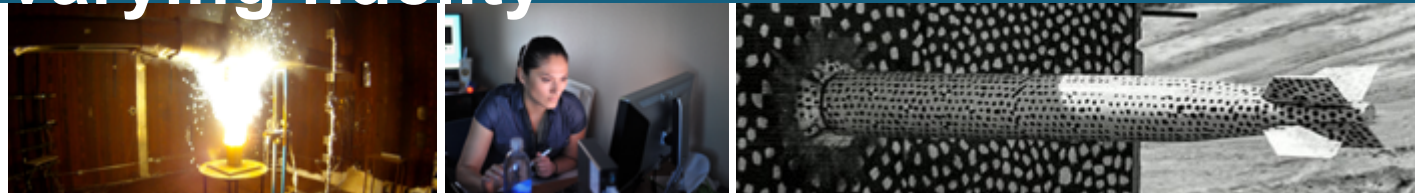


Adaptive resource allocation for surrogate modeling of systems comprised of multiple disciplines with varying fidelity



John Jakeman Sandia National Laboratories

Samuel Friedman (TAMU), Michael Eldred (SNL),
Lorenzo Tamellini (CNR-IMARTI), Alex Gorodetsky
(UMich), Doug Allaire (TAMU)

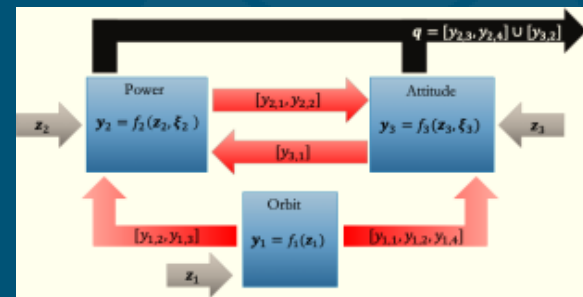
IX International Conference on Coupled Problems in
Science and Engineering

PROBLEM SUMMARY



Goal:
UQ of coupled
systems

OUTER-LOOP
PROCESS



PROBLEM SUMMARY

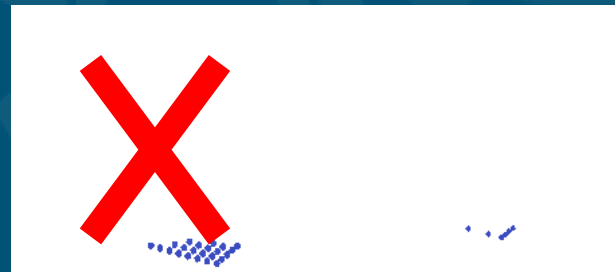
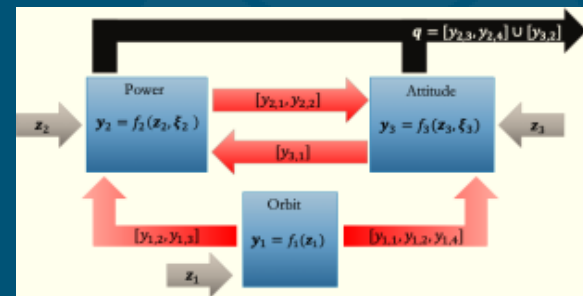


Goal:
UQ of coupled
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OUTER-LOOP
PROCESS

Challenge:
Expensive models
intractable

OUTER-LOOP
PROCESS



PROBLEM SUMMARY



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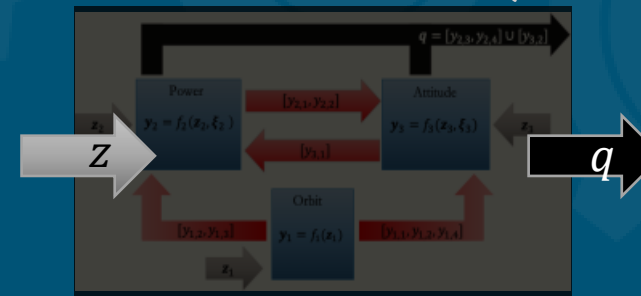
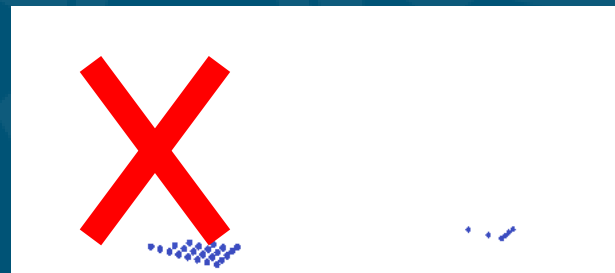
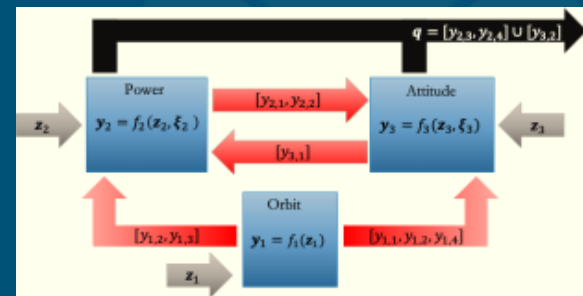
OUTER-LOOP
PROCESS

Challenge:
Expensive models
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OUTER-LOOP
PROCESS

Existing approach:
Black-box surrogate

OUTER-LOOP
PROCESS



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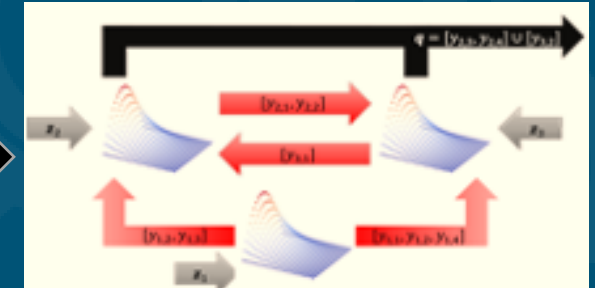
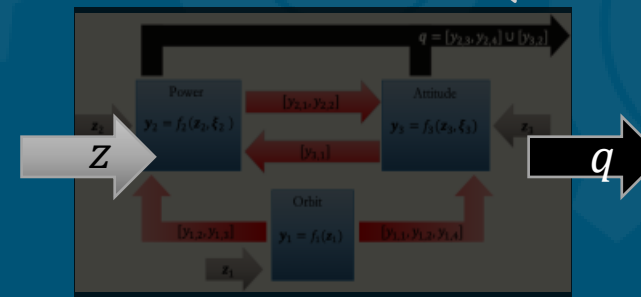
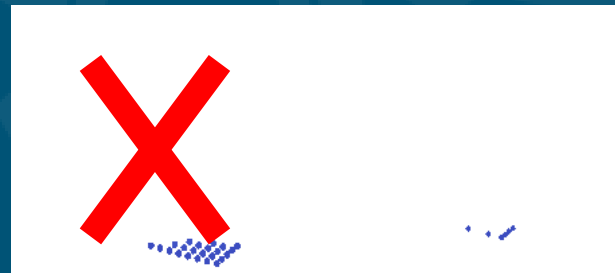
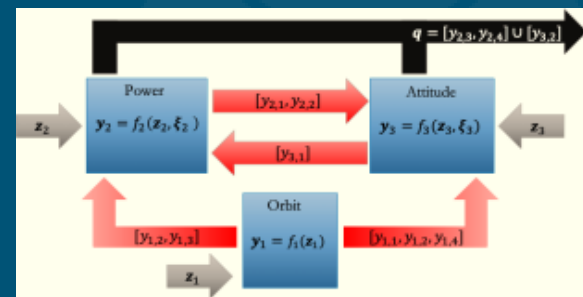
OUTER-LOOP
PROCESS

Existing approach:
Black-box surrogate

OUTER-LOOP
PROCESS

Novel solution:
Build surrogates of
components

OUTER-LOOP
PROCESS



Outcome:
Reduce cost by 10-100X

PROBLEM SETUP



Map from system parameters to all outputs $\mathbf{y} = f(\mathbf{z}) : \Gamma \rightarrow \Upsilon$

Collection of all system parameters $\mathbf{z} = (z_1, \dots, z_D)^T \in \Gamma \subseteq \mathbb{R}^D$

System comprised of K Components

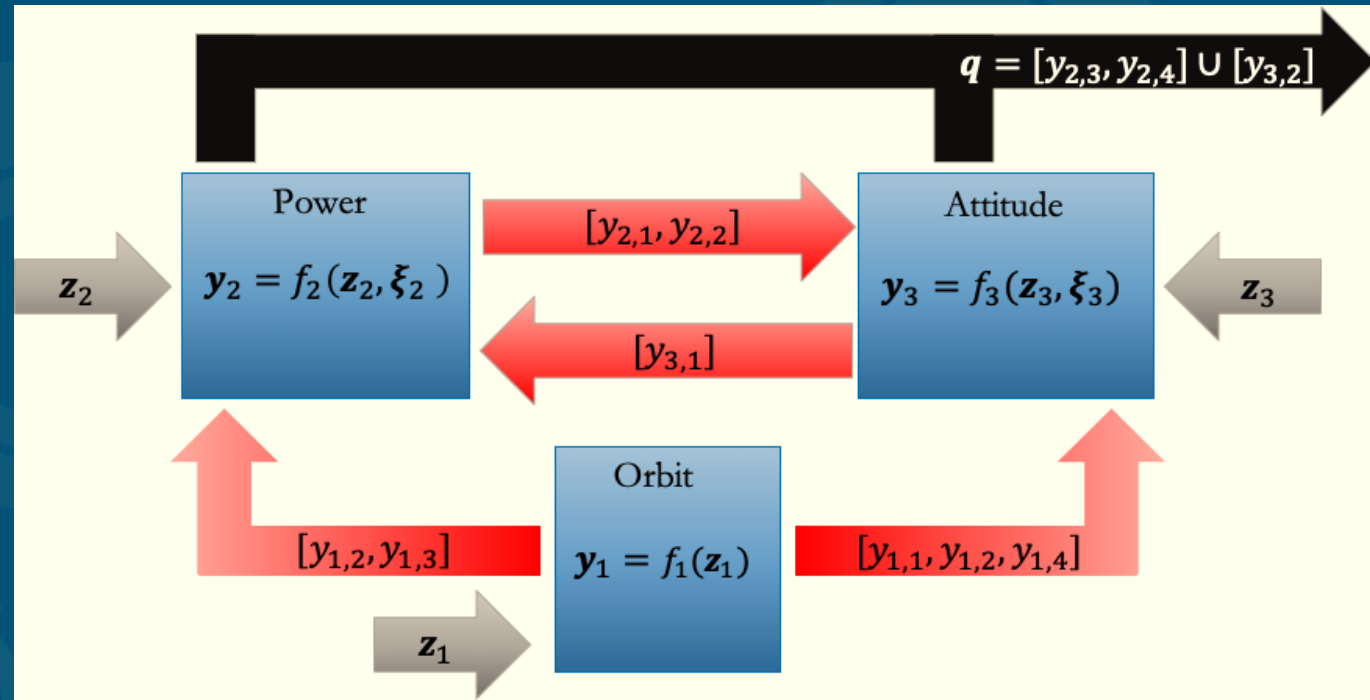
$$\mathbf{y}_k = f_k(\mathbf{z}_k, \boldsymbol{\xi}_k) : \Gamma_k \times \Xi_k \rightarrow \Upsilon_k,$$

