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Paper #14349

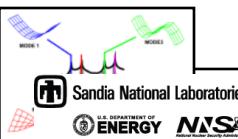
Actual Field Response Simulation Using Modified Laboratory Loading Conditions

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IMAC XLI

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Outline

Motivation

History

Model

Cases

Conclusions

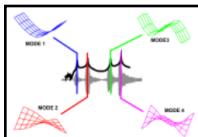
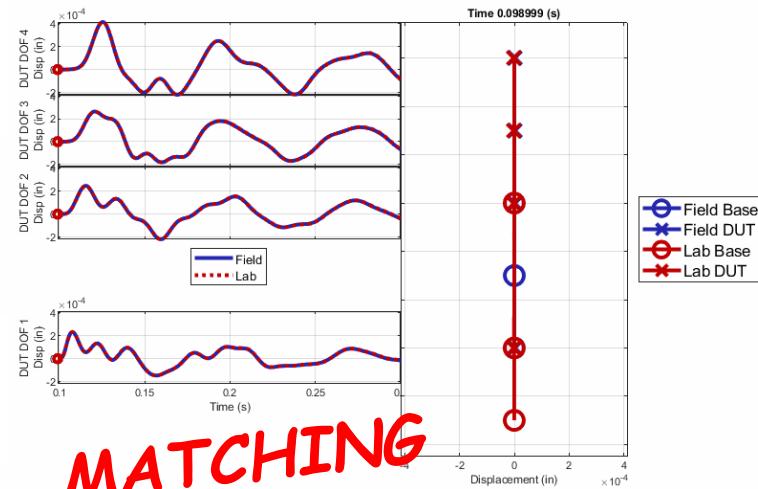
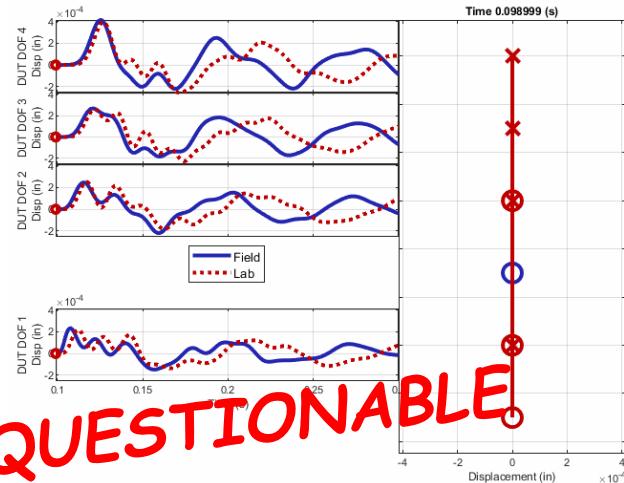
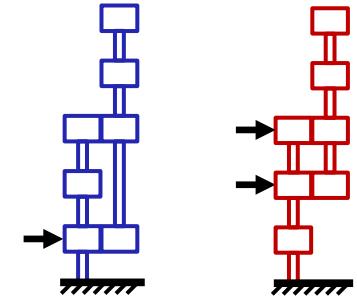
Motivation

Brief history of test specifications

Analytical Model Description

Case Studies

Conclusions



Motivation

Motivation

History

Model

Cases

Conclusions

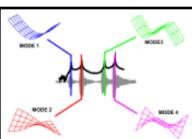
Vibration tests are used to qualify designs

Lab responses don't match the field

- *Boundary condition discrepancies*
- *Load discrepancies*
- *Unnecessary test failures*

Techniques are driving toward faithfully reproducing field responses

Ultimate goal is to simulate realistic damage mechanism in laboratory testing



Early Days

Motivation

History

Model

Cases

Conclusions

Institutions developed (1940s)

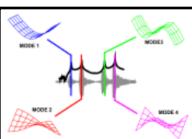
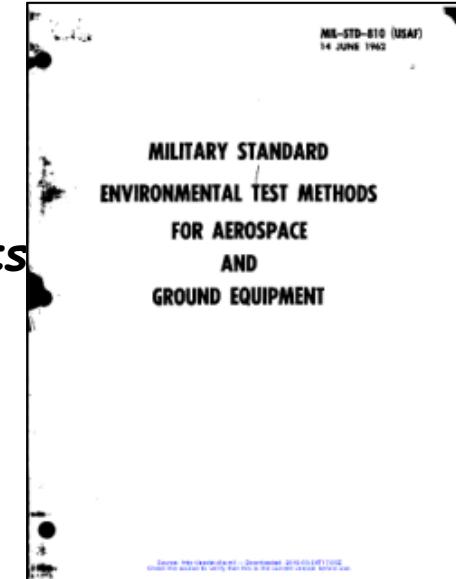
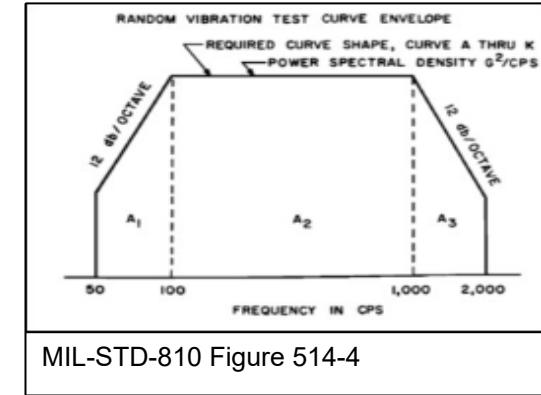
- *Independent test methods*
- *Independent test specifications*

Concerns with broad flat specifications (1950s)

Community called for a standard

MIL-STD-810 (1962)

- *Reduce cost: Simple and repeatable*
- *Single axis input covering multiple environments*
- *Rigid fixture, control at interface*
- *Incorrectly assumed rigid systems*
- *De-emphasize correlation of lab to field (seen as advanced solutions)*
- *Intended as starting point*



Early Days

Please understand:

We tried to make testing simple and repeatable with the same inputs, but the excitors and fixtures were different from lab to lab so the responses might never be the same. This is fine for some test articles, but more is needed for high consequence designs.



a standard
)

Simple and repeatable
but covering multiple
control at interface
assumed rigid systems
correlation of lab to
advanced solutions)

Intended as starting point



Simple 1DOF Inputs Need Improvement

Motivation

History

Model

Cases

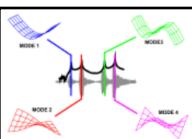
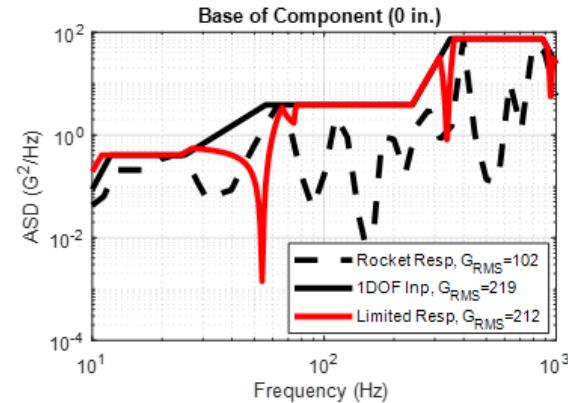
Conclusions

Inappropriate single axis test failures

- *OK in field*
- *Very high lab test responses common*
- *Possibly miss design flaws*
- *Hesitant to publish failures*

Limiting single axis vibration tests

- *In the field, input valleys are natural*
- *Straight line enveloping fills in valleys*
- *Shaker can impart too much force*
- *Results in extremely high responses*
- *Force input and/or response limit*
- *Added to standards*



Simple 1DOF Inputs Need Improvement

Motivation

History

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Conclusions

Inappropriate single axis test failures

- *OK in field*
- *Very high lab test responses common*

Please understand:

We had to do force limiting because we were overtesting hardware, but that doesn't address that the inputs are wrong. This is a band aid for the symptoms of bad inputs rather than fixing the real problem. For high consequence testing, we need to do better.

- *Results in extremely high responses*
- *Force input and/or response limit*
- *Added to standards*



Multiple Input testing

Motivation

History

Model

Cases

Conclusions

Can reduce test time and cost

Base excitation (input at single location)

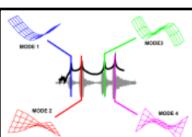
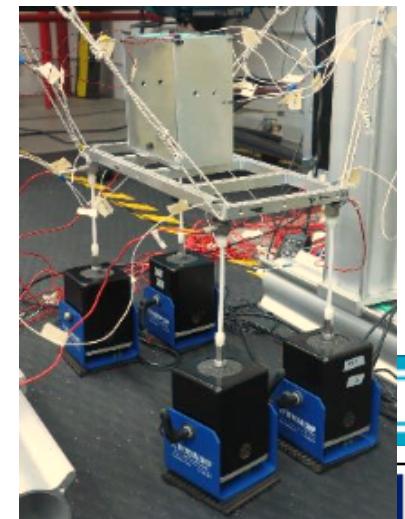
- 3-axis: 3 translations
- 6-axis: 3 translations, 3 rotations



Photo from Aerospace Testing International

Multiple input testing

- Modal shakers, base shakers, others
- Impedance Matched, Multi-Axis Testing (IMMAT)
- Direct loads on connections with multiple DOFs



Fixture Neutralization (FINE) Methods

Motivation

History

Model

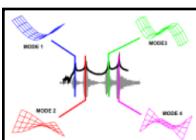
Cases

Conclusions

One dynamic boundary condition in the field, different boundary condition in the laboratory

Applying the same inputs will result in undesired responses

Determine new laboratory inputs to replicate the field responses in the laboratory



Fixture Neutralization (FINE) Methods

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Impedance Based FINE - only connection DOFs

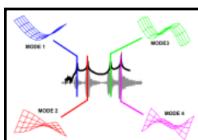
$$\left\{ \mathbf{x}_c^{(L_2)} \right\} = \left(H_{cc}^{(D)} + H_{cc}^{(L_2)} \right) \left(H_{cc}^{(D)} + H_{cc}^{(L_1)} \right)^g \left\{ \mathbf{x}_c^{(L_1)} \right\}$$

