

# IMPROVING DIGITAL TWINS BY LEARNING FROM A FLEET OF ASSETS

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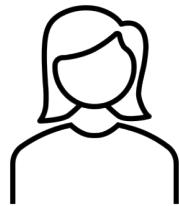
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**Advanced  
Scientific**

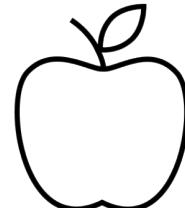
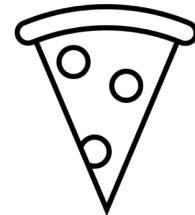
**RISE**  
Robust      Interpretable      Scalable      Efficient

# A DIGITAL TWIN

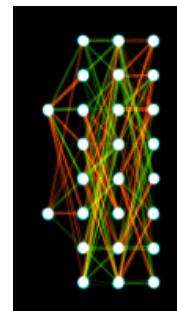
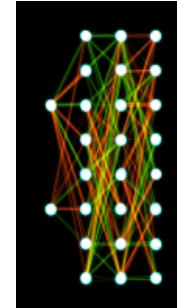
A digital twin is an evolving virtual model of a specific system or physical asset that assimilates data over its lifecycle to becomes a “patient-specific” model that can be used for intelligent automation and decision making.



Person



Data

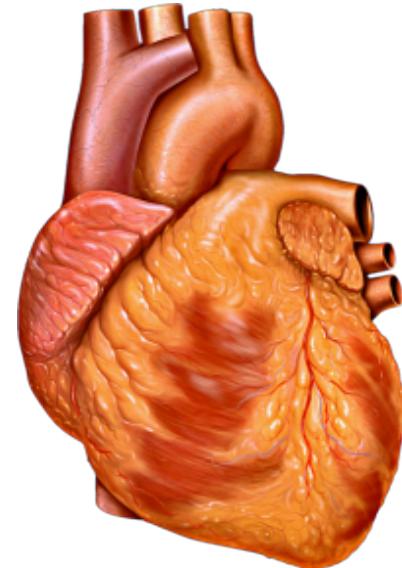


Digital Twin



Decision  
making

# SCIENTIFIC DIGITAL TWINS



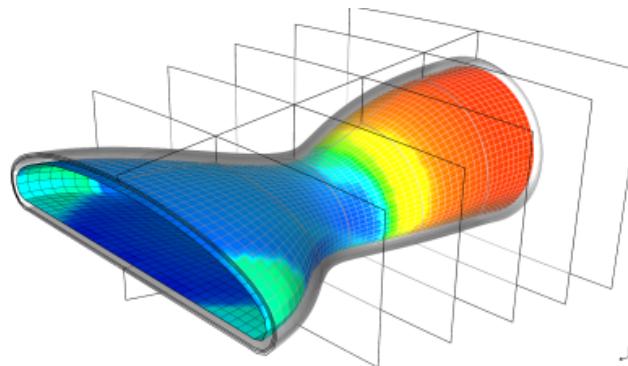
# FORMULATING A DIGITAL TWIN

## Assimilation

Want to calibrate the digital twin  $M$  to the physical asset

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

Asset



Digital  
Twin

$$M(s, t, x; \theta_k)$$

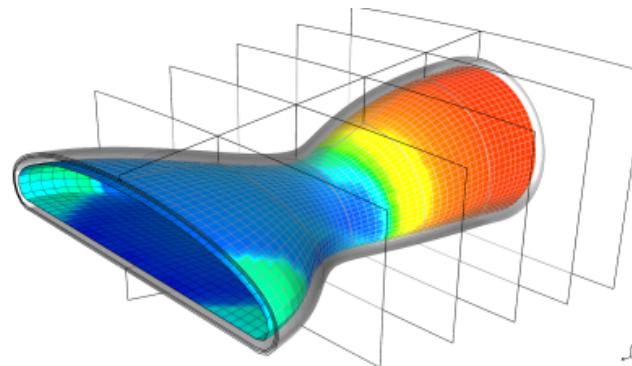
# FORMULATING A DIGITAL TWIN

## Assimilation

Want to calibrate the digital twin  $M$  to the physical asset

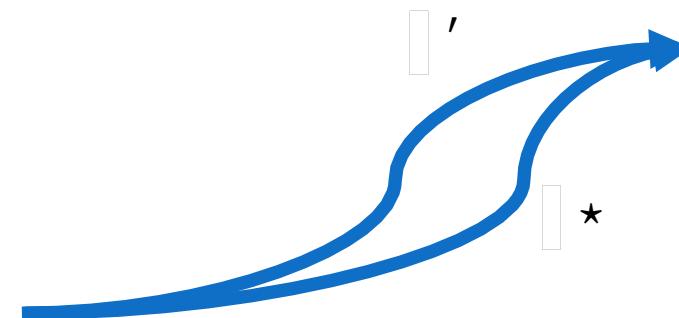
$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

Asset



## Prediction

Want to use the digital twin to determine how to fly asset safely given current health



Digital  
Twin

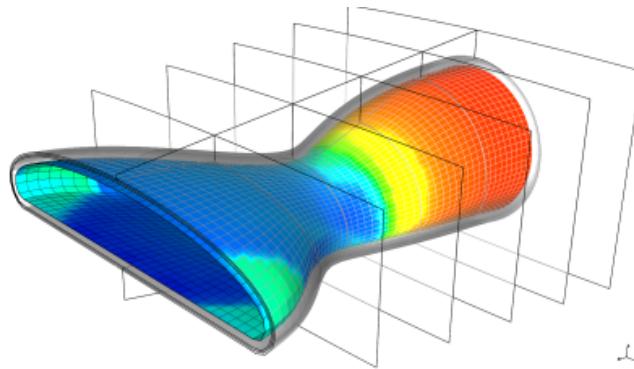
$$M(s, t, x; \theta_k)$$

# FORMULATING A DIGITAL TWIN

Want to predict performance  
under different flight scenarios  $x$

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

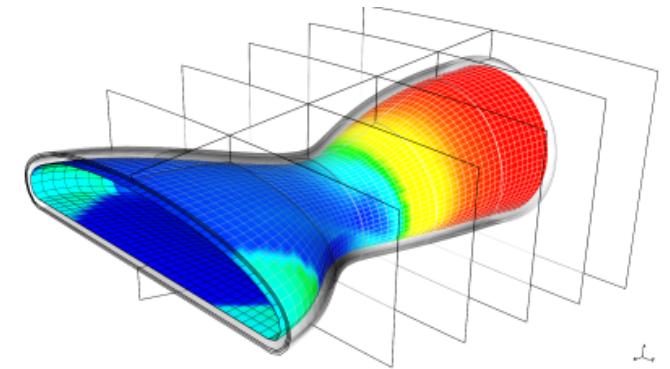
Asset



Collect data to infer health  $\theta^*$

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

Event changes  
health of asset  
 $\theta_k \rightarrow \theta_{k+1}$



Digital  
Twin

$$M(s, t, x; \theta_k)$$

Time

$$M(s, t, x; \theta_{k+1})$$

# FORMULATING A DIGITAL TWIN

The following process is often used to update and predict with a digital twin developed using first principles, e.g. PDE model.

Collect observations

$$y = h(s; x, \theta^*) + \epsilon$$

Temperature of nozzle

Infer posterior of model variables

$$p(\theta | y) \propto p(y | \theta) p(\theta)$$

Estimate thermal conductivity due to changes in deteriorating insulation

Propagate posterior through predictive model

$$\mathbb{E}(\cdot, \cdot) = \mathbb{E}(\cdot | \cdot, \cdot, \cdot)$$

Predict maximum stress for specific future flight scenarios  $x$

# A DATA DRIVEN DIGITAL TWIN

The following process is often used to update and predict with a purely data-driven digital twin

Want to construct approximation

Collect observations

Learn approximation unknowns  $\theta$

$$f(x; \theta) \approx \hat{g}_N(x; \theta_n) = \sum_{n=0}^N \theta_n \phi_n(x)$$

$$w = f(x; \theta^*) + \epsilon$$

$$\operatorname{argmin}_{\theta} \|w - \hat{g}_N(x, \theta)\|_{\Sigma_{\epsilon}}$$

