

Deep Neural Networks as Surrogates for Intractable Constraints and Problem Dimension Reduction: SC AC- OPF

AICHE Annual Meeting

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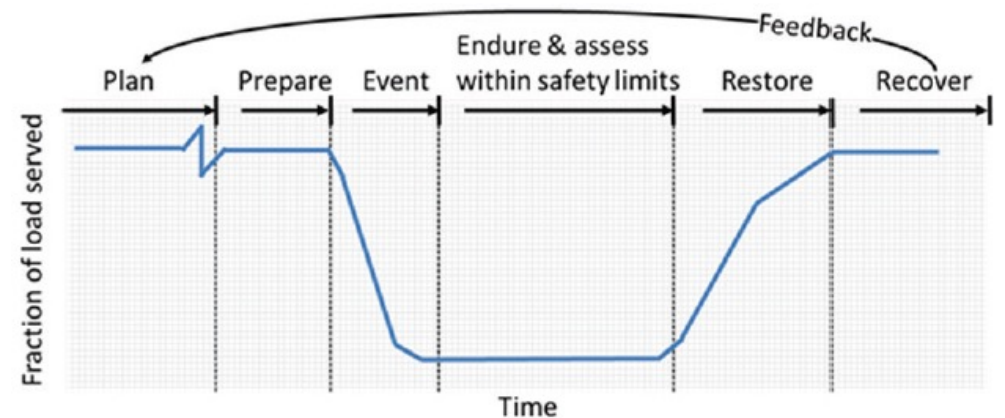
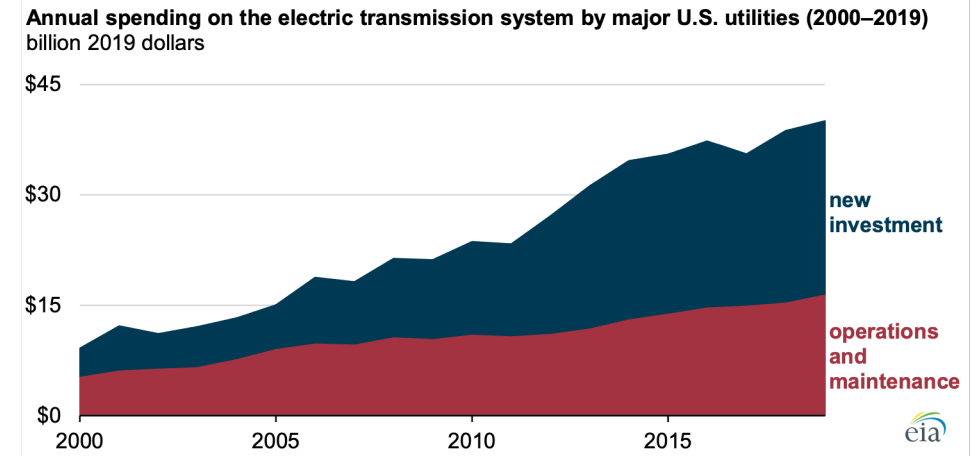


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Problem Motivation: Balancing Grid Security with Economic Dispatch

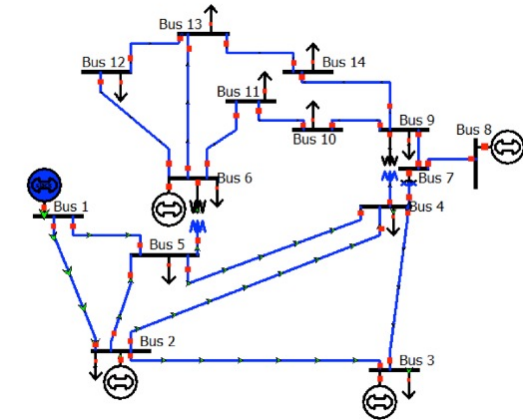
- Utilities spent \$16.6 billion on systems operations and maintenance in 2019 [1]
- FERC predicts effective optimization could save tens of billions annually [2]
- Grids operated close to their optimal points pose risk of large-scale outage in case of contingency [3]
- Important to weigh **optimality** and **security**
- Contingency events may take a long time to rectify



