

Canonical and Noncanonical Hamiltonian Model Reduction through Benchmark Examples

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Hamiltonian Systems

- Archetype for conservative systems: $\dot{\mathbf{x}} = \{\mathbf{x}, H\} = \mathbf{L}\nabla H$.
 - Governed by scalar potential function H and SS matrix \mathbf{L} .
- \mathbf{L} defines (potentially degenerate) Poisson bracket $\{F, G\} = \nabla F \cdot \mathbf{L}\nabla G$.
 - Satisfies Jacobi identity $\{F, \{G, H\}\} + \{G, \{H, F\}\} + \{H, \{F, G\}\} = 0$.
- Guarantees that flow is $\perp \nabla H$ and energy is conserved:

$$\dot{H}(\mathbf{x}) = \dot{\mathbf{x}} \cdot \nabla H = \mathbf{L}\nabla H \cdot \nabla H = -\mathbf{L}\nabla H \cdot \nabla H = 0.$$

Examples of Hamiltonian systems

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- Undamped simple harmonic oscillator: $m\ddot{x} = -kx$

$$H = \frac{1}{2m} (p^2 + q^2) \quad \mathbf{L} = \mathbf{J} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

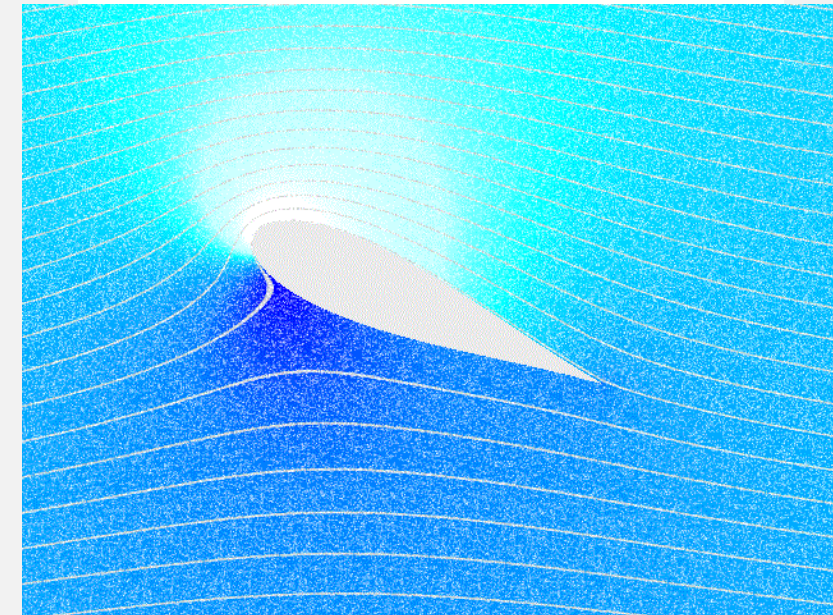
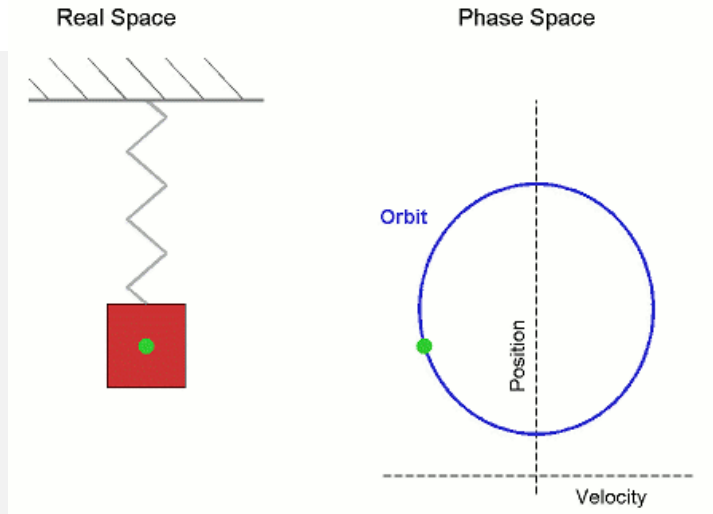
$$p = m\dot{x}, \quad q = m\sqrt{\frac{k}{m}}x$$

- Incompressible Euler: $\dot{\omega} = \omega \cdot \nabla \mathbf{u} - \mathbf{u} \cdot \nabla \omega$

$$H = \frac{1}{2} \int |\mathbf{u}|^2 dx. \quad L(\omega) = (\omega \cdot \nabla - \nabla \omega) \nabla \times$$

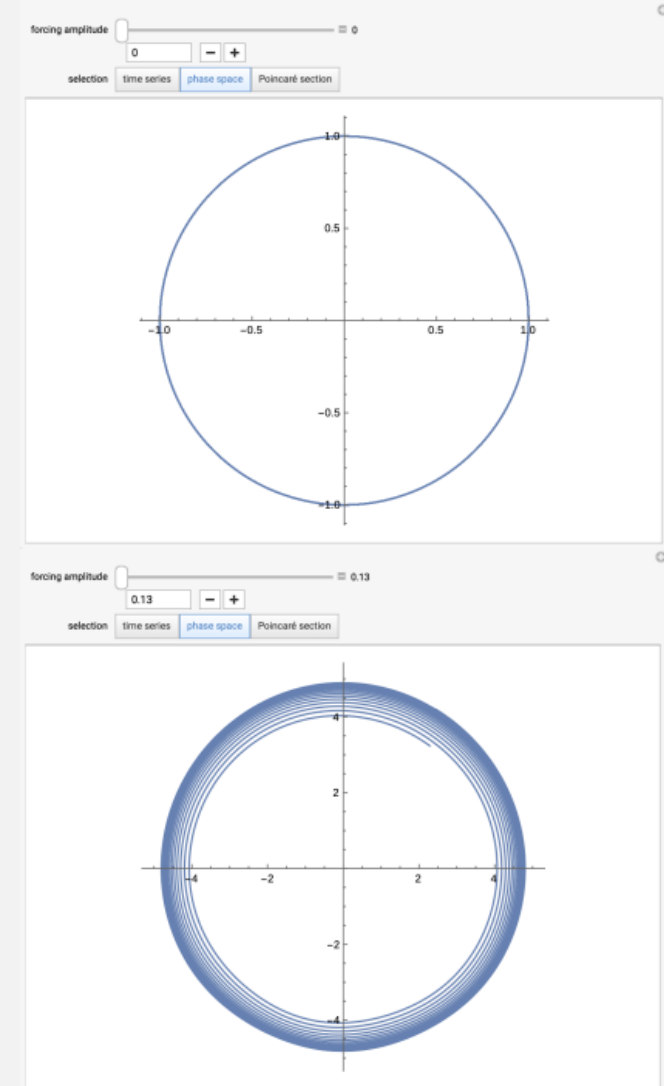
- Warning! Vorticity is the Hamiltonian variable!

$$\omega = \nabla \times \mathbf{u}$$



Why do we like Hamiltonian systems?

