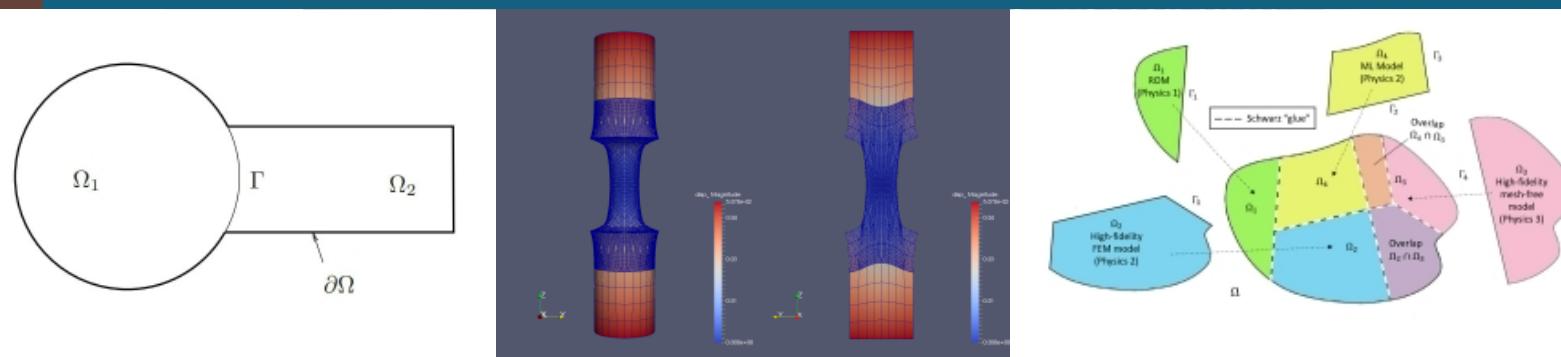




Sandia  
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Laboratories

# The Schwarz Alternating Method for ROM\*-FOM<sup>#</sup> and ROM-ROM Coupling



Irina Tezaur<sup>1</sup>, Alejandro Mota<sup>1</sup>, Yukiko Shimizu<sup>1</sup>, Joshua Barnett<sup>1,2</sup>

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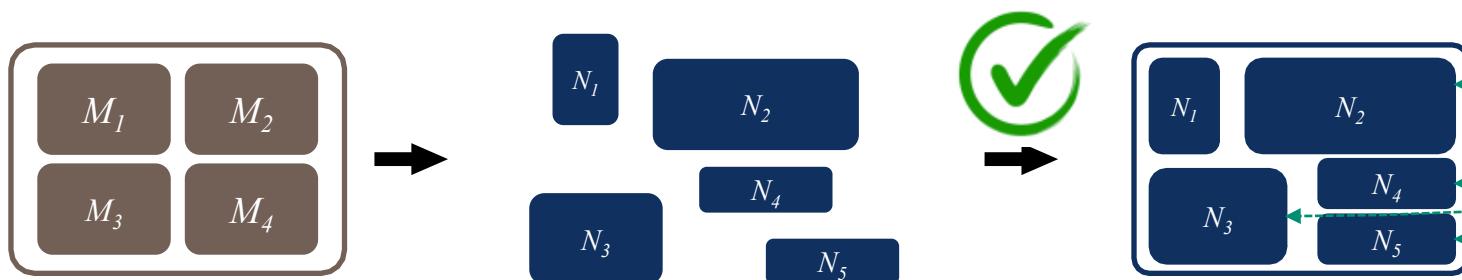
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# Motivation

The past decades have seen tremendous investment in **simulation frameworks for coupled multi-scale and multi-physics problems**.

- Frameworks rely on **established mathematical theories** to couple physics components.
- Most existing coupling frameworks are based on **traditional discretization methods**.



## Complex System Model

- PDEs, ODEs
- Nonlocal integral
- Classical DFT,
- Atomistic...

## Traditional Methods

- Mesh-based (FE, FV, FD),
- Meshless (SPH, MLS),
- Implicit, explicit,
- Eulerian, Lagrangian...

## Coupled Numerical Model

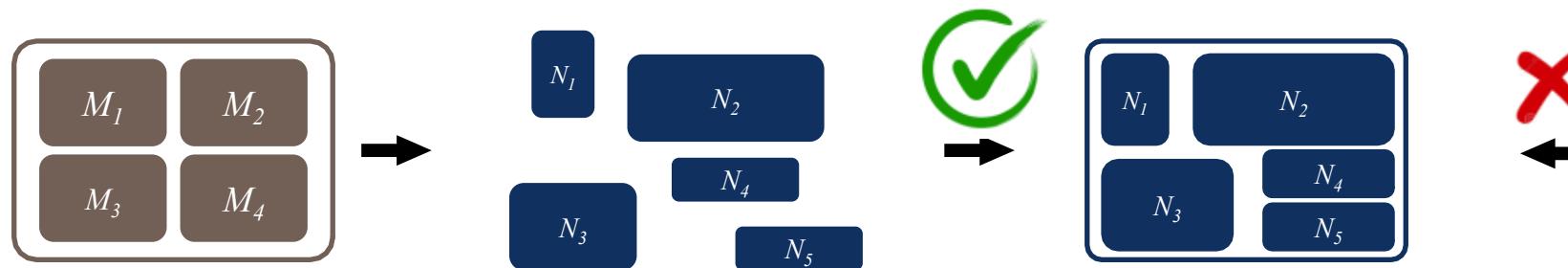
- Monolithic (Lagrange multipliers)
- Partitioned (loose) coupling
- Iterative (Schwarz, optimization)



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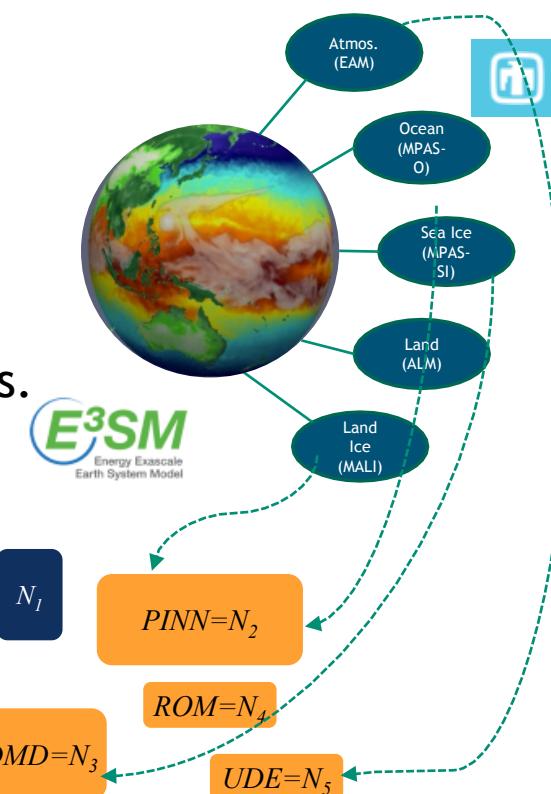
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## Traditional + Data-Driven Methods

- PINNs
- Neural ODEs
- Projection-based ROMs, ...

- There is currently a big push to integrate **data-driven methods** into modeling & simulation toolchains.

Unfortunately, existing algorithmic and software infrastructures are **ill-equipped** to handle plug-and-play integration of **non-traditional, data-driven models**!



# 4 | Flexible Heterogeneous Numerical Methods (fHNM) Project



## Principal research objective:

- Discover mathematical principles guiding the assembly of standard and data-driven numerical models into stable, accurate and physically consistent **flexible Heterogeneous Numerical Methods**

## Principal research challenges: we lack mathematical and algorithmic understanding of how to

- “Mix-and-match” standard and data-driven models from three-classes
  - *Class A*: projection-based reduced order models (ROMs) ***This talk***
  - *Class B*: machine-learned models, i.e., Physics-Informed Neural Networks (PINNs)
  - *Class C*: flow map approximation models, i.e., dynamic model decomposition (DMD) models
- Ensure **well-posedness & physical consistency** of the resulting **heterogeneous models**.
- **Solve** such heterogeneous models efficiently.

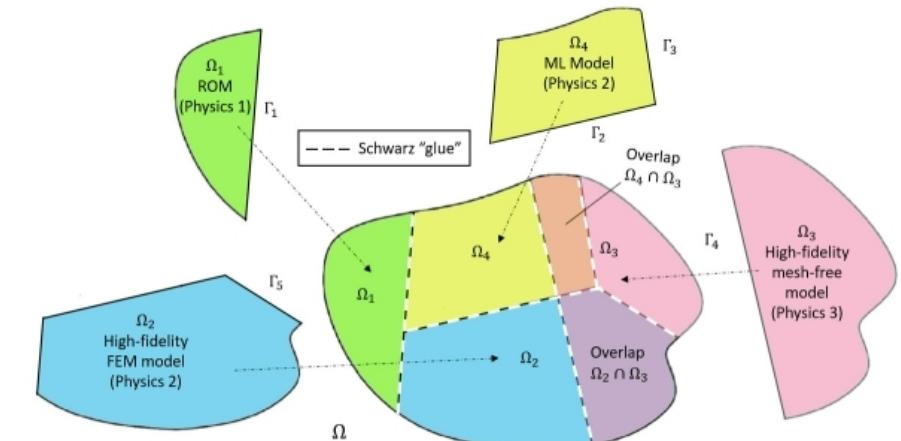
## Three coupling methods:

- Alternating Schwarz-based coupling ***This talk***

- Optimization-based coupling

- Generalized mortar methods

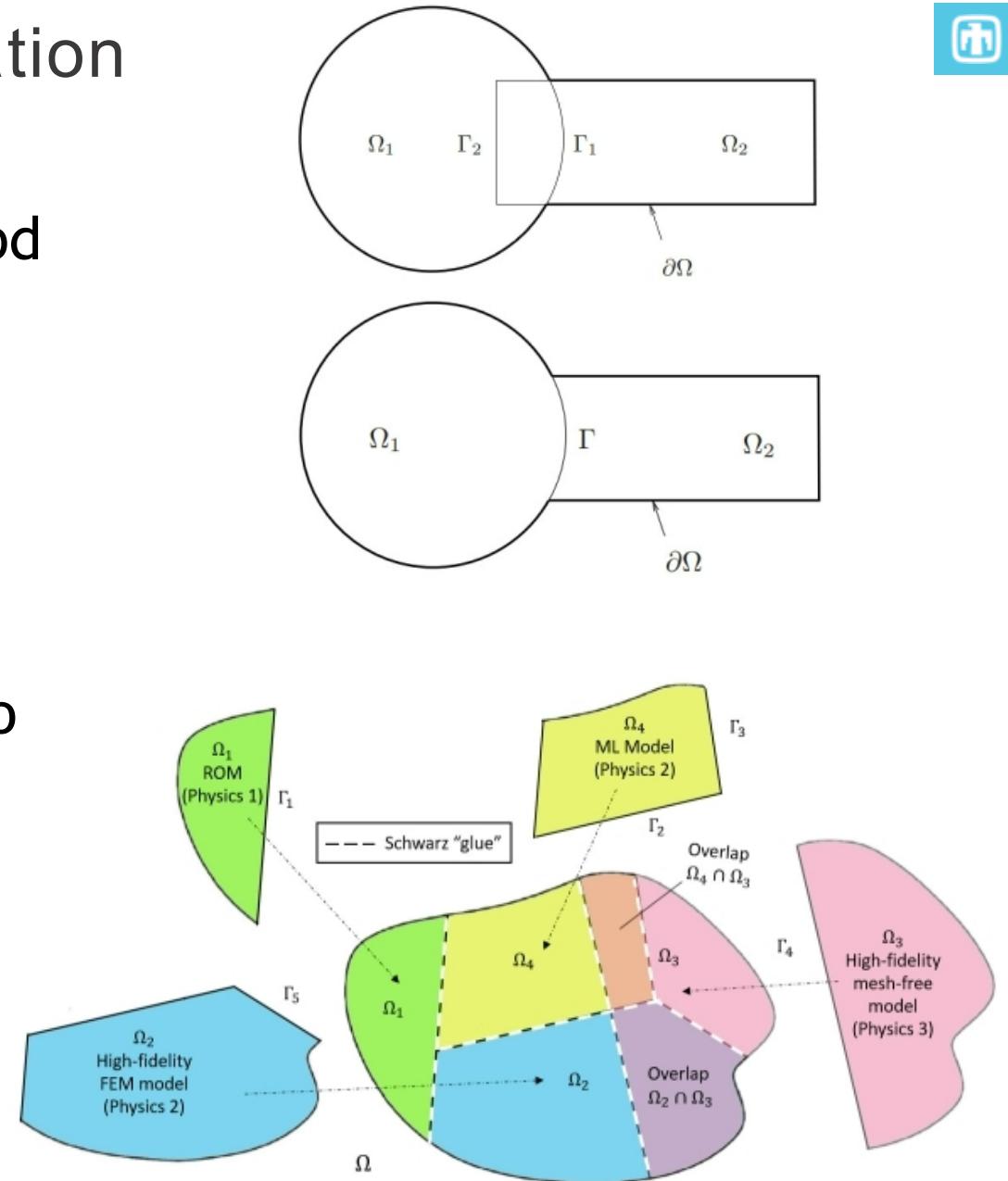
***Talk by A. DeCastro***



# Outline For Remainder of Presentation



1. Overview of the Schwarz Alternating Method for Concurrent Coupling
2. Overview of Projection-Based Model Order Reduction
3. Extension of Schwarz Alternating Method to ROM-FOM and ROM-ROM coupling
4. Numerical Results
5. Summary and Future Work



