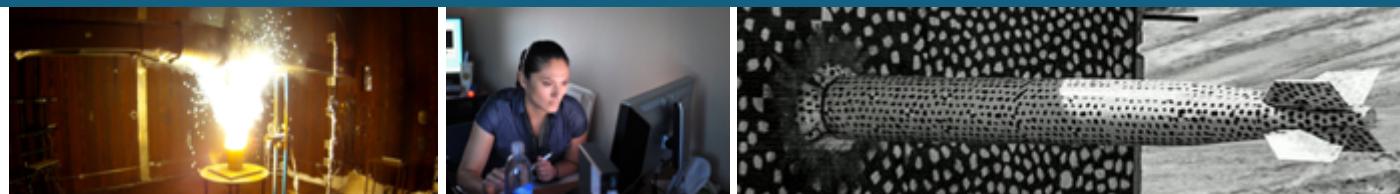




Meshing Ugly Geometry with Sculpt using Winding Numbers



17th USNCCM MS321 MeshTrends
July 2023

Presented by

Scott A. Mitchell
CCR Center for Computing Research
Sandia National Laboratories



This material is based upon work supported by the U.S. Department of Energy, Office of Science, Office of Advanced Scientific Computing Research (ASCR), Applied Mathematics Program.





Traditional meshing algorithms need **perfect** geometry

- Perfecting it takes too long and drives scientists crazy

We develop meshing algorithms that work on **ugly** geometry

- Price is geometric and *topological* (new) fidelity to the input
- TetWild, etc., already do this, but without quantified topological accuracy

We propose math to

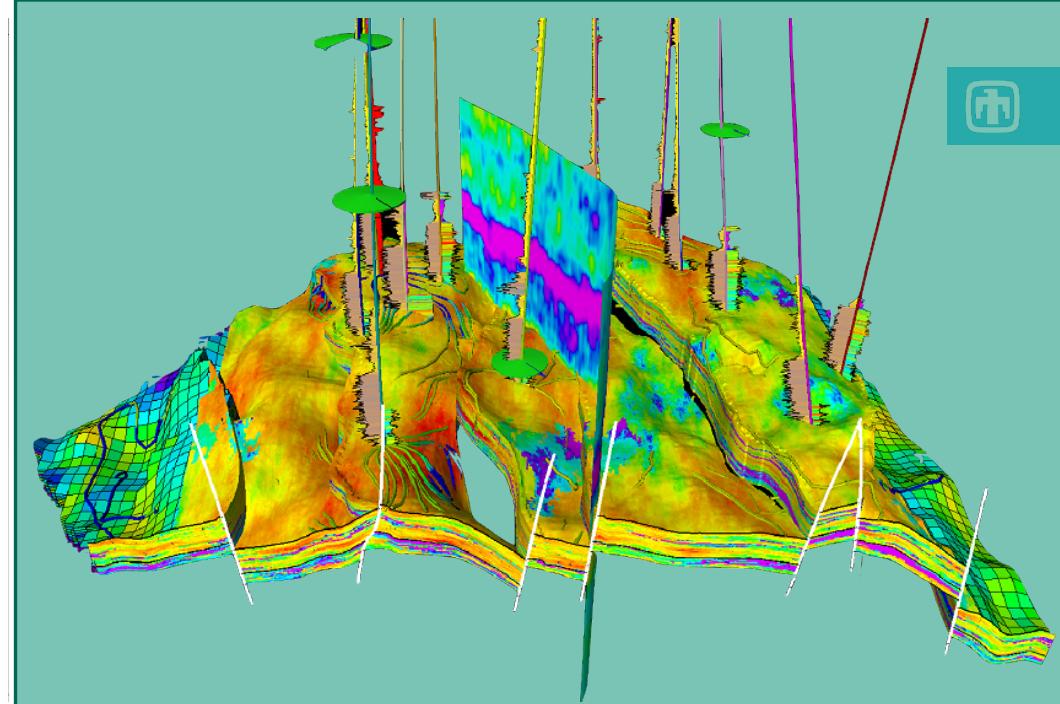
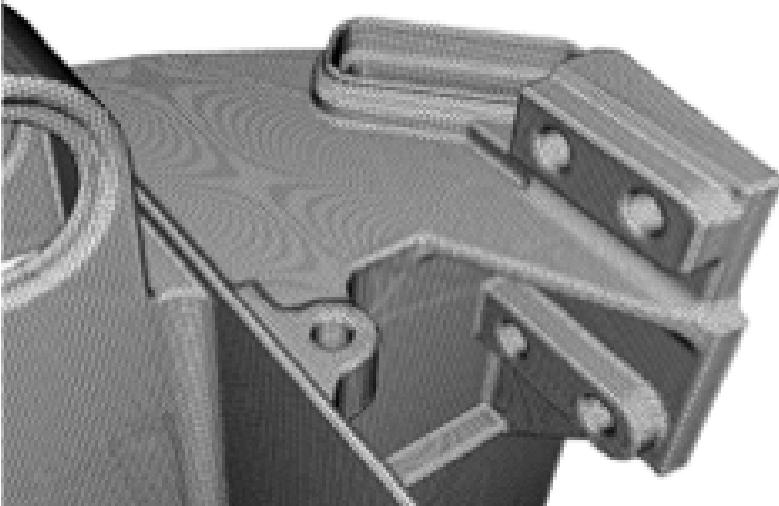
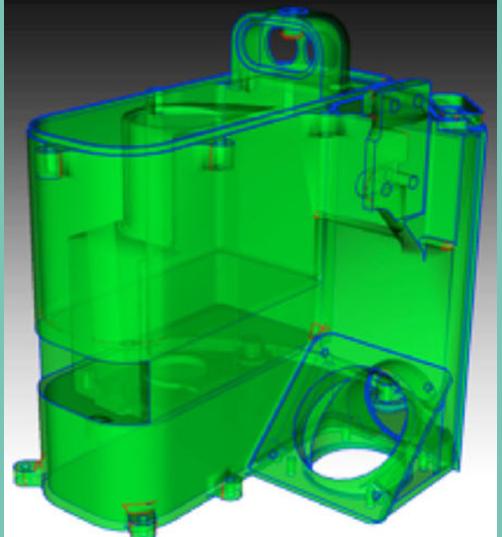
- **Measure** geometric and topological fidelity
 - By persistent homology
- **Prove** fidelity bounds
 - Parameterized by scientist-elected mesh size
 - Parameterized by measures of geometric ugliness

Sculpt

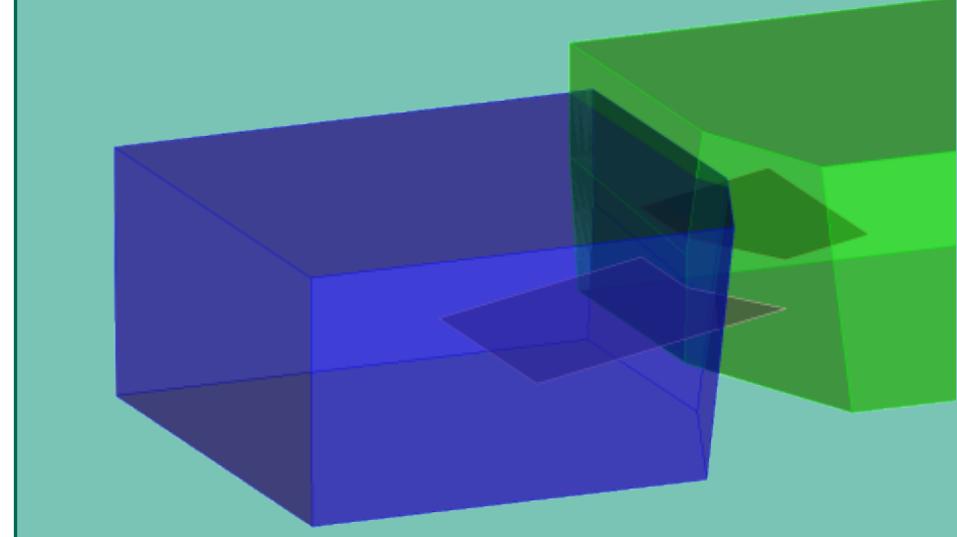
Fundamentally reconstructs the geometry

- Extend to ugly geometry
 - e.g. non-watertight geometry, gaps, overlaps, pinch points
 - by winding number in libigl for graceful inside/out