- Dynamics governed by *one* function.
 - Generally chaotic but controlled. Phase space volume doesn't change.
 - KAM theorem: “small” perturbations of integrable system yield “small” changes in periodicity.
- Connection with geodesics on Riemannian manifolds.
 - Optimal transport



Proper Orthogonal Decomposition

- Suppose $\dot{\mathbf{x}} = \mathbf{A}\mathbf{x} + \mathbf{f}(\mathbf{x})$ for $\mathbf{x} \in \mathbb{R}^N$ large.
- Do PCA on solution snapshots $\mathbf{X} = \mathbf{x}(t_j, \boldsymbol{\mu}_j)$, $1 \leq j \leq N_t$.
 - Yields $\mathbf{X} \approx \mathbf{U}\boldsymbol{\Sigma}\mathbf{V}^\top$, Galerkin projection $\tilde{\mathbf{x}} = \mathbf{U}\hat{\mathbf{x}}$.
- Orthogonality of POD basis \mathbf{U} implies, for $\hat{\mathbf{x}} \in \mathbb{R}^n$, $\hat{f} = f \circ \tilde{\mathbf{x}}$,
$$\dot{\hat{\mathbf{x}}} = \mathbf{U}^\top \mathbf{A} \mathbf{U} \hat{\mathbf{x}} + \mathbf{U}^\top \mathbf{f}(\mathbf{U} \hat{\mathbf{x}}) := \hat{\mathbf{A}} \hat{\mathbf{x}} + \hat{\mathbf{f}}(\hat{\mathbf{x}})$$
- ODE of size N converted to ODE of size n .

1D wave equation

$$h(s) = \begin{cases} 1 - \frac{3}{2}s^2 + \frac{3}{4}s^3 & 0 \leq s \leq 1, \\ \frac{1}{4}(2-s)^3 & 1 \leq s \leq 2, \\ 0 & s > 2. \end{cases}$$

$$s(x) = 10|x - \frac{1}{2}| \quad \text{Initial condition}$$

- Want to solve $\frac{\partial^2 \varphi}{\partial t^2} = c^2 \frac{\partial^2 \varphi}{\partial x^2},$

- Recast as $q = \varphi$ and $p = \varphi_t$ $\mathcal{H}(q, p) = \int_0^\ell \left[\frac{1}{2}p^2 + \frac{1}{2}c^2 q_x^2 \right] dx,$

- Discretization yields $H_d(\mathbf{y}) = \sum_1^n \left[\frac{1}{2}p_i^2 + \frac{c^2(q_{i+1} - q_i)^2}{4\Delta x^2} + \frac{c^2(q_i - q_{i-1})^2}{4\Delta x^2} \right],$

- Assume periodic BCs

- FOM system is $\dot{\mathbf{y}} = \mathbf{J}_{2n} \nabla_{\mathbf{y}} H_d(\mathbf{y}) = \begin{bmatrix} \mathbf{0} & \mathbf{I}_n \\ -\mathbf{I}_n & \mathbf{0} \end{bmatrix} \begin{bmatrix} -c^2 \mathbf{D}_{fd} & \mathbf{0} \\ \mathbf{0} & \mathbf{I}_n \end{bmatrix} \mathbf{y} = \begin{bmatrix} \mathbf{0} & \mathbf{I}_n \\ c^2 \mathbf{D}_{fd} & \mathbf{0} \end{bmatrix} \mathbf{y},$

Is standard POD good enough?

- Naïve Galerkin projection yields

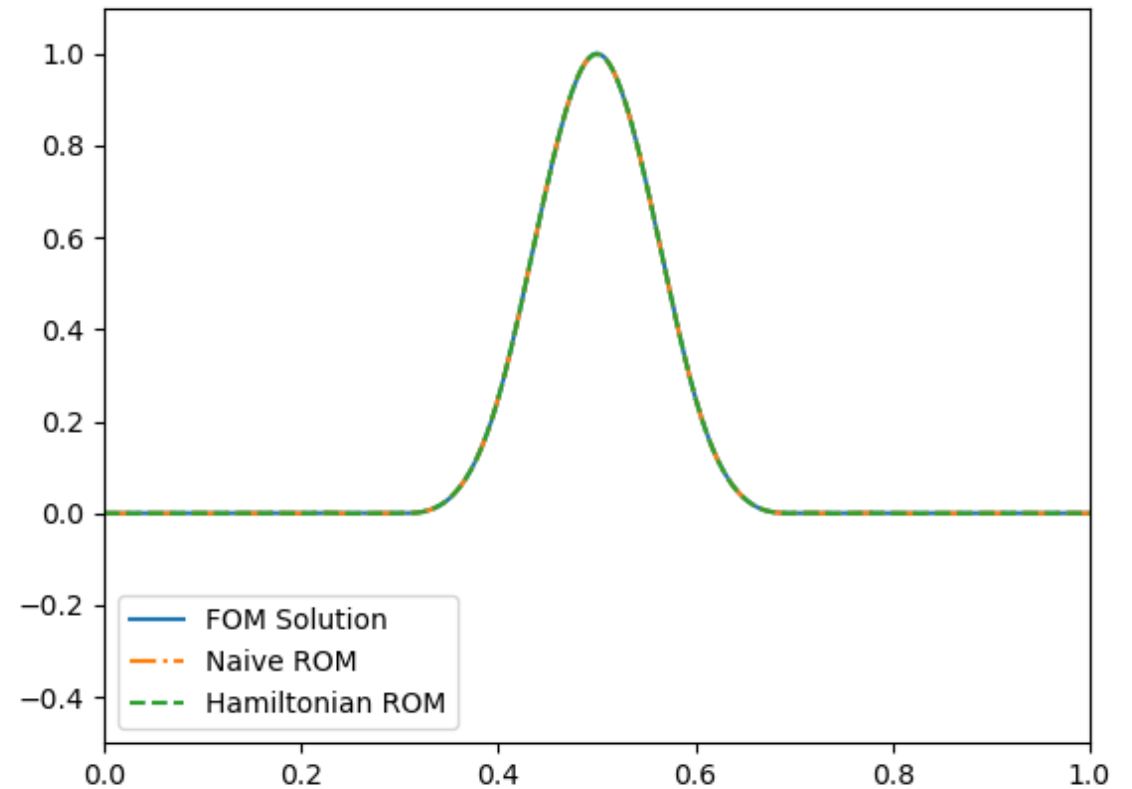
$$\dot{\hat{\mathbf{y}}} = \mathbf{U}^\top \mathbf{J}_{2n} \nabla H(\tilde{\mathbf{y}}) .$$

