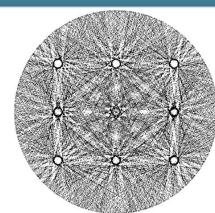


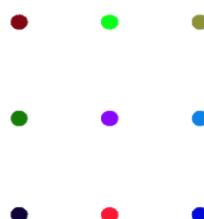
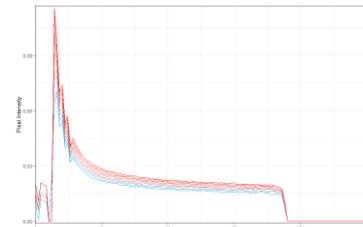
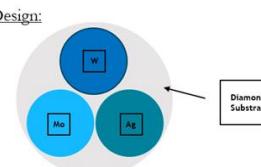


Sandia
National
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A Process to Colorize and Assess Visualizations of Noisy X-Ray Computed Tomography Hyperspectral Data of Materials with Similar Spectral Signatures



Patterned-Anode Design:



Joshua Clifford, Emily Kemp, Ben Limpanukorn,
Edward S. Jimenez

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Joint NSS-MIC Session 2, October 19



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Background



Past Research

- Denoising hyperspectral data
- Material classification with hyperspectral data
- Coloring hyperspectral data using dimension reduction techniques

Objectives

- Represent hyperspectral computed tomography (HCT) data in a single colorized image
- Maximize contrast between distinct materials with similar compositions (different mixture concentrations of similar materials)
- Maximize smoothness within homogeneous materials

Potential Impact

- Rapid human interpretability of complex HCT signatures
- More robust material identification methods
- Industrial, medical, and security-based applications

Methods



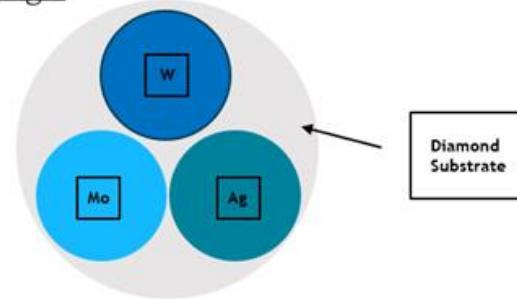
Data



HCT System

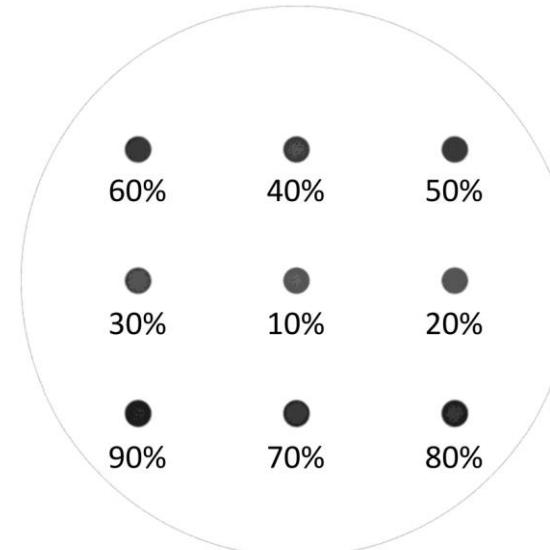
- PHITS simulations
- Patterned anode (tungsten, molybdenum, and silver)
- 225kVp electron beam impinging on anode
- Detector channelizing photons into 128 energy channels across 300 keV

Patterned-Anode Design:



Objects

- Cylindrical
- Mixtures of H_2O and H_2O_2



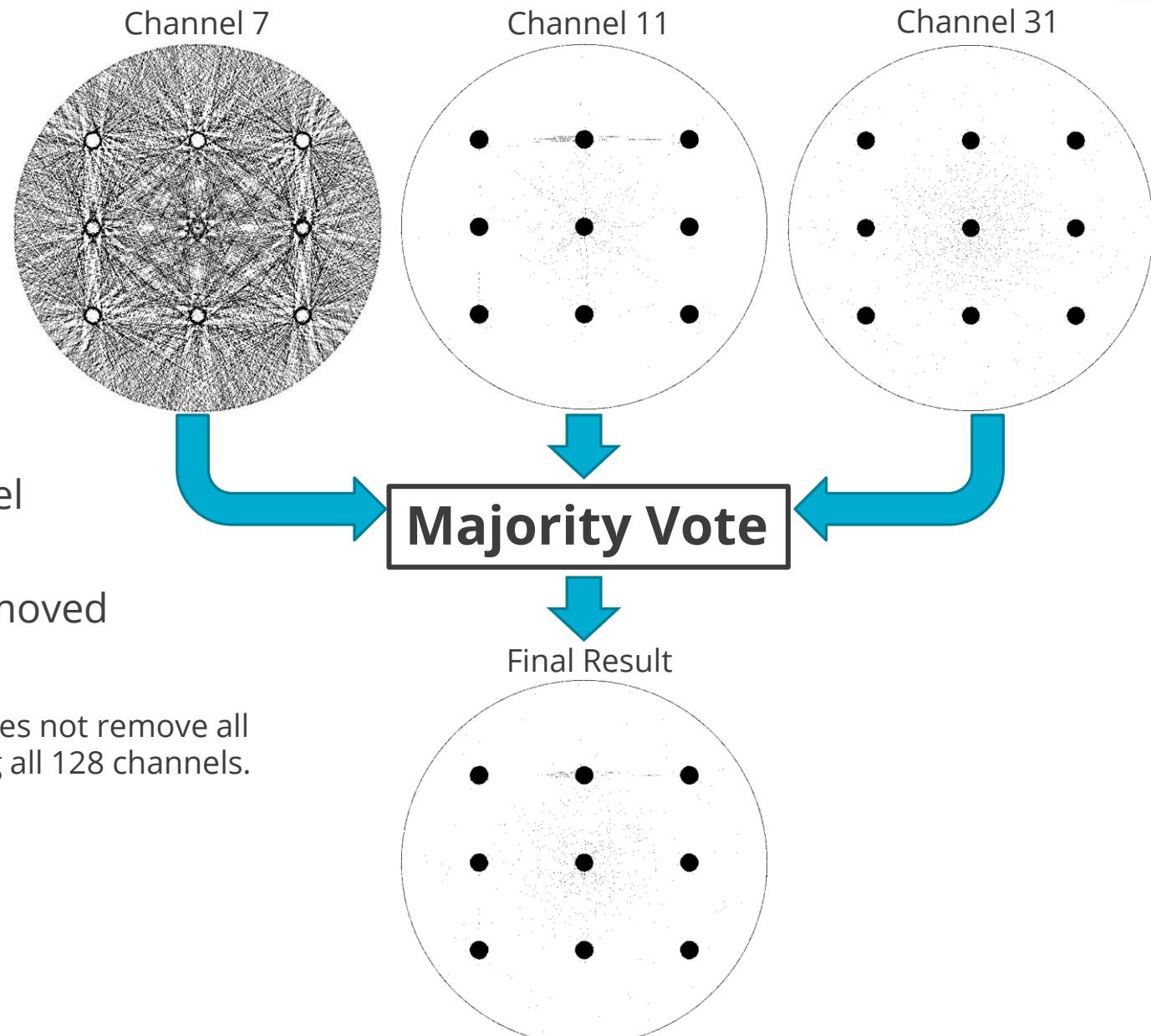
Reconstructed image of cylinders labeled with their concentrations of H_2O_2 to H_2O

Preprocessing Methods



Novel “majority vote” thresholding

- Multilevel thresholding on each channel
- Each channel result counts as a vote
- Each pixel with < 50% of the vote is removed



Note: In the small 3 channel example to the right, it does not remove all pixels not in objects of interest, but it works well using all 128 channels.