Modal Based FINE - Includes modal insight

$$\left\{ F_j^{(DL_2)} \right\} = \left[H_{ij}^{(DL_2)} \right]^g \left\{ x_i^{(DL_1)} \right\}$$

Modal Amplitude Contribution Map (MACM) Equation - Lab modal acceleration to match field modal accelerations

$$\left[\bar{H}^{(DL_2)} \right] \left[U_j^{(DL_2)} \right]^T \left[\left[U_i^{(DL_2)} \right] \left[\bar{H}^{(DL_2)} \right] \left[U_j^{(DL_2)} \right]^T \right]^g \left[U_i^{(DL_1)} \right] \bullet \left\{ \bar{x}^{(DL_1)} \right\}$$



Field Configuration

Motivation

History

Model

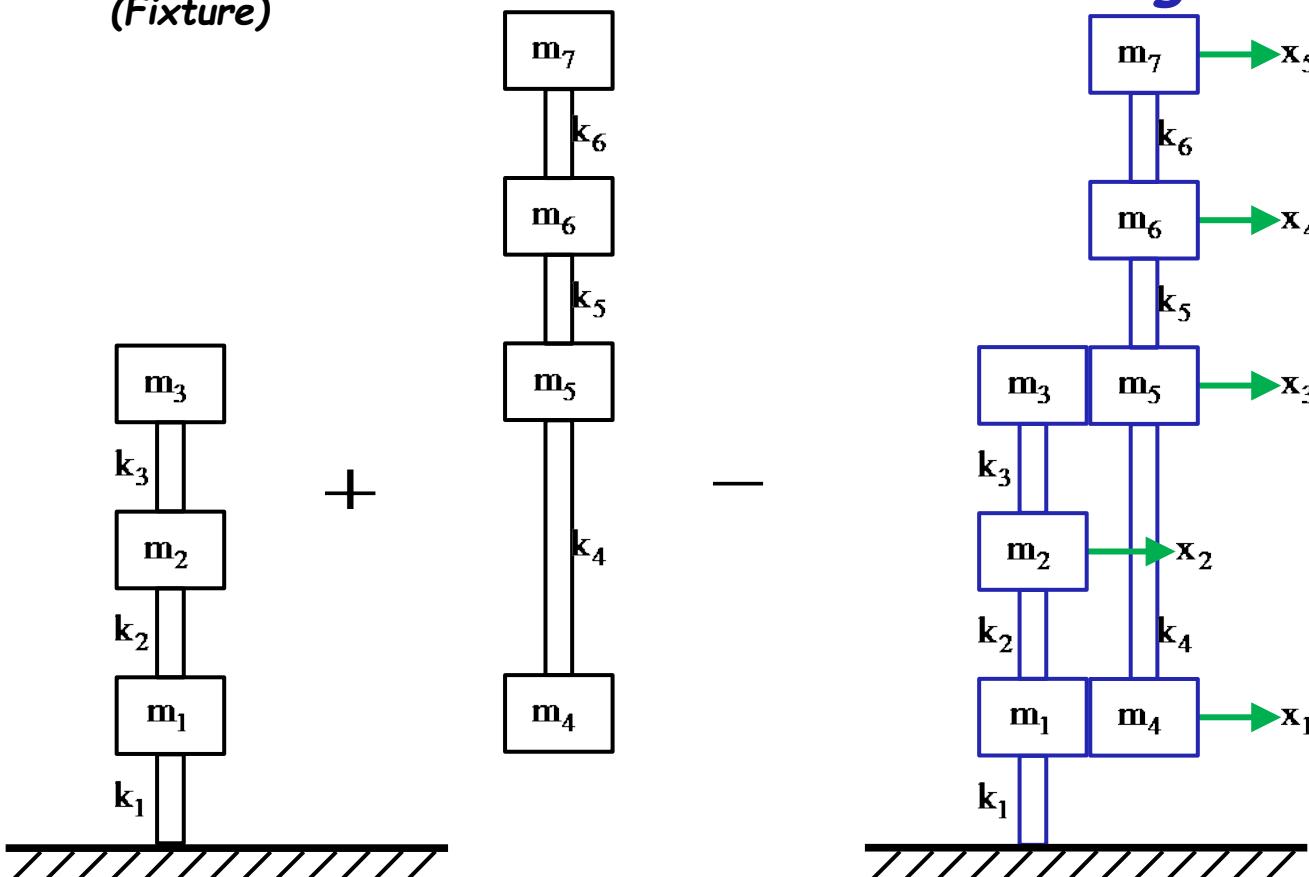
Cases

Conclusions

Base
(Fixture)

DUT

Field
Config



Laboratory Configuration

Motivation

History

Model

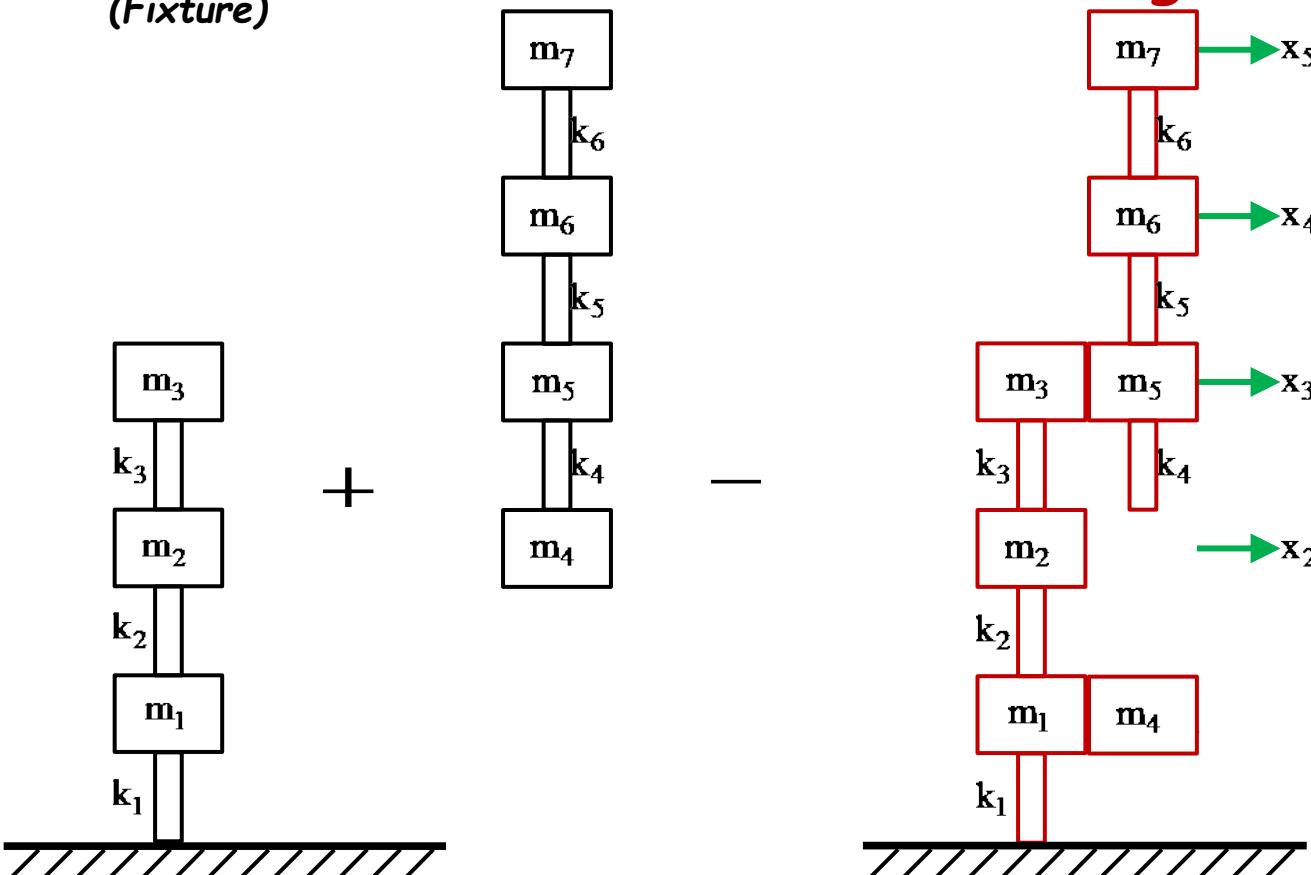
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Laboratory Configuration

