

Enabling Catalyst Adoption in SPARC

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Abstract—This paper reports on Catalyst usability and initial adoption by SPARC analysts. The use case approach highlights the analysts’ perspective. Impediments to adoption can be due to deficiencies in software capabilities, or analysts may identify mundane inconveniences and barriers that prevent them from fully leveraging Catalyst. With that said, for many analyst tasks Catalyst provides enough relative advantage that they have begun applying it in their production work, and they recognize the potential for it to solve problems they currently struggle with. The findings in this report include specific issues and minor bugs in ParaView Python scripting, which are viewed as having straightforward solutions, as well as a broader adoption analysis.

Index Terms—visualization, analysis, in situ, usability, adoption

I. INTRODUCTION

Almost every widely used product starts as an idea, goes through a stage of development and prototyping to demonstrate the capability or utility, and finally, goes through another stage of development to make a usable product. The demonstration, or second, phase addresses *utility*: the capability addresses a need, and if they exist, is potentially better than the alternatives. The third stage, often called “the valley of death,” focuses on usability and adoption. *Usability* means that a user of the product can realize the capability provided by the product. A user might say a product is “too difficult to use” or “too complicated to understand,” to complete their task to indicate barriers to usability. Even if a product provides utility and is usable, it has to fit in the environment of the user. Barriers to *adoption* include, e.g., metric wrenches when the user has nuts and bolts in imperial units, or software that does not run on the operating system of the user’s computer. Viewed broadly, the lack of utility and usability are barriers to adoption. Of course, many ideas start this process but far fewer become widely used products.

In situ analysis and visualization for engineering and science simulations on High Performance Computing (HPC) platforms are in the demonstration phase. The primary capability is that by generating analysis and visualization results as the simulation is running, one avoids writing large simulation data files to disc. On state of the art HPC platforms, file I/O is

relatively expensive and reducing the necessary I/O is highly desirable. A secondary and perhaps under appreciated benefit is automation. If the analysis and visualization steps are known in advance and can be completed as part of the simulation, analysts don’t have to postprocess the data their simulation wrote to files. Uncertainty quantification and sensitivity analysis frequently involve large ensembles of calculations, and automated analysis and visualization of the results is crucial, even when postprocessing.

This paper reports our progress on the adoption phase for Catalyst in SPARC. Sandia Parallel Aerodynamics Research Code (SPARC) is an engineering simulation code for fluid dynamics, principally the flow around vehicles re-entering the earth’s atmosphere [1]. Catalyst [2] is the in situ version of the ParaView visualization application [3], [4]. The primary user interface for ParaView is a Graphical User Interface (GUI), and after reading simulation data files produced by SPARC, the user interactively applies operations to the data to produce visualization outputs. The user interface for Catalyst is a ParaView Python script: ParaView commands are accessible through Python modules and expressed in Python syntax. The general workflow, as recommended by Kitware (the developer of ParaView and Catalyst), is to first generate the images desired in ParaView from an existing set of simulation data files. Then the user can generate a ParaView Python script from the ParaView GUI that captures the commands that generated the images. This script can be interpreted by Catalyst to generate images when invoked by SPARC. We focus on this workflow and the ParaView Python scripts. Of particular interest is understanding and editing the scripts, because analysts want to generate an initial script on a small simulation and use a modified script for a similar but much more expensive simulation. We did not examine the usability of the ParaView GUI or SPARC, except where they affect the usability of Catalyst. We are also interested in the adoption of Catalyst and ParaView for quantitative analysis, but in this paper we only examine visualization.

ParaView is a mature software application with a large, established user base. Catalyst has essentially the same utility, so in this paper we focus on Catalyst usability and adoption.

We chose an analyst driven, use case approach. Use cases are concrete examples of typical tasks an analyst (Catalyst user) would like to accomplish.

II. CODE INTEGRATION AND SUPPORT

A. Catalyst Integration Considerations

Based on our Catalyst SPARC integration experience, some important factors to consider when integrating Catalyst with a simulation code are:

- How to control Catalyst from the simulation input deck.
- How to link Catalyst to the simulation (dynamic run-time library or direct link).
- Performance impact on the simulation, for example [5].
- Transferring simulation mesh data structures to Visualization ToolKit (VTK) mesh data structures.
- DevOps infrastructure to build, deploy, and test Catalyst with simulation.

