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# OPTIMIZATION TO GENERATE EQUATIONS OF STATE FOR HYDROGEN PRODUCTION

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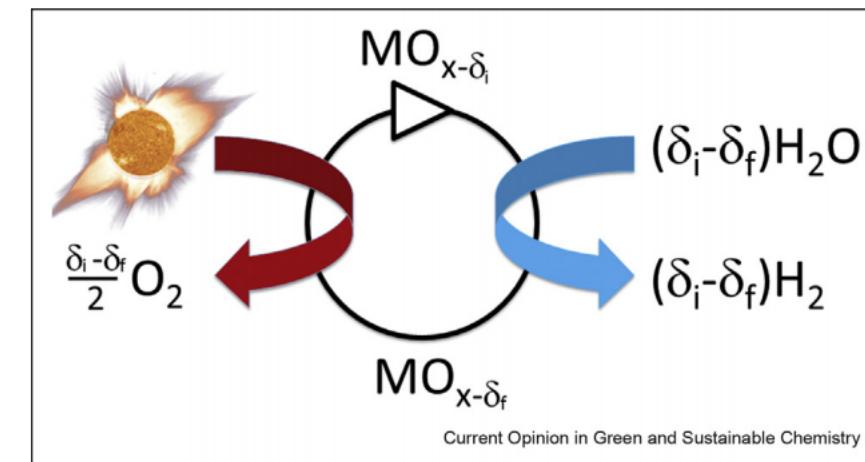
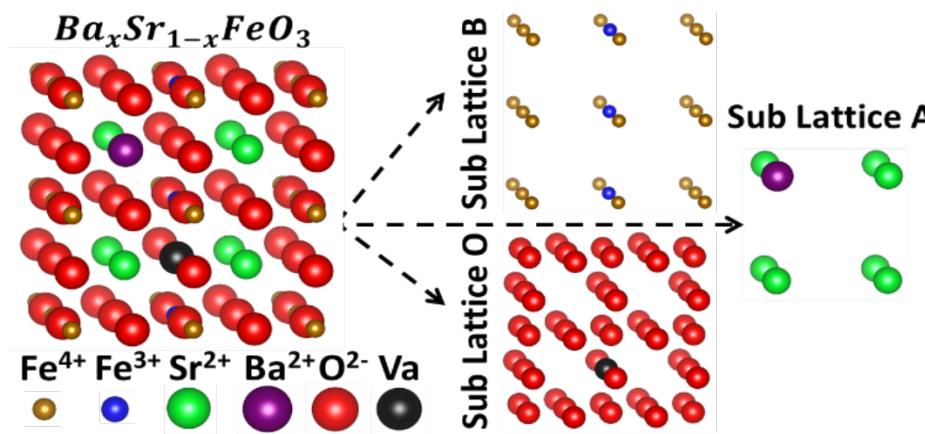


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# PROJECT OVERVIEW

# PROJECT AIM: DETERMINE CATALYSTS FOR WATER SPLITTING

- Development of software to create an equation of state (EOS) for water splitting catalysts
- Compute efficiency of process
- Perovskites are used
- Goal – to optimize catalyst configuration



Schematic of a general two-step solar powered thermochemical cycle for splitting water using nonstoichiometric metal oxides.

McDaniel, *Current Opinion in Green and Sustainable Chemistry*. 2017

## CURRENT CHALLENGES TO THE PROJECT

- Not a lot of experimental data available
- DFT formulation, experimental uncertainty
- Nonlinearities in equations
- Many solutions
- Trouble converging
- Picking the right combination of terms in formulation

Summer project focus – solving equations

## EQUATIONS – FULL PROBLEM

$$G_0^{\text{soln}} = G^{\text{endmembers}} - TS_{\text{config}}$$

Thermodynamics to fit endmembers – Gibbs free energy required to get enthalpy and entropy

$$G_0^{\text{soln}} = E_{\text{DFT}}$$

Linear equation

$$\frac{\partial G_0^{\text{soln}}(T, \delta, x)}{\partial \delta} = -\mu_O^{\text{gas,exp}}$$

Has nonlinearities, difficult to solve

See also: Wilson SA, Stechel EB, Muhich CL. 2023. Overcoming significant challenges in extracting off-stoichiometric thermodynamics using the compound energy formalism through complementary use of experimental and first principles data: A case study of  $\text{Ba}_{1-x}\text{Sr}_x\text{FeO}_{3-\delta}$ . Solid State Ionics. Vol. 390.

