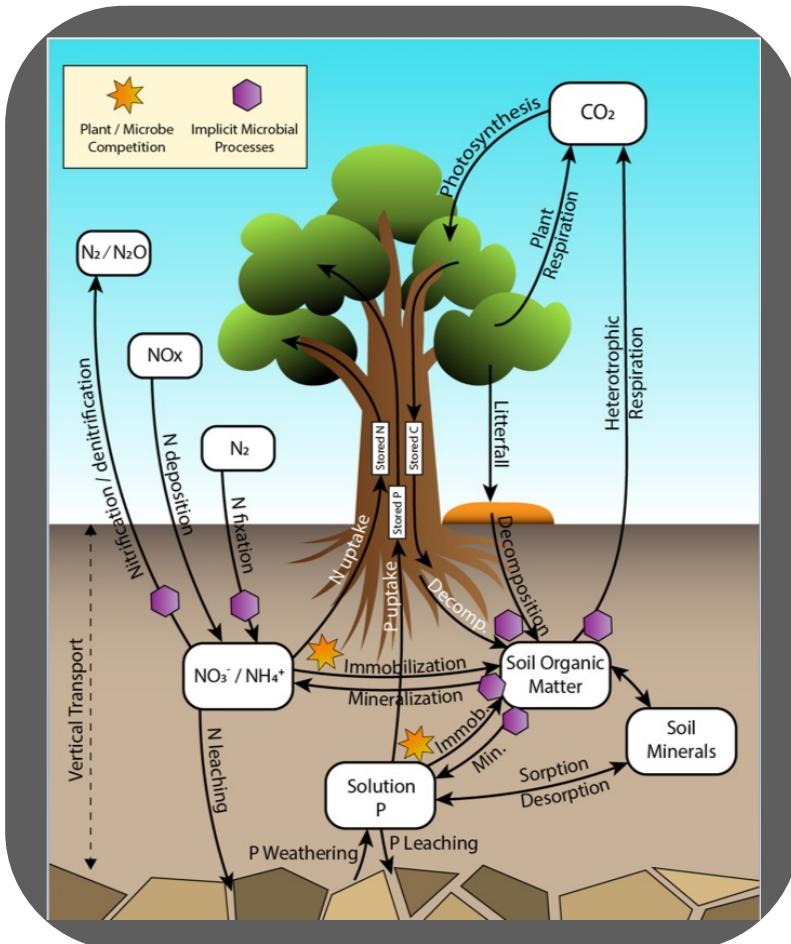


Motivation and Overview

- Land-surface model parametric uncertainty remains large
- High model expense → Need for **model surrogates** for sample-intensive studies, such as ...
 - Global sensitivity analysis (forward UQ)
 - Model calibration (inverse UQ)
- Major **challenges**
 - Expensive model evaluation, small ensembles
 - High dimensional (spatio-temporal) outputs
- Reduced-dimensional, inexpensive surrogate construction via Karhunen-Loève expansions and Neural Networks (KLNN)
- Surrogate enables global sensitivity analysis and Bayesian model calibration



E3SM Land Model (ELM): focus on carbon and energy cycle

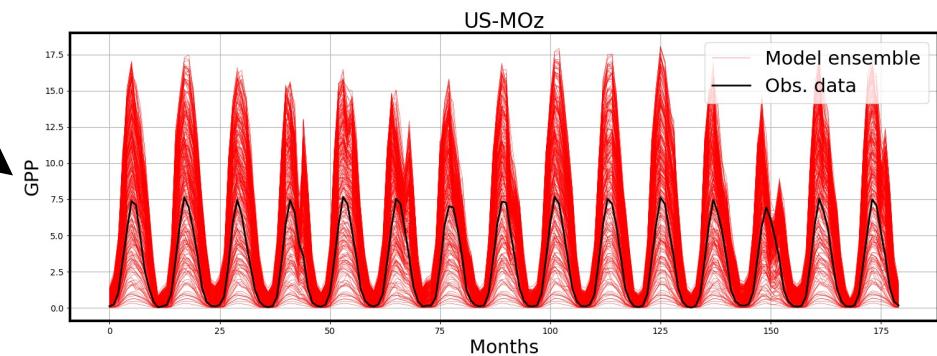
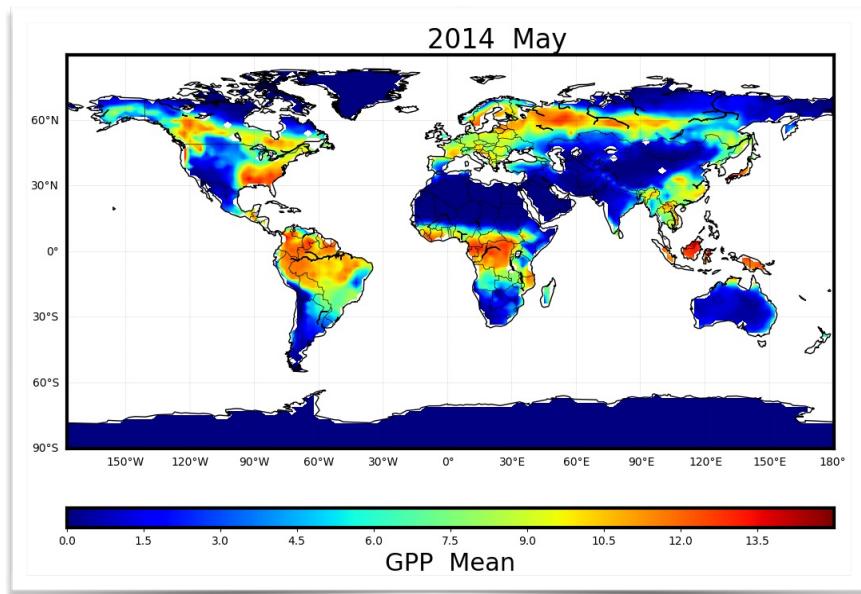


Satellite Phenology version
used for this study
(close to CLM4.5)

Quantity of Interest:
Gross primary productivity
(GPP)...

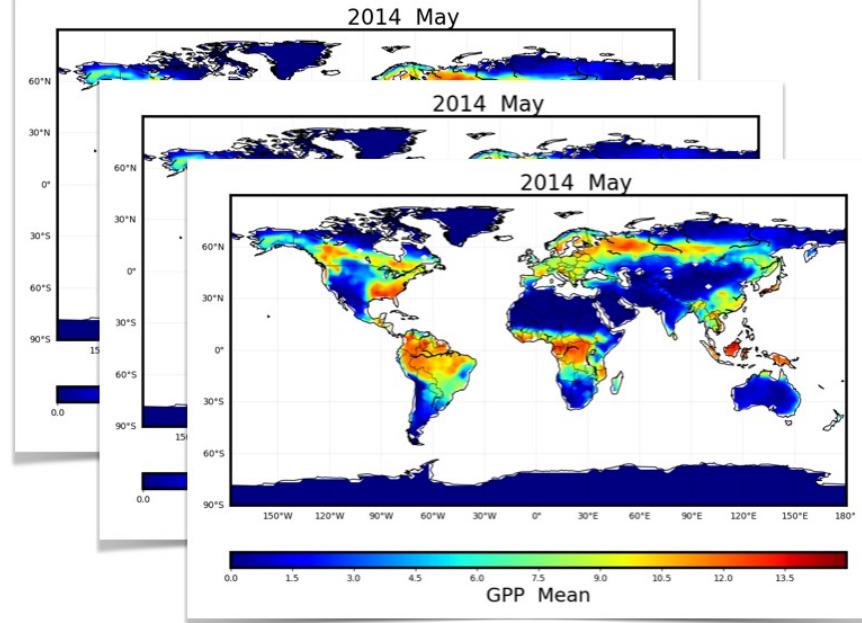
... resolved in space, ...

... and in time.



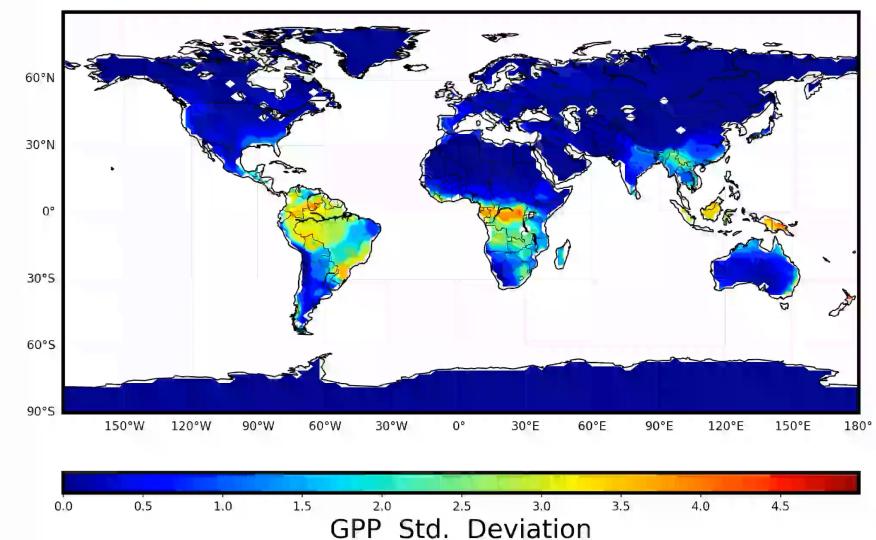
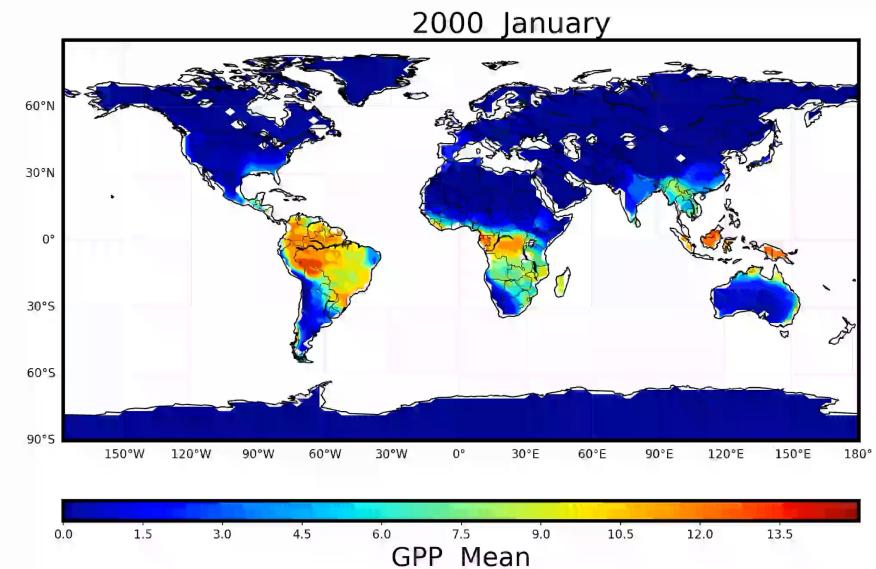
Model Ensemble (275 samples)

1.9x2.5 resolution, satellite phenology



Perturbed Parameters

Parameter	Description	Min	Max
flnr	Fraction of leaf in RuBisCO	0	0.25
mbbopt	Stomatal slope (Ball-Berry)	2	13
bbbopt	Stomatal intercept (Ball-Berry)	1000	40000
roota_par	Rooting depth distribution	1	10
vcmaxha	Activation energy for Vcmax	50000	90000
vcmaxse	Entropy for Vcmax	640	700
jmaxha	Activation energy for jmax	50000	90000
dayl_scaling	Day length factor	0	2.5
dleaf	Characteristic leaf dimension	0.01	0.1
xi	Leaf/stem orientation index	-0.6	0.8



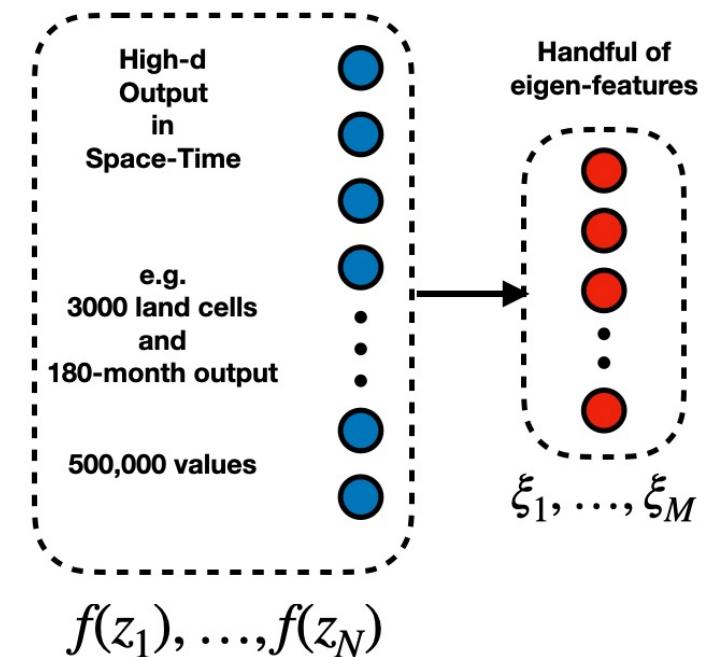
Dimensionality Reduction via Karhunen-Loève Expansion

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

f($\lambda; z$) ≈ $\bar{f}(z)$ + $\sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$

Uncertain parameters “Certain” conditions

- Spatio-temporal model output $f(\lambda; z)$, where $z = (x, y, t)$
- Output field has large dimensionally $N = N_x \times N_y \times N_t$
- Eigenpairs $(\mu_m, \phi_m(z))$ are found via eigen-solve
- Analysis reduces to $M \ll N$ eigenfeatures ξ_1, \dots, ξ_M
- Under the hood: this is essentially an SVD

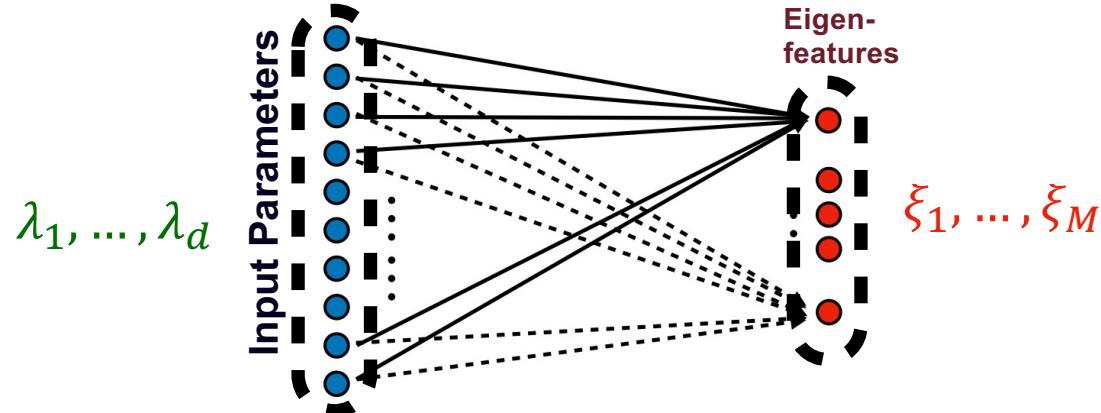


KL+PC = reduced dimensional spatio-temporal surrogate

The goal is to construct a surrogate with respect to uncertain parameters λ , such that

$$f(\lambda; z_i) \approx f_s(\lambda; z_i) \text{ for all conditions } z_i.$$

Instead of building surrogate for each individual z_i for $i = 1, \dots, N$,
we construct polynomial chaos (PC) surrogate for ξ_1, \dots, ξ_M where $M \ll N$.



