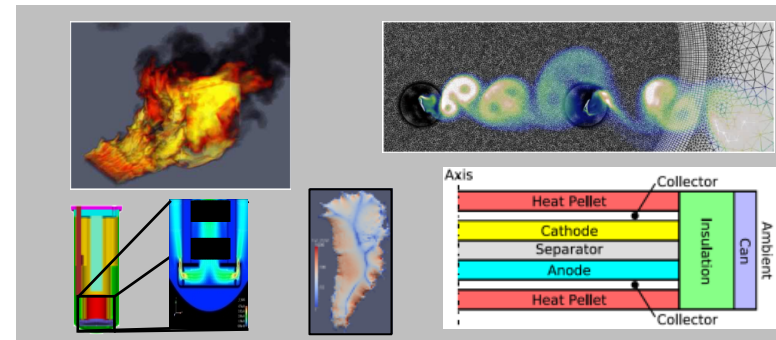
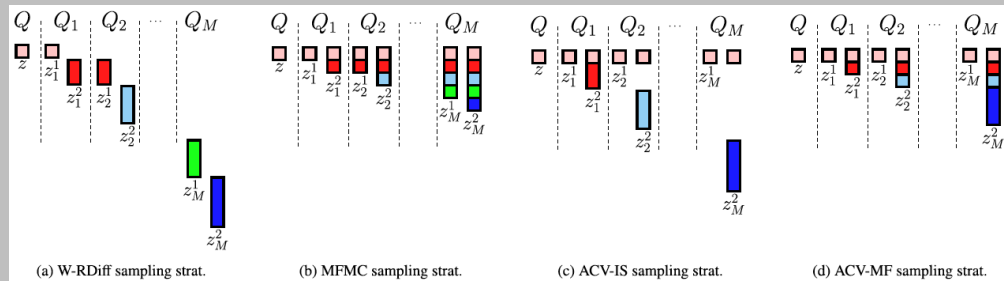


*Exceptional service in the national interest*



## Model Ensemble Configuration for Multifidelity UQ

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# Multilevel / Multifidelity Estimators based on Sampling

Estimator	Type	Sample allocation
MLMC	1D: hierarchical, recursive	Analytic
MFMC	1D: hierarchical, recursive	Analytic, Numerical
MLMF MC	2D: HF,LF pair + resolutions	Analytic
ACV	Non-recursive / peer: all CV pairings target root	Numerical
Gen. ACV	Search over approx sets & DAGs (MFMC + ACV + intermediate)	Numerical
ML BLUE	Model groupings	Numerical

**Motivation:** production deployments of ML/MF methods encounter a variety of challenges that can impede performance

- Accurate a priori / offline estimations of  $\text{Covar}[Q]$  are often impractical, and should rather be integrated and optimized  
→ *iterated pilot approaches*
- LF models often have parameters that trade accuracy vs. cost (set via SME judgment, but intuition often inaccurate in this context)  
→ *hyper-parameter model tuning*
- Numerical solutions [ACV, GenACV] often suffer from multi-modality (and multiple solutions may exhibit similar performance)  
→ *augment local solutions: multi-start local from analytic initial guesses, global + local*
- For general model ensembles, the best approximation selections and CV pairings/groupings are not known a priori  
→ *ensemble selection and DAG enumeration*

Each of these concerns introduces additional sequenced or nested iteration, or expands the scale of an integrated optimization

# Ensemble Configuration in Multifidelity Sampling

Model-tuning

$$\arg \min_{\theta} \left[ \arg \min_{\mathbf{r}, N} \frac{\text{Var}[Q]}{N} (1 - R^2(\theta, \mathbf{r})) \quad s.t. \quad N \left( w + \sum_{i=1}^M w_i(\theta) r_i \right) \leq C \right]$$

Not swappable without  $N_{\text{shared}}$  re-eval.  
Refinement is deferable:  
tuning often projection-based

Covariance refinement:  $\Delta N_{\text{shared}} \rightarrow \text{Covar}[Q]$

Ensemble selection: best subset (drop low value approx.)

CV selection (enumerate/optimize DAG pairings)

Separated for  
numerical reasons

$$\arg \min_{\mathbf{r}, N} \frac{\text{Var}[Q]}{N} (1 - R^2(\theta, \mathbf{r})) \quad s.t. \quad N \left( w + \sum_{i=1}^M w_i(\theta) r_i \right) \leq C$$

Resource Allocation: cost  $\longleftrightarrow$  accuracy

Fixed covariance (GenACV w/ MFMC, ACV as special cases)

Variable covariance: converge on  $N_{\text{shared}}$ , tune w.r.t.  $\theta$

# Outer loops (modifying covariance): review of previous work

**Iterated Pilots** → integrate pilot sample as *online cost* and optimize total

- {MFMC, ACV, GenACV} utilize a shared  $N^{(i)}$  for estimation of  $\text{Covar}[Q]$  across models

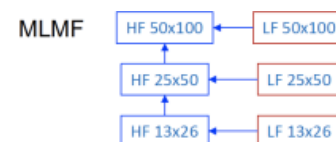
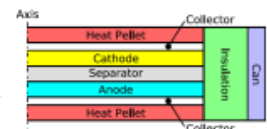
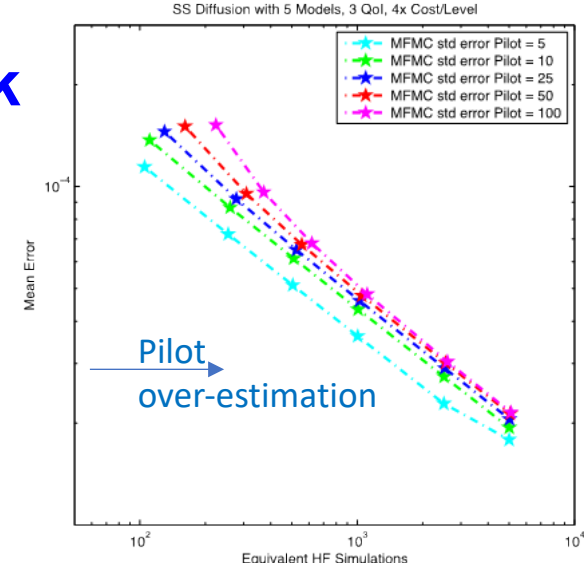
**Initialize:** select small shared pilot  $N^{(0)}$  expected to under-shoot optimal profile

- 1) Sample all models
- 2)  $N^{(i)}$  shared samples →  $\text{Cov}_{LL}^{(i)}, \text{Cov}_{LH}^{(i)}$  → opt. solver →  $r^*, N^*$
- 3) Compute one-sided  $\Delta N$  for shared samples from  $N^{(i)}$  to  $N^*$ 
  - A. Optional: apply under-relaxation factor  $\gamma$
  - B. If non-zero increment, advance (i) and return to 1)

- Avoid inefficiency (over-est.) or inaccuracy (under-est.). Numerical solves provide resilience → find near-optimal solns. incorporating large pilots.