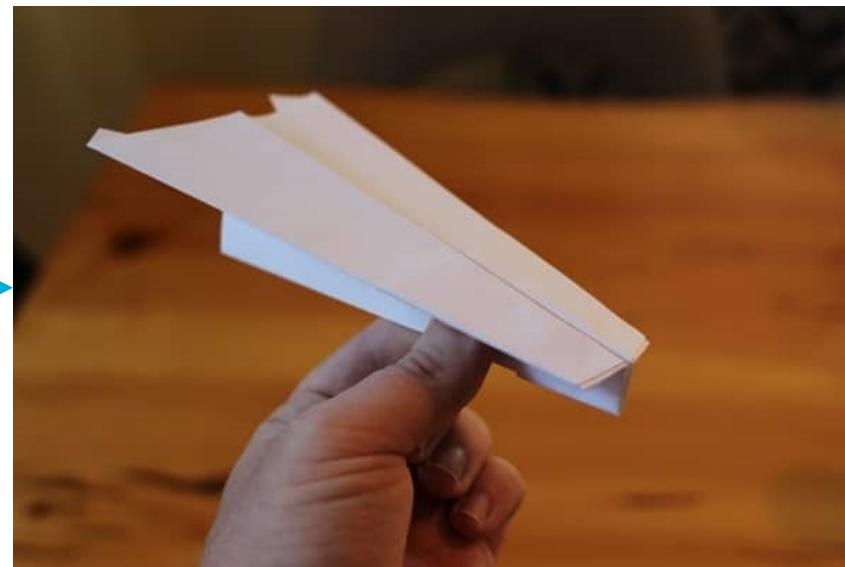
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# MY WORK WITH OPTIMIZATION

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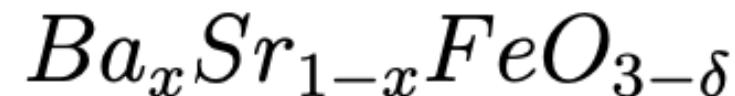
# TOY PROBLEM – SUMMER PROJECT OVERVIEW

- Based on original problem
- Simplified down to the main focus
- Known solution, generated data
- Easily increase complexity as solver gets working



## PROBLEM SETUP – OVERALL EQUATIONS

$$A_{m \times n} \cdot c_{n \times 1} = b_{m \times 1}$$



m = number of data, n = number of coefficients

Parameters:

- x: scalar, 0-1
- T: vector with dimensions [nData,1]
- $\delta_0$ : set to 0.02
- c exact: random vector on the order of  $10^{-3}$  to  $10^{-5}$
- $T_{ref}$ : reference temperature = 500 K
- $\Delta\delta$ : vector with dimensions [nData,1], <0.5

Variables: c guess and  $\delta$

## EQUATIONS IN MORE DETAIL

Nonlinear constraint: linear in  $c$ , nonlinear in  $\delta$

$$\frac{\partial G}{\partial \delta}(x, T, \delta_0, c) = -\mu_{O_2, g_{ref}}$$

$$\begin{bmatrix} \frac{\partial G}{\partial \delta} \\ \vdots \end{bmatrix} = \textcircled{A(x, T, \delta)} \cdot c \longrightarrow \begin{matrix} A \\ m \times n \end{matrix} \cdot \begin{matrix} c \\ n \times 1 \end{matrix} = \begin{matrix} b \\ m \times 1 \end{matrix}$$

$$= -\mu_{O_2, g_{ref}}$$

$$\delta = \delta_0 + \Delta \delta$$

$$L_i = A_i + B_i \times T + C_i \times T \log(T)$$

$$A, B, C = f(x, \delta)$$

*A, computed at each data point*

## ABOUT PYOMO: PYTHON OPTIMIZATION MODELING OBJECTS

- Python-based
- Open source software for optimization models
- Using Ipopt solver – interior point optimizer
  - Compare to the existing two solvers
  - Better functionality, but refactoring code required



# PYOMO MODEL COMPONENTS

Variables: changing parts, to be solved for

Parameters: data required for optimization to occur

Constraints: equations, inequalities, or other relations connecting parts of the model