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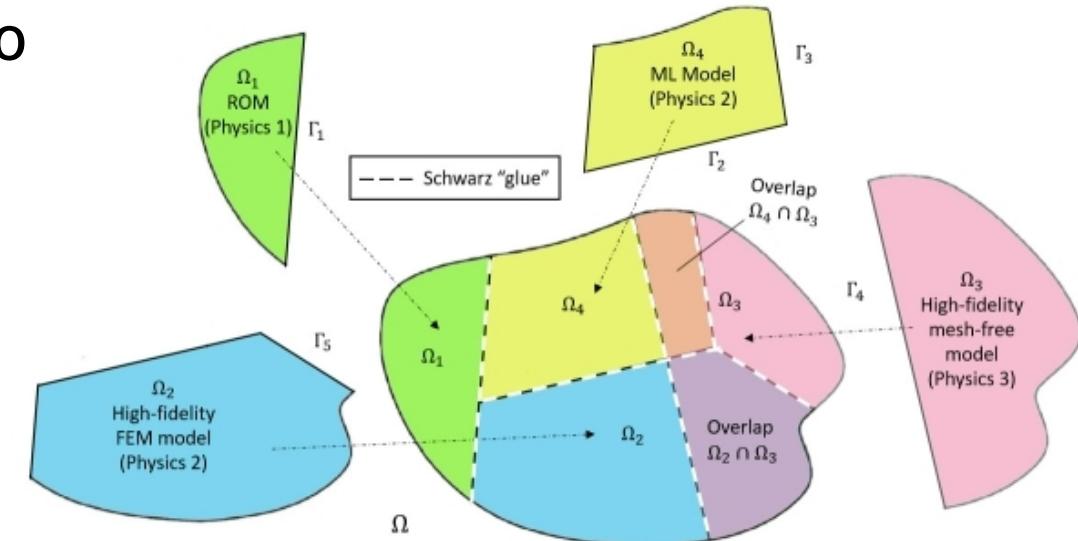
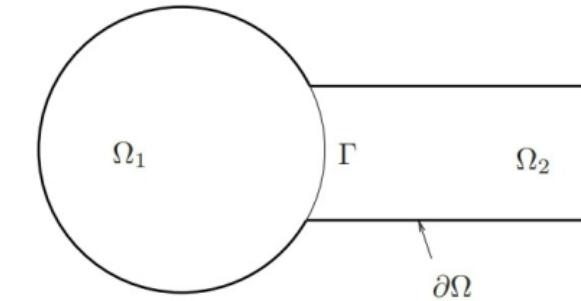
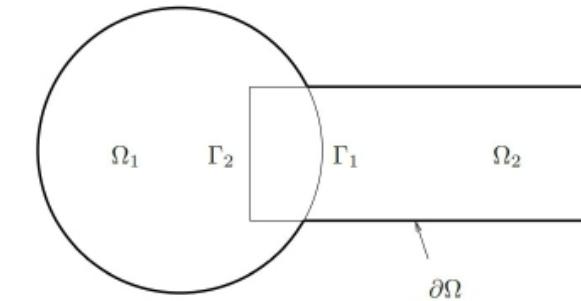
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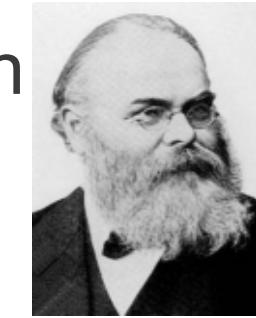


# Schwarz Alternating Method for Domain Decomposition



- Proposed in 1870 by H. Schwarz for solving Laplace PDE on irregular domains.

**Crux of Method:** if the solution is known in regularly shaped domains, use those as pieces to iteratively build a solution for the more complex domain.



H. Schwarz (1843-1921)

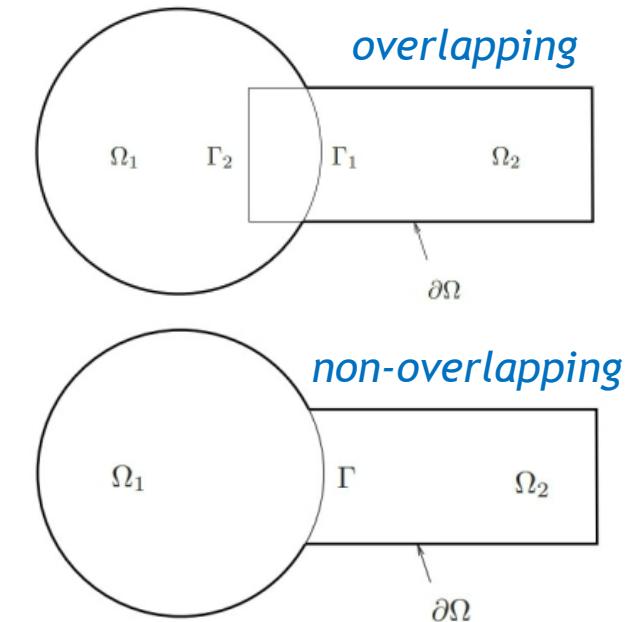
## Basic Schwarz Algorithm

### Initialize:

- Solve PDE by any method on  $\Omega_1$  w/ initial guess for transmission BCs on  $\Gamma_1$ .

### Iterate until convergence:

- Solve PDE by any method on  $\Omega_2$  w/ transmission BCs on  $\Gamma_2$  based on values just obtained for  $\Omega_1$ .
- Solve PDE by any method on  $\Omega_1$  w/ transmission BCs on  $\Gamma_1$  based on values just obtained for  $\Omega_2$ .



- Schwarz alternating method most commonly used as a *preconditioner* for Krylov iterative methods to solve linear algebraic equations.

**Novel idea:** using the Schwarz alternating as a *discretization method* for solving multi-scale or multi-physics partial differential equations (PDEs).

# How We Use the Schwarz Alternating Method



AS A ***PRECONDITIONER***  
FOR THE LINEARIZED  
SYSTEM



AS A ***SOLVER*** FOR THE  
COUPLED  
FULLY NONLINEAR  
PROBLEM

# 9 Spatial Coupling via Alternating Schwarz

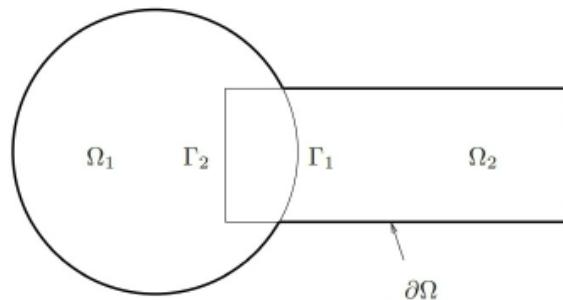


## Overlapping Domain Decomposition

$$\begin{cases} \mathcal{L}u_1^{n+1} = f, & \text{in } \Omega_1, \\ u_1^{n+1} = g, & \text{on } \partial\Omega_1 \setminus \Gamma_1, \\ u_1^{n+1} = u_2^n, & \text{on } \Gamma_1, \end{cases}$$

$$\begin{cases} \mathcal{L}u_2^{n+1} = f, & \text{in } \Omega_2, \\ u_2^{n+1} = g, & \text{on } \partial\Omega_2 \setminus \Gamma_2, \\ u_2^{n+1} = u_1^{n+1}, & \text{on } \Gamma_2. \end{cases}$$

**Model PDE:**  $\begin{cases} \mathcal{L}u = f, & \text{in } \Omega, \\ u = g, & \text{on } \partial\Omega. \end{cases}$



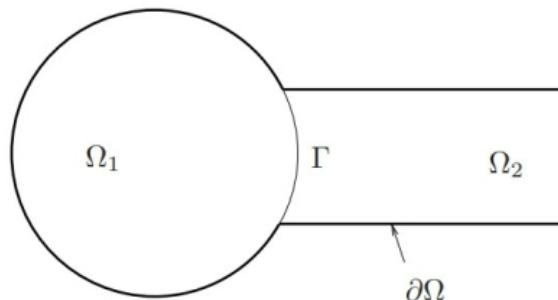
- Dirichlet-Dirichlet transmission BCs [Schwarz, 1870; Lions, 1988]

## Non-overlapping Domain Decomposition

$$\begin{cases} \mathcal{L}u_1^{n+1} = f, & \text{in } \Omega_1, \\ u_1^{n+1} = g, & \text{on } \partial\Omega_1 \setminus \Gamma, \\ u_1^{n+1} = \lambda_{n+1}, & \text{on } \Gamma, \end{cases}$$

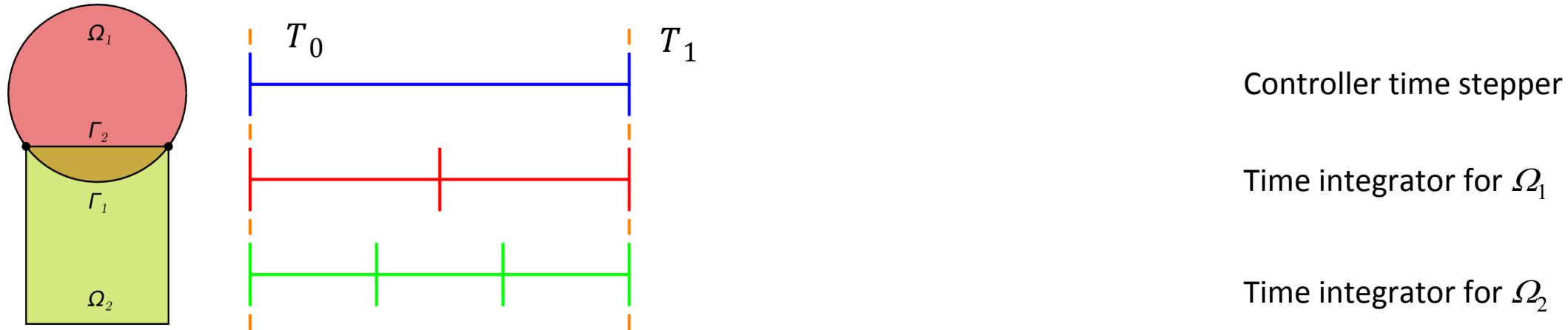
$$\begin{cases} \mathcal{L}u_2^{n+1} = f, & \text{in } \Omega_2, \\ u_2^{n+1} = g, & \text{on } \partial\Omega_2 \setminus \Gamma, \\ \frac{\partial u_2^{n+1}}{\partial \mathbf{n}_2} = \frac{\partial u_1^{n+1}}{\partial \mathbf{n}_2}, & \text{on } \Gamma, \end{cases}$$

$$\lambda_{n+1} = \theta u_2^n + (1 - \theta) \lambda_n, \quad \text{on } \Gamma, \quad \text{for } n \geq 1.$$