**Hyper-Parameter Model Tuning** → tune approximations to achieve best accuracy vs. cost trade-off

$$\arg \min_{\theta} \left[ \arg \min_{r, N} \frac{\text{Var}[Q]}{N} (1 - R^2(\theta, r)) \quad s.t. \quad N \left( w + \sum_{i=1}^M w_i(\theta) r_i \right) \leq C \right]$$



**Hand-tuned:** refine across discrete combinations until  $\rho > 0.9$  obtained for all QoI

Hand-tuned hyper-parameters:	
0.01	initial time step
0.10	predictor-corrector tol
0.10	nonlinear residual tol
Projected MLCV Estimator Variance:	.050092
Single fidelity accuracy for equiv cost:	1.3668 (969 HF)
Single fidelity cost for equiv accuracy:	26,440 HF (EstVar 0.050092)

27.3x

Hand-tuned hyper-parameters:	
0.01	initial time step
0.10	predictor-corrector tol
0.10	nonlinear residual tol
Projected ACV Estimator Variance:	.053138
Single fidelity accuracy for equiv cost:	1.3178 (1005 HF)
Single fidelity cost for equiv accuracy:	24,925 HF (EstVar .053138)

24.8x

**EGO-tuned:** global minimization of variance of selected estimator (max iter = 80)

Optimal hyper-parameters:	
0.0084097	initial time step
0.0061138	predictor-corrector tol
0.028493	nonlinear residual tol
Projected MLCV Estimator Variance:	.034396
Single fidelity accuracy for equiv cost:	1.3654 (970 HF)
Single fidelity cost for equiv accuracy:	38,506 HF (EstVar 0.034396)

39.7x

Optimal hyper-parameters:	
0.0067487	initial time step
0.0010880	predictor-corrector tol
0.046707	nonlinear residual tol
Projected ACV Estimator Variance:	.0092395
Single fidelity accuracy for equiv cost:	1.3192 (1004 HF)
Single fidelity cost for equiv accuracy:	143,340 HF (EstVar 0.0092395)

143x

Greater tuning impact for more flexible estimators → GenACV

# Inner Loop (fixed covariance): Competed numerical solvers

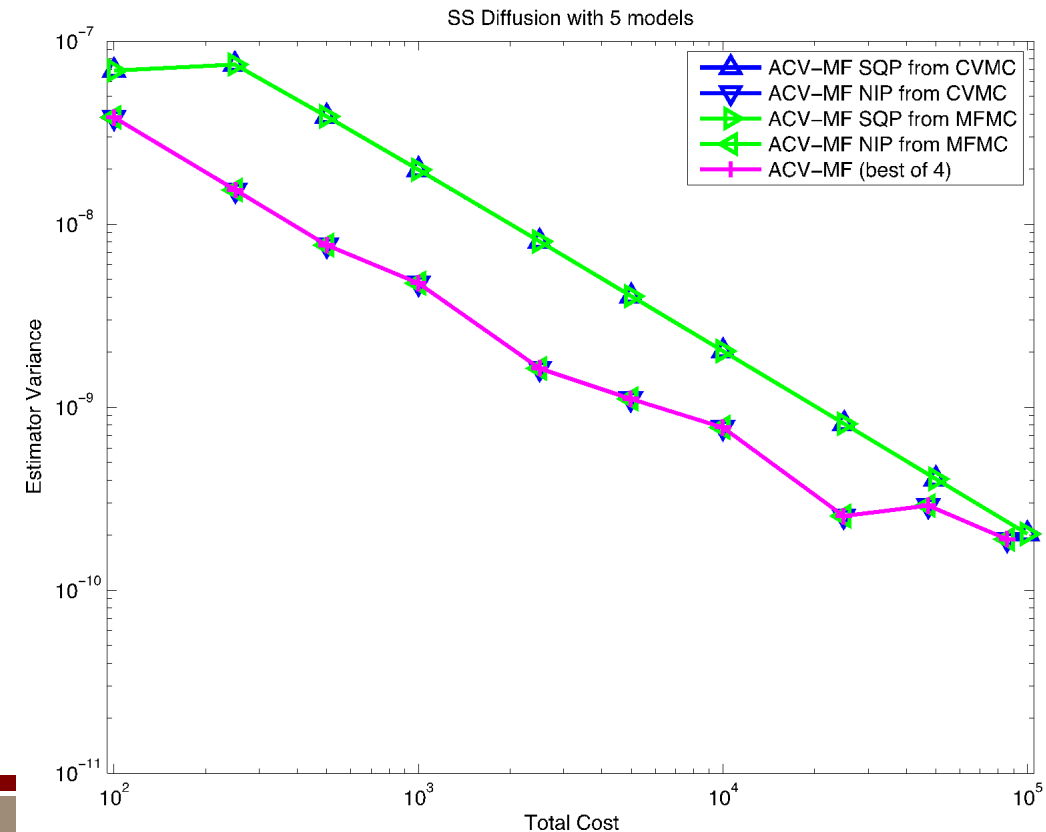
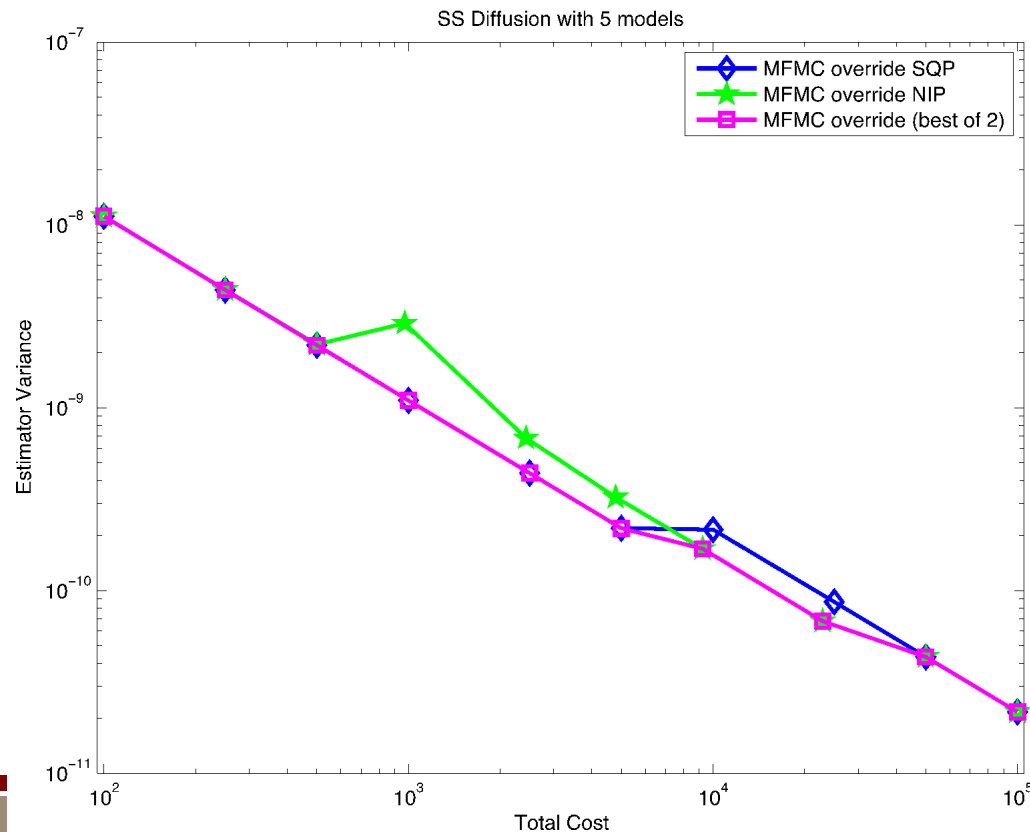
## First iteration: multi-start / multi-solver

