

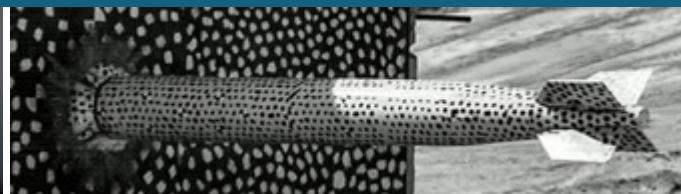
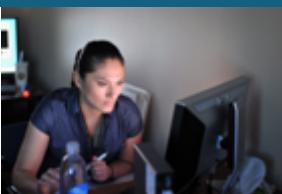
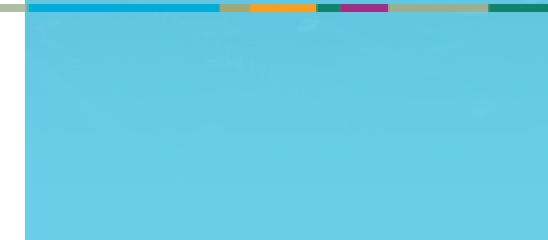


Sandia
National
Laboratories

SAND2020-11992PE

Applied WEC modeling and control design

Oct. 29 2020, UMass-Amherst



Presented by

Ryan Coe, rcoe@sandia.gov

Slides based on combined work of the author, Giorgio Bacelli,
Dominic Forbush, Steven Spencer, and others



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Class agenda



- I. About me
- II. Wave energy background
- III. Case-study (with examples in MATLAB)
 - I. Modeling a WEC
 - II. Controlling a WEC

3 MATLAB examples



SNL-WaterPower / fbWecCntrl

Code Issues Pull requests Projects Security Insights

Code

master 2 branches 0 tags

ryancoe address warnings from MATLAB code analyzer report ec9b169 on Sep 16 29 commits

data add missing MAT file for MIMO WaveBot last month

src move WecPower to stand-alone function 3 months ago

.gitignore initial commit 6 months ago

COPYING initial commit 6 months ago

README.md add link to preprint on TechRxiv last month

demo_foswec.m address warnings from MATLAB code analyzer report last month

demo_waveBot.m address warnings from MATLAB code analyzer report last month

fbWecCntrlTest.m address warnings from MATLAB code analyzer report last month

README.md

fbWecCntrl

NOTE: this code is fully-functional, but not supported and users should not expect responses to issues

fbWecCntrl is a set of MATLAB functions and scripts demonstrating a causal impedance matching approach to wave energy converter (WEC) control design. The methods applied in this code are detailed in a journal paper manuscript (preprint available here <https://doi.org/10.36227/techrxiv.12939488>), and is a fork of code originally published on [M4HK-DR](#).

```
@Article{Coe2020practical,
  author  = {Ryan G. Coe and Giorgio Bacelli and Dominic Forbush},
  title   = {A practical approach to wave energy modeling and control},
  date    = {2020},
  journaltitle = {Renewable and Sustainable Energy Reviews (under review)},
  doi     = {10.36227/techrxiv.12939488}
}
```

Getting started

This code has been tested on MATLAB 2020a (9.8.0.1323502) and has the following dependencies.

About

Feedback controller design of wave energy converters (WECs)

Readme

GPL-3.0 License

Releases

No releases published

Packages

No packages published

Contributors 2

ryancoe Ryan Coe
dforbush2

Languages

MATLAB 100.0%

1. Go to the `fbWecCntrl` repository:
<https://github.com/SNL-WaterPower/fbWecCntrl>
2. Download or clone the repository (clone preferred to allow for easier updates)
3. Follow instructions installing*:
<https://github.com/SNL-WaterPower/fbWecCntrl#getting-started>
4. The material for the lecture is located in the seminar_examples directory

* Note that WAFO (<https://github.com/wafo-project/wafo>) is used to generate JONSWAP wave spectra - you will need this too to run some of the examples



About me

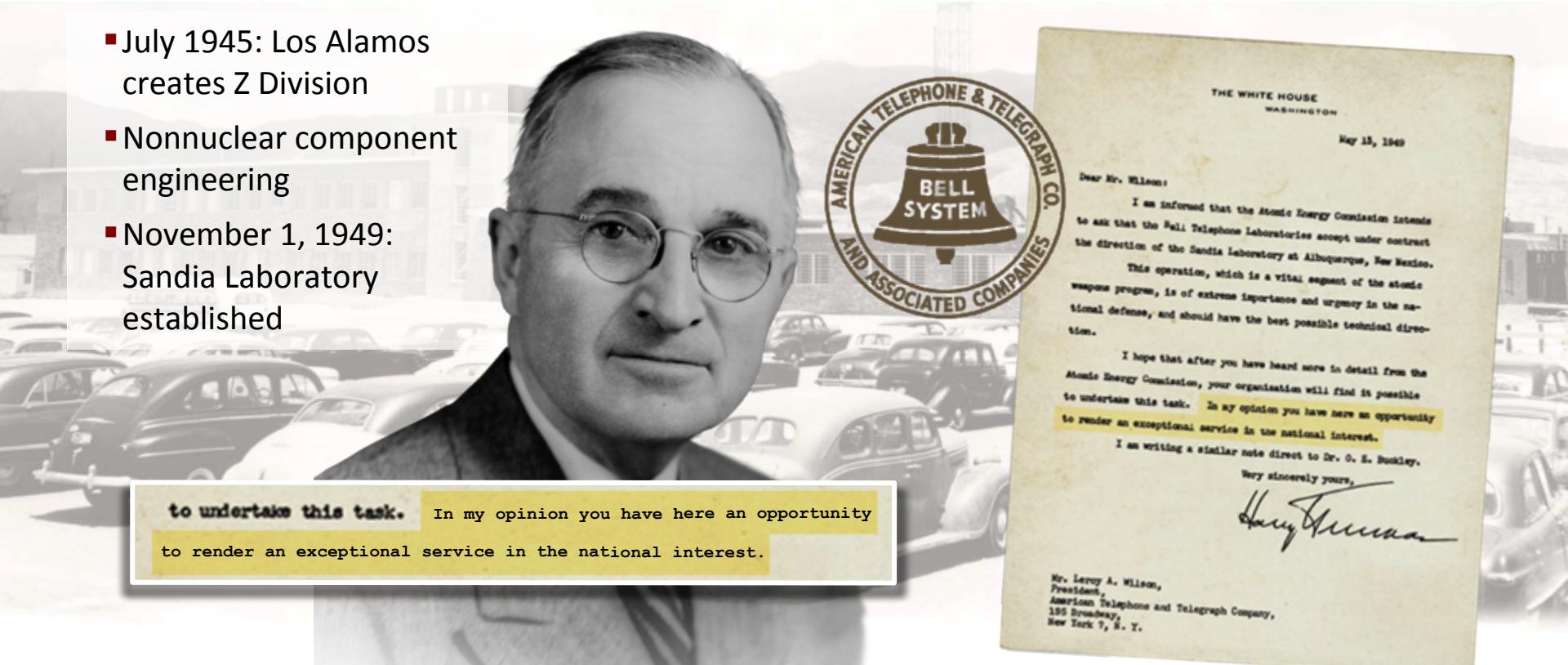


Sandia National Labs



Exceptional service in the national interest

- July 1945: Los Alamos creates Z Division
- Nonnuclear component engineering
- November 1, 1949: Sandia Laboratory established