- NOT Hamiltonian,

$$\mathbf{U}^\top \mathbf{L} \neq -\mathbf{L}^\top \mathbf{U} .$$

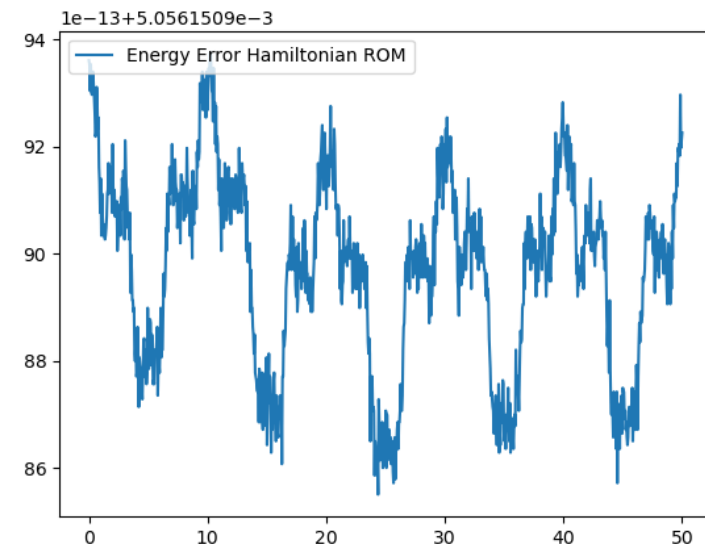
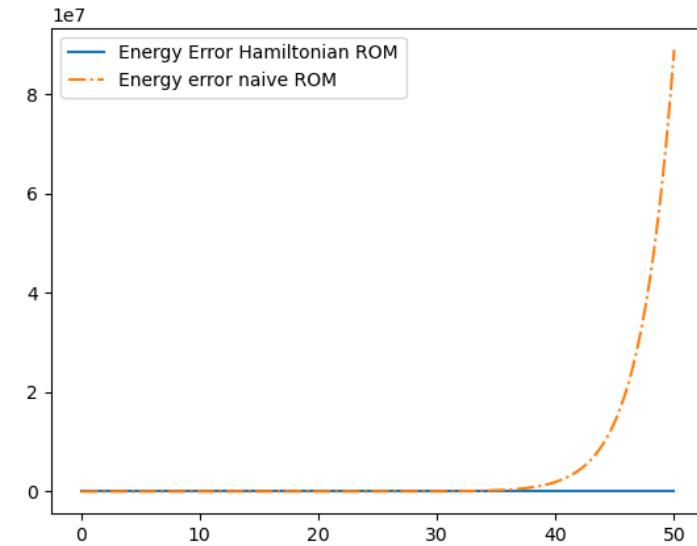
- Do we care?

- Yes, predictive behavior is poor



What happened?

- Naïve Galerkin ROM is...
 - **Not** Hamiltonian (energy not conserved).
 - **Not** symplectic (Jacobi identity violated).
- Conversely, Hamiltonian ROM satisfies both.
 - Phase space volume never changes.
- How can we get this in our ROM?



Intrusive Hamiltonian ROMs

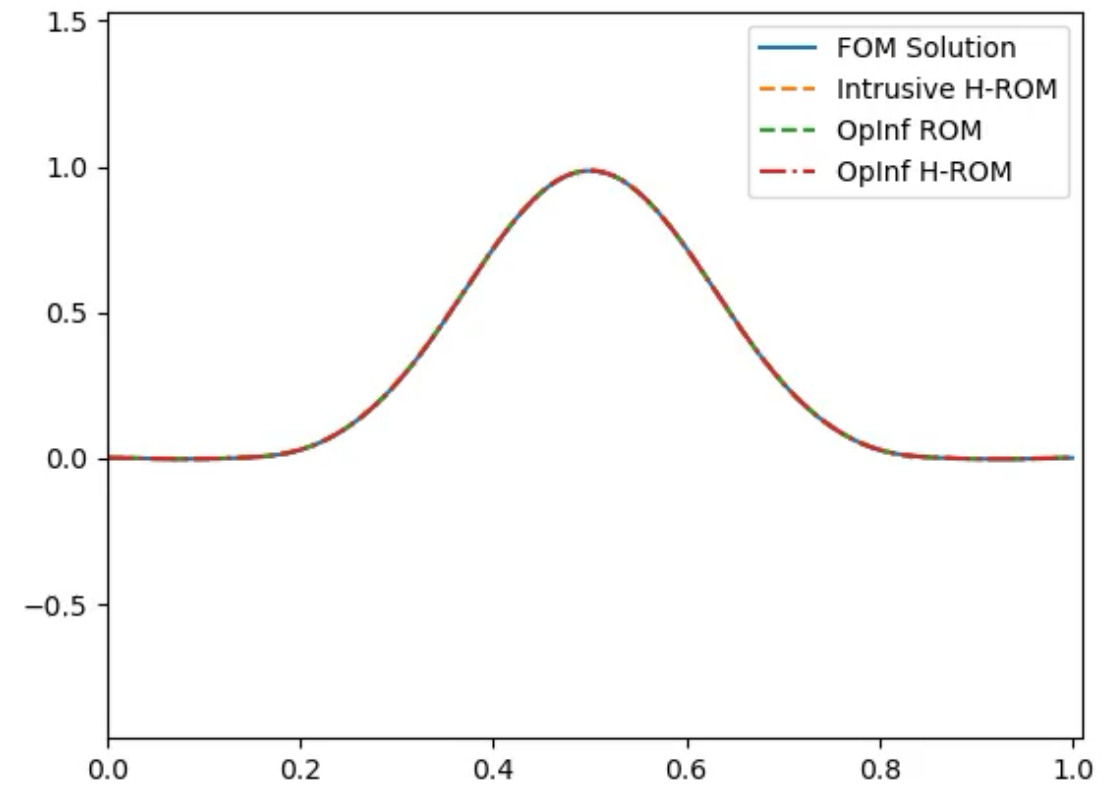
- One simple solution due to Y. Gong, Q. Wang, Z. Wang (2017):
 - Recall that $\nabla \hat{H}(\hat{\mathbf{x}}) = \tilde{\mathbf{x}}' \cdot \nabla H(\tilde{\mathbf{x}}) = \mathbf{U}^\top \nabla H(\tilde{\mathbf{x}})$.
- We want $\mathbf{U}^\top \mathbf{L} \nabla H(\tilde{\mathbf{x}}) = \hat{\mathbf{L}} \mathbf{U}^\top \nabla H(\tilde{\mathbf{x}}) = \hat{\mathbf{L}} \nabla \hat{H}(\hat{\mathbf{x}})$.
 - Implies the overdetermined system $\mathbf{U}^\top \mathbf{L} = \hat{\mathbf{L}} \mathbf{U}^\top$.
 - Solution is $\hat{\mathbf{L}} = \mathbf{U}^\top \mathbf{L} \mathbf{U}$.
- Yields low-dim Hamiltonian system $\dot{\hat{\mathbf{x}}} = \hat{\mathbf{L}}(\tilde{\mathbf{x}}) \nabla \hat{H}(\hat{\mathbf{x}})$.

