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## Diesel Generator Model Development and Validation using Moving Horizon Estimation

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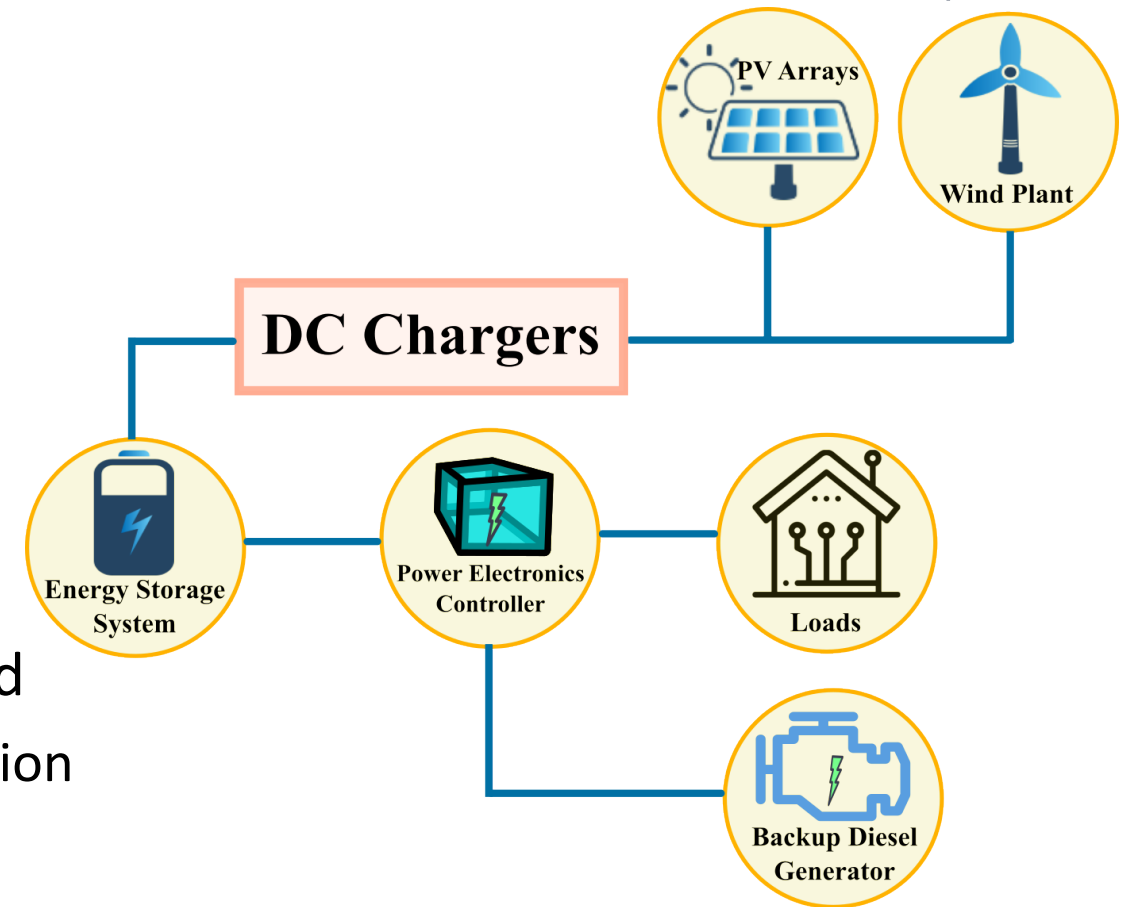
# Diesel-backed Microgrids



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- renewables integrated into diesel genset backed microgrids
  - ▲ reduce overall fuel consumption
- diesel-backed inverter-based generation
  - ▲ faster, stochastic and non-linear dynamics
    - variability microgrid parameters
    - uncertainties in state variables
- optimal control of inverter resources is needed
  - ▲ require accurate modeling and online estimation techniques for genset



**Objective** : to model and validate a frequency dynamics model of the diesel genset using moving horizon estimation technique

# Moving Horizon Estimation



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- finite horizon optimization-based estimation process
- infer state variables and parameters of system from its measurements