B. Catalyst Integration with IOSS

The Input Output SubSystem (IOSS) library is part of the Sandia Engineering Analysis Code Access System (SEACAS) package from Sandia National Laboratories (SNL). Many SNL simulation codes, such as SPARC, Nalu, and Sierra Adagio, use IOSS to output files in Exodus II and CFD General Notation System (CGNS) formats in parallel. The central abstraction presented by IOSS is a database that encapsulates details about how mesh data and associated variables are written by a simulation code. IOSS is similar to the SENSEI in-situ framework [6], in that it provides an interface between the simulation and multiple analysis targets. The Catalyst integration in IOSS implements two new IOSS output types: one for structured mesh output like CGNS and one for unstructured mesh output like Exodus II.

Rather than writing to a set of files in parallel, the Catalyst IOSS types convert the data to equivalent VTK data structures, and then send the mesh data to Catalyst in parallel. Catalyst runs a Python script that produces images, data extracts, and analysis products. Catalyst runs in-situ, using the same Message Passing Interface (MPI) ranks as the simulation code.

Simulation codes that use IOSS for writing simulation data to files require minimal changes to send that data to Catalyst. Furthermore, the Catalyst integration can be tested independently of the simulation code by using test drivers that feed input mesh data from files through the test suite.

Catalyst is a large code library that has varied build requirements on different HPC platforms. For this reason, the Catalyst IOSS databases use a split implementation. The IOSS side provides an interface between the simulation and the Catalyst IOSS database types. The Catalyst side resides in a dynamically loadable plugin library (sometimes called the *adapter*) that converts the mesh data to VTK data structures, and then calls Catalyst. Simulation code build systems do not have to link against Catalyst libraries directly, which allows the Catalyst portion to be built, tested, and deployed separately. In this work ParaView 5.10.1 was used to create the Catalyst

scripts. IOSS provided Catalyst 5.10.0, which used Catalyst API 1.0.

C. SPARC Integration with Catalyst IOSS

To enhance compatibility with SPARC analyst experience using file based I/O to Exodus II and CGNS files, input deck controls for Catalyst are implemented with a syntax parallel to the file based controls. New Catalyst input deck blocks use existing syntax for output frequency scheduling, variable selection, and output database type. Minimal new syntax was added to specify the Python script name and multiple mesh inputs to the same Catalyst script.

The Catalyst IOSS plugin must be built, tested, and deployed on all HPC platforms where SPARC is supported. Project developers employ the DevOps tools Ansible-Tower, Ansible, CDash, and CTest to meet this requirement. To give analysts early access to new features in SPARC and Catalyst, “advanced feature builds” are deployed on some HPC platforms. These advanced feature builds were used in the walkthroughs described below. In-situ technology is a new capability for analysts. A robust DevOps process lets us identify and fix issues and redeploy rapidly, which is crucial for analyst adoption.

III. METHODOLOGY

A major challenge in the design and development of visualization tools is ensuring that the product will be adopted by real-world users and be practicable for their needs. As noted by Fisher et al., a common stumbling block for the visualization and visual analytics community is that tool developers are often “not very consistent in articulating and applying methodological principles for system design and end-user evaluation” [10]. Insufficient rigor can lead to misunderstanding users’ real needs or designing systems to solve the wrong problems. For that reason, a key goal of our effort has been to engage with prospective users directly and develop a systematic understanding of their needs.

A. Theoretical Framework: Five Characteristics of Innovation

In this study, we applied the Diffusion of Innovations (DOI) as a theoretical lens to investigate analysts’ experiences with Catalyst in SPARC [8]. DOI theory, first pioneered by communication theorist and sociologist Everett Rogers in 1962, seeks to explain how and why innovative ideas and technologies are adopted and spread throughout a social system. In this approach, how an innovation is perceived by prospective adopters depends on different dimensions of perceived utility; as explained by Rogers, “The characteristics of innovations, as perceived by individuals, help to explain their different rate of adoption” [9, pp. 15-16]. These characteristics include

- **Relative Advantage:** The degree to which an innovation is perceived as better than the idea it supersedes.
- **Compatibility:** The degree to which an innovation is perceived as being consistent with the existing values, past experiences, and needs of potential adopters.

- **Complexity:** The degree to which an innovation is perceived as difficult to understand and use.
- **Trialability:** The degree to which an innovation may be experimented with on a limited basis.
- **Observability:** The degree to which the results of an innovation are visible to others.

According to Rogers, “Innovations that are perceived by individuals as having greater relative advantage, compatibility, trialability, observability, and less complexity will be adopted more rapidly than other innovations,” [9, p. 16], and “Given that an innovation exists, communication must take place if the innovation is to spread,” [9, p. 17]. What makes DOI theory particularly useful is that it helps in navigating the trade-offs between different dimensions of utility. For example, the Catalyst capability may promote relative advantage through code proximity (the ability of the visualizer to provide easy and fast access to underlying source code, see [7]), but in doing so this may also increase complexity until certain barriers to adoption are addressed.

