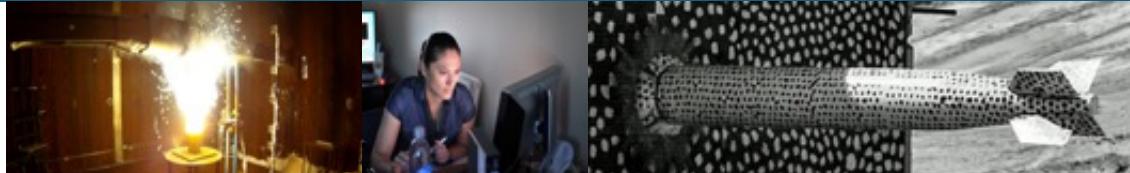




Full Kinetic and Drift Kinetic Descriptions of Electrons Within MITLs Near a Load



M.H. Hess and E.G. Evstatiev

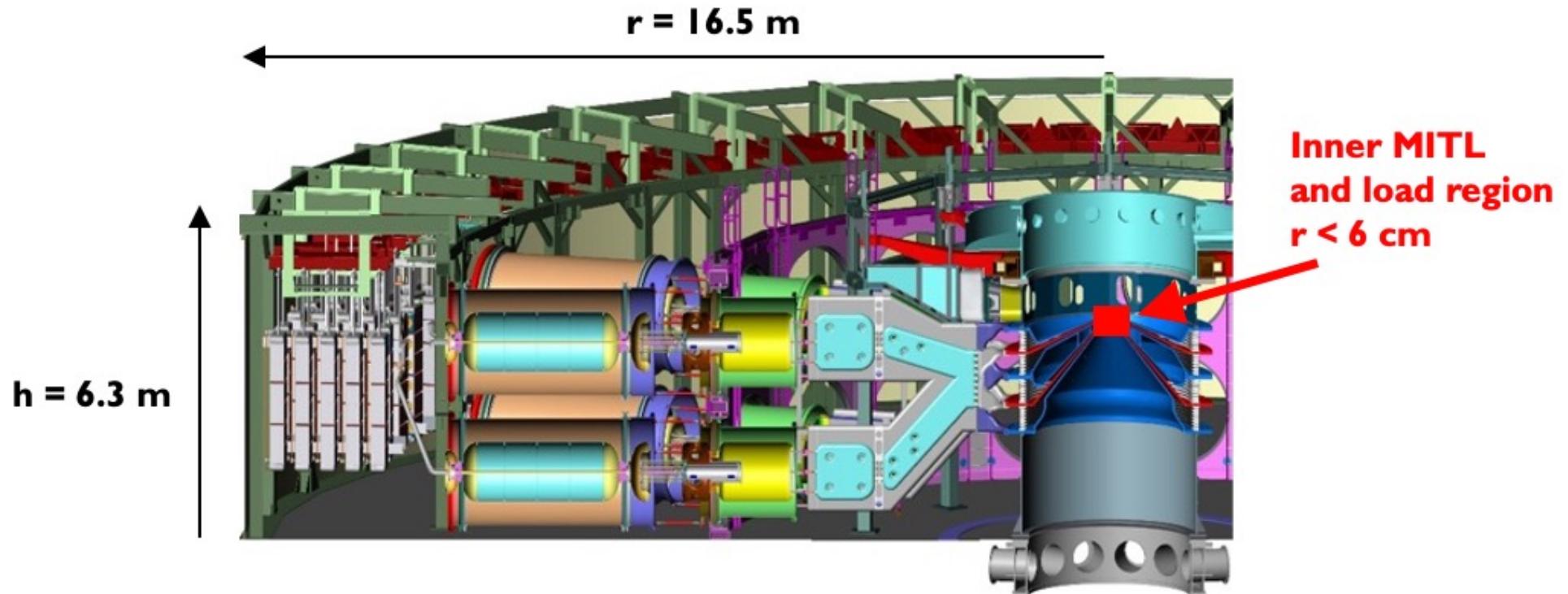
Sandia National Laboratories



Sandia National Laboratories is a multimission laboratory managed and operated by National Technology & Engineering Solutions of Sandia, LLC, a wholly owned subsidiary of Honeywell International Inc., for the U.S. Department of Energy's National Nuclear Security Administration under contract DE-NA0003525. Partial support is provided by the Sandia National Laboratories Grand Challenge-LDRD #209240 and the Exploratory Express-LDRD #223791.

Why are fields and electron dynamics near a MITL load so important?

- Z machine is the largest pulsed power machine in the world capable of delivering < 30 MA of current.
- The inner MITL conducts power to the load which is located at the center of the machine.
- The following analysis can be used to directly understand fields/electron dynamics near the load. The fields/electron dynamics from this analysis are checked using the fully electromagnetic code EMPIRE developed at Sandia National Laboratories.



Assumptions*



1. The MITL is cylindrically symmetric.
2. The magnetic field is specified by Ampere's Law in the limit $c \rightarrow \infty$ (no displacement current) for a time-dependent MITL current $I(t)$.
$$\mathbf{B} = -\frac{\mu_0 I(t) \mathbf{e}_\phi}{2\pi r}$$
3. The MITL surfaces are perfect conductors.
4. The load, which defines the “end” of the MITL, is also represented as a perfect conducting surface.

*The following work can be found in **M. H. Hess and E. G. Evstatiev**, “**Electron Dynamics Within a MITL Containing a Load**”, **IEEE Transactions On Plasma Science (accepted for publication 2021)**. (SAND 2021-11933 J)

Electric Field Equations



- The electric fields, which are in the radial and axial directions, can be solved using Maxwell's Equations.

