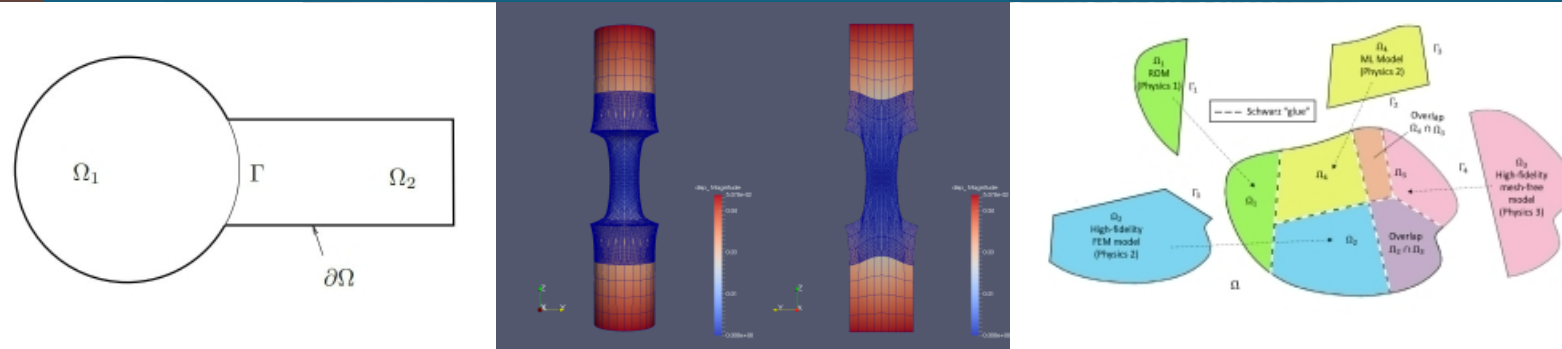




The Schwarz Alternating Method for ROM*-FOM[#] and ROM-ROM Coupling



* Reduced Order Model
Full Order Model

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WCCM 2022

July 31 - August 5, 2022

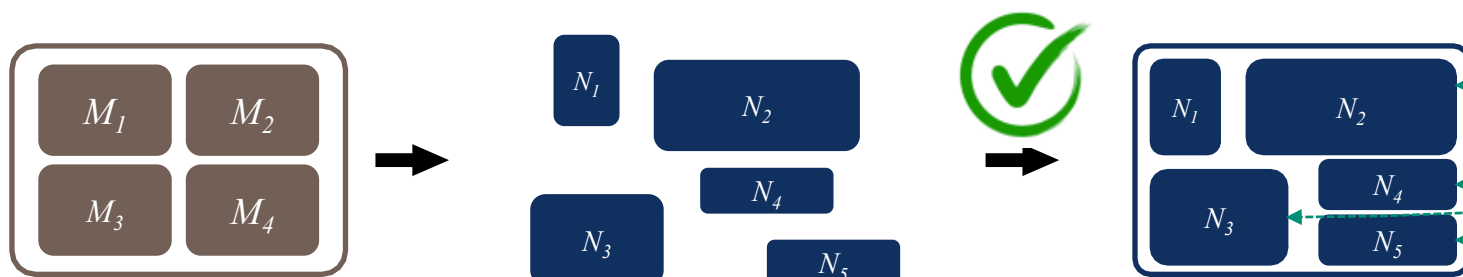
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Motivation

The past decades have seen tremendous investment in **simulation frameworks for coupled multi-scale and multi-physics problems**.

- Frameworks rely on **established mathematical theories** to couple physics components.
- Most existing coupling frameworks are based on **traditional discretization methods**.



Complex System Model

- PDEs, ODEs
- Nonlocal integral
- Classical DFT,
- Atomistic...

Traditional Methods

- Mesh-based (FE, FV, FD),
- Meshless (SPH, MLS),
- Implicit, explicit,
- Eulerian, Lagrangian...

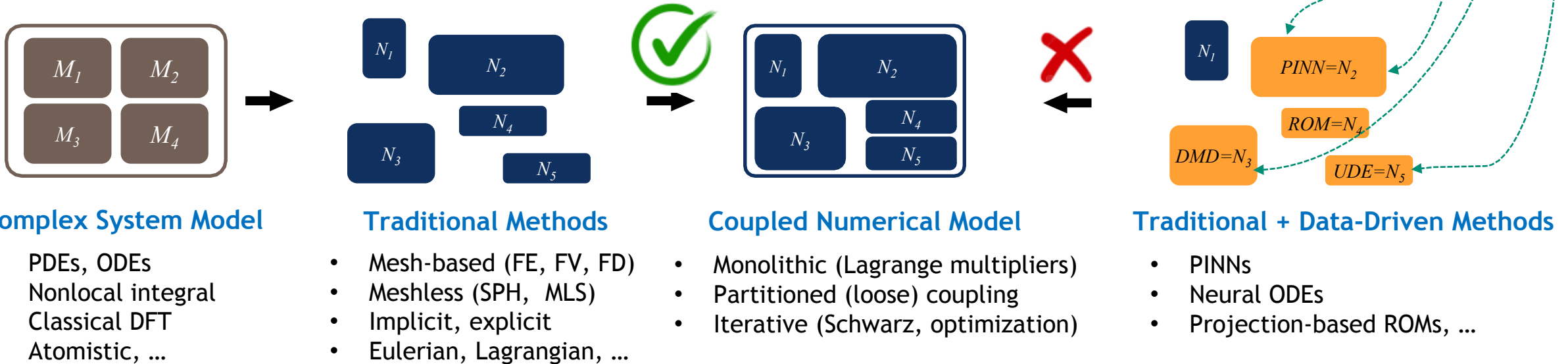
Coupled Numerical Model

- Monolithic (Lagrange multipliers)
- Partitioned (loose) coupling
- Iterative (Schwarz, optimization)

Motivation

The past decades have seen tremendous investment in **simulation frameworks for coupled multi-scale and multi-physics problems**.

- Frameworks rely on **established mathematical theories** to couple physics components.
- Most existing coupling frameworks are based on **traditional discretization methods**.



- There is currently a big push to integrate **data-driven methods** into modeling & simulation toolchains.

Unfortunately, existing algorithmic and software infrastructures are **ill-equipped** to handle plug-and-play integration of **non-traditional, data-driven models**!

Principal research objective:

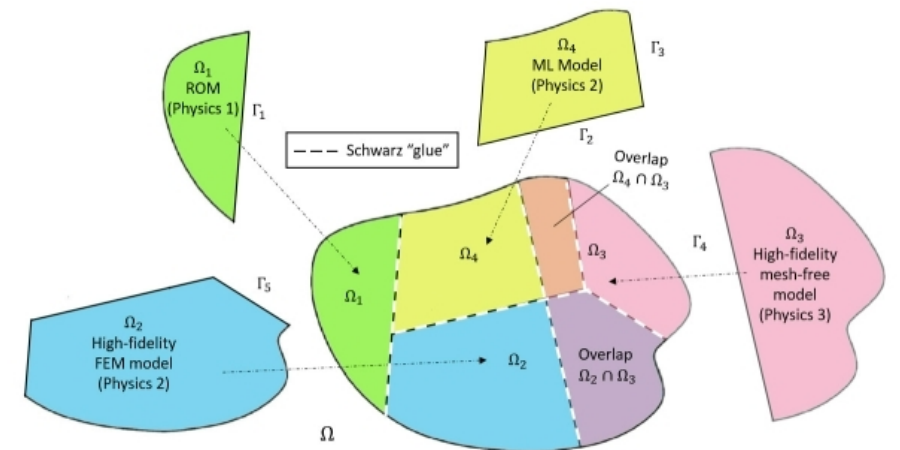
- Discover mathematical principles guiding the assembly of standard and data-driven numerical models into stable, accurate and physically consistent **flexible Heterogeneous Numerical Methods**

Principal research challenges: we lack mathematical and algorithmic understanding of how to

- “Mix-and-match” standard and data-driven models from three-classes
 - **Class A:** projection-based reduced order models (ROMs) *This talk*
 - **Class B:** machine-learned models, i.e., Physics-Informed Neural Networks (PINNs)
 - **Class C:** flow map approximation models, i.e., dynamic model decomposition (DMD) models
- Ensure **well-posedness & physical consistency** of the resulting **heterogeneous models**.
- Solve such heterogeneous models efficiently.

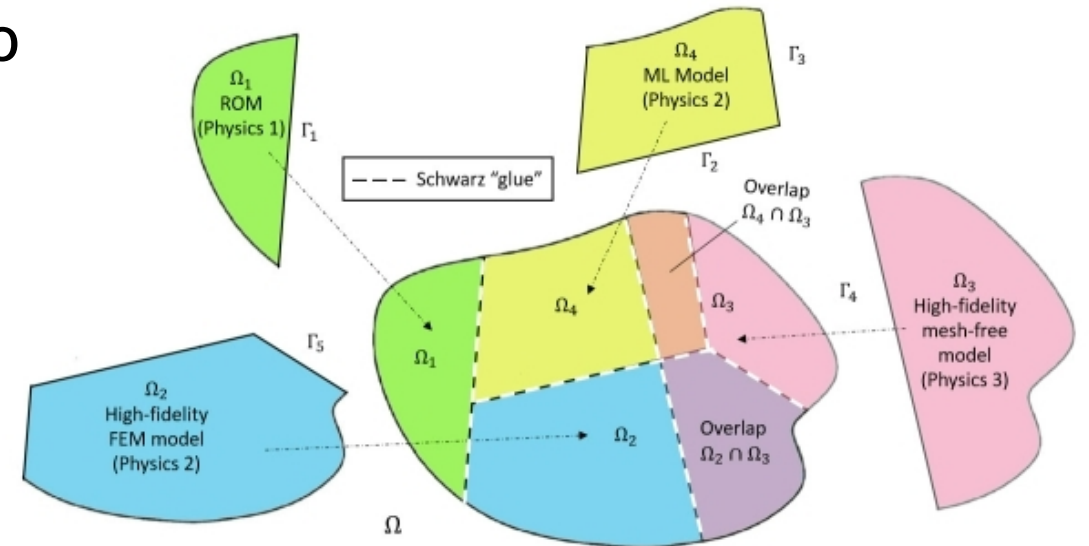
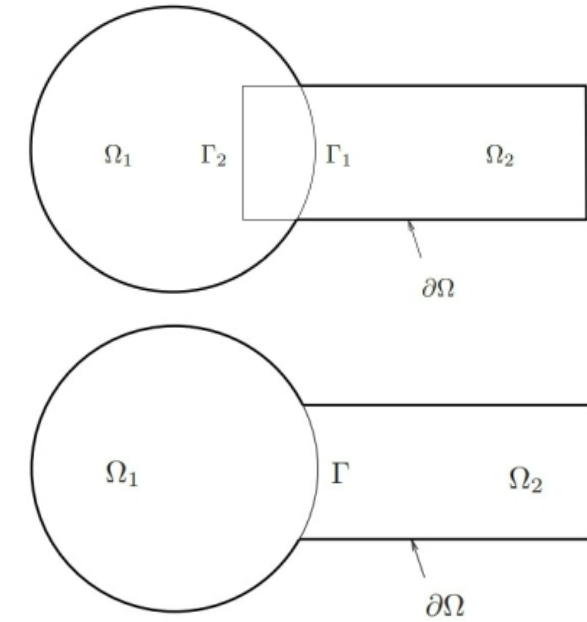
Three coupling methods:

- Alternating Schwarz-based coupling *This talk*
- Optimization-based coupling
- Generalized mortar methods *Talk by A. DeCastro*



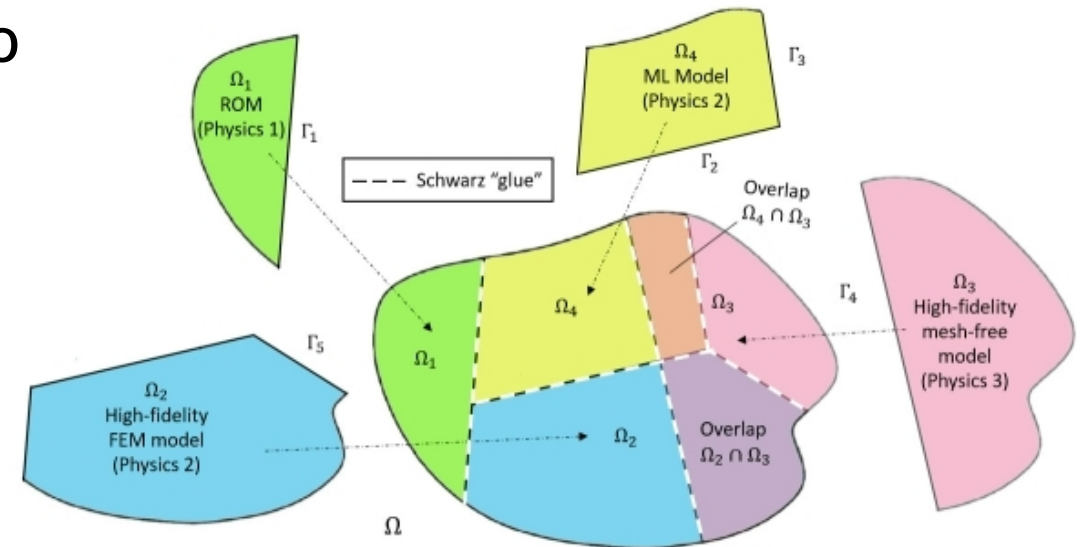
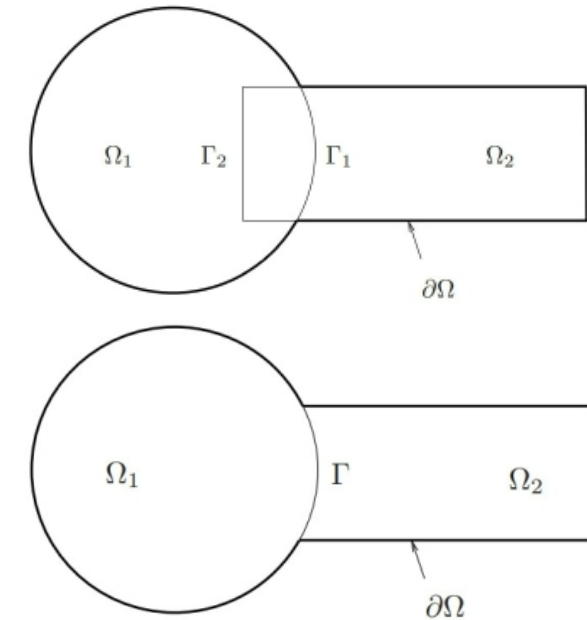
Outline For Remainder of Presentation

1. Overview of the Schwarz Alternating Method for Concurrent Coupling
2. Overview of Projection-Based Model Order Reduction
3. Extension of Schwarz Alternating Method to ROM-FOM and ROM-ROM coupling
4. Numerical Results
5. Summary and Future Work

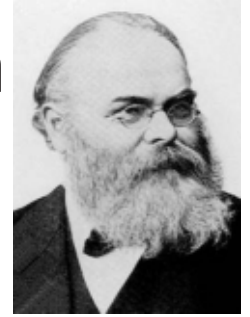


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Schwarz Alternating Method for Domain Decomposition



H. Schwarz (1843-1921)

- Proposed in 1870 by H. Schwarz for solving Laplace PDE on irregular domains.

Crux of Method: if the solution is known in regularly shaped domains, use those as pieces to iteratively build a solution for the more complex domain.

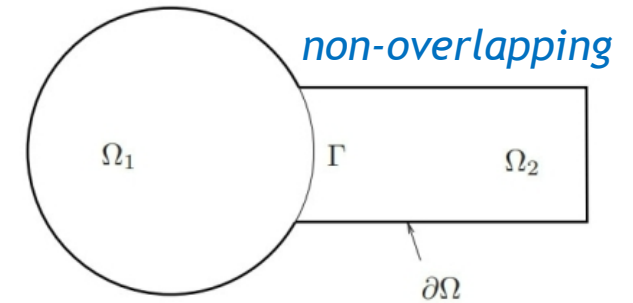
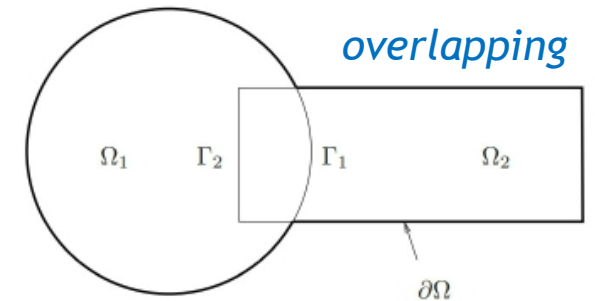
Basic Schwarz Algorithm

Initialize:

- Solve PDE by any method on Ω_1 w/ initial guess for transmission BCs on Γ_1 .

Iterate until convergence:

- Solve PDE by any method on Ω_2 w/ transmission BCs on Γ_2 based on values just obtained for Ω_1 .
- Solve PDE by any method on Ω_1 w/ transmission BCs on Γ_1 based on values just obtained for Ω_2 .



- Schwarz alternating method most commonly used as a **preconditioner** for Krylov iterative methods to solve linear algebraic equations.

Novel idea: using the Schwarz alternating as a **discretization method** for solving multi-scale or multi-physics partial differential equations (PDEs).



AS A *PRECONDITIONER*
FOR THE LINEARIZED
SYSTEM



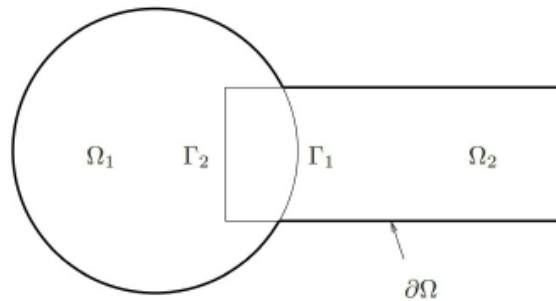
AS A *SOLVER* FOR THE
COUPLED
FULLY NONLINEAR
PROBLEM

Overlapping Domain Decomposition

$$\text{Model PDE: } \begin{cases} \mathcal{L}u = f, & \text{in } \Omega, \\ u = g, & \text{on } \partial\Omega. \end{cases}$$

$$\begin{cases} \mathcal{L}u_1^{n+1} = f, & \text{in } \Omega_1, \\ u_1^{n+1} = g, & \text{on } \partial\Omega_1 \setminus \Gamma_1, \\ u_1^{n+1} = u_2^n, & \text{on } \Gamma_1, \end{cases}$$

$$\begin{cases} \mathcal{L}u_2^{n+1} = f, & \text{in } \Omega_2, \\ u_2^{n+1} = g, & \text{on } \partial\Omega_2 \setminus \Gamma_2, \\ u_2^{n+1} = u_1^{n+1}, & \text{on } \Gamma_2. \end{cases}$$



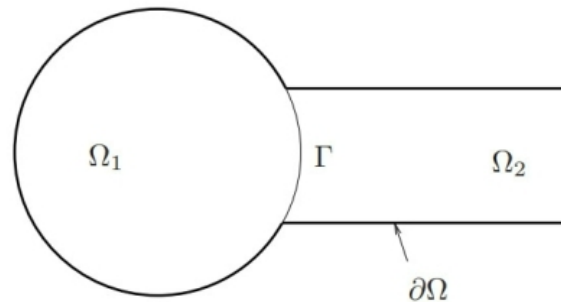
- Dirichlet-Dirichlet transmission BCs [Schwarz, 1870; Lions, 1988]

Non-overlapping Domain Decomposition

$$\begin{cases} \mathcal{L}u_1^{n+1} = f, & \text{in } \Omega_1, \\ u_1^{n+1} = g, & \text{on } \partial\Omega_1 \setminus \Gamma, \\ u_1^{n+1} = \lambda_{n+1}, & \text{on } \Gamma, \end{cases}$$

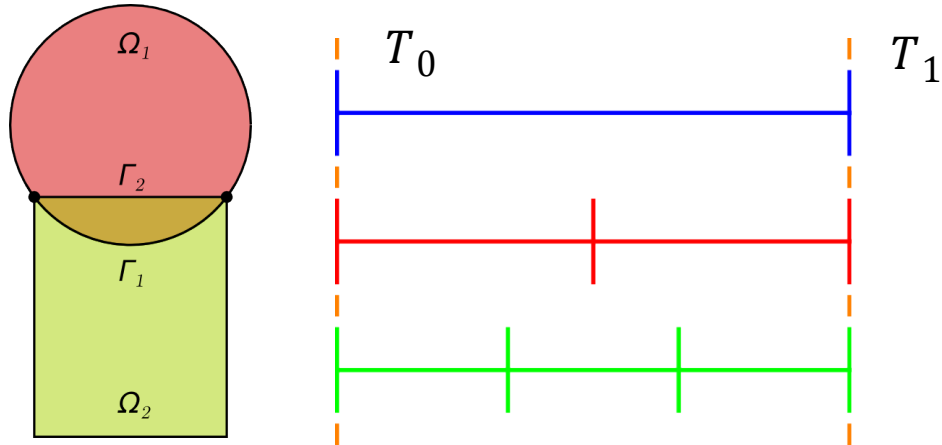
$$\begin{cases} \mathcal{L}u_2^{n+1} = f, & \text{in } \Omega_2, \\ u_2^{n+1} = g, & \text{on } \partial\Omega_2 \setminus \Gamma, \\ \frac{\partial u_2^{n+1}}{\partial \mathbf{n}_2} = \frac{\partial u_1^{n+1}}{\partial \mathbf{n}_2}, & \text{on } \Gamma, \end{cases}$$

$$\lambda_{n+1} = \theta u_2^n + (1 - \theta) \lambda_n, \text{ on } \Gamma, \text{ for } n \geq 1.$$