Thus DOI theory enables researchers to explore the interplay of different innovation adoption drivers. Along these same lines, DOI theory has previously been used to study user adoption of data visualization and analytics tools in diverse contexts including healthcare [12], education [14], construction [13], and geospatial analytics [18].

B. Walkthrough and Content Analysis

Our Subject Matter Expert (SME) developed two image generation use case workflows using ParaView, Catalyst, and SPARC. The workflow steps constituted instructions to be followed by analysts during a guided walkthrough interview. The SME also performed a technical analysis, in which bugs and usability issues were identified, while determining the steps of the workflow. Three analyst interviews were conducted, each lasting 60 – 90 minutes. In each interview, the analyst followed the instructions for the workflow steps, and the SME observed the analysts’ actions, answered questions, provided explanations, and responded to feedback. A content analysis was employed to analyze the video, audio, and transcripts of the use case walkthroughs. Content analysis is a methodology used to identify patterns in texts and can be quantitative, qualitative, or both [15]. Rogers’ five characteristics of innovations were used as categories to quantitatively code analysts’ statements from the interview transcripts. Six project team members representing diverse scientific and engineering domains independently coded each of the interviews by watching the videos and matching the audio to the transcripts.

IV. RESULTS AND DISCUSSION

A. Use Cases

Two image generation use cases were designed to identify specific usability barriers encountered while executing an in-situ visualization workflow leveraging ParaView, Catalyst, and SPARC.

The simulation for the first use case models the flow over a blunt-nosed, axisymmetric vehicle at 10° angle of attack

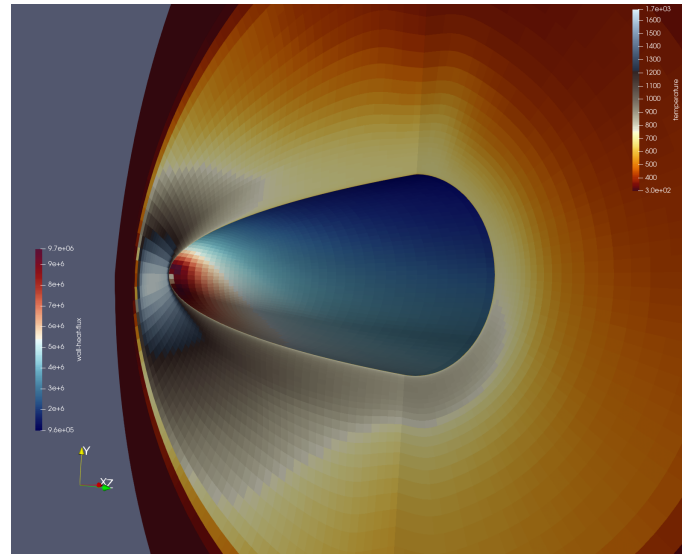


Fig. 1. Use Case 1: Corner view of flowfield temperature on symmetry and exit planes and heat transfer on the vehicle surface.

(AoA), traveling at Mach 5 at sea level. SPARC iteratively solves for the steady-state, turbulent flowfield. This simulation is inexpensive, the amount of data written is small, and while images are produced throughout the simulation, only those at the end of the simulation are needed. However, it includes all the realism needed for investigating Catalyst usability and adoption. Images of the flowfield temperature are produced on the symmetry and exit planes of the simulation. The symmetry plane is the xy -plane through $z = 0$, and the exit plane is the yz -plane at the maximum value of x . A third image shows the heat flux on the vehicle surface, and the fourth image, shown in Fig. 1, includes both planes and the surface. SPARC analysts regularly produce images like these as a first look to confirm the simulation ran as expected, and then to identify any important flowfield structures.

The second use case is a large eddy simulation (LES) of the flow over a cone at Mach 8 at 6° AoA. This simulation runs on 100 nodes of an ASC CTS-1 machine; it is a modest calculation by current LES and supercomputing standards, but large enough that analysts limit how frequently they write the flowfield solution to disk. In Fig. 2, a contour surface of the Q-criterion identifies resolved vortical structures, and coloring the contour surface by temperature is useful for understanding heat transfer to the cone surface. The symmetry and exit planes display the gas density from a different simulation, stored in files and read by Catalyst during the LES simulation.

B. Technical Findings

Technical findings are defined in the present paper as specific issues or recommendations identified by the SME or interviewees for ParaView, Catalyst, and the ParaView Python scripting interface.

