

Quantification and Propagation of Uncertainties in Machine Learning Interatomic Potentials for Molecular Dynamics

Model errors and active learning

SIAM UQ

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ENERGY

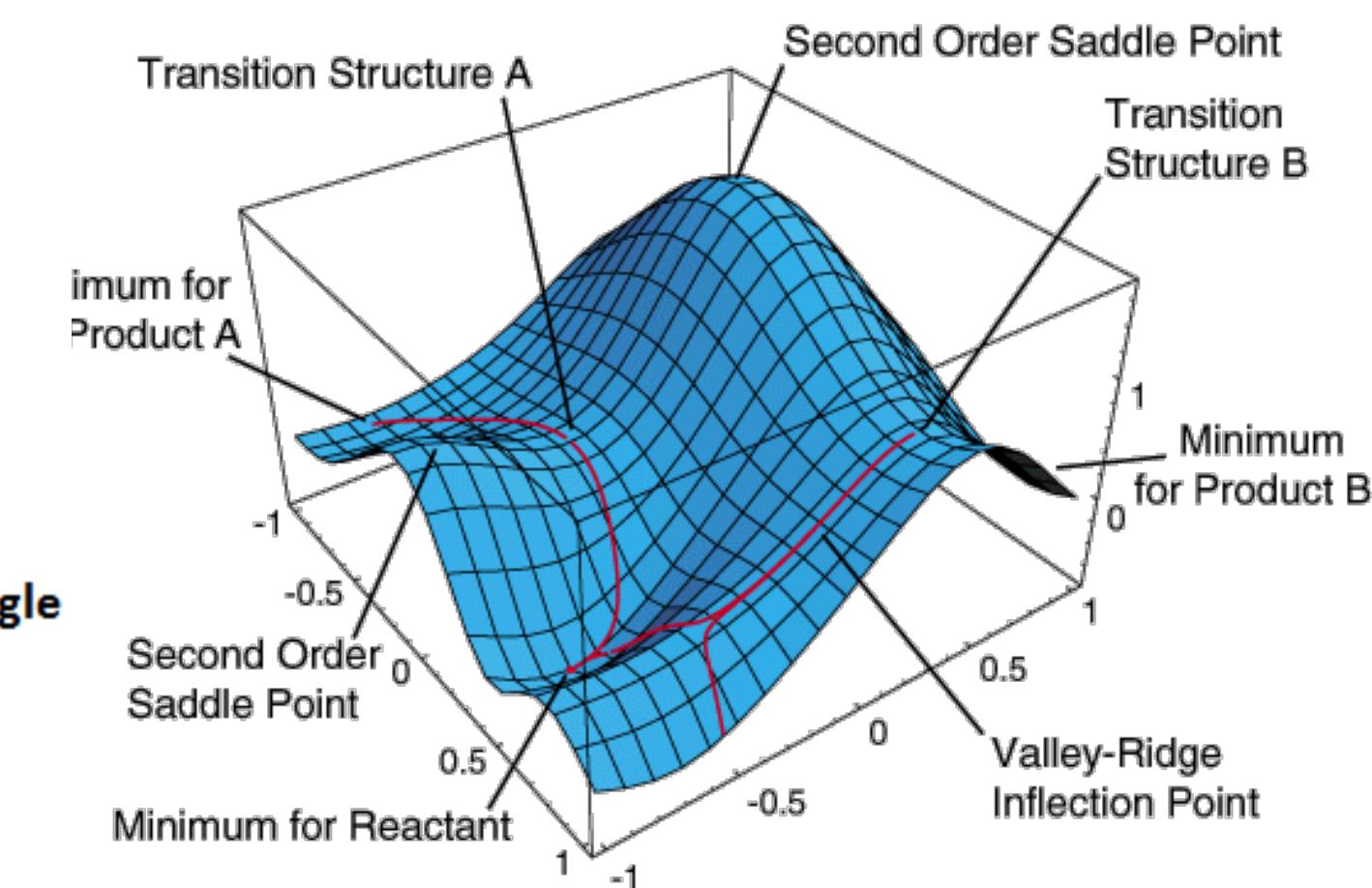
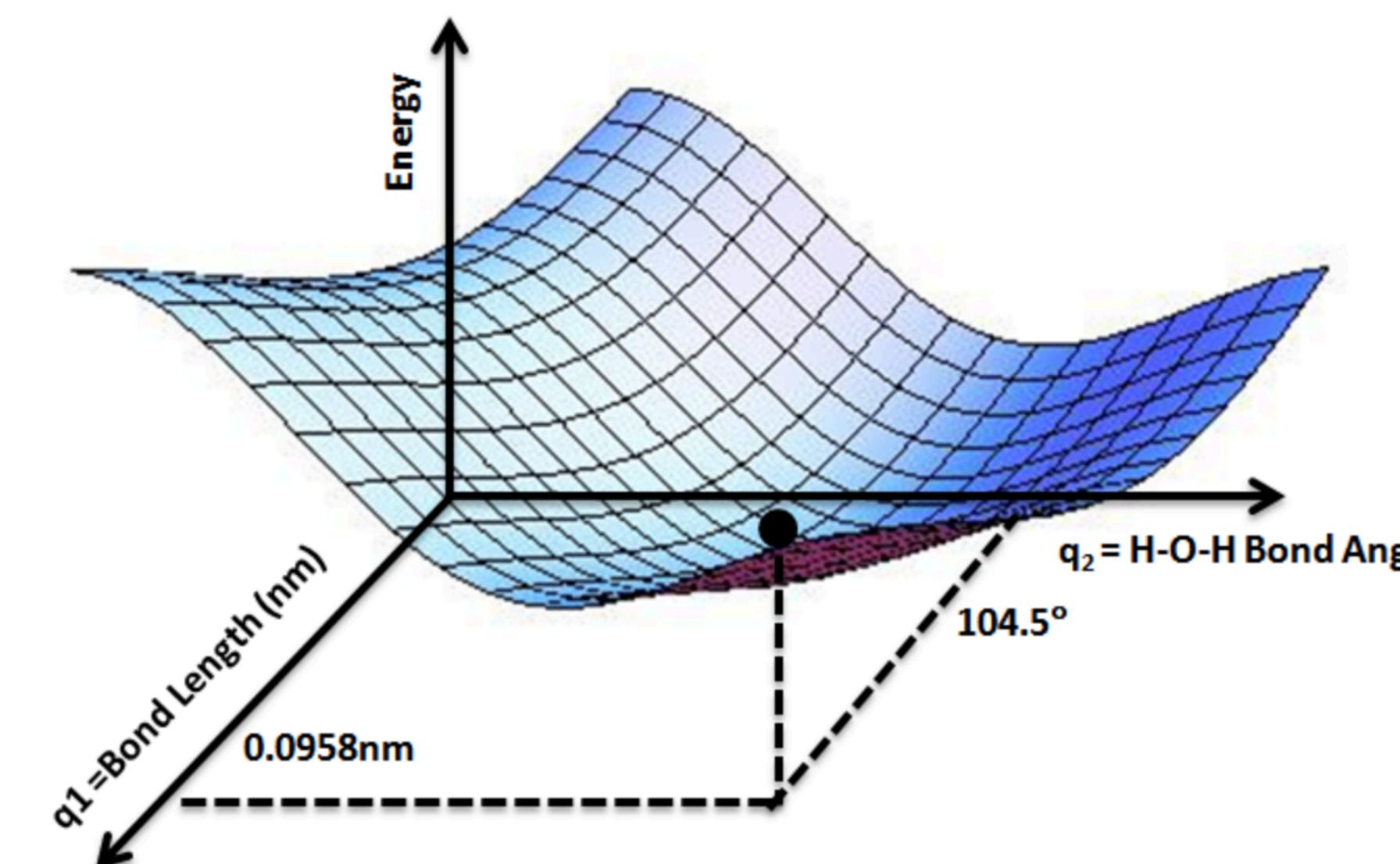
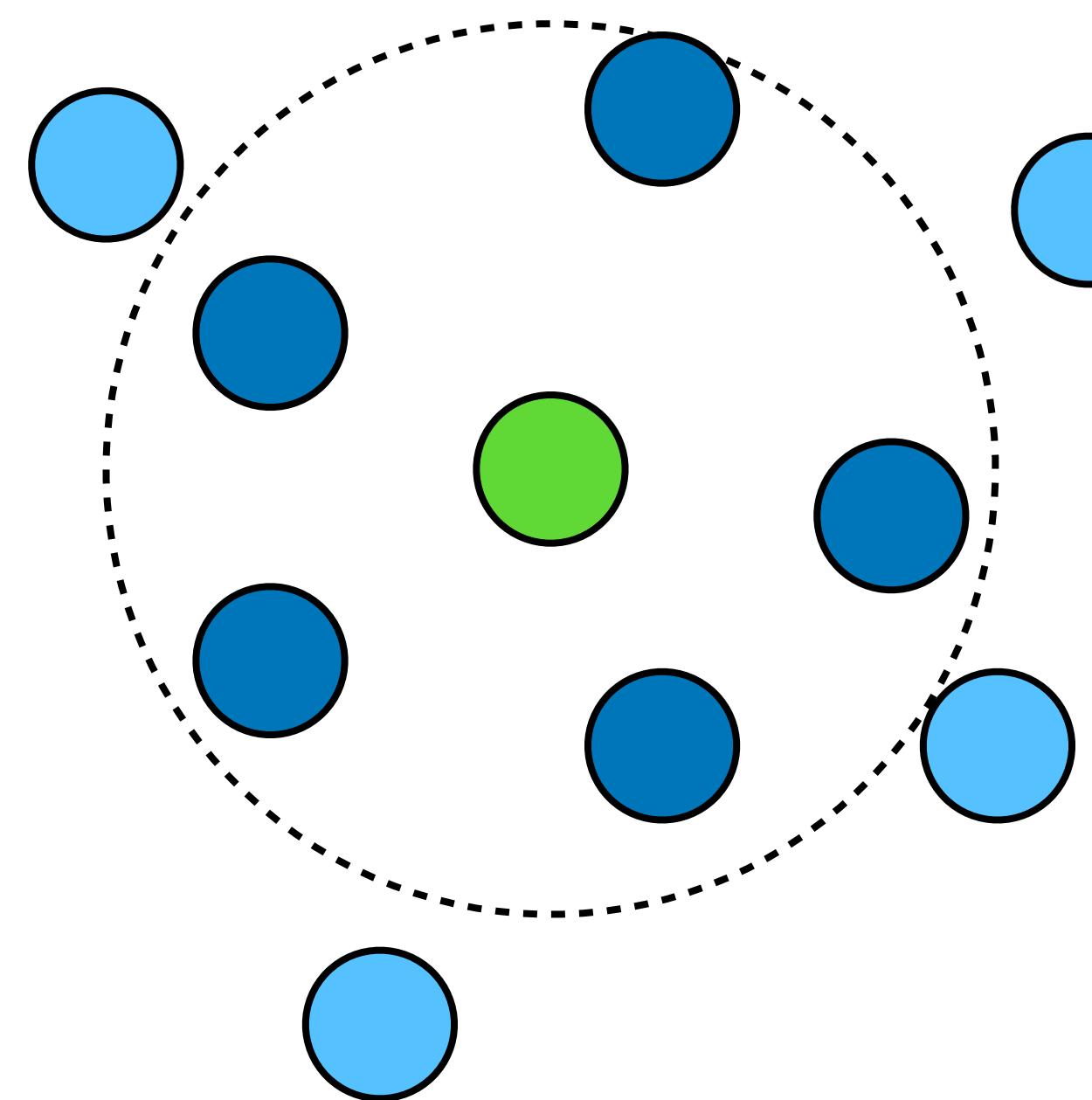
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Outline

