

Towards information limit in a low photon 3 dimensional x-ray imaging

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****NRL**

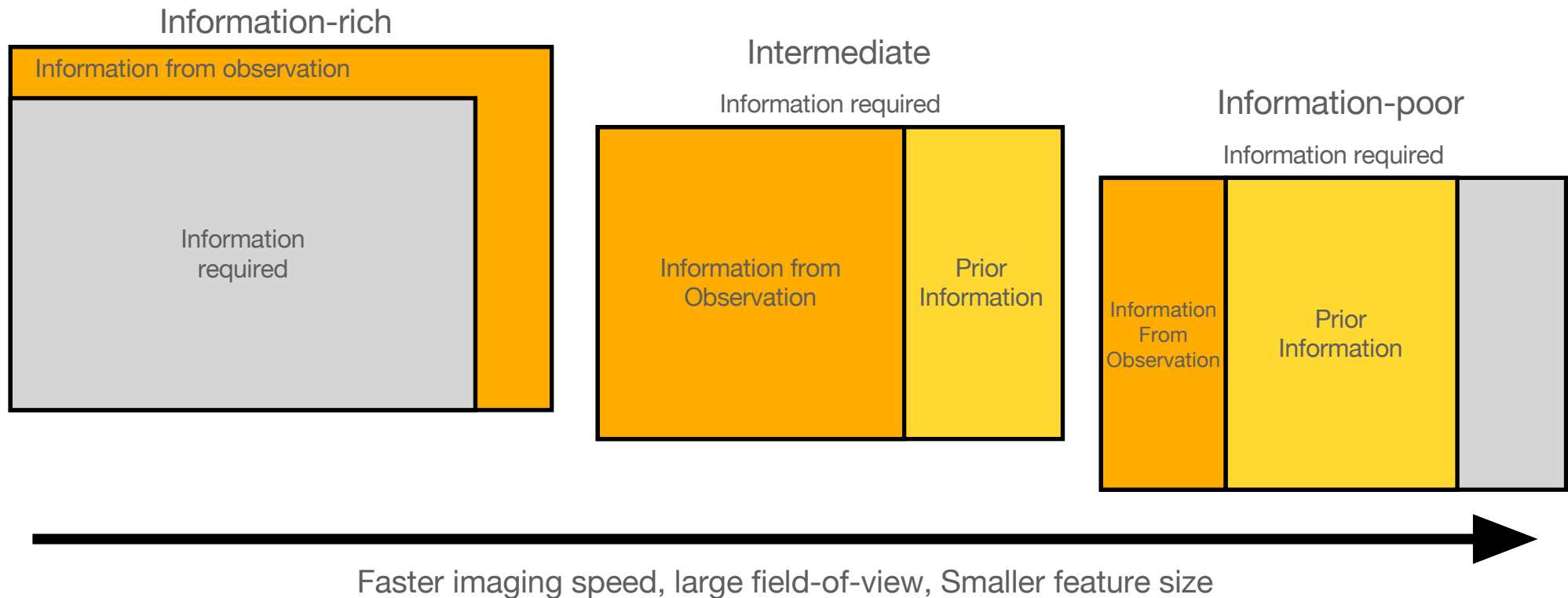
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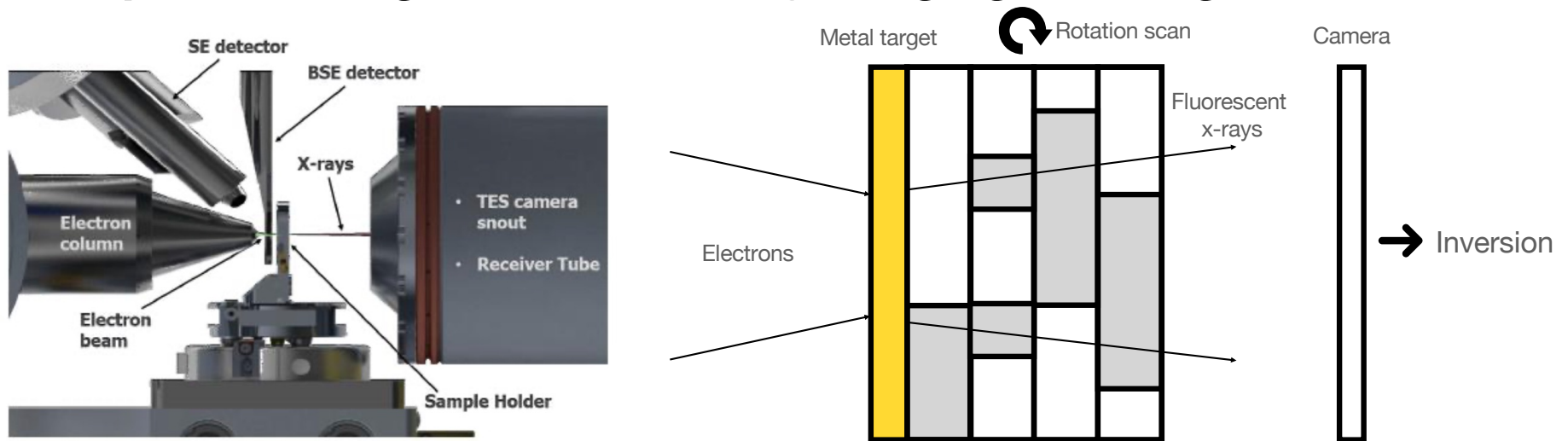
Information-based approach towards imaging

