



Optimization of an Optical Shutter using Machine Learning

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- Topology Optimization
 - Structural
 - Photonics
- Most basic form
 - Discretize problem
 - Governing equations, boundary conditions
 - Finite element setup
 - Allocate a given amount of material across the points
 - **Density function (ρ)**
 - Determine objective (cost) function to minimize
 - Extinction ratio and temperature rise targets
 - **Solve finite element model**
 - Sensitivity analysis
 - Updates
 - **Repeat**

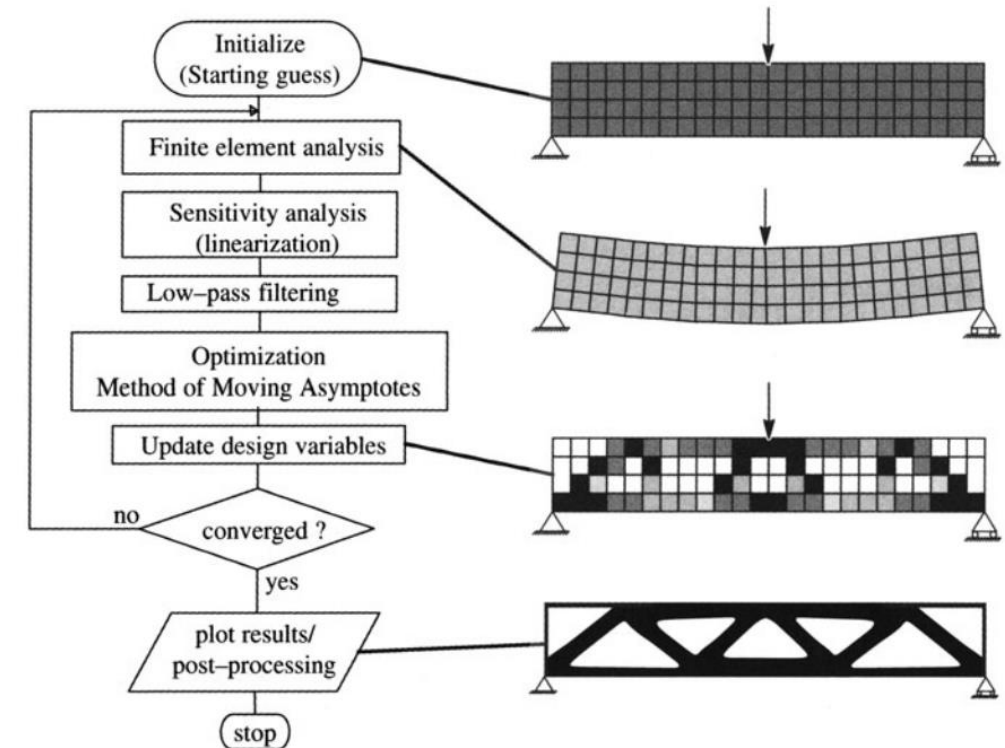
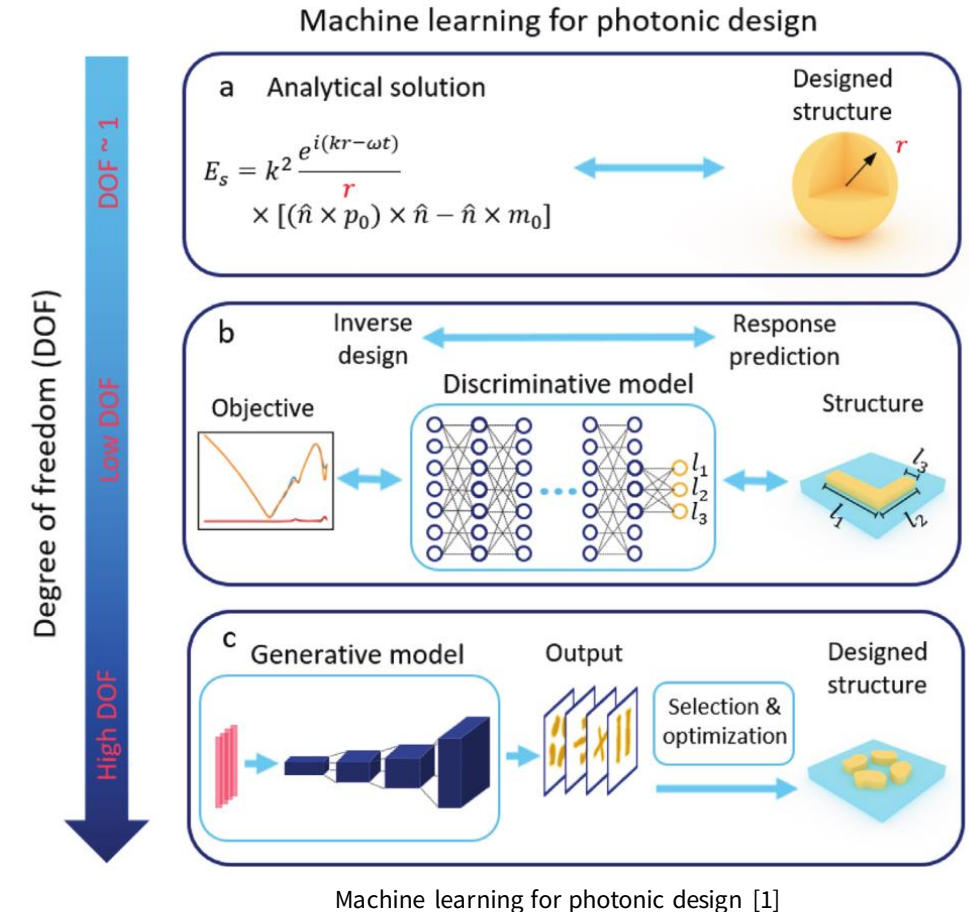


Fig. 1.5. The flow of computations for topology design using the material distribution method and the Method of Moving Asymptotes (MMA) for optimization. The low-pass filter step (filtering of sensitivities) is discussed in Sec. 1.3.1.

Source: Bendsoe and Sigmund, "Topology Optimization: Theory, Methods, and Applications", 2003

- Challenges
 - **Requires costly finite element solver calls each iteration**
 - Large optimization problems
 - Parallel Computing
 - Advanced iterative solvers
 - Multi-scale or Multi-Resolution Approaches
- Neural Networks in Topology Optimization [1]
 - Supplement
 - Replace
 - Solver
 - Predict density function [2]



[1] Z. Liu, D. Zhu, L. Raju, and W. Cai, "Tackling Photonic Inverse Design with Machine Learning", Advanced Science, vol. 8, no. 5, p. 2002923, Mar. 2021.

[2] A. Chandrasekhar and K. Suresh, "TOuNN: Topology Optimization using Neural Networks", Structural and Multidisciplinary Optimization, vol. 63, no. 3, pp. 1135–1149, Mar. 2021.

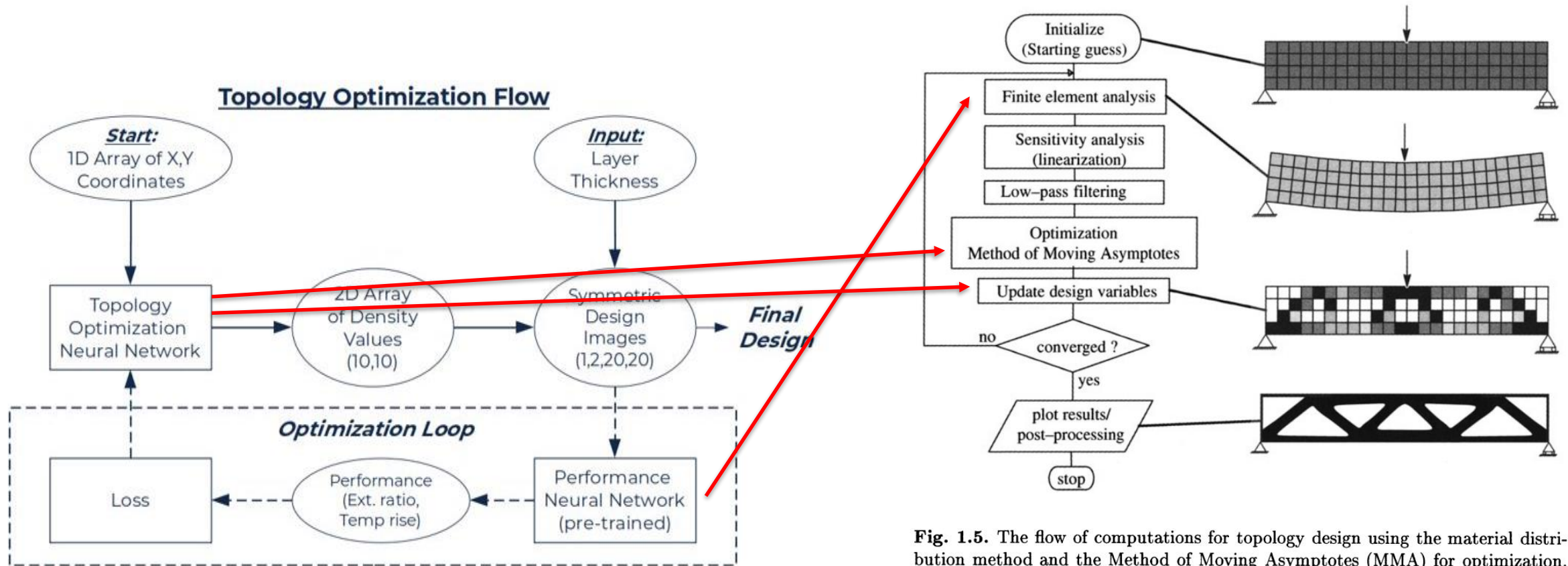


Fig. 1.5. The flow of computations for topology design using the material distribution method and the Method of Moving Asymptotes (MMA) for optimization. The low-pass filter step (filtering of sensitivities) is discussed in Sec. 1.3.1.

