



# GAMVT: Generative Algorithm for MultiVariate Timeseries

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SAND number



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# Outline

Motivation

GAMVT

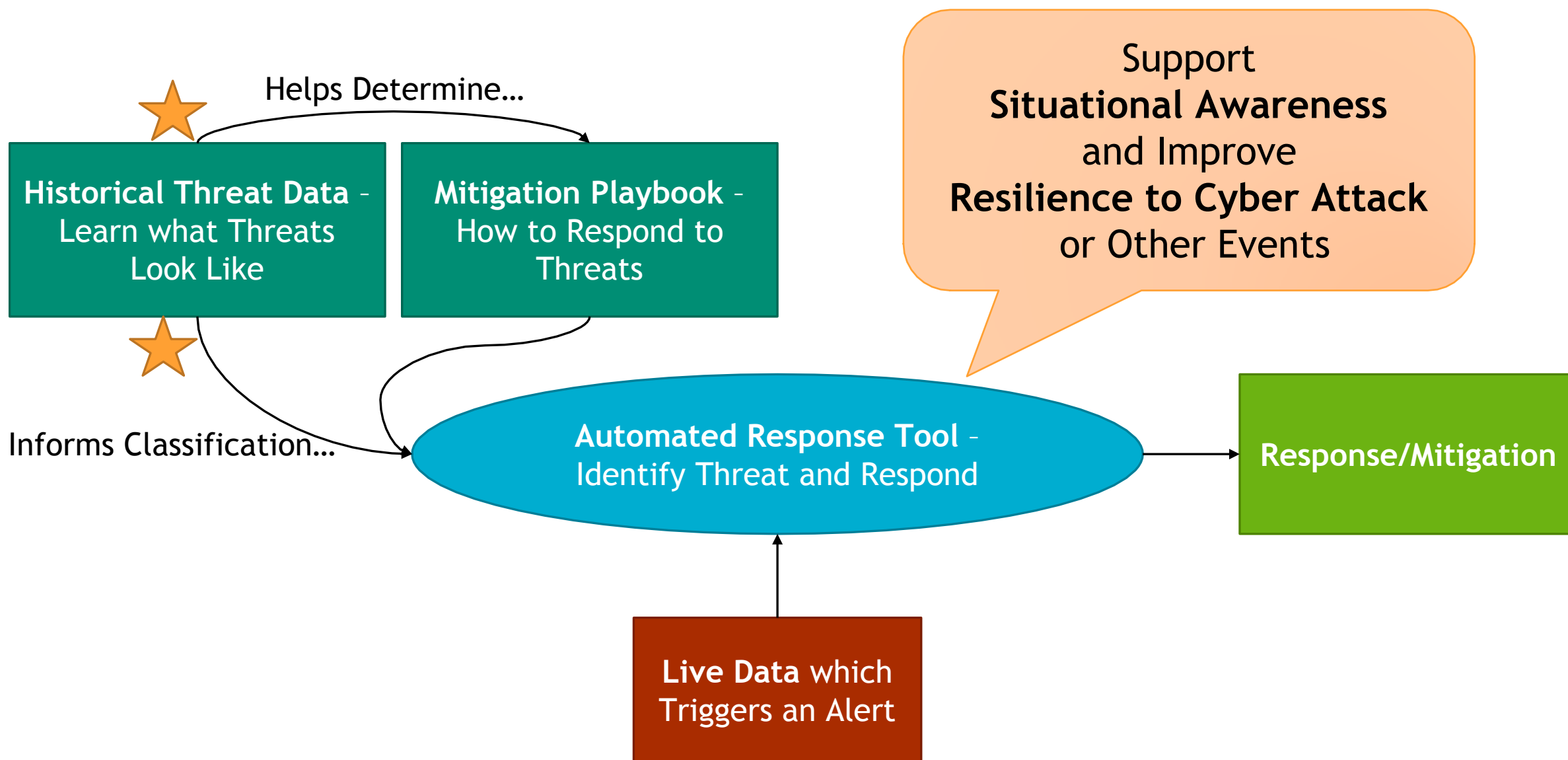
Use Case

Results

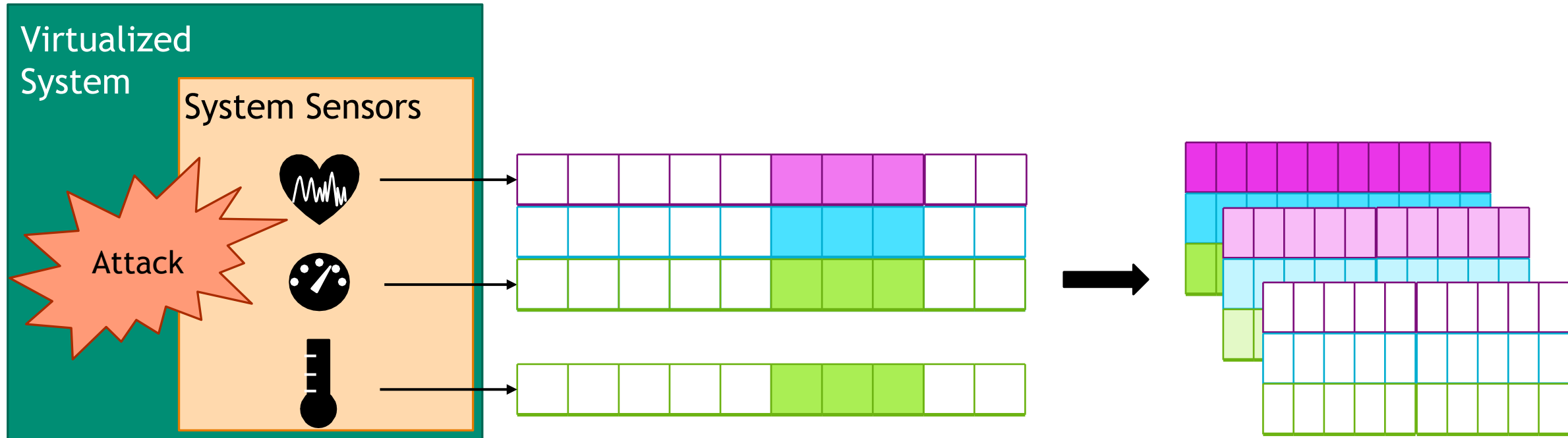
Future Work



# Motivation: Automated Response in a Cyber System



## Motivation: System Emulation



# Motivation: Generating Enough Data



## Generate All Data Through Emulation?

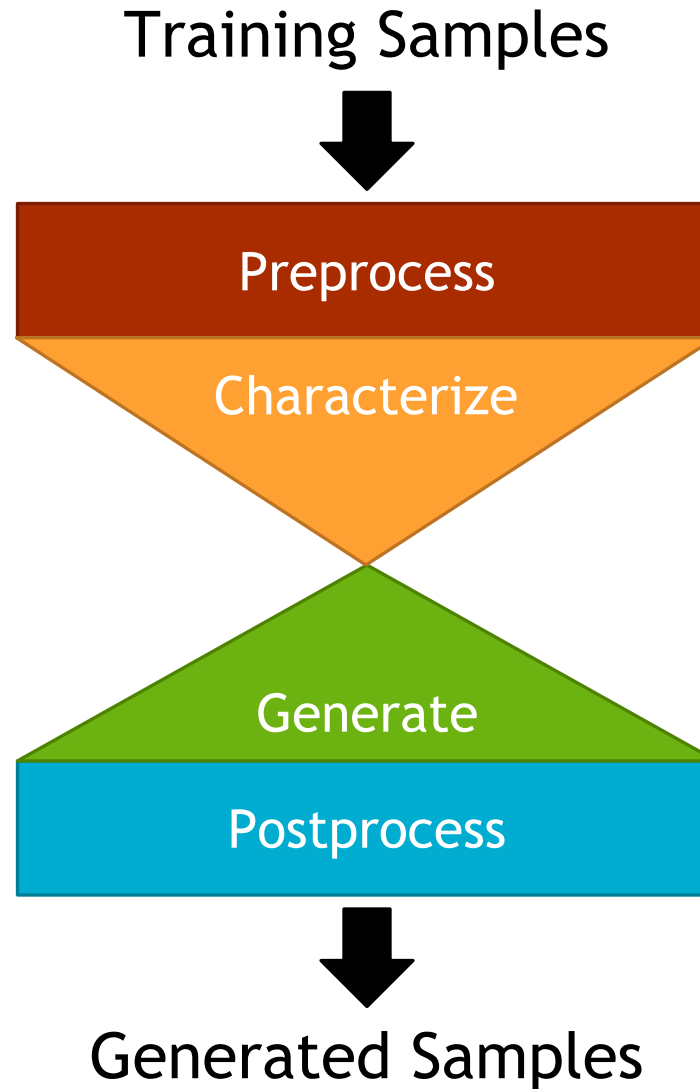
- Too Slow

## Perturb the Existing Data?

- Results in Samples with Inverted Timeline or Missing/Unordered Variables