Classification of imaging problems based on information amount



Overview

Develop inverse algorithms for x-ray imaging 3D integrated circuits

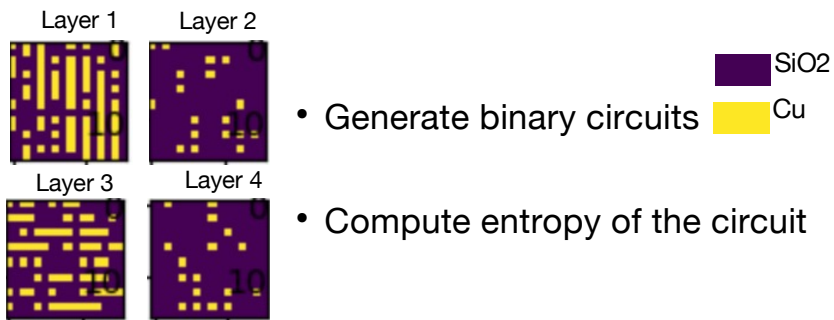


Questions to address

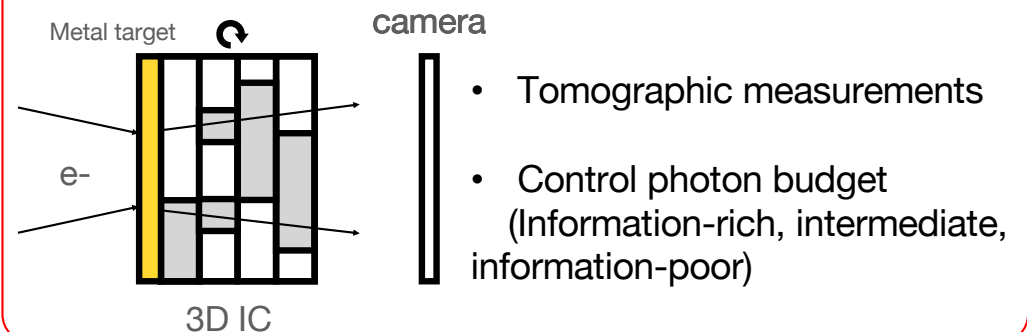
- How much information is required for 3D imaging?
- How do machine learning algorithms perform compared to classical maximum-likelihood estimation algorithm?
 - information-rich, intermediate, and information-poor
- What is an information-theoretic bound for imaging, and how can we compute it?

Research routine

Generate fake 3D circuits CircuitFaker

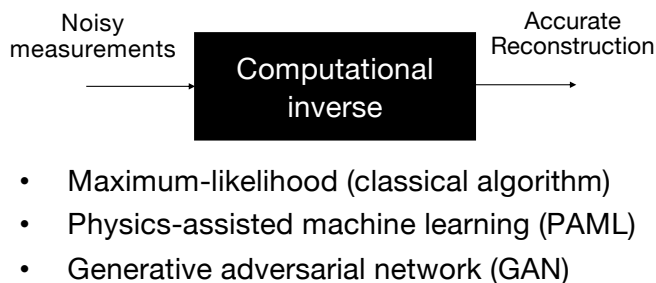


Simulate x-ray imaging of 3D integrated circuits



Acknowledgement: Dr. Courtenay Vaughn

Design inverse algorithms



Performance test (classical vs ML)