Can we perform traditional topology optimization with a dual neural network approach?

- Artificial Neural Networks (NNs)
 - Collection of nodes ("neurons")
 - Weights and biases
 - Non-linear activation function
 - Application examples: image classification, regression
- Utilize Convolutional Neural Networks (CNNs)
 - Heavily used for image recognition
 - Train model using labeled data (supervised model)
 - Replace solver call after training
 - Scanning an image, looking for patterns
 - Excels at image/pattern recognition
 - Dot product between kernel (filter) and feature combine to create feature map
- Utilizing Pytorch, an open source ML package

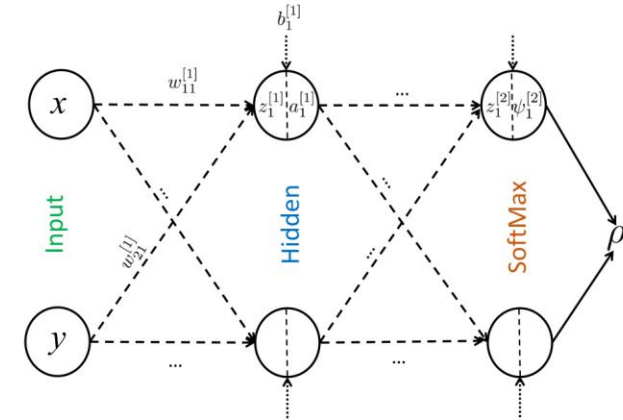
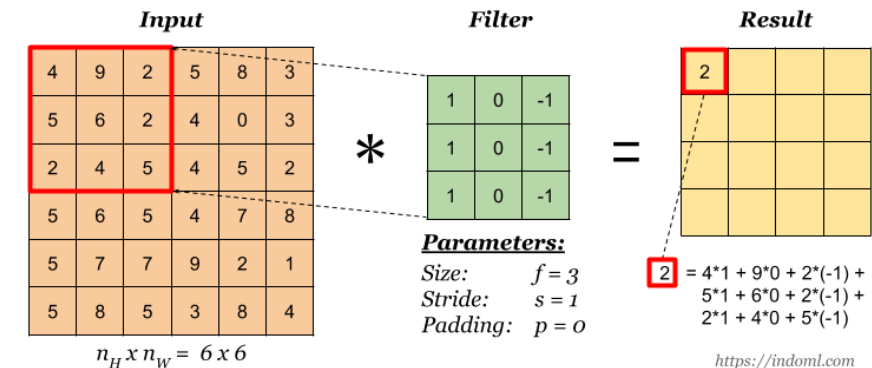


Fig. 4 Illustration of a simple network with one hidden layer of height 2

Source: Chandrasekhar and Suresh, "TOuNN: Topology Optimization using Neural Networks," <https://doi.org/10.1007/s00158-020-02748-4>

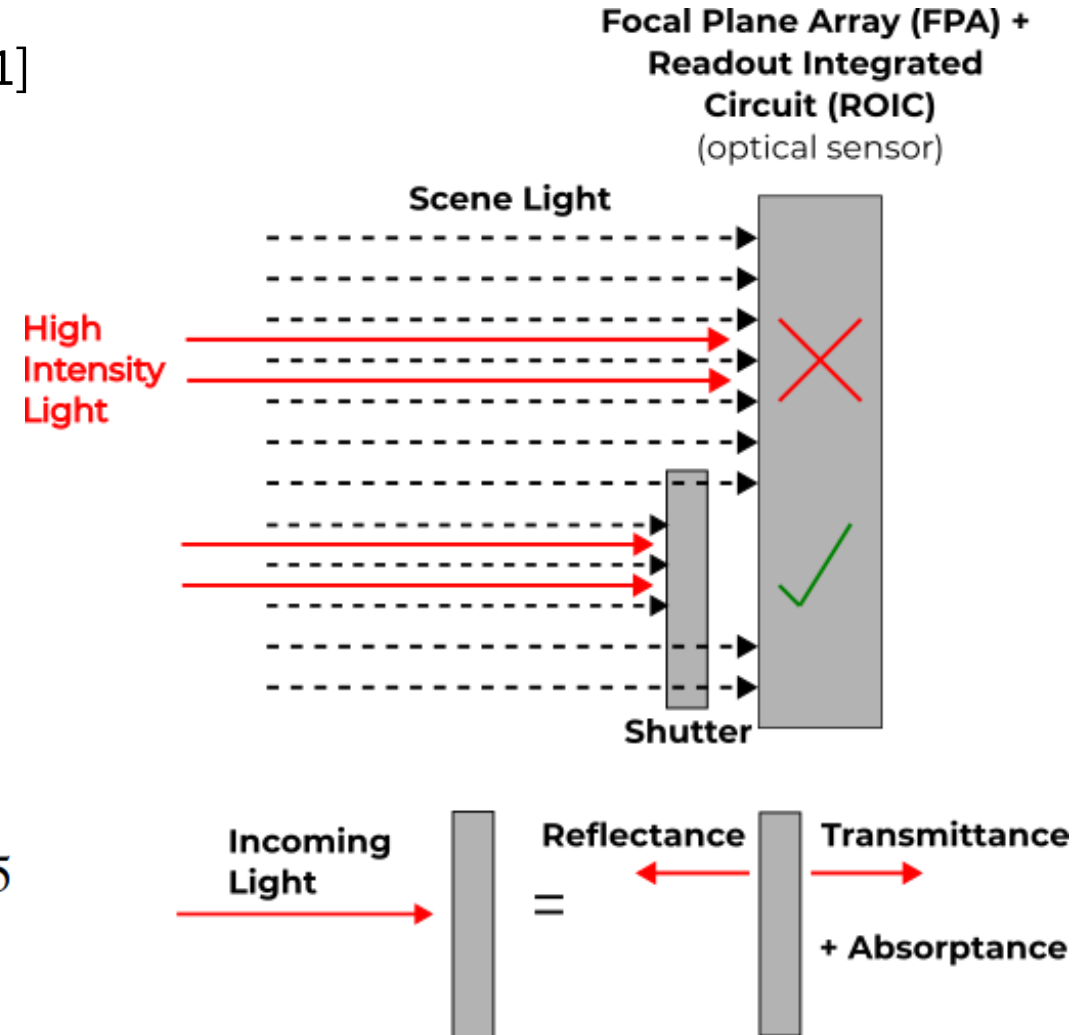


Source: <https://medium.com/analytics-vidhya/everything-you-need-to-know-about-convolutional-neural-networks-cnns-3a82f7aa29c5>

