



# How to Train Your Digital Twin: Practical Deep Learning Approaches to Modeling As-built Components

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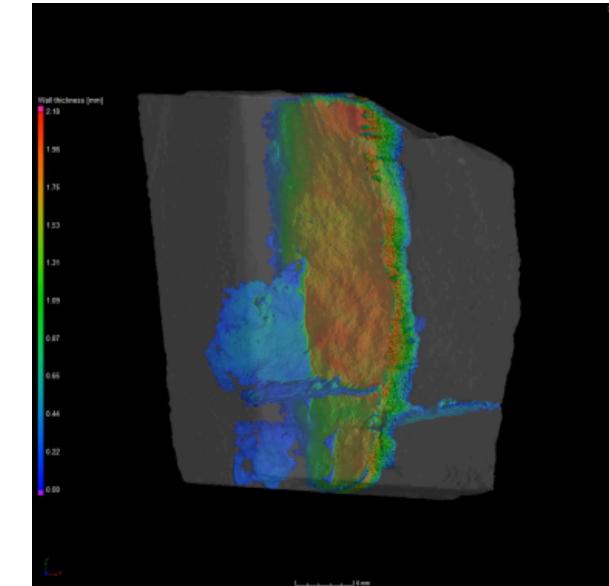
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# How do we build digital twins?



## Challenges:

- Idealized models fail to capture impact of defects.
- Overwhelming amounts of data cannot be manually analyzed.
- Uncertainty lurks everywhere.
- Limited or incomplete data availability constrains AI approaches.



## Practical approaches:

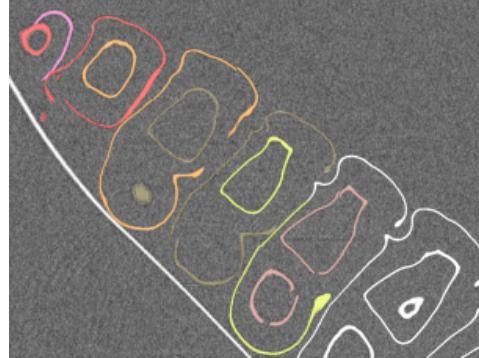
- Nondestructive multimodal data collection can characterize systems.
- Deep learning models can ingest all the data to predict a range of system properties.
- Domain knowledge can be incorporated to improve models and interpret predictions.

# Emerging capabilities enable digital twins



## Advances in computer vision

- Feature-based Anomaly Detection System (FADS)
- Volumetric segmentation

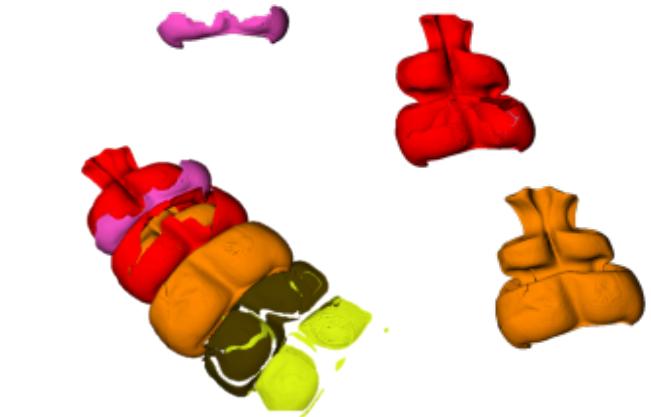


## Uncertainty quantification for image-based simulation

- Efficient Quantification of Uncertainty in Image-based Physics Simulations (EQUIPS) workflow

## Beyond Fingerprinting

- Physics-Informed Multimodal Autoencoders (PIMA)



# Automatic anomaly detection in high reliability as-built parts from images

Kevin Potter, Anthony Garland



# Feature Based Anomaly Detection System (FADS)

Anthony Garland

Extends the deep-one-class classification idea

Works via a **pretrained network** to provide the mapping

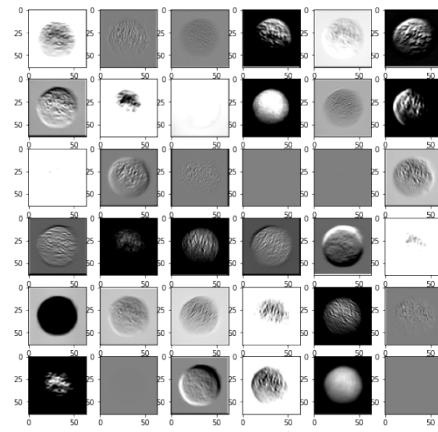
- **Record** the activations from the model's convolutional filters
- **Aggregate** each filter to a single value (max, min, mean, etc.)
- Develop a **statistical** model of expected convolutional activations ( $\bar{x}$  and  $\sigma$ ) based on the nominal images' activations
- At inference time, measure activation of the input image from the same model and **normalize** based on the nominal statistics

Example nominal data (hazelnuts)

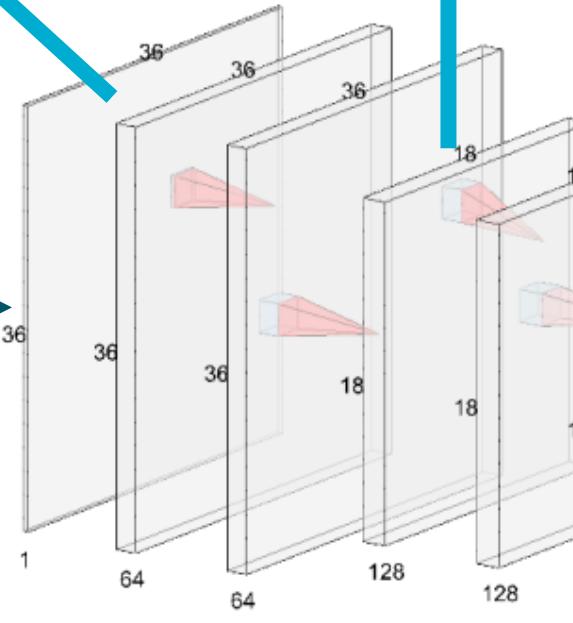




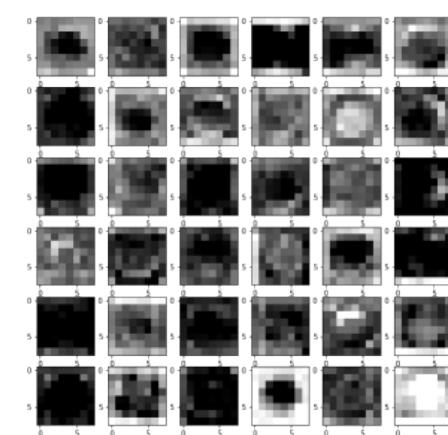
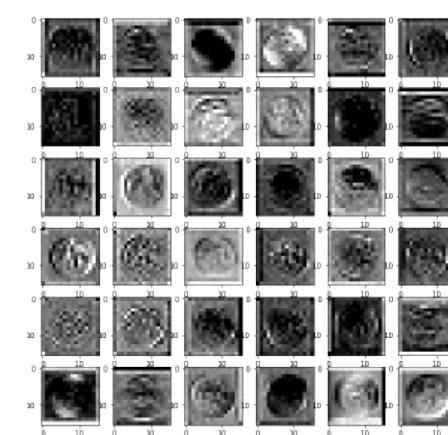
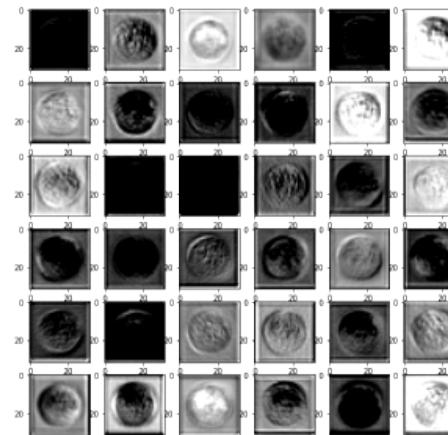
# CNN activations



Input Image



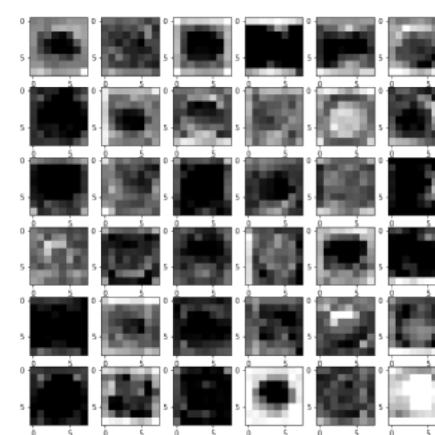
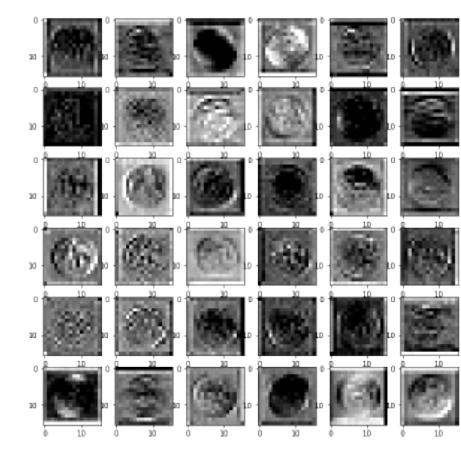
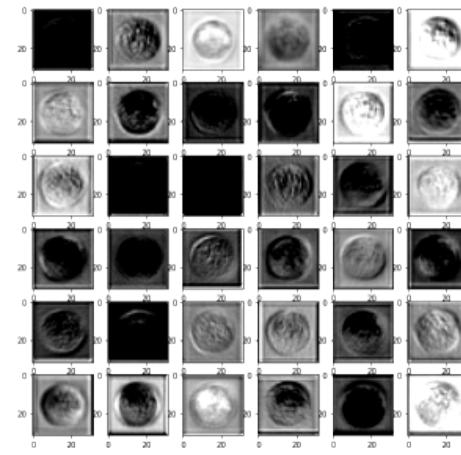
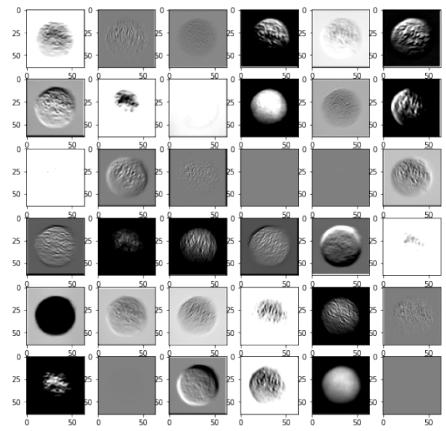
Example CNN activations



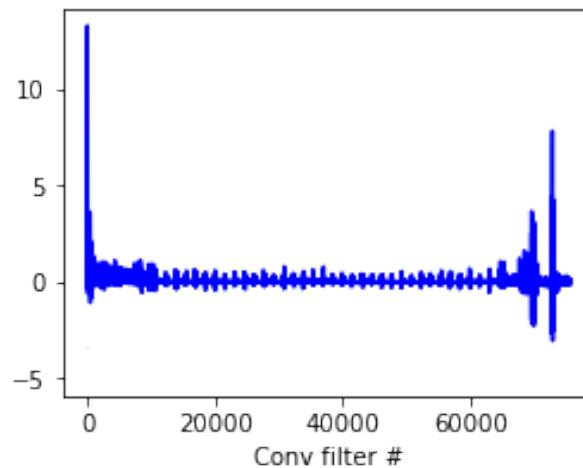
Generic Pretrained  
Convolutional Model



## Aggregate activations



Collapse each filter's activations to a single value and stack

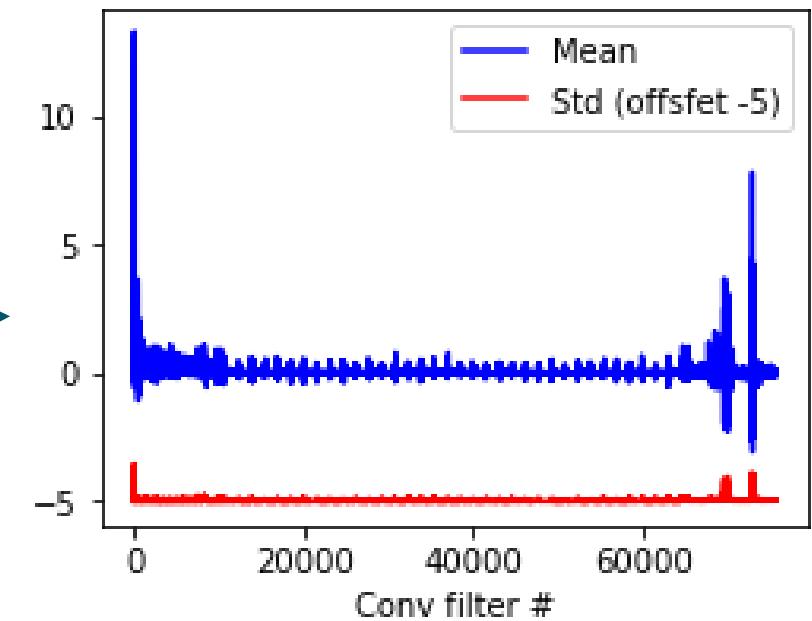


## Learn the nominal datasets activation stats for each filter



Nominal images  
("training" set)