- Analytic solutions as initial guesses:
  - MFMC (ordered, reordered using average  $\rho^2_{LH}$ )
  - Pairwise CVMC for given ensemble + DAG

- Solvers
  - SQP (via NPSOL)
  - NIP (via OPT++)

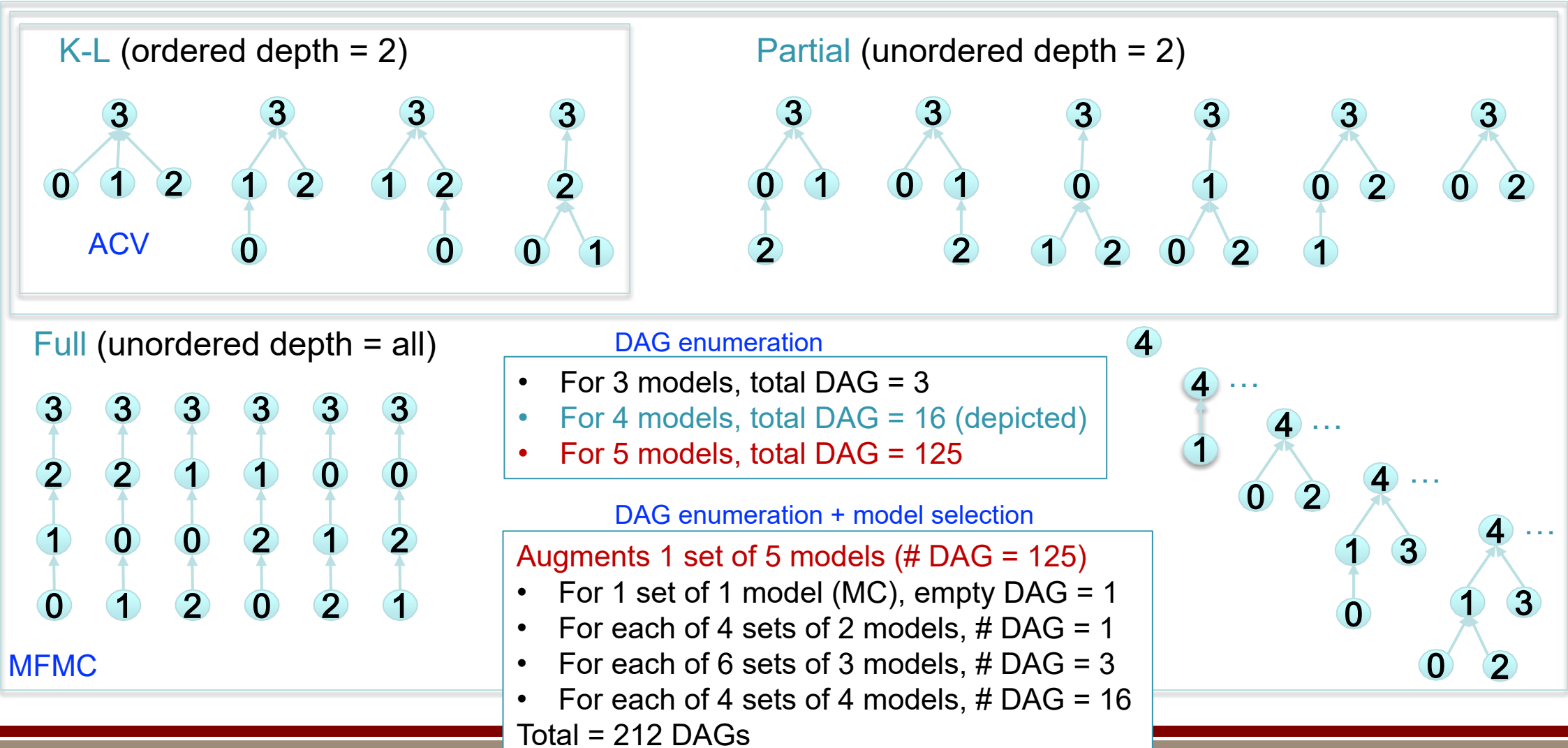
## Subsequent iterations (if online/iterated)

