

Is Discrete-Direct model calibration and uncertainty propagation more Trustworthy for estimating Tail Probabilities and Percentiles than Bayesian approaches?

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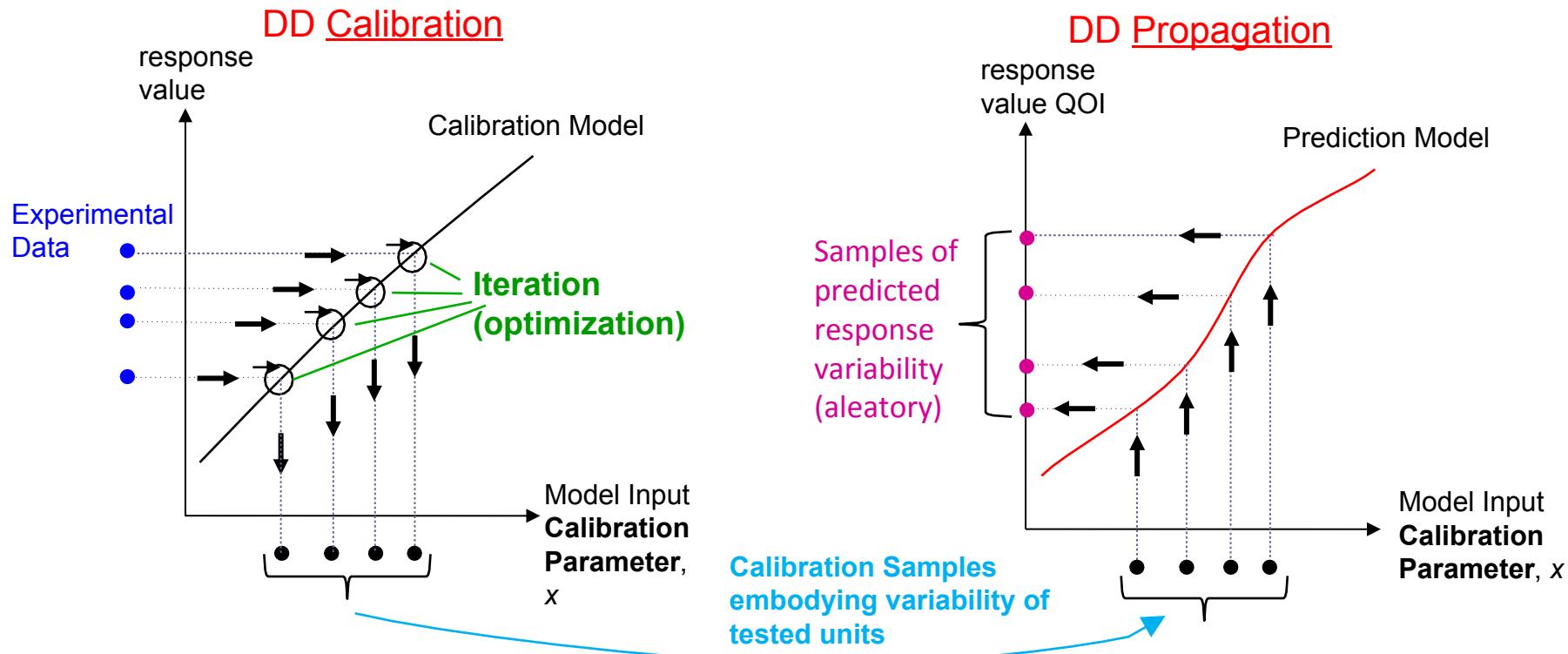
Outline



- **Introduce the Discrete-Direct (DD) model calibration and uncertainty propagation approach:**
 - calibrate a material/phenomena/device model to each of multiple replicate experiments to incorporate stochastic variability effects into the model and propagate them to predictions
- **Compare DD, Bayesian, and other calibration-prediction approaches for stochastic calibration-propagation problems under conditions of sparse replicate test data:**
 - cost
 - complexity
 - trustworthiness



