



Exceptional service in the national interest

Capturing Deformation Mechanisms in Additively Manufactured Parts through High-fidelity Modeling and Computed Tomography

Kyle Johnson, Chris Laursen, Andrew Polonsky, Jay Carroll, Kyle Karlson, John Emery, Charlotte Kramer

TMS Annual Meeting

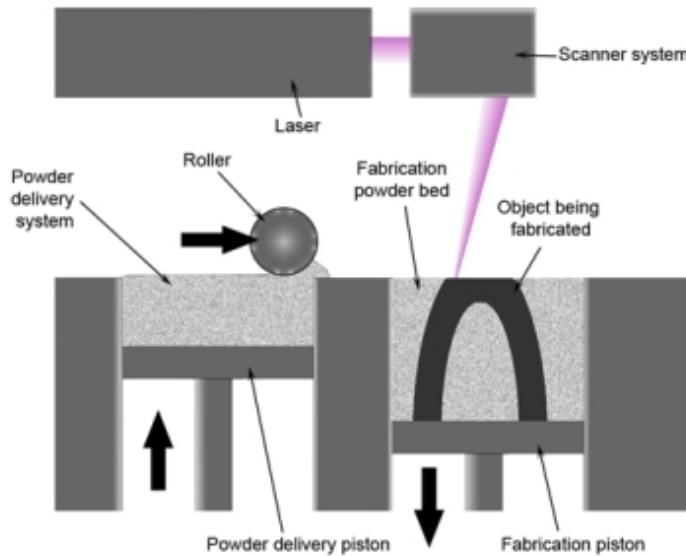
March 3, 2022



Outline

- Background on Additive Manufacturing Characterization
- Motivation – Machine Learning
- Mechanical Testing and CT Characterization
- Model Calibration
- Fracture Predictions

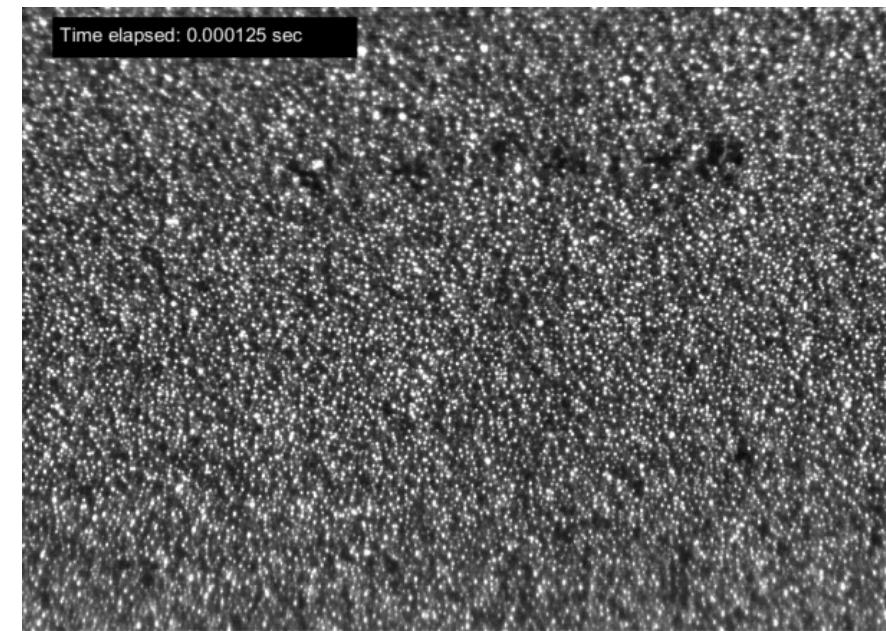
Laser Powder Bed Fusion (LPBF)



LPBF Process¹

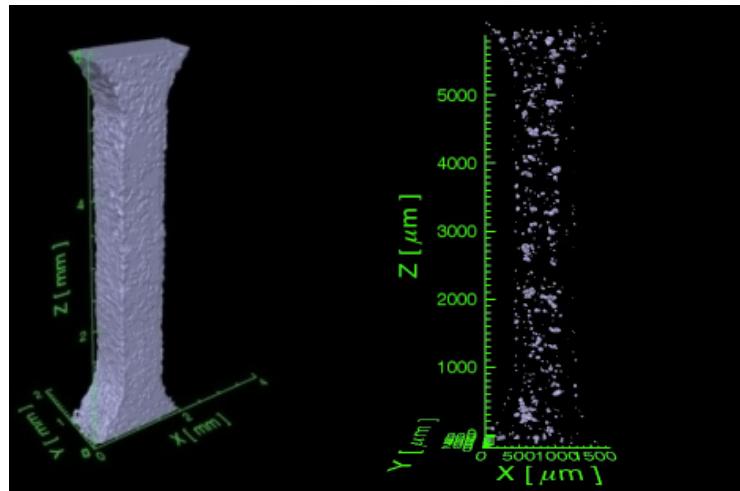


Different LPBF Scan Paths
Bradley Jared (UTK)

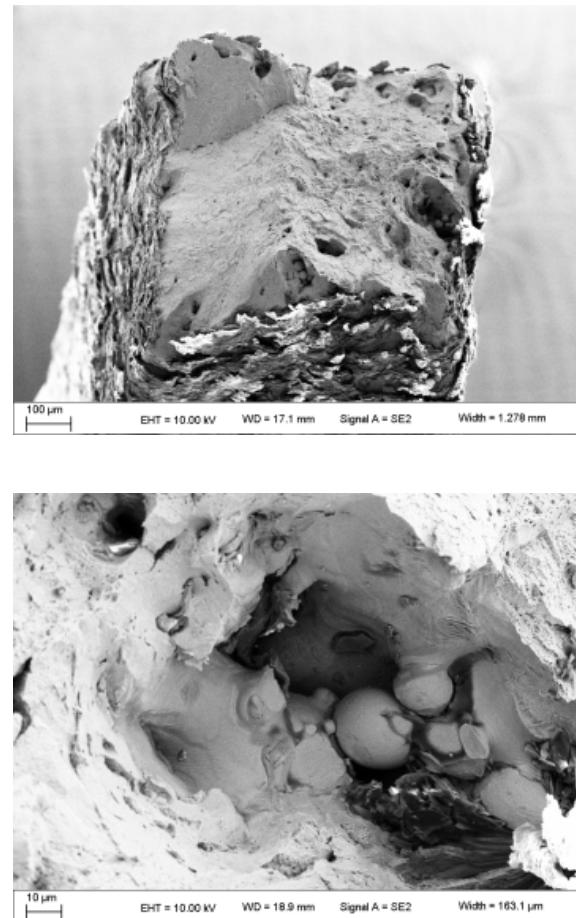


Bidare, P. et al. *Acta Mat 2018*

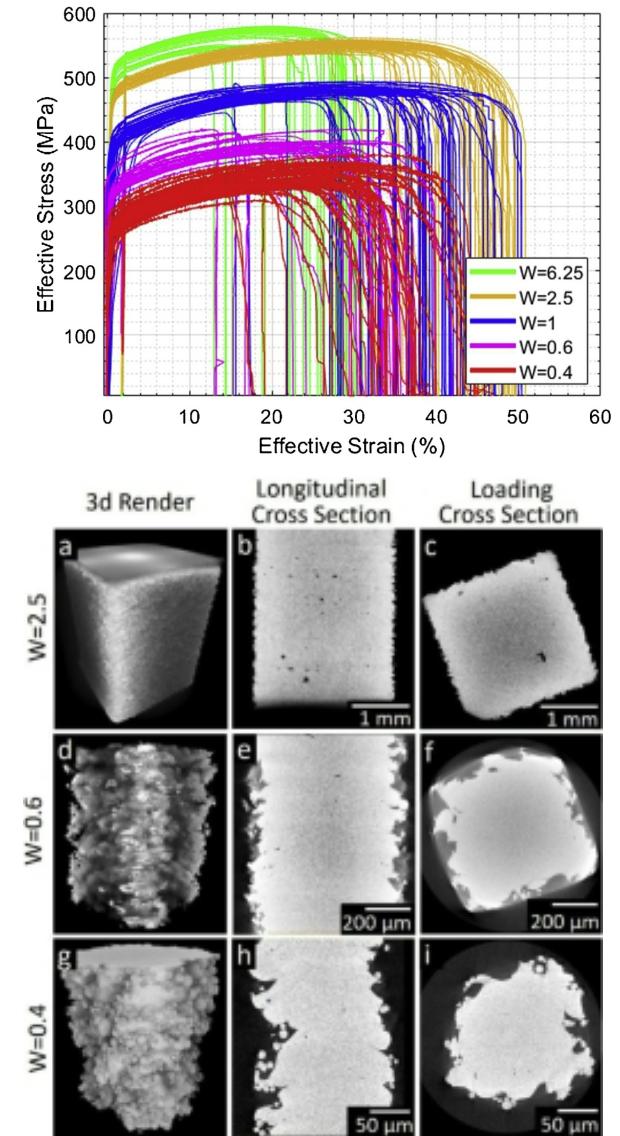
LPBF can produce significant mechanical variability



(J. Madison, T. Ivanoff, O. Underwood, SNL)

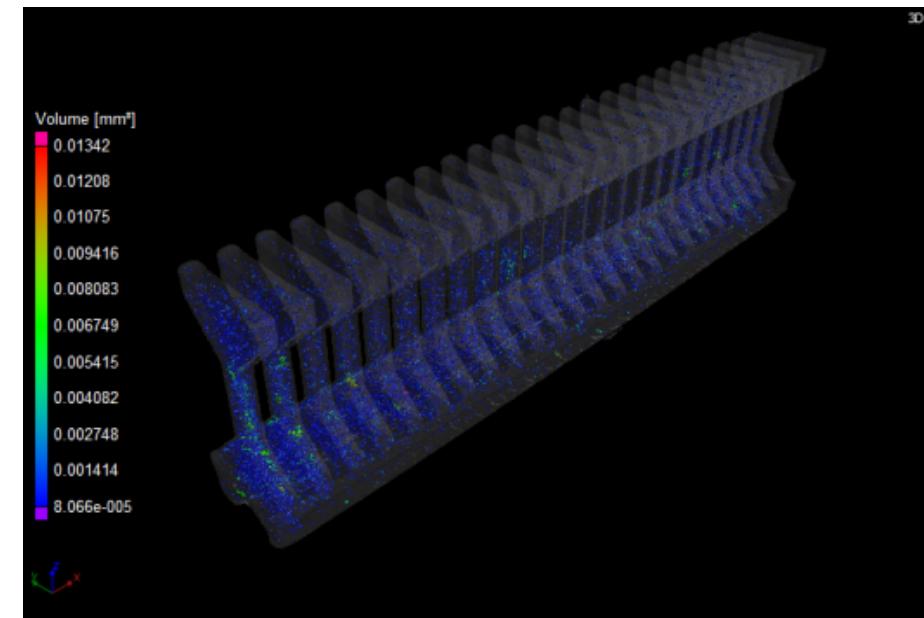
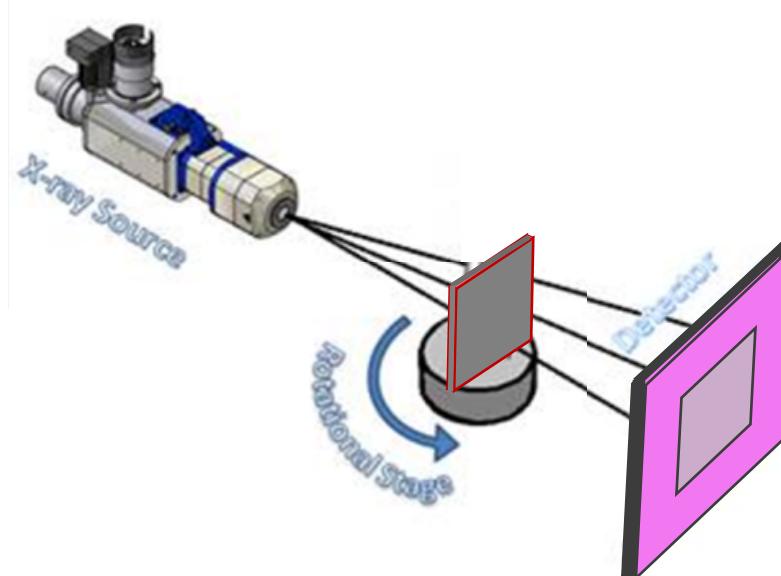
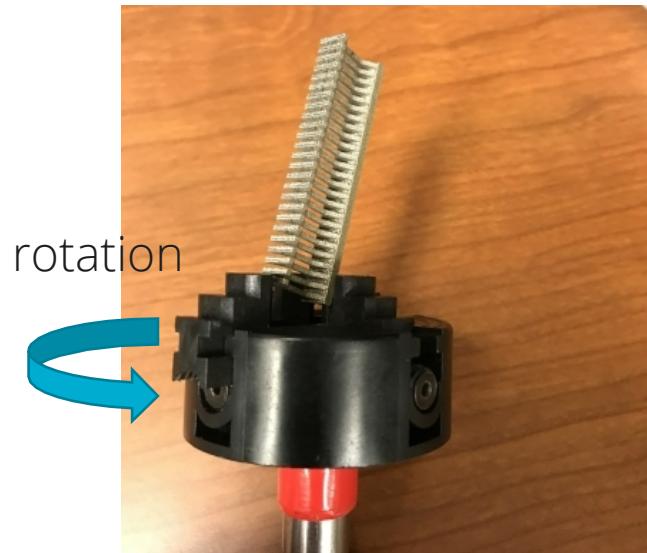