- Relevant for multi-material and multi-physics coupling
- Alternating Dirichlet-Neumann transmission BCs [Zanolli *et al.*, 1987]
- Robin-Robin transmission BCs also lead to convergence [Lions, 1990]
- $\theta \in [0,1]$: relaxation parameter (can help convergence)

Time-Advancement Within the Schwarz Framework



Controller time stepper

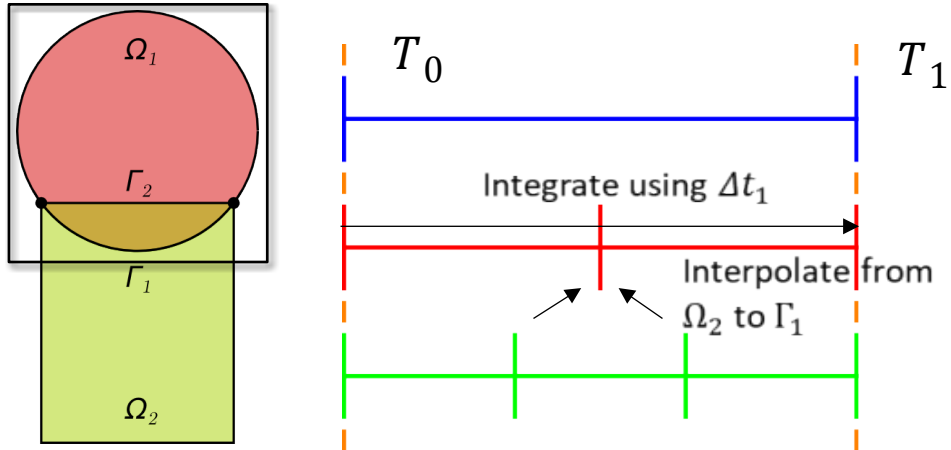
Time integrator for Ω_1

Time integrator for Ω_2

Step 0: Initialize $i = 0$ (controller time index).

$$\text{Model PDE: } \begin{cases} \dot{u} = f - \mathcal{L}u, & \text{in } \Omega, \\ u(x, t) = g(t), & \text{on } \partial\Omega, \\ u(x, 0) = u_0, & \text{in } \Omega \end{cases}$$

Time-Advancement Within the Schwarz Framework



Controller time stepper

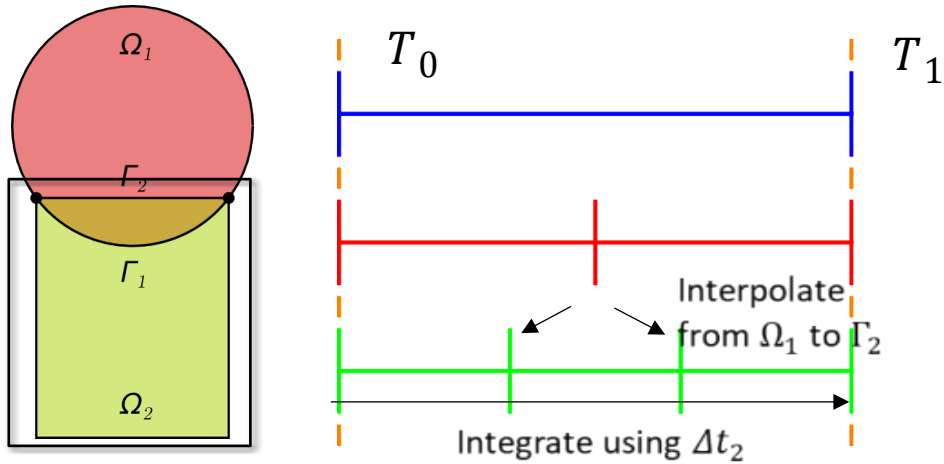
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Controller time stepper

Time integrator for Ω_1

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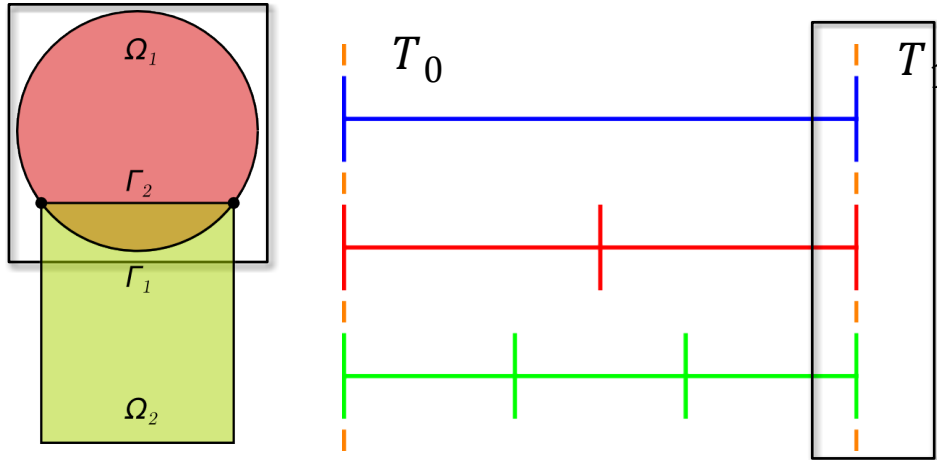
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Step 2: Advance Ω_2 solution from time T_i to time T_{i+1} using time-stepper in Ω_2 with time-step Δt_2 , using solution in Ω_1 interpolated to Γ_2 at times $T_i + n\Delta t_2$.

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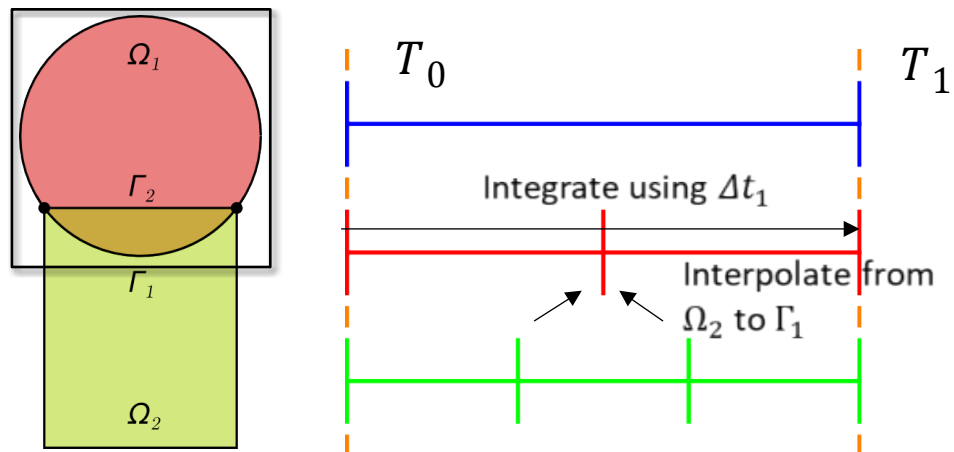
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Step 3: Check for convergence at time T_{i+1} .

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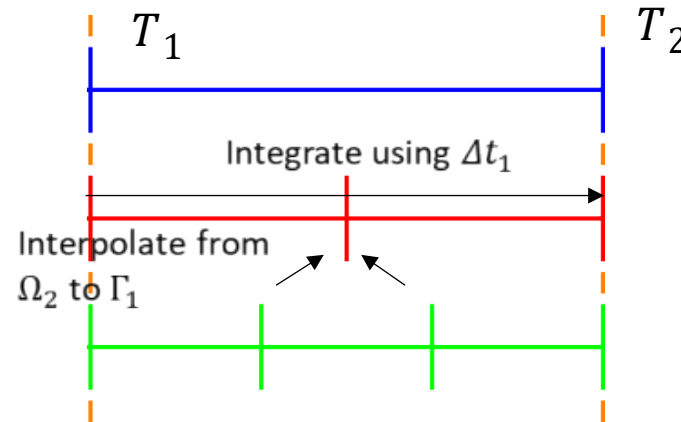
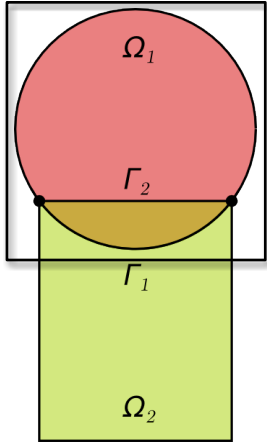
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Step 3: Check for convergence at time T_{i+1} .

➤ If unconverged, return to Step 1.

$$\text{Model PDE: } \begin{cases} \dot{u} = f - \mathcal{L}u, & \text{in } \Omega, \\ u(x, t) = g(t), & \text{on } \partial\Omega, \\ u(x, 0) = u_0, & \text{in } \Omega \end{cases}$$



Controller time stepper

Time integrator for Ω_1

Time integrator for Ω_2

Can use ***different integrators*** with ***different time steps*** within each domain!

Step 0: Initialize $i = 0$ (controller time index).

Step 1: Advance Ω_1 solution from time T_i to time T_{i+1} using time-stepper in Ω_1 with time-step Δt_1 , using solution in Ω_2 interpolated to Γ_1 at times $T_i + n\Delta t_1$.

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Step 3: Check for convergence at time T_{i+1} .

- If unconverged, return to Step 1.
- If converged, set $i = i + 1$ and return to Step 1.

$$\text{Model PDE: } \begin{cases} \dot{u} = f - \mathcal{L}u, & \text{in } \Omega, \\ u(x, t) = g(t), & \text{on } \partial\Omega, \\ u(x, 0) = u_0, & \text{in } \Omega \end{cases}$$

Schwarz for Multi-scale FOM-FOM Coupling in Solid Mechanics

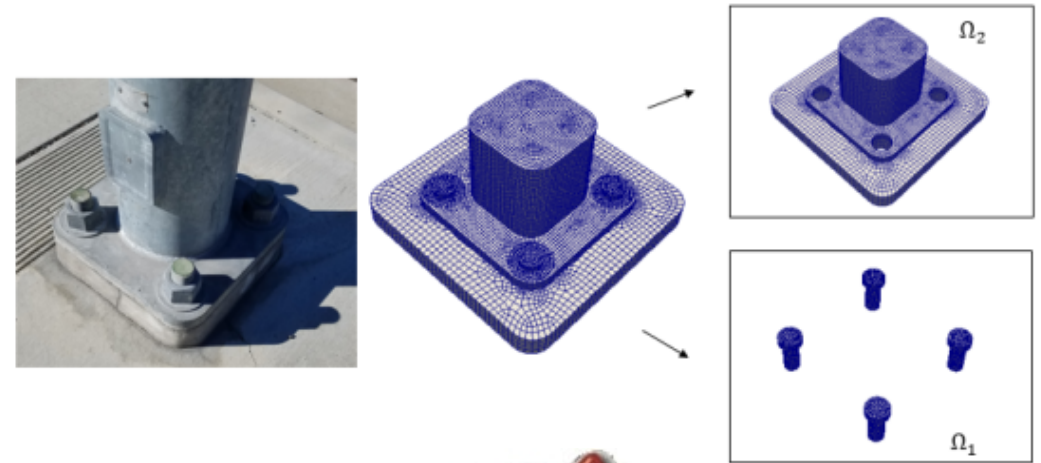


Model Solid Mechanics PDEs:

Quasistatic: $\text{Div } \mathbf{P} + \rho_0 \mathbf{B} = \mathbf{0} \quad \text{in } \Omega$

Dynamic: $\text{Div } \mathbf{P} + \rho_0 \mathbf{B} = \rho_0 \ddot{\boldsymbol{\varphi}} \quad \text{in } \Omega \times I$

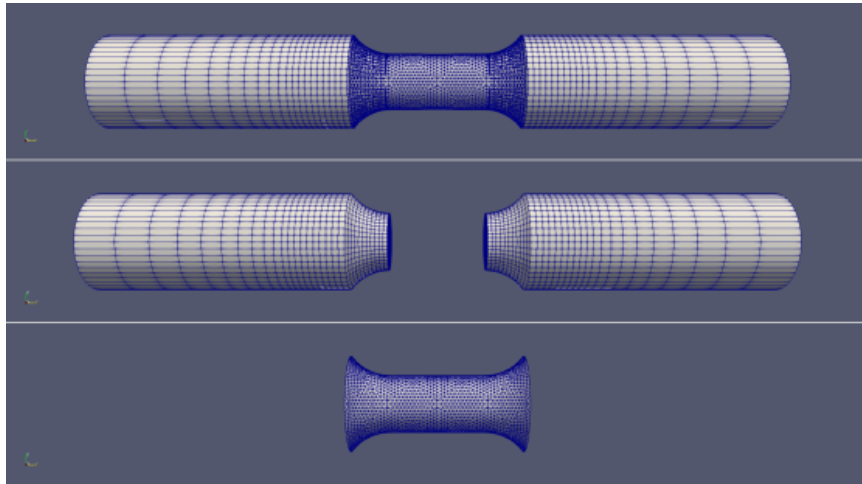
- Coupling is *concurrent* (two-way).
- *Ease of implementation* into existing massively-parallel HPC codes.
- *Scalable, fast, robust* (we target *real* engineering problems, e.g., analyses involving failure of bolted components!).
- Coupling does not introduce *nonphysical artifacts*.
- *Theoretical* convergence properties/guarantees.
- “*Plug-and-play*” framework:
 - Ability to couple regions with *different non-conformal meshes*, *different element types* and *different levels of refinement* to simplify task of *meshing complex geometries*.
 - Ability to use *different solvers/time-integrators* in different regions.



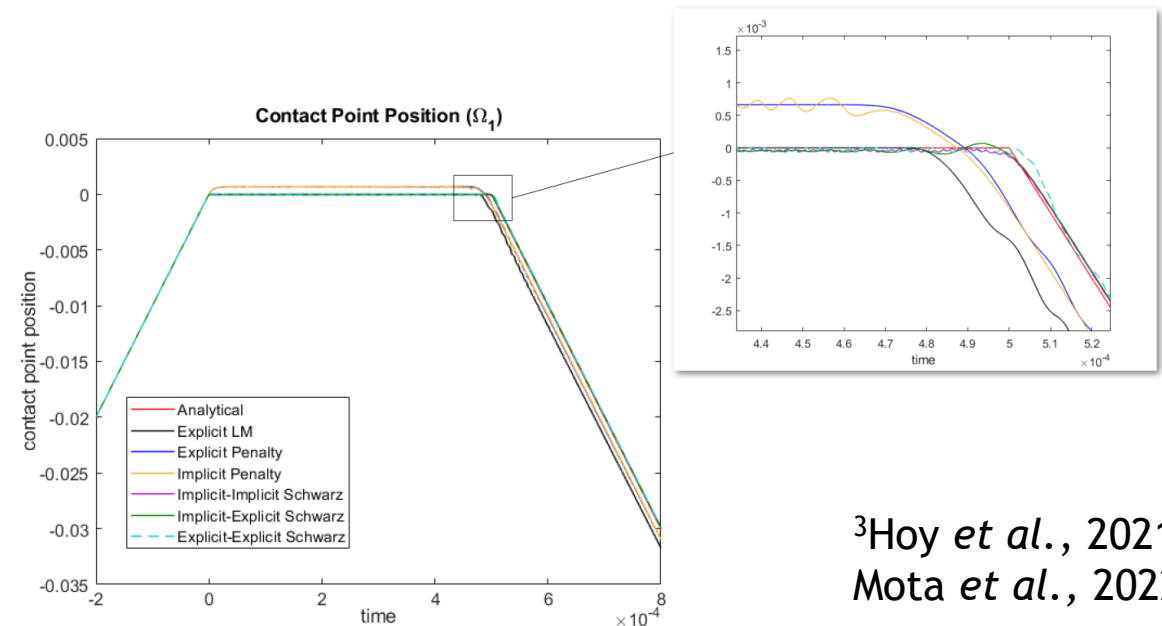
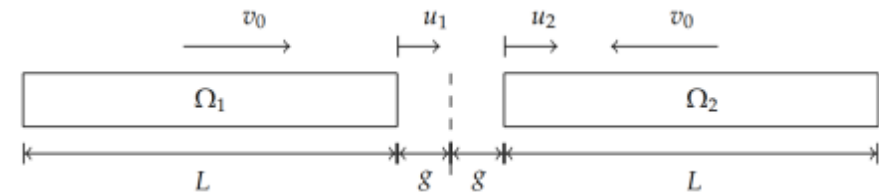
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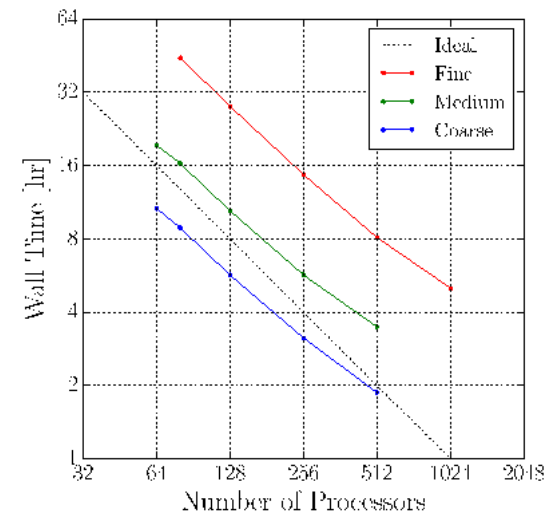
The overlapping Schwarz alternating method has been developed/implemented for concurrent multi-scale quasistatic¹ & dynamic² modeling in Sandia's *Albany*/LCM and *Sierra*/SM codes.



We are currently developing a novel contact method³ based on non-overlapping Schwarz.



³Hoy *et al.*, 2021;
Mota *et al.*, 2022.



	CPU times	# Schwarz iters
Single Ω	3h 34m	—
Schwarz	2h 42m	3.22

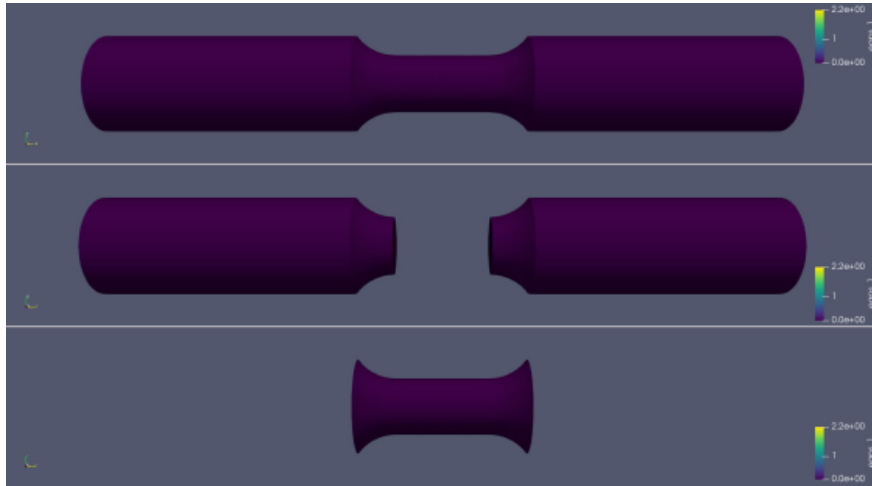


¹Mota *et al.*, 2017. ²Mota *et al.*, 2022.

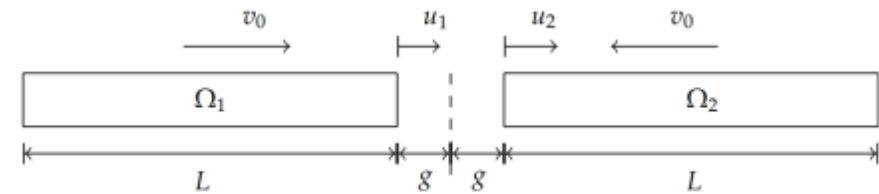
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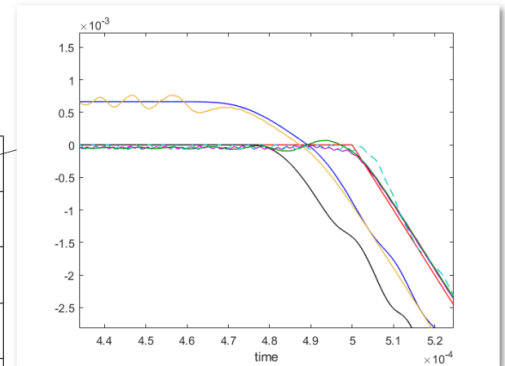
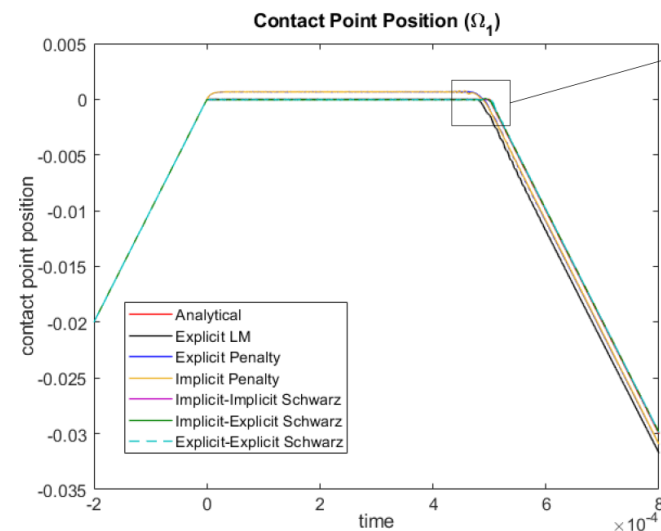
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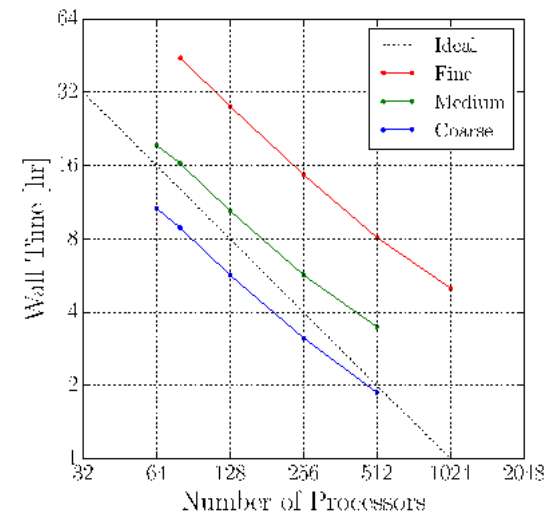
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Talk by A. Mota