Components have subset of system

variables

$$\mathbf{z}_k = \mathbf{R}_k \mathbf{z} \in \mathbb{R}^{D_k} \quad \boldsymbol{\xi}_k = \mathbf{R}_k^\xi \mathbf{y} \in \mathbb{R}^{S_k}$$

Denote evaluation of system via the functional $G_z : (f_1, \dots, f_K) \mapsto f(\mathbf{z})$.



Goal to predict subset of system outputs

$$\mathbf{q} = \mathbf{R}^y \mathbf{y} \in \mathbb{R}^{Q^{\text{sys}}}$$

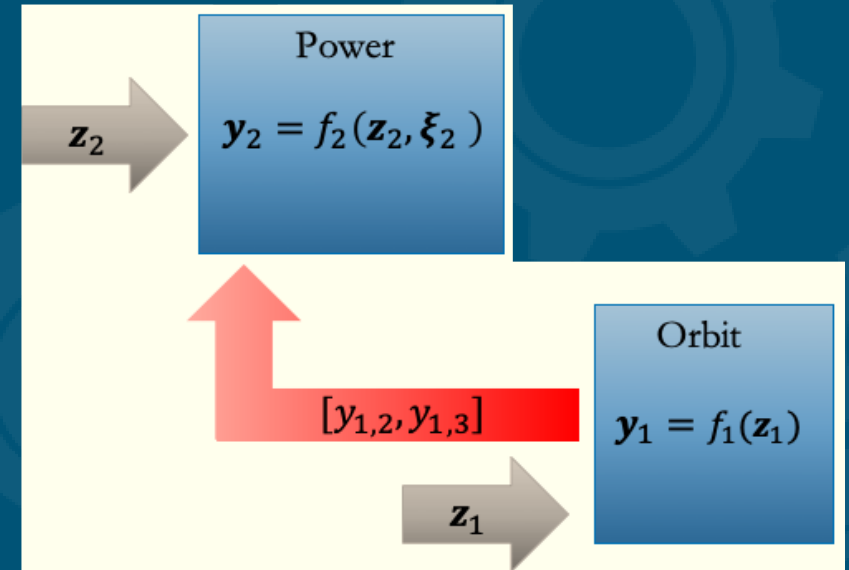
EVALUATING SYSTEMS OF COMPONENTS



Feed-forward coupling

$$\mathbf{y}_k = f_k(\mathbf{z}_k, \boldsymbol{\xi}_k) \quad \boldsymbol{\xi}_k = \mathbf{y}_{k-1} = f_{k-1}(\mathbf{z}_{k-1}),$$

Simply pass output \mathbf{y}_{k-1} as input to f_k

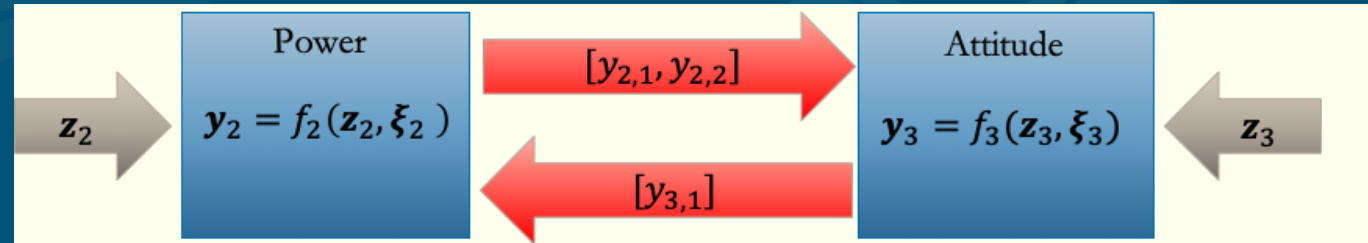


EVALUATING SYSTEMS OF COMPONENTS



Feedback-coupling

$$\begin{cases} \mathbf{y}_j = f_j(\mathbf{z}_j, \boldsymbol{\xi}_j), & \boldsymbol{\xi}_j = \mathbf{y}_k \\ \mathbf{y}_k = f_k(\mathbf{z}_k, \boldsymbol{\xi}_k), & \boldsymbol{\xi}_k = \mathbf{y}_j \end{cases}$$



Use iteration function

$$F(\boldsymbol{\xi}) = \begin{bmatrix} f_j(\mathbf{z}_j, \boldsymbol{\xi}_j) \\ f_k(\mathbf{z}_k, \boldsymbol{\xi}_k) \end{bmatrix} \quad \boldsymbol{\xi} = [\boldsymbol{\xi}_j, \boldsymbol{\xi}_k]^\top$$

Starting from $\boldsymbol{\xi}^0$ we iterate until

$$\boldsymbol{\xi}^t = F(\boldsymbol{\xi}^{t-1}) \quad \|\boldsymbol{\xi}^t - \boldsymbol{\xi}^{t-1}\| < \nu$$

MODEL FIDELITY



Often models of varying fidelity (accuracy and cost) are available for a component

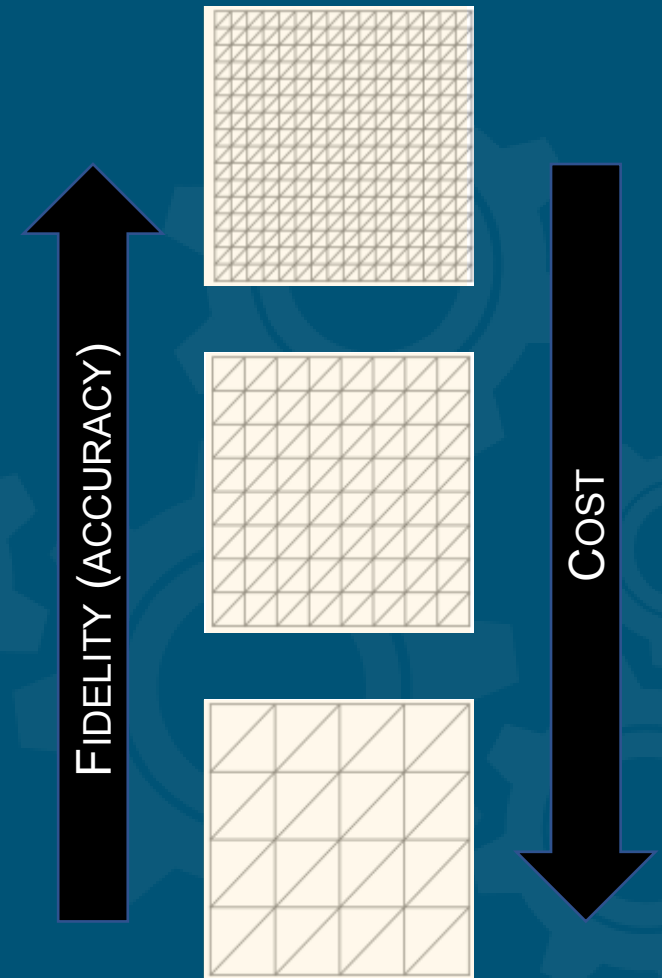
Assume models have hyper-parameters, e.g. mesh size, time-step, convergence tolerance, etc.

$$\alpha = (\alpha_1, \dots, \alpha_{R_k}) \in \mathbb{N}^{R_k}$$

Assume error decreases with fidelity

$$\|J_{k, \alpha^*} - J_k\| \leq \|J_{k, \alpha} - J_k\| \quad \alpha^* \geq \alpha,$$