$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

\uparrow

$\xi_m^{PC}(\lambda)$

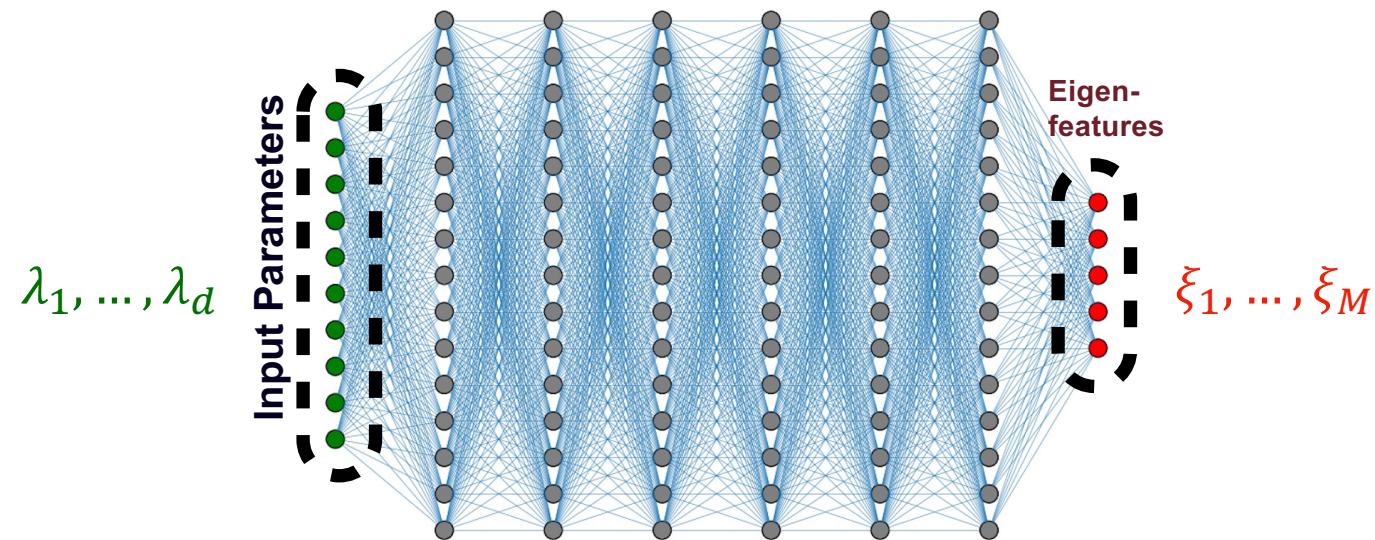


KL+NN = reduced dimensional spatio-temporal surrogate

The goal is to construct a surrogate with respect to uncertain parameters λ , such that

$$f(\lambda; z_i) \approx f_s(\lambda; z_i) \text{ for all conditions } z_i.$$

Instead of building surrogate for each individual z_i for $i = 1, \dots, N$, we construct neural network (NN) surrogate for ξ_1, \dots, ξ_M where $M \ll N$.



$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

\uparrow
 $\xi_m^{NN}(\lambda)$

PC vs NN comparison

Polynomial Chaos

Simple regression,
easy to train

GSA and variance decomposition,
More interpretable

Neural Network

More flexible,
highly customizable

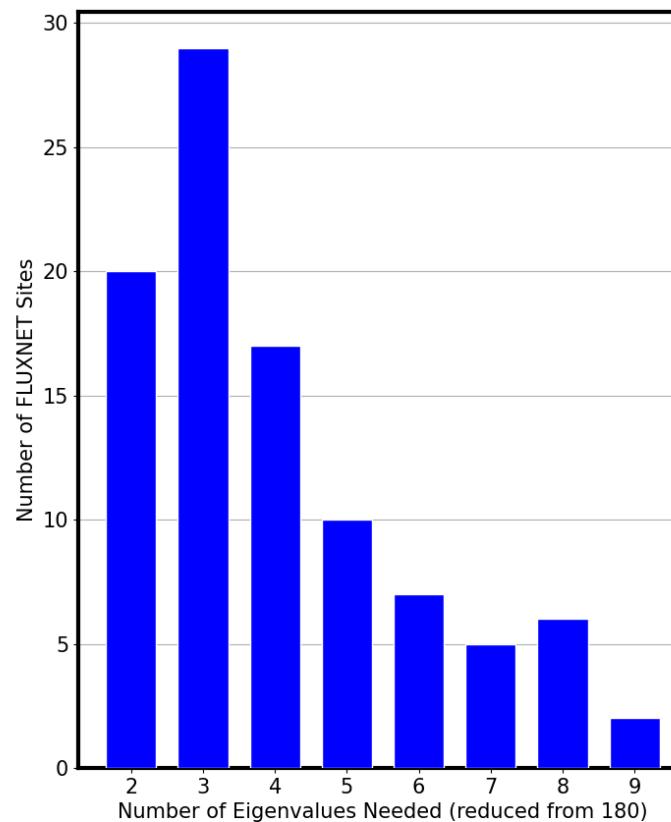
Multiple outputs at once,
More accurate (in theory)

Several case studies

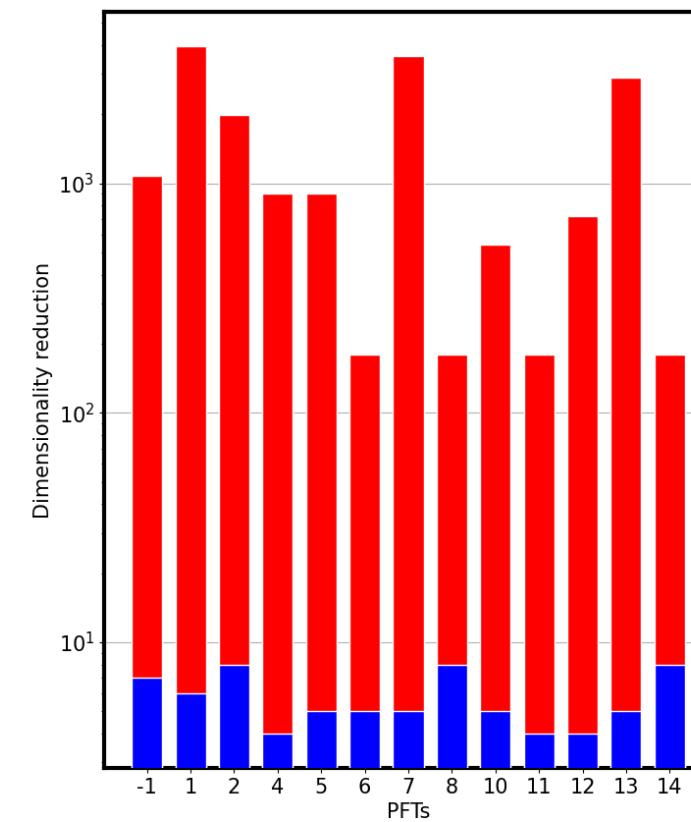
Space \ Time	$N_t = 180$ Months (full 15 years)	$N_t = 12$ Months (average out interannual)	$N_t = 4$ Seasons (average out within seasons)	$N_t = 1$ (global time-average)
FLUXNET sites $N_x = 96$ (or group by PFTs)	F180	F12	F4	F1
Global 144x96 $N_x \cong 4000$ vegetated cells (or regional zoom)	G180	G12	G4	G1

Dimensionality reduction via KL

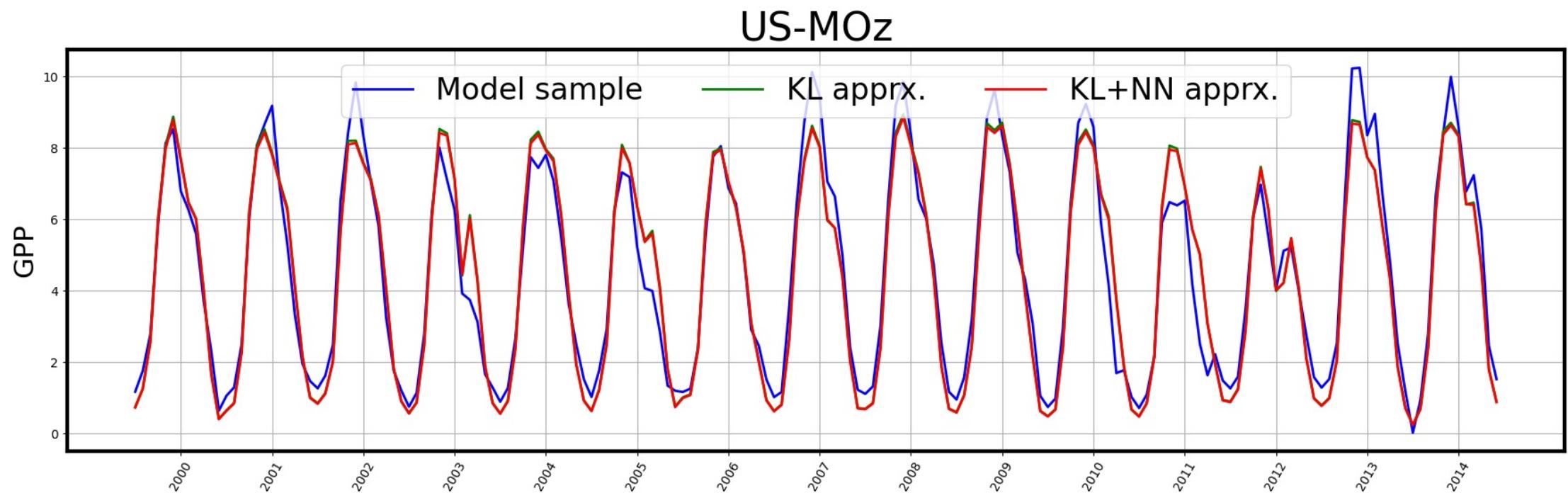
Per-site dimensionality reduction



Per-PFT dimensionality reduction

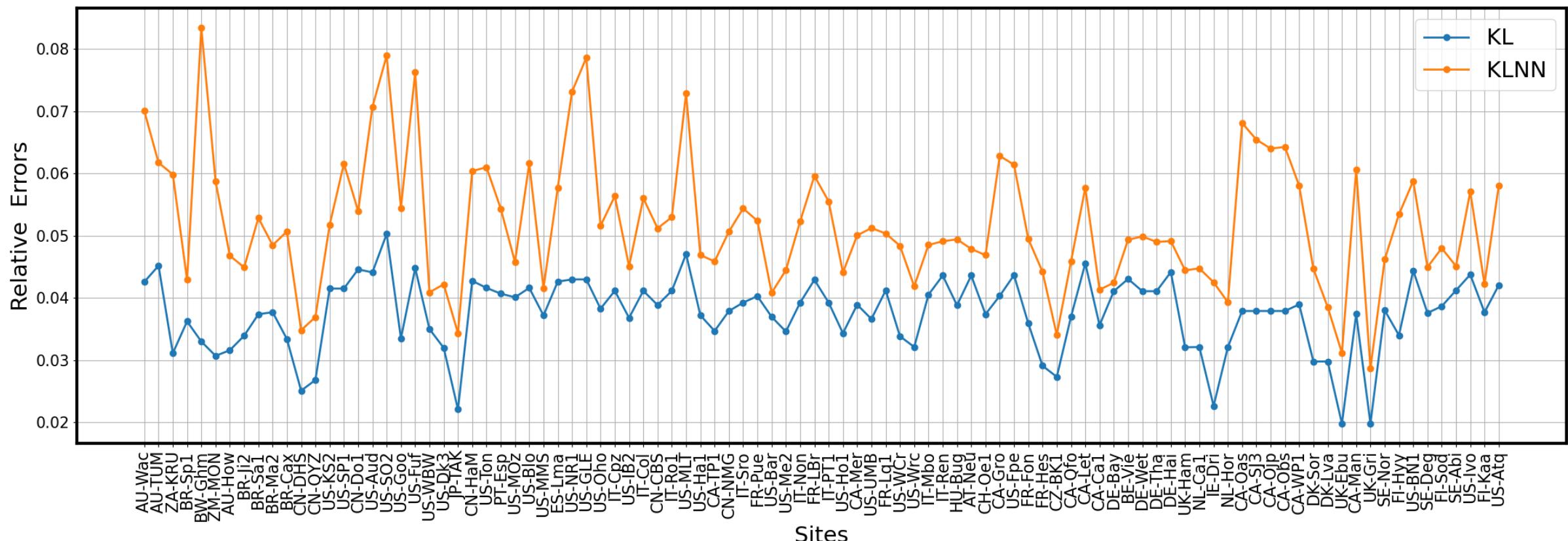


KL+NN a single training sample approximation

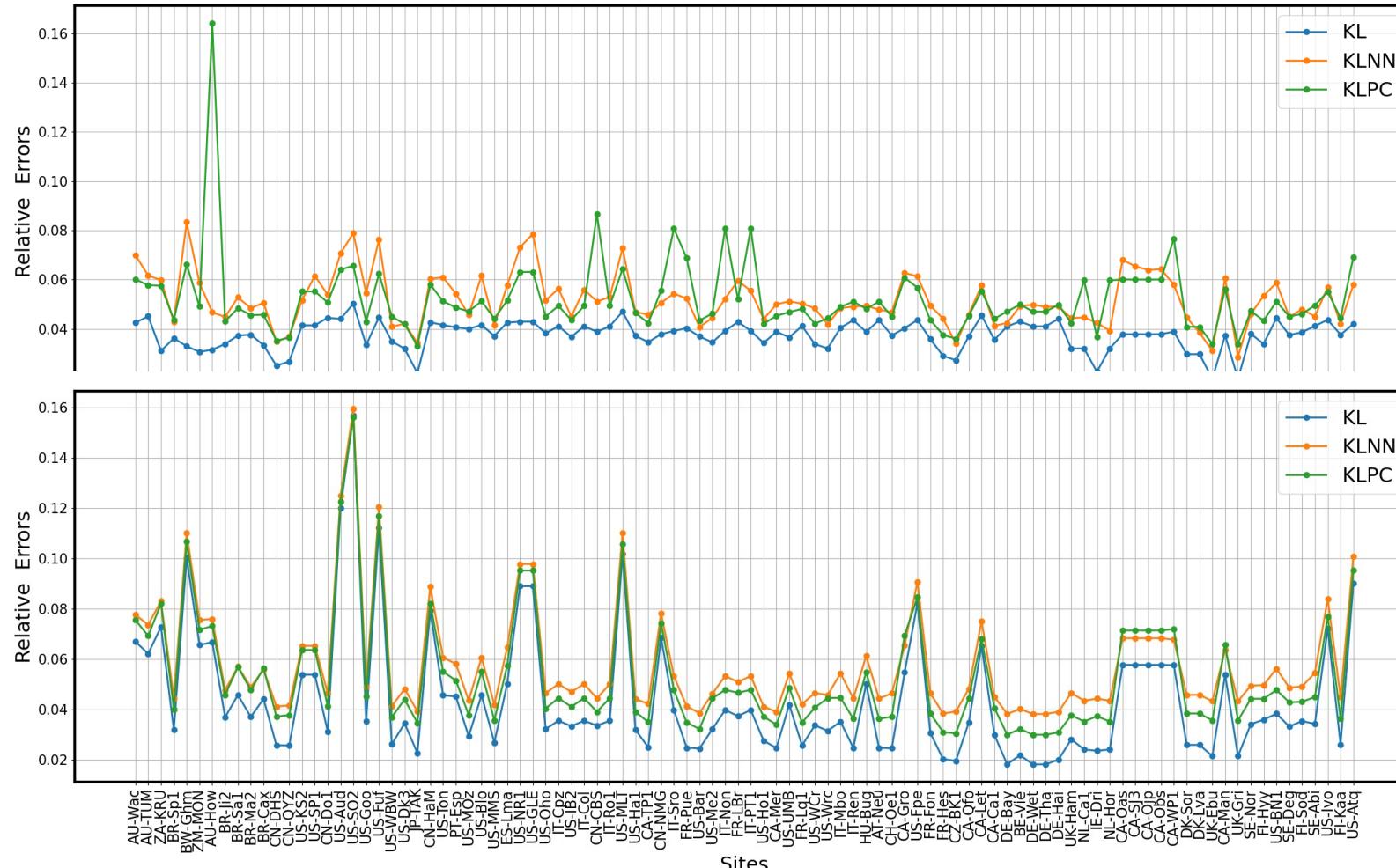


KL+NN surrogate performance

Instead of $96 \times 180 = 17280$ surrogates, we build
a single NN surrogate in the reduced, 8-dimensional latent space