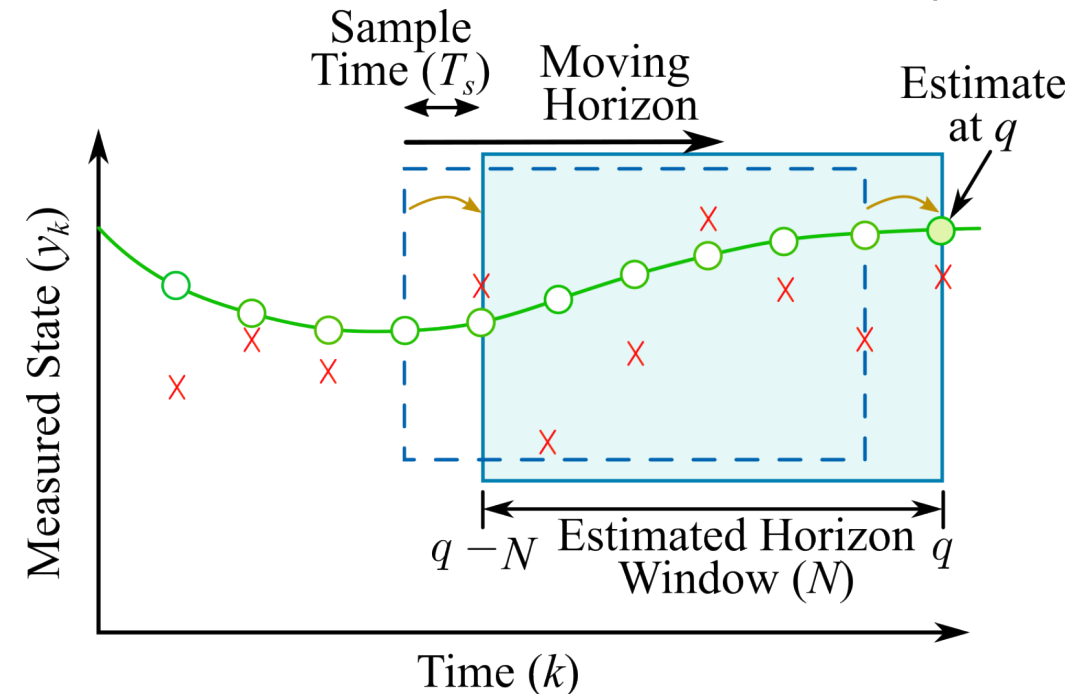
- ▲ provides estimations for non-linear systems the presence of both Gaussian and non-Gaussian noise

where,

$N$  = horizon length

$T_s$  = sampling time of MHE

$y_k$  = measured states at discrete time instant  $k$



**Inputs** : measurements of system

**Outputs** : state and parameters estimates

✗ represent measurements and ○ represent the estimated values

# Frequency Dynamics of Diesel Model



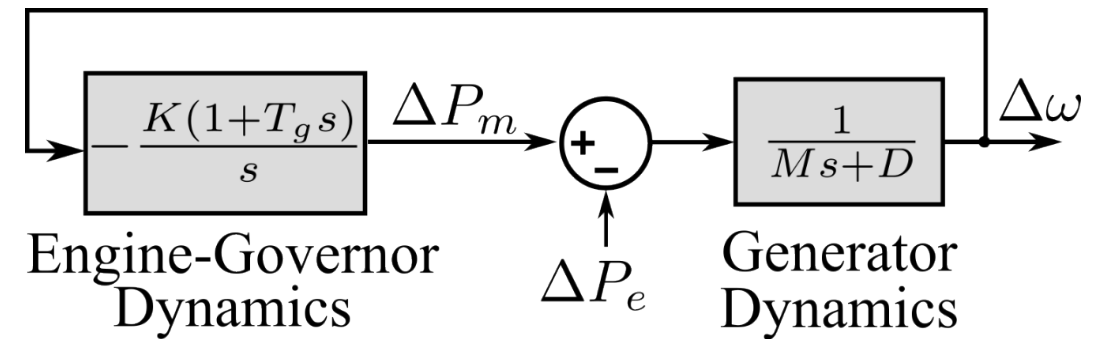
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- system frequency dynamics:

$$\frac{d}{dt} \begin{bmatrix} z \\ \omega \end{bmatrix} = \begin{bmatrix} 0 & -K \\ \frac{1}{M} & -\frac{D}{M} - \frac{KT_g}{M} \end{bmatrix} \begin{bmatrix} z \\ \omega \end{bmatrix} + \begin{bmatrix} 0 \\ -\frac{1}{M} \end{bmatrix} P_e$$

