



Sandia
National
Laboratories

Detecting False Data Injection Attacks in Battery Stacks Using Physics-Based Modeling and Cumulative Sum Algorithm

Victoria Obrien

*Electrical Engineering
Department at Texas Tech
University*

*Energy Storage Technology
& Systems at Sandia
National Laboratories*

Lubbock, TX /
Albuquerque, NM, USA

Victoria.Obrien@ttu.edu
vaobrie@sandia.gov

Vittal S. Rao

*Electrical Engineering
Department*

Texas Tech University

Lubbock, TX, USA

Vittal.rao@ttu.edu

Rodrigo D. Trevizan

*Energy Storage Technology
& Systems*

*Sandia National
Laboratories*

Albuquerque, NM, USA

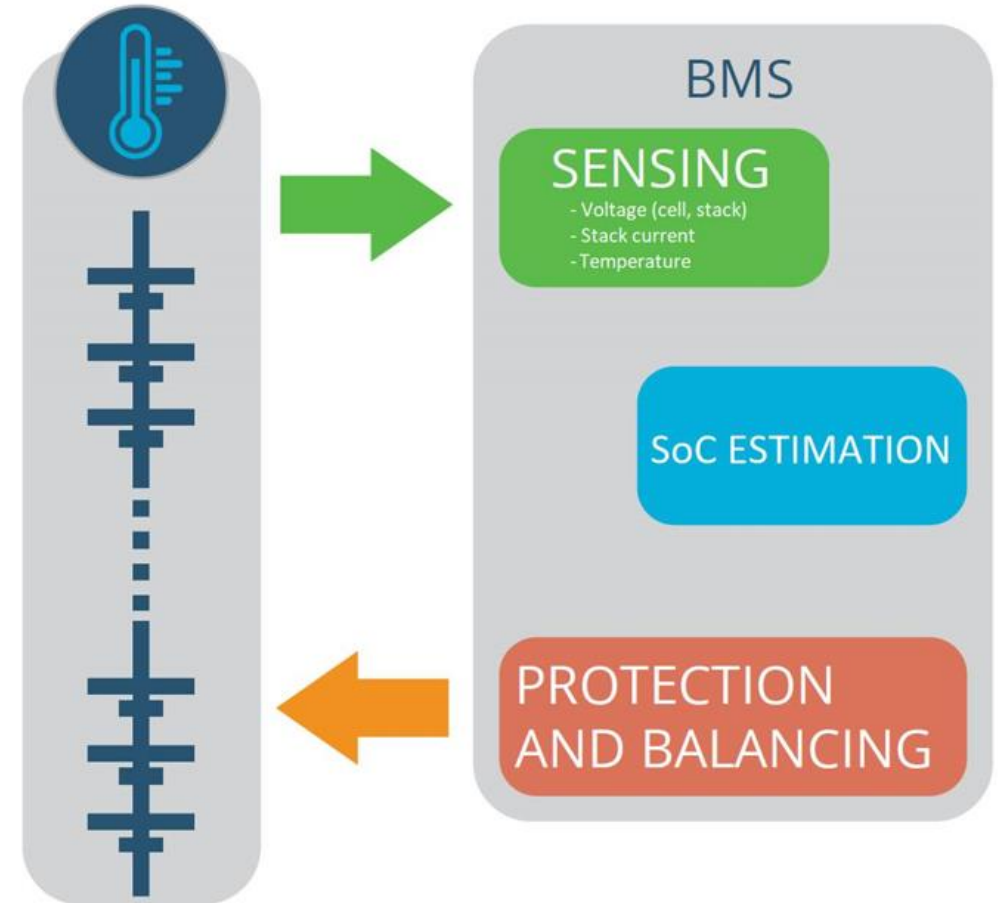
rdtrevi@sandia.gov

- False Data Injection Attacks (FDIAs) can inject false measurements on sensors, monitor sensor readings, or deny service,
 - Typically evade traditional bad data detectors
 - Can cause equipment malfunction