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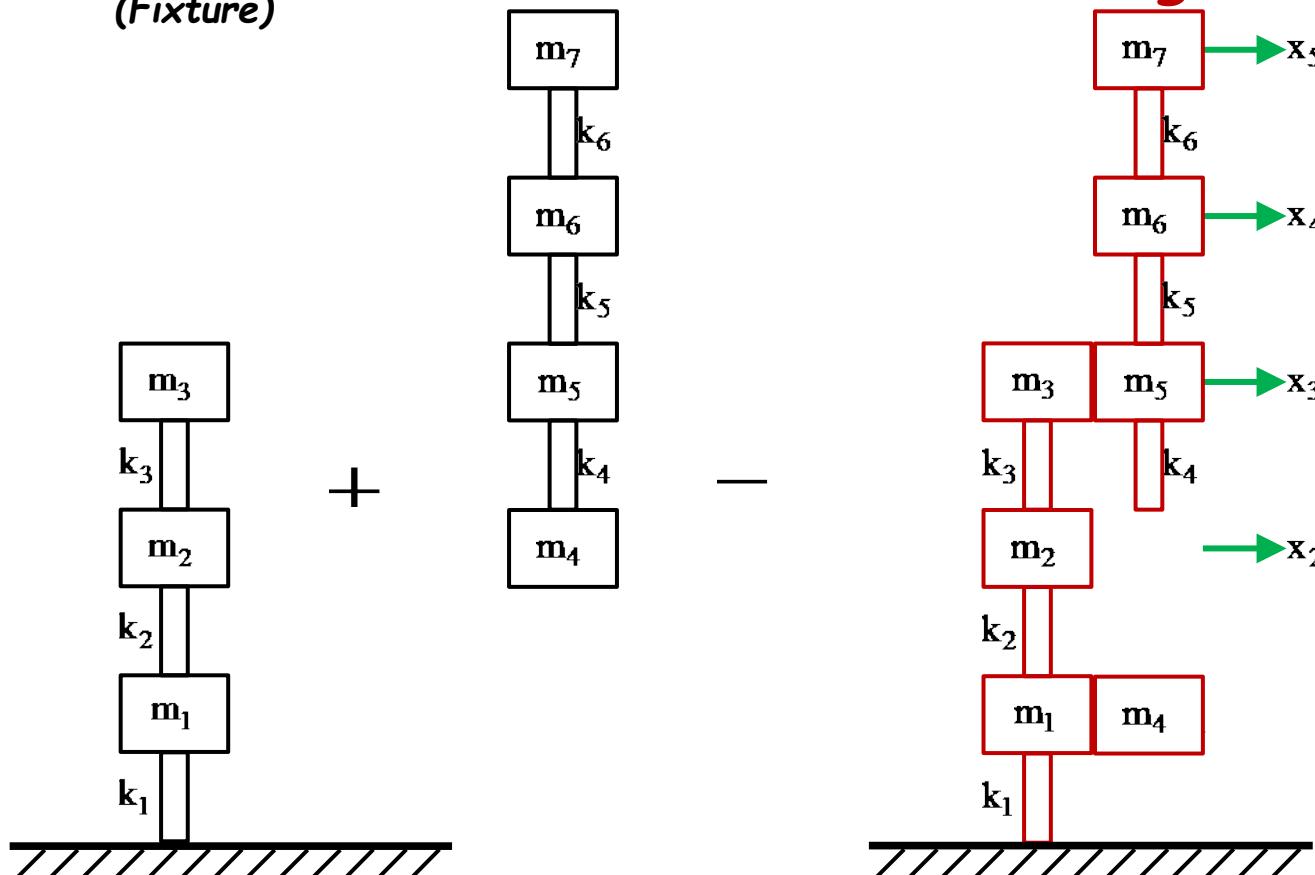
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Base
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Laboratory Configuration

Motivation

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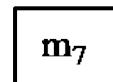
Cases

Conclusions

Base
(Fixture)

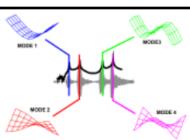
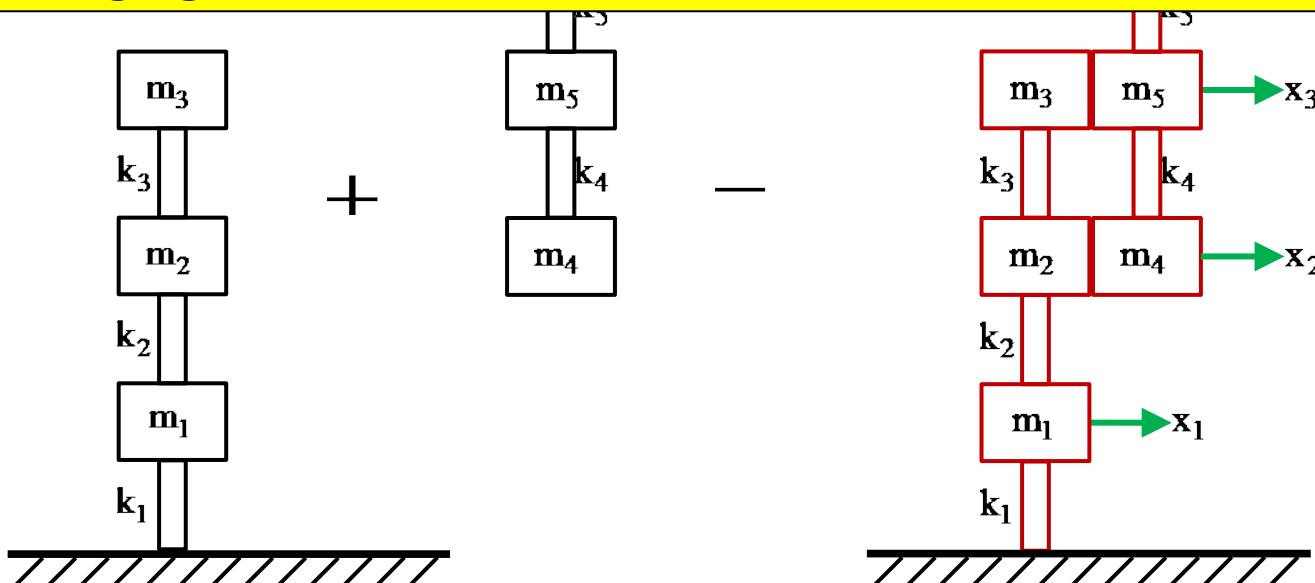
DUT

Lab
Config



To change the boundary condition from the field to the lab,

I'm only changing one connection location for the DUT to the Fixture



Models Side by Side

Motivation

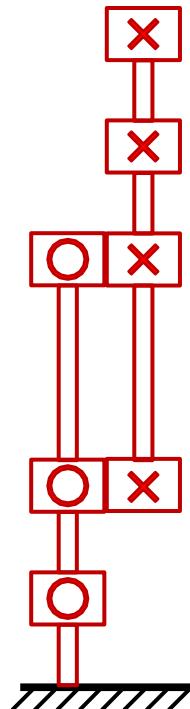
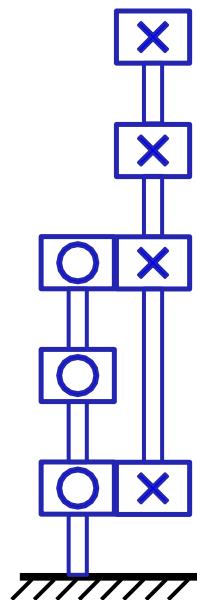
History

Model

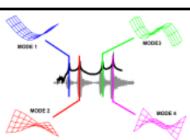
Cases

Conclusions

Two models will be used to show the difference between the field and lab



Impedance and Modal FINE have same solutions



System Mode Shape Comparisons

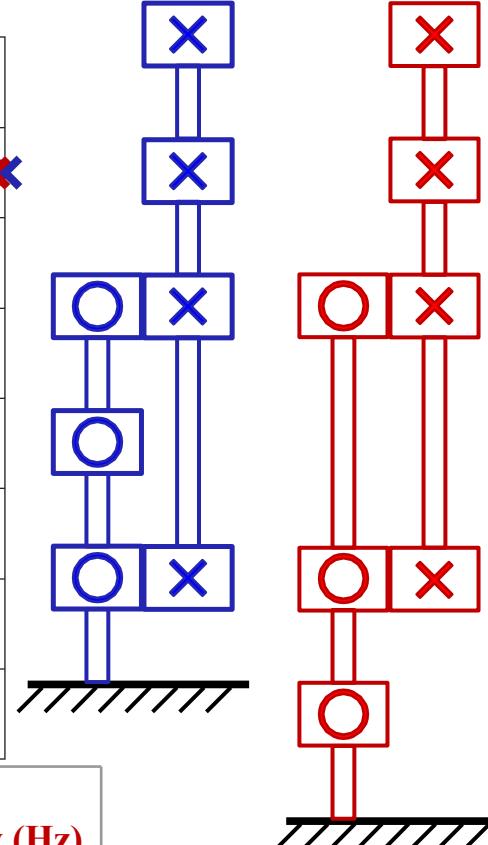
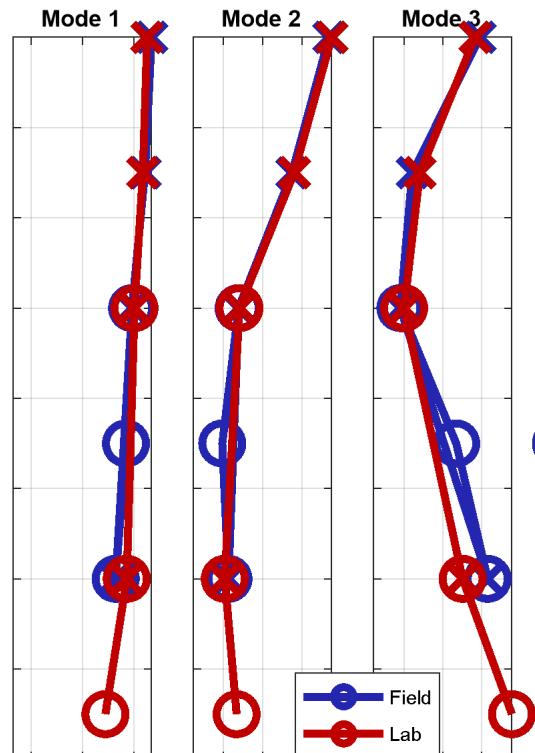
Motivation

History

Model

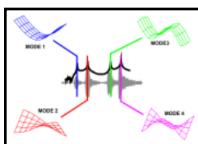
Cases

Conclusions



Mode Number	Field Natural Frequency (Hz)	Laboratory Natural Frequency (Hz)
1	13.1	10.9
2	31.3	30.9
3	56.6	54.8
4	66.5	66.9
5	72.5	74.0