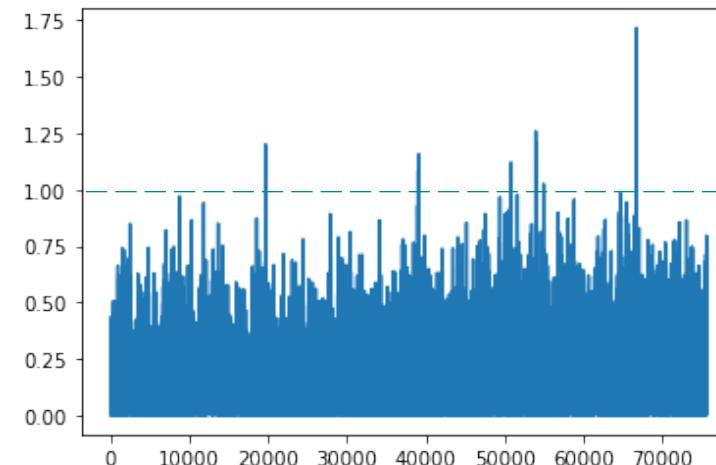
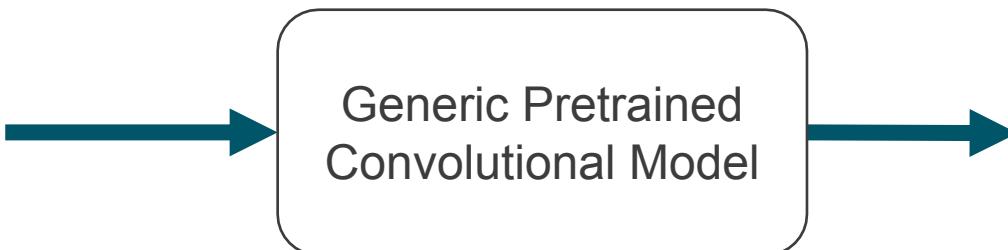
Generic Pretrained  
Convolutional Model



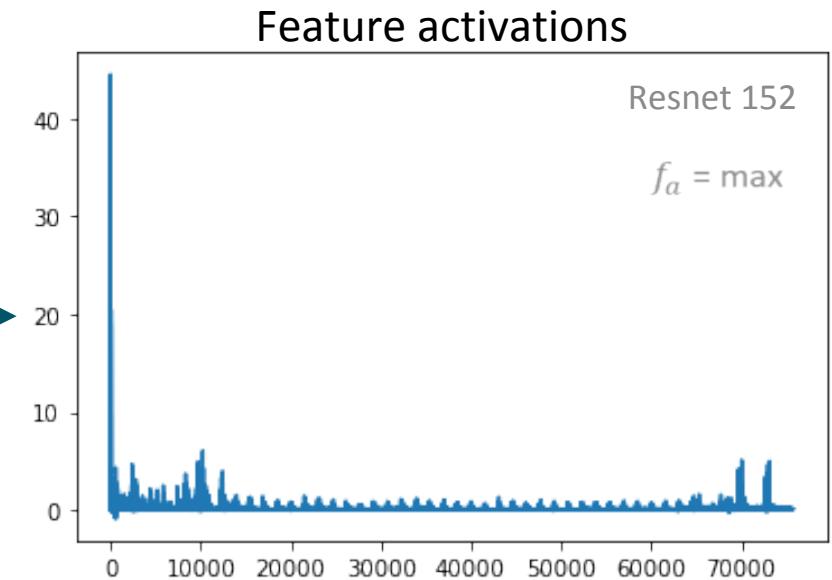
## 2-D FADS example – inference normalization



Input image

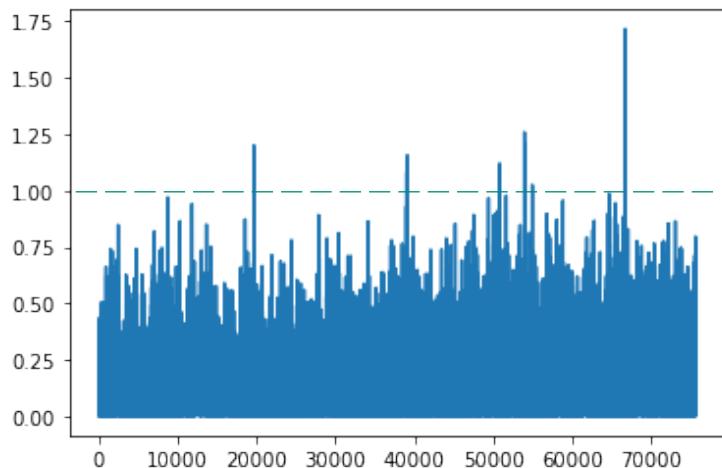


R-vector (standard deviations from nominal mean)

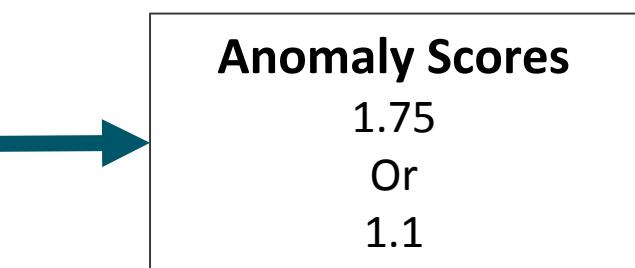
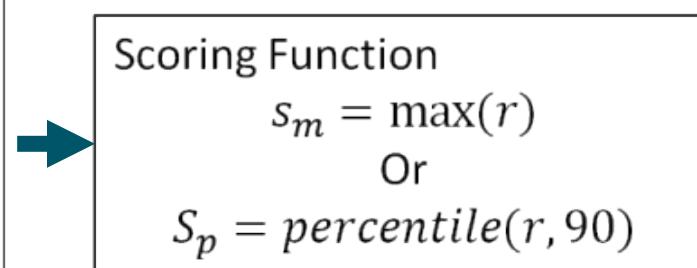


Normalize against  
“training” set

## 2-D FADS example – converting to a threshold

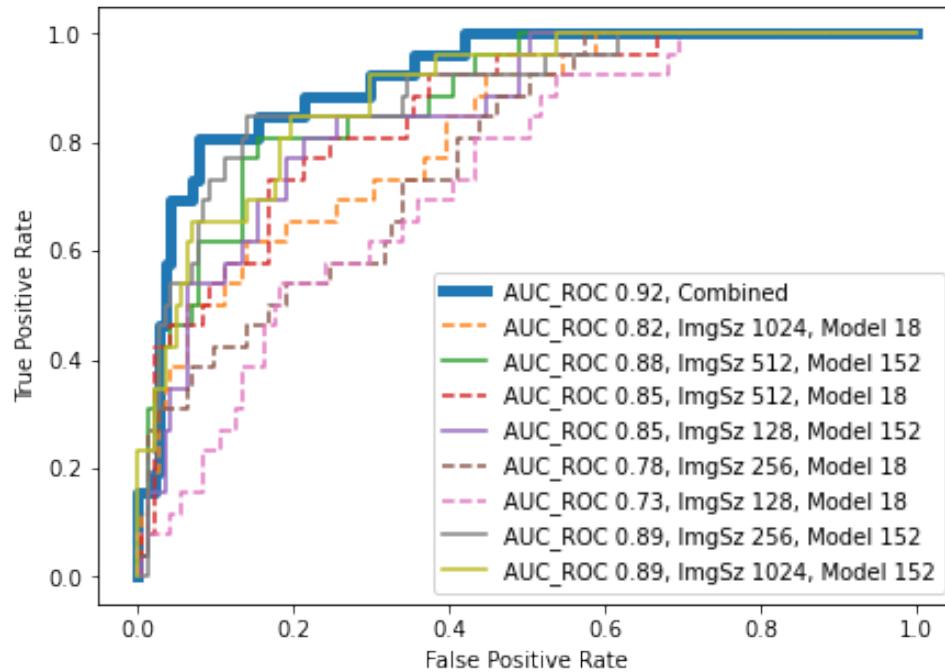


R-vector (standard deviations from  
nominal mean)

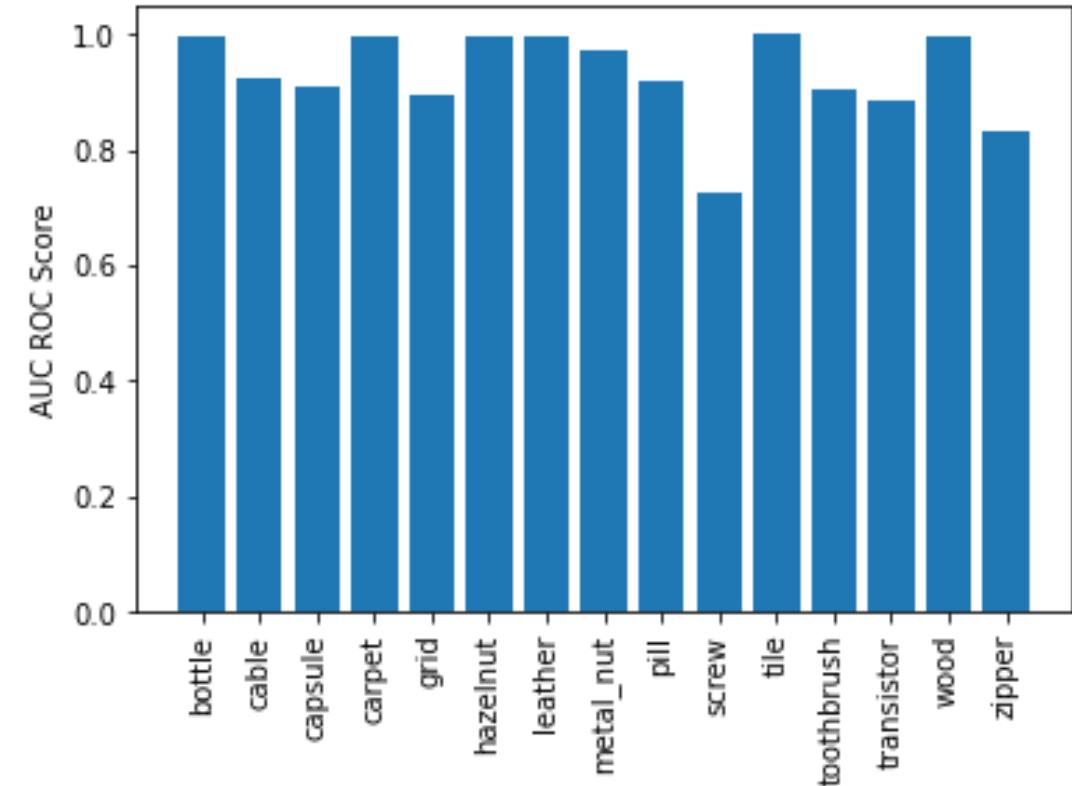


# FADS on MVTec AD dataset (whole image)

ROC for pill category



FADs AUC score on each class

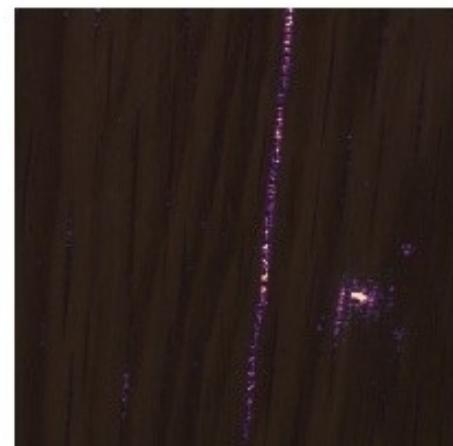
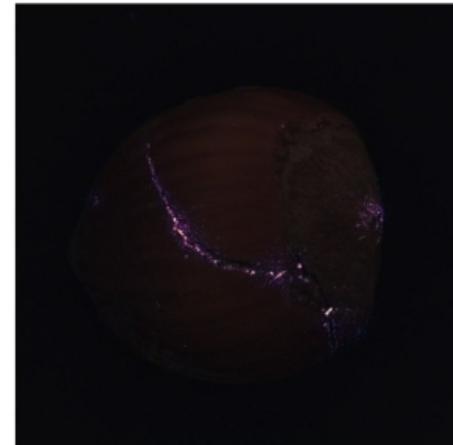
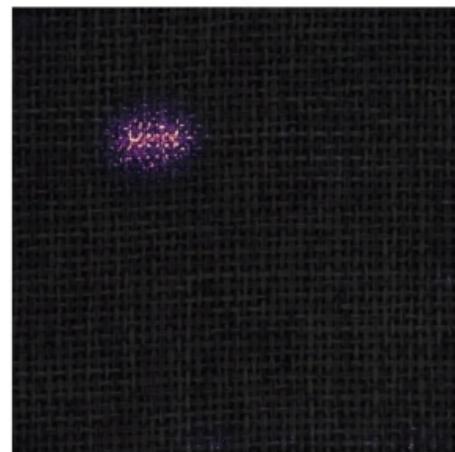


