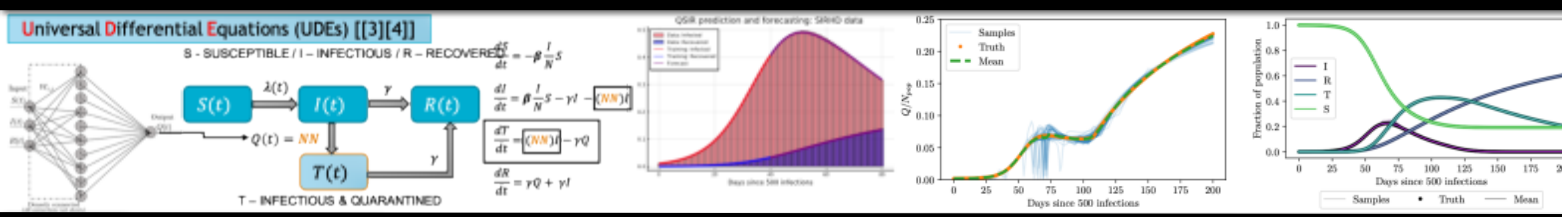
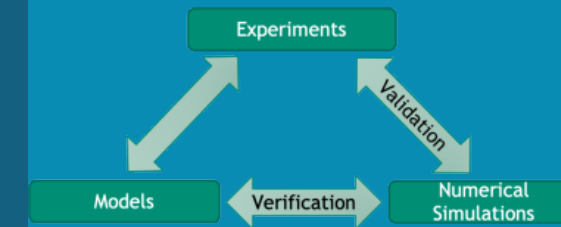




Assessing the Efficacy of Universal Differential Equations to Learn Missing Dynamics from a Subset of Observable State Variables



Presented By

Erin C.S. Acquesta (5954) & Teresa Portone (1463)

In collaboration with:

Chris Rackauckas (MIT) & Raj Dandekar (MIT)



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All Models are Wrong, Some are Useful

-George Box



Modeling real-world phenomena to any degree of accuracy is a challenge that the scientific research community has navigated since its foundation.

Historically researchers have utilized and continue to utilize:

Verification: Are we solving the equations correctly?

Validation: Are we solving the correct equations?

Uncertainty Quantification:

- What uncertainty is attributed to inherent random behavior (i.e. aleatory)?
- What uncertainty is attributed to the fact that we don't know (i.e. epistemic)?

System Identification: Statistical methods to build mathematical models of dynamical systems from measured data.

Today:

Scientific Machine Learning: Area of machine learning focused on the use of machine learned models used in lieu of, complementary to, or as surrogates for computational simulation models used for science and engineering.

Epidemiology



The **study** of the **distribution** and **determinants** of **health-related states** or **events** in **specified populations**, and the **application** of this study to the control of health problems [1]

Nomenclature:

Basic Reproduction Number, R_0 , “R-naught”

The expected number of infections from one infected individual introduced into a population of 100% susceptible individuals.

Replacement Number, $R_{\text{eff}}(t)$, “R-effective”

After the early stages of an epidemic has passed, the number of secondary infections is expected to go down as the number of susceptible individuals goes down.

Virus

Pathology

Severe Acute Respiratory Syndrome Coronavirus 2 (SARS-CoV-2)

Viruses are named based on their genetic structure to facilitate the development of diagnostic tests, vaccines and medicines.

Disease

Epidemiology

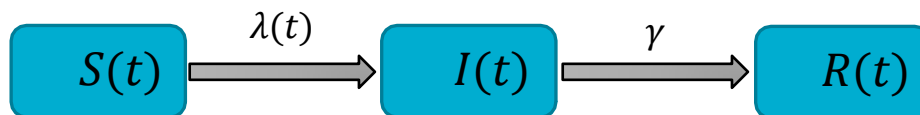
COronaVirus Disease, 2019 (COVID-19)

Diseases are named to enable discussion on disease prevent, spread, transmissibility, severity and treatment.

Compartmental Models for Infectious Disease [2]



S - SUSCEPTIBLE / I - INFECTIOUS / R - RECOVERED



System of ordinary differential equations (ODEs):

$$\frac{dS(t)}{dt} = -\beta \frac{I(t)}{N} S(t)$$

$$\frac{dI(t)}{dt} = \beta \frac{I(t)}{N} S(t) - \gamma I(t)$$

$$\frac{dR(t)}{dt} = \gamma I(t)$$

Force of Infection Function: $\lambda(t) := \beta \frac{I}{N}$ → Model $R_0 = \beta \frac{1}{\gamma}$

Infection rate: β

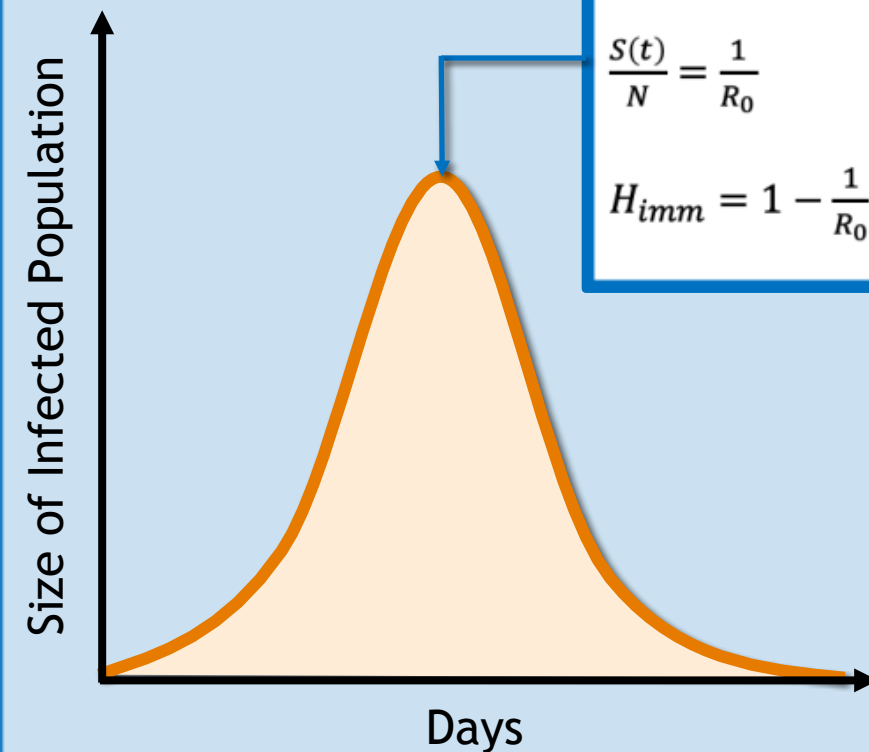
Recover rate: γ

Residence Time in $I(t)$: $\frac{1}{\gamma}$

Total Population: $N = S(t) + I(t) + R(t)$

*Note: the total population size is constant under this formulation

Notional Plot of Infected Population, $I(t)$



Case Counts for Covid-19 in United States



We know the classic SIR model is under-representative of the real-world phenomenon it is intended to simulate.