Sculpt already did engineering domains



Extend Sculpt to Seismic Domains



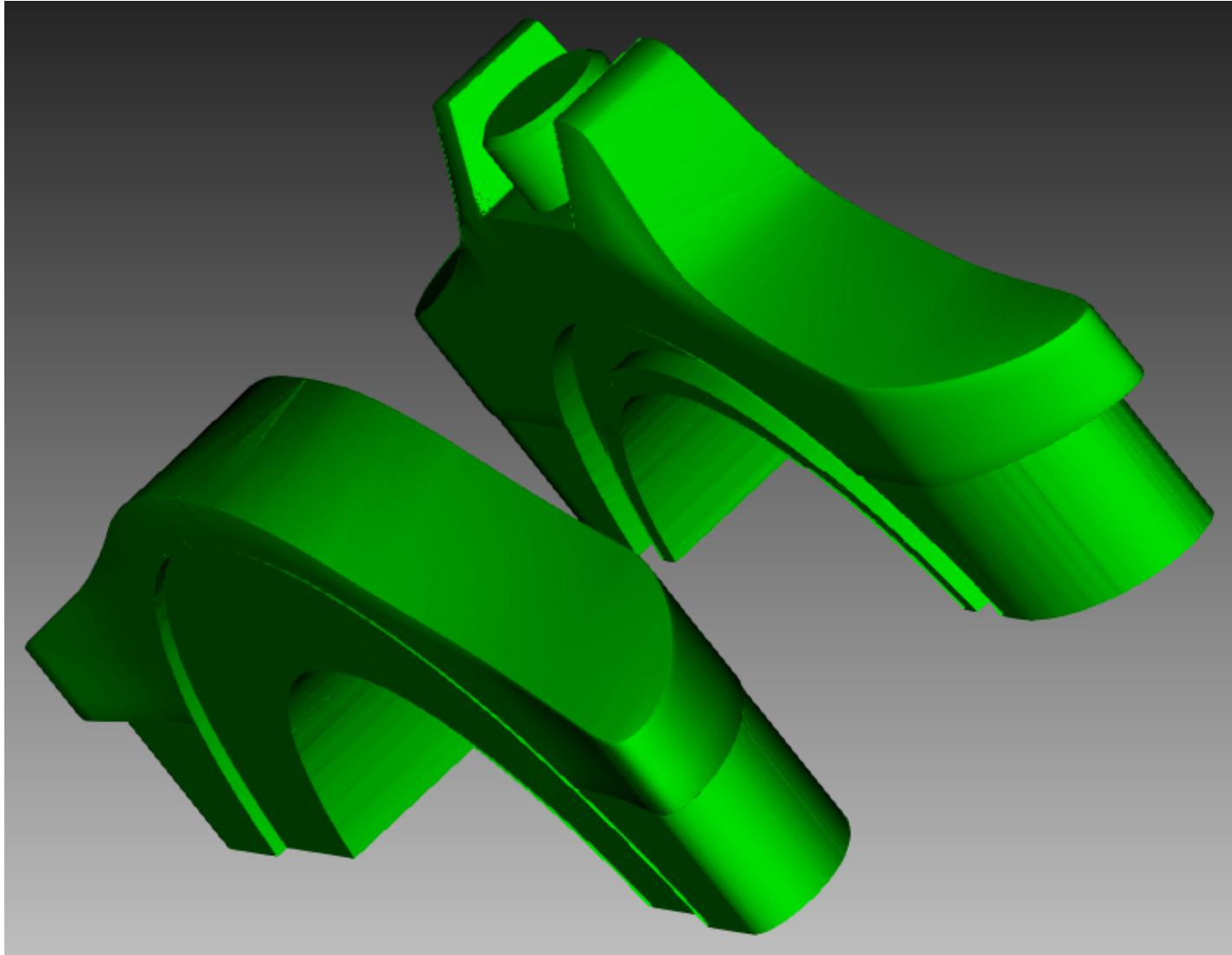
Geometric Fantasy and Reality



Thingi10k watch model,
and motivation,
courtesy Jacobson, Panozzo et al.



Fantasy



Reality

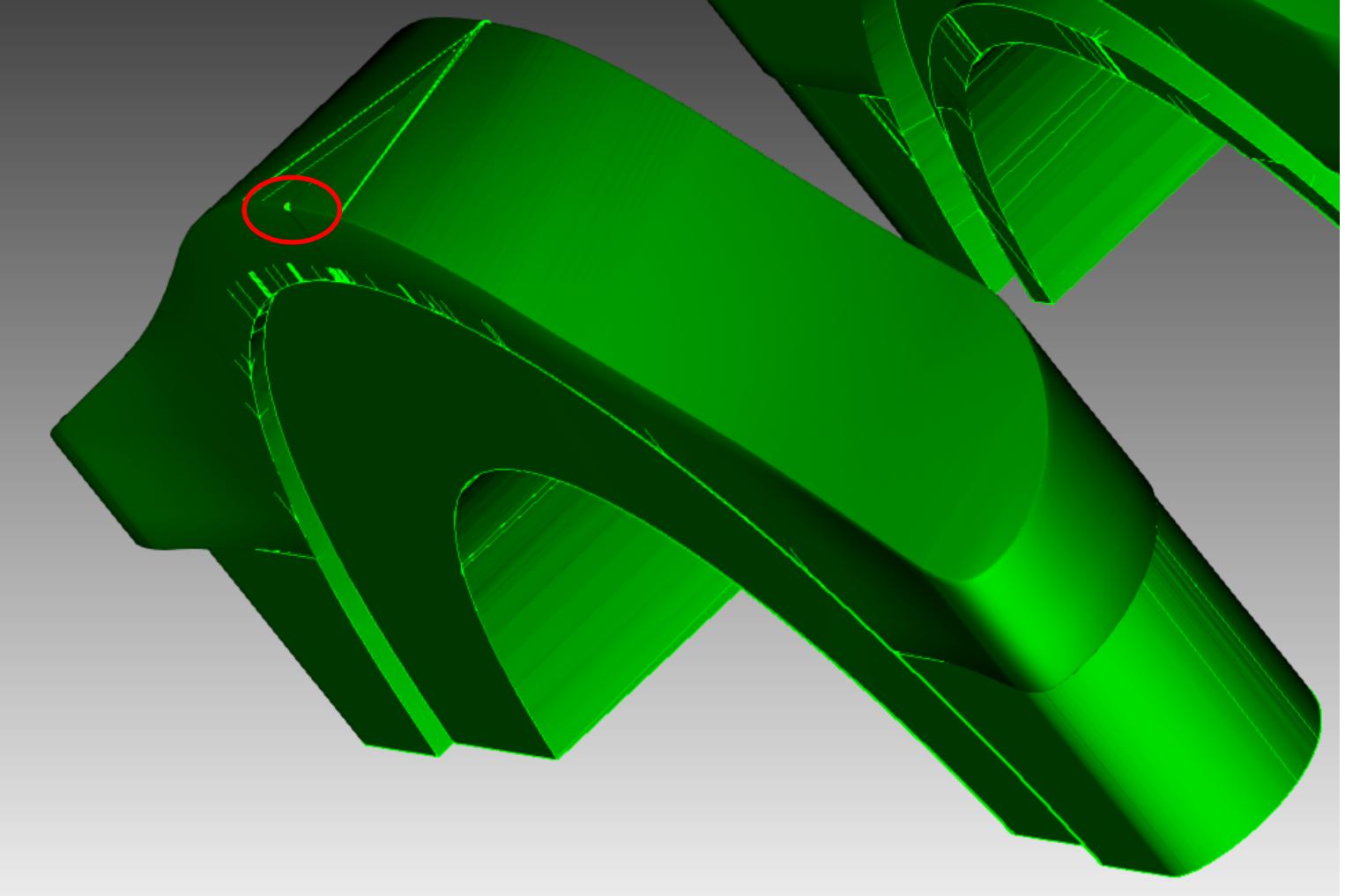
Geometric Fantasy and Reality



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Fantasy



Reality

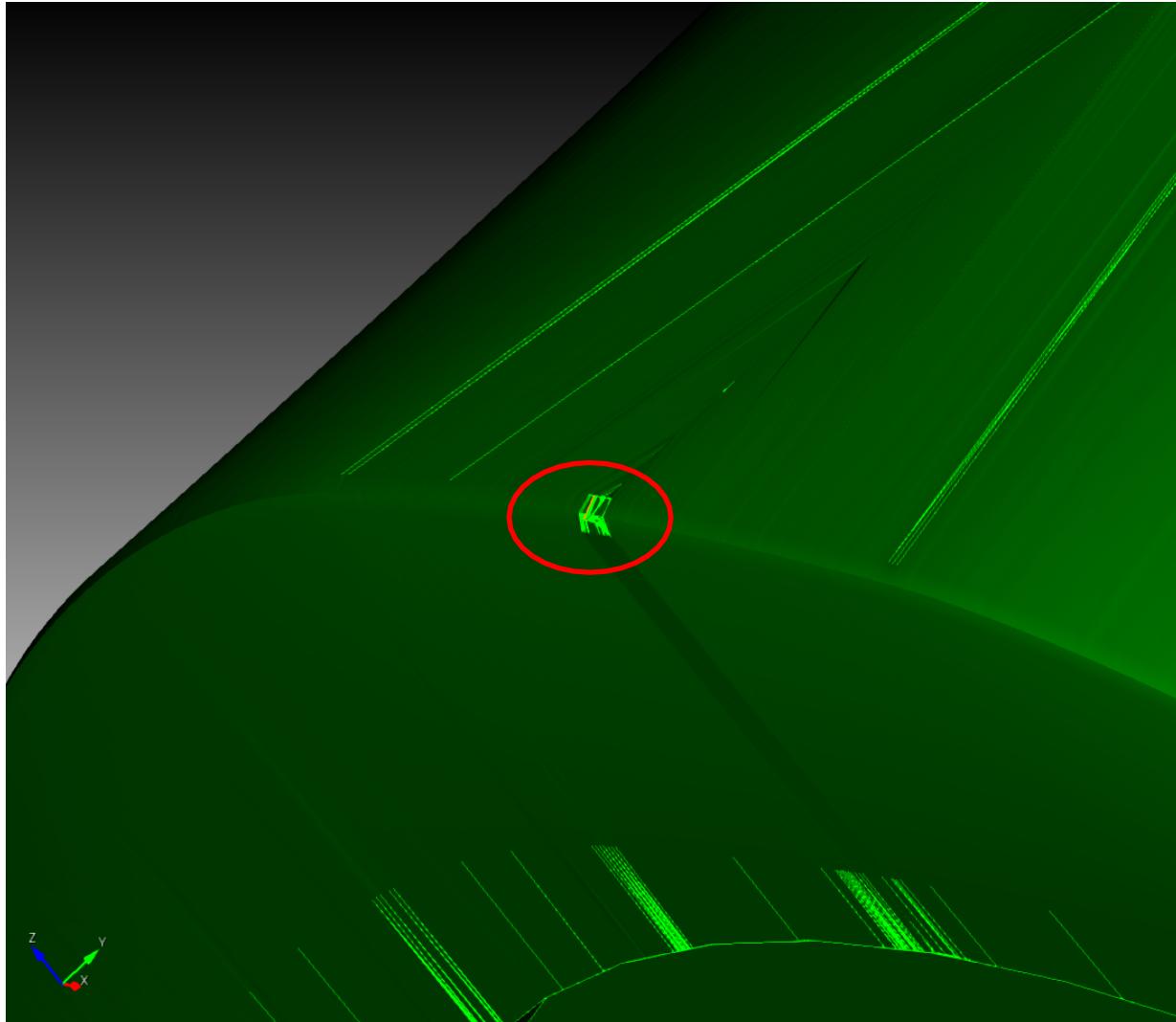
Geometric Fantasy and Reality



Thingi10k watch model,
and motivation,
courtesy Jacobson, Panozzo et al.