## Use Existing Deep Learning Methods for Data Generation?

- Image Data  $\neq$  Multivariate Timeseries Data
- Large Training Dataset Requirements





## Maintain Certain Data Artifacts

- Data Types
- Sample Shape

## Simplify the Data

- Better Captures Trends
- Improves Results of First Step of Characterization: Timeseries Clustering

## 1. Timestep Clustering with TICC\*

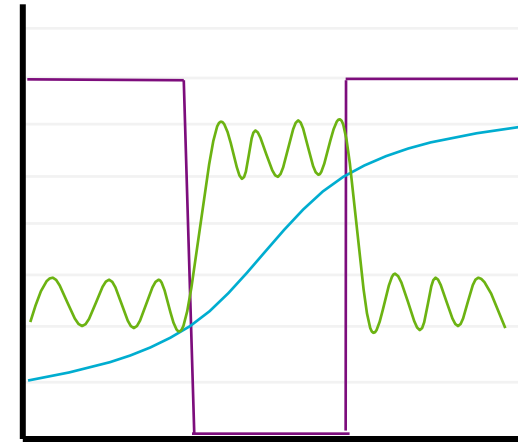
- How do variables relate to each other in a given cluster?
- Additional Subdivision of Samples by Cluster Label

## 2. Pattern Inference and Section Statistics

- What order do sections appear in?
- How long are those sections?