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Impulse Load

Motivation

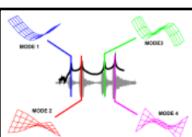
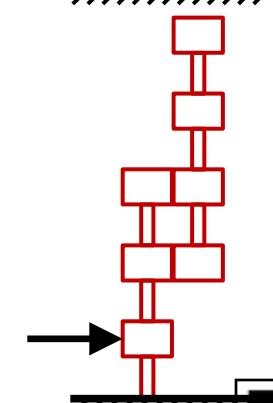
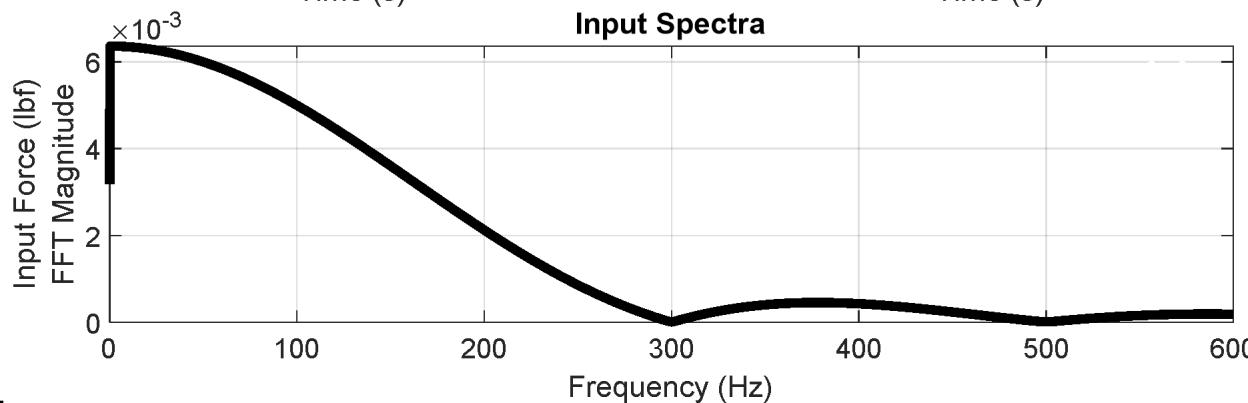
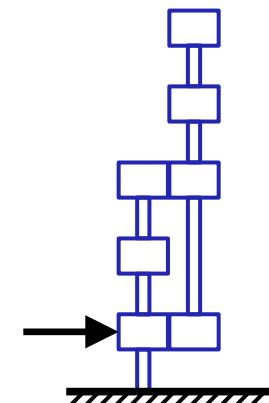
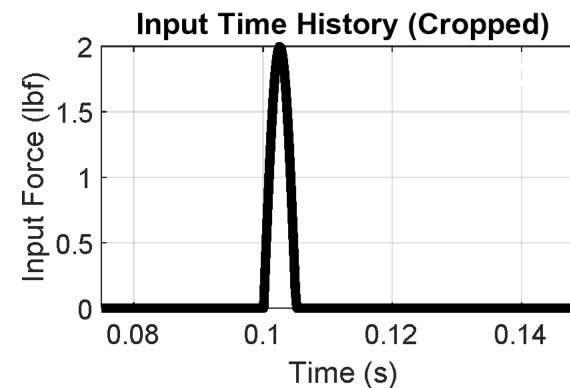
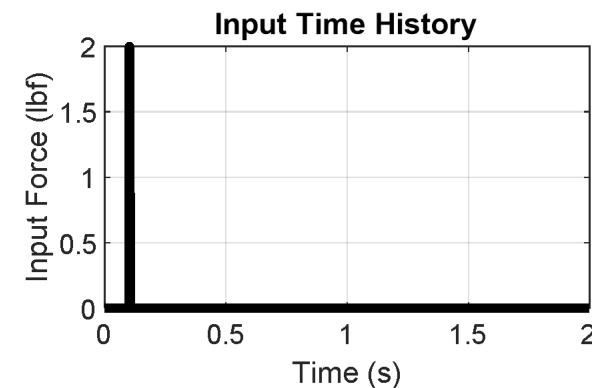
History

Model

Cases

Conclusions

Using the same load for both field and lab produces the wrong DUT response



Same Load to Field and Laboratory

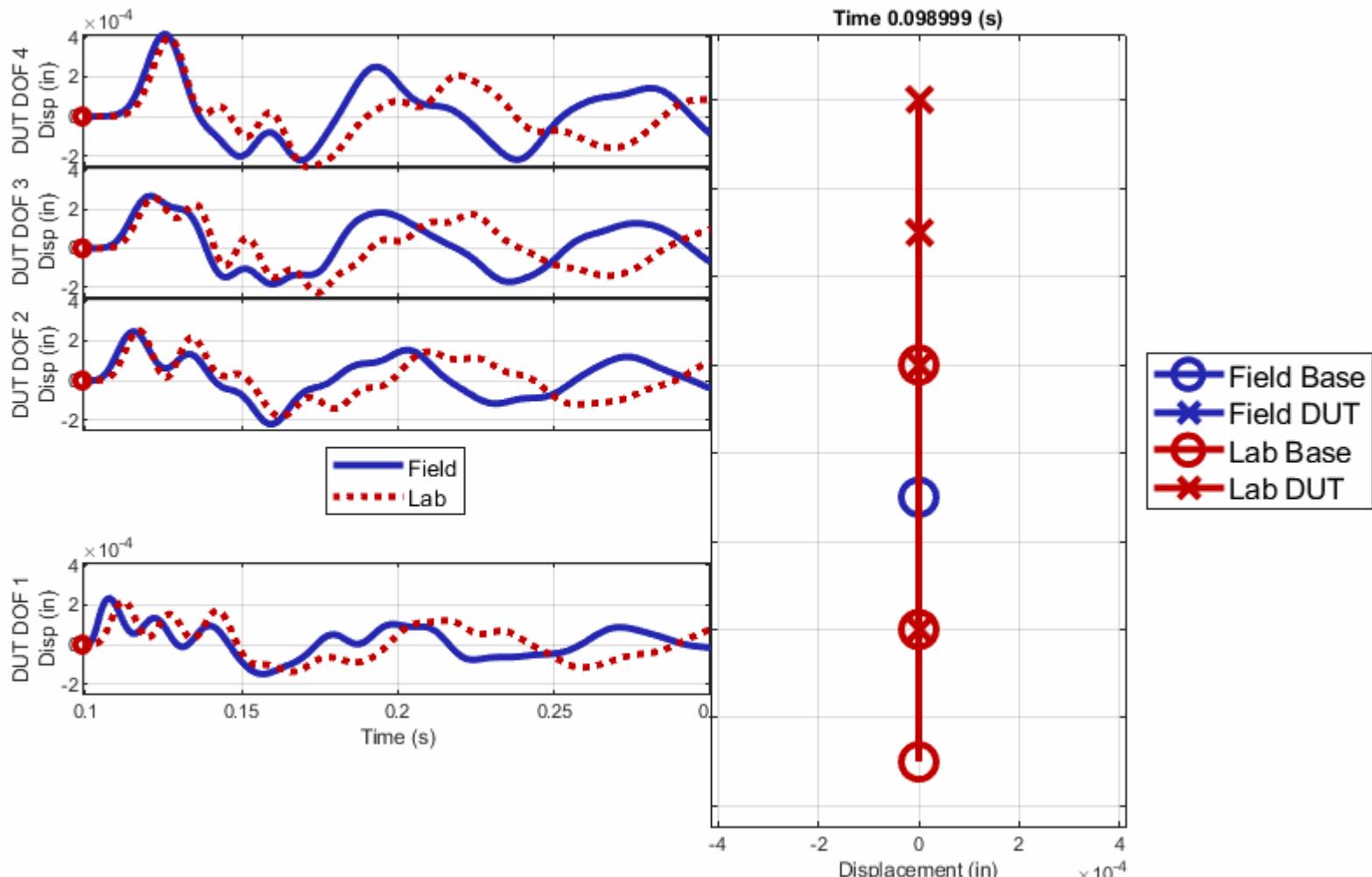
Motivation

History

Model

Cases

Conclusions



Need Modified Laboratory Loads

Motivation

History

Model

Cases

Conclusions

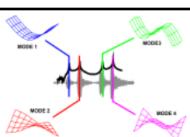
Modified forces are necessary for the DUT response to be the same in the lab as they are in the field