System prediction accuracy depends on component fidelity



SURROGATE MODELING



Surrogates can reduce cost of using high-fidelity components

$$f_{k, [\alpha, \beta]}(\mathbf{u}_k) \approx f_k(\mathbf{u}_k)$$

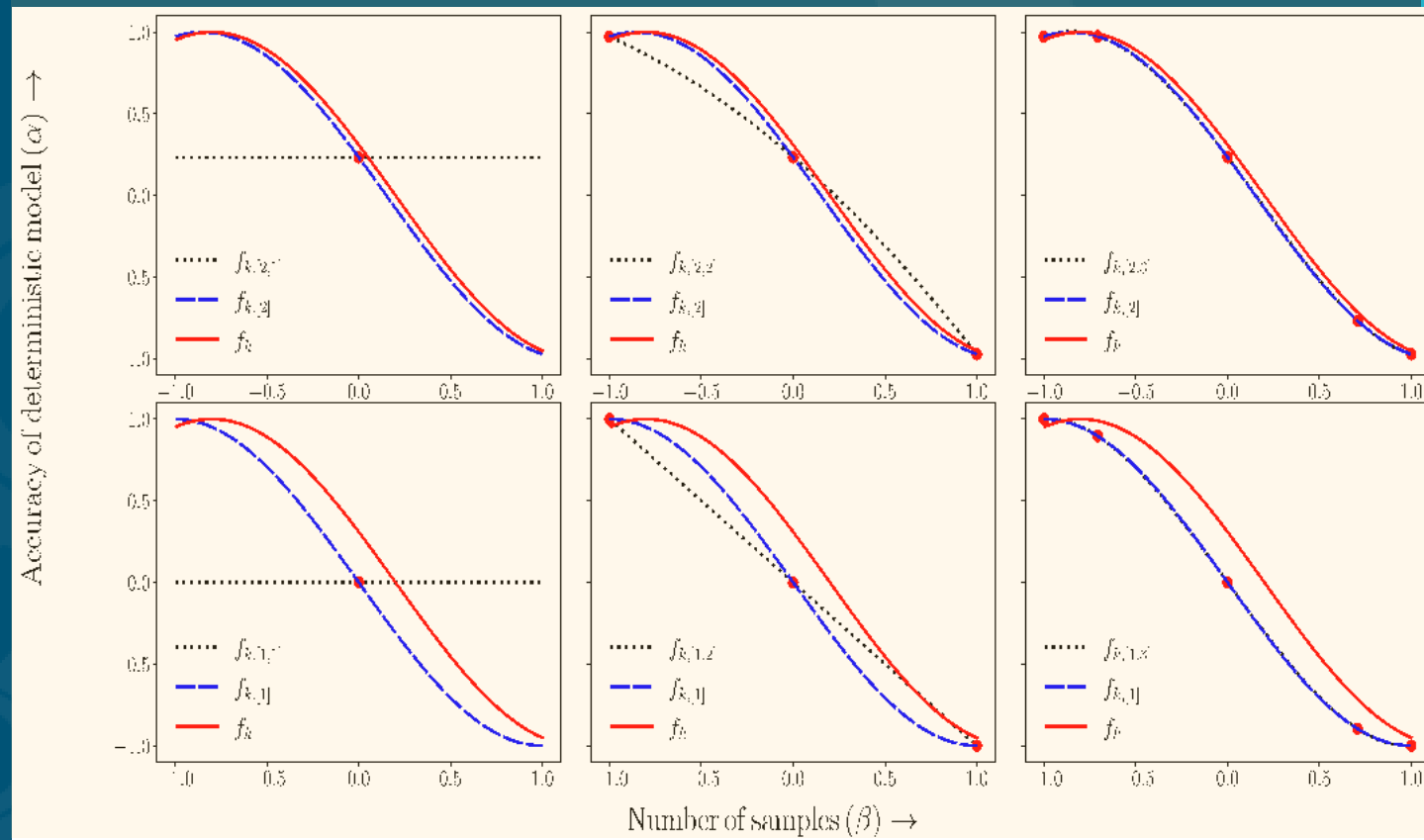
$$\mathbf{u}_k := [\mathbf{z}_k^\top, \boldsymbol{\xi}_k^\top]^\top$$

Use training data

$$\mathcal{U}_{k, \beta} = \left\{ \mathbf{u}_k^{(m)} \right\}_{m=1}^M$$
$$\left\{ f_{k, \alpha}(\mathbf{u}_k^{(m)}) \right\}_{m=1}^M$$

Error depends on fidelity α and surrogate error β

$$\|f_k - f_{k, [\square, \beta]}\| \leq \|f_k - f_{k, \square}\| + \|f_{k, \square} - f_{k, [\square, \beta]}\|$$



CHARACTERIZING THE COUPLING VARIABLES



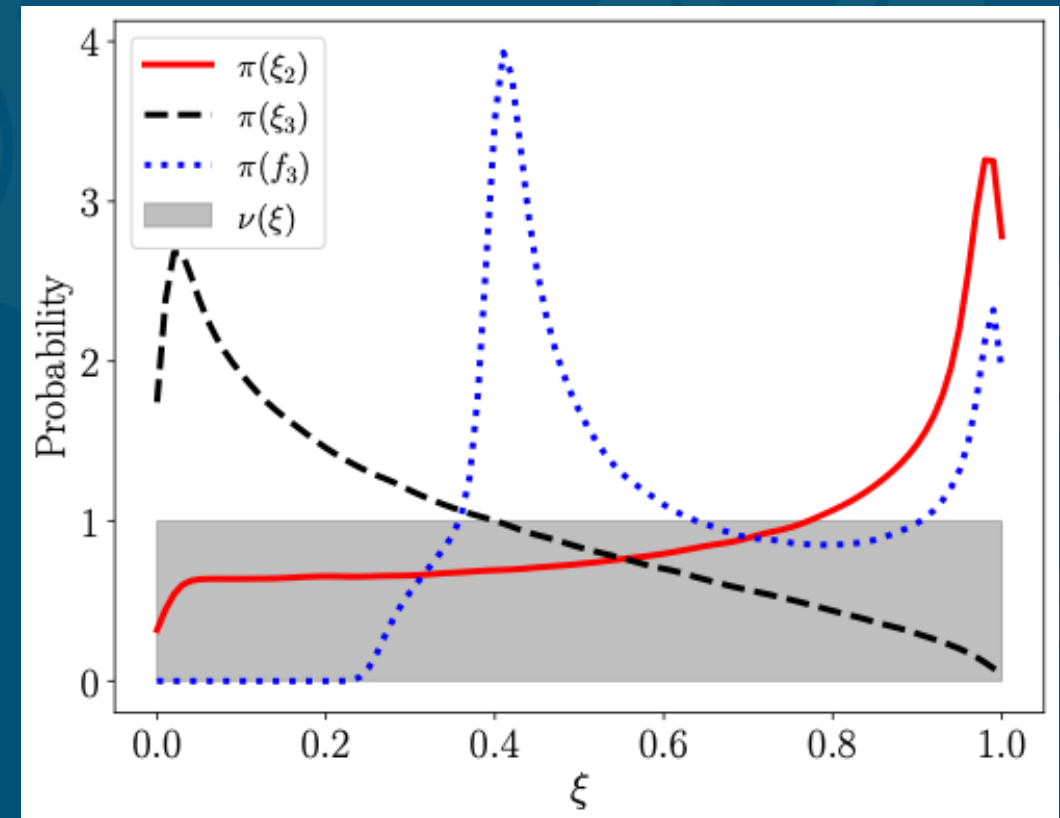
We must specify the ranges of the coupling variables.

$$\mathbf{y}_k = f_k(\mathbf{z}_k, \xi_k)$$

The ranges of the coupling variables are unknown a priori

The estimated range of the coupling variables matters

The distribution of the coupling variables matters a lot less



CHARACTERIZING THE COUPLING VARIABLES

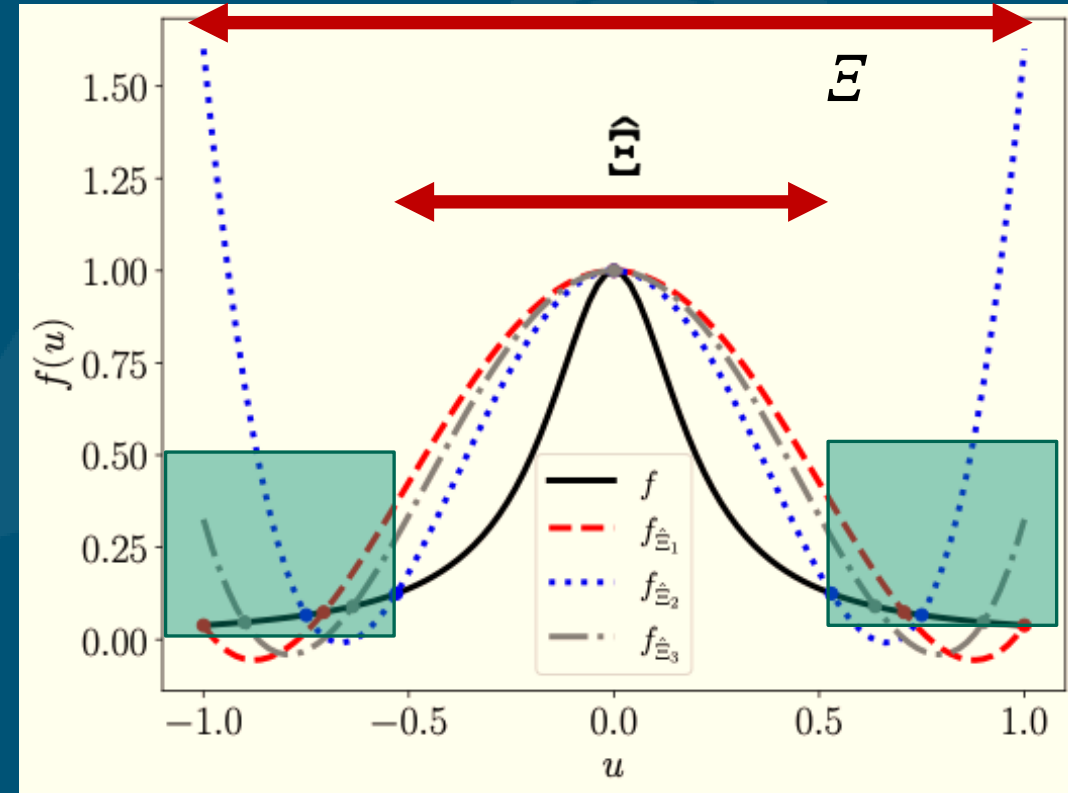


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Lemma 3.1 (Strong convergence [9]).