## 3. Value Statistics

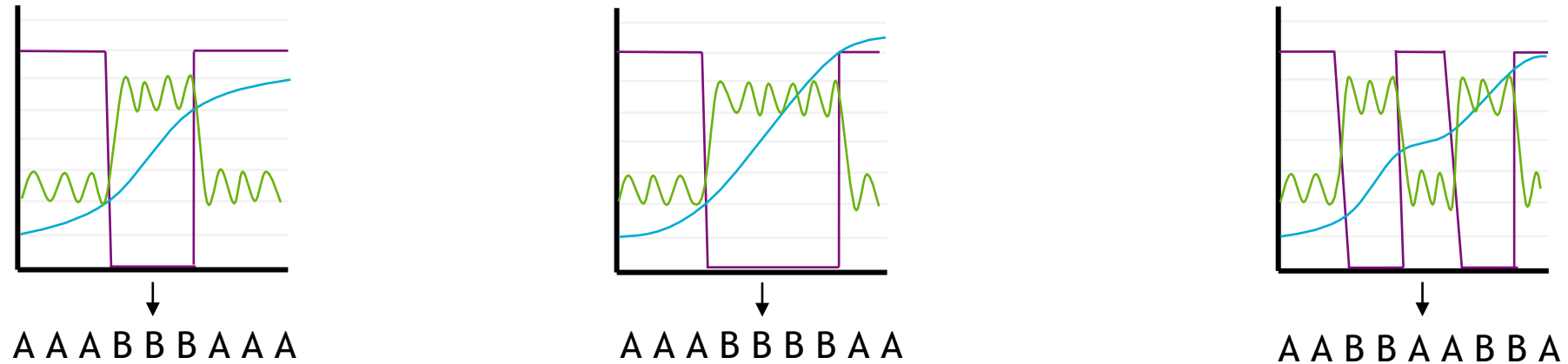
- What trends exist in the preprocessed data, per-class and per-cluster?
- Mean, Minimum, Maximum for each variable



Call “Value Statistics”  
something more specific

\* D. Hallac, S. Vare, S. Boyd, and J. Leskovec, “Toeplitz Inverse Covariance-Based Clustering of Multivariate Time Series Data”, 2017. [Online]. Available: [arXiv.org, https://arxiv.org/abs/1706.03161](https://arxiv.org/abs/1706.03161).





Pattern =  $[A[BA]^1, 2]$

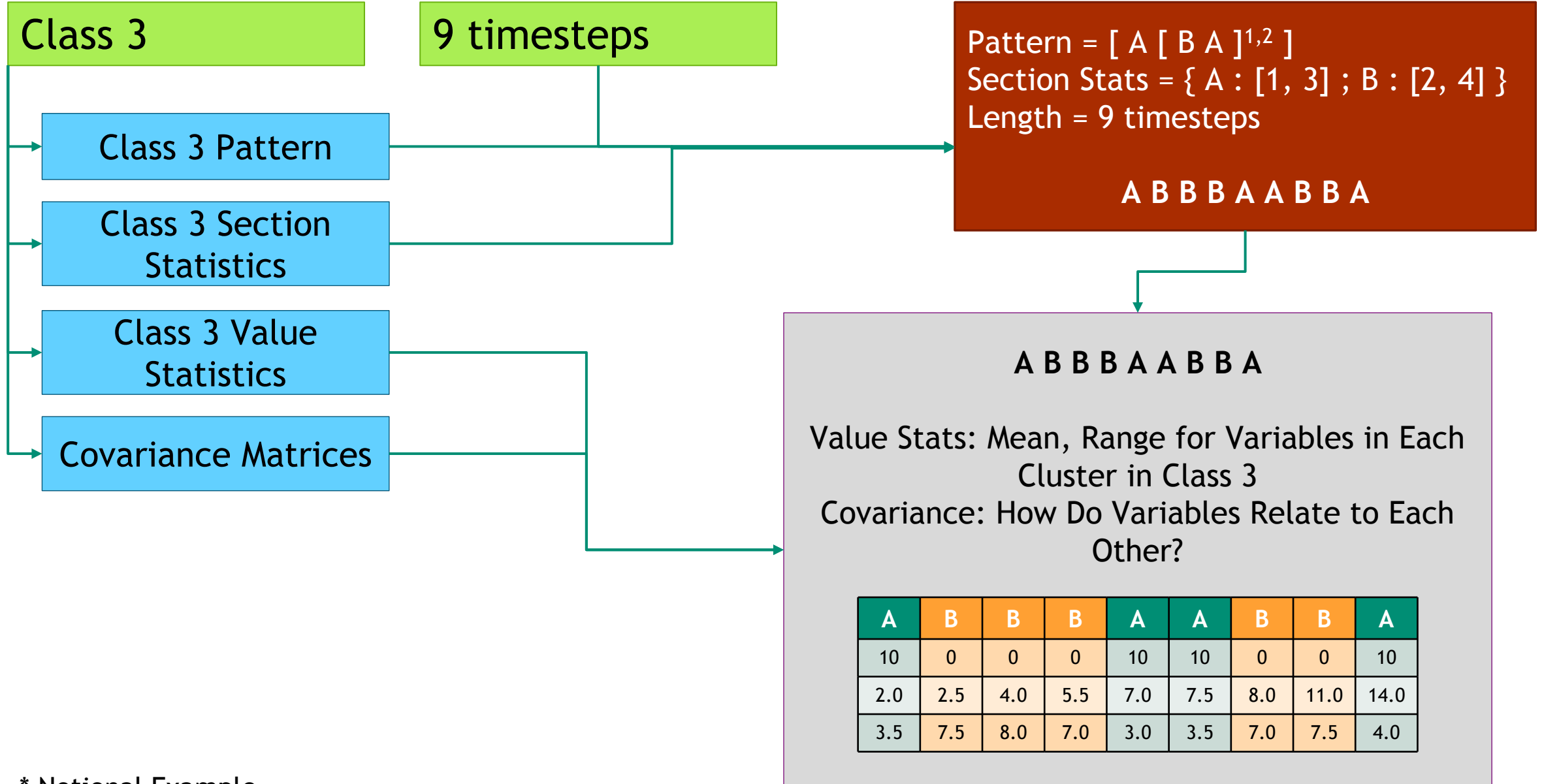
	Section Statistics	Value Statistics
A		
B		

