

IMPROVING DIGITAL TWINS BY LEARNING FROM A FLEET OF ASSETS

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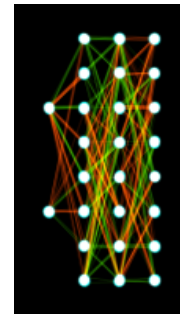
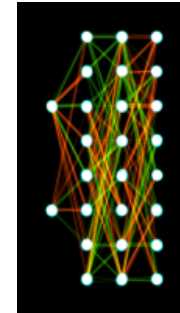
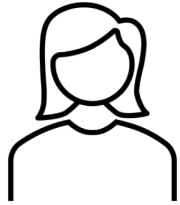
Advanced
Scientific

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A DIGITAL TWIN

A digital twin is an evolving virtual model of a specific system or physical asset that assimilates data over its lifecycle to become a “patient-specific” model that can be used for intelligent automation and decision making.



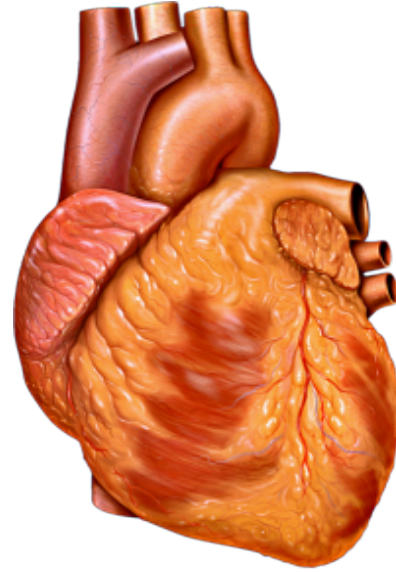
Person

Data

Digital Twin

Decision
making

SCIENTIFIC DIGITAL TWINS



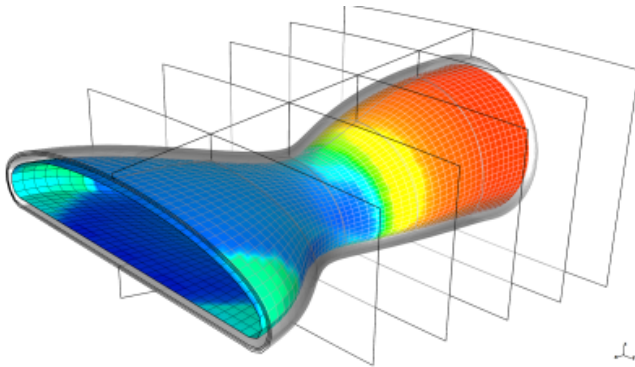
FORMULATING A DIGITAL TWIN

Assimilation

Want to calibrate the digital twin M to the physical asset

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

Asset



Digital
Twin

$$M(s, t, x; \theta_k)$$

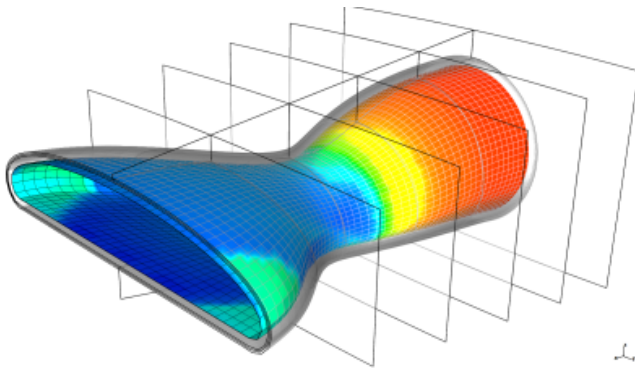
FORMULATING A DIGITAL TWIN

Assimilation

Want to calibrate the digital twin M to the physical asset

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

Asset

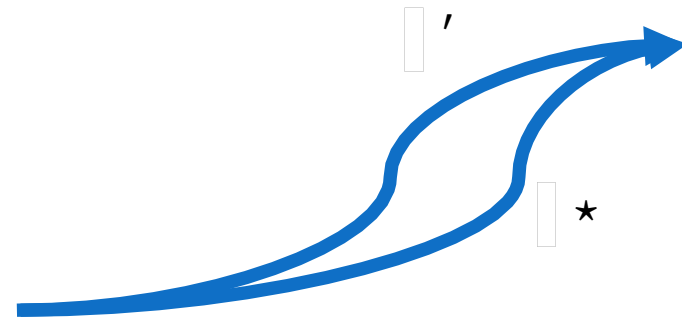


Digital
Twin

$$M(s, t, x; \theta_k)$$

Prediction

Want to use the digital twin to determine how to fly asset safely given current health

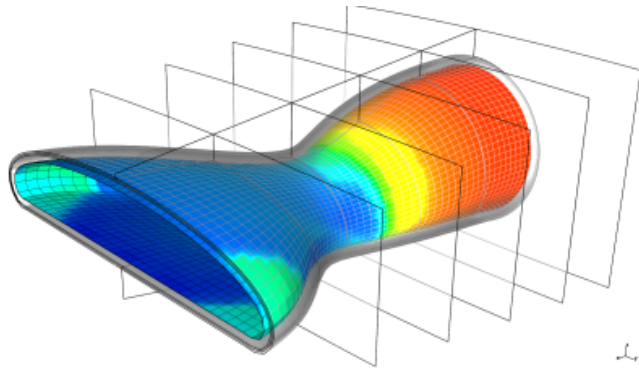


FORMULATING A DIGITAL TWIN

Want to predict performance
under different flight scenarios x

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$

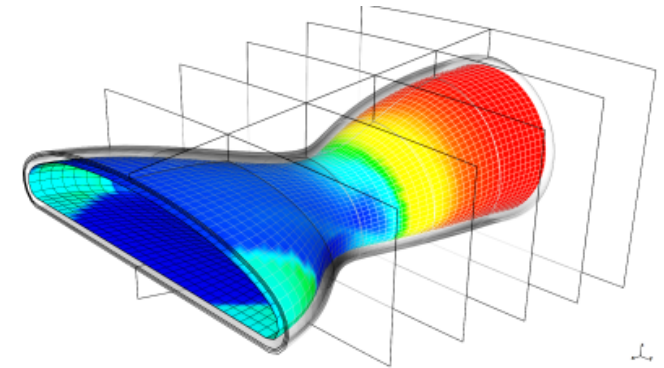
Asset



Event changes
health of asset
 $\theta_k \rightarrow \theta_{k+1}$

Collect data to infer health θ^*

$$y = h(M(s, x, t; \theta^*)) + \epsilon$$



Digital
Twin

$$M(s, t, x; \theta_k)$$

$$M(s, t, x; \theta_{k+1})$$

Time

FORMULATING A DIGITAL TWIN

The following process is often used to update and predict with a digital twin developed using first principles, e.g. PDE model.

Collect observations

$$y = h(s; x, \theta^*) + \epsilon$$

Temperature of nozzle

Infer posterior of model variables

$$p(\theta | y) \propto p(y | \theta)p(\theta)$$

Estimate thermal conductivity due to changes in deteriorating insulation

Propagate posterior through predictive model

$$p(s, \theta) = p(s | (\theta, x, t))$$

Predict maximum stress for specific future flight scenarios x

A DATA DRIVEN DIGITAL TWIN

The following process is often used to update and predict with a purely data-driven digital twin

Want to construct approximation

$$f(x; \theta) \approx \hat{g}_N(x; \theta_n) = \sum_{n=0}^N \theta_n \phi_n(x)$$

Stress f vs flight scenarios x

Collect observations

$$w = f(x; \theta^*) + \epsilon$$

Observations are of stress directly

Learn approximation unknowns θ

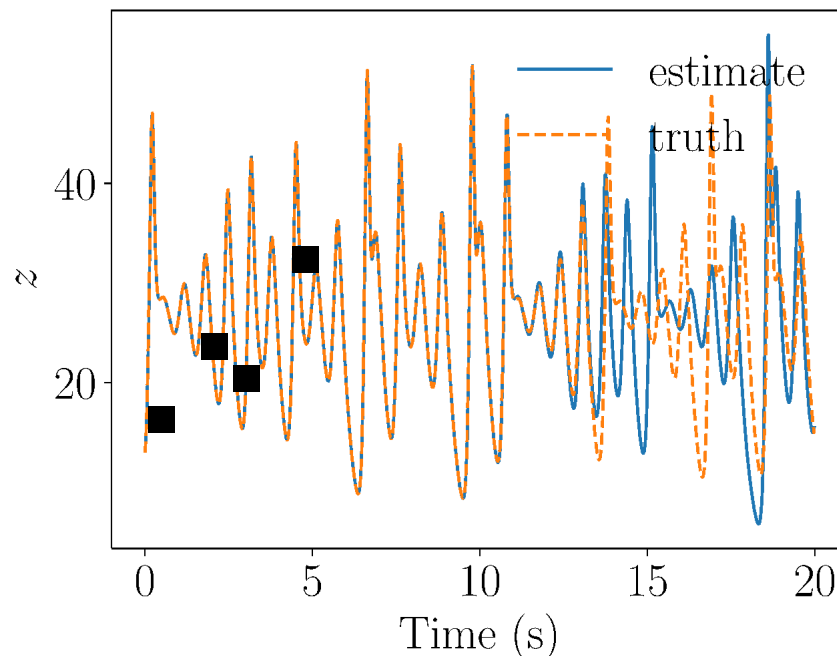
$$\operatorname{argmin}_{\theta} ||w - \hat{g}_N(x, \theta)||_{\Sigma_{\epsilon}}$$