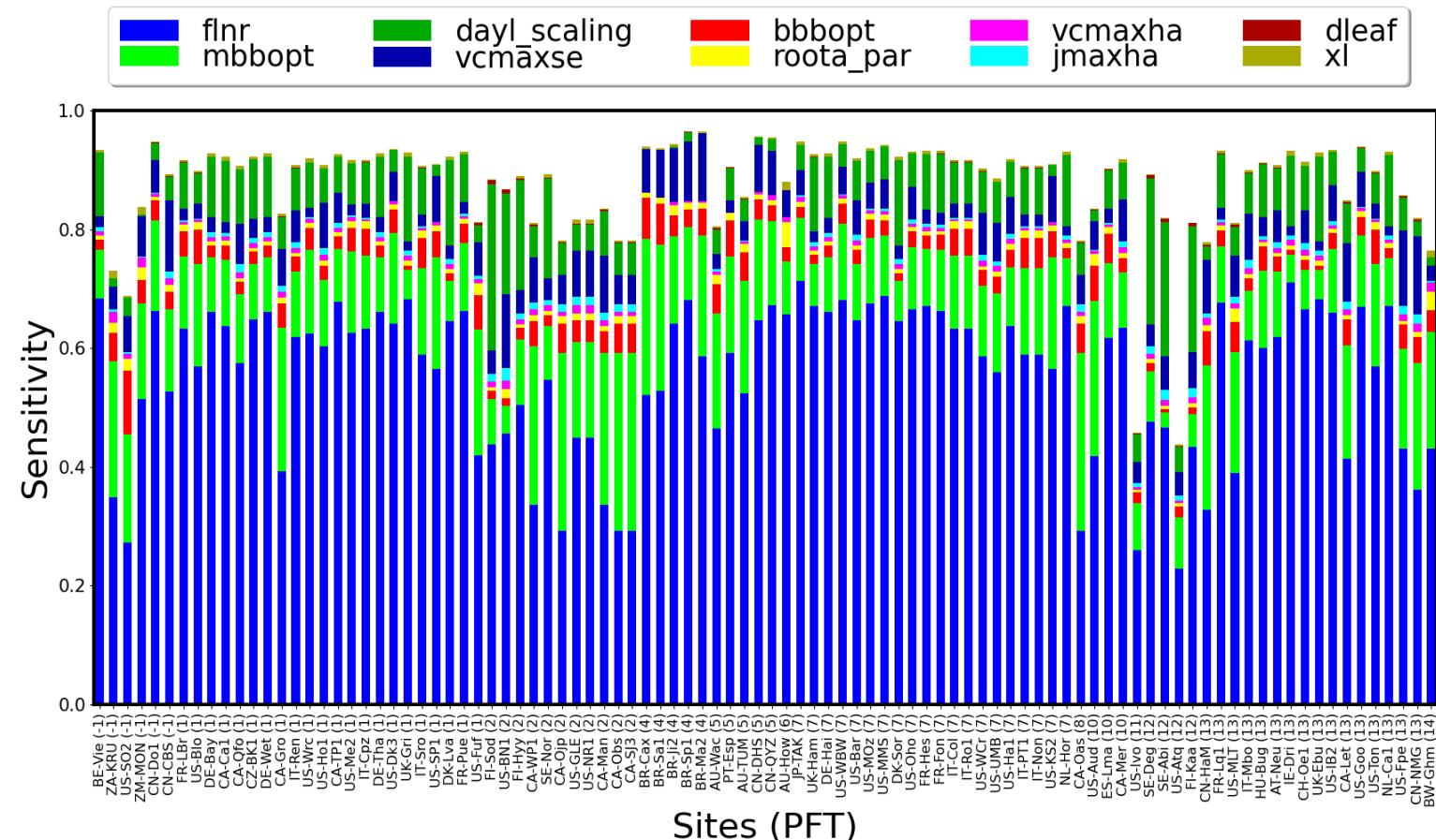
PC vs NN comparison



96 temporal surrogates
with each 180 outputs

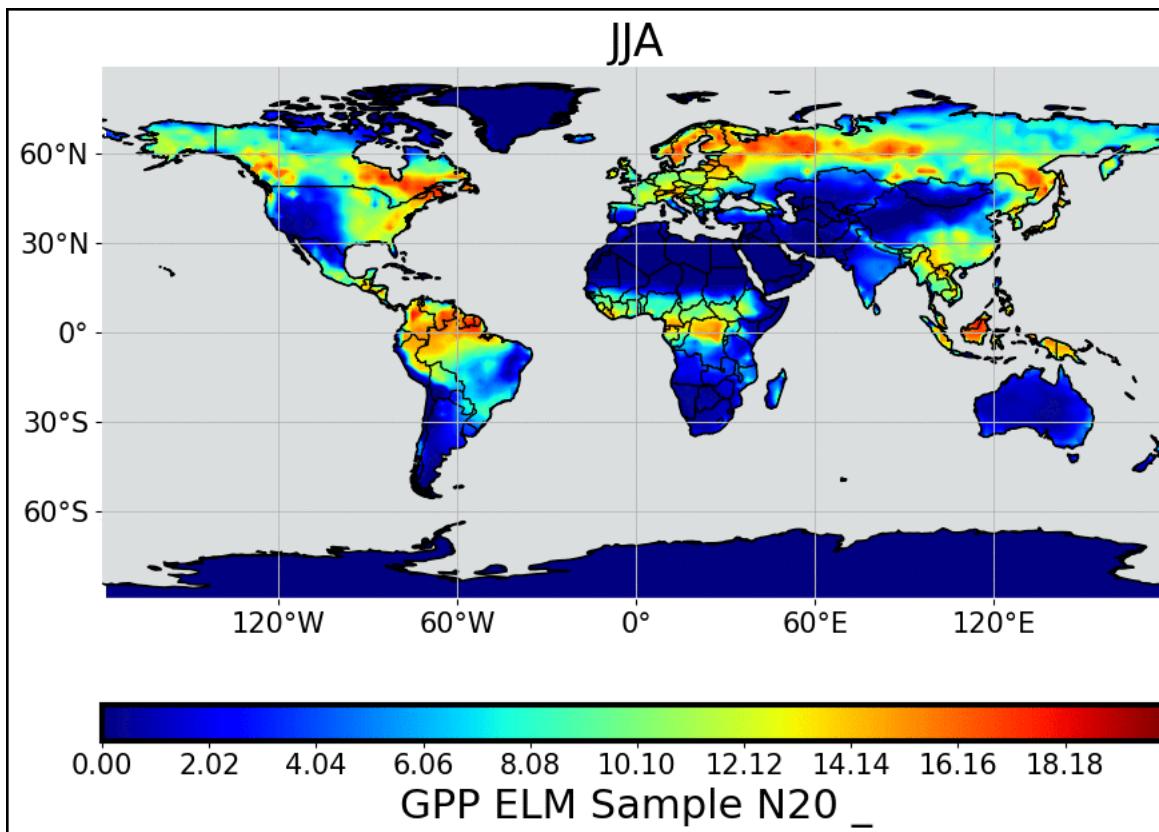
Single spatio-temporal
surrogate
with 96x180 outputs

Sensitivity at 96 FLUXNET sites: RuBisCO leaf fraction is the most impactful parameter

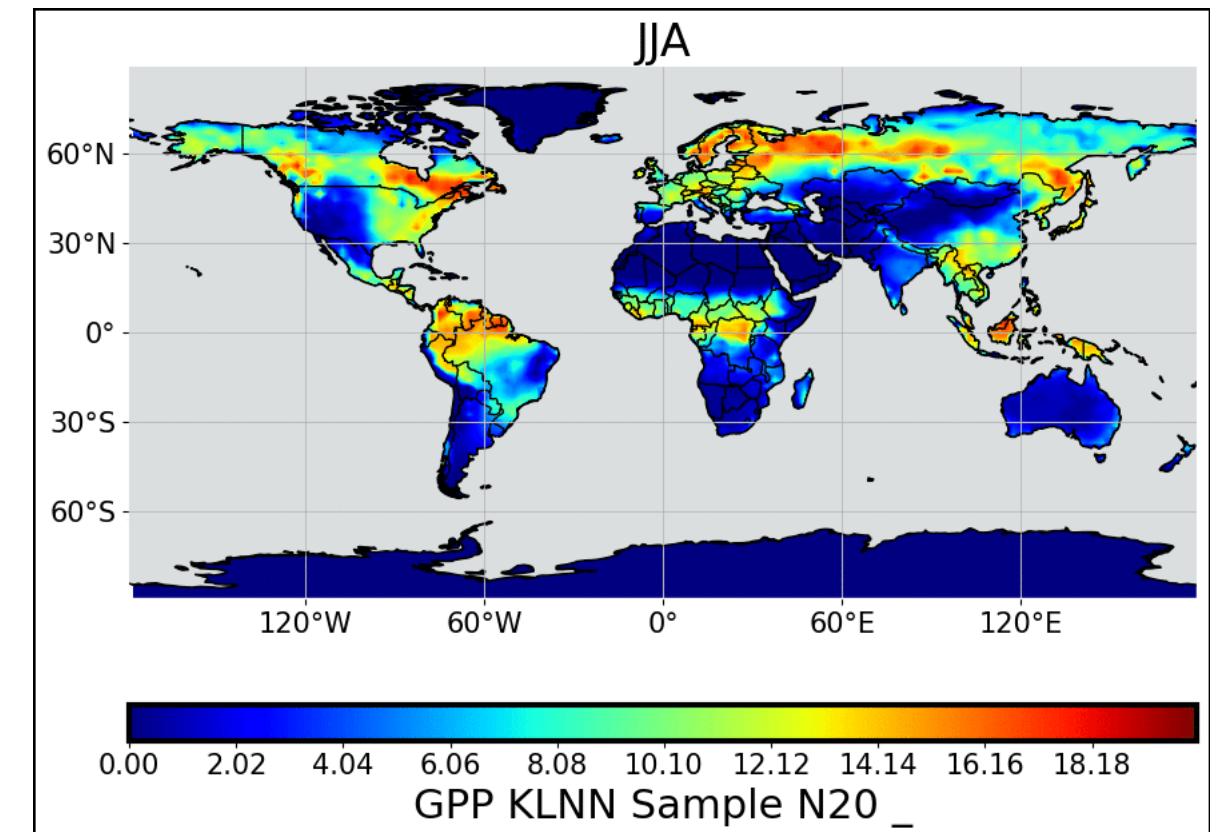


Dimensionality reduction from 4000 cells x 4 seasons = **16000** to **11-dimensional latent space**

