

# On Neumann-type Boundary Conditions for Nonlocal Models

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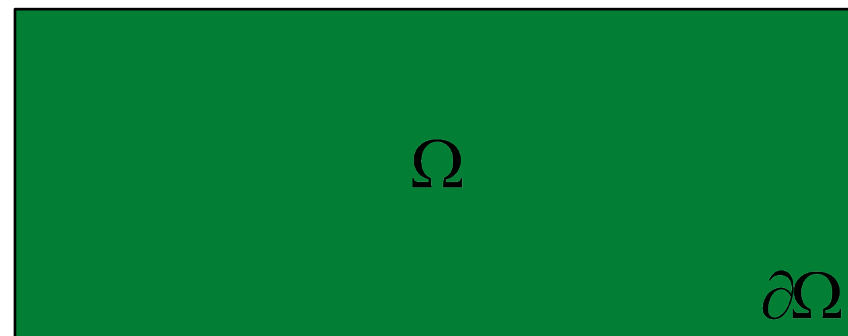
# Local and Nonlocal Models and Boundaries



- Local model (i.e., PDEs)

$$-\nabla^2 u(\mathbf{x}) = f(\mathbf{x}) \quad \mathbf{x} \in \Omega$$

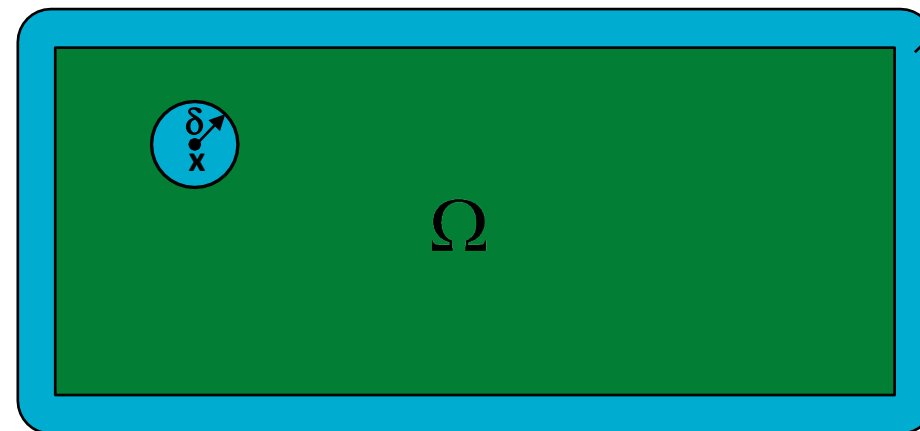
- Apply boundary conditions on boundary of domain (hence the name)



- Nonlocal model (i.e., integral equations)

$$\int_{B(\mathbf{x})} (u(\mathbf{y}) - u(\mathbf{x})) \mu(\mathbf{y}, \mathbf{x}) d\mathbf{y} \quad \text{for } \mathbf{x} \in \Omega$$

- Nonlocal “boundary” is volumetric region, sometimes called “nonlocal boundary”, “collar”, etc.
- Boundary conditions for these models are called “nonlocal boundary conditions”, “volume constraints”, etc.



# Nonlocal Calculus



□ We will utilize the following operators from nonlocal calculus<sup>\*,\*\*</sup>

$$\alpha(\mathbf{x}, \mathbf{y}) : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^k$$

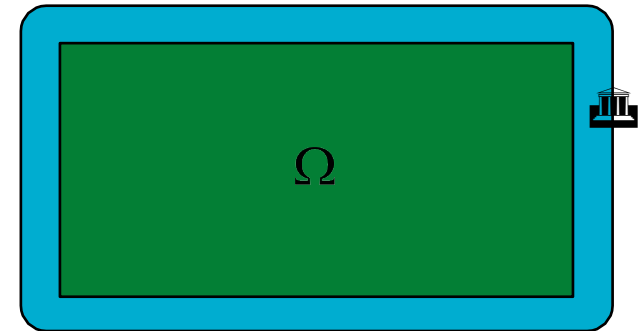
$$\mu(\mathbf{x}, \mathbf{y}) = \alpha(\mathbf{x}, \mathbf{y}) \cdot \alpha(\mathbf{y}, \mathbf{x})$$

