



# Numerical Investigation on the Performance of a Variance Deconvolution Estimator



Kayla Clements, Gianluca Geraci, Aaron Olson

2022 ANS Annual Meeting



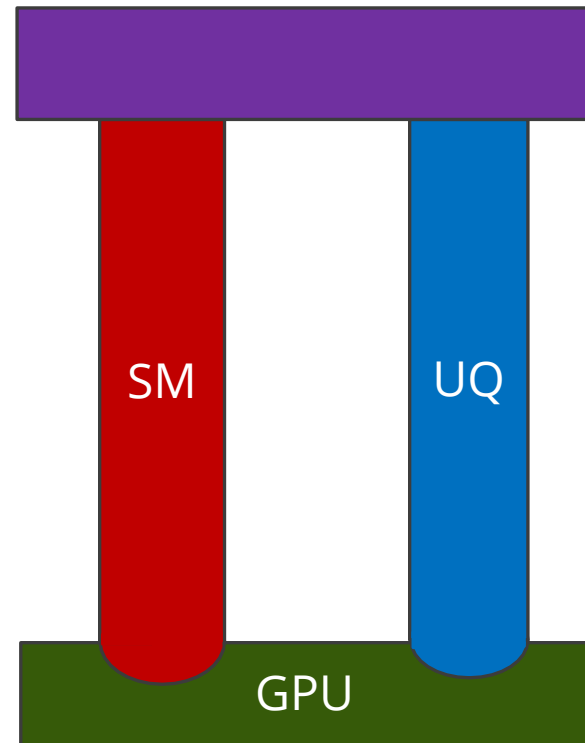
# Motivation – Next-Generation Monte Carlo Project



Develop efficient, embedded **stochastic media (SM)** and **uncertainty quantification (UQ)** Monte Carlo transport methods for the GPU.

SM in Embeddable UQ methods:

- Notation, expressions, adaptations
- Multi-fidelity acceleration



Embeddable UQ Goals:

- Variance deconvolution
- NISP approach to PCE
- Sampling-based GSA method



# Background – Uncertainty Quantification



- Quantity of interest (QoI):  $Q(\xi)$
- $p^{th}$  moment equation
  - $\mathbb{E}[Q^p] = \frac{1}{N} \sum_{i=1}^N Q_i^p$
  - $\text{Var}[Q] = \mathbb{E}[Q^2] - \mathbb{E}[Q]^2$
- Sampling UQ algorithm:
  1. Sample UQ parameter  $\xi$
  2. Solve for QoI  $Q(\xi)$  with existing solver
  3. Repeat for a number of UQ samples
  4. Evaluate statistics, e.g.  $\mathbb{E}[Q]$  and  $\text{Var}[Q]$ , over UQ space

# Background – Monte Carlo Particle Transport



$$\mu \frac{\partial \psi(x, \mu)}{\partial x} + \Sigma_t(x) \psi(x, \mu) = 0$$

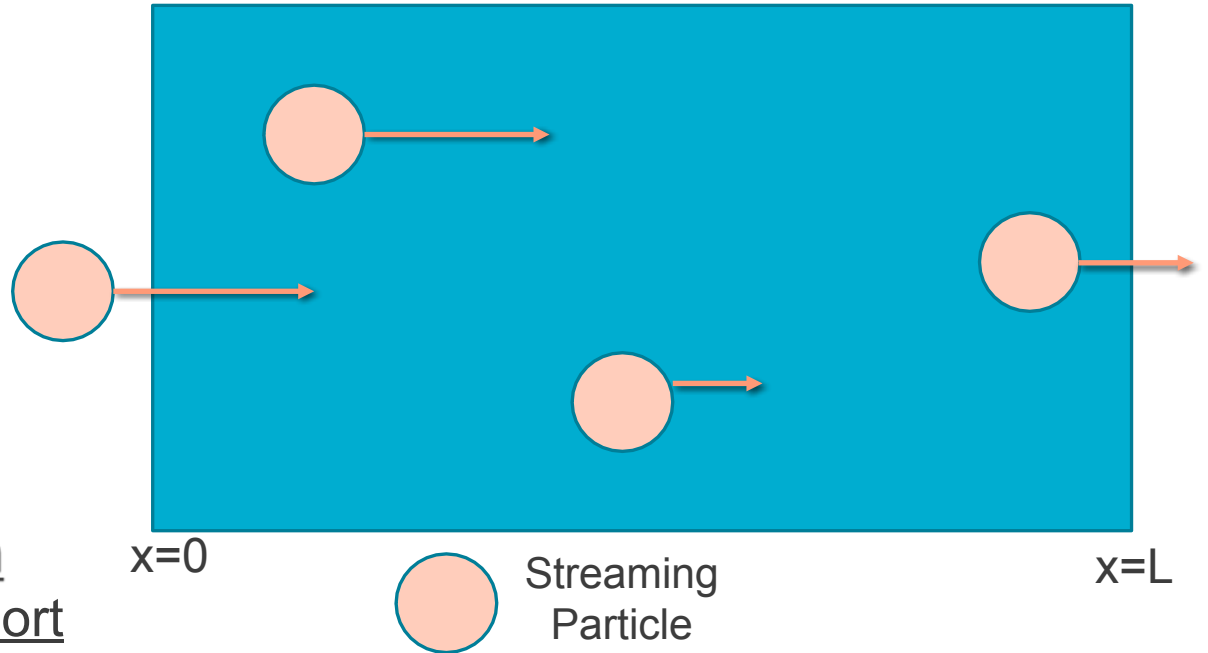
$$0 \leq \mu \leq 1, -1 \leq \mu \leq 1$$