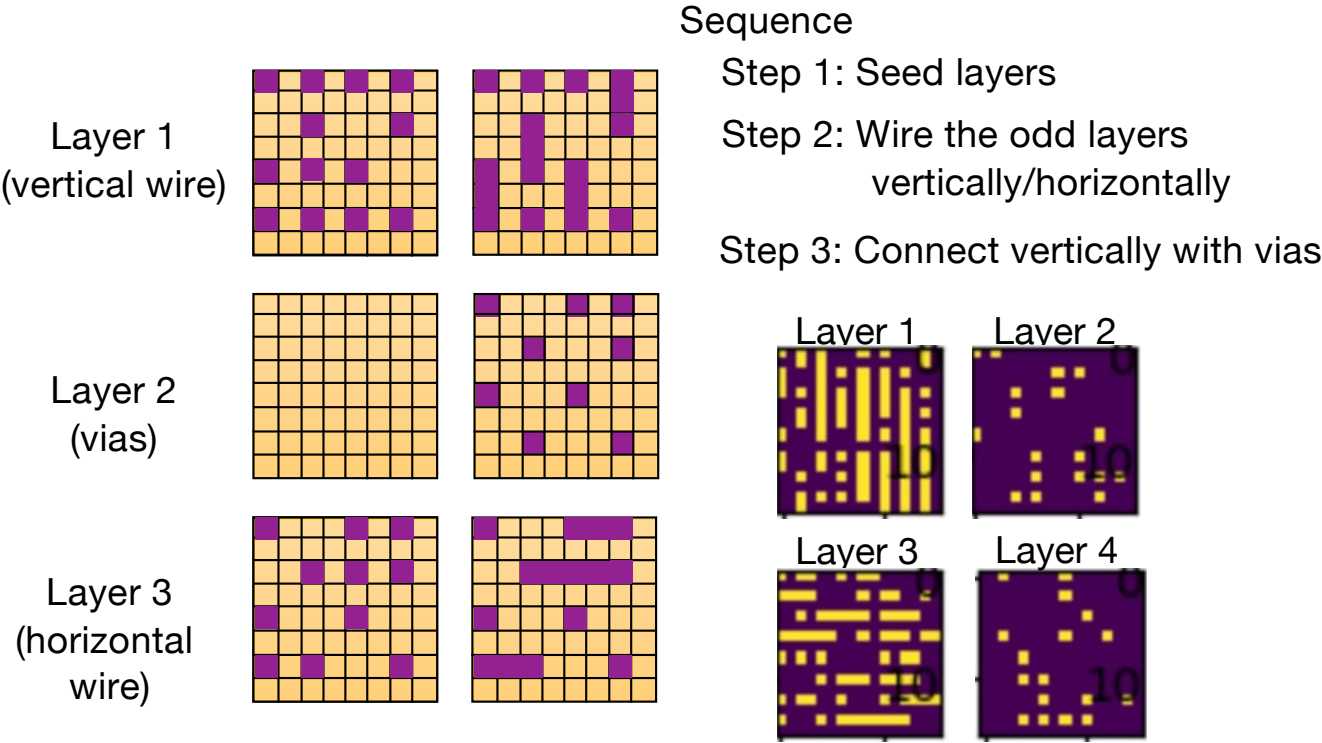
- Define evaluation criteria: bit error rate
- Compare classical vs ML algorithms
- Find information-rich, intermediate, and information-poor regime

Compute information bound

- Mutual information
- Monte Carlo approximation
- Theoretic bound in reconstruction quality at a given photon budget

CircuitFaker: generate circuit with pre-defined design rule

- Generate binary circuits (Cu or SiO2) that emulate real-world integrated circuits
- Can compute amount of information within the circuit



N Bernoulli trials

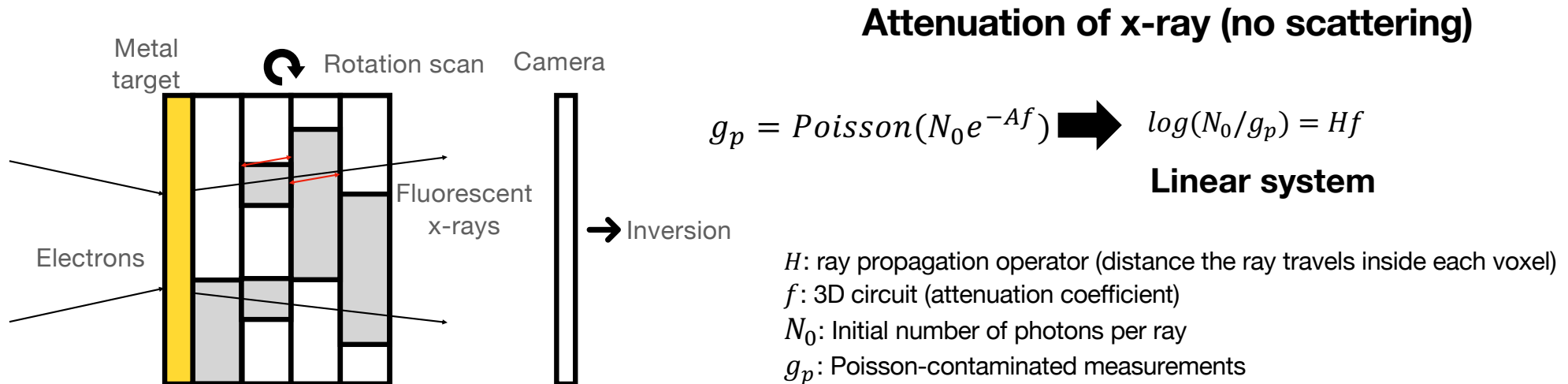
m_j Bernoulli trials
($j=x,y,z$)