Stress  $f$  vs flight scenarios  $x$

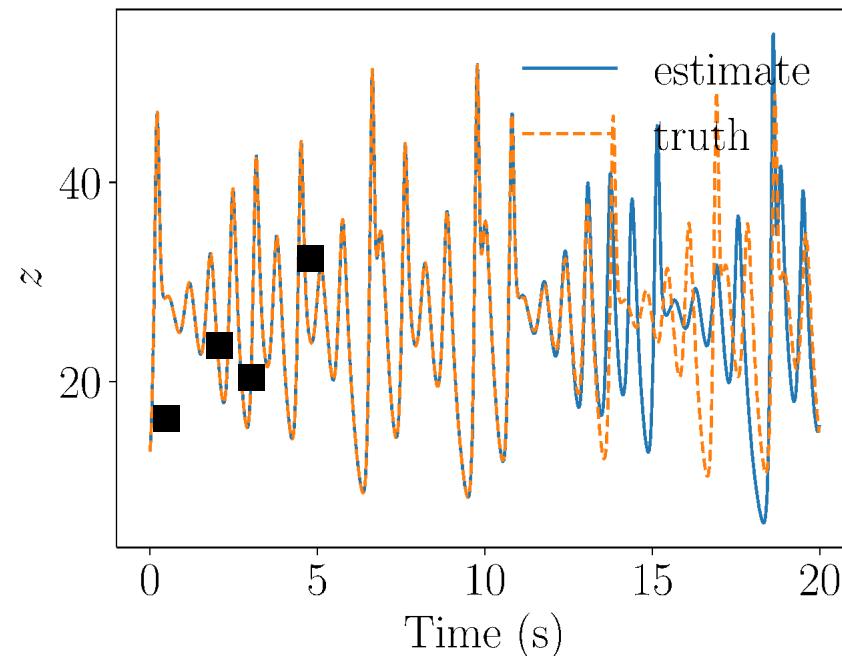
Observations are of stress directly

E.g. Use MLE

# CHALLENGE

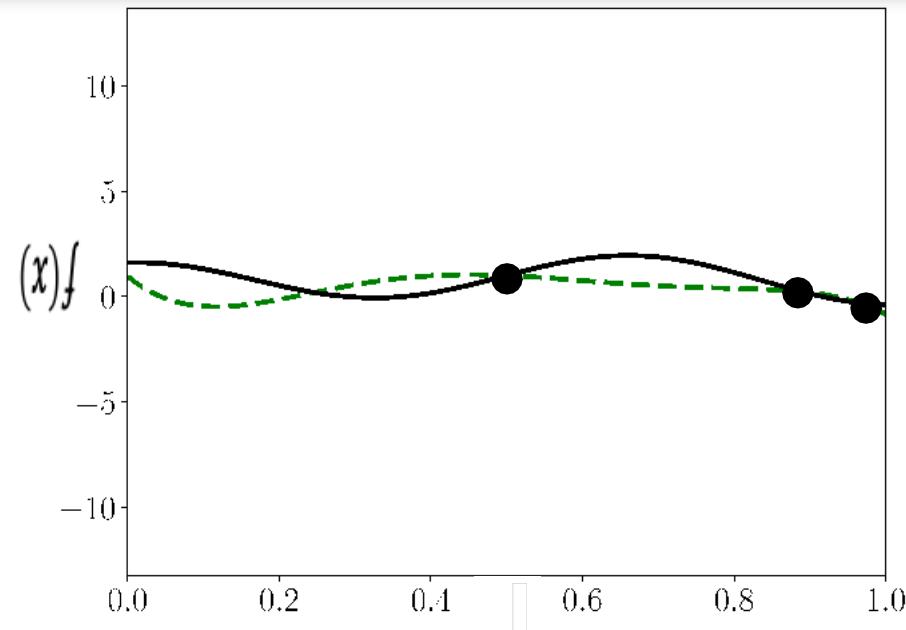
How can we make informative inferences to enable accurate prediction when data is limited?

A first principles digital twin



$$\begin{aligned}\dot{x}_1 &= \sigma(x_2 - x_1), \\ \dot{x}_2 &= x_1(\rho - x_3) - x_2, \\ \dot{x}_3 &= x_1x_2 - \beta x_3\end{aligned}\quad \theta = [\sigma \rho \beta]$$

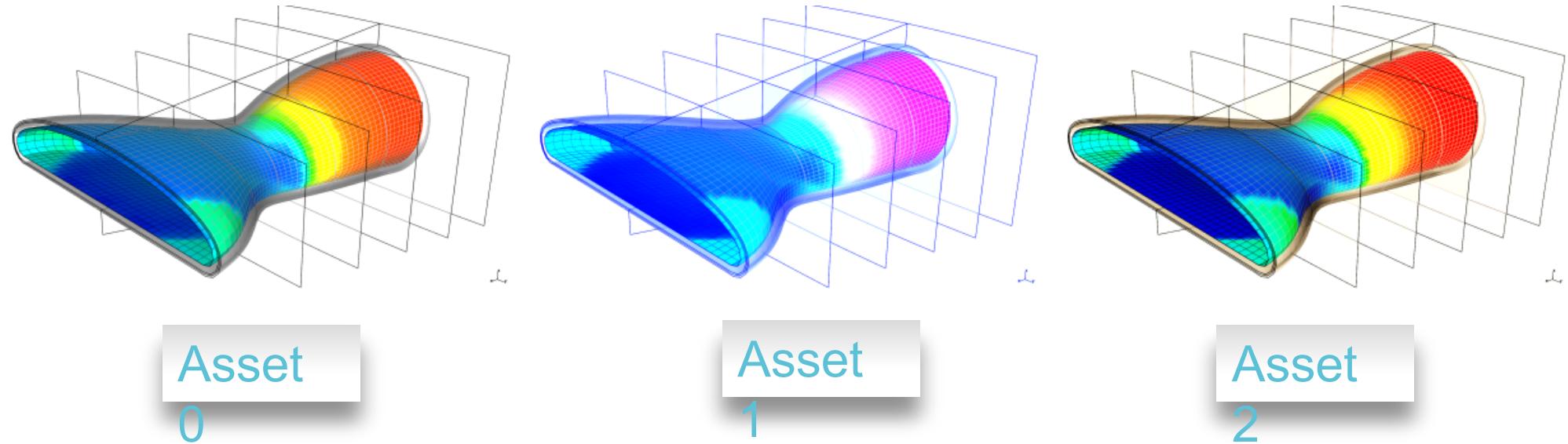
A purely data-driven digital twin



$$\hat{g}_N(x; \theta_n) = \sum_{n=0}^N \theta_n \phi_n(x) \quad \theta_n \sim \mathcal{U}(0, 1)$$

# DIGITAL TWINS OF ASSET CLASSES

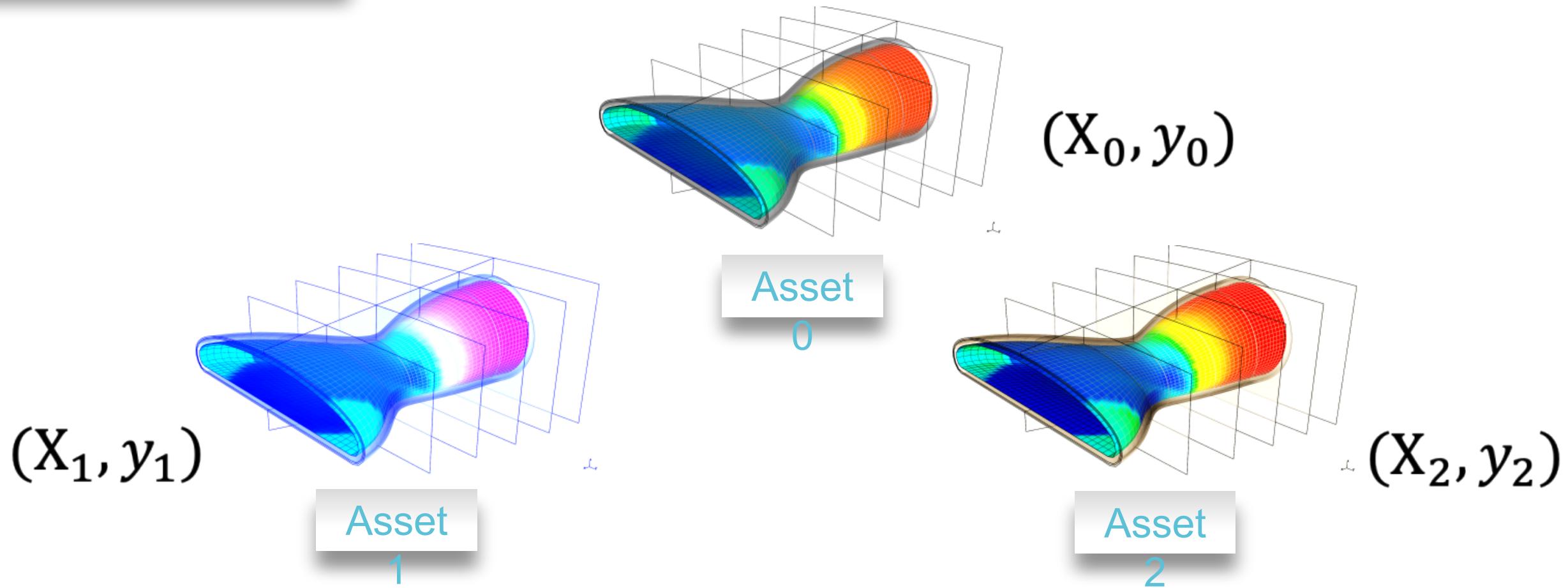
Often an asset is one of many within a class of assets. The exact health of these assets will depend on manufacturing differences (e.g. additive manufacturing) and/or the operating conditions of each individual asset.



However, many assets are similar and we will exploit relationships in the observational data to improve the predictive capability of digital twins.