ParaView has different classes of objects. *Filters* are processing units assembled into a pipeline. The output of each

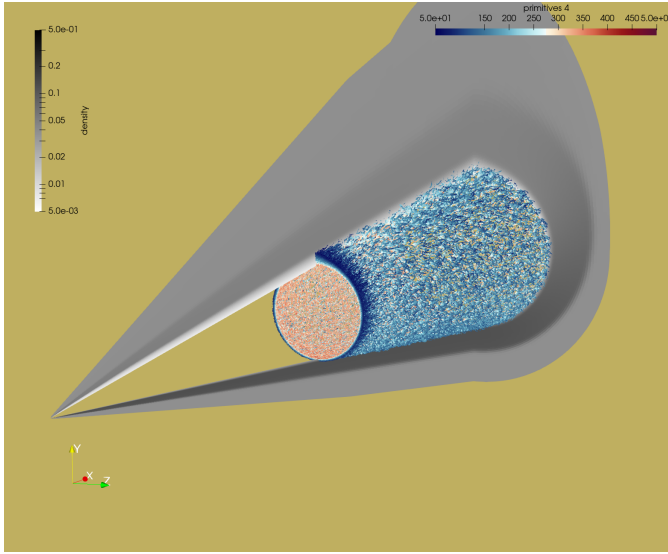


Fig. 2. Use Case 2: Isocontour of Q-criterion colored by temperature (labeled as “primitives 4”) from LES, with steady state density (log scale) on symmetry and exit planes.

filter may be displayed, as defined by its *representation*. A *view* composes the image from the active representations it contains. *Extractors*, or extracts, were added in version 5.10.0, and describe file output; data extractors save the output of a filter, and image extracts save the image in a View.

The scripts generated by the ParaView GUI are verbose and difficult for the analyst to understand. There are many lines specifying the properties of representations and views, and many of them are not necessary to include. Either the user has not changed the property values from their default values, or that property was not needed to make the image. Many of these properties are set by the user indirectly, such as through a mouse or widget interaction, and the associated property is not familiar to the analyst by the name in the script. Consequently the analyst may be uncertain about which representation and view properties are necessary, so they are hesitant to edit or delete them.

The scripts generated by the ParaView GUI embed specificity of the dataset in a way that is difficult for an analyst to identify. For example, in the color lookup table, the data value and the corresponding 3-tuple defining the color are just appended together in a Python list, with no structure to distinguish the value from the tuple or one value-tuple pair from another. To rescale the color table to different minimum and maximum values, an analyst would have to recognize the structure from the values in the list, then recompute each data value and edit the list appropriately. It would be much easier to just specify the color table for a value range of, say, 0 to 1, and have Catalyst compute the corresponding values given user-specified minimum and maximum values, as the analyst would do in the ParaView GUI. There are many places in the script like this, though the color lookup table is particularly difficult to edit. As a reminder, easy modification of the scripts

to apply to a different dataset is crucial, because the benefit of in situ analysis is only realized when applying it to simulations that have not yet been run.

Another issue is that some properties recorded in the Catalyst script are not intuitive. For example, the view properties that specify the camera’s location and orientation are easy to identify, but it is difficult for an analyst to know how to adjust the values to get the updated image they desire. In ParaView, these parameters are accessible but rarely displayed – instead, the analyst updates the view by using the mouse, seeing the effects but not the actual values of the camera properties.

The scripts generated by the GUI are best thought of as “journal” files that record the necessary information to regenerate the output image or data file, rather than a clear description that leads to easy understanding and adaptation to a different data set. Fortunately, the issues identified in the GUI-generated scripts have straightforward solutions, and we are working developers at Kitware to address them.

C. Usability and Adoption Findings

Usability and adoption findings were developed by performing a content analysis on the walkthroughs with analysts. Two hundred and ten unique statements made by three analysts during the interviews were identified across the image generation use cases. Each statement was then categorized into only one of the five characteristics of innovations by each coder [15]. Across the six coders, we used Cohen’s Kappa [16], [17] to measure pairwise intercoder reliability (0.2238 average unadjusted). Intercoder reliability was calculated by taking the average pairwise kappa among the six coders based on whether or not they coded a statement, irrespective of *how* they coded the statement. A common discrepancy among coders was that while some coders labeled each statement at the beginning, others labeled statements at the middle or end. Therefore to compensate for this irregularity, we adjusted the kappa by grouping statements with those before and after (0.3276 adjusted). Additionally, while three coders were aligned in their coding schema (0.3641 unadjusted, 0.4181 adjusted) suggesting moderate agreement, others were not as well-aligned, resulting in lower kappa scores overall for the six coders due to the misalignment. Agreement among six coders was fair (0.21 - 0.40). Kappa scores were lower than desirable, but still within acceptable limits.