Let $\mu: \hat{\Omega} \rightarrow \mathbb{R}$ and $\nu: \Omega \rightarrow \mathbb{R}$ denote two densities which satisfy

$$\delta = 1 - \int_{\hat{\Omega}} \nu(u) du$$



CHARACTERIZING THE COUPLING VARIABLES



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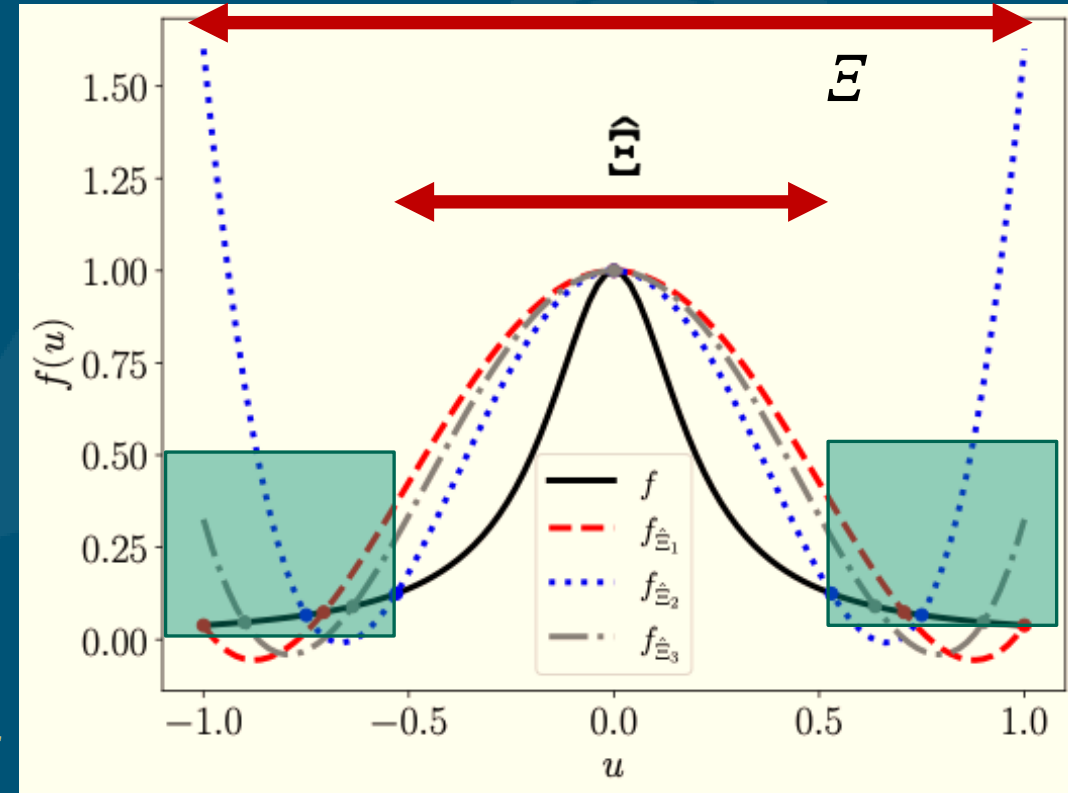
$$\delta = 1 - \int_{\Omega \setminus \hat{\Omega}} \nu(u) du$$

Given an approximation $f_{\hat{\Omega}}$ of f with approximation error ϵ , i.e.,

$$\epsilon := \|f - f_{\hat{\Omega}}\|_{L^p(\Omega)}, \quad p \geq 1,$$

then, if f is bounded with $C_f = \|f\|_{L^1(\Omega)}$, it holds that

$$\|f - f_{\hat{\Omega}}\|_{L^p(\Omega)} \leq C_r^{1/p} \epsilon + C_f \delta^{1/p}, \quad \text{provided } C_r := \max_{u \in \hat{\Omega}} \frac{\nu(u)}{\mu(u)} < 1.$$



EVALUATING SYSTEMS USING COMPONENT SURROGATES

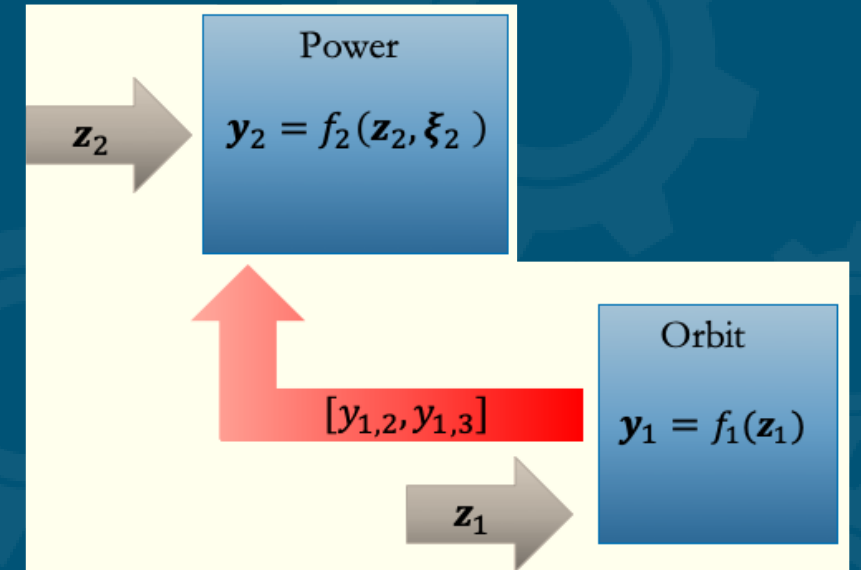
Proposition 3.1 (Feed-forward surrogate error)

Assume f_k is Lipschitz continuous. If

$$\|y_{k,q} - y_{k,\mathcal{I}_{k,q}}\|_{L^\infty(\Gamma)} \leq \epsilon_k \forall q = 1, \dots, Q,$$

and

$$f = f_{1,\mathcal{I}_1} \circ f_{2,\mathcal{I}_2} \circ \dots \circ f_{K,\mathcal{I}_K} \quad f = f_1 \circ f_2 \circ \dots \circ f_K$$



EVALUATING SYSTEMS USING COMPONENT SURROGATES



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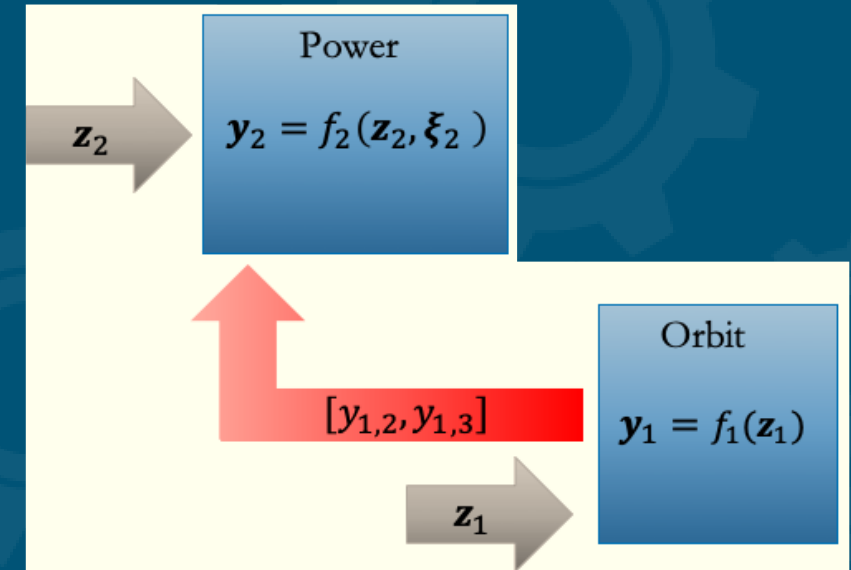
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then

$$\sup_{z \in \Gamma} \max_{q=1, \dots, Q} |f_q(z) - \hat{f}_q(z)| \leq \epsilon \frac{1 - L^K}{1 - L}$$

where $L = \max_{k=1, \dots, K} L_k$ and $\epsilon = \max_{k=1, \dots, K} \epsilon_k$.



EVALUATING SYSTEMS USING COMPONENT SURROGATES

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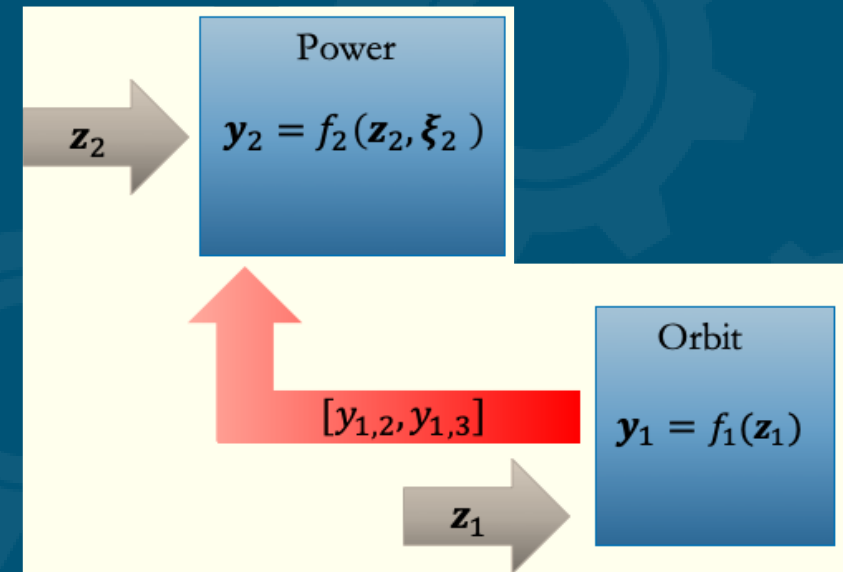
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Proof

$$\begin{aligned} \|f(z) - \hat{f}(z)\| &= \|f_K \circ \dots \circ f_1(z) - f_{K,\mathcal{I}_K} \circ \dots \circ f_{1,\mathcal{I}_1}(z)\| \\ &\leq \underline{\epsilon}_K + L_K \|f_{K-1} \circ \dots \circ f_1(z) - f_{K-1,\mathcal{I}_{K-1}} \circ \dots \circ f_{1,\mathcal{I}_1}(z)\| \\ &\leq \epsilon_K + \epsilon_{K-1} L_K + \epsilon_{K-2} L_K L_{K-1} + \dots + \epsilon_1 \prod_{k=1}^K L_k \end{aligned}$$



MULTI-INDEX STOCHASTIC COLLOCATION

Approximate each component as a linear combination of surrogates built using different model fidelities.