# CONNECTING TWINS VIA THEIR OUTPUTS

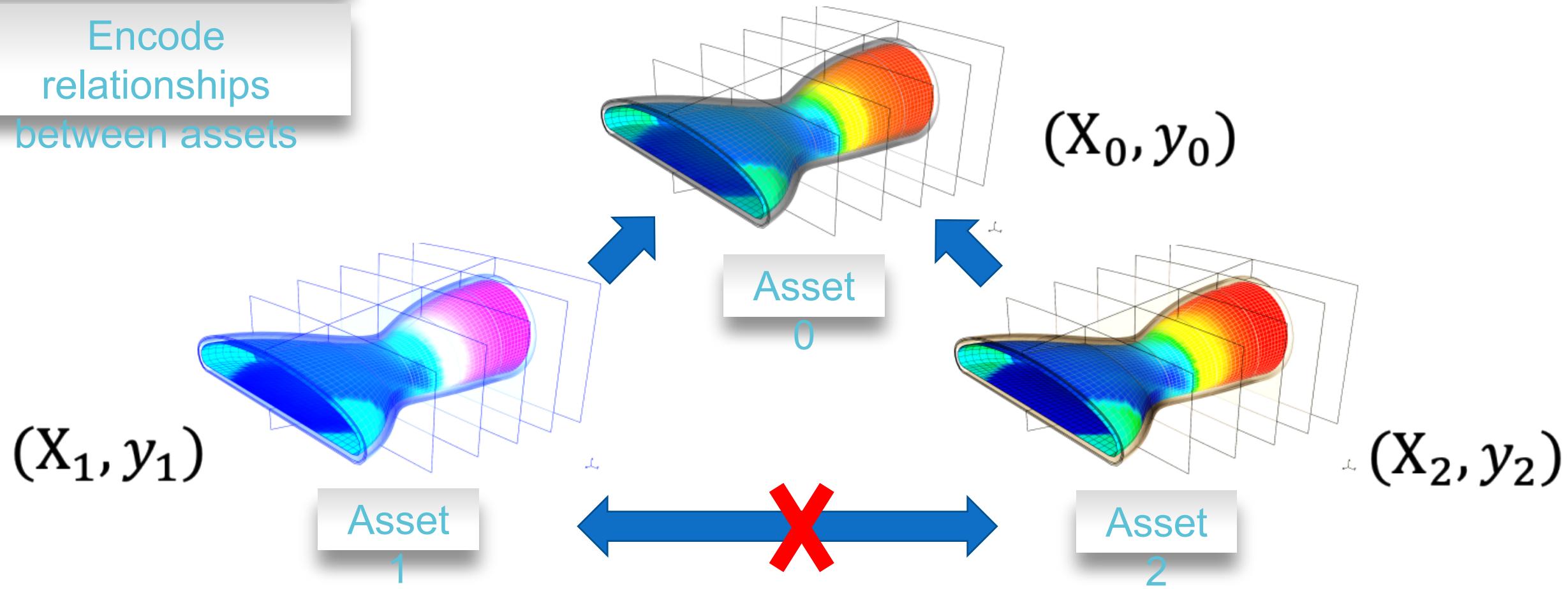
Collect data for  
each asset



# CONNECTING TWINS VIA THEIR OUTPUTS

Collect data for each asset

Encode relationships between assets



# CONNECTING TWINS VIA THEIR OUTPUTS

Collect data for each asset

Encode relationships between assets

Formulate models for each asset

$(X_1, y_1)$

Asset

$1(\square; 1)$

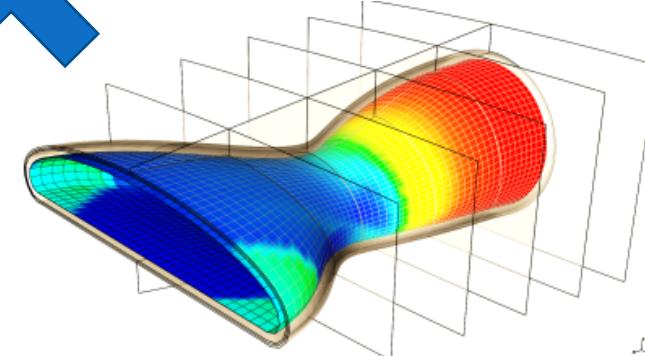
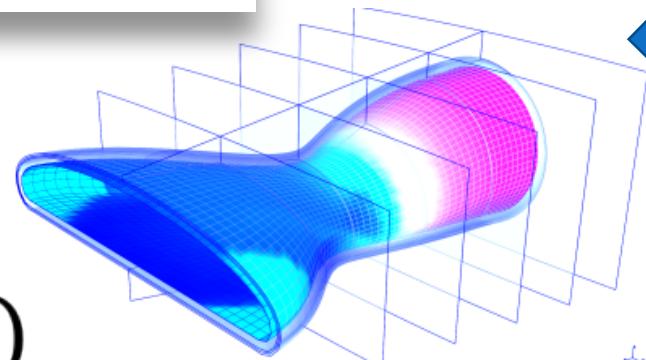
$$g_0(x, g_1(x; \theta_1), g_2(x; \theta_2); \theta_2)$$

Asset  
0

$(X_0, y_0)$

Asset

$2(\square; 2)$



$(X_2, y_2)$

# OUTPUT-BASED ASSET CLASS LEARNING

Place all data into  $G$  a directed acyclic graph

$$y_G = [y_0^\top, y_1^\top, y_2^\top]^\top \quad (DAG)$$
$$\theta_G = [\theta_0^\top, \theta_1^\top, \theta_2^\top]^\top$$
$$X_G = \{X_0, X_1, X_2\}$$

Use graph to formulate likelihood function

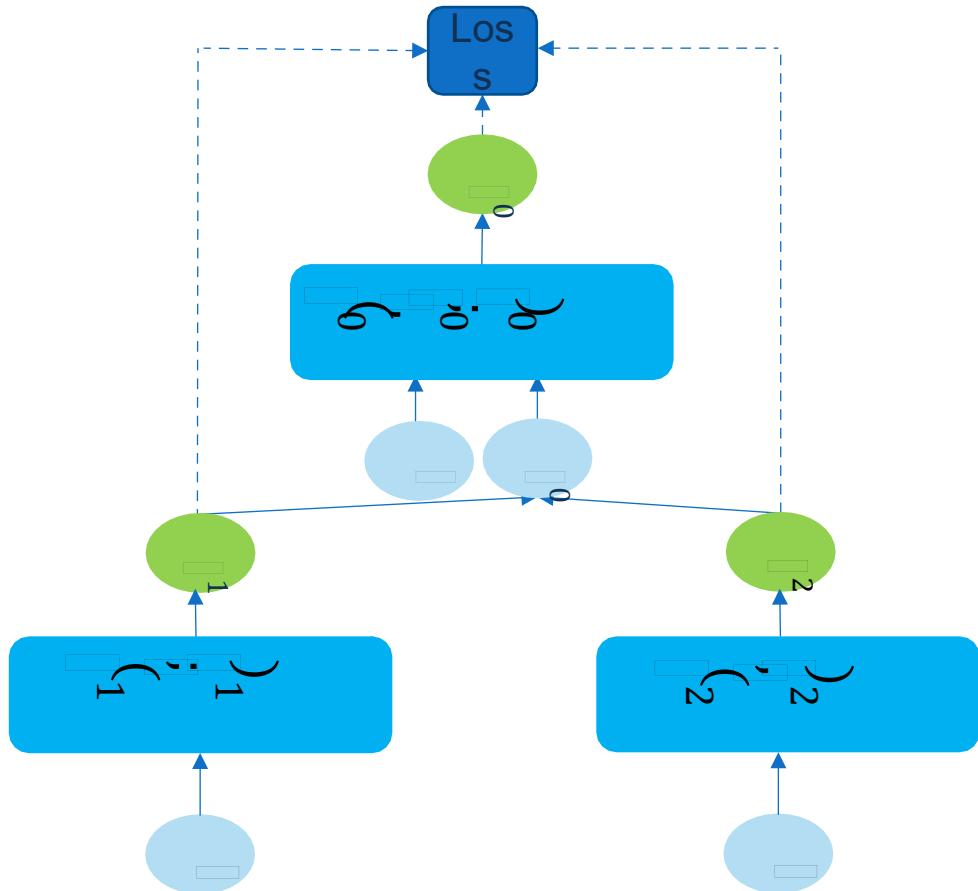
$$p(y_G | X_G, \theta_G) = p(y_0 | X_G, \theta_G) p(y_1 | X_1, \theta_1) p(y_2 | X_2, \theta_2)$$

For peer assets  $k > 0$

$$\log p(y_k | X_k, \theta_k) \propto \|y_k - g_k(X_k; \theta_k)\|_{\Sigma_{\epsilon_k}}^2$$

For asset of interest  $k = 0$

$$\log p(y_0 | X_G, \theta_G) = -\frac{N_0}{2} \log \pi - N_0 \log |\Sigma_{\epsilon_0}| - \frac{1}{2} (y_0 - g(X_0; \theta_G))^\top \Sigma_{\epsilon_0}^{-1} (y_0 - g(X_0; \theta_G))$$