Preprocessing Methods



Binary erosion (remove additional remaining artifacts)

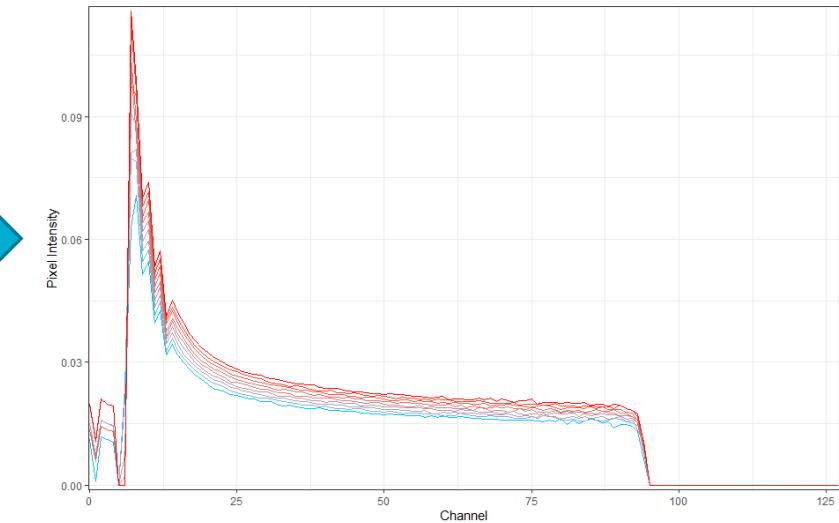
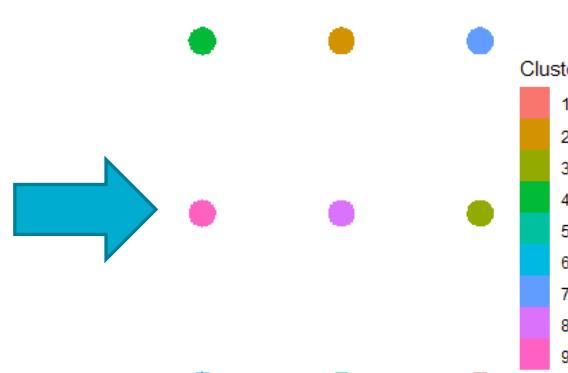
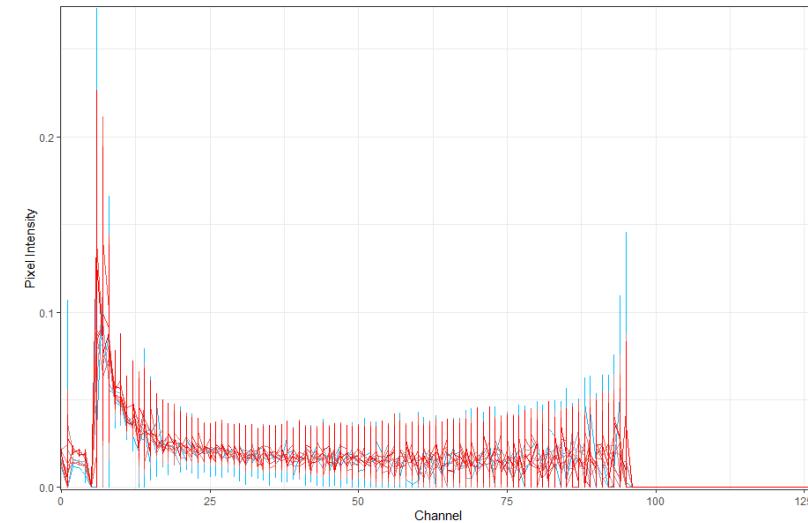
Channel filtering (removing uninformative low-energy channels)

Spatial smoothing (box, Gaussian, or median filter)

Clustering (grouping objects by location/channel intensities)

+ object value assignment (channel mean/median or smoothing splines over channels)

