



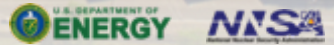
# Kokkos Resilience



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# Hardware Heterogeneity, Resilience, and the Exascale Era



- Recent years have shown a drive towards increased hardware heterogeneity in computing clusters
  - Computational heterogeneity (many-core, GPUs, other accelerators)
  - I/O heterogeneity (deep memory hierarchies, local persistent storage, external parallel file systems, key-value stores, etc)
- Mean time between failure (MTBF) is decreasing (errors occur more often!) as systems become more complex
- How can software leverage the diversity of hardware in both computation and I/O while remaining resilient and performant?

# Performance Portability and Resilience



- *Performance portability* is a property of software where the software can be written once and re-used without performance degradation on heterogeneous hardware
  - Usually enabled by a programming model or library
  - Libraries include *Kokkos*, *RAJA*, *DPC++*, and others
- Main resilience strategy for a lot of hardware is checkpoint/restart
  - Can we exploit the ubiquity of programming models such as *Kokkos* to provide resilience for Exascale applications?



- We introduce *Kokkos-Resilience*, an extension of *Kokkos* for adding resilience to performance-portable applications
  - Allow user to define checkpoint regions for resilient code where `Kokkos::Views` are captured
  - Introduces Resilient Execution spaces for detecting and rectifying soft errors
  - Interoperates with data checkpointing frameworks such as *VELOC* and process-level recovery frameworks
- <https://github.com/kokkos/kokkos-resilience>

# Kokkos Background



- Programming model for performance portable C++
- <https://github.com/kokkos/kokkos>
- Data abstraction: `Kokkos::View<>`
- Execution abstraction: `Kokkos::parallel_for()`, `Kokkos::parallel_reduce()`, `Kokkos::parallel_scan()`
- Common use patterns:
  - View creation at program initialization
  - Iterations reading and writing to Views via parallel dispatch

```
1  auto view = Kokkos::View< double ** >( /* ... */ );
2
3  for ( int iter = 0; iter < max_iter; ++iter ) {
4      Kokkos::parallel_for( /* ... */, KOKKOS_LAMBDA( int i ) {
5          do_calculation( view );
6          // More operations on view...
7      } );
8  }
```

- How would an application author typically add checkpoint/restart?
  - Usually would want to checkpoint view every few iterations
  - Would need to write I/O code and check for restart
  - Custom logic for restart to ensure restart correctness



```
1  auto view = KR::View< double ** >( /* ... */ );
2
3  for ( int iter = 0; iter < max_iter; ++iter ) {
4      KR::checkpoint(plugin, "test_checkpoint", iter, [=]() {
5          Kokkos::parallel_for( /* ... */, KOKKOS_LAMBDA( int i ) {
6              do_calculation( view );
7              // More operations on view...
8          } );
9      } );
10 }
```

- Define a scope in which any operations on Kokkos views are made resilient
- Resilience is enabled by checkpoint/restart
- Can include multiple parallel dispatch operations
- Implicit checkpointing of views used inside of the scope
- Checkpoint regions can be defined by lambdas (preferred) but any functor will do