E.g. Use MLE

CHALLENGE

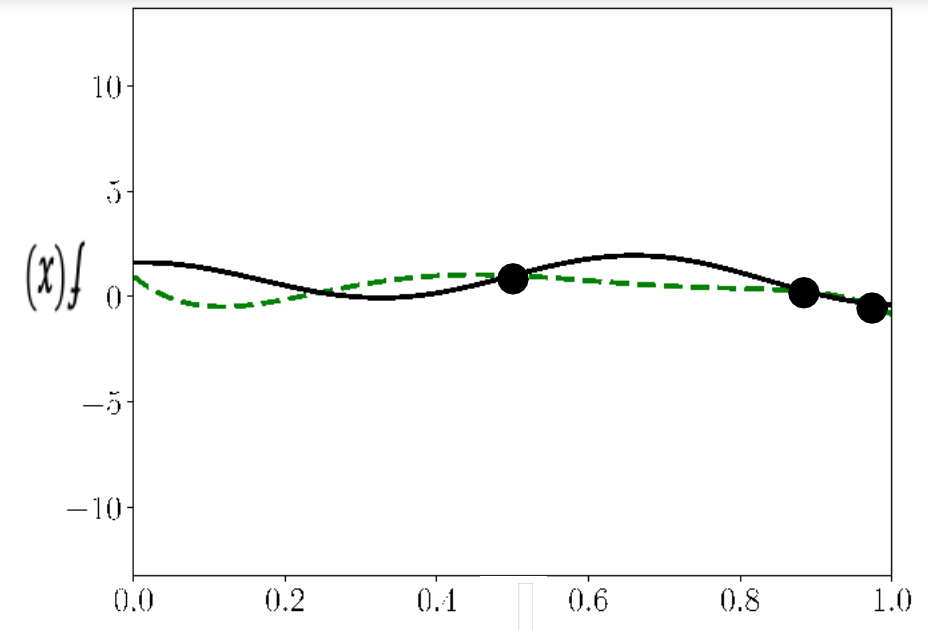
How can we make informative inferences to enable accurate prediction when data is limited?

A first principles digital twin



$$\begin{aligned} \dot{x}_1 &= \sigma(x_2 - x_1), \\ \dot{x}_2 &= x_1(\rho - x_3) - x_2, \\ \dot{x}_3 &= x_1x_2 - \beta x_3 \end{aligned} \quad \theta = [\sigma\rho\beta]$$

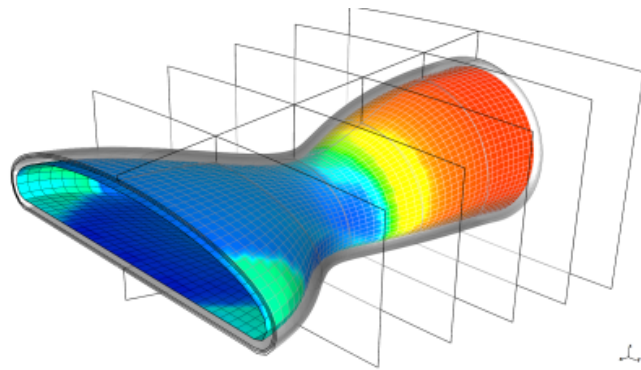
A purely data-driven digital twin



$$\hat{g}_N(x; \theta_n) = \sum_{n=0}^N \theta_n \phi_n(x) \quad \theta_n \sim (0,1)$$

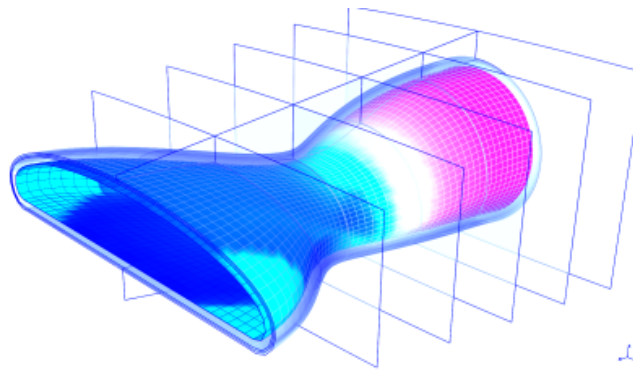
DIGITAL TWINS OF ASSET CLASSES

Often an asset is one of many within a class of assets. The exact health of these assets will depend on manufacturing differences (e.g. additive manufacturing) and/or the operating conditions of each individual asset.



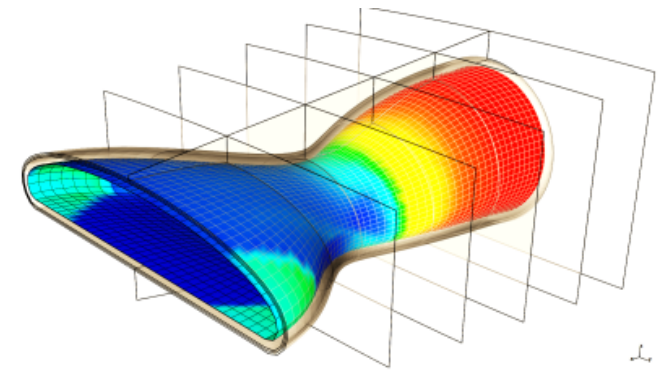
Asset

0



Asset

1



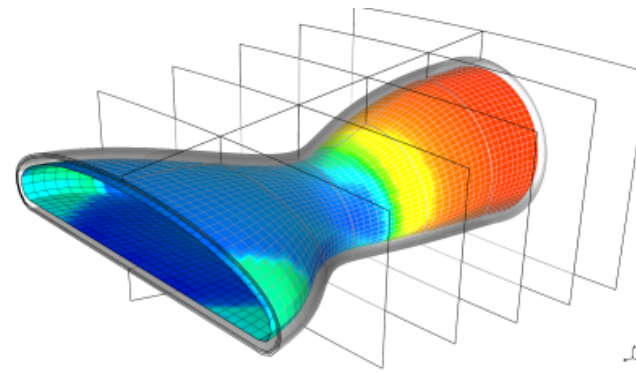
Asset

2

However, many assets are similar and we will exploit relationships in the observational data to improve the predictive capability of digital twins.

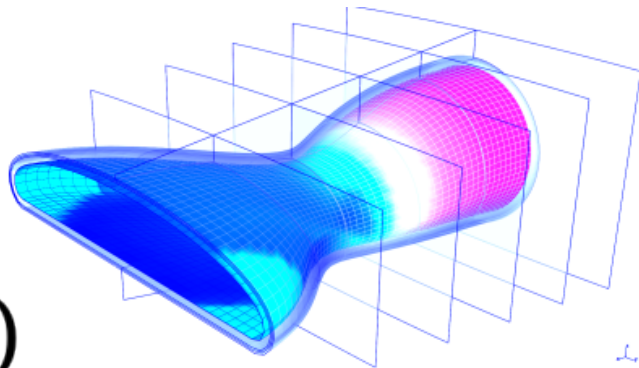
CONNECTING TWINS VIA THEIR OUTPUTS

Collect data for
each asset



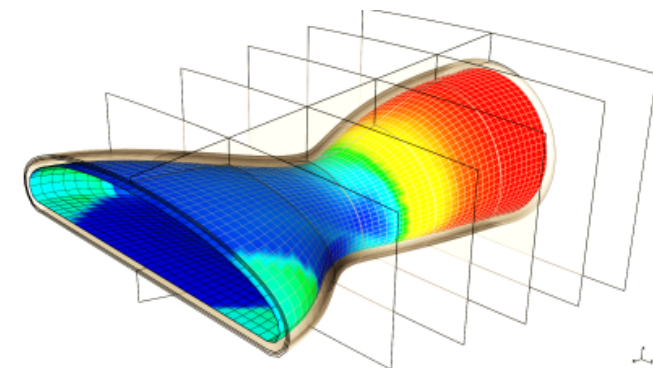
(X_0, y_0)

Asset
0



(X_1, y_1)