Nonintrusive Hamiltonian ROMs

- What happens if no access to FOM code? *Operator inference*.
- Partial solution for canonical systems (Sharma, Kramer, Wang 2022):
 - Postulate a reduced Hamiltonian $\hat{H}(\hat{\mathbf{q}}, \hat{\mathbf{p}}) = \hat{\mathbf{q}}^\top \hat{\mathbf{A}}_{qq} \hat{\mathbf{q}} + \hat{\mathbf{p}}^\top \hat{\mathbf{A}}_{pp} \hat{\mathbf{p}}$.
 - Dynamical system becomes $\begin{pmatrix} \dot{\hat{\mathbf{q}}} \\ \dot{\hat{\mathbf{p}}} \end{pmatrix} = \begin{pmatrix} 0 & \mathbf{I} \\ -\mathbf{I} & 0 \end{pmatrix} \begin{pmatrix} \hat{\mathbf{A}}_{qq} & \mathbf{0} \\ \mathbf{0} & \hat{\mathbf{A}}_{pp} \end{pmatrix} \begin{pmatrix} \hat{\mathbf{q}} \\ \hat{\mathbf{p}} \end{pmatrix}$.
 - Infer $\hat{\mathbf{A}}_{qq} = \operatorname{argmin}_{\hat{\mathbf{A}}=\hat{\mathbf{A}}^\top} \left| \hat{\mathbf{X}}_{p,t} + \hat{\mathbf{A}} \hat{\mathbf{X}}_q \right|^2$ $\hat{\mathbf{A}}_{pp} = \operatorname{argmin}_{\hat{\mathbf{A}}=\hat{\mathbf{A}}^\top} \left| \hat{\mathbf{X}}_{q,t} - \hat{\mathbf{A}} \hat{\mathbf{X}}_p \right|^2$

Does it work?

- Yeah! But...
 - Relies on $\mathbf{U}^\top \mathbf{J} = \mathbf{J}_r \mathbf{U}^\top$.
 - Needs a block-diagonal $\nabla \hat{H}$
- How to extend to more general systems?



Hamiltonian Operator Inference

- Recognize special case of more general OpInf procedure:
 - Can solve $\operatorname{argmin}_{\hat{\mathbf{L}} \text{ or } \hat{\mathbf{A}}} \left| \hat{\mathbf{X}}_t - \hat{\mathbf{L}} \hat{\mathbf{A}} \hat{\mathbf{X}} \right|^2$, $\hat{\mathbf{L}}^\top = -\hat{\mathbf{L}}, \hat{\mathbf{A}}^\top = \hat{\mathbf{A}}$.
- If \mathbf{L} is known, this is “*canonical*” inference!
- If ∇H is known, this is *noncanonical* inference.

KdV Equation

- Consider solving $u_t = \alpha u u_x + \rho u_x + \gamma u_{xxx}, \quad [-L, L] \times [0, T]$

- Recast as $u_t = \mathcal{D} \frac{\delta \mathcal{H}}{\delta u}, \quad \mathcal{H} = \int_0^L \left(\frac{\alpha}{6} u^3 + \frac{\rho}{2} u^2 - \frac{\nu}{2} u_x^2 \right) dx, \quad \mathcal{D} = \partial_x$

- Discretizing with periodic BCs yields

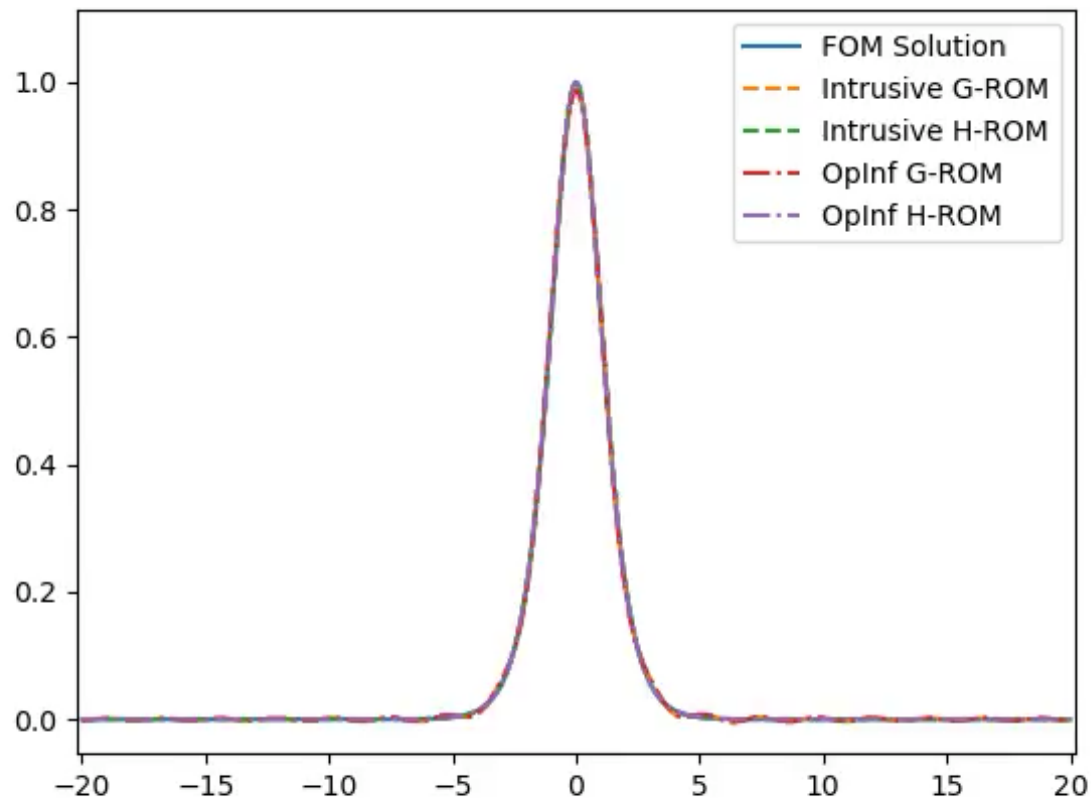
$$\mathbf{A} = \frac{1}{2\Delta x} \begin{pmatrix} 0 & 1 & 0 & 0 & \cdots & -1 \\ -1 & 0 & 1 & 0 & \cdots & 0 \\ & & \ddots & \ddots & \ddots & \\ 0 & \cdots & 0 & -1 & 0 & 1 \\ 1 & \cdots & 0 & 0 & -1 & 0 \end{pmatrix}, \quad \mathbf{B} = \frac{1}{\Delta x^2} \begin{pmatrix} -2 & 1 & 0 & 0 & \cdots & 1 \\ 1 & -2 & 1 & 0 & \cdots & 0 \\ & & \ddots & \ddots & \ddots & \\ 0 & \cdots & 0 & 1 & -2 & 1 \\ 1 & \cdots & 0 & 0 & 1 & -2 \end{pmatrix}$$

$$\begin{aligned} \frac{d\mathbf{u}}{dt} &= \mathbf{A} \nabla_{\mathbf{u}} H(\mathbf{u}) \\ &= \mathbf{A} \left(\frac{\alpha}{2} \mathbf{u}^2 + \rho \mathbf{u} + \nu \mathbf{B} \mathbf{u} \right) \end{aligned}$$