We employed Friedman’s test to determine whether any of the five innovation characteristics were consistently labeled more frequently by different coders [19]. This test yielded a p-value of 0.00027, indicating that there are innovation characteristics consistently rated higher than others across coders. Next, we used the post-hoc Friedman-Nemenyi test to measure which pairs of innovation characteristics were significantly more or less frequent relative to each other [20]. The test revealed that Relative Advantage is consistently coded more frequently than Observability ($p=0.036466$), and Compatibility more frequently than Observability ($p=0.00100$).

Table I illustrates the number of unique statements (210) that were coded in each of the characteristics of innovations

TABLE I
CODED FREQUENCIES OF DOI CHARACTERISTICS USED IN THE
QUALITATIVE ANALYSIS OF THE FLOWFIELDS AND LES USE CASES.

Innovation Characteristics	Flowfields Use Case	LES Use Case
Relative Advantage	24	7
Compatibility	51	26
Trialability	33	9
Observability	6	2
Complexity	41	11
Total Number of Codes Applied	155	55

categories. Fewer analysts’ statements were coded for the characteristic Observability; this was not surprising since Catalyst has only been deployed in SPARC as a beta capability, so the analyst community is not familiar with it. Additionally, in each use case, analysts’ statements offered support for relative advantage with respect to data manipulation through testimonials such as, “*Yeah, so I can see myself using this immediately for some of our cavity works that we work on.*” and “*Yeah, it seems quite useful right out of the box.*”

While not depicted in Tab. I, 48 usability barriers were identified from 41 analysts’ statements. In seven of the analysts’ statements, more than one coder identified different usability barriers for the same statement. Our findings indicate that some analysts’ statements corroborated the technical analysis performed by the SME, for example, with respect to color lookup tables being impractical to modify directly in both the flowfield and LES image generation use cases. When asked by the SME, “*Do you think you could write that part yourself without the GUI?*” an analyst performing the workflow steps for the flowfield use case stated, “*We didn’t change the color map for this but if we had to I don’t know that I would be able to do that by hand.*” Another added, “*I would say there’s a difference, right, between editing a script that’s there, and creating it completely from scratch.*” When asked by the SME “*What else do you see in here or what do you think about the process we went through? ... Is this tractable?*” an analyst executing the steps for the LES use case stated, “*Some components of it, I think you’re right where it would be more valuable to be able to dig into the Python script.*” It was observed that there appeared to be a lack of intuitiveness of GUI visual elements in the Catalyst script, and in the case of LES, understanding, editing, or modifying image-specific parts of the Catalyst script was difficult.

With respect to adoption, applying Rogers’ Innovation Characteristics to our use cases confirmed that SPARC analysts saw the value of Catalyst for their work (relative advantage), and that it could be easily incorporated in their existing workflows (compatibility). The factors limiting adoption are complexity, associated with difficulty understanding and editing Catalyst scripts produced from the ParaView GUI, and observability, which we believe can be addressed by documentation, examples, training, and direct engagement with analysts.

Our research was exploratory in nature, and as such prone to limitations. For example, the findings of the present study are

specific to the particular uses cases and the dataset was small. Intercooder agreement should also improve as we engage in further data collection and align our coding practices.

V. CONCLUSION

Catalyst in SPARC is entering the adoption stage for analysts in a production environment. Building on several years of effort, Catalyst is now integrated into SPARC in its parsing, simulation data transfer, and broader software engineering processes. This foundation permits developers to give more attention to usability and adoption.

We found that in practice, the Catalyst scripts generated by the ParaView GUI are journal files – they are effective for repeating an existing analysis, but they are difficult for Catalyst users to understand and modify for new analyses. For image generation tasks, the scripts are verbose and information specific to the original dataset is embedded in such a way that it is hard to find and modify. However, we believe straightforward solutions to these issues can be found and implemented, and we are working with Kitware to that end. For some information in the scripts, such as the specification of camera properties and color tables, the ParaView GUI or other tools may provide the best mechanism for the analyst to specify what to include in their Catalyst script.

Through our UUA analysis, with respect to compatibility (one of Rogers’ five characteristics of innovation), we concluded that analysts in our walkthroughs focused on determining how Catalyst would fit in their existing workflows. With respect to observability, we are using these preliminary results to guide our efforts to build a user community. We have deployed the workflow recipes on the SPARC Analysts’ wiki to address some of the barriers identified by users such as the need for documentation. Our UUA results are exploratory, but have given us insights into the process of addressing usability barriers and technology adoption by directly engaging with the analysts for whom Catalyst was designed.

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