□ Nonlocal point divergence

$$D[v](\mathbf{x}) = \int_{\Omega \cup \Gamma} (v(\mathbf{x}, \mathbf{y}) \cdot \alpha(\mathbf{x}, \mathbf{y}) - v(\mathbf{y}, \mathbf{x}) \cdot \alpha(\mathbf{y}, \mathbf{x})) d\mathbf{y} \quad \text{for } \mathbf{x} \in \Omega$$

□ Nonlocal two-point gradient

$$G[u](\mathbf{x}, \mathbf{y}) = (u(\mathbf{y}) - u(\mathbf{x})) \alpha(\mathbf{y}, \mathbf{x}) \quad \text{for } (\mathbf{x}, \mathbf{y}) \in \mathbb{R}^n \times \mathbb{R}^n$$



□ Nonlocal normal operator

$$N[v](\mathbf{x}) = - \int_{\Omega \cup \Gamma} (v(\mathbf{x}, \mathbf{y}) \cdot \alpha(\mathbf{x}, \mathbf{y}) - v(\mathbf{y}, \mathbf{x}) \cdot \alpha(\mathbf{y}, \mathbf{x})) d\mathbf{y} \quad \text{for } \mathbf{x} \in \Gamma$$

□ Nonlocal Laplacian

$$L[u](\mathbf{x}) = D[G[u]](\mathbf{x}) = 2 \int_{\Omega \cup \Gamma} (u(\mathbf{y}) - u(\mathbf{x})) \mu(\mathbf{y}, \mathbf{x}) d\mathbf{y} \quad \text{for } \mathbf{x} \in \Omega$$

\*Q. Du, M. Gunzburger, R. Lehoucq, and K. Zhou, A nonlocal vector calculus, nonlocal volume-constrained problems, and nonlocal balance laws, *Mathematical Models and Methods in Applied Sciences*, 23 (2013), pp. 493-540.

\*\* B. Hinds and P. Radu., Dirichlet's principle and wellposedness of steady state solutions for a nonlocal peridynamics model, *Appl. Math. and Comput.*, 219 (2012), pp. 1411-1419.

# Classical Neumann Boundary Value Problem



- Poisson equation with Neumann boundary conditions is energy minimizer of functional

$$E[u] = \int_{\Omega} \frac{1}{2} |\nabla u|^2 dx - \int_{\Omega} f(x)u(x)dx + \int_{\partial\Omega} g(x)u(x)d\sigma$$



$$\begin{aligned} -\nabla^2 u(x) &= f(x) & \mathbf{x} \in \Omega \\ \nabla u \cdot \mathbf{n} &= g(x) & \mathbf{x} \in \partial\Omega \end{aligned}$$

- Compatibility condition (necessary condition for solution existence):

$$\int_{\partial\Omega} g(x) dx = \int_{\Omega} f(x) dx$$

- Pure Neumann BVP is singular (constant function in kernel)
- Can solve numerically using (for example) Moore-Penrose Pseudoinverse, which gives minimum-norm solution.

# Nonlocal Neumann Boundary Value Problem



□ Many others\* have observed analogous nonlocal energy

$$E[u] = \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} |Gu|^2 dV_x dV_y - \int_{\Omega} u(x) f(x) dV_x + \int_{\Gamma} u(x) g(x) dV_x$$

□ Using differentiation in Hilbert spaces and (nonlocal) integration by parts, compute

$$0 = \frac{d}{dt} E[u + tv] \Big|_{t=0}$$

$$= - \int_{\Omega} [L[u](x) - f(x)] v(x) dV_x - \int_{\Gamma} \left[ \int_{\Omega \cup \Gamma} 2(u(y) - u(x)) \mu(y - x) dV_y - g(x) \right] v(x) dV_x$$

□ Which yields the nonlocal boundary value problem

$$-L[u](x) = - \int_{\Omega \cup \Gamma} [u(y) - u(x)] \mu(y - x) dV_y = f(x), \quad x \in \Omega$$

$$N[Gu](x) = 2 \int_{\Omega \cup \Gamma} [u(y) - u(x)] \mu(y - x) dV_y = g(x), \quad x \in \Gamma$$

□ We desire this system to converge to its local counterpart for consistency with classical physics.