$$\psi(0, \mu) = 1, \mu \geq 0, \quad \psi(L, \mu) = 0, \mu > 0$$

$$\Sigma_t(\xi) = \Sigma_t + \Delta \Sigma_t * \xi, \quad \xi \sim U(-1, 1)$$

## UQ Sampling Algorithm

1. Sample UQ Monte Carlo Transport
2. Initialize particle  $\xi$ :
2. Sample distance to next collision
3. Stream particle – boundary? collision?
4. Continue until particle is either absorbed or exits system
5. Start again with a new particle until all particles have finished
6. Repeat for all histories, then average quantities of interest
4. Perform UQ analysis



# Theory – Estimator Statistics



- Uncertain parameter  $\Sigma_t$

$$\Sigma_t(\xi) = \Sigma_t + \Delta\Sigma_t * \xi, \xi \sim U(-1,1)$$

- Parameter uncertainty  $\xi$  and Monte Carlo solver uncertainty  $\eta$

$$f = f(\xi, \eta)$$

$$T(\xi_i) = \mathbb{E}_\eta[f(\xi_i, \eta)] = \frac{1}{N} \sum_{j=1}^N f(\xi_i, \eta_j) \approx \frac{1}{N_\eta} \sum_{j=1}^{N_\eta} f(\xi_i, \eta_j) = \tilde{T}(\xi_i)$$

- Average code response

$$\mathbb{E}_\xi[T] = \frac{1}{N} \sum_{i=1}^N T_i \approx \frac{1}{N_\xi} \sum_{i=1}^{N_\xi} \tilde{T}(\xi_i)$$

# Theory – Variance Deconvolution I



- Goal:  $\mathbb{V}ar[T(\xi)]$   
$$= \mathbb{V}ar_{\xi}[T(\xi, \eta)] \approx \mathbb{V}ar_{\xi}[\tilde{T}(\xi, \eta)]$$

- Law of total variance

$$\mathbb{V}ar_Y[Z(X, Y)] = \mathbb{V}ar_Y[\mathbb{E}_X[Z]] + \mathbb{E}_Y[\mathbb{V}ar_X[Z]]$$

- Applied to solver response

$$\mathbb{V}ar[\tilde{T}(\xi, \eta)] = \mathbb{V}ar_{\xi} \left[ \mathbb{E}_{\eta}[\tilde{T}(\xi, \eta)] \right] + \mathbb{E}_{\xi} \left[ \mathbb{V}ar_{\eta}[\tilde{T}(\xi, \eta)] \right]$$

$$\mathbb{V}ar[\tilde{T}(\xi, \eta)] = \mathbb{V}ar_{\xi} \left[ \mathbb{E}_{\eta}[\tilde{T}(\xi, \eta)] \right] + \mathbb{E}_{\xi} \left[ \mathbb{V}ar_{\eta}[\tilde{T}(\xi, \eta)] \right]$$

$$\mathbb{V}ar[\tilde{T}(\xi, \eta)] = \mathbb{V}ar_{\xi}[T] + \frac{1}{N_{\eta}} \mathbb{E}_{\xi}[\sigma_{\eta}^2]$$

$$\mathbb{V}ar_{\xi}[T] = \mathbb{V}ar[\tilde{T}(\xi, \eta)] - \frac{1}{N_{\eta}} \mathbb{E}_{\xi}[\sigma_{\eta}^2]$$