- Warm start from previous best soln (1) keyed for active ensemble + DAG



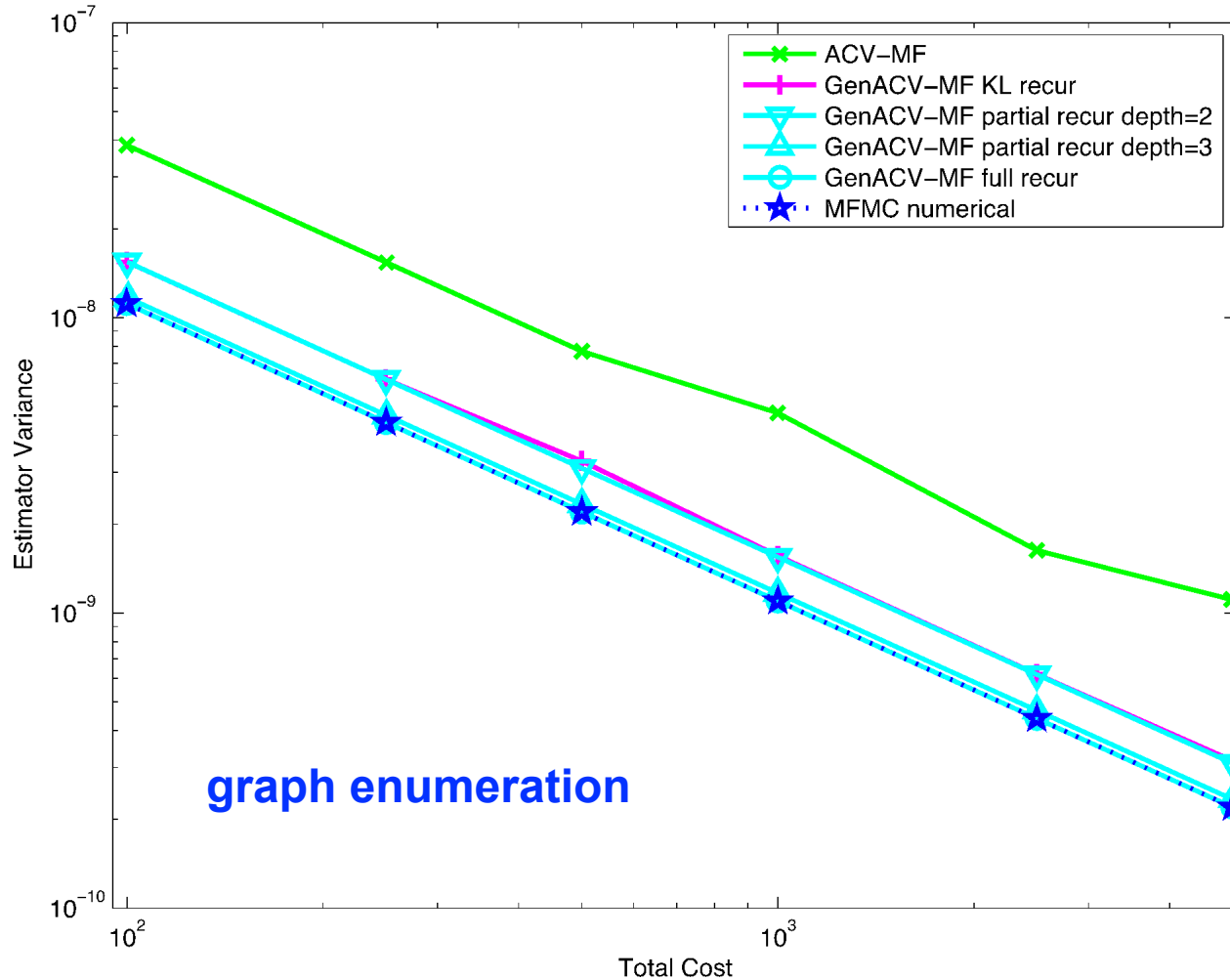
Explore possible model dependencies, as defined by DAGs that identify control variate pairings

- GenACV-MF is inclusive of current estimators MFMC and ACV-MF



# Generalized ACV: test problem 1

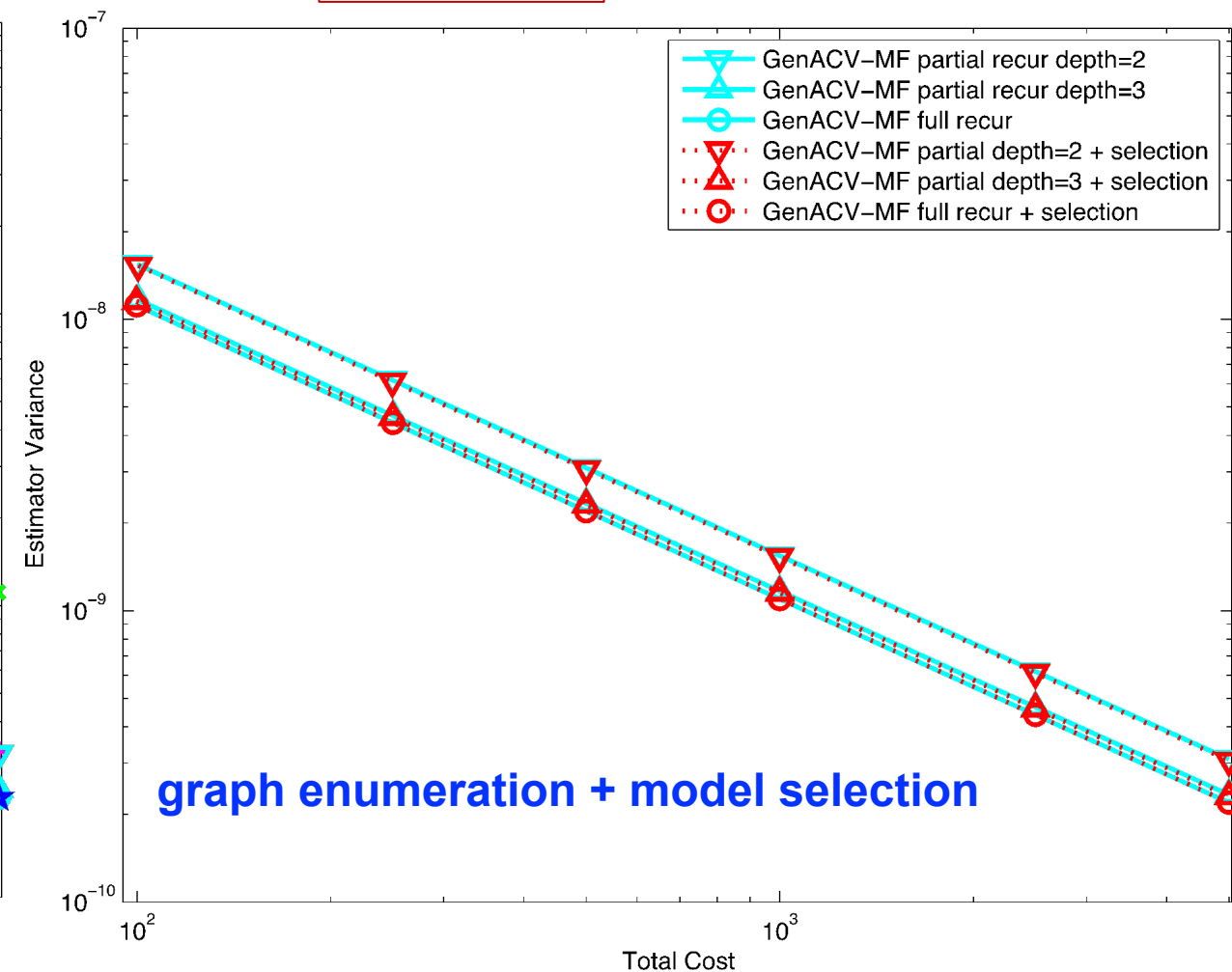
Steady state 1D diffusion: 5 well-ordered models  
resolutions = {4,8,16,32,64}, relative cost = {1,4,16,64,256}