FADS achieves an average AUC of 0.93

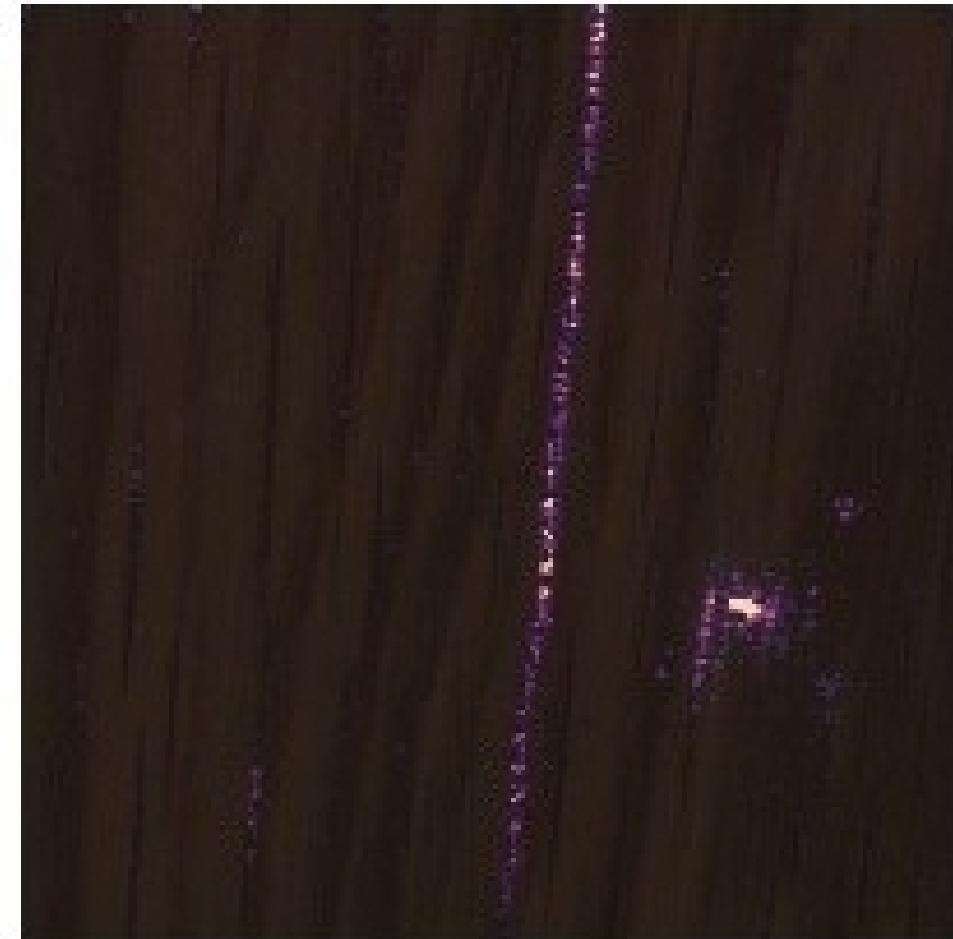
## FADS can also highlight the anomalies

By taking the gradient to minimize the anomaly score with respect to the input, the pixels that contribute to anomalousness are highlighted

- Very sensitive – wood image picks up a scuff that is barely visible for instance
- Still fast as it uses a single backward pass



FADS can also highlight the anomalies



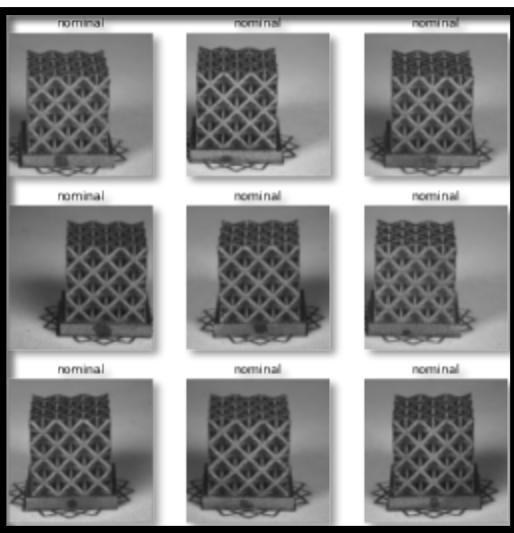
# FADS against a real world application

## Additive Manufacturing

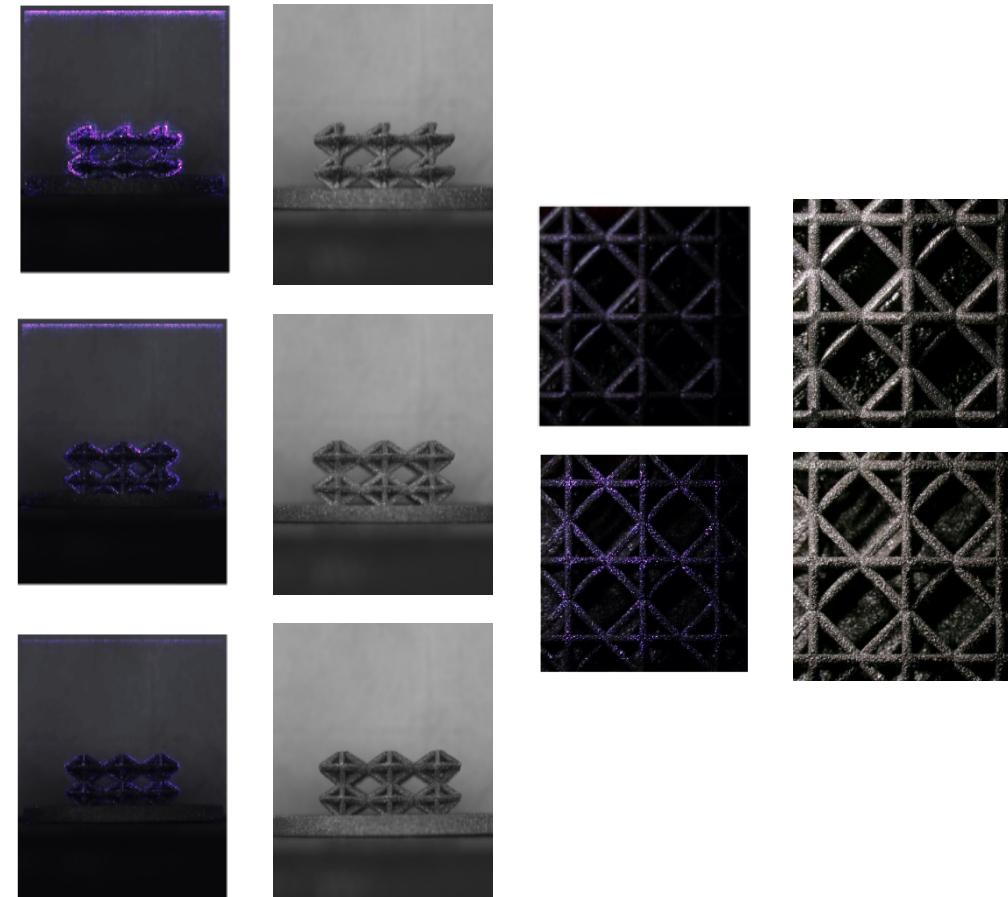
(right) Localizing flaws in real prints

(below) Dedicated print testing: Using just images, identify defective parts with incorrect print process settings

- “Trained” on 18 lattices
- Result: Avg AUC of 0.99



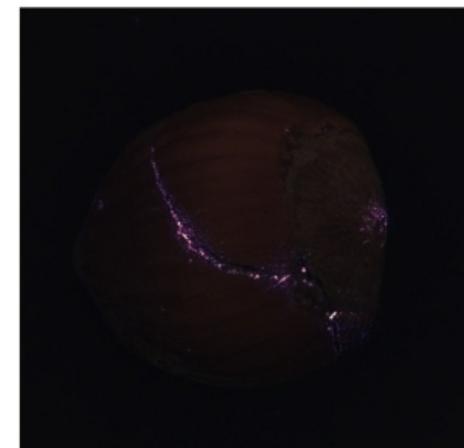
3-D Printed Lattice



Visualization of the regions causing high anomaly scores

## FADS key insights

- Powerful transfer learning from models pretrained on massive, unrelated datasets
- Features relevant to separate normal from abnormal examples highlighted without supervision
- Limited number of training examples adequate for high accuracy



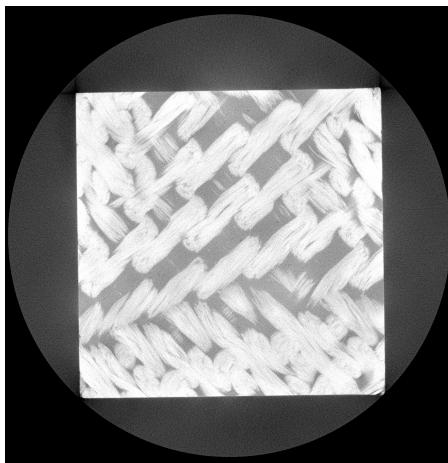
# Credible Automated Meshing of Images

Scott Roberts, PI

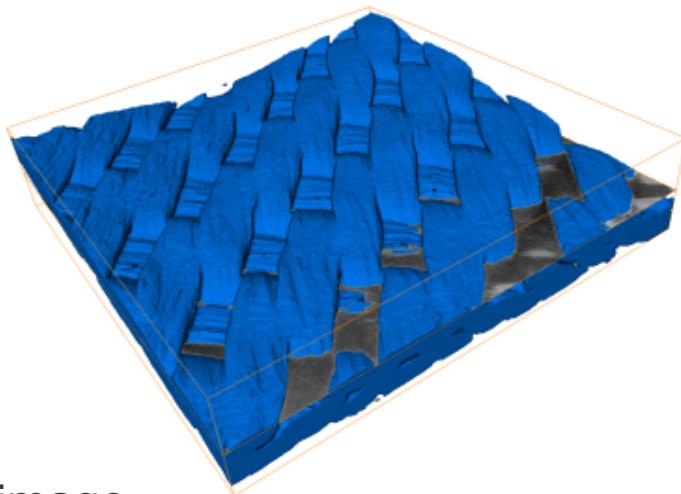


# Credible, Automated Meshing of Images (CAMI) LDRD

Raw greyscale image (XCT)



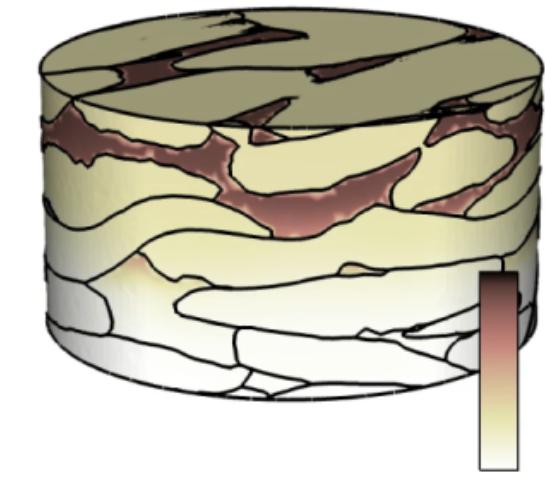
Surface mesh (STL)



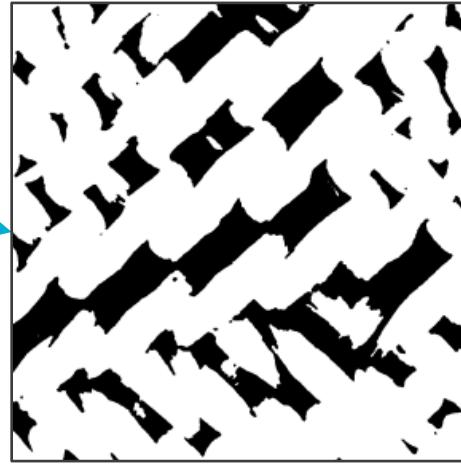
## Meshing:

- CDFEM + snap + Emend
- High quality

Physics simulation



Segmented image



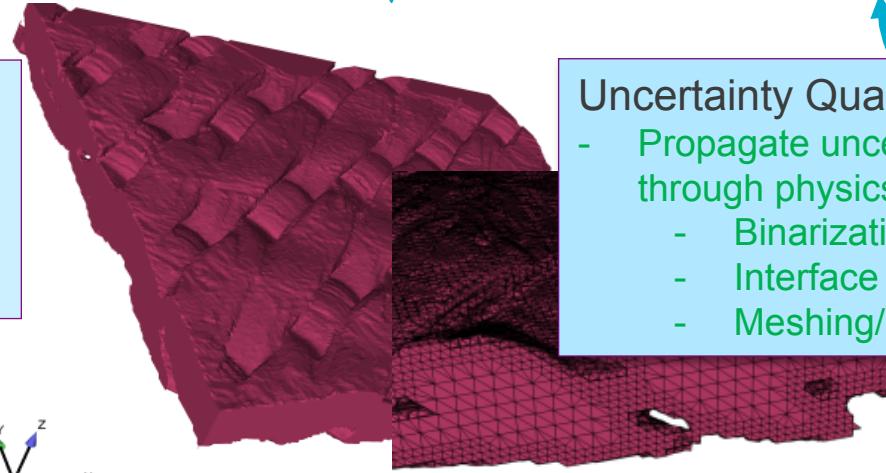
## Segmentation:

- Automated: deep learning
- Repeatable

## Interface Identification:

- Automated
- Marching cubes on smooth data

Volume mesh



## Uncertainty Quantification:

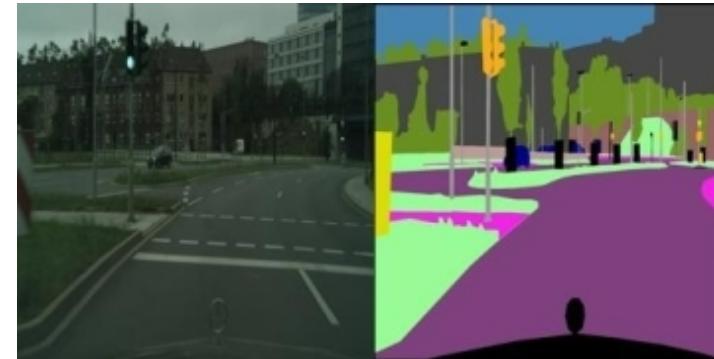
- Propagate uncertainty through physics predictions
  - Binarization
  - Interface identification
  - Meshing/resolution

# Segmentation is a classic computer vision problem



Image segmentation is well studied

- Small files
- Large training sets

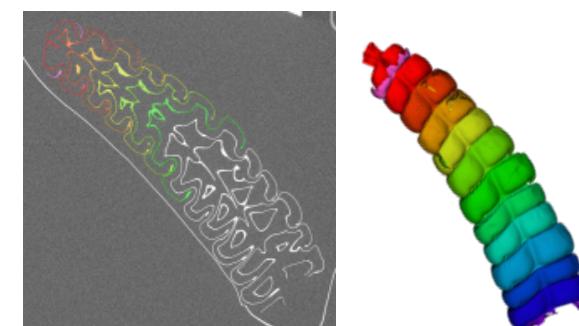


<https://www.cityscapes-dataset.com/>

Cityscape  
(~1e5 pixels)

CT segmentation is different

- Volumetric; larger files
- Class imbalance (lots of background)
- Noise/artifacts in scans
- Small training sets with “bad” human labels
- Inconsistent scan quality (domain shift)



Rattlesnake Tail  
(~1e9 voxels)

Medical researchers are leading this work toward Deep Learning solutions

# Mitigating challenges

Volumetric; larger files

- Train with random subvolumes

Class imbalance (lots of background)

- Loss function sets weights inversely with class fraction for each subvolume
- Normalization methods can separate foreground from background

Noise/artifacts in scans

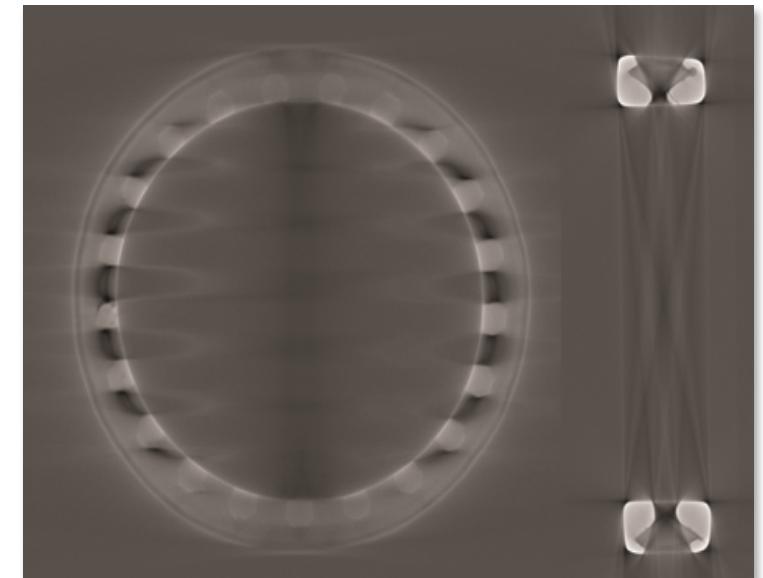
- Convolutional Neural Network (CNN) architecture learns to recognize shapes

Small training sets with “bad” human labels

- 1-3 volumetric training examples is often sufficient
- Errors in labels are overcome if the errors are inconsistent

Inconsistent scan quality (domain shift)

- Use UQ to drive corrections to predictions
- Cari’s dissertation!



# Supervised: Encoder-decoder network with skip connections

Encoder learns features at different resolutions

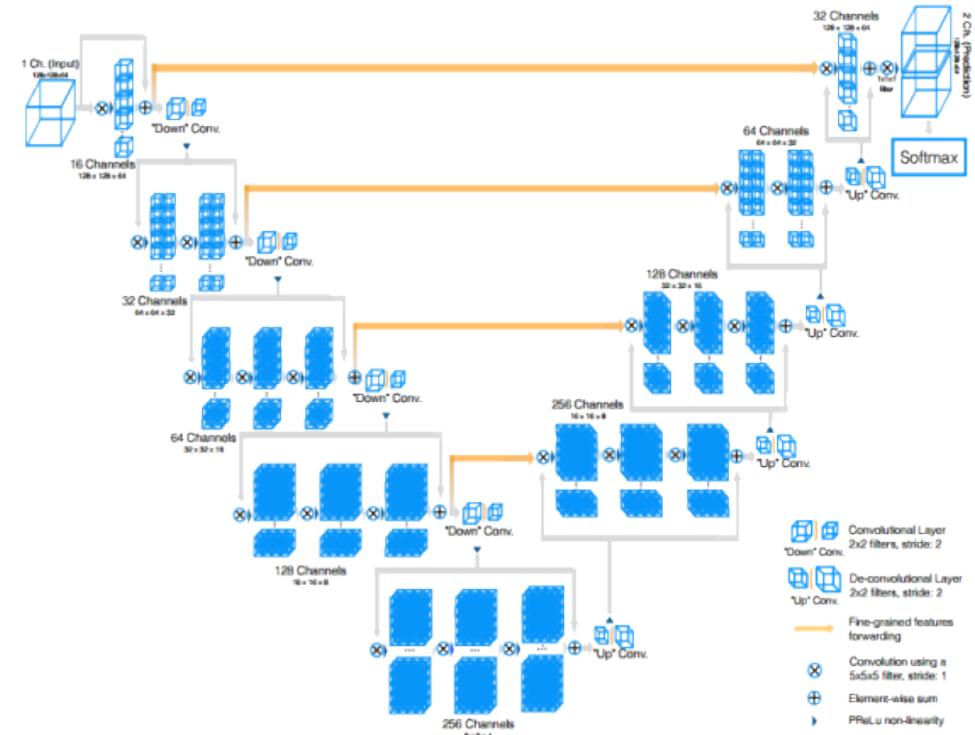
Decoder uses encoded features passed via skip connections for segmentation

U-net: significant advance for biomedical segmentation

- Olaf Ronneberger, Philipp Fischer, Thomas Brox , “U-Net: Convolutional Networks for Biomedical Image Segmentation”, in Medical Image Computing and Computer-Assisted Intervention (MICCAI), Springer, LNCS, Vol.9351: 234--241, 2015

V-net follows as a natural extension to handle 3D images

- F. Milletari, N. Navab, and S. A. Ahmadi, “V-net: Fully convolutional neural networks for volumetric medical image segmentation,” in 2016 Fourth International Conference on 3D Vision (3DV), Oct 2016, pp.565–571

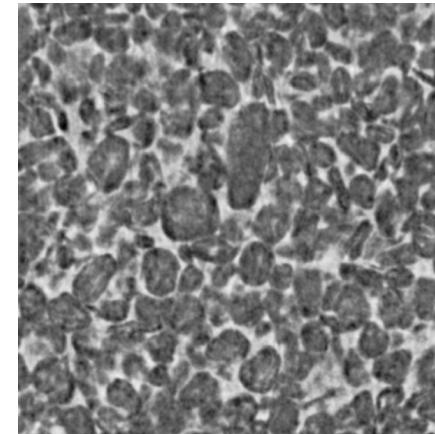


V-Net architecture for segmenting volumetric data (2016)

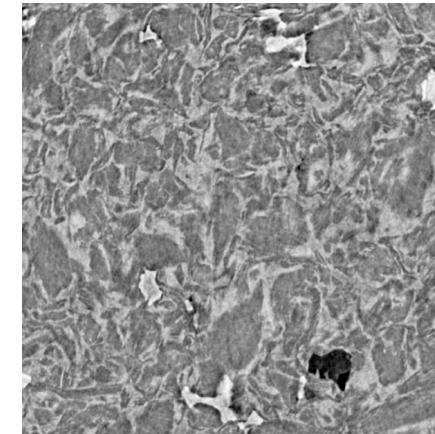
# Example: Train V-Net to segment batteries

DOMAIN NAME	ACCURACY
E35	0.984
Tesla	0.973
Litarion	0.966
25R6	0.955
Electrode_I_1	0.948
Electrode_III_1	0.945
GCA400	0.928
Electrode_IV_1	0.917
Electrode_II_2	0.902
GCA2000	0.900
Electrode_I_2	0.892
Electrode_III_2	0.773
Electrode_IV_3	0.748
Electrode_IV_2	0.745
Electrode_II_3	0.699
Electrode_III_3	0.668
<b>Mean</b>	<b>0.8714375</b>