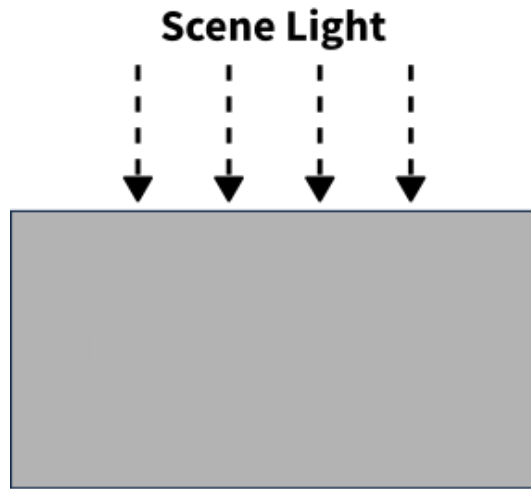
- **Application:** sensor protection using optical shutter [1]
 - Passive
 - Thermal activation
- Utilize **Vanadium Dioxide (VO₂)**
 - Phase change material
- Figures of merit
 - Extinction ratio
 - Temperature rise

$$\text{extinction ratio} = ER = 10 \log_{10} \frac{T_{r_{ins}}}{T_{r_{met}}}$$

$$\text{temperature rise} = dT = \text{Final Temperature} - 273.15$$

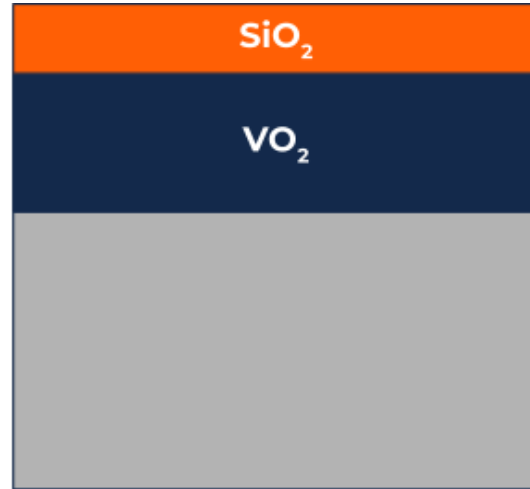


[1] M. G. Wood, A. McKay, T. J. Morin, D. K. Serkland, T. S. Luk, S. L. Wolfley, L. Gastian, J. P. Mudrick, B. Jaspersion, and H. T. Johnson, "Optically-triggered optical limiters for short-wavelength infrared sensor protection", in 2021 Conference on Lasers and Electro-Optics (CLEO), 2021, pp. 1–2.



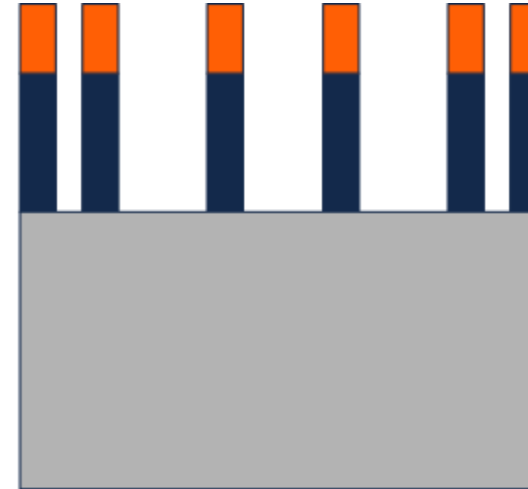
No Film

Low Extinction
No Temp Rise



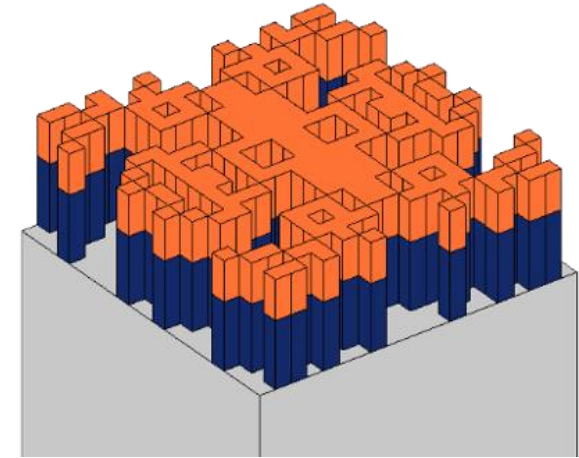
Full Film

High Extinction
Avg Temp Rise



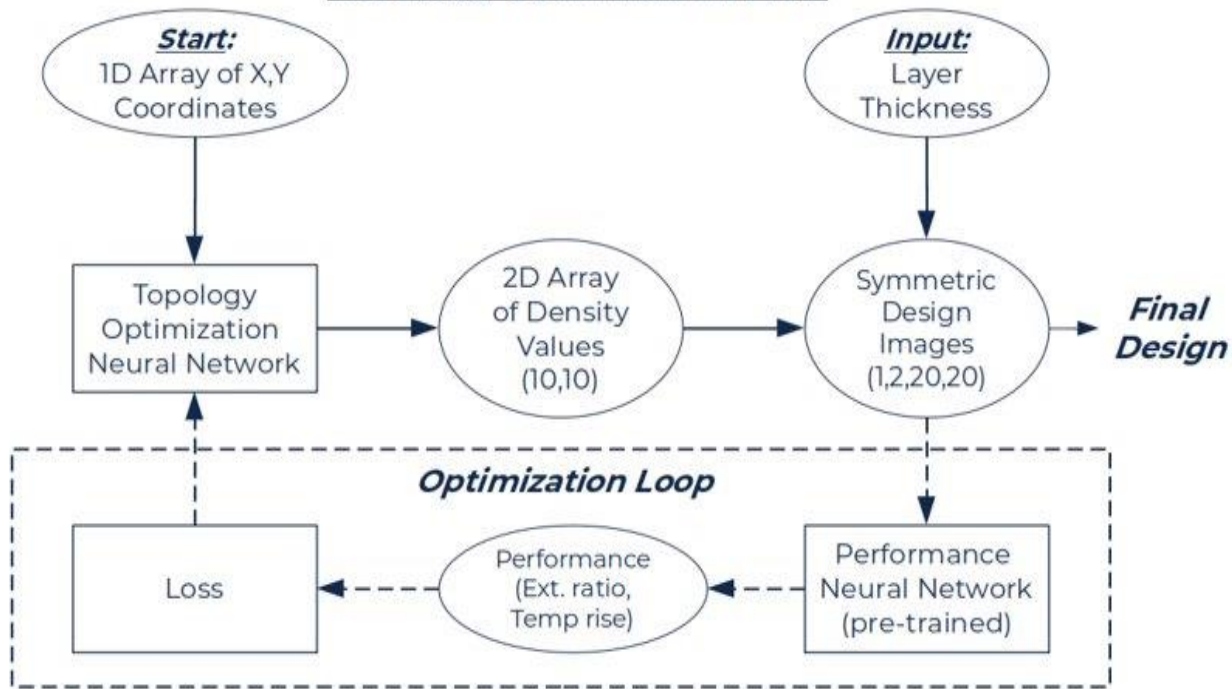
Pixelated Design

Intermediate Extinction
Improved Temp Rise?



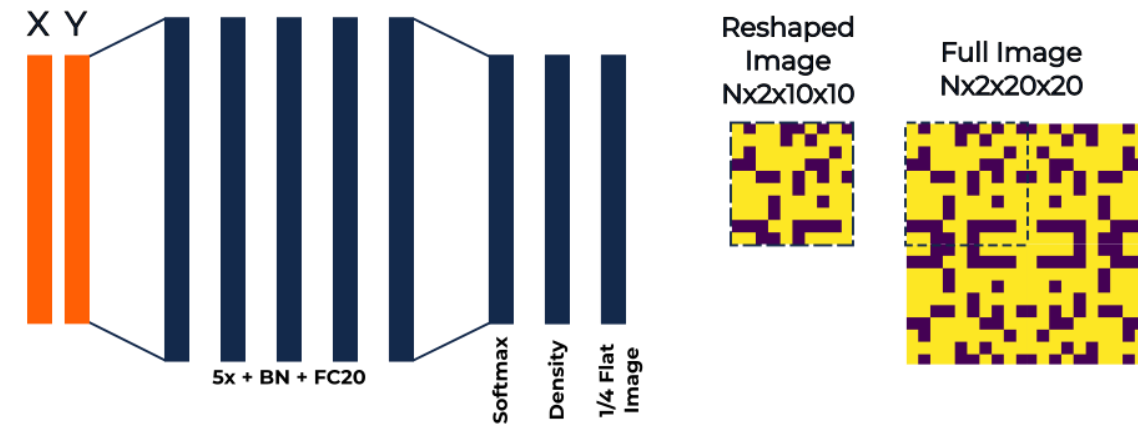
Can we find a pixelated design that maximizes temperature rise for a given extinction ratio?