Kramer et al., *IJF* 2019



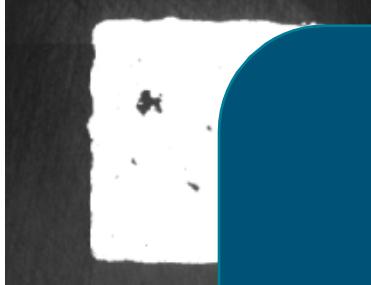
Roach, A.M. et al. *Additive Manufacturing* 2020

Computed Tomography (CT) offers a way to quantify defect structure



Challenges remain in use of CT data

Serial sectioning



Low threshold (80)



Middle threshold (155)

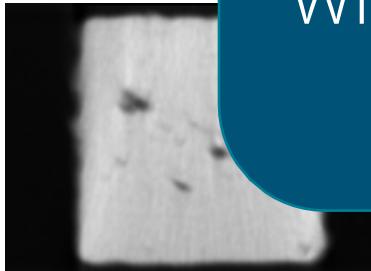


High threshold (230)



Motivation: Can we make meaningful performance predictions with knowledge of defect structure?

CT



Retain object edges
Lose all void detail



Retain object edges
Capture some detail



Lose object edges
Capture voids (slightly enlarged)

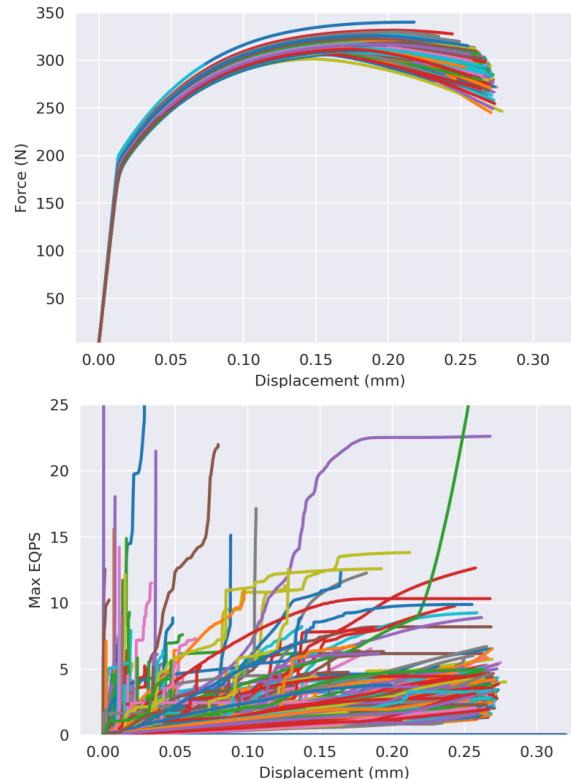
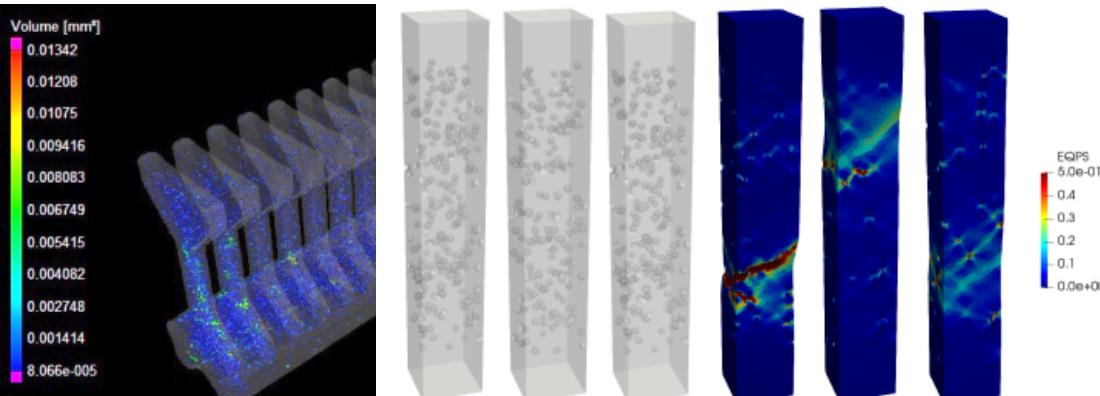


Predicting behavior of additively manufactured parts using Deep Learning

3D Convolutional Neural Networks were used to predict behavior, such as peak load, based on pore distributions orders of magnitude faster than traditional FEA.

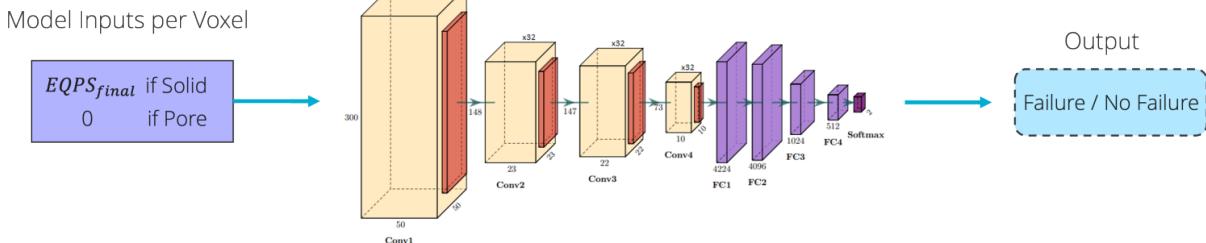
Pore distributions significantly impacted force-displacement behavior and evolution of equivalent plastic strain (EQPS)

Experimental CT pore distributions were used to generate synthetic pore realizations in tension specimens, which cause variations in mechanical performance



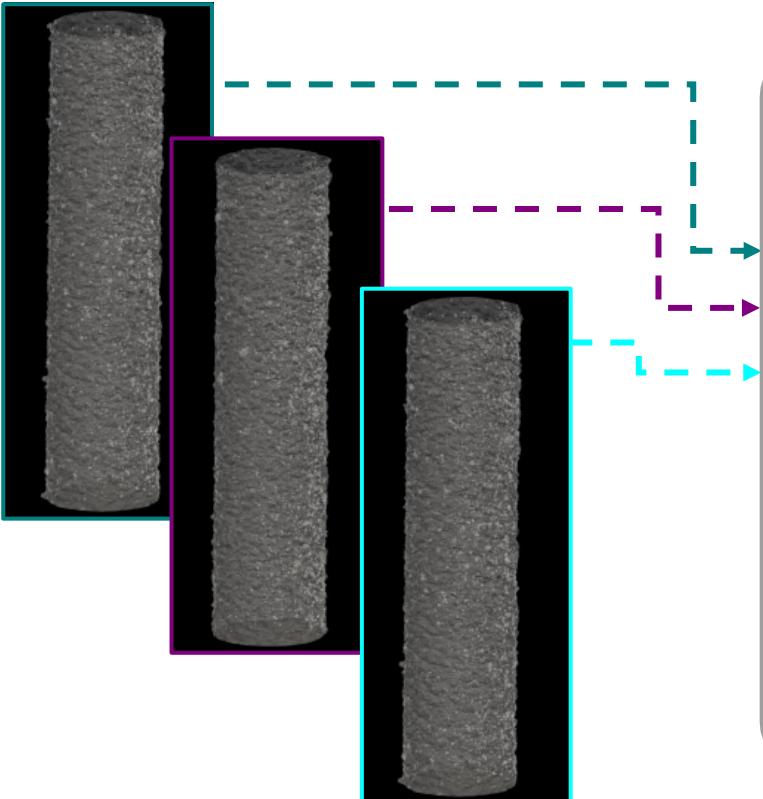
- Convolutional neural networks was used to classify part performance based on chosen failure metrics (peak load, EQPS, etc.) by learning effects of complex pore networks
- Synthetic data did not account for pore metrics other than volume.

3D CNN Formulation

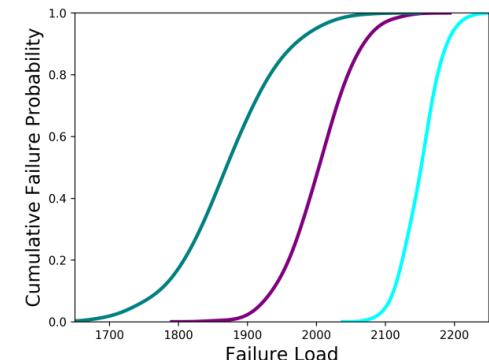


Vision: Rapid failure prediction based on microstructure enabled by Machine Learning

Microstructure



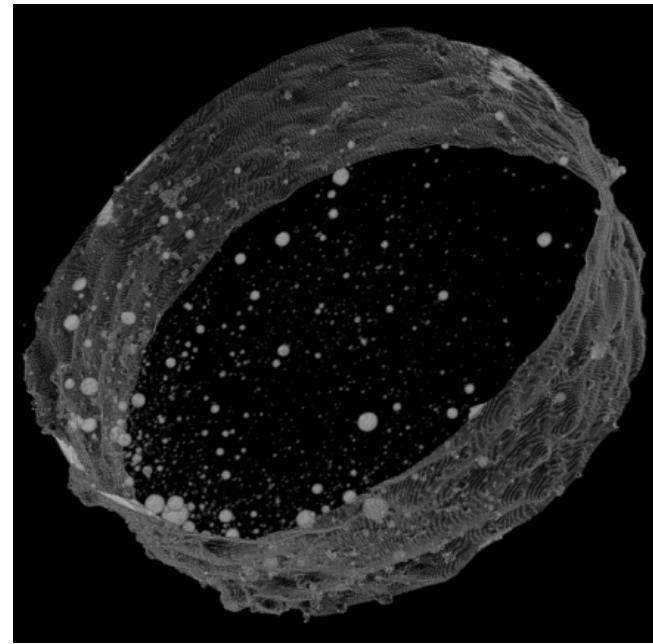
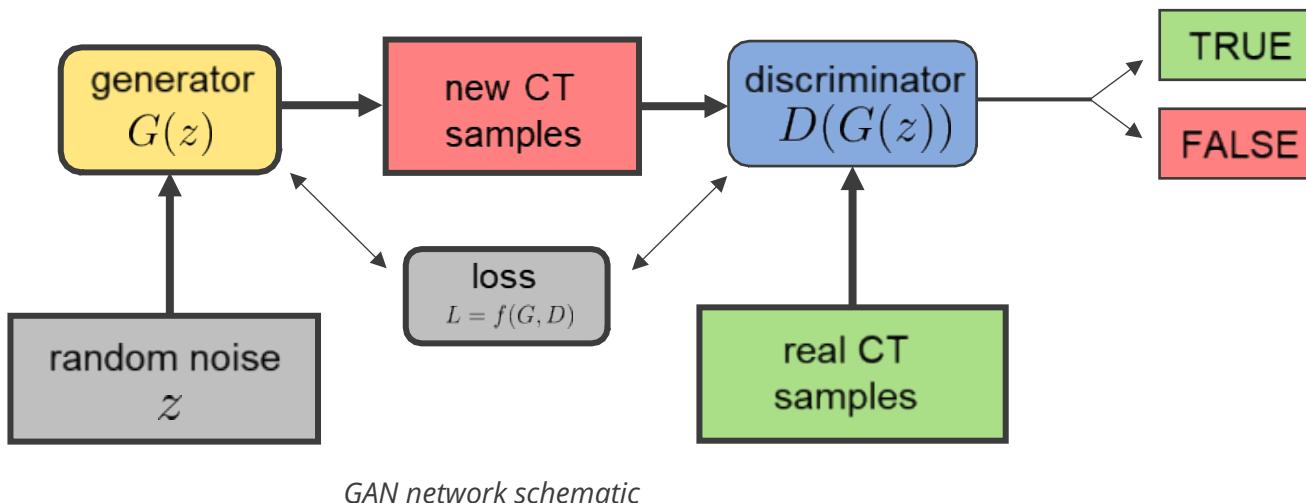
Simulation Code