TRAINING SET

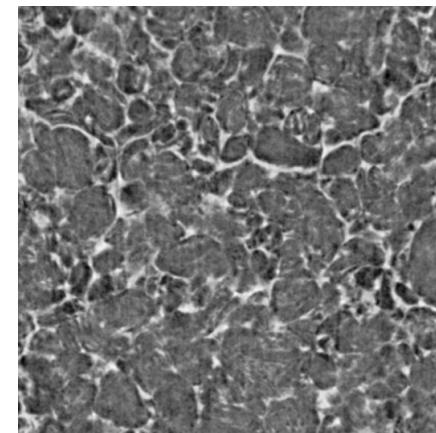


Litarion

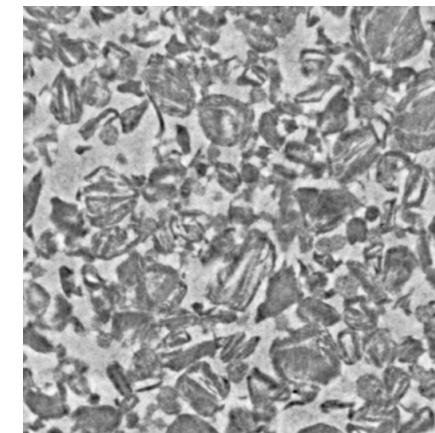


Electrode IV\_1

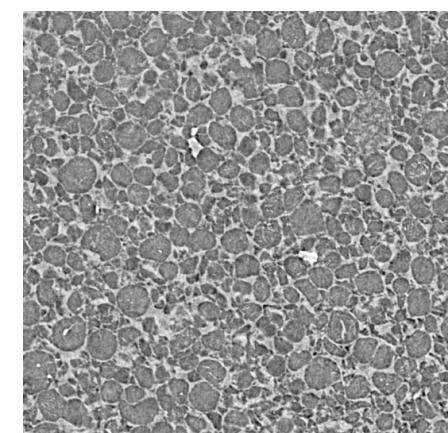
TEST SET



E35



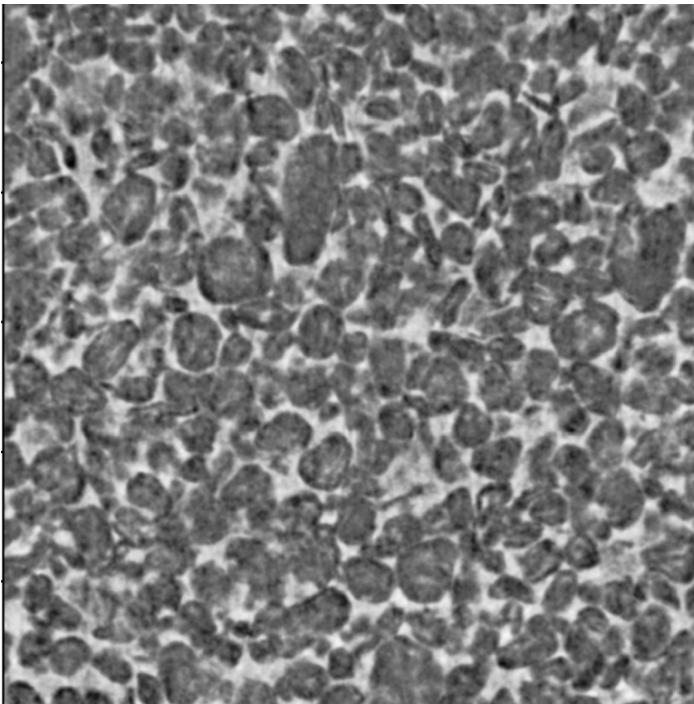
GCA400



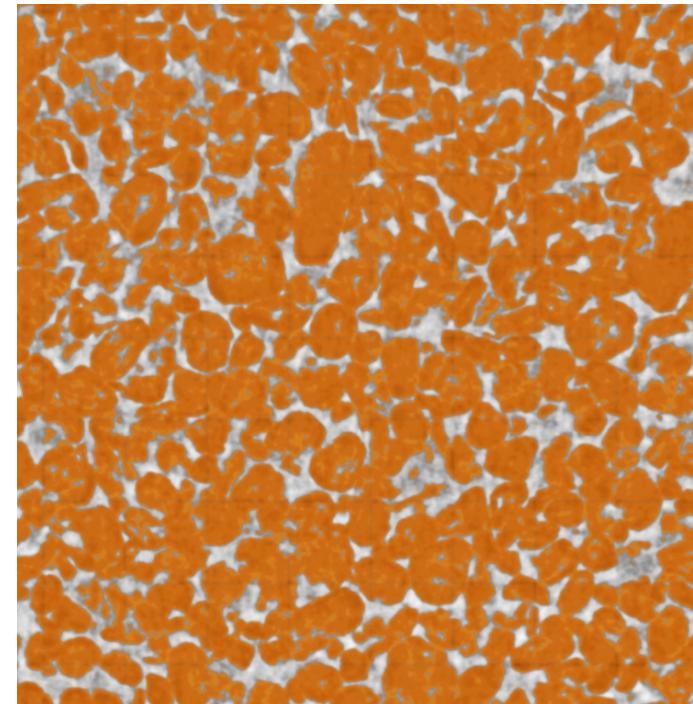
Electrode II\_3

# Inference results in training domain are as expected

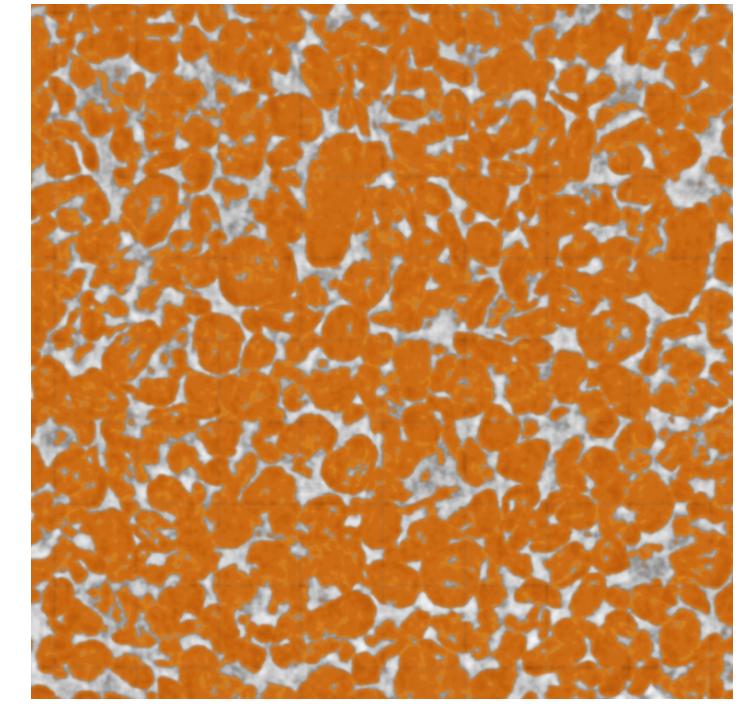
Litarion CT scan slice



Human label



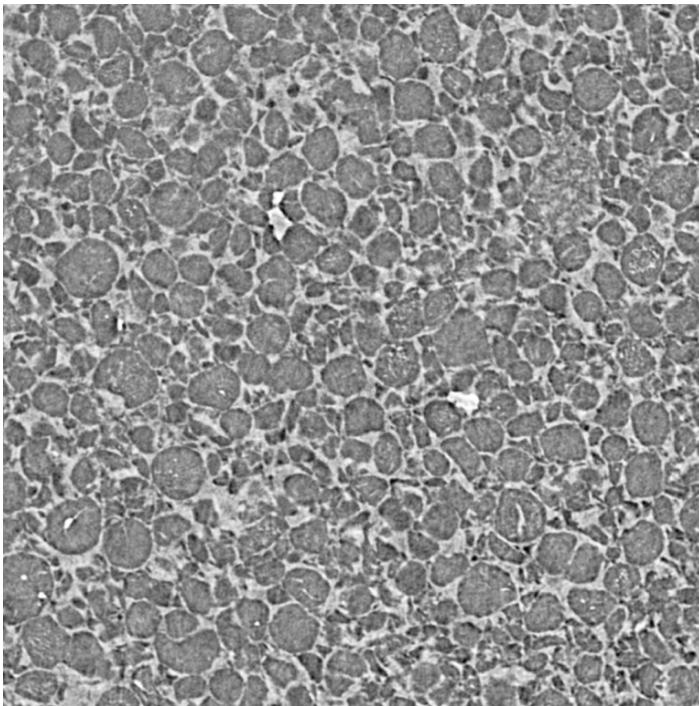
ML prediction



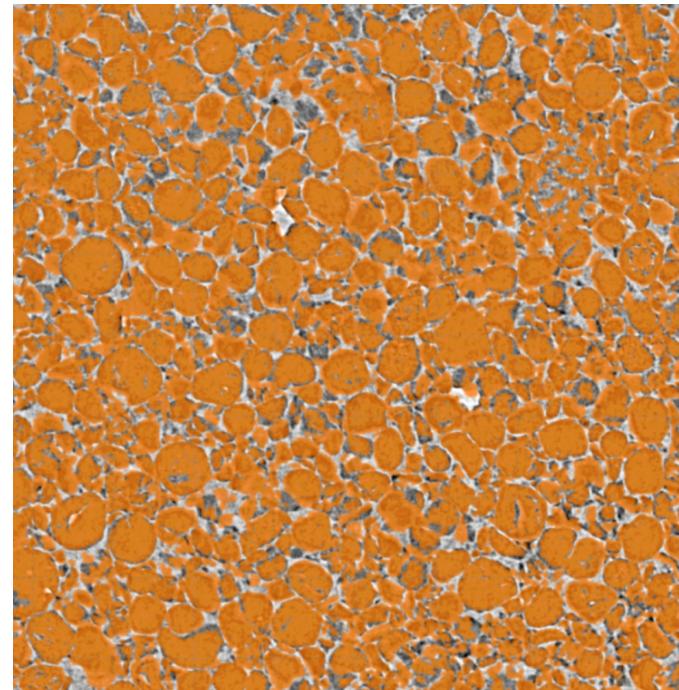
ML segmentation is 96.6% accurate to the human label

Inference results outside the training domain are qualitatively better than accuracy measurements indicate

Electrode II\_3 CT scan slice



Human label



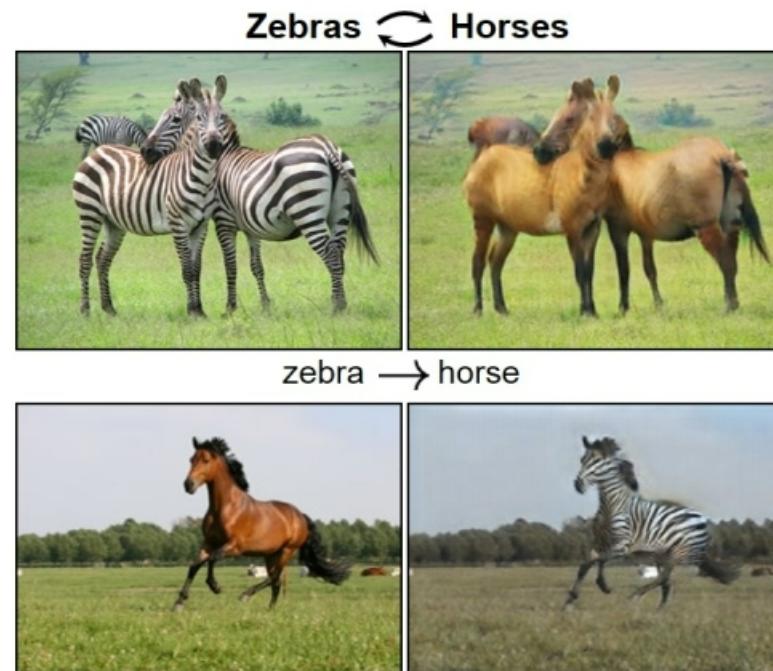
ML prediction



ML segmentation is 69.9% accurate to the human label...but looks qualitatively better

## Alternative approach: CycleGAN translates images between domains

Zhu, J. Y., Park, T., Isola, P., & Efros, A. A. (2017). Unpaired image-to-image translation using cycle-consistent adversarial networks. arXiv preprint.



Learns two functions:

$$F(x) = \text{Horse to zebra}$$
$$G(x) = \text{Zebra to horse}$$

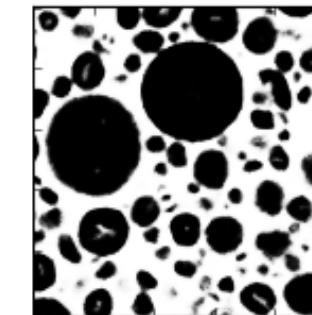
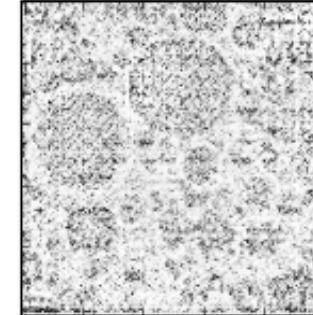
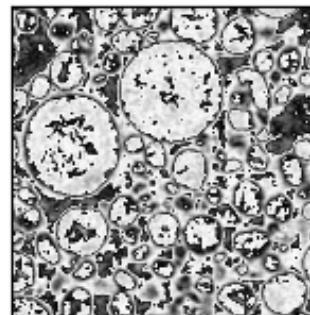
Cycles back to starting point to learn without paired examples

$$F(G(x)) = x$$

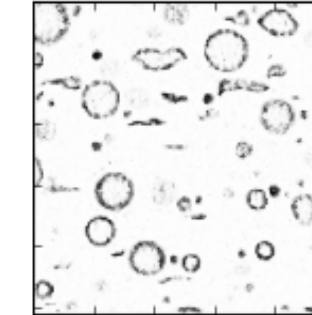
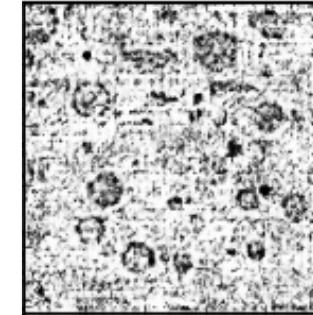
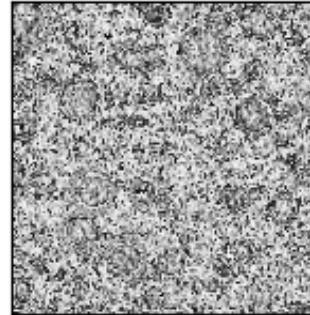
# CycleGAN translates between material domains capturing relevant features

CT Slice → Style Swapped → Cycled Back

Battery → Foam → Battery



Foam → Battery → Foam



CycleGAN provides a rough segmentation of both battery and foam

## Semi-supervised: Domain adaptation can reduce supervised labeling cost

Repurpose labels from one domain (battery) to another domain (foam)

- CycleGAN transforms foam CTs into the “style” of battery labels
- Semi-supervised

Hand-labeled small slices from 7 CT scans of foam

Used 2 labels to select stopping point

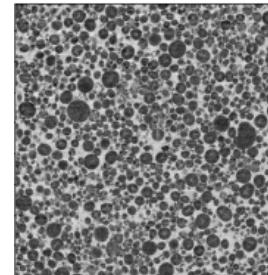
Inferred over remaining 5 volumes

Post-process (fill in gaps) with standard CV methods

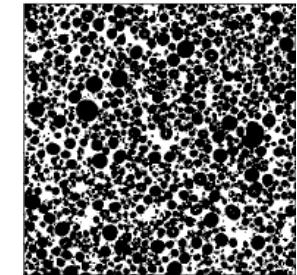
Average 94.8% accuracy when compared with human labeled slices