Peer DAG is not well suited → GenACV recovers MFMC at full depth

$$-\frac{d}{dx} \left[ a(x, \xi) \frac{du}{dx}(x, \xi) \right] = 10, \quad (x, \xi) \in (0, 1) \times I_\xi$$

$$u(0, \xi) = 0, \quad u(1, \xi) = 0.$$



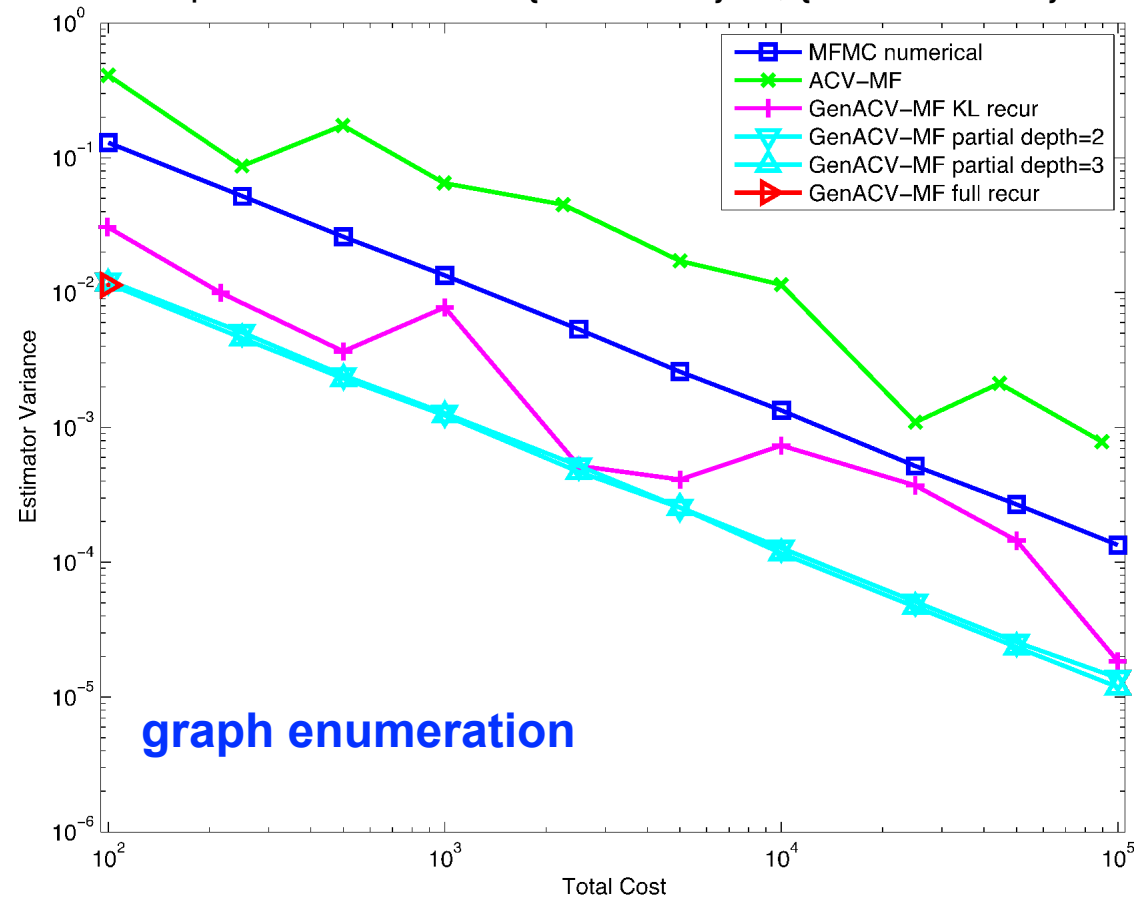
All approximations are useful (slight improvements for restricted depth)