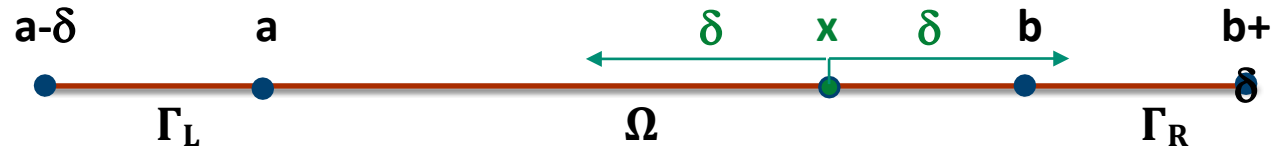
# Convergence of Nonlocal Laplacian



- Given an appropriate kernel  $\mu$ , convergence has been oft-demonstrated

$$\lim_{\delta \rightarrow 0} L[u](x) = \nabla^2 u(x) \quad \text{for } x \in \Omega$$

- Define 1D model



- Assume  $\mu = 3 / \delta^3$ ; Compute Taylor series:

$$\frac{3}{\delta^3} \int_{x-\delta}^{x+\delta} [u(y) - u(x)] dy = u''(x) + \frac{\delta^2}{20} u^{(4)}(x) + K \quad \text{for } x \in \Omega$$

- Domain of integration for all points  $x \in \Omega$  is symmetric. Odd derivatives cancel.

- Moreover,

$$\|L[u](x) - \nabla^2 u(x)\| = o(\delta^2)$$

# Convergence of Nonlocal Neumann Operator



- Given same kernel  $\mu$ , consider the convergence

$$N [Gu](\mathbf{x}) \rightarrow \frac{\partial u}{\partial n}(\mathbf{a}) = u'(\mathbf{a}) \quad \text{for } \mathbf{x} \in \Gamma_L, \mathbf{x} \rightarrow \mathbf{a}, \delta \rightarrow 0$$

- Define 1D model



- Assume  $\mu = 3 / \delta^3$ ; Compute Taylor series.

- Domain of integration for all points  $x \in \Gamma$  **not** symmetric. Odd derivatives do not cancel.

$$\frac{3}{\delta^3} \int_{a-\delta}^{x+\delta} [u(y) - u(x)] dy = \frac{3}{\delta^3} (a-x)(a-x-2\delta)u'(x) + K \quad \text{for } x \in \Gamma_L$$

$$\approx \frac{1}{\delta} u'(x) + K$$

Coefficient is x-dependent and divergent!

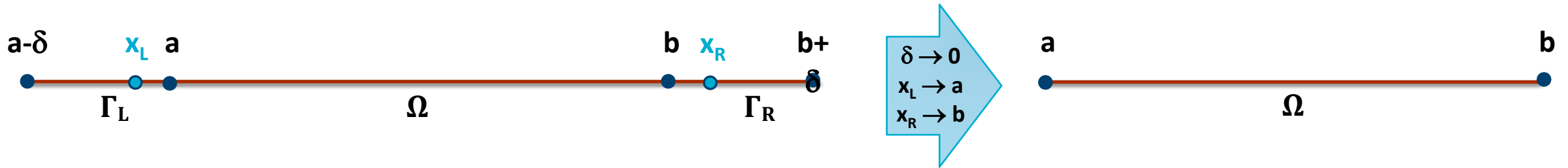
- Why the singularity?

- The kernel  $\mu$  was chosen to ensure nonlocal Laplacian converged to local Laplacian as  $\delta \rightarrow 0$ .
- In general, nonlocal boundary (collar) must be treated differently than bulk for nonlocal models.
- Variational approach scales nonlocal Neumann operator (collar) same as nonlocal Laplacian!**

# A New Type of Convergence



- Convergence of Neumann-type nonlocal operator to its differential equivalent as  $\delta \rightarrow 0$  requires consideration of
  - Nonlocal Neumann operator evaluated at  $u(x)$ ,  $x \in \Gamma$ , where  $x$  varies as  $|\Gamma| \rightarrow 0$
  - Rate at which any individual point  $x \in \Gamma$  approaches  $\partial\Omega$  as  $\delta \rightarrow 0$
  - Operator-point condensed convergence;  $u(x)$  is fixed



- Achieving desired convergence requires  $x$ -dependent scaling  $\sigma(x, \mu)$ .