Topology Optimization Flow

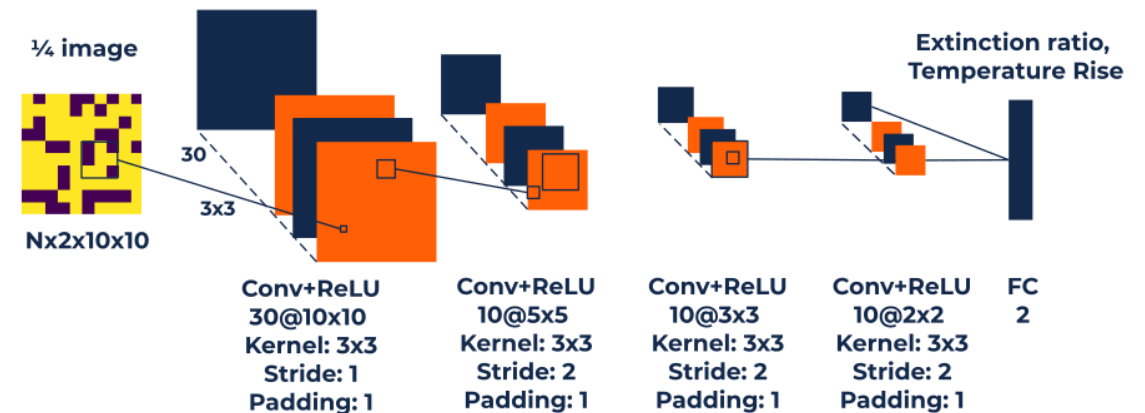


$$\text{Loss} = \left(\frac{ER_{pred} - ER_{target}}{ER_{target}} \right)^2 + \left(\frac{dT_{pred} - dT_{target}}{dT_{target}} \right)^2$$

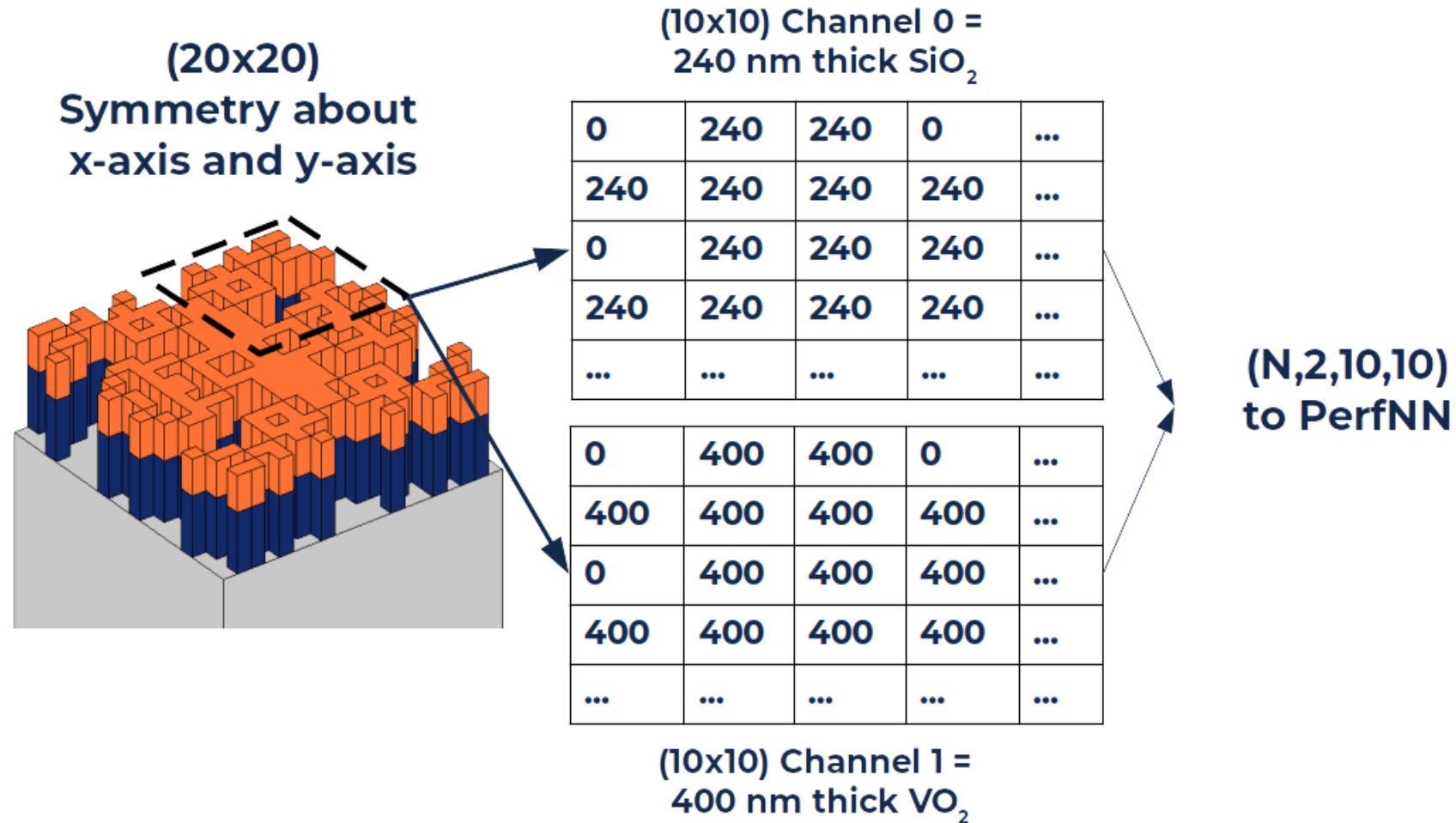
Topology Optimization Neural Network (5x) Batchnorm + Linear hidden layers (20 nodes per layer)