Source: Enhancing the Resilience of the Nations Electricity System (2017)

Power Flow Model Description

- Optimal Power Flow (OPF) programs balance load demands with generator setpoints in the most economic way [4]:
 - AC-OPF: non-linear, non-convex
 - Convex relaxations of AC-OPF
 - DC-OPF: linearized version
 - Global [5] vs local methods
- Security constrained OPF used to optimize to more secure operating points [6]:
 - $N-1$ security signifies an operating point that can handle any single outage in the system
 - Extremely computationally expensive, exponentially increases variable space



Source: IEEE PG-Lib OPF Case 14

$$\text{Min } C(p^g) \quad (1)$$

$$\sum_{k(n,m)} p_{k(n,m)}^f + \sum_{k(n,m)} p_{k(n,m)}^t - p_n^g + p_n^d = 0 \quad (2)$$

$$\sum_{k(n,m)} q_{k(n,m)}^f + \sum_{k(n,m)} q_{k(n,m)}^t - q_n^g + q_n^d = 0 \quad (3)$$

$$V^{\min} \leq V \leq V^{\max} \quad (4)$$

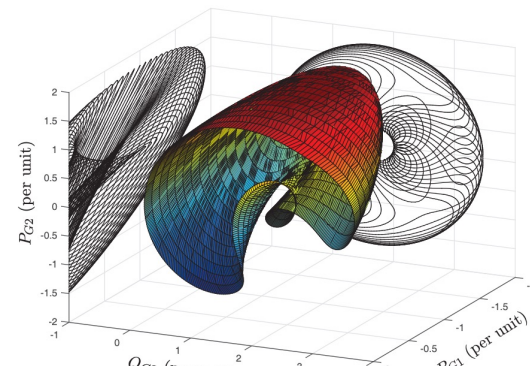
$$\theta_{nm}^{\min} \leq \theta_n - \theta_m \leq \theta_{nm}^{\max} \quad (5)$$

$$P_n^{\min} < P_n < P_n^{\max} \quad (6)$$

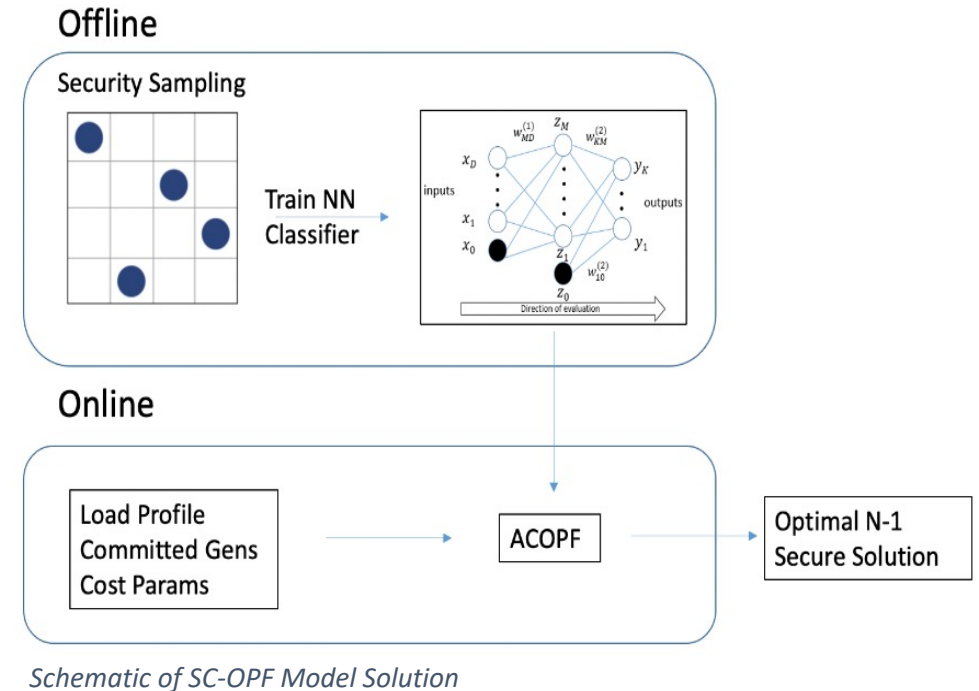
$$Q_n^{\min} < Q_n < Q_n^{\max} \quad (7)$$