# SINGLE FIDELITY GAUSSIAN PROCESS (GPs)

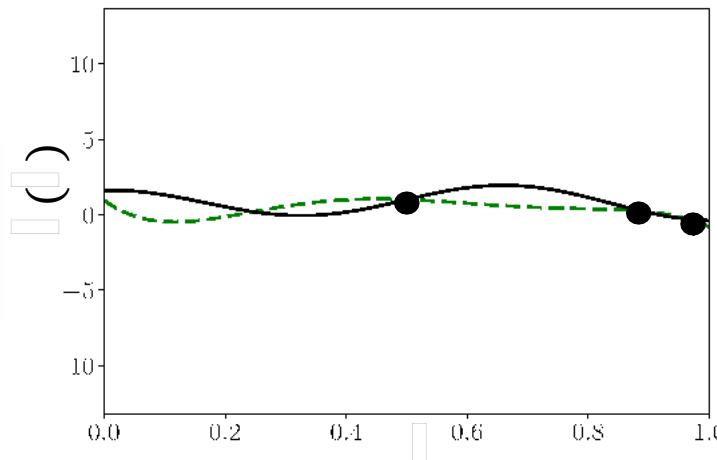
We will build multi-asset digital twins using Gaussian processes

Given data  $(X, y)$  and covariance kernel  $C$  a single asset GP posterior mean and variance are

$$m(x) = t(x)^\top C(X, X)^{-1} y$$

$$\sigma^2(x) = C(x, x) - t(x)^\top C(X, X)^{-1} t(x), \quad t(x) = C(x, X)$$

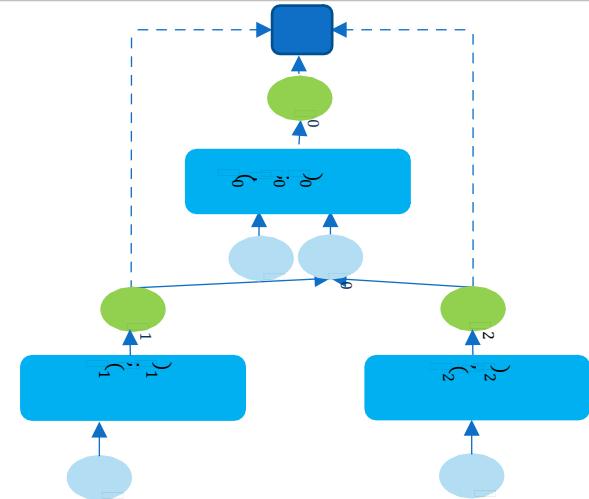
But approximation will be poor for limited data



# GAUSSIAN PROCESS DISCREPANCY MODELING

Assume multiplicative and additive  
discrepancy

$$g_0(x, g_1(x), g_2(x); \theta_2) = \rho_1(x; \theta_2^{\rho_1})g_1(x) + \rho_2(x; \theta_2^{\rho_2})g_2(x) + \delta(x; \theta_2^\delta)$$



Assume  $\mathbf{g}_1, \mathbf{g}_2, \boldsymbol{\delta}$  are Gaussian processes with correlation matrices  $\mathbf{C}_0, \mathbf{C}_1, \mathbf{C}_2$

$$C = \begin{bmatrix} C_0(X_0, X_0) + \rho_{12}^2 C_1(X_0, X_0) + \rho_{13}^2 C_2(X_0, X_0) & \rho_{12} C_1(X_0, X_1) & \rho_{13} C_2(X_0, X_2) \\ \rho_{12} C_1(X_1, X_0) & C_1(X_1, X_1) & 0 \\ \rho_{13} C_2(X_2, X_0) & 0 & C_2(X_2, X_2) \end{bmatrix}$$

# TRAINING MULTI-ASSET GPs

Finding GP hyperparameters by minimizing the negative log likelihood is challenging

$$\text{NLL} = \frac{1}{2} \log (\det \mathbf{C}) + \frac{1}{2} \mathbf{y}^T \mathbf{C}^{-1} \mathbf{y} + \frac{N}{2} \log (2\pi)$$

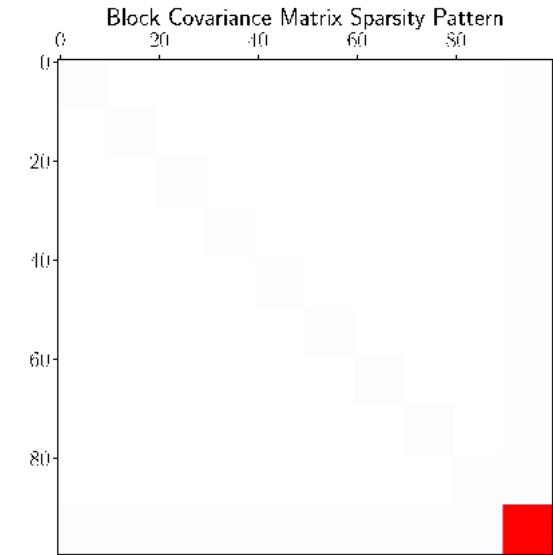
Naïve Cholesky factorization of  $\mathbf{C}$  is expensive

$$O(N^3),$$

$$N = \sum_{k=0}^K N_k$$

But we can exploit sparse covariance to efficiently evaluate NLL and its gradient (left  $K=10$  peers)

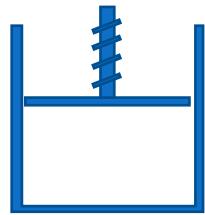
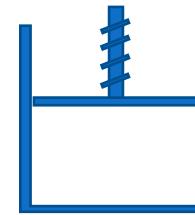
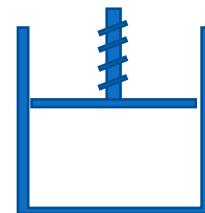
$$O(\widehat{N}^3), \quad \widehat{N} = \max(N_k)$$



# PISTON EXAMPLE

Predict cycle time of a piston as a function of piston weight and spring coefficient

$$C(x) = 2\pi \sqrt{\frac{M}{k + S^2 \frac{P_0 V_0}{T_0} \frac{T_a}{V^2}}}$$
$$V = \frac{S}{2k} \left( \sqrt{A^2 + 4k \frac{P_0 V_0}{T_0} T_a} - A \right)$$
$$A = P_0 S + 19.62 M - \frac{k V_0}{S}$$