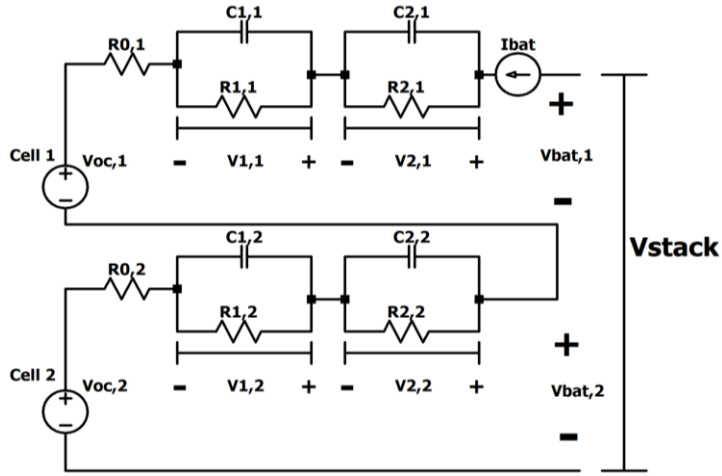
Contributions of this work:

- Accurate SoC estimation for a stack of batteries
 - Current literature focuses on modeling batteries as single cells or modeling stacks of batteries using the “big cell” approximation [1] - [6]
- Quick detection of small magnitude FDIAs in SoC estimation for a stack of batteries using a physical models, an Extended Kalman Filter (EKF), and a statistics-based Cumulative Sum (CUSUM) Algorithm
- Monitoring battery stacks will allow the EKF to compute estimations in the event of some sensor failures – adding robustness to the estimation

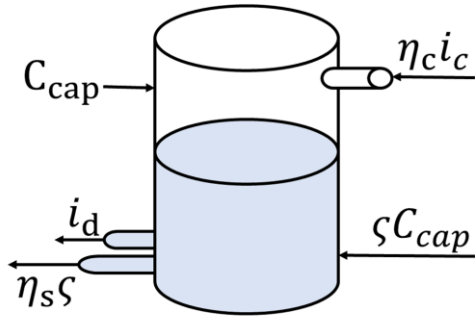
BATTERY MODULE



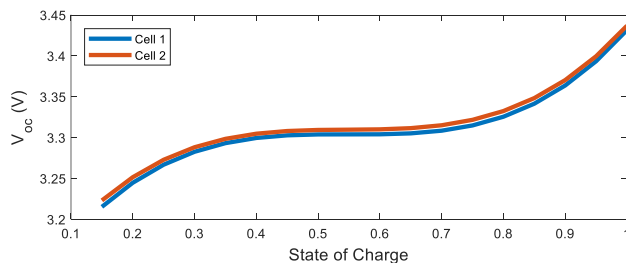
SoC Estimation for Battery Stacks



Equivalent Circuit Model



Battery Charge Reservoir Model



Average Open Circuit Voltage of Cells, as done in [7]

Governing Equations:

$$x[k+1] = f(x[k], u[k], w[k])$$

$$y[k] = g(x[k], u[k], v[k])$$

where $w[k] \sim \mathcal{N}(0, Q)$ and $v[k] \sim \mathcal{N}(0, R)$

$$i_{bat}[k] = i_c[k] + i_d[k]$$

$$\varsigma_1[k+1] = e^{-\eta_{s1}\Delta t} \varsigma_1[k] + \frac{\eta_{c1}\Delta t}{C_{cap1}} i_c[k] + \frac{\Delta t}{C_{cap1}} i_d[k]$$

$$\varsigma_2[k+1] = e^{-\eta_{s2}\Delta t} \varsigma_2[k] + \frac{\eta_{c2}\Delta t}{C_{cap2}} i_c[k] + \frac{\Delta t}{C_{cap2}} i_d[k]$$

$$v_{1,1}[k+1] = e^{-\frac{\Delta t}{R_{1,1}C_{1,1}}} v_{1,1}[k] + \frac{\Delta t}{C_{1,1}} i_c[k] + \frac{\Delta t}{C_{1,1}} i_d[k]$$