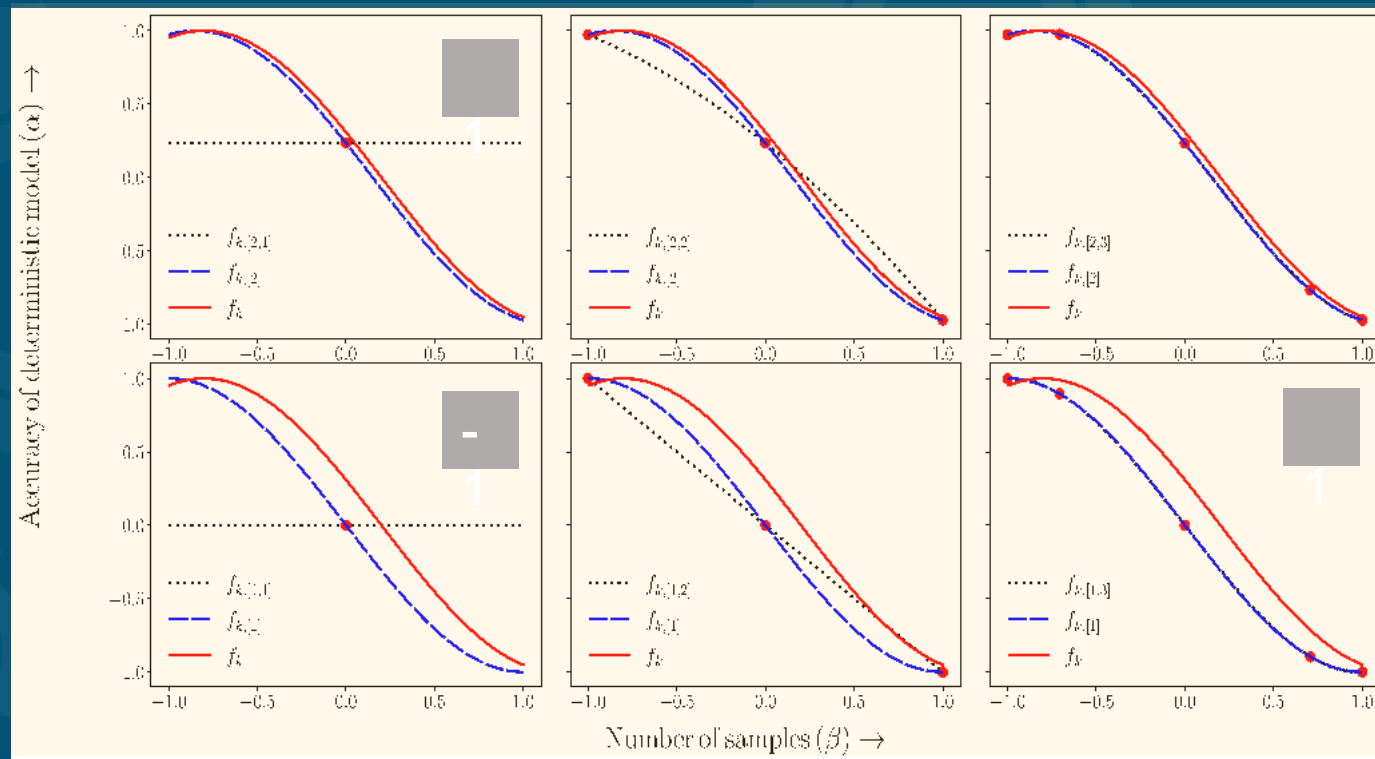
$$f(\mathbf{u}) \approx f_{\mathcal{I}}(\mathbf{u}) = \sum_{[\alpha, \beta] \in \mathcal{I}} c_{[\alpha, \beta]} f_{[\alpha, \beta]}(\mathbf{u})$$

Coefficients given by

$$c_{[\alpha, \beta]} = \sum_{\substack{[i, j] \in \{0, 1\}^{R+N} \\ [\alpha+i, \beta+j] \in \mathcal{I}_k}} (-1)^{\| [i, j] \|_1}$$

We use tensor-product interpolants for each fidelity

$$f_{[\alpha, \beta]}(\mathbf{u}) = \sum_{j \leq m(\beta)} f_{\alpha}(\mathbf{u}_{\beta}^{(j)}) \mathcal{L}_{\beta}^{(j)}(\mathbf{u}).$$

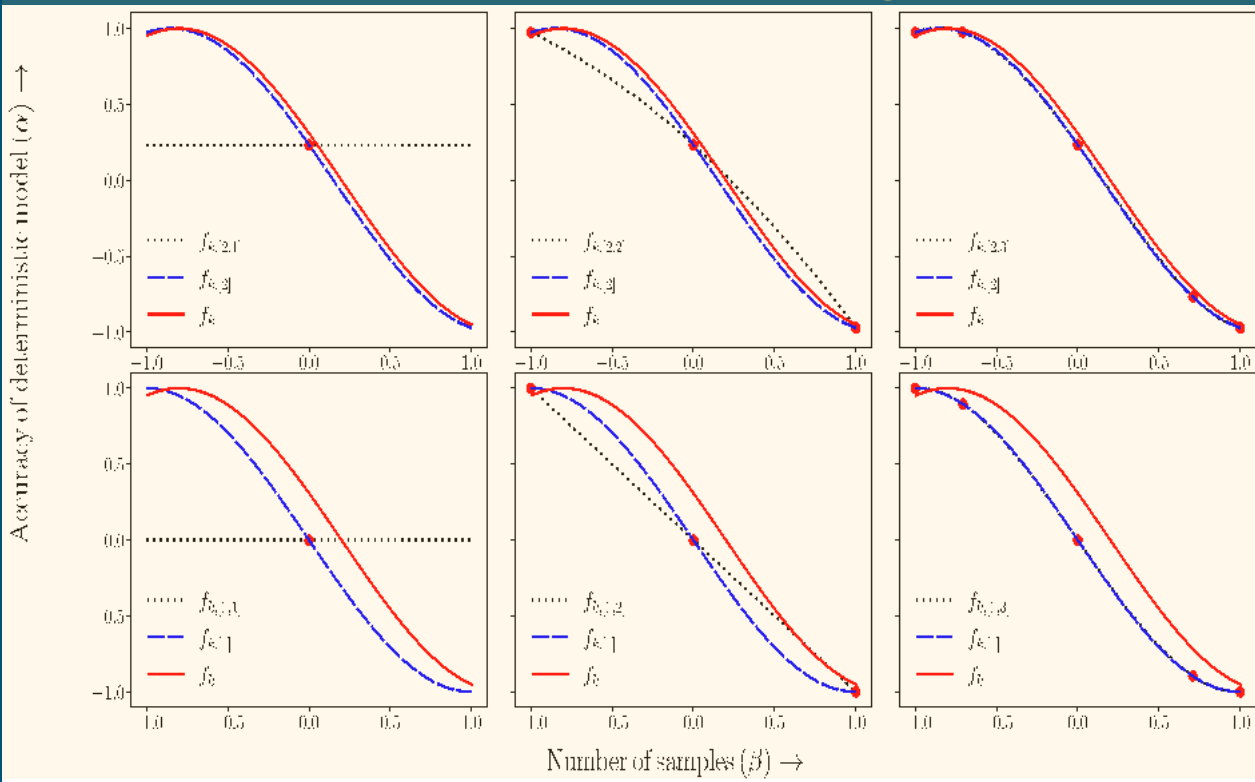


MULTI-INDEX STOCHASTIC COLLOCATION FOR A COMPONENT



Pose resource allocation as a binary knapsack problem

$$\max \sum_{[\alpha, \beta] \in \mathbb{N}_0^{n_\alpha + n_\beta}} \Delta E_{\alpha, \beta} \delta_{\alpha, \beta} \text{ such that } \sum_{[\alpha, \beta] \in \mathbb{N}_0^{n_\alpha + n_\beta}} \Delta W_{\alpha, \beta} \delta_{\alpha, \beta} \leq W_{max}$$