- exciter and flux dynamics are very fast, neglected
- simplified governor represented by single time-constant ( $T_g$ )
- $M$  and  $D$  are parameters of generator dynamics
- model is used for **predictive model in MHE**



$a_{12}, a_{21}, a_{22}$  = parameters  
 $P_e$  = electrical power  
 $\omega$  = frequency  
 $P_m$  = mechanical power

$a_{12} = K, a_{21} = \frac{1}{M}, a_{22} = \frac{D}{M} + \frac{KT_g}{M}$   
 $D$  = damping constant  
 $M$  = inertia constant  
 $z$  = state variable  
 $K$  = governor gain  
 $T_g$  = time constant

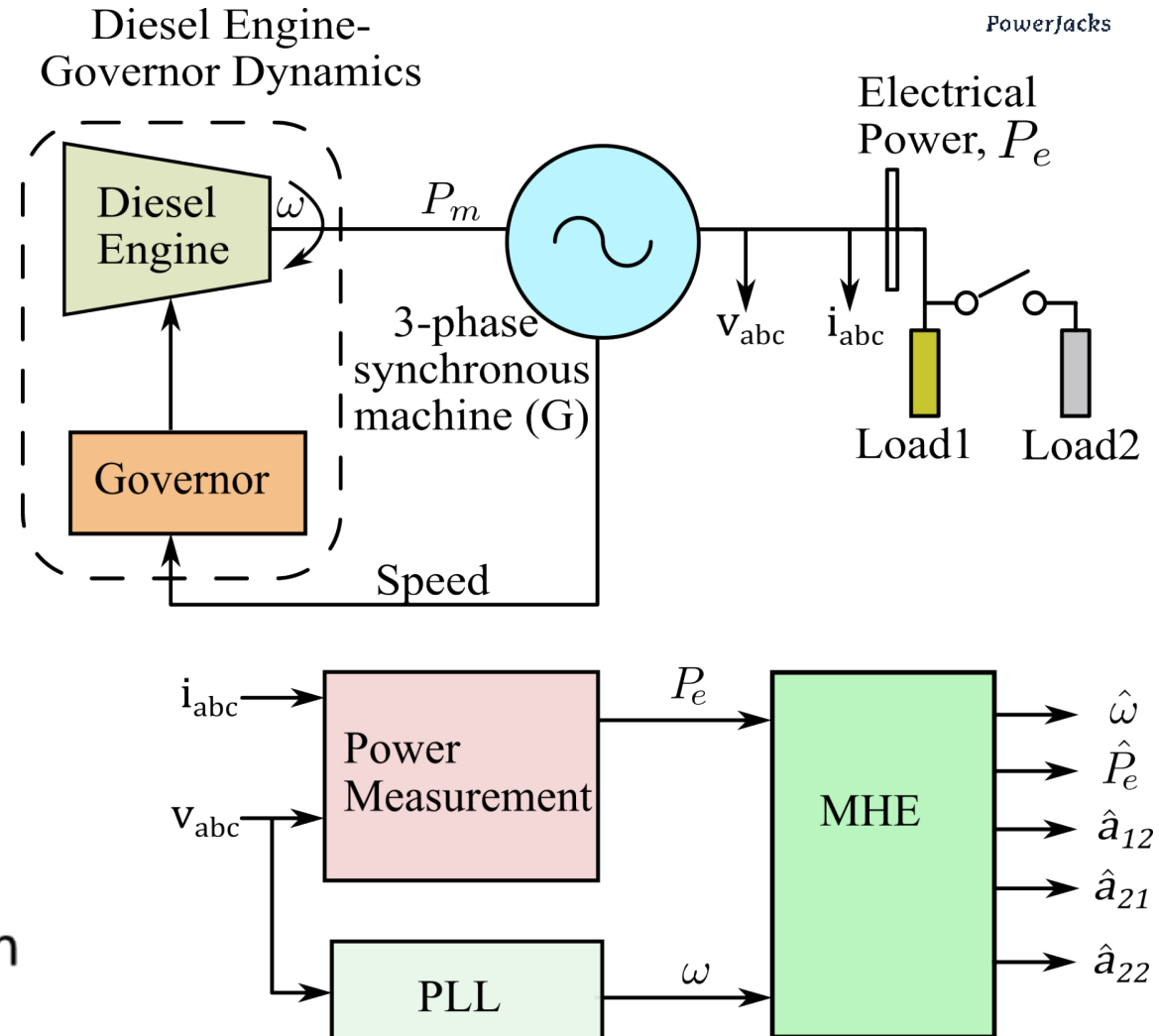
# Simulation Setup of Diesel Genset



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- actual simulations carried in **detailed gensets**
  - ▲ diesel genset : 406 kVA, 460 V
  - ▲ base resistive load of 25% : 100kW
  - ▲ perturbation power of 40% of total gen capacity :165kW
- non-Gaussian noise of covariance  $10^{-7}$  added to frequency
- model and estimate diesel gensets parameters with validating steps
- sample time of 0.003 s and horizon length of 700 chosen for MHE