Albuquerque, NM

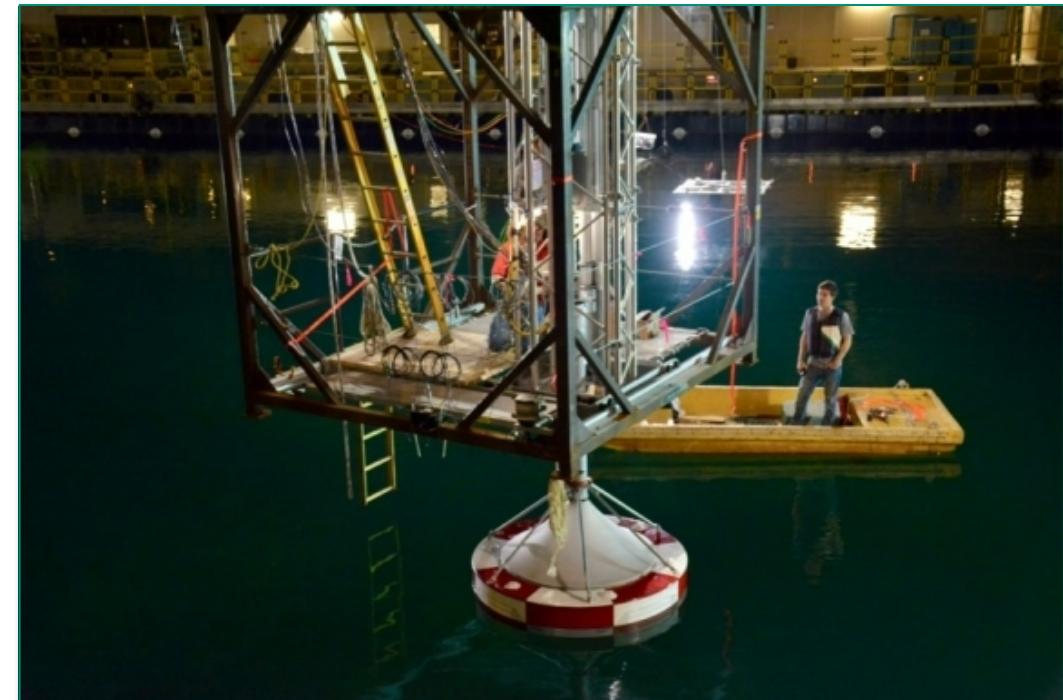




BS and PhD from Virginia Tech (Go Hokies!)

Sandia researcher for ~7 years

Hobbies: fly fishing, rock climbing, linear algebra



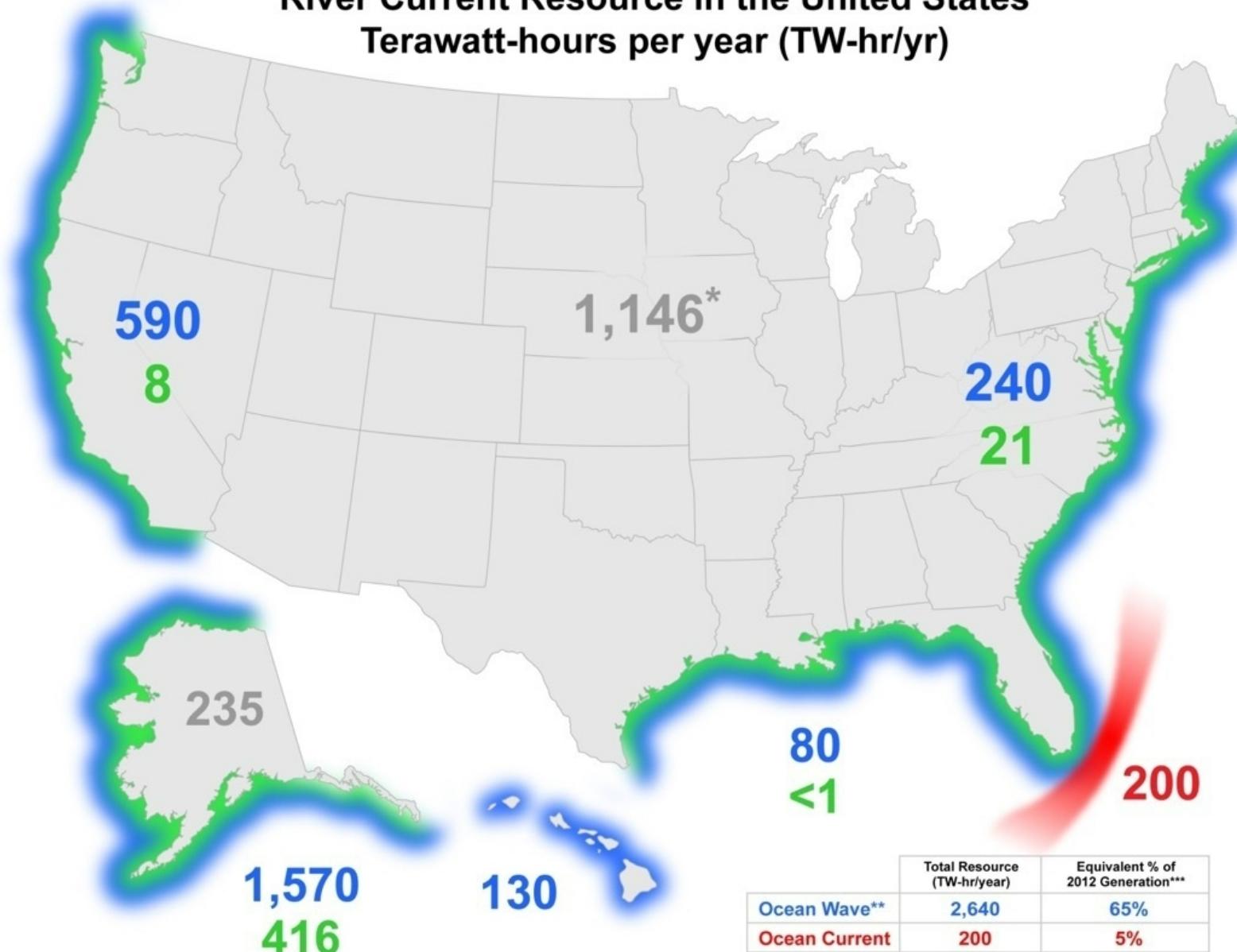


Background



The Ocean Wave, Ocean Current, Tidal Current, and River Current Resource in the United States

Terawatt-hours per year (TW-hr/yr)



Ocean Wave: P. Jacobson, G. Hagerman, and G. Scott, "Mapping and Assessment of the United States Ocean Wave Energy Resource," Electric Power Research Institute, Report Number 1024637, 2011.