$\Delta E_{\alpha, \beta}$: Change in error (estimated) for each increment

$\Delta W_{\alpha, \beta}$: Change in work for each increment

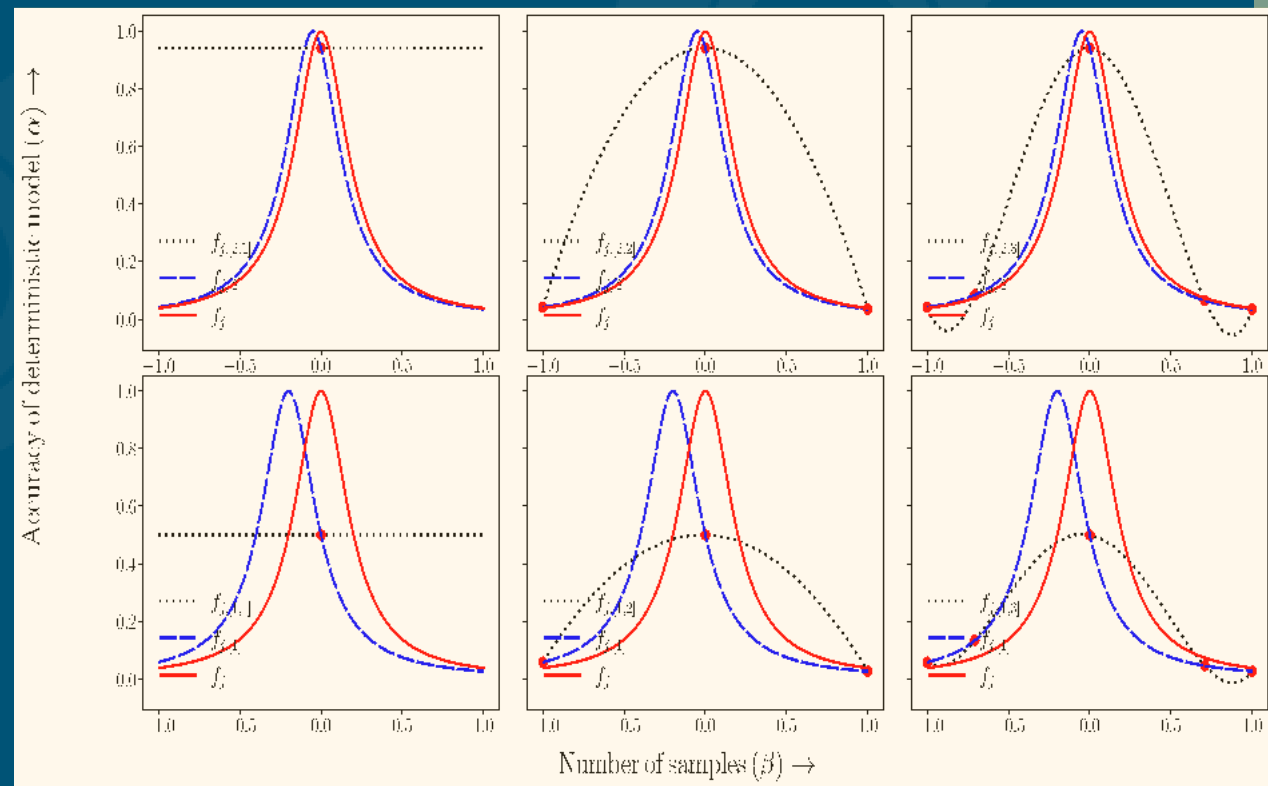
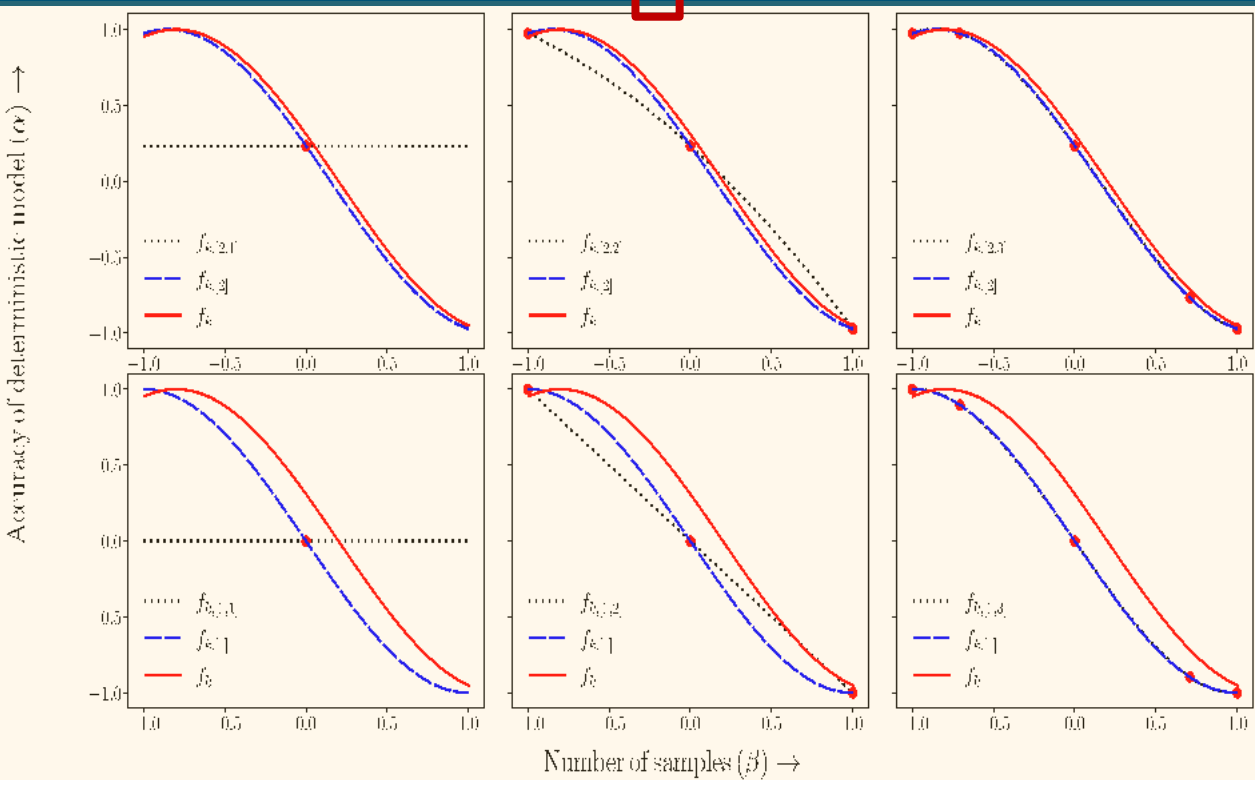
$$\gamma_{\alpha, \beta}^k = \frac{\Delta E_{[\alpha, \beta]}^k}{\Delta W_{[\alpha, \beta]}^k}$$



MULTI-INDEX STOCHASTIC COLLOCATION FOR SYSTEMS

Must choose which component to refine based on error in system QoI

$$\max \sum_{[\alpha, \beta, k]} \Delta E_{\alpha, \beta, k} \delta_{\alpha, \beta, k} \text{ such that } \sum_{[\alpha, \beta, k]} \Delta W_{\alpha, \beta, k} \delta_{\alpha, \beta, k} \leq W_{max}$$



$\Delta E_{\alpha, \beta, k}$: Change in error (estimated) for each increment

Evaluate samples at a set of samples to compute change in system QoI

$$\gamma_{\alpha, \beta}^k = \frac{\Delta E_{[\alpha, \beta]}^k}{\Delta W_{[\alpha, \beta]}^k}$$

ESTIMATING THE RANGES OF THE COUPLING VARIABLES



Interpolants built on tensor product of 1D Leja sequences

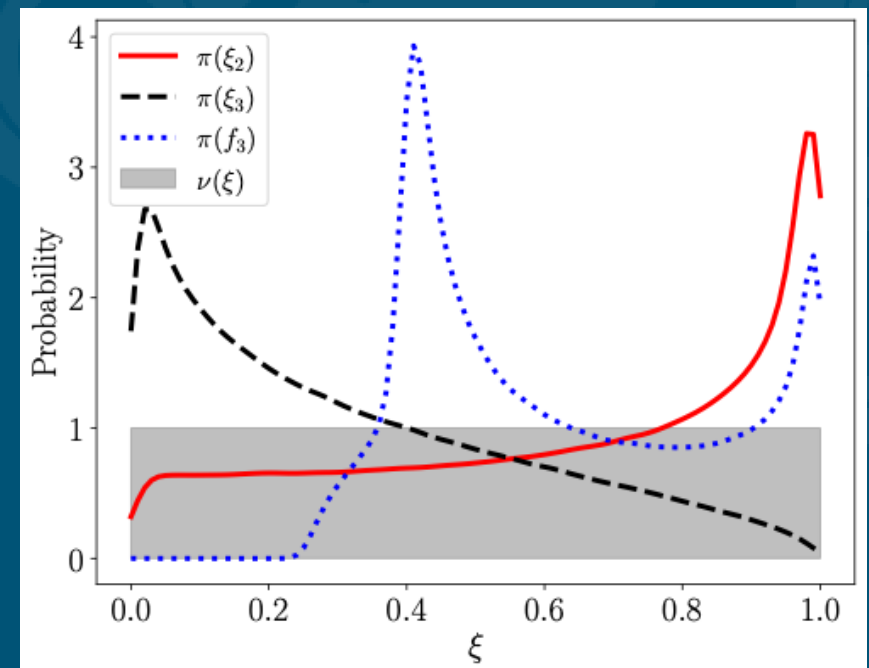
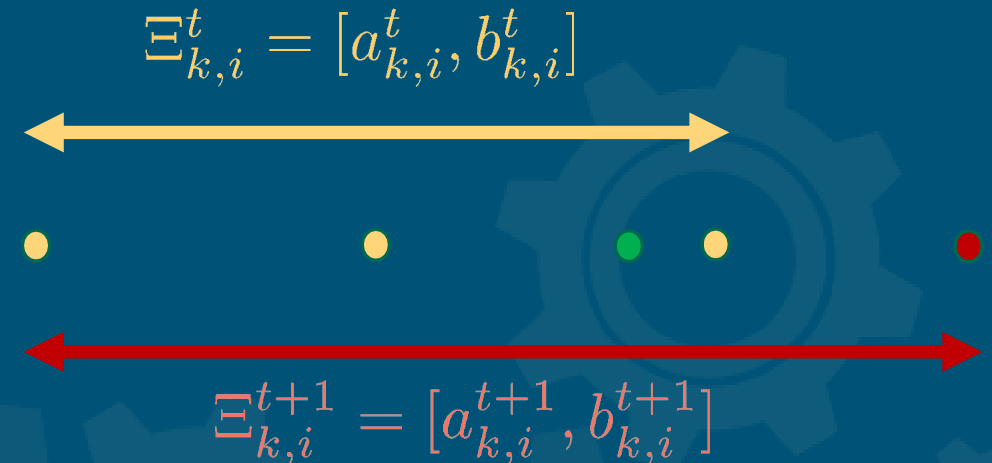
$$u^{(L+1)} = \operatorname{argmax}_{u \in I} v(u) \prod_{l=1}^L |u - u^{(l)}|$$

To compute error indicators we must evaluate integrated surrogates at set of random samples of \mathbf{z}

We update ranges according to

$$a_{k,i}^{t+1} = \min \left(a_{k,i}^t, \min_{\mathbf{z} \in \mathcal{U}_{\text{refine}}} f_{m, \mathcal{I}_m^{t+1}, q}(\mathbf{z}) \right)$$

$$b_{k,i}^{t+1} = \max \left(b_{k,i}^t, \max_{\mathbf{z} \in \mathcal{U}_{\text{refine}}} f_{m, \mathcal{I}_m^{t+1}, q}(\mathbf{z}) \right)$$