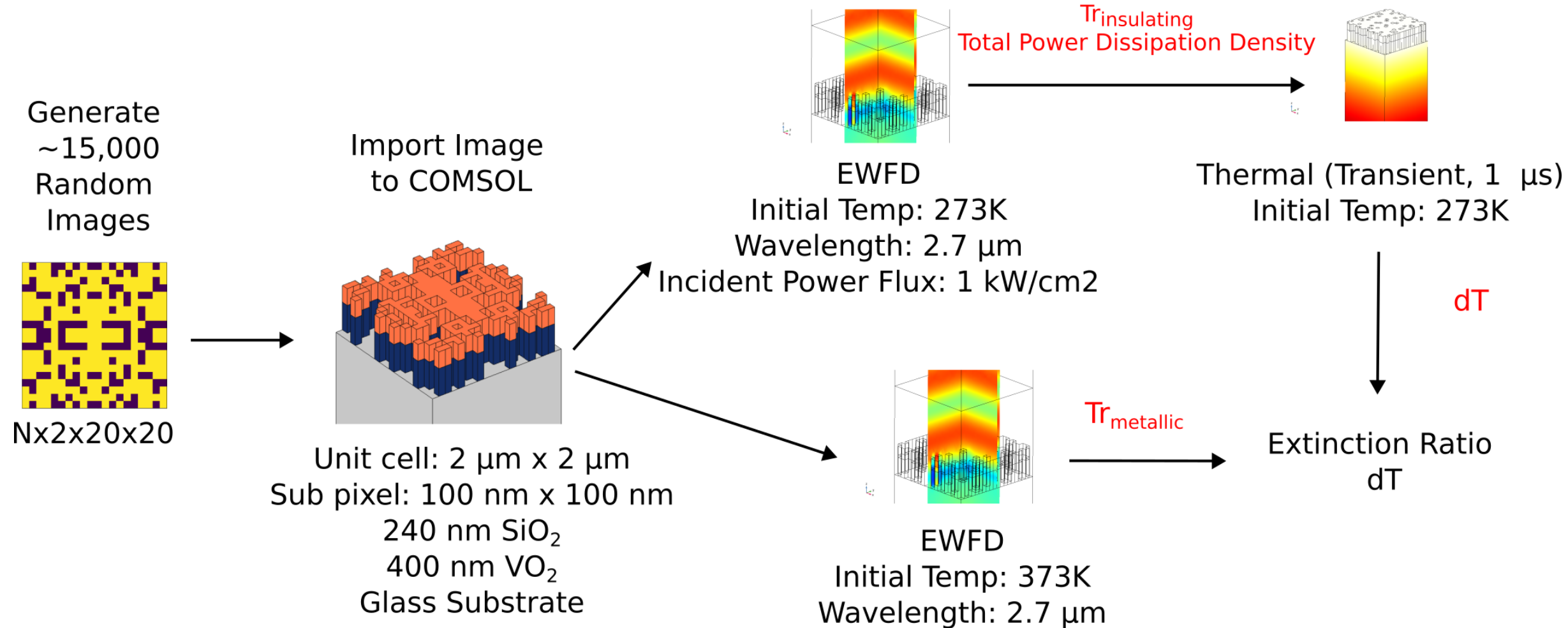


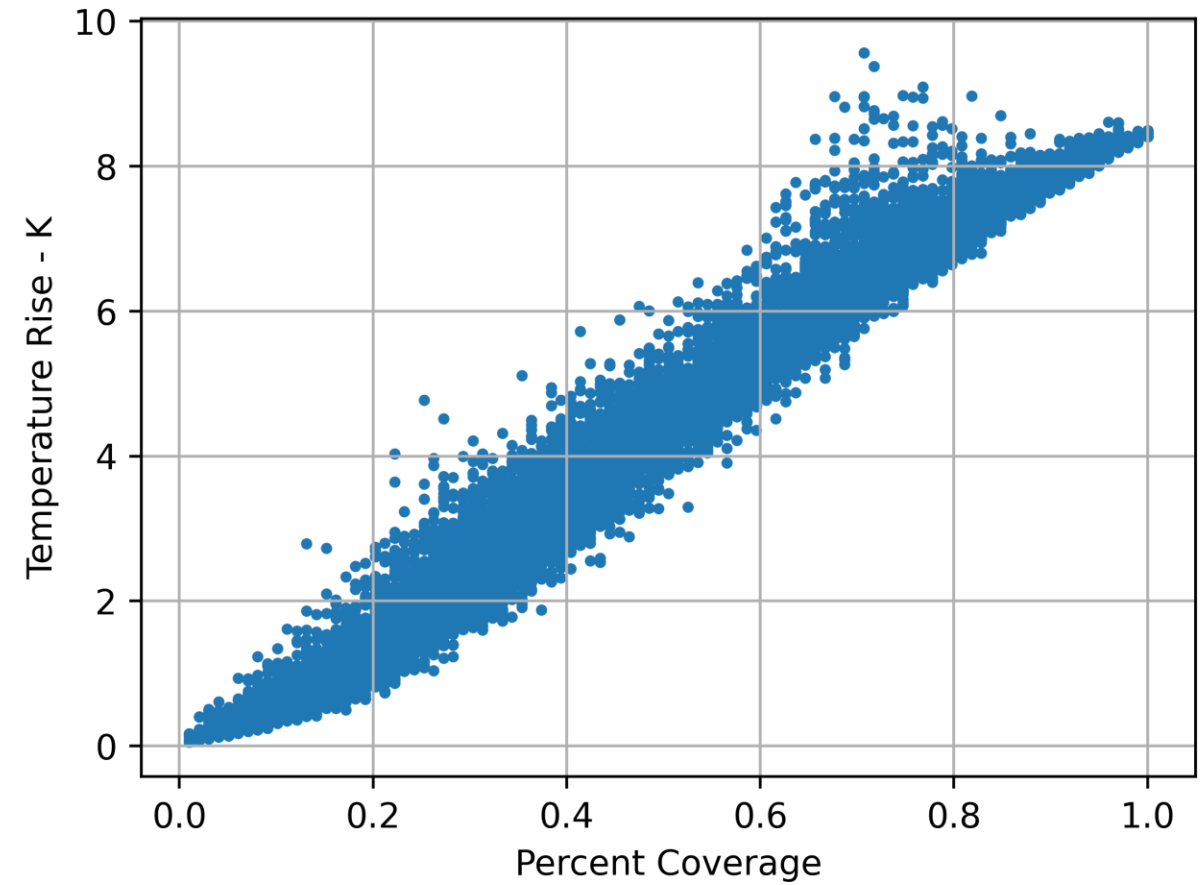
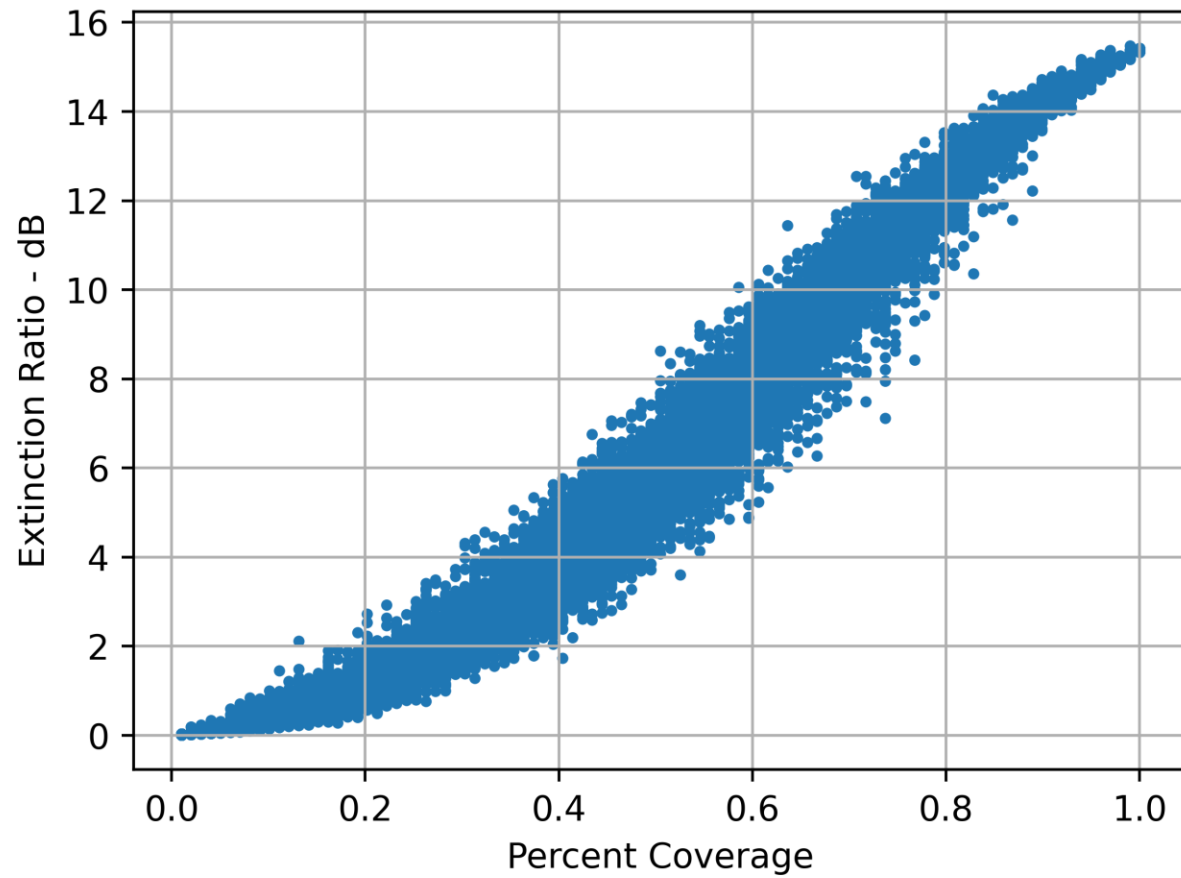
Performance Neural Network 4x Convolutional Layers + ReLU 1x Fully Connected Linear Layer