Doesn't matter if you use

Impedance FINE

or

Modal FINE



Impedance Based FINE

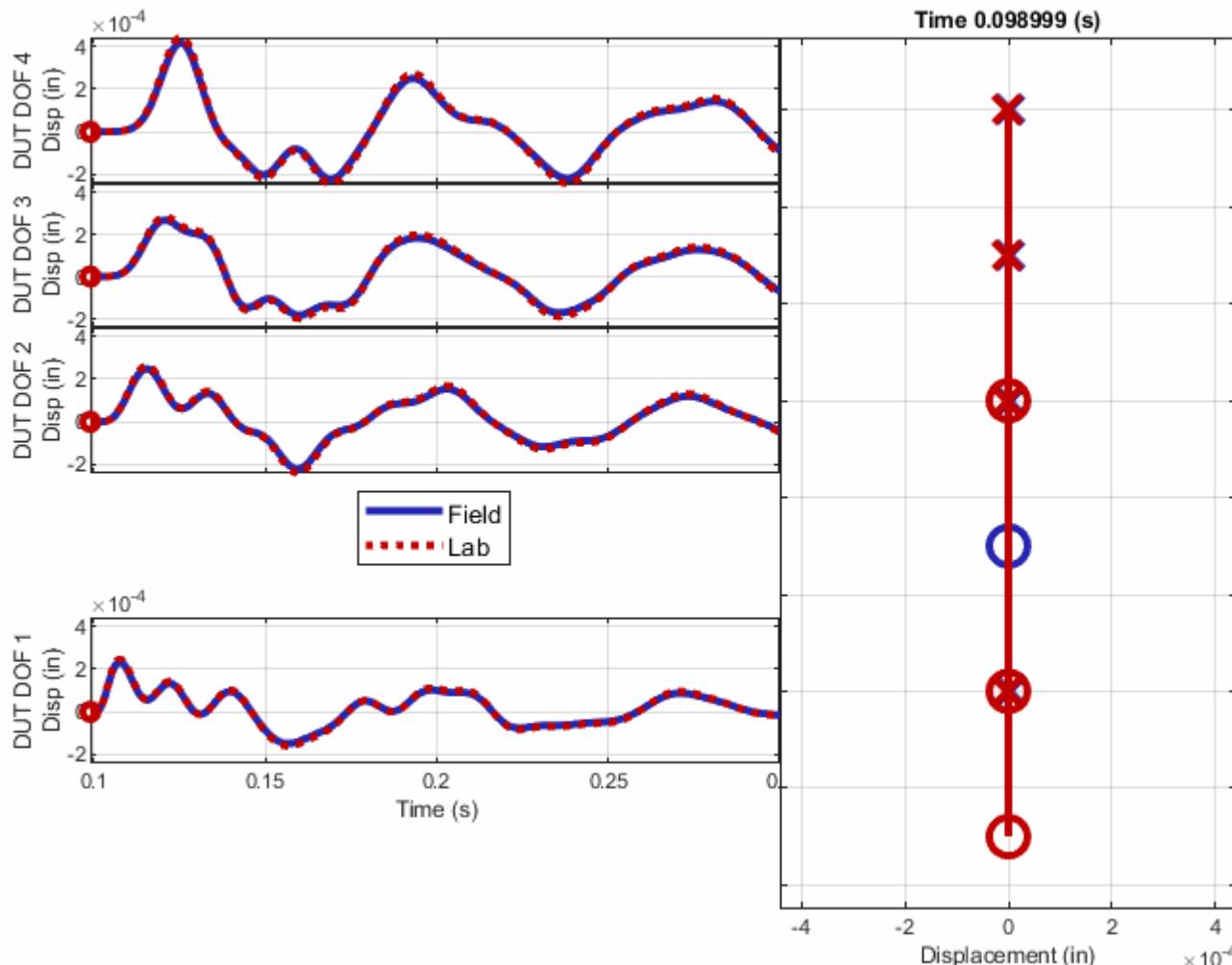
Motivation

History

Model

Cases

Conclusions



Modal Based FINE

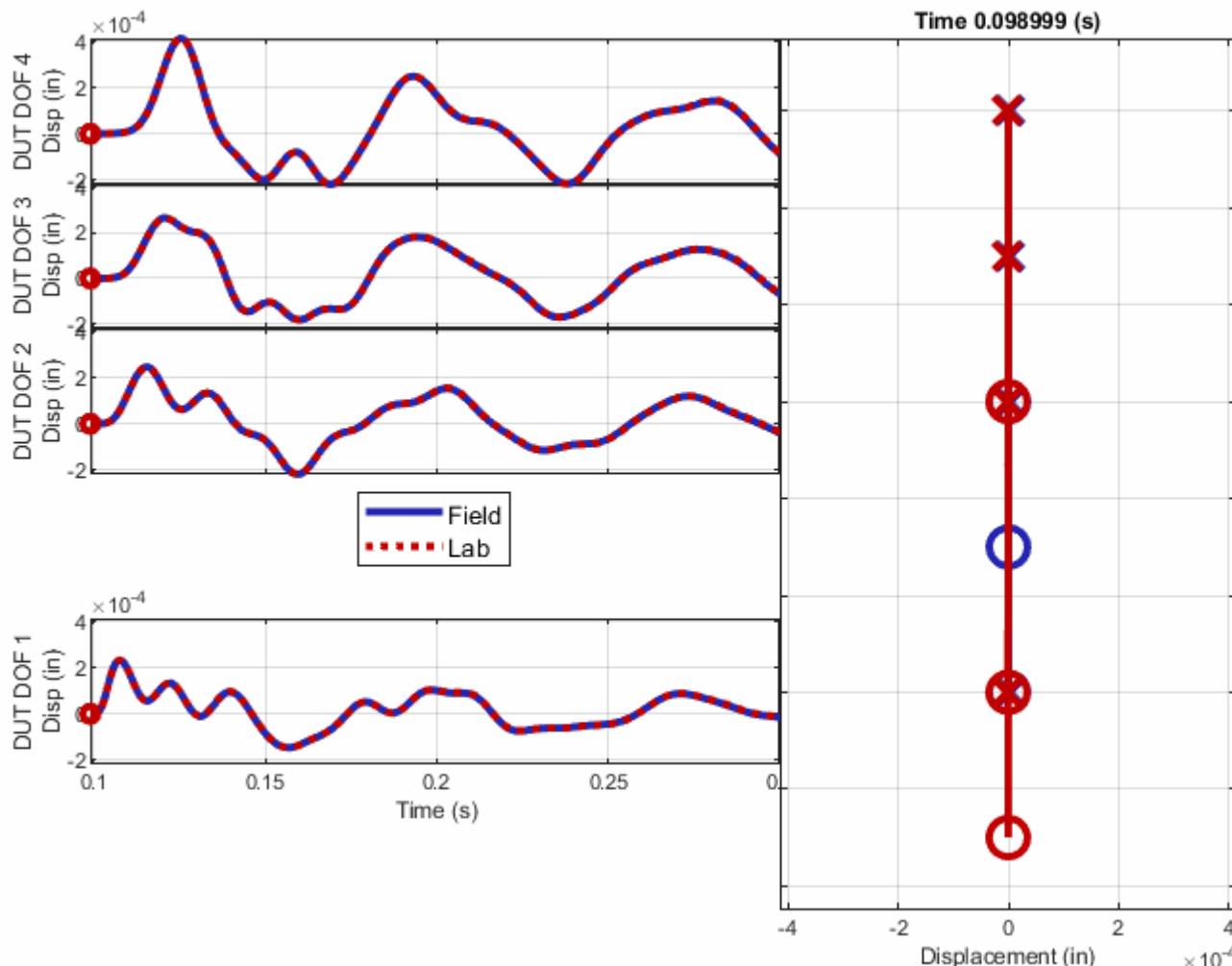
Motivation

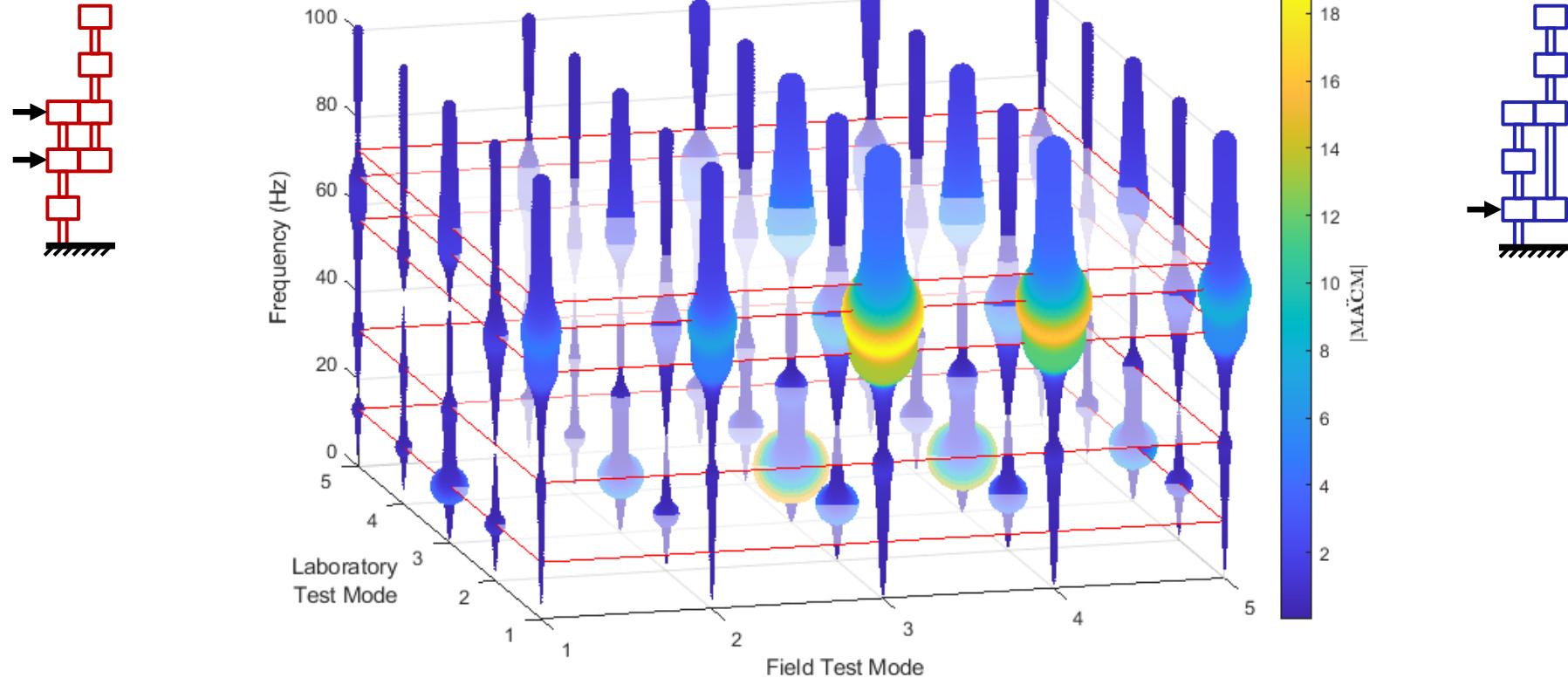
History

Model

Cases

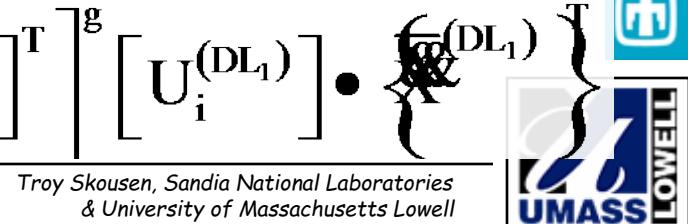
Conclusions





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Troy Skousen, Sandia National Laboratories
& University of Massachusetts Lowell

Simply Supported Beam (Field Example)