Parametric  
variance

Total (polluted)  
variance

Average  
Monte Carlo  
solver variance

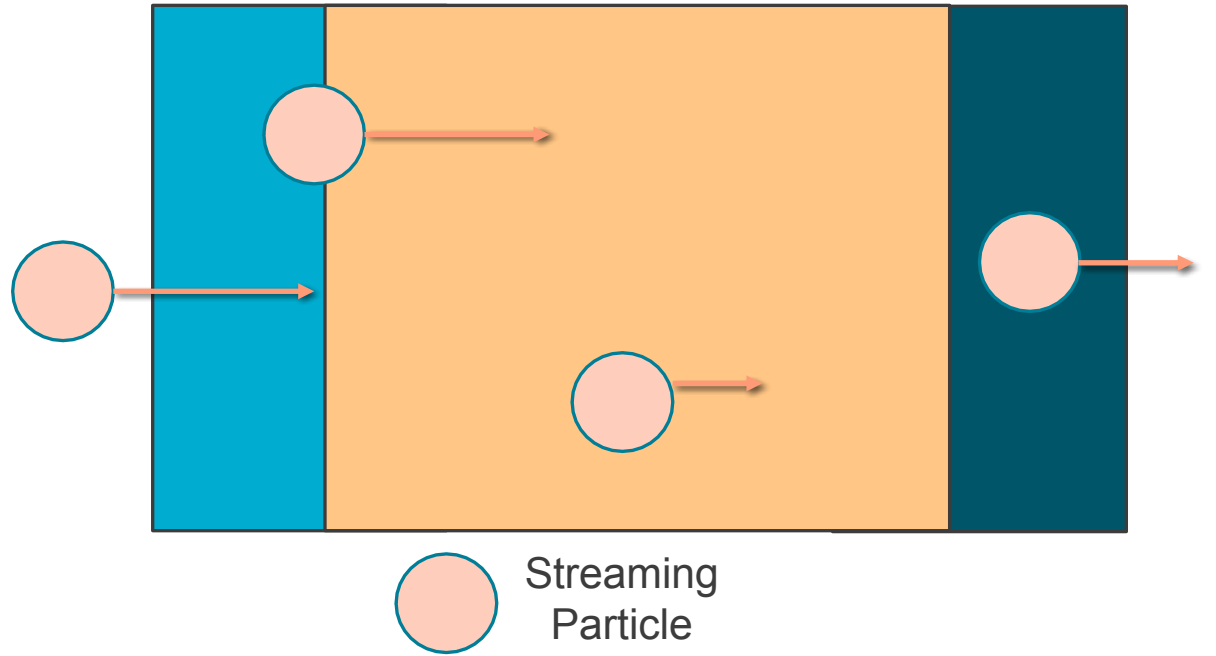
# Example – Problem Description



$$\mu \frac{\partial \psi(x, \mu, \xi)}{\partial x} + \Sigma_t(x, \xi) \psi(x, \mu, \xi) = 0$$

$$0 \leq \mu \leq 1, \quad -1 \leq \xi \leq 1$$

$$\psi(0, \mu) = 1, \mu \geq 0, \quad \psi(L, \mu) = 0, \mu > 0$$



$$\Sigma_t(\xi) = \bar{\Sigma}_t + \Delta \Sigma_t * \xi, \quad \xi \sim U(-1, 1)$$

$$c = \Sigma_s / \Sigma_t(\xi) = \bar{c} + \Delta c * \xi, \quad \xi \sim U(-1, 1)$$

Problem Parameters				Scattering Parameters	
	$x_R$	$\Sigma_{t,m}^0$	$\Sigma_{t,m}^\Delta$	$c_{s,m}^0$	$c_{s,m}^\Delta$
m = 1	2.0	0.90	0.70	0.50	0.40
m = 2	5.0	0.15	0.12	0.50	0.40
m = 3	6.0	0.60	0.50	0.50	0.40

Table I: 1D attenuation problem parameters.



## Example – Solver Algorithm

1. Determine number of realizations  $N_\xi$  and number of histories  $N_\eta$
2. For  $i = 1:N_\xi$ 
  - a) Sample  $\xi$  and calculate  $\Sigma_t(\xi_i)$
  - b) For  $j = 1:N_\eta$ 
    - Run simulation to compute  $f(\xi_i, \eta_j)$
  - c) Calculate  $\tilde{T}(\xi_i) = \frac{1}{N_\eta} \sum_{j=1}^{N_\eta} f(\xi_i, \eta_j)$
  - d) Calculate  $\sigma_\eta^2(\xi^{(i)}) \approx \frac{1}{N_\eta - 1} \sum_{j=1}^{N_\eta} \left( f(\xi^{(i)}, \eta^{(j)}) - \frac{1}{N_\eta} \sum_{s=1}^{N_\eta} \tilde{f}(\xi^{(i)}, \eta^{(s)}) \right)^2$
3. Calculate average of stochastic noise over the whole parameter space:  $\mathbb{E}[\sigma_\eta^2] \approx \frac{1}{N_\xi} \sum_{i=1}^{N_\xi} \sigma_\eta^2(\xi^{(i)})$
4. Calculate sample variance of solutions from Monte Carlo simulations over parameter space:
 