Example of Clustering + Object Value Assignment

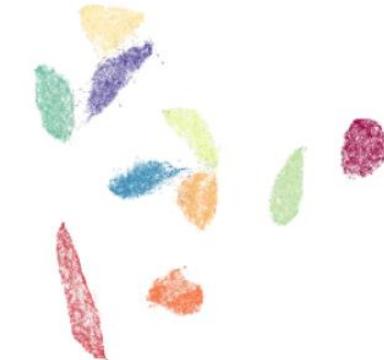


Colorization Methods



Dimension Reduction

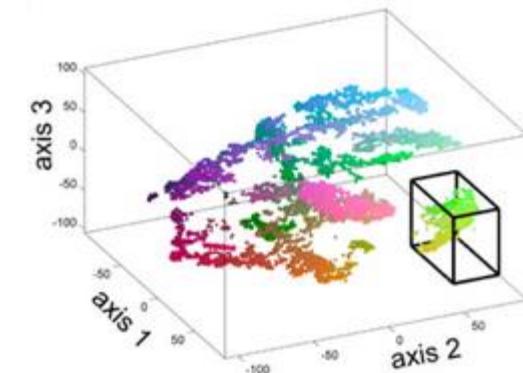
- Uniform Manifold Approximation and Projection (UMAP)
- t-distributed Stochastic Neighbor Embedding (t-SNE)
- Others tested but not presented, did not perform as well
- Represent 128 channels in 3 dimensions for RGB coloring



Example UMAP 2D representation of MNIST digit images from McInnes, Healy, & Melville [12]

Linear Models

- Logistic Regression
 - Predicting concentration from channel intensities
- Quadratic Regression
 - Using model parameters as RGB color dimensions



Example t-SNE to RGB translation from Fonville et al. [6]

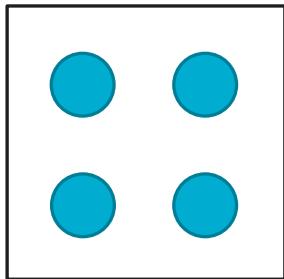
Colorization Assessment Metrics



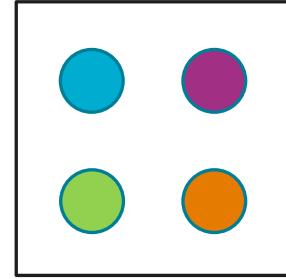
After the final colorization is produced, there are several visual attributes that we wished to measure. The metrics to assess these attributes were based on the RGB additive color model.

Contrast

- Color differences between each pair of objects.
- *Think:* The visual/color contrast within an image.



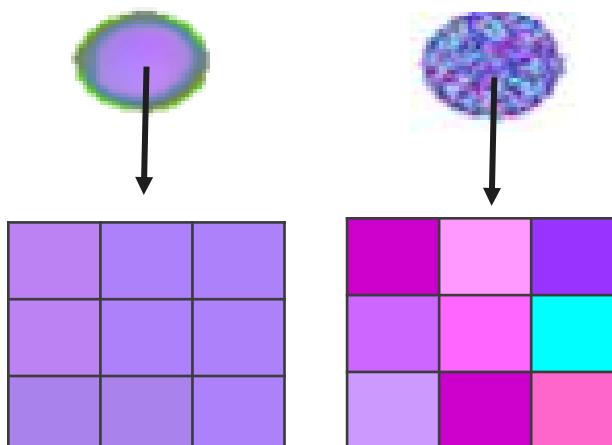
Low Contrast



High Contrast

Local Color Variance

- Color differences between neighboring pixels within objects.
- *Think:* The amount of speckle within an object.

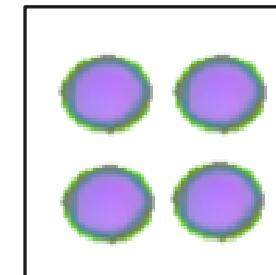


Low LCV

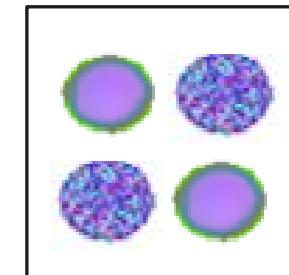
High LCV

Inconsistency

- Coloring differences within objects.
- *Think:* How similar all the objects are in an image with respect to the smoothness or speckle.