Motivation

History

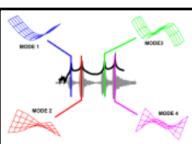
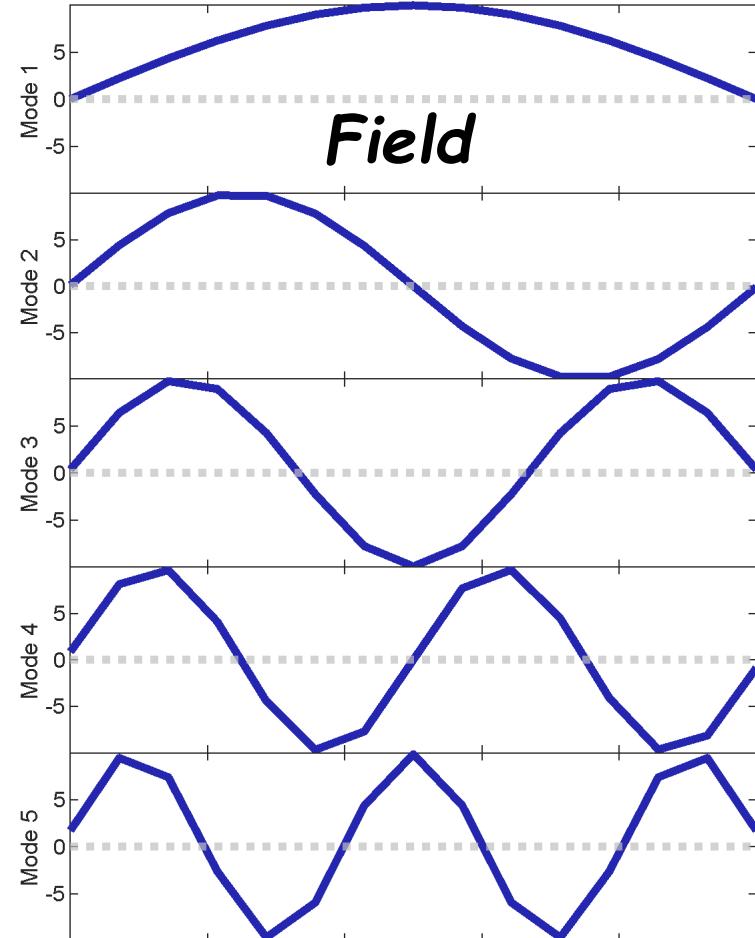
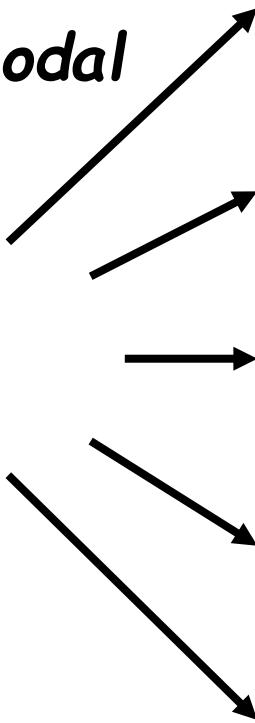
Model

Cases

Conclusions

*Simply supported beam
motion = linear
combination of modal
motion*

$$\mathbf{x} = \mathbf{U} \mathbf{\tilde{x}}$$



Free - Free Beam (Lab Example)

Motivation

History

Model

Cases

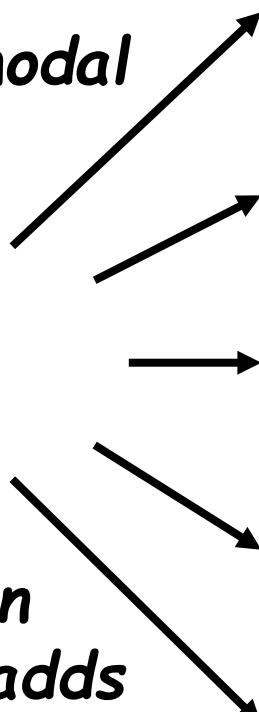
Conclusions

*Free - free beam
motion = linear
combination of modal
motion*

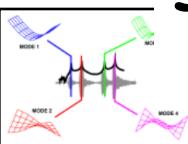
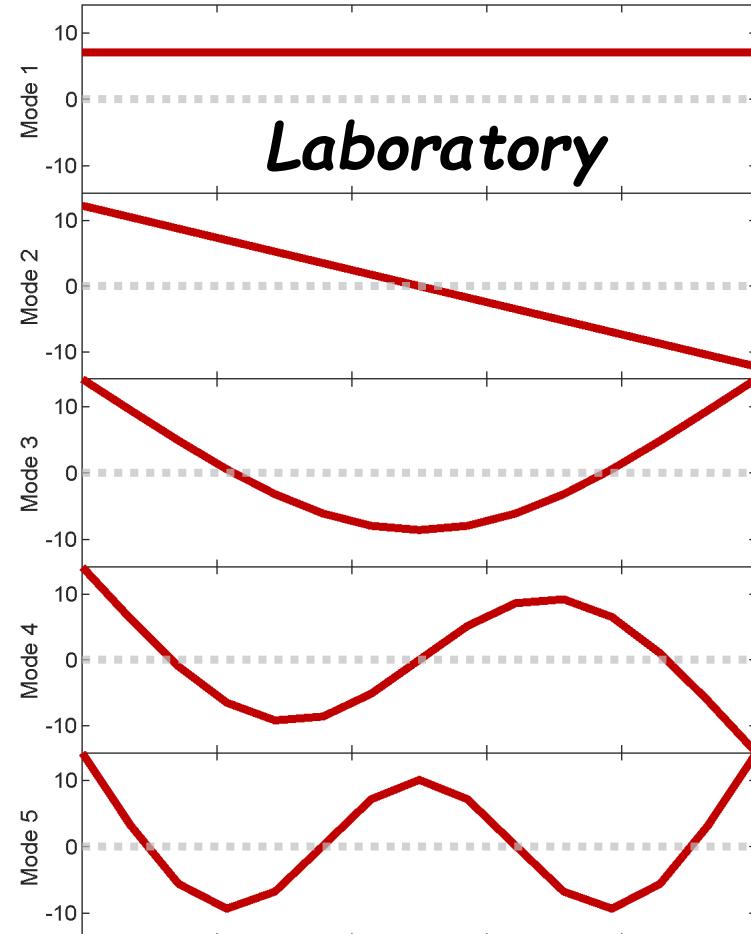
$$\mathbf{X} = \mathbf{U}\mathbf{\bar{X}}$$



Free - Free Beam



*What combination
of these modes adds
up to each of the simply
supported beam modes?*



Simply Supported Beam Mode 1 from Free - Free

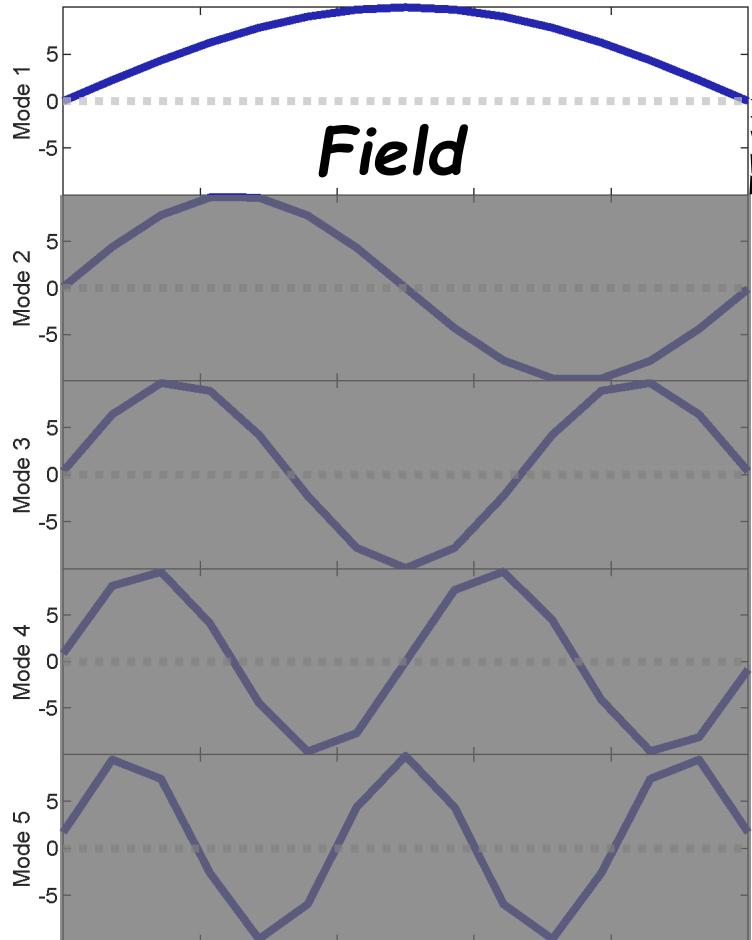
Motivation

History

Model

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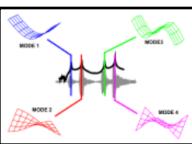
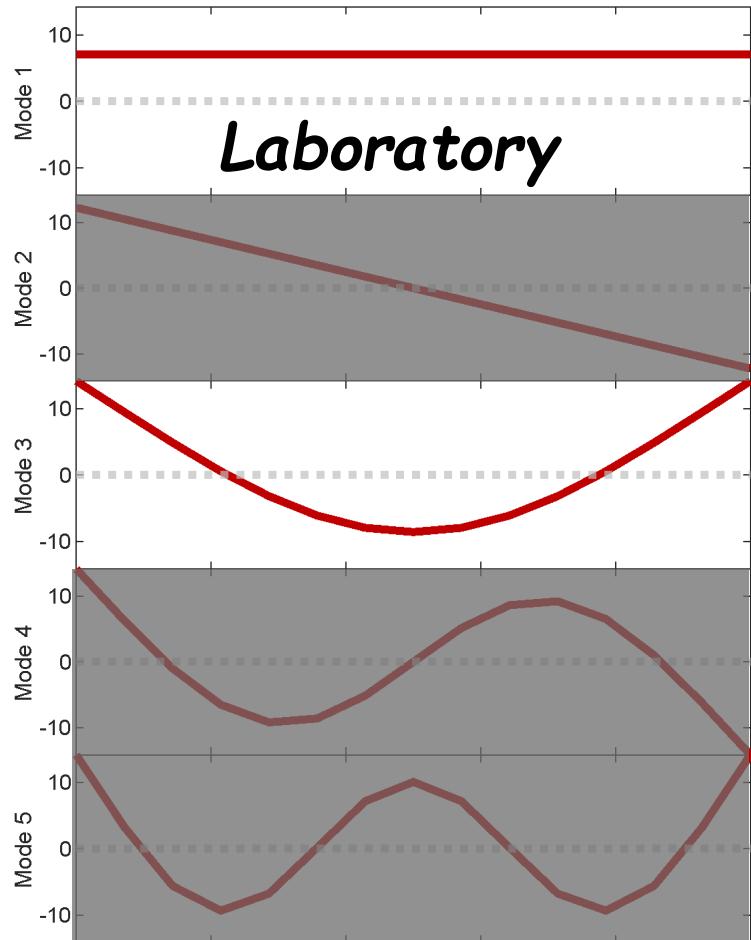
0.89