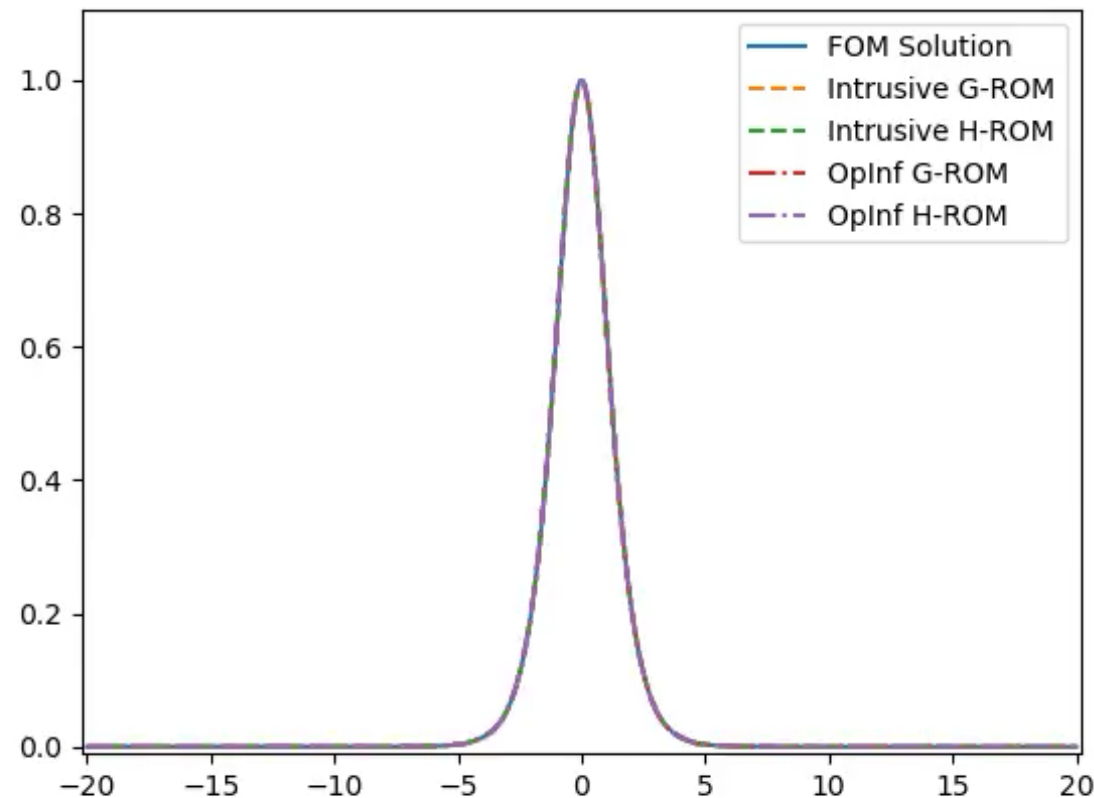
$$u_0(x) = \text{sech}^2 \left(\frac{x}{\sqrt{2}} \right)$$

- $\mathbf{A} = \mathbf{L}$ is non-canonical!

KdV Equation

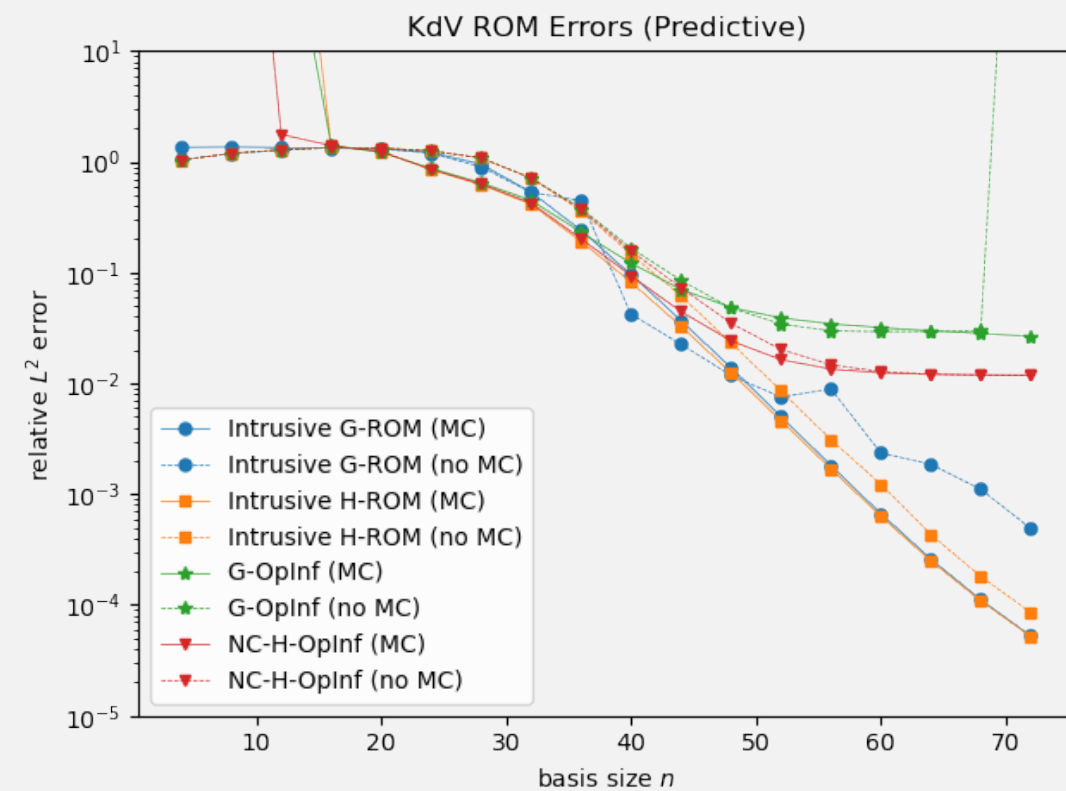
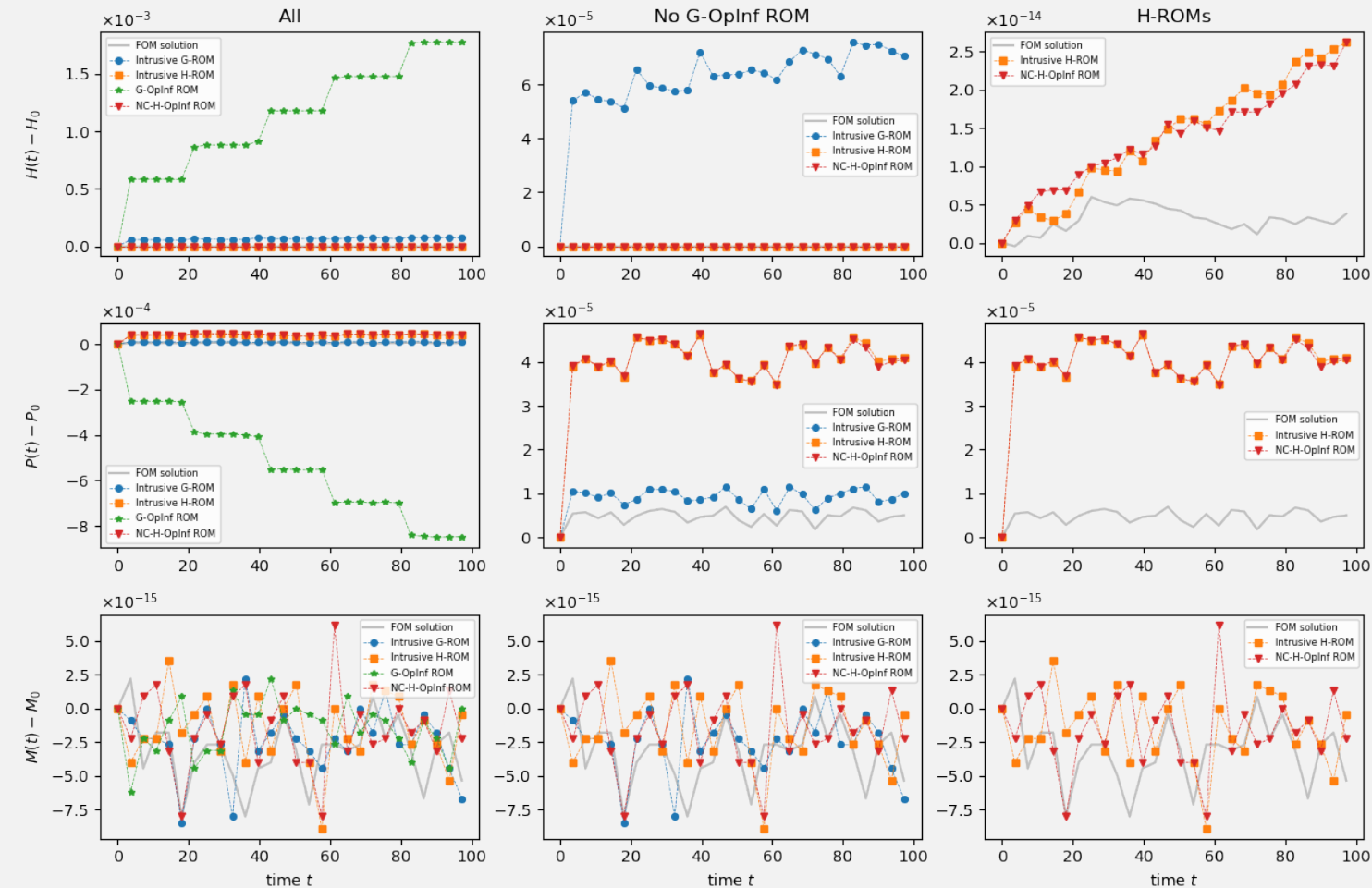