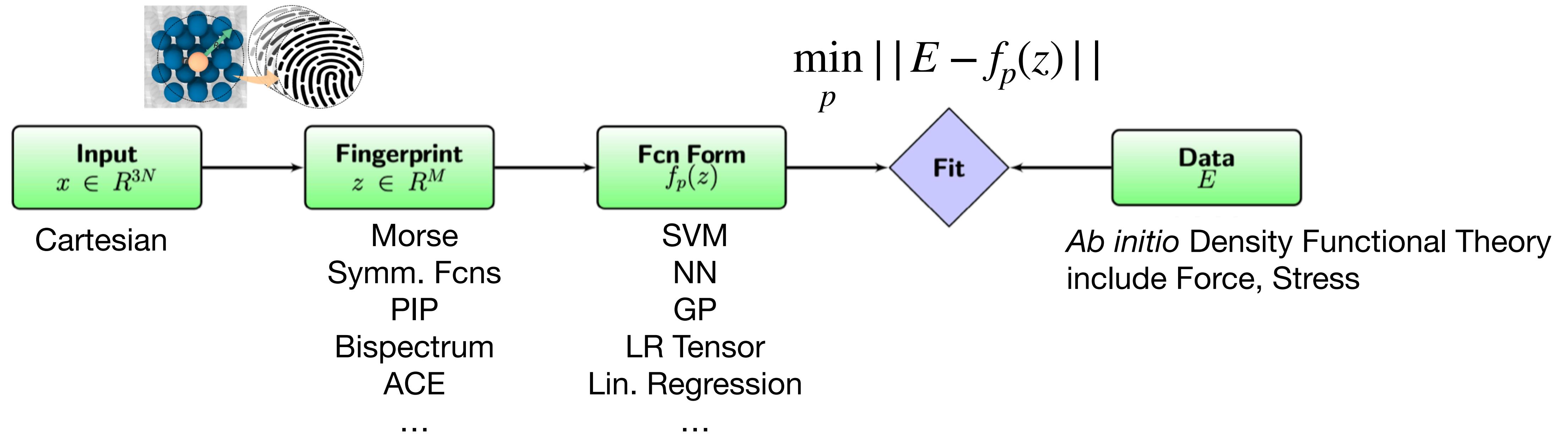
- Interatomic potentials as building blocks to approximate potential energy surfaces
- Machine learning interatomic potentials (MLIAP) - a supervised ML problem
- Active learning and need for uncertainty estimation in MLIAP construction
- (Bayesian) MLIAP hinges on proper assumptions for model-data discrepancies
- Embedded model error approach for uncertainty estimation in MLIAPs

Interatomic Potentials

- Object of interest: potential energy E of a system defined by a configuration x , where x encapsulates coordinates of all atoms in the system
- Typically additive form. $E(x) = E_{ref} + \sum_i E(x_i) + \dots$ using local environments



Ingredients of MLIAPs (supervised ML problem)



- Training data (x_i, E_i) for $i = 1, \dots, S$ and $x_i \in R^{3N}$
- Input representation, aka fingerprint, aka descriptor $x \rightarrow z(x)$
- Parametrized functional form of the approximation class $f_p(z)$
- Loss function: $\min_p \sum_{i=1}^S [E_i - f_p(z_i)]^2 + \text{regularization}$

State-of-the-art: largely manual and lacking systematic UQ

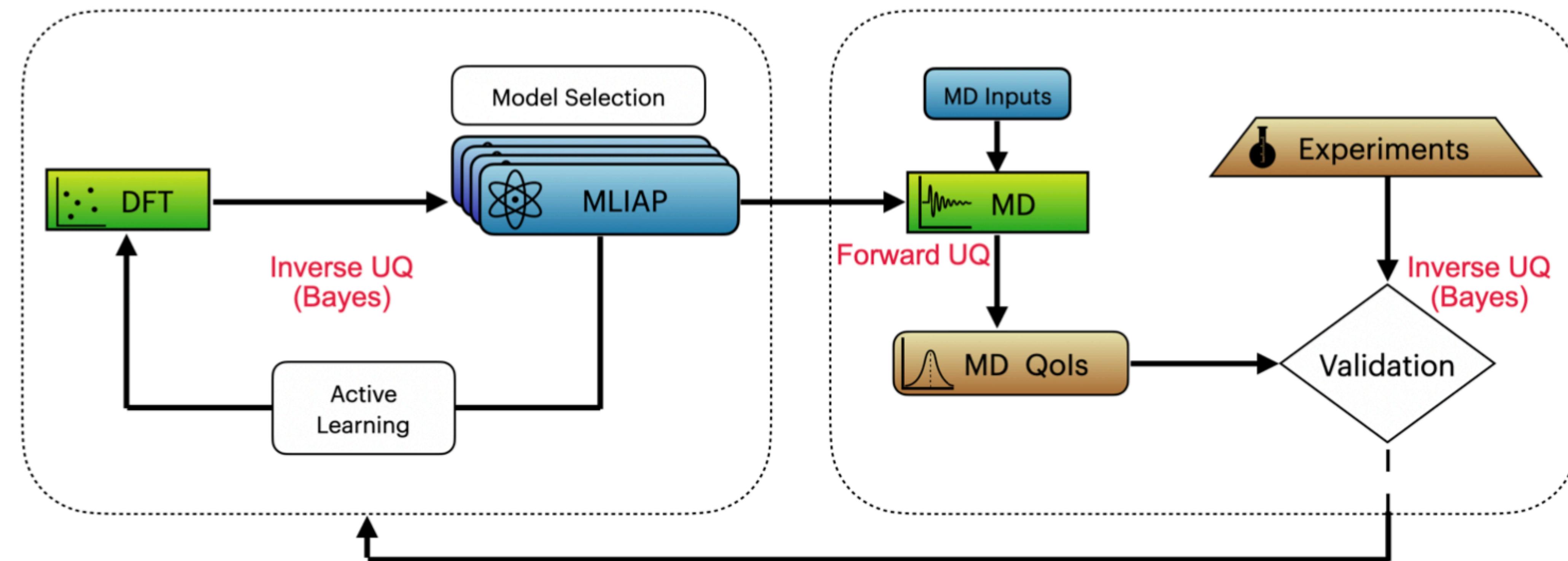
MLIAP Construction

- ◆ Good training set selection: active learning
- ◆ Fingerprint choice: invariances, symmetries
- ◆ Functional form choice: model selection
- ◆ Loss function: regularization, weighting energies and forces

MLIAP Usage

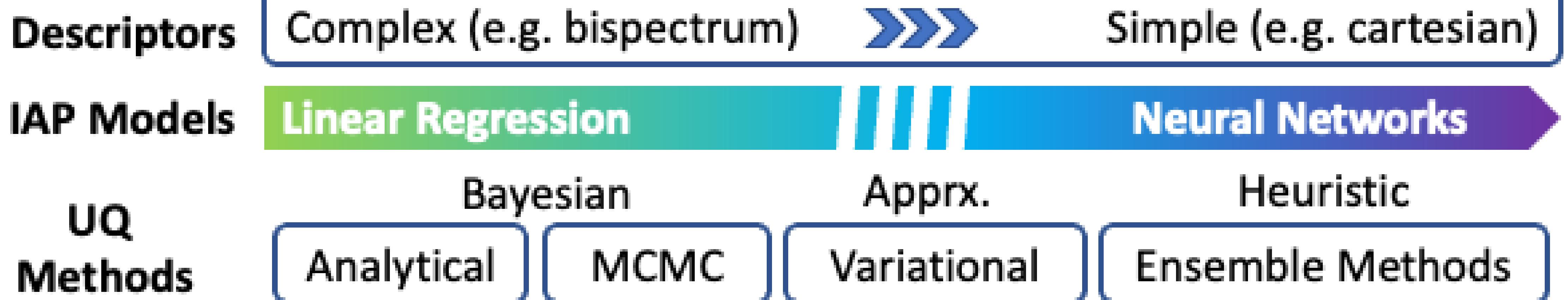
- ◆ Find reaction pathways, saddle points
- ◆ Pipe the IAPs to MD simulations

Big Picture

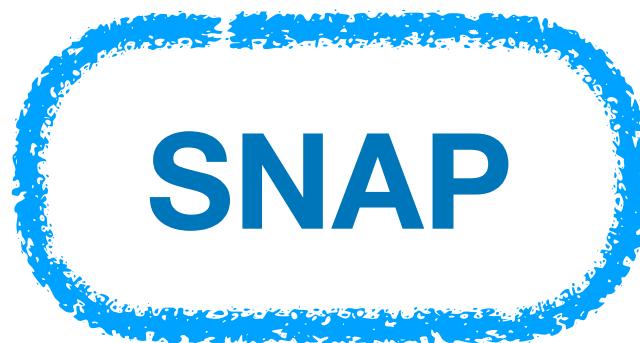


**Bayesian inference of IAPs, model errors
Active learning**

Equipping parametric fits with uncertainties



Equipping parametric fits with uncertainties



A.P. Thompson et al. “Spectral neighbor analysis method for automated generation of quantum-accurate interatomic potentials”, *Journal of Computational Physics*, 285(15), pp. 316-330, 2015.

Descriptors

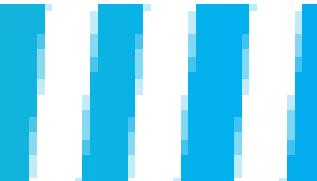
Complex (e.g. bispectrum)



Simple (e.g. cartesian)

IAP Models

Linear Regression



Neural Networks

UQ Methods

Bayesian

Apprx.

Heuristic

Analytical

MCMC

Variational

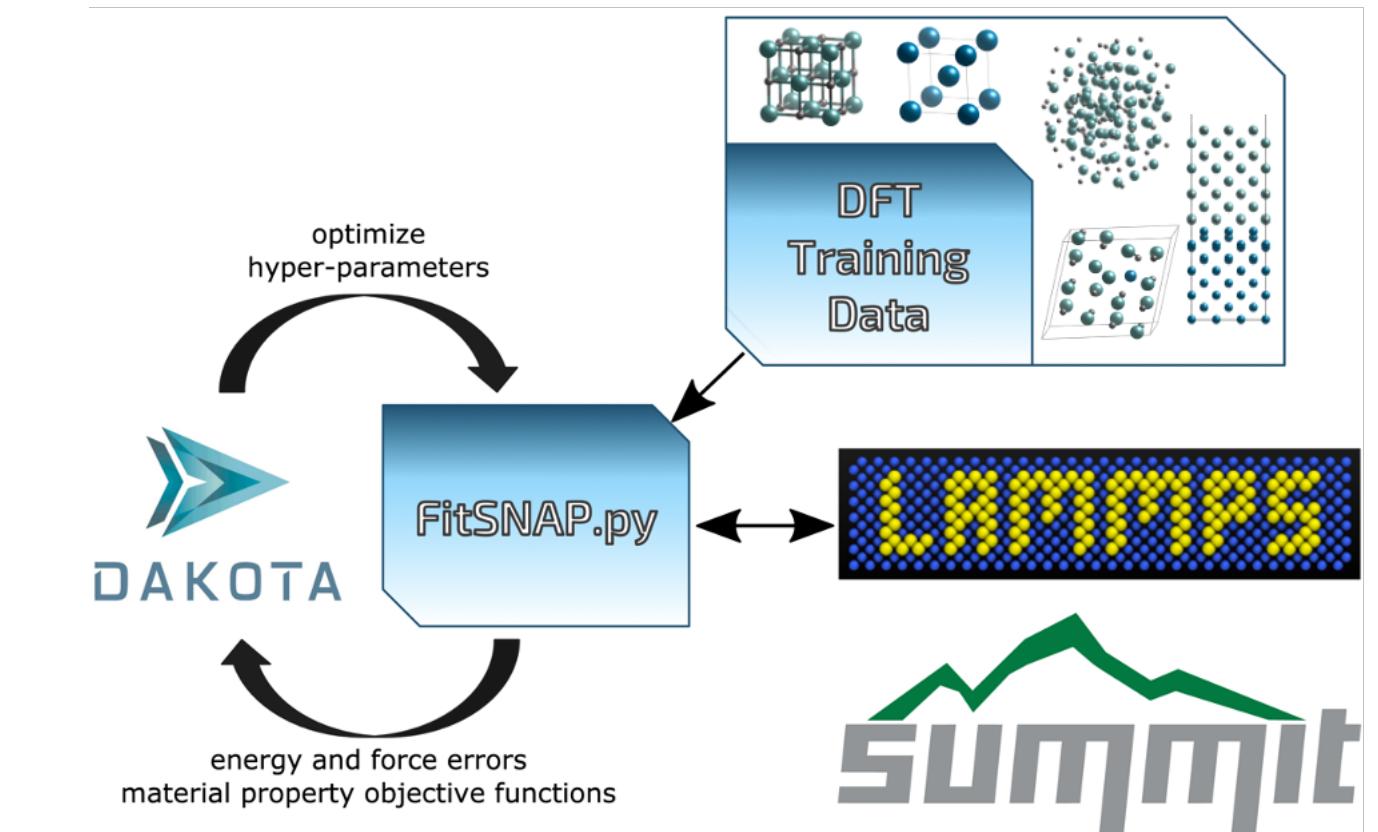
Ensemble Methods

Spectral neighbor analysis potential (SNAP) details

- Uses **bispectrum** as fingerprints:
 - uses hyper spherical harmonics
 - respects rotational, permutational, translational invariances
 - incorporates forces and stresses as well
 - tunable complexity/order

$$E(x) \approx \sum_k c_k B_k(x)$$

A.P. Thompson et al. “Spectral neighbor analysis method for automated generation of quantum-accurate interatomic potentials”, *Journal of Computational Physics*, 285(15), pp. 316-330, 2015.