Gauss's Law:

$$\nabla \cdot \mathbf{E} = 0$$

Faraday's Law:

$$\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$$

**Boundary
Condition at MITL
Surface and Load:**

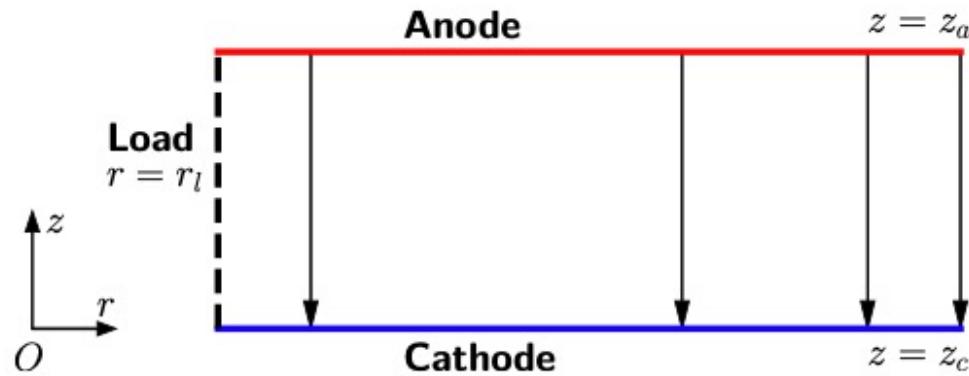
$$\mathbf{n} \times \mathbf{E}|_S = 0$$

Types of MITLs Examined

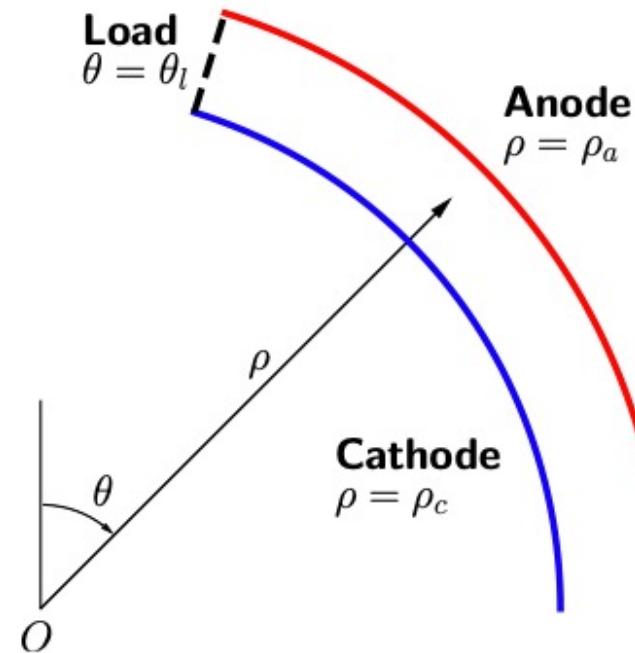


- We examine two different types of MITLs: radial and spherically curved.

Radial MITL



Spherically Curved MITL





Lagrangian function of coordinates and velocities:

$$L(Q_1 \dots Q_s, \dot{Q}_1 \dots \dot{Q}_s)$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{Q}_i} = \frac{\partial L}{\partial Q_i}$$

Radial MITL

Electric Field:

$$\mathbf{E} = -\frac{\mu_0 I}{2\pi} \ln\left(\frac{r}{r_l}\right) \mathbf{e}_z$$

Vector Potential:

$$\mathbf{A} = \frac{\mu_0 I}{2\pi} \ln\left(\frac{r}{R}\right) \mathbf{e}_z$$

Lagrangian:

$$L = -mc^2 \sqrt{1 - \frac{1}{c^2} \left(\dot{r}^2 + r^2 \dot{\phi}^2 + \dot{z}^2 \right)} + q\mathbf{v} \cdot \mathbf{A}$$

Spherical MITL

Electric Field:

$$\mathbf{E} = \frac{\mu_0 I \rho_a \rho_c}{2\pi \rho^2} \ln\left(\frac{\csc\theta + \cot\theta}{\csc\theta_l + \cot\theta_l}\right) \mathbf{e}_\rho + \frac{\mu_0 I (\rho - \rho_a)(\rho - \rho_c)}{2\pi \sin\theta \rho^2} \mathbf{e}_\theta$$

Vector Potential:

$$\mathbf{A} = -\frac{\mu_0 I \rho_a \rho_c}{2\pi \rho^2} \ln\left(\frac{\csc\theta + \cot\theta}{\csc\theta_l + \cot\theta_l}\right) \mathbf{e}_\rho - \frac{\mu_0 I (\rho - \rho_a)(\rho - \rho_c)}{2\pi \sin\theta \rho^2} \mathbf{e}_\theta$$

Lagrangian:

$$L = -mc^2 \sqrt{1 - \frac{1}{c^2} \left(\dot{\rho}^2 + \rho^2 \dot{\theta}^2 + \rho^2 \sin^2 \theta \dot{\phi}^2 \right)} + q\mathbf{v} \cdot \mathbf{A}$$