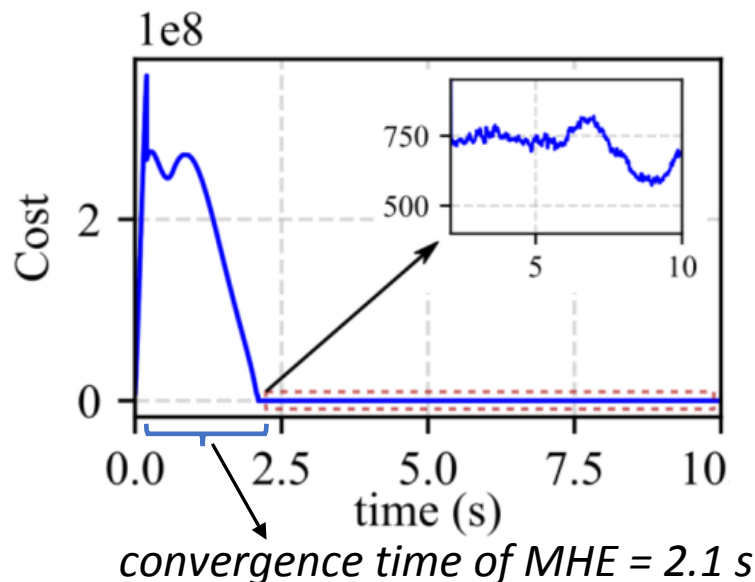
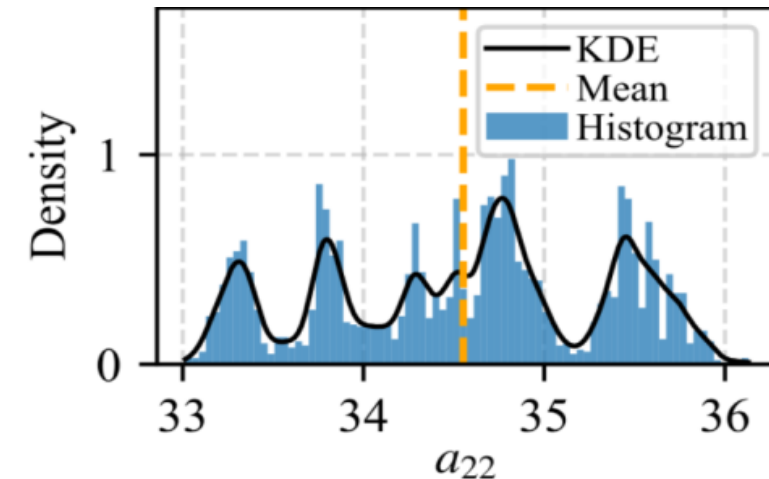
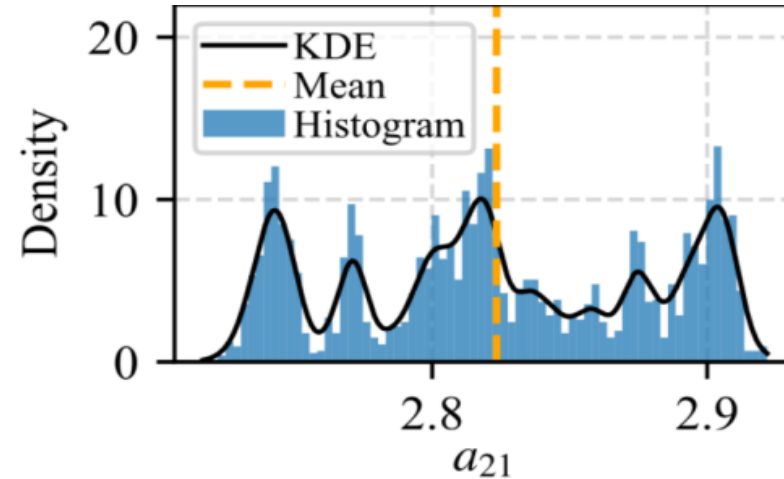
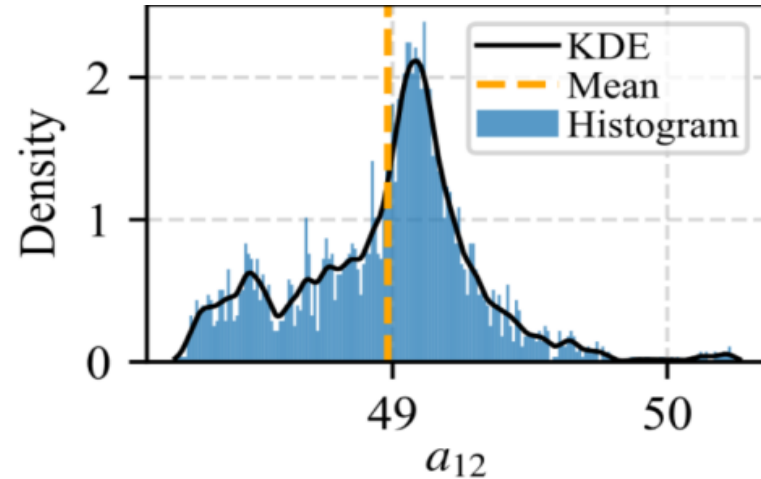