Battery

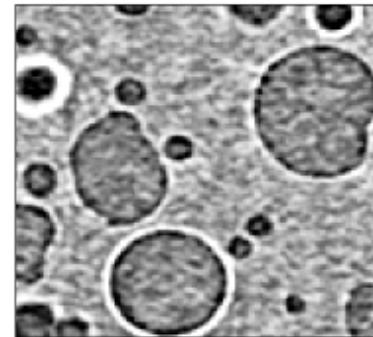
CT Scan



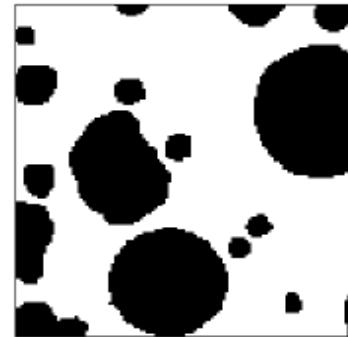
ML prediction



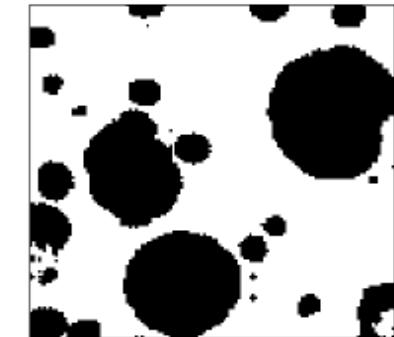
CT Scan Slice



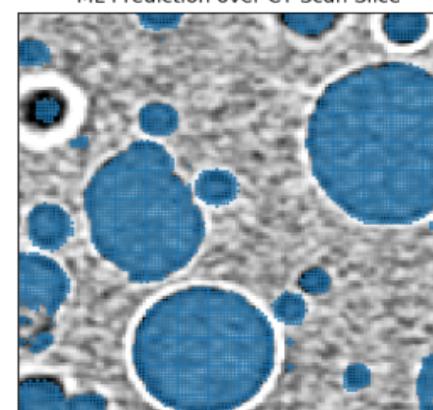
Human Label



ML Prediction



Foam



# Data preprocessing and augmentation

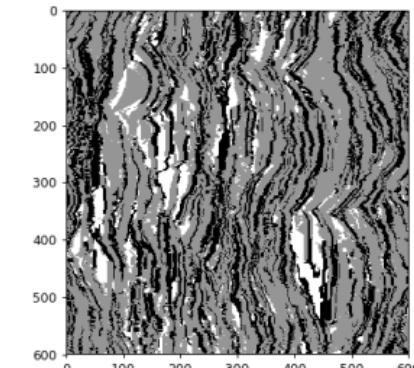
Making the problem as easy as possible for the DL algorithm with preprocessing can dramatically improve results

- Choose normalization function that helps to separate challenging classes
- Manual inspection is important for selecting the best methods
- Example: Using log function might push most of the background to negative values

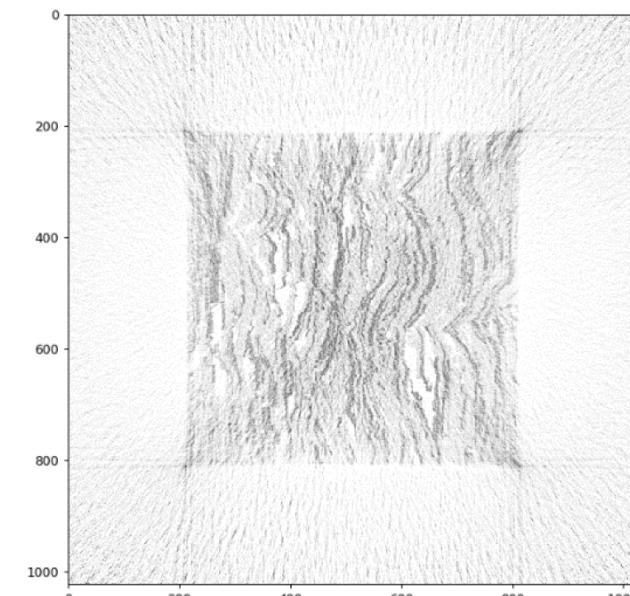
Data augmentation methods

- Flip along each axis
- Generate synthetic data from perfect numerical models:  
ASTRA toolbox <https://www.astra-toolbox.com/>

Numerical model of material

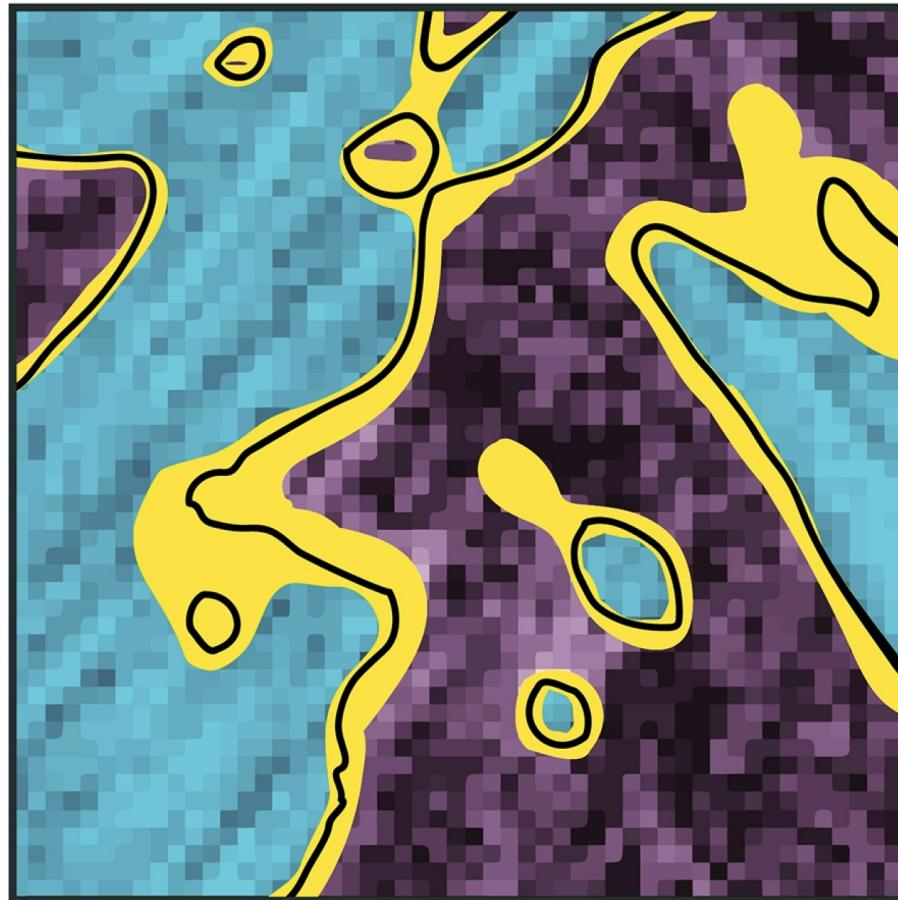
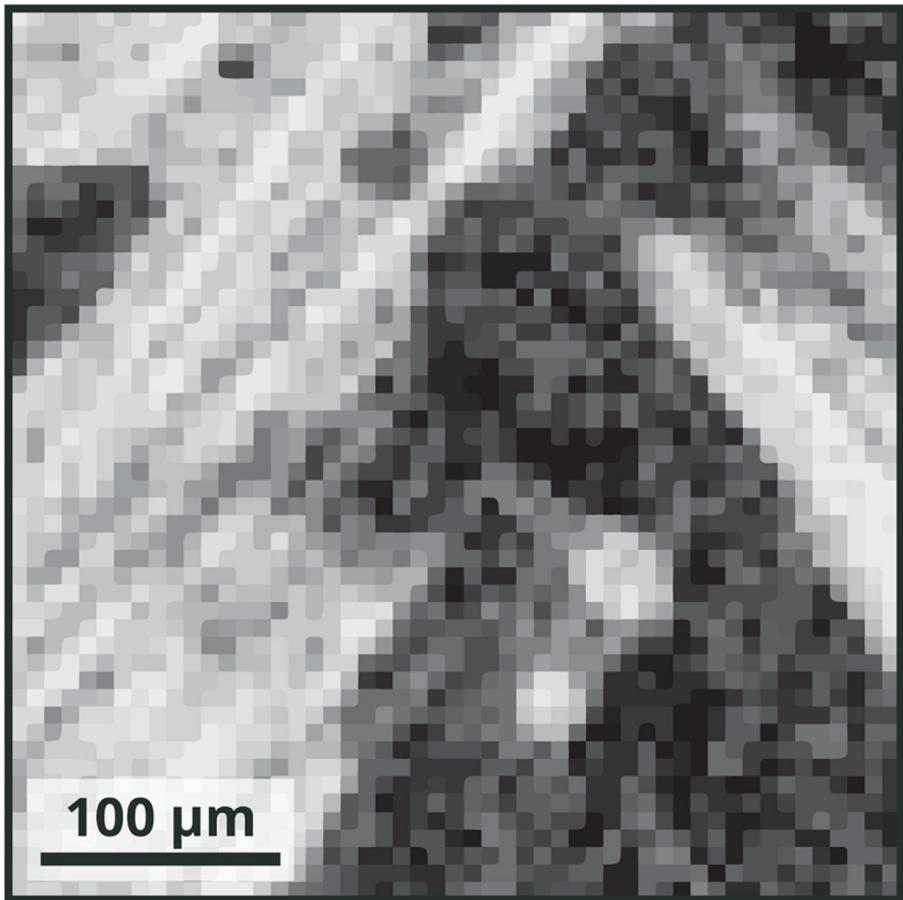


Slice of synthetic CT scan



Martinez, Carianne, et al. "Automated Segmentation of Porous Thermal Spray Material CT Scans with Geometric Uncertainty Estimation." SAND2020-9099

## Image segmentation uncertainty



# Uncertainty can be used to inform segmentation

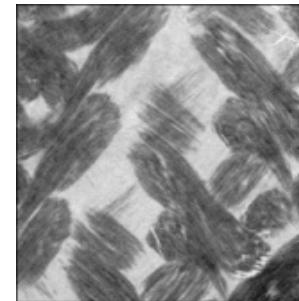
Neural networks measure per-voxel segmentation uncertainty

Provides a measure of the model's credibility on a particular task

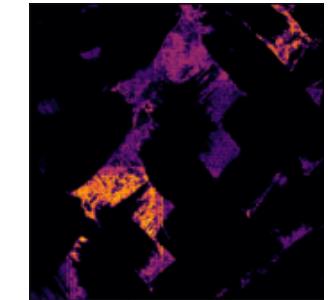
Enables neural networks to overcome domain shift

- This additional information offers an insight into the model
- New ways to mitigate common problems

Slice of scan of woven composite material



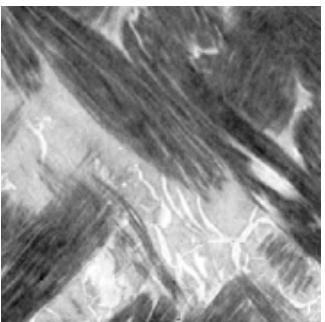
Uncertainty map - brighter pixel values indicate higher uncertainty



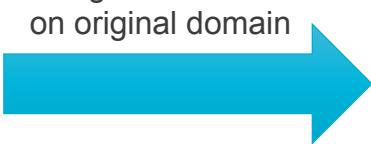
High uncertainty indicates this model should not be trusted in this domain

We leverage uncertainty maps to enable generalization of a trained model to shifted domains

CT slice from shifted domain



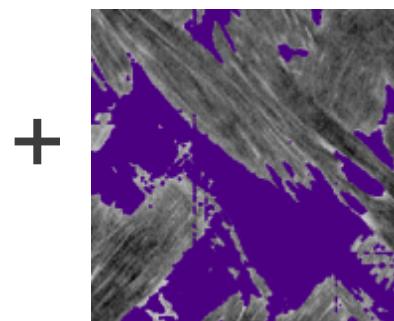
Predict segmentation using model trained on original domain