New reported cases



Image Credit: NYT <https://www.nytimes.com/interactive/2021/us/covid-cases.html> [accessed 2021/07/12]

“All models are wrong”:

- Homogenous behaviors.
- Uniform mixing of the population.
- Lacks influence on disease transmission from interventions.
 - Quarantine
 - Social Distancing
 - Personal Protective Equipment (PPE)

“Some are useful”:

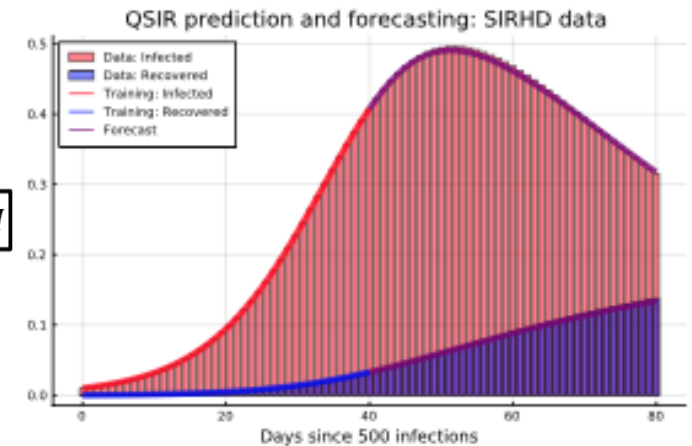
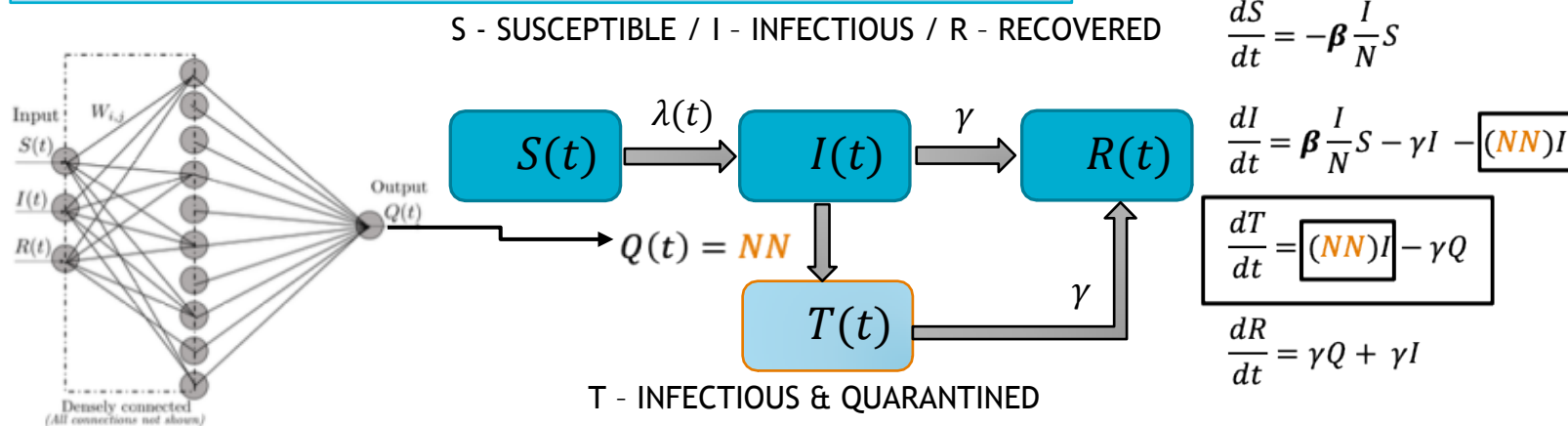
- During an emergent pandemic, we do NOT have the details to build heterogeneous models.
- Model calibration may provide insight into the baseline parameters.
- These are the baseline dynamics that have been used for decades in all infectious disease models.

Scientific Machine Learning (SciML)



Area of machine learning focused on the use of machine learned models used in lieu of, complementary to, or as surrogates for computational simulation models used for science and engineering.

Universal Differential Equations (UDEs) [[3][4]]



Physics-Informed Neural Networks (PINNs) [5]

Data-driven solutions to Partial Differential Equations (PDEs)

$$u_t + \mathcal{N}[u] = 0, \quad x \in \Omega \subset \mathbb{R}^m, t \in [0, T]$$

where $u(t, x)$ denotes the latent (hidden) solution,
 $\mathcal{N}[\cdot]$ is a nonlinear differential operator

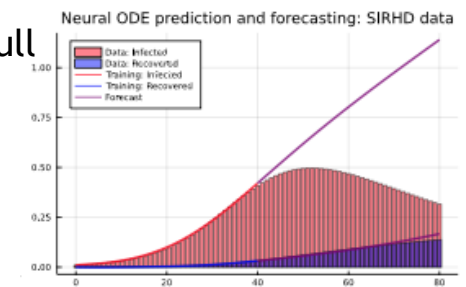
Then.... $u(t, x) = \text{NN}$

Neural Ordinary Differential Equations (ODEs) [6]

Simulating unknown dynamics for a full
 System of ODEs:

$$\frac{dU(t)}{dt} = \text{NN}(U)$$

where $U = [S, I, R]$



Universal Differential Equations (UDEs) [7]

UDEs are part of the SciML libraries written in Julia: <https://sciml.ai>

Julia is a high-level high-performance parallel computing language: <https://julialang.org>

Efficient Training of Universal Differential Equations via Differentiable Programming

- Given discrete data points: (t_i, \mathbf{d}_i) where
 - $t_i \in [t_0, t_1]$ are discrete points along the time horizon and
 - \mathbf{d}_i are the corresponding realizations representing the state solutions (e.g. $S(t), I(t), R(t)$).
- **Objective:** minimize the cost function, $\mathcal{C}(\theta)$, on the current approximation to the solution, $u^{[j]}(t)$, to the dynamical system, $\frac{du}{dt} = F(u, t, \text{NN}_{\theta}(u, t))$.

$$\mathcal{C}(\theta) = \sum_i \|u^{[j]}(t_i) - \mathbf{d}_i\|$$

- “Differentiable programming framework with reverse-mode accumulation is used to allow for deriving on-the-fly approximation for the wide range of differential equation types.”