Requirements: Training data with accurate microstructure and mechanical behavior

Ongoing work: Using GANs to augment CT images of AM material to preserve underlying pore statistics

- Generative Adversarial Networks (GANs) produce new samples from a training set while preserving the underlying statistics.
- GANs are trained to minimize the distance between the distribution of the training data and the generated samples.
- Collaboration with Prof. Amir Farimani and Francis Ogoke (CMU)



Metric	Notes
Volume Distribution	
Nearest Neighbor Distances	
Location Distribution	
Ellipticity	$\sqrt{\frac{a^2 - c^2}{a^2}}$
Moment of Inertia	
Surface Area	
Mallat Scattering Transform	$ x * \psi_{\lambda_p} * \psi_{\lambda_{p'}} * \phi_J$



Can we accurately predict failure in AM parts?

Questions to be answered:

1. What level of scan resolution do we need?
2. Are surfaces or pores more important?
3. How do plasticity and damage models affect results?

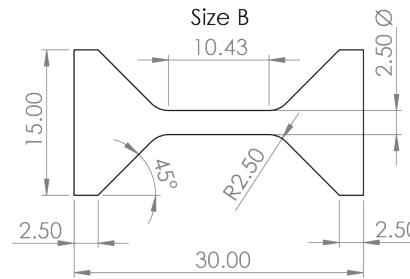
Study carried out on Al-Si10-Mg specimens with pre-test CT scans and post-test blue light scans

Resolutions studied

- 64x64: ~43 μm voxels
- 128x128: ~21 μm voxels
- 256x256: ~10 μm voxels
- Actual Scan: 4.56 μm voxels

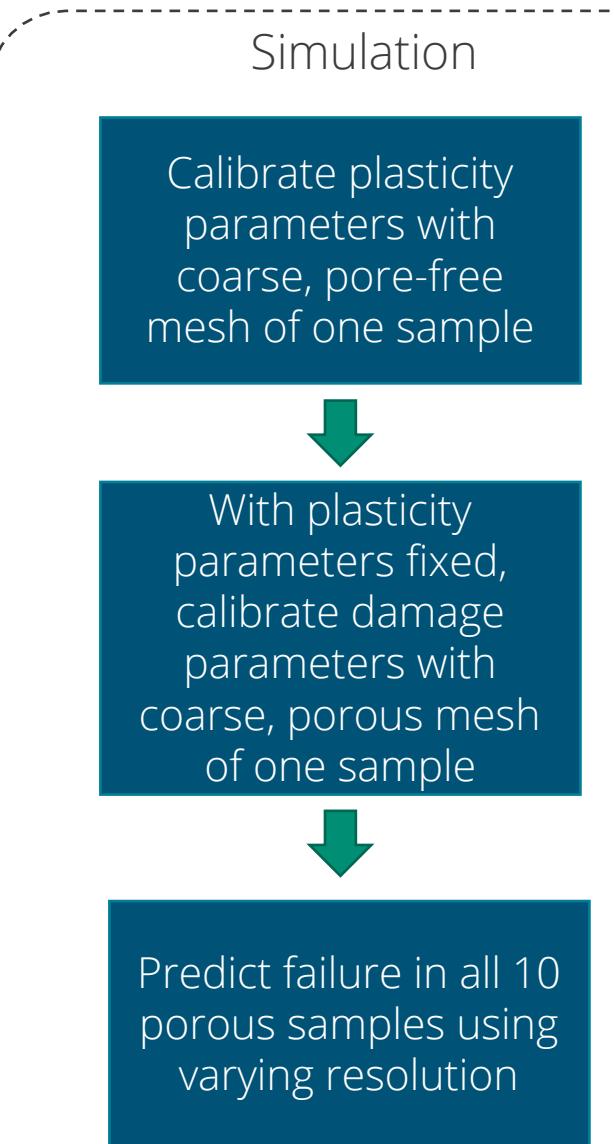
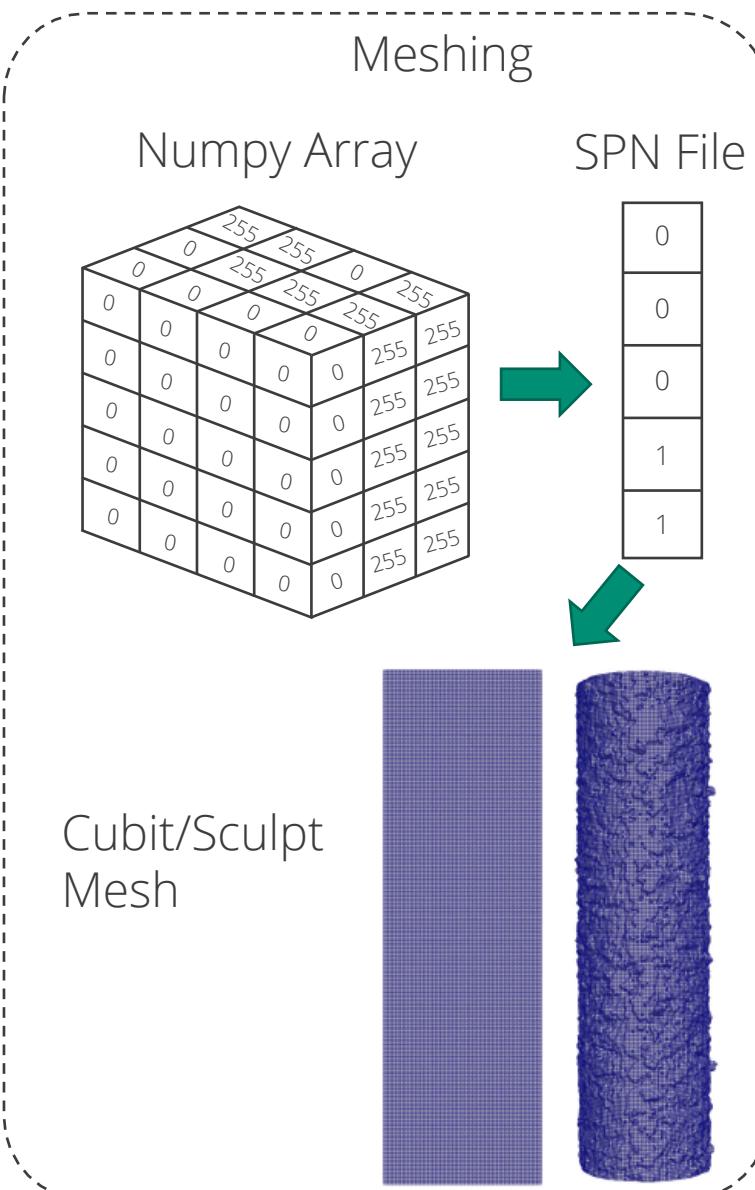
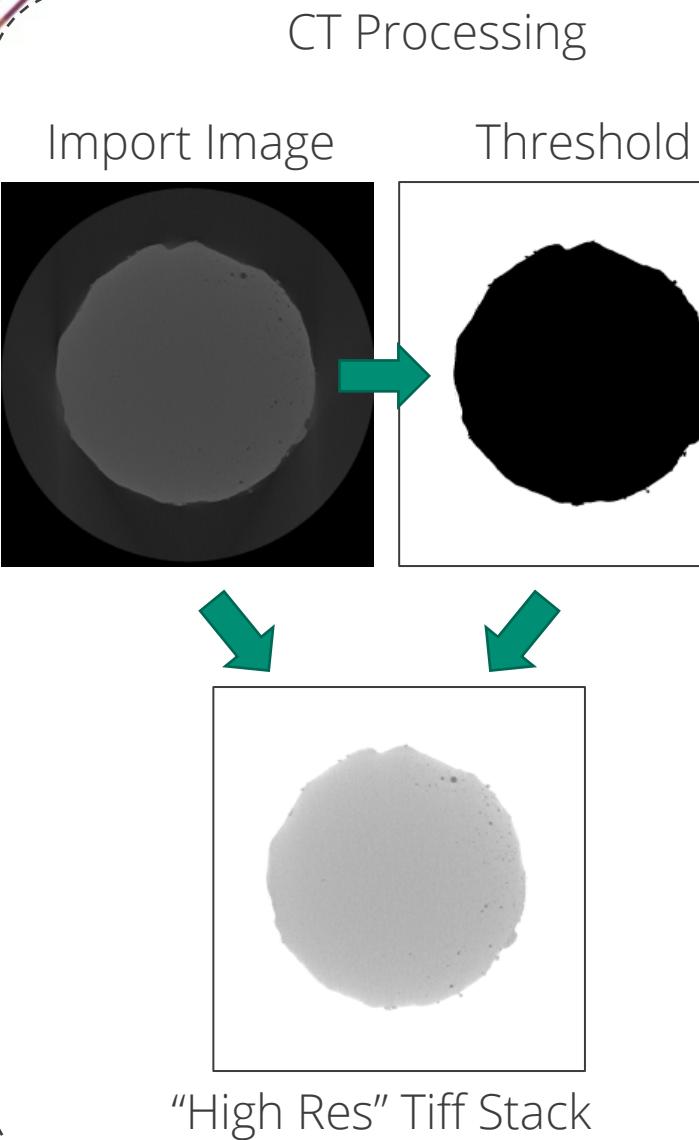
LPBF process and μ CT scanning parameters

- Material: AlSi10Mg
- Heat Treatment: "Stress Relief Anneal" 290°C for 2 hrs
- Sample Orientation: Tensile direction normal to build
- Cylindrical gauge high-throughput tensile samples
 - Equipment: SLM Solutions 280HL
 - Laser Power: 350 W
 - Speed: 1100 mm/s
 - Hatch Spacing: 150 μ m
 - Layer Thickness: 30 μ m
- CT resolution: HF26 - 4.56 μ m