Low Inconsistency



High Inconsistency

Results

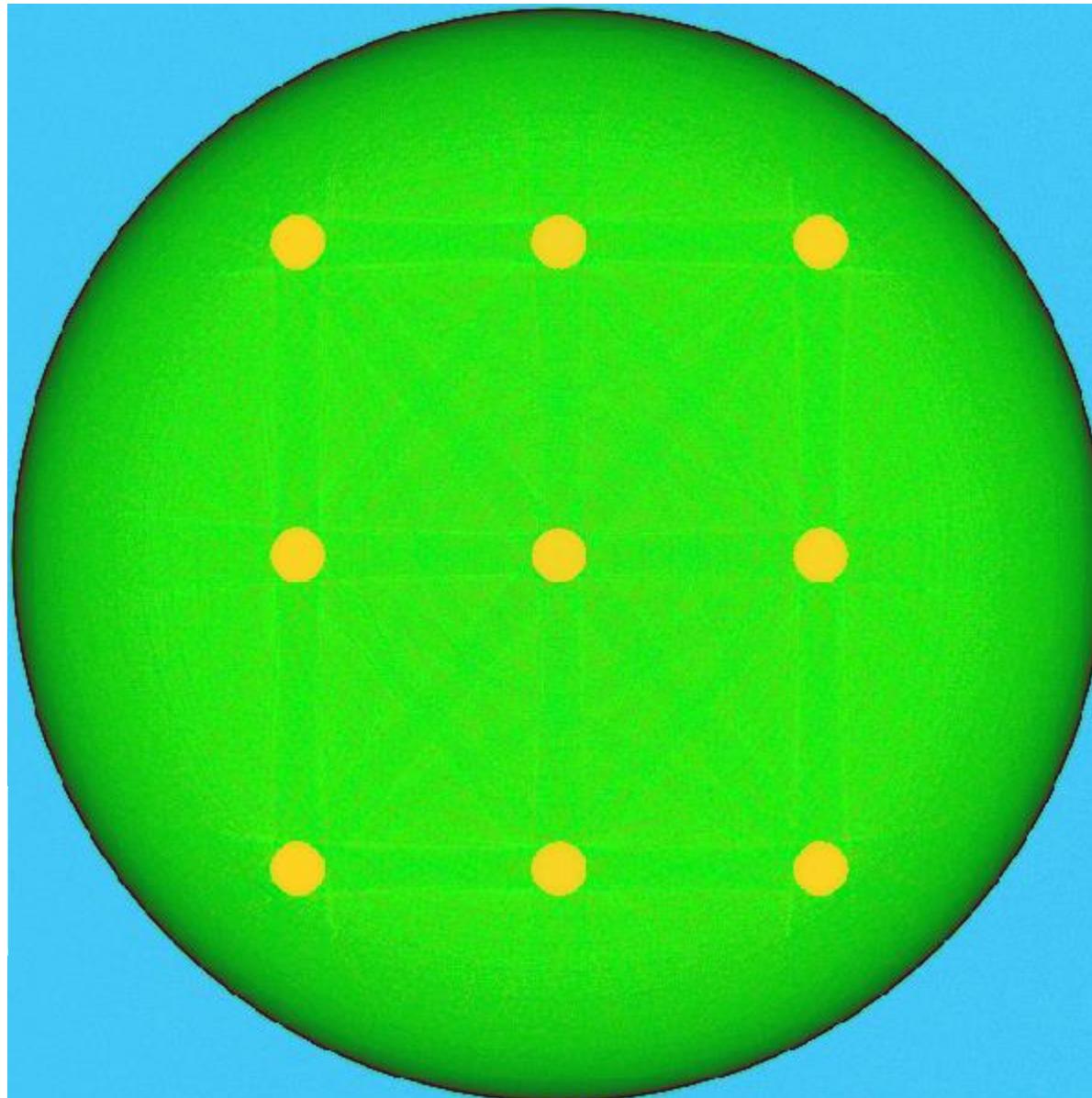
Before Majority-Voting Thresholding + Erosion



Before any preprocessing:

- Many artifacts due to system noise
- No contrast between objects of interest

Metric Results (only for objects)
Contrast = 0.0082
Local Color Var = 0.0003
Inconsistency = 0.0000