$$v_{2,1}[k+1] = e^{-\frac{\Delta t}{R_{2,1}C_{2,1}}} v_{2,1}[k] + \frac{\Delta t}{C_{2,1}} i_c[k] + \frac{\Delta t}{C_{2,1}} i_d[k]$$

$$v_{1,2}[k+1] = e^{-\frac{\Delta t}{R_{1,2}C_{1,2}}} v_{1,2}[k] + \frac{\Delta t}{C_{1,2}} i_c[k] + \frac{\Delta t}{C_{1,2}} i_d[k]$$

$$v_{2,2}[k+1] = e^{-\frac{\Delta t}{R_{2,2}C_{2,2}}} v_{2,2}[k] + \frac{\Delta t}{C_{2,2}} i_c[k] + \frac{\Delta t}{C_{2,2}} i_d[k]$$

$$v_{bat1}[k] = v_{oc1}(\varsigma_1[k]) + v_{1,1}[k] + v_{2,1}[k] + R_{0,1}(i_c[k] + i_d[k])$$

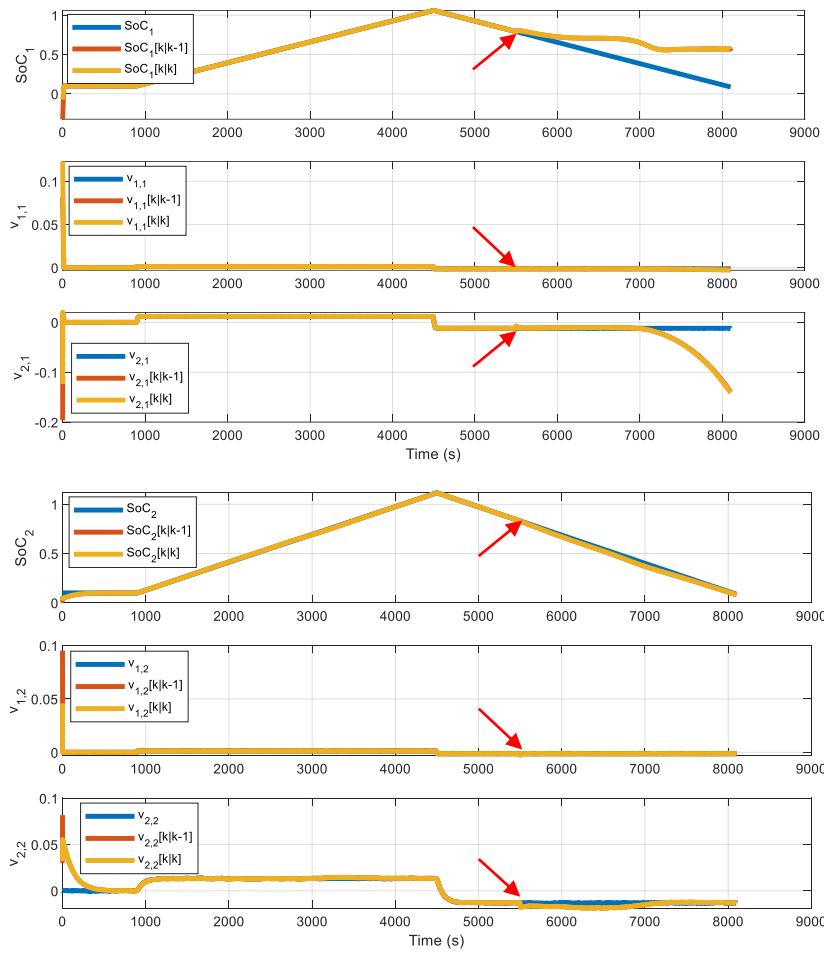
$$v_{bat2}[k] = v_{oc2}(\varsigma_2[k]) + v_{1,2}[k] + v_{2,2}[k] + R_{0,2}(i_c[k] + i_d[k])$$