- Relevant for multi-material and multi-physics coupling
- Alternating Dirichlet-Neumann transmission BCs [Zanolli et al., 1987]
- Robin-Robin transmission BCs also lead to convergence [Lions, 1990]
- $\theta \in [0,1]$ : relaxation parameter (can help convergence)

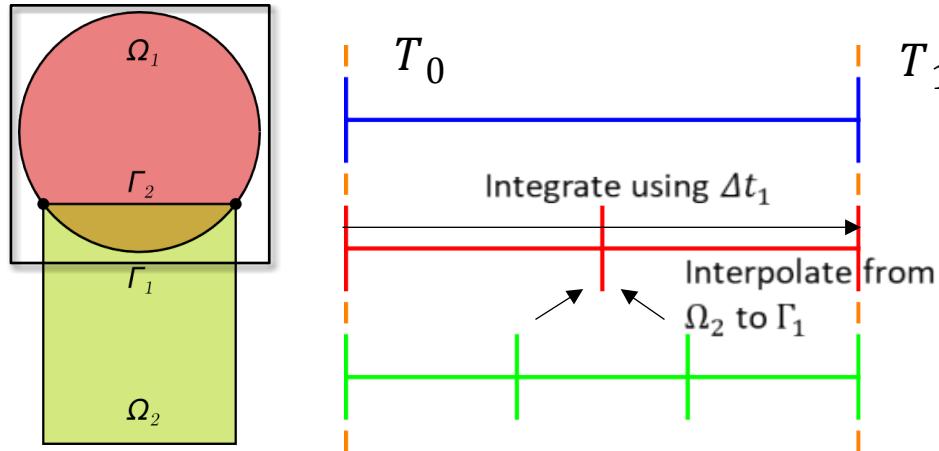
# Time-Advancement Within the Schwarz Framework



**Step 0:** Initialize  $i = 0$  (controller time index).

**Model PDE:** 
$$\begin{cases} \dot{u} = f - \mathcal{L}u, & \text{in } \Omega, \\ u(x, t) = g(t), & \text{on } \partial\Omega, \\ u(x, 0) = u_0, & \text{in } \Omega \end{cases}$$

# Time-Advancement Within the Schwarz Framework



Controller time stepper

Time integrator for  $\Omega_1$

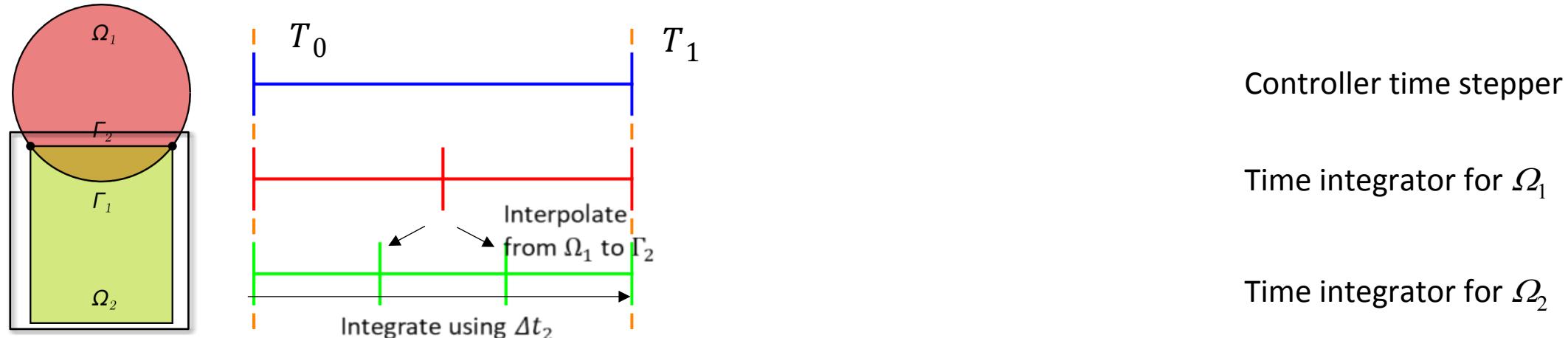
Time integrator for  $\Omega_2$

**Step 0:** Initialize  $i = 0$  (controller time index).

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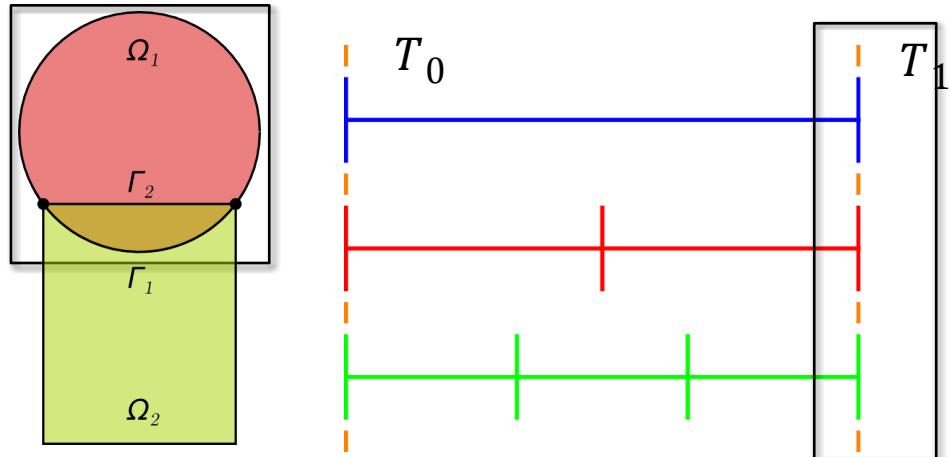
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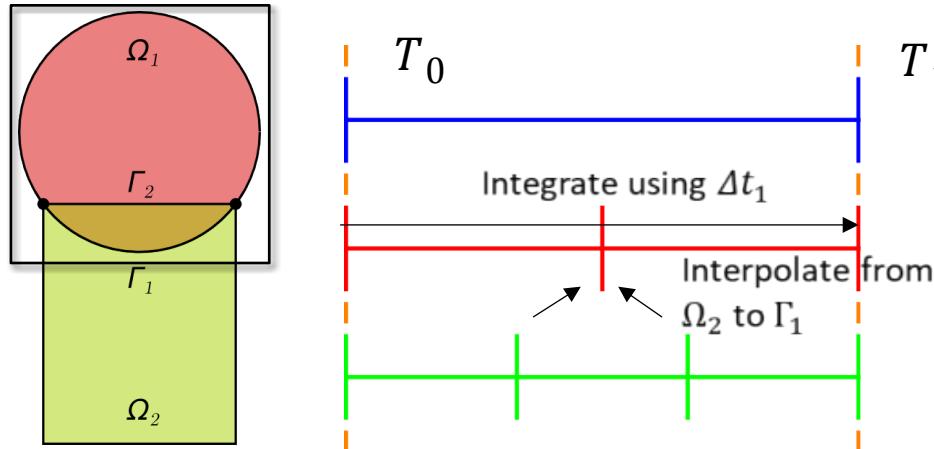
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**Step 3:** Check for convergence at time  $T_{i+1}$ .

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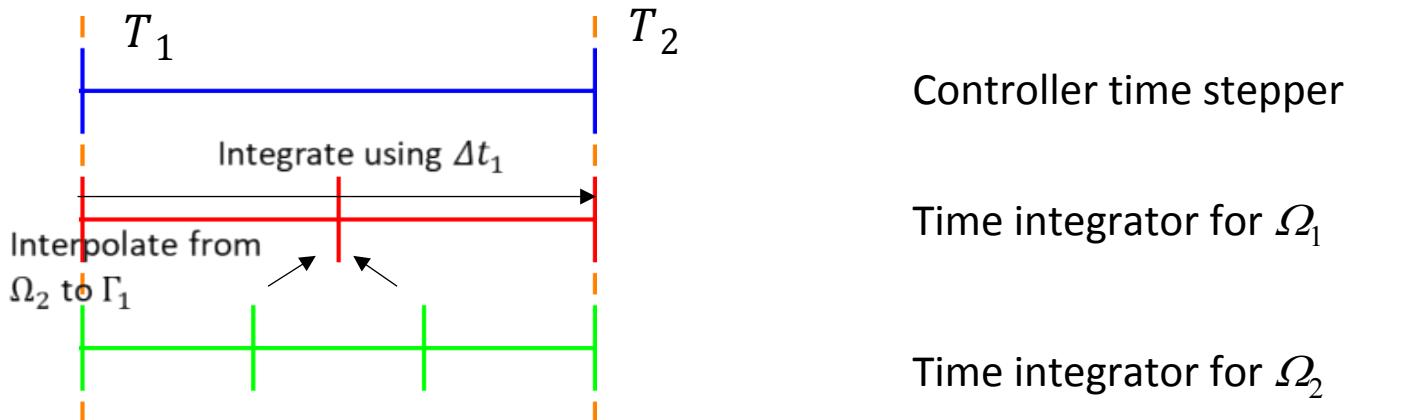
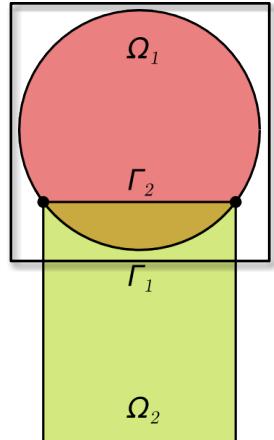
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➤ If unconverged, return to Step 1.

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# Time-Advancement Within the Schwarz Framework



**Step 0:** Initialize  $i = 0$  (controller time index).

Can use *different integrators* with *different time steps* within each domain!

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**Step 3:** Check for convergence at time  $T_{i+1}$ .

- If unconverged, return to Step 1.
- If converged, set  $i = i + 1$  and return to Step 1.

