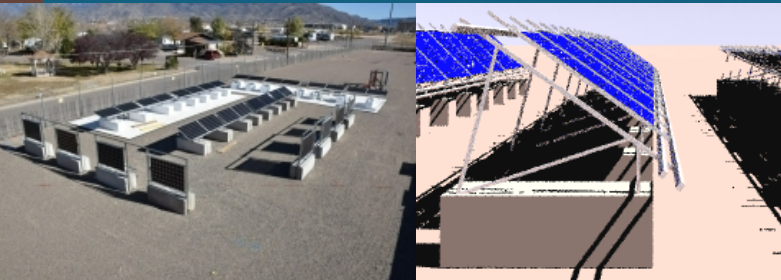




Approaches to Sky Image Based Single Axis Tracker Algorithms



PRESENTED BY

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Single axis tracking in varied weather conditions



- ❖ Most SAT algorithms (such as pvlib's) **only follow the Sun**
- ❖ This is optimal when there are **no clouds**
- ❖ Cloud covering the Sun = less direct, more diffuse
 - ❖ When it's very cloudy, **move trackers towards the horizontal to maximize**

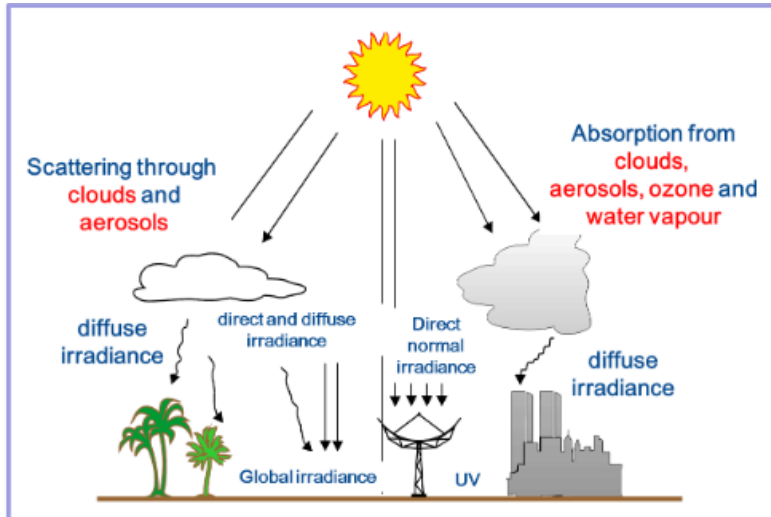
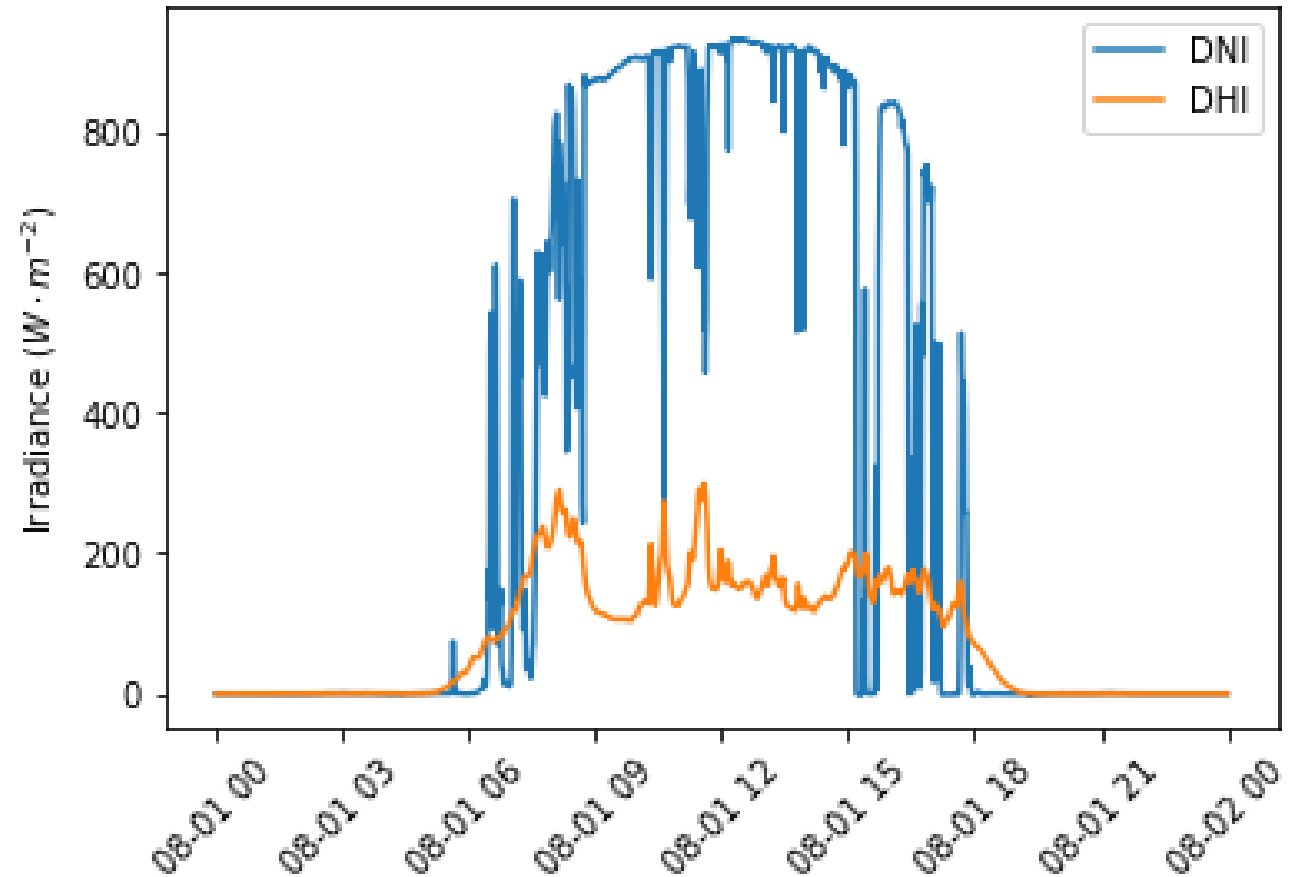