$$\text{Var}_\xi[\tilde{T}(\xi, \eta)] \approx \frac{1}{N_\xi - 1} \sum_{j=1}^{N_\xi} (\tilde{T}(\xi_i) - \tilde{T}_{avg})^2$$
5. Solve for the true variance over the parameter space by removing the average stochastic MC noise from the measured solution variance:

$$\text{Var}_\xi[T] = \text{Var}[\tilde{T}(\xi, \eta)] - \frac{1}{N_\eta} \mathbb{E}_\xi[\sigma_\eta^2]$$

# Results – Attenuation Only



Sampling estimator: $S_T^2 \approx \text{Var}_\xi[T]$			
	Benchmark	Deconvolved	Analytic
$\mathbb{E}[T]$	8.915E-2	8.870E-2	8.378E-2
$S_T^2$	5.789E-3	5.768E-3	5.505E-3

Table II. Mean Qol and parametric variance.

- Benchmark:  $N_\eta = 10^5, N_\xi = 10^3$  ( $C = 10^8$ )
- Variance deconvolution:  $N_\eta = 10^1, N_\xi = 10^3$  ( $C = 10^4$ )

Variance -- 25000 Est. Realiz,  $(N_\xi, N_\eta) = (300, 5)$

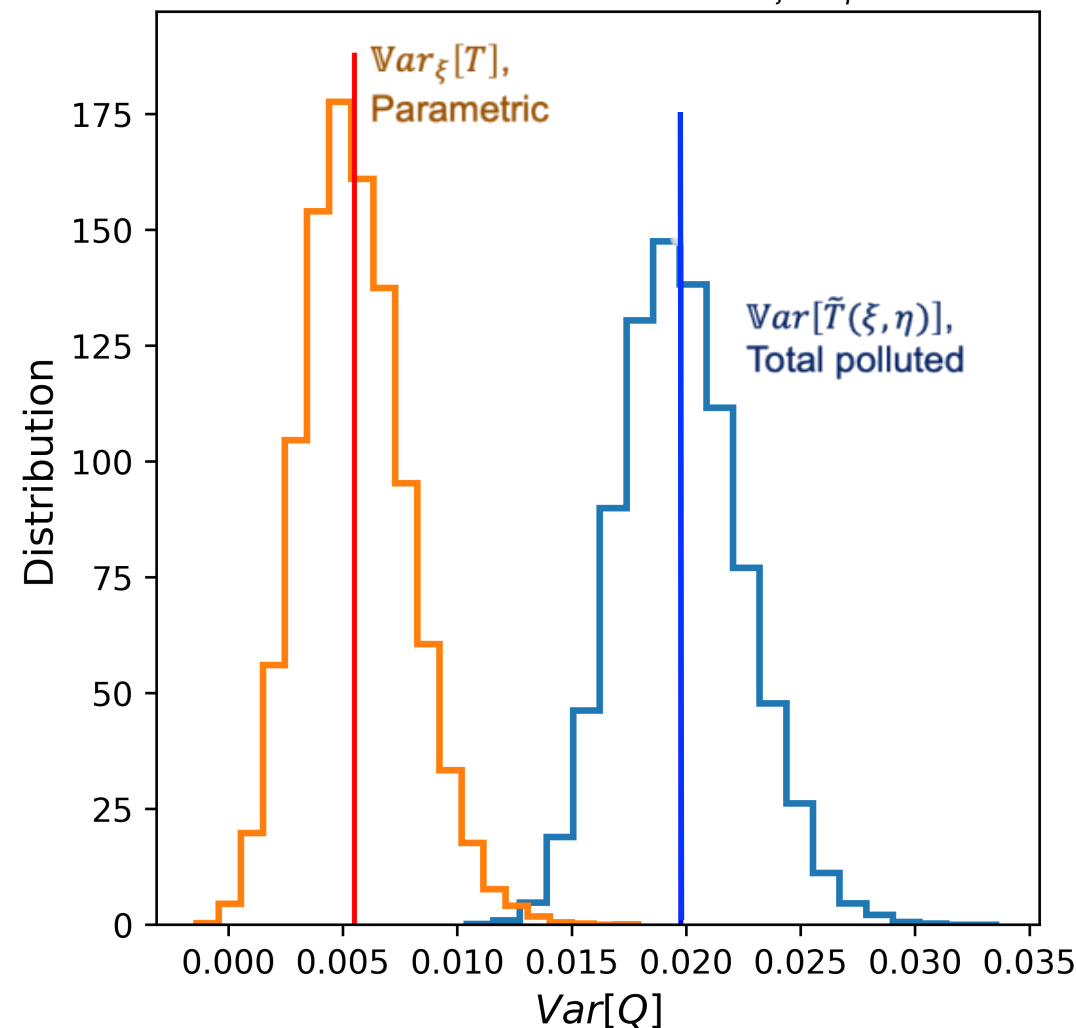


Figure I: 1D radiation transport problem ( $m=3$ ). 25,000 variance deconvolution repetitions.