$N = 500, n=36$



$N = 500, n=48$

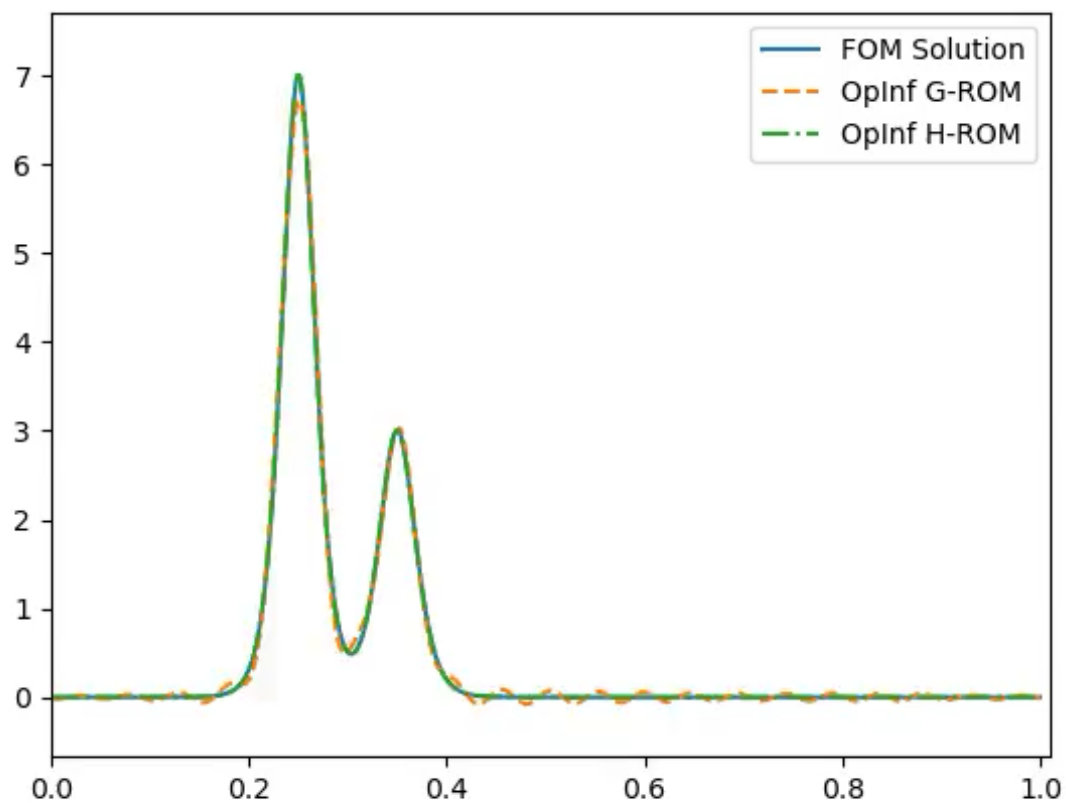
KdV Equation



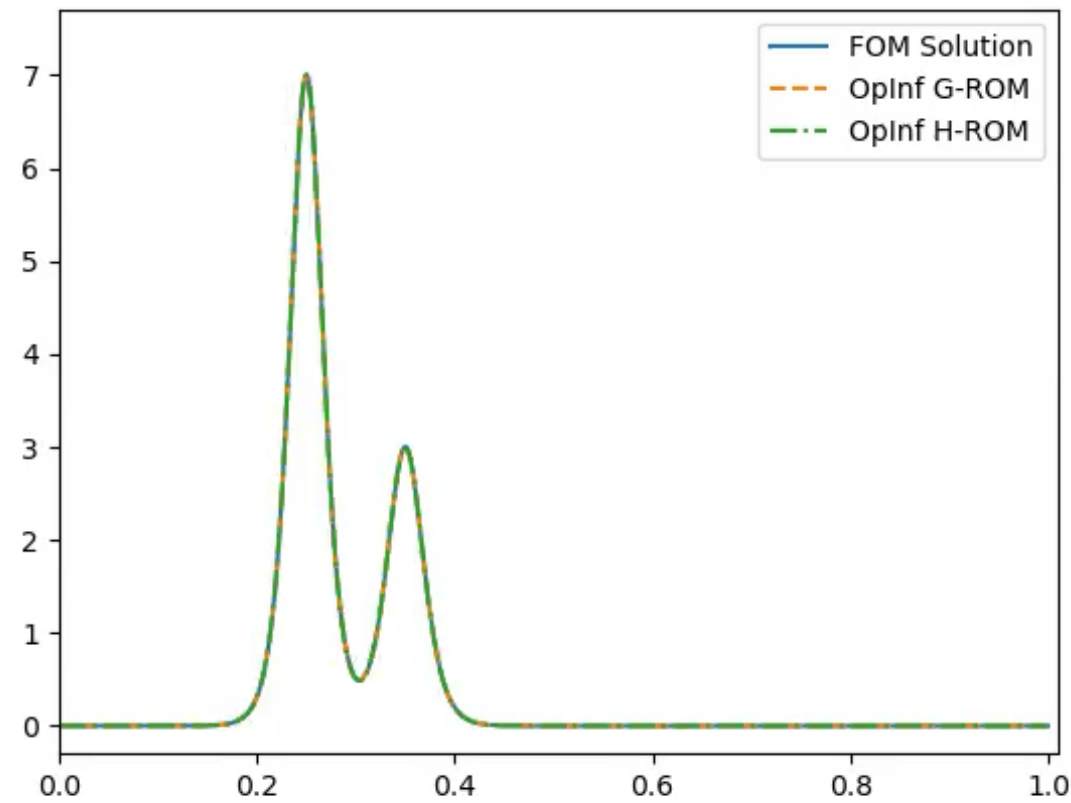
BBM Equation

- Benjamin-Bona-Mahoney equation: $\dot{x} = \alpha x_s + \beta x x_s - \gamma \dot{x}_{ss}.$