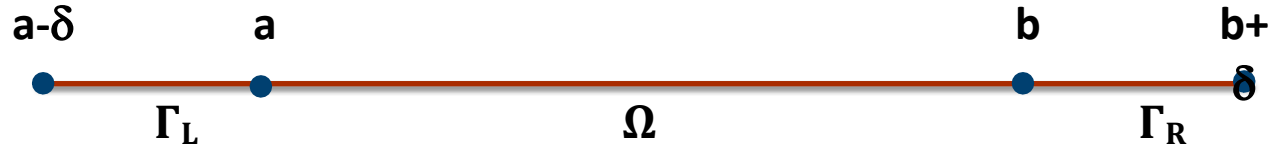
$$\sigma_L(x, \mu)_N [Gu](x) \rightarrow \frac{\partial u}{\partial n}(a) = u'(a) \quad \text{for } x \in \Gamma_L, x \rightarrow a, \delta \rightarrow 0$$

$$\sigma_R(x, \mu)_N [Gu](x) \rightarrow \frac{\partial u}{\partial n}(b) = u'(b) \quad \text{for } x \in \Gamma_R, x \rightarrow b, \delta \rightarrow 0$$

# Nonlocal Neumann Operator Convergence



□ Consider convergence at the left endpoint of a 1D domain ( $\delta \rightarrow 0$ ,  $x \in (a - \delta, a)$ ,  $x \rightarrow a$ ):



□ Taylor series with remainder tells us

$$\sigma(x, \mu) N [Gu](x) = \sigma(x, \mu) u'(x) \int_{a-\delta}^{x+\delta} (y-x) \mu(y-x) dy + \sigma(x, \mu) \int_{a-\delta}^{x+\delta} u''(\xi) \frac{|y-x|^2}{2} \mu(y-x) dy$$

□ from which we conclude

$$\sigma(x, \mu) = \left( \int_{a-\delta}^{x+\delta} (y-x) \mu(y-x) dy \right)^{-1}$$

□ If  $x \rightarrow a$  proportionally to  $\delta$ , then

$$\sigma(x, \mu) N [Gu](x) = u'(x) + O(\delta)$$

□ Asymmetry of integrand results in (at most) 1st order convergence in  $\delta$ .

□ What does this mean for convergence of solutions?

# Solution Convergence & Nonlocal Compatibility Condition



- Correctly scaled and convergent nonlocal Neumann problem:

$$-L[u](x) = - \int_{\Omega \cup \Gamma} [u(y) - u(x)] \mu(y - x) dV_y = f(x), \quad x \in \Omega$$

$$N[Gu](x) = \int_{\Omega \cup \Gamma} [u(y) - u(x)] \mu(y - x) dV_y = \frac{g(x)}{\sigma(x, \mu)}, \quad x \in \Gamma$$

- Theorem: Let  $u_\delta(x)$  and  $u(x)$  be sufficiently smooth solutions to the nonlocal and local Neumann BVPs, respectively. Then there exists  $C > 0$  such that

$$\|u_\delta(x) - u(x)\|_{L_2(\Omega)} \leq C\delta^2$$

- Remark #1: Solution convergence still second order even though operator convergence is first order!
- Remark #2: Neumann operator scaling unnecessary for homogeneous BVP (i.e.,  $g(x) = 0$ ).

# Nonlocal Neumann Boundary Value Problem Revisited



□ What went wrong before?

$$E[u] = \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} |Gu|^2 dV_x dV_y - \int_{\Omega} u(x) f(x) dV_x + \int_{\Gamma} u(x) g(x) dV_x$$

□ Previous nonlocal energy functional scaled incorrectly ...

□ ... but scaling error only manifests for inhomogeneous BVPs!

Goes to zero as  $\delta \rightarrow 0!$

□ Correctly scaled nonlocal energy functional:

$$E[u] = \frac{1}{2} \int_{\Omega \cup \Gamma} \int_{\Omega \cup \Gamma} |Gu|^2 dV_x dV_y - \int_{\Omega} u(x) f(x) dV_x + \int_{\Gamma} u(x) \frac{g(x)}{\sigma(x, \mu)} dV_x$$

□ yields correctly scaled nonlocal boundary value problem

$$-L[u](x) = - \int_{\Omega \cup \Gamma} [u(y) - u(x)] \mu(y - x) dV_y = f(x), \quad x \in \Omega$$

$$N[Gu](x) = 2 \int_{\Omega \cup \Gamma} [u(y) - u(x)] \mu(y - x) dV_y = \frac{g(x)}{\sigma(x, \mu)}, \quad x \in \Gamma$$