Example computation

For 16 x 16 x 4 circuits according to circuitFaker

Information required 185.5 bits

Simulate x-ray imaging of 3D integrated circuit



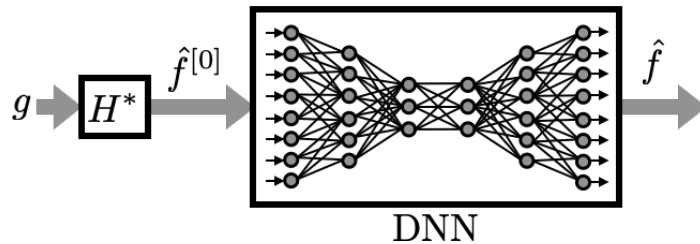
Imaging conditions

- Reduce angular scan range (reduce dimensions of g_p)
- Reduce photon budget (N_0)

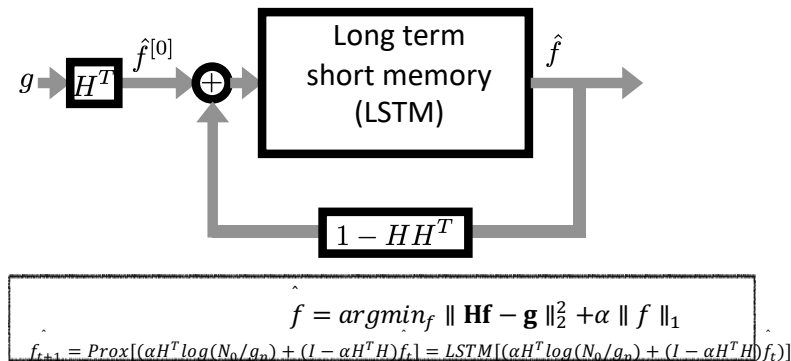
Machine learning algorithms development

Approach 1: Physics-assisted machine learning

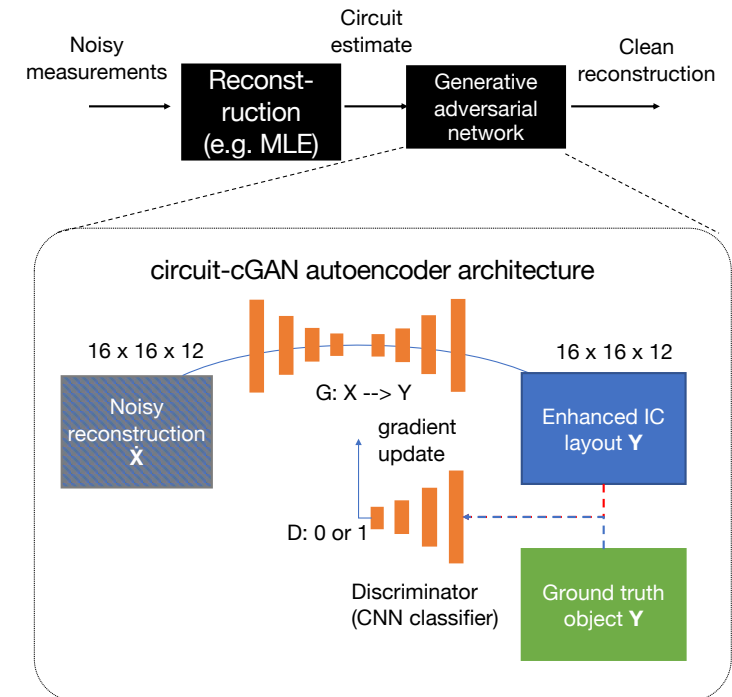
a) Approximant-based



b) Iterative shrinkage algorithm with LSTM



Reconstruction + Approach 2: generative adversarial network (GAN) denoising



Bit error rate: evaluation criteria

Frequency of wrong predictions in classifying materials in IC voxels

Maximum likelihood classifier

Step 1: Compute $p(\hat{f} = 0|\hat{f})$ and $p(\hat{f} = 1|\hat{f})$.