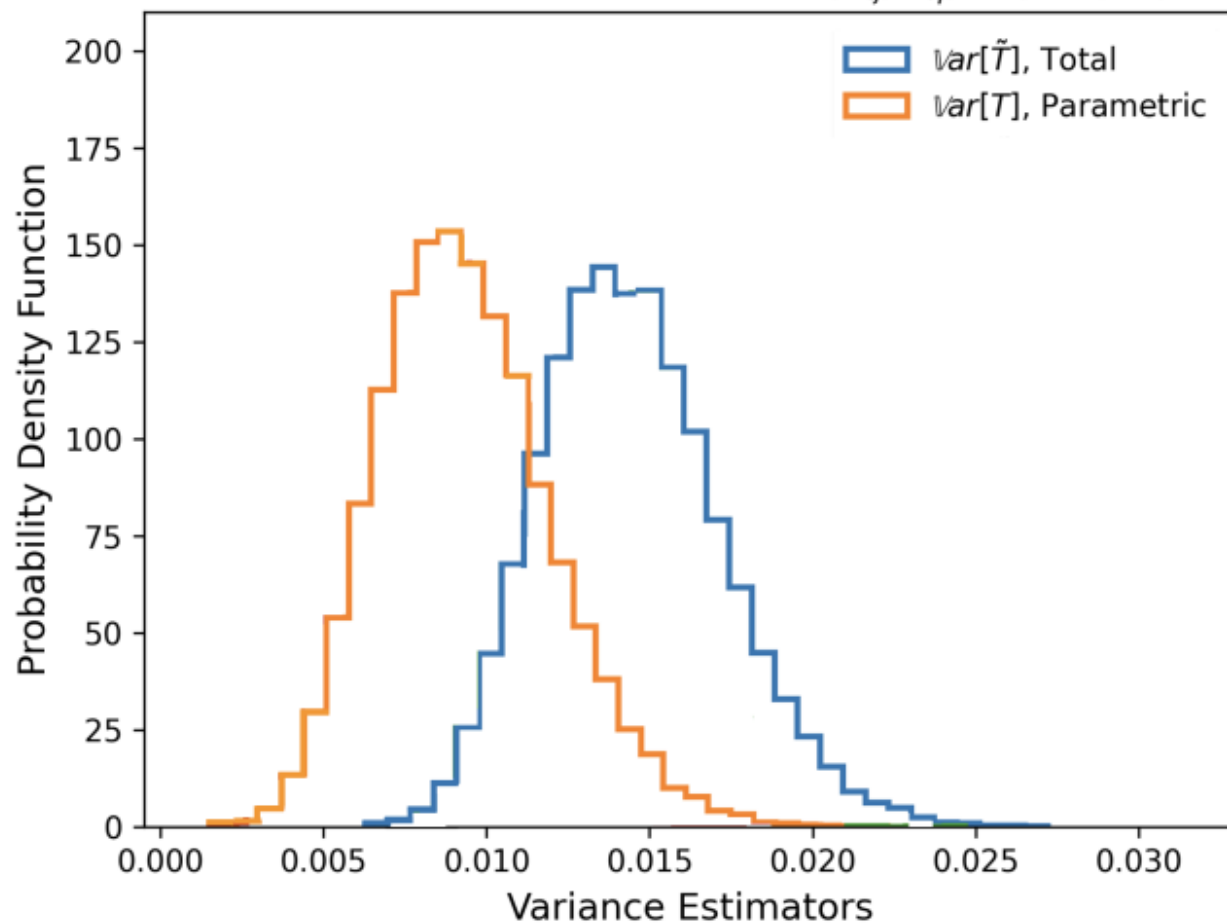
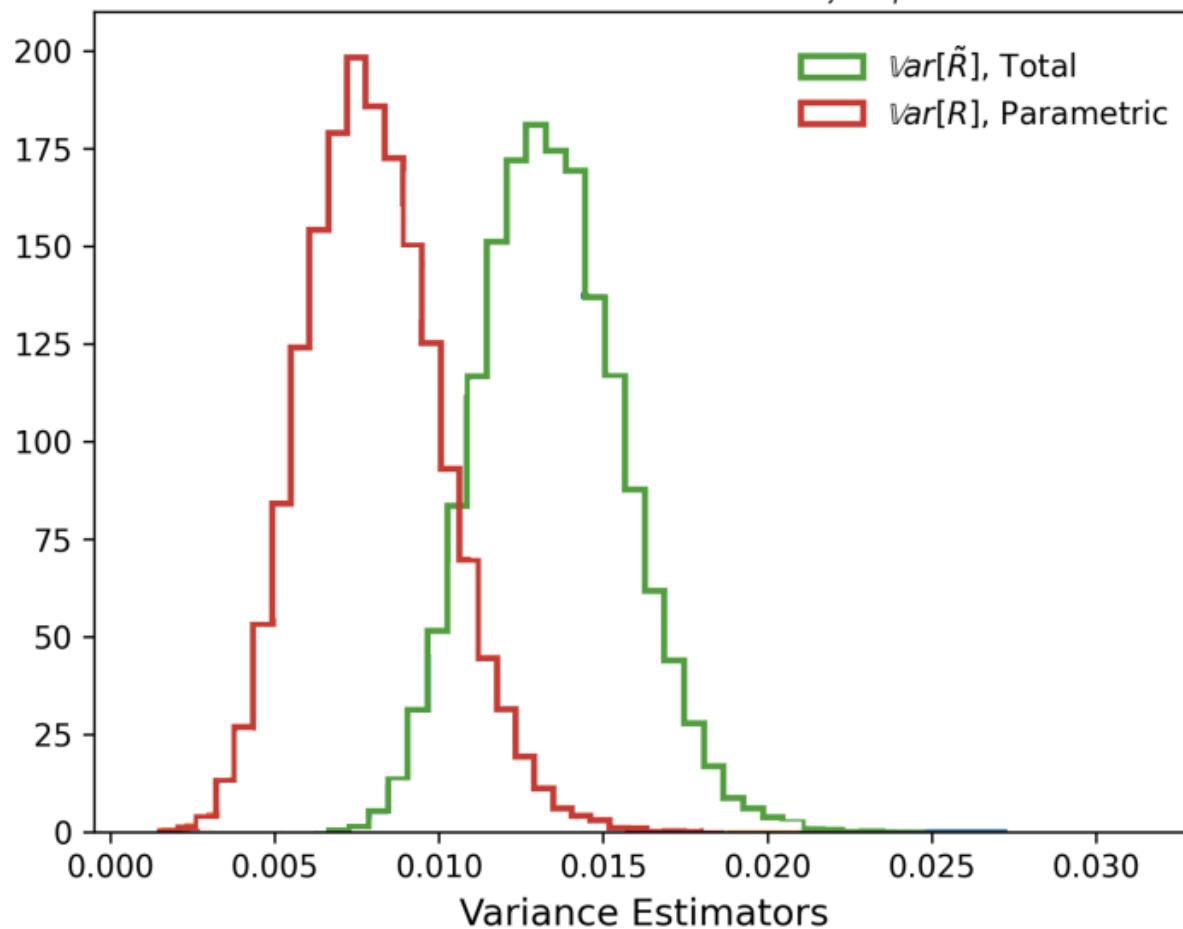
Variance -- 25000 Realizations --  $(N_\xi, N_\eta) = (100, 20)$ Variance -- 25000 Realizations --  $(N_\xi, N_\eta) = (100, 20)$ 

Figure II: Variance deconvolution results for transmittance (left) and reflectance (right) in a problem with scattering.