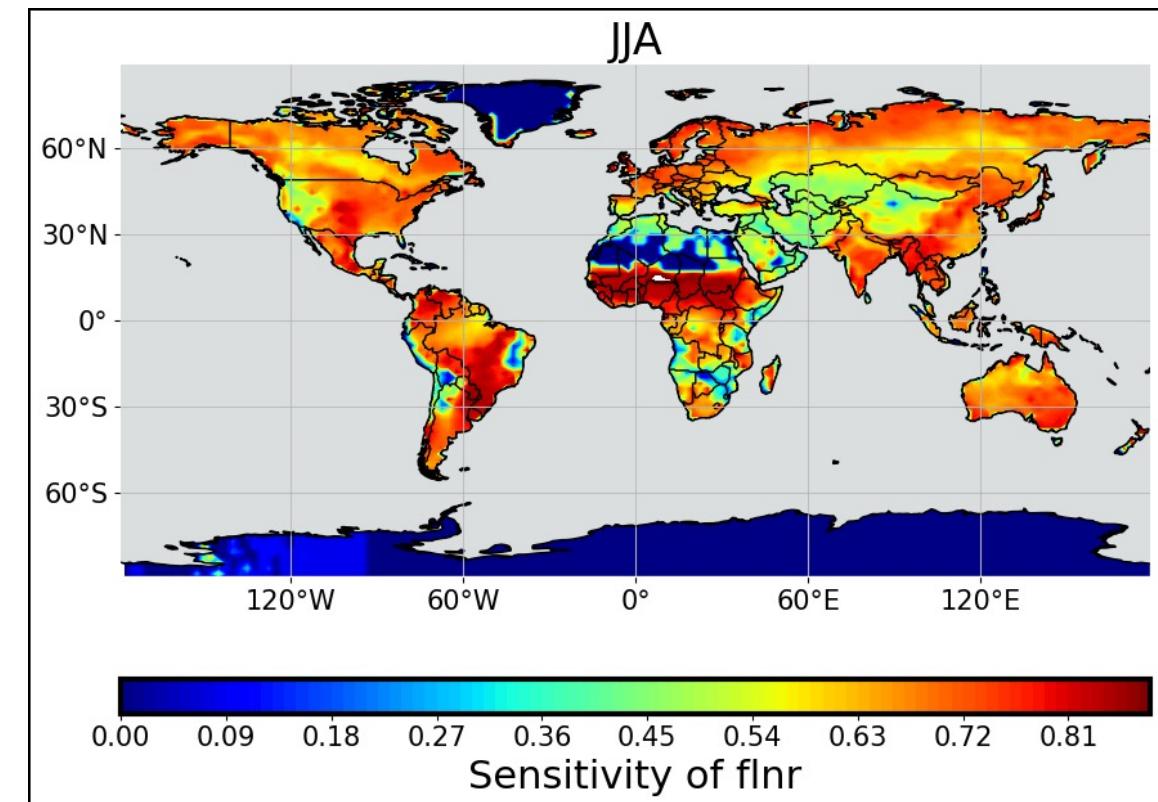
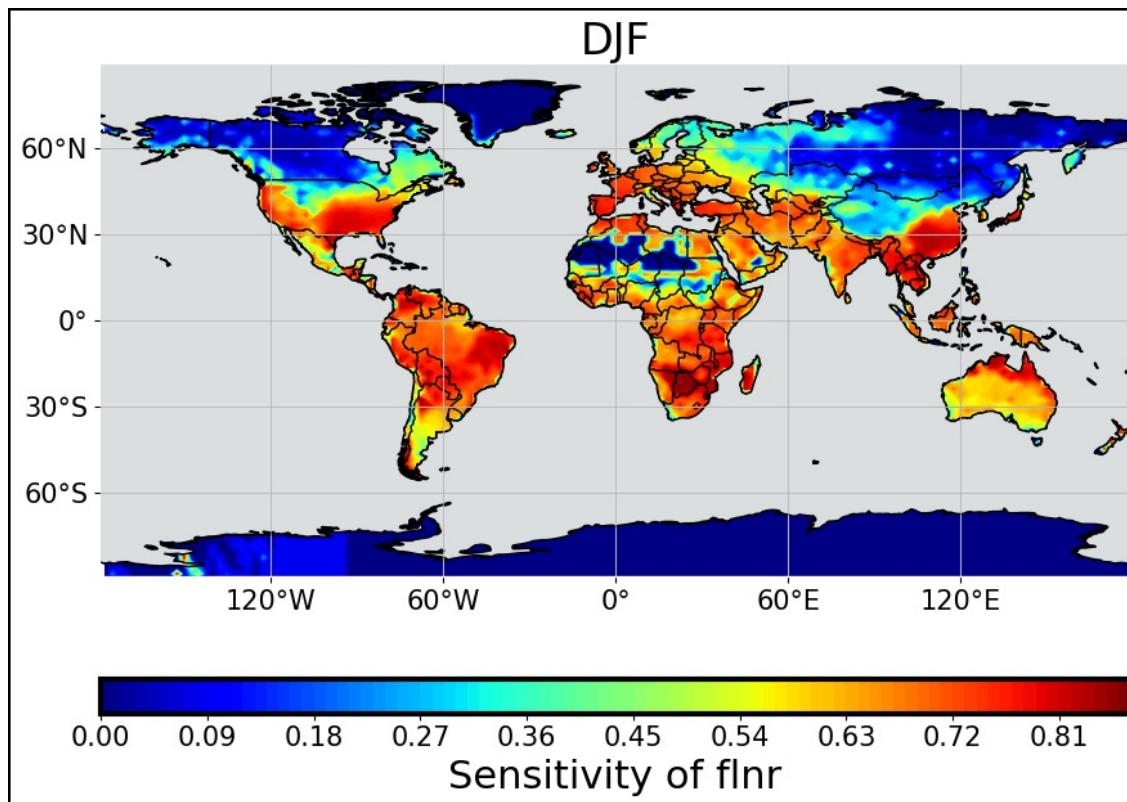
ELM Model Samples



KLNN Surrogate Samples



fLNR sensitivity across the globe



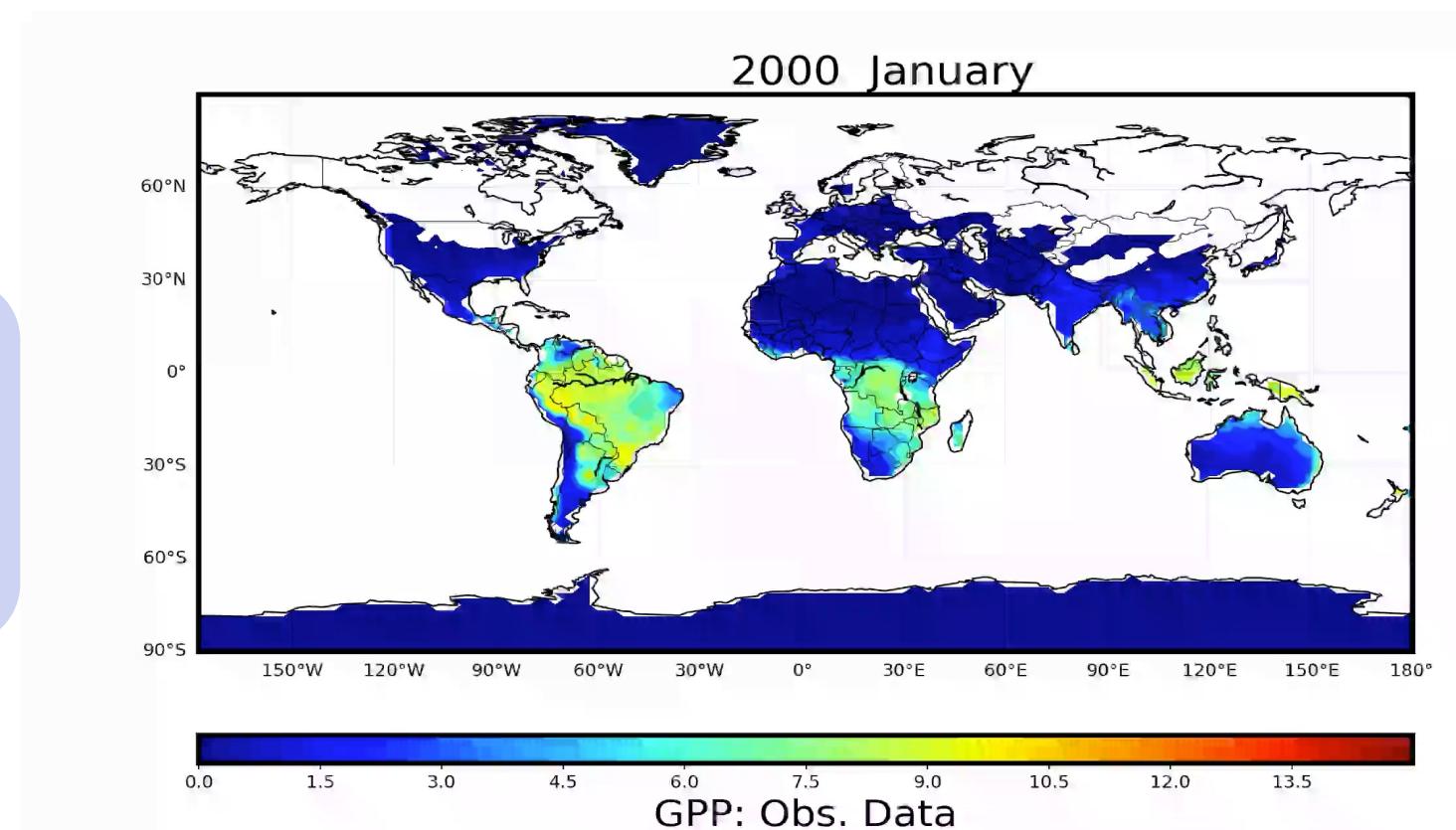


Surrogate-enabled Bayesian calibration

Reference Data

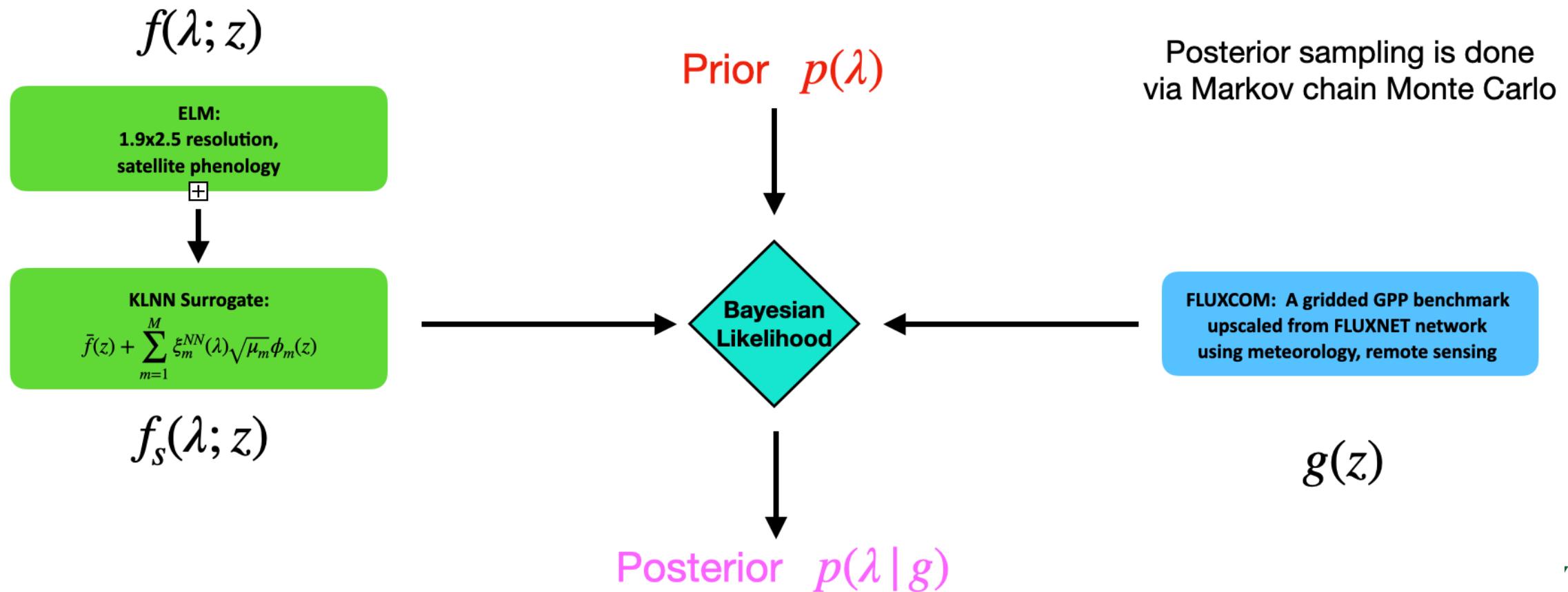
FLUXCOM: A gridded GPP benchmark upscaled from FLUXNET network using meteorology, remote sensing

<https://www.fluxcom.org/>



Bayes' formula

$$p(\lambda | g) \propto p(g | \lambda) p(\lambda)$$



Bayesian Likelihood is constructed in the reduced space

Bayes' formula

$$p(\lambda|g) \propto p(g|\lambda)p(\lambda)$$

KLNN surrogate:

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m^{NN}(\lambda) \sqrt{\mu_m} \phi_m(z)$$

Project observed data to the KL eigenspace:

$$g(z) \approx \bar{f}(z) + \sum_{m=1}^M \eta_m \sqrt{\mu_m} \phi_m(z)$$

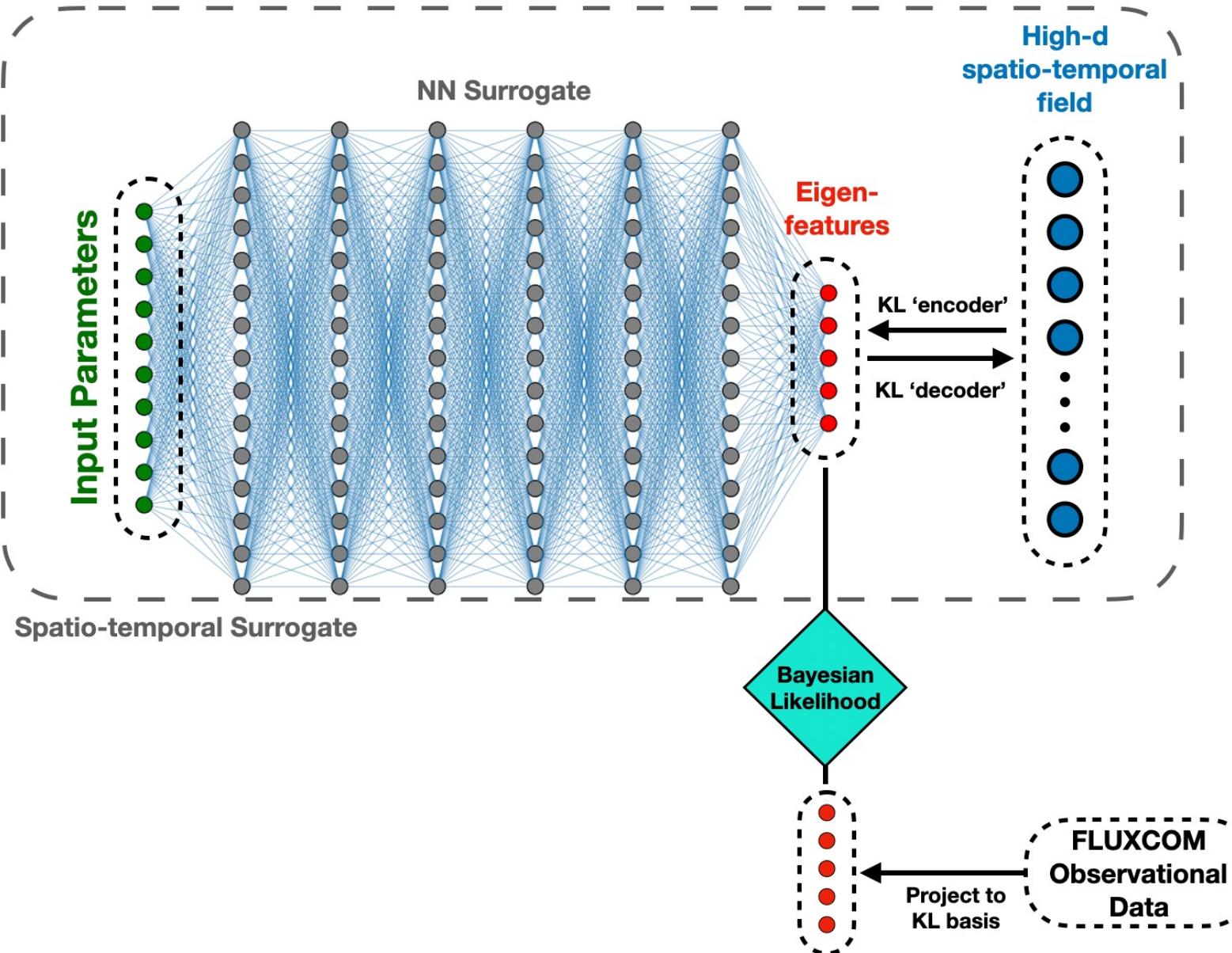
Pointwise likelihood (naïve) :

$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp\left(-\sum_{i=1}^N \frac{(g(z_i) - f(\lambda; z_i))^2}{2\sigma_i^2}\right)$$