Fantasy



Reality

Geometric Fantasy and Reality

Venus:

You're fantasizing again.
Why would we want to?



Fantasy

Co-author:
We must make VoroCrust
reconstruct not just the samples, but
all input triangles and edges
exactly!



Reality

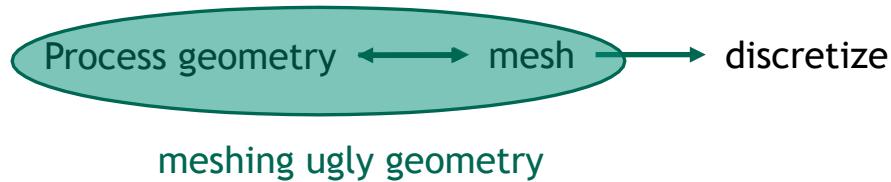


Thingi10k watch model,
and motivation,
Jacobson, Panozzo et al.

Research Objectives



Dominant philosophy of practice and theory change:



Goals: Free scientist to

- use any geometry available
- select any mesh size regardless of geometry
- Mesh is discrete approximation to geometry

Research objectives to achieve goals scale smaller than the mesh

- Fidelity measures, math definitions
resolution?
- Algorithms with quantified fidelity described by mathematical theorems

Geometry Input

Old School

- Perfect
 - Smooth manifolds or
 - Watertight CAD models
- Defines desired mesh size
 - Scientist can select finer, not coarser
- Defines mesh geometry
- Defines mesh topology

New School

- Inexplicable
 - Point clouds
 - Triangle soups
- Independent of mesh size
 - Scientist can select any mesh size
- Approx. mesh geometry
- Approx. mesh topology

9 Research Objectives



Choose your mesh: pick any two, the third is dependent!

1. Element Quality
2. Geometric & Topological Fidelity
3. Local Size (# elements)

Old School

1 + 2 exactly reconstruct input geometry & topology
→ **3** small elements near small and sharp features

New School

1 + 3 mesh size is what the scientist needs
→ **2** Geometric and topological fidelity is approximate

Local feature size, lfs

- Traditional measure of input geometry
- Limits max local mesh size
- Predicts geometric fidelity
 - Distance between mesh and geometry

Geometry Input

Old School

- Perfect
 - Smooth manifolds or
 - Watertight CAD models
- Defines desired mesh size
 - Scientist can select finer, not coarser
- Defines mesh geometry
- Defines mesh topology

New School

- Inexplicable
 - Point clouds
 - Triangle soups
- Independent of mesh size
 - Scientist can select any mesh size
- Approx. mesh geometry
- Approx. mesh topology

Persistent Homology

- Measures how topology changes with geometric resolution
- If mesh size > lfs, can we predict the topological fidelity?
 - Input geometry topology vs. output mesh topology

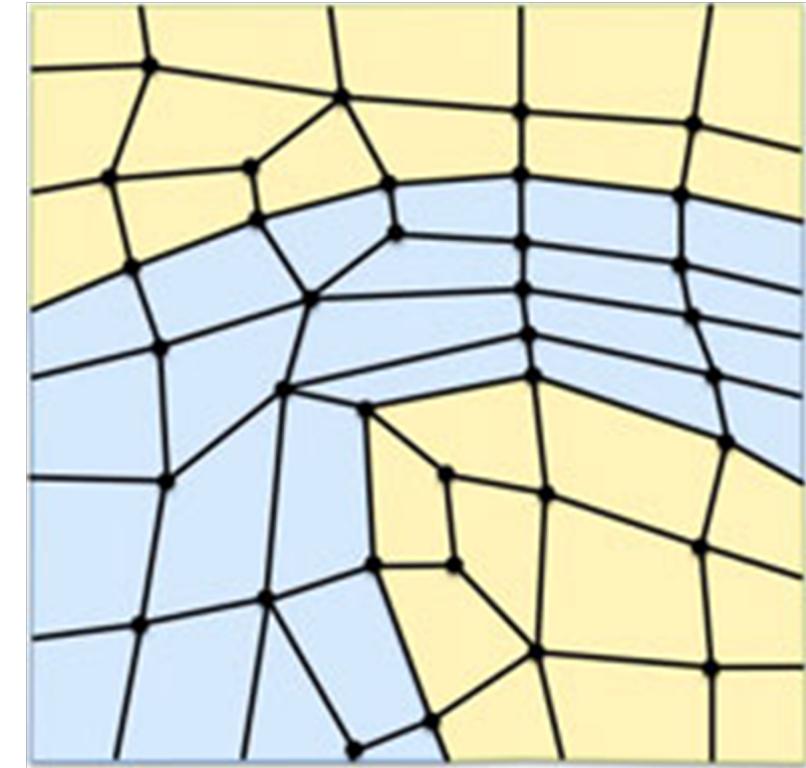
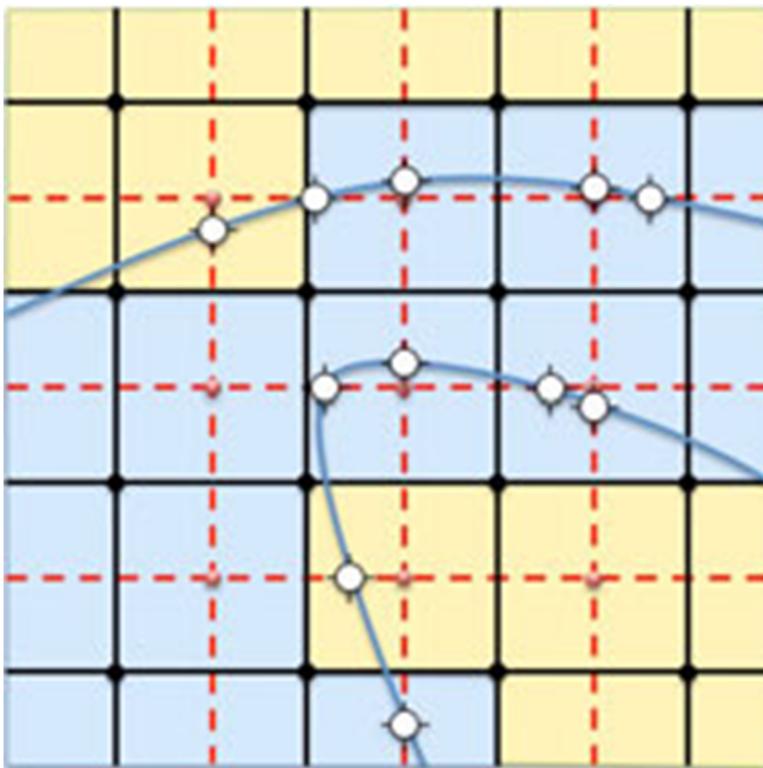
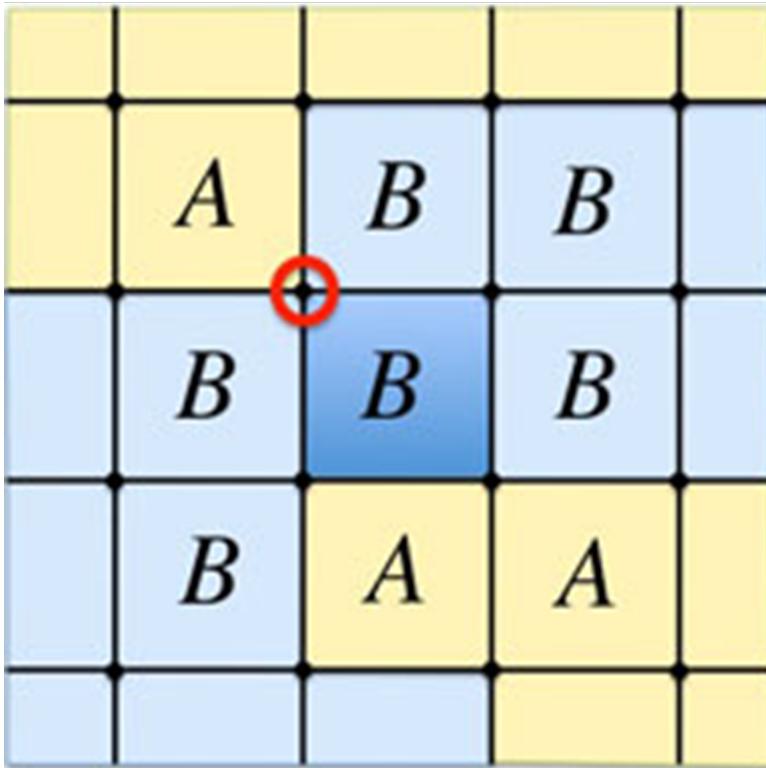
Algorithms we are going to prove things about.

1. Sculpt: Marching-Cubes Hex Meshing 3D

Sculpt images courtesy

Steven J. Owen, Matthew L. Staten, and Marguerite C. Sorensen. Parallel hex meshing from volume fractions. In William Roshan Quadros, editor, *International Meshing Roundtable*, pages 161–178, Berlin, Heidelberg, 2012. Springer Berlin Heidelberg.

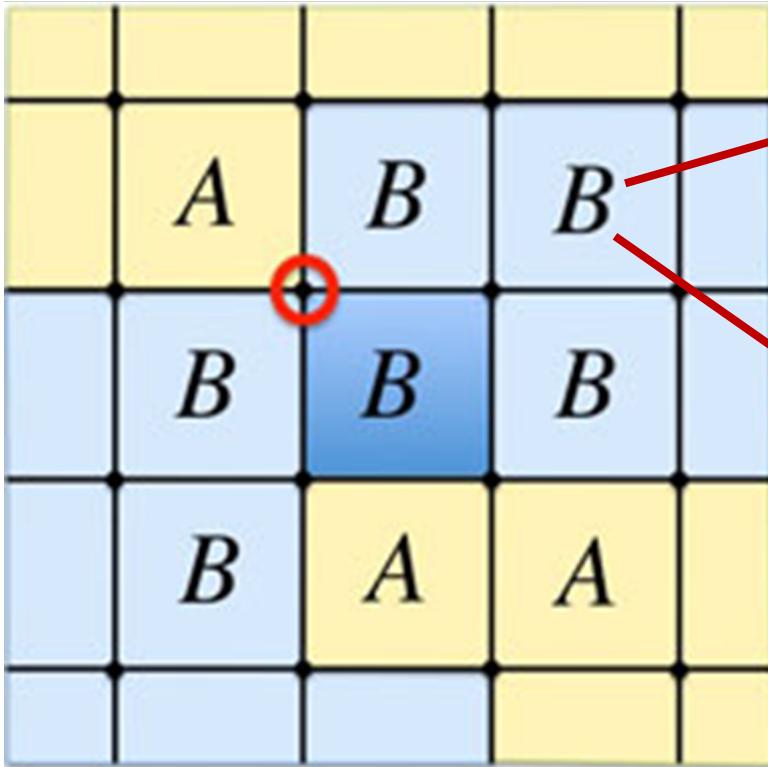
- Background grid
- Assign volume fractions
- Assign materials to nodes
- Construct hex mesh with consistent global topology



Algorithms we are going to prove things about.