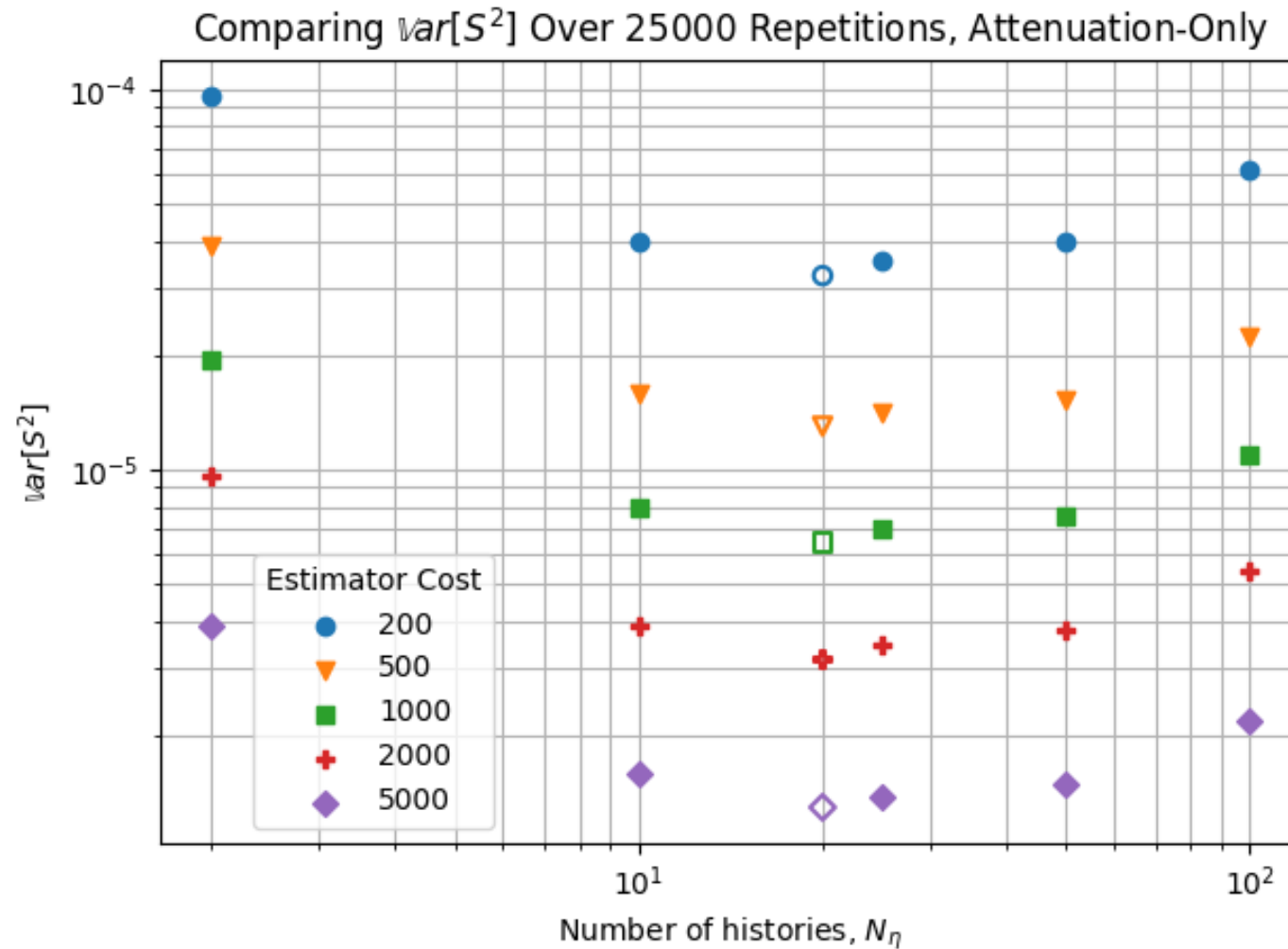
# Numerical Study



- Sampling estimator  $S^2 \approx \mathbb{V}ar_{\xi}[T]$  is unbiased
- Total estimator cost  $C = N_{\xi} \times N_{\eta}$
- Goal: accurate estimate of  $S^2$