Asset
1



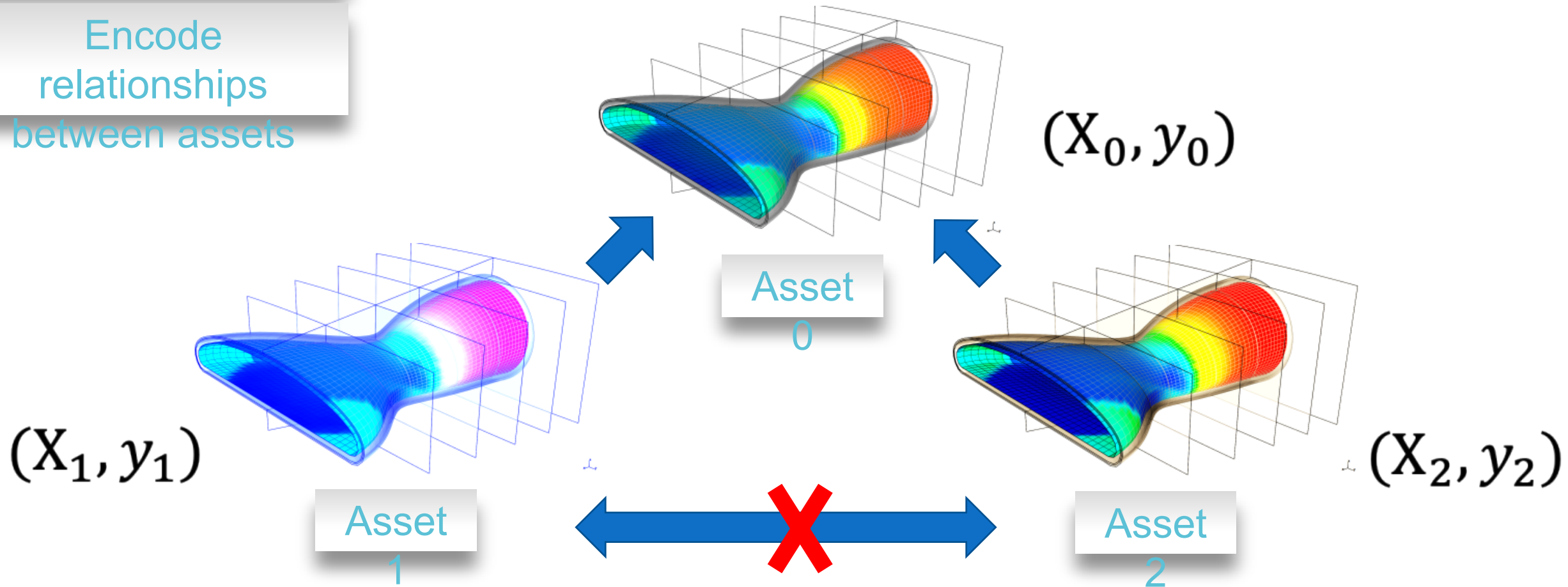
(X_2, y_2)

Asset
2

CONNECTING TWINS VIA THEIR OUTPUTS

Collect data for
each asset

Encode
relationships
between assets



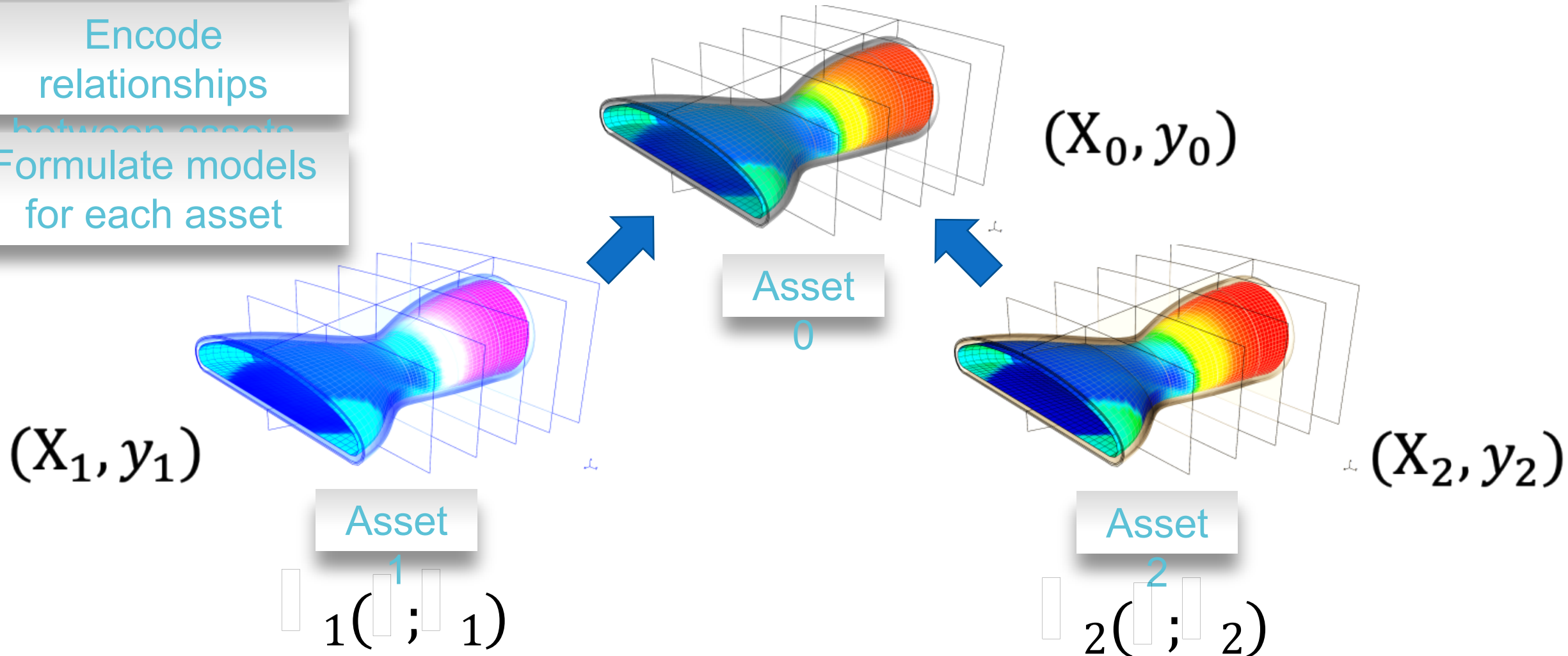
CONNECTING TWINS VIA THEIR OUTPUTS

Collect data for
each asset

Encode
relationships
between assets

Formulate models
for each asset

$$g_0(x, g_1(x; \theta_1), g_2(x; \theta_2); \theta_2)$$



OUTPUT-BASED ASSET CLASS LEARNING

Place all data into G a directed acyclic graph (DAG)

$$y_G = [y_0^\top, y_1^\top, y_2^\top]^\top \quad X_G = \{X_0, X_1, X_2\}$$

$$\theta_G = [\theta_0^\top, \theta_1^\top, \theta_2^\top]^\top$$

Use graph to formulate likelihood function

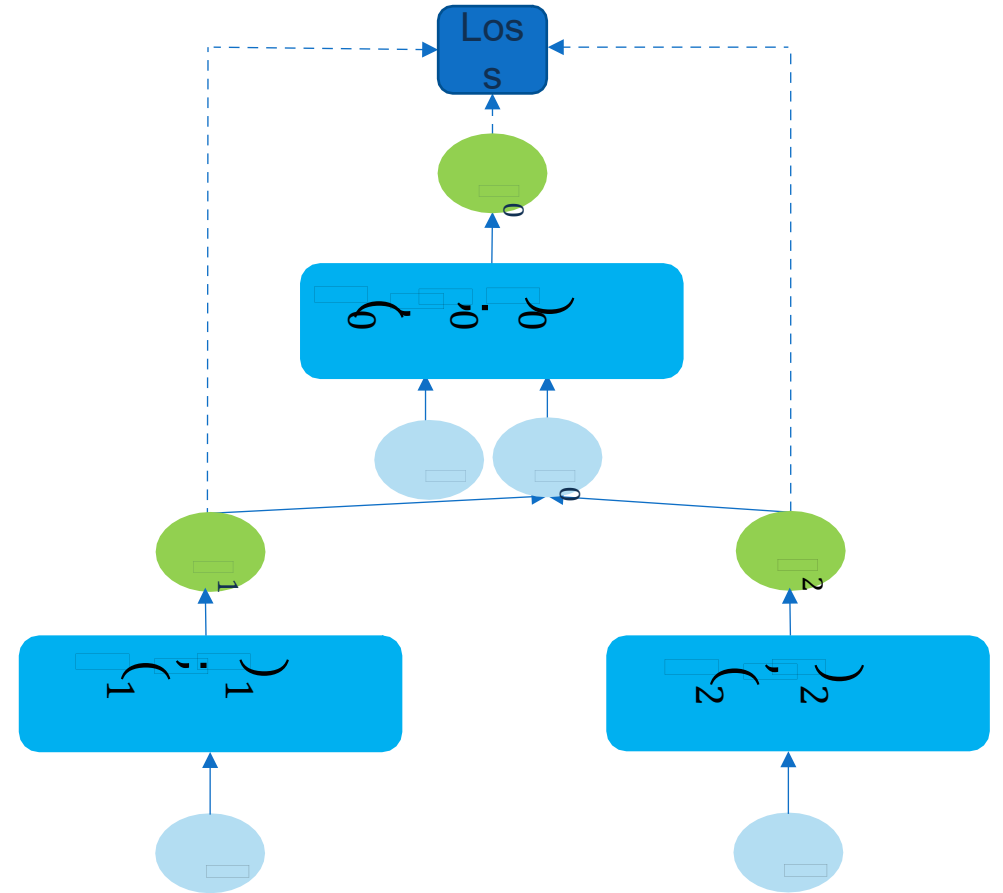
$$p(y_G | X_G, \theta_G) = p(y_0 | X_G, \theta_G) p(y_1 | X_1, \theta_1) p(y_2 | X_2, \theta_2)$$

For peer assets $k > 0$

$$\log p(y_k | X_k, \theta_k) \propto \|y_k - g_k(X_k; \theta_k)\|_{\Sigma_{\epsilon_k}}^2$$