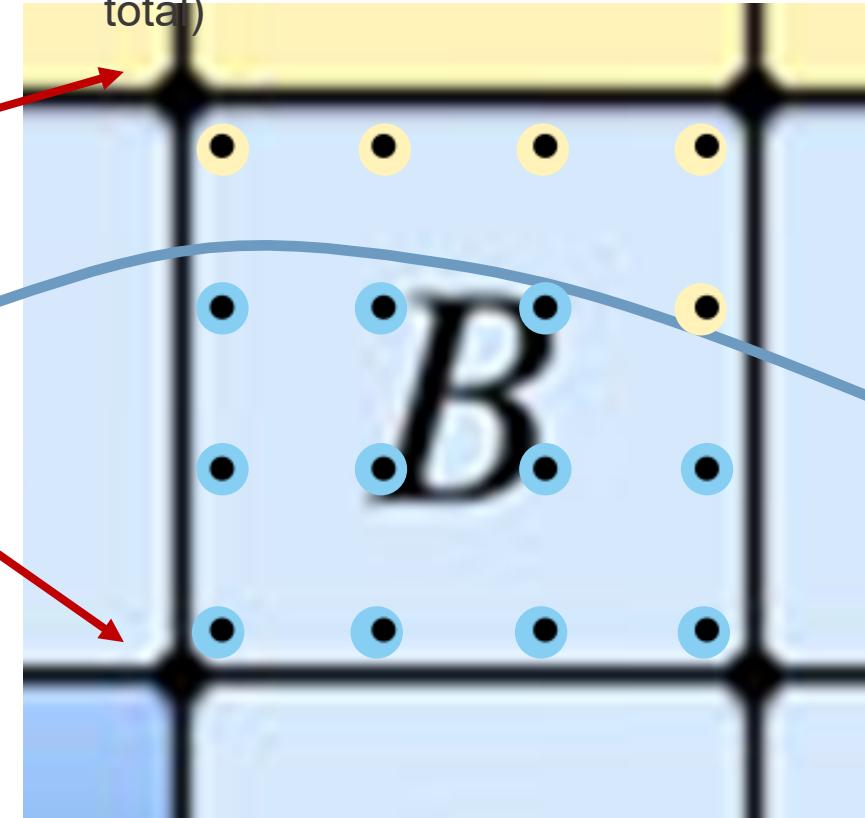
1. Sculpt: Marching-Cubes Hex Meshing 3D

- Background grid
- **Assign volume fractions**



Assign volume fractions

- Discrete query points in each cell
- Determine which volume, A or B, it is inside
 - Is p inside A or out?
 - Is p inside B or out?
- Volume fraction A is $(\text{number in A}) / (\text{number total})$



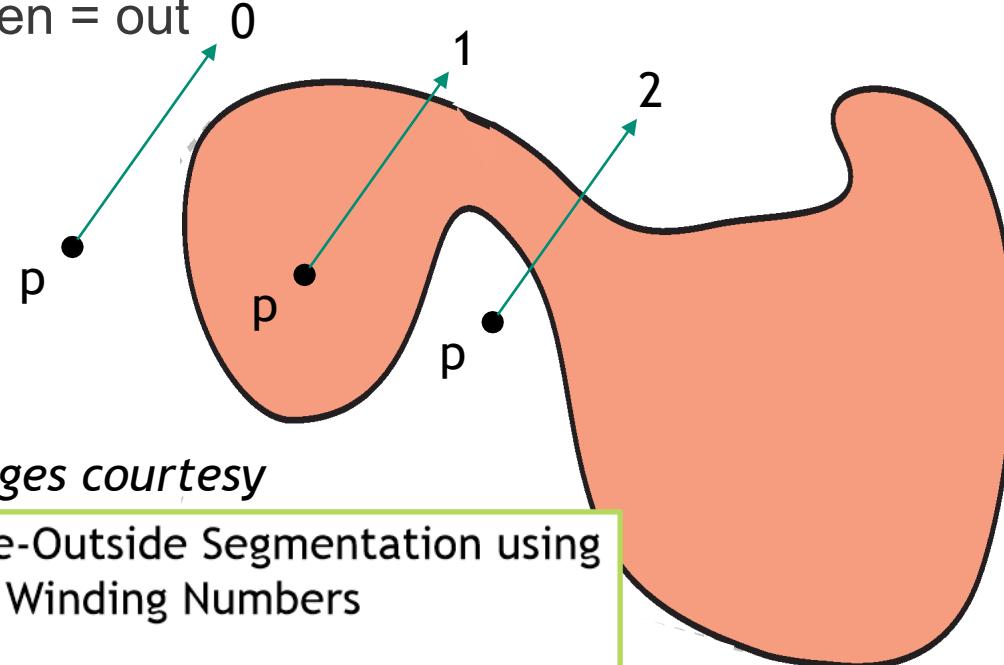
A
Object bdy

B

Ray Casting for Inside/Out



Def. p Inside? Cast (random) **ray** from p to infinity
 Count number of times ray crosses object boundary
 if odd = inside
 even = out



Base images courtesy

Robust Inside-Outside Segmentation using
 Generalized Winding Numbers

Alec Jacobson
 Ladislav Kavan
 Olga Sorkine-Hornung

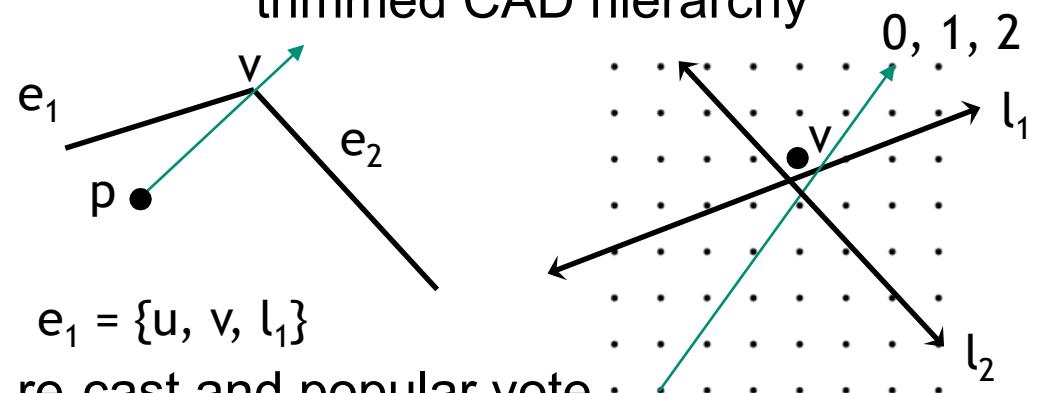
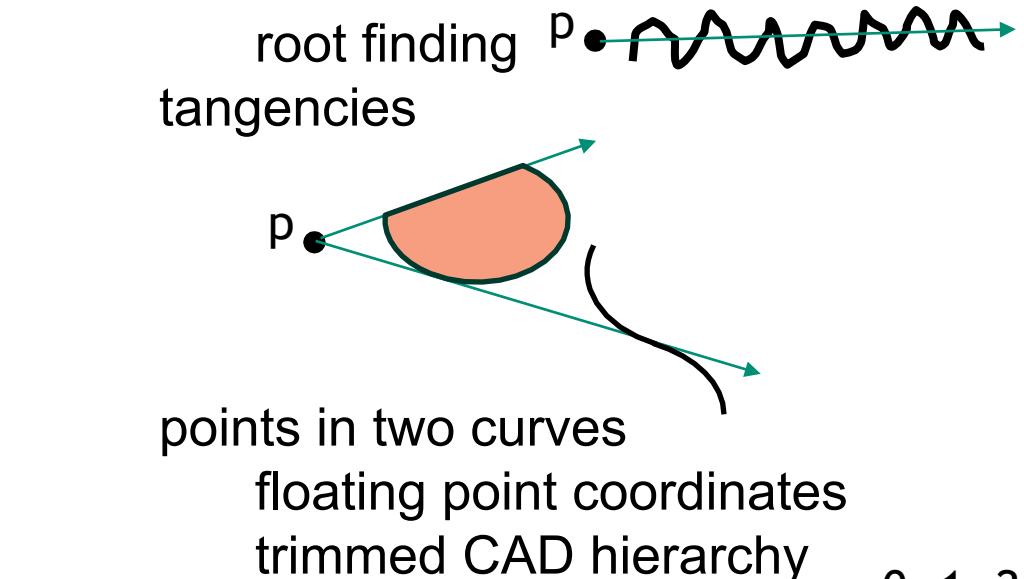
ETH Zurich
 University of Pennsylvania
 ETH Zurich