# Parameter Estimation Results and Analysis



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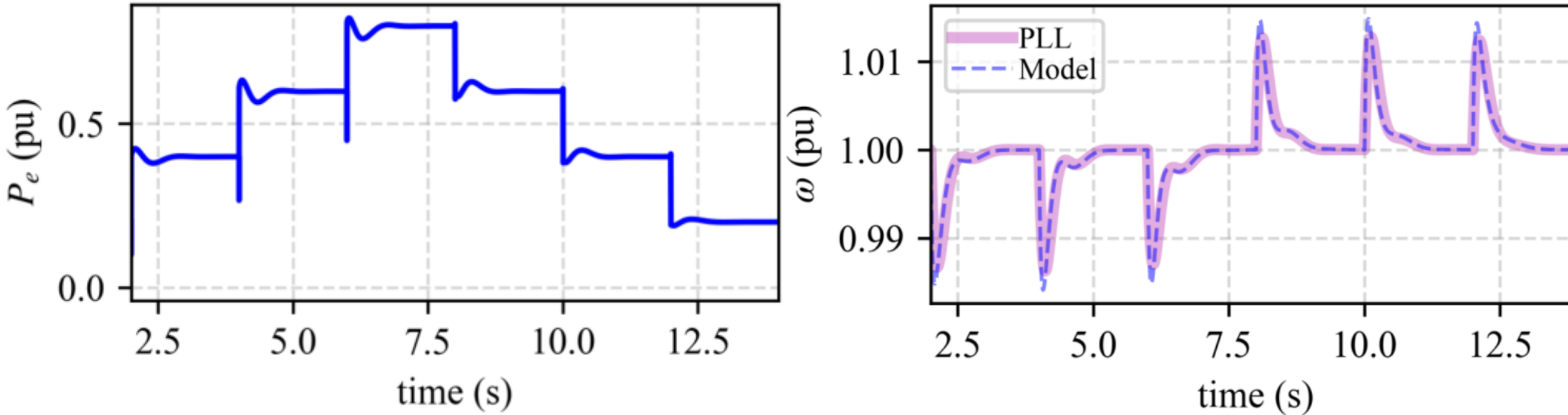
- mean of  $a_{12}$  = 48.67, CoV = 0.678%
- mean of  $a_{21}$  = 2.84, CoV = 1.997%
- mean of  $a_{22}$  = 34.63, CoV = 2.24%
- cost function is not exactly zero after convergence
  - ▲ because of the noise in the measurements

# Estimates Validation and Model Accuracy



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- validation achieved using estimated parameters in model
  - ▲ different loading conditions
  - ▲ using the electrical power ( $P_e$ ) from detailed genset as input
- base load : 80 kW, 20% load change at every 2s
- NRMSE = 3.17%



# Conclusions

- MHE provides online estimates of states and parameters of a diesel genset
  - ▲ under typical PLL measurement noise and distributions
- developed and validated frequency dynamics model of gensets
  - ▲ can be used in design and estimation of renewable integrated diesel generator system

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