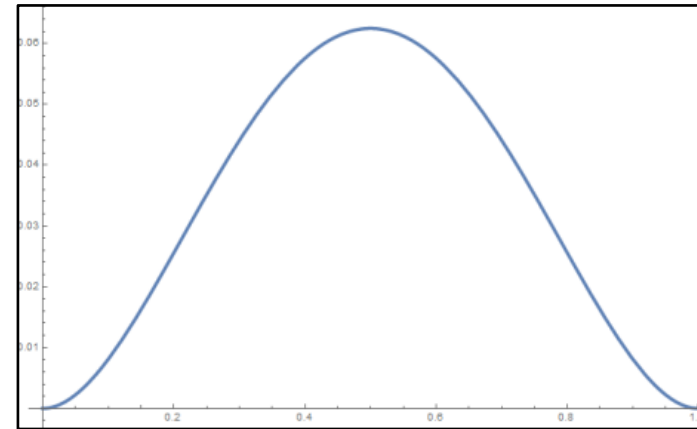
# Nonlocal Neumann BVP: Analytical Example



- What do solutions associated with nonlocal Neumann boundary conditions look like?
  - Given  $u(x)$  for  $x \in \Omega$ , if  $\mu(y-x)$  constant we can solve analytically for  $u(x)$  for  $x \in \Gamma$  (Fredholm Integral Equation of Second Kind)
  - This is not required for numerical solution; We do so here for curiosity

- Let
  - $u(x) = x^2(1-x)^2$ ,  $x \in \Omega = (0,1)$
  - $\delta = 0.1$
  - $N[G u](x) = 0$ ,  $x \in \Gamma$

- Observations:
  - $u(x)$ ,  $x \in \Gamma$ , is smooth except for discontinuity at boundary



$$-\nabla^2 u(x) = f(x), \quad x \in \Omega$$

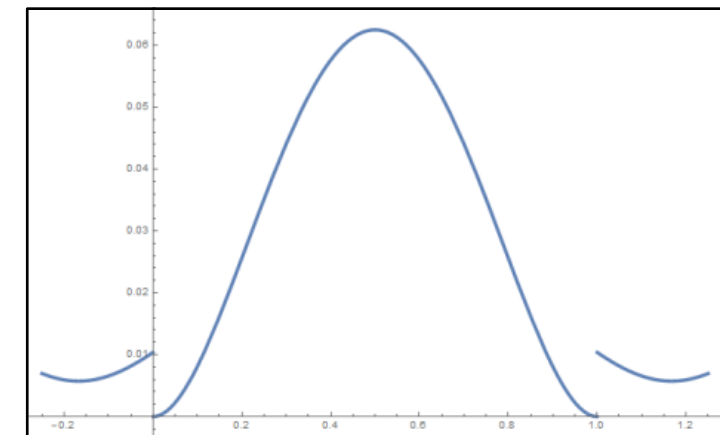
$$\nabla u(x) \cdot n = 0, \quad x \in \Gamma$$

**Local  
Poisson's Equation**

$$-L[u](x) = f(x), \quad x \in \Omega$$

$$N[Gu](x) = 0, \quad x \in \Gamma$$

**Nonlocal  
Poisson's Equation**



# Nonlocal Neumann BVP: Computation



□ Nonlocal Poisson's equation:

$$\begin{aligned}
 -\int_{x-\delta}^{x+\delta} (u(y) - u(x)) \mu(y-x) dy &= f(x) & \mathbf{x} \in \Omega &= (0, 1) \\
 \int_{-\delta}^{x+\delta} (u(y) - u(x)) \mu(y-x) dy &= \frac{g_L(x)}{\sigma_L(x, \mu)} & \mathbf{x} \in \Gamma_L &= (-\delta, 0) \\
 \int_{x-\delta}^{1+\delta} (u(y) - u(x)) \mu(y-x) dy &= \frac{g_R(x)}{\sigma_R(x, \mu)} & \mathbf{x} \in \Gamma_R &= (1, 1 + \delta)
 \end{aligned}$$