“Each sample starts with a section of ‘A’, followed by one or two repetitions of a section ‘B’ and a section of ‘A’”

Covariance ( A )

Covariance ( B )

# GAMVT: Generation

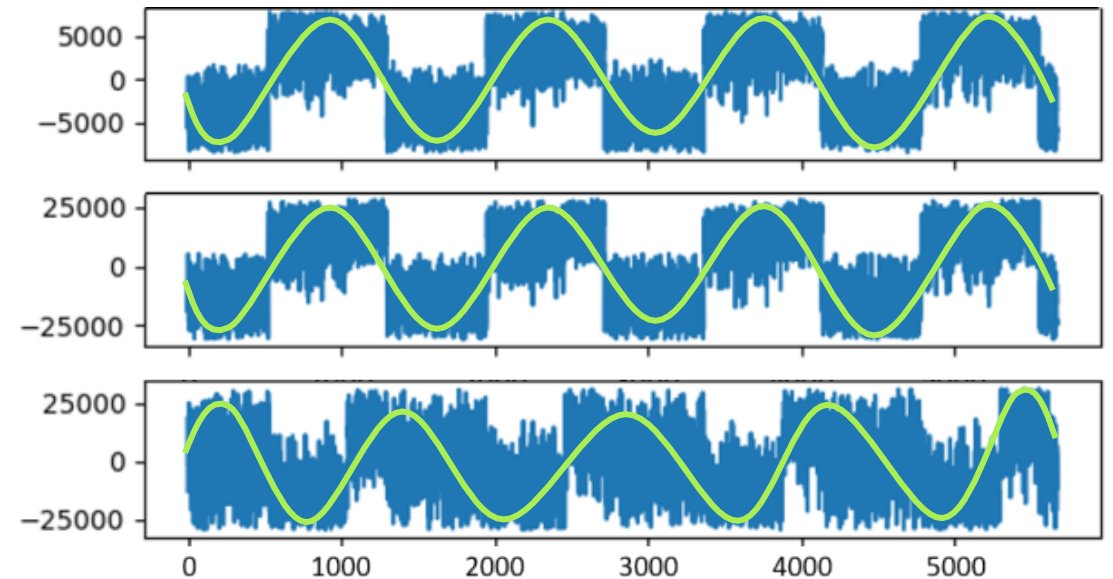
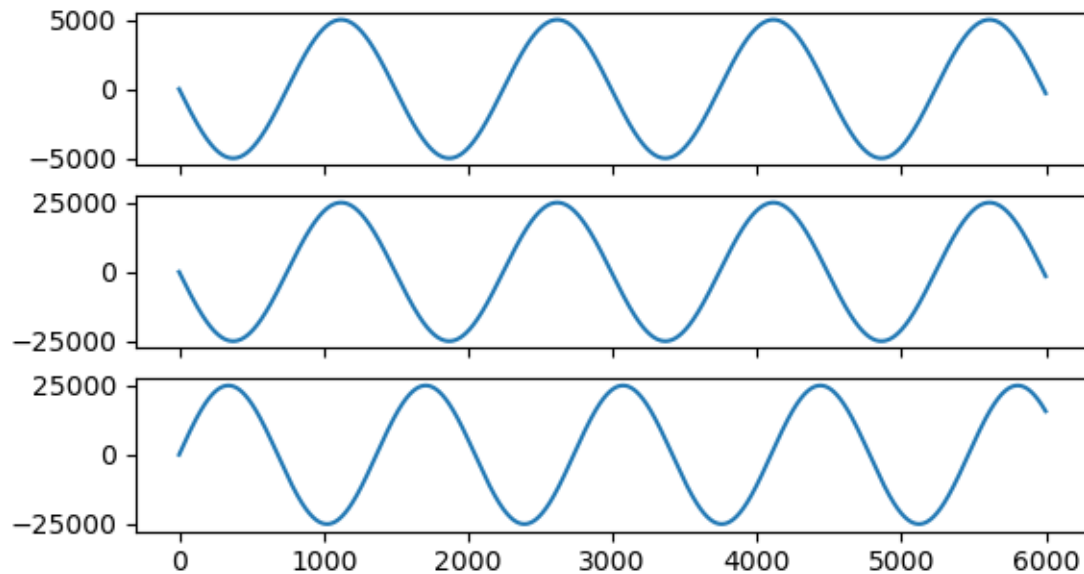