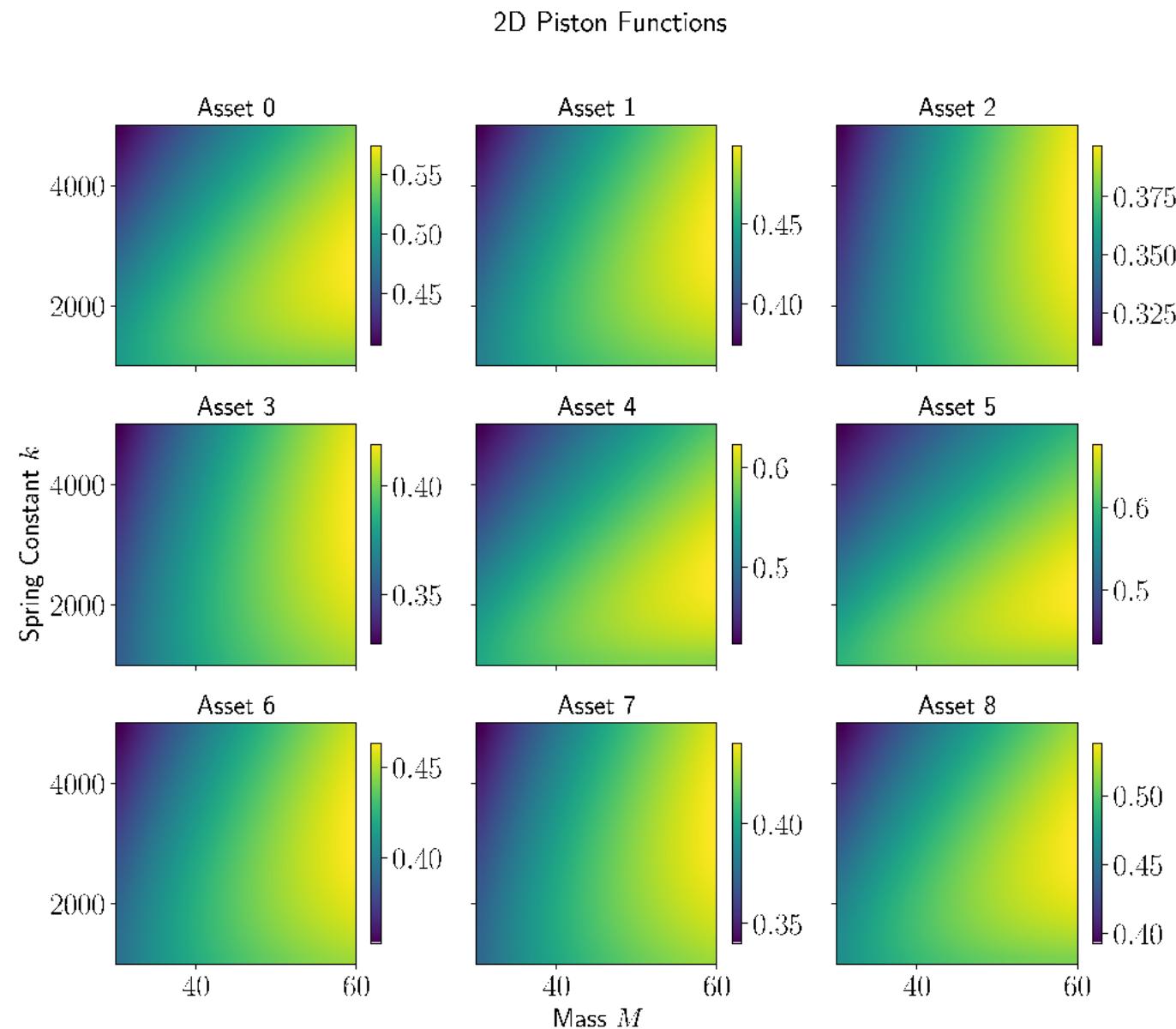


## Input variables $x$

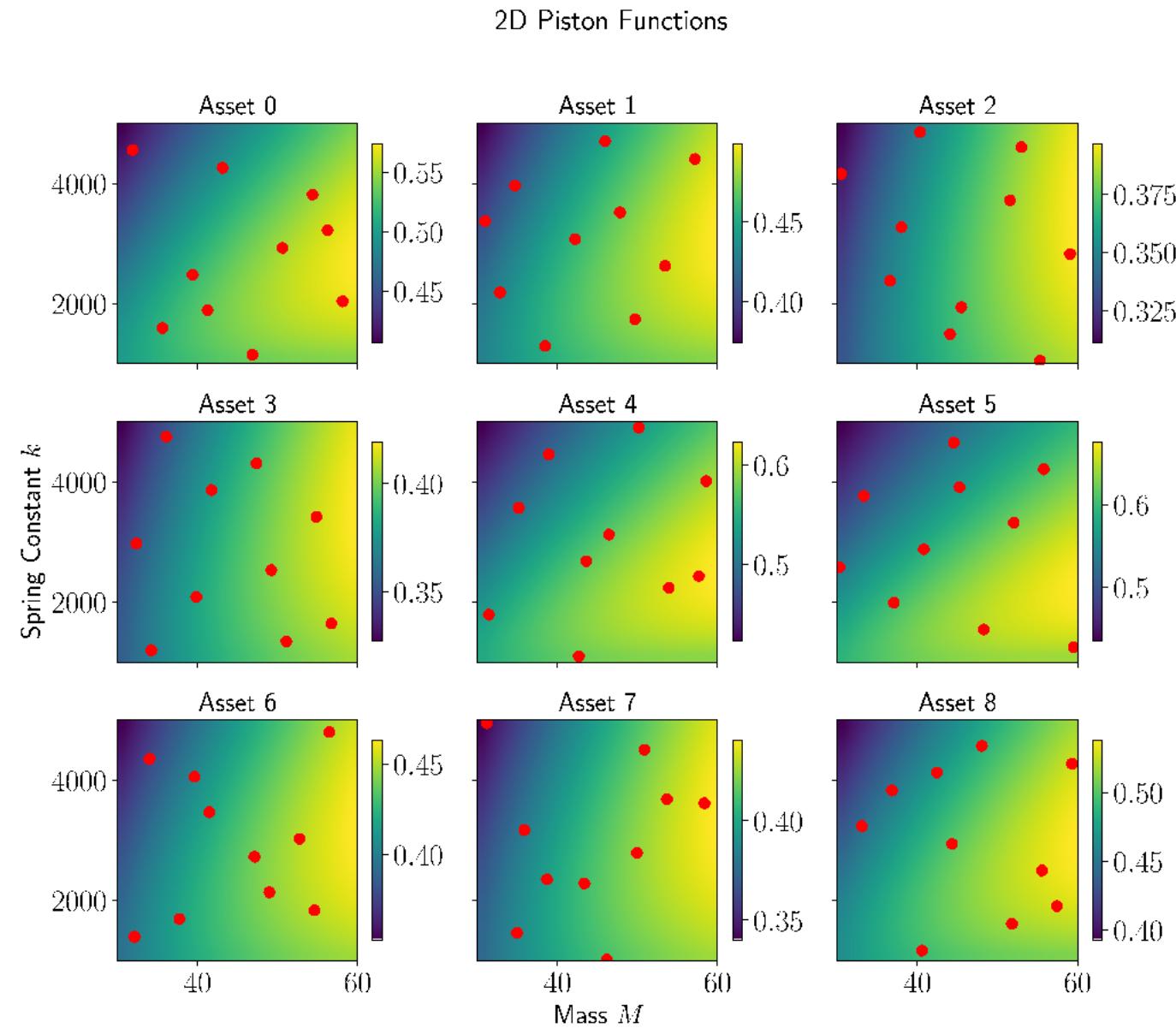
$M \in [30, 60]$	piston weight (kg)
$S \in [0.005, 0.020]$	piston surface area ( $\text{m}^2$ )
$V_0 \in [0.002, 0.010]$	initial gas volume ( $\text{m}^3$ )
$k \in [1000, 5000]$	spring coefficient (N/m)
$P_0 \in [90000, 110000]$	atmospheric pressure ( $\text{N/m}^2$ )
$T_a \in [290, 296]$	ambient temperature (K)
$T_0 \in [340, 360]$	filling gas temperature (K)

## Latent variables

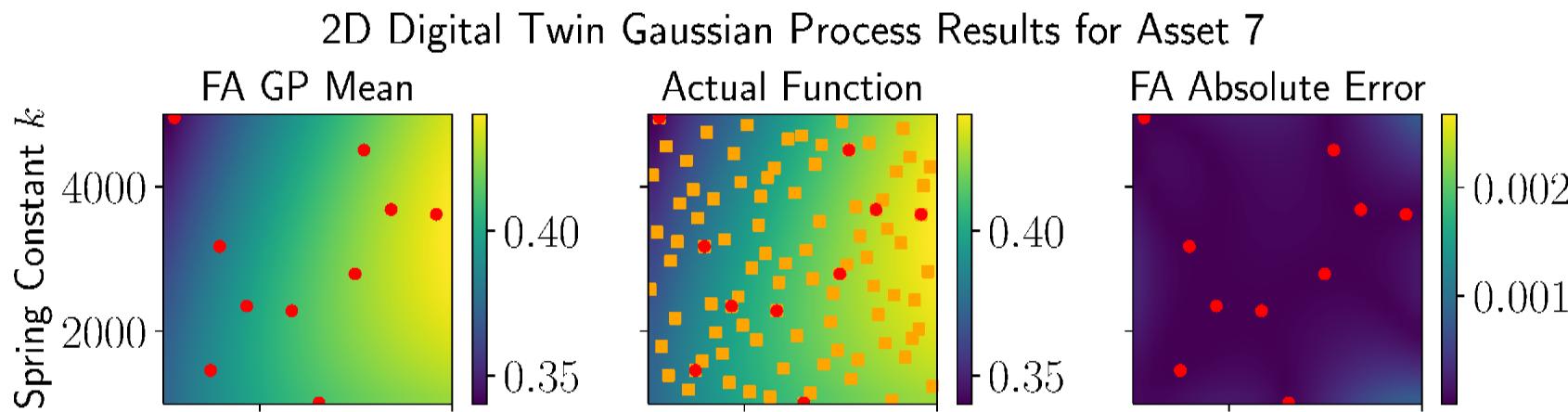
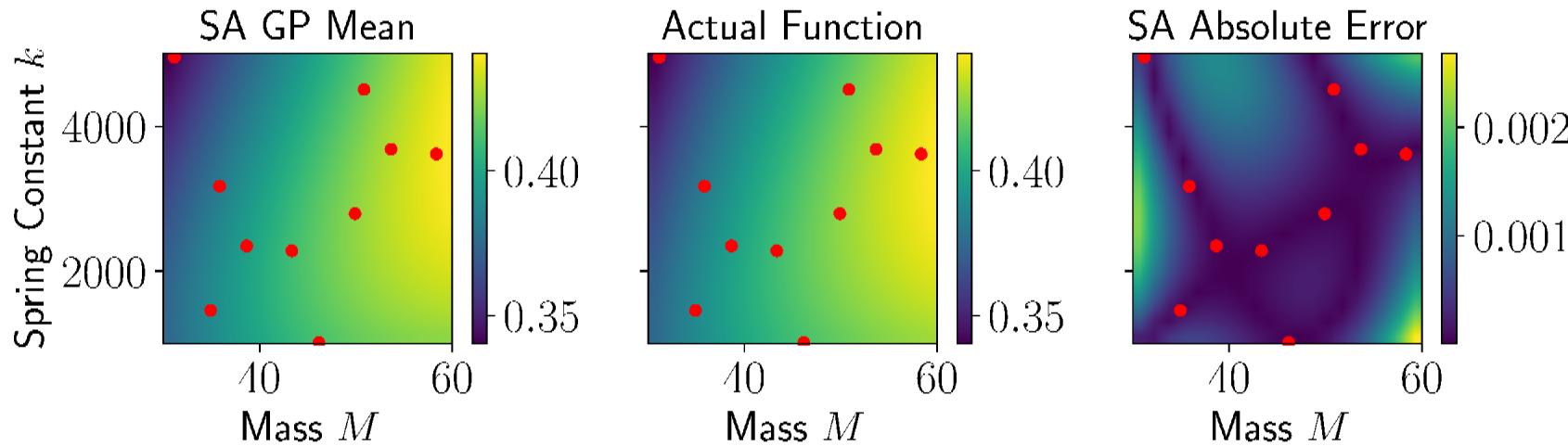
# PISTON EXAMPLE: RESPONSE SURFACES