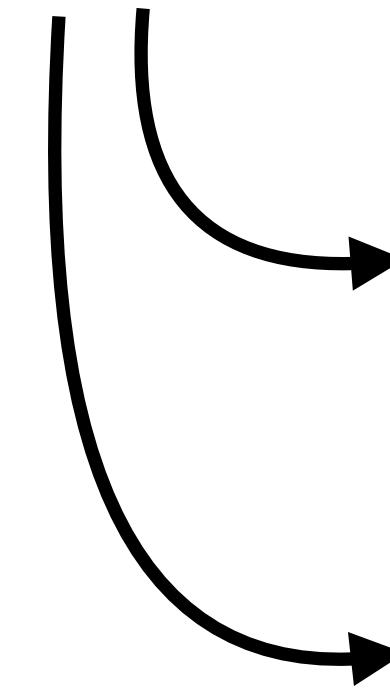


- Uses **linear regression** as model form:
 - built on hyper spherical harmonics basis functions
 - generalized to quadratic form as well

M. Wood and A. Thompson , “Extending the accuracy of the SNAP interatomic potential form”, *Journal of Chemical Physics*, 148, 2018.

(Bayesian) Parameter Inference

- Given a model $f(x, c)$ and data $y_i = y(x_i)$, calibrate parameters c .



Linear model $y \approx Ac$ with coefficients c

NN model $y \approx NN_c(x)$ with weights/biases c

- Bayesian least-squares fit:

$$p(c | y) \propto p(y | c)p(c) \propto \prod_{i=1}^N \exp\left(-\frac{(f(x_i, c) - y_i)^2}{2\sigma_i^2}\right)$$

Corresponding data model

$$y_i = f(x_i, c) + \sigma_i \epsilon_i$$

Elephant in the room: model is assumed to be ***the*** correct model behind data

$$y_i = f(x_i, c) + \sigma_i \epsilon_i$$

Ignoring model error hurts in a few ways:

- ◆ One gets biased estimates of parameters c (crucial if the model is physical, and/or c is propagated through other models)
- ◆ More data leads to overconfident predictions (we become more and more certain about the wrong values of the data)
- ◆ More evident when there is no (observational/experimental) data error: e.g. DFT is data, and MLIAPI is model

Posterior uncertainty does not capture true discrepancy

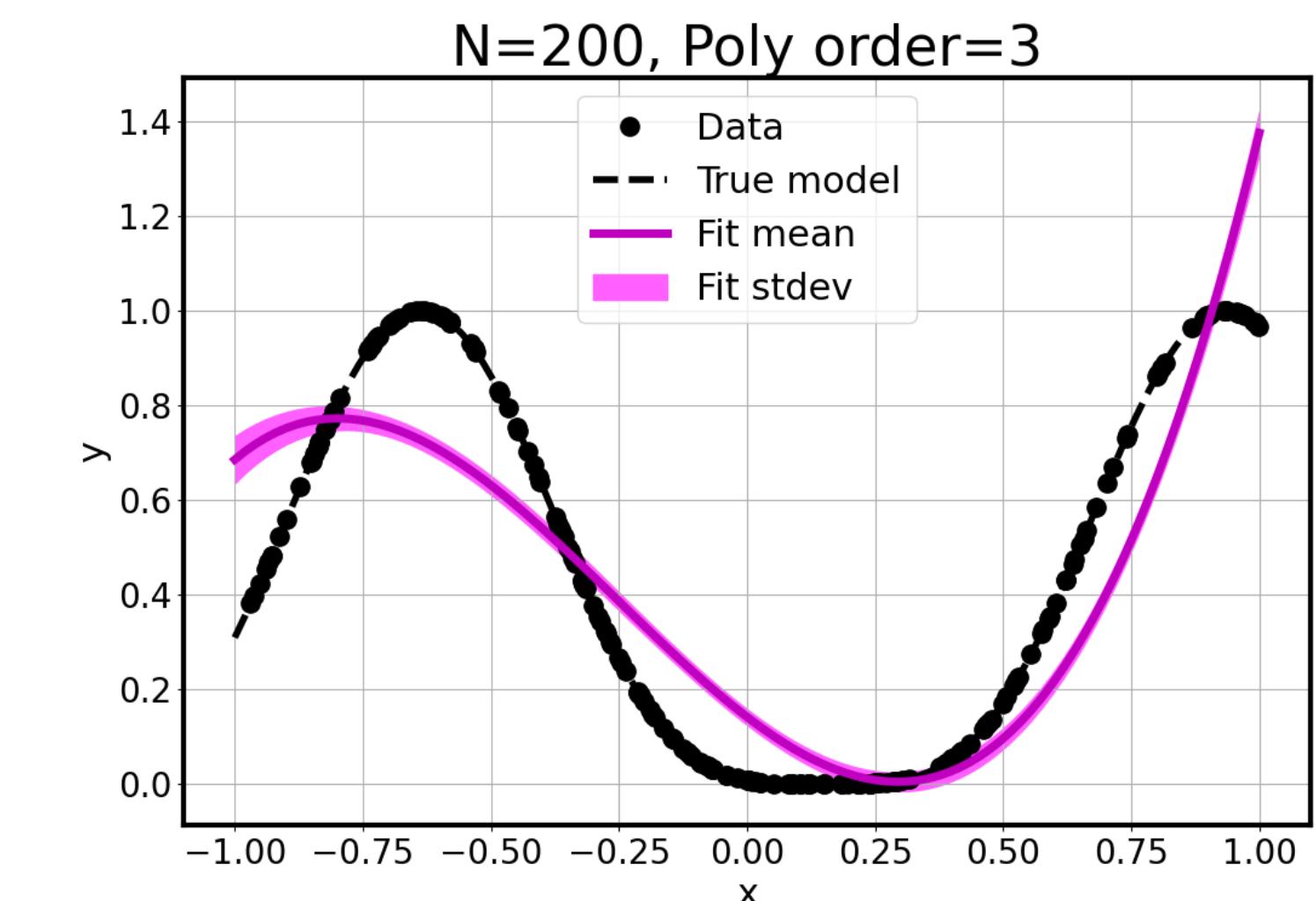
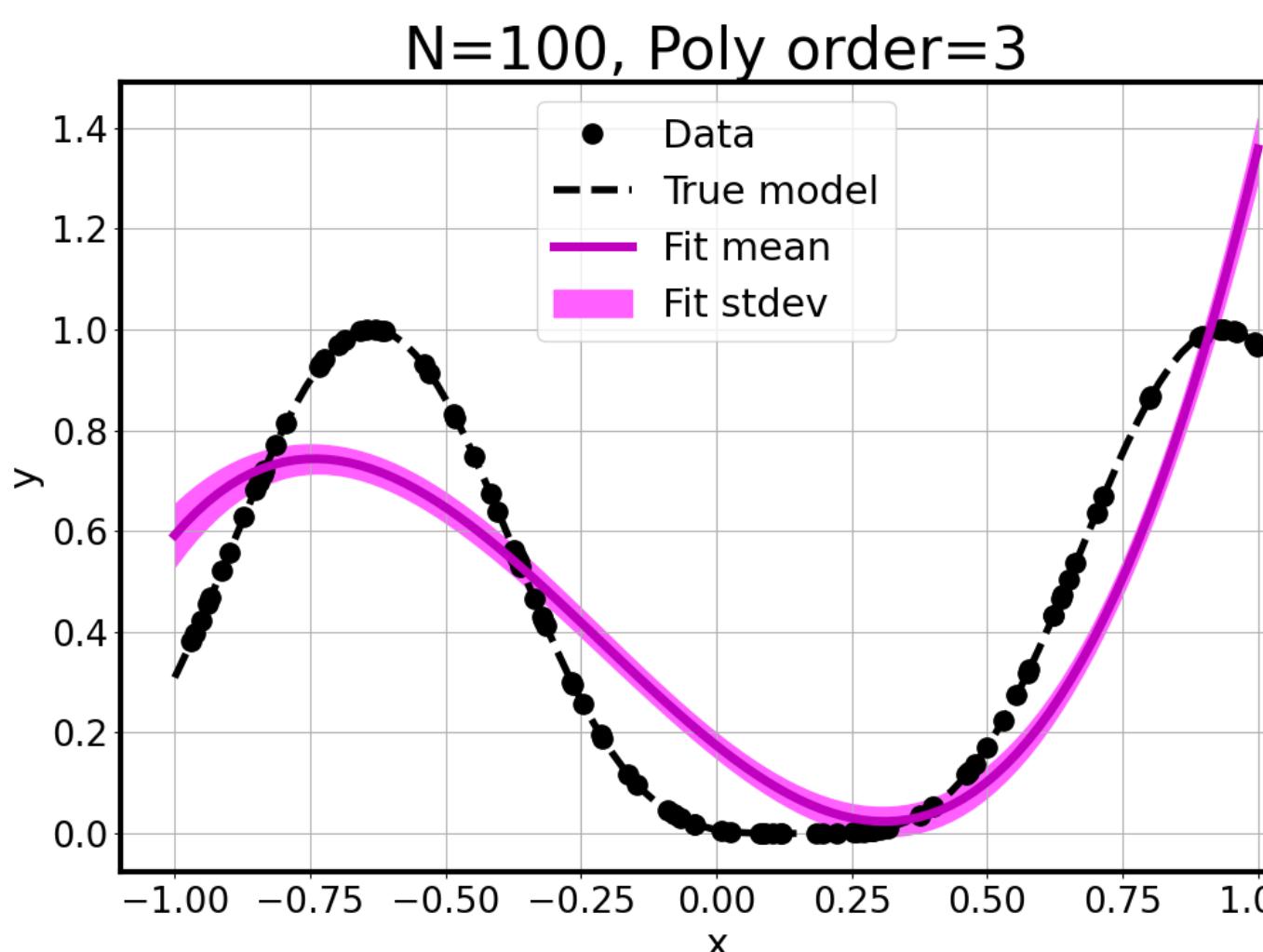
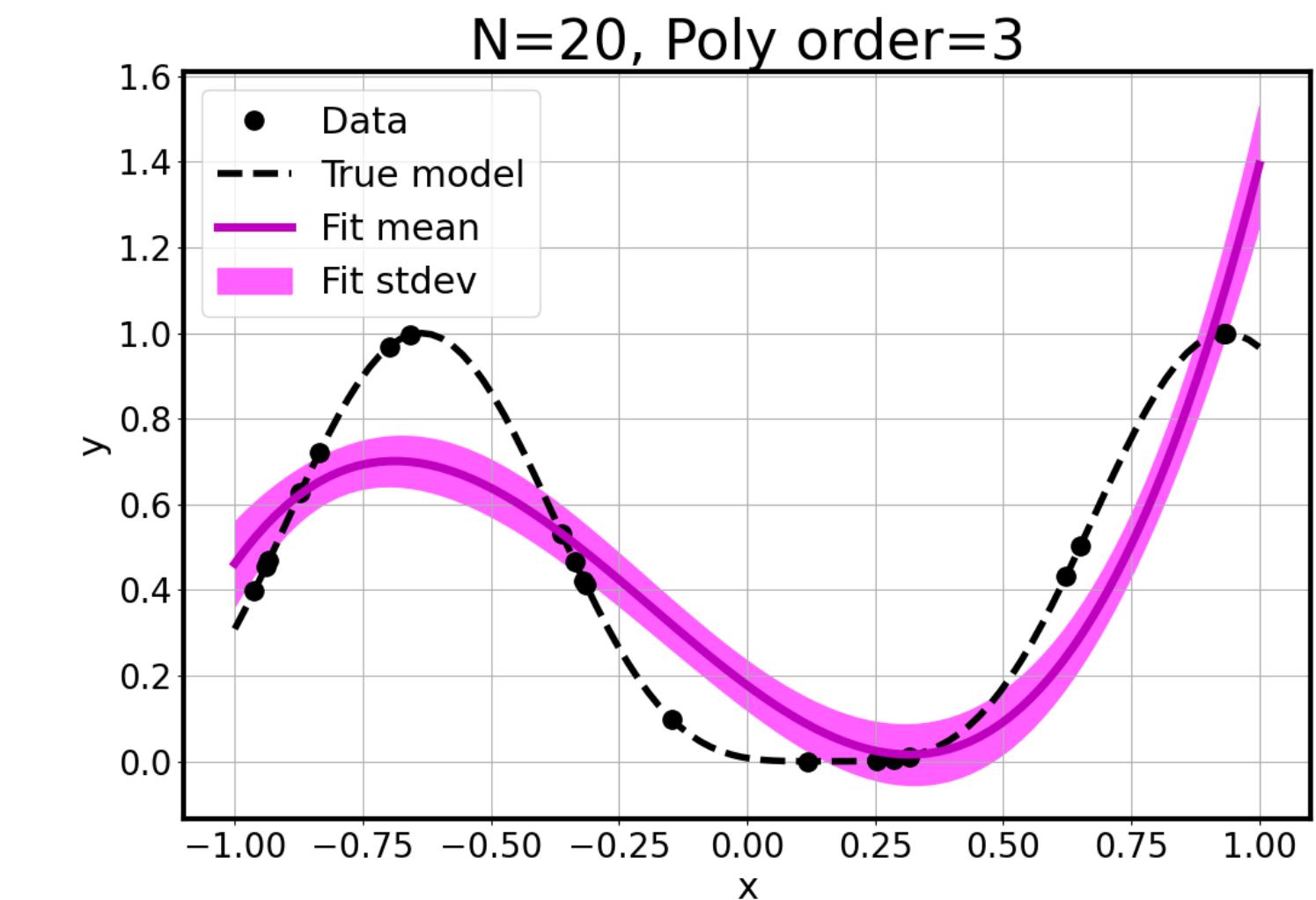
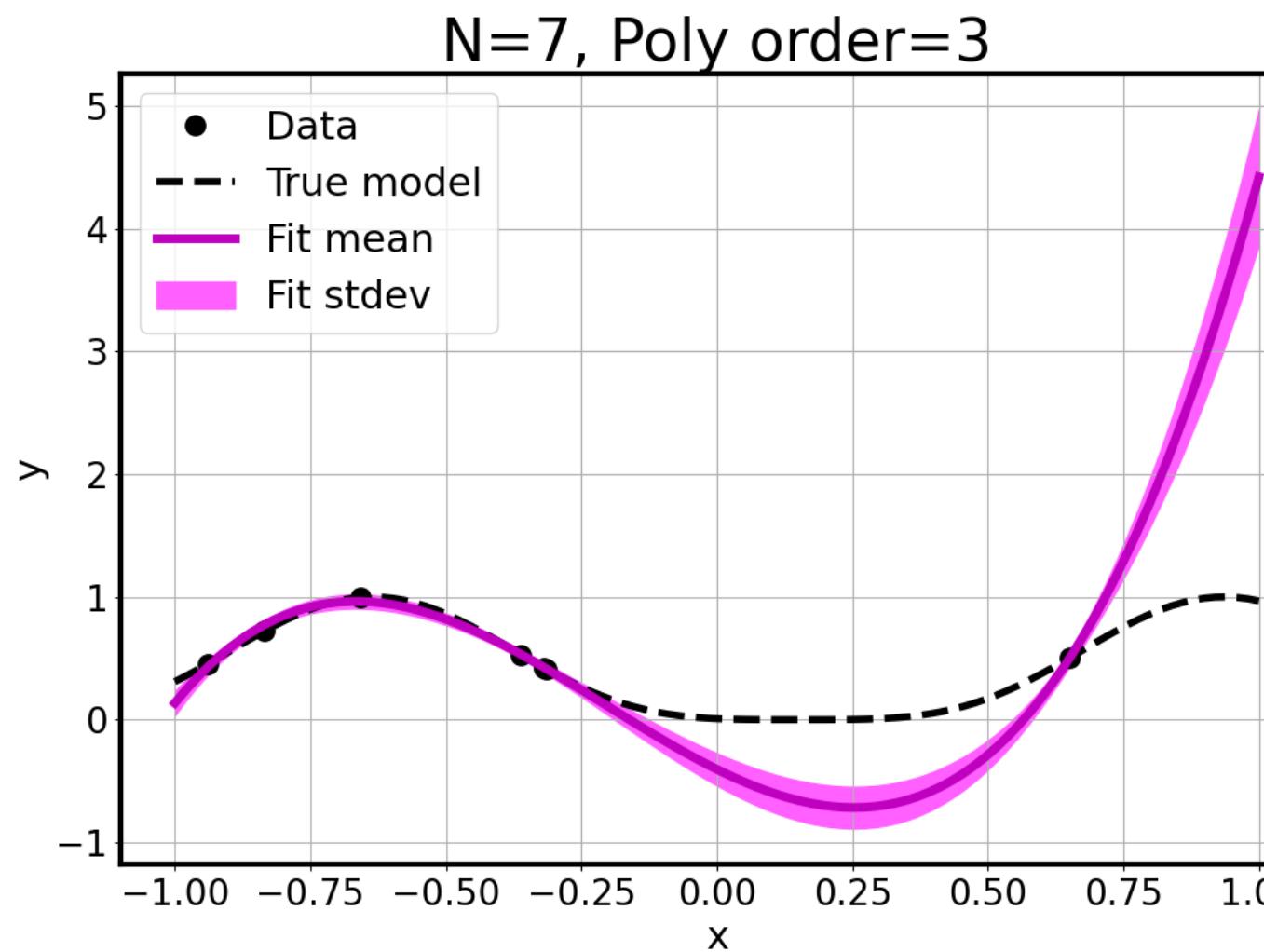
Synthetic data