Ocean Current: K. Haas, H. Fritz, S. French, and V. Neary, "Assessment of Energy Production Potential from Ocean Currents Along the United States Coastlines," Georgia Tech Research Corporation, 2013.

Tidal Current: K. Haas, H. Fritz, S. French, B. Smith, and V. Neary, "Assessment of Energy Production Potential from Tidal Streams in the United States," Georgia Tech Research Corporation, 2011.

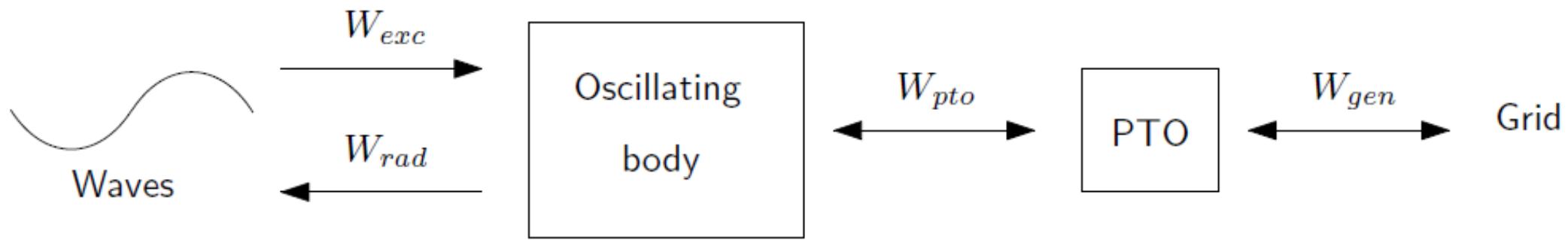
River Current: T. Ravens, K. Cunningham, and G. Scott, "Assessment and Mapping of the Riverine Hydrokinetic Resource in the Continental United States," Electrical Power Research Institute, Report Number 1026680, 2012.

*Resource distributed throughout the river systems in the United States.

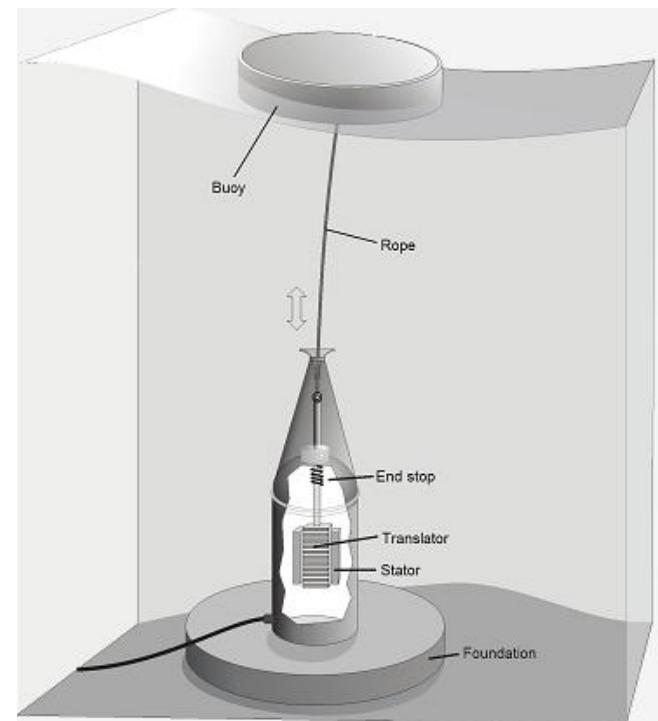
**Resource data for the 200-m depth contour.

***The size of the resource with respect to total U.S. electricity generation in 2012, which was 4,054 TW-hr (U.S. Energy Information Administration, "Electric Power Monthly," May 2013).

What is a Wave Energy Converter?



Energy transfer through an oscillating body wave energy converter



Wave Energy Transport



Most of the energy within a wave is contained near the surface.



wave energy devices are designed to stay near the water surface to maximize the energy available for capture