\* Notional Example

## Undo Preprocessing

- Undo Simplifications
- Reinforce Data Types

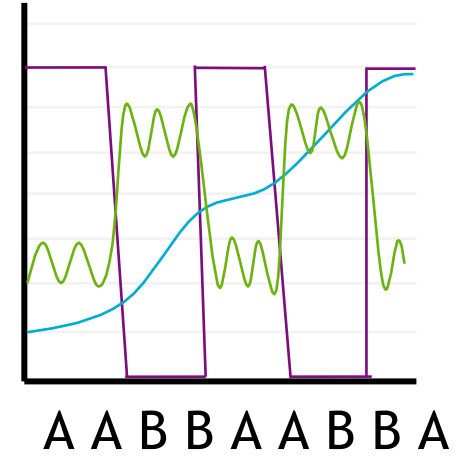
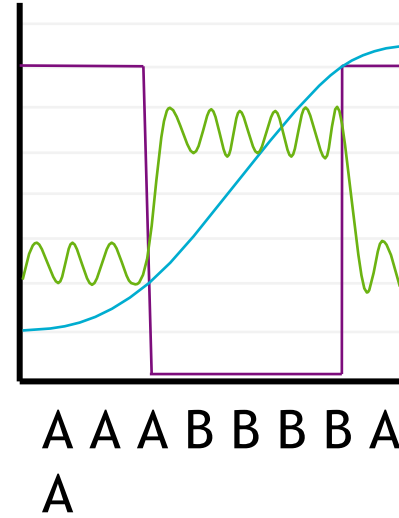
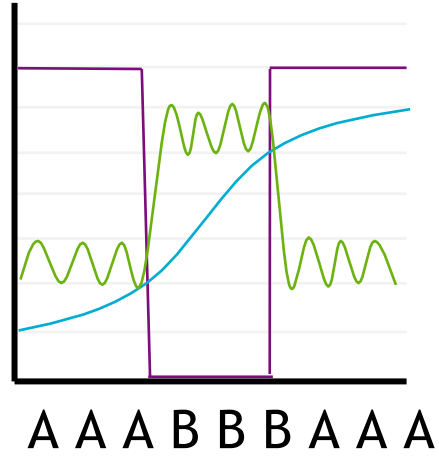
## Smooth Generated Results



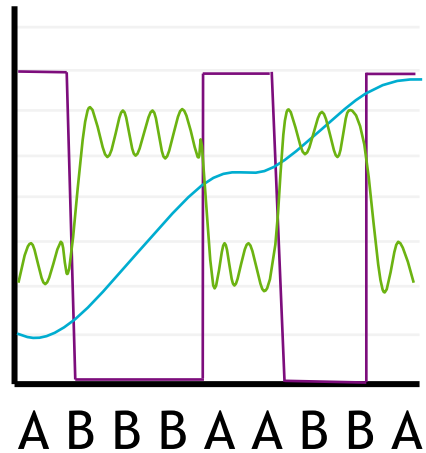
# GAMVT-Generated Sample



Training Set:



Generated Sample:



# Use Case: Space-Cyber System



## NASA-Developed satellite emulation – NOS3

### Variables from System Sensor

- GPS
  - X, Y, Z position components
  - X, Y, Z velocity components
- Camera
  - On/Off state
  - Memory usage

### Sample Classes

- 1 baseline, 3 attacks
- 50 samples total

The screenshot displays an Ubuntu Desktop environment with several applications running. The main window is the COSMOS Command and Telemetry Server - STP1 Configuration. It features a table with columns: Interface, Connect/Disconnect, Connected?, Clients, Tx Q Size, Rx Q Size, Bytes Tx, Bytes Rx, and Cmd Pkt. The table shows two interfaces: CFS\_INT and COSMOSINT, both connected. Below the table, there is a log window showing system messages. Other windows include the STP1 Flight Software, NOS Engine Standalone Server, and Simulators. The desktop also shows a map application and a file manager.