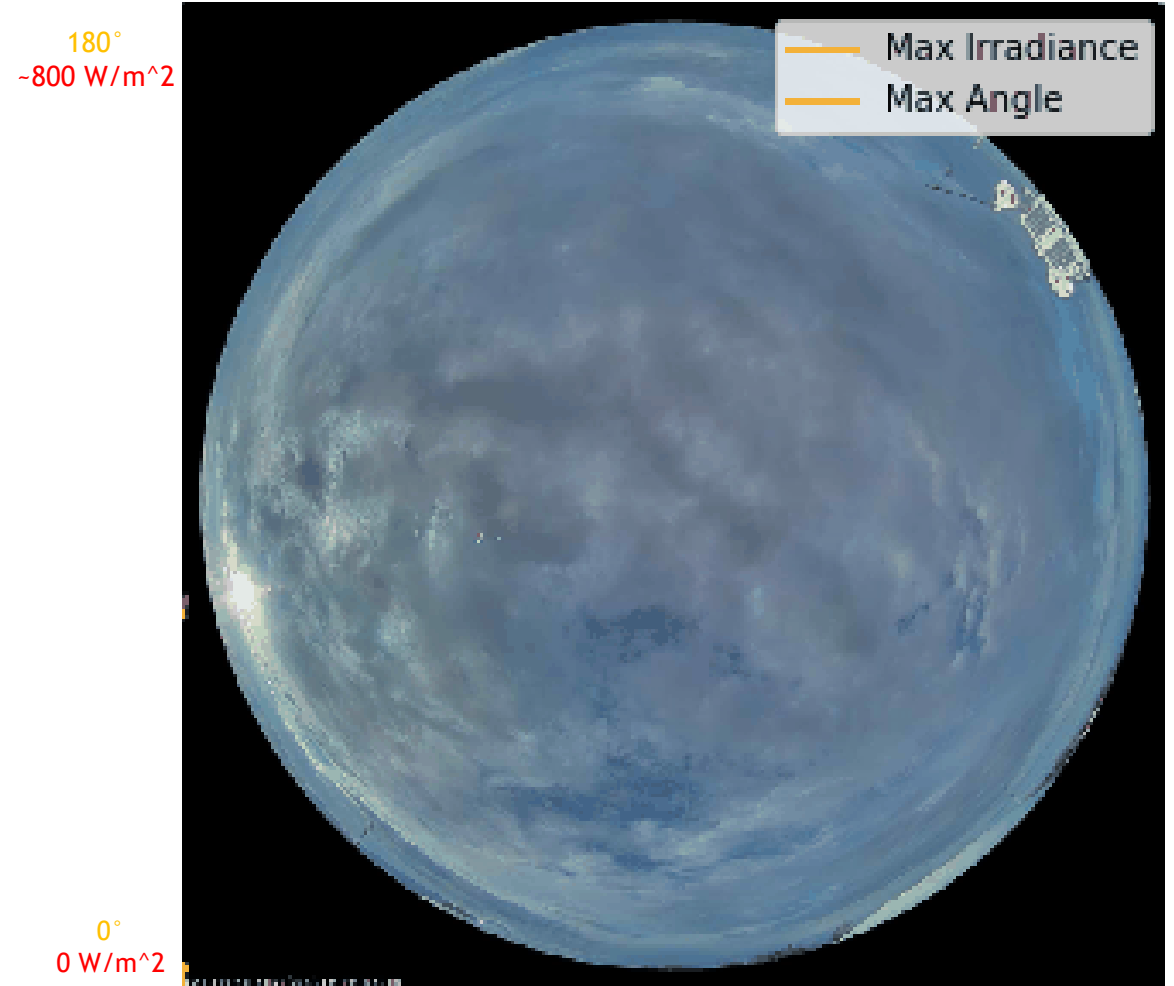
Figure: Copernicus Atmosphere Monitoring Service