Objective: function to be minimized or maximized

```
def fit_loss(m,c):
    error = 0
    for i in range(m.nData()):
        cABC = dG_dy_matrices(m,m.d+m.dd_values[i],m.T_values[i])
        # value = np.dot(cABC,c)
        value = pyo.sum_product(cABC,c,index=range(3*m.nCoeffs()))
        error += (m.b()[i]-value)**2
    v_lambda = 1.e-3
    error += pyo.sum_product(c,c)*v_lambda
    return error
```

```
m = pyo.ConcreteModel('Toy problem simplified')

m.nData = pyo.Param(
    initialize = 100,
    doc="Number of data points",
    domain=pyo.PositiveIntegers,
    mutable=True
)
m.x = pyo.Param(
    # initialize=np.random.rand(), # fix this to one value
    initialize=0.5,
    doc="Site fraction, ranges 0-1"
)
```

```
m.d = pyo.Var( # guess for d0
    initialize = 0.001,
    bounds = (0,0.5),
    doc="delta_0 variable value to solve for"
)
```

```
eqns = calculate_d0(m)

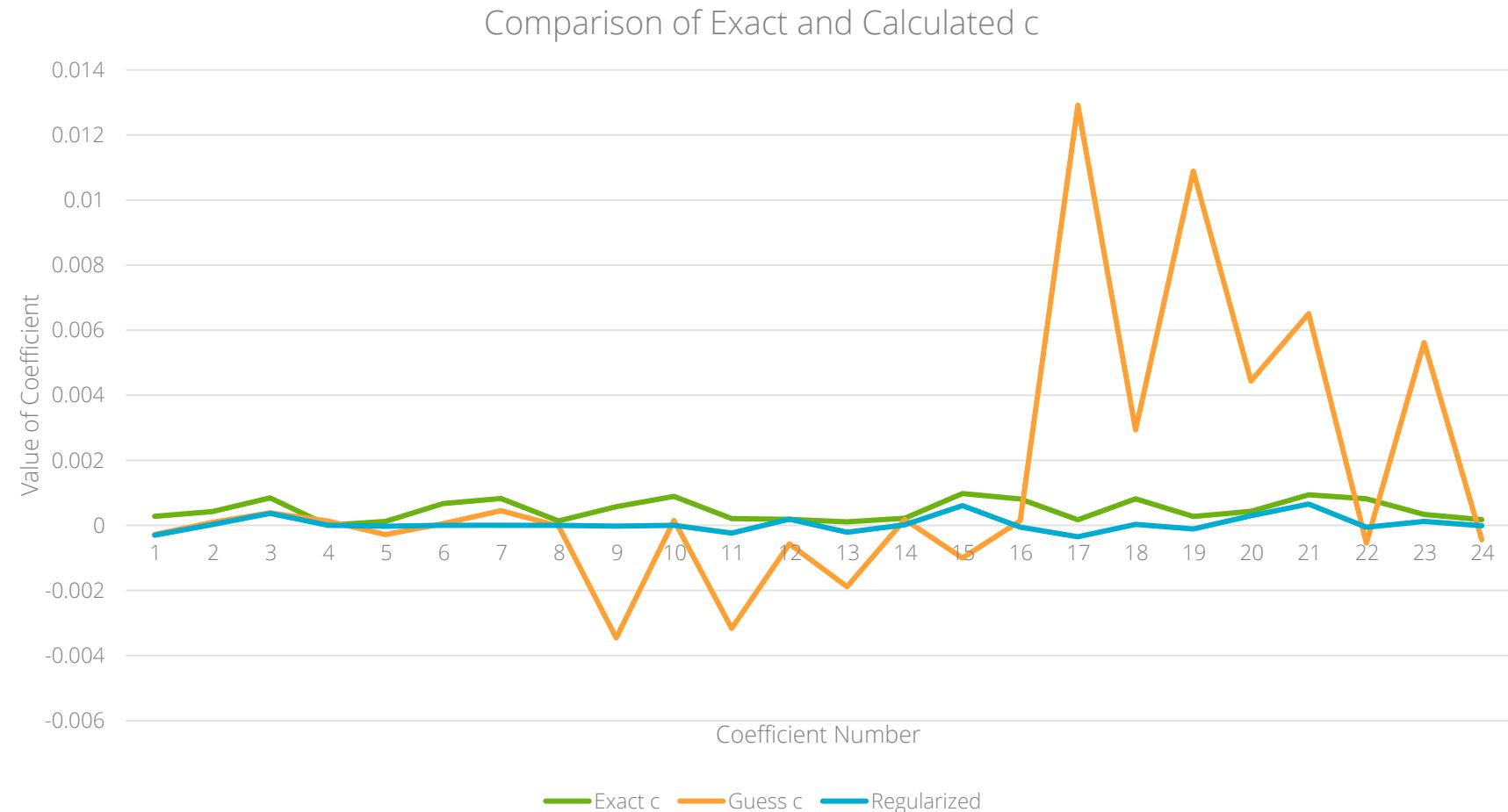
m.cons = pyo.ConstraintList()
m.cons.add(eqns == 0) # want zero error
```

```
m.obj = pyo.Objective(
    expr=fit_loss(m,m.c_guess),
    sense=pyo.minimize
)
```