## Resilient Abstractions - Scoped Resilient Execution Contexts

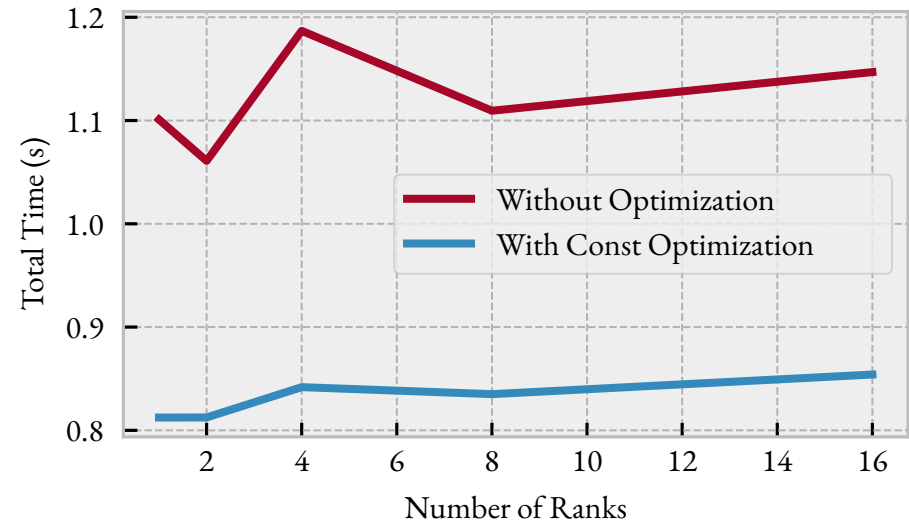


- Automatic recovery
  - Check if restart conditions are met (existence of a checkpoint, restart flag, etc.)
  - The lambda *is not* executed
  - Stored checkpoints written to the captured views
  - Execution proceeds *as if* the lambda was executed
- Before someone asks – this does mean the lambdas generally should be *pure* and avoid writing to global entities (output should be done by writing to views)





```
1 KR::View< double * > ping( /*...*/ ), pong( /*...*/ );
2 for ( int i = 0; i < max_ts; ++i ) {
3     KR::View< const double * > read;
4     KR::View< double * > write;
5     if ( i % 2 )
6         read = pong; write = ping;
7     else
8         read = ping; write = pong;
9     KokkosResilience::checkpoint( ctx, "iterate", i, [=]() {
10         Kokkos::parallel_for( /*...*/, KOKKOS_LAMBDA( int j ) {
11             write( j ) = do_calculation( read );
12         } );
13     } );
14 }
```

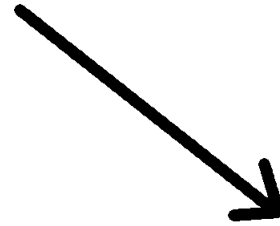


*Figure: Weak scaling of the ping-pong microbenchmark.*

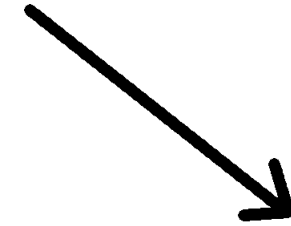
- More complex applications or poorly served by naively checkpoint every view
- The example above shows a simple ping-pong buffer sample where the read and write views alternate



- Deduplication:
  - Hash views by label (to account for user intent in case a view is reallocated)
  - Provide functions to declare *aliases* in the rare circumstance that the same view has a different label
- Read-only views:
  - Views that are declared as **const** can only be read from
  - We can use this type information to avoid checkpointing these views
  - Similar techniques can be applied to views that are “transient”, i.e. are only used as scratch space inside an iteration (needs manual tagging)



Segmentation fault  
(core dumped)



$1+1 = 3$

- Fail-stop errors are easy to detect, the program crashes
- How can we detect fail-continue (soft) errors with Kokkos Resilience?
- Example errors: lock semantics, encryption/decryption, database index corruption, and more



```
1  auto view = Kokkos::View< double **, KR::ResHostSpace >( /* ... */ );
2  auto range_policy = Kokkos::RangePolicy< KR::ResOpenMP >( /* ... */ );
3
4  for ( int iter = 0; iter < max_iter; ++iter ) {
5      Kokkos::parallel_for( range_policy, KOKKOS_LAMBDA( int i ) {
6          do_calculation( view );
7          // More operations on view...
8      } );
9  }
```

- Views are replicated, and then the kernel is executed concurrently on the replicated views
- Double and Triple Modular Redundancy supported
- Voting step proceeds in parallel after triplicate execution completed



- We interop cleanly with non-resilient Kokkos code
- *Kokkos-Resilience* provides an abstraction layer for user applications for tracking execution regions that should be checkpointed or restarted
  - Actual checkpointing deferred to the resilience backend
    - *VELOC* – Multi-level asynchronous checkpoint/restart  
<https://github.com/ECP-VeloC/VELOC>
      - Used for low-overhead efficient asynchronous checkpointing
      - Designed specifically for high performance HPC machines
    - *stdfile* – Standard IO binary blob
      - Synchronous, Primarily used for testing purposes



- There are many aspects of recovery – data recovery, control-flow recovery, and process recovery
  - *Kokkos-Resilience* provides control flow recovery
  - Also uses, backends like *VELOC* for data recovery
  - Integrating this with process recovery is challenging particularly since we depend on MPI communicators when interfacing with MPI+Kokkos programs
    - We have done recent work on interoperability and integration with Fenix on top of ULFM for process recovery
    - Adapts to changes in the communicator, recovery status, failure states



**The framework is still experimental, we need your feedback to improve it.**

- We are working on adding more resilient execution spaces, checkpointing backends, and parallel constructs.
- There are also several collaboration efforts:

GaTech Supplement Kokkos resilience with a Clang-based tool and runtime checkpoint manager

- More robust compile-time information for the runtime manager

UTK Pattern aware checkpoints for improving checkpoint performance of Kokkos applications

UofU Data staging interface for `Kokkos::View`

# Kokkos Resilience



- We've introduced a new resilience capability to Kokkos applications: Kokkos Resilience
  - Automatic View checkpointing
  - Resilient execution spaces
  - Interopability with data level and process level recovery frameworks
- <https://github.com/kokkos/kokkos-resilience>
- Please feel free to contact us on the #resilience channel on the Kokkos Slack.



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