STP1 Flight Software

NOS Engine Standalone Server

Simulators

# Visualized Data Sample



X, Y, Z Coordinate Position Data

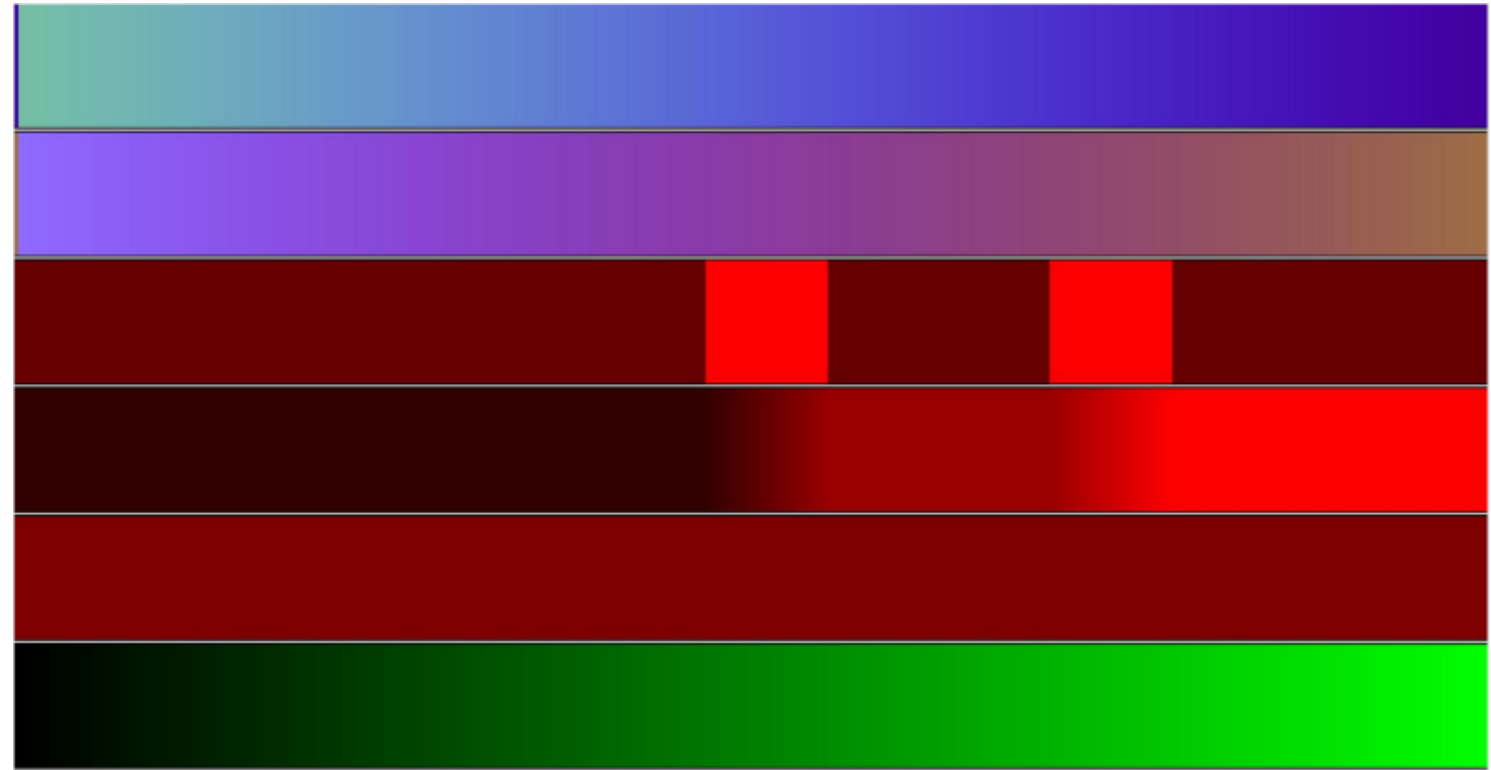
X, Y, Z Coordinate Velocity Data

Camera On/Off State

Camera Memory Usage

(Reserved for Future Usage)

Timestamps



**Generation Objective:** To generate samples that differ from the real data, but which are similarly smooth and contain similar features to the real data.