Using pullbacks:

Given a function $f(x) = y$ the pullback at x is the function:

$$B_f^x(y) = y^T f'(x)$$

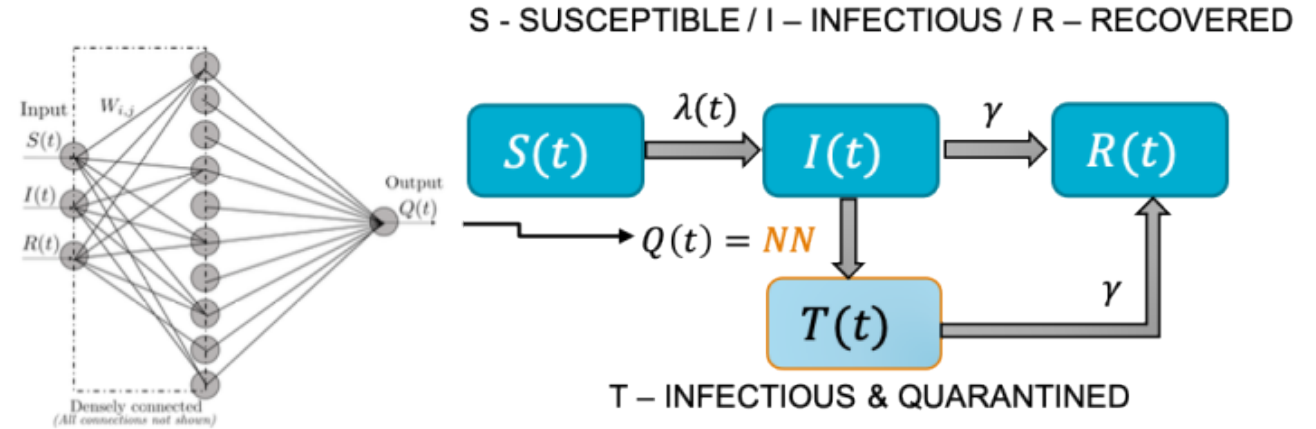
then, the pullback of a cost function computes the gradient.

Assessing the Effects of Quarantine Control in COVID-19 Spread [4]

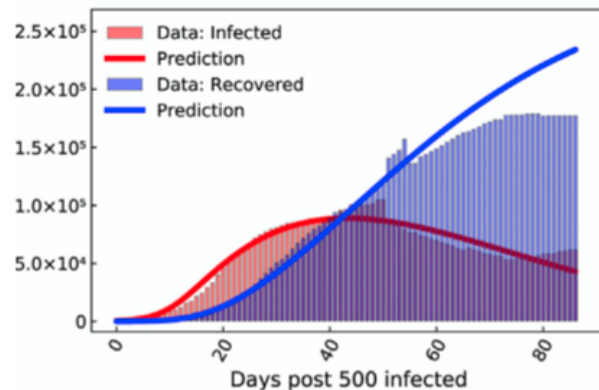


UDEs are a useful and valuable tool to learn what we don't already know!!

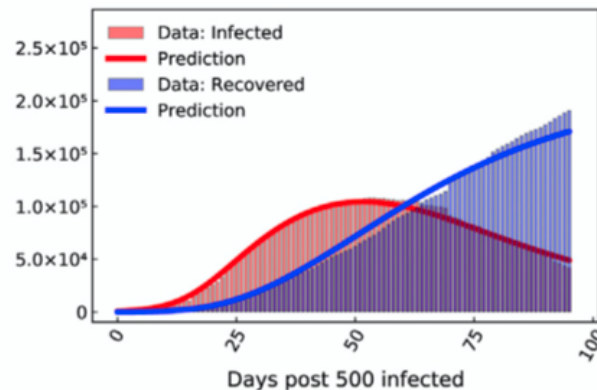
It can provide invaluable insight during an emergent pandemic.



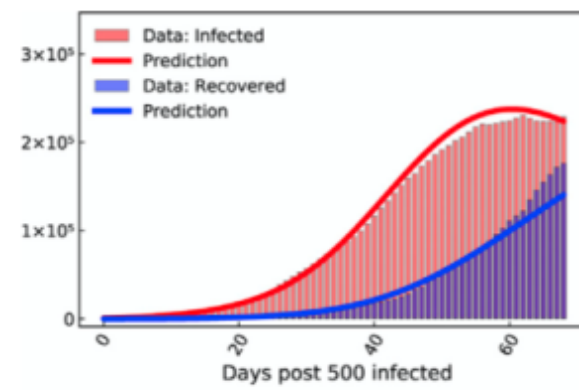
Learning the effect of quarantine around the world:



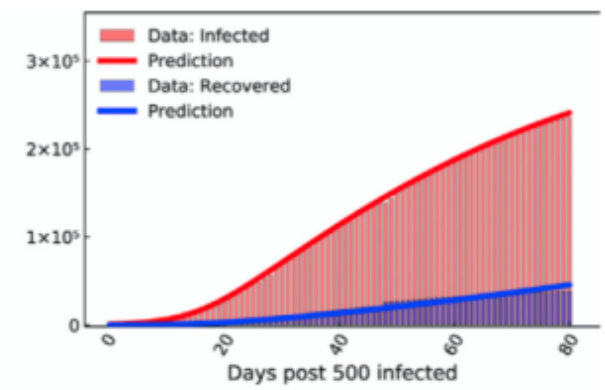
Spain



Italy



Russia



UK

UDEs for Compartment Models of Infectious Disease [4]



Dandekar et. al. used UDEs to represent isolation dynamics for COVID-19.

$$\frac{dS(t)}{dt} = -\frac{\beta I(t)}{N_{pop}} S(t)$$

$$\frac{dI(t)}{dt} = \frac{\beta I(t)}{N_{pop}} S(t) - \gamma I(t) - Q(t) I(t)$$

$$\frac{dT(t)}{dt} = Q(t) I(t) - \delta T(t)$$

$$\frac{dR(t)}{dt} = \delta I(t) + \delta T(t)$$

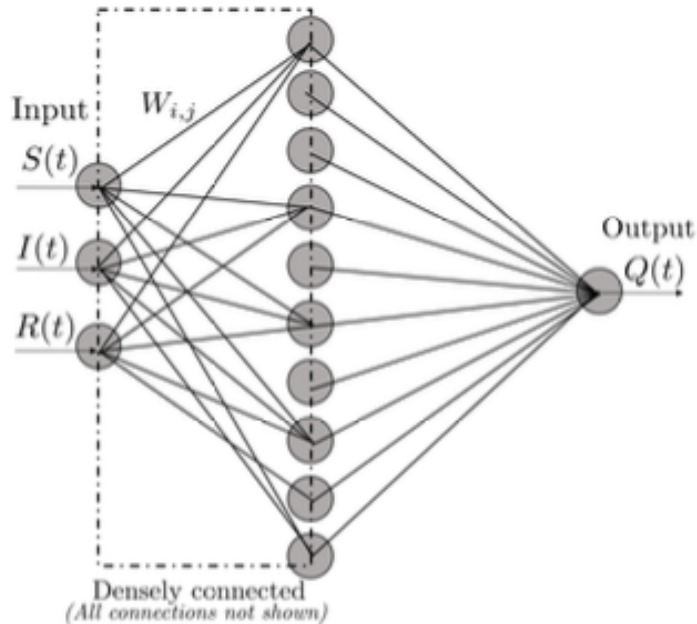
- Introduced an isolation state $T(t)$.
- UDE for the *nonlinear* transition rate from $I(t)$ into $T(t)$, denoted $Q(t)$.
- $Q(t)$ is approximated with a small neural network trained on data for $I(t)$ & $R(t)$, denoted $NN_{\theta}(u, t)$.
- By definition constrained to conserve population,

$$\frac{dN_{pop}}{dt} = 0$$

Loss Function:

$$L_{NN}(\theta, \beta, \gamma, \delta) = \|\log(I(t)) - \log(I_{data}(t))\|^2 + \|\log(R(t)) - \log(R_{data}(t))\|^2$$