³Hoy *et al.*, 2021;
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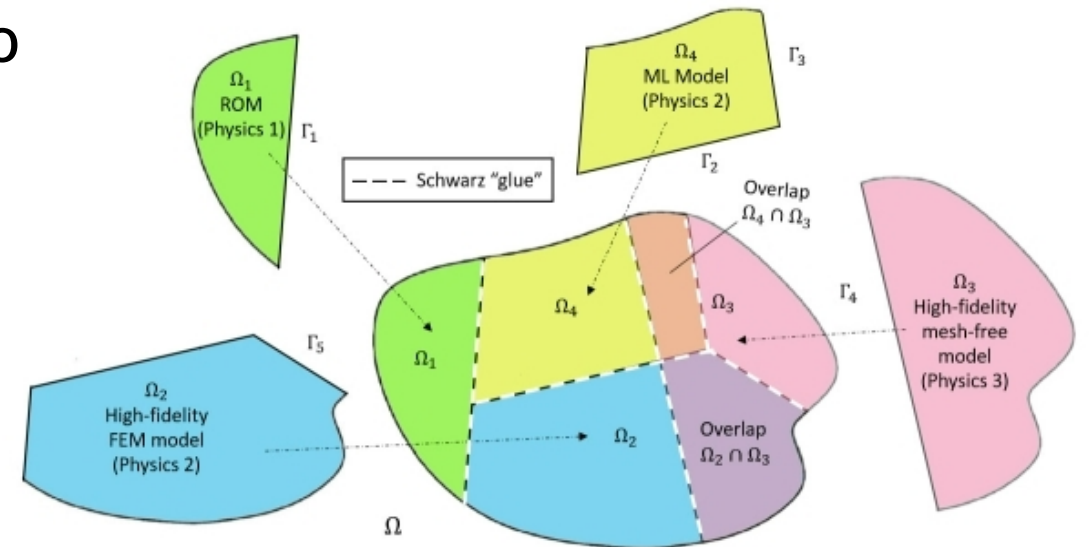
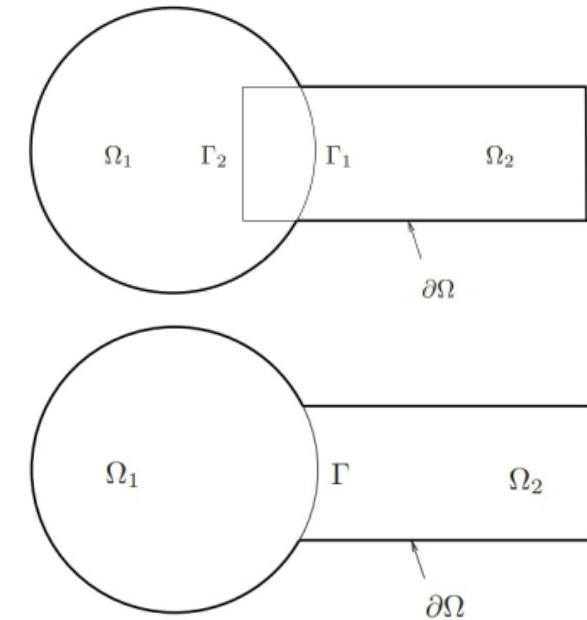
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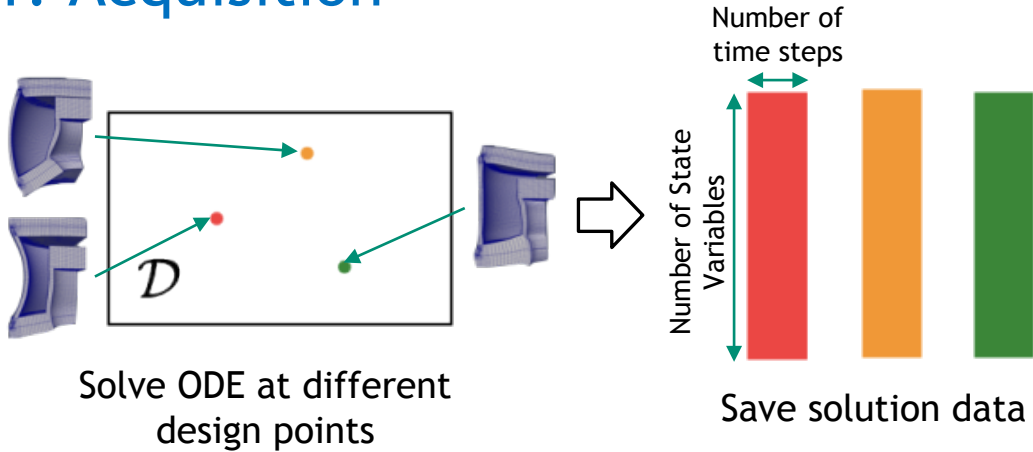
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Projection-Based Model Order Reduction via the POD/Galerkin Method

Full Order Model (FOM): $M \frac{d^2 x}{dt^2} + f_{\text{int}}(x) = f_{\text{ext}}(x)$

1. Acquisition



2. Learning

Proper Orthogonal Decomposition (POD):

$$X = \begin{bmatrix} \text{red} & \text{orange} & \text{green} \end{bmatrix} = \Phi \begin{bmatrix} \text{brown} & \text{blue} \end{bmatrix} \begin{matrix} \Sigma \\ \text{v}^T \end{matrix}$$

3. Projection-Based Reduction

Reduce the number of unknowns

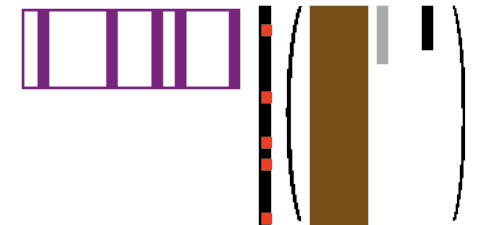
$$x(t) \approx \tilde{x}(t) = \Phi \hat{x}(t)$$

Perform Galerkin projection

$$\Phi^T M \Phi \frac{d^2 \hat{x}}{dt^2} + \Phi^T f_{\text{int}}(\Phi \hat{x}) = \Phi^T f_{\text{ext}}$$

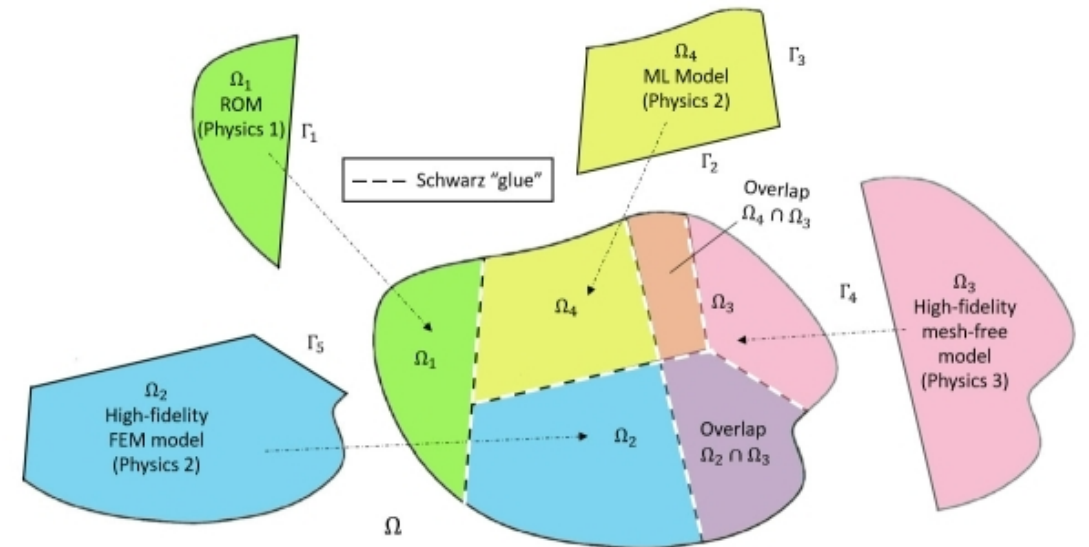
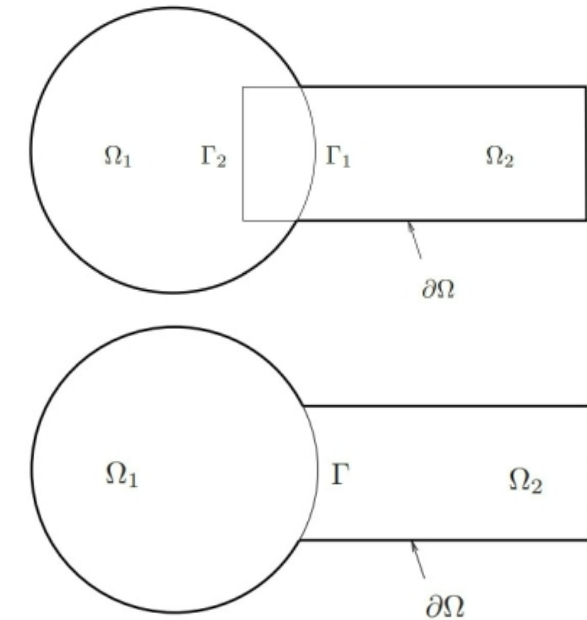
Hyper-reduce nonlinear terms

$$f_{\text{int}}(\Phi \hat{x}) \approx A f_{\text{int}}(\Phi \hat{x})$$



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Schwarz Extensions to ROM-FOM and ROM-ROM Couplings

Enforcement of Dirichlet boundary conditions (DBC) in ROM at indices i_{Dir}

- Method I in [Gunzburger *et al.* 2007] is employed

$$\mathbf{d}(t) = \bar{\mathbf{d}} + \Phi \hat{\mathbf{d}}(t), \quad \mathbf{v}(t) = \bar{\mathbf{v}} + \Phi \hat{\mathbf{v}}(t), \quad \mathbf{a}(t) = \bar{\mathbf{a}} + \Phi \hat{\mathbf{a}}(t)$$