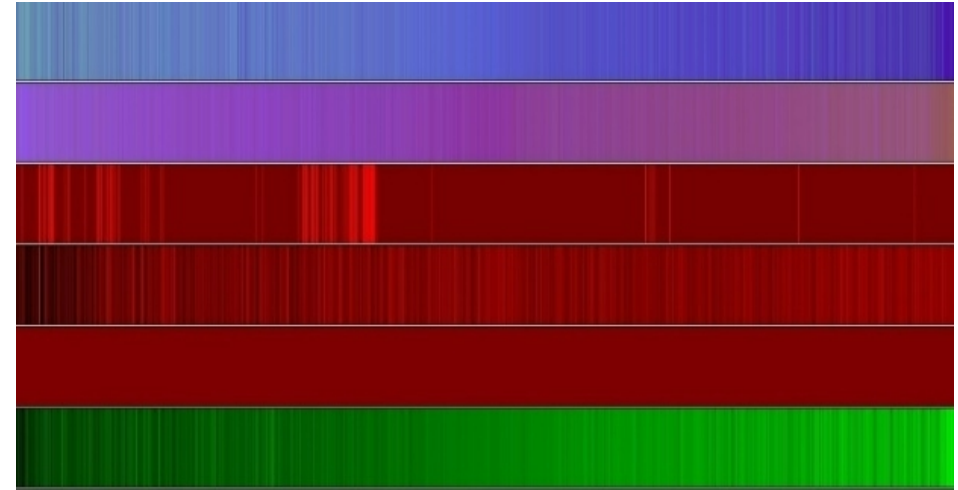
# Deep Learning Approaches



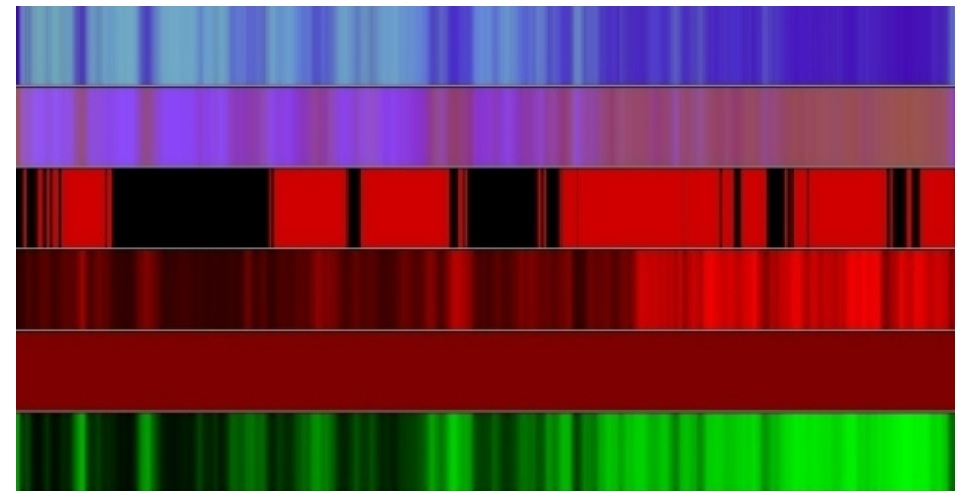
Real data



Generative Adversarial Network

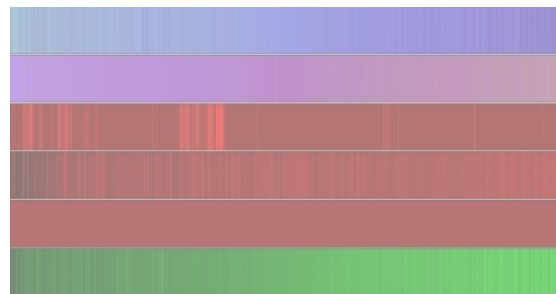


Variational Autoencoder

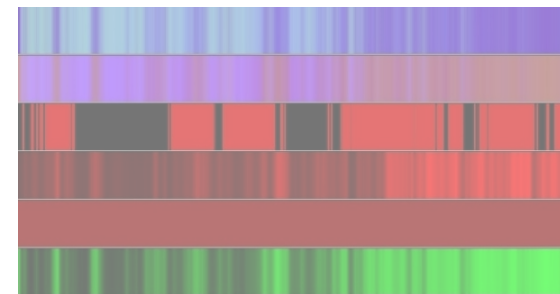


# GAMVT Results

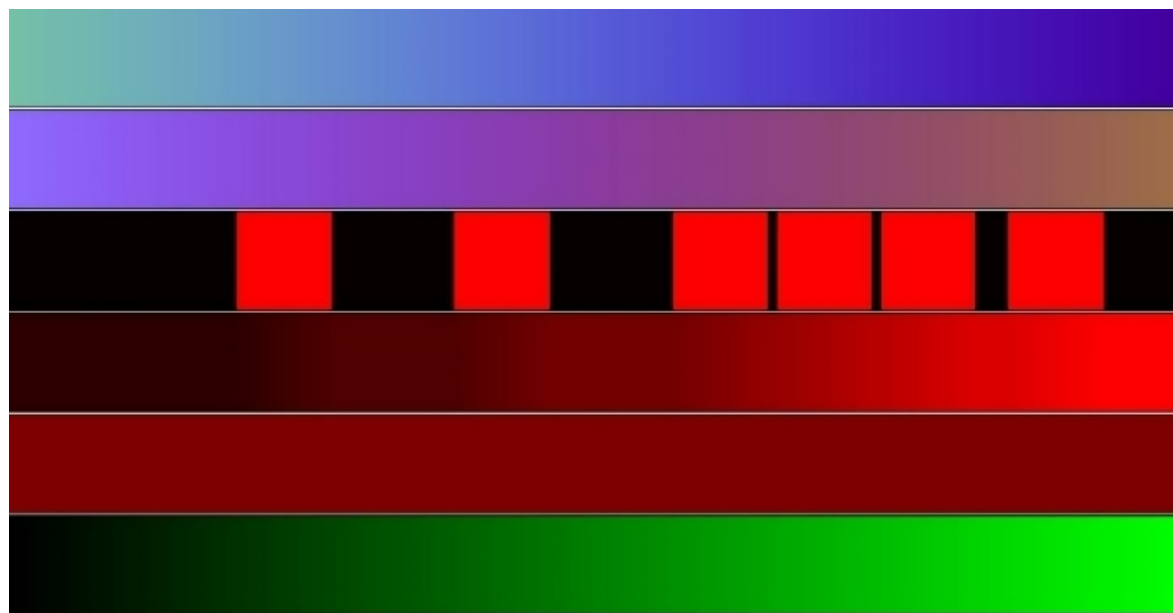
GAN



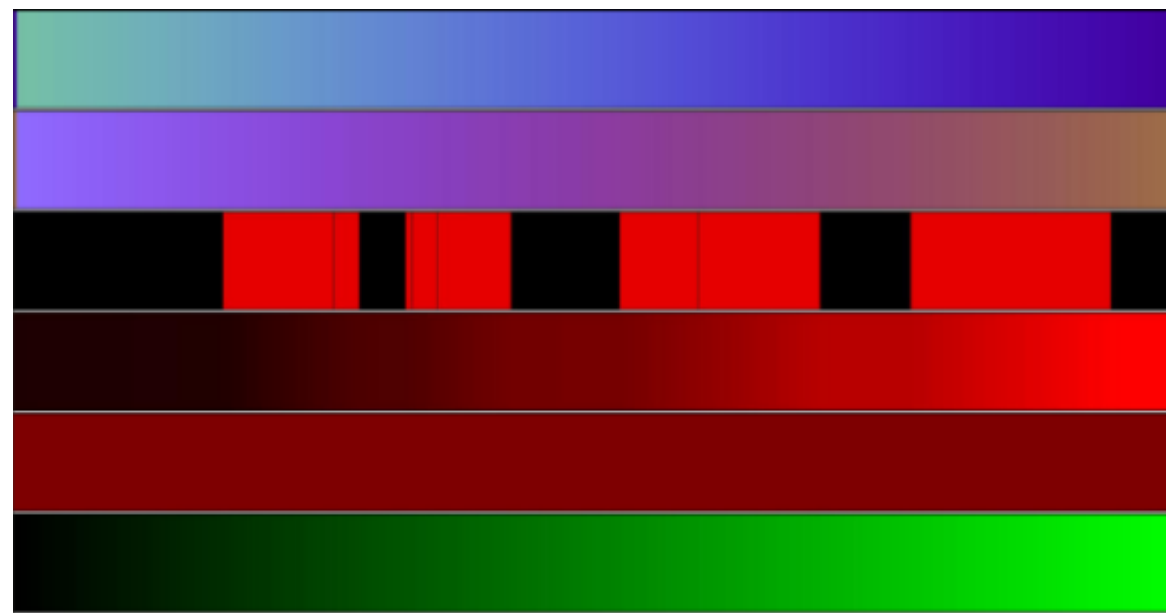
VAE



Real data