Reduced likelihood :

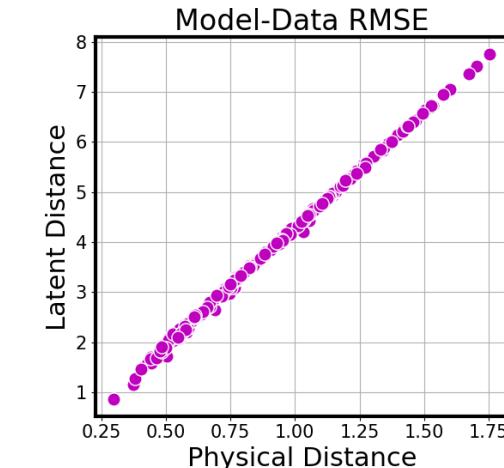
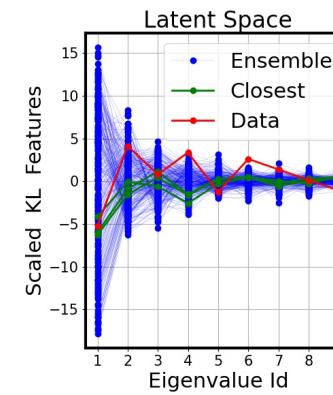
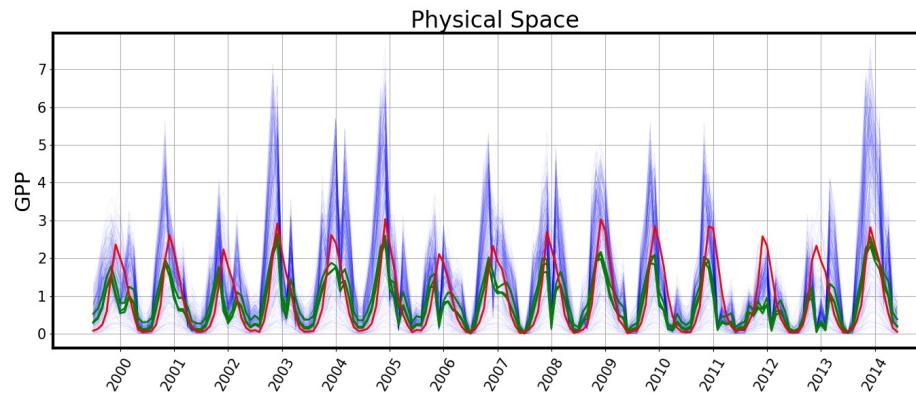
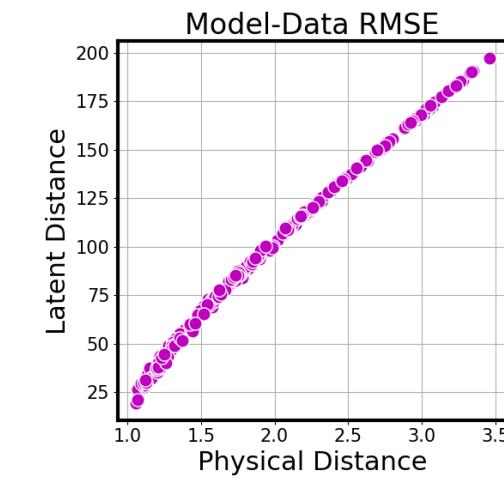
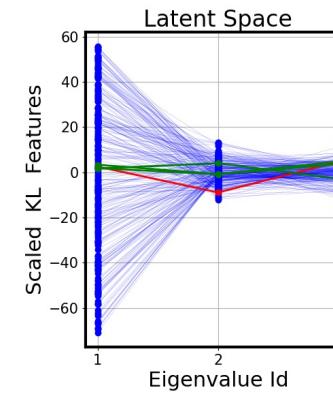
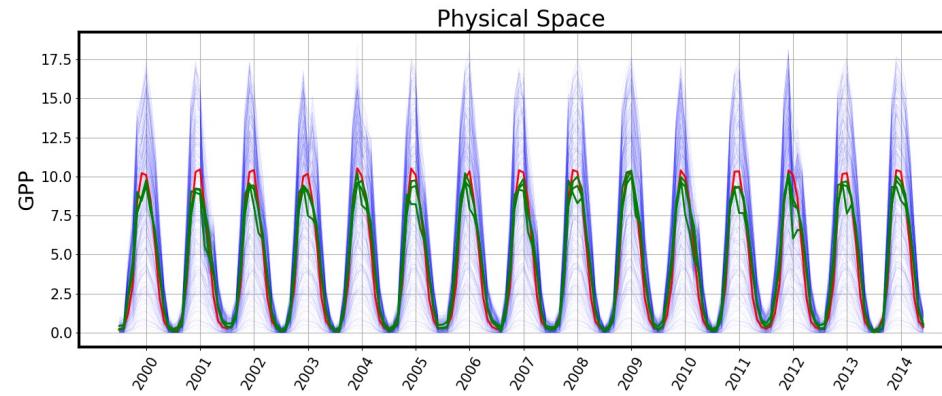
$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp\left(-\sum_{m=1}^M \frac{(\eta_m - \xi_m^{NN}(\lambda))^2}{2\sigma^2}\right)$$

Eigenfeatures ξ_m 's are uncorrelated, zero-mean, unit variance, hence iid gaussian likelihood is a much better assumption in the reduced space.



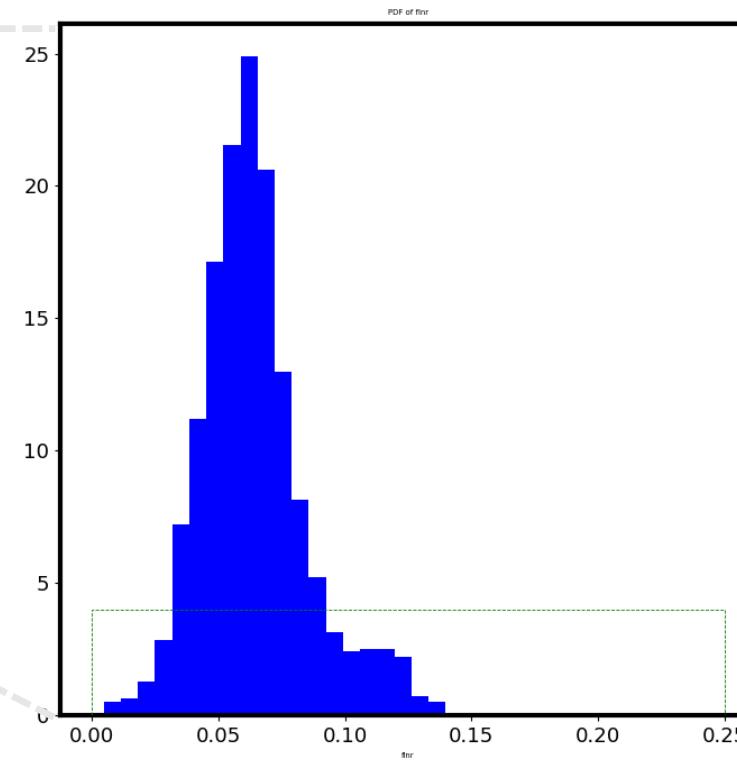
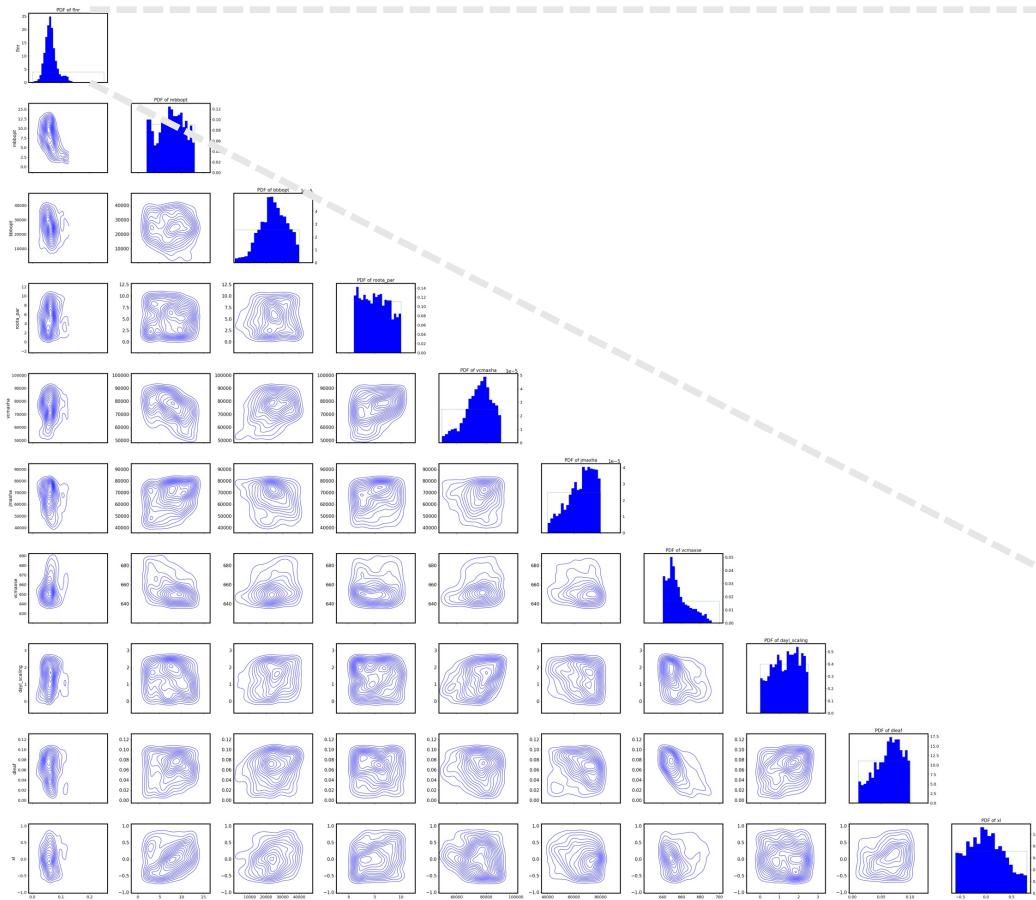
Surrogate-enabled calibration workflow incorporates both forward and inverse UQ tasks

Latent space distance is well-correlated with the physical distance between model and data



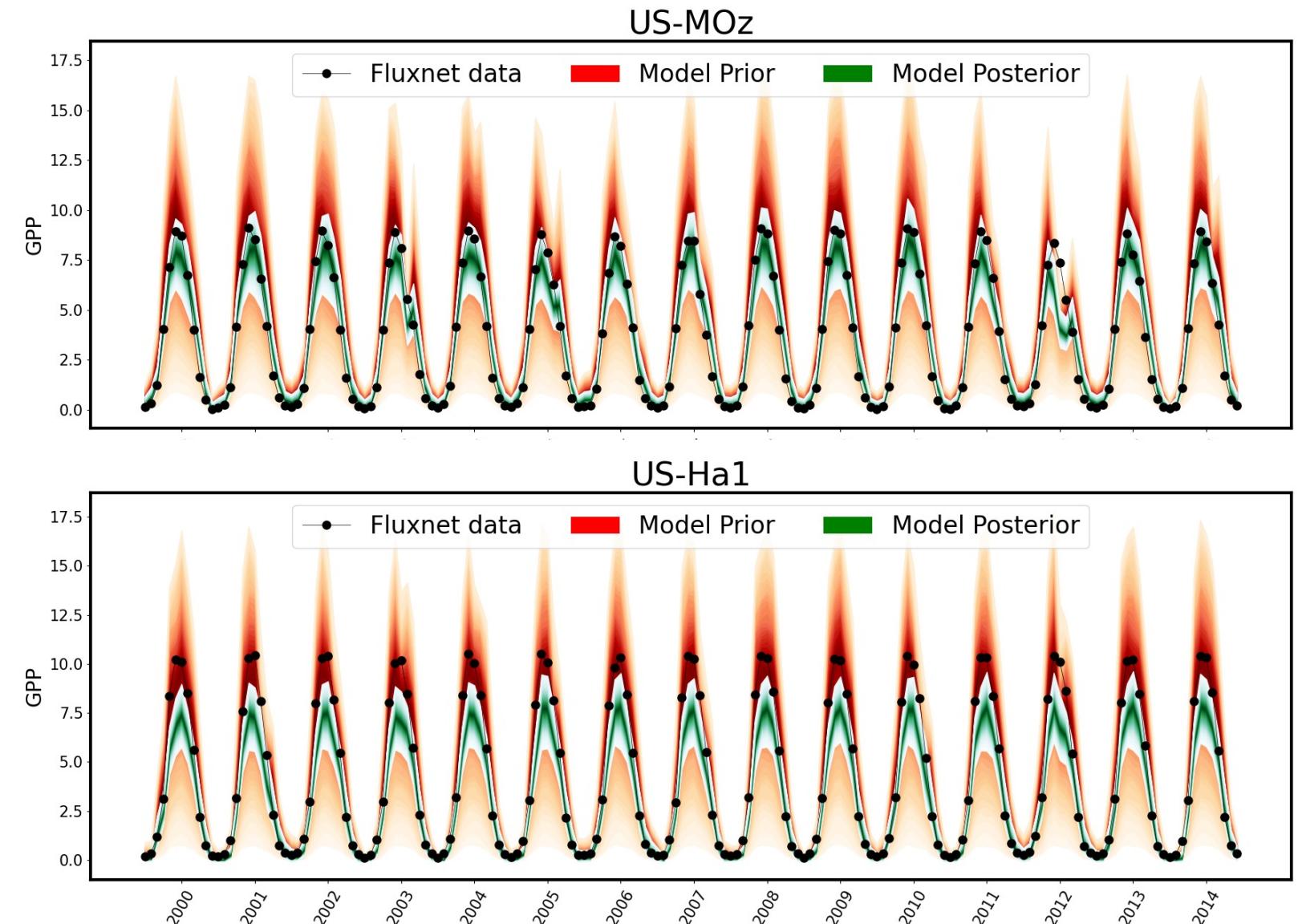


Bayesian calibration enabled by KLNN surrogate



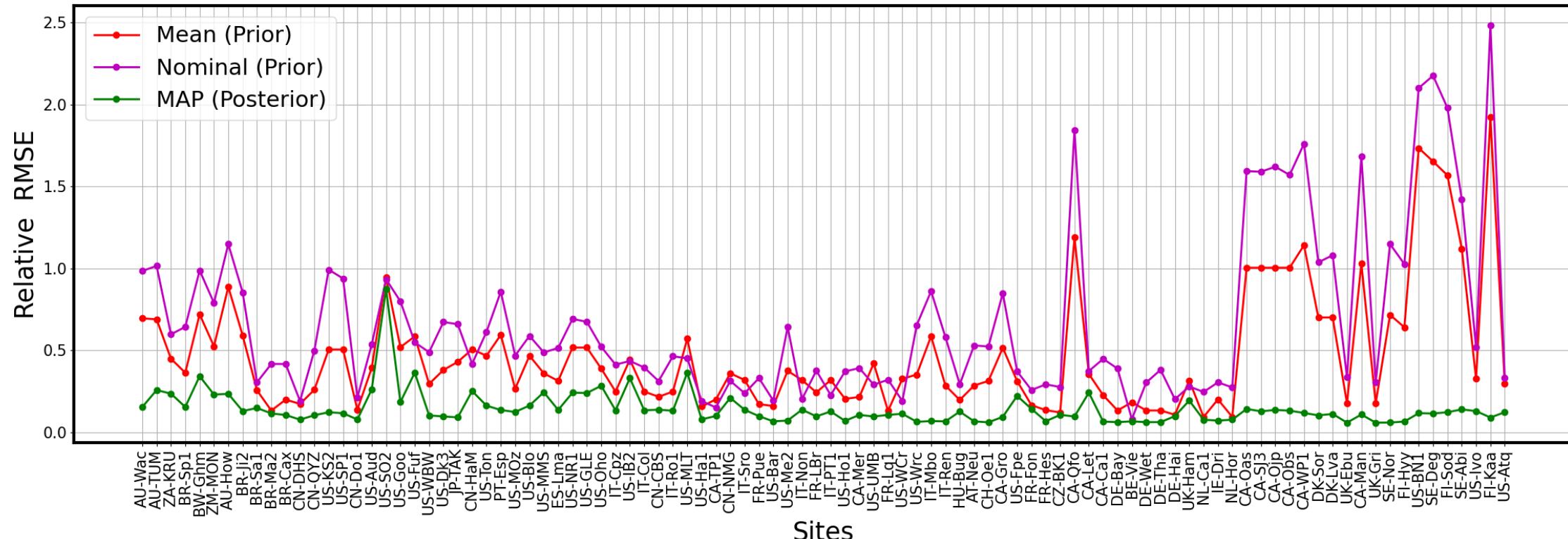
RuBisCO leaf fraction (**fLNR**) is the most constrained parameter