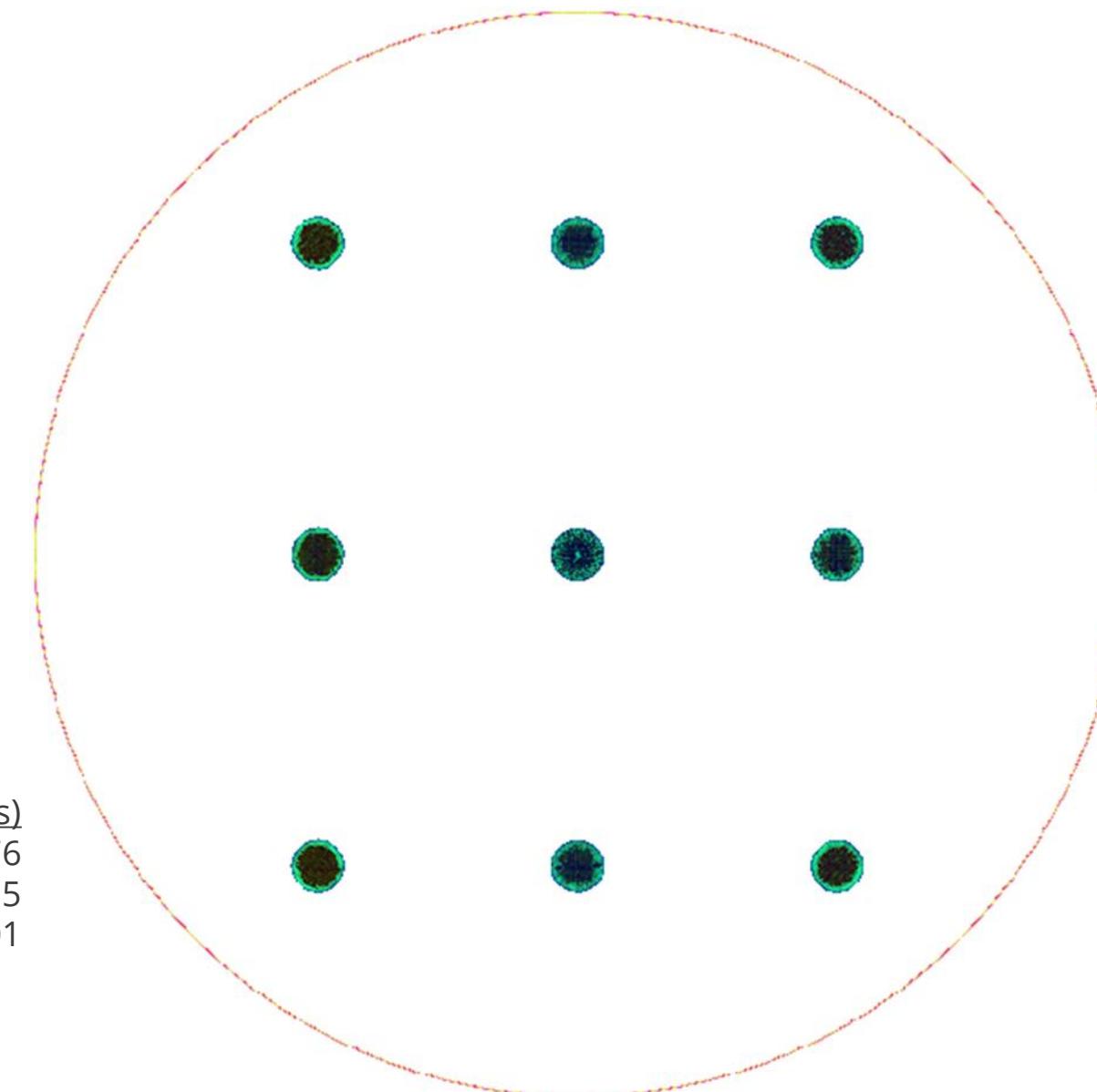


After Majority-Voting Thresholding + Before Erosion



After thresholding:

- Most non-object pixels removed
- Objects have large amounts of local color variance and fairly low contrast
- Remaining non-object pixels are scan boundary artifact due to reconstruction



Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%

Metric Results (only for objects)

Contrast = 0.1376

Local Color Var = 0.0815

Inconsistency = 0.0001

After Majority-Voting Thresholding + Erosion



After thresholding + erosion:

- All non-object pixels removed
- Slightly more contrast between objects and much lower local color variance
- Issue with edge artifact in objects, which was localized to a few low-energy channels



Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%

Metric Results
Contrast = 0.1460
Local Color Var = 0.0222
Inconsistency = 0.0001

Edge Artifact Removal



Coloring after removing channels driving object edge artifacts...

Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%

Very effective for reference data (high photon count)



Metric Results
 Contrast = 0.3961
 Local Color Var = 0.0215
 Inconsistency = 0.0009

Not so effective for sample data



Metric Results
 Contrast = 0.2378
 Local Color Var = 0.0728
 Inconsistency = 0.0007

Median Assignment

vs.

Median Filtering



Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%



Metric Results

Contrast = 0.4908
Local Color Var = 0.0000
Inconsistency = 0.0000



Metric Results

Contrast = 0.2957
Local Color Var = 0.0118
Inconsistency = 0.0025

Median assignment requires object segmentation, but produces high contrast.
Median filtering provides a useful alternative with simple pixel-level processing.

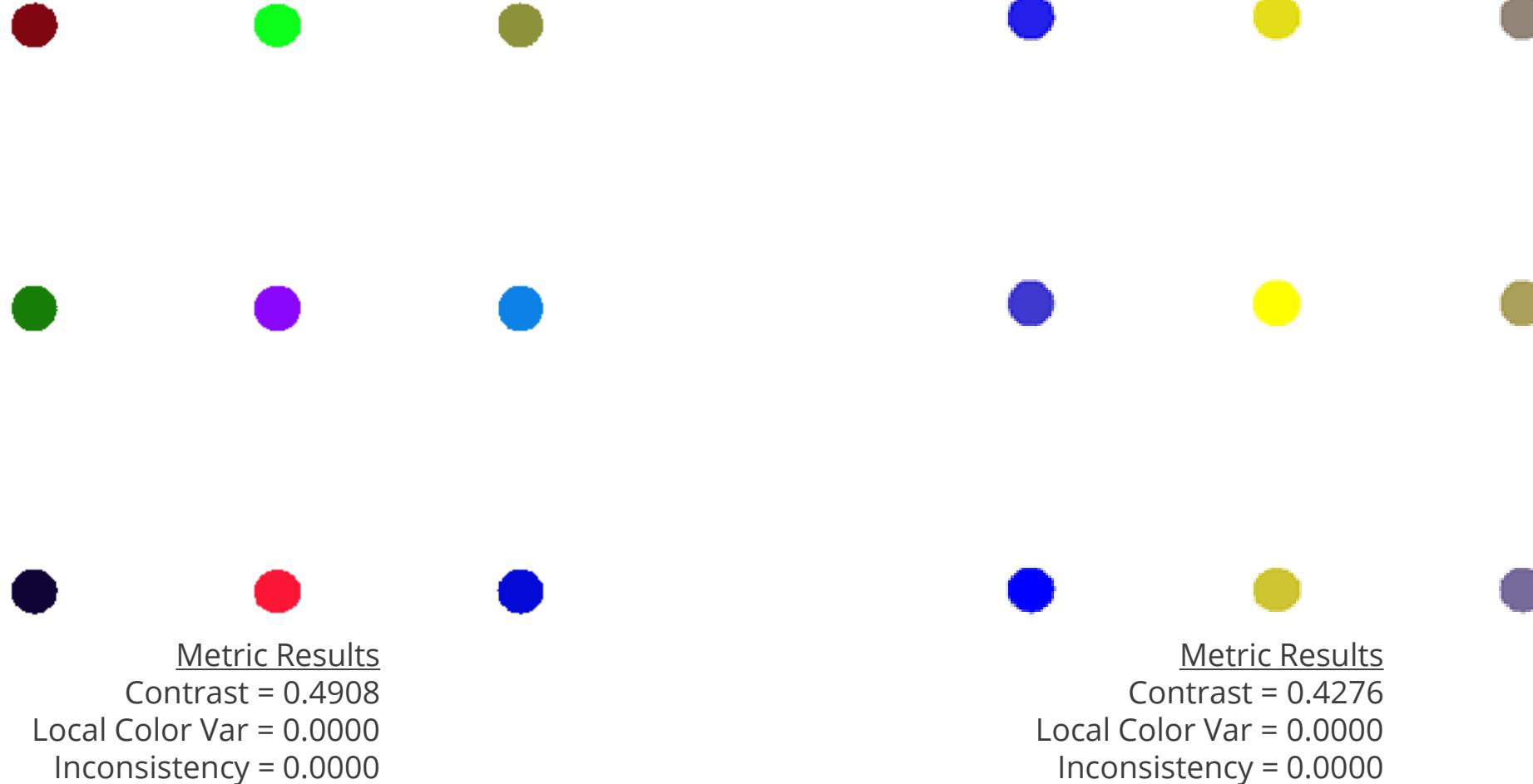
UMAP

vs.

t-SNE



Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%



UMAP provides more separation between objects, resulting in better contrast. However, both methods do not allow easy interpretation of concentrations.

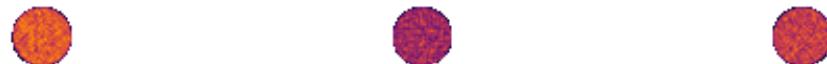
Linear Model Colorization



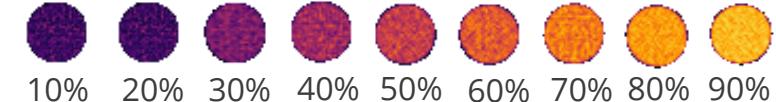
Using linear models retains good contrast, and increases interpretability by coloring concentrations on a meaningful gradient.

Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%

Logistic Regression
(on pixels)



Objects arranged in
ascending order by
concentration



Metric Results

Contrast = 0.2651
Local Color Var = 0.0444
Inconsistency = 0.0004

Linear Model Colorization



Using linear models retains good contrast, and increases interpretability by coloring concentrations on a meaningful gradient.