- POD modes made to satisfy homogeneous DBCs: $\Phi(\mathbf{i}_{\text{Dir}}, :) = \mathbf{0}$
- BCs imposed by modifying $\bar{\mathbf{d}}, \bar{\mathbf{v}}, \bar{\mathbf{a}}$: $\bar{\mathbf{d}}(\mathbf{i}_{\text{Dir}}) \leftarrow \chi_d, \bar{\mathbf{v}}(\mathbf{i}_{\text{Dir}}) \leftarrow \chi_v, \bar{\mathbf{a}}(\mathbf{i}_{\text{Dir}}) \leftarrow \chi_a$

Choice of domain decomposition

- Error-based indicators that help decide in what region of the domain a ROM can be viable should drive domain decomposition (future work)

Snapshot collection and reduced basis construction

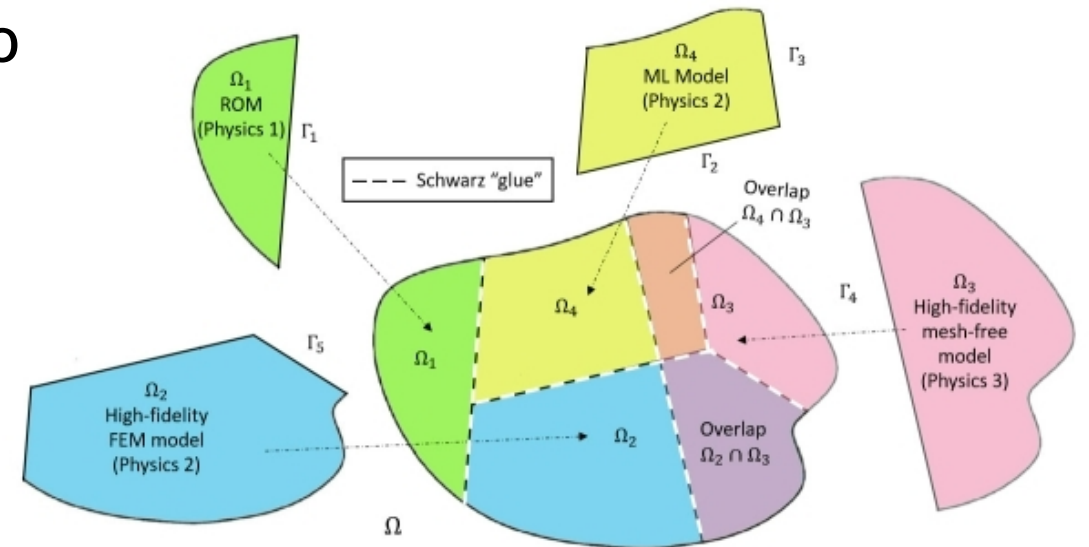
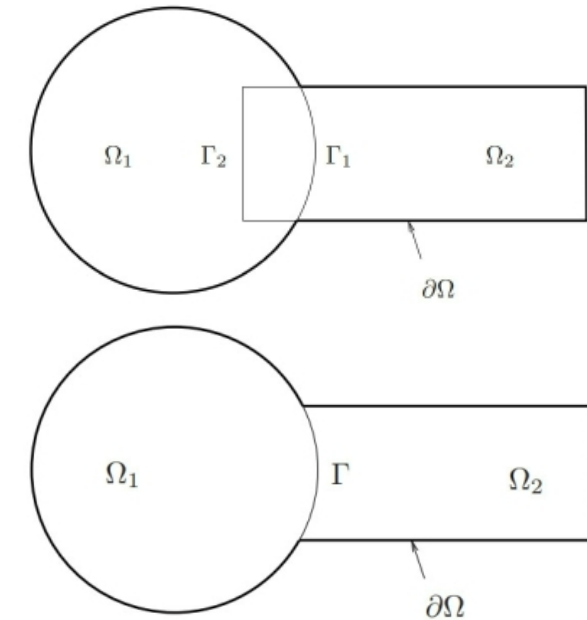
- Ideally, one would generate snapshots/reduced bases separately in each subdomain Ω_i
- POD results presented herein use snapshots obtained via FOM-FOM coupling on $\Omega = \bigcup_i \Omega_i$

*For nonlinear solid mechanics, special hyper-reduction methods need to preserve Hamiltonian structure, e.g., Energy-Conserving Sampling and Weighting Method (ECSW) [Farhat *et al.* 2015]*

- Results here are for linear problem, so hyper-reduction is not required

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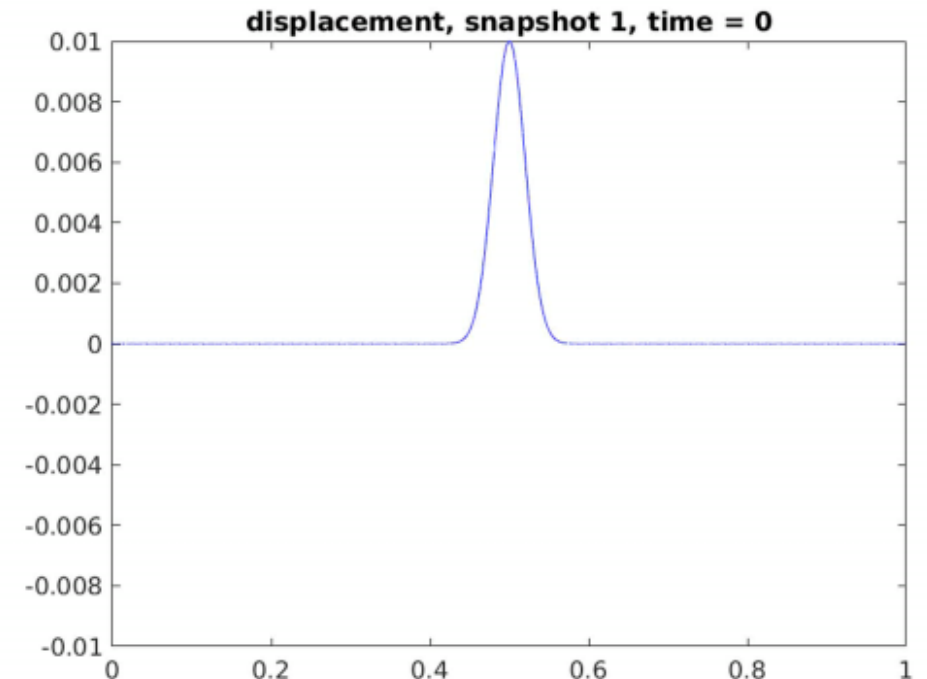


Numerical Example: Linear Elastic Wave Propagation Problem

- Linear elastic **clamped beam** with Gaussian initial condition for the z -displacement.
- Simple problem with analytical exact solution but very **stringent test** for discretization methods.
- **Couplings tested:** FOM-FOM, FOM-ROM, ROM-ROM, implicit-explicit, implicit-implicit, explicit-explicit.
- ROMs are **reproductive** and based on the **POD/Galerkin** method.
 - 50 POD modes capture $\sim 100\%$ snapshot energy



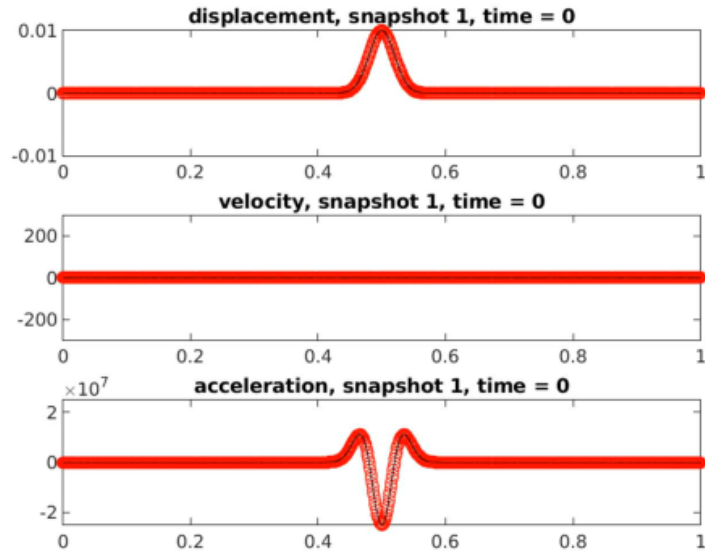
Above: 3D rendering of clamped beam with Gaussian initial condition.
Right: Initial condition (blue) and final solution (red). Wave profile is negative of initial profile at time $T = 1.0e-3$.



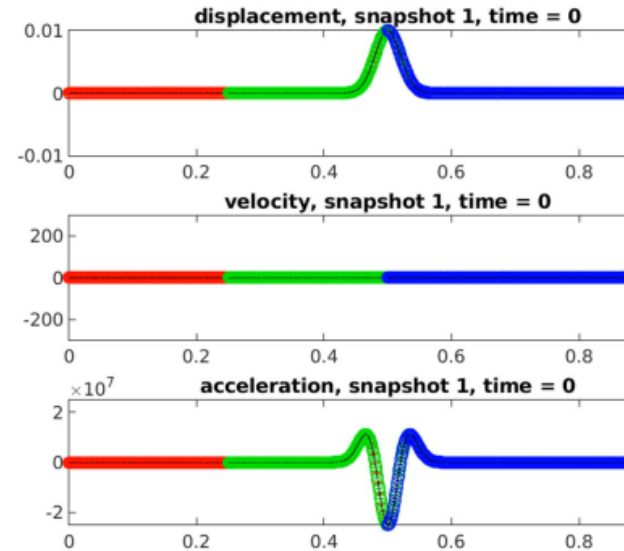
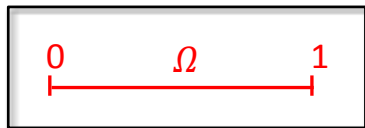
Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



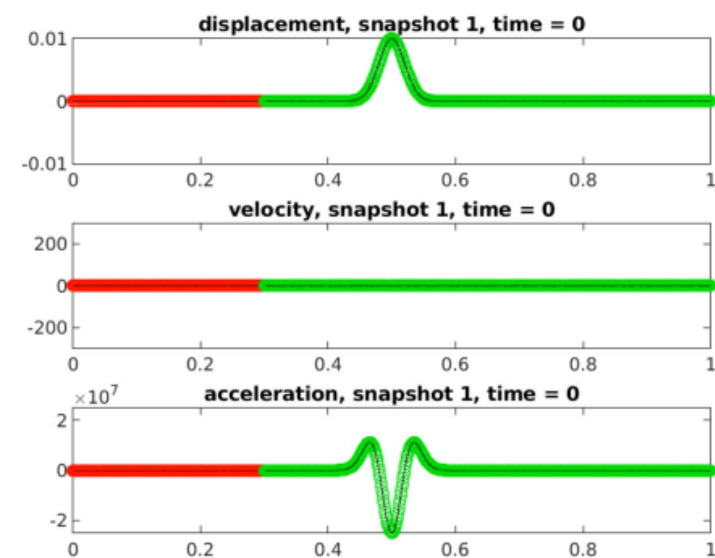
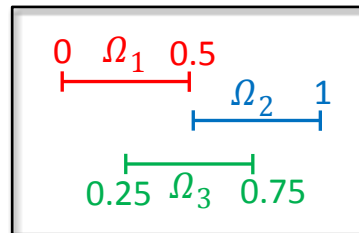
Coupling delivers accurate solution if each subdomain model is reasonably accurate, can couple different discretizations with different Δx , Δt and basis sizes.