Relationship between angles, irradiance, and weather



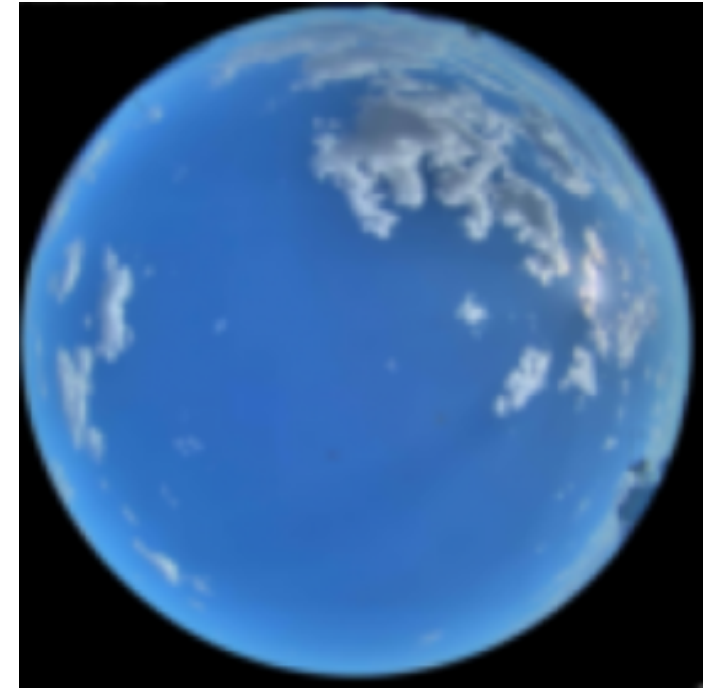
- ❖ Orange line: Normalized angle of max irradiance
- ❖ Red line: Normalized irradiance at max angle
- ❖ “Spiky” signal- angle of max irradiance would not be a good tracking strategy
- ❖ Short-term effects often not modeled due to coarser aggregations, but are impactful