0.00

-0.45

0.00

-0.03



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Simply Supported Beam Mode 2 from Free - Free

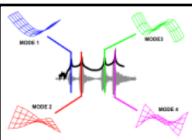
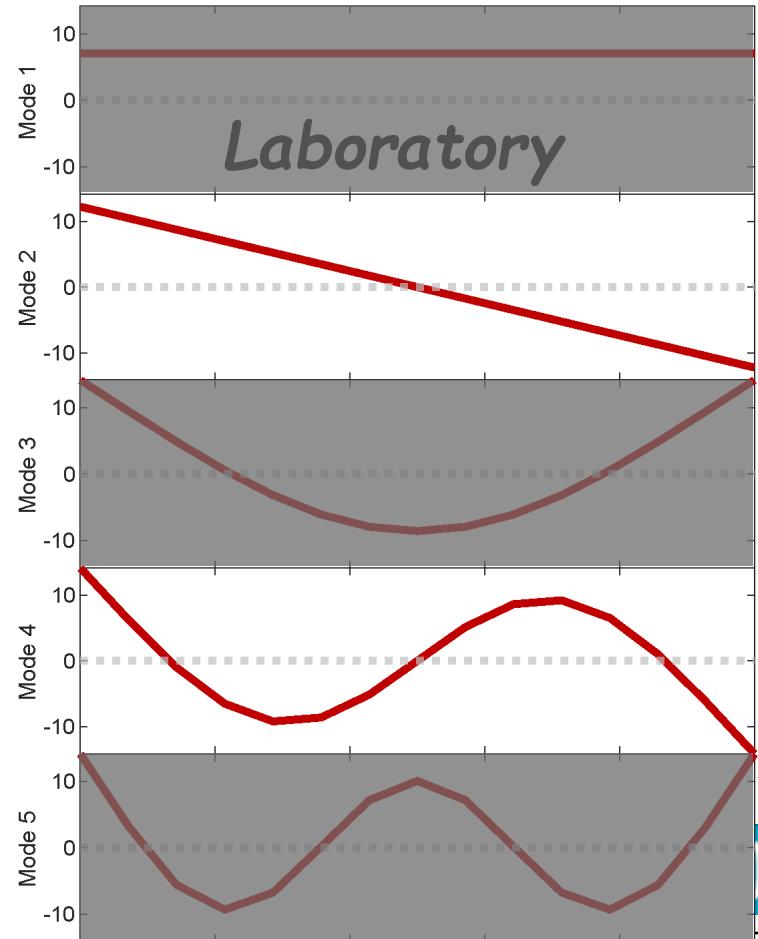
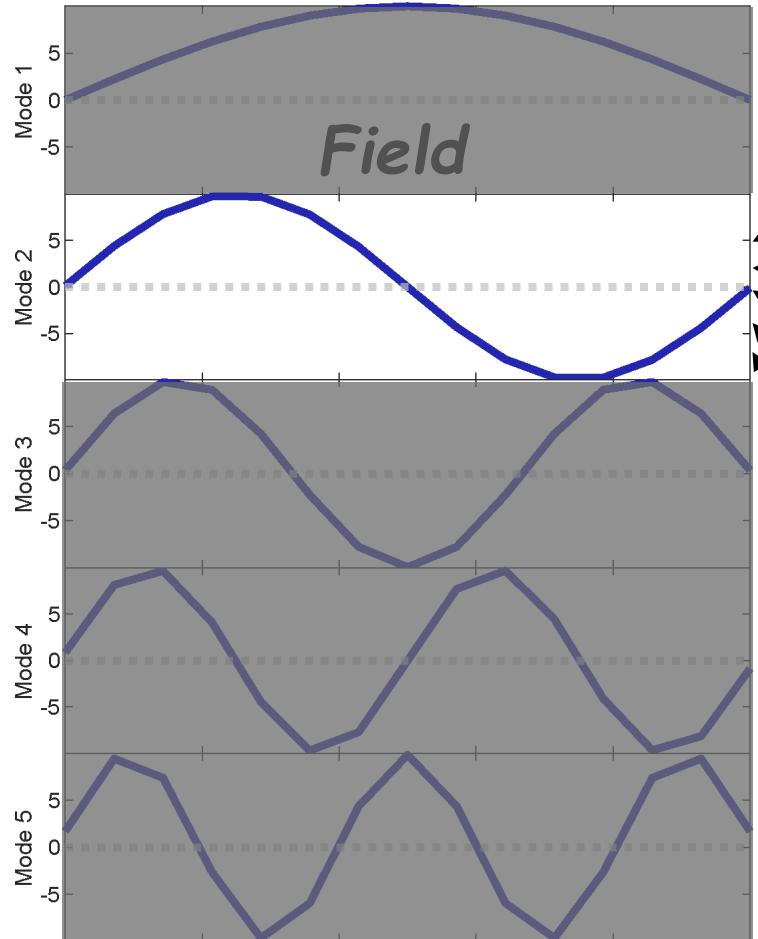
Motivation

History

Model

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Conclusions



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MACM Provides More Information

Mode mixing found in U_{12} transformation matrix

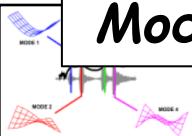
$$U_{12} = U_1^g U_2$$

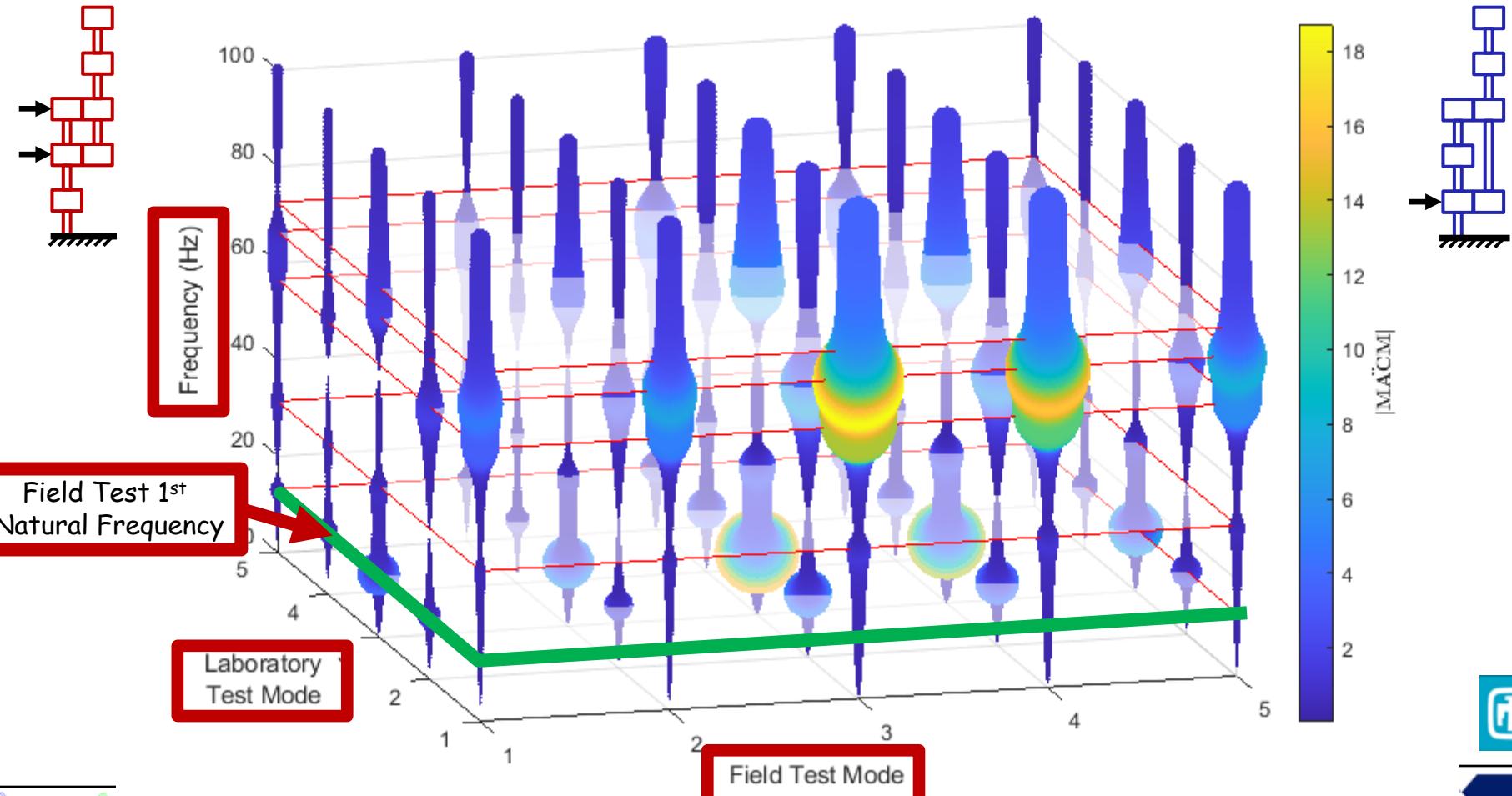
MACM

- *Field modal response*
- *Laboratory mode mixing for each Field Mode*
- *By frequency*

$$\left[\begin{bmatrix} \bar{\mathbf{x}}^{(DL_2)} \\ \bar{\mathbf{H}}^{(DL_2)} \end{bmatrix} \left[U_j^{(DL_2)} \right]^T \left[U_i^{(DL_2)} \right] \begin{bmatrix} \bar{\mathbf{x}}^{(DL_2)} \\ \bar{\mathbf{H}}^{(DL_2)} \end{bmatrix} \left[U_j^{(DL_2)} \right]^T \right]^g \left[U_i^{(DL_1)} \right] \bullet \left. \begin{bmatrix} \bar{\mathbf{x}}^{(DL_1)} \\ \bar{\mathbf{H}}^{(DL_1)} \end{bmatrix} \right\}$$