Challenges:

non-linear surfaces

root finding

tangencies

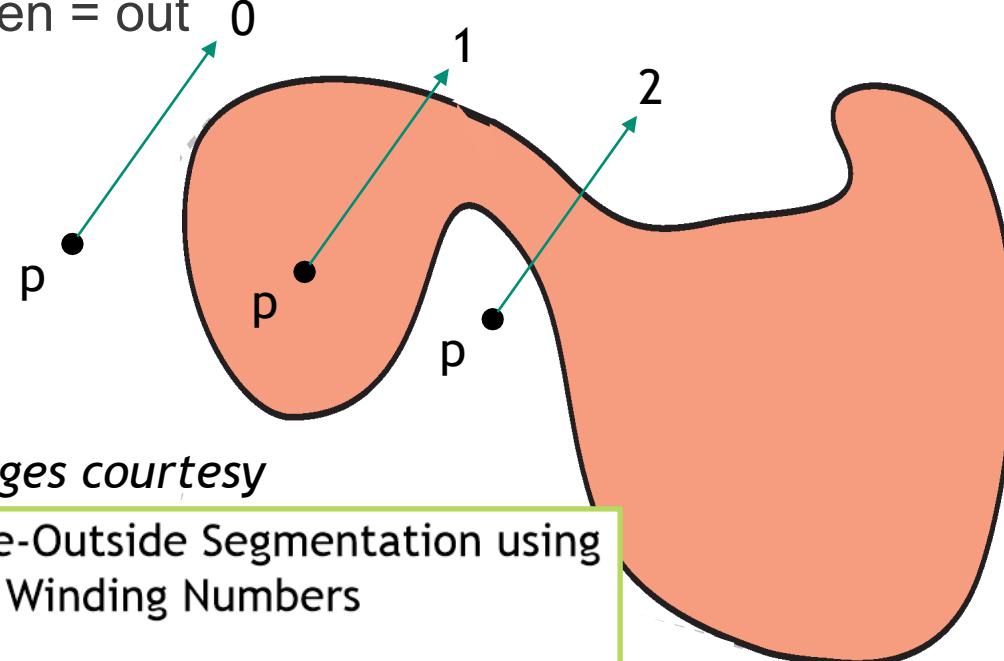


Solutions: re-cast and popular vote

Ray Casting for Inside/Out



Def. p Inside? Cast (random) **ray** from p to infinity
Count number of times ray **crosses** object boundary
 if odd = inside
 even = out



Base images courtesy

Robust Inside-Outside Segmentation using
 Generalized Winding Numbers

Alec Jacobson
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 Olga Sorkine-Hornung

ETH Zurich
 University of Pennsylvania
 ETH Zurich

Fundamental issue:

“Does it cross?” is discrete decision
 based on imprecise floating point calculation
where it crosses

Any discrete **error is large, 1**,
 regardless of how small the error is
 in the floating point calculation

Re-cast and popular vote
 reduces the final probability of error,
 but not its magnitude.

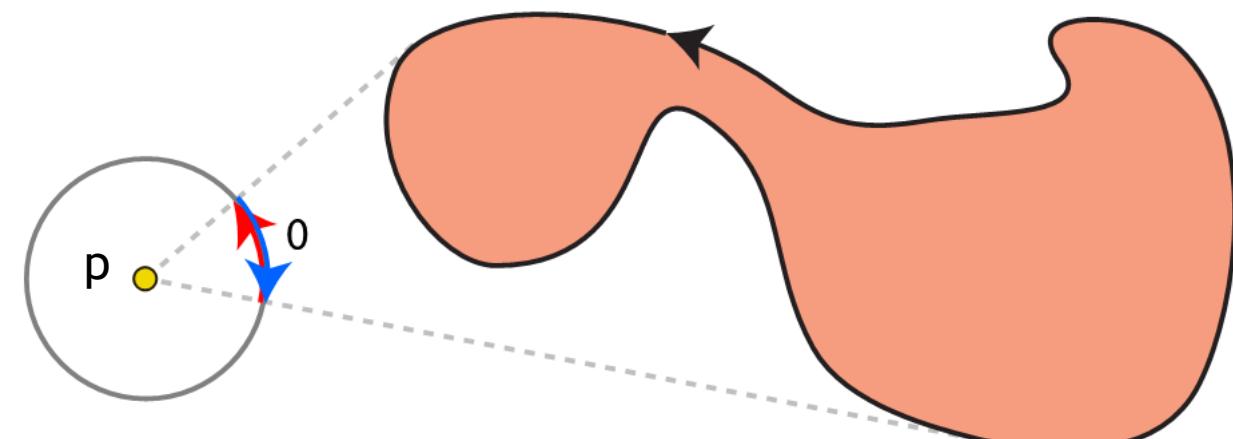
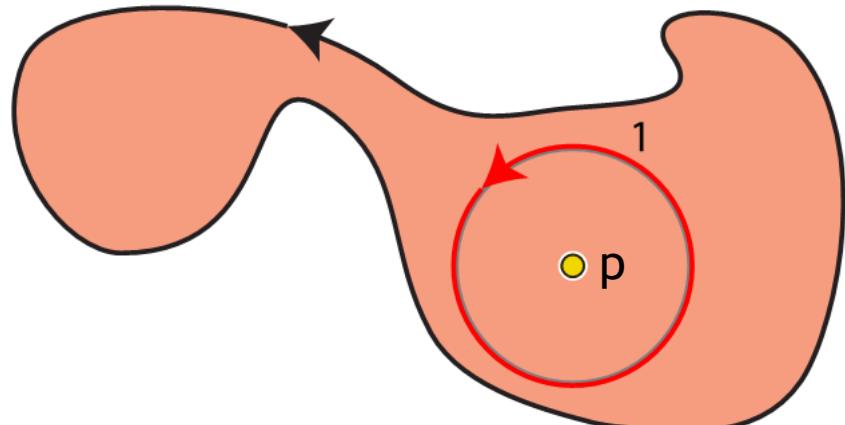
Solutions: re-cast and popular vote

Winding Number for Inside/Out

Def. Winding Number: for query point p , traverse boundary of object, counting the *number* of times it goes (*winds*) around p

$$w(p) = \frac{1}{2\pi} \oint_C d\theta$$

If shape is watertight, winding number is perfect measure of inside



Winding number images courtesy

Robust Inside-Outside Segmentation using Generalized Winding Numbers

Alec Jacobson

Ladislav Kavan

Olga Sorkine-Hornung

ETH Zurich

University of Pennsylvania

ETH Zurich



October 9, 2013



Fundamental improvement:
Answer is a floating point calculation
from entire boundary.

Any error is small, so rounding to 0,1 usually OK
Errors arise in human-ambiguous cases

Winding Number for Inside/Out – how to calculate

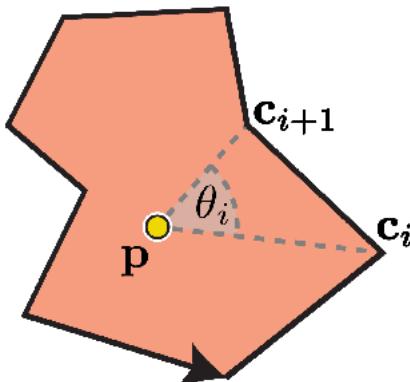


Naive discretization is simple and exact

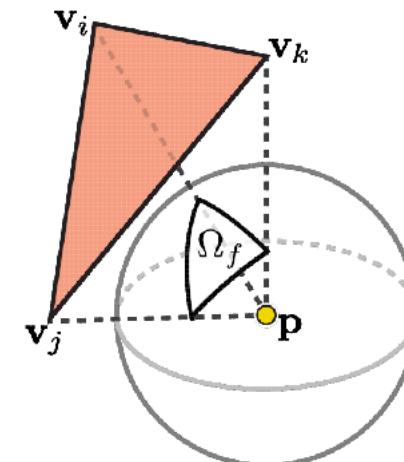
$$w(p) = \frac{1}{2\pi} \int_C d\mathbf{s}$$



$$w(p) = \frac{1}{2\pi} \sum_{i=1}^{n'} \theta_i$$



Generalizes elegantly to 3D via solid angle



$$w(p) = \frac{1}{4\pi} \int_S \sin(\varphi) d\mathbf{s} d\varphi$$



$$w(p) = \frac{1}{4\pi} \sum_{f=1}^{n'} \Omega_f$$

Angle subtended by each boundary piece (triangle)

- Order-independent calculation → easy parallel

Approximate groups of far-away triangles by large triangles, hierarchical octree

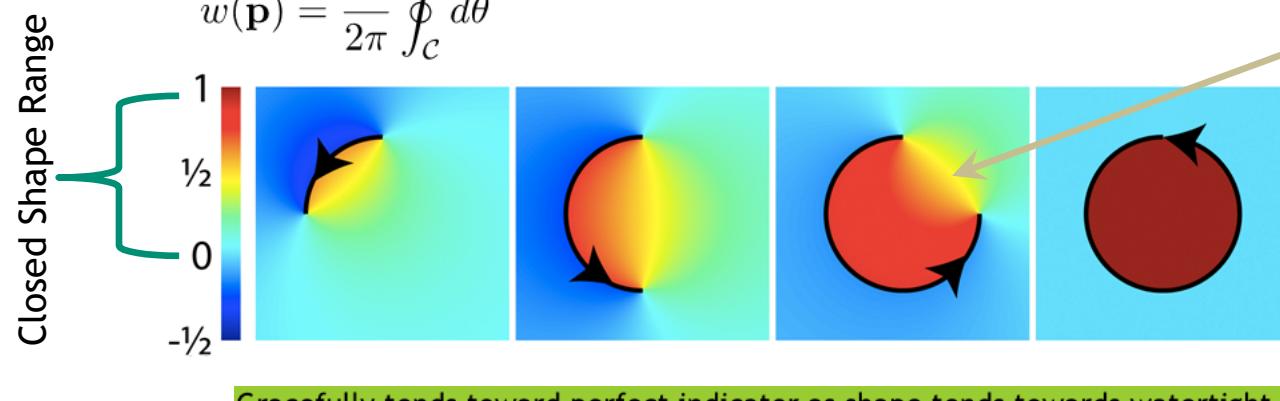
- “Fast Winding Numbers for Soups and Clouds”