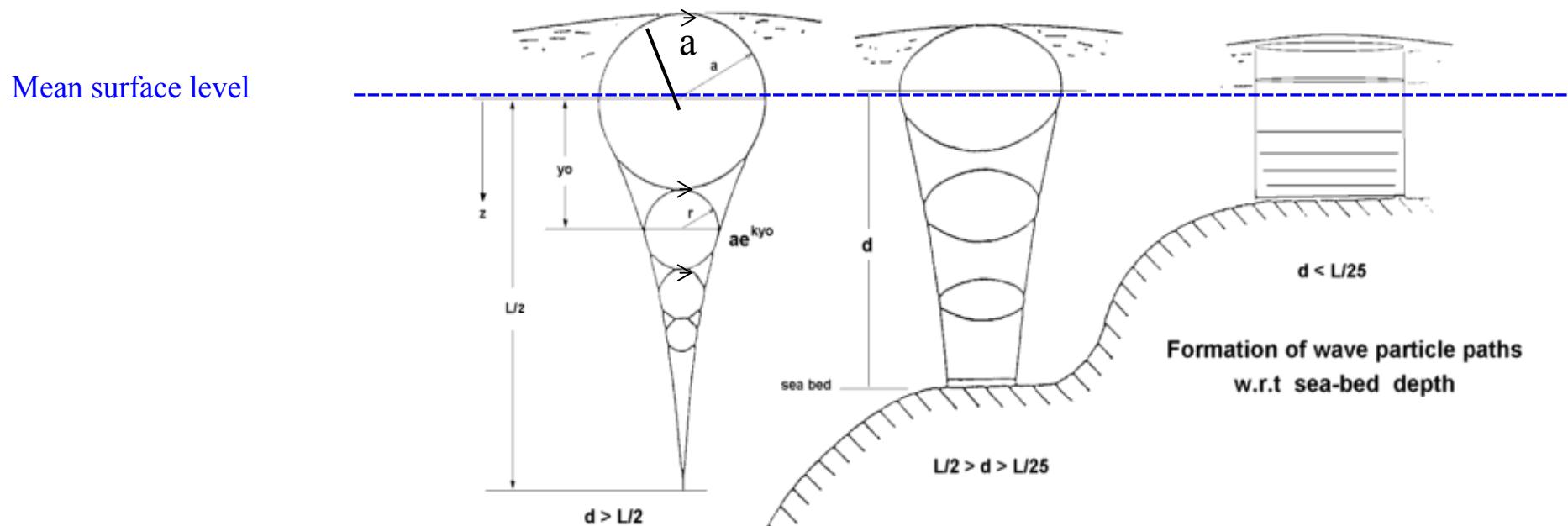
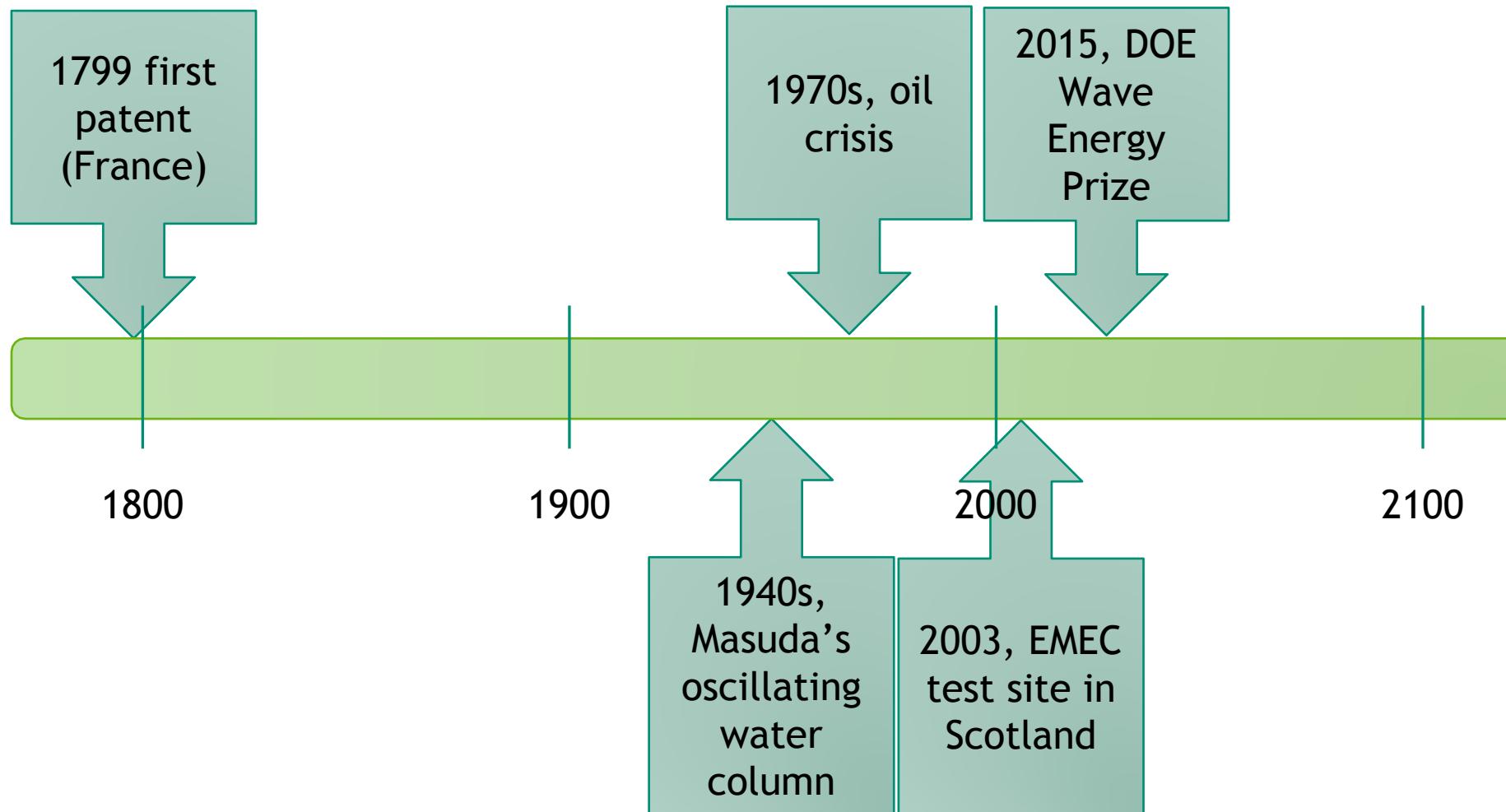
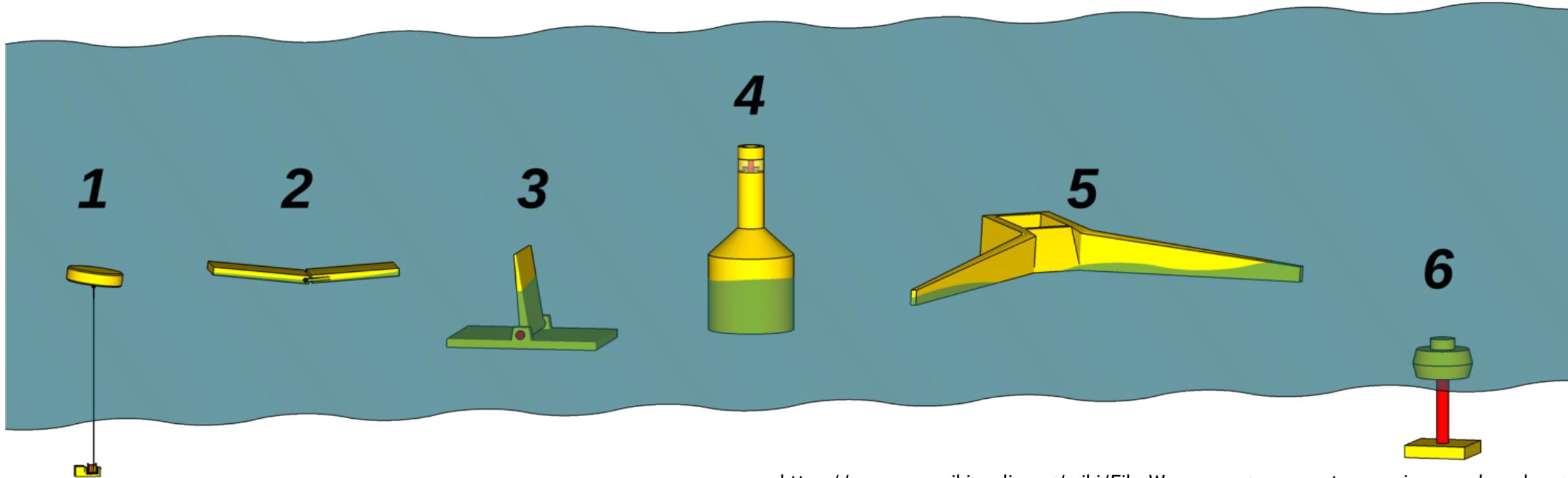