□ Consider manufactured solution  $u(x)$

□ Verify  $h$ -convergence

□ Verify  $\delta$ -convergence

□ Issue #1: Asymptotic incompatibility for certain discretizations\*

□ Use piecewise linear discretization

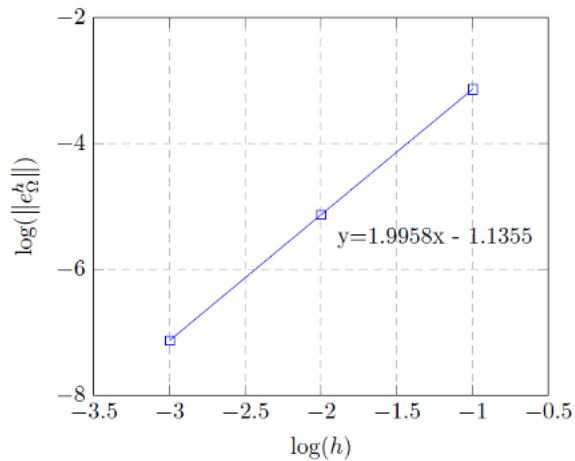
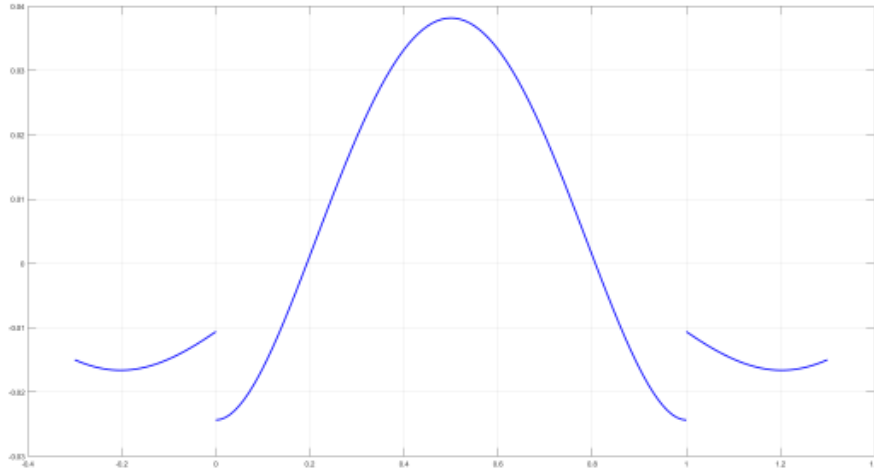
□ Issue #2: Solution may be discontinuous in  $\Omega = (0,1)$ , and definitely has discontinuity at  $x = 0,1$ .

□ Use discontinuous Galerkin discretization

# Example #1: Homogeneous Pure Neumann BVP

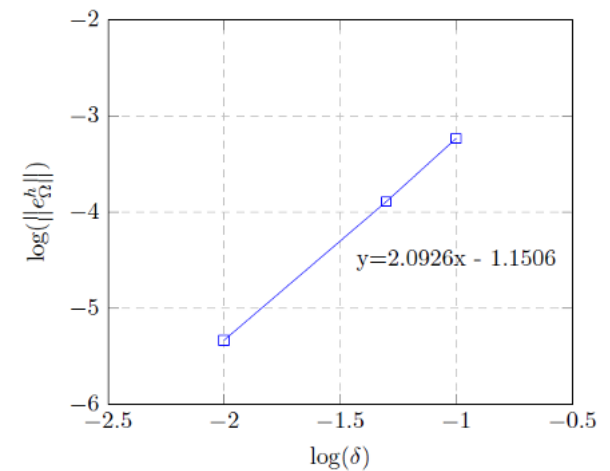


- Assume  $\mu = 3 / \delta^3$ ,  $g_L(x) = g_R(x) = 0$ . Choice of  $\sigma_L(x, \mu)$ ,  $\sigma_R(x, \mu)$  does not matter!
- Let  $u(x) = x^2(1-x)^2 - 1/30$ ,  $x \in \Omega$
- Note that  $u'(0) = u'(1) = 0$ .



Log(error) vs.  $\log(h)$ ,  $\delta = 0.3$

$$\begin{aligned}
 -\mu \int_{x-\delta}^{x+\delta} (u(y) - u(x)) dy &= f(x) & x \in \Omega &= (0, 1) \\
 \mu \int_{-\delta}^{x+\delta} (u(y) - u(x)) dy &= 0 & x \in \Gamma_L &= (-\delta, 0) \\
 \mu \int_{x-\delta}^{1+\delta} (u(y) - u(x)) dy &= 0 & x \in \Gamma_R &= (1, 1+\delta)
 \end{aligned}$$