Full Kinetic Radial MITL Particle Trajectory Equations



In order to simplify our discussion, we assume

$$v_\phi(t) = 0$$

Momentum Equations:

$$\frac{dp_r}{dt} = \frac{p_\phi^2}{\gamma mr} + \frac{q\mu_0 Iv_z}{2\pi r}$$

$$\frac{d(rp_\phi)}{dt} = 0$$

$$\frac{dp_z}{dt} = qE_z - \frac{q\mu_0 Iv_r}{2\pi r}$$

$$\frac{dp_r}{dt} = \frac{q\mu_0 Iv_z}{2\pi r}$$

$$\frac{dp_\phi}{dt} = 0$$

$$\frac{dp_z}{dt} = qE_z - \frac{q\mu_0 Iv_r}{2\pi r}$$

Position Equations:

$$\frac{dr}{dt} = v_r \quad \frac{d\phi}{dt} = \frac{v_\phi}{r} \quad \frac{dz}{dt} = v_z$$

Full Kinetic Spherically Curved MITL Particle Trajectory Equations



In order to simplify our discussion, we assume

$$v_\phi(t) = 0$$

$$\frac{dp_\rho}{dt} = \frac{p_\theta^2 + p_\phi^2}{\gamma m \rho} + qE_\rho - \frac{q\mu_0 I v_\theta}{2\pi \rho \sin\theta}$$

Momentum Equations:

$$\frac{dp_\theta}{dt} = \frac{-p_\rho p_\theta + p_\phi^2 \cot(\theta)}{\gamma m \rho} + qE_\theta + \frac{q\mu_0 I v_\rho}{2\pi \rho \sin\theta}$$

$$\frac{d(\rho \sin\theta p_\phi)}{dt} = 0$$

$$\frac{dp_\rho}{dt} = \frac{p_\theta^2}{\gamma m \rho} + qE_\rho - \frac{q\mu_0 I v_\theta}{2\pi \rho \sin\theta}$$

$$\frac{dp_\theta}{dt} = \frac{-p_\rho p_\theta}{\gamma m \rho} + qE_\theta + \frac{q\mu_0 I v_\rho}{2\pi \rho \sin\theta}$$

$$\frac{dp_\phi}{dt} = 0$$

Position Equations:

$$\frac{d\rho}{dt} = v_\rho \quad \frac{d\theta}{dt} = \frac{v_\theta}{\rho} \quad \frac{d\phi}{dt} = \frac{v_\phi}{\rho \sin\theta}$$

9 Drift Kinetic Approximation

- The guiding center drift motion for a particle in an inner MITL can be described by a combination of $E \times B$ and $\text{grad } B$ drifts. Since we assume the particle's azimuthal velocity is zero at emission, curvature B drift is also zero.

**Guiding Center
Equation*:**

$$\mathbf{v}_{\text{gc}} = \frac{\mathbf{E} \times \mathbf{B}}{B^2} + \frac{\mu}{q\gamma} \frac{\mathbf{B} \times \nabla B}{B^2}$$

**Relativistic Adiabatic
Invariant
(Magnetic Moment)**:**

$$\mu = \frac{p_{\perp}^2}{2mB}$$

*R. J. Goldston and P. H. Rutherford, Introduction to Plasma Physics (1995) p. 51.

**A. J. Brizard and A. A. Chan, Phys. Plasmas 8 4762 (2001).

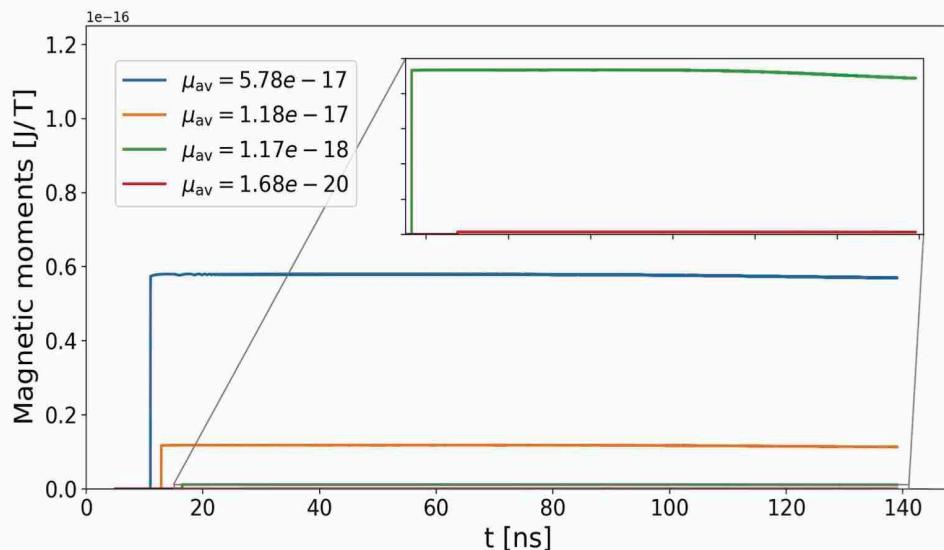
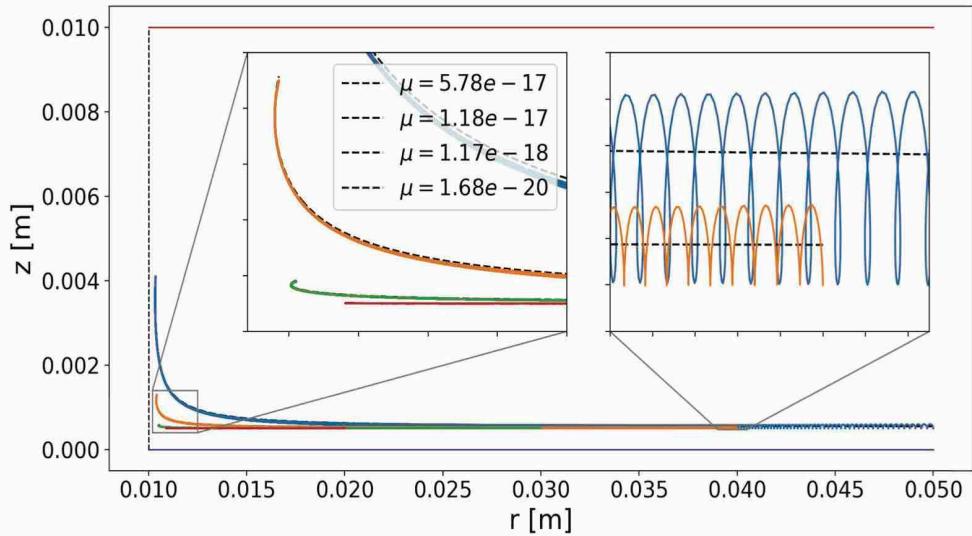
Full Kinetic vs. Drift Kinetic (Radial MITL)