Big Picture: Using ML Surrogates to Embed Intractable Constraints into Nonlinear Programs (NLP)

- Embedding deep NN into large scale NLP problems
- NN embed complex security function
- Tractable solution time for online economic dispatch
- Can be used to boost security in large-scale grid problems
- Integration with familiar optimization (Pyomo) and power flow (Egret) software



Visual Representation of Feasible Space for Small Grid (Source: Hiskens et al 2001 IEEE Transactions on Power Systems)



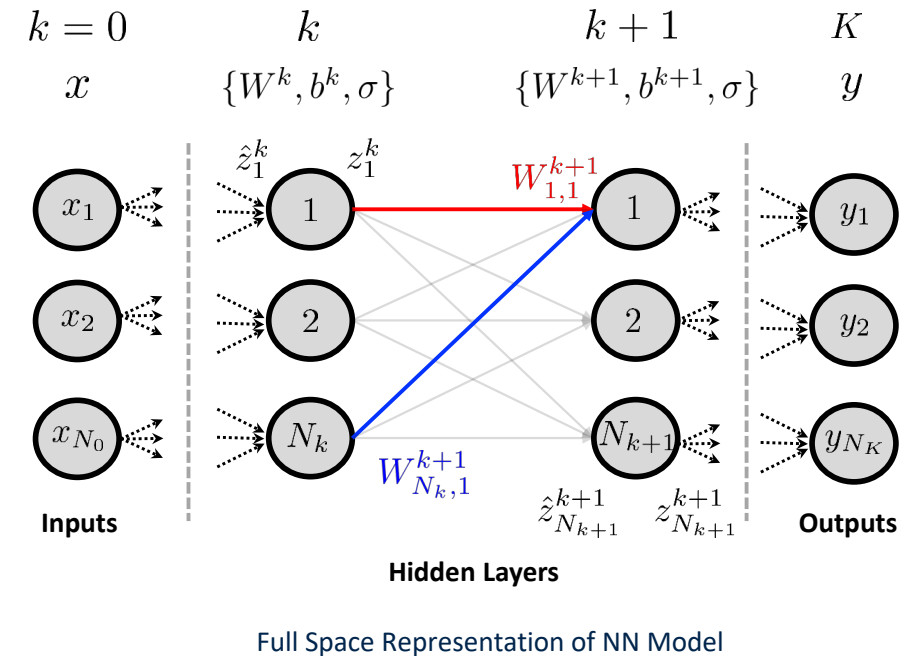
Schematic of SC-OPF Model Solution

Literature Review

- Hybrid models have been used in PSE for many applications:
 - Parallel mechanistic and parametric models for improving predictions in activated sludge process [14]
 - Series NN and kinetic model for lignocellulosic fermentation [15]
- Black-box feasibility functions for Kriging, NN models [16-17]
 - Pharmaceutical, process models (low dimensionality)
- Linear regression models trained to map security boundary for given load profile[18]
 - Smaller case studies, not generalizable
- ReLU network as security constraint for MINLP and MILP approximation [19]
 - Integer variables, power flow equation approximation, IEEE Case 14
- Fit NN to full optimization solution instead of secure space [20]
 - Not flexible to changes in costing function, network parameters

Methodology: Formulating a NN into NLP (Full Space)

- Inputs x , fully connected sequential layers, outputs y
- Direct encoding of NN model into intermediate variables z
- Here activation functions are explicitly encoded into variables/constraints in optimization model