Universal Approximation Theorem



Universal Approximation Theorem [[8],[9],[10]]:

(one version) Fix a continuous function $\sigma: \mathbb{R} \rightarrow \mathbb{R}$ (**activation function**) and positive integers d, D . The function σ is not a polynomial if and only if, for every continuous function $f: \mathbb{R}^d \rightarrow \mathbb{R}^D$ (**target function**), every compact set K of \mathbb{R}^d , and every $\varepsilon > 0$ there exists a continuous function $f_\varepsilon: \mathbb{R}^d \rightarrow \mathbb{R}^D$ (**the layer output**) with representation

$$f_\varepsilon = W_2 \circ \sigma \circ W_1$$

where W_2, W_1 are composable affine maps and \circ denotes component-wise composition, such that the approximation is bounded

$$\sup_{x \in K} \|f(x) - f_\varepsilon(x)\| < \varepsilon$$

Although the Universal Approximation Theorem is necessary condition for neural networks to be universal approximators, it is not a sufficient condition in practice.

How do we know we are learning something useful?!?

Inferring Transition into Quarantine with Incomplete Data



- Dandekar et. al. used observations of $I(t), R(t)$ to infer transition rates (including $Q(t)$) for COVID-19.
- There are many applications for which *only a subset* of the state variables can be observed.

How does this affect the ability to recover “useful” information about $Q(t)$ & disease dynamics?!?

Experimental Plan

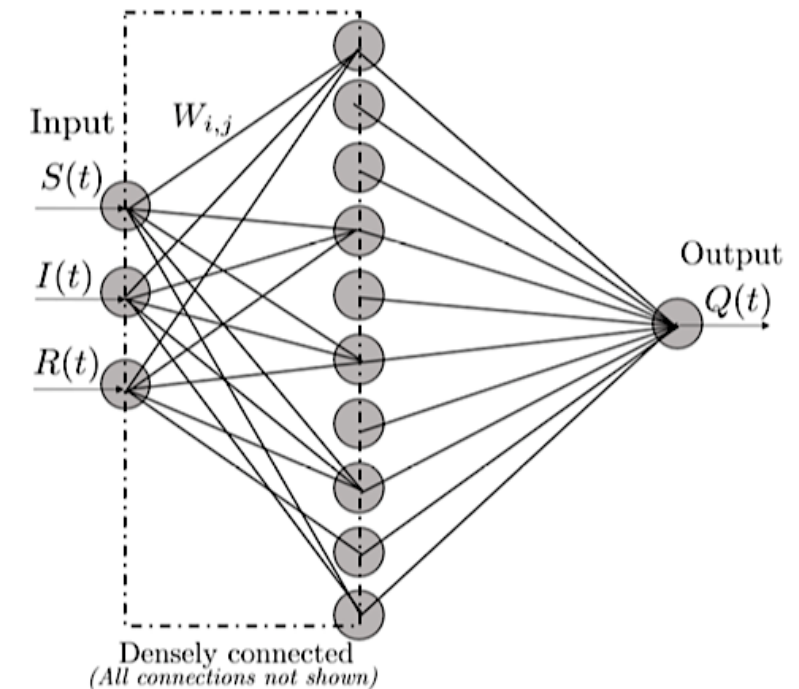
1. Generate synthetic data with prespecified NN_{θ^*} .
2. Infer $NN_{\hat{\theta}}$ & transition rate parameters $\hat{\beta}, \hat{\gamma}, \hat{\delta}$ from combinatorial subsets of state variable observations.
 - a. Data = $[I, R, T], [I, R], [I, T], [R, T], [I], [R], [T]$
3. Study mean-squared error (MSE) of inferred $\hat{Q}(t)$ vs “true” $Q^*(t)$ used to generate data for each dataset to determine when inference degrades.

Problem Specification/State of Knowledge



Assumptions:

- NN_{θ} fully-connected neural network of **depth 1**, **width 10**, and a **ReLU** activation functions.
- NN_{θ} architecture the same for data generation & inference.
- Synthetic data not corrupted by noise.
- Initial condition assumed known for state variables $S(0), I(0), T(0)$, and $R(0)$.
- All transition rate parameters β, γ , and δ uncertain; distributions derived from literature.
- Neural network parameters, θ and ODE parameters, β, γ , and δ



Ensemble Training: Robust Learning and Uncertainty Quantification

Approach

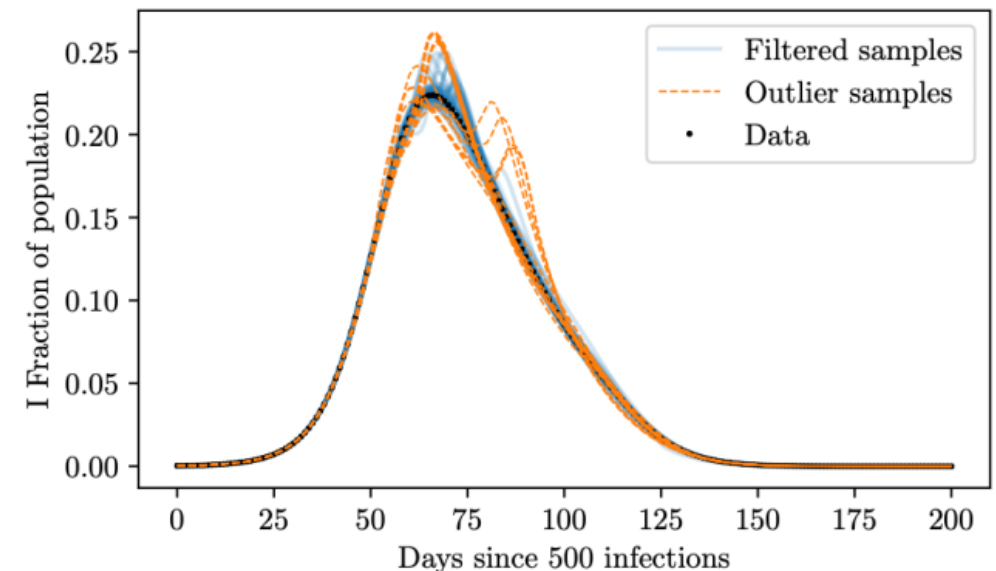
For each of the 7 possible observable state combinations: $\{[I, R, T], [I, R], [I, T], [R, T], [I], [R], [T]\}$

1. Run 100 training replicates to learn $\{NN_{\theta}^k\}$, $\{\hat{\beta}^k\}$, $\{\hat{\gamma}^k\}$, and $\{\hat{\delta}^k\}$, for $k = 1, \dots, 100$.
 - a. Each parameter is randomly initialized at the beginning of training.
 - b. Due to the vanishing gradient problem:
 - i. Filter out outlier ensemble members (those with very large MSE).
2. This will result in $n \leq 100$ realizations for optimal transition rate parameters and approximations for $Q(t)$