Winding Number for Inside/Out of Ugly Geometry



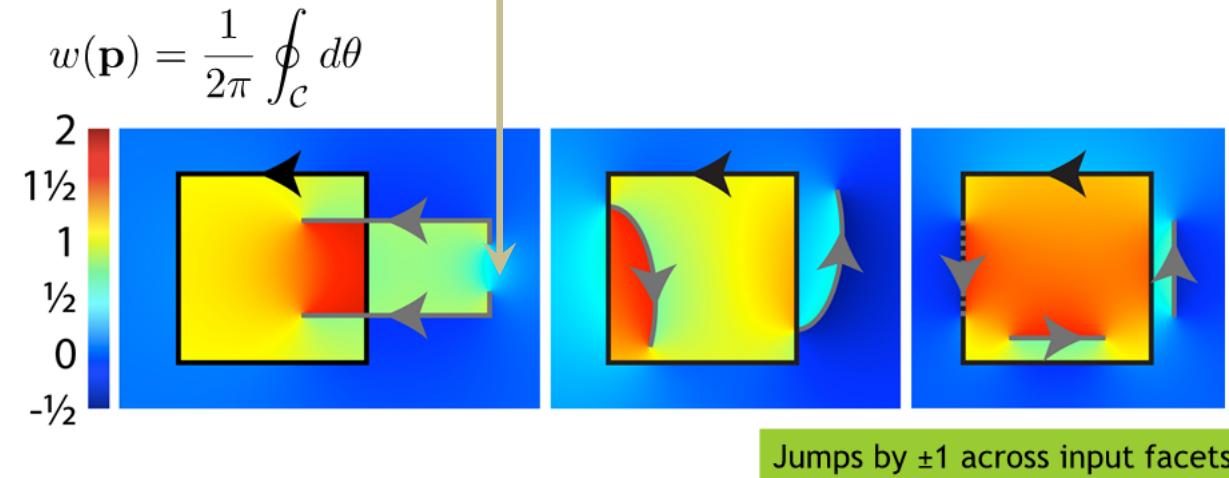
Types of ugliness:

What happens if the shape is open?

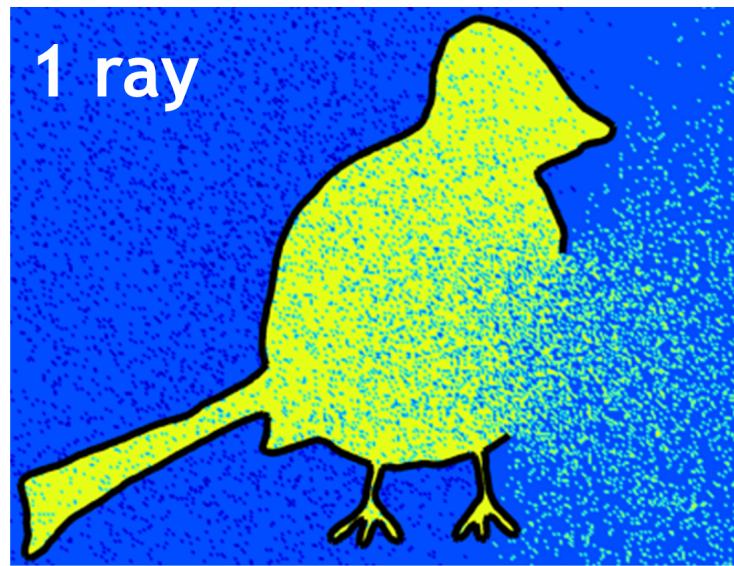
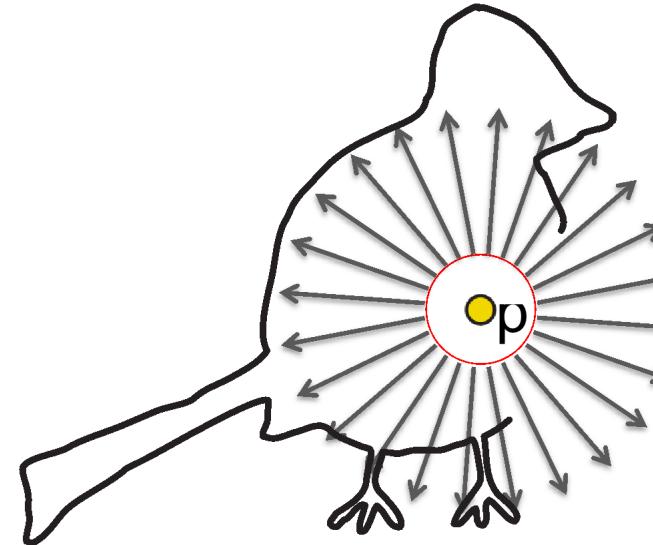
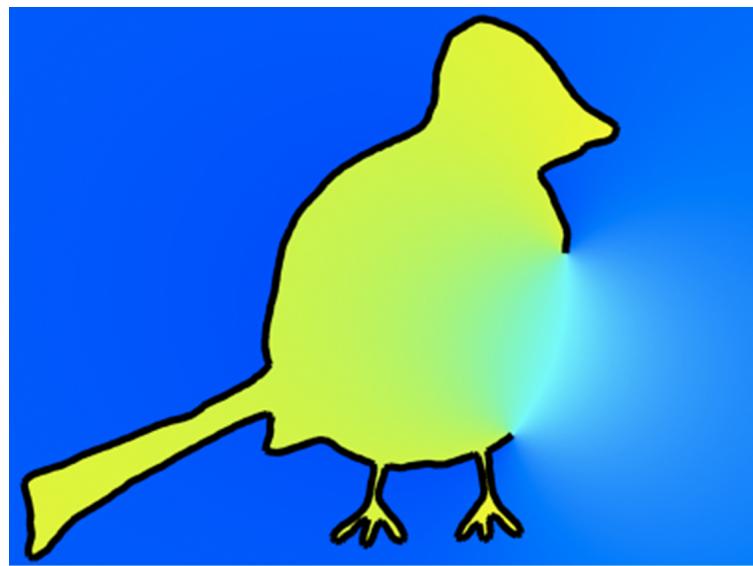
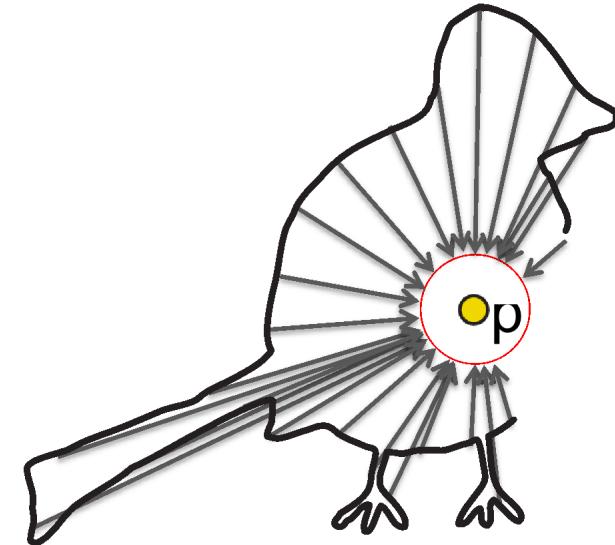


Ambiguous cases for humans and winding numbers (≈ 0.5) coincide

What if shape is self-intersecting? Non-manifold?



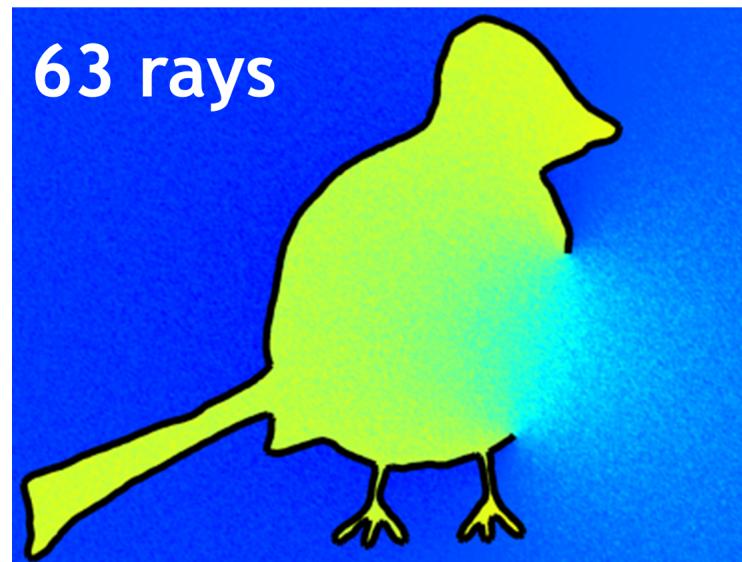
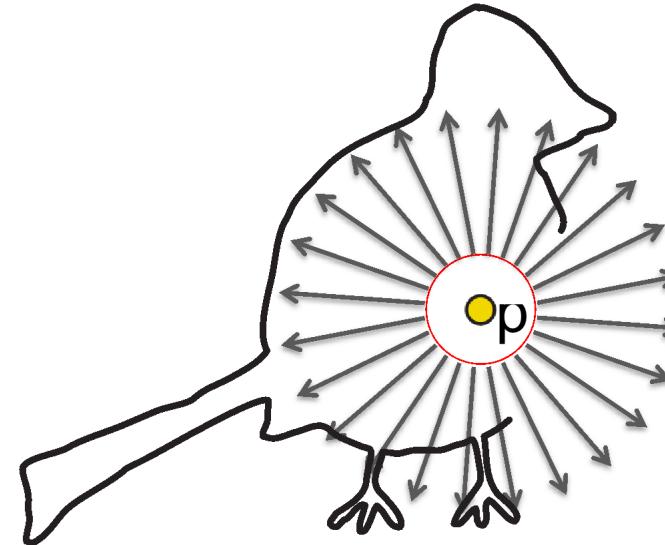
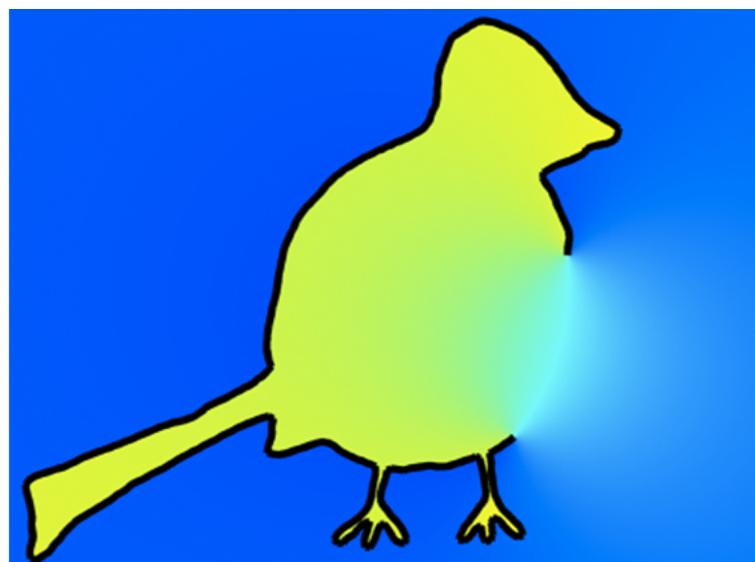
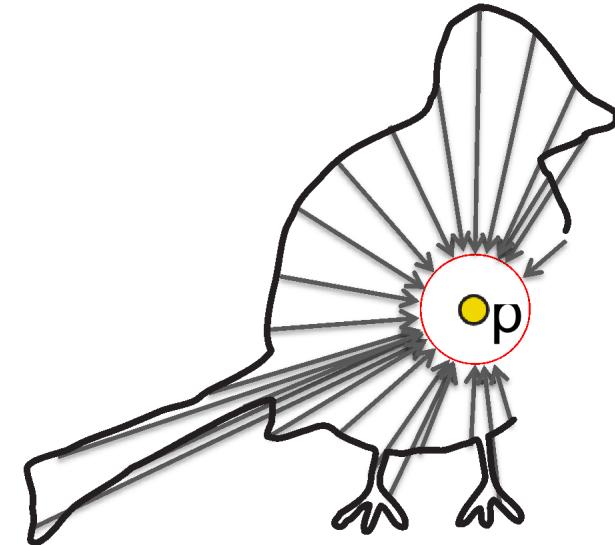
Winding Number Ambiguity vs. Ray Casting Errors