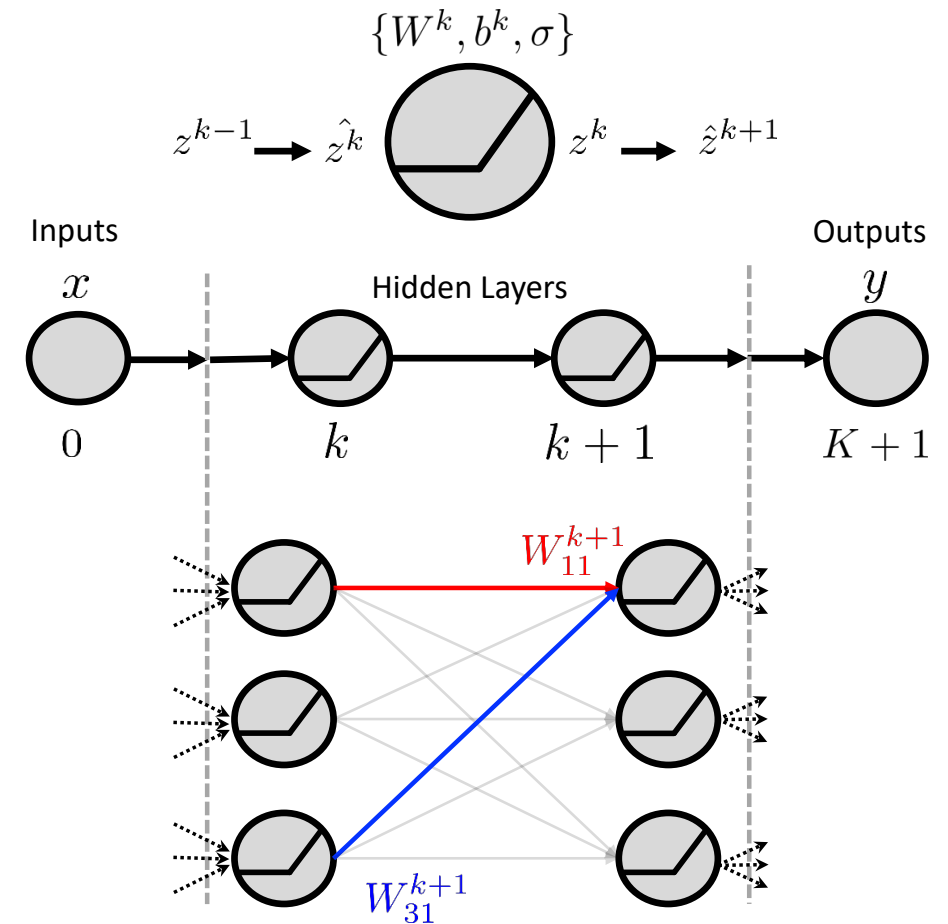
$$z_n^0 = x_n \longrightarrow \hat{z}_n^k = f(W, b, z_n^{k-1}) \longrightarrow z_n^k = \sigma(\hat{z}_n^k) \longrightarrow y_n = f(W, b, z_n^k)$$

Methodology: Formulating a NN into NLP (Reduced Space)

- Inputs x map directly to outputs y with a single constraint
- Internals of NN not treated as variables
- Has shown to produce superior relaxations in global optimization [ref]
- Reduces overall model size
- Internal variables less important after training

Reduced Space Formulation

$$\begin{aligned} \min_{x,y} \quad & f(x, y) \\ \text{s.t.} \quad & y = NN(x) \\ & g(x, y) \leq 0 \\ & x \in X, y \in Y \end{aligned}$$



Reduced Space Representation of NN Model

Methodology: Formulating ReLU NNs (MILP, Complementarity)

- ReLU NNs are increasingly common in ML literature [ref]
- Can be represented as MILP
- Not advantageous for hybrid SC-OPF as underlying physics still non-linear (MINLP)
- Complementarity formulation relaxes model to eliminate integer variables

ReLU is piecewise linear:

$$z = \max(\hat{z}, 0)$$

MILP can give bounds:

$$0 \leq (z_n^k - \hat{z}_n^k) \perp z_n^k$$

Complimentarity:

$$(z_n^k - \hat{z}_n^k)z_n^k = \varepsilon \quad \forall n \in N, \forall k \in K$$
$$\varepsilon \geq 0$$