**Model PDE:** 
$$\begin{cases} \dot{u} = f - \mathcal{L}u, & \text{in } \Omega, \\ u(x, t) = g(t), & \text{on } \partial\Omega, \\ u(x, 0) = u_0, & \text{in } \Omega \end{cases}$$

# Schwarz for Multi-scale FOM-FOM Coupling in Solid Mechanics

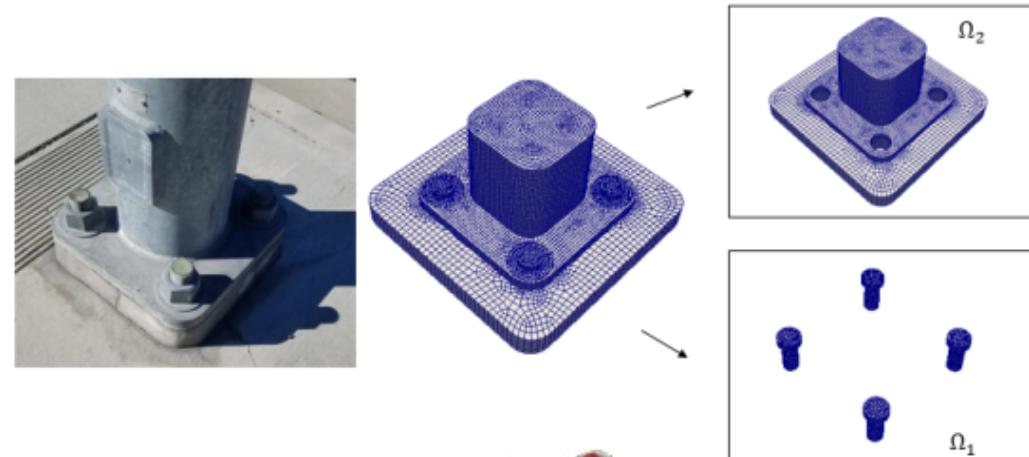


*Model Solid Mechanics PDEs:*

- Coupling is ***concurrent*** (two-way).
- ***Ease of implementation*** into existing massively-parallel HPC codes.
- ***Scalable, fast, robust*** (we target *real* engineering problems, e.g., analyses involving failure of bolted components!).
- Coupling does not introduce ***nonphysical artifacts***.
- ***Theoretical*** convergence properties/guarantees.
- ***“Plug-and-play” framework:***

$$\text{Quasistatic: } \operatorname{Div} \mathbf{P} + \rho_0 \mathbf{B} = \mathbf{0} \quad \text{in } \Omega$$

$$\text{Dynamic: } \operatorname{Div} \mathbf{P} + \rho_0 \mathbf{B} = \rho_0 \ddot{\varphi} \quad \text{in } \Omega \times I$$



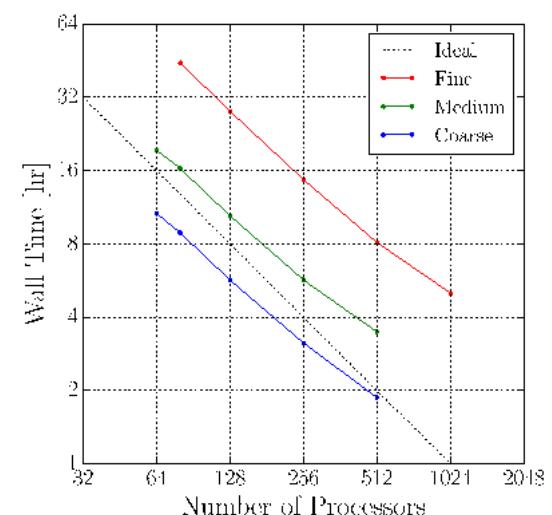
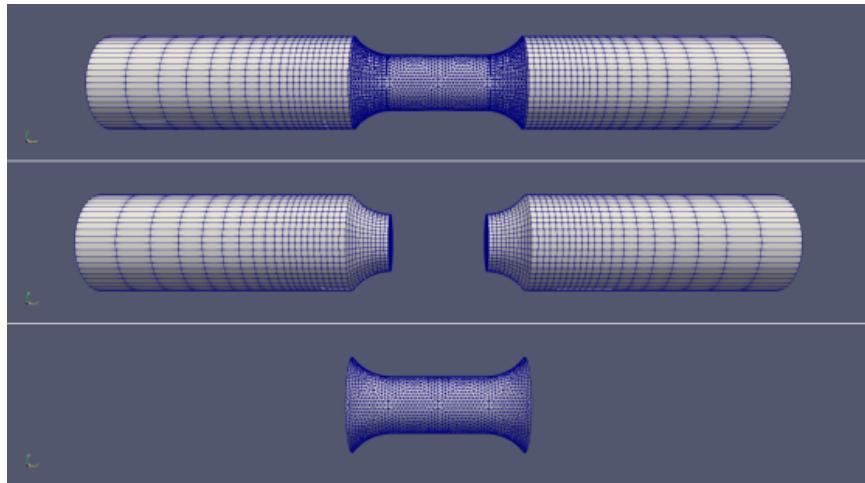
- Ability to couple regions with ***different non-conformal meshes, different element types and different levels of refinement*** to simplify task of ***meshing complex geometries***.
- Ability to use ***different solvers/time-integrators*** in different regions.

# Schwarz for Multi-scale FOM-FOM Coupling in Solid Mechanics and Contact Dynamics

17



The overlapping Schwarz alternating method has been developed/implemented for concurrent multi-scale quasistatic<sup>1</sup> & dynamic<sup>2</sup> modeling in Sandia's *Albany/LCM* and *Sierra/SM* codes.

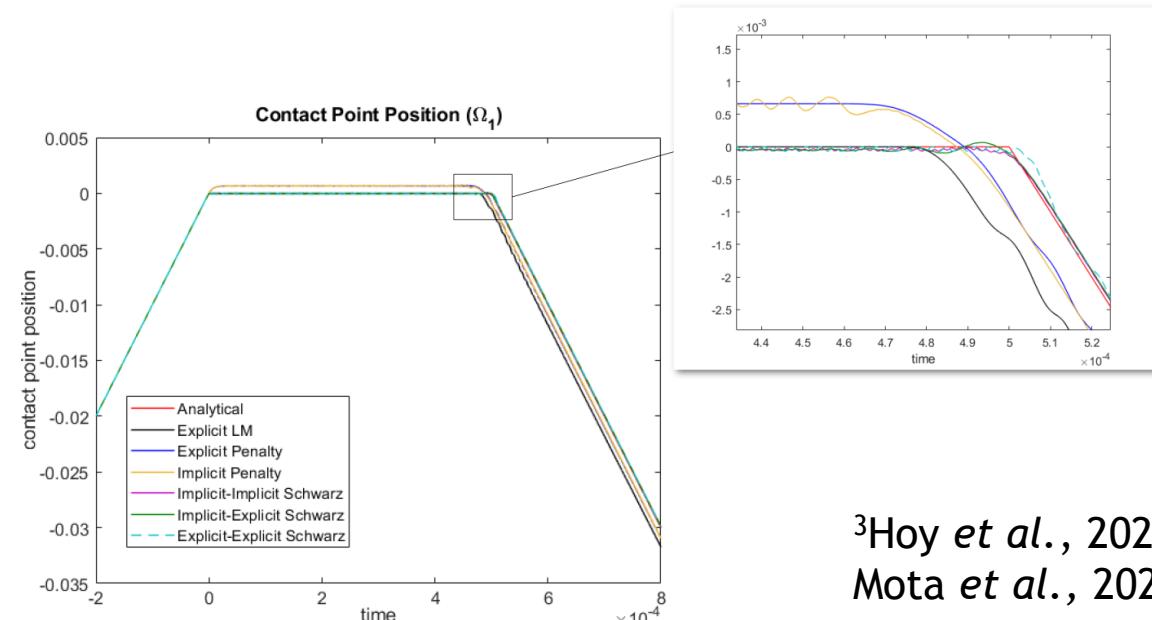
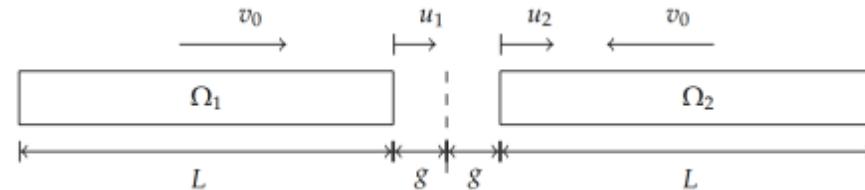


	CPU times	# Schwarz iters
Single $\Omega$	3h 34m	—
Schwarz	2h 42m	3.22



<sup>1</sup>Mota *et al.*, 2017. <sup>2</sup>Mota *et al.*, 2022.

We are currently developing a novel contact method<sup>3</sup> based on non-overlapping Schwarz.



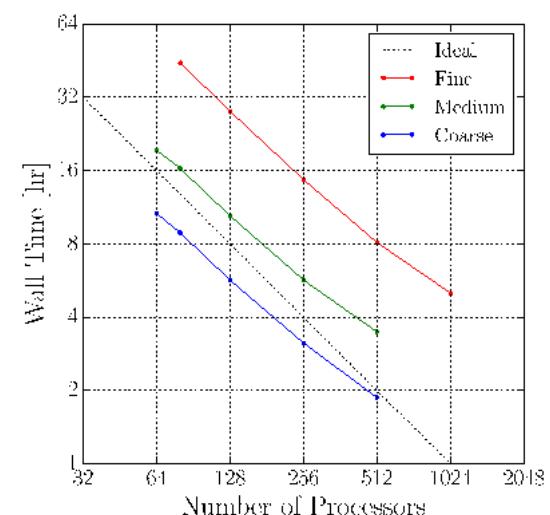
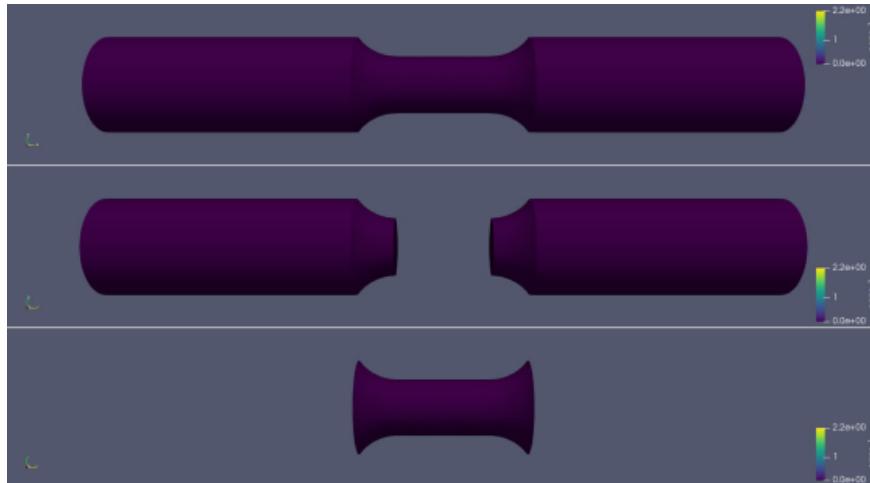
<sup>3</sup>Hoy *et al.*, 2021;  
Mota *et al.*, 2022.

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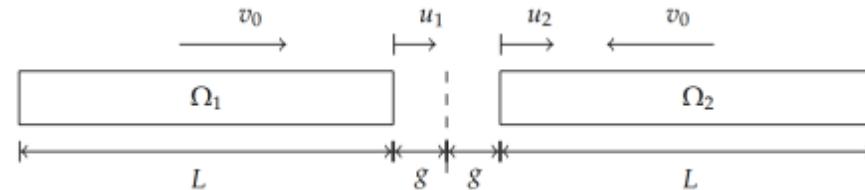


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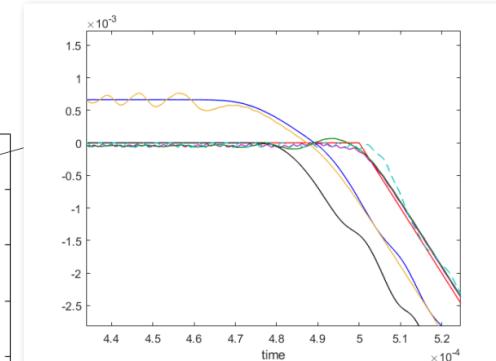
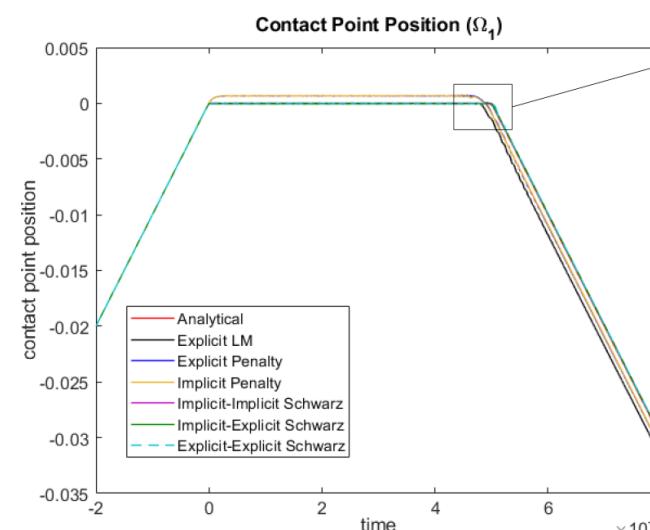