# Generalized ACV: test problem 2

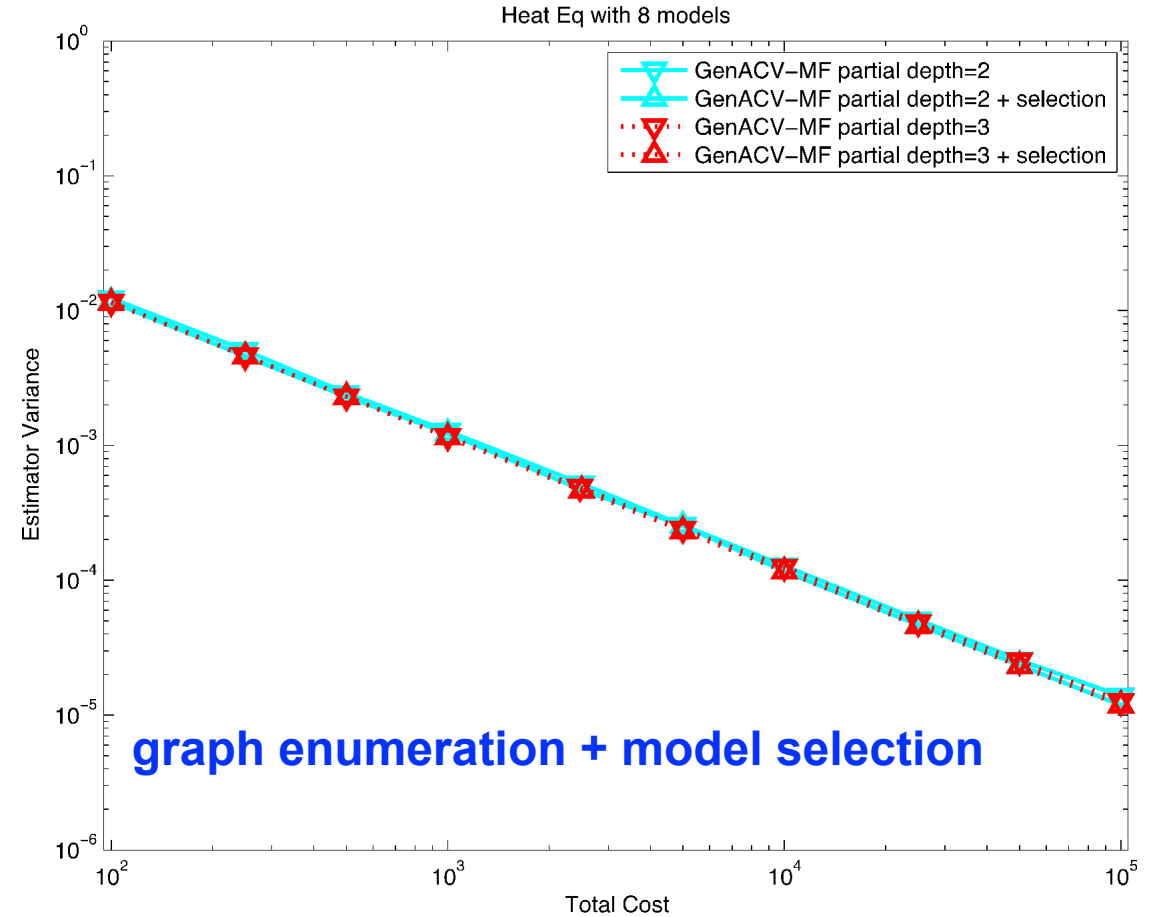
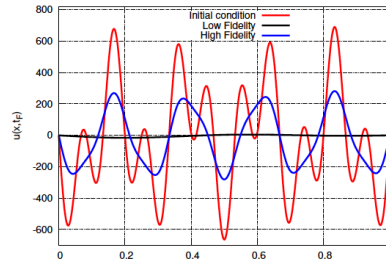
1D transient diffusion (“heat equation”)

- 8 models in 2D hierarchy: multifidelity + multilevel
- Fourier solution modes = 3 LF, 21 HF
- Spatial coordinates = {5 15 30 60} LF, {30 60 100 200} HF



More complex hierarchy benefits significantly from DAG search  
Solver noise could be smoothed with sample replicates

$$\begin{cases} \frac{\partial u(x, \xi, t)}{\partial t} - \alpha(\xi) \frac{\partial^2 u(x, \xi, t)}{\partial x^2} = 0, & \alpha > 0, x \in [0, L] = \Omega \subset \mathbb{R} \\ u(x, \xi, 0) = u_0(x, \xi), & t \in [0, t_F] \text{ and } \xi \in \Xi \subset \mathbb{R}^d \\ u(x, \xi, t)|_{\partial\Omega} = 0 \\ u_0(x, \xi) = \mathcal{G}(\xi)\mathcal{F}_1(x) + \mathcal{I}(\xi)\mathcal{F}_2(x) \end{cases}$$



Model selection adds a small amount of additional performance,  
but all models generally providing utility

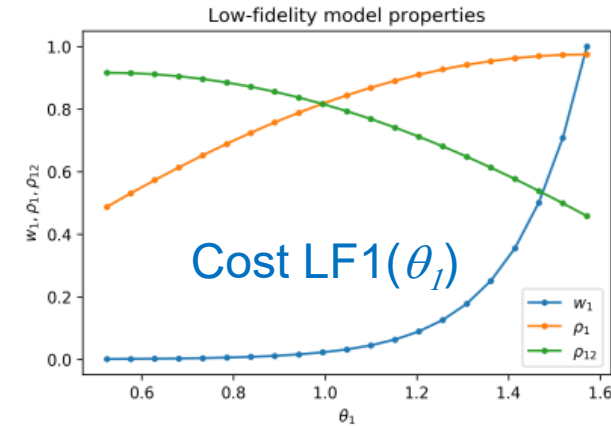
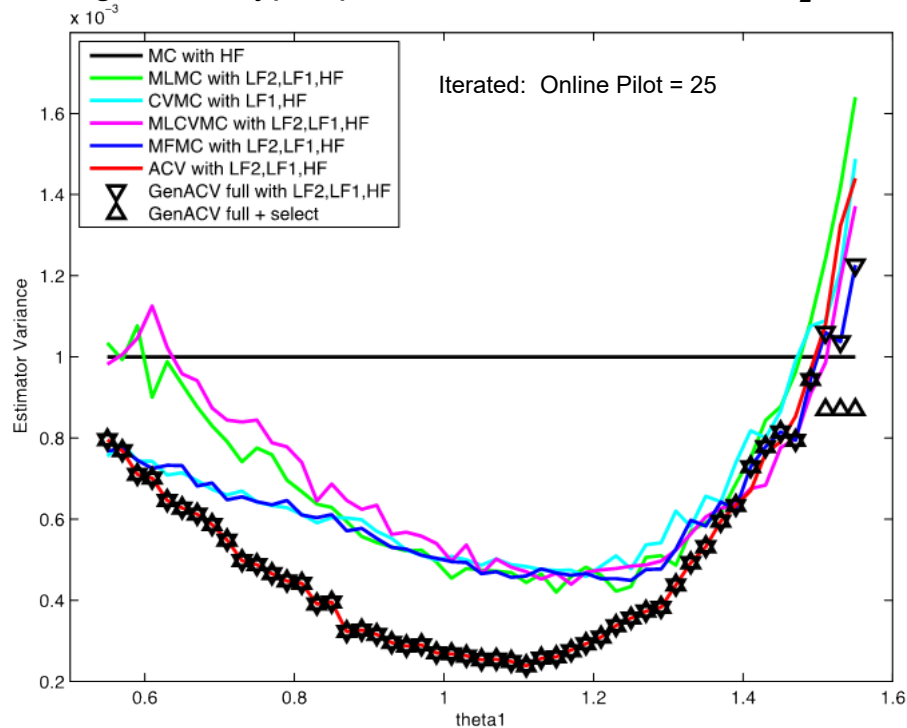