OptML: Bridging Pyomo Optimization Tools and ML Libraries

```
import pyomo.environ as pyo
from tensorflow import keras

from optml import OptMLBlock
from optml.neuralnet import FullSpaceContinuousFormulation, ReducedSpaceContinuousFormulation
from optml.neuralnet import ReLUBigMFormulation
from optml.neuralnet import load_keras_sequential

neural_net = keras.models.load_model('Saved NN Model')
net=load_keras_sequential(neural_net)
formulation = ReducedSpaceContinuousFormulation(net)

m=pyo.ConcreteModel()

m.nn = OptMLBlock()
m.nn.y=pyo.Var(m.nn.outputindex)
m.nn.build_formulation(formulation, input_vars=[inputs], output_vars=m.nn.y)
```

- Simple way to load tensorflow based NNs into pyomo
- Tools for reduced space, full space, MILP, complementarity
- Block structure to add combine with existing pyomo models

<https://github.com/or-fusion/OptML/tree/main>

Methodology: Model Guided Sampling

Sampling Algorithm for Boundary Points

Initial_Loads=[$LF^{\min}, \dots, LF^{\max}$], Load_Directions=[$\vec{LD}^0, \dots, \vec{LD}^j$]

for IL **in** Initial_Loads:

for LD **in** Load_Dirs:

$\max(SF)$

 s. t. $g_0(x_0, u_0) = 0$

$g_c(x_c, u_c) = 0$

$x_L \leq x_0 \leq x_U, u_L \leq u_0 \leq u_U$

$x_L \leq x_c \leq x_U, u_L \leq u_c \leq u_U$

$p_l = IL * LD * SF$

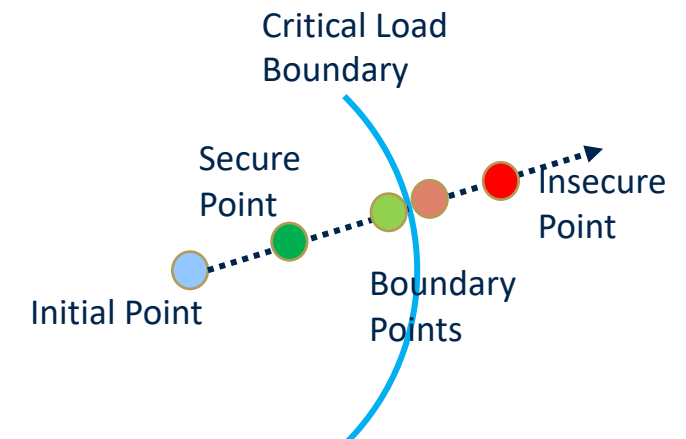
$\frac{p_l}{\sqrt{p_l^2 + q_l^2}} = \text{Power Factor}$

- Algorithm can be parallelized (single contingencies independent)
- Point where security constraint becomes active is much more informative to NN classifier

Existing sampling approaches include use of hyperspheres [21]

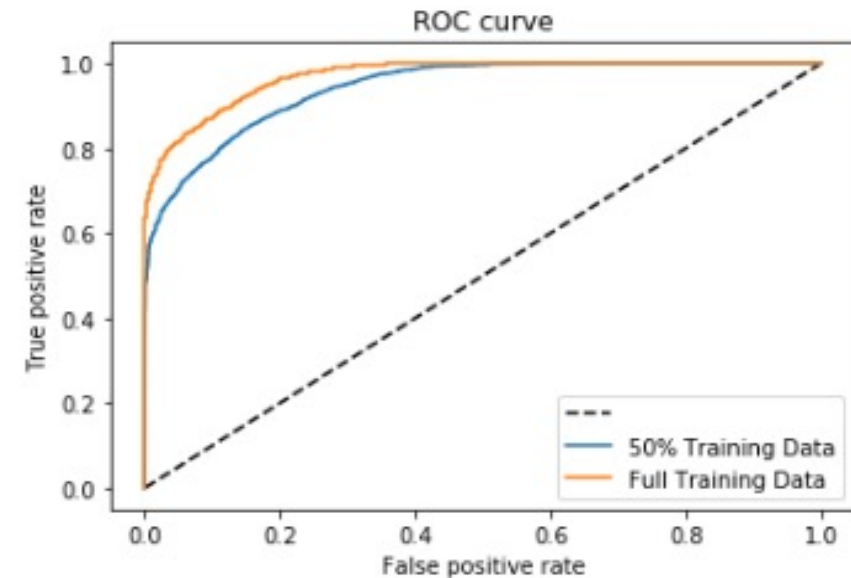
LHS sampling of initial load conditions and ramping vectors