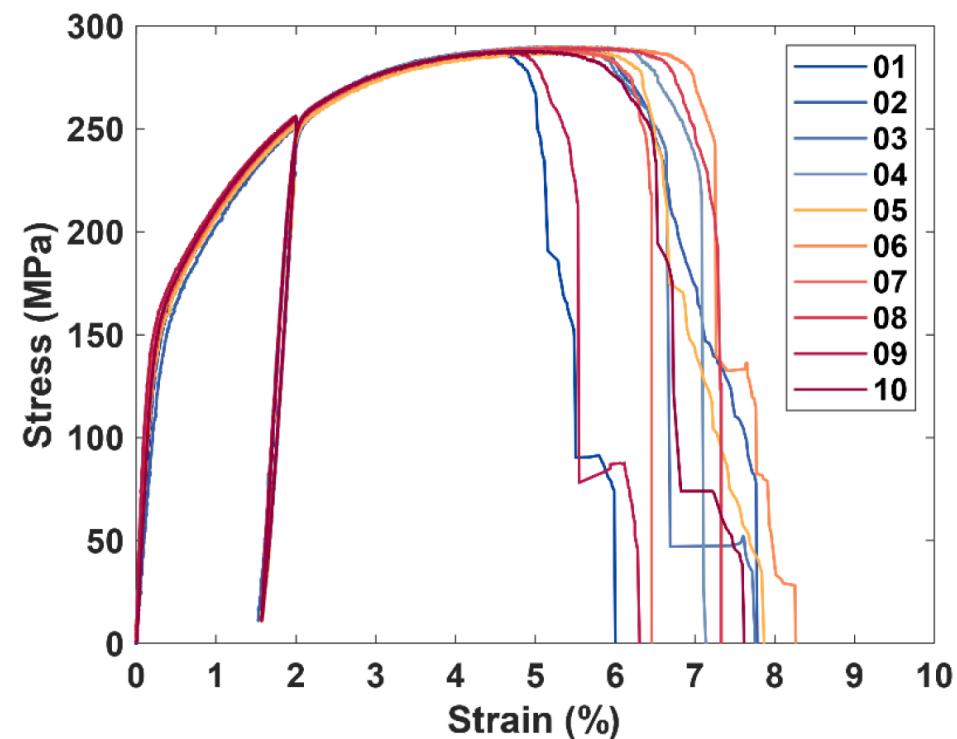
Jay Carroll talk – "Dominant microstructural features impacting failure in Additively Manufactured AlSi10Mg"
Feb. 3, 10:15AM-10:45AM

Modeling Workflow

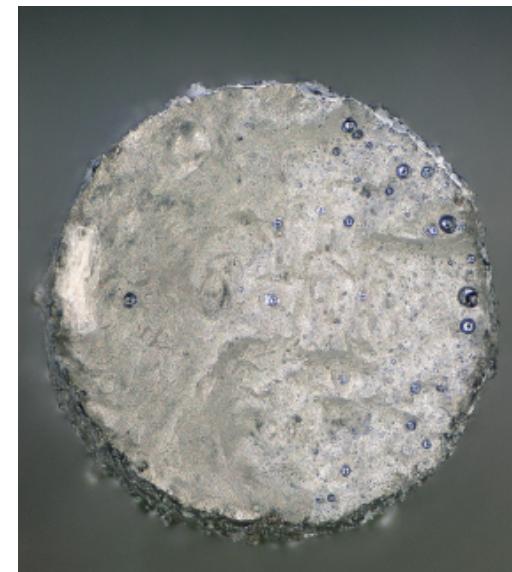
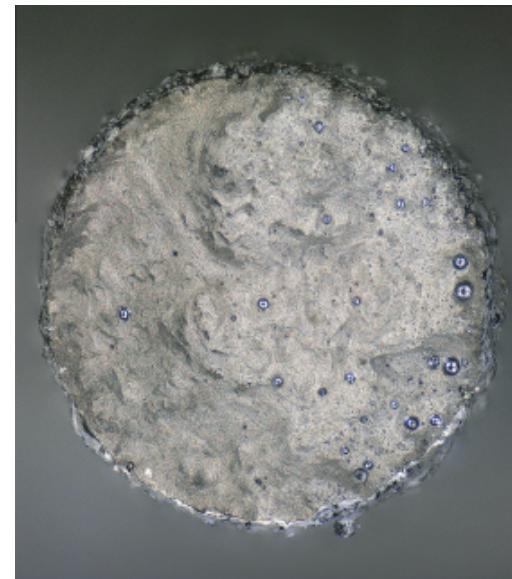


Mechanical Testing

	UTS (MPa)	UNF _{elg} (%)	Ductility (%)	Unloading Modulus (GPa)	Yield Stress (MPa)	Yield Strain (%)
H-BR05-4	288.3	4.927	5.738	60.4	196.1	0.526
H-BR05-5	284.2	4.997	6.350	58.6	175.9	0.500
H-BR05-6	287.6	5.412	6.941	58.3	177.7	0.505



Top



Bottom

Post Mortem Fracture Surface Processing

- Acquire data using the ATOS 3D structured light scanner (GOM)
- Import STL file into custom MATLAB script to adjust for plastic strain in the tensile axis ($\epsilon_{unf} - \epsilon_y$)
- Manually select the nodes of the fracture surface



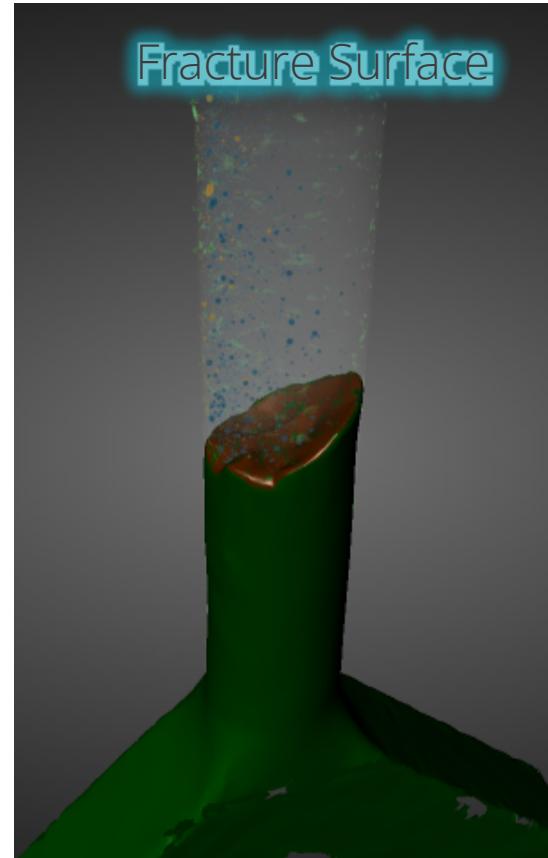
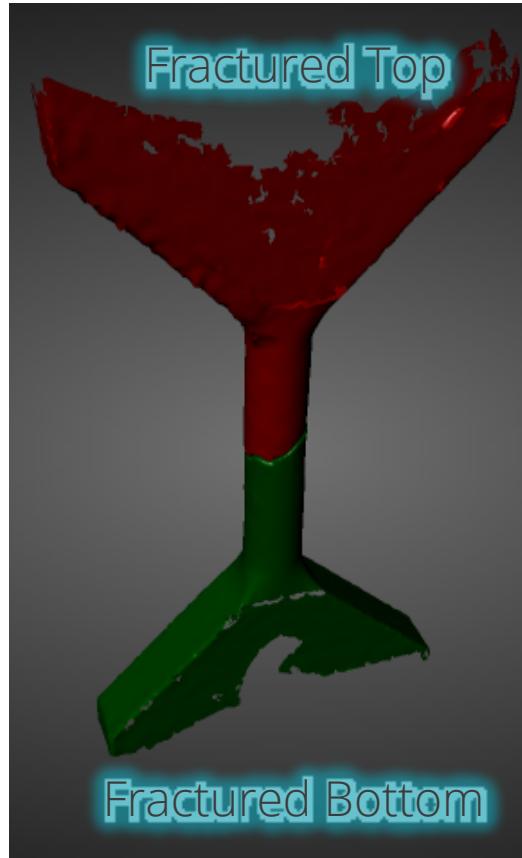
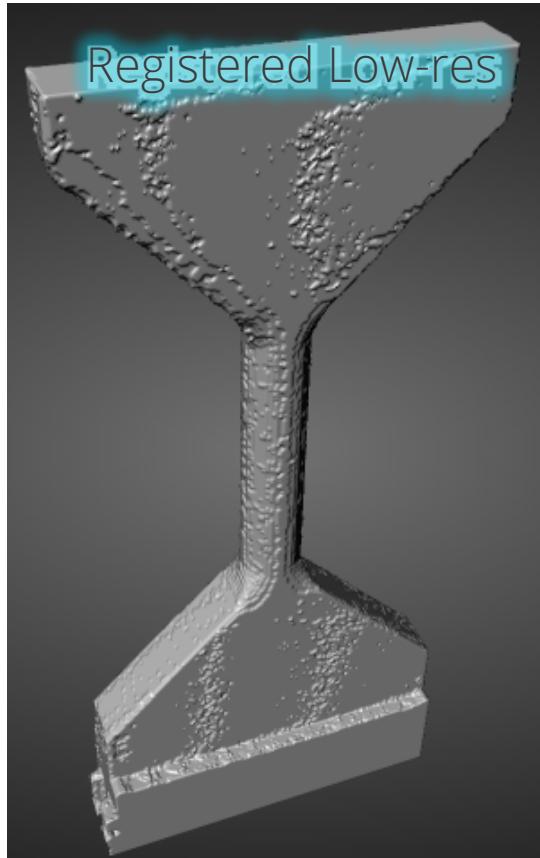
Scanned Component

Strain Adjusted Component

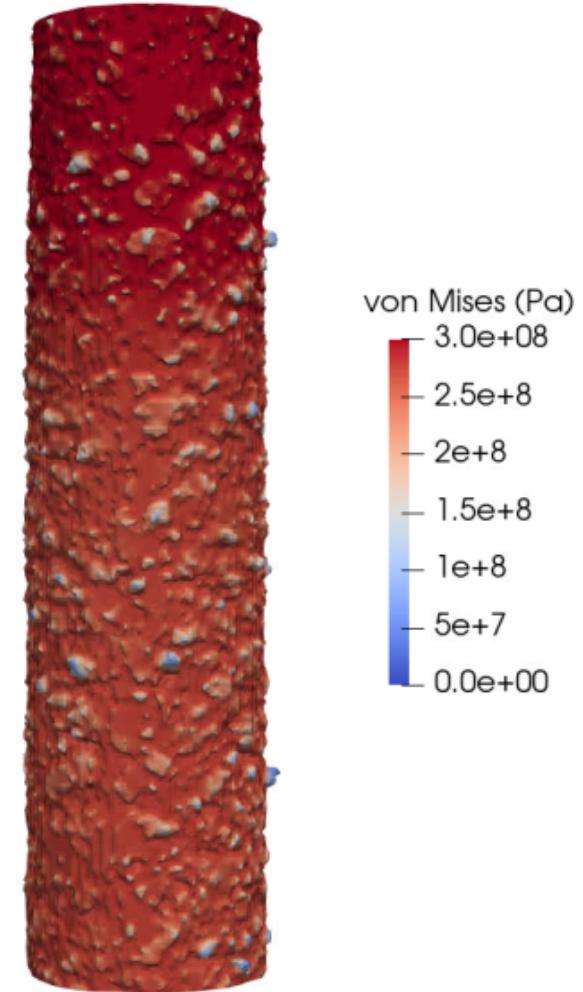
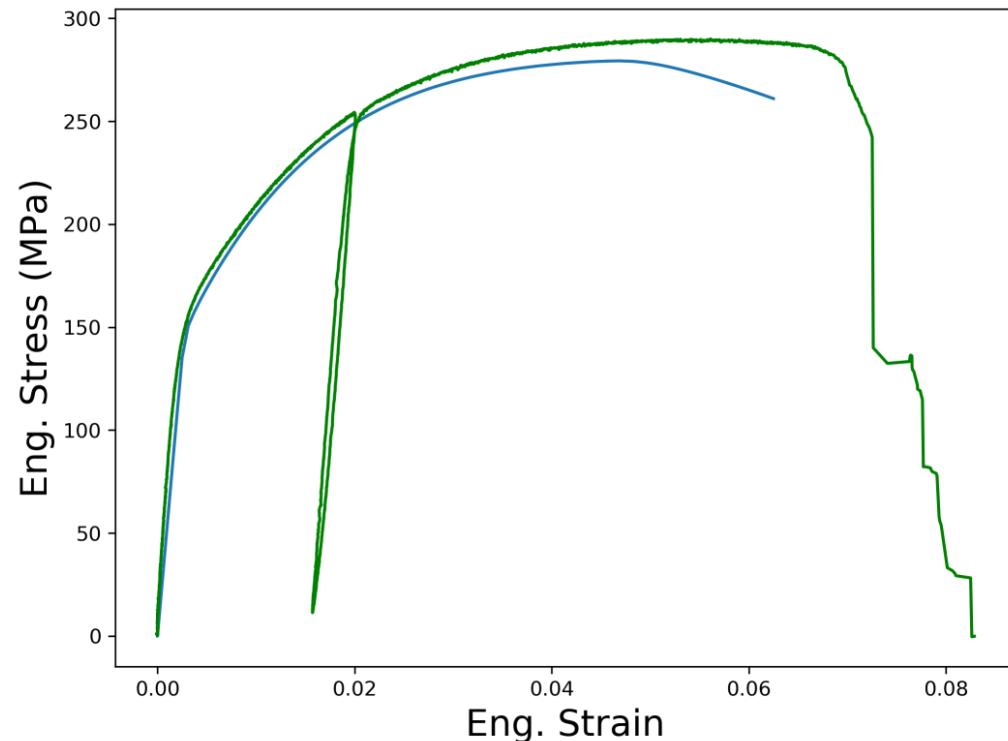
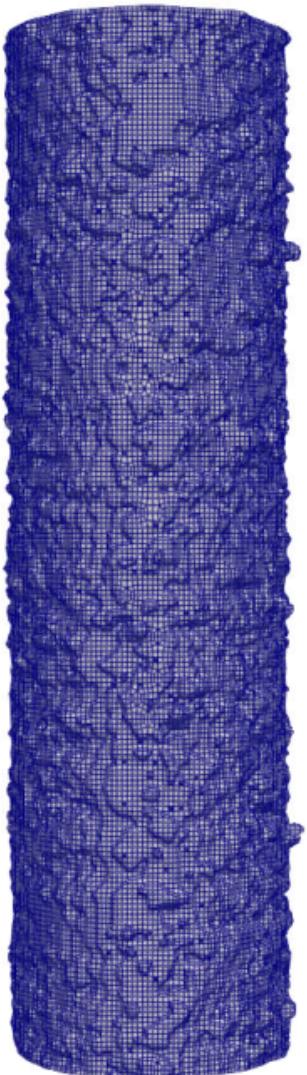
Fracture Surface