# Putting it all together: tuning, iterated pilots, ensemble + DAG selection

## “Tunable Model” Definitions (JCP 2020)

$$\begin{aligned}Q(\theta) &= \sqrt{11} \begin{bmatrix} \cos(\theta) x^5 + \sin(\theta) y^5 \end{bmatrix} \\Q_1(\theta_1) &= \sqrt{7} \begin{bmatrix} \cos(\theta_1) x^3 + \sin(\theta_1) y^3 \end{bmatrix} \\Q_2(\theta_2) &= \sqrt{3} \begin{bmatrix} \cos(\theta_2) x + \sin(\theta_2) y \end{bmatrix}\end{aligned}$$

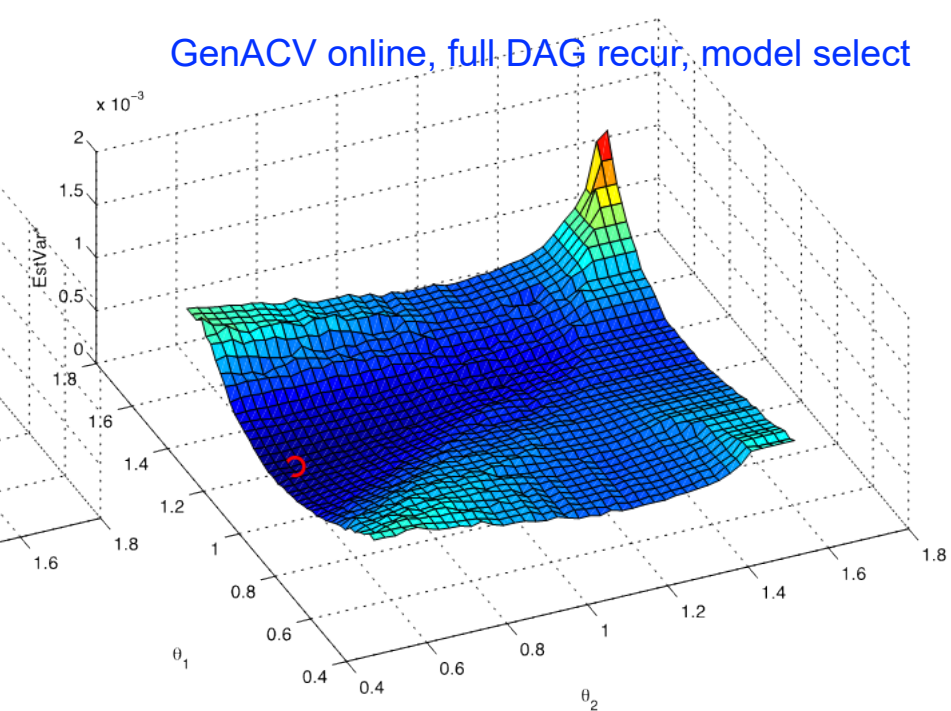
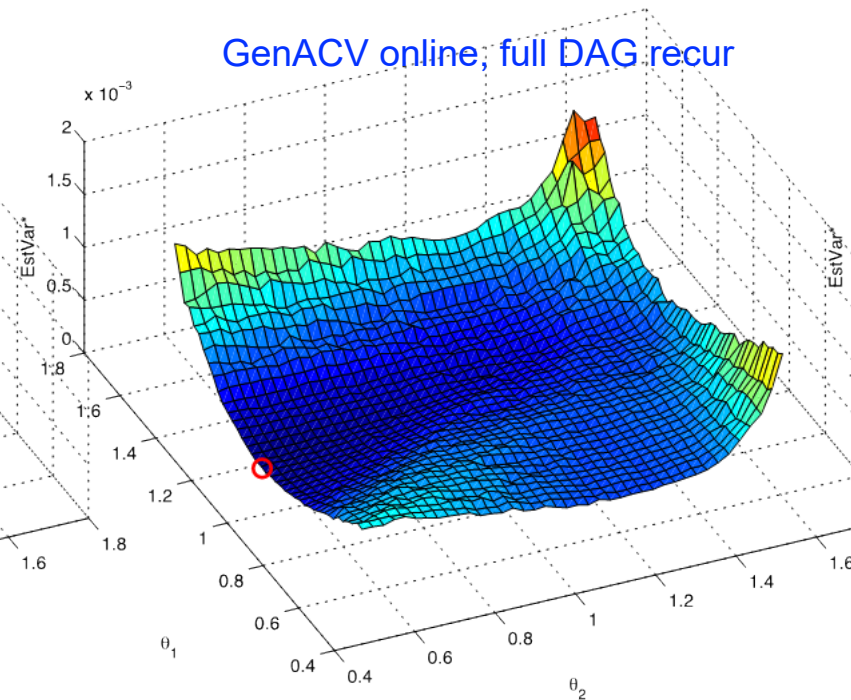
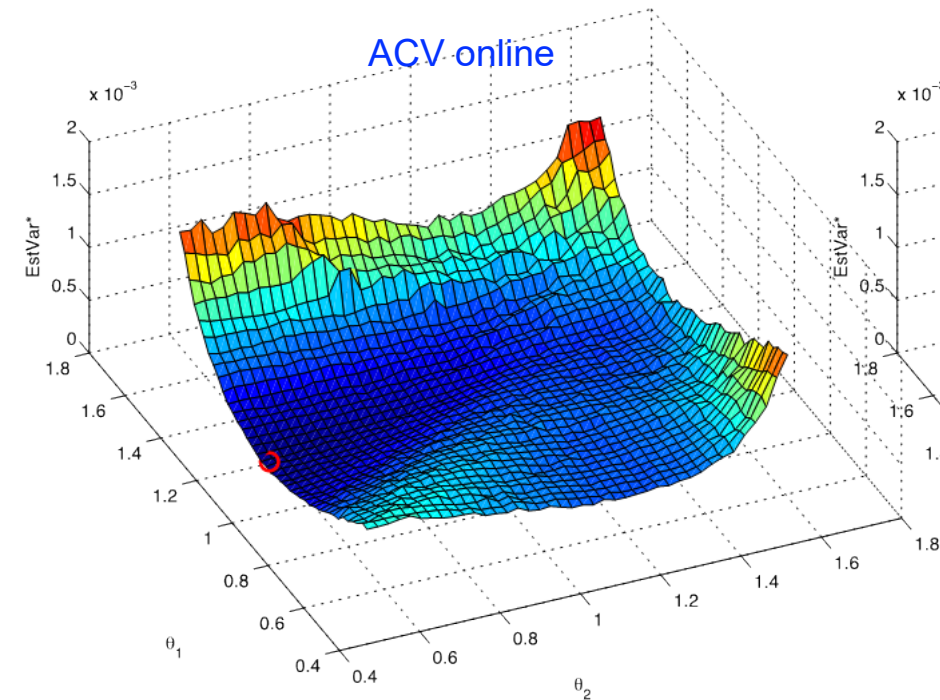
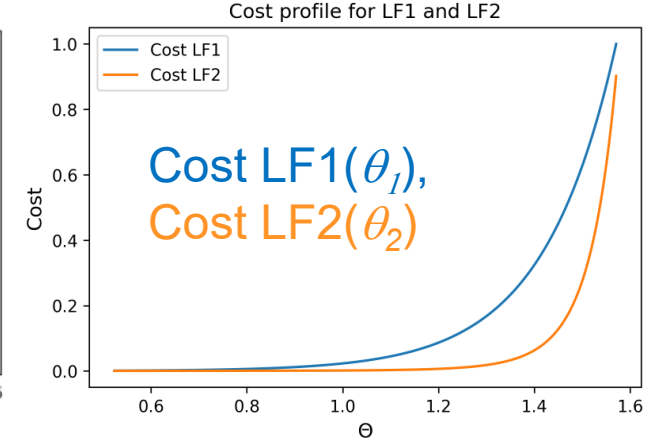
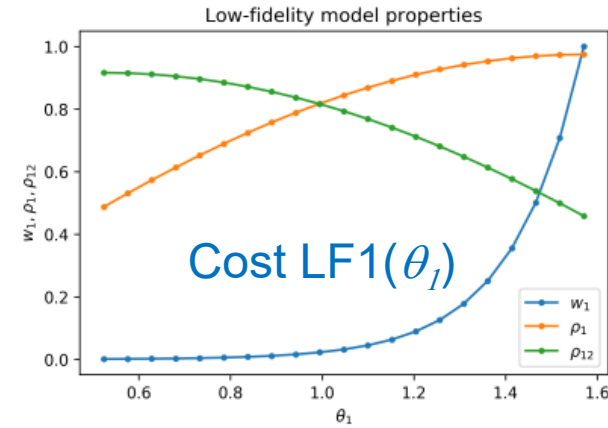
Start with tuning 1 parameter ( $\theta_1$ ) for mid-fidelity  
high / low hyper-parameters fixed:  $\theta = \pi/2$ ,  $\theta_2 = \pi/6$