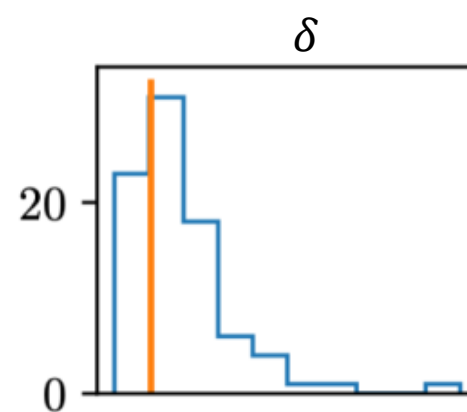
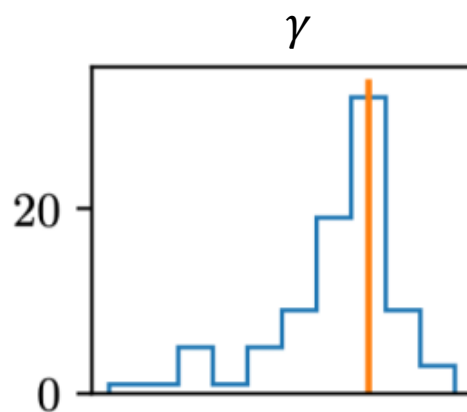
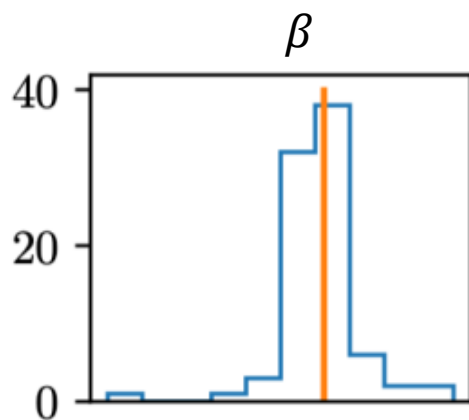
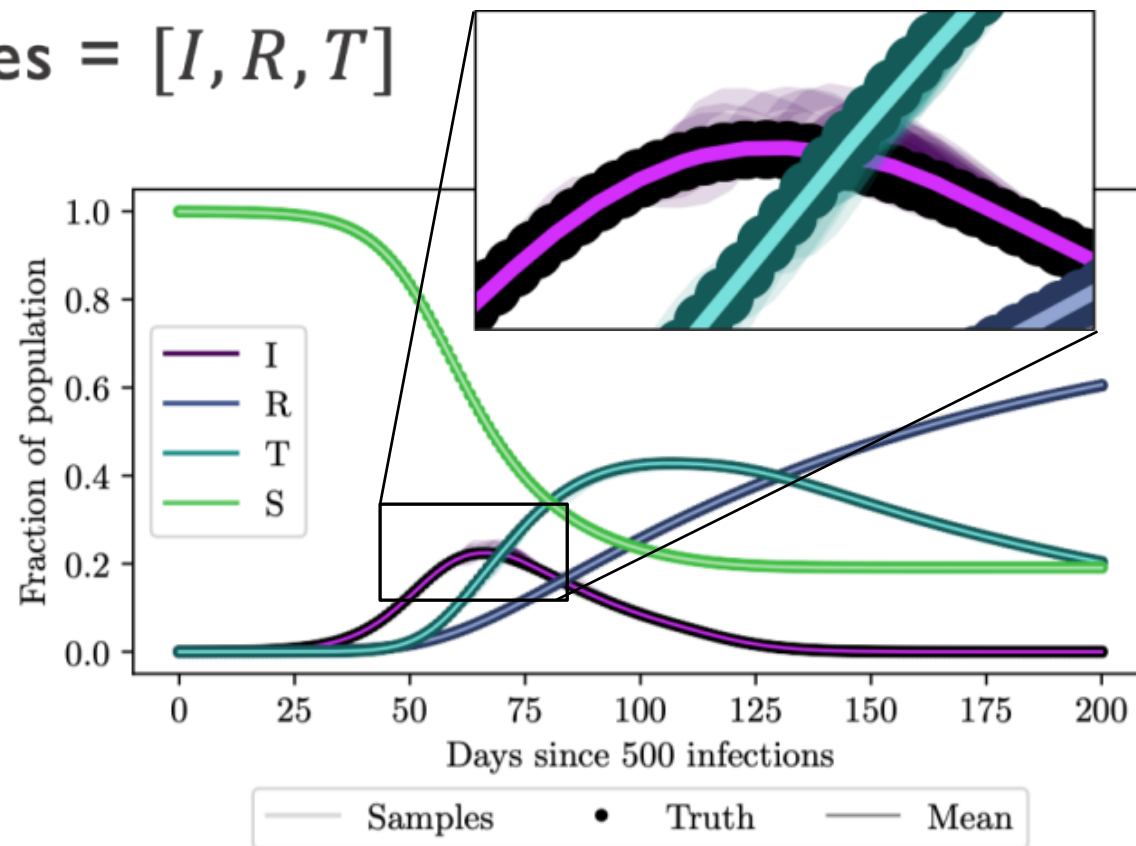
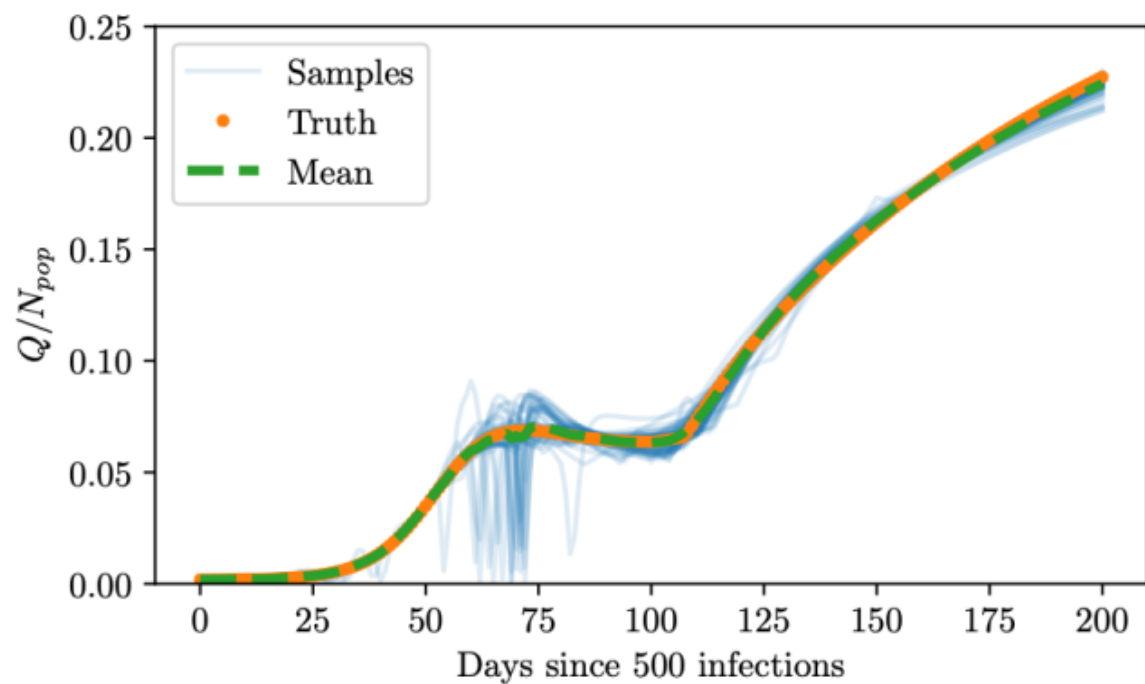
Uncertainty Quantification Opportunity