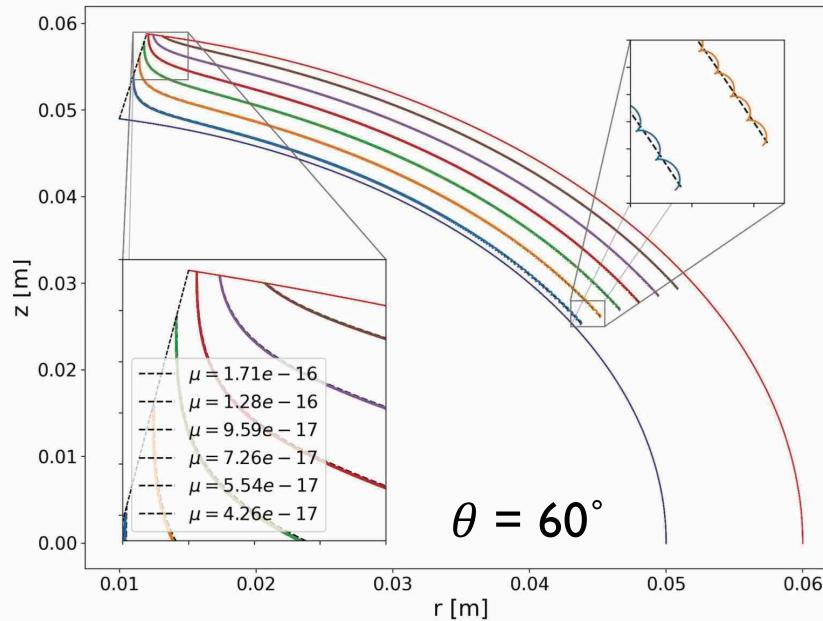
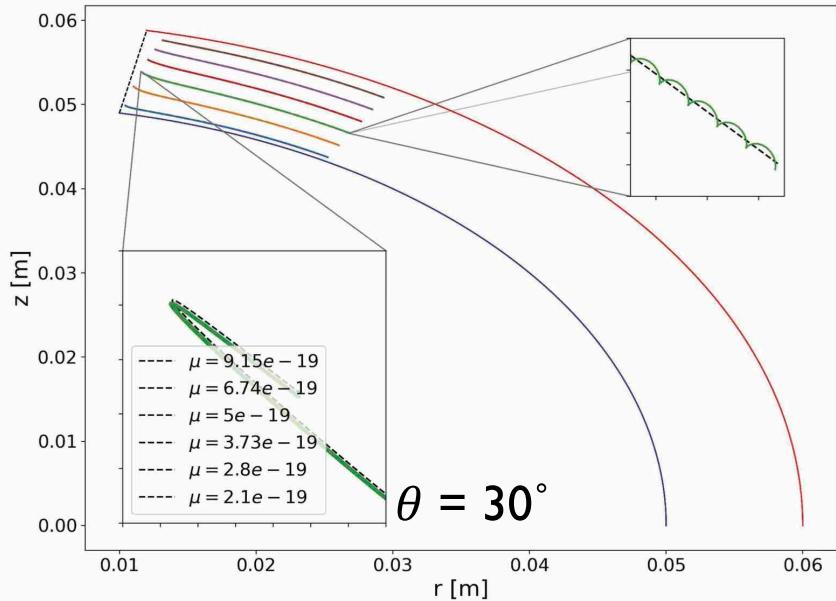
- We use a 20 MA peak current with 120 ns pulse length current drive.

$$I(t) = I_{\text{peak}} \sin^2 \left(\frac{\pi t}{2\tau_{\text{peak}}} \right)$$

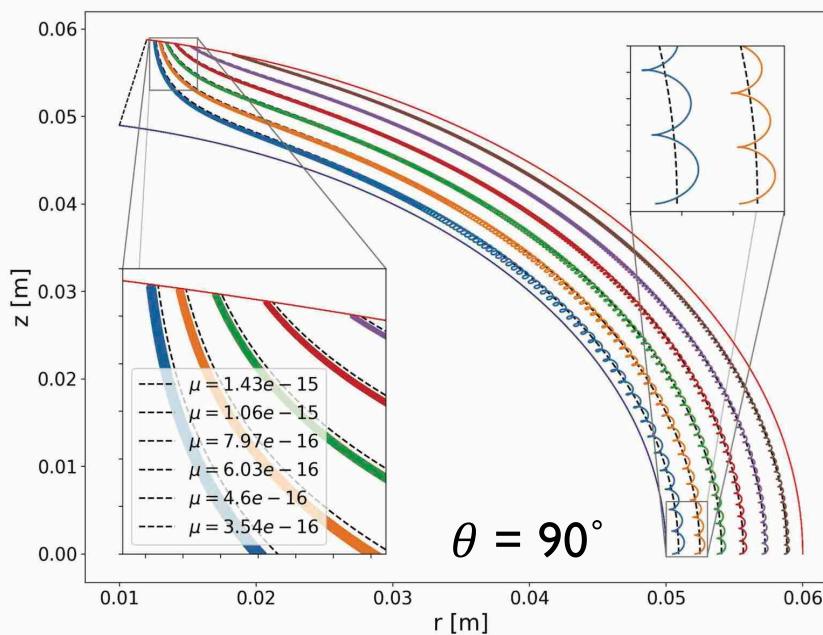
- We compare a full kinetic 4th order R-K scheme using $dt=10^{-15}$ s and the drift kinetic equations solved with a 2nd order R-K scheme with $dt=10^{-12}$ s.
- The initial drift kinetic axial position is set to half the initial cycloidal orbit size of the full kinetic trajectory.
- Electron emission is at 24 MV/m.