For asset of interest $k = 0$

$$\log p(y_0 | X_G, \theta_G) = -\frac{N_0}{2} \log \pi - N_0 \log |\Sigma_{\epsilon_0}| - \frac{1}{2} (y_0 - g(X_0; \theta_G))^\top \Sigma_{\epsilon_0}^{-1} (y_0 - g(X_0; \theta_G))$$



SINGLE FIDELITY GAUSSIAN PROCESS (GPs)

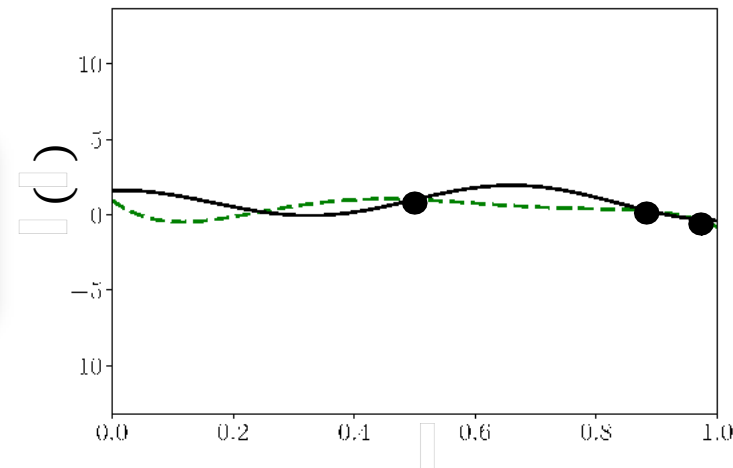
We will build multi-asset digital twins using Gaussian processes

Given data (X, y) and covariance kernel C a single asset GP posterior mean and variance are

$$m(x) = t(x)^\top C(X, X)^{-1} y$$

$$\sigma^2(x) = C(x, x) - t(x)^\top C(X, X)^{-1} t(x), \quad t(x) = C(x, X)$$

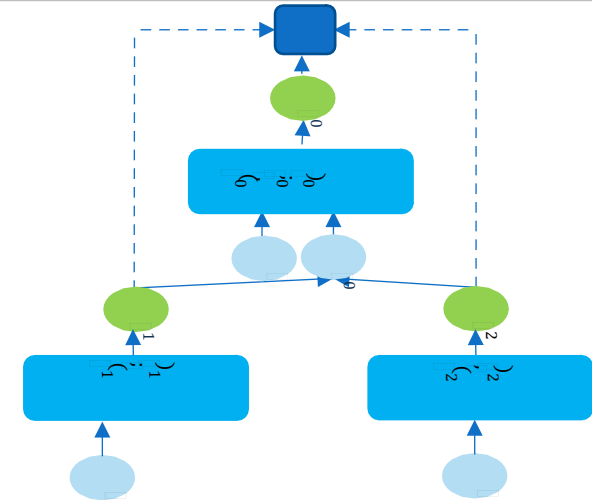
But approximation will be poor for limited data



GAUSSIAN PROCESS DISCREPANCY MODELING

Assume multiplicate and additive discrepancy

$$g_0(x, g_1(x), g_2(x); \theta_2) = \rho_1(x; \theta_2^{\rho_1})g_1(x) + \rho_2(x; \theta_2^{\rho_2})g_2(x) + \delta(x; \theta_2^\delta)$$



Assume g_1, g_2, δ are Gaussian processes with correlation matrices C_0, C_1, C_2

$$C = \begin{bmatrix} C_0(X_0, X_0) + \rho_{12}^2 C_1(X_0, X_0) + \rho_{13}^2 C_2(X_0, X_0) & \rho_{12} C_1(X_0, X_1) & \rho_{13} C_2(X_0, X_2) \\ \rho_{12} C_1(X_1, X_0) & C_1(X_1, X_1) & 0 \\ \rho_{13} C_2(X_2, X_0) & 0 & C_2(X_2, X_2) \end{bmatrix}$$

TRAINING MULTI-ASSET GPs

Finding GP hyperparameters by minimizing the negative log likelihood is
challenging

$$\text{NLL} = \frac{1}{2} \log(\det \mathbf{C}) + \frac{1}{2} \mathbf{y}^T \mathbf{C}^{-1} \mathbf{y} + \frac{N}{2} \log(2\pi)$$

Naïve Cholesky factorization of \mathbf{C} is expensive

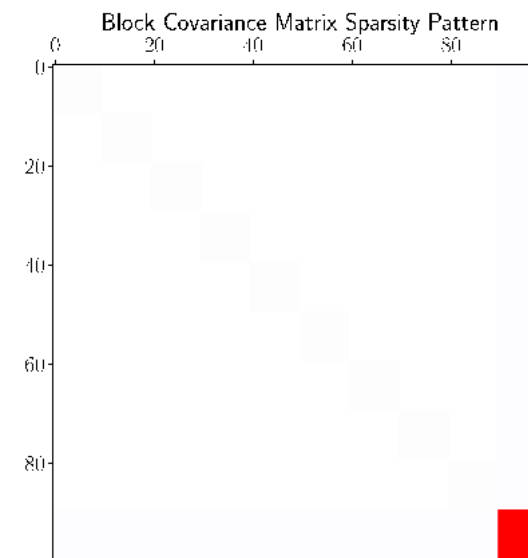
$$O(N^3),$$

$$N = \sum_{k=0}^K N_k$$

But we can exploit sparse
covariance to efficiently evaluate
NLL and its gradient

(left $K=10$ peers)

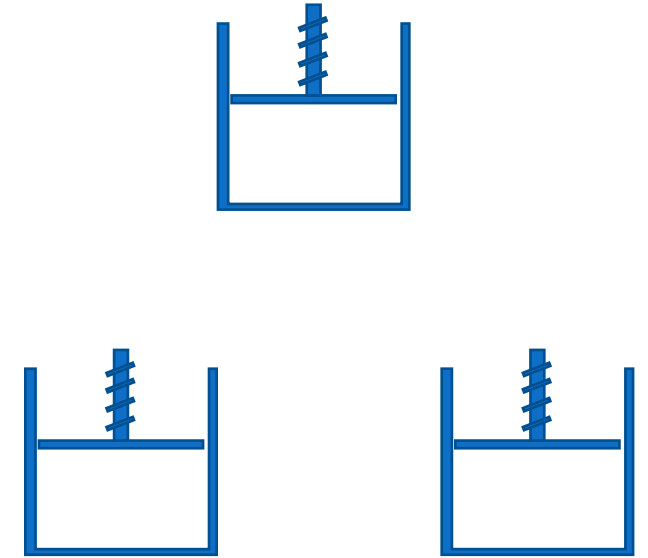
$$O(\hat{N}^3), \quad \hat{N} = \max(N_k)$$



PISTON EXAMPLE

Predict cycle time of a piston as a function of piston weight and spring coefficient

$$C(\mathbf{x}) = 2\pi \sqrt{\frac{M}{k + S^2 \frac{P_0 V_0}{T_0} \frac{T_a}{V^2}}}$$
$$V = \frac{S}{2k} \left(\sqrt{A^2 + 4k \frac{P_0 V_0}{T_0} T_a} - A \right)$$
$$A = P_0 S + 19.62M - \frac{kV_0}{S}$$