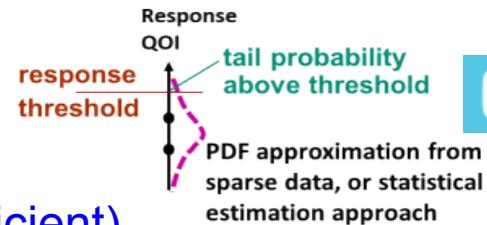
“Discrete Direct” (DD) Model Calibration and Uncertainty Propagation



- Propagate the discrete values of the calibration parameters
- Straightforwardly extends to problems with multiple calibration parameters
- N runs of model to propagate N param. values or sets from N calibration experiments
- Simple to update w/new experiments/data that may become available (w/out Bayes' rule & machinery)



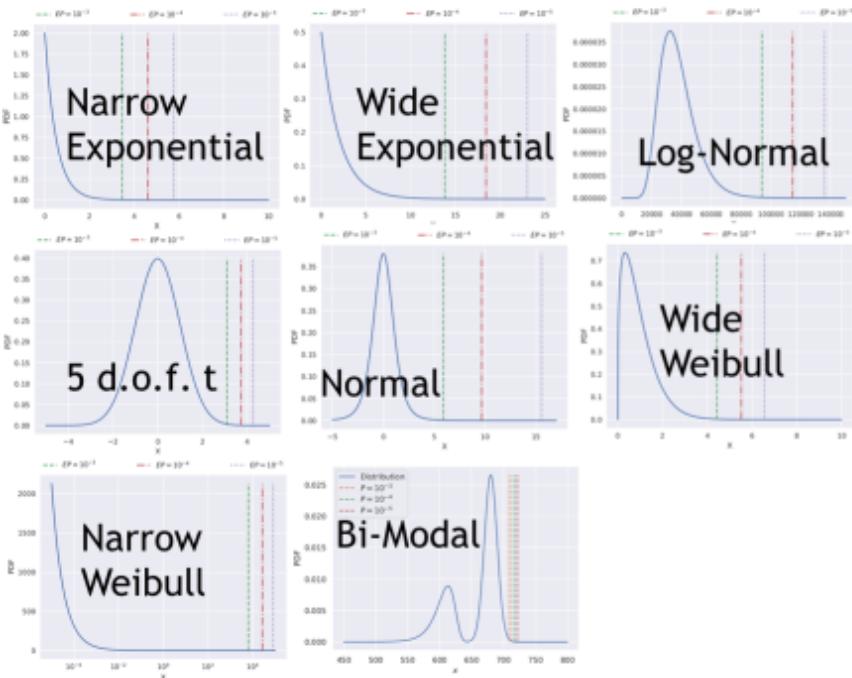
Testing and Optimization of Sparse-Sample 1-D Tail-Probability Estimation Methods



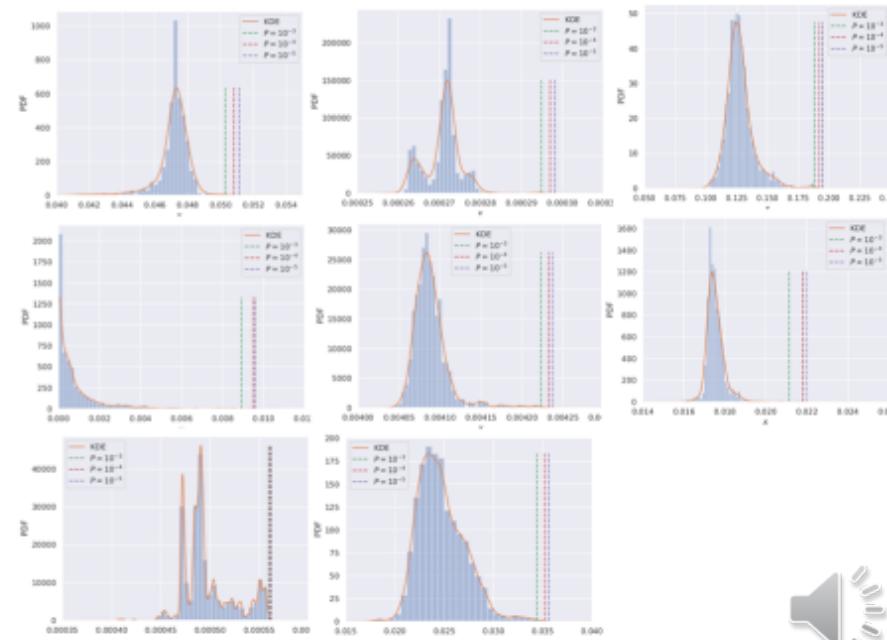
Objective: be conservative but not overly conservative (efficient)