# PISTON EXAMPLE: TRAINING DATA

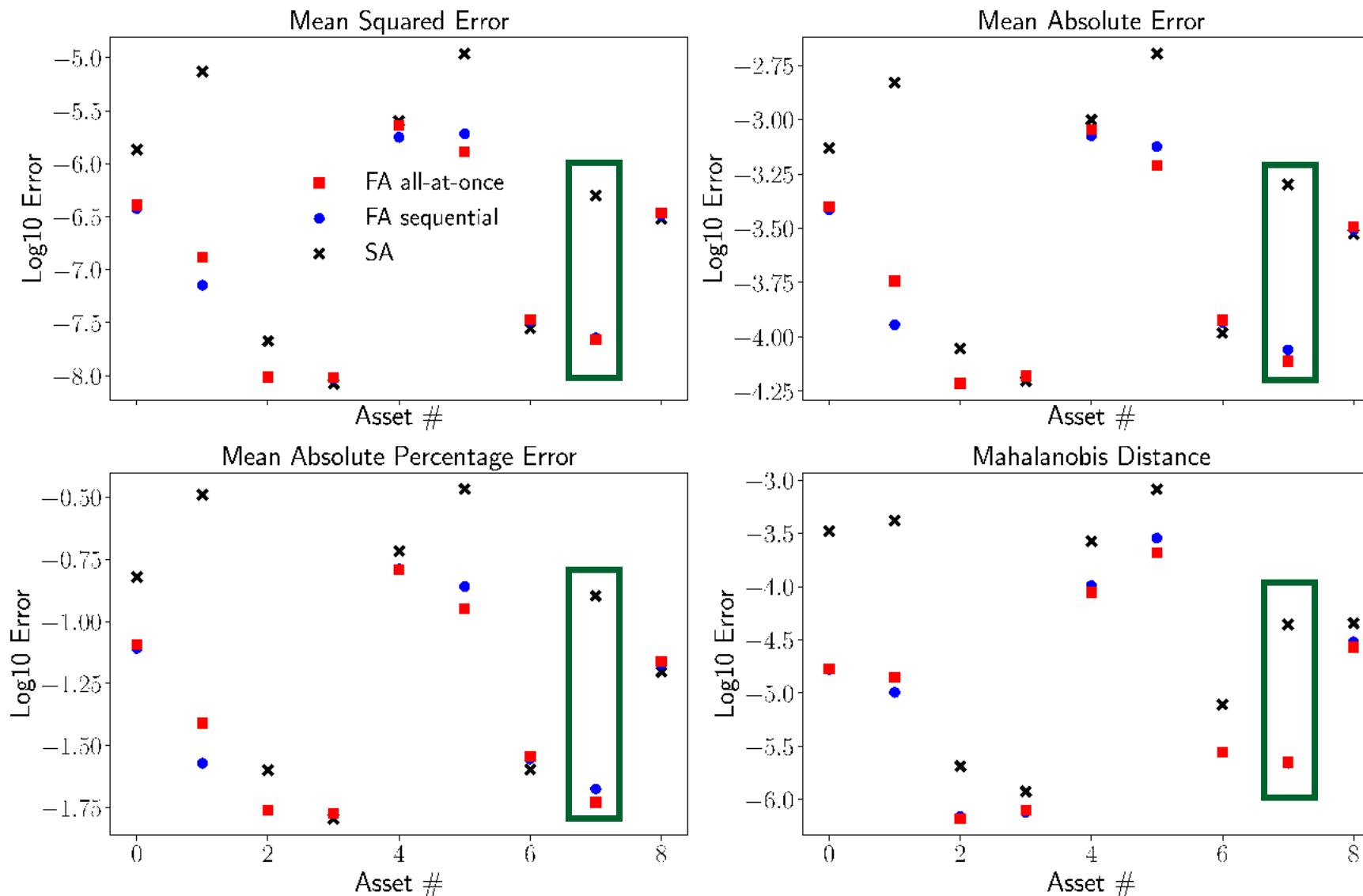


# PISTON EXAMPLE: ERROR FOR SINGLE ASSET



# PISTON EXAMPLE: ERROR FOR ALL ASSETS

2D Piston Fleet of Assets Error Metrics

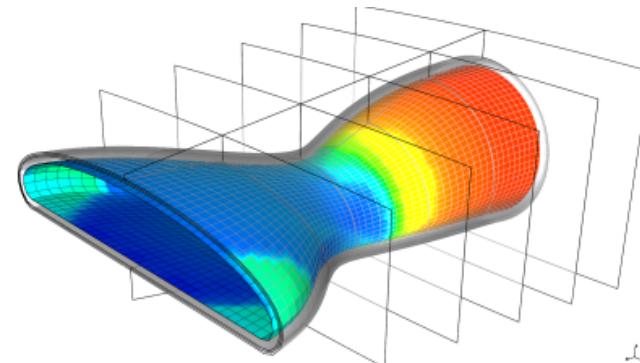


# CONNECTING TWINS VIA PARAMETERS

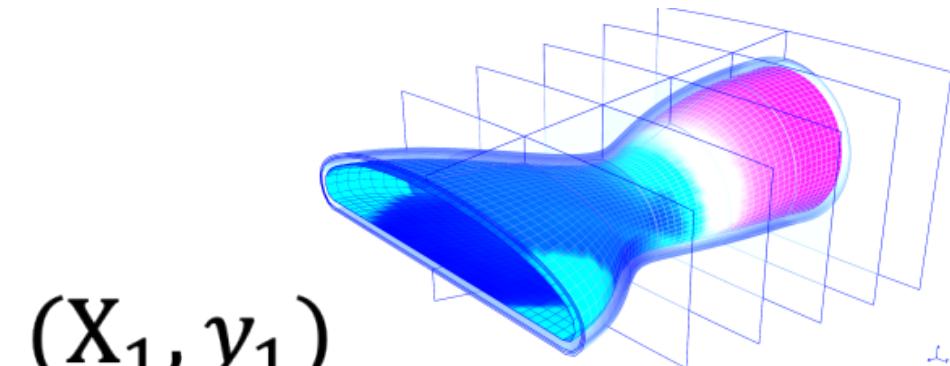
Collect data for each asset

Formulate model for each asset

$$g_0(x; \theta_1, \theta_2)$$



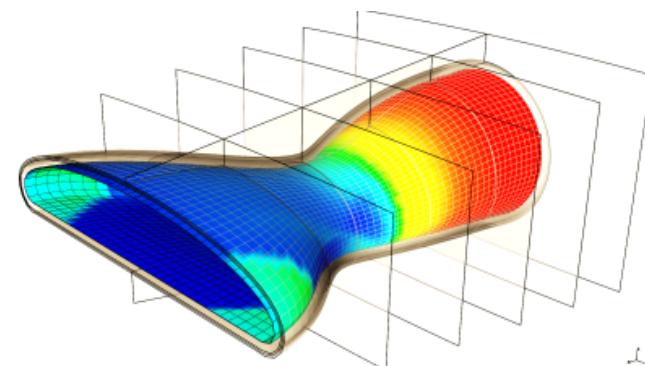
$$(X_0, y_0)$$



$$(X_1, y_1)$$

Asset

$$1(x; \theta_1)$$



$$(X_2, y_2)$$

Asset

$$2(x; \theta_2)$$

# LATENT VARIABLE-BASED ASSET CLASS LEARNING

Assume variables are related by latent variables  $\theta$

$$\theta_G = [\theta_0, \theta_{\sim 0}^\top]^\top \quad \theta_0 = A\theta_{\sim 0} + b + \nu$$

Using hierarchical priors posterior is given by

$$\begin{aligned} p(\theta_G, A, b \mid y) &\propto p(y \mid \theta_G, A, b) p(\theta_G, A, b) \\ &= p(y \mid \theta_G) p(\theta_{\sim 0}) p(A) p(b) \end{aligned}$$