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*Talk by A. Mota*



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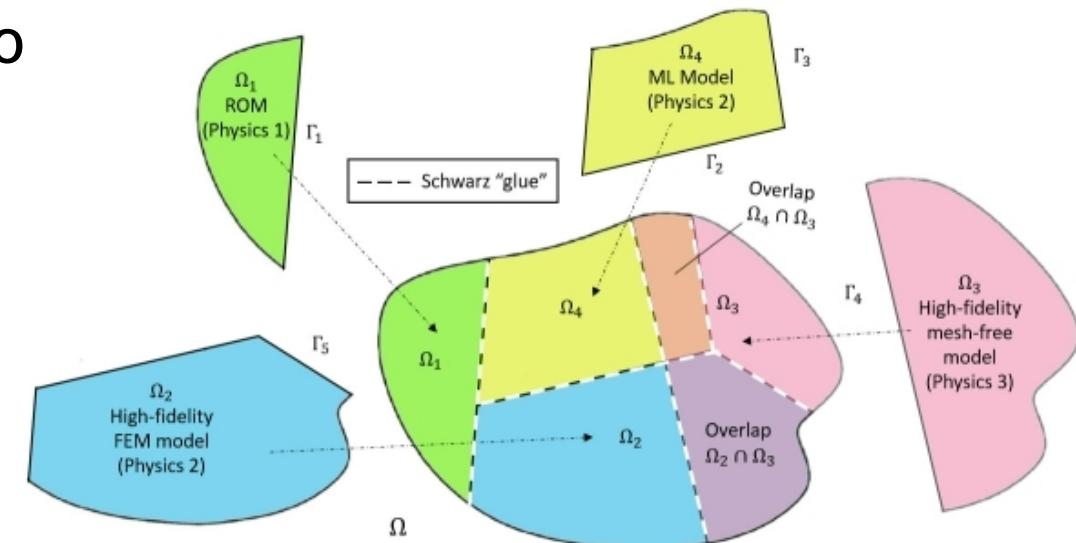
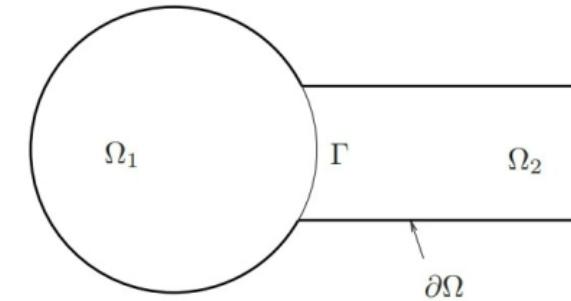
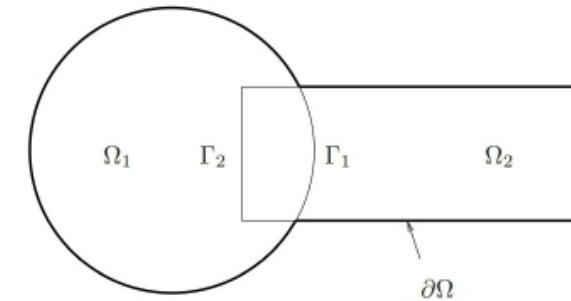
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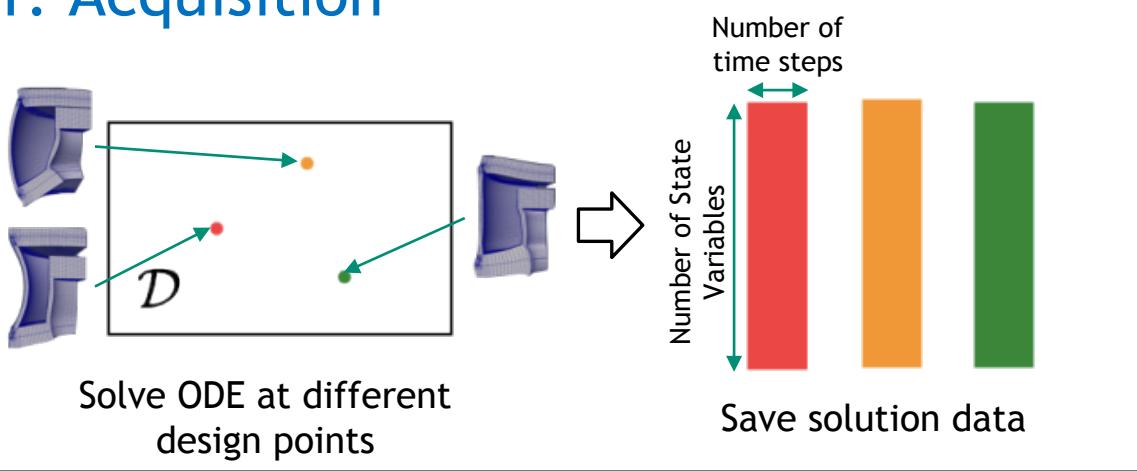


# Projection-Based Model Order Reduction via the POD/Galerkin Method



$$\text{Full Order Model (FOM): } \mathbf{M} \frac{d^2 \mathbf{x}}{dt^2} + \mathbf{f}_{\text{int}}(\mathbf{x}) = \mathbf{f}_{\text{ext}}(\mathbf{x})$$

## 1. Acquisition



## 2. Learning

Proper Orthogonal Decomposition (POD):

$$\mathbf{x} = \begin{matrix} \text{Red Bar} \\ \text{Orange Bar} \\ \text{Green Bar} \end{matrix} = \begin{matrix} \text{Brown Bar} \\ \text{Blue Bar} \end{matrix} \Sigma \begin{matrix} \text{Blue Bar} \\ \text{Purple Bar} \end{matrix}^T$$

## 3. Projection-Based Reduction

Reduce the number of unknowns

$$\mathbf{x}(t) \approx \tilde{\mathbf{x}}(t) = \Phi \hat{\mathbf{x}}(t)$$

Perform Galerkin projection

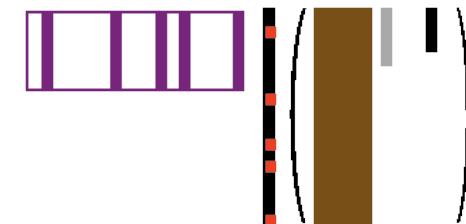
$$\Phi^T \mathbf{M} \Phi \frac{d^2 \hat{\mathbf{x}}}{dt^2} + \Phi^T \mathbf{f}_{\text{int}}(\Phi \hat{\mathbf{x}}) = \Phi^T \mathbf{f}_{\text{ext}}$$

Hyper-reduce nonlinear terms



Hyper-reduction/sample mesh

$$\mathbf{f}_{\text{int}}(\Phi \hat{\mathbf{x}}) \approx \mathbf{A} \mathbf{f}_{\text{int}}(\Phi \hat{\mathbf{x}})$$



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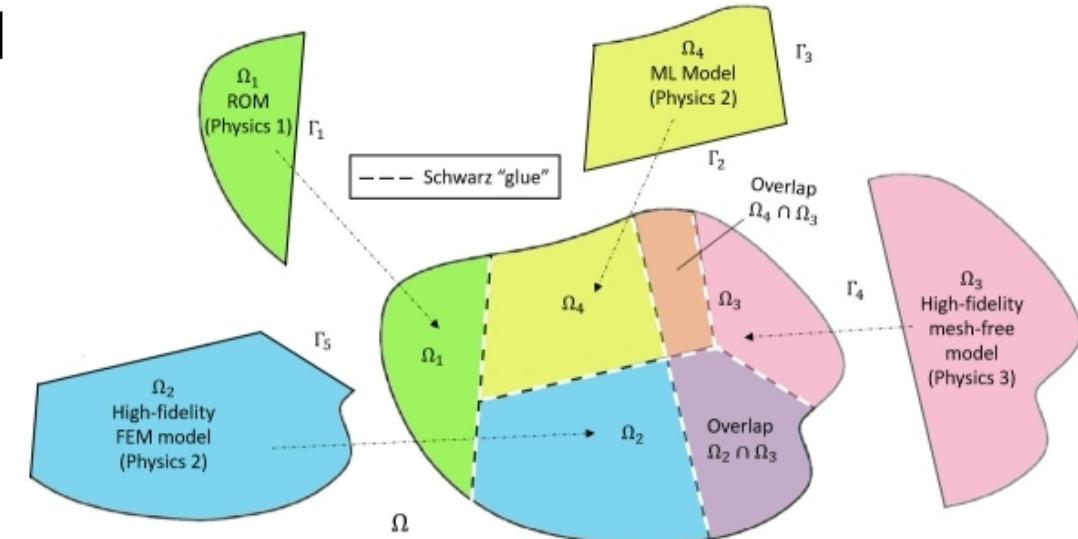
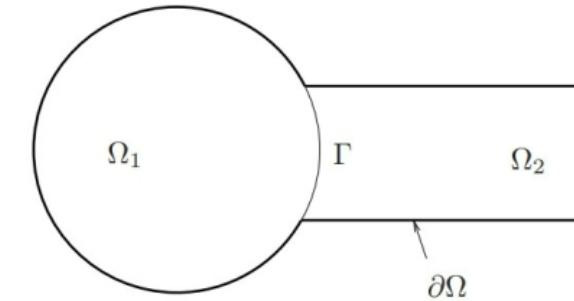
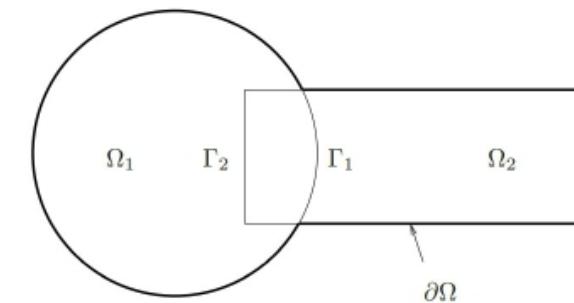
1. Overview of the Schwarz Alternating Method for Concurrent Coupling

2. Overview of Projection-Based Model Order Reduction

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5. Summary and Future Work



# Schwarz Extensions to ROM-FOM and ROM-ROM Couplings

## *Enforcement of Dirichlet boundary conditions (DBC)s in ROM at indices $i_{\text{Dir}}$*

- Method I in [Gunzburger *et al.* 2007] is employed

$$\mathbf{d}(t) = \bar{\mathbf{d}} + \Phi \hat{\mathbf{d}}(t), \quad \mathbf{v}(t) = \bar{\mathbf{v}} + \Phi \hat{\mathbf{v}}(t), \quad \mathbf{a}(t) = \bar{\mathbf{a}} + \Phi \hat{\mathbf{a}}(t)$$

- POD modes made to satisfy homogeneous DBCs:  $\Phi(i_{\text{Dir}}, :) = \mathbf{0}$
- BCs imposed by modifying  $\bar{\mathbf{d}}$ ,  $\bar{\mathbf{v}}$ ,  $\bar{\mathbf{a}}$ :  $\bar{\mathbf{d}}(i_{\text{Dir}}) \leftarrow \chi_d$ ,  $\bar{\mathbf{v}}(i_{\text{Dir}}) \leftarrow \chi_v$ ,  $\bar{\mathbf{a}}(i_{\text{Dir}}) \leftarrow \chi_a$

## *Choice of domain decomposition*

- Error-based indicators that help decide in what region of the domain a ROM can be viable should drive domain decomposition (future work)

## *Snapshot collection and reduced basis construction*

- Ideally, one would generate snapshots/reduced bases separately in each subdomain  $\Omega_i$
- POD results presented herein use snapshots obtained via FOM-FOM coupling on  $\Omega = \bigcup_i \Omega_i$