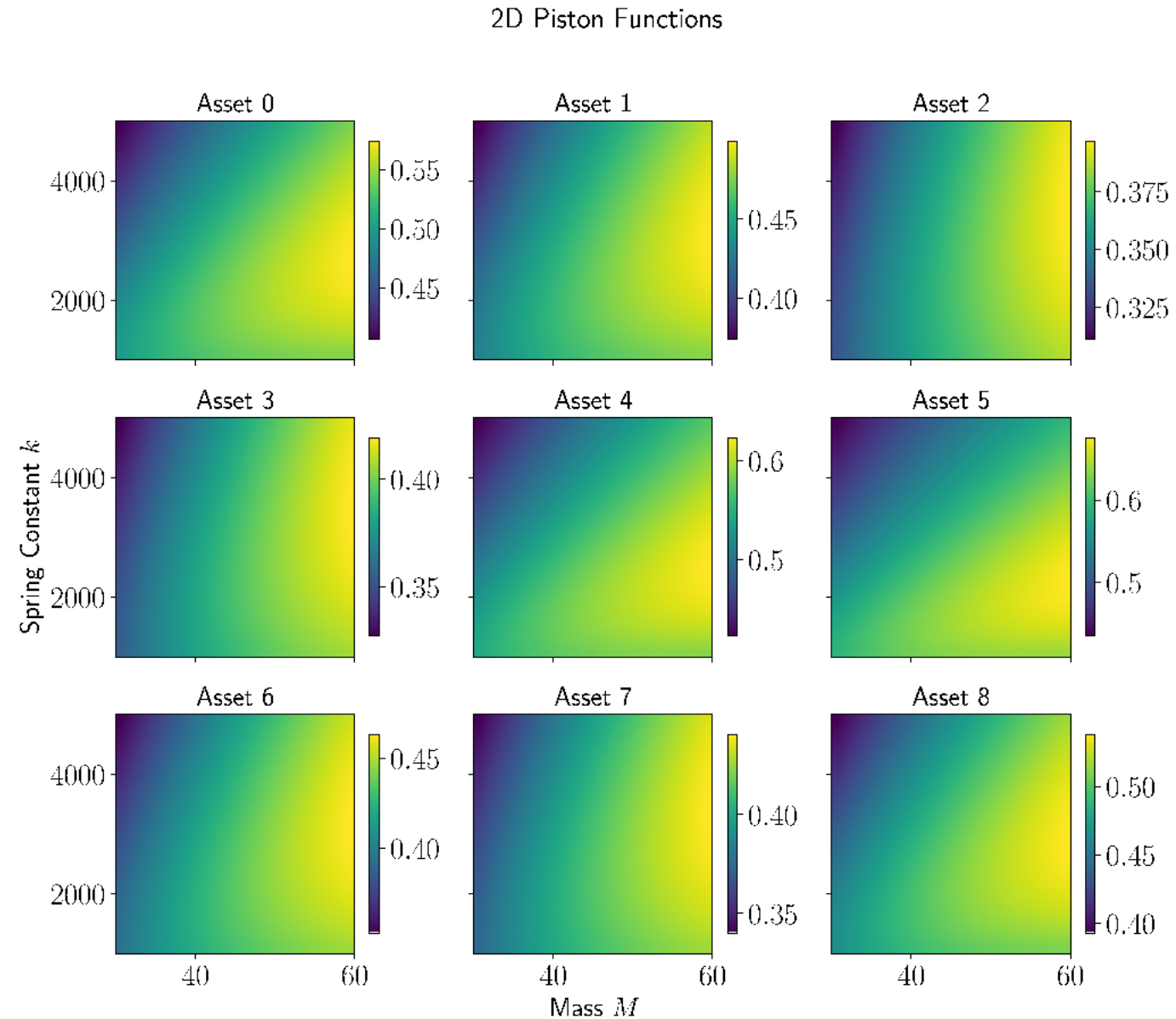
Input variables \mathbf{x}

Latent variables

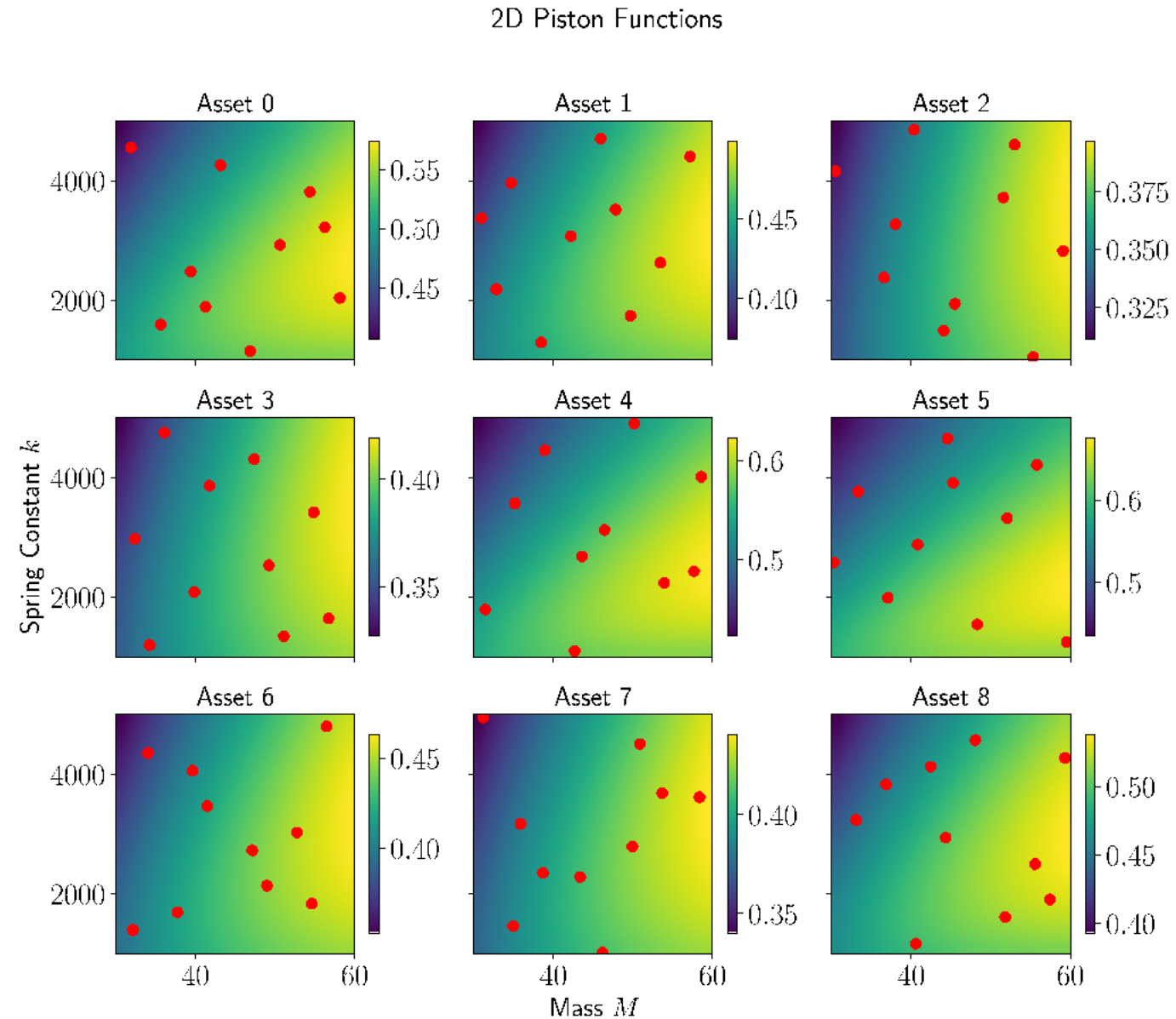
$M \in [30, 60]$	piston weight (kg)
$S \in [0.005, 0.020]$	piston surface area (m ²)
$V_0 \in [0.002, 0.010]$	initial gas volume (m ³)
$k \in [1000, 5000]$	spring coefficient (N/m)
$P_0 \in [90000, 110000]$	atmospheric pressure (N/m ²)
$T_a \in [290, 296]$	ambient temperature (K)
$T_0 \in [340, 360]$	filling gas temperature (K)

Benchmark problem for surrogate modeling:

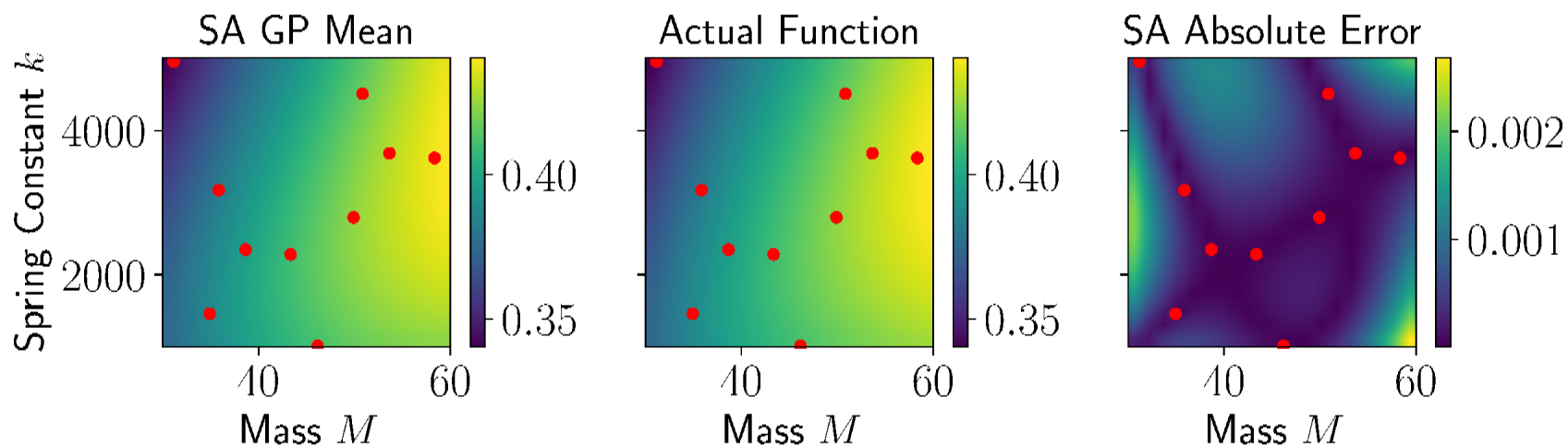
PISTON EXAMPLE: RESPONSE SURFACES



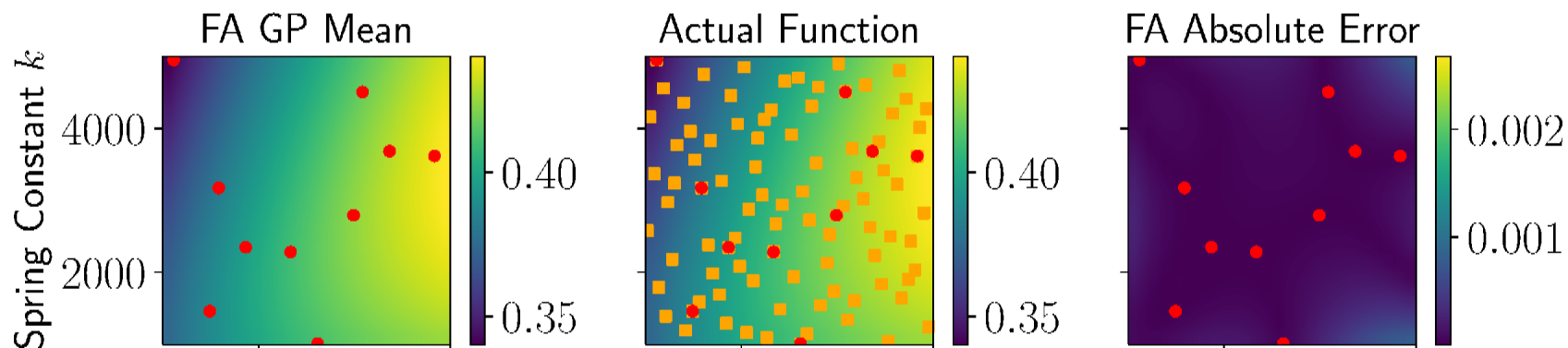
PISTON EXAMPLE: TRAINING DATA



PISTON EXAMPLE: ERROR FOR SINGLE ASSET

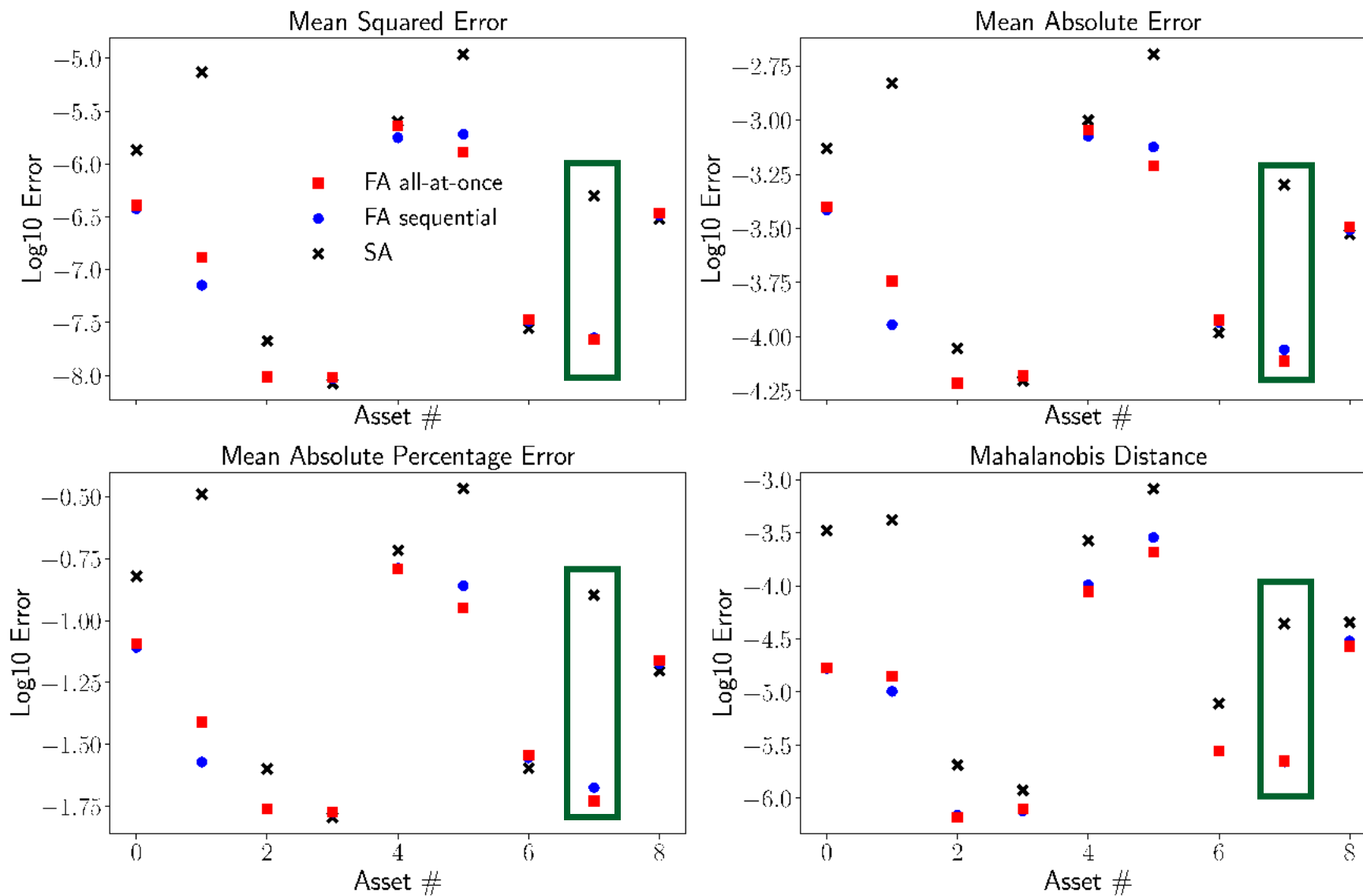


2D Digital Twin Gaussian Process Results for Asset 7



PISTON EXAMPLE: ERROR FOR ALL ASSETS

2D Piston Fleet of Assets Error Metrics

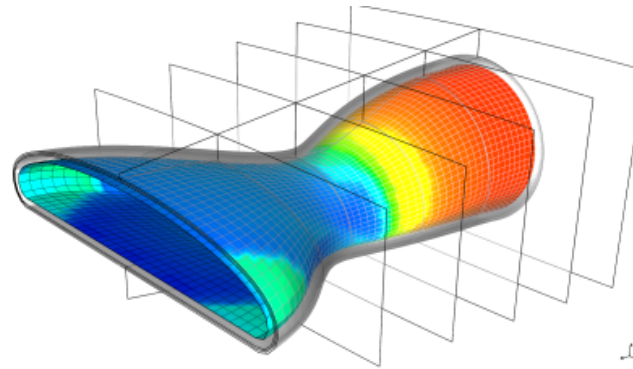


CONNECTING TWINS VIA PARAMETERS

Collect data for
each asset

Formulate
model for each
asset

$$g_0(x; \theta_1, \theta_2)$$

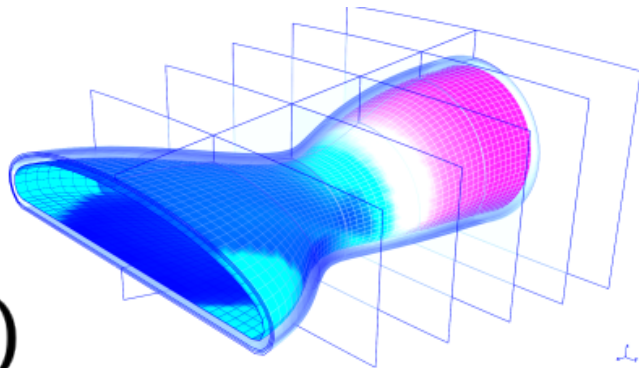


(X_0, y_0)

Asset

0

(X_1, y_1)

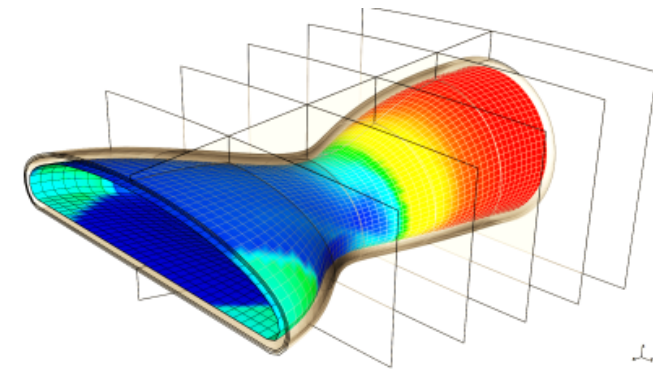


Asset

1

$$g_1(x; \theta_1)$$

(X_2, y_2)



Asset

2

$$g_2(x; \theta_2)$$

LATENT VARIABLE-BASED ASSET CLASS LEARNING

Assume variables are related by latent variables θ

$$\theta_G = [\theta_0, \theta_{\sim 0}^\top]^\top \quad \theta_0 = A\theta_{\sim 0} + b + v$$

Using hierarchical priors posterior is given by

$$p(\theta_G, A, b \mid y) \propto p(y \mid \theta_G, A, b) p(\theta_G, A, b) \\ = p(y \mid \theta_G) p(\theta_{\sim 0}) p(A) p(b)$$