Coupling the Data

- Use the high-resolution scan as the datum for all processing
- Register low-resolution µCT scan to high-resolution µCT scan
- Import and register fracture components to the low-resolution scan
- Import and register the fracture surface to the fractured tensile sample
- Additional data registered to the high-resolution scan: Sample Surface, Regression Surface, Surface Voids



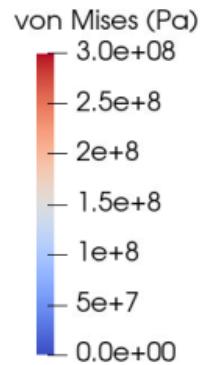
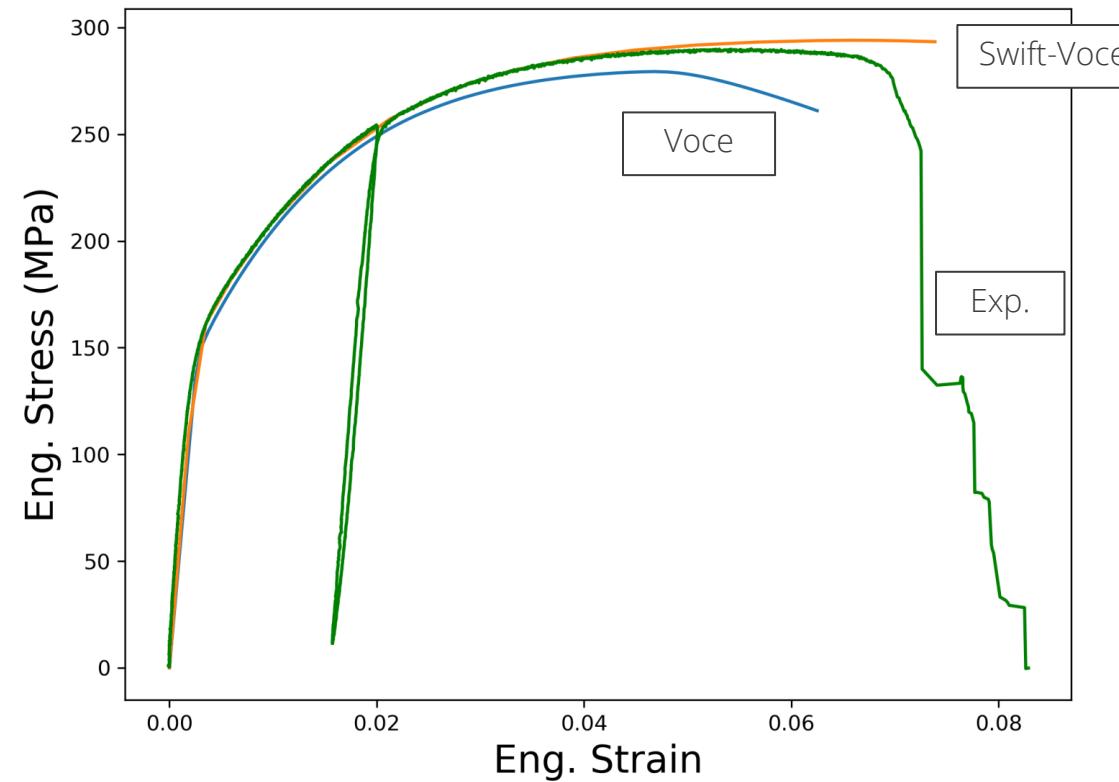
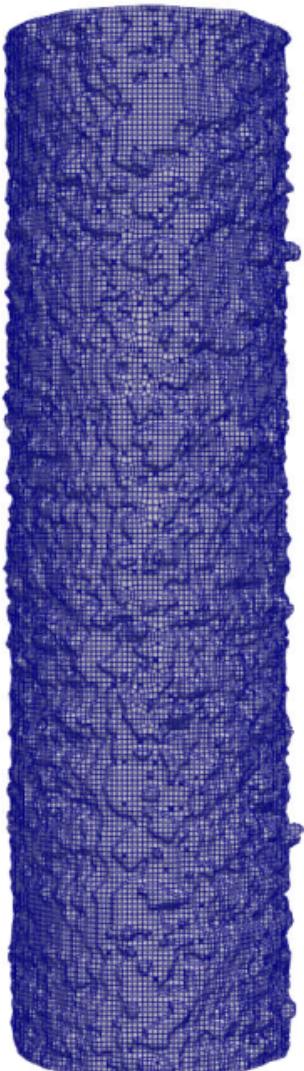
Calibration step 1: Capture plasticity response



- Initial calibration using coarse scan resolution with no pores
- Plasticity is captured with Voce¹ hardening model

$$\bar{\sigma} = \sigma_y + A(1 - \exp(-n\bar{\varepsilon}^p))$$

Accurate plasticity response requires right model form

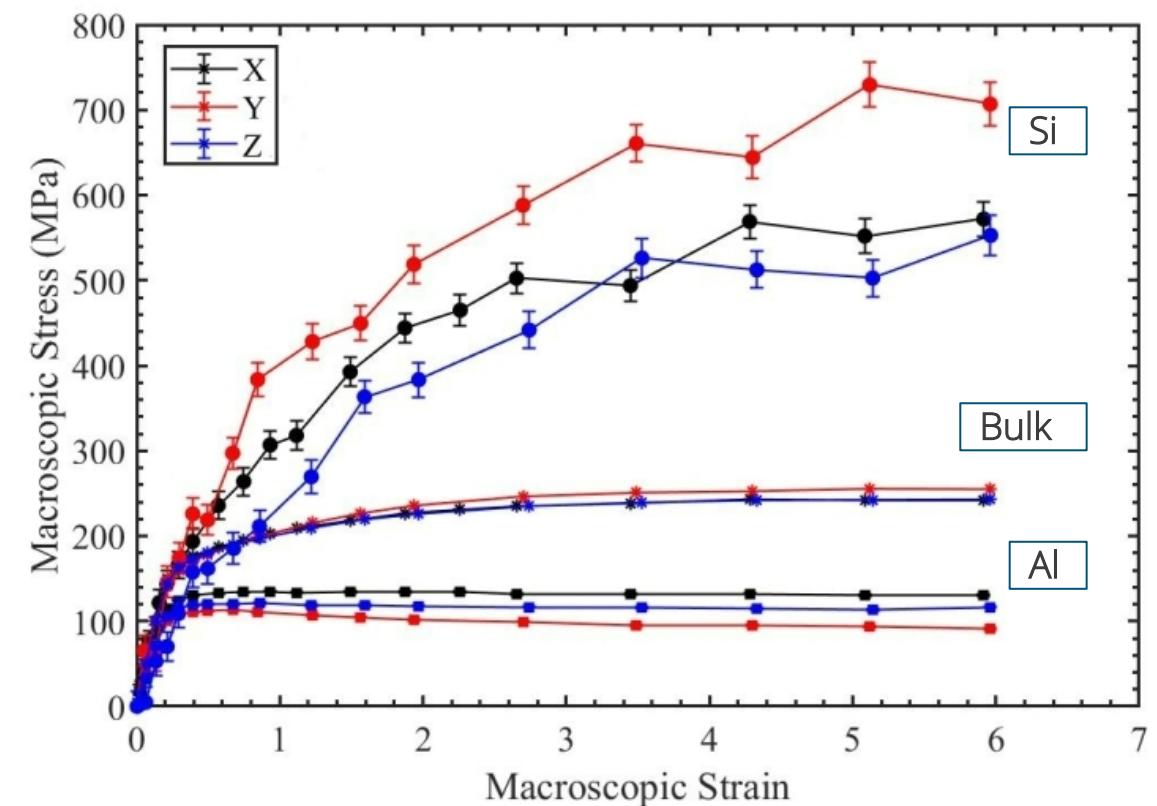
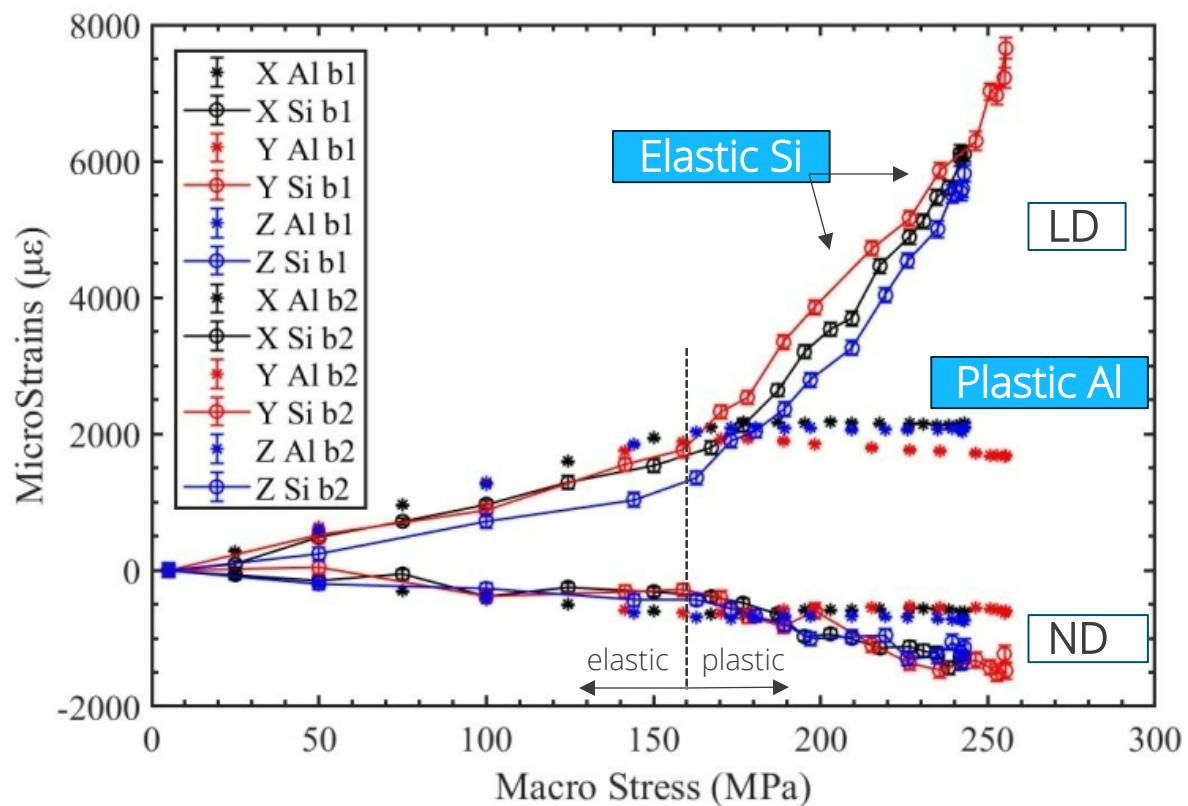