Full Kinetic vs. Drift Kinetic (Spherically Curved MITL)



- For the spherical MITL, electrons are emitted at different initial MITL angles.
- For smaller initial angles, the initial electric field is smaller → smaller magnetic moment → smaller grad B drift.
- For larger initial angles, the initial electric field is larger → larger magnetic moment → larger grad B drift.



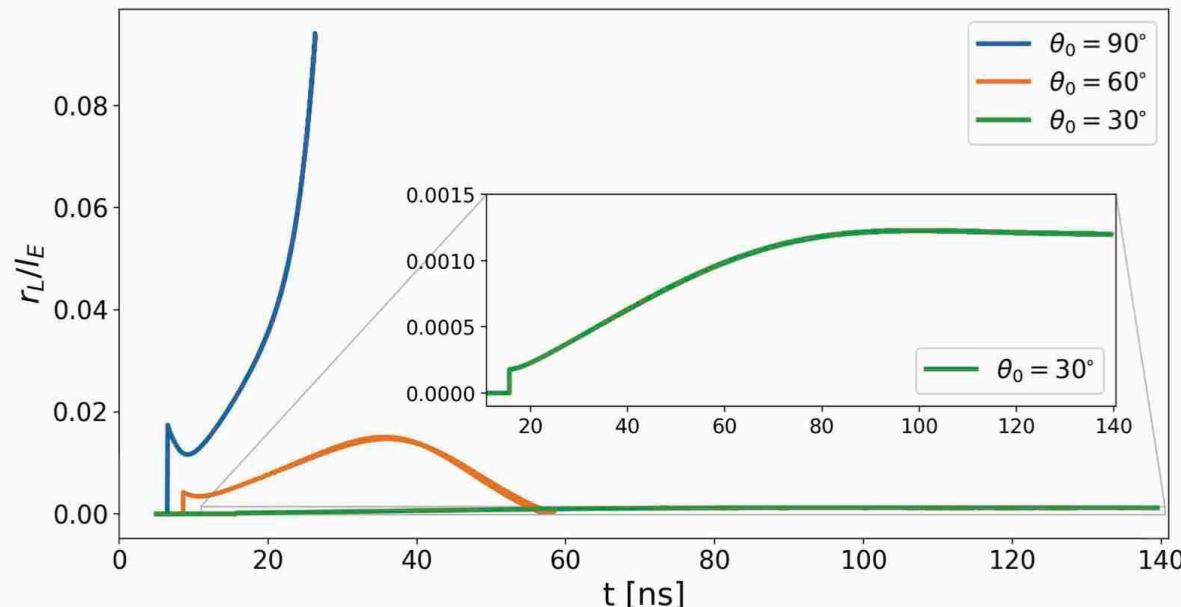
How good is the comparison of Full Kinetics vs. Drift Kinetics?

- In general, the smaller the ratio $r_L/l_E = \text{Larmor radius/electric field gradient length}$ where