Time evolution
of GPP at select
FLUXNET sites



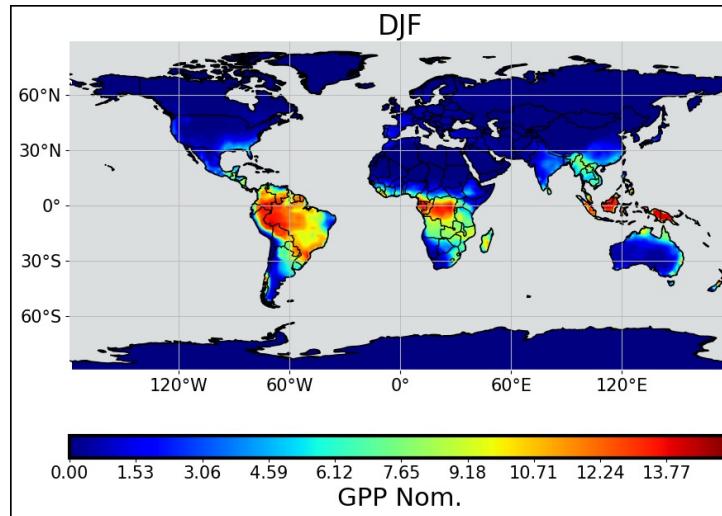
Calibration brings model prediction closer to reference data

Site-specific parameters

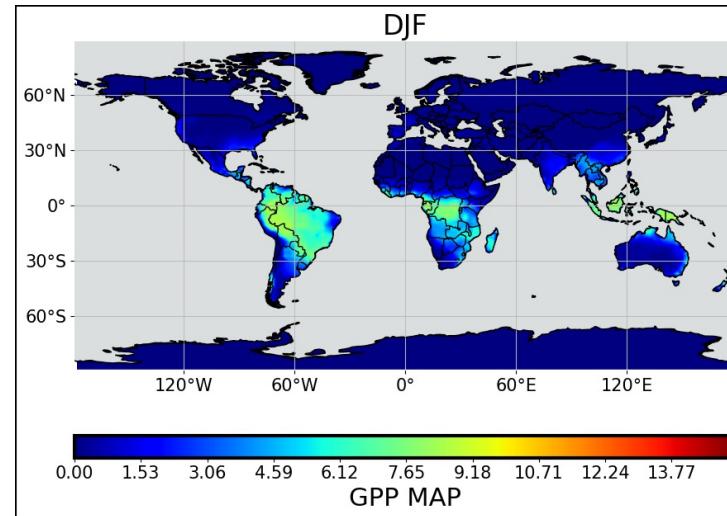




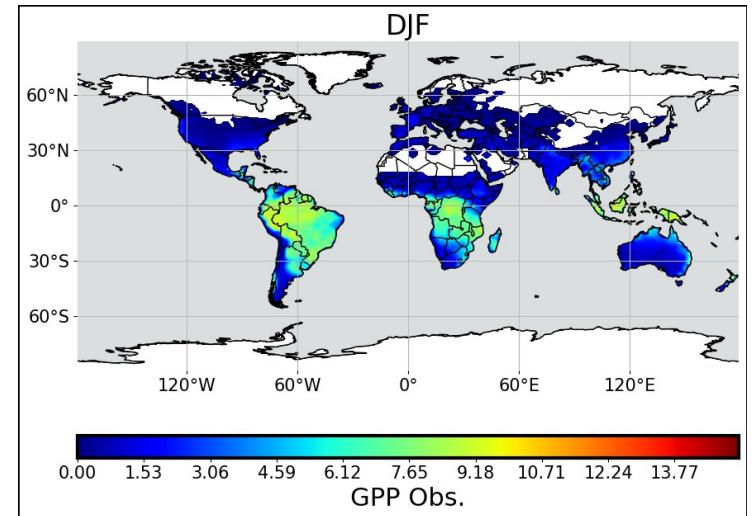
Nominal parameter (prior)



Max a posteriori (MAP)

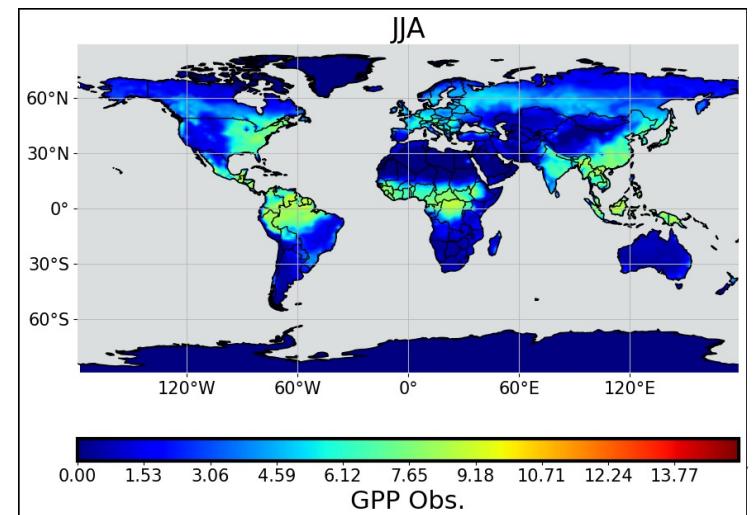
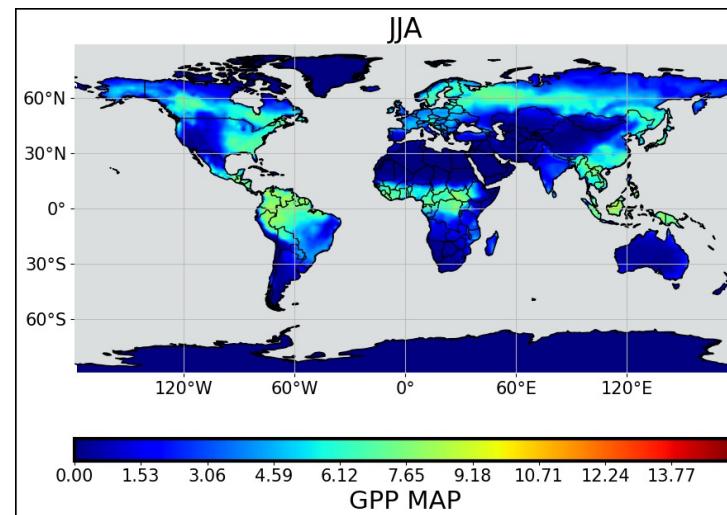
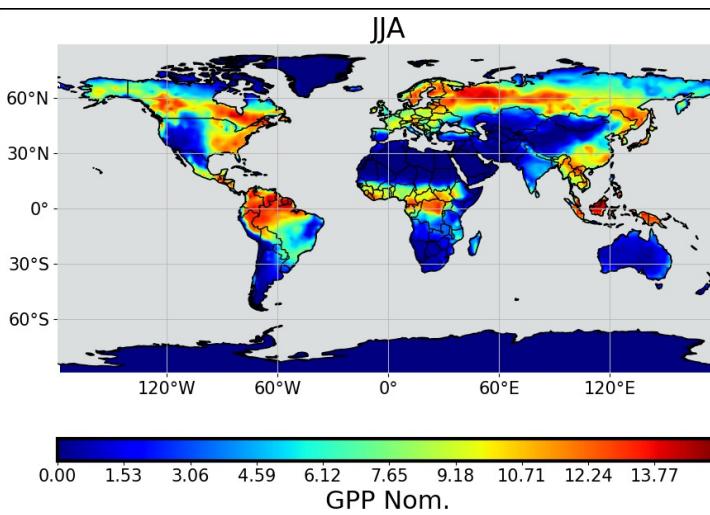


Reference data



Winter

Summer





Summary

- Karhunen-Loève (KL) decomposition reduces the spatio-temporal output dimensionality, taking advantage of correlations over space and time.
- Neural network (NN) surrogate in the reduced eigenspace leads to a spatio-temporal KLNN surrogate that is a small fraction of ELM cost.
- KLNN surrogate enables sampling based global sensitivity analysis and Bayesian calibration performed in the eigenspace.

Ongoing work:

- *Potential PFT-dependent reparameterization to improve model's ability to match reference data.*
- *Calibration with embedded model discrepancy to avoid overfitting.*



Additional Material

KL truncation relies on variance retention

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m(\lambda) \sqrt{\mu_m} \phi_m(z)$$

$$Var[f(z)] = \sum_{m=1}^M \mu_m \phi_m^2(z)$$

$$Var[f] = \sum_{m=1}^M \mu_m$$

$$M = \operatorname{argmin}_{M'} \frac{\sum_{m=1}^{M'} \mu_m}{\sum_{m=1}^{\infty} \mu_m} > 0.99$$

KL is essentially a Singular Value Decomposition

KL

$$f(\lambda^k; zi) - \bar{f}(zi) \approx \sum_{m=1}^M \xi_m(\lambda^k) \sqrt{\mu_m} \phi_m(zi)$$

$$F_{ki} = \sum_{m=1}^M U_{km} \Sigma_{mm} V_{im}$$

SVD

$$F = U \Sigma V^T$$

Karhunen-Loève expansion

- is centralized (first subtract the mean)
- often comes with the continuous form
- has random variable interpretation for the latent features (aka left singular vectors) ξ_m

Polynomial Chaos intro

- Our traditional tool for uncertainty representation and propagation
- Random variables represented as polynomial expansion of standard random variables,

such as gaussian or uniform

$$\xi = \sum_{k=1}^K c_k \psi_k(\eta)$$

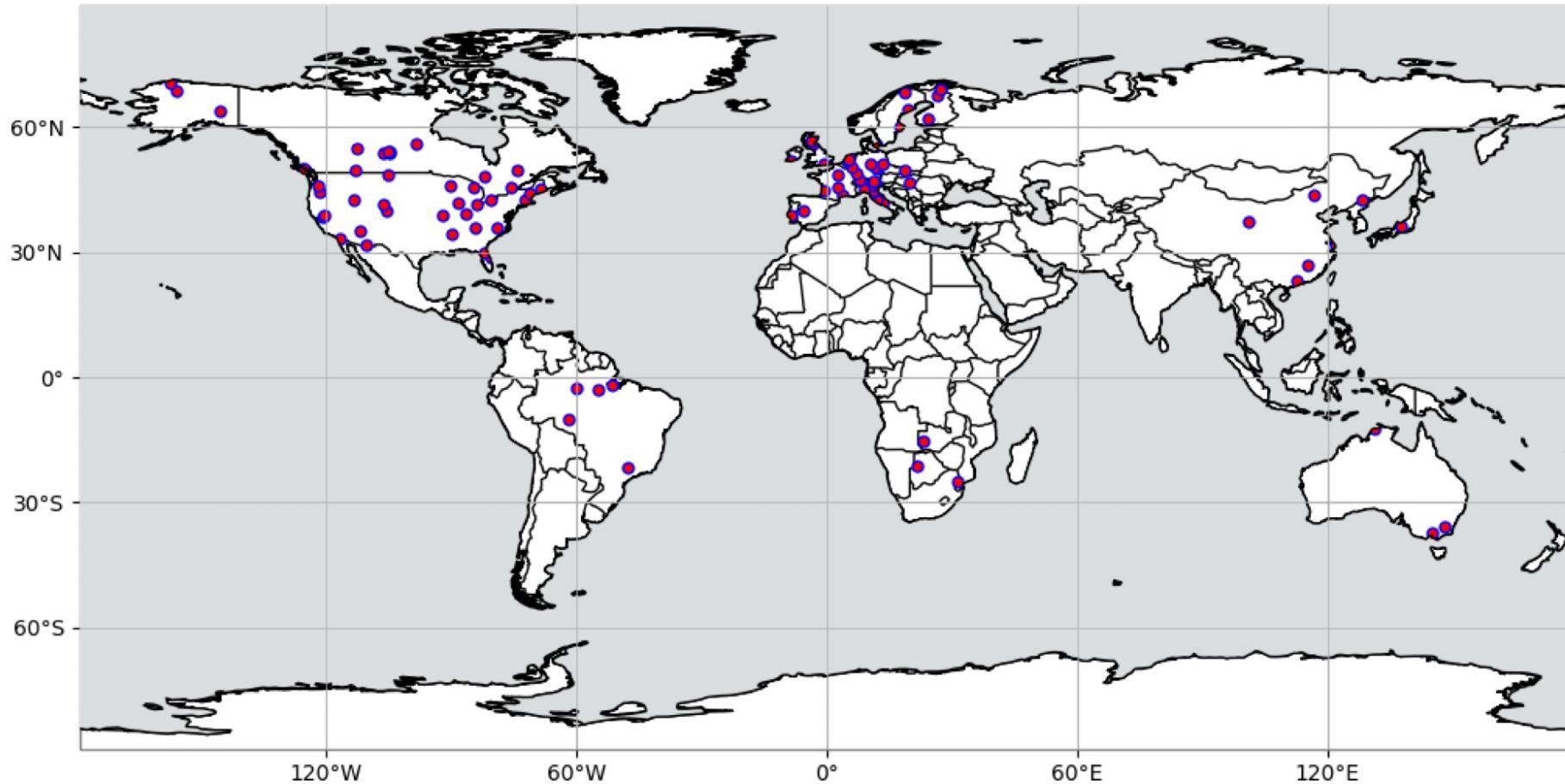
- Convenient for uncertainty propagation