- Hamiltonian: $H(x) = \frac{1}{2} \int_0^\ell \alpha x^2 + \frac{\beta}{3} x^3 ds,$
- Poisson structure: $L = - (1 - \partial_s^2)^{-1} \partial_s,$
- Intrusive H-ROM not feasible
 - Can we still get a good OpInf H-ROM?

BBM Equation

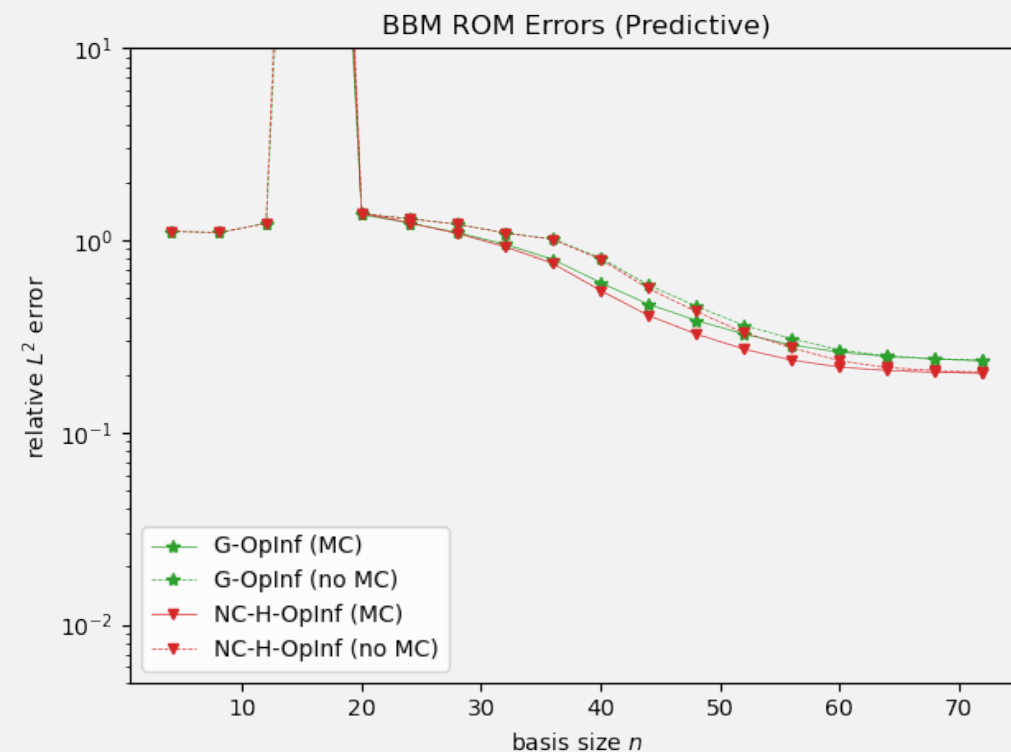
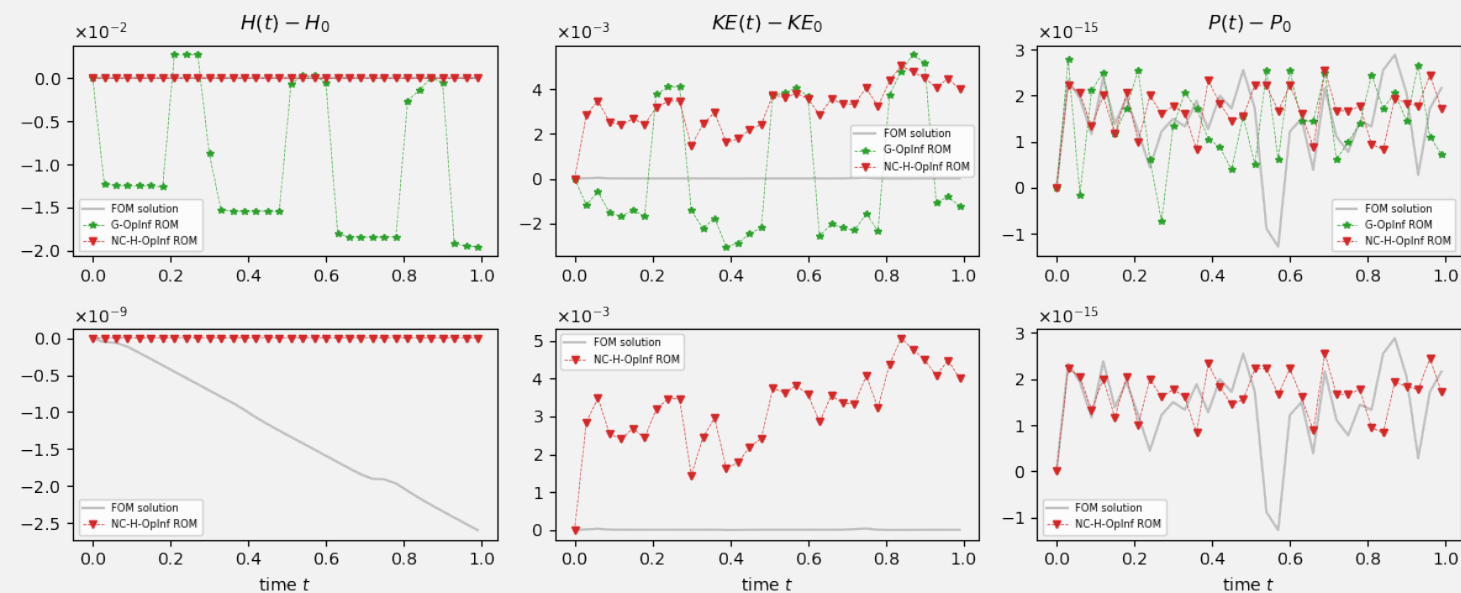