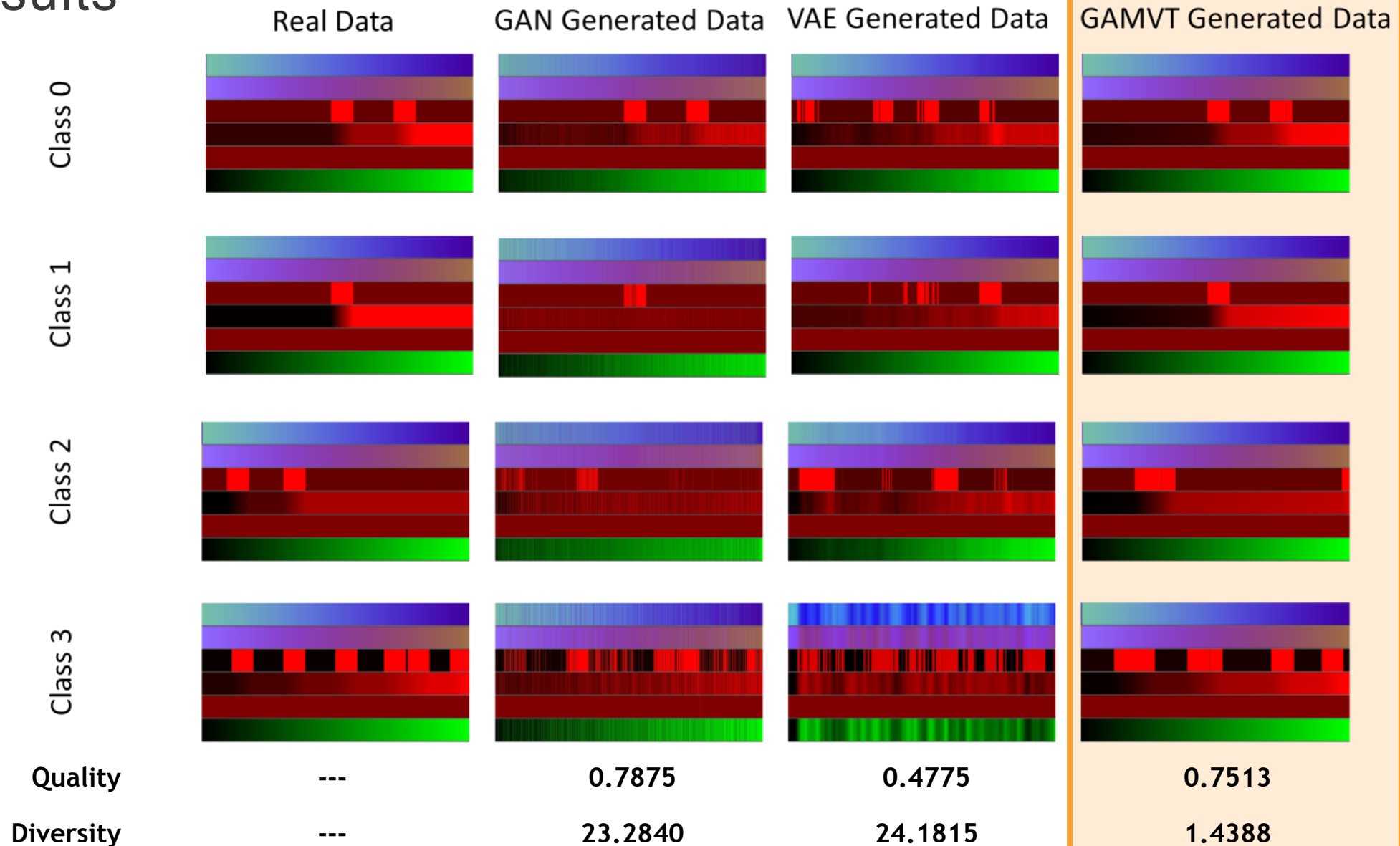


GAMVT





# Results





Test Generated Data with Downstream Process

Support More Complex Datasets

- Improve handling of oscillatory data
- Test and Develop with more complex relationships
- Expand support for a variety of generated distributions

Develop Methodology for Finding the Best Set of Pre/Post-Processing Functions



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