- Large numerical study with $> 3e+08$ performance tests
- ~20 established and newly developed methods: variants, combinations, hybrids
- tail probability magnitudes $10^{-1}, 10^{-2}, 10^{-3}, 10^{-4}, 10^{-5}$
- # samples $N = 2, 3, 4, \dots, 20$
- 16 diverse distribution shapes below
- 10K random sampling trials for each combinations of the above factors studied

8 analytical PDFs



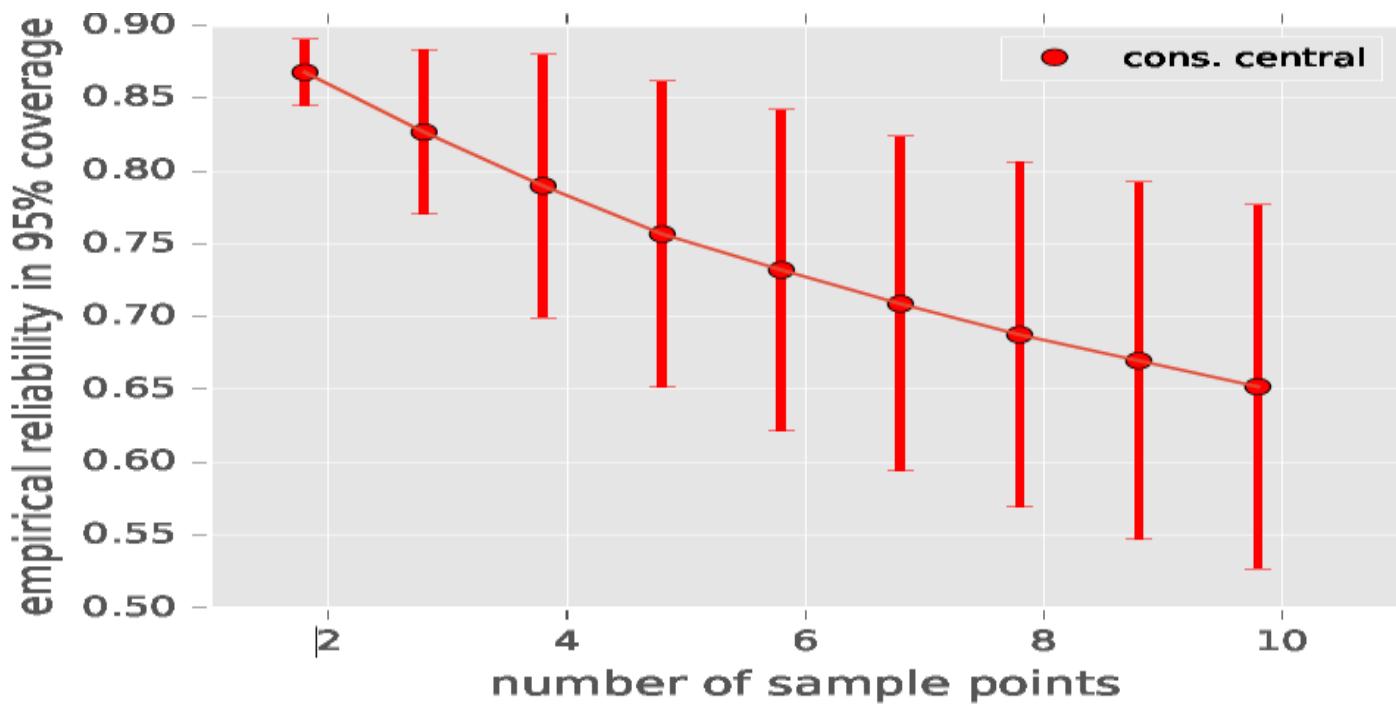
8 empirical PDFs



Robustness of 95/90 TIs for Bounding Central 95% of Non-Normal Distributions



Empirical success rates on 144 Non-Normal distributions
(bars capture 90% of the 144 cases)