- Addition of extra Swift¹ hardening term improves response

$$\bar{\sigma} = \sigma_y + h\bar{\varepsilon}^p + A(1 - \exp(-n\bar{\varepsilon}^p))$$

A mechanism for late stage hardening in bulk response

LD = Longitudinal Direction (Tensile Axis)
 ND = Normal Direction



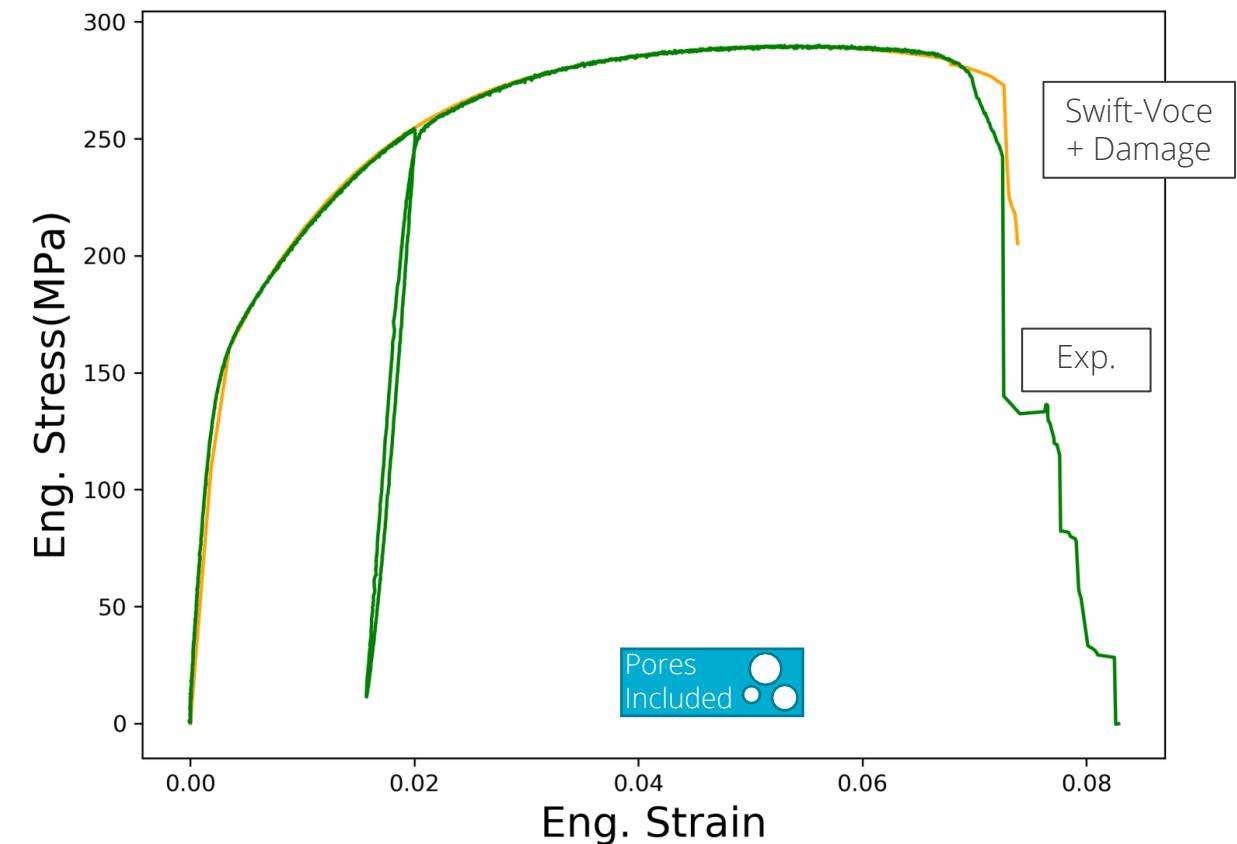
- Stress partitioning study at Los Alamos Neutron Science Center revealed Si particles (~10%) remain elastic until failure

Calibration step 2: Capture failure with damage model

- Add coarse scan mesh with pores
- Voids below scan resolution assumed to be captured by initial void volume fraction and Cocks-Ashby¹ void growth:

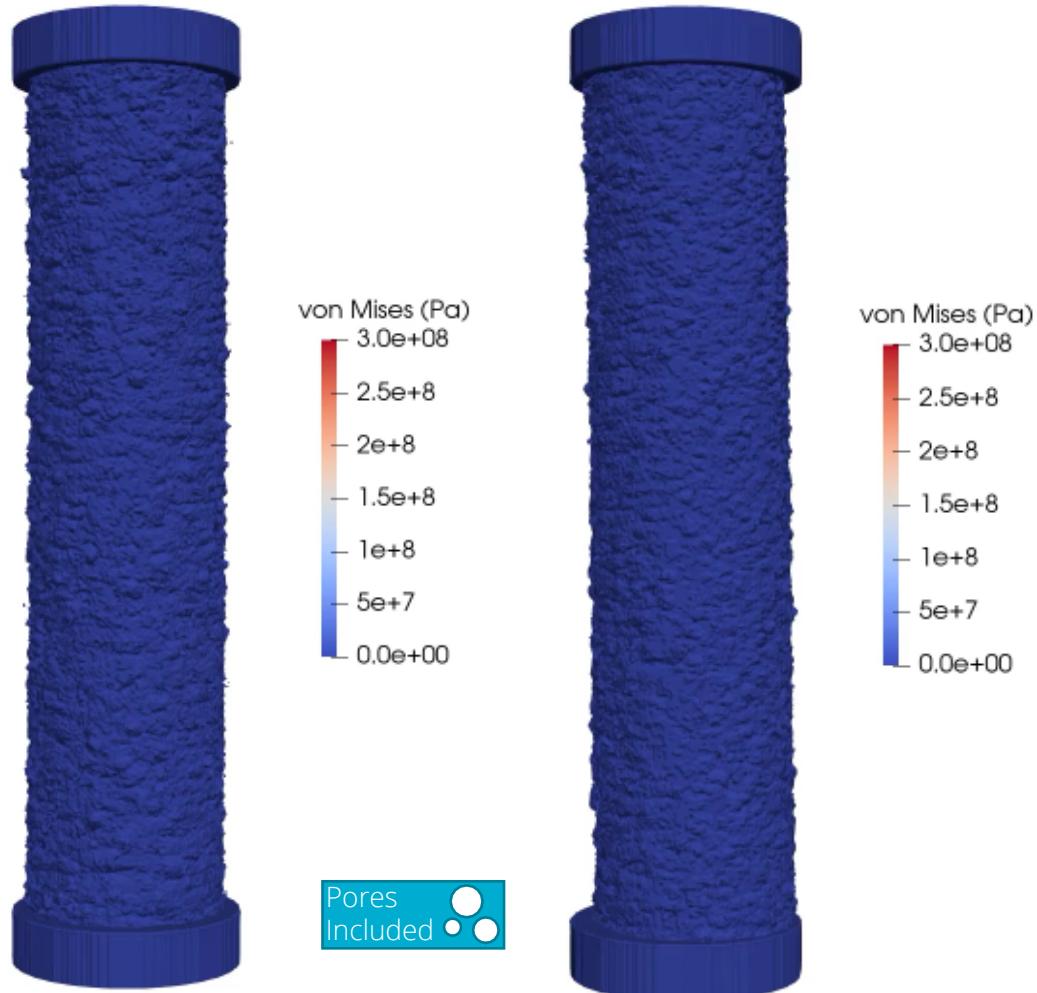
$$\dot{\phi} = \sqrt{\frac{2}{3}} \dot{\epsilon}_p \frac{1 - (1 - \phi)^{m+1}}{(1 - \phi)^m} \sinh \left[\frac{2(2m - 1)}{2m + 1} \frac{\langle p \rangle}{\sigma_e} \right]$$

- Modular damage model is not coupled to stress response (no softening)
- Elements are removed when critical damage (ϕ) threshold of 0.15 is reached



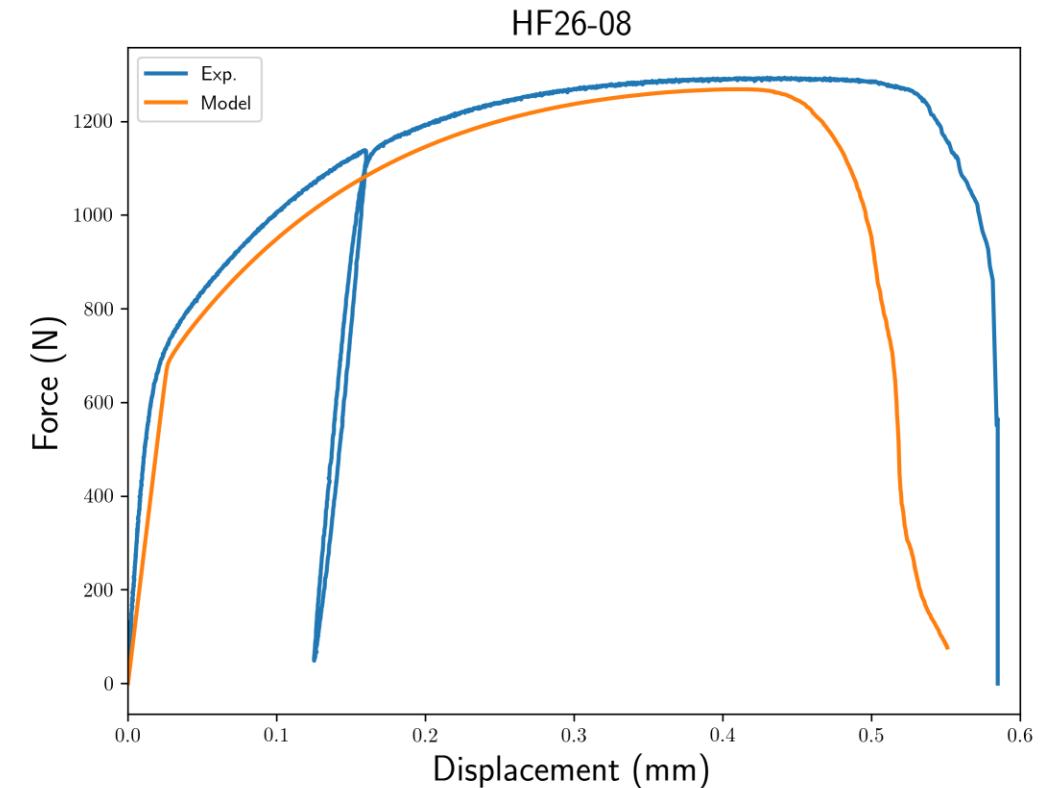
¹Cocks, A.C.F. and Ashby, M.F., Metal Science 1980