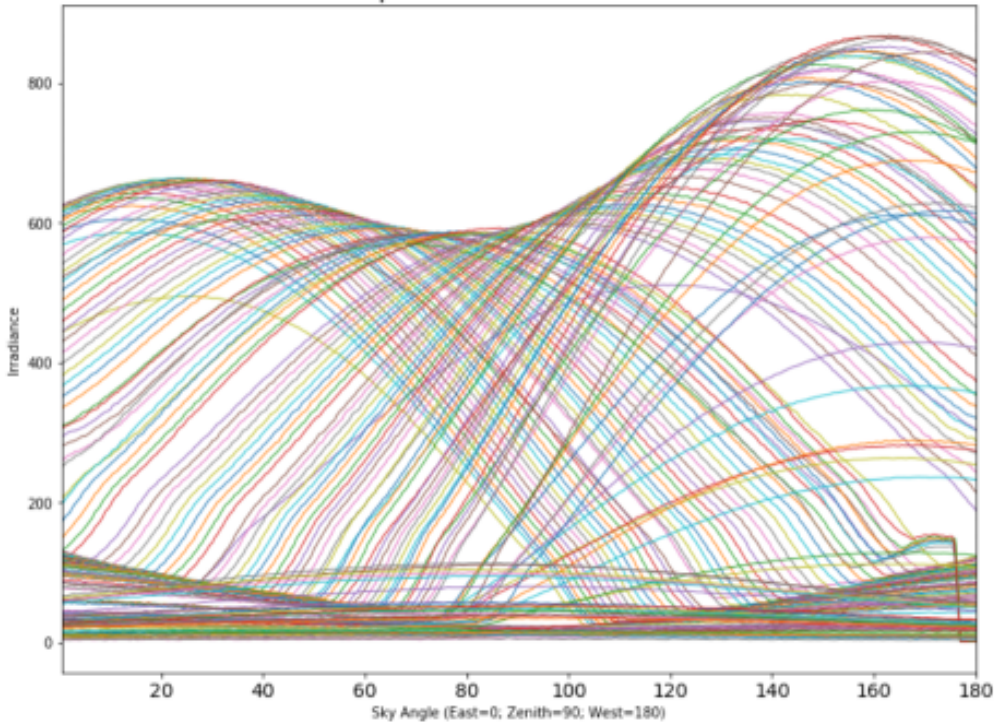
Data collection and sensors

- ❖ Sky images collected in real time
- ❖ Validation data is collected with a Multi Planar Irradiance Sensor (MPIS)
 - ❖ Irrad. sensor rotating on same axis as tracker

❖ Physical MiniSATe testbench



Sample MPIS Irradiance Profiles



Multiple possible approaches



- ❖ We plan to implement and test three different types of algorithms
 - ❖ Cloud coverage heuristic
 - ❖ Past- n regression
 - ❖ Deep Reinforcement Learning

- ❖ Each approach uses a neural network of some type to do:
 - ❖ Cloud segmentation
 - ❖ Prediction of angle of *maximal irradiance*
 - ❖ Prediction of optimal *movement strategy*

These are different, due to tracker movement costs, wear and tears, etc

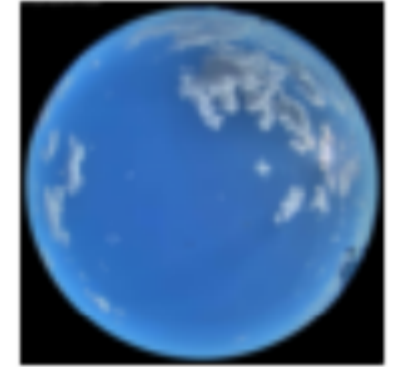
- ❖ Each has different drawbacks, such as
 - ❖ Manual input & bias for movement strategy
 - ❖ Reliant on accurate angle predictions
 - ❖ Difficult to train & generalize

These two are also less explainable due to lack of explicit decision tree

Cloud Coverage Heuristic

- ❖ Concept:
 - ❖ If extended cloud cover: **Move towards the horizontal by some amount**
 - ❖ Else, **follow the Sun**
 - ❖ Further conditions based on **system knowledge**
- ❖ Many methods of calculating cloud coverage in literature
 - ❖ Your sky camera probably has one already
 - ❖ I presented a **neural network** based model at PVSC
- ❖ Has additional parameters:
 - ❖ **% coverage** to be considered cloudy
 - ❖ **Number of previous timesteps** to consider
- ❖ Simulations find this algorithm to be a **~0.06-0.08% gain in ABQ, NM**
 - ❖ Grid search over parameter space yields highly reactive tracker
- ❖ Advantages: Simple, configurable
- ❖ Disadvantages: Site specific heuristics/parameters