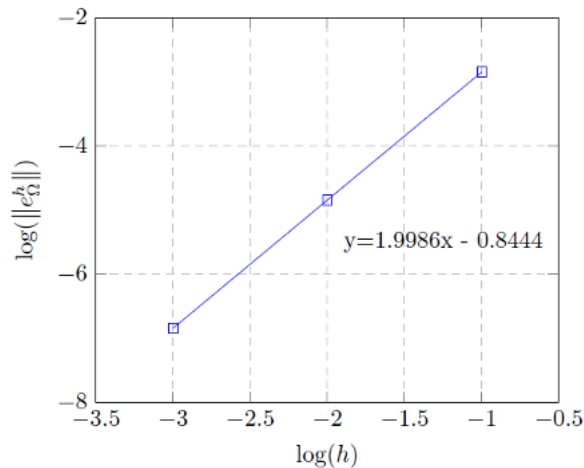
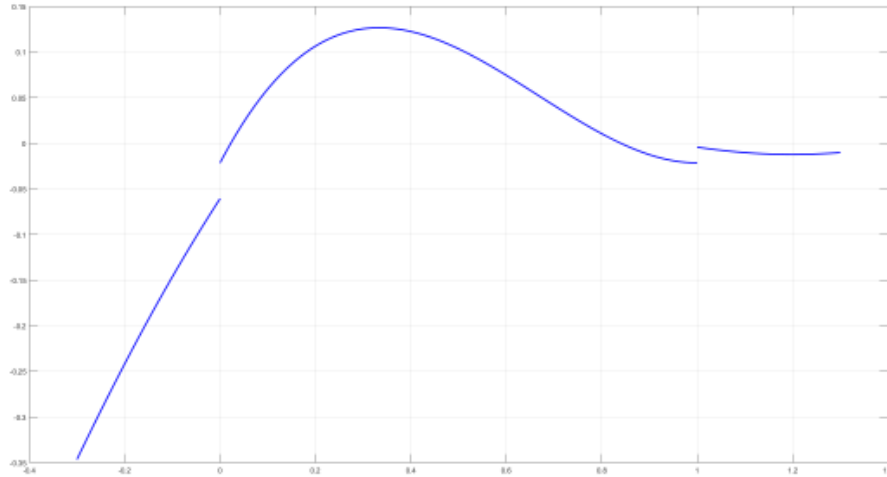


Log(error) vs.  $\log(\delta)$ ,  $h = 0.001$

# Example #2: Inhomogeneous Pure Neumann BVP

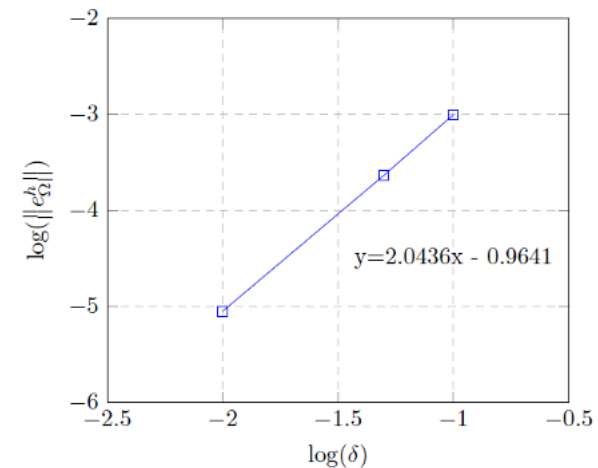


- Assume  $\mu = 3 / \delta^3$ ,  $g_L(x, \mu) = 1$ ;  $g_R(x) = 0$ . Implies  $\sigma_L(x, \mu) = -2\delta^3 / (3x^2 + 6x\delta)$ .
- Let  $u(x) = x(1-x)^2 - 1/12$ ,  $x \in \Omega$
- Note that  $u'(0) = 1$ ;  $u'(1) = 0$ .



Log(error) vs.  $\log(h)$ ,  $\delta = 0.3$

$$\begin{aligned}
 -\mu \int_{x-\delta}^{x+\delta} (u(y) - u(x)) dy &= f(x) & x \in \Omega = (0, 1) \\
 \mu \int_{-\delta}^{x+\delta} (u(y) - u(x)) dy &= \frac{-(3x^2 + 6x\delta)}{2\delta^3} & x \in \Gamma_L = (-\delta, 0) \\
 \mu \int_{x-\delta}^{1+\delta} (u(y) - u(x)) dy &= 0 & x \in \Gamma_R = (1, 1 + \delta)
 \end{aligned}$$