Fig. orbital motion of the water particles

Wave energy, a (brief) history

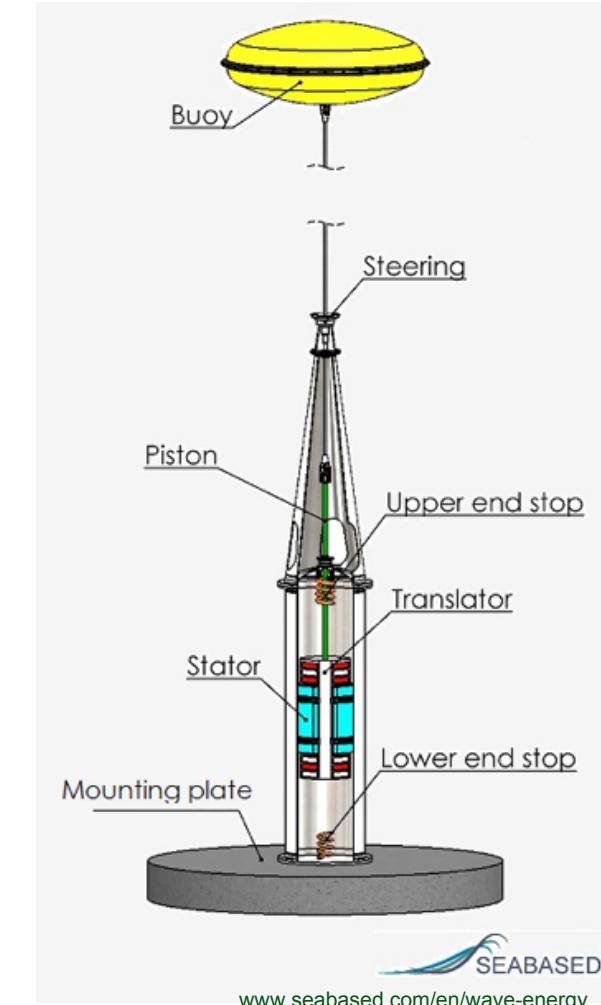
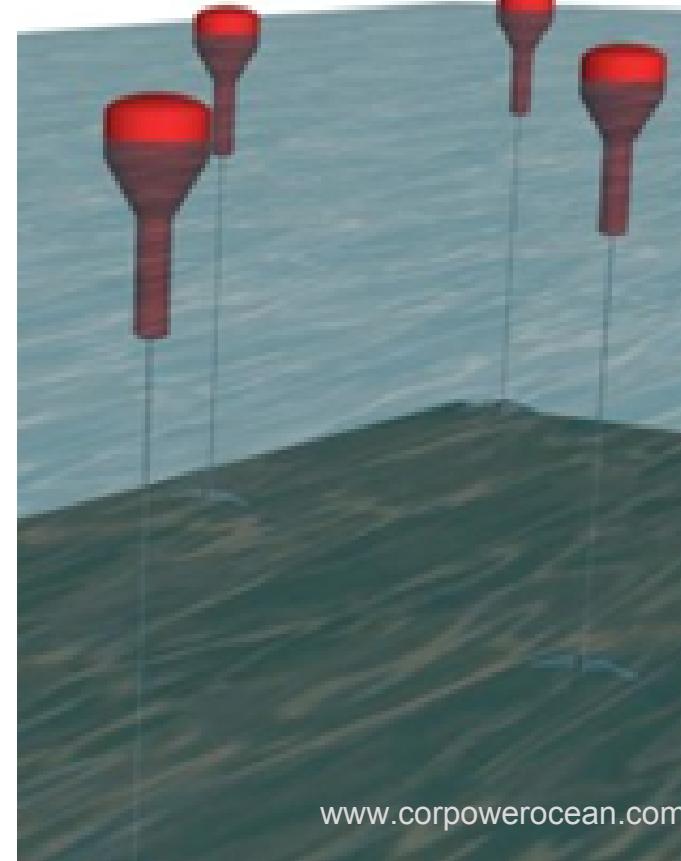
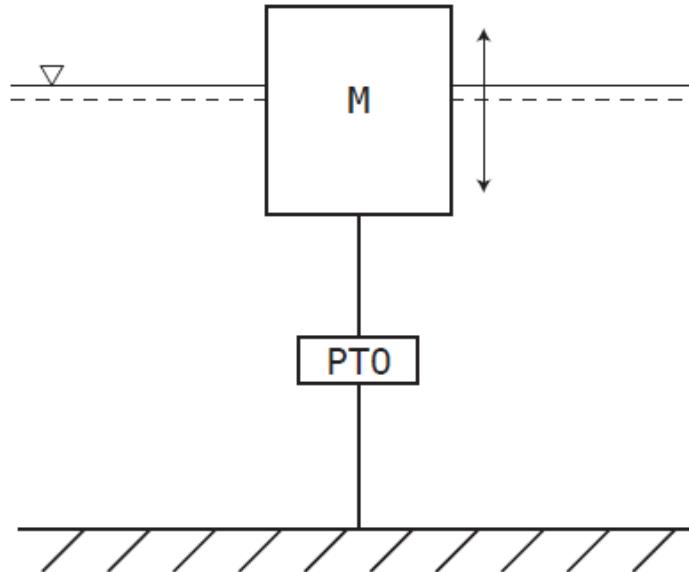


Wave energy concepts

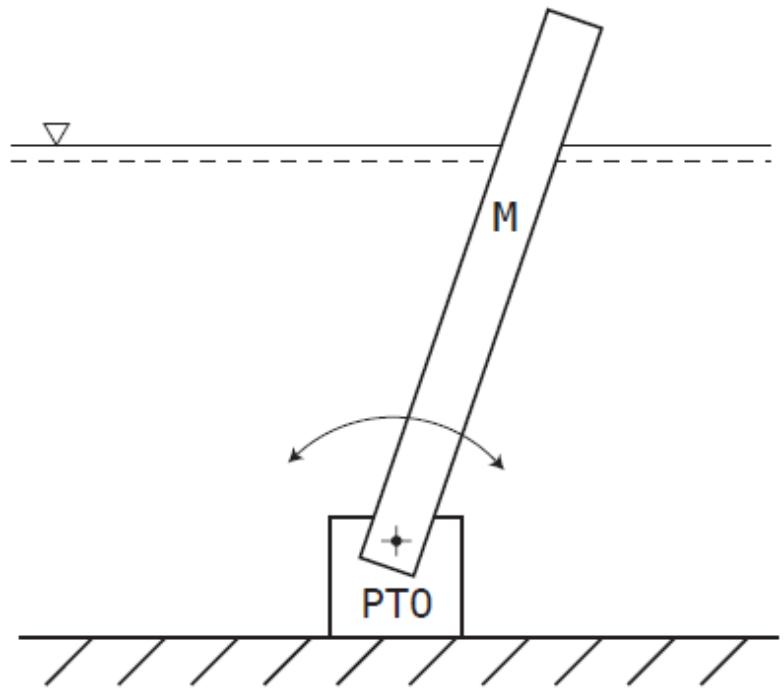


https://commons.wikimedia.org/wiki/File:Wave_energy_concepts_overview_numbered.png