$$y(x) = \sin^4(2x - 0.3)$$

Cubic fit

$$y_i \approx \sum_{k=0}^3 c_k B_k(x)$$

More data leads to
overconfident prediction



Capturing Model Error in Likelihood (a.k.a. Data Model)

$$y_i = f(x_i, c) + \delta(x_i) + \sigma_i \epsilon_i$$

External correction

(Kennedy-O'Hagan):

- Kennedy, O'Hagan, “Bayesian Calibration of Computer Models”.
J Royal Stat Soc: Series B (Stat Meth), 63: 425-464, 2001.

$$y_i = f(x_i, c + \delta(x_i)) + \sigma_i \epsilon_i$$

Internal correction

(embedded model error):

- Allows meaningful usage of calibrated model
- ‘Leftover’ noise term even with no data error
- Respects physics (not too relevant in our context)

• Sargsyan, Najm, Ghanem, “On the Statistical Calibration of Physical Models”.
Int. J. Chem. Kinet., 47: 246-276, 2015.

• Sargsyan, Huan, Najm, “Embedded Model Error Representation for Bayesian Model Calibration”.
Int. J. Uncert. Quantif., 9(4): 365-394, 2019.

Embedded Model Error for Linear Regression Models

$$\underline{y_i \approx \sum_{k=0}^P c_k B_k(x) + \sigma_i \epsilon_i}$$

‘Embed’ uncertainty in
all (or selected) coefficients

$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x) = \sum_{k=0}^P c_k B_k(x) + \sum_{k=0}^P d_k B_k(x) \xi_k$$

Note:
No formal distinction between
internal and external corrections,
but internal allows for interpretation
and model-informed error

(still Gaussian, but correlated,
and model-informed)

Embedded Model Error: likelihood choice is challenging

Classical data model

$$y_i \approx \sum_{k=0}^P c_k B_k(x) + \sigma_i \epsilon_i$$

$$p(c | y) \propto \prod_{i=1}^N \exp \left(-\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2}{2\sigma_i^2} \right)$$

MCMC sampling of c

Embedded model error

$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x) = \sum_{k=0}^P c_k B_k(x) + \sum_{k=0}^P d_k B_k(x) \xi_k$$

Option 1 (IID)

$$p(c, d | y) \propto \prod_{i=1}^N \exp \left(-\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2}{2 \sum_{k=0}^K d_k^2 B_k(x_i)^2} \right)$$

MCMC sampling of c, d
or
simply optimize the posterior for c, d

Embedded Model Error: likelihood choice is challenging

Classical data model

$$y_i \approx \sum_{k=0}^P c_k B_k(x) + \sigma_i \epsilon_i$$

$$p(c | y) \propto \prod_{i=1}^N \exp \left(-\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2}{2\sigma_i^2} \right)$$

MCMC sampling of c

Embedded model error

$$y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x) = \sum_{k=0}^P c_k B_k(x) + \sum_{k=0}^P d_k B_k(x) \xi_k$$

Option 2 (ABC)

$$p(c, d | y) \propto \prod_{i=1}^N \exp \left(-\frac{(\sum_{k=0}^P c_k B_k(x_i) - y_i)^2 + (\sqrt{\sum_{k=0}^P d_k^2 B_k^2(x_i)} - \alpha | \sum_{k=0}^P c_k B_k(x_i) - y_i |)^2}{2\epsilon^2} \right)$$

Pushed forward predictive uncertainty captures the true discrepancy from the data