$p(\hat{f} = 0|\hat{f}) = p(\hat{f}|\hat{f} = 0)p_0$: Likelihood for 0

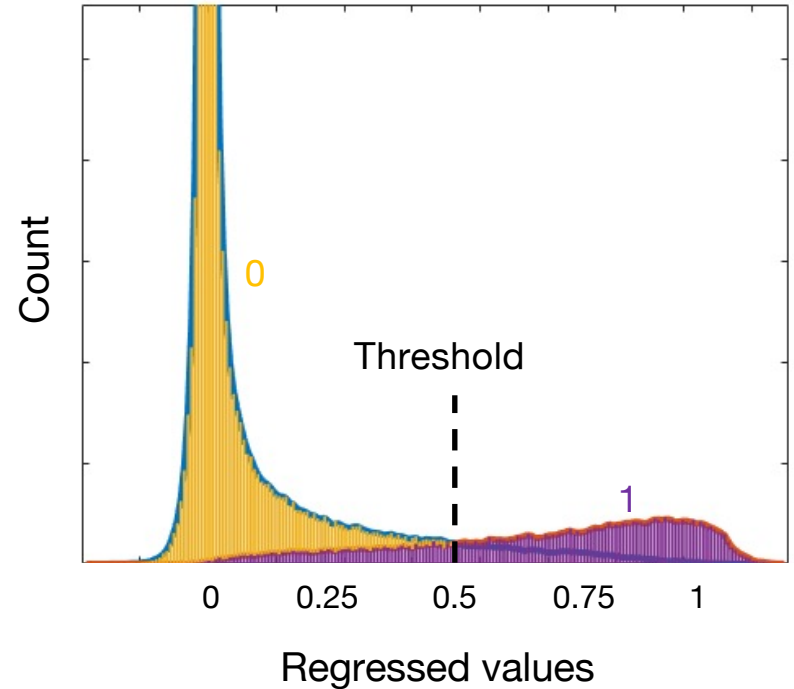
$p(\hat{f} = 1|\hat{f}) = p(\hat{f}|\hat{f} = 1)p_1$: Likelihood for 1

$p(\hat{f} = 0|\hat{f}) > p(\hat{f} = 1|\hat{f})$: Classify as 0
 p_0, p_1 : Prior distribution of 0 and 1 in ICs

$p(\hat{f} = 0|\hat{f}) < p(\hat{f} = 1|\hat{f})$: Classify as 1

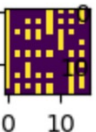



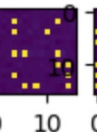




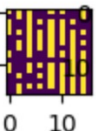
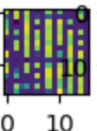
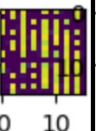
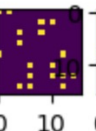

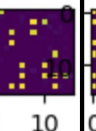
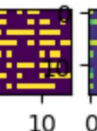
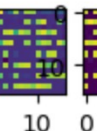

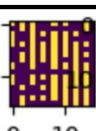
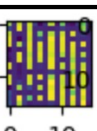
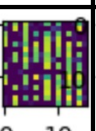
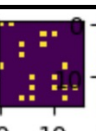
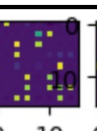
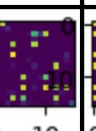
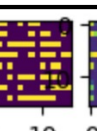
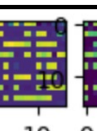
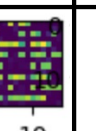


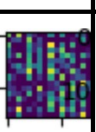
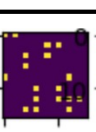
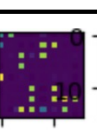
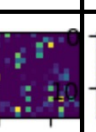

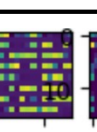
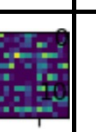

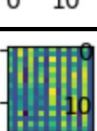


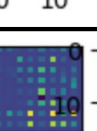


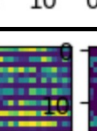

Step 2: Choose intersection point as a threshold in order to classify 0 & 1.

Step 3: Compute error rate for 0 & 1 (BER_0 and BER_1).