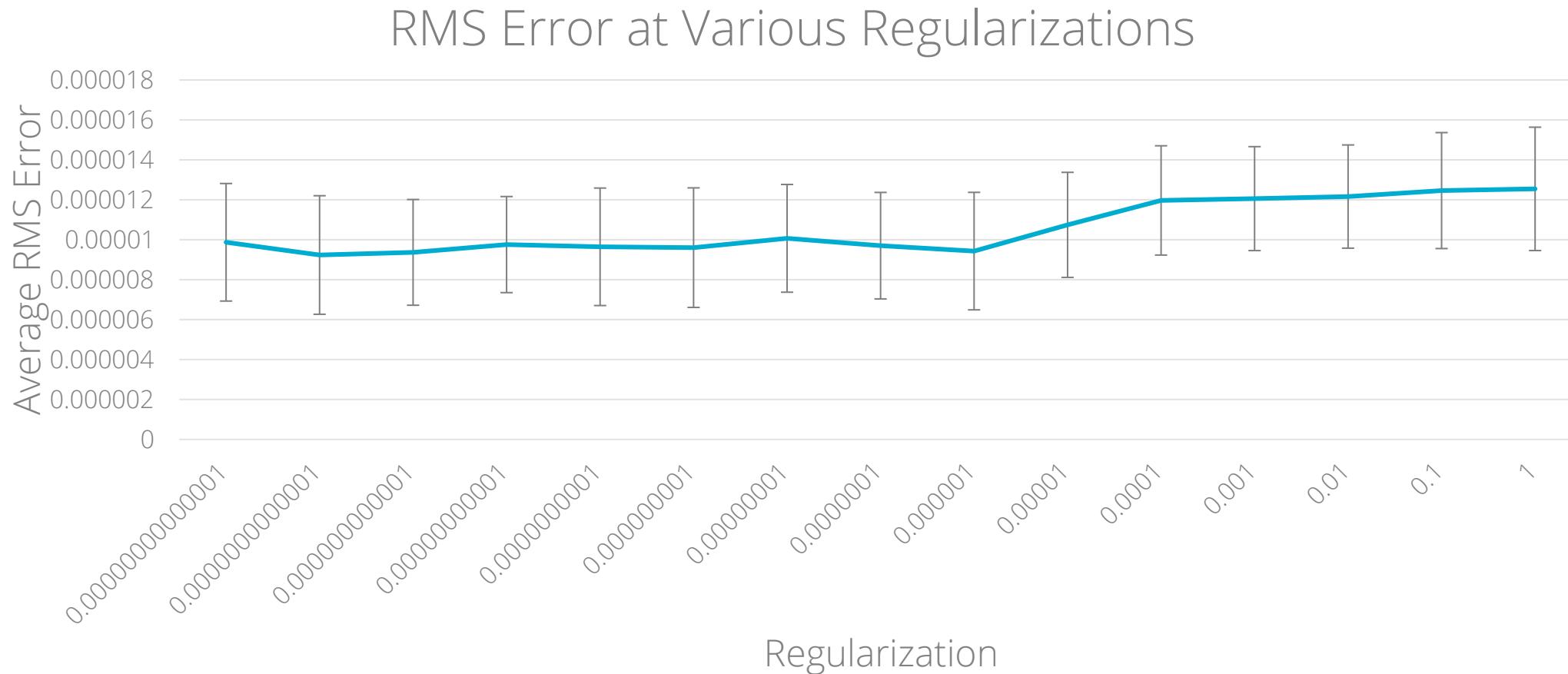
# RESULTS: ASSESSING THE SOLVER'S ACCURACY

Using 24 coefficients:

- Low loss function with and without regularization
- Regularization of 1.e-3 added to select the smallest solution



# COMPARISON OF VARYING LEVELS OF REGULARIZATION



By repeatedly running the solver, an ideal level of regularization can be selected. At zero regularization, the average RMS error is 3680417.

## NEXT STEPS OF ACTION

- Optimizing the regularization
- Examining the accuracy of  $\Delta\delta$  values
- Improving solver accuracy – refining solver parameters
- Lastly – increasing complexity

## ACKNOWLEDGEMENTS

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