$$f(\xi) = \sum_{k=0}^K f_k \psi_k(\eta)$$

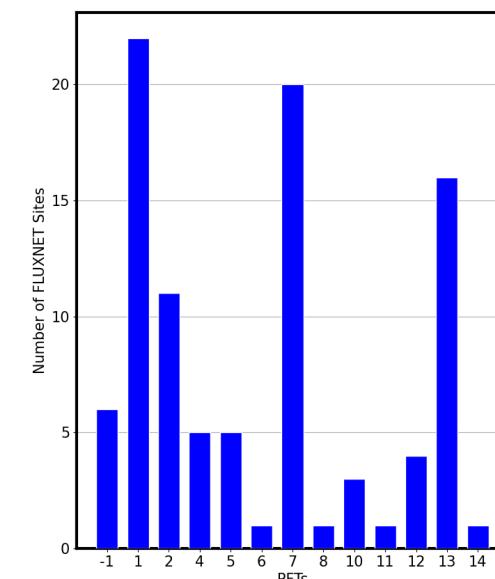
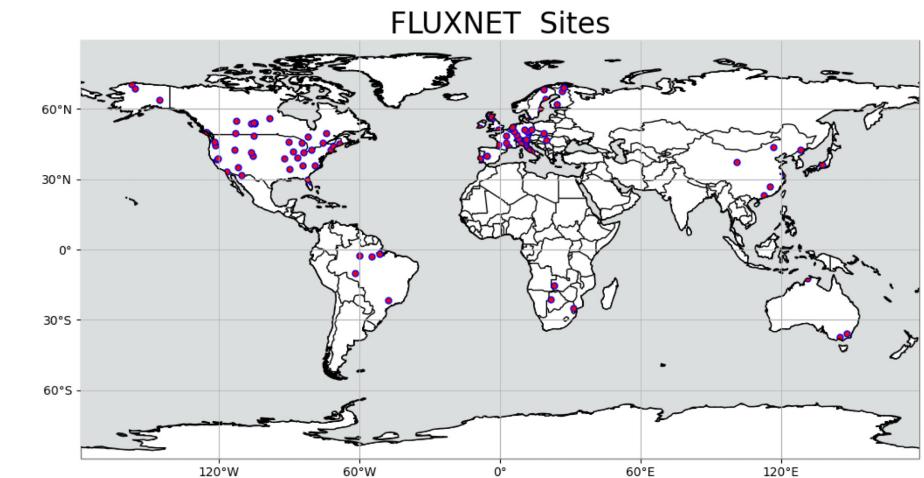
- Moment estimation
- Global Sensitivity Analysis (a.k.a. Sobol indices or variance-based decomposition)



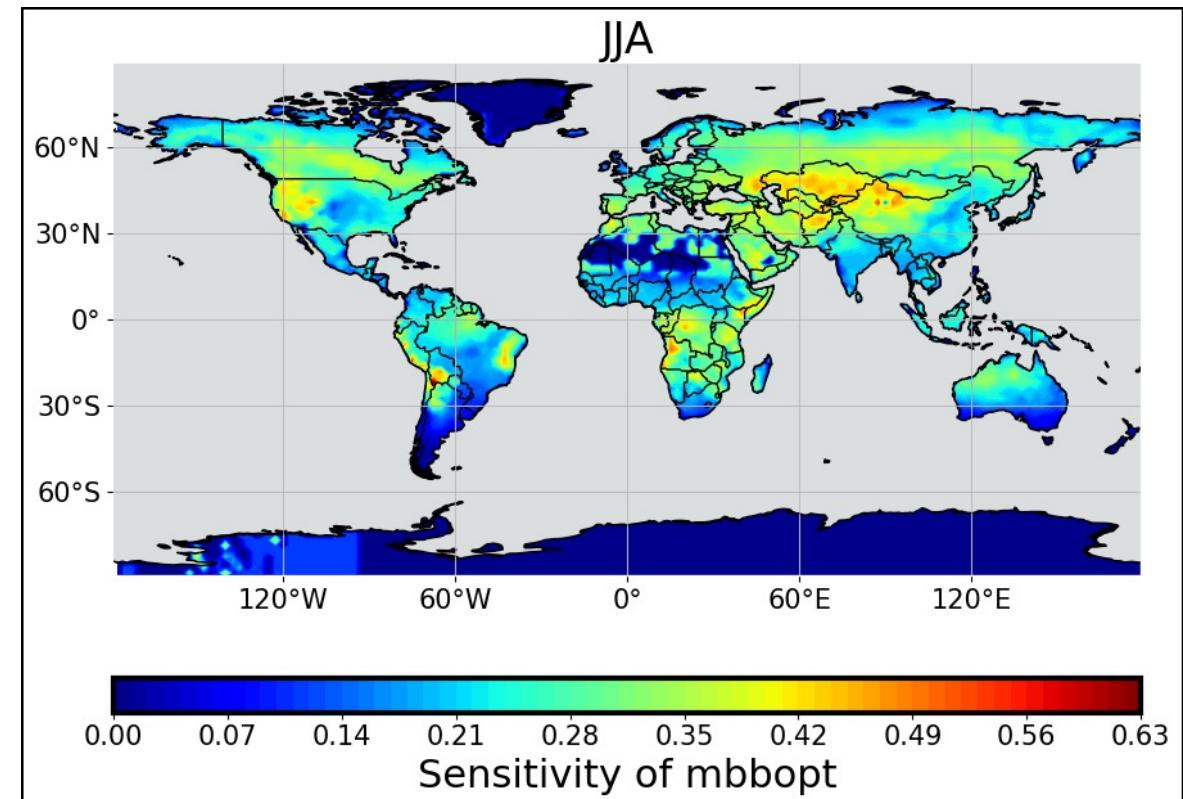
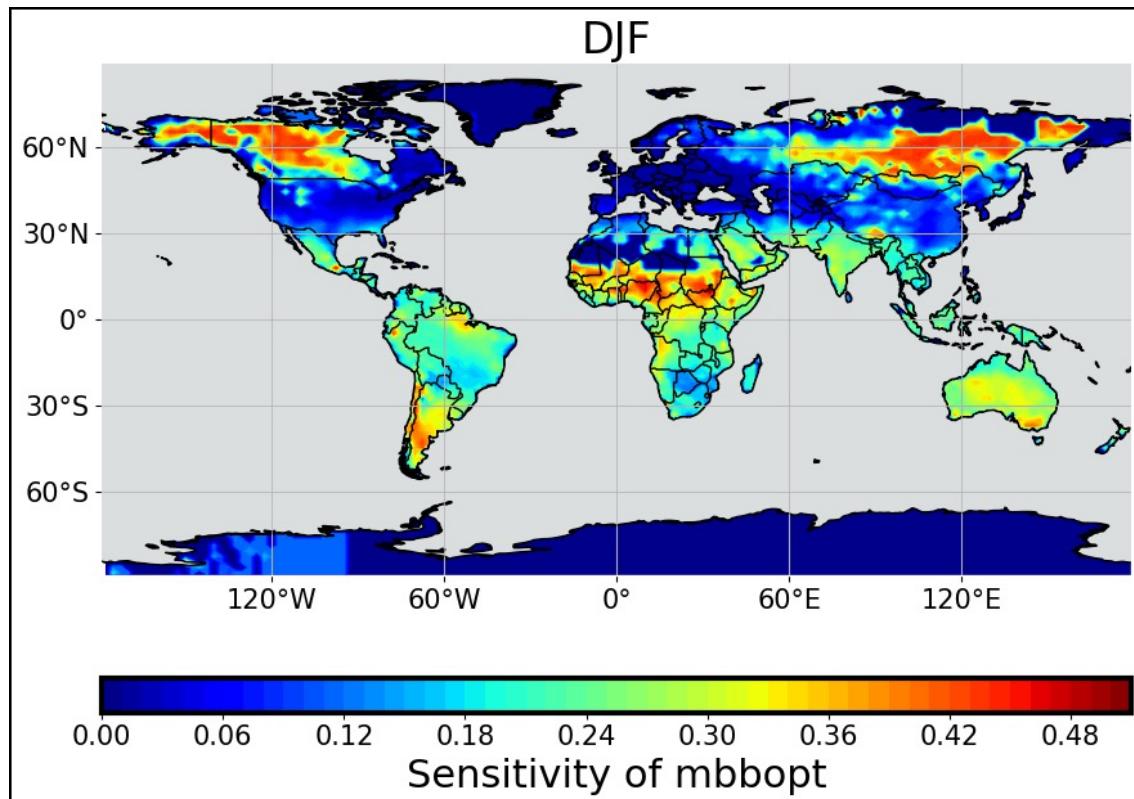
Methodological evaluation at 96 FLUXNET sites



ID	PFT Name	Count
1	Boreal evergreen needleleaf tree	22
2	Temperate evergreen needleleaf tree	11
3	Boreal deciduous needleleaf tree	0
4	Tropical evergreen broadleaf tree	5
5	Temperate evergreen broadleaf tree	5
6	Tropical deciduous broadleaf tree	1
7	Temperate deciduous broadleaf tree	20
8	Boreal deciduous broadleaf tree	1
9	Broadleaf evergreen shrub	0
10	Temperate deciduous broadleaf shrub	3
11	Boreal deciduous broadleaf shrub	1
12	C3 arctic grass	4
13	C3 non-arctic grass	16
14	C4 grass	1
-1	Mixed	6



mbbopt sensitivity across the globe



Bayesian Likelihood in the reduced space TBD

KLNN surrogate:

$$f(\lambda; z) \approx \bar{f}(z) + \sum_{m=1}^M \xi_m^{NN}(\lambda) \sqrt{\mu_m} \phi_m(z)$$

Project observed data to the KL eigenspace:

$$g(z) \approx \bar{f}(z) + \sum_{m=1}^M \eta_m \sqrt{\mu_m} \phi_m(z)$$

Pointwise likelihood (old) :

$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp \left(- \sum_{i=1}^N \frac{(g(z_i) - f(\lambda; z_i))^2}{2\sigma_i^2} \right)$$

Data model (old) :

$$g(z_i) = f(\lambda; z_i) + \sigma_i \epsilon_i$$

i.i.d. Normal

$$L_g(\lambda) \equiv p(g|\lambda) \propto \exp \left(- \sum_{m=1}^M \frac{(\eta_m - \xi_m^{NN}(\lambda))^2}{2\sigma^2} \right)$$

Data model (new) :

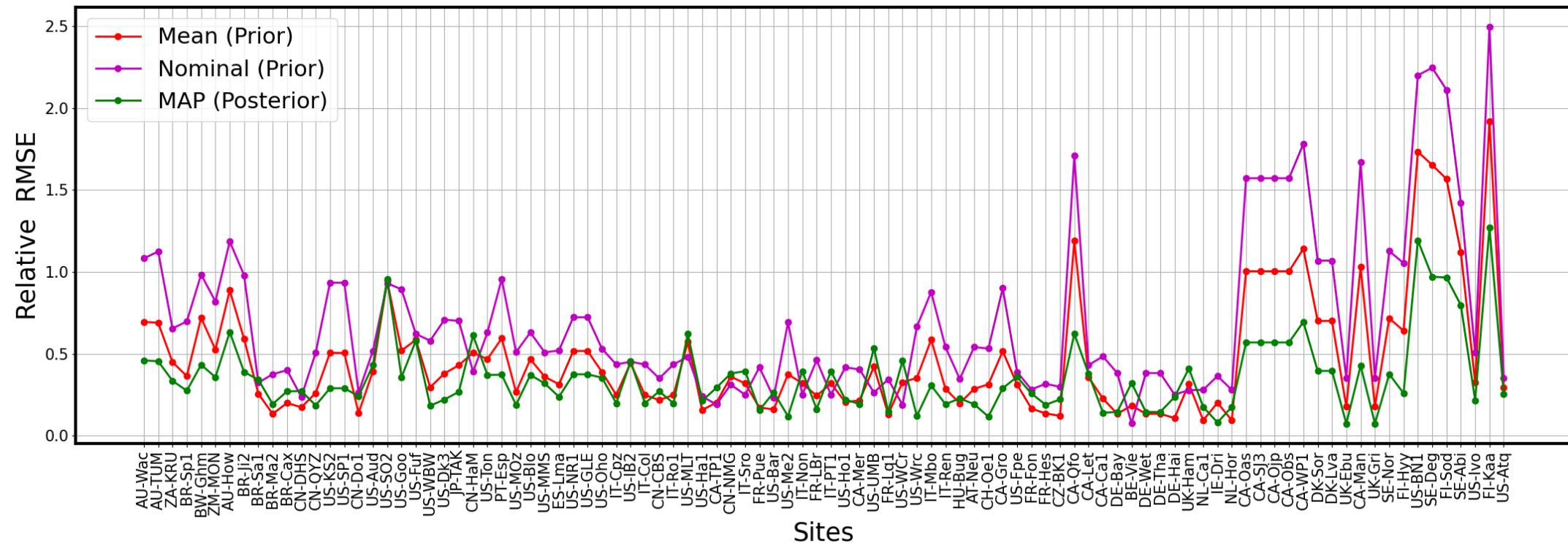
$$\eta_m = \xi_m^{NN}(\lambda) + \tilde{\sigma} \epsilon_m$$

MVN (physics-based)

$$g(z_i) = f(\lambda; z_i) + \sum_{m=1}^M \tilde{\epsilon}_m \sqrt{\mu_m} \phi_m(z_i)$$

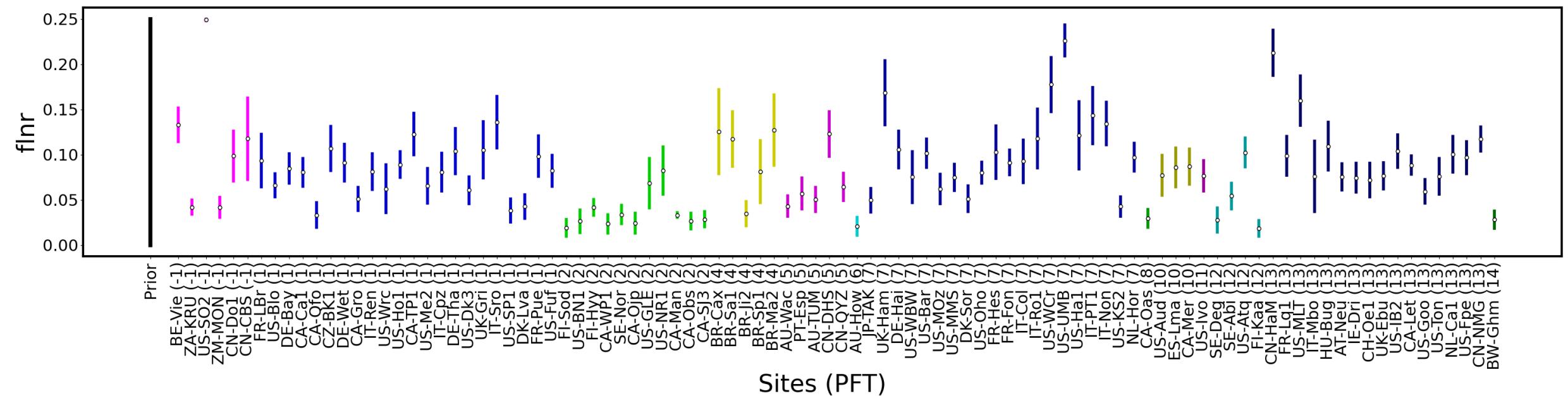
Calibration brings model prediction closer to reference data