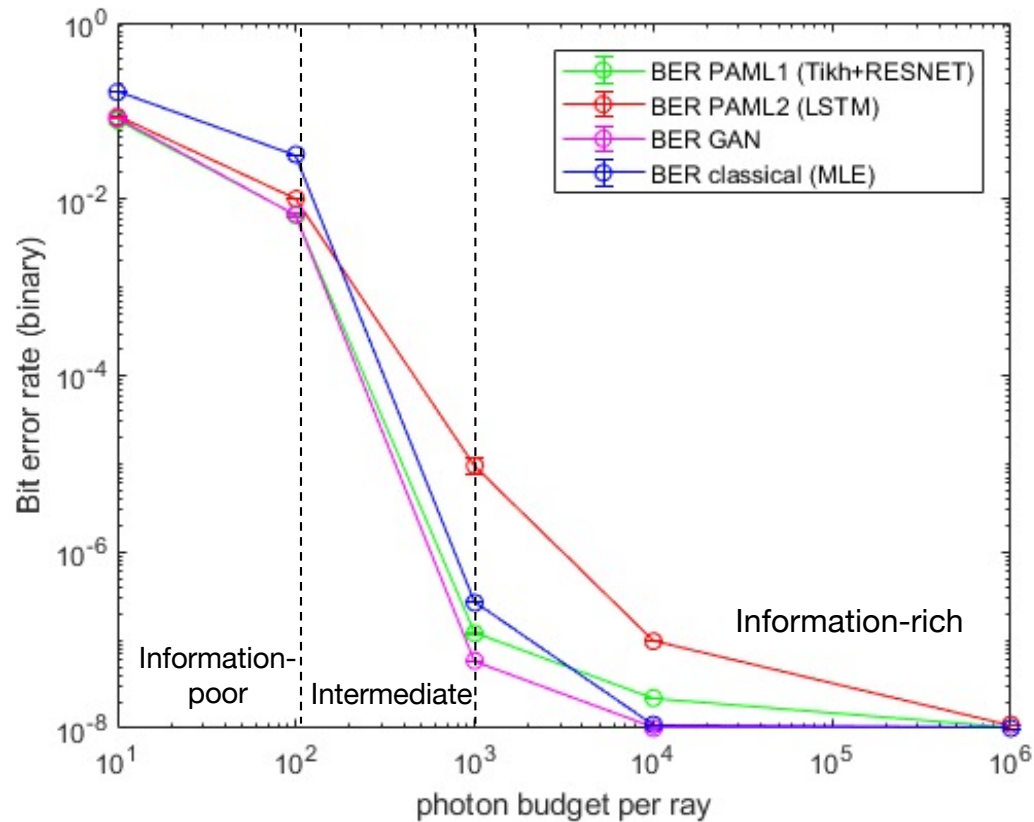


Reconstruction results

- 24 tomographic angles
- +/-90 deg

	Layer 1			Layer 2			Layer 3			Bit error rate (PAML / classical)
	Reference	PAML	Classical	Reference	PAML	Classical	Reference	PAML	Classical	
10^6 photons										1e-8 / 1e-8
10^4 photons										2.2e-8 / 1.1e-8
10^3 photons										1.2e-7 / 2.6e-7
10^2 photons										6.5e-4 / 3.2e-2
10^1 photons										7.7e-3 / 1.6e-1

Performance summary



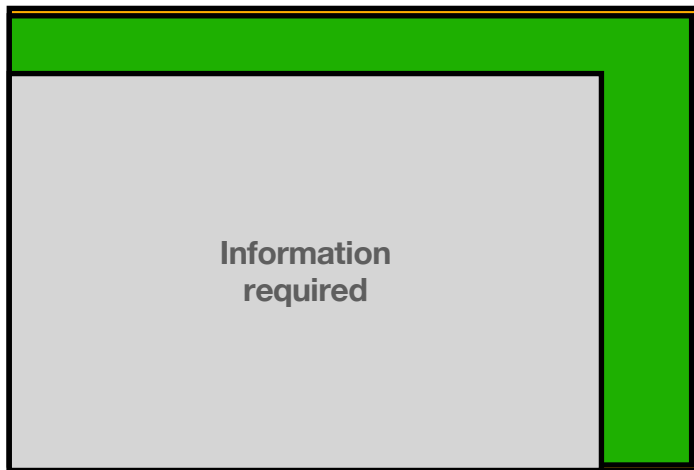
- **Information-rich:** classical maximum-likelihood and machine learning (ML) algorithms show comparable performance.
- **Intermediate:** ML starts to excel. Compromise between accuracy and dwell time
- **Information-poor:** ML algorithms show $\sim 5\times$ improved error rates at low photon budget (<100).

Information-theoretic bound for imaging

How much information can we retrieve from imaging?