Wave energy concepts – heaving point absorber

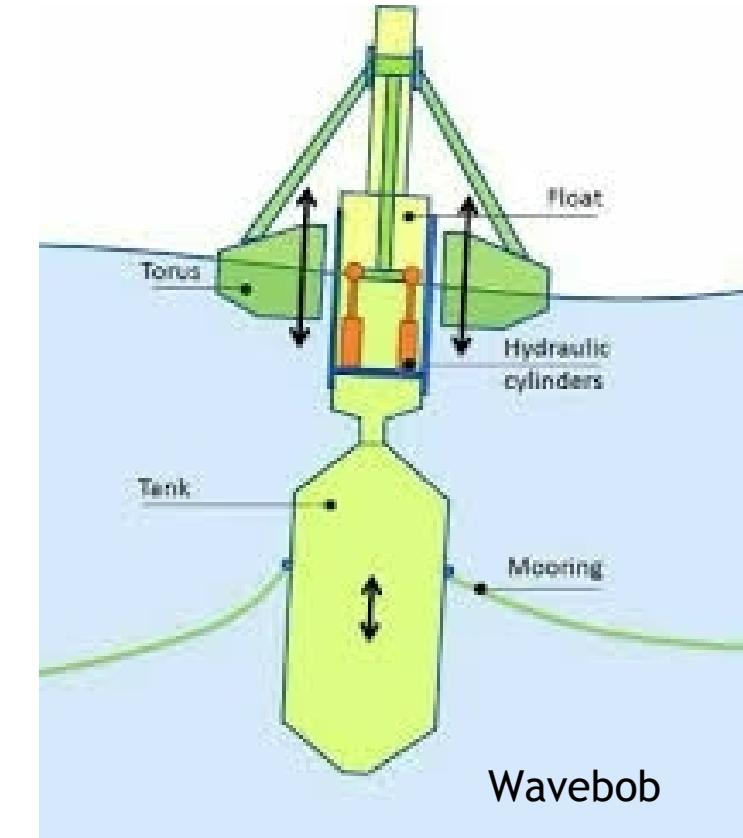
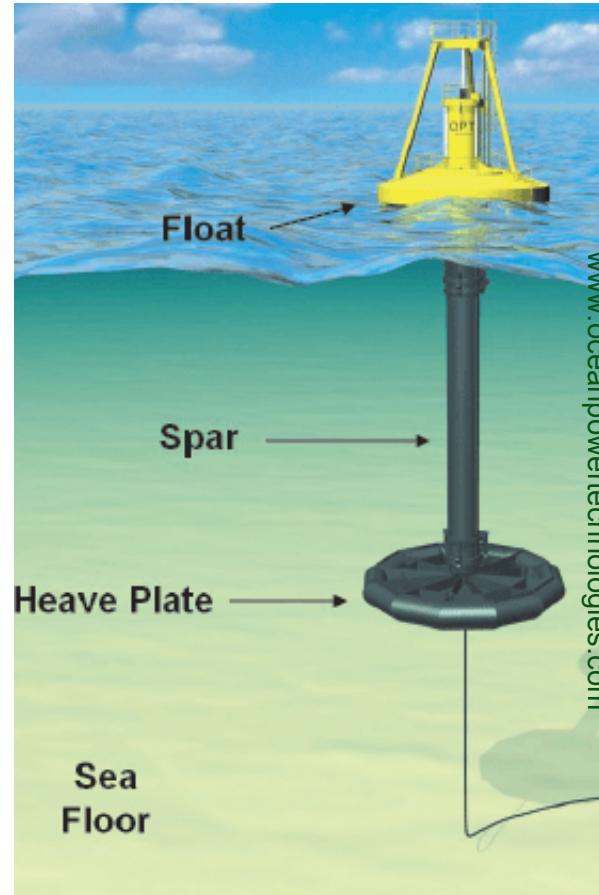
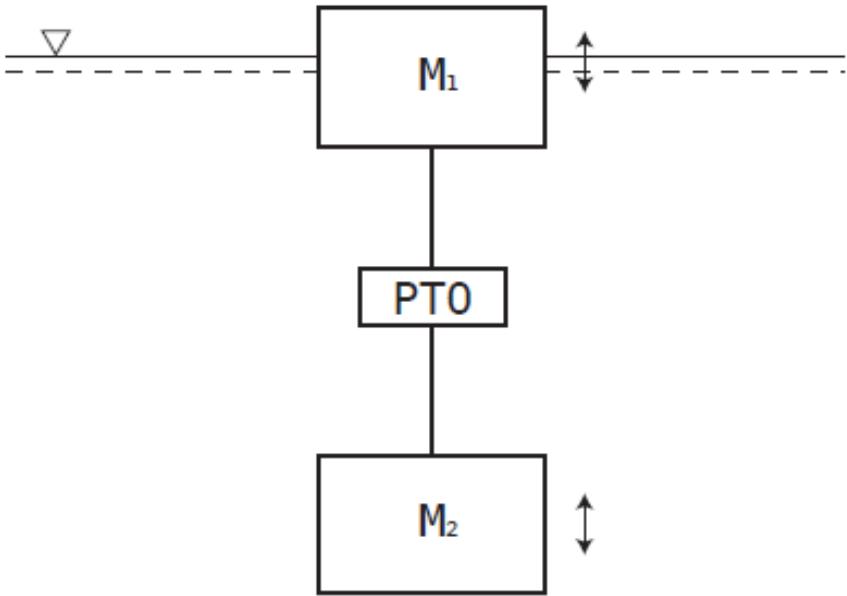