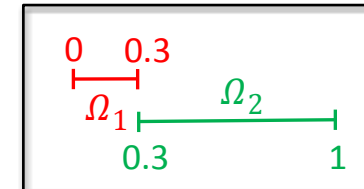
Single Domain FOM



3 overlapping subdomain
ROM¹-FOM²-ROM³



2 non-overlapping subdomain
FOM⁴-ROM⁵ ($\theta = 1$)



¹Implicit 40 mode POD ROM, $\Delta t=1e-6$, $\Delta x=1.25e-3$

²Implicit FOM, $\Delta t=1e-6$, $\Delta x=8.33e-4$

³Explicit 50 mode POD ROM, $\Delta t=1e-7$, $\Delta x=1e-3$

⁵Implicit FOM, $\Delta t=2.25e-7$, $\Delta x=1e-6$

⁴Explicit 50 mode POD ROM, $\Delta t=2.25e-7$, $\Delta x=1e-6$

Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



Coupled models are reasonably accurate w.r.t. FOM-FOM coupled analogs and convergence with respect to basis refinement for ROM-FOM and ROM-ROM coupling is observed.

	disp MSE ⁶	velo MSE	acce MSE
Overlapping ROM ¹ -FOM ² -ROM ³	1.05e-4	1.40e-3	2.32e-2
Non-overlapping FOM ⁴ -ROM ⁵	2.78e-5	2.20e-4	3.30e-3

¹Implicit 40 mode POD ROM, $\Delta t = 1e-6$, $\Delta x = 1.25e-3$

²Implicit FOM, $\Delta t = 1e-6$, $\Delta x = 8.33e-4$

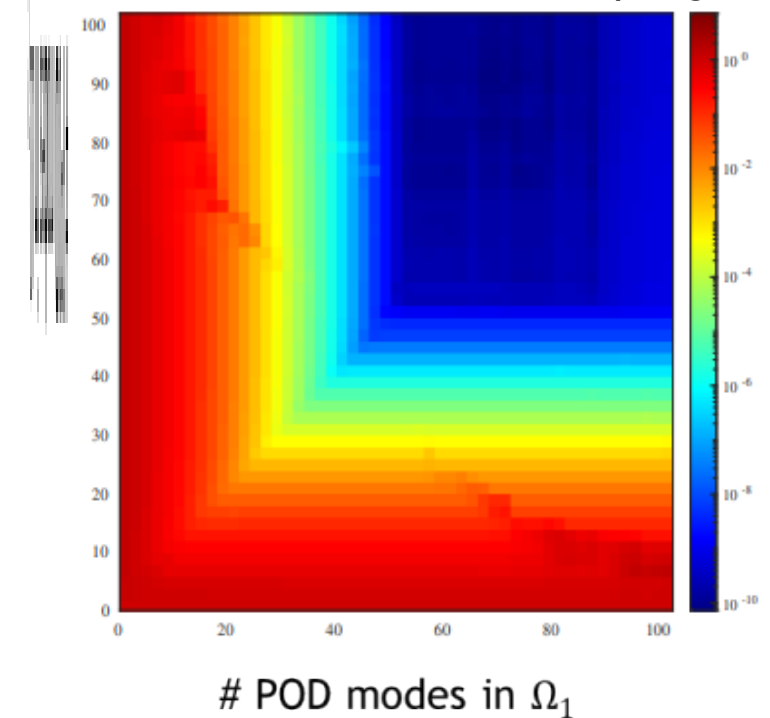
³Explicit 50 mode POD ROM, $\Delta t = 1e-7$, $\Delta x = 1e-3$

⁴Implicit FOM, $\Delta t = 2.25e-7$, $\Delta x = 1e-6$

⁵Explicit 50 mode POD ROM, $\Delta t = 2.25e-7$, $\Delta x = 1e-6$

$$^6\text{MSE} = \text{mean squared error} = \sqrt{\sum_{n=1}^{N_t} \|\tilde{\mathbf{u}}^n(\boldsymbol{\mu}) - \mathbf{u}^n(\boldsymbol{\mu})\|_2^2} / \sqrt{\sum_{n=1}^{N_t} \|\mathbf{u}^n(\boldsymbol{\mu})\|_2^2}.$$

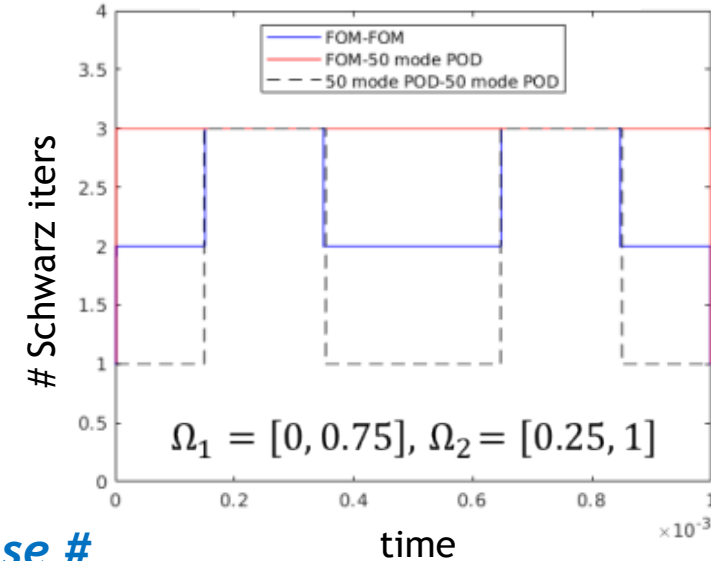
MSE in displacement for 2 subdomain ROM-ROM coupling



Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



	Online CPU time	Total # Schwarz iters
Overlapping FOM ¹ -FOM ² -FOM ³	68.7s	2972
Overlapping ROM ⁴ -FOM ² -ROM ⁵	81.6s	4000
Non-overlapping FOM ⁶ -FOM ⁷	38.0s	10,516
Non-overlapping FOM ⁶ -ROM ⁸	49.8s	13,366



CPU-Time
FOM-FOM:
7.48e1
CPU-Time
FOM-ROM:
1.16e2
CPU-Time
ROM-ROM:
7.16e1

- ¹Implicit FOM, $\Delta t = 1e-6$, $\Delta x = 1.25e-3$
- ²Implicit FOM, $\Delta t = 1e-6$, $\Delta x = 8.33e-4$
- ³Explicit FOM, $\Delta t = 1e-7$, $\Delta x = 1e-3$
- ⁴Implicit 30 mode POD ROM, $\Delta t = 1e-6$, $\Delta x = 1.25e-3$
- ⁵Explicit 50 mode POD ROM, $\Delta t = 1e-7$, $\Delta x = 1e-3$
- ⁶Implicit FOM, $\Delta t = 2.25e-7$, $\Delta x = 1e-6$
- ⁷Explicit FOM, $\Delta t = 2.25e-7$, $\Delta x = 1e-6$
- ⁸Explicit 50 mode POD ROM, $\Delta t = 2.25e-7$, $\Delta x = 1e-6$

ROM-FOM and ROM-ROM couplings often (but not always) increase # Schwarz iterations relative to FOM-FOM coupling.

➤ Key to improving efficiency is reducing # Schwarz iterations.

ROMs with fewer modes do not always give rise to smaller CPU times.

➤ Less accurate models \Rightarrow more Schwarz iterations needed for convergence.

Using smaller time steps can decrease # Schwarz iterations.

WIP: optimizing ROM-FOM and ROM-ROM coupling implementation and devising ways to reduce # Schwarz iterations (e.g., through relaxation parameter θ)

Linear Elastic Wave Propagation Problem: FOM-ROM and ROM-ROM Couplings



Inaccurate model + accurate model \neq accurate model.