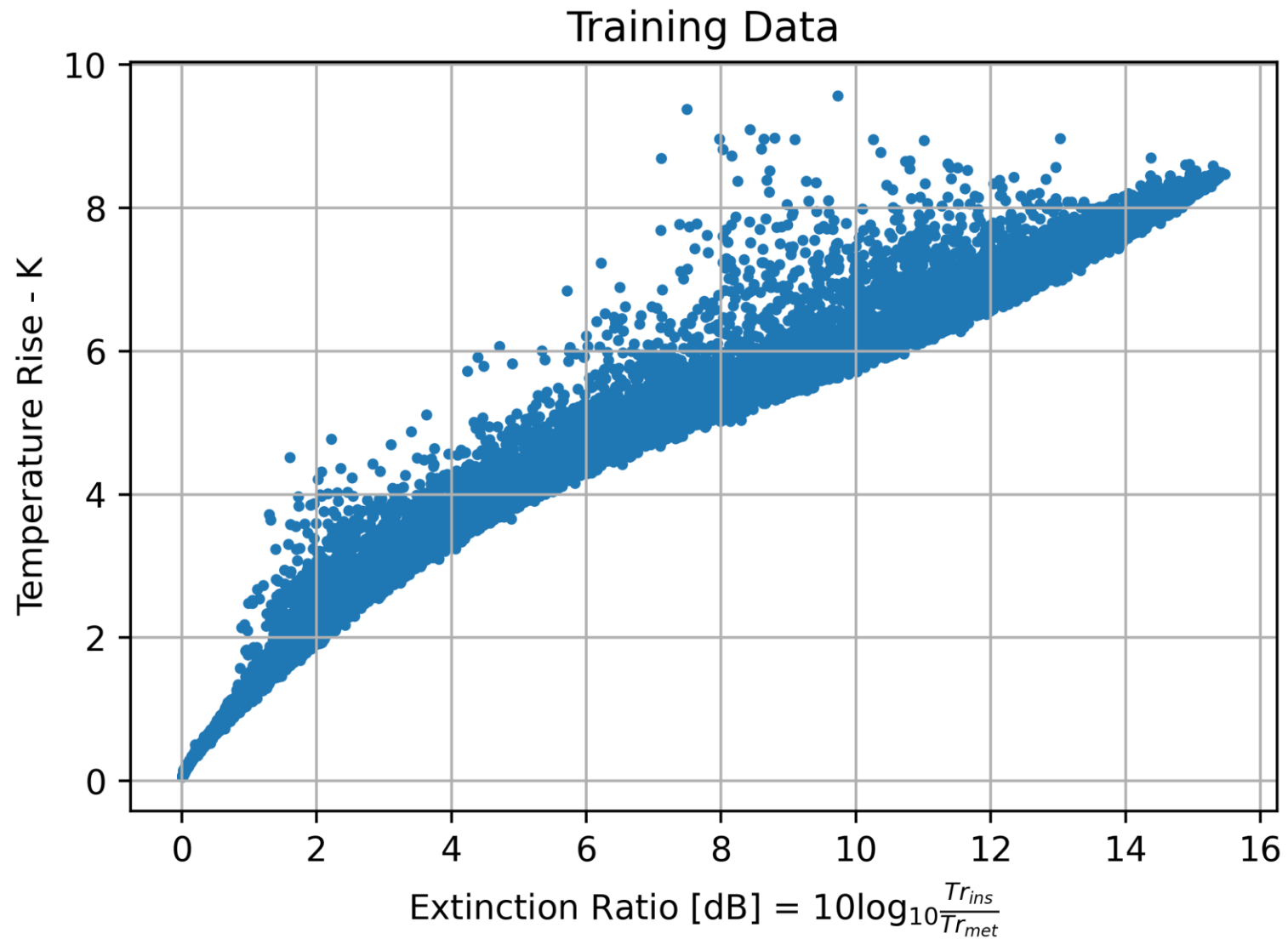


Design as Input Image





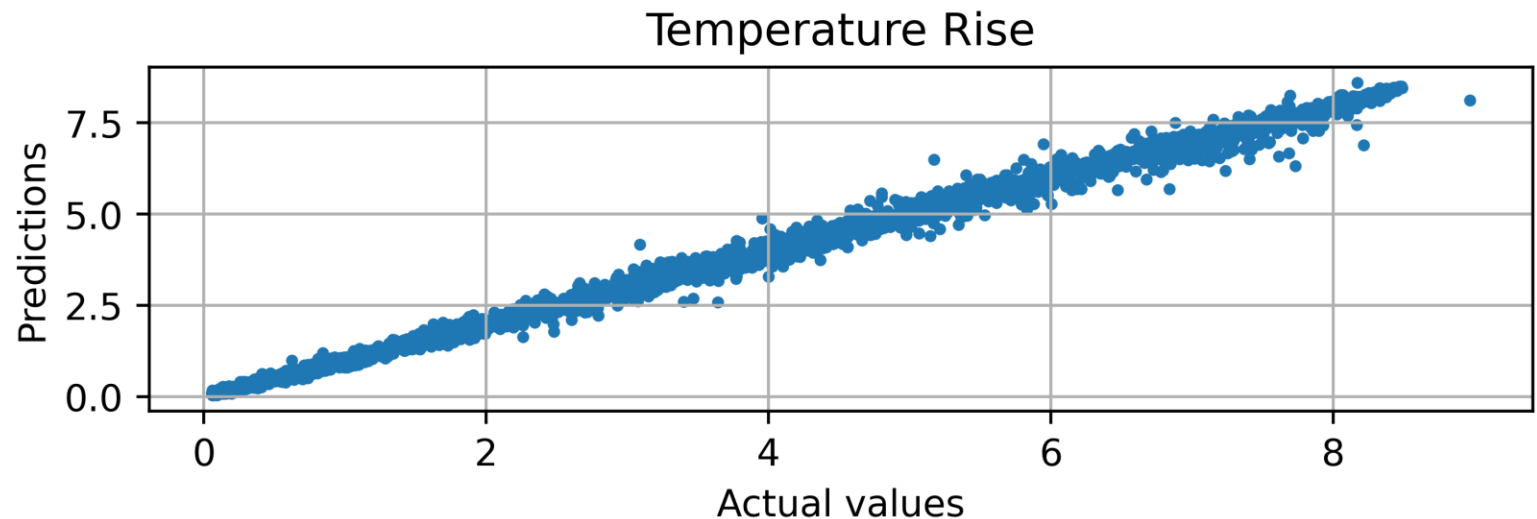
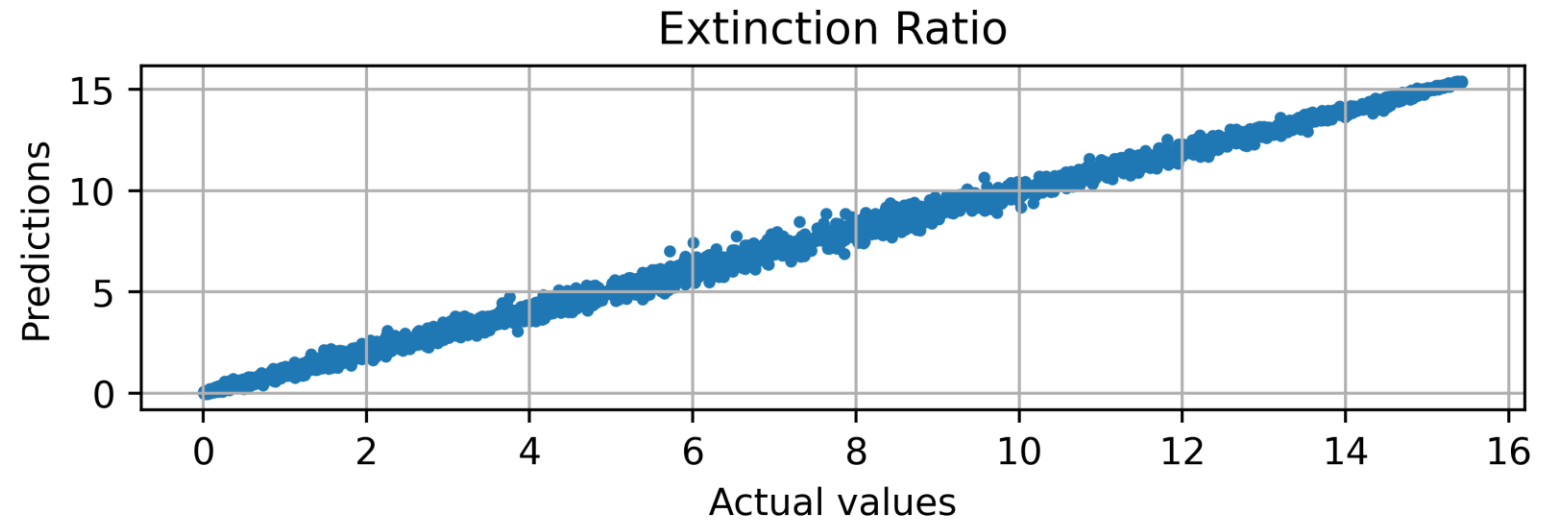
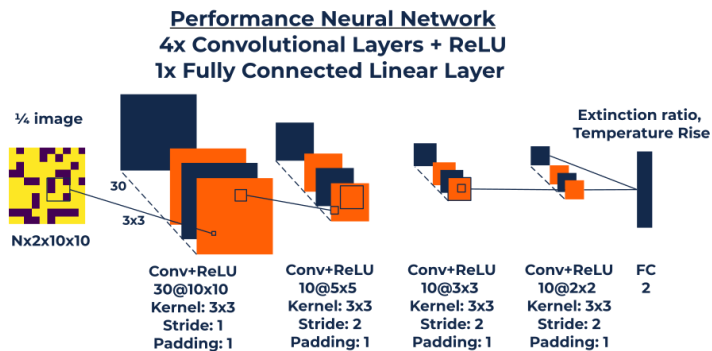




Trained performance:

- Avg abs error
 - ~13% Ext. Ratio
 - ~5.75% dT
- Maximum difference
 - ~1.44 dB ext. Ratio
 - ~1.4 K dT

Average absolute error:
$$\frac{1}{N} \sum_{i=1..N} \frac{|\text{pred}_i - \text{actual}_i|}{\text{actual}_i}$$