$$l_E = \frac{E}{|\nabla E|}$$

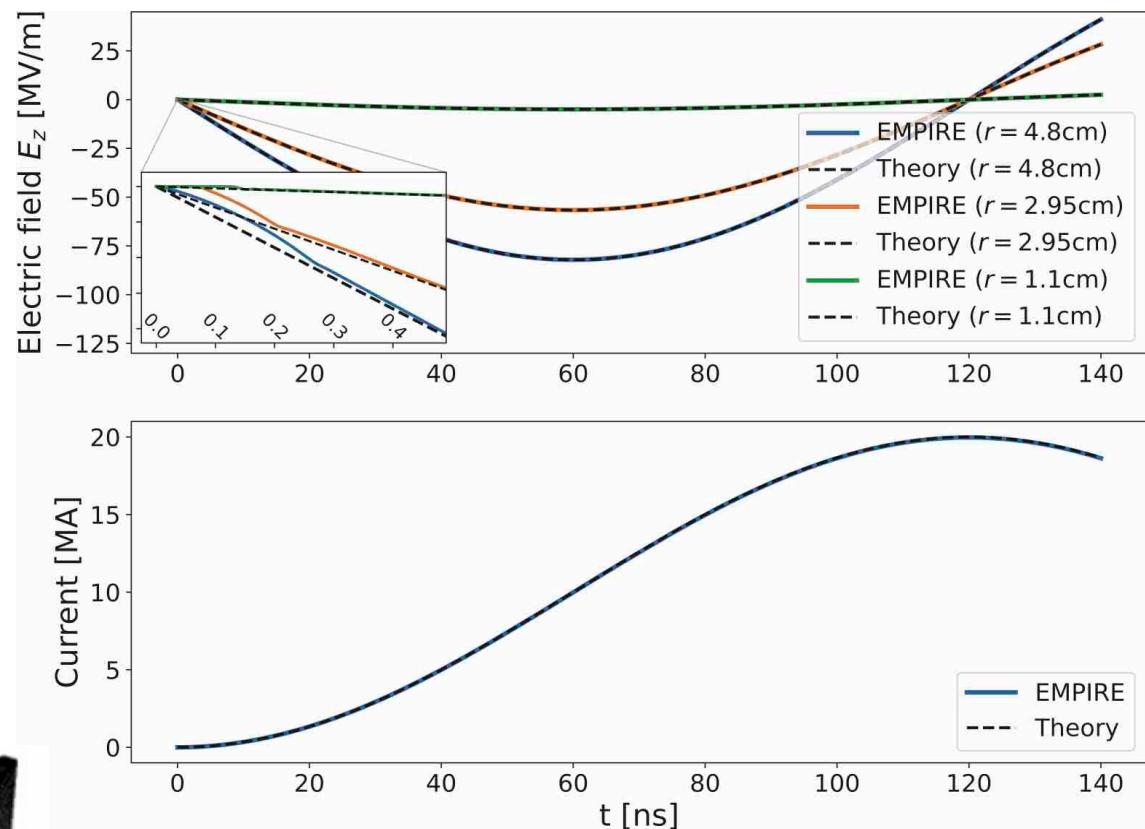
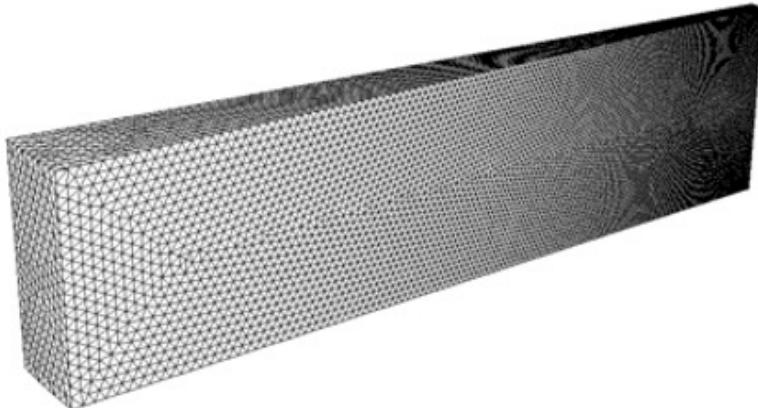
the better the drift kinetic model agrees with the full kinetic model.

- Since smaller initial emission angles \rightarrow smaller Larmor radii, then the drift kinetic model at smaller initial angles agrees better with the full kinetic model.



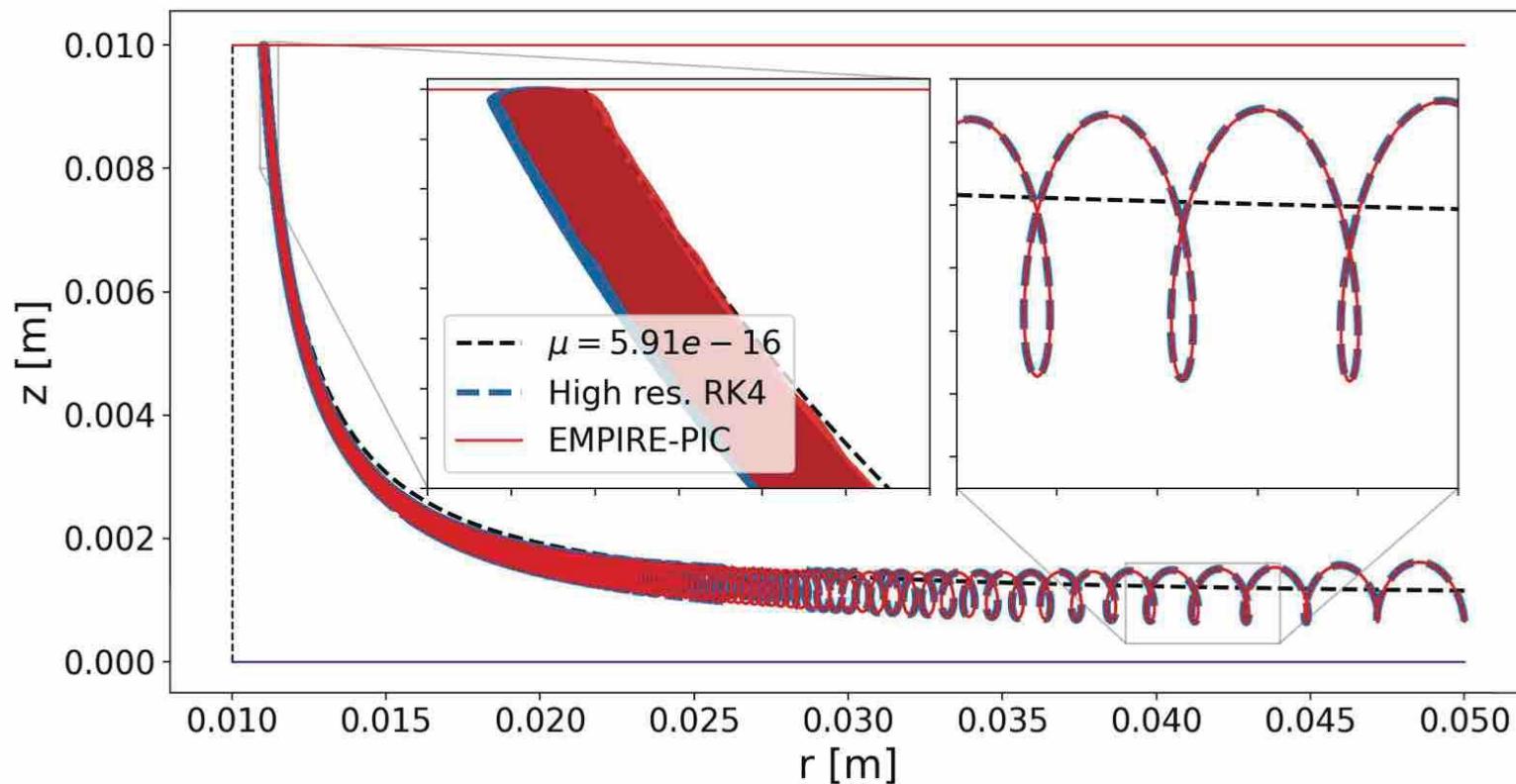
Theory vs. EMPIRE (Radial MITL Fields)