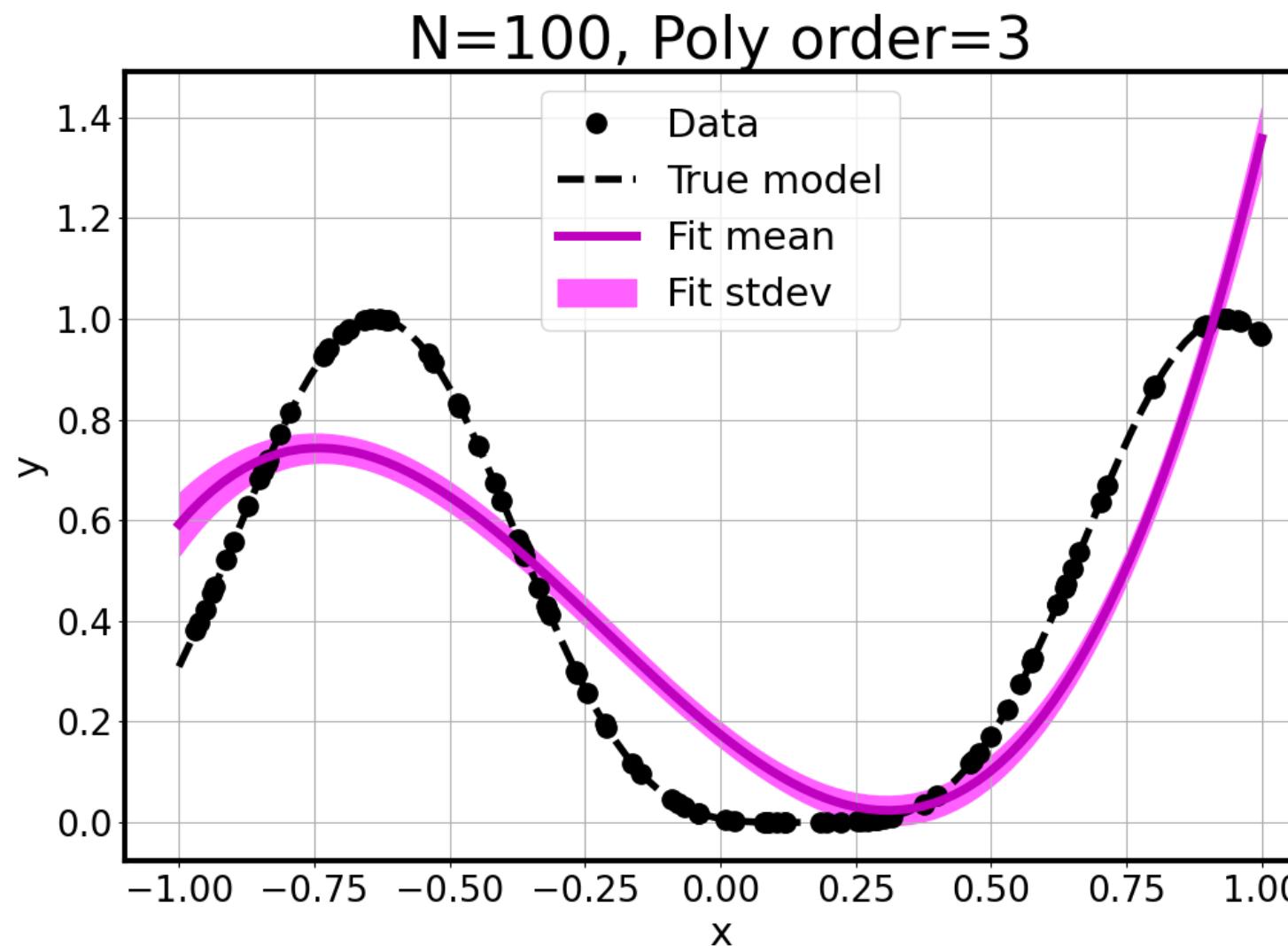
Synthetic data

$$y(x) = \sin^4(2x - 0.3)$$

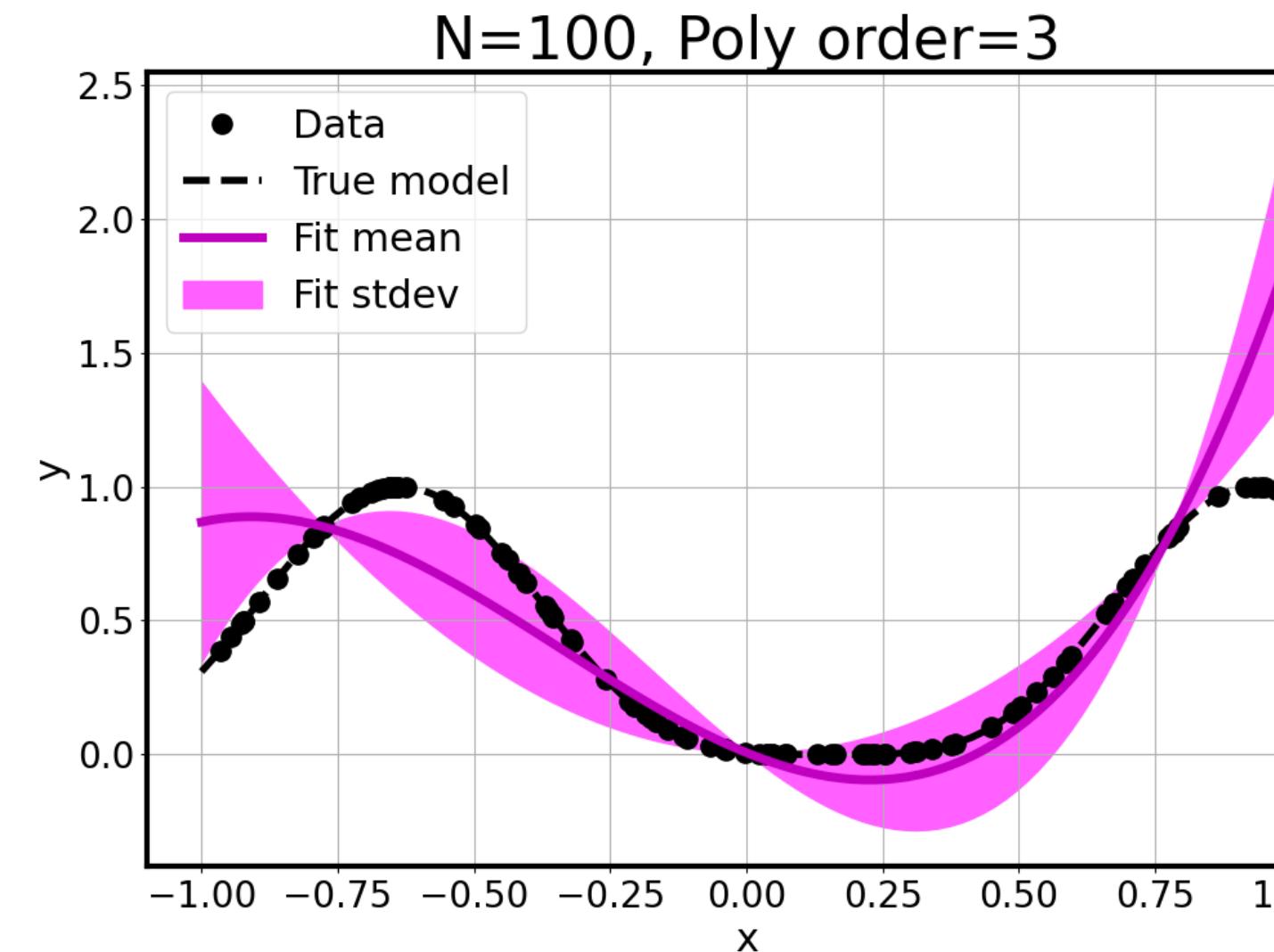
Cubic fit

$$y_i \approx \sum_{k=0}^3 c_k B_k(x)$$

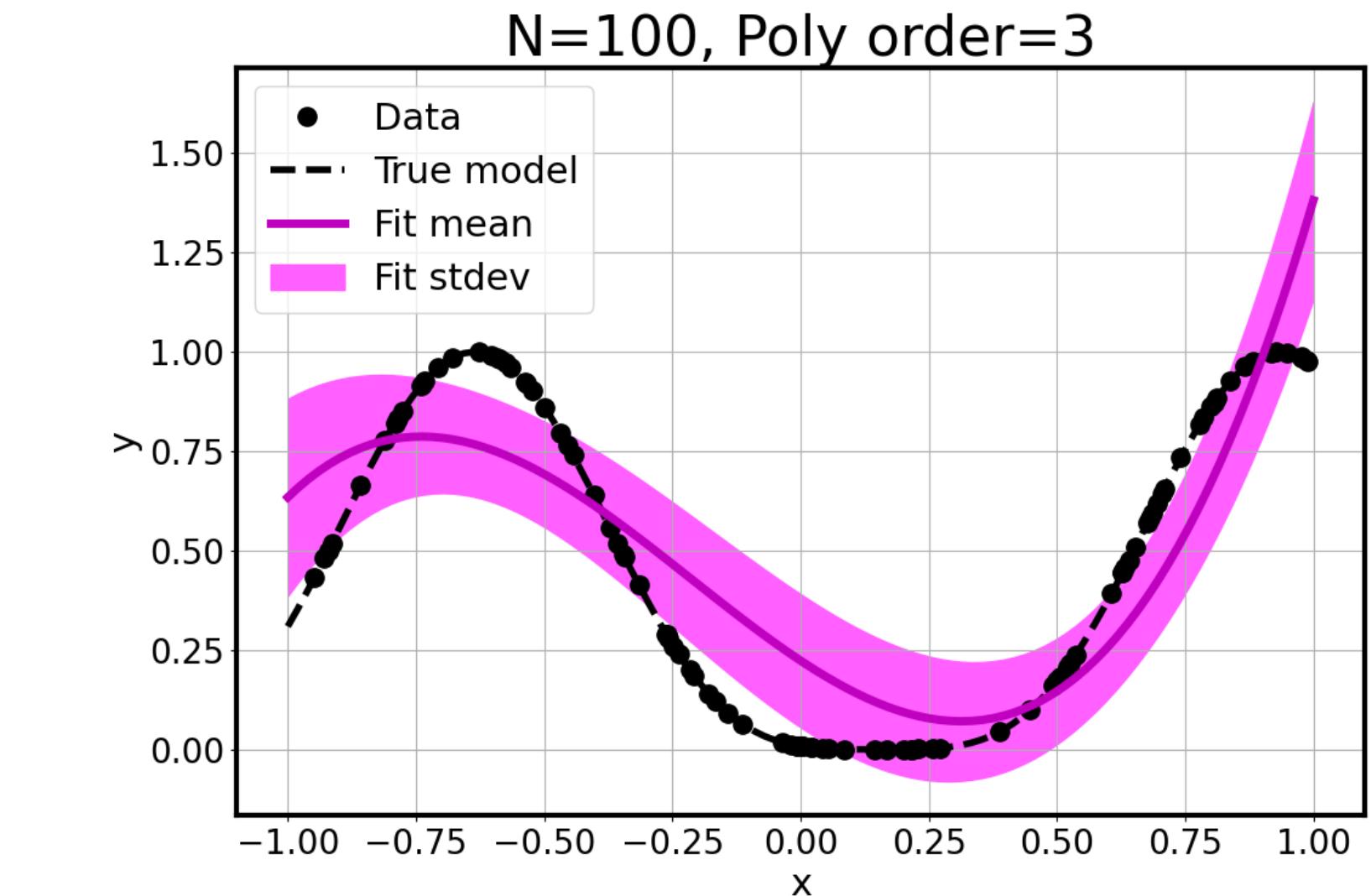
Classical case



Model error, IID likelihood