Crack path can accurately be captured (for certain samples)



~21 μm voxels, different views

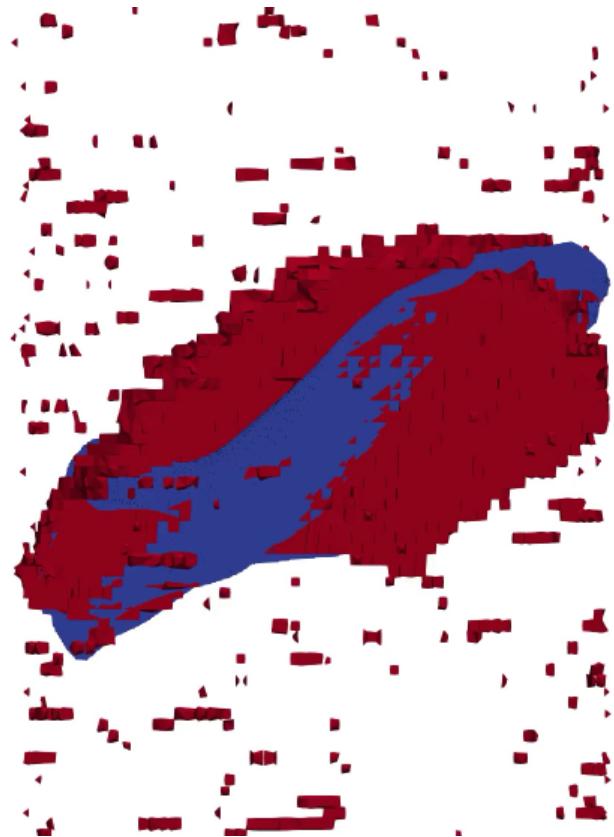
Sample 08



- Higher resolution reduces force response
- Smaller elements decrease failure strain with local damage model

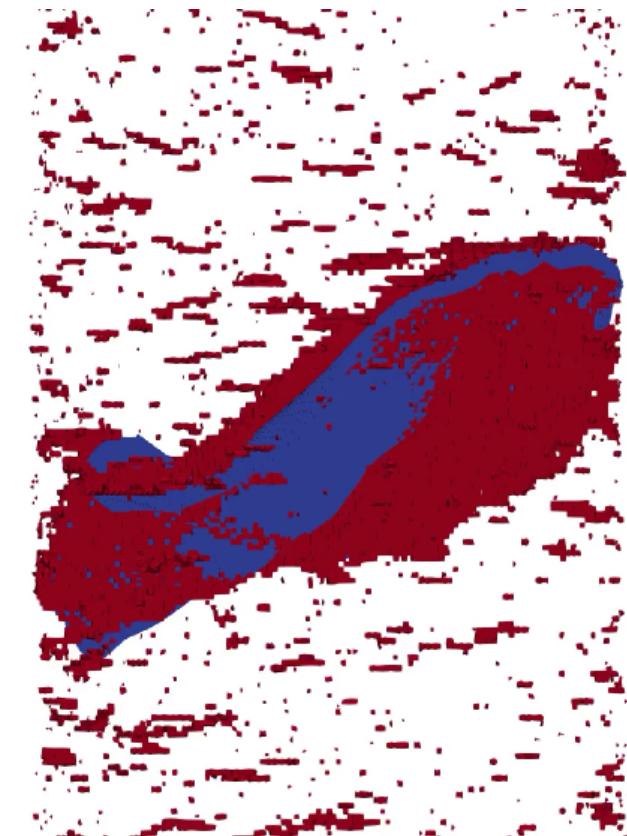
Higher resolution scans improve crack path predictions

Sample 08



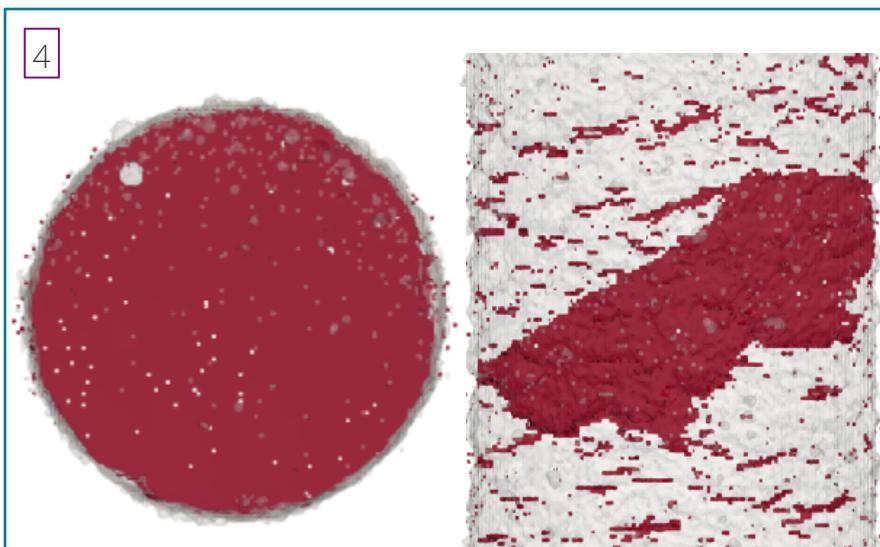
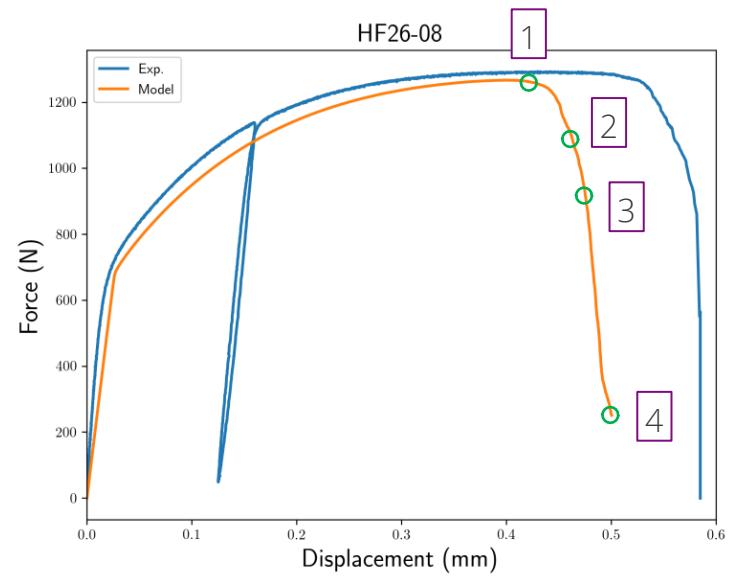
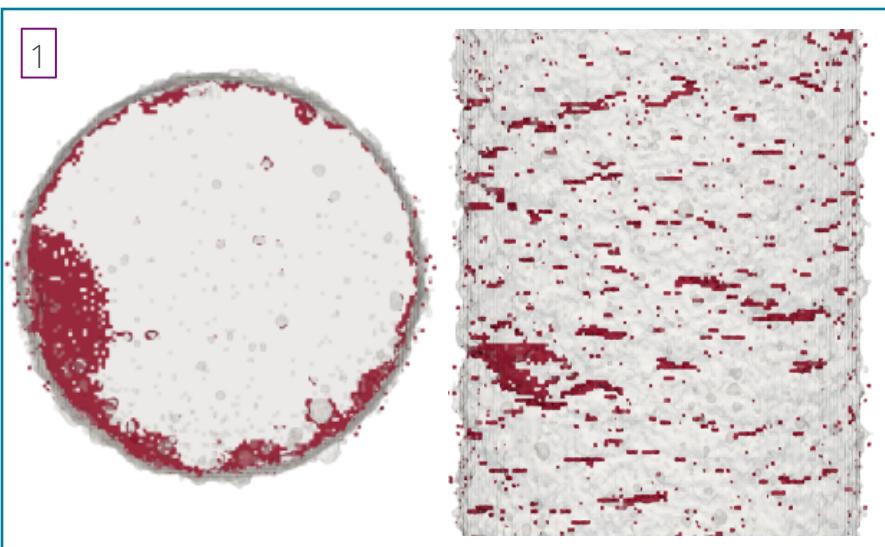
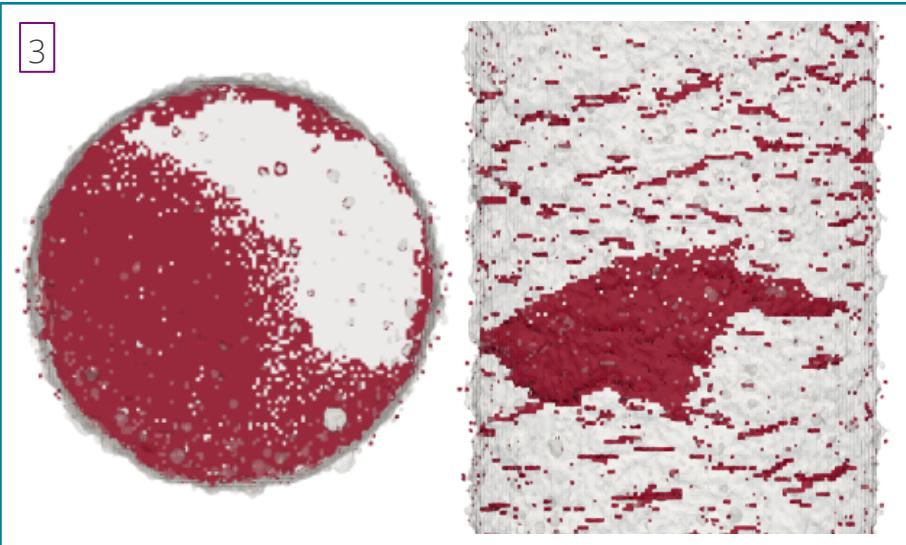
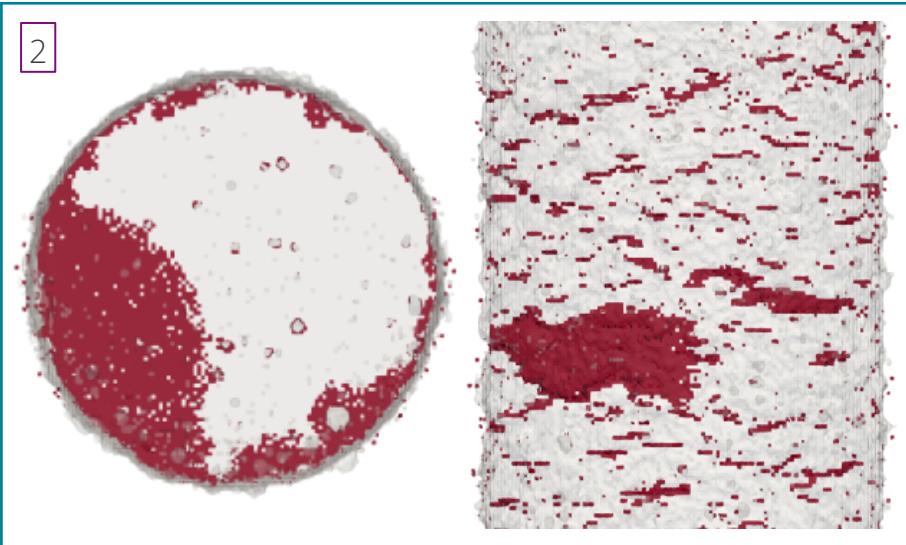
Experiment – Blue
Model - Red