- We use the radial MITL example with a 20 MA peak current to test the $c \rightarrow \infty$ limit model against the fully EM code EMPIRE developed at Sandia.
- We get excellent agreement with the spatial dependence of the voltage and electric field.



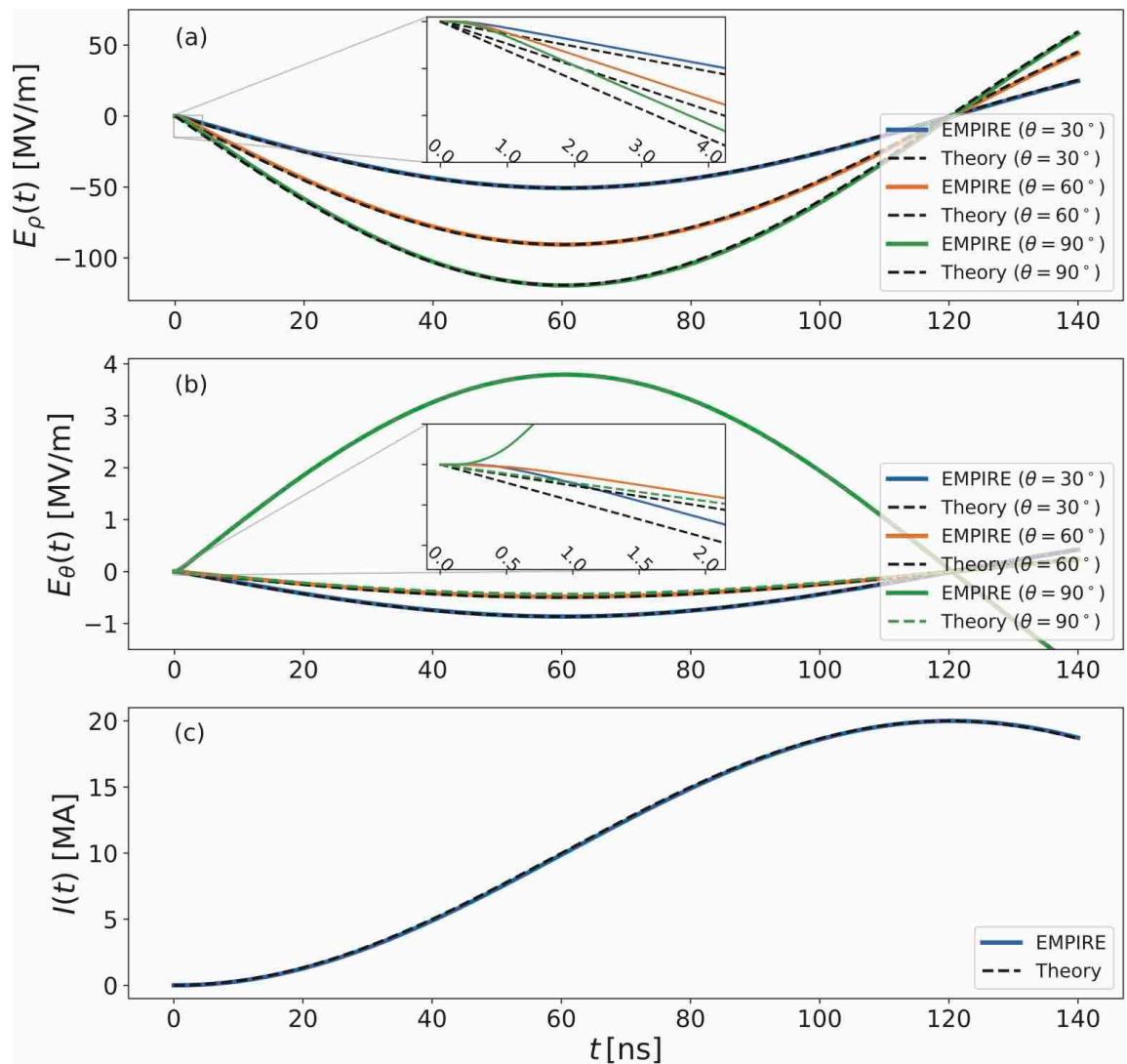
Full/Drift Kinetic vs. EMPIRE-PIC (Radial MITL Trajectories)

- In order to better resolve cyclotron orbits near the load, we lower the peak current to 2 MA. We also lower the electric field threshold to 2.4 MV/m.
- We get excellent agreement with full kinetic simulation of particle trajectories.