Test data generated with arbitrary cost function shows good performance

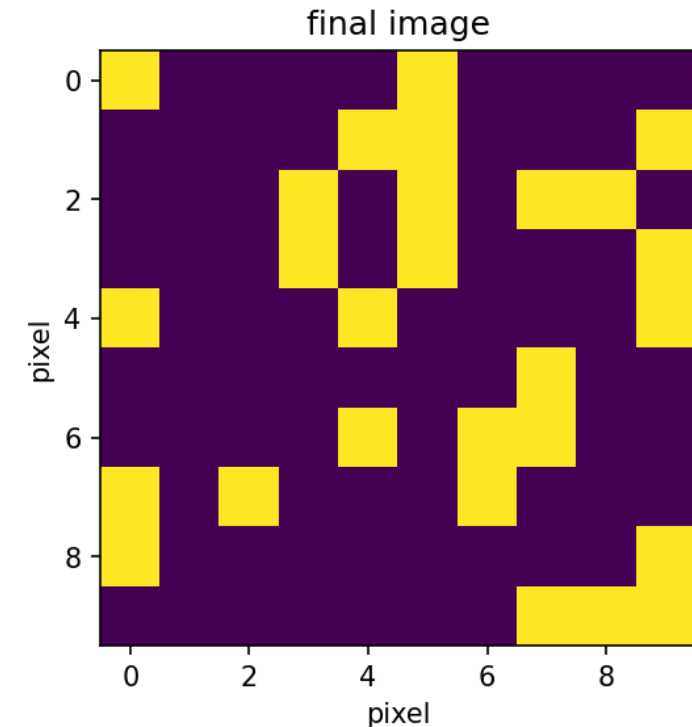
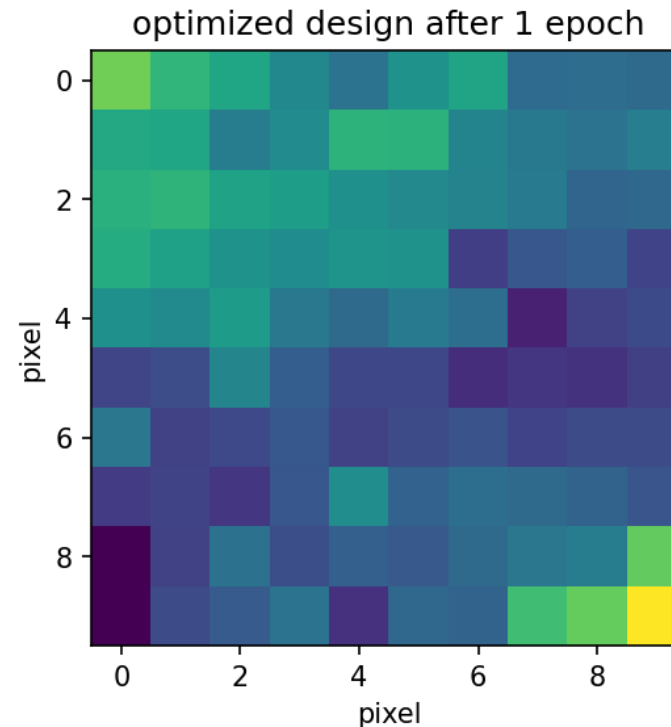
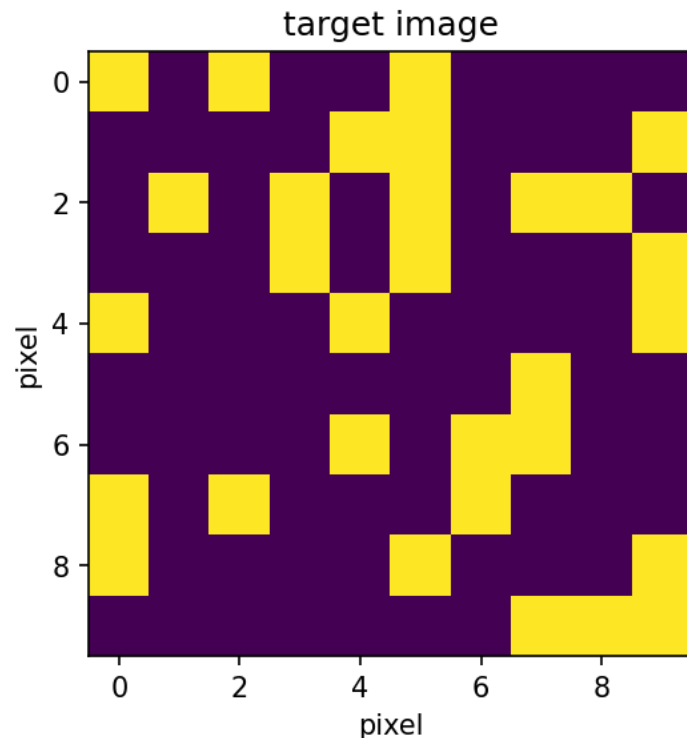
- Random "ideal" image selected
- Dummy loss function
- Translate loss into "predicted" Ext Ratio, Temp Rise

$$Loss = \sum_i \sum_j |x_{i,j} - t_{i,j}|$$

$$Tr_{insulating} = 1 - 0.5 \frac{Loss}{Loss_{max}}$$

$$Tr_{metallic} = 0.5 \frac{Loss}{Loss_{max}}$$

$$dT = 10 \left(1 - \frac{Loss}{Loss_{max}} \right)$$

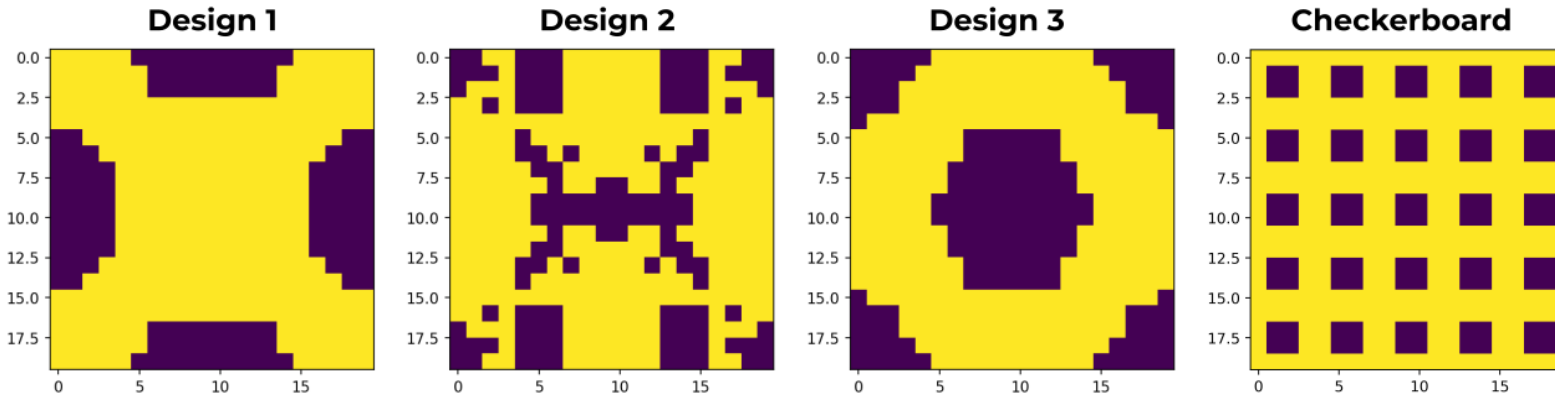


Training the Topology Optimization Neural Network

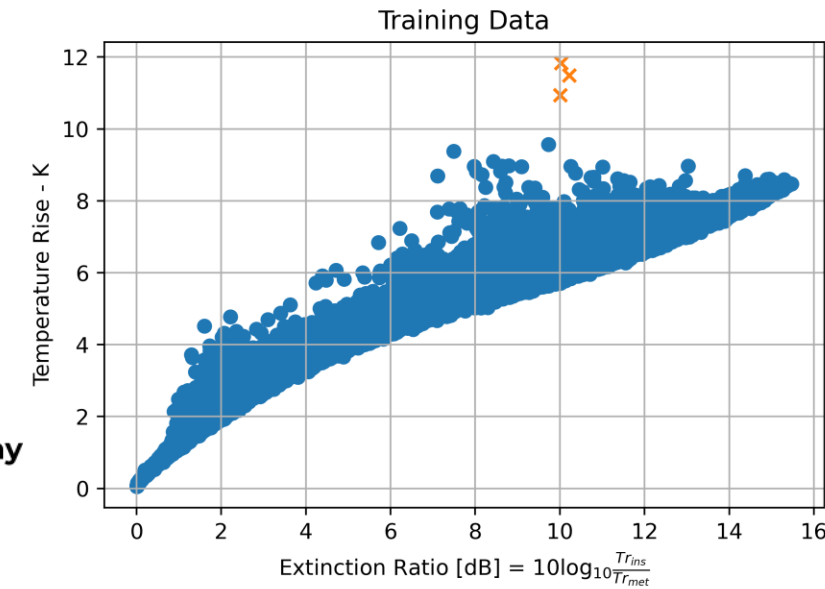


Sample Designs

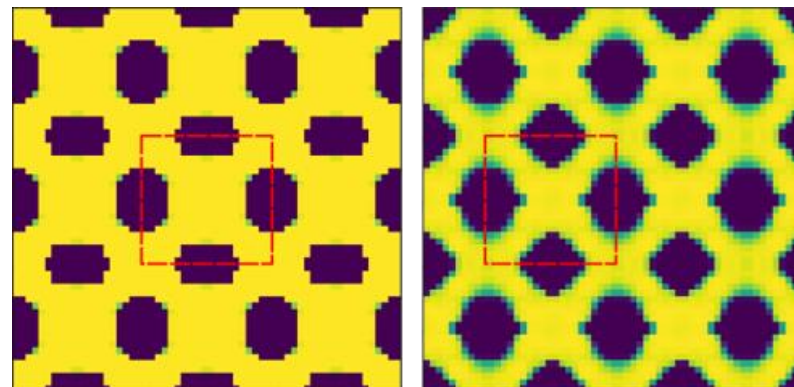
(Glass Substrate + 400 VO₂ + 240 SiO₂)