$$v_{stack}[k] = v_{bat1}[k] + v_{bat2}[k]$$

$k, \Delta t$	Current time step, sampling time	Kalman Filter Variables
u	System input	
y, \hat{y}	Model output, predicted output	
x, \hat{x}	State, predicted state	
w	Process noise	
v	Measurement noise	System State Variables
ς_1	Battery SoC for Cell1	
$v_{1,1}$	RC voltage drop 1 for cell 1	
$v_{2,1}$	RC voltage drop 2 for cell 1	
ς_2	Battery SoC for Cell 2	
$v_{1,2}$	RC voltage drop 1 for cell 2	System Inputs
$v_{2,2}$	RC voltage drop 2 for cell 2	
i_d	Discharge current	
i_c	Charge current	
v_{bat1}	Battery voltage for cell 1	System Outputs
v_{bat2}	Battery voltage for cell 2	
v_{stack}	Battery stack voltage	
i_{bat}	Battery current	

Extended Kalman Filter:

- Required to estimate the SoC of the battery stack using the nonlinear relationship between open circuit voltages and SoC
- The a priori measurement residuals derived from the EKF are used in the CUSUM algorithm to detect FDIAs



Cumulative Sum Algorithm:

- Performed using a priori residual data with mean ($\mu = 0$):

$$z[k|k-1] = y[k] - \hat{y}[k|k-1]$$

- Population Standard Deviation:

$$\sigma_z = \frac{A_3 \bar{s}}{3}$$

- Upper / Lower Control Limit:

$$UCL = h\sigma_z, LCL = -h\sigma_z$$

- High and Low CUSUM:

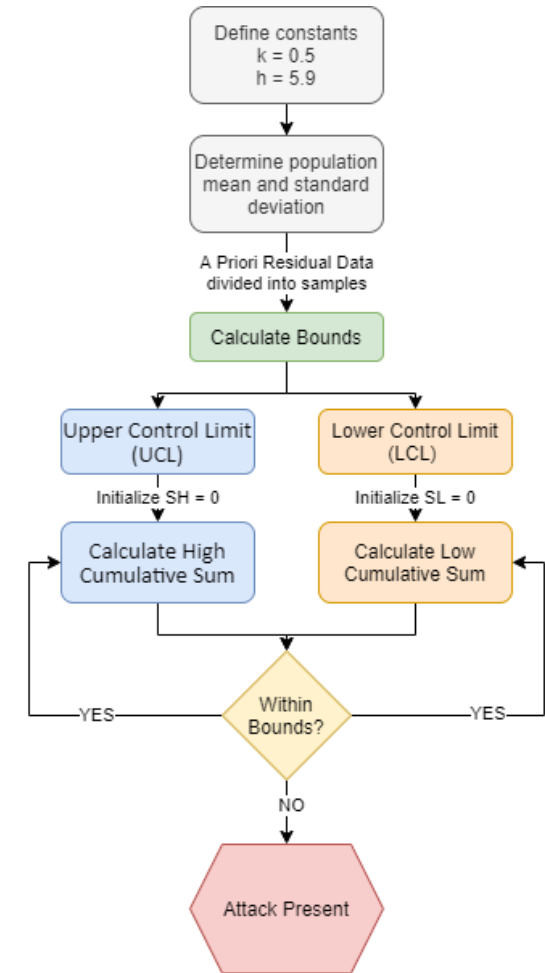
$$SH_i = \max(0, \bar{z}_i - \mu - k\sigma_z + SH_{i-1})$$

$$SL_i = \min(0, \bar{z}_i - \mu + k\sigma_z + SL_{i-1})$$

- Determine presence of attack:

$$SH_i > UCL \text{ or } SL_i < LCL \rightarrow \text{attack present}$$

$$SH_i \leq UCL \text{ and } SL_i \geq LCL \rightarrow \text{no attack}$$

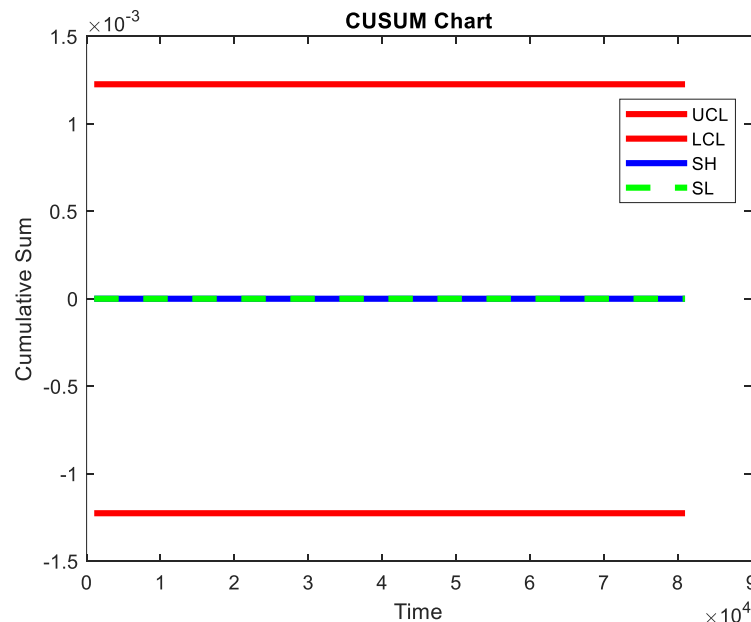


CUSUM Algorithm Flowchart

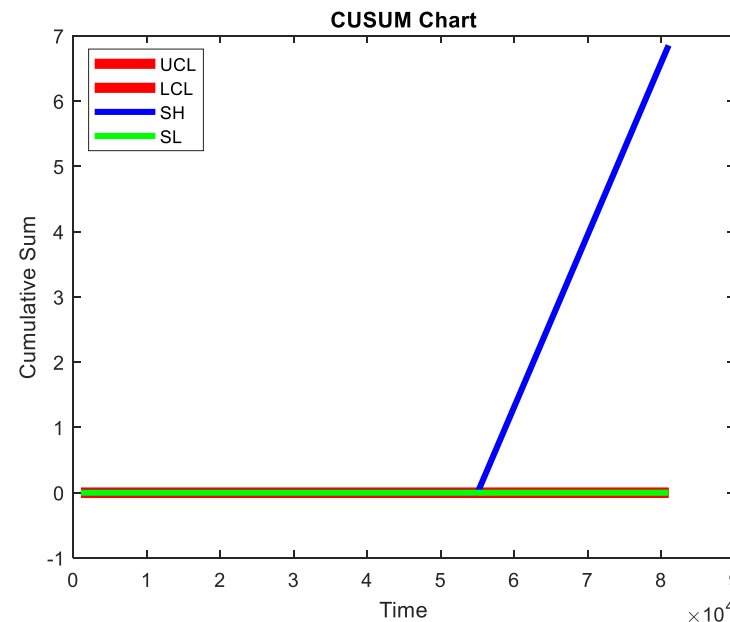
Results and Conclusions



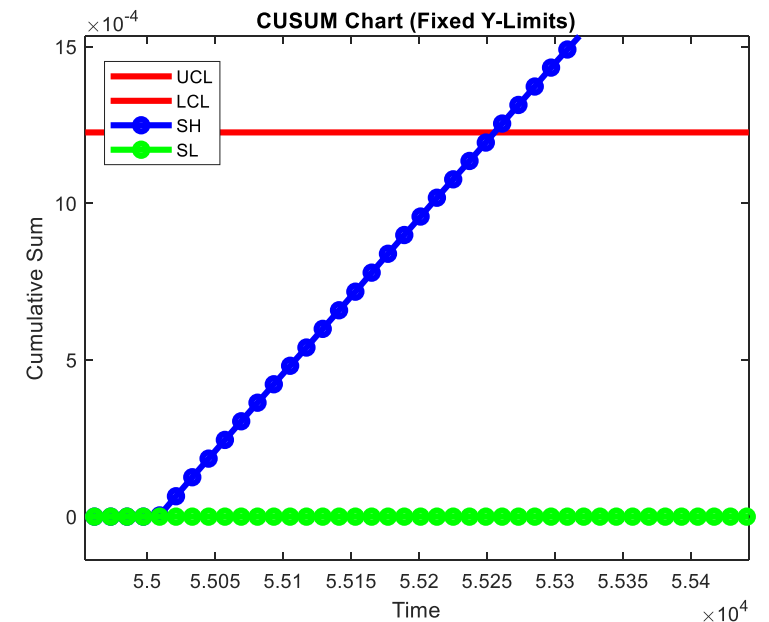
- The method described can be used to quickly detect FDIA in BESS state estimation
 - This CUSUM Algorithm could detect attacks as low as 500 μV added to v_{bat_1} measurement
 - The algorithm resulted in zero false alarms
- Performing estimation with a stack of batteries, rather than a single cell, adds redundancy to the measurements allowing the system to remain observable when all but one sensor failed
 - Created a more robust estimation algorithm



CUSUM Chart with no Attack Present



CUSUM Chart with 500 μV Attack Present on the v_{bat_1} Measurement



CUSUM Chart with 500 μV Attack Present on the v_{bat_1} Measurement (zoomed view)

Acknowledgements

The authors would like to thank Dr. Imre Gyuk, Director of the Energy Storage Program, for his continued support. We also acknowledge the support of the U.S Department of Education's program on Graduate Assistance in Areas of National Need (GAANN) grant to Texas Tech University.

Project Deliverables and Publications

- V. Obrien, R. D. Trevizan and V. Rao, "Detecting False Data Injection Attacks to Battery State Estimation Using Cumulative Sum Algorithm," *53rd North American Power Symposium (NAPS)*, Nov. 2021 pp 1-6, *Accepted for publication*.