# Putting it all together: tuning, iterated pilots, ensemble + DAG selection

## “Tunable Model” Definitions (JCP 2020)

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In general, hyper-parameter model tuning amplifies the utility of non-hierarchical estimators and DAG flexibility

Production deployments of multifidelity methods encounter a variety of challenges

- Accurate offline estimations of  $\text{Covar}[Q]$  are expensive and should be integrated and optimized → *Iterated online pilots*
- LF models often have parameters that trade accuracy vs. cost → *Hyper-parameter model tuning*
- Numerical solutions are not always reliable w/ local solvers → *Multistart/Multisolver, Global/Local*
- Best selections/pairings/groupings often unknown a priori → *Model selection/DAG enumeration*

## *Outer loop (varying the inter-model covariance; previous work)*

- Iterated pilots: avoid pilot under-/over-estimation or, with numerical solutions, mitigate the effects
- Hyper-parameter model tuning with bi-level & AAO approaches: especially effective with less structured estimators

## *Inner loop (fixing the inter-model covariance; recent work)*

- Refine solver definitions with competition/sequencing → *additional refinements in progress*
- Optimize CV pairings via DAG enumeration → *clear benefit*
- Select most performant ensemble of approximations → *marginal additional benefit for std test cases w/ good models; poor model cases discarded for model mis-tuning*

## *Next steps*

- Streamline for efficiency (model tuning + large enumerations can become impractical even for simple test problems)
  - Solvers for MFMC/ACV/GenACV: multi-start/multi-solver → sequenced global-local search
  - ML-BLUE can unify ensemble configuration steps, SDP may aid in solver challenges?
  - MINLP / heuristic search strategies to short-circuit brute-force enumerations in GenACV

Extra

# Inner Loop (fixed covariance): Sequenced numerical solvers

## First iteration

- Global search as initial guess(es):
  - EGO (Bayesian opt; maximize EIF w/ DIRECT+local)
  - **DIRECT (GP indirection may not add much in this case)**
- Local refinement
  - SQP (via NPSOL)
  - NIP (via OPT++)

## Subsequent iterations (if online/iterated)

- Warm start from previous best soln (1) keyed for active ensemble + DAG

## TO DO LIST:

- Heat eq 8 models: identify best DAGs with/without model selection
- DIRECT + Local
- Model selection for KL
- ML BLUE
- Model selection for MFMC? (ACV fixed depth = all)
- Model selection without DAG enumeration (set ACV partial depth=1 and/or support “no recursion”)
- Include MC case in count and enumeration