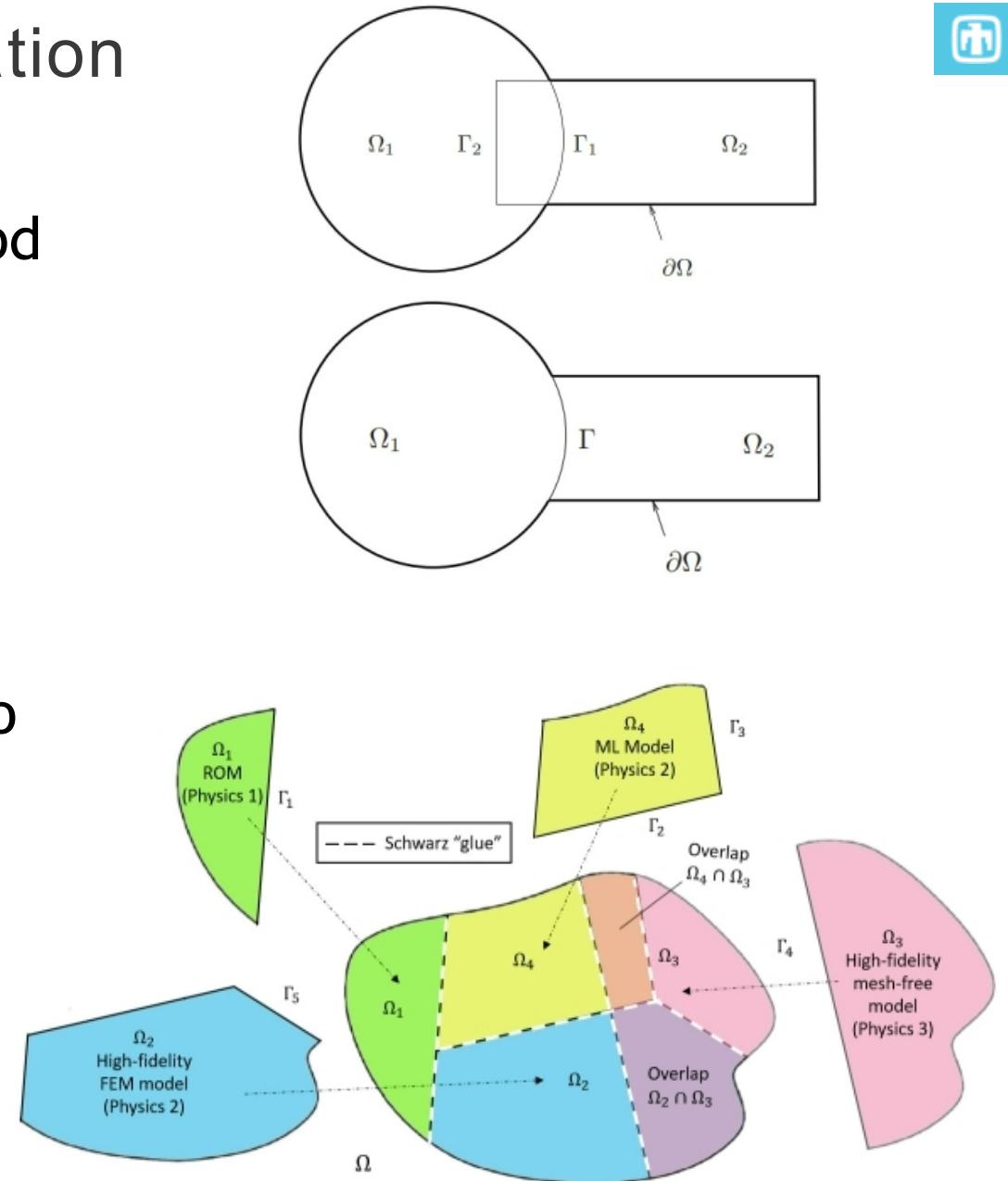
*For nonlinear solid mechanics, special hyper-reduction methods need to preserve Hamiltonian structure, e.g., Energy-Conserving Sampling and Weighting Method (ECSW) [Farhat *et al.* 2015]*

- Results here are for linear problem, so hyper-reduction is not required

# Outline For Remainder of Presentation



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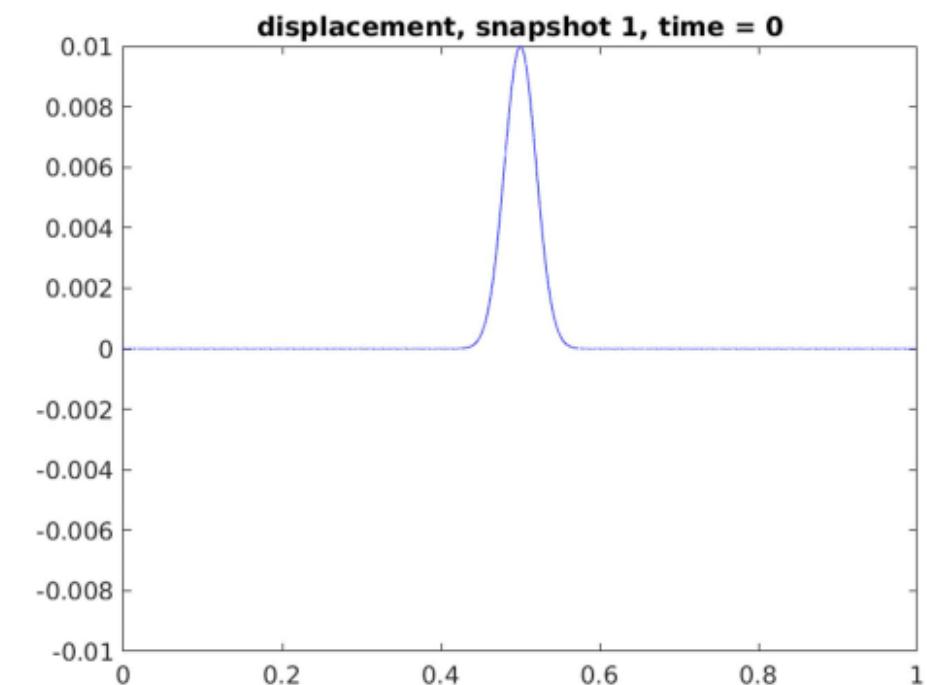


# Numerical Example: Linear Elastic Wave Propagation Problem

- Linear elastic *clamped beam* with Gaussian initial condition for the  $z$ -displacement.
- Simple problem with analytical exact solution but very *stringent test* for discretization methods.
- *Couplings tested:* FOM-FOM, FOM-ROM, ROM-ROM, implicit-explicit, implicit-implicit, explicit-explicit.
- ROMs are *reproductive* and based on the *POD/Galerkin* method.
  - 50 POD modes capture  $\sim 100\%$  snapshot energy



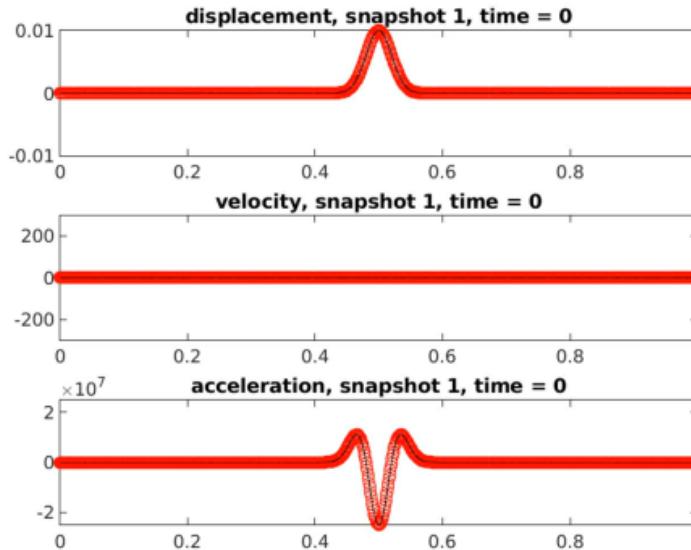
Above: 3D rendering of clamped beam with Gaussian initial condition.  
 Right: Initial condition (blue) and final solution (red). Wave profile is negative of initial profile at time  $T = 1.0e-3$ .



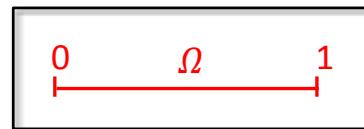
# Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



*Coupling delivers accurate solution if each subdomain model is reasonably accurate, can couple different discretizations with different  $\Delta x$ ,  $\Delta t$  and basis sizes.*



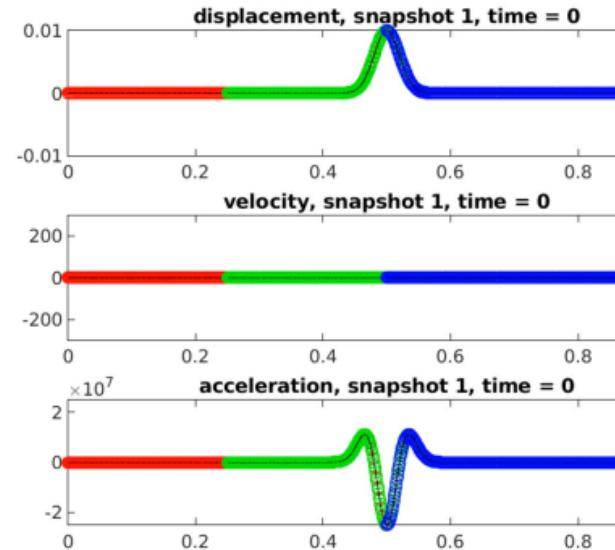
Single Domain FOM



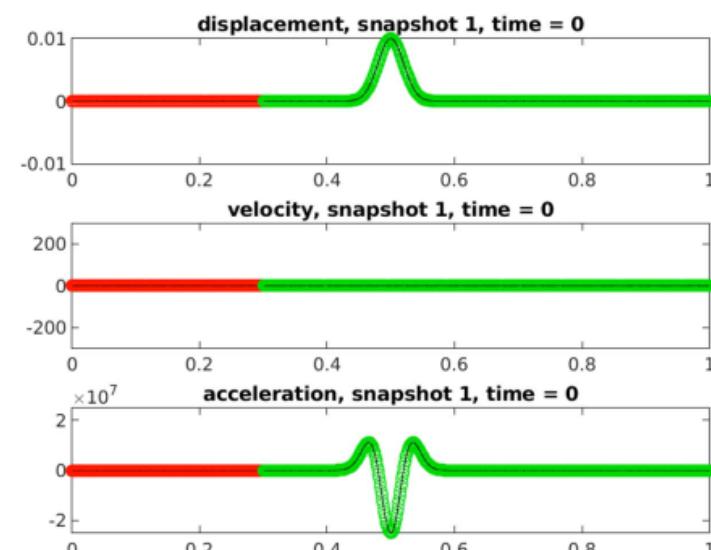
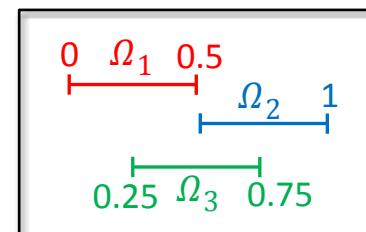
<sup>1</sup>Implicit 40 mode POD ROM,  $\Delta t=1e-6$ ,  $\Delta x=1.25e-3$

<sup>2</sup>Implicit FOM,  $\Delta t =1e-6$ ,  $\Delta x =8.33e-4$

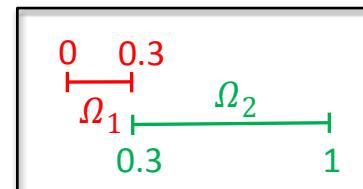
<sup>3</sup>Explicit 50 mode POD ROM,  $\Delta t =1e-7$ ,  $\Delta x =1e-3$



3 overlapping subdomain  
ROM<sup>1</sup>-FOM<sup>2</sup>-ROM<sup>3</sup>



2 non-overlapping subdomain  
FOM<sup>4</sup>-ROM<sup>5</sup> ( $\theta = 1$ )