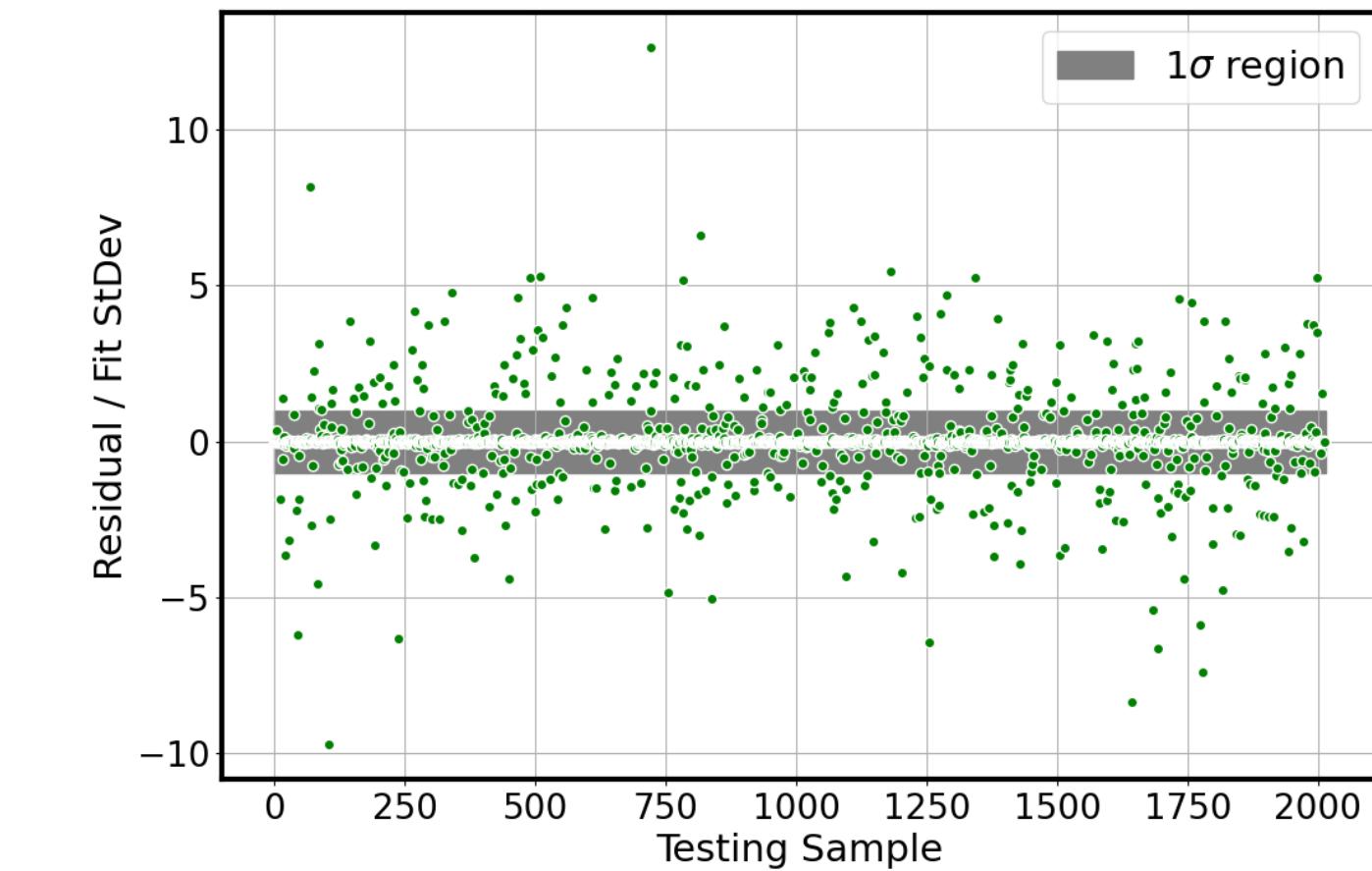
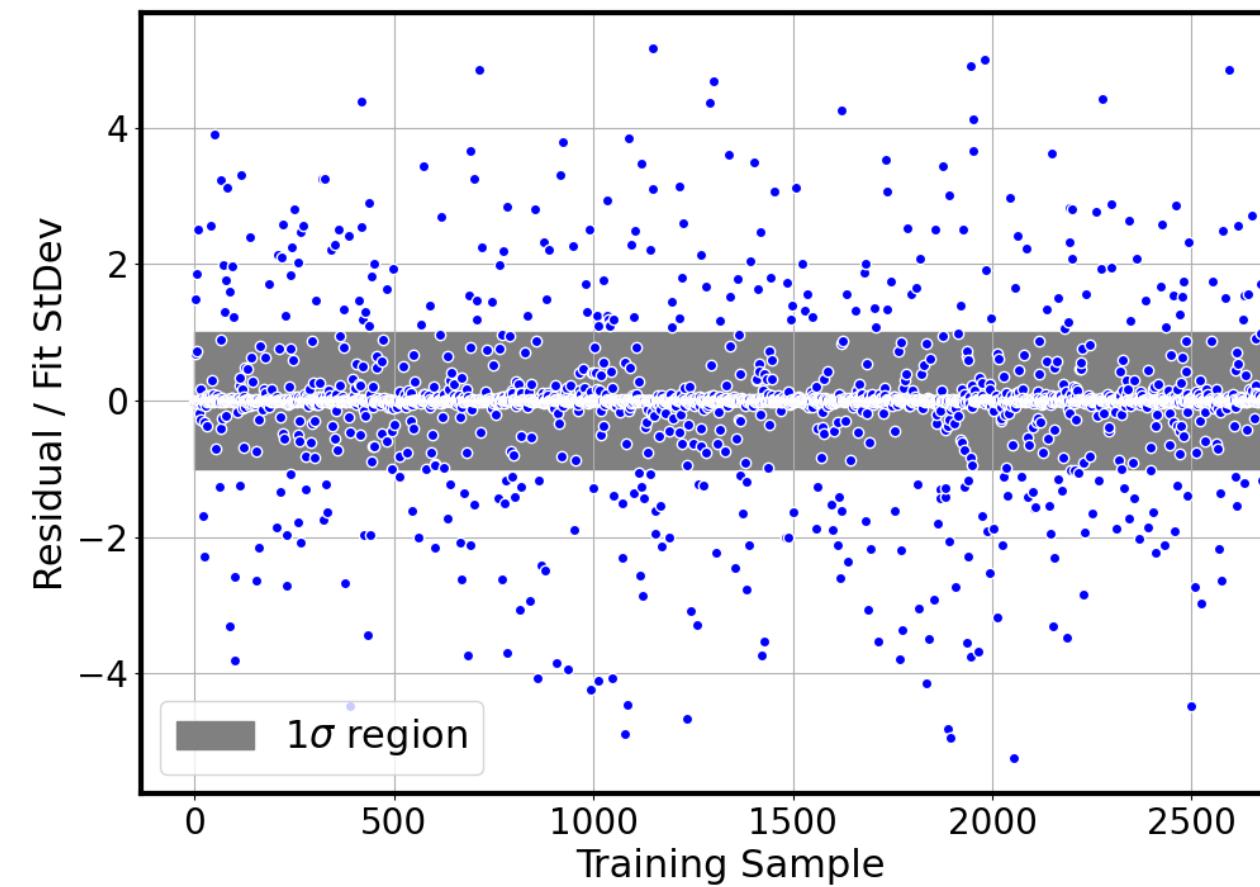
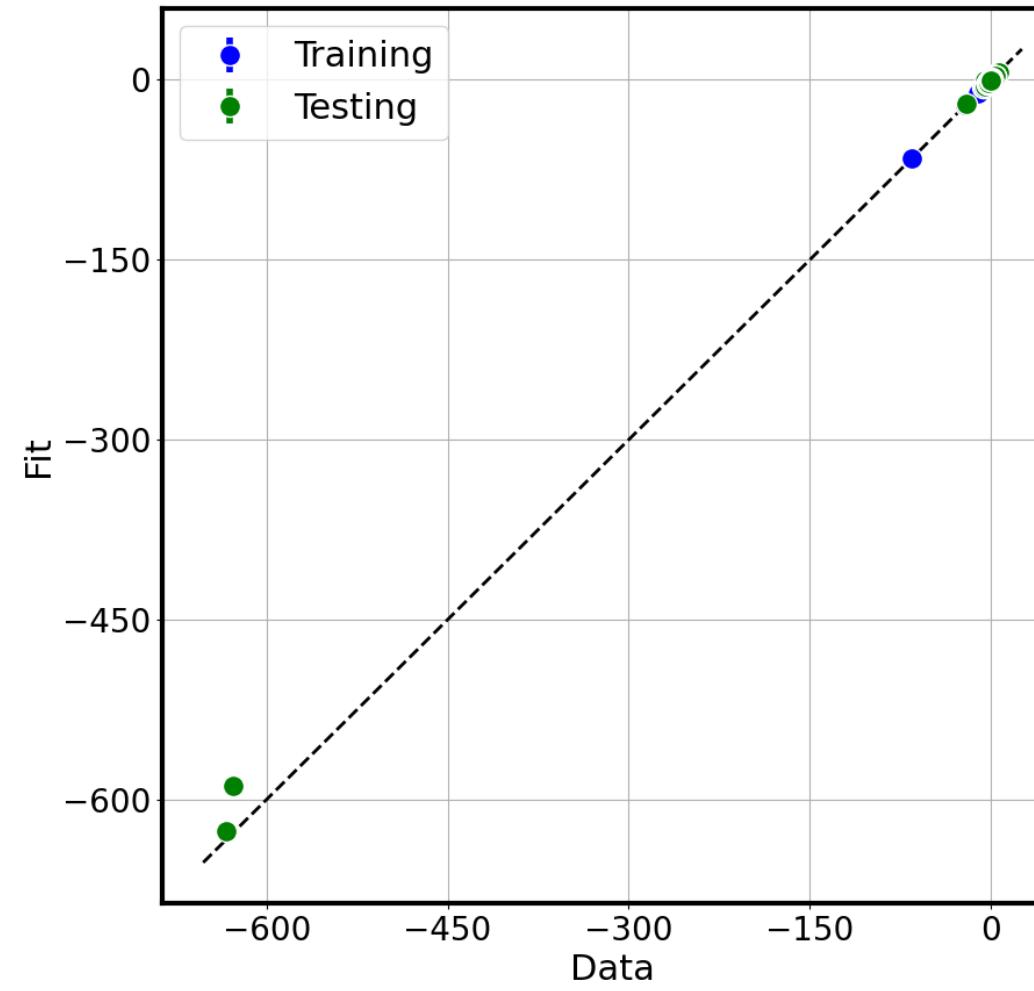


Model error, ABC likelihood

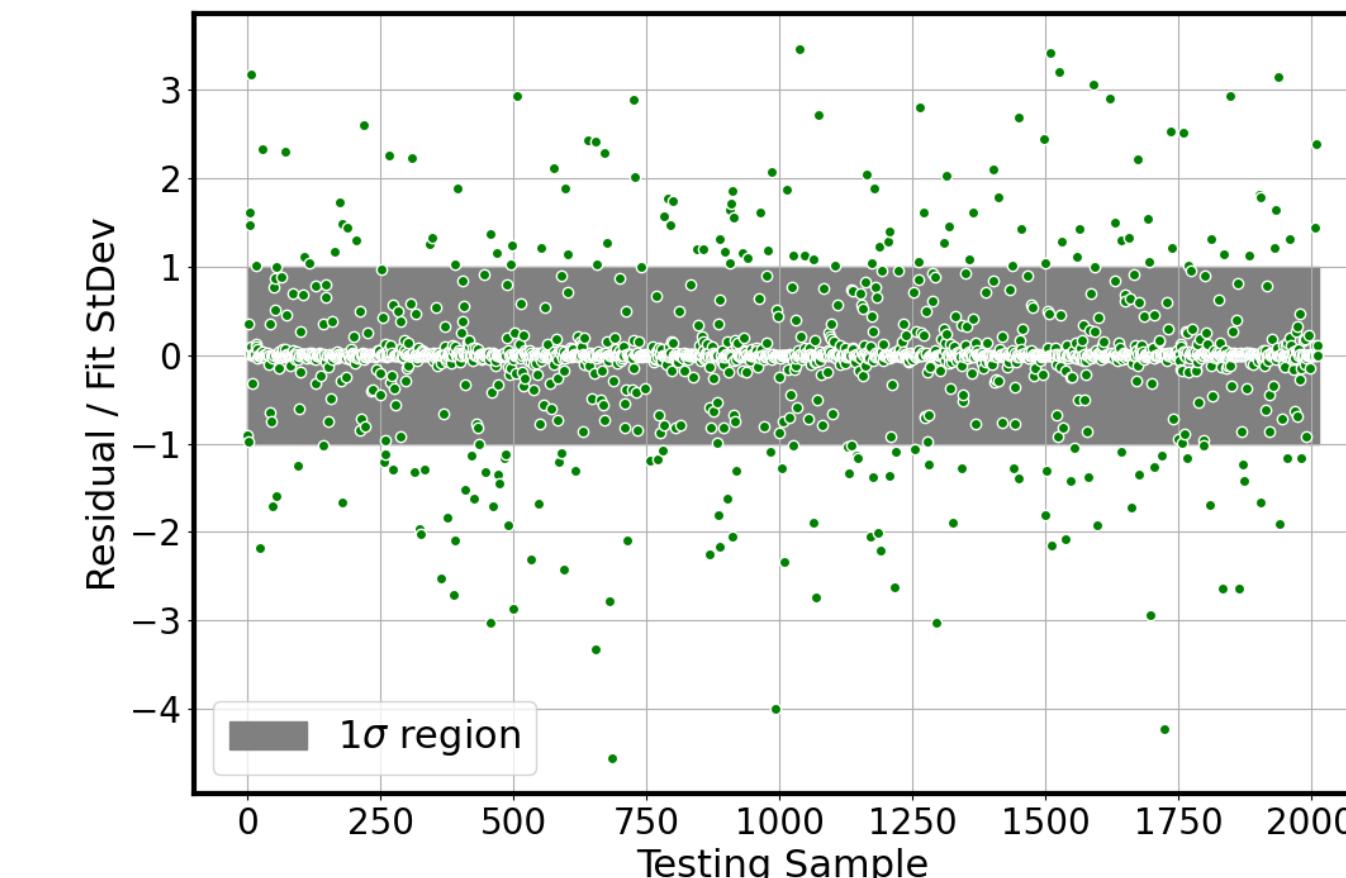
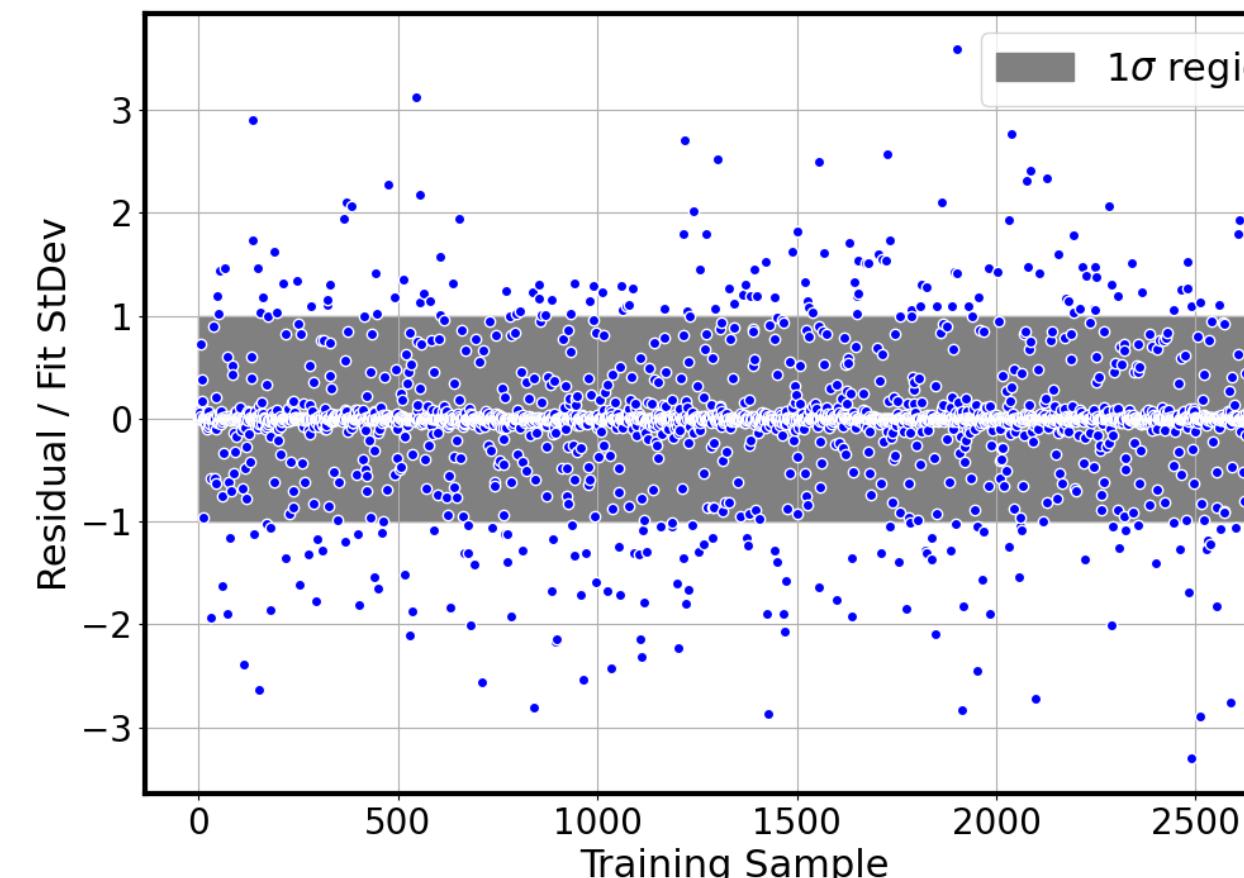
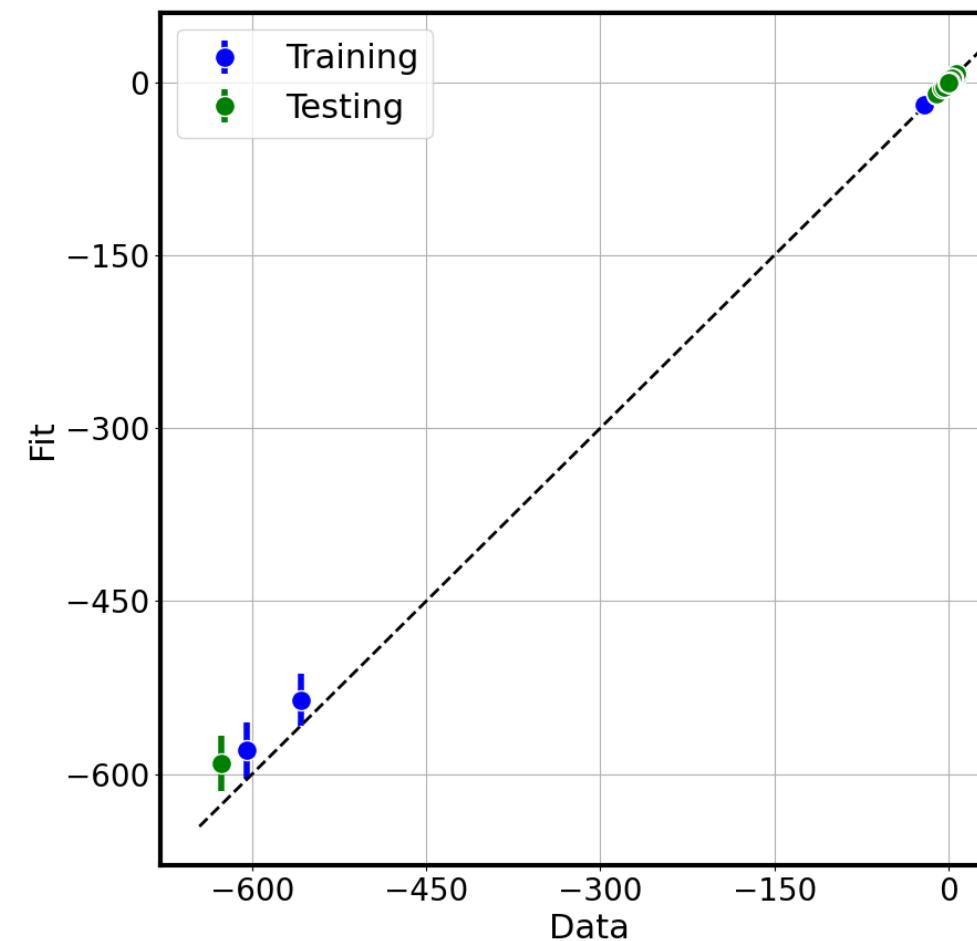