Information-rich

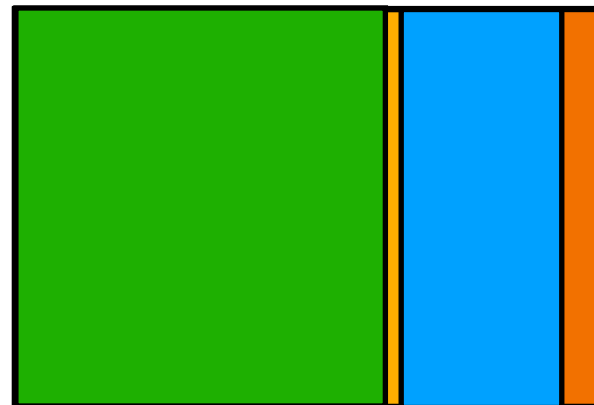
Information available from
observations



Information classical
algorithm exploits

Intermediate

Information available = Information from observation + Prior Information

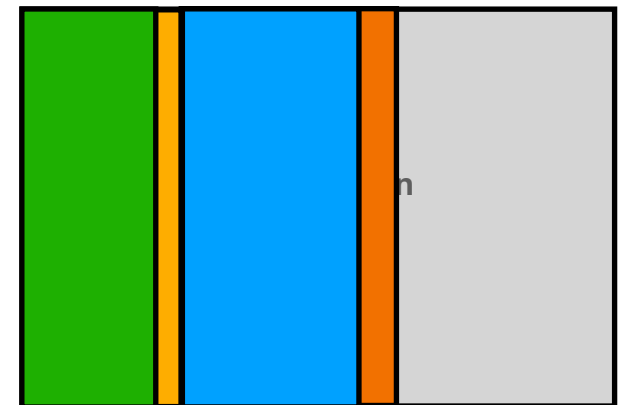


Information classical
algorithms exploit

Additional "prior"
information used by ML

Information-poor

Information from Observation + Prior Information = Information available



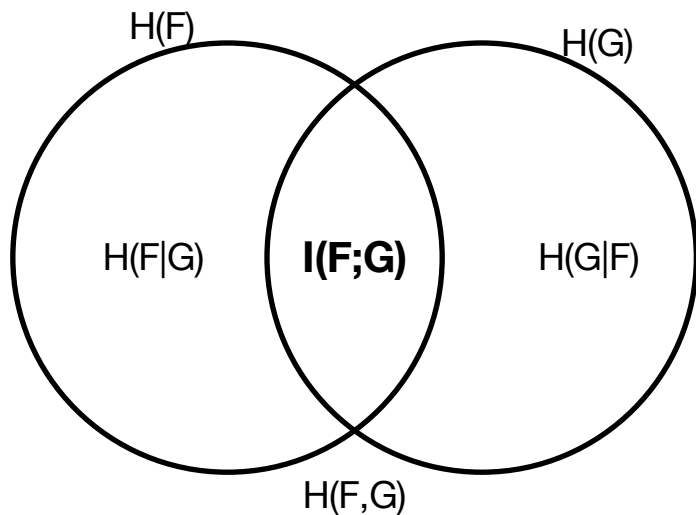
Information classical
algorithms exploit

Additional "prior"
information used by ML

How can we compute total amount of "available information"?

Information-theoretic bound for imaging

Mutual information



- $C = I(F; G) = H(F) - H(F|G)$
 $= I(G; F) = H(G) - H(G|F)$
- $H(F)$: Entropy, total amount of information to be retrieved in 3D circuits
- $H(F|G)$: Conditional entropy
 $H(F|G) = 0$: Perfect imaging (measurement G fully retrieves information in F)
 $H(F|G) > 0$: Imperfect imaging (measurement G can't fully retrieved information in F)

Residual uncertainty:

$$1 - \frac{I(F; G)}{H(F)}$$

$$= 1 - \frac{2018}{1855} = 0.895$$

16 x 16 x 11 rays
 +/-75 deg
 100 photons

Information
 Available: 120.8 bits

16 x 16 x 4 circuit
 Information required: 185.5 bits

Computation of $I(G; F) = H(G) - H(G|F)$

Monte Carlo approximation

$H(G|F)$

Known from CircuitFaker

Approximate
With Monte Carlo

$$H(G|F) = \sum_f H(G|F = f)p(f)$$

$$= E_f[H(G|F = f)] \sim$$

$$\frac{1}{N_{sample}} \sum_{f_{MCsample}} H(G|F = f)$$

Conditional entropy for N independent Poisson pdf's
(N: pixel counts)

For loop:

Sample circuit, f

Compute conditional entropy $H(G|F = f)$

End

Average over $H(G|F = f)$ to compute $H(G|F)$

$H(G)$

Nested for-loops

Inner loop: compute $p(g)$ with Monte Carlo

$$p(g) = \sum_f p(g|f)p(f) = E_f[p(g|f)] \sim \frac{1}{N_{MC}} \sum_i p(g|f_i)$$

Outer loop: compute $H(g)$ with Monte Carlo

$$H(G) = -\sum_g p(g) \log p(g) = -E_g[\log p(g)]$$

Outer for-loop:

Inner for-loop:

1. sample f

2. compute $p(g|f)$'s using sampled f

end

Average over $p(g|f)$ to compute $p(g)$ (Bayes' rule + MC integration)