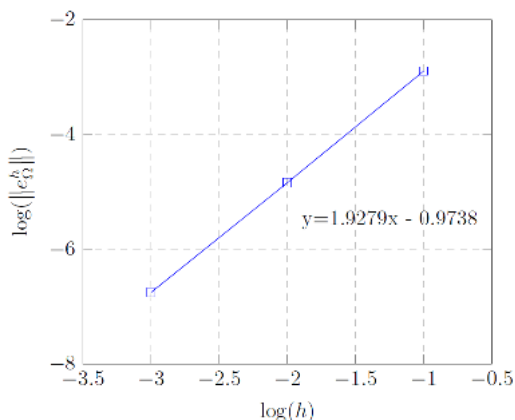
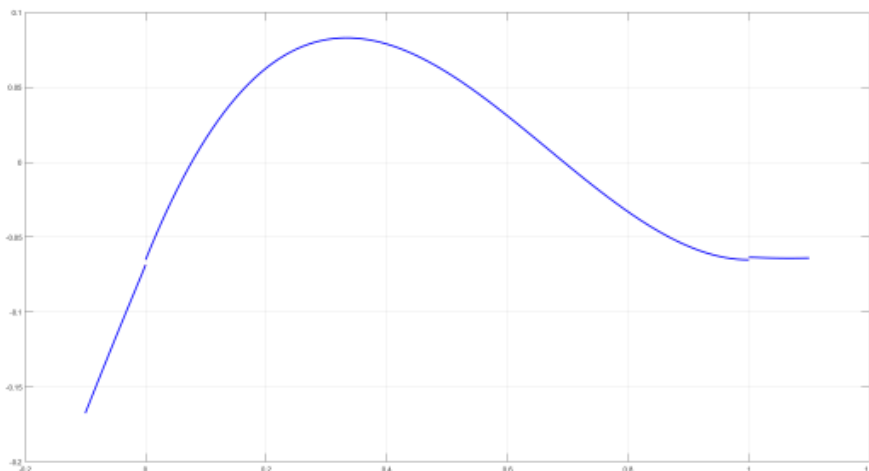


Log(error) vs.  $\log(\delta)$ ,  $h = 0.001$

# Example #3: Inhomogeneous Pure Neumann BVP

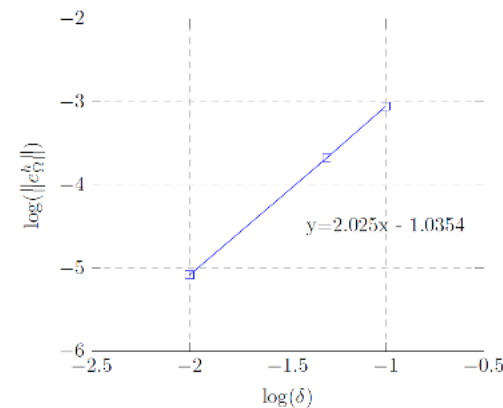


- Assume  $\mu(y-x) = -(s-3) / \delta^{3-s} |x-y|^s$ ;  $g_L(x, \mu) = 0$ ;  $g_R(x) = 0$ . Choice of  $\sigma_L(x, \mu)$ ,  $\sigma_R(x, \mu)$  does not matter!
- Let  $s=1/2$ ; Let  $u(x) = x(1-x)^2 - 1/12$ ,  $x \in \Omega$
- Note that  $u'(0) = 1$ ;  $u'(1) = 0$ .



Log(error) vs.  $\log(h)$ ,  $\delta = 0.3$

$$\begin{aligned}
 - \int_{x-\delta}^{x+\delta} (u(y) - u(x)) \mu(y-x) dy &= f(x) & x \in \Omega &= (0, 1) \\
 \int_{-\delta}^{x+\delta} (u(y) - u(x)) \mu(y-x) dy &= \frac{1}{\sigma_L(x, \mu)} & x \in \Gamma_L &= (-\delta, 0) \\
 \int_{x-\delta}^{1+\delta} (u(y) - u(x)) \mu(y-x) dy &= 0 & x \in \Gamma_R &= (1, 1+\delta)
 \end{aligned}$$



Log(error) vs.  $\log(\delta)$ ,  $h = 0.001$

# Conclusions



- Demonstrated nonlocal Neumann operator consistent with local differential counterpart**
  - Convergence must be considered differently than nonlocal Laplace operator**
  - Results in position-dependent scaling**
  
- Advantages**
  - Consistent with local Neumann boundary condition**
  - Implement and apply as easily as local boundary condition**
  
- Questions?**