Original

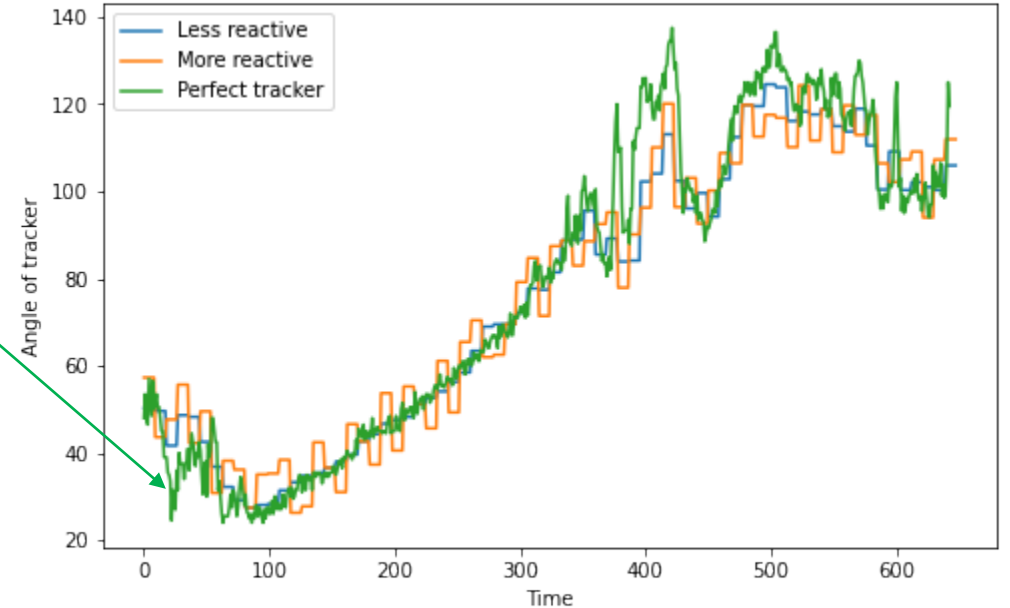
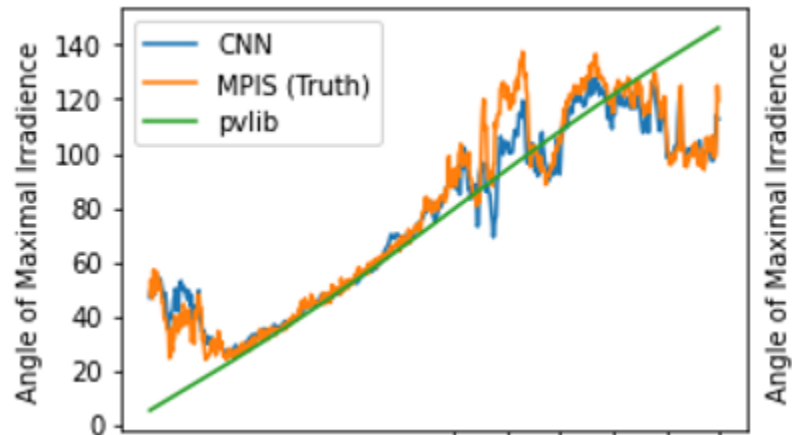


CAE prediction

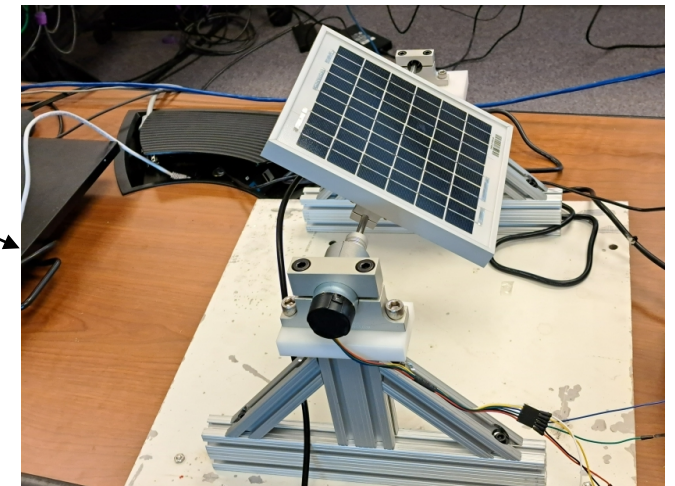


Past- n regression for tracker motion

- Use past n minutes of angles of **maximal irradiance**
- Move by **some threshold r** in direction of slope
- Update tracker **every k minutes**
- Advantages: explainable, adjustable
- Disadvantages: requires specialized device (eg MPIS) to find angle of max irradiance
 - Prototype sensor for wide deployment
 - Convolutional neural network (CNN)



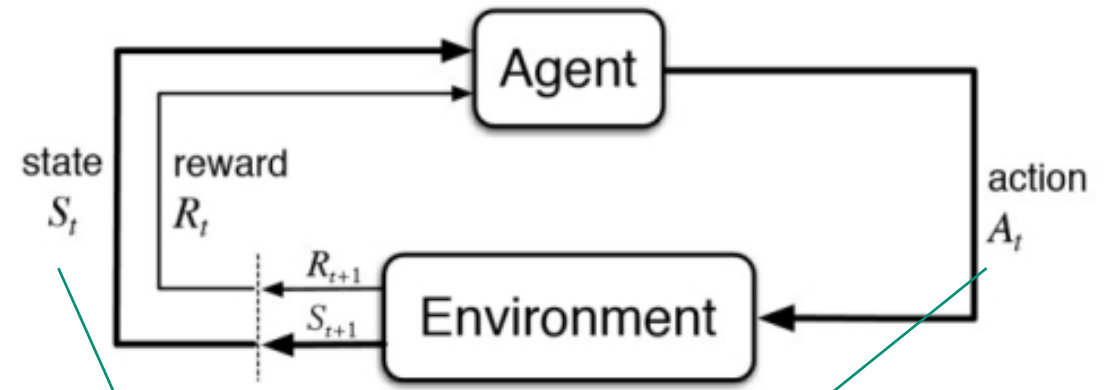
Algorithm can be adjusted by changing n , r , k to desired specificity