<sup>5</sup>Implicit FOM,  $\Delta t =2.25e-7$ ,  
 $\Delta x =1e-6$

<sup>4</sup>Explicit 50 mode POD ROM,  
 $\Delta t =2.25e-7$ ,  $\Delta x =1e-6$

# Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



*Coupled models are reasonably accurate w.r.t. FOM-FOM coupled analogs and convergence with respect to basis refinement for ROM-FOM and ROM-ROM coupling is observed.*

	disp MSE <sup>6</sup>	velo MSE	acce MSE
Overlapping ROM <sup>1</sup> -FOM <sup>2</sup> -ROM <sup>3</sup>	1.05e-4	1.40e-3	2.32e-2
Non-overlapping FOM <sup>4</sup> -ROM <sup>5</sup>	2.78e-5	2.20e-4	3.30e-3

<sup>1</sup>Implicit 40 mode POD ROM,  $\Delta t = 1e-6$ ,  $\Delta x = 1.25e-3$

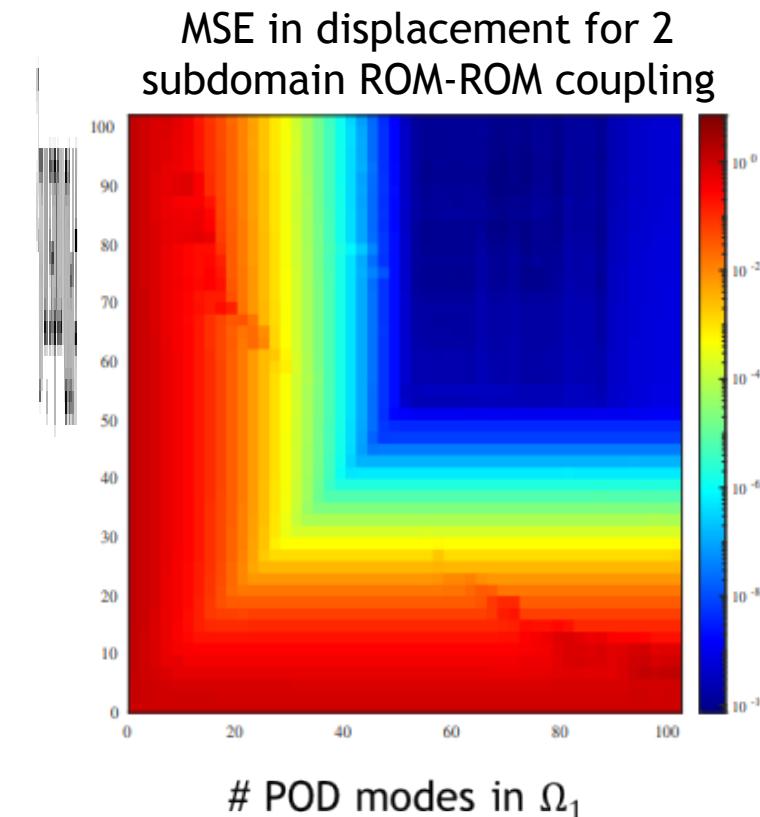
<sup>2</sup>Implicit FOM,  $\Delta t = 1e-6$ ,  $\Delta x = 8.33e-4$

<sup>3</sup>Explicit 50 mode POD ROM,  $\Delta t = 1e-7$ ,  $\Delta x = 1e-3$

<sup>4</sup>Implicit FOM,  $\Delta t = 2.25e-7$ ,  $\Delta x = 1e-6$

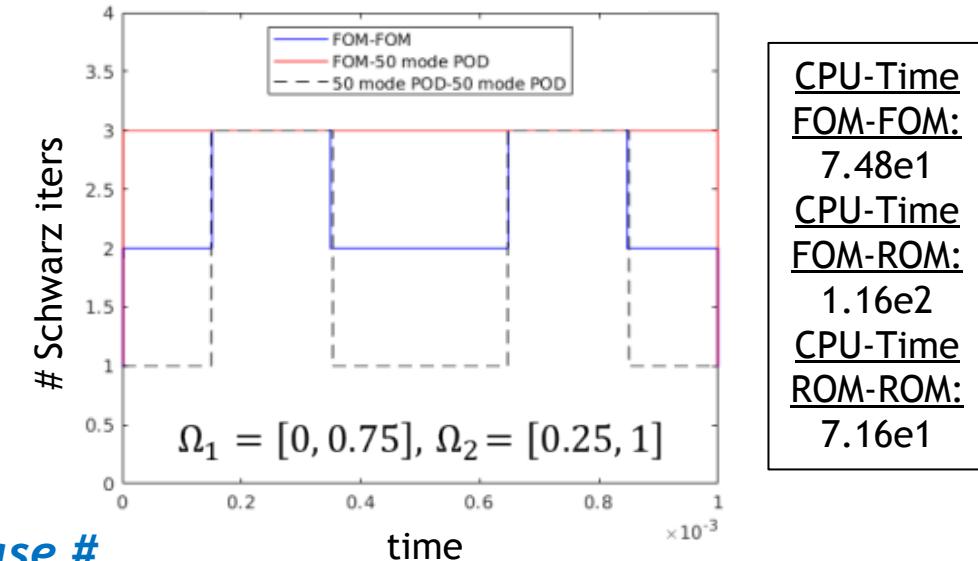
<sup>5</sup>Explicit 50 mode POD ROM,  $\Delta t = 2.25e-7$ ,  $\Delta x = 1e-6$

$$\text{MSE} = \text{mean squared error} = \sqrt{\sum_{n=1}^{N_t} \|\tilde{\mathbf{u}}^n(\boldsymbol{\mu}) - \mathbf{u}^n(\boldsymbol{\mu})\|_2^2} \Big/ \sqrt{\sum_{n=1}^{N_t} \|\mathbf{u}^n(\boldsymbol{\mu})\|_2^2}.$$



# Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings

	Online CPU time	Total # Schwarz iters
Overlapping FOM <sup>1</sup> -FOM <sup>2</sup> -FOM <sup>3</sup>	68.7s	2972
Overlapping ROM <sup>4</sup> -FOM <sup>2</sup> -ROM <sup>5</sup>	81.6s	4000
Non-overlapping FOM <sup>6</sup> -FOM <sup>7</sup>	38.0s	10,516
Non-overlapping FOM <sup>6</sup> -ROM <sup>8</sup>	49.8s	13,366



CPU-Time FOM-FOM: 7.48e1  
CPU-Time FOM-ROM: 1.16e2  
CPU-Time ROM-ROM: 7.16e1

*ROM-FOM and ROM-ROM couplings often (but not always) increase # Schwarz iterations relative to FOM-FOM coupling.*

➤ Key to improving efficiency is reducing # Schwarz iterations.

*ROMs with fewer modes do not always give rise to smaller CPU times.*

➤ Less accurate models ⇒ more Schwarz iterations needed for convergence.

*Using smaller time steps can decrease # Schwarz iterations.*

**WIP:** *optimizing ROM-FOM and ROM-ROM coupling implementation and devising ways to reduce # Schwarz iterations (e.g., through relaxation parameter  $\theta$ )*

<sup>1</sup>Implicit FOM,  $\Delta t = 1e-6$ ,  $\Delta x = 1.25e-3$

<sup>2</sup>Implicit FOM,  $\Delta t = 1e-6$ ,  $\Delta x = 8.33e-4$

<sup>3</sup>Explicit FOM,  $\Delta t = 1e-7$ ,  $\Delta x = 1e-3$

<sup>4</sup>Implicit 30 mode POD ROM,  $\Delta t = 1e-6$ ,  $\Delta x = 1.25e-3$

<sup>5</sup>Explicit 50 mode POD ROM,  $\Delta t = 1e-7$ ,  $\Delta x = 1e-3$

<sup>6</sup>Implicit FOM,  $\Delta t = 2.25e-7$ ,  $\Delta x = 1e-6$

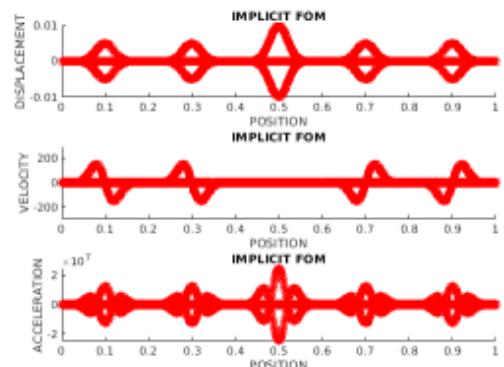
<sup>7</sup>Explicit FOM,  $\Delta t = 2.25e-7$ ,  $\Delta x = 1e-6$

<sup>8</sup>Explicit 50 mode POD ROM,  $\Delta t = 2.25e-7$ ,  $\Delta x = 1e-6$

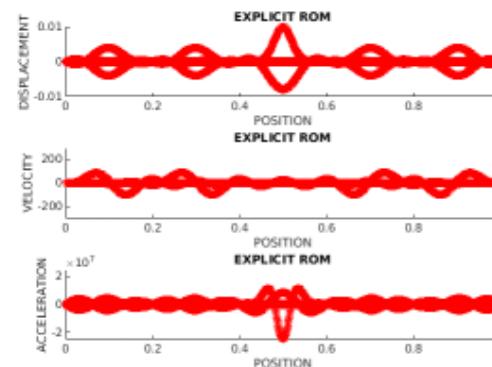
# Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



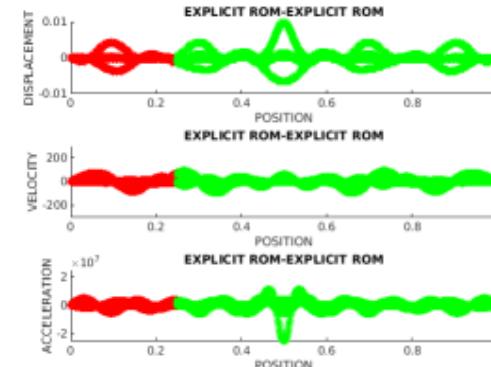
*Inaccurate model + accurate model  $\neq$  accurate model.*



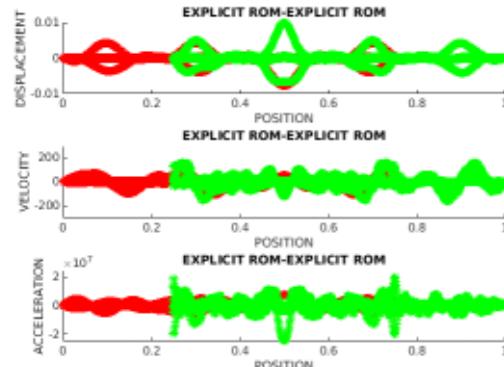
Single Domain, FOM (truth)



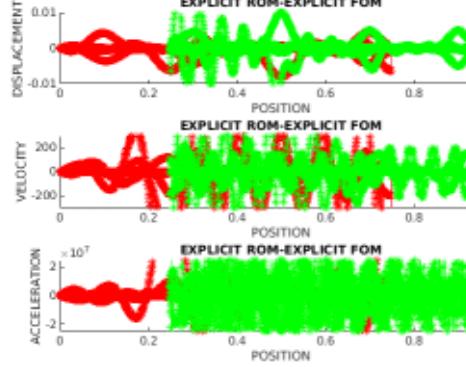
Single Domain, 10 mode POD



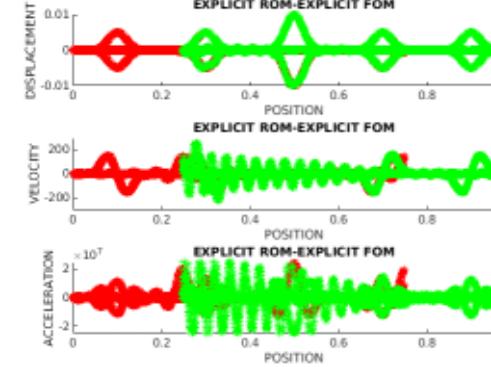
10 mode POD – 10 mode POD



10 mode POD – 50 mode POD



10 mode POD – FOM



20 mode POD – FOM

Figures above:  $\Omega_1 = [0, 0.75]$ ,  $\Omega_2 = [0.25, 1]$

Observation suggests need for “smart” domain decomposition.