Optimization formulation to find max scaling factor before security constraint is violated



Classifier Accuracy Results

- ROC explains trade-off between conservativeness and accuracy (can be tuned in optimization problem: softmax output)
- Sequential Model: 118 inputs, 2 hidden layers, 20 nodes
- **89% accuracy** for test points on IEEE Case 118
- ReLU and tanh networks are able to achieve identical accuracy



Receiver Operating Curve (ROC) for IEEE Case 118 Security Classifier

Methodology: NN SC-OPF Reformulation

- Incorporating security constraints makes problem very large
- IEEE Case 30: 450 -> 18,400 variables
- Classification of security in original variable space
- Secure space is encoded much more efficiently
- Expensive simulations can be done offline so that online solution is fast

Extensive Formulation

$$\begin{aligned} \min_{x_0, u_0, x_c, u_c} & f(u_0) + \rho \sum_{c \in \mathcal{C}} f_c(u_c, u_0) \\ g_0(x_0, u_0) &= 0 \\ g_c(x_c, u_c) &= 0 \quad \forall c \in \mathcal{C} \\ x_L &\leq x_0 \leq x_U, u_L \leq u_0 \leq u_U \\ x_L &\leq x_c \leq x_U, u_L \leq u_c \leq u_U \quad \forall c \in \mathcal{C} \end{aligned}$$

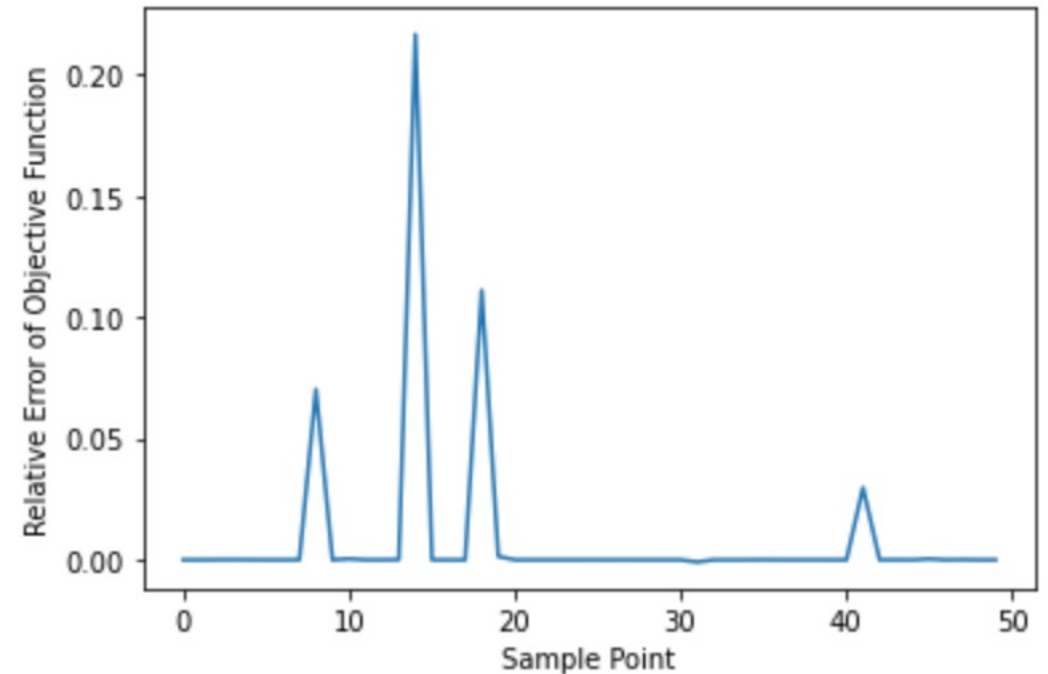
Hybrid Reformulation

$$\begin{aligned} \min_{x, u} & f(u) \\ g(x, u) &= 0 \\ x_L &\leq x \leq x_U, u_L \leq u \leq u_U \\ y_{sec} &= NN(x, u) \\ y_{sec} &\leq \alpha \end{aligned}$$