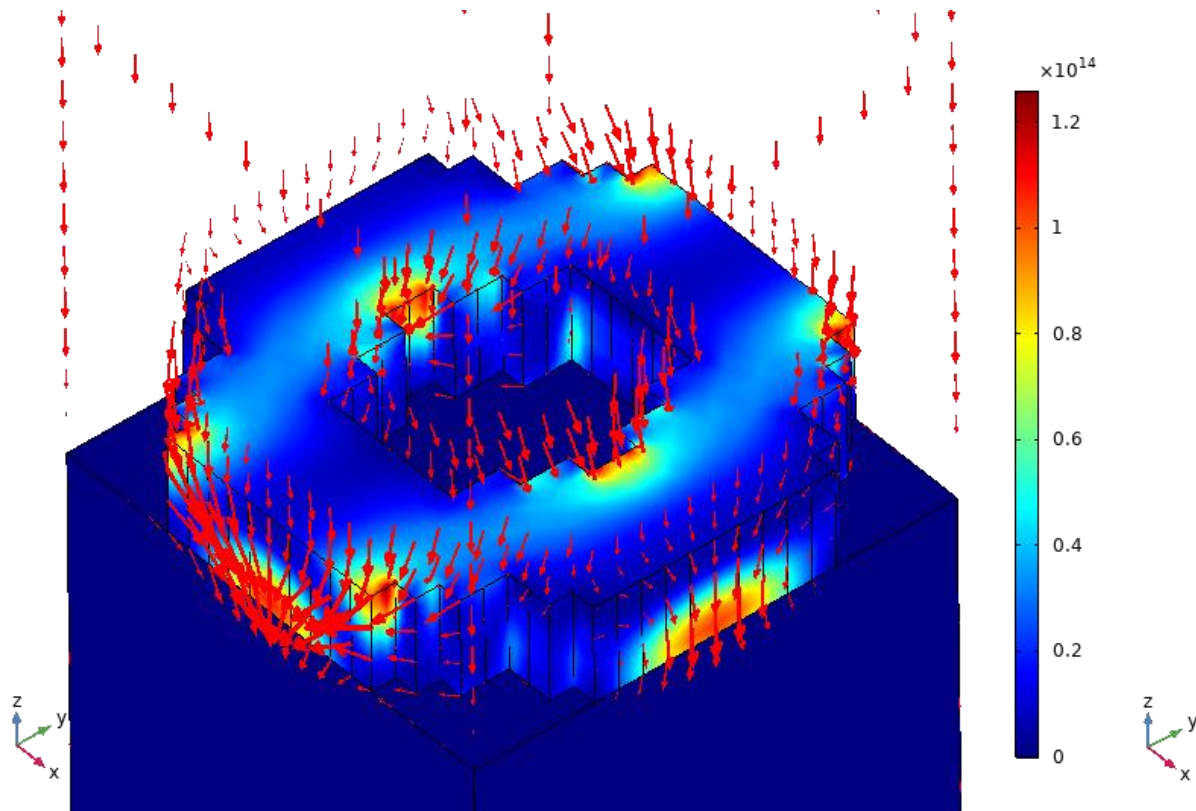


	Design 1		Design 2		Design 3		Checkerboard	Circle Array
Method	NN	COMSOL	NN	COMSOL	NN	COMSOL	COMSOL	COMSOL
Extinction Ratio	10.01	12.14	10.22	8.96	10.03	11.44	12.39	10.14
Temperature Rise	10.94	13.77	11.49	11.31	11.83	13.86	2.45	14.1
Percent Coverage	70%		68%		65%		75%	61%

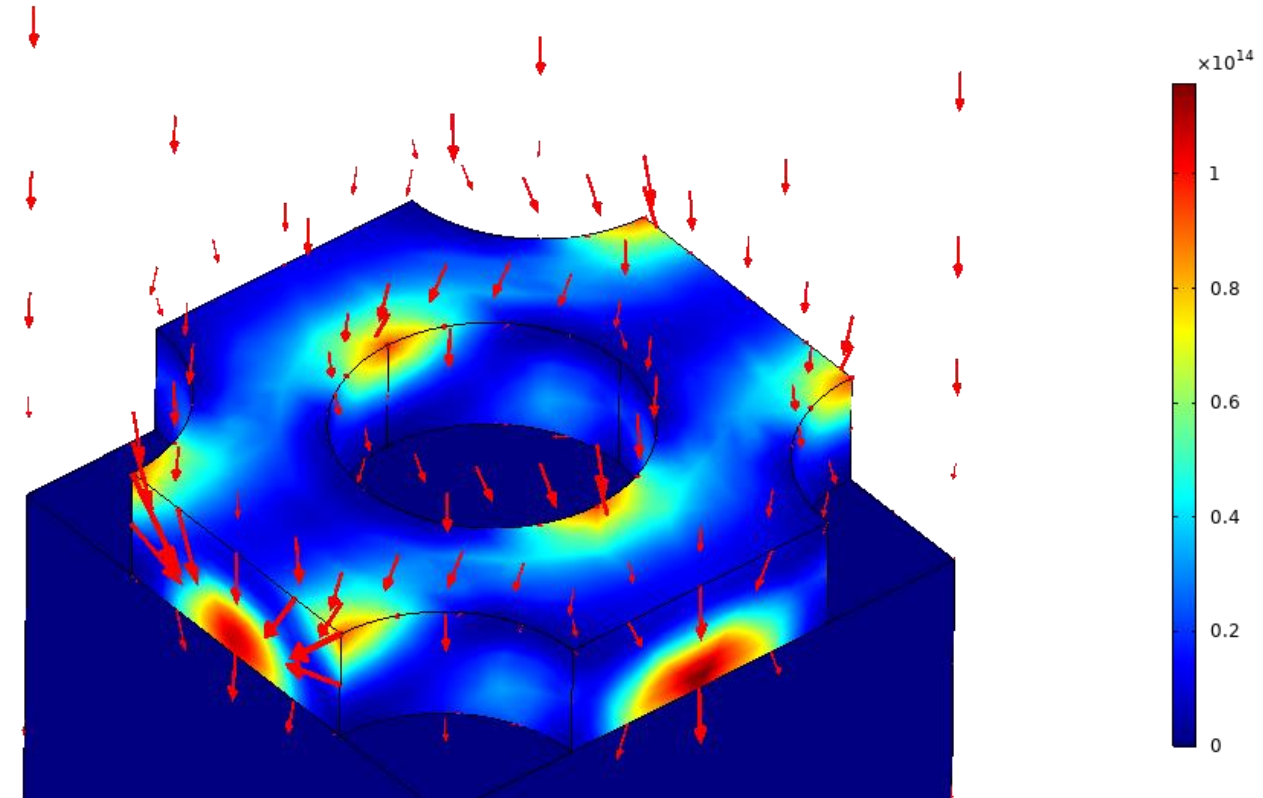


Design 1 vs Design 3 (3x3 shown)





Volume plot: Electromagnetic Power Loss Density
Arrows: Directional Energy Flux (Poynting vector)



Poynting vector

$$\mathbf{S} = \frac{1}{2} \mathbf{E} \times \mathbf{H}^*$$

- Dual neural networks for topology optimization
 - Performance Neural Network
 - Topology Optimization Neural Network
- Future work
 - Fabrication and testing of (3x) designs
 - Transfer learning: use simple model to pre-train PerfNN and use with more complex, coupled, EM/thermal time domain simulation



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- PerfNN
 - Convolutional NN
 - Four hidden layers + FC output
 - Varying number of feature maps, stride and padding
 - Activation function: ReLU
 - Output: Extinction ratio and dT
 - Loss function: MSE
 - Adam optimizer
- TopOptNN
 - Fully-connected feed-forward NN
 - Five FC hidden layers + Softmax output
 - Includes batch normalization
 - Activation function: Leaky ReLU
 - Output: first column of softmax probability distribution is used as density
 - SIMP-like constraint
 - Image = x^p [400,240]
 - Loss function: see slide
 - Adam optimizer

Training Data