Unusable segmentation



Uncertainty map



Apply advanced uncertainty based refinement method



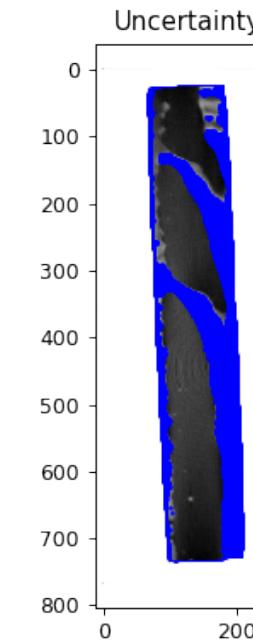
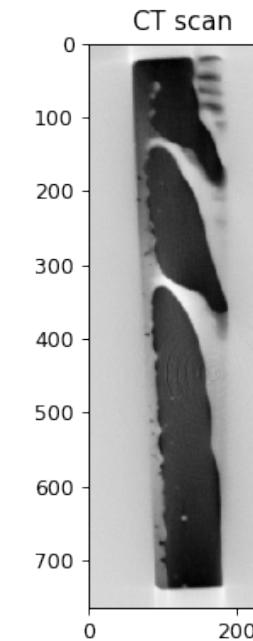
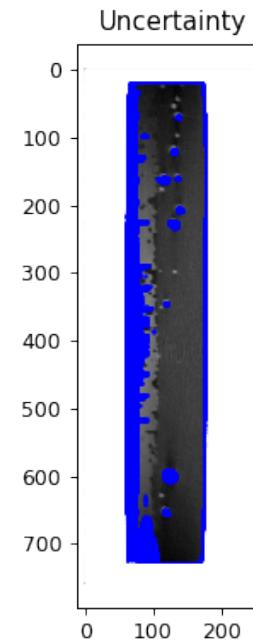
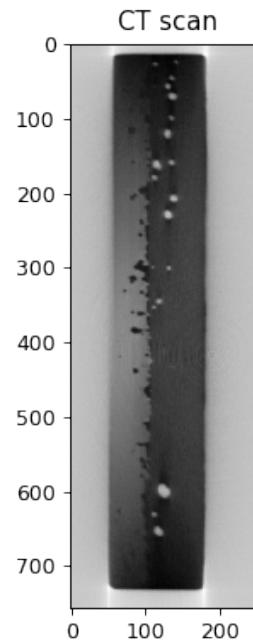
Refined segmentation



# Happy accident leads to anomaly detection algorithm (Kyle Karlson)

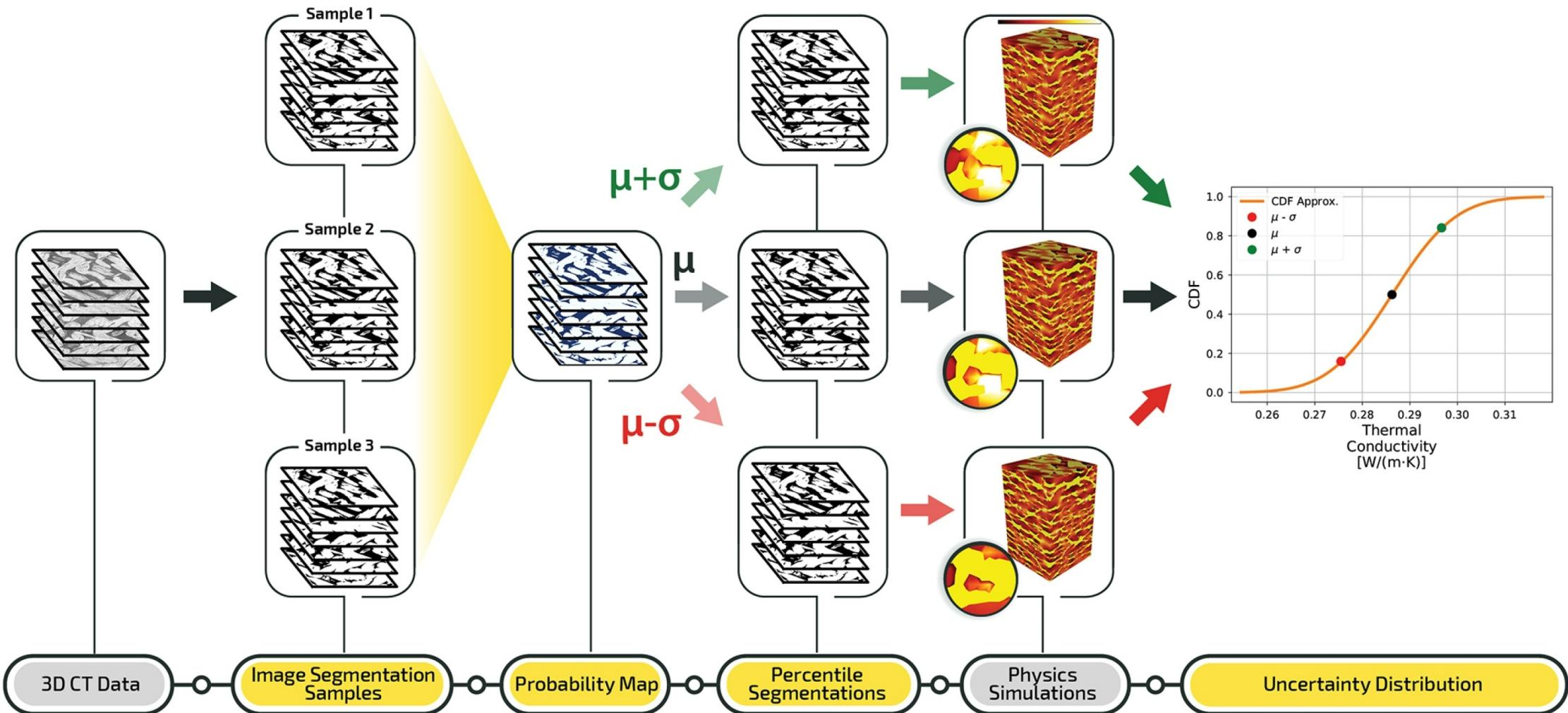
Training the neural network on the wrong labels resulted in poor segmentations but high uncertainty around interesting features

Preliminary result – requires further research and validation

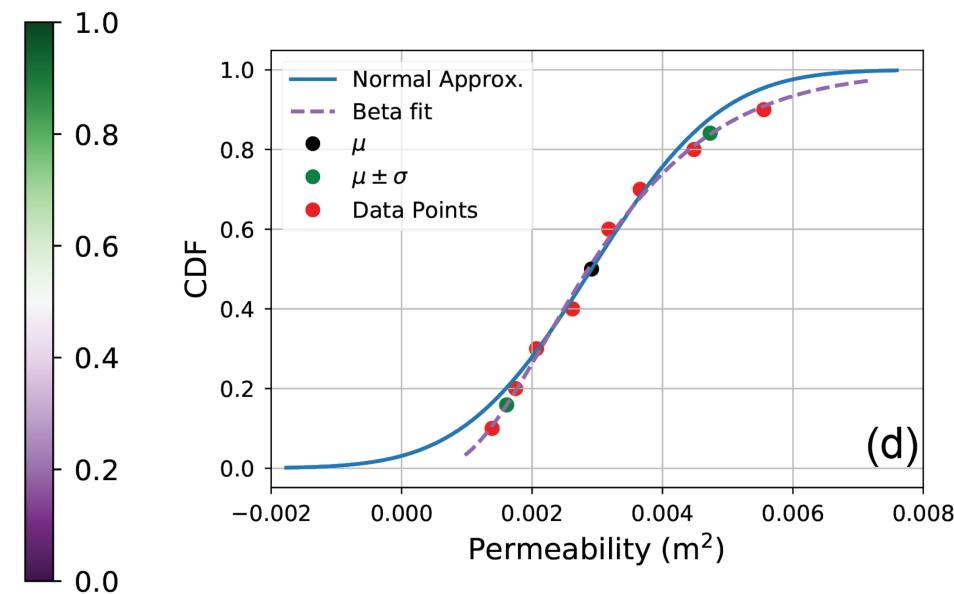
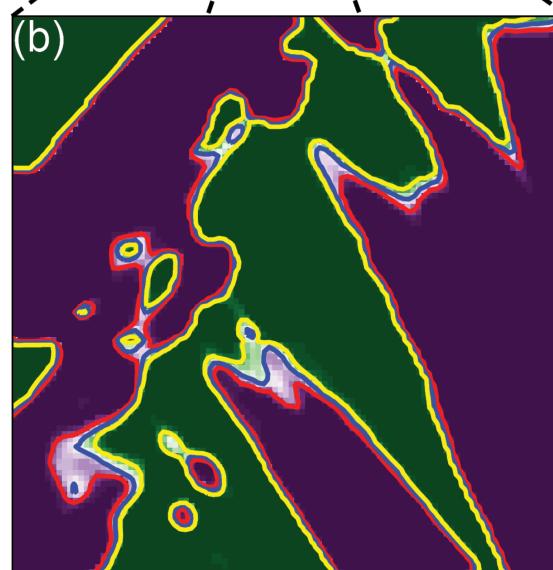
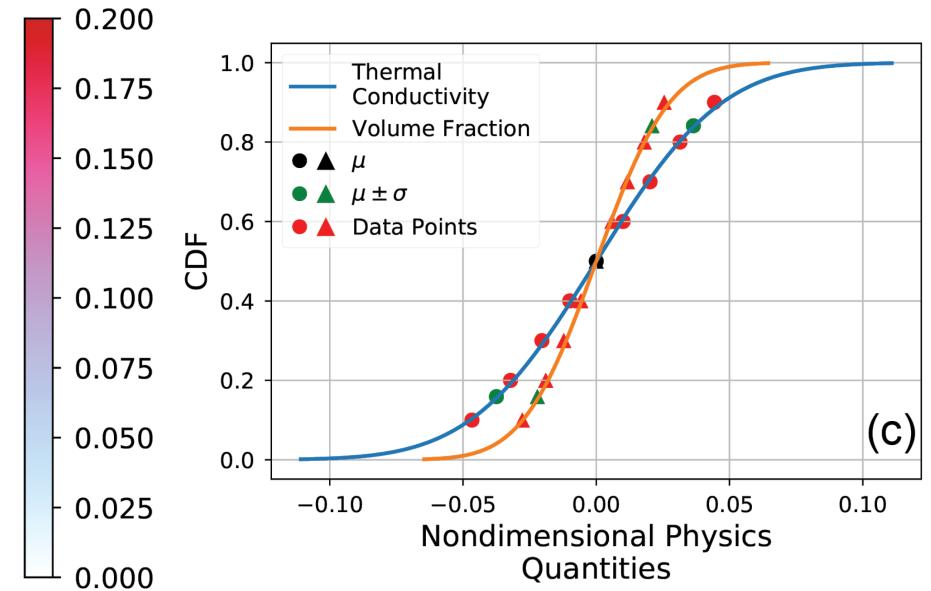
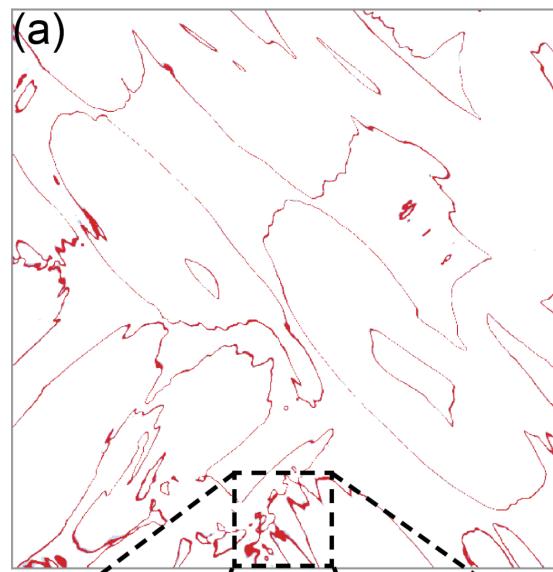


Potential Impact: Uncertainty can highlight anomalous regions

# Efficient Quantification of Uncertainty in Image-based Physics Simulations (EQUIPS)

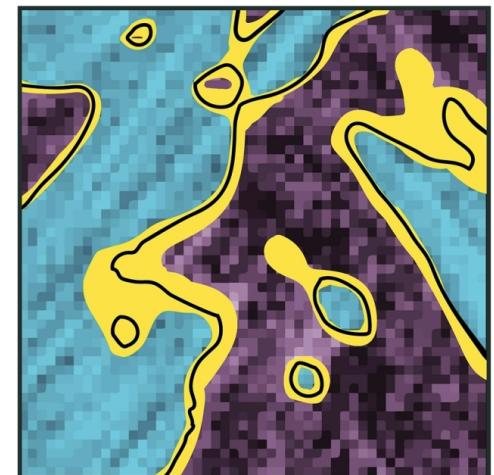
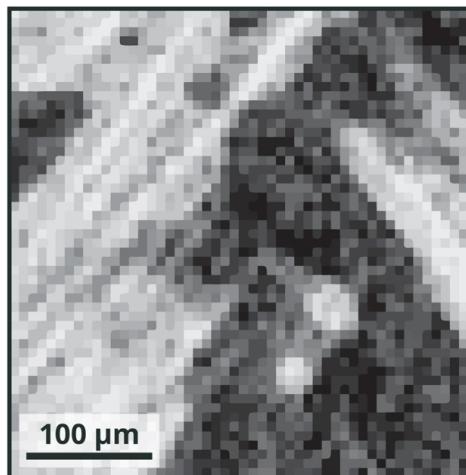


## Exemplar: Thermal protection system (TPS) materials



## CAMI key insights

- Volumetric segmentation of materials can be credibly automated with few labeled examples.
- Image-based simulations can be sensitive to small changes in geometries.
- Deep learning models can interpret images into geometries with uncertainty.
- A subset of simulations can characterize expected system properties.