Deep Q Learning for tracker motion



- Use Deep Q Learning, a type of reinforcement learning (RL) to predict **optimal movement strategy**
- Agent receives **rewards** (eg irradiance received) and **learns** based on expected future reward.
 - “What move will result in the maximal power received at the end of the day?”
- Approximate decision lookup table (function) with ANN
- Advantages: data-driven, adaptable
- Disadvantages: “black box”, computationally intensive to train



actions

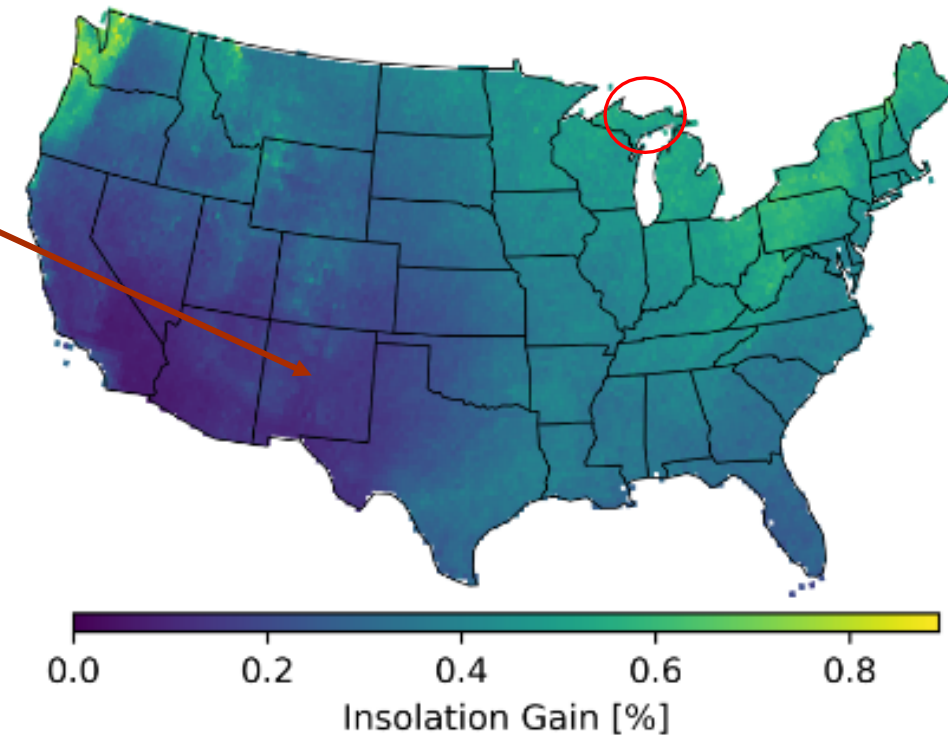
states	a_0	a_1	a_2	...
s_0	$Q(s_0, a_0)$	$Q(s_0, a_1)$	$Q(s_0, a_2)$...
s_1	$Q(s_1, a_0)$	$Q(s_1, a_1)$	$Q(s_1, a_2)$...
s_2	$Q(s_2, a_0)$	$Q(s_2, a_1)$	$Q(s_2, a_2)$...
⋮	⋮	⋮	⋮	⋮

Sky image

Expected movement reward

Current Results & Next Steps

- ❖ Problem: **ABQ, NM is too good for PV!**
 - ❖ Extended periods of cloudiness are **rare** for much of the year
 - ❖ High overall irradiance dominated by direct component
- ❖ So, models behave “unrealistically” in most cases
 - ❖ Cloud coverage is **too reactive** (teleportation)
 - ❖ Past- n regression **oscillates**
 - ❖ RL **doesn't move at all** (risk vs reward!)
- ❖ **Other conditions** must be considered
 - ❖ Snow shedding
 - ❖ Wind
 - ❖ Terrain
- ❖ Next step: **Install MPIS & Sky Camera at Michigan Tech RTU**



Anderson & Aneja PVSC 2022



Questions?



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