W-ZrC Dataset

Uncertainty without model error



Uncertainty with model error



Several challenges/choices

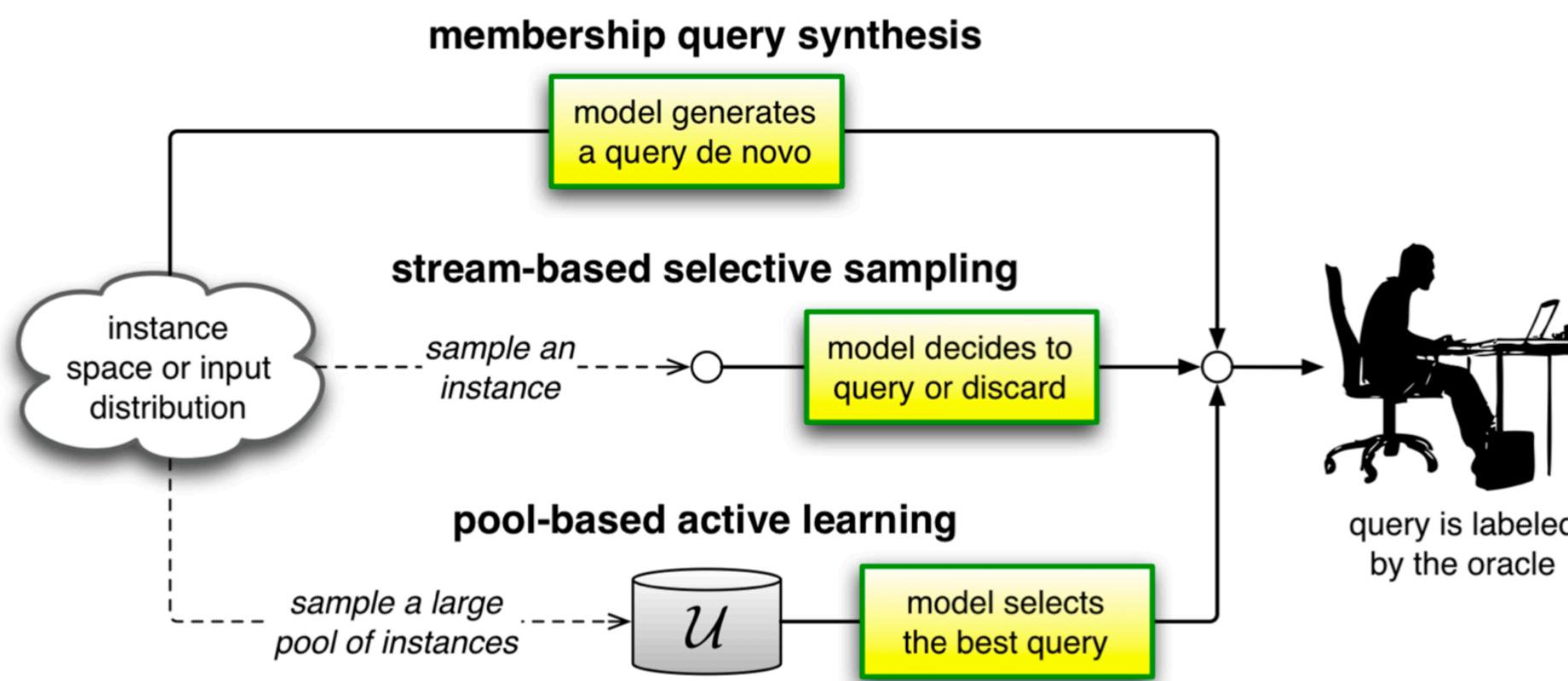
- Embedding type: e.g.

$$\text{additive } y_i \approx \sum_{k=0}^P (c_k + d_k \xi_k) B_k(x) \text{ or multiplicative } y_i \approx \sum_{k=0}^P (c_k + c_k d_k \xi_k) B_k(x)$$

- Degenerate (Gaussian) likelihoods: resort to approximate Bayesian computation (ABC) or independent (IID) assumptions
- Difficult posterior PDFs for MCMC, choice of priors for embedding parameters
- Which coefficients to embed the model error in?
- Connect predictive uncertainty and the residual error with an extrapolation metric
- Weighting between energies, forces and stresses
- Major challenge: data sizes are large, linear algebra chokes

Active Learning: motivation

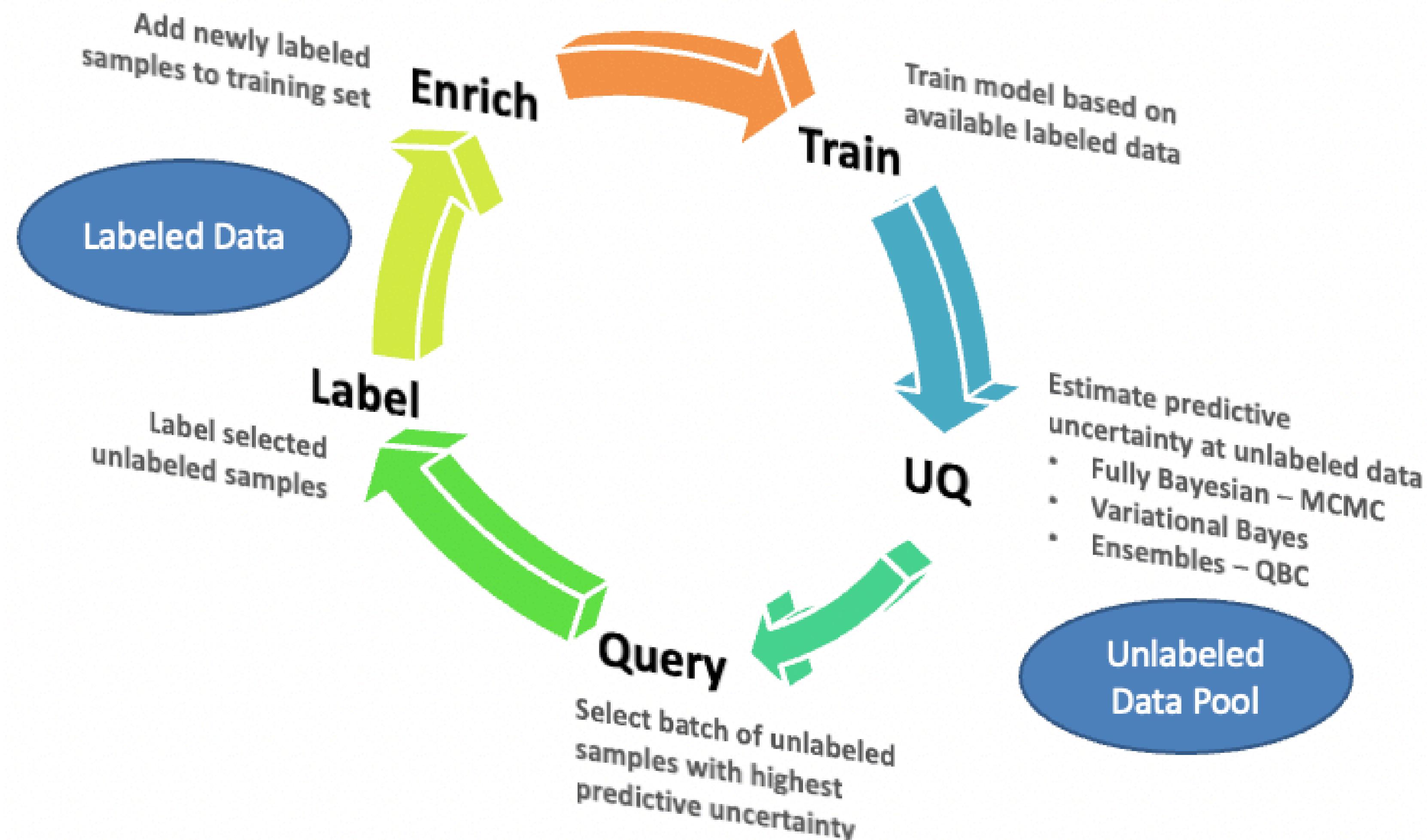
- Choose the training samples adaptively
- Achieve greater accuracy with fewer training samples
- In conventional ML, minimize human effort of labeling images
- For us, minimize the number of *ab initio* QM calculations
- (aka optimal experimental/computational design)