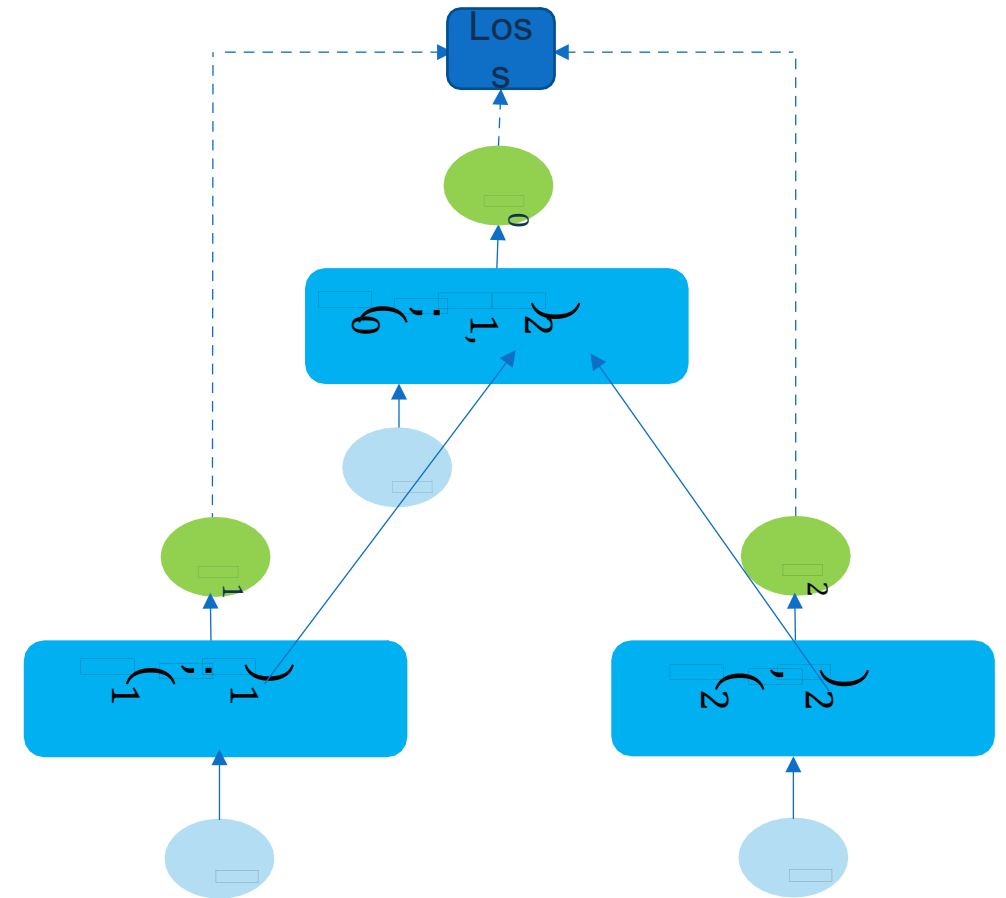
Log likelihood is

$$\log p(y \mid \theta_G) = \log p(y_0 \mid \theta_G) + \sum_{k=1}^K \log p(y_k \mid \theta_k)$$

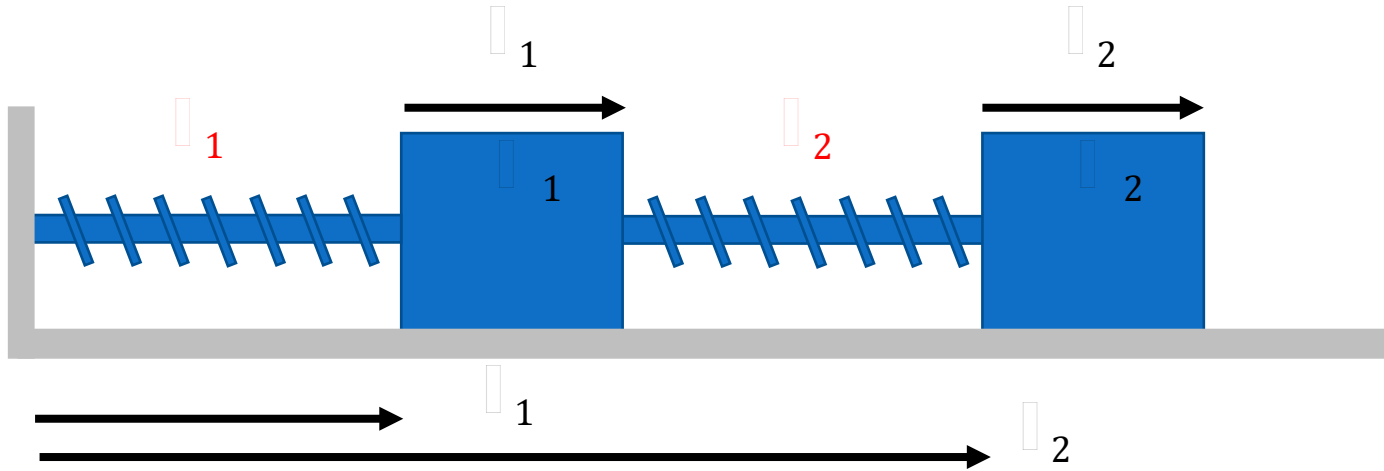
For asset of interest $k = 0$

$$\log p(y_0 \mid X_G, \theta_G) = -\frac{N_0}{2} \log \pi - N_0 \log |\Sigma_{\epsilon_0 v}| - \frac{1}{2} (y_0 - g_0(X_0; \gamma_G))^\top \Sigma_{\epsilon_0 v}^{-1} (y_0 - g_0(X_0; \gamma_G))$$

$$\Sigma_{\epsilon_0 v} = \Sigma_{\epsilon_0} + \Phi \Sigma_v \Phi^\top \quad \text{Assuming linear model } g_0 = \Phi(X) \theta_0$$



SPRING SYSTEM EXAMPLE

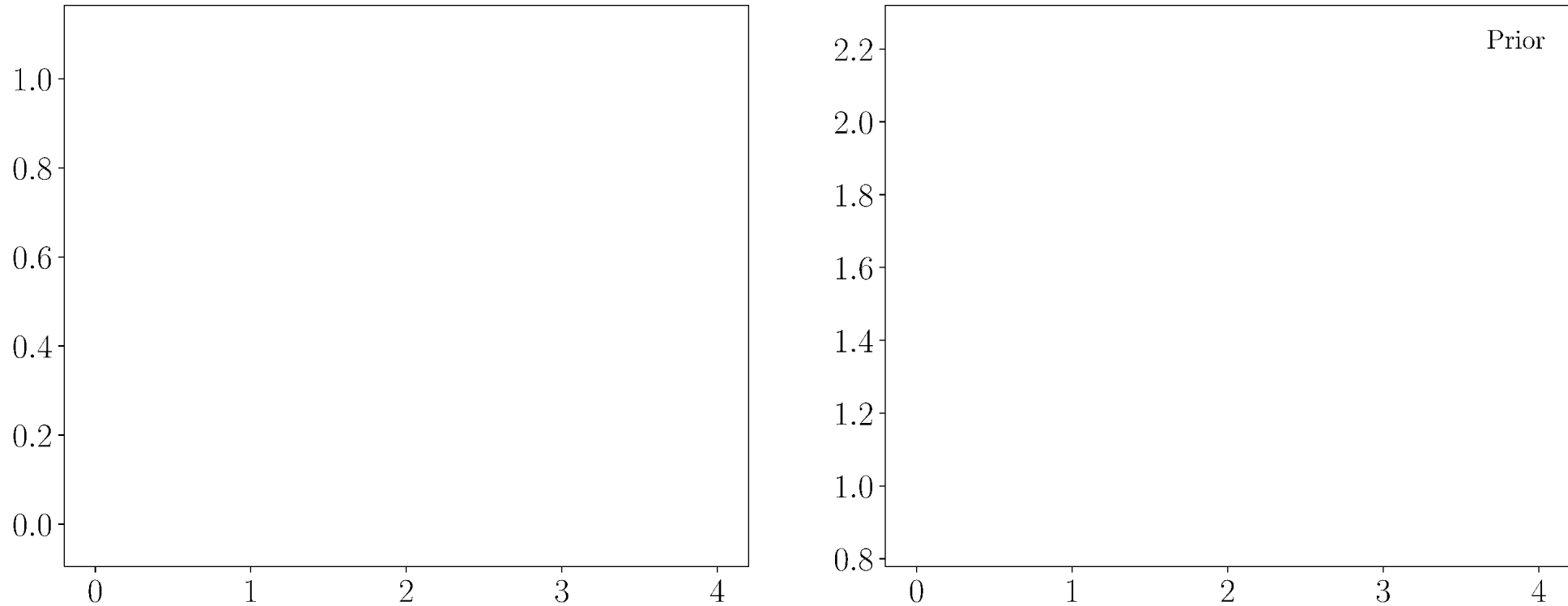


$$\begin{aligned} m_1 x_1'' + b_1 x_1' + k_1(x_1 - L_1) - k_2(x_2 - x_1 - L_2) &= 0 \\ m_2 x_2'' + b_2 x_2' + k_2(x_2 - x_1 - L_2) &= 0 \end{aligned}$$