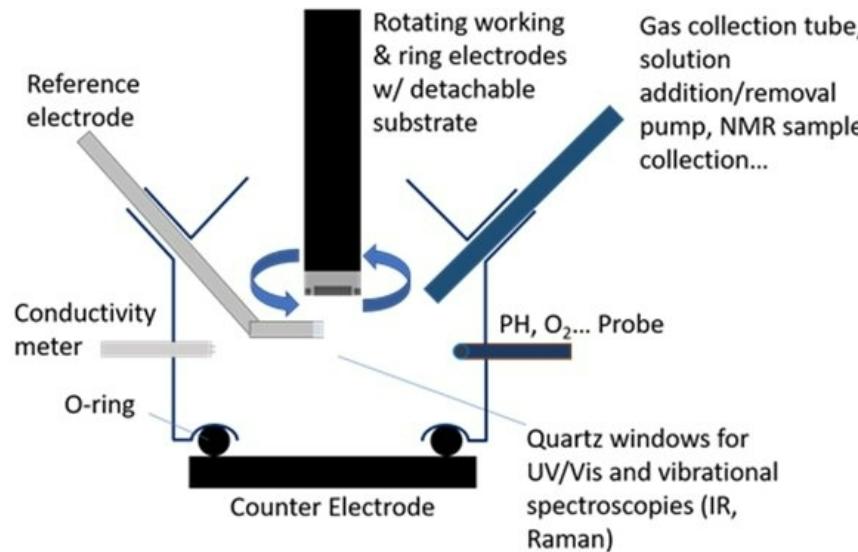


# Beyond Fingerprinting Grand Challenge LDRD

Brad Boyce and Remi Dingreville, Co-PIs



# Goal: AI-enabled high-throughput materials co-design



## High-throughput fabrication

**Fabrication:** thin films (laser powder bed fusion, electroplating, physical vapor deposition), semiconductor

components, integrated lasers and silicon photonics

**Process:** high-dimensional control parameter space

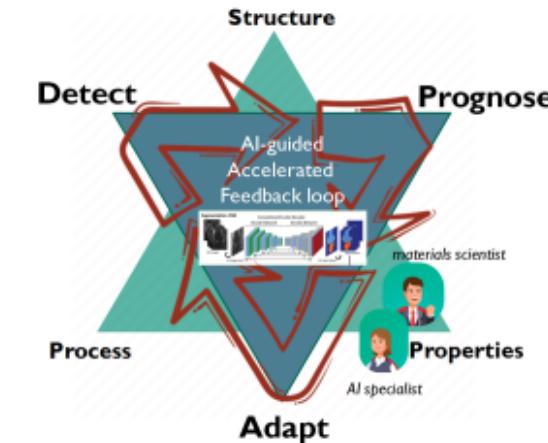
**Structure:** molecular/mesoscale description of material

**Property:** targeted mechanical/electromagnetic property

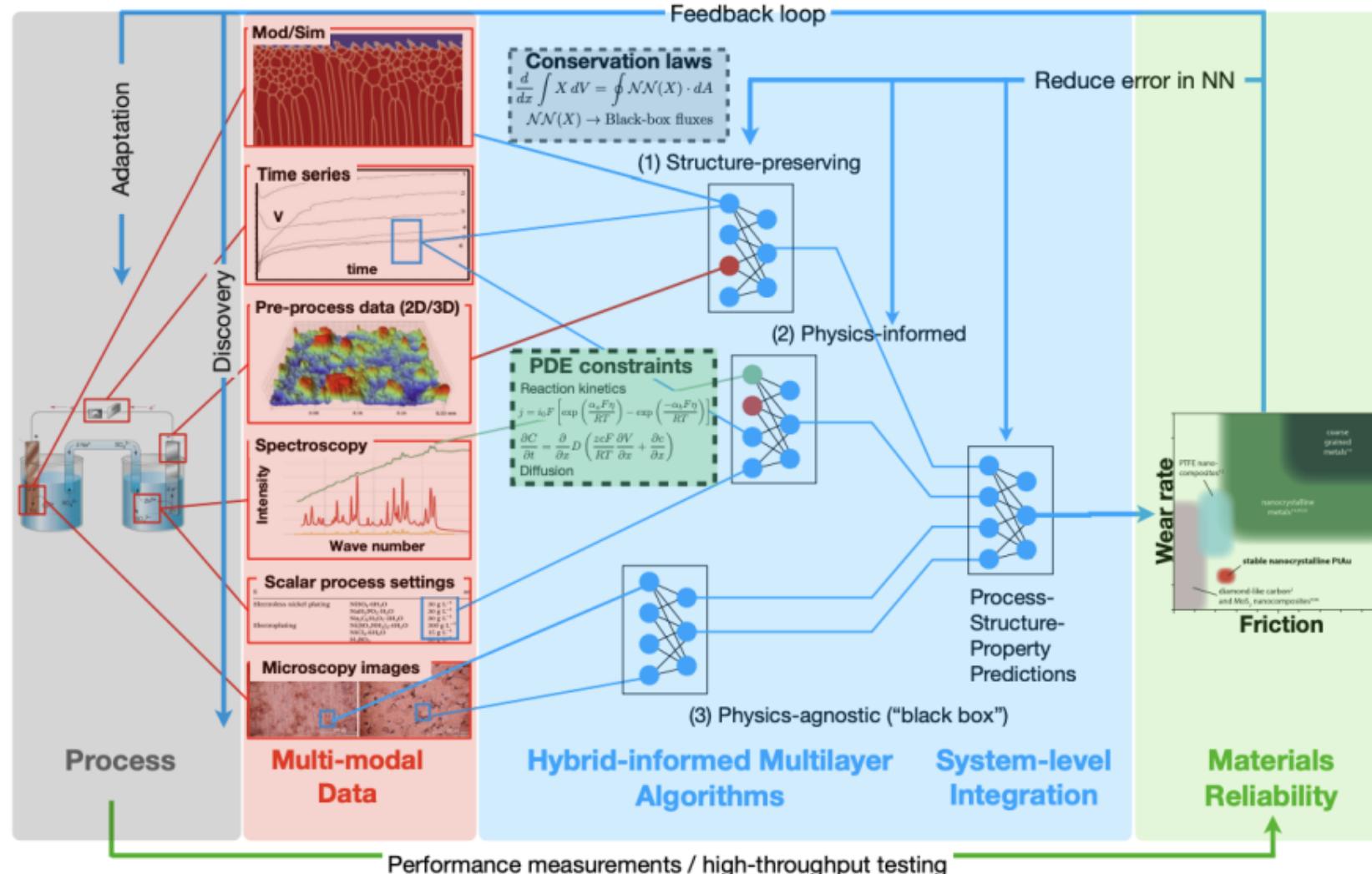


Figure 7. An example witness artifact that enables rapid measurement of 11 material properties in a compact footprint.

## High-throughput characterization

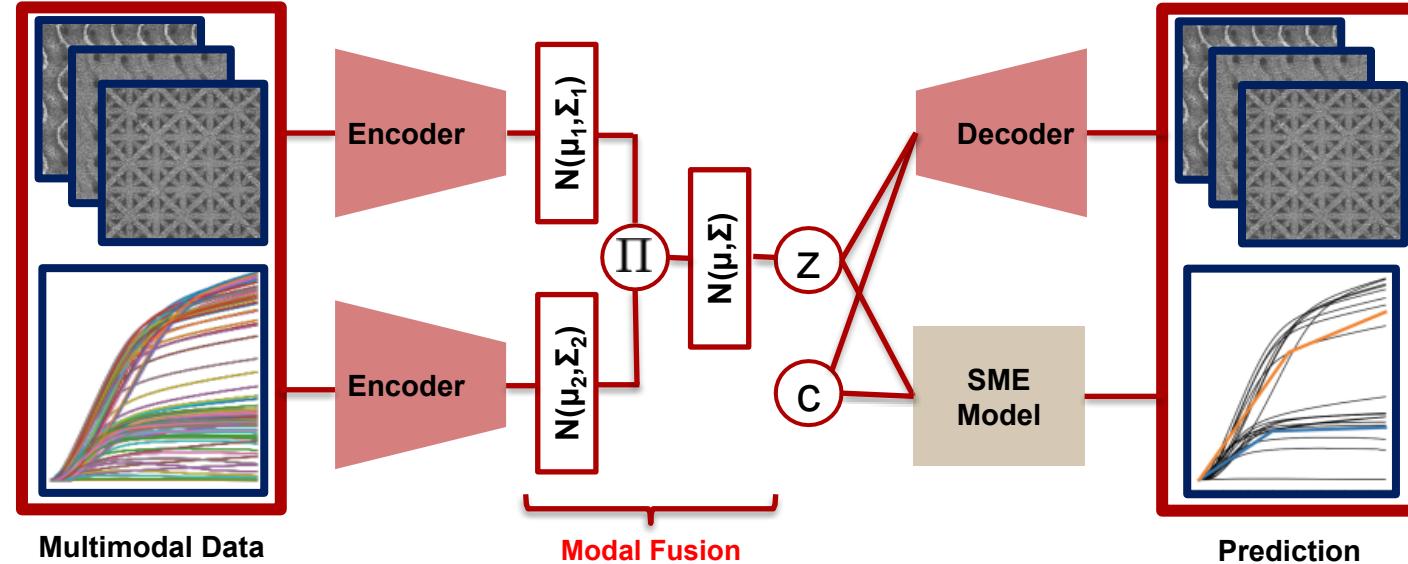


# Hybrid-informed multilayer algorithm (Himulaya)



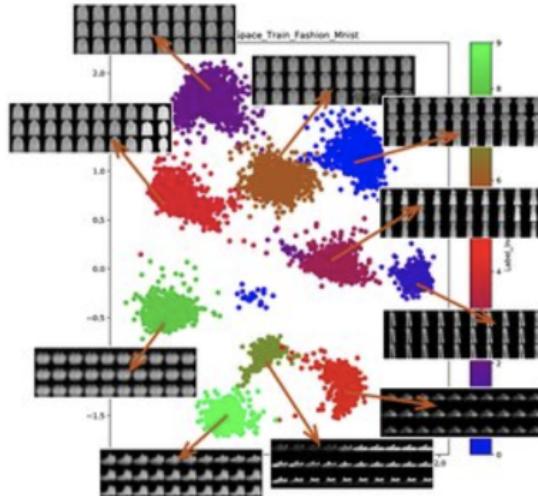
**Objective:** Exploit multimodality spanning process-structure-property gap, embed physical modeling expertise, learn fingerprints to detect, prognose + adapt

# PIMA – physics-informed multimodal autoencoder (Nat Trask)



Trask, N., Martinez, C., Lee, K., & Boyce, B. (2022). Unsupervised physics-informed disentanglement of multimodal data for high-throughput scientific discovery. *arXiv preprint arXiv:2202.03242*.

**Informal Idea:**  
We discover a shared latent representation of data providing a Rosetta stone for across modalities w/ uncertainty

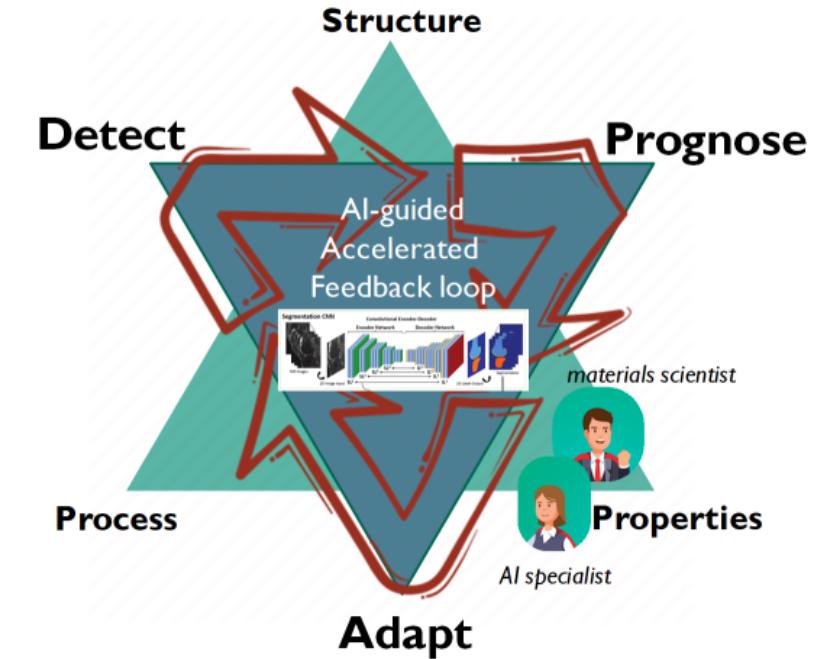


**Formal Idea:**

- Gaussian product distribution gives deep posterior embedding for each modality
- Gauss mixture prior in latent space identifies populations in data across modalities
- *Closed form expressions* for loss – no Monte Carlo
  - Supports Bayesian inference across modalities

## Digital twin building blocks:

- Advances in automated processing of multimodal data
- Leveraging transfer learning
- Uncertainty quantification for each workflow step
- Incorporation of domain knowledge
- Integrated interdisciplinary teams





Questions?  
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