Accuracy can be improved by “gluing” several smaller, spatially-local models

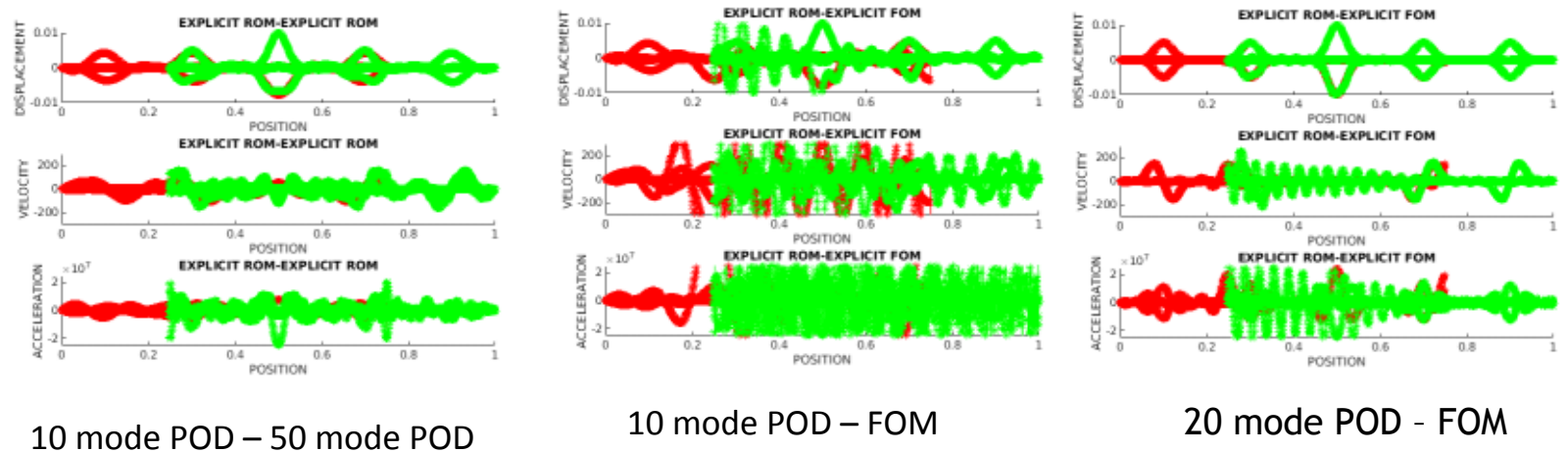
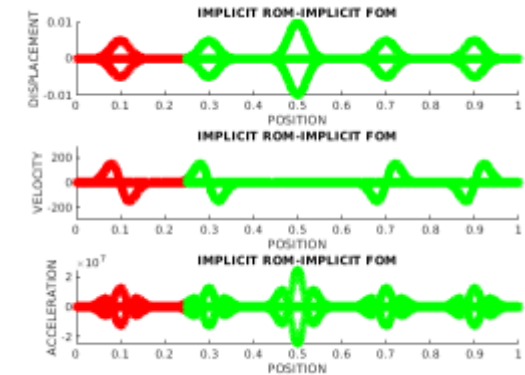
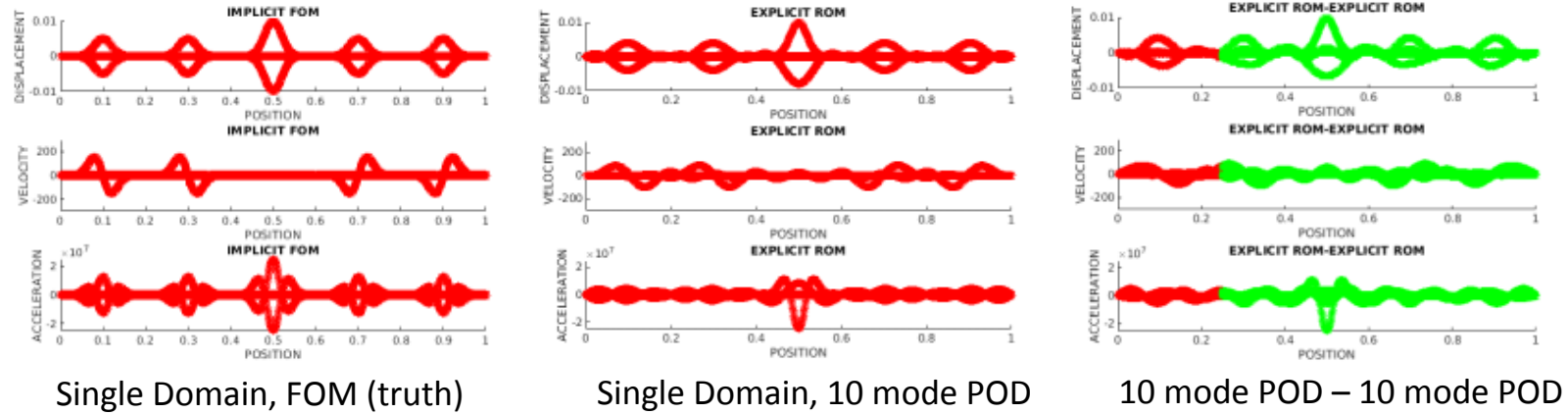
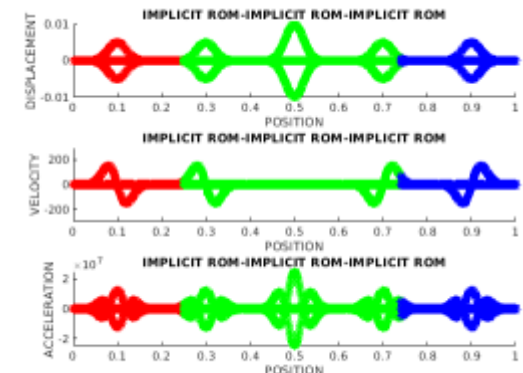


Figure above: $\Omega_1 = [0, 0.3]$, $\Omega_2 = [0.25, 1]$, 20 mode POD - FOM

Figure below: $\Omega_1 = [0, 0.26]$, $\Omega_2 = [0.25, 0.75]$, $\Omega_3 = [0.74, 1]$, 15 mode POD - 30 mode POD - 15 mode POD

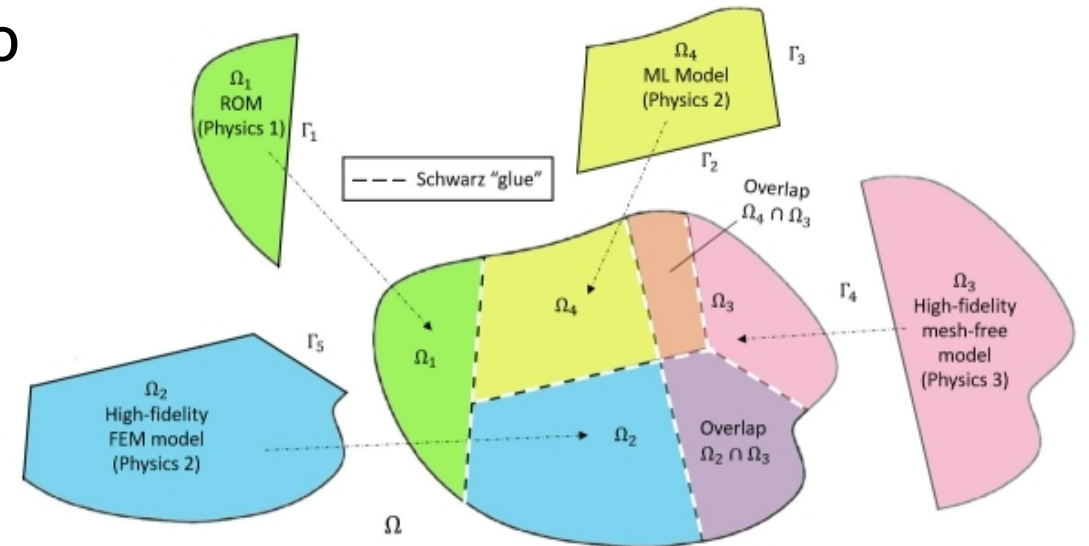
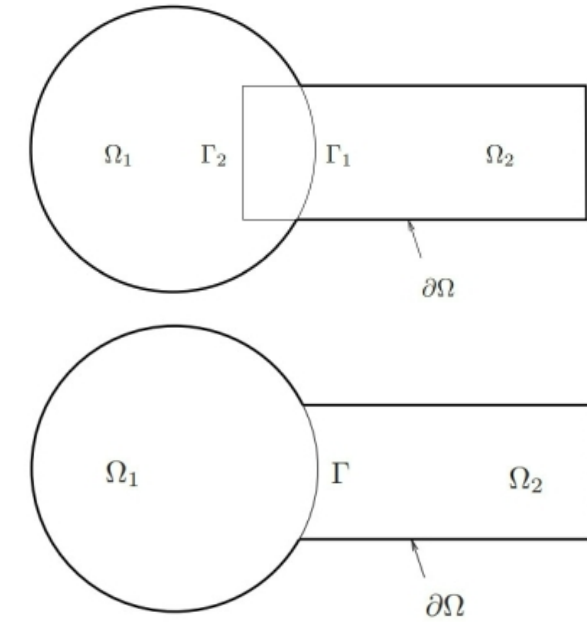


Figures above: $\Omega_1 = [0, 0.75]$, $\Omega_2 = [0.25, 1]$

Observation suggests need for “smart” domain decomposition.

Outline For Remainder of Presentation

1. Overview of the Schwarz Alternating Method for Concurrent Coupling
2. Overview of Projection-Based Model Order Reduction
3. Extension of Schwarz Alternating Method to ROM-FOM and ROM-ROM coupling
4. Numerical Results
5. Summary and Future Work





Summary:

- Initial prototyping suggests that the Schwarz alternating method can be **effective coupling** method that enables coupling of **conventional and data-driven models** (projection-based ROMs).
- The coupling methodology enables the use of **different mesh resolutions, reduced basis sizes, and different time integrators with different time steps** in different subdomains.
- Preliminary results suggest that the **choice of domain decomposition (DD)** is critical to accuracy of the coupled model.

Ongoing/future work:

- Implementation/prototyping of coupling method on **non-linear problems** with ECSW-based hyper-reduction.
- Implementation/prototyping of coupling method in **multi-D**.
- Investigation of methodologies for reducing the number of Schwarz iterations and **improving performance** when performing FOM-ROM and ROM-ROM coupling.
- Development of **error indicators** to guide DD in an error-controlling way, e.g., [Bergmann *et al.* 2018].
- **Analysis** of proposed coupling approach for FOM-ROM and ROM-ROM coupling.
- Development of **snapshot collection approaches** that do not require full system simulation.
- Extension of the coupling framework to include **Physics-Informed Neural Networks (PINNs)**.
- Extension of coupling method to **multi-material and multi-physics problems**.



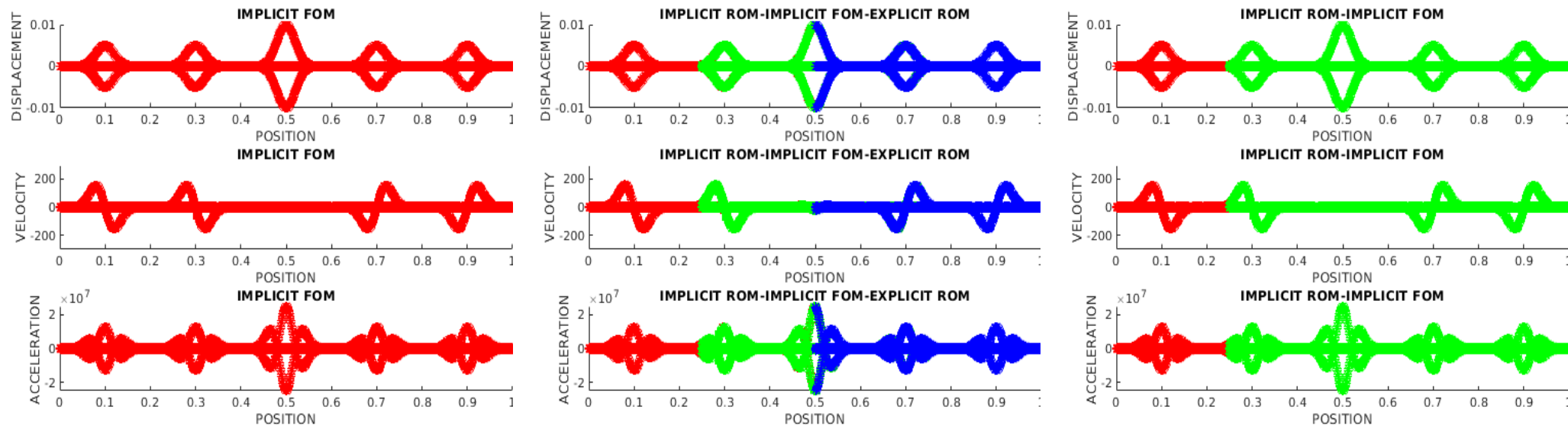
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Start of Backup Slides

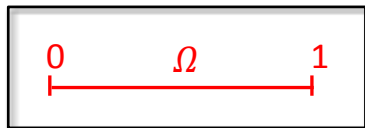
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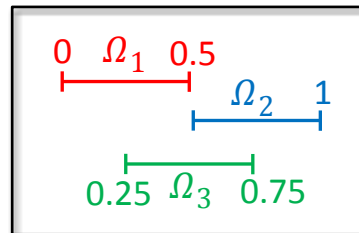
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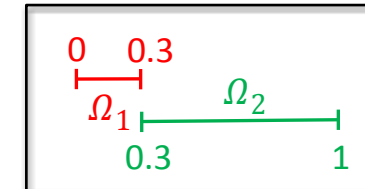
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