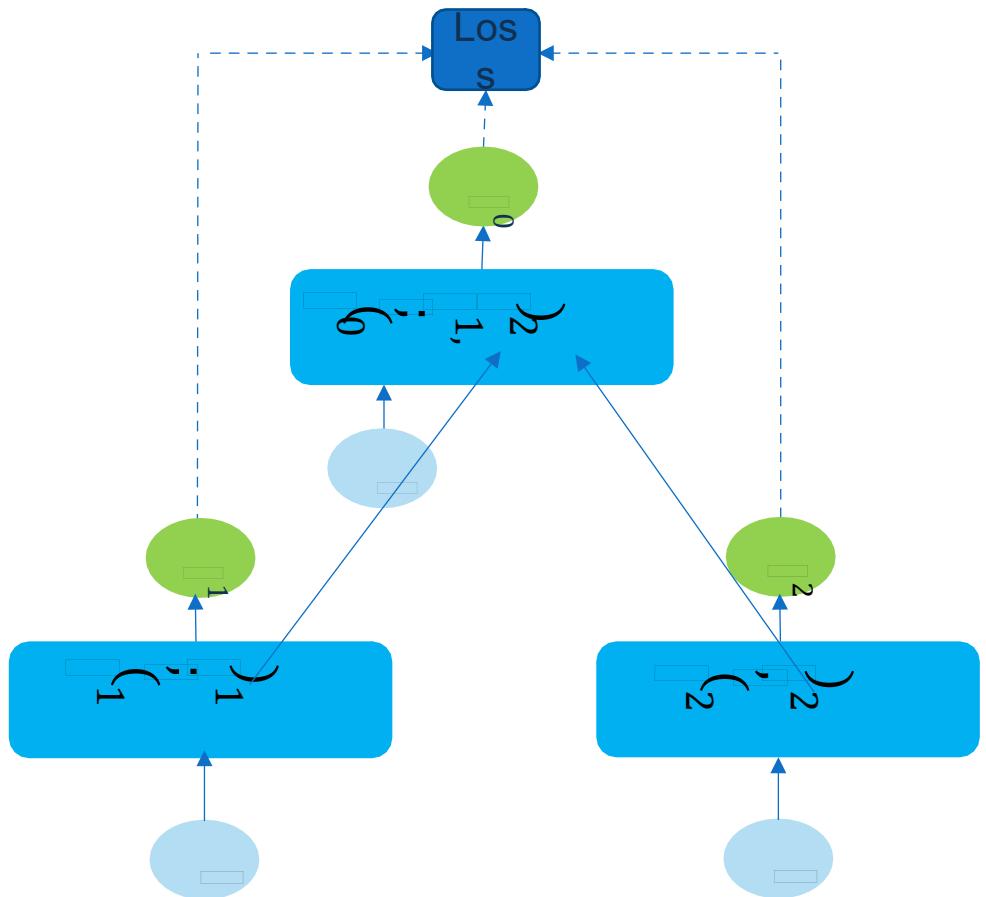
Log likelihood is

$$\log p(y \mid \theta_G) = \log p(y_0 \mid \theta_G) + \sum_{k=1}^K \log p(y_k \mid \theta_k)$$

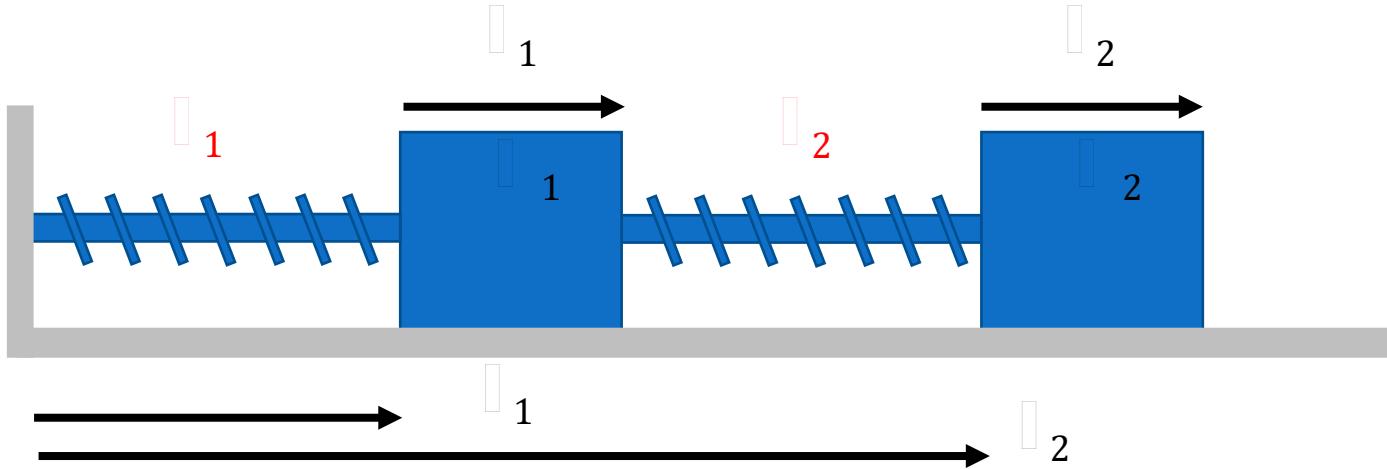
For asset of interest  $k = 0$

$$\log p(y_0 \mid X_G, \theta_G) = -\frac{N_0}{2} \log \pi - N_0 \log |\Sigma_{\epsilon_0 \nu}| - \frac{1}{2} (y_0 - g_0(X_0; \gamma_G))^\top \Sigma_{\epsilon_0 \nu}^{-1} (y_0 - g_0(X_0; \gamma_G))$$

$$\Sigma_{\epsilon_0 \nu} = \Sigma_{\epsilon_0} + \Phi \Sigma_\nu \Phi^\top \quad \text{Assuming linear model } g_0 = \Phi(X) \theta_0$$



# SPRING SYSTEM EXAMPLE

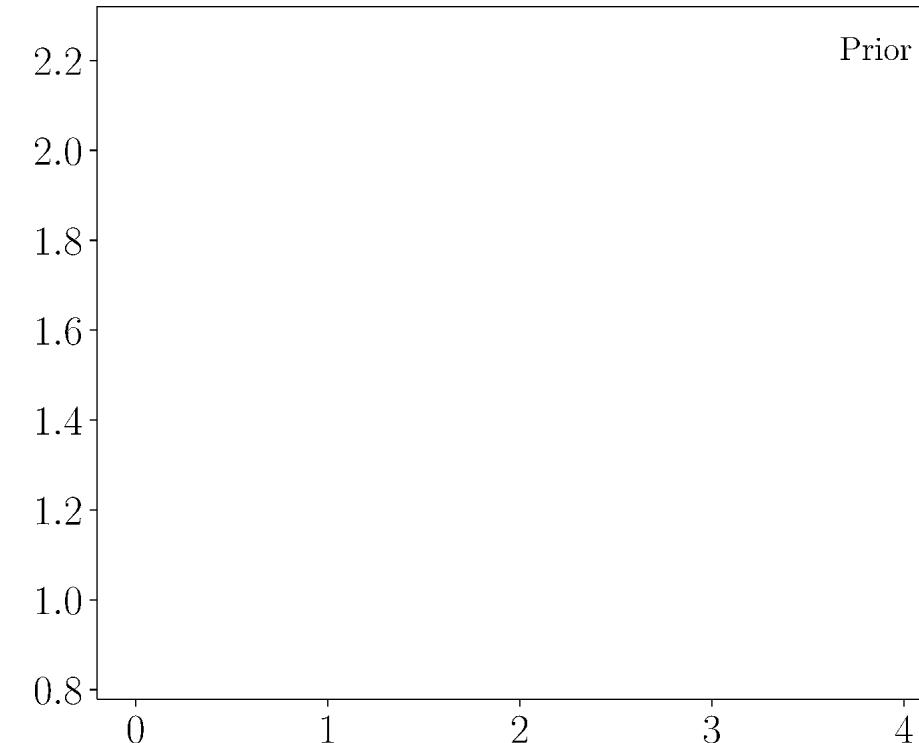
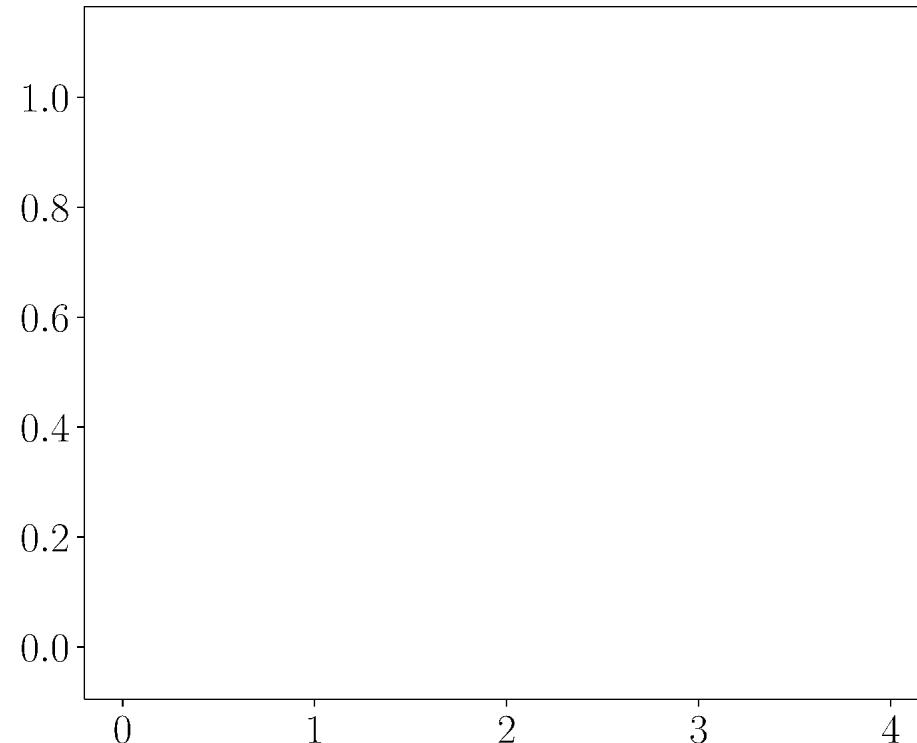


$$m_1 x_1'' + b_1 x_1' + k_1(x_1 - L_1) - k_2(x_2 - x_1 - L_2) = 0$$
$$m_2 x_2'' + b_2 x_2' + k_2(x_2 - x_1 - L_2) = 0$$