Wave energy concepts – pitching (flapping) device

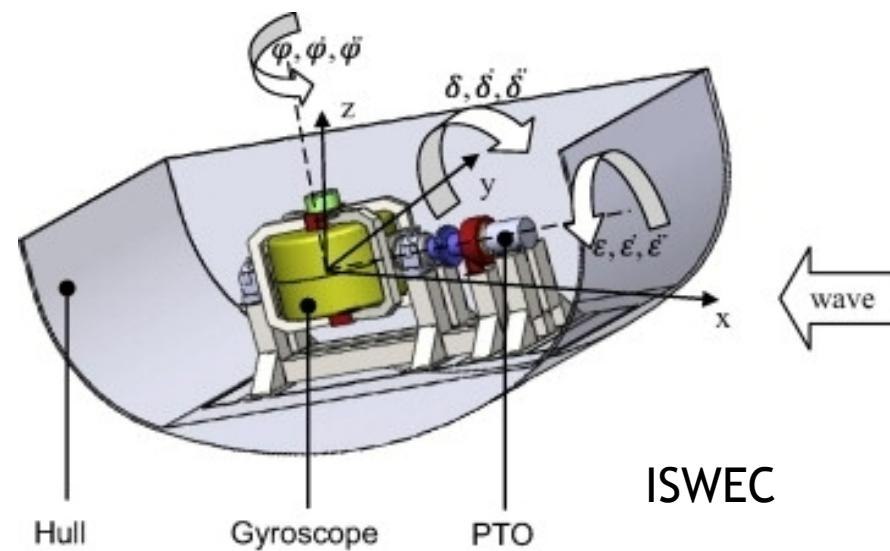
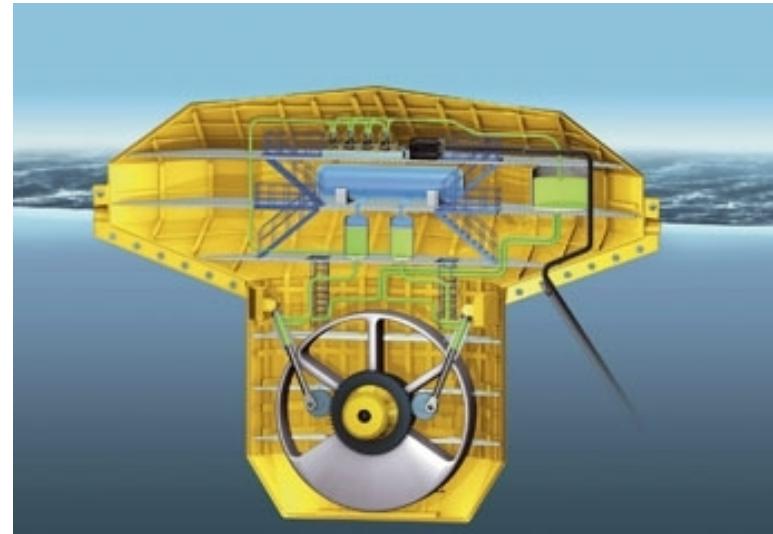
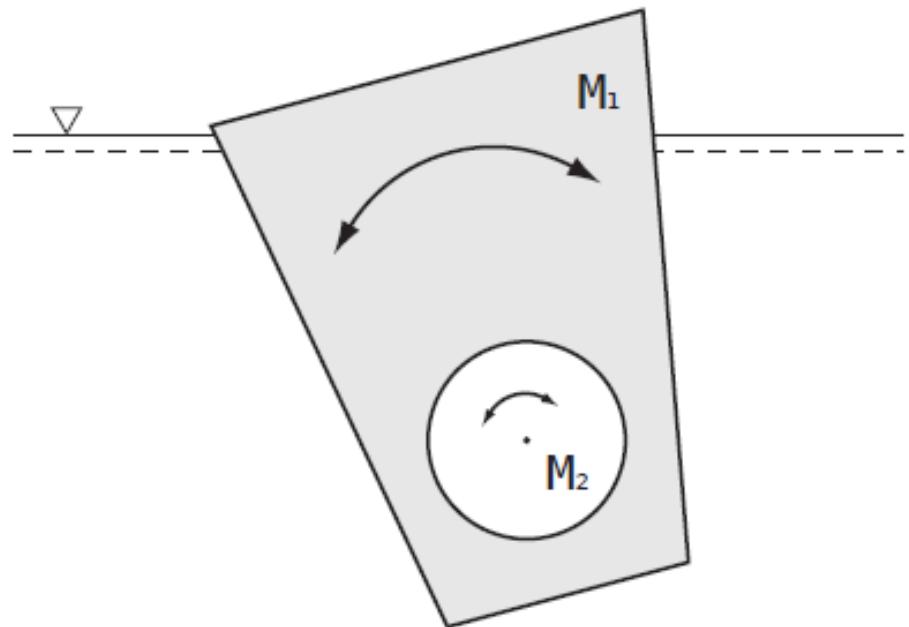


www.aquamarinepower.com

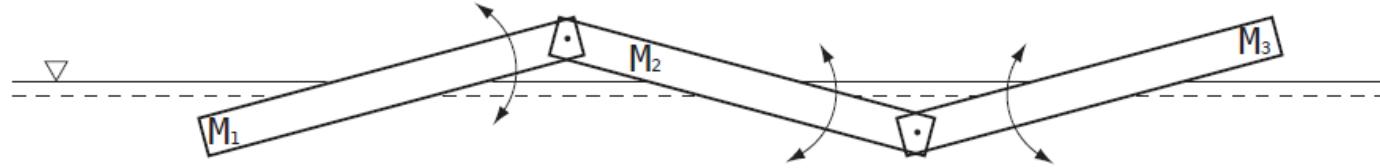
Wave energy concepts - Self-reacting point absorber