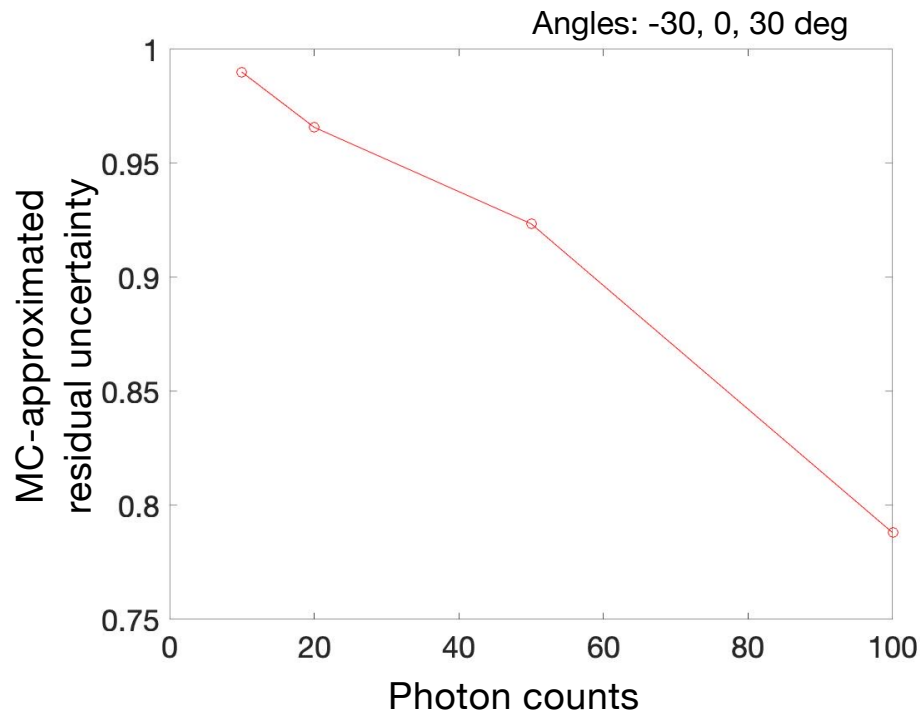
end

Average of $-\log(p(g))$'s to compute $H(g)$ (MC integration)

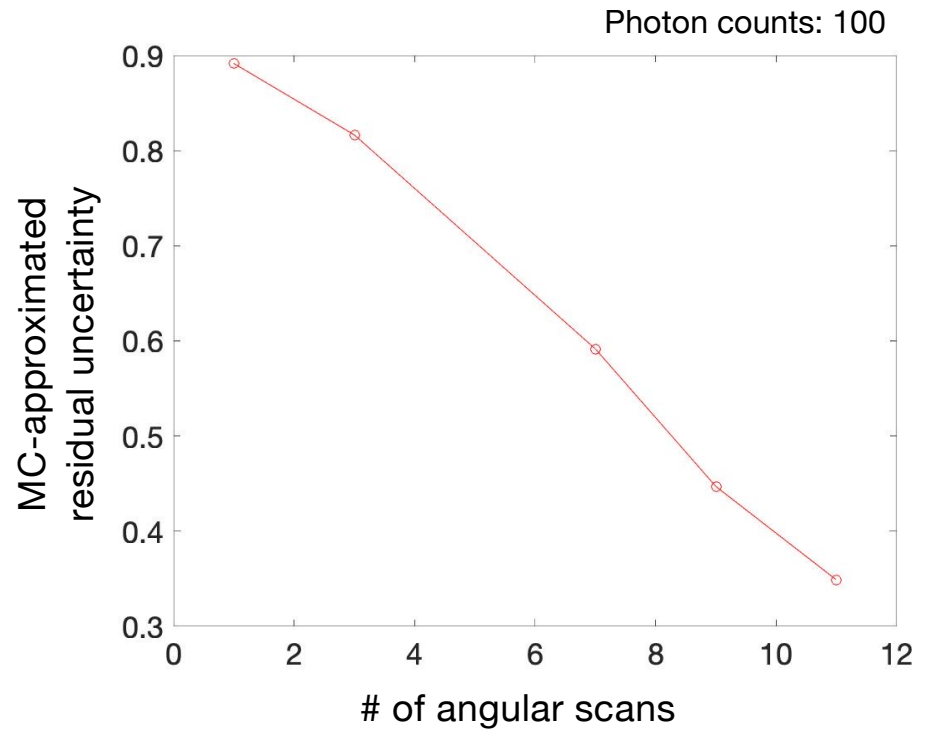
Example computation

Theoretical bound for BER in reconstruction of $16 \times 16 \times 4$ circuits

1) Changing photon counts



2) Changing number of scan



Summary

- Categorized imaging problem according to amount of information available: information-rich, intermediate, and information-poor.
- In information-rich regime, no gain from using ML compared to maximum-likelihood algorithm.
- In information-poor regime, ML excels maximum-likelihood algorithm by exploiting prior information, but not accurate enough for practical use.
- In intermediate regime, ML help reduce efforts in observations (e.g. reduce scan time) without compromising accuracy and practicality.
- Information-theoretic bound can be computed using mutual information and Monte Carlo approximation.