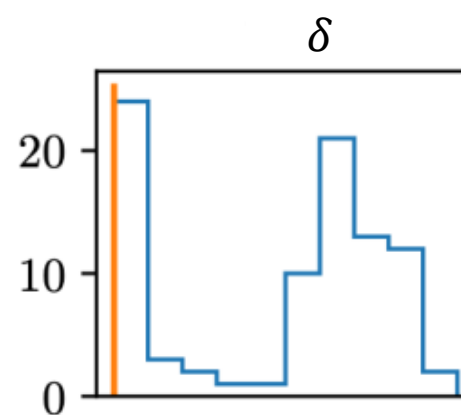
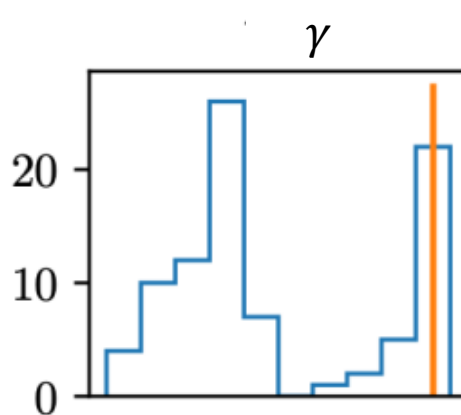
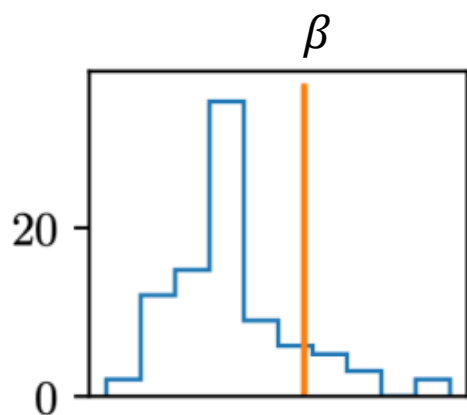
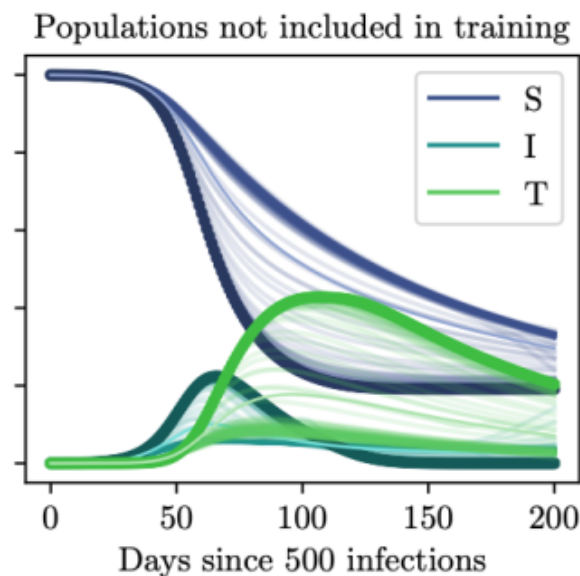
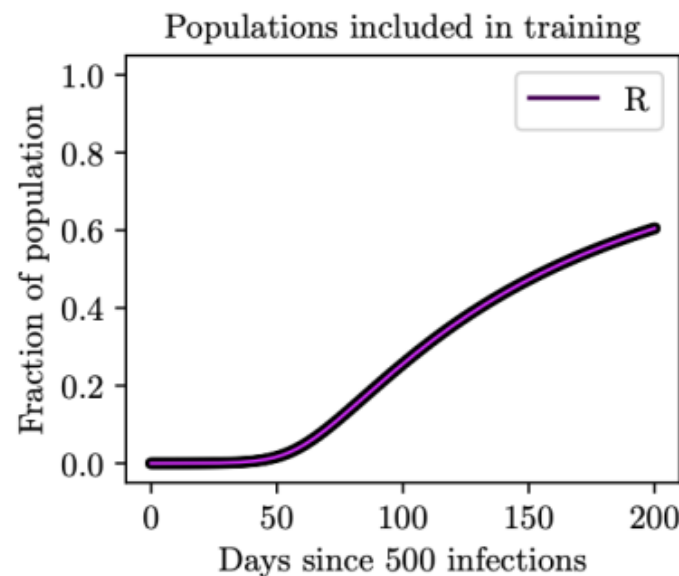
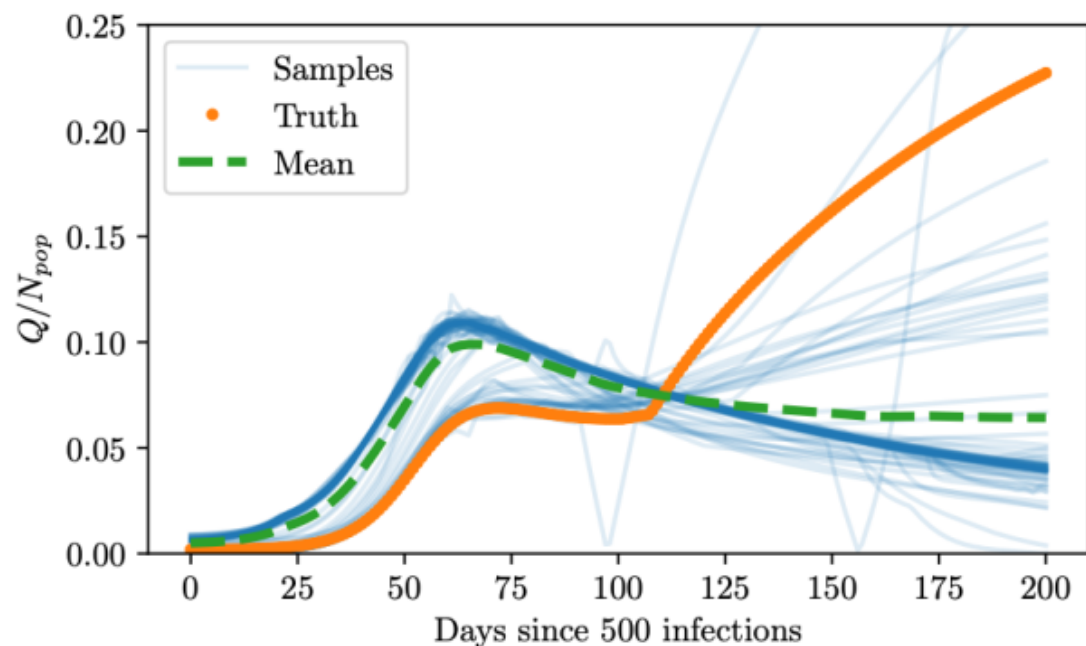
The ensembles provides an estimate on the variance for:

- Unobserved state variable trajectories.
- Optimized transition rate parameters.
- $Q(t)$



Training Results: Observable States = $[I, R, T]$

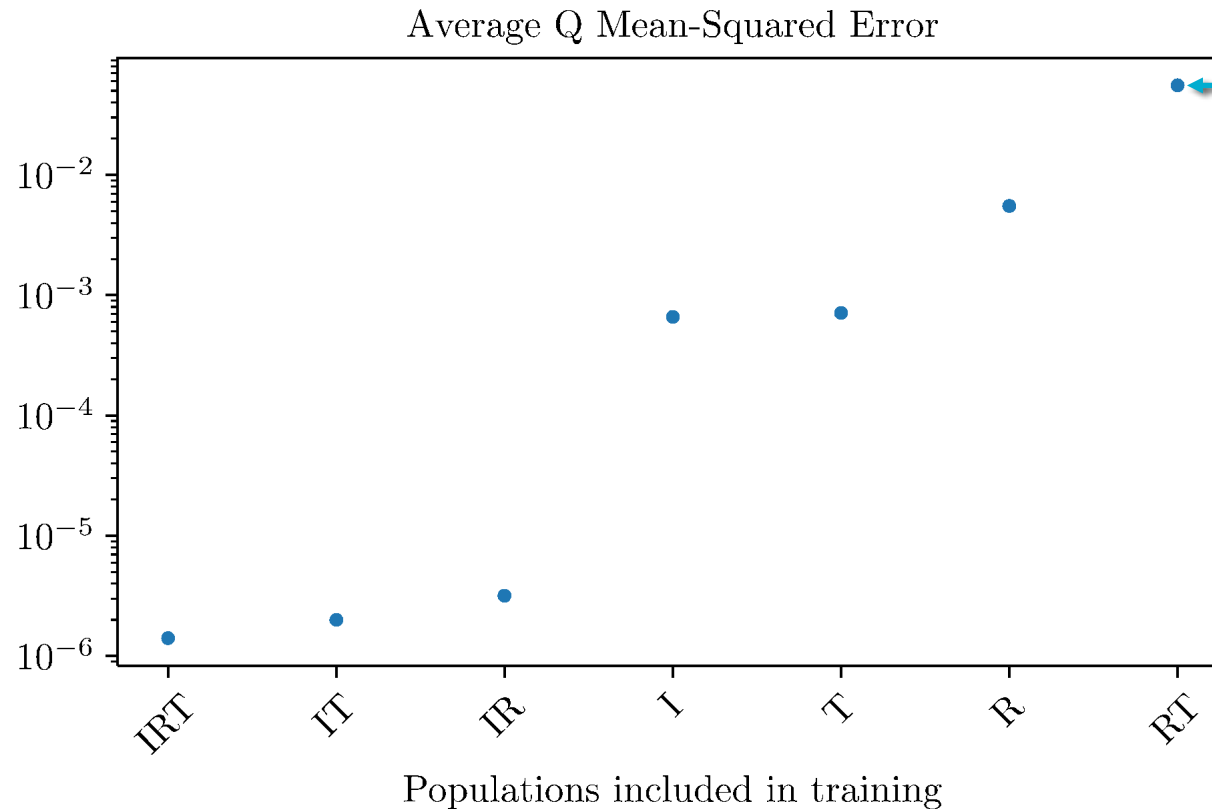


Training Results, Observable States = $[R]$ 

Ranking Q Recovery by Subset of Observable States

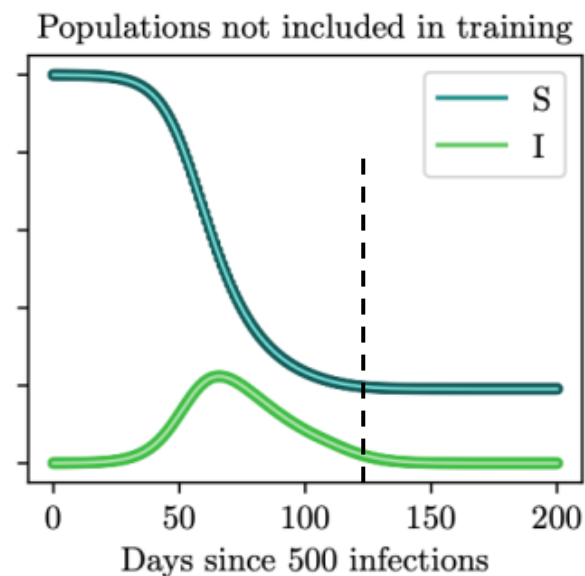
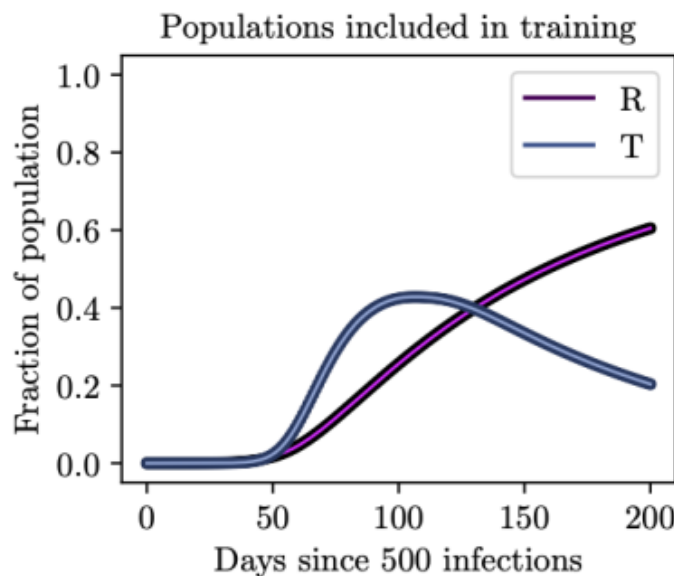
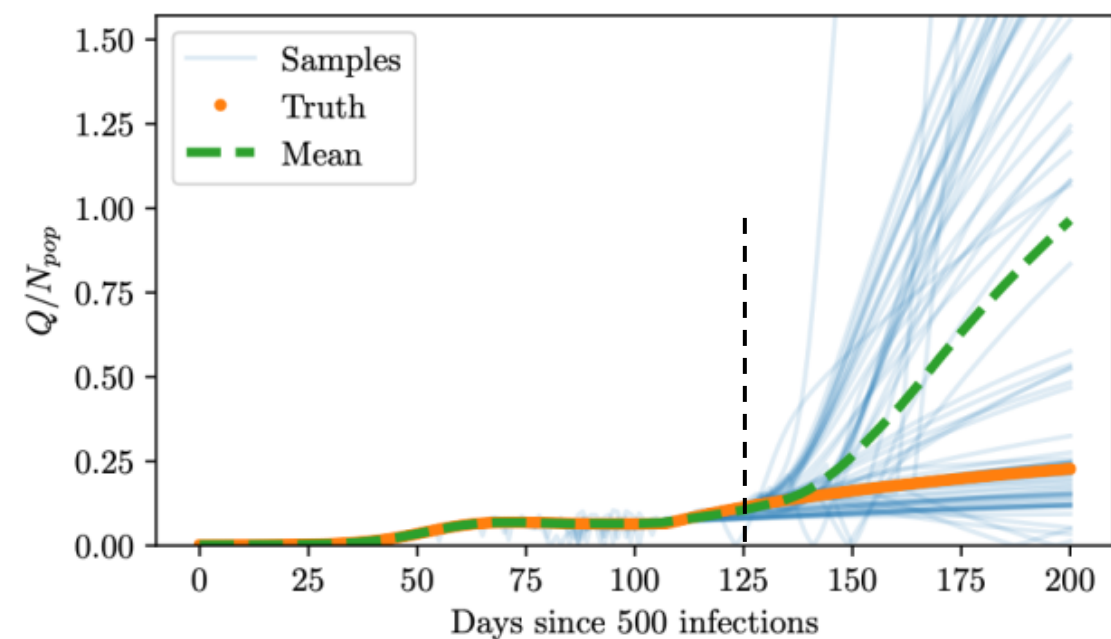