 - V. Obrien, R. D. Trevizan, and V. Rao, " Detection of false data injection attacks targeting state of charge estimation of battery energy storage systems," *2021 Advanced Energy Conference*, Jun 2021. *Winner of best graduate student poster award*.
-

References

- [1] D. Rosewater, S. Ferreira, D. Schoenwald, J. Hawkins and S. Santoso, "Battery Energy Storage State-of-Charge Forecasting: Models, Optimization, and Accuracy," in *IEEE Trans. Smart Grid*, vol. 10, no. 3, pp. 2453-2462, May 2019.
- [2] D. M. Rosewater, D. A. Copp, T. A. Nguyen, R. H. Byrne and S. Santoso, "Battery Energy Storage Models for Optimal Control," in *IEEE Access*, vol. 7, pp. 178357-178391, 2019.
- [3] Yang, S., Deng, C., Zhang, Y., & He, Y. (2017). State of Charge Estimation for Lithium-Ion Battery with a Temperature-Compensated Model. *Energies*, 10(10), 1560. doi:10.3390/en10101560
- [4] Fonseca, J M.L., Sambandam, Gnana K, Raj, Krishna, Rajashekara, Kaushik, & Atcitty, Stanley. *Offline Parameter Estimation Method for Equivalent Circuit Model of Lithium-ion Batteries in Grid Energy Storage*. United States.
- [5] Ye, Dan & Zhang, Tian-Yu. (2019). Summation Detector for False Data-Injection Attack in Cyber-Physical Systems. *IEEE Transactions on Cybernetics*. PP. 10.1109/TCYB.2019.2915124.
- [6] W. Ma, J. Qiu, J. Liang and B. Chen, "Linear Kalman Filtering Algorithm With Noisy Control Input Variable," in *IEEE Trans. Circuits and Systems II: Express Briefs*, vol. 66, no. 7, pp. 1282-1286, July 2019, doi: 10.1109/TCSII.2018.2878951.
- [7] Z. Liu and H. He, "Sensor fault detection and isolation for a lithium-ion battery pack in electric vehicles using adaptive extended Kalman filter", *Appl. Energy*, vol. 185, pp. 2033-2044, 201