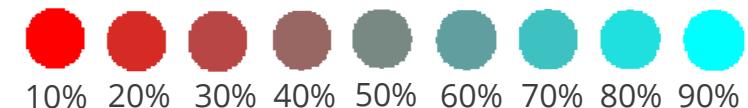
Concentration Key		
60%	40%	50%
30%	10%	20%
90%	70%	80%

Quadratic Regression

(median assignment, normalized parameters)



Objects arranged in ascending order by concentration



Metric Results

Contrast = 0.4083

Local Color Var = 0.0000

Inconsistency = 0.0000

Method Comparison



Preprocessing	None	MLT	• MLT • Erosion	• MLT • Erosion • Channel Removal	• MLT • Erosion • Channel Removal	• MLT • Erosion • Channel Removal • Median Filter	• MLT • Erosion • Channel Removal • Median Assign	• MLT • Erosion • Channel Removal • Median Assign	• MLT • Erosion • Channel Removal • Median Assign	
Colorization	UMAP	UMAP	UMAP	UMAP	Logistic Regression	UMAP	UMAP	t-SNE	Quadratic Regression	
Metric Results	Contrast	0.0082	0.1376	0.1460	0.2378	0.2651	0.2957	0.4908	0.4276	0.4083
	Local Color Var	0.0003	0.0815	0.0222	0.0728	0.0444	0.0118	0.0000	0.0000	0.0000
	Inconsistency	0.0000	0.0001	0.0001	0.0007	0.0004	0.0025	0.0000	0.0000	0.0000

Note: For each method, best performing methods highlighted in green and worst performing methods highlighted in red.

Future Directions



Develop methods

- Automate channel selection for filtering
- Improve polynomial regression fit and parameter normalization
- Metrics comparing between different scans of objects

Test robustness across different

- Materials
- Shapes
- Sizes
- Arrangements

Understand HCT data

- Photon counts (understand/calibrate for drift and detector degradation)
- Real-world system (currently under construction)

Thank you! Questions?



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