Theory vs. EMPIRE (Spherically Curved MITL)

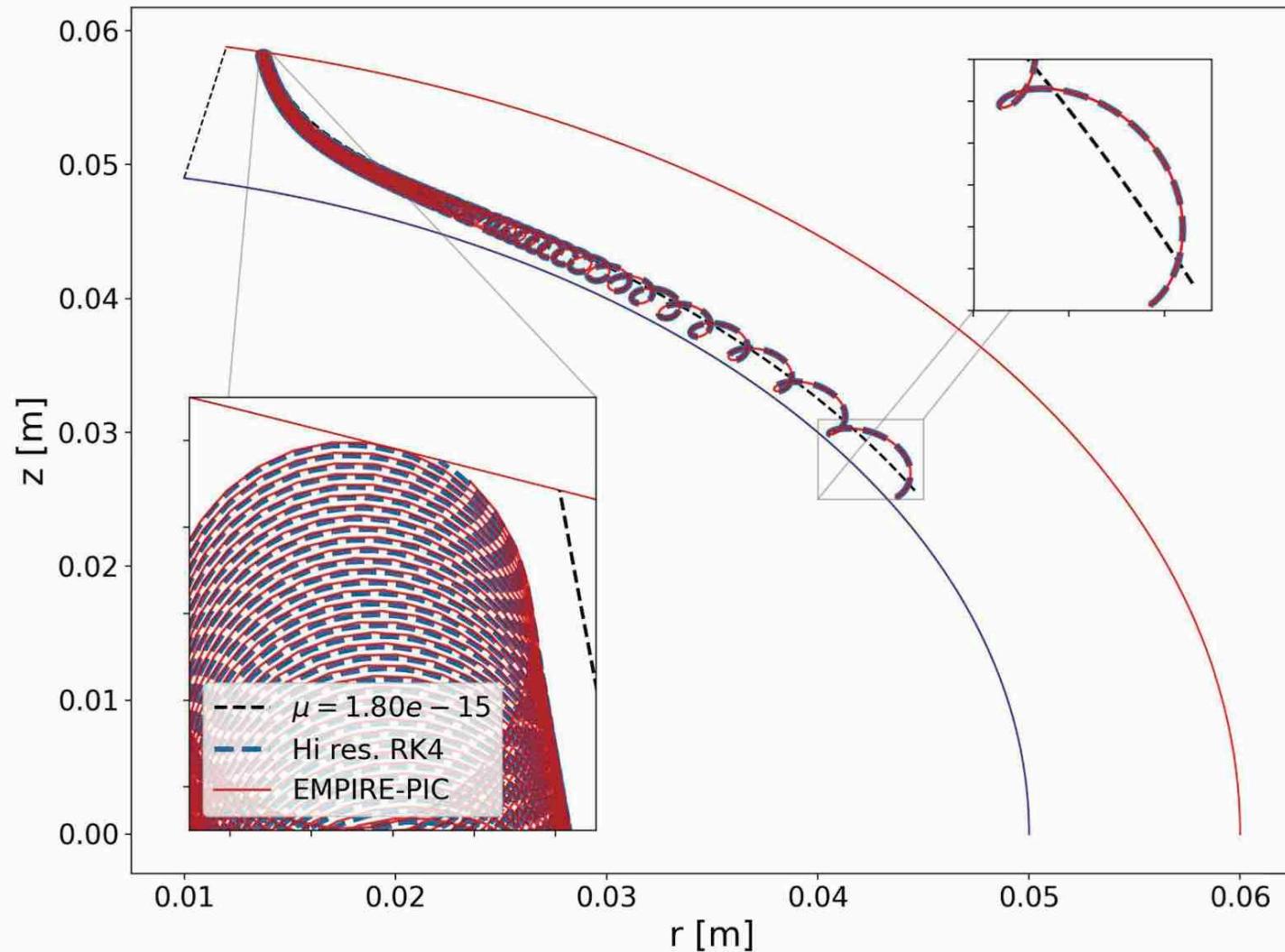
- We include an axial extension into the EMPIRE simulation to provide the correct field BCs into the spherical MITL section.
- E_ρ has excellent agreement between theory and EMPIRE.
- There is disagreement at larger angles for E_θ due to either the difference in the mode structure supported by the fully EM model vs. the $c \rightarrow \infty$ model or a boundary constraint due to the MITL extension.



Full/Drift Kinetic vs. EMPIRE-PIC (Spherically Curved MITL)



- The agreement between the theoretical model and the fully electromagnetic model trajectories is excellent. (E-field threshold is 2.4 MV/m).



Summary



- We have analyzed the fields and electron trajectories for radial and spherically curved MITLs.
- A drift kinetic model that incorporates $\mathbf{E} \times \mathbf{B}$ and grad \mathbf{B} drifts provides an overall excellent approximation to the full kinetic electron motion.
 - The drift kinetic model shows differences with the full kinetic model when the Larmor radius grows relative to the electric field gradient scale length.
- The fields/full kinetic/drift kinetic dynamics for the two MITL problems have been tested against the electromagnetic code EMPIRE.
 - We get excellent agreement between theory/EMPIRE for fields/trajectories in the radial MITL case.
 - We get excellent agreement for E_ϕ in the spherically curved MITL, and some disagreement with E_θ at large angles between the full EM model and the $c \rightarrow \infty$ model.
 - Small differences in trajectories between the full/drift kinetic and EMPIRE are also observed. Overall, both the $c \rightarrow \infty$ and the drift kinetic approximation provide excellent representations of electron trajectories when compared with EMPIRE results.