Extensive vs Hybrid Comparison {Case 118}

- Obj-> Average: 0.85% optimality gap or relative error between objective function
 - Nearly identical obj fcn values for most cases
- CPU: 5.27 sec for extensive
- CPU: 0.32 sec for hybrid model (tanh)
- CPU: 0.35 sec for ReLU-complementarity

Model mismatch-> 0.615% average error in real power variables

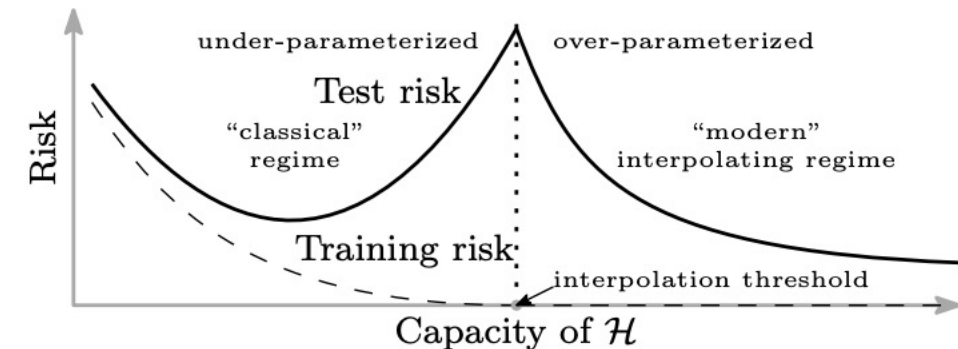
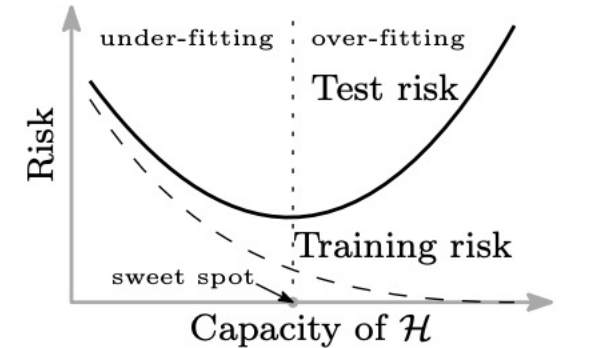


Conclusions

- Modern grid systems require intensive **optimization**
- Enforcing **grid security** can be mathematically challenging
- Neural Network classifiers can be formulated naturally within NLP OPF problems
 - ReLU, Tanh
 - Reduced, Full Space
- High accuracy conferred through feasibility sampling
- Balance of computation and accuracy

Future Work and Anticipated Challenges

- Larger case studies than Case 118
 - Parallelization of sampling algorithm
 - Input feature selection for NN classifier
 - Selection of most prescient contingency events
- NN sparsification, parameterization [23]:
 - Larger NN classifiers will be harder to optimize
 - Sparsification can greatly speed up NLP solution
 - Lottery ticket hypothesis (90% reduction possible with same accuracy)
- Further OptML tools:
 - New ML models
 - NN verification case studies



Non-intuitive generalization of over-parameterized deep ML models (Source: Reconciling Modern Machine Learning Practice and the bias-variance trade-off)

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Thank you!

Questions?

Supplementary Slides

AC Power Flow Equations

$$\sum_{k(n,m) \in K_n^{out}} p_{k(n,m)}^f + \sum_{k(n,m) \in K_n^{in}} p_{k(n,m)}^t - p_n^g + p_n^d = 0, \quad \forall n \in N \quad (1)$$

$$\sum_{k(n,m) \in K_n^{out}} q_{k(n,m)}^f + \sum_{k(n,m) \in K_n^{in}} q_{k(n,m)}^t - q_n^g + q_n^d = 0, \quad \forall n \in N \quad (2)$$

$$p_{k(n,m)}^f = g_k v_n^2 - v_n v_m (g_k \cos \theta_{n,m} + b_k \sin \theta_{n,m}), \quad \forall k \in K \quad (3)$$

$$p_{k(n,m)}^t = g_k v_m^2 - v_n v_m (g_k \cos \theta_{n,m} - b_k \sin \theta_{n,m}), \quad \forall k \in K \quad (4)$$

$$q_{k(n,m)}^f = -(b_k + b_k^{sh}) v_n^2 - v_n v_m (g_k \sin \theta_{n,m} - b_k \cos \theta_{n,m}), \quad \forall k \in K \quad (5)$$