Common parameters for all sites



Local (site-specific) fLNR posterior PDFs

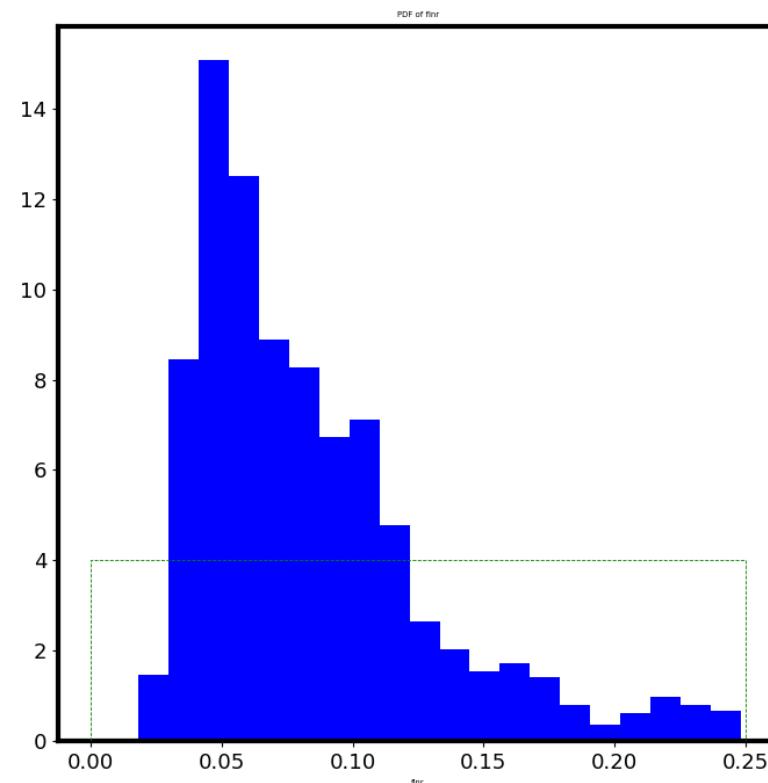
Grouped by PFTs



Two calibration regimes

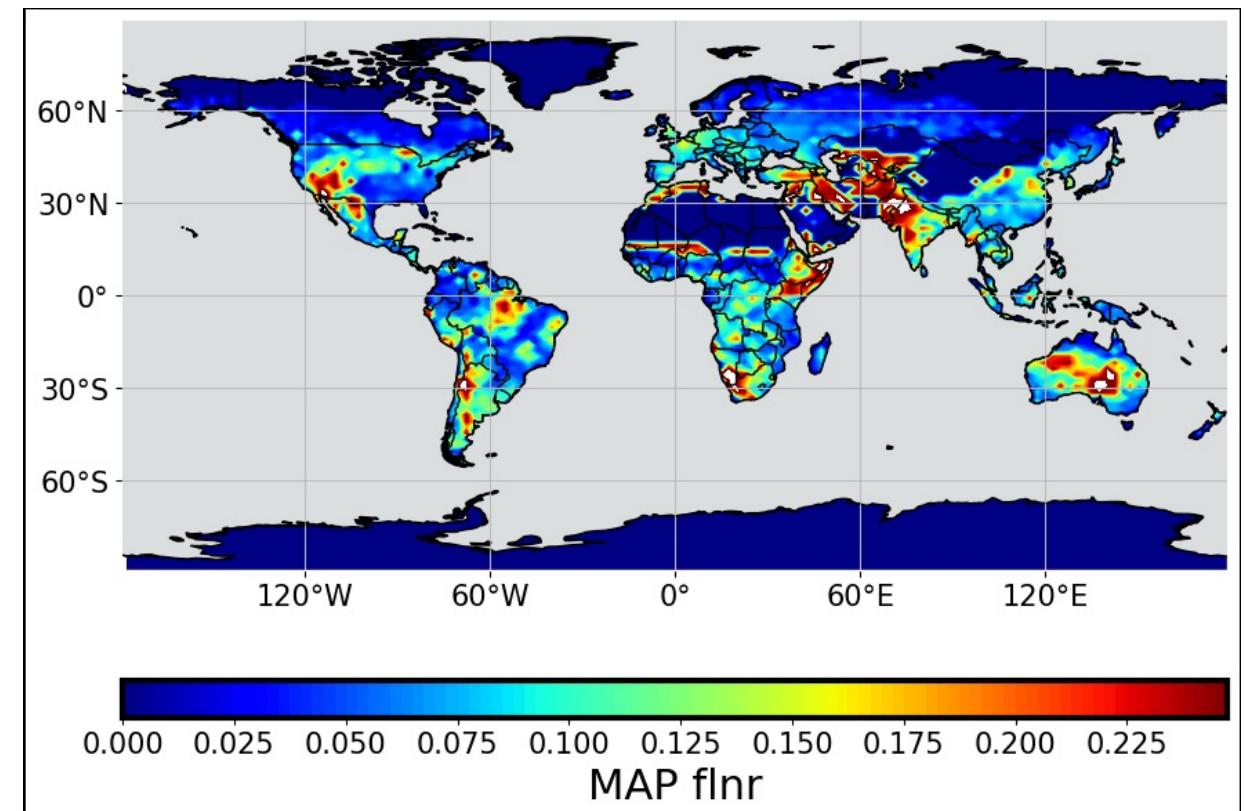
One global surrogate

Fixed global fLNR parameter

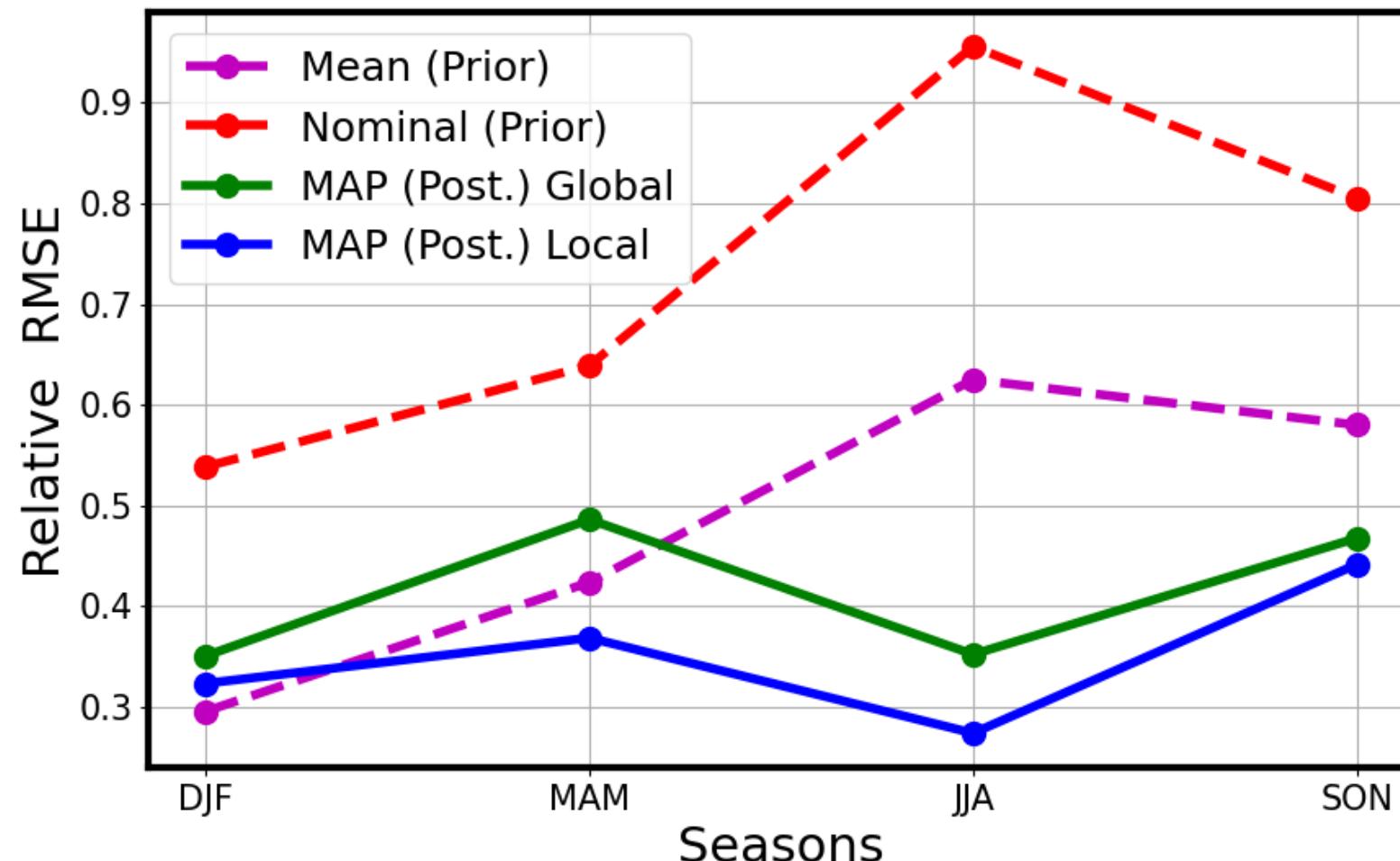


One surrogate per grid cell

Local fLNR parameter

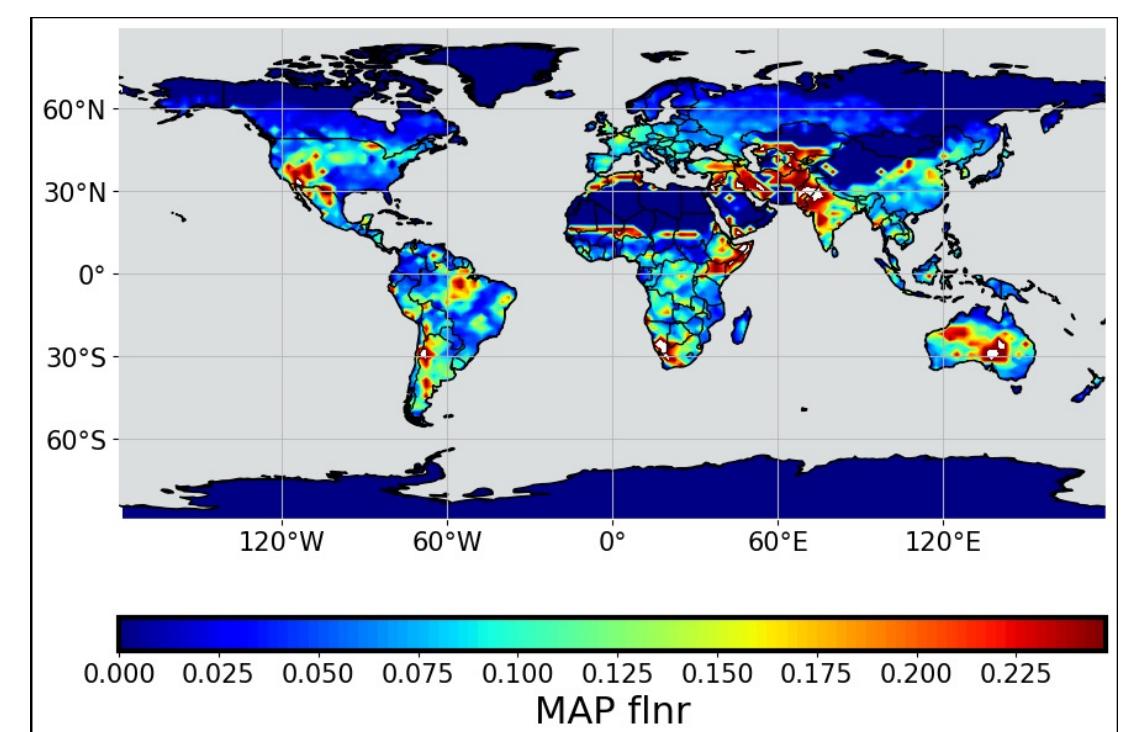
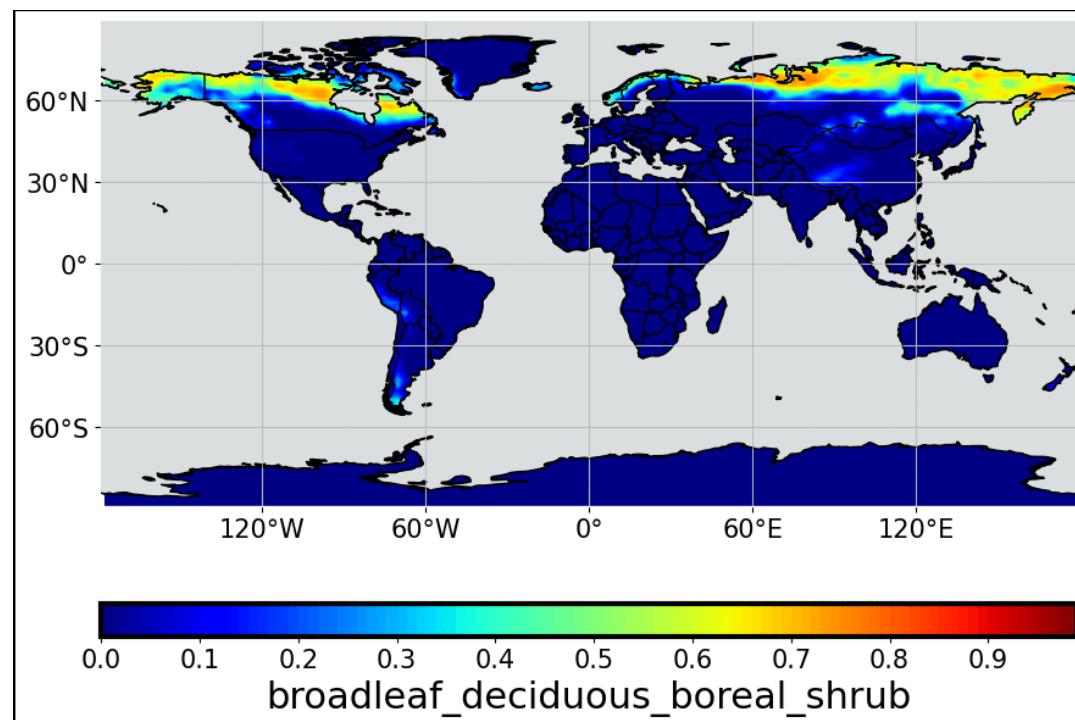


Localized calibration works slightly better



Correlate PFT fractions globally with best fLNR values

PFT Fractions for all PFTs



Correlate PFT fractions globally with best fLNR values