Wave energy concepts - Self-reacting wave energy converter with internal mass

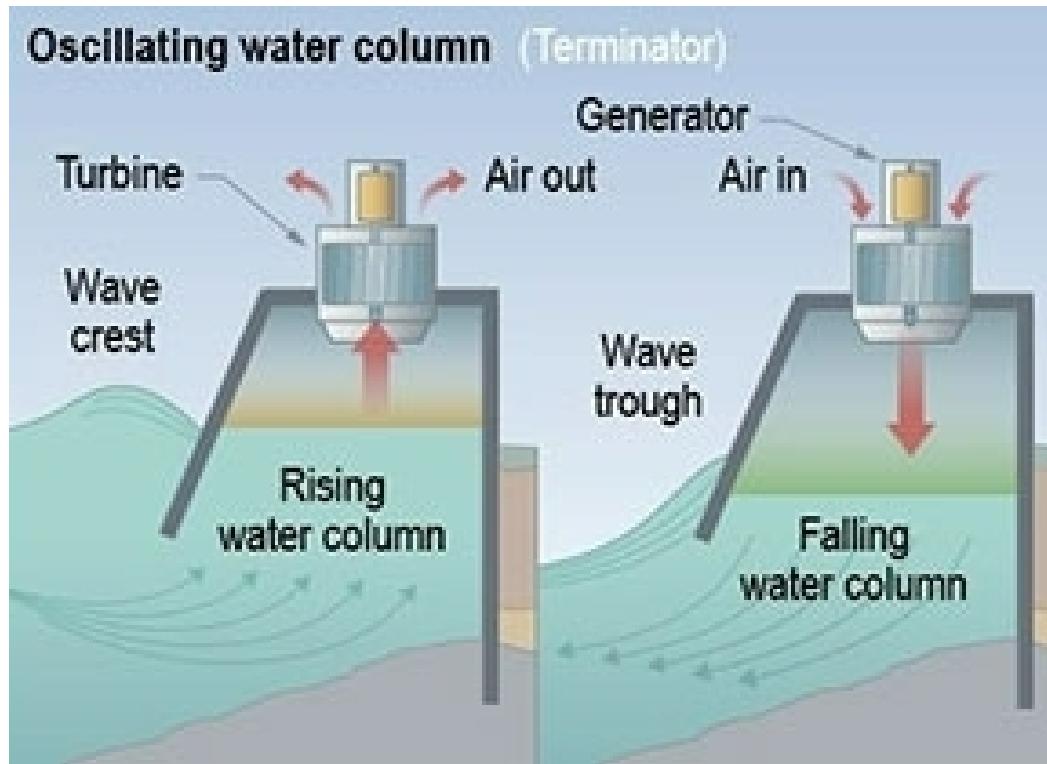


Wave energy concepts - attenuators

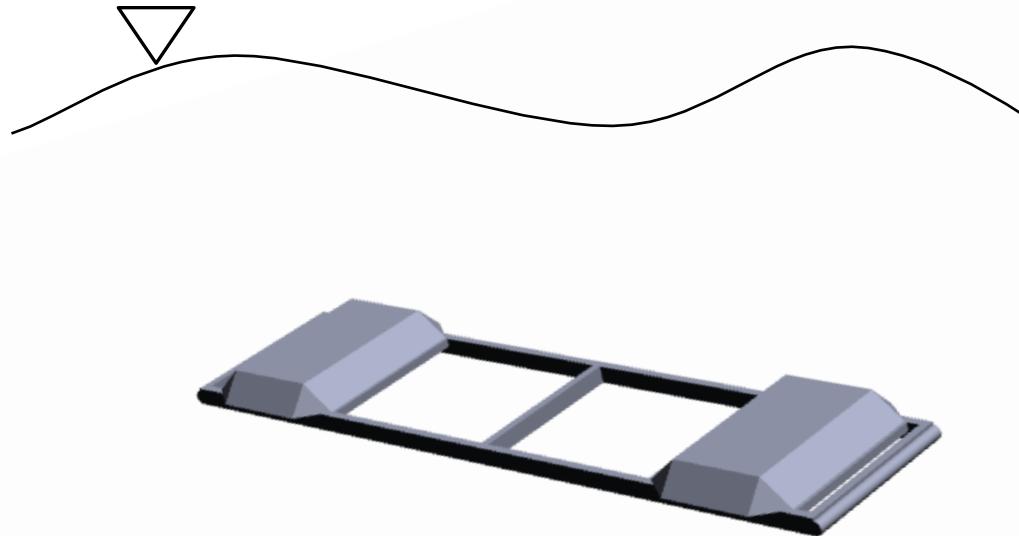


Pelamis wave energy

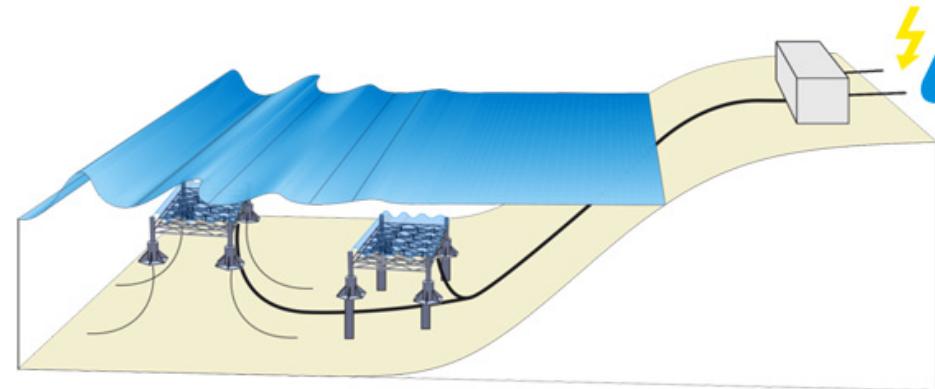
Wave energy concepts – oscillating water column (OWC)



Pressure differential devices



<https://www.m3wave.com>

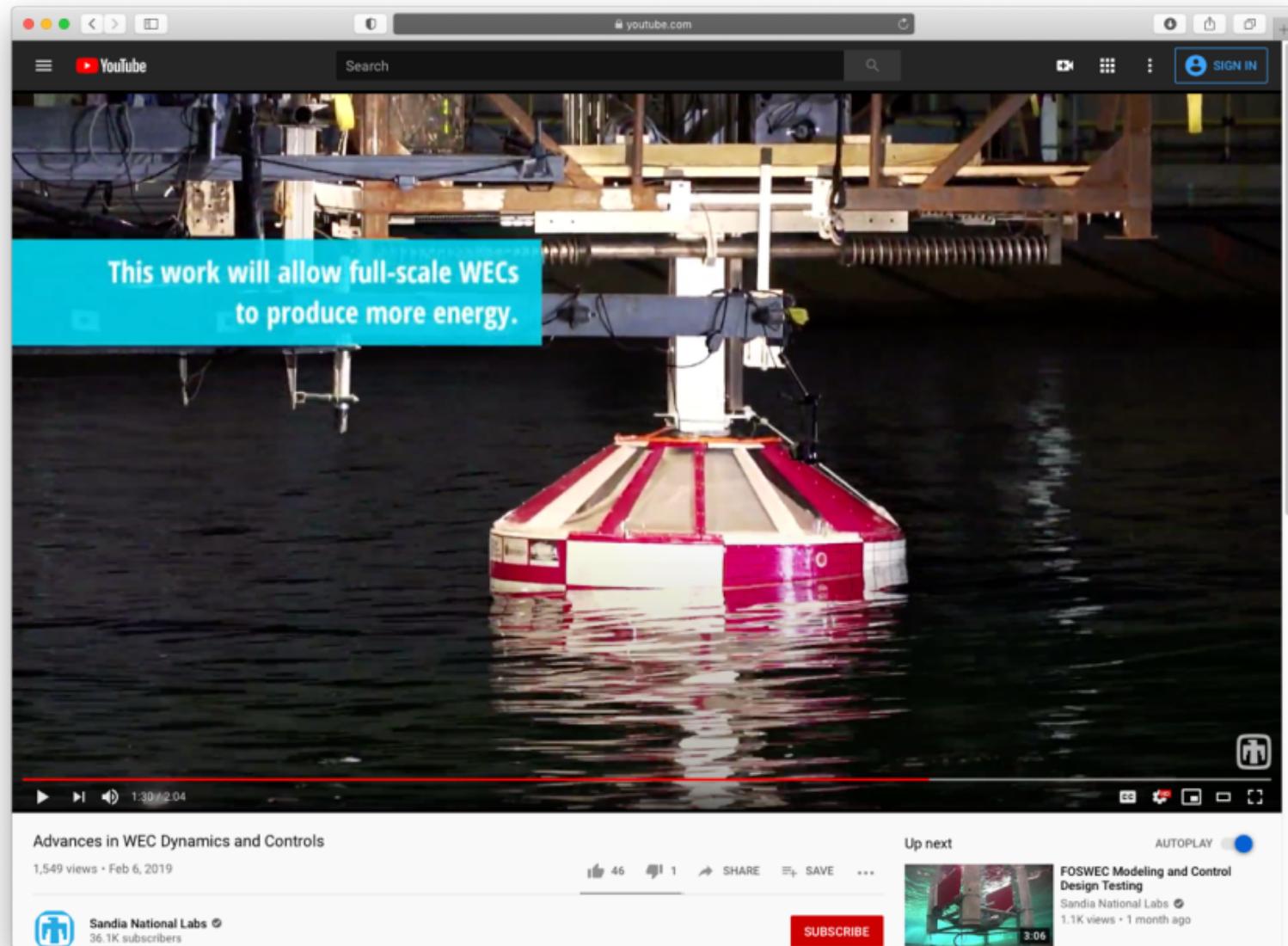


<http://calwave.org>