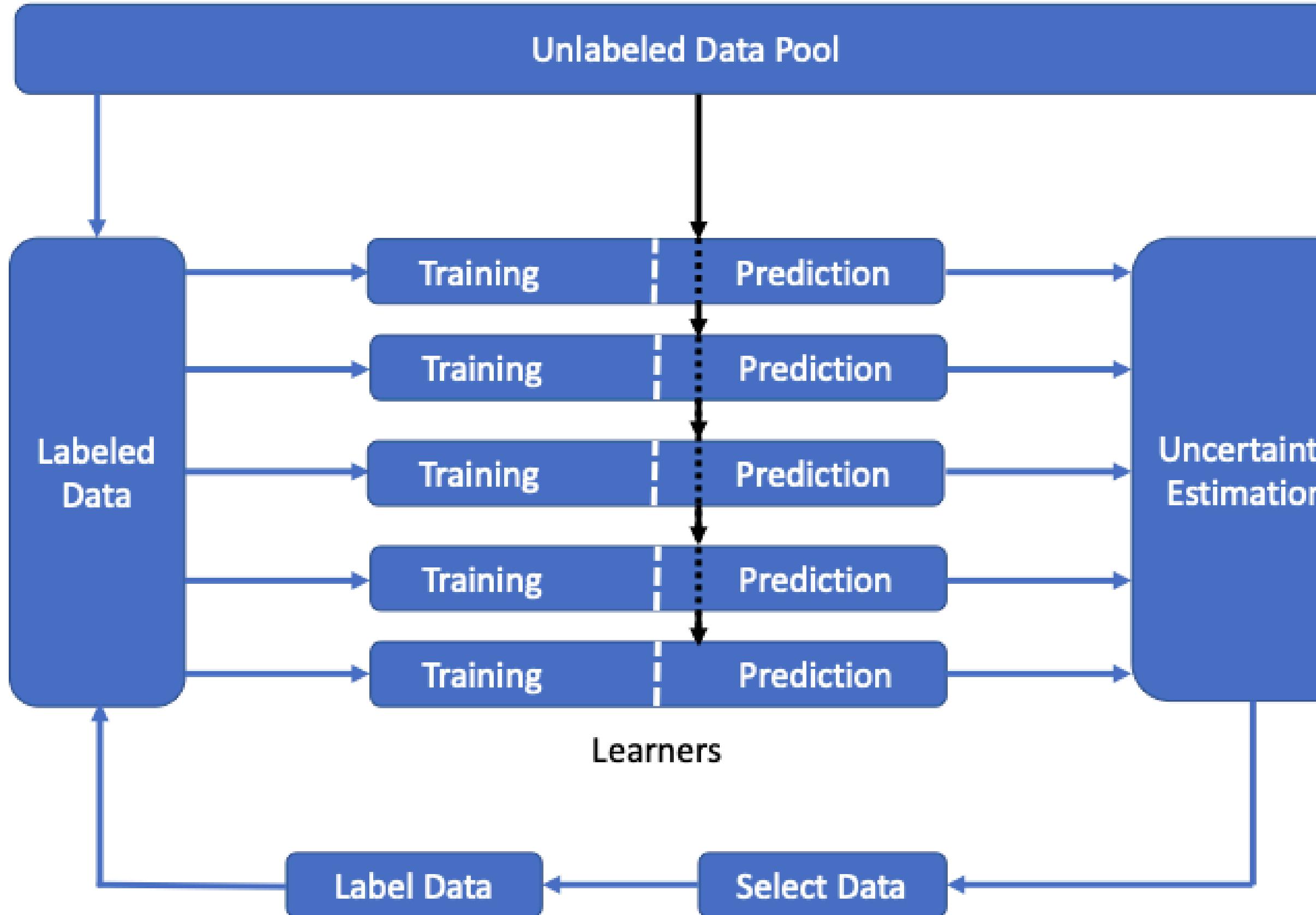
Detect and query extrapolative (high-uncertainty?) configurations on-the-fly and get QM data for those.

Key: query strategy, whether to query QM or not. If such decision can be made reliably, then one does not need to start with a very good training set.

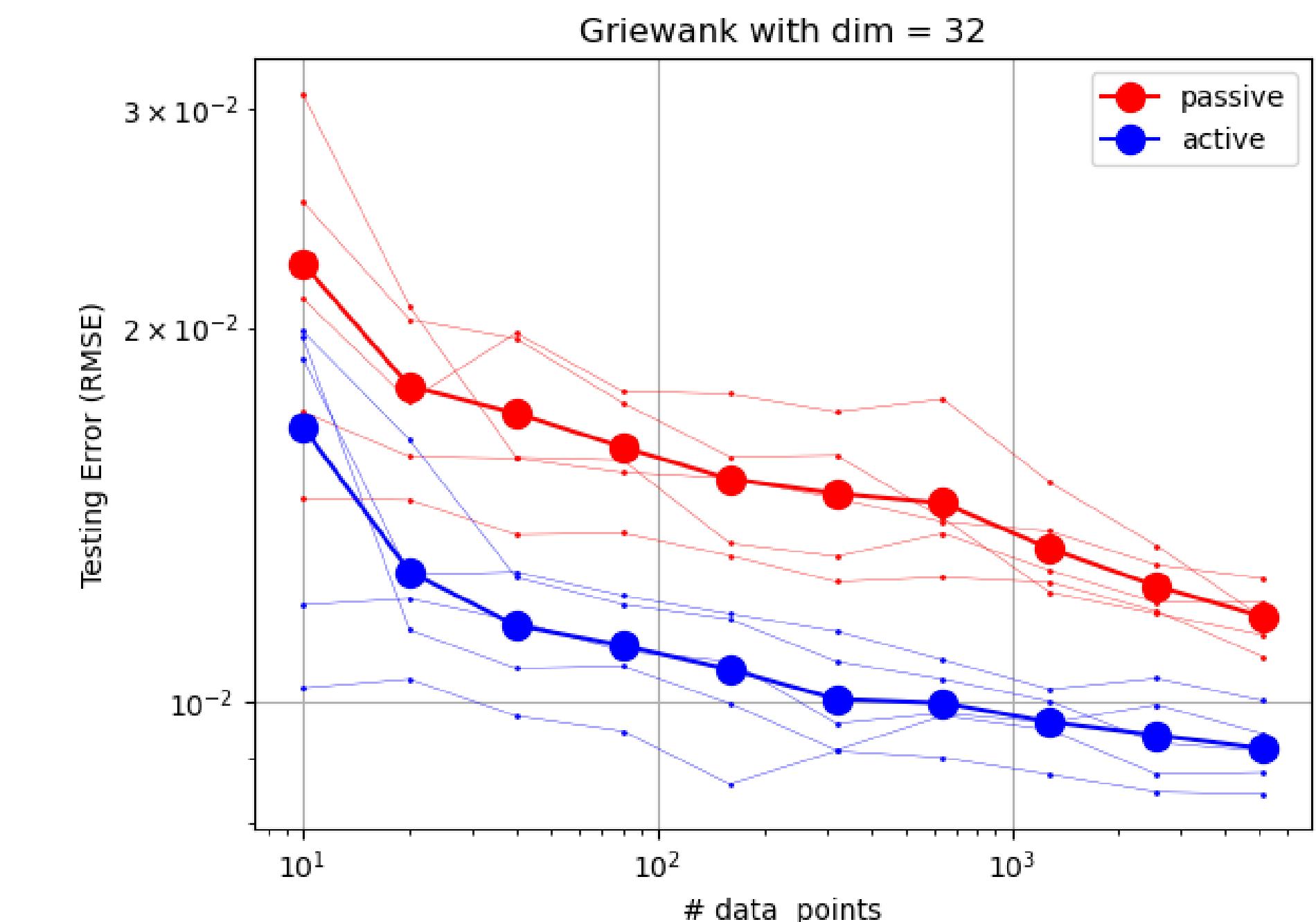
Active Learning Loop



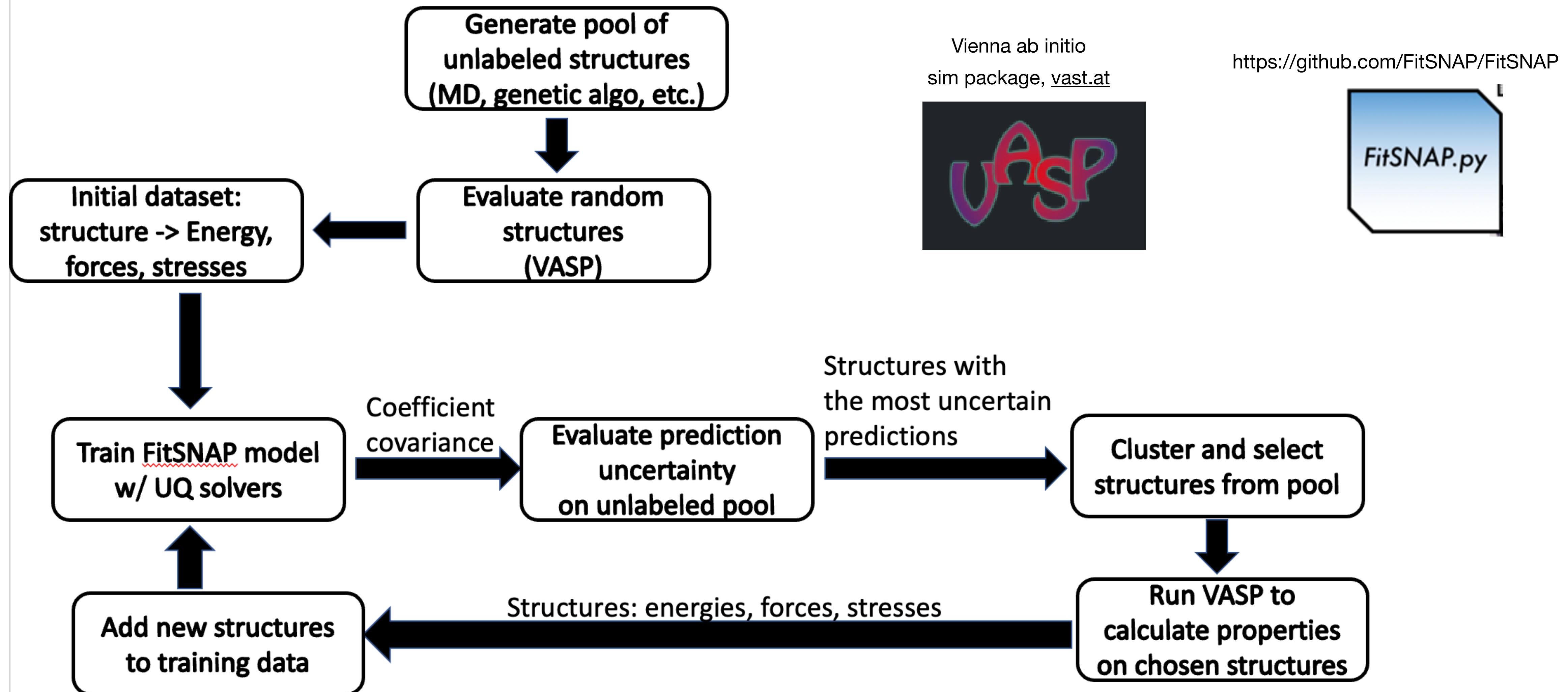
Active Learning: Query-by-Committee (QBC)



- Start with a training set of N points
- Launch K learners, each with fN training points ($f=0.8$)
- Evaluate the learners' performance at all points in the pool
- Select training points from the pool that correspond to the highest 'disagreement' and add them to the training set



Active Learning: current workflow



Summary

- Embedded **model error** for Bayesian inference of MLIAPs
 - Leads to data model with baked-in uncertainty
 - Meaningful model-error uncertainty capturing the true residual
 - Choices to make: priors, likelihoods, MCMC sampler, where to embed...
- Initiating a workflow for **active learning** via QBC
 - Anchored in uncertainty estimation, even if heuristic
 - Promising initial results
 - Choices to make: query strategy, UQ method, metric of ‘newness’...