ESTIMATING THE RANGES OF THE COUPLING VARIABLES

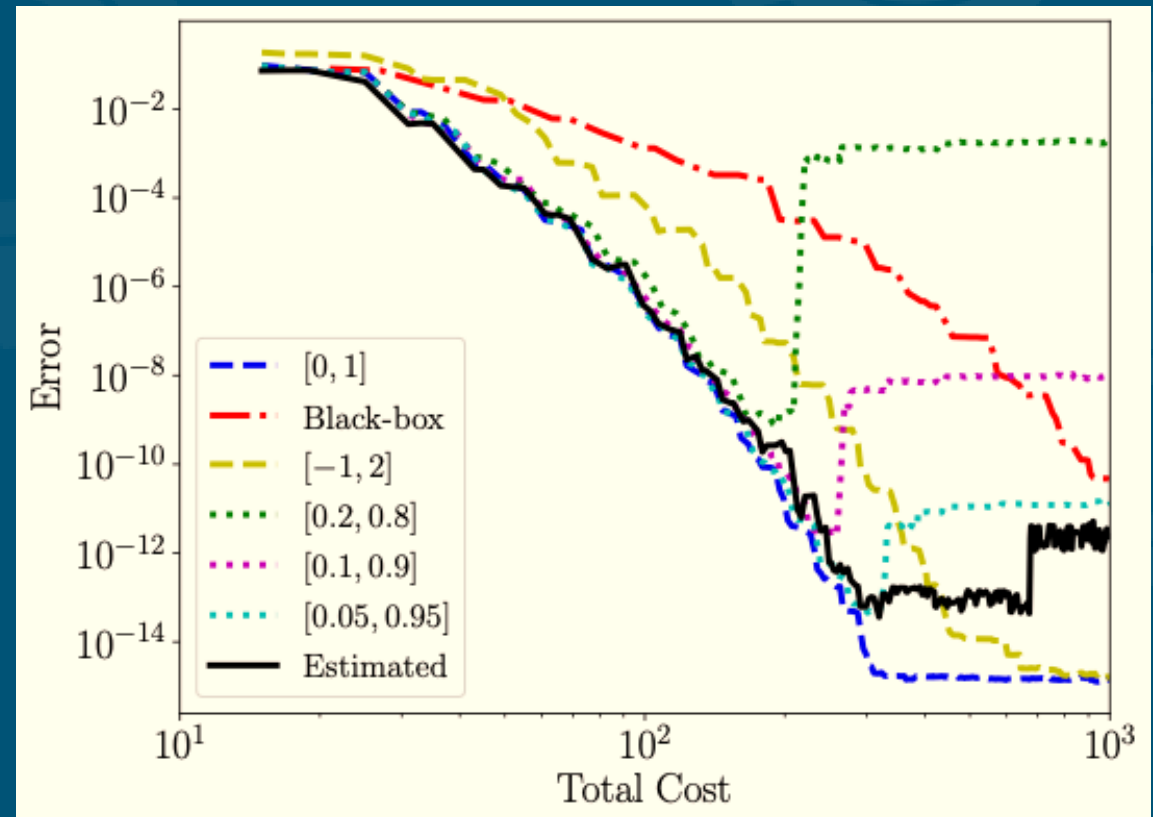
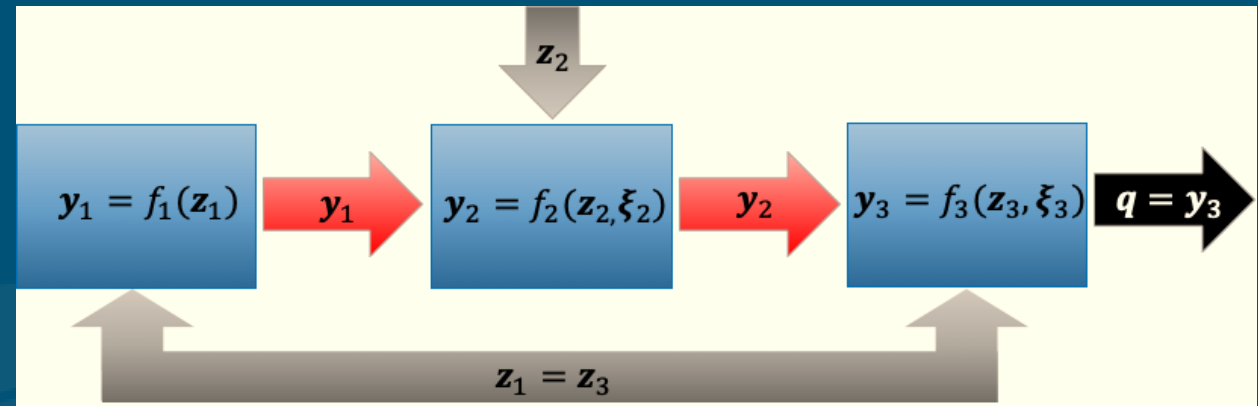


Adaptive component modeling is much more efficient than treating system as black-box

Under-estimating range introduces large errors

Over-estimation has little impact

Range can be estimated effectively



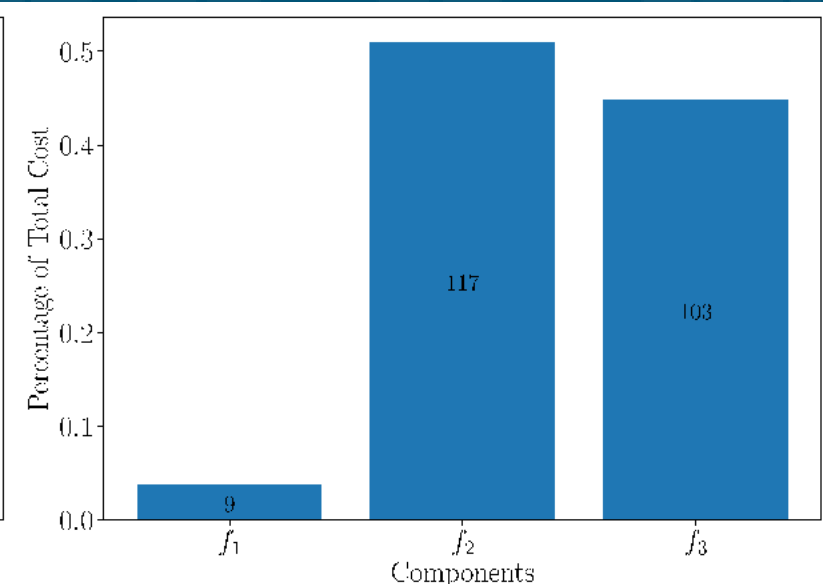
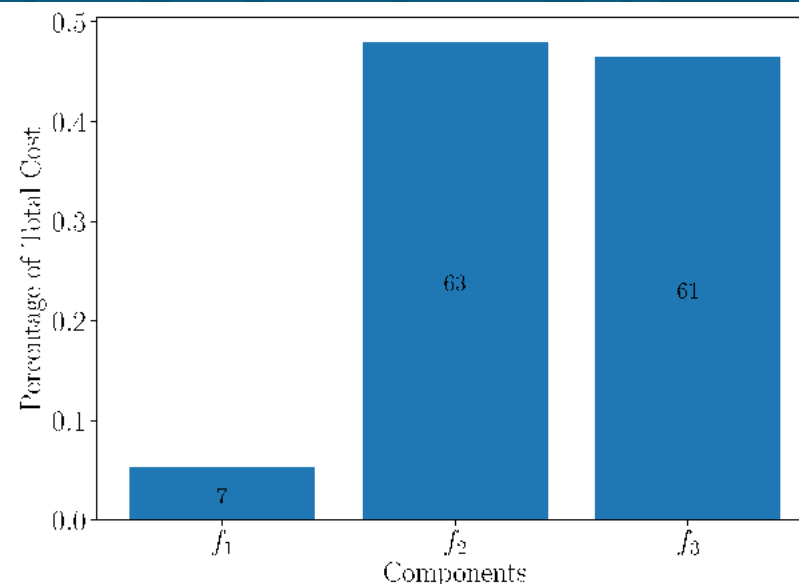
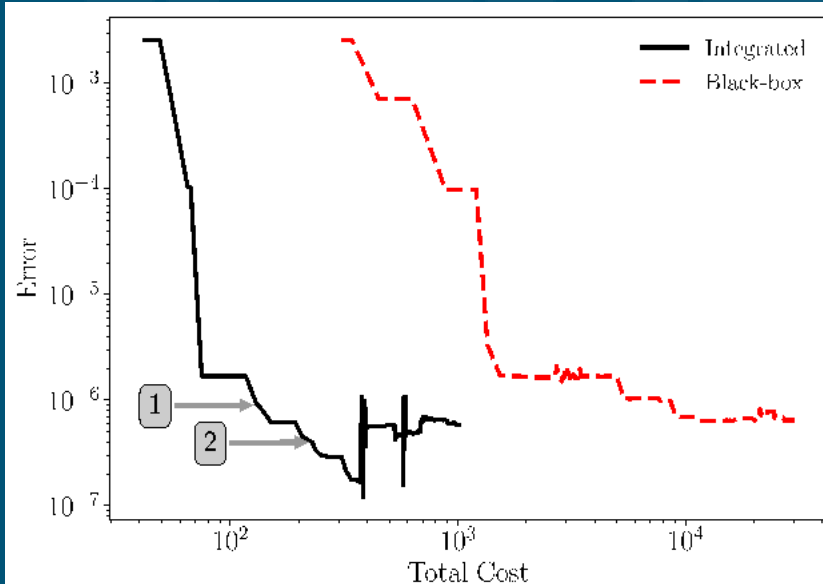
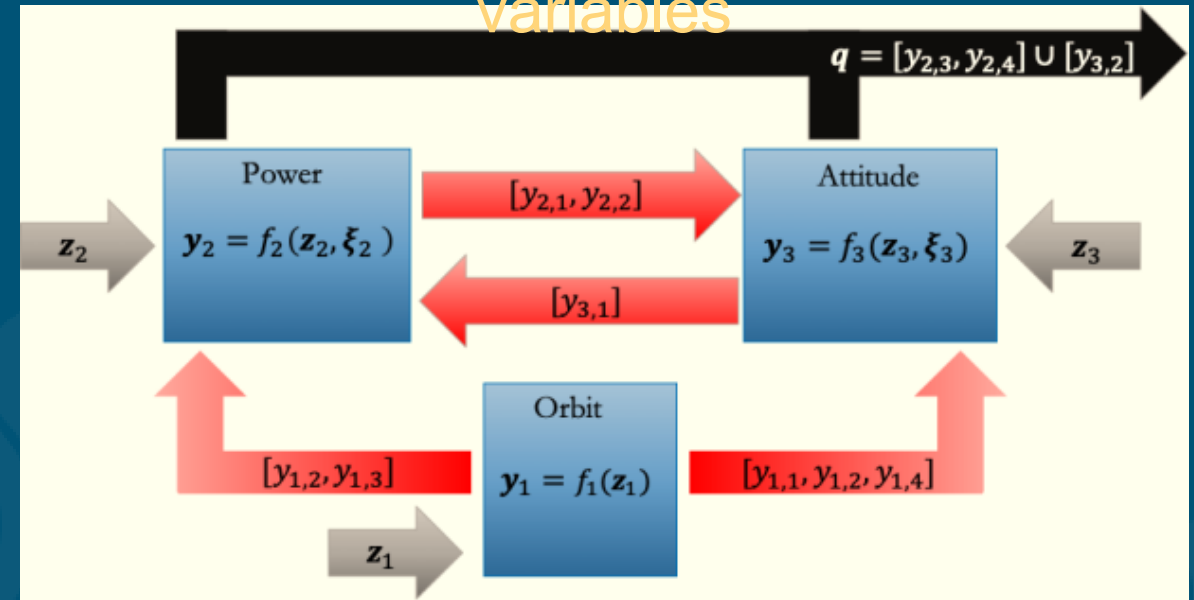
FIRE-DETECTION SATELLITE