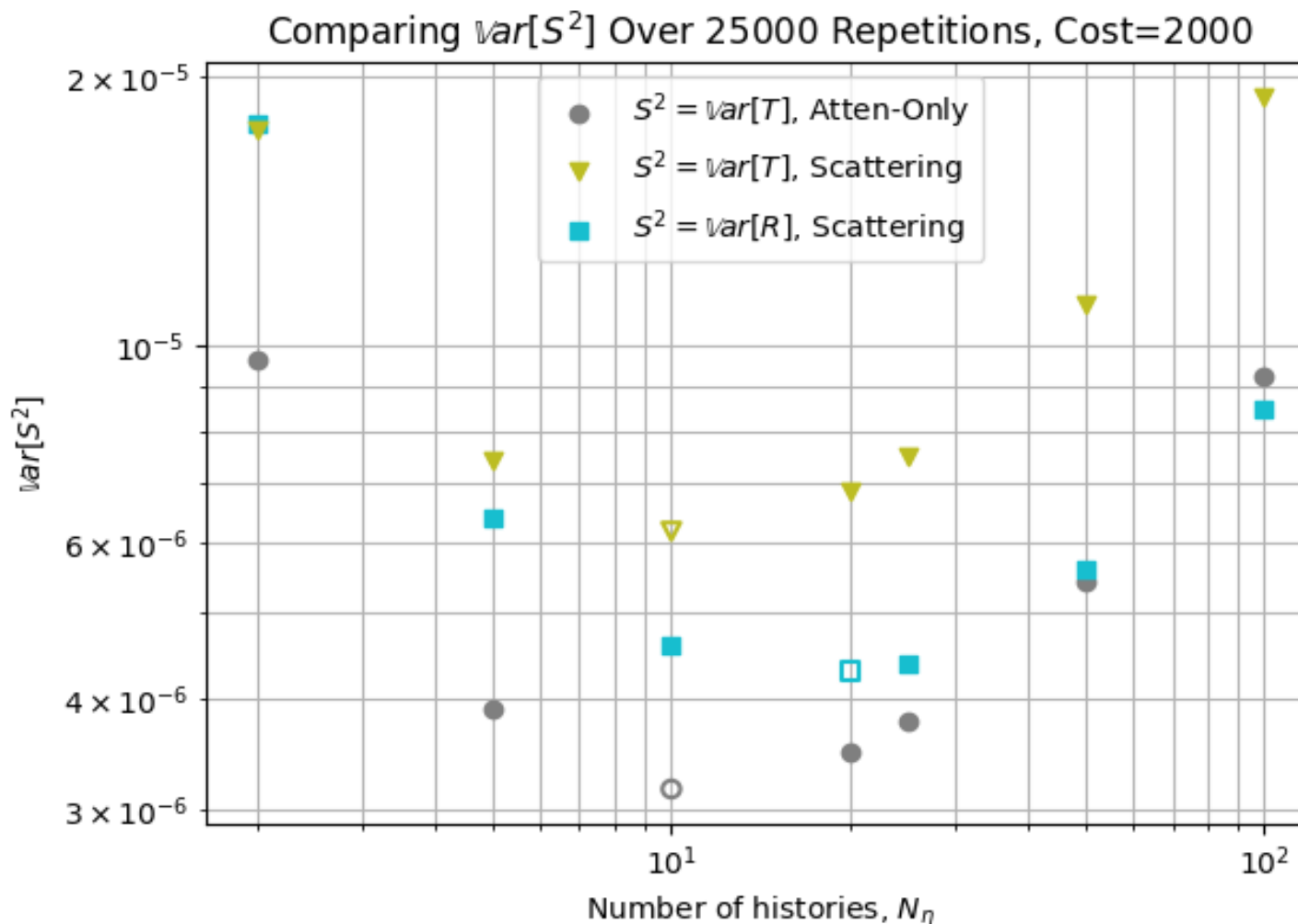
For given cost, find  $N_{\xi}$  and  $N_{\eta}$  that minimize  $\mathbb{V}ar[S^2]$

# Numerical Study Results – Attenuation Only



Total estimator cost  
 $C = N_\xi \times N_\eta$

Figure III.  $\text{Var}[S^2]$  as a function of  $N_\eta$  for a variety of total estimator costs, log-log plot. Unfilled point is minimum  $\text{Var}[S^2]$ .



Total estimator cost  
 $C = N_\xi \times N_\eta = 2000$

Figure IV.  $\text{Var}[S^2]$  as a function of  $N_\eta$  for the attenuation-only and scattering cases. Log-log plot, estimator cost  $N_\xi \times N_\eta = 2000$ . Unfilled point is minimum  $\text{Var}[S^2]$ .

# Conclusions and Future Goals



- “De-polluted” total variance by removing contribution from Monte Carlo transport solver
- Performed a numerical campaign to understand the estimator variance trade off between particle histories  $N_\eta$  and UQ samples  $N_\xi$
- Found that  $\text{Var}[S^2]$  is minimized at different locations for different Qols, even within one problem

## Future/Related work:

- Use variance deconvolution to efficiently compute Sobol Indices for Monte Carlo solvers
- Working towards closed-form solution to allow estimation of a cost distribution that minimizes  $\text{Var}[S^2]$  that takes re-sampling cost into account
- Related work – G. Geraci and A.J. Olson, “Deconvolution strategies for efficient parametric variance estimation in stochastic media transport problems,” Transport Methods Technical Session

# Questions?