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$$v_n^{min} \leq v_n \leq v_n^{max}, \quad \forall n \in N \quad (7)$$

$$\theta_{nm}^{min} \leq \theta_n - \theta_m \leq \theta_{nm}^{max}, \quad \forall \{n, m\} \in K \quad (8)$$

$$p_n^{min} \leq p_n \leq p_n^{max}, \quad \forall n \in N \quad (9)$$

$$q_n^{min} \leq q_n \leq q_n^{max}, \quad \forall n \in N \quad (10)$$

AC Optimal Power Flow Formulation

$$\text{Min } C(p^g) \quad (1)$$

$$\text{s. t. } \sum_{k(n,m) \in K_n^{\text{out}}} p_{k(n,m)}^f + \sum_{k(n,m) \in K_n^{\text{in}}} p_{k(n,m)}^t - p_n^g + p_n^d = 0, \quad \forall n \in N \quad (2)$$

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$$(p_k^f + q_k^f)^2 \leq (\text{Thermal Limit})^2, \quad \forall k \in K \quad (12)$$

$$(p_k^t + q_k^t)^2 \leq (\text{Thermal Limit})^2, \quad \forall k \in K \quad (13)$$

Security Constrained AC Optimal Power Flow

$$\text{Min } C(p^g) \quad (1)$$

$$\text{s.t. } \sum_{k(n,m) \in K_n^{\text{out}}} p_{k(n,m)}^f + \sum_{k(n,m) \in K_n^{\text{in}}} p_{k(n,m)}^t - p_n^g + p_n^d = 0, \quad \forall n \in N, \forall c \in C \quad (2)$$

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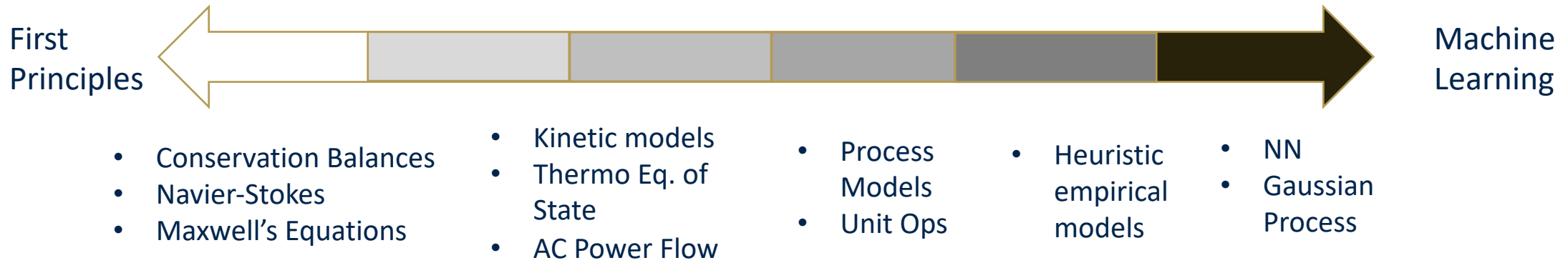
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Two Successful Modeling Paradigms Used for Engineering Applications



- First-principle (FP) models are difficult to develop, expensive to solve, but **generalize well** and are interpretable [1]
- Machine learning (ML) models are easy to develop, **fast to solve**, but generalize poorly and are not easily interpreted
- Creating models with both elements allows us to solve new problems, improve speed and accuracy of engineering model predictions [2]

NN SC-OPF Comparison Results

- Literature study for extensive form SC-ACOPF takes ~**400 sec** [22]
- NN-SC-ACOPF **averages 7 sec** and never exceeds 15 sec

Formulation	Avg Opt Gap	CPU (s)	% <i>N-1</i> Insecure
SCOPF Extensive			
NN SCOPF			