$N = 1024, n=36$



$N = 1024, n=72$

BBM Equation

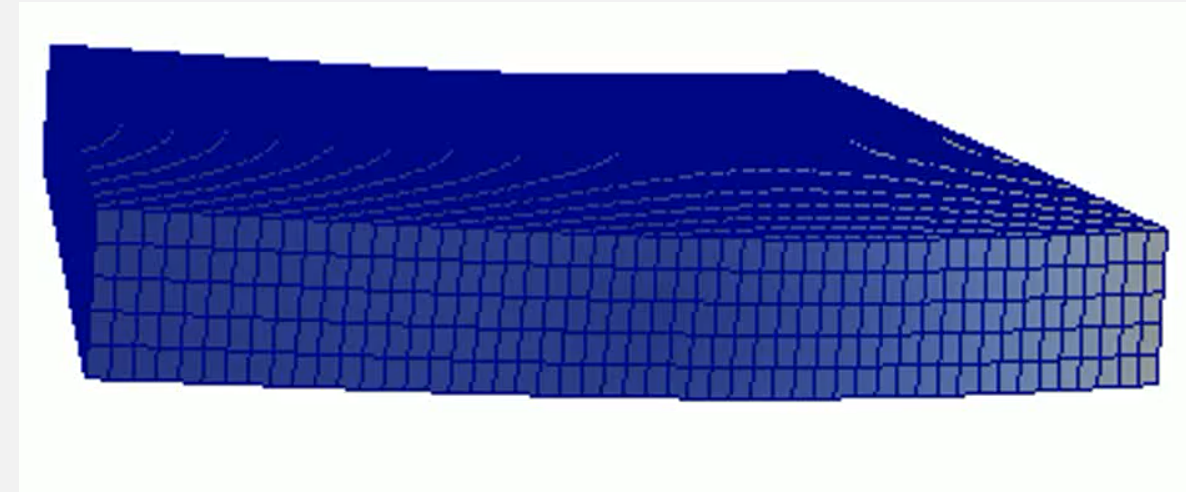


Problem solved?

- Only in simple cases.
 - Issues when scaling up...
- Consider a 3D linear elastic system:

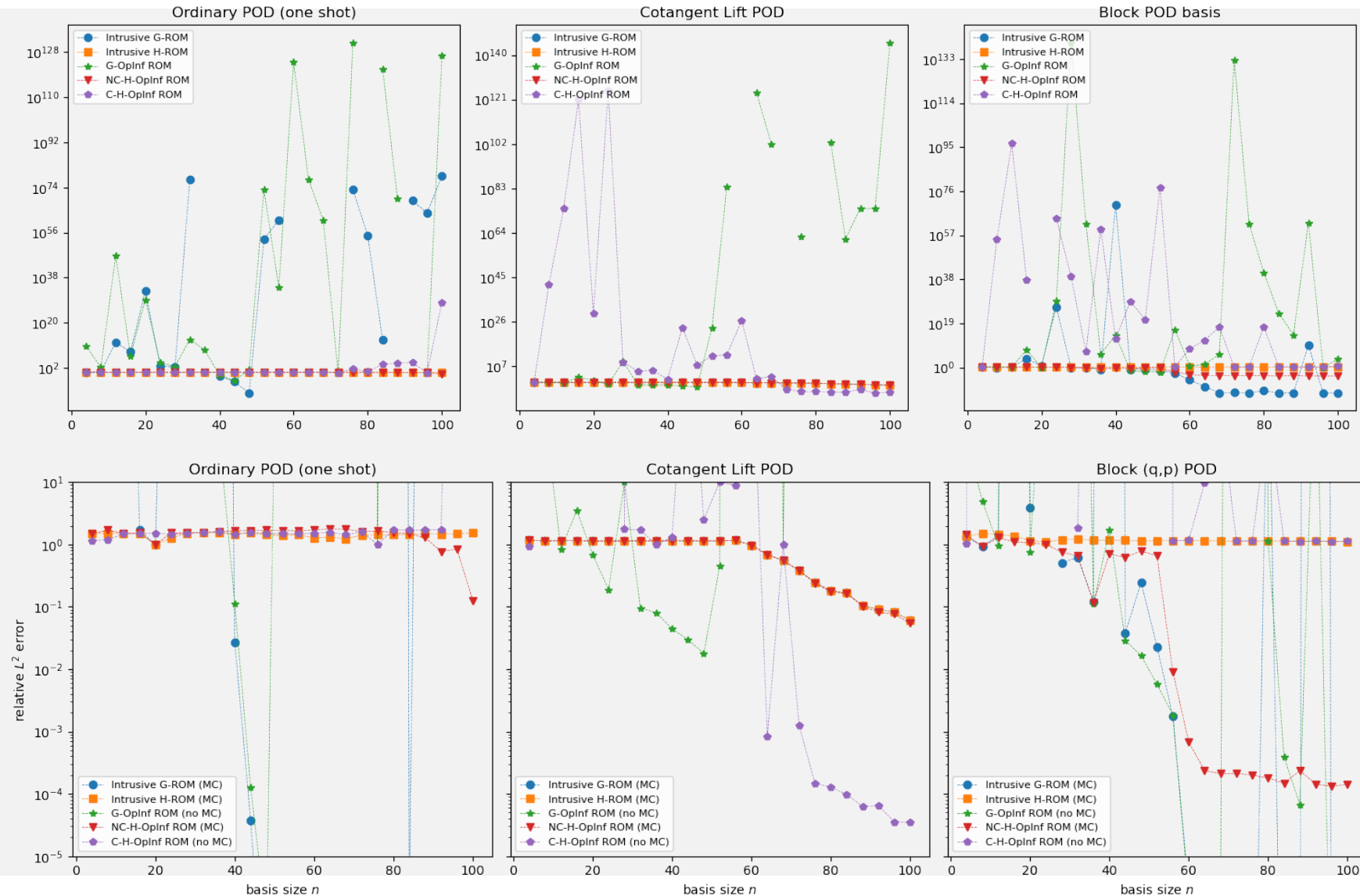
$$\mathbf{M}\ddot{\mathbf{q}} + \mathbf{K}\mathbf{q} = \mathbf{0}.$$

- Equivalent Hamiltonian form: $\dot{\mathbf{x}} = \begin{pmatrix} \dot{\mathbf{q}} \\ \dot{\mathbf{p}} \end{pmatrix} = \begin{pmatrix} \mathbf{0} & \mathbf{I} \\ -\mathbf{I} & \mathbf{0} \end{pmatrix} \begin{pmatrix} \mathbf{K} & \mathbf{0} \\ \mathbf{0} & \mathbf{M}^{-1} \end{pmatrix} \begin{pmatrix} \mathbf{q} \\ \mathbf{p} \end{pmatrix} = \mathbf{J}\mathbf{A}\mathbf{x},$



$$H(\mathbf{q}, \mathbf{p}) = \frac{1}{2} (\mathbf{q}^\top \mathbf{K} \mathbf{q} + \mathbf{p}^\top \mathbf{M}^{-1} \mathbf{p})$$

Good news and bad



Thank you!

Contact: adgrube@sandia.gov

References:

A. Gruber, M. Gunzburger, L. Ju, Z. Wang, “Energetically Consistent Model Reduction for Metriplectic Systems”, CMAME, 2023

A. Gruber, I. Tezaur, M. Gunzburger, “Canonical and Noncanonical Hamiltonian Operator Inference”, (coming soon!)

Codes:

<https://github.com/agrubertx/metriplectic> POD-ROM

<https://github.com/ikalash/HamiltonianOpInf>