Lab: Separated Modal Response





Focus on MACM for 3rd Field Test Mode

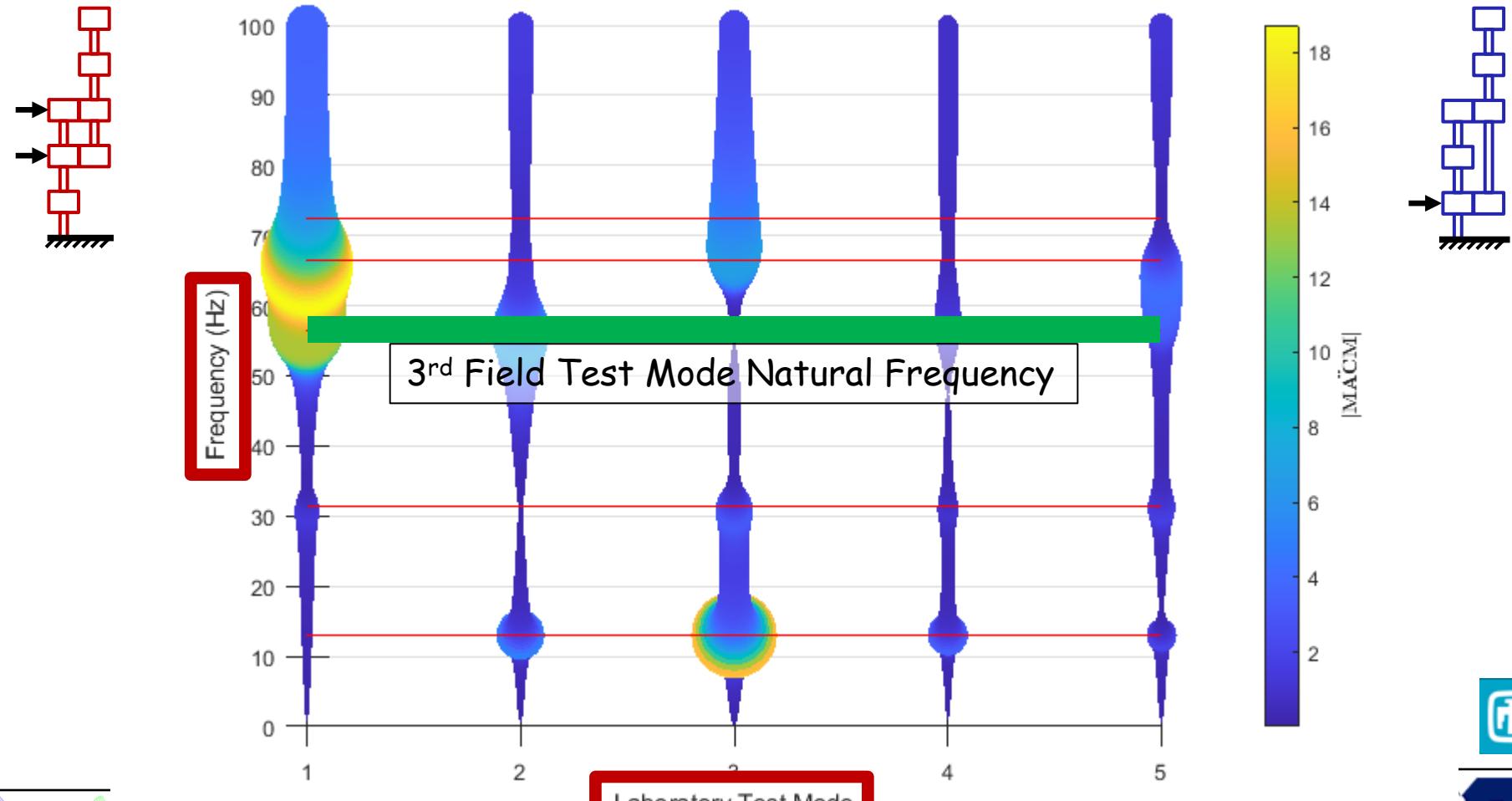
Motivation

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Top Down View of MACM

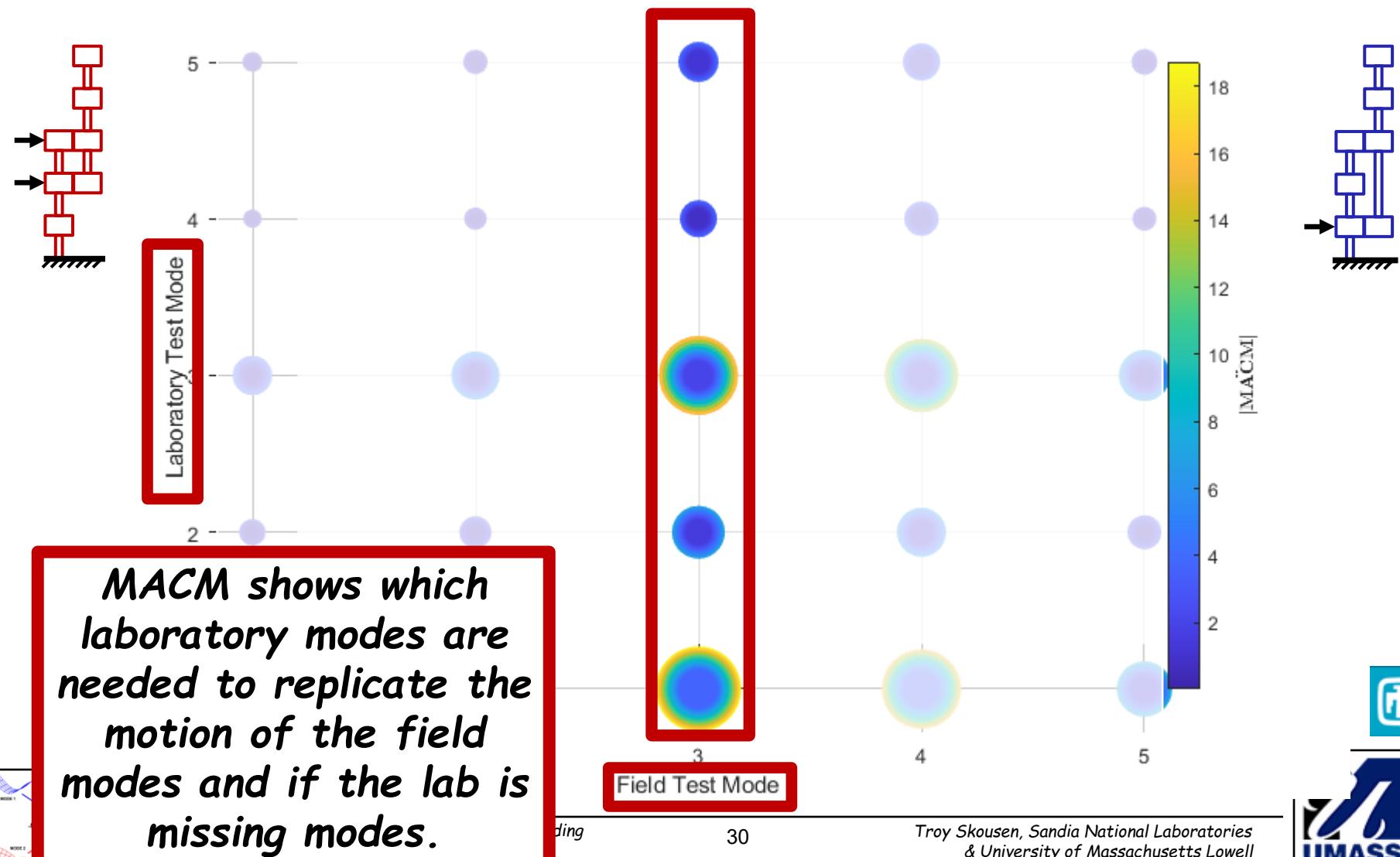
Motivation

History

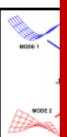
Model

Cases

Conclusions



MACM shows which laboratory modes are needed to replicate the motion of the field modes and if the lab is missing modes.



Observations and Future Direction

Motivation

History

Model

Cases

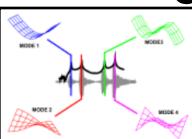
Conclusions

*When the boundary condition changes,
(i.e., field to lab) new inputs required
to obtain proper field response in the lab*

*Impedance and Modal Fixture Neutralization
methods can generate new inputs to cause
response to match*

*Modal/MACM information shows if needed modes
are missing in the lab*

*Developing a method that blends the capabilities
and information from the two FINE techniques*



Summary

Motivation

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Model

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Conclusions

Brief history of qualification testing discussed

Impedance and Modal FINE models presented

Viable path to address field to lab differences