8 random variables

Approach can be used with feed-forward and feed-back coupling

Resources allocated based on sensitivity of system QoI to each component



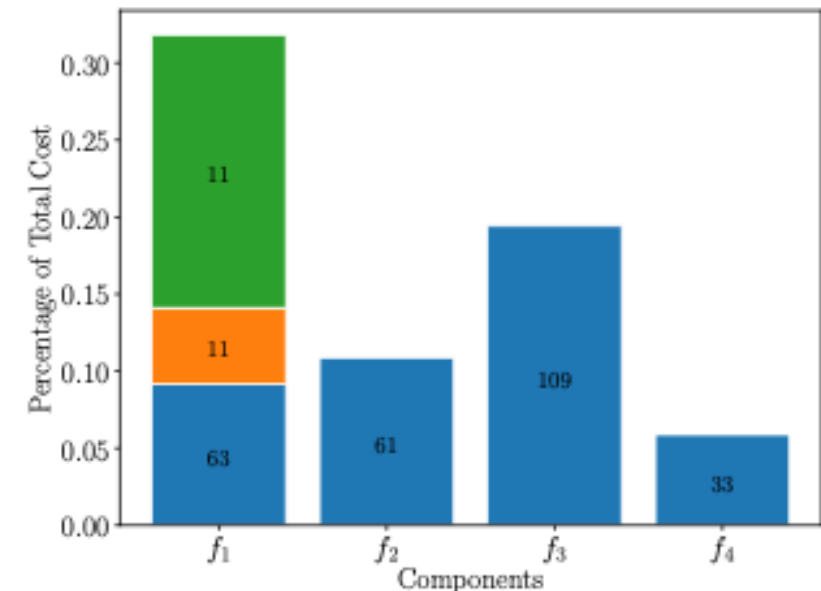
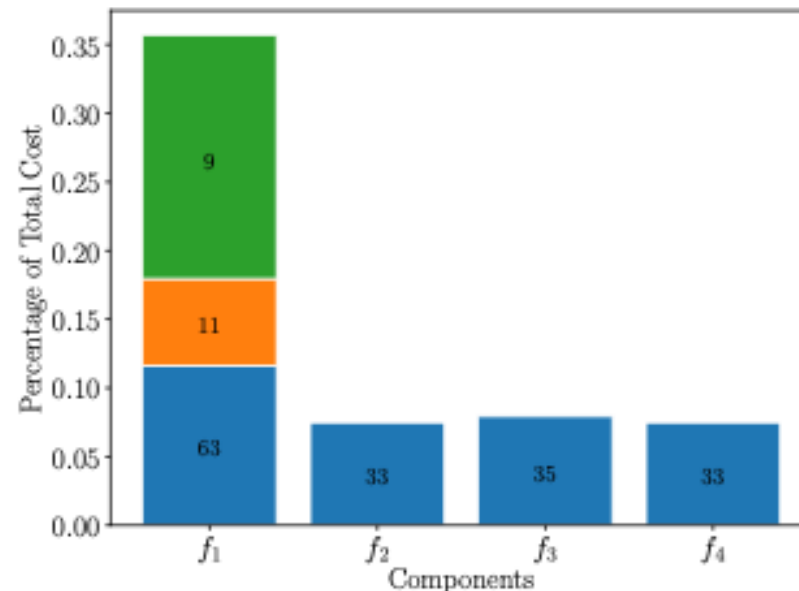
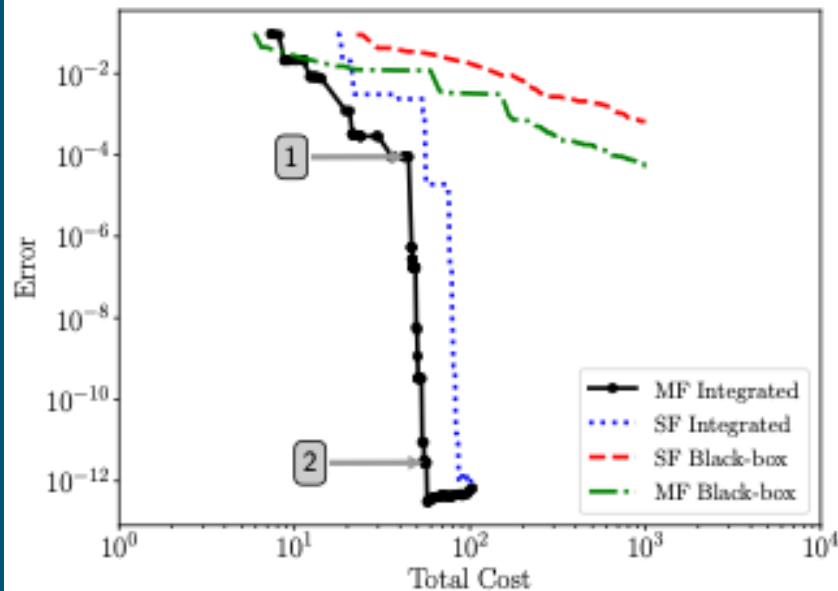
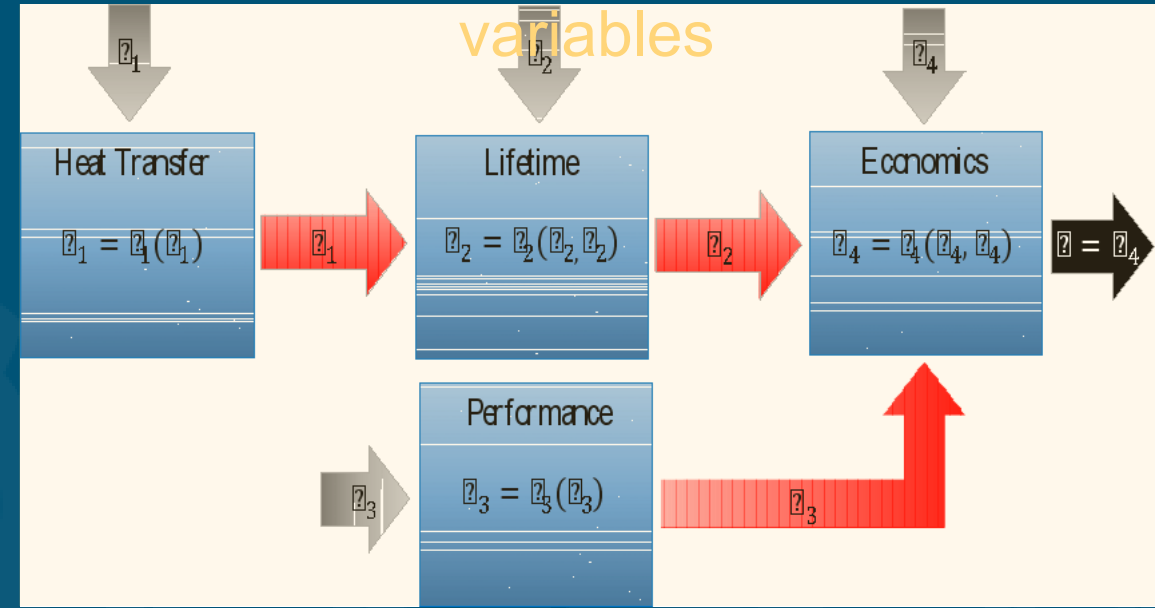
GAS-TURBINE OPERATING REVENUE



Approach can be used to when multiple fidelity models are available

Predictive accuracy of model fidelity is balanced with error in the surrogate

11 random variables



The structure of coupled systems should be exploited when constructing surrogates

We build surrogates of each component

The accuracy of each component surrogate depends on its predictive utility per unit cost

Our approach can reduce cost of UQ by 10-1000X