1 ray

Causes serious issues
for algorithms that
mesh convex hull and
discard elements
outside

Winding Number Ambiguity vs. Ray Casting Errors



63 rays

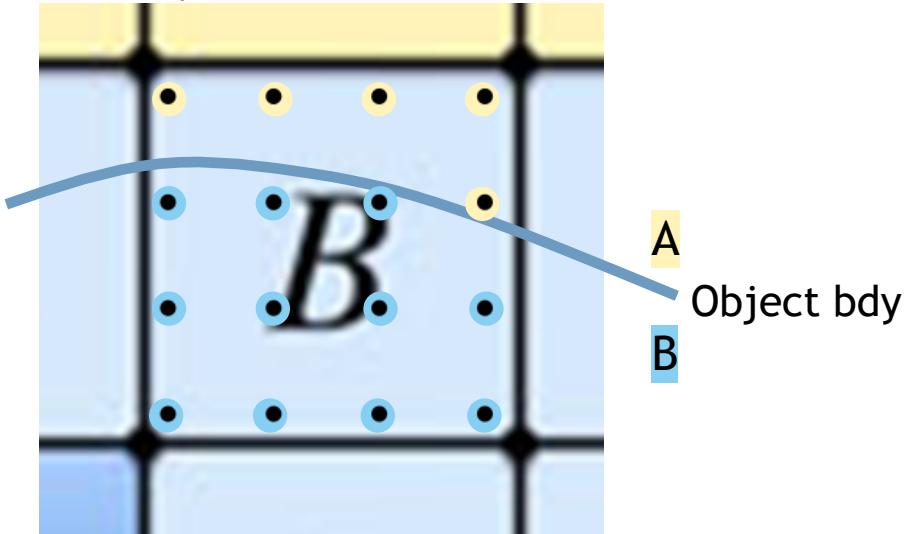
Sculpt Volume Fractions from Winding Number from libigl



igl open-source

Assign volume fractions

- Discrete query points in each cell
- Determine which volume, A or B, it is inside
 - Is p inside A or out?
 - Is p inside B or out?
- Volume fraction A is (number in A / (number total))



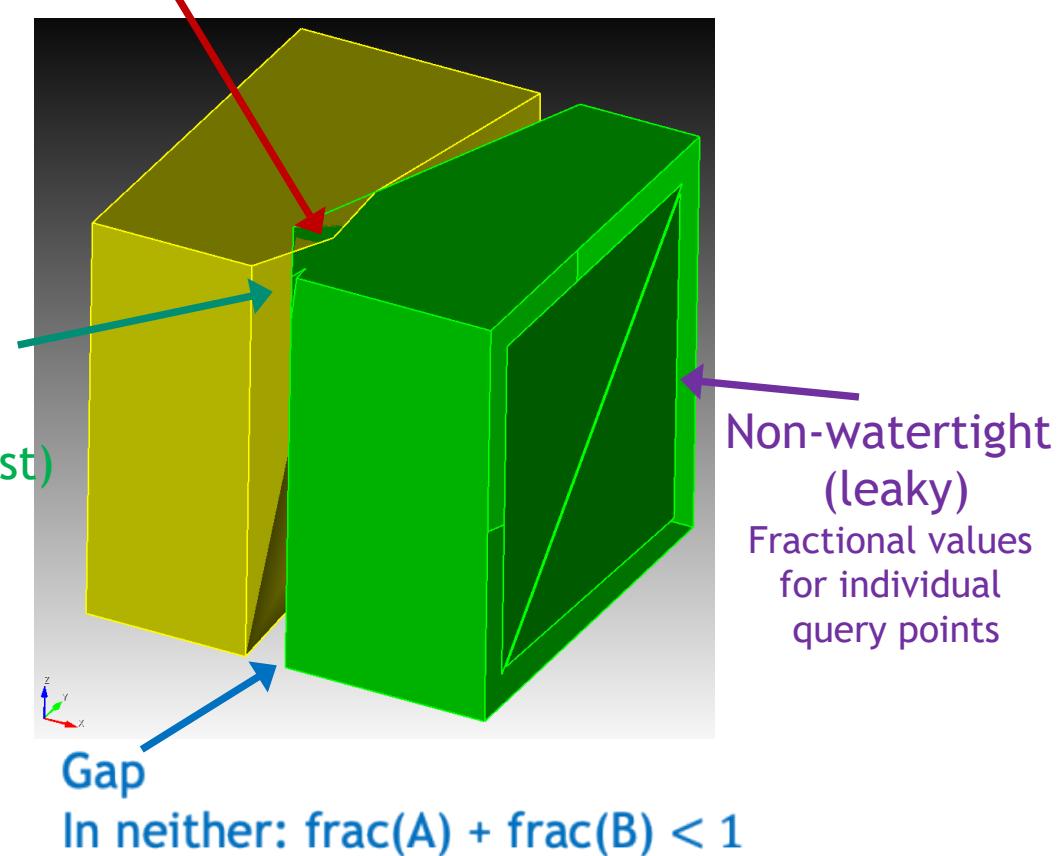
Feature smaller
than grid
(scale of interest)