- Computed MSE of ensemble-mean (average) $\bar{Q}(t)$ vs “true” $Q^*(t)$ used to generate the data.
- Ranked data scenarios by MSE.

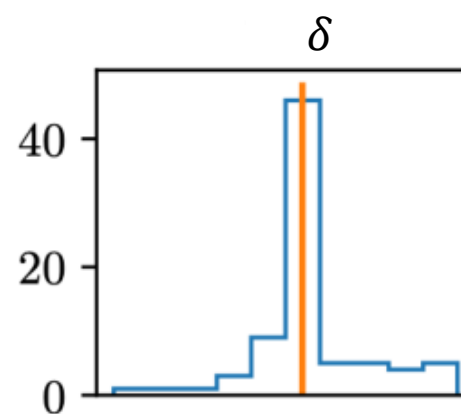
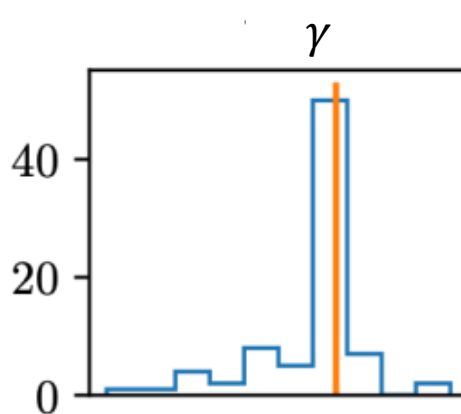
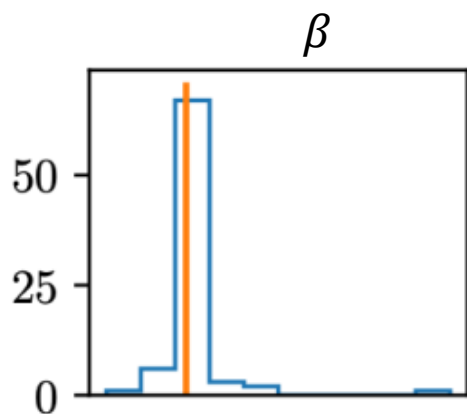


Why is this the worst case!?

Training Results, Observable States = $[R, T]$



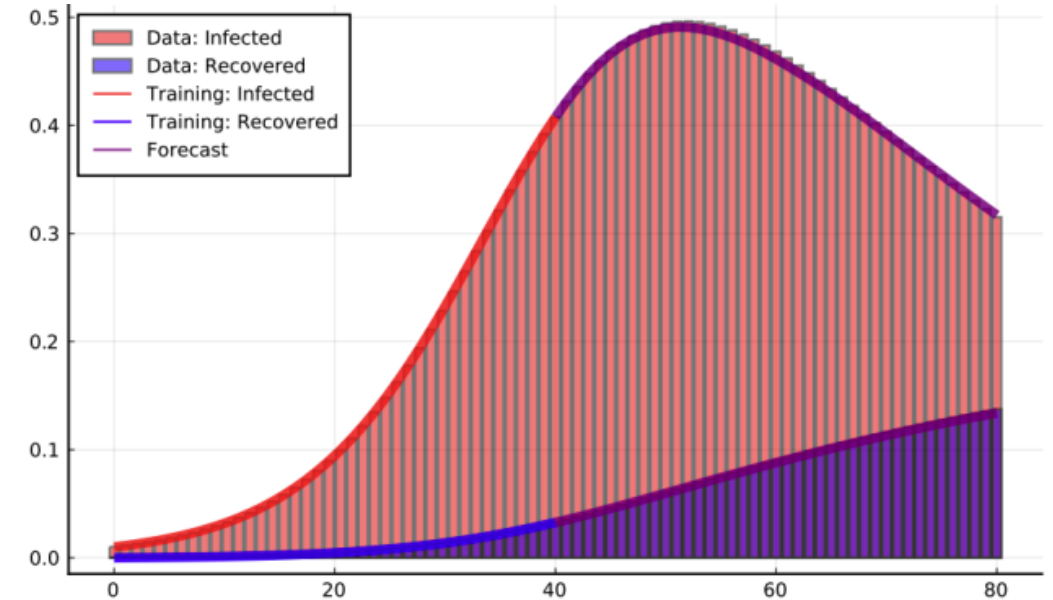
— Samples • Data — Mean



Conclusions & Future Work



- Developed a procedure to study success of UDE training when only able to observe subsets of state variables.
- Ensemble of training results provides understanding of uncertainty in inferred dynamics.
- Next steps:
 - Noisy and/or sparse data
 - Data generated from more complex model



- For more complex model must determine appropriate accuracy metric (no “true Q ” to compare to).
- Potential metric: MSE of observed state variables extrapolated beyond time horizon of training data.

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Appendix



Initial sampling of transition rate params

- Transition rate parameters are interdependent.
- Instead randomly sample independent variables and computed derived transition rates.
- For SIRHDT model, e.g., hospitalized population H can flow into R or D.
- τ_{HR}, τ_{HD} can be defined in terms of
 - r_{HR}, r_{HD} ratios of populations flowing into H and D
 - T_H - residence time in hospitalized population
- Then

$$\tau_{HR} = \frac{r_{HR}}{T_H}, \quad \tau_{HD} = \frac{r_{HD}}{T_H}$$

- Reasonable ranges to sample r_*, T_* derived from the literature and used to define distributions from which they are sampled for initial guesses to optimization.

Filtering procedure



- Computed MSE for each ensemble member, each population in the data.
- Filtered out any ensemble member whose MSE was deemed an outlier using the interquartile range (IQR) heuristic threshold:

$$Q_3 + 1.5 IQR = Q_3 + 1.5(Q_3 - Q_1)$$

where $Q_1 = 0.25$ quantile, $Q_3 = 0.75$ quantile.