Assume spring coefficient has deteriorated differently for each asset

ASSIGN A PRIOR ENCODING PRIOR KNOWLEDGE

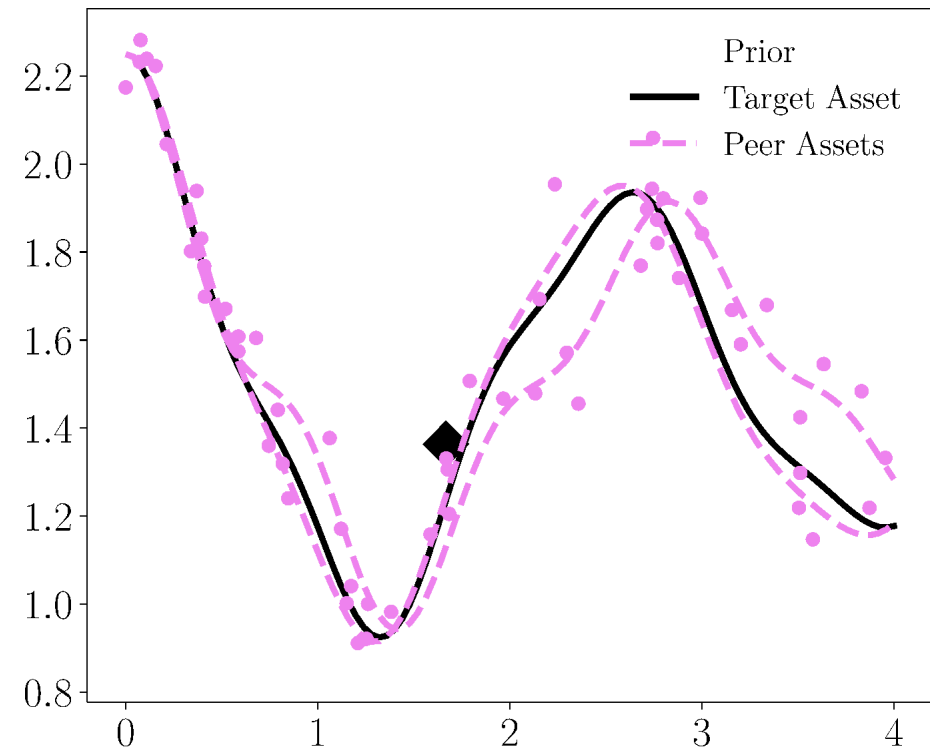
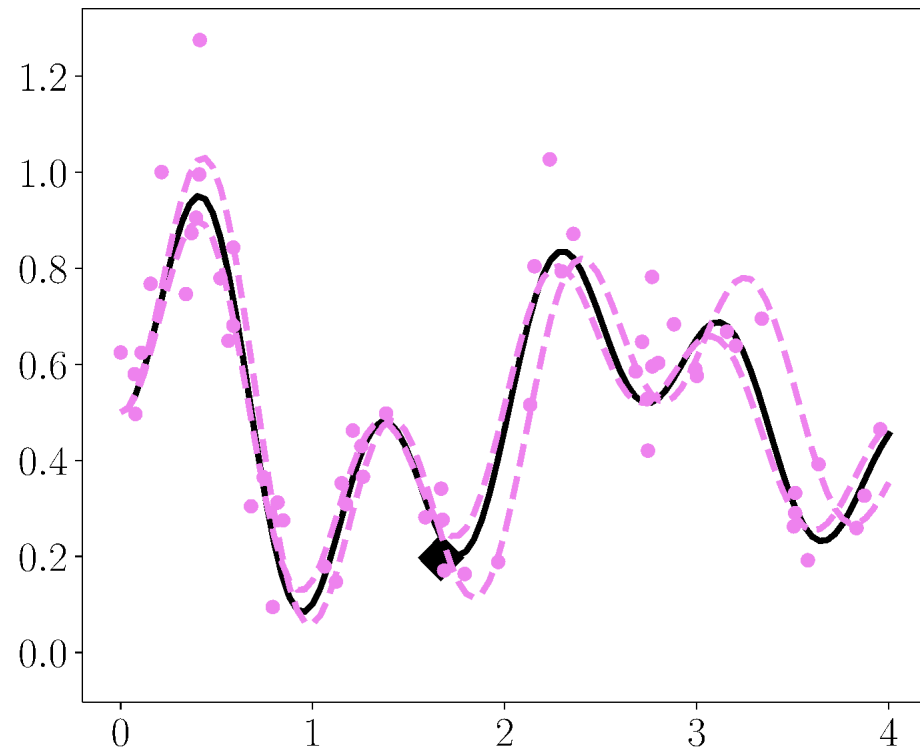
$$\begin{aligned} p(\theta_{\sim 0}) &\sim N(\mu_{\sim 0}, \Sigma_{\sim 0}) \\ A &= \text{diag}(a), \quad p(a) \sim N(1/K, \Sigma_a) \\ p(b) &\sim N(0, \Sigma_b) \end{aligned}$$



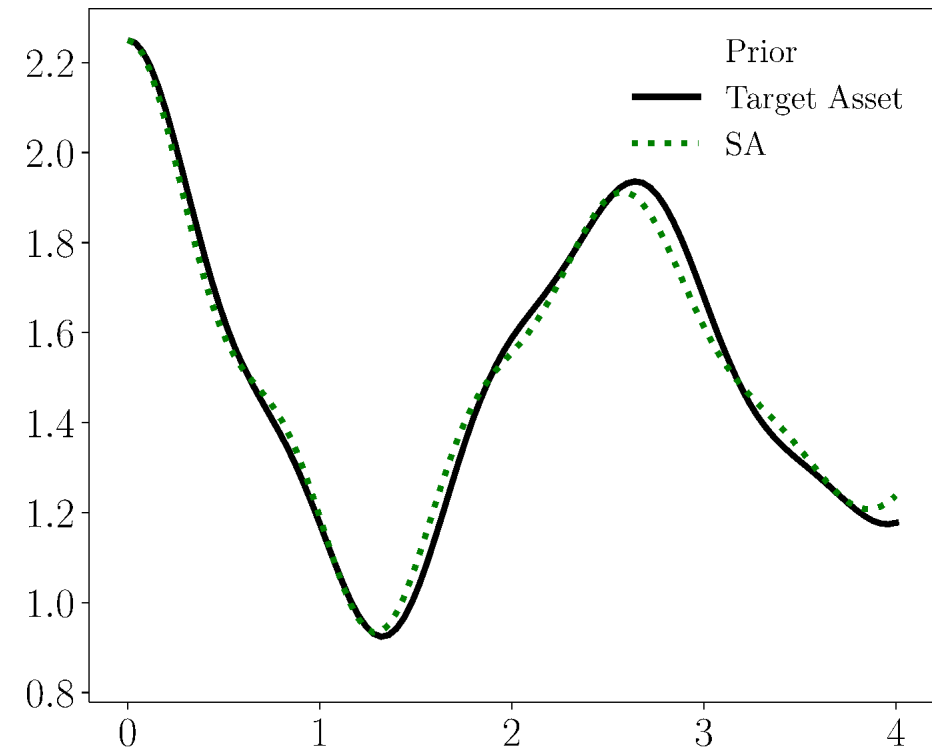
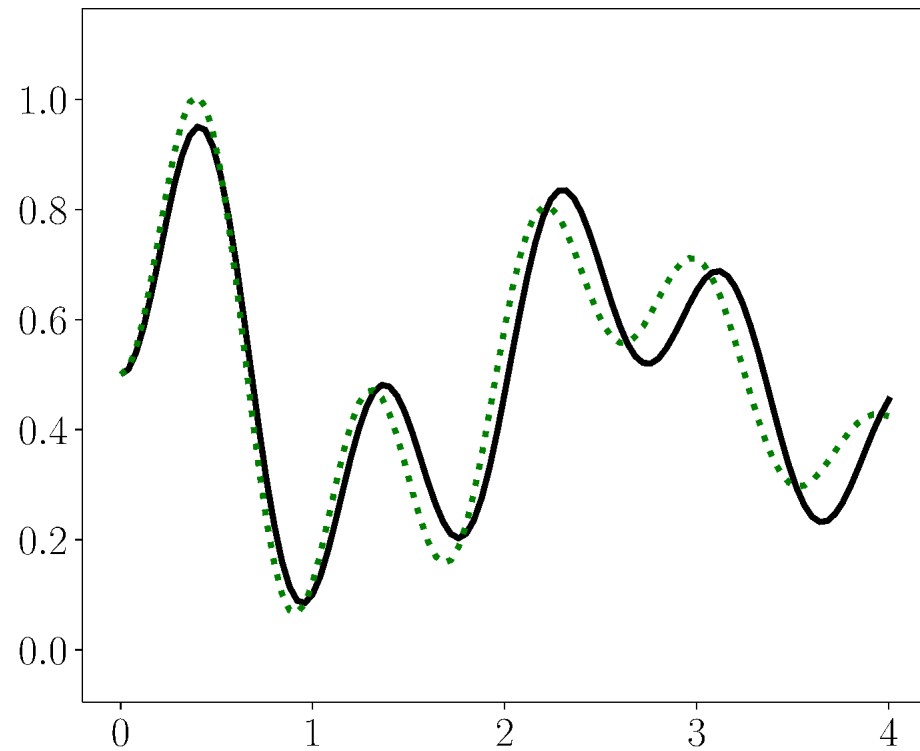
Prior predictive for target asset

COLLECT DATA FROM ALL ASSETS IN THE FLEET

Using all assets we have a rich data set



USING ONLY DATA FROM A SINGLE ASSET PRODUCES A POOR DIGITAL TWIN



USING DATA FROM THE FLEET IMPROVES PERFORMANCE OF A SINGLE TWIN DRAMATICALLY