Regular background grid of cells and query points

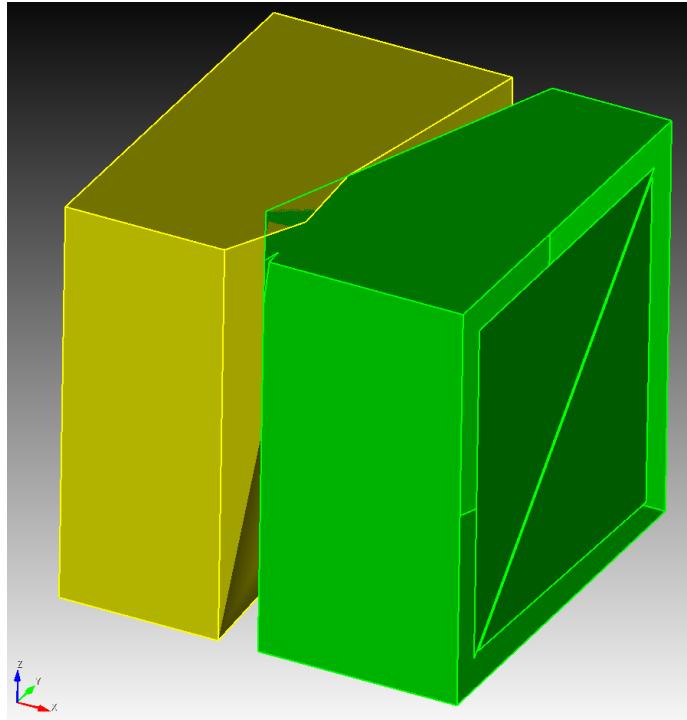
- Normalize if sum fractions >1 or <1

In both A and B: $\text{frac}(A) + \text{frac}(B) > 1$

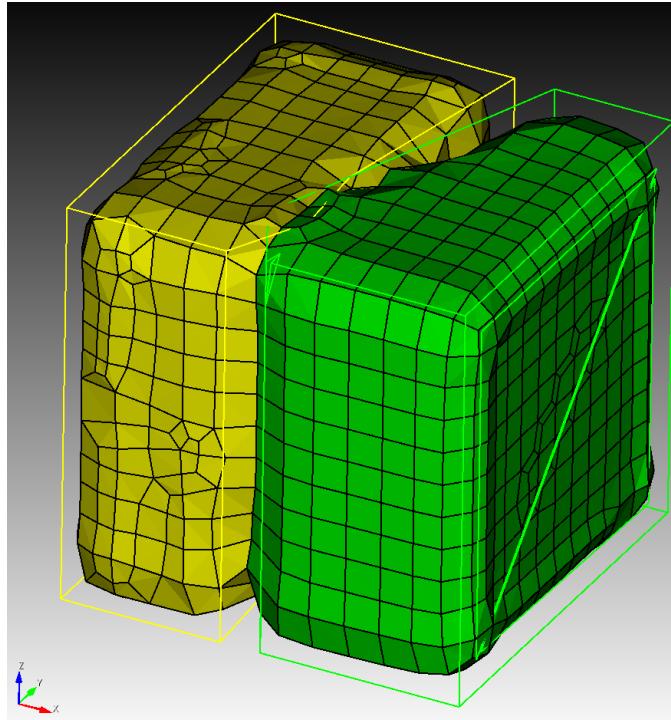
Overlap



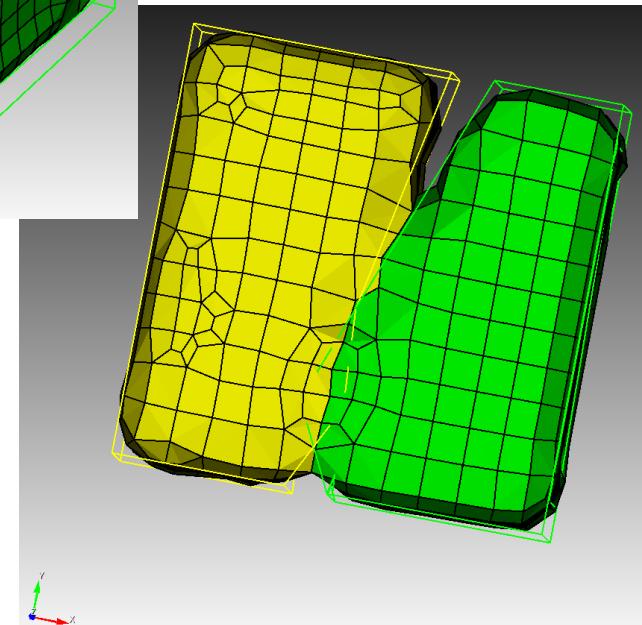
Sculpt Mesh from Uniform Background Grid



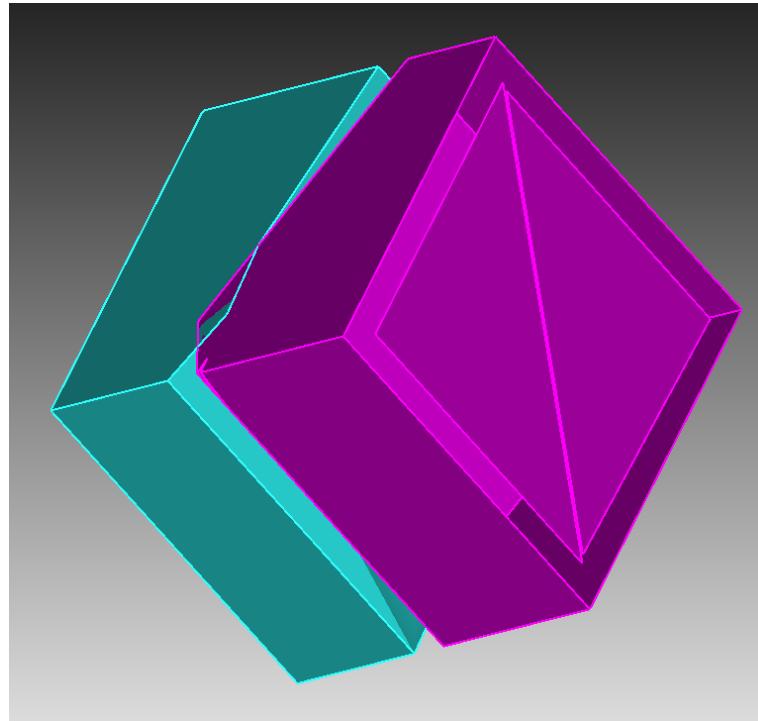
Input



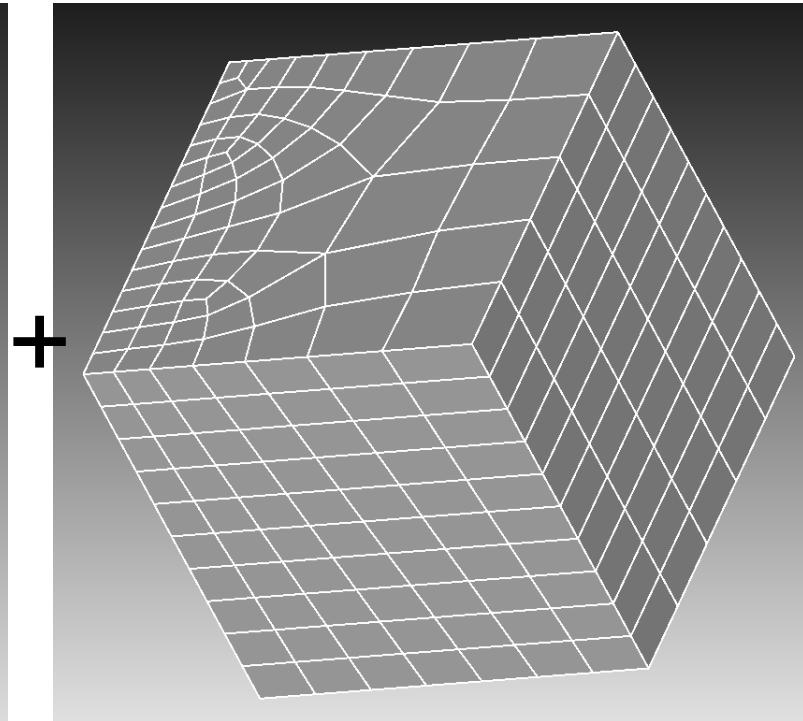
Output



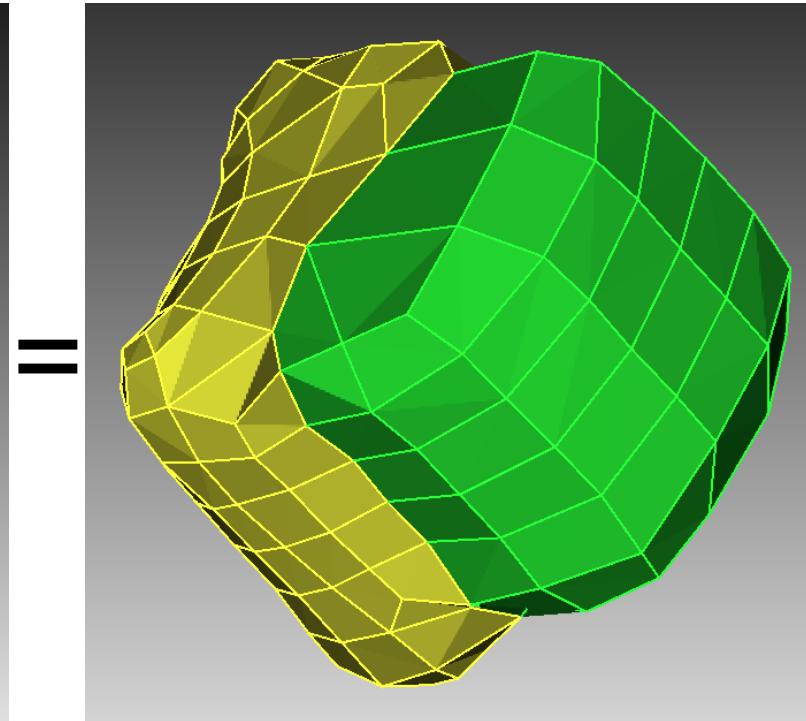
Sculpt Mesh from Custom Background Grid



Input
Geom



Input
Grid



Output
Mesh

Future work



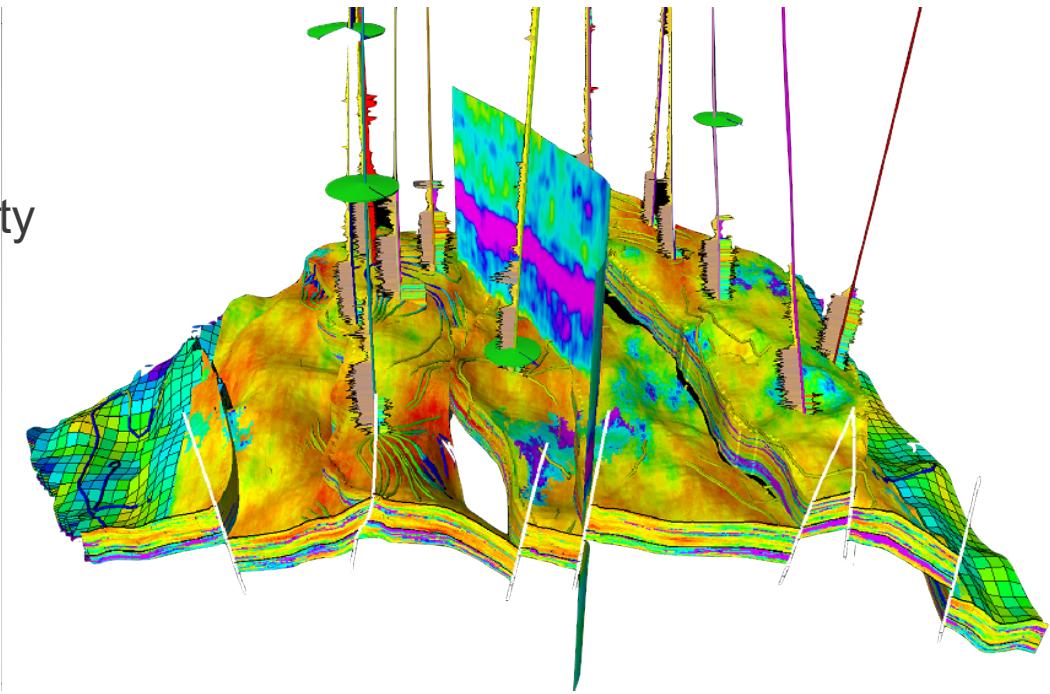
Use persistent homology of ugly geometry to

- Quantify tradeoffs between topological and geometric fidelity
- Predict mesh topology for given background grid
- Choose background grid size to achieve given user-desired topology
- Aleph — **A Library for Exploring Persistent Homology**



Use shrink wrapping to

- Mesh finer than geometric fidelity
- Non-noisy mesh despite noisy geometry



More complex domains



Thank you

This material is based upon work supported by the U.S. Department of Energy, Office of Science, Office of Advanced Scientific Computing Research (ASCR), Applied Mathematics Program.

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