Accuracy can be improved by “gluing” several smaller, spatially-local models

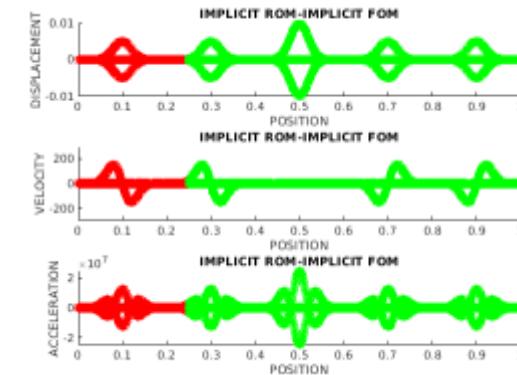
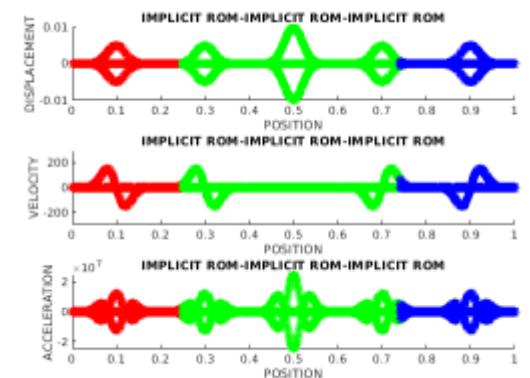


Figure above:  $\Omega_1 = [0, 0.3]$ ,  $\Omega_2 = [0.25, 1]$ , 20 mode POD - FOM

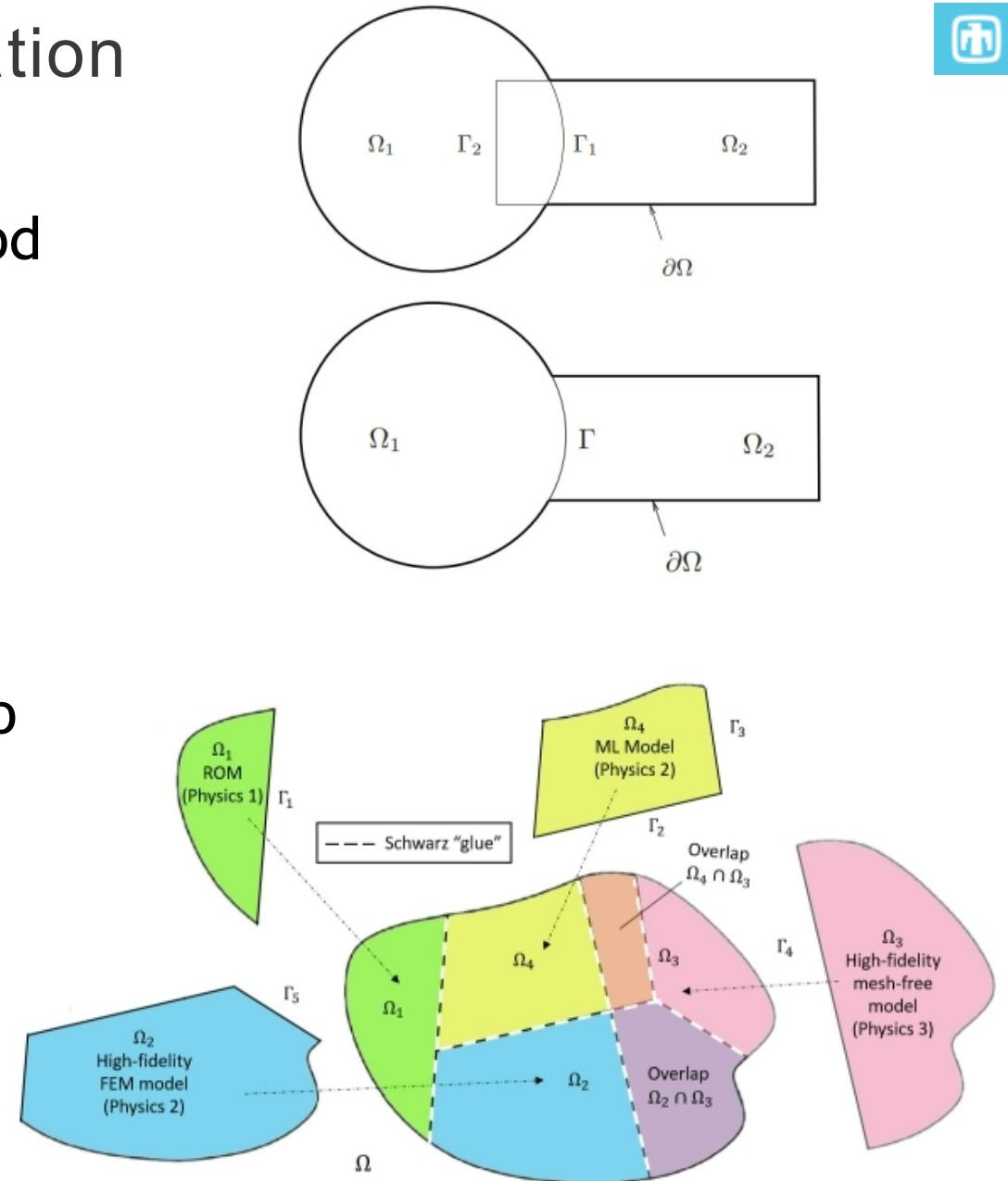
Figure below:  $\Omega_1 = [0, 0.26]$ ,  $\Omega_2 = [0.25, 0.75]$ ,  $\Omega_3 = [0.74, 1]$ , 15 mode POD - 30 mode POD - 15 mode POD



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### Summary:

- Initial prototyping suggests that the Schwarz alternating method can be **effective coupling** method that enables coupling of **conventional and data-driven models** (projection-based ROMs).
- The coupling methodology enables the use of **different mesh resolutions, reduced basis sizes, and different time integrators with different time steps** in different subdomains.
- Preliminary results suggest that the **choice of domain decomposition (DD)** is critical to accuracy of the coupled model.

### Ongoing/future work:

- Implementation/prototyping of coupling method on **non-linear problems** with ECSW-based hyper-reduction.
- Implementation/prototyping of coupling method in **multi-D**.
- Investigation of methodologies for reducing the number of Schwarz iterations and **improving performance** when performing FOM-ROM and ROM-ROM coupling.
- Development of **error indicators** to guide DD in an error-controlling way, e.g., [Bergmann *et al.* 2018].
- Analysis** of proposed coupling approach for FOM-ROM and ROM-ROM coupling.
- Development of **snapshot collection approaches** that do not require full system simulation.
- Extension of the coupling framework to include **Physics-Informed Neural Networks (PINNs)**.
- Extension of coupling method to **multi-material and multi-physics problems**.

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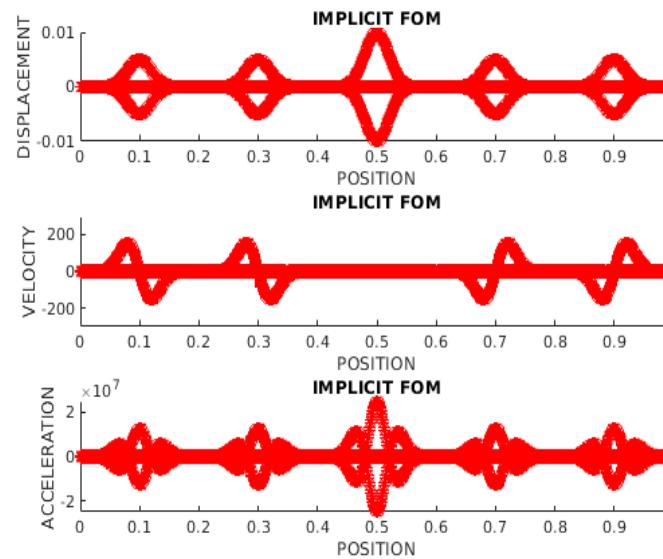


# Start of Backup Slides

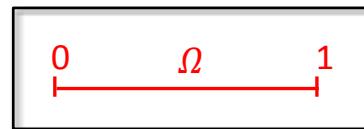
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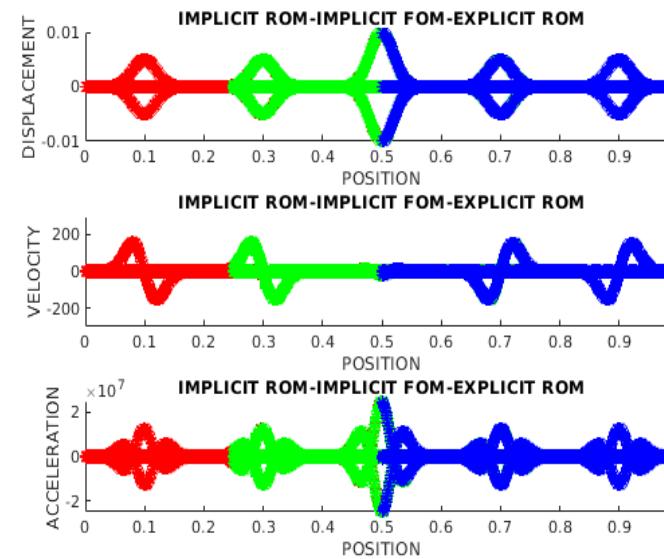
Single Domain FOM



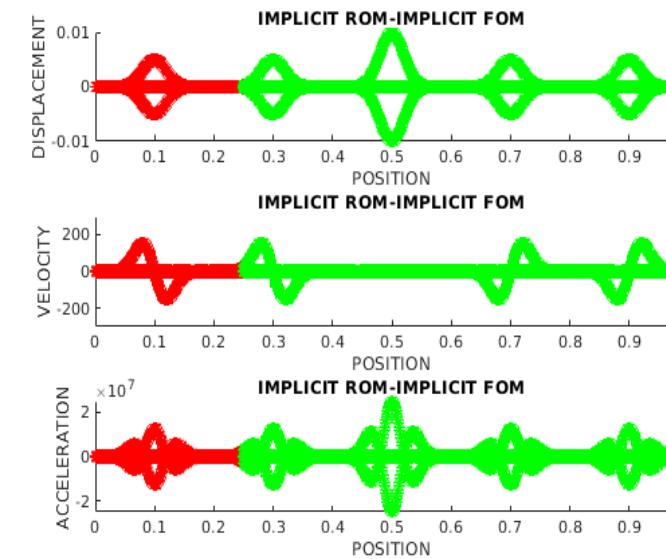
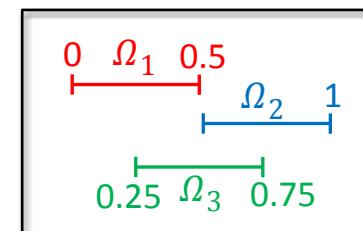
<sup>1</sup>Implicit 40 mode POD ROM,  $\Delta t=1e-6$ ,  $\Delta x=1.25e-3$

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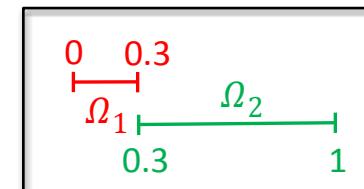
<sup>3</sup>Explicit 50 mode POD ROM,  $\Delta t =1e-7$ ,  $\Delta x =1e-3$



3 overlapping subdomain  
ROM<sup>1</sup>-FOM<sup>2</sup>-ROM<sup>3</sup>



2 non-overlapping subdomain  
FOM<sup>4</sup>-ROM<sup>5</sup> ( $\theta = 1$ )



<sup>5</sup>Implicit FOM,  $\Delta t =2.25e-7$ ,  
 $\Delta x =1e-6$

<sup>4</sup>Explicit 50 mode POD ROM,  
 $\Delta t =2.25e-7$ ,  $\Delta x =1e-6$