~43 μm voxels
688k elements
144 cpus
16 hour run time



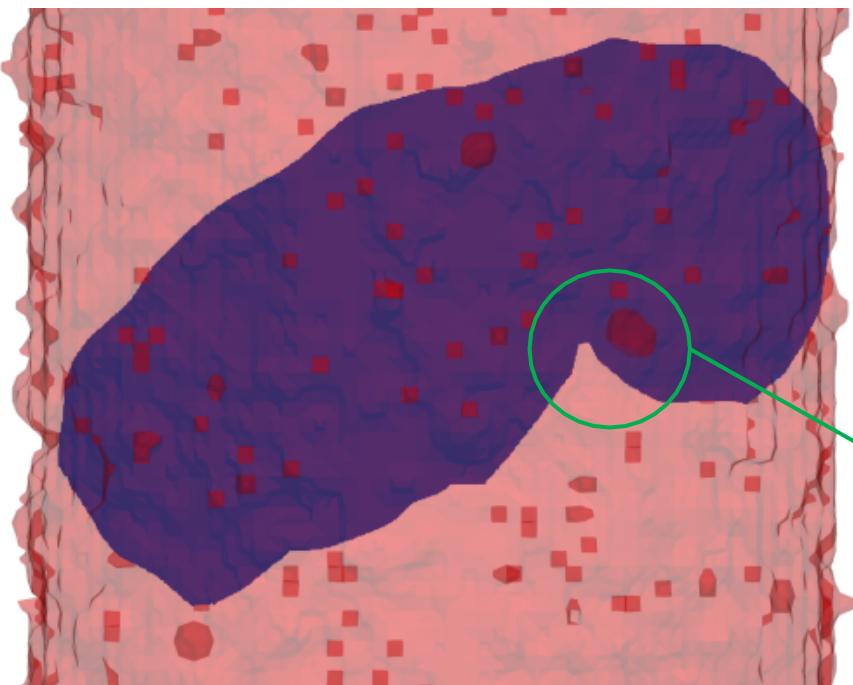
~21 μm voxels
5.2M elements
1056 cpus
24 hour run time

Crack initiates at large surface defect



Crack path is affected by large defects

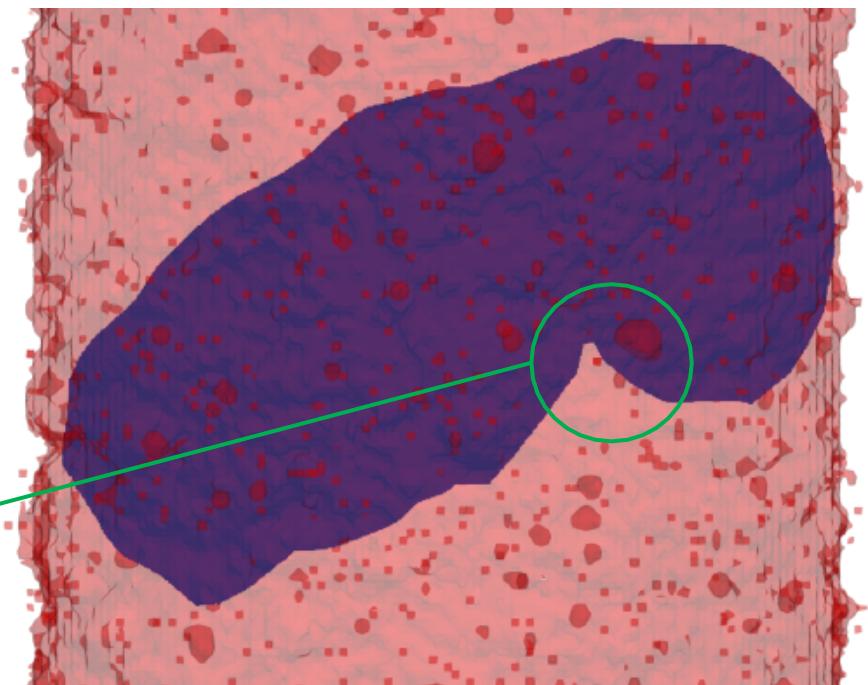
Sample 08



~43 μm voxels

Experiment – Blue
Model – Red

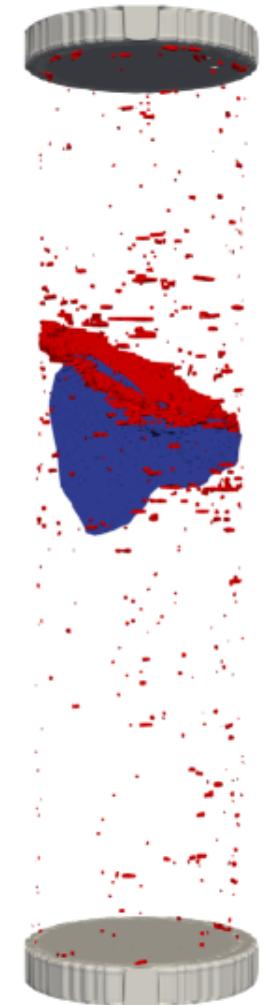
Large void
appears to shift
crack path



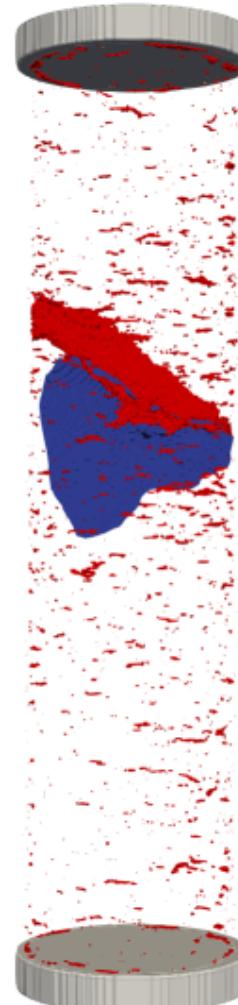
~21 μm voxels

In a different sample, surface roughness appears to drive initiation, while pore structure affects propagation

Sample 01

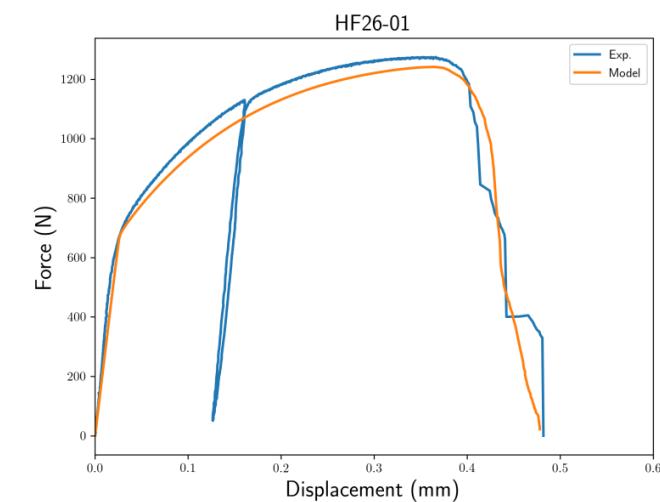
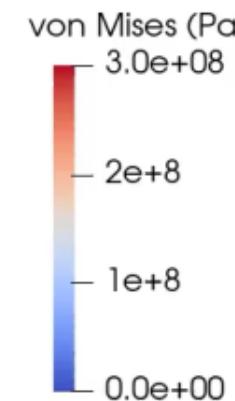


~43 μm voxels
with pores

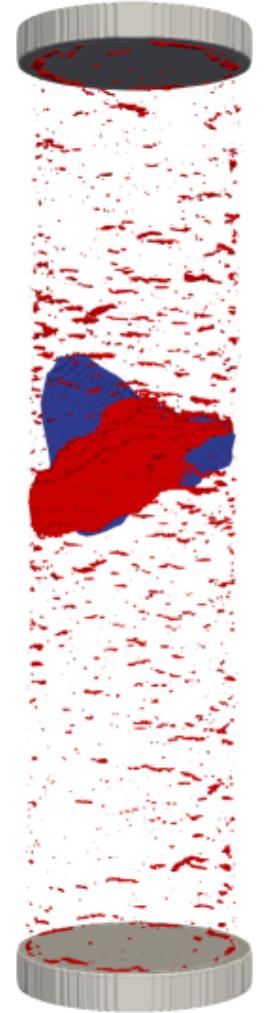


Pores
Included

~21 μm voxels
with pores



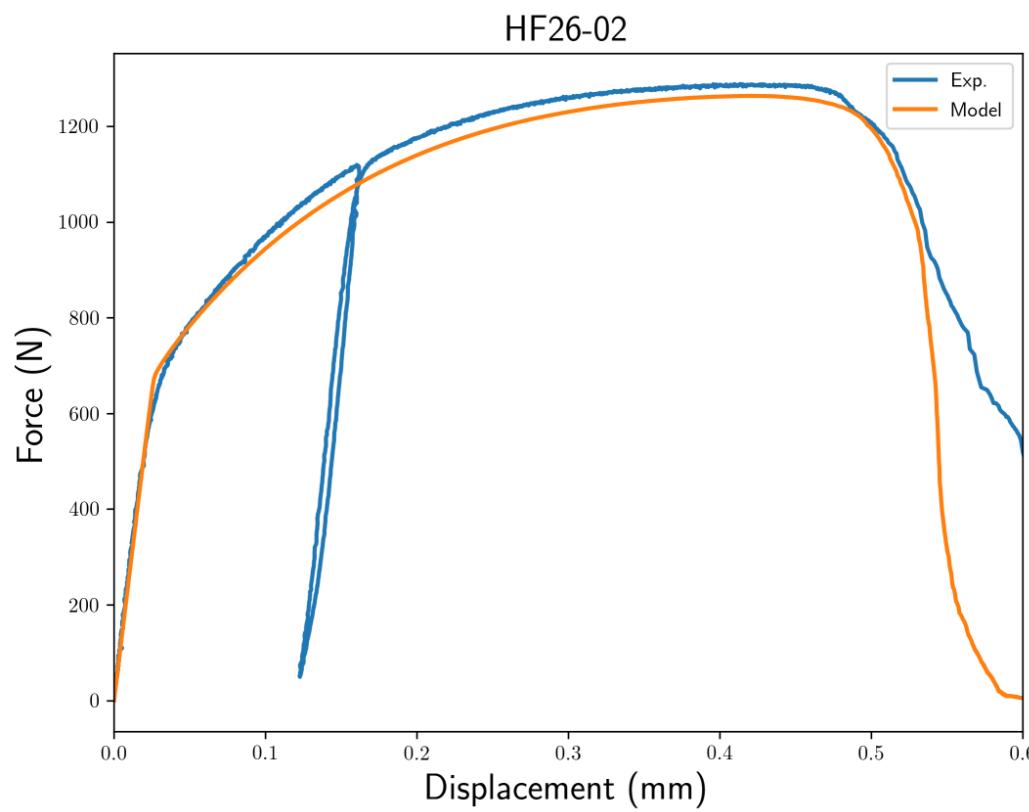
No Pores



~21 μm voxels
no pores

Additional work is needed to determine why crack paths in some samples are incorrectly predicted

Sample 02





Summary

- Computed Tomography can be a powerful tool for assessing defects and model validation/improvement
- Plasticity model form has large impact on accurately capturing response
- Surface roughness appears to drive initiation in *these samples*
- Coarse resolution was able to capture initiation location correctly
- Pores have minimal effect prior to peak load
- Pores have an effect on crack propagation
- Crack path is still incorrect at 21um voxel size for some samples
 - 10 um voxel size running now

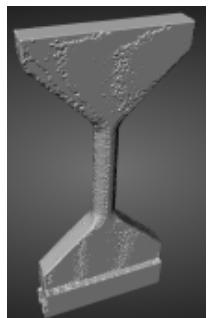


Challenges

- Simulations are very expensive, 10 um size ~46M elements
- Meshing can take hours in parallel
- Registration – easy to flip array axes
- Small decisions on boundary conditions have major effects
- Visualization

Future Work

- Incorporate low resolution scan of grips into model for better boundary condition representation
- Iteratively smoothing surfaces up to smooth cylinder – isolate pore effect
- Update damage parameters for smaller mesh size in higher resolution models
- Mesh size study for same voxel resolution





Questions?
Interested in a postdoc position in this area?
kyljohn@sandia.gov