Assume spring coefficient has deteriorated  
differently for each asset

# ASSIGN A PRIOR ENCODING PRIOR KNOWLEDGE

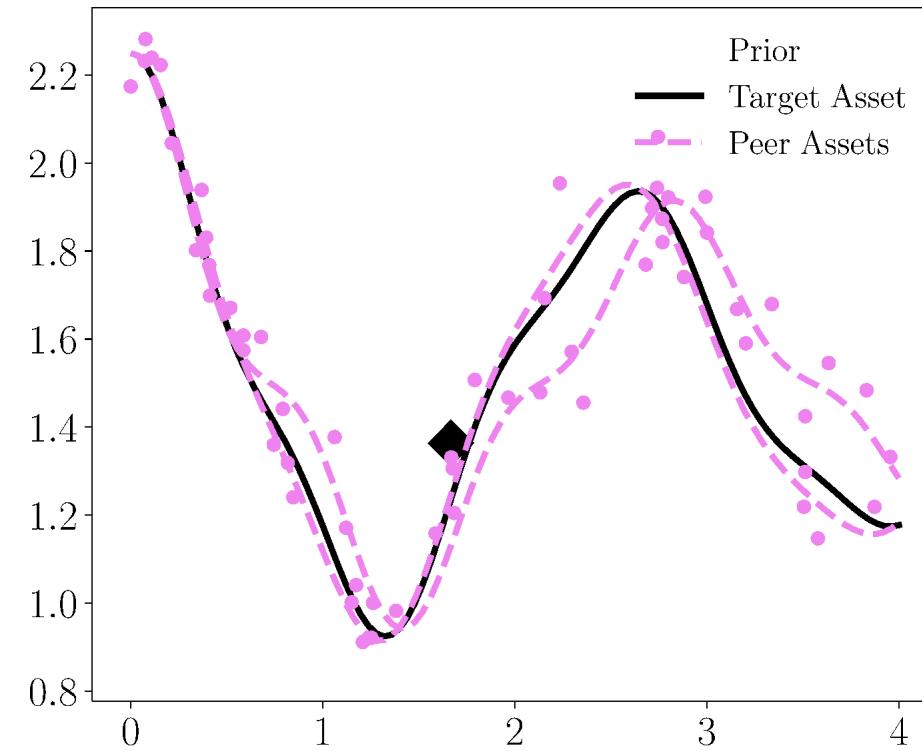
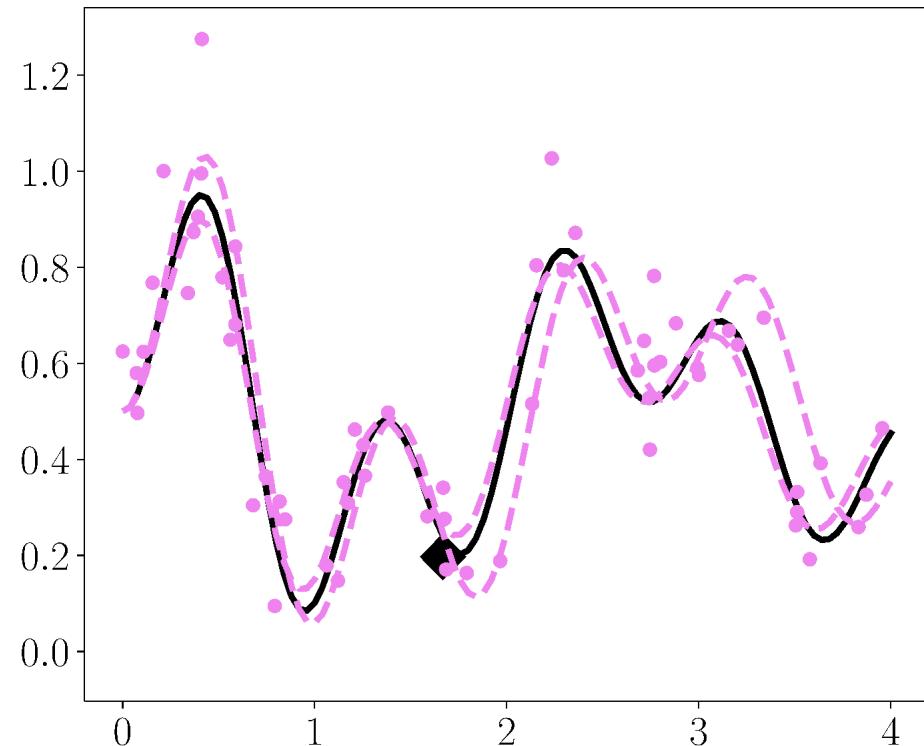
$$p(\theta_{\sim 0}) \sim N(\mu_{\sim 0}, \Sigma_{\sim 0})$$
$$A = \text{diag}(a), \quad p(a) \sim N(1/K, \Sigma_a)$$
$$p(b) \sim N(0, \Sigma_b)$$



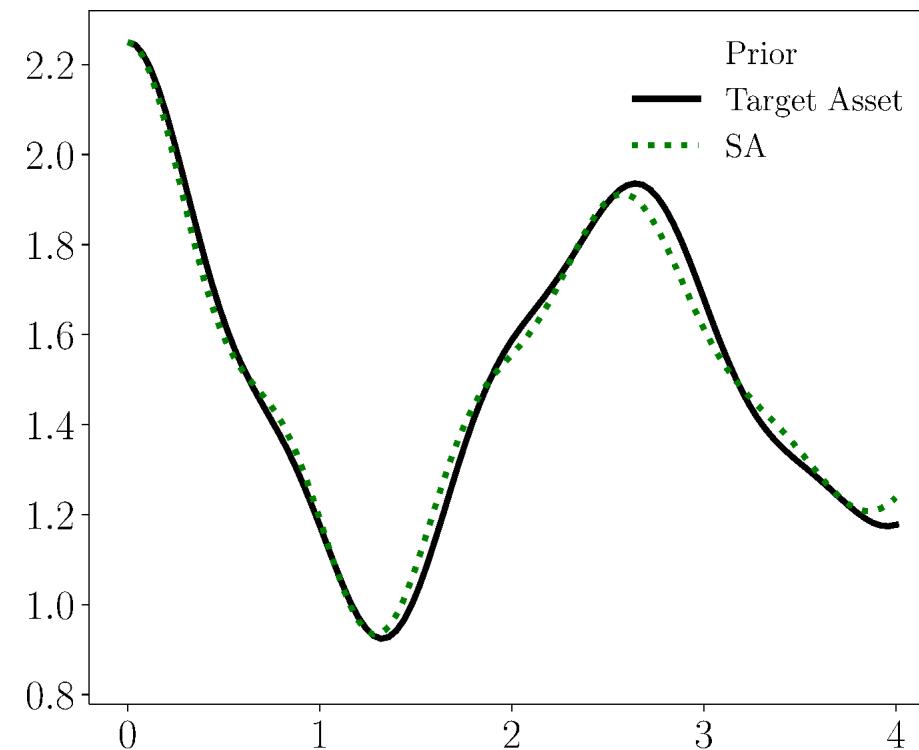
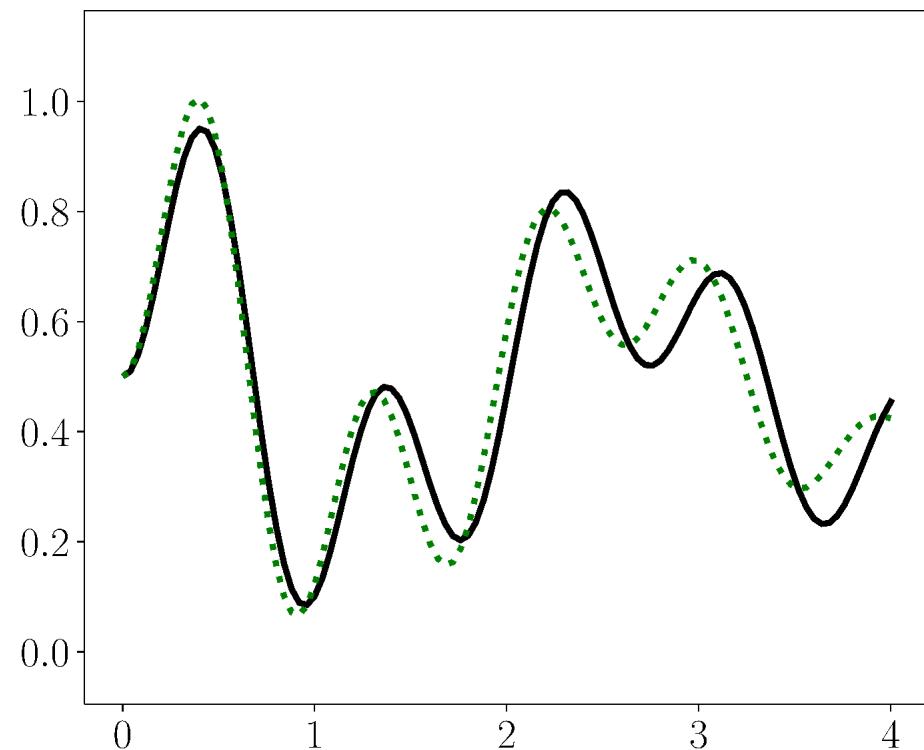
Prior predictive for target asset

# COLLECT DATA FROM ALL ASSETS IN THE FLEET

Using all assets we have a rich data set



# USING ONLY DATA FROM A SINGLE ASSET PRODUCES A POOR DIGITAL TWIN



# USING DATA FROM THE FLEET IMPROVES PERFORMANCE OF A SINGLE TWIN DRAMATICALLY