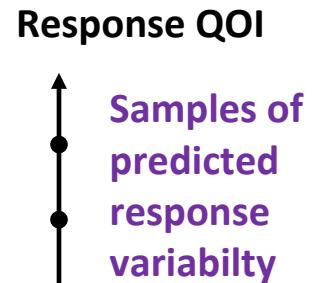
- Can get higher reliabilities for $N \geq 3$ by using Statistical Jackknifing and averaging resulting TIs

DD Simplicity, Cost, and Trustworthiness

Advantages: maps Multi-D UQ ↗ 1-D UQ



- **Example:**
 - a model with 3 calibration parameters
 - N=2 replicate experiments
- **DD: 2 calibrations → 2 parameter sets → 2 runs of prediction model → 2 values of response**
 - get a 1-D UQ problem with 2 samples of response
 - empirical confidence levels on bounding estimates of response statistics
- **Some other calibration-propagation approaches would try to infer a 3-D Joint PDF of variability of the calibration parameters from the 2 calibration parameter sets (data points) in the 3-D space, then propagate the JPDF**
 - get a highly questionable JPDF and predicted PDF of response, uncertainty would be difficult and expensive to reliably estimate
 - JPDF propagation requires high expense or a surrogate model (added complexity, uncertainty, and more runs of the prediction model than DD)



Bayesian Approaches:

Additional Difficulties and Uncertainties



- Bayesian approaches would typically propose PDF model forms for the marginal distributions of the calibration-parameter aleatory variations
 - *hyper-parameters* of the proposed aleatory PDFs are assigned prior distributions to describe their uncertainties
 - little to no prior knowledge would generally be available concerning hyper-parameter values, especially for non-Normal distributions which have non-intuitive parameters
 - so, broad uncertainties would most prudently be assigned
 - The hyper-parameters are calibrated by Bayesian updating using experimental data to reduce their uncertainties
 - sparse experimental data ↗ hyper-parameter uncertainties will remain relatively broad after Bayesian updating
 - The proposed aleatory PDF model forms themselves will likely be incorrect in the first place because sparse data does not support accurate selection of PDF model forms



Additional Difficulties/Uncertainties with Bayesian Approaches (cont'd)



- The many formulation options in Bayesian approaches can lead to substantial analyst-to-analyst and results variability
 - Use a hyper-parameter formulation or don't?
 - Use a discrepancy term or don't?
 - What type of parametric and/or non-parametric PDF model forms or formulations, and Priors, will be used?
 - What sampling approach (MCMC or other) will be used, and what surrogate modeling approach will be used to make it affordable?
- A Bayesian-derived JPDF with linear dependency approximations will have substantial error/uncertainty that must be appropriately characterized and accounted for
 - *How is this done? Has the effectiveness been characterized in realistic and representative test problems under random trials?*
 - *How well can I trust the results in real applications?*



Closing Remarks



- The DD calibration-UQ approach for sparse calibration data is versatile and relatively simple, inexpensive, and reliable in terms of characterized confidence of giving conservative estimates of response statistics
- The methodology has been confirmed on several test problems
 - 4 calibration variables, strain-rate dependent material plasticity model calibrated to 4 stress-strain curves, 16 Can-Crush output responses (ASME UQ-Risk journal paper)
 - 8 calibration variables, material plasticity model calibrated to 5 stress-strain curves, Pressure Vessel max load
 - radiation-damaged electronics (3 device models calibrated to time-dependent functional data curves, then used in circuit response tail-probability predictions)
- A Sandia document with more detailed discussion of these issues will likely be available by the time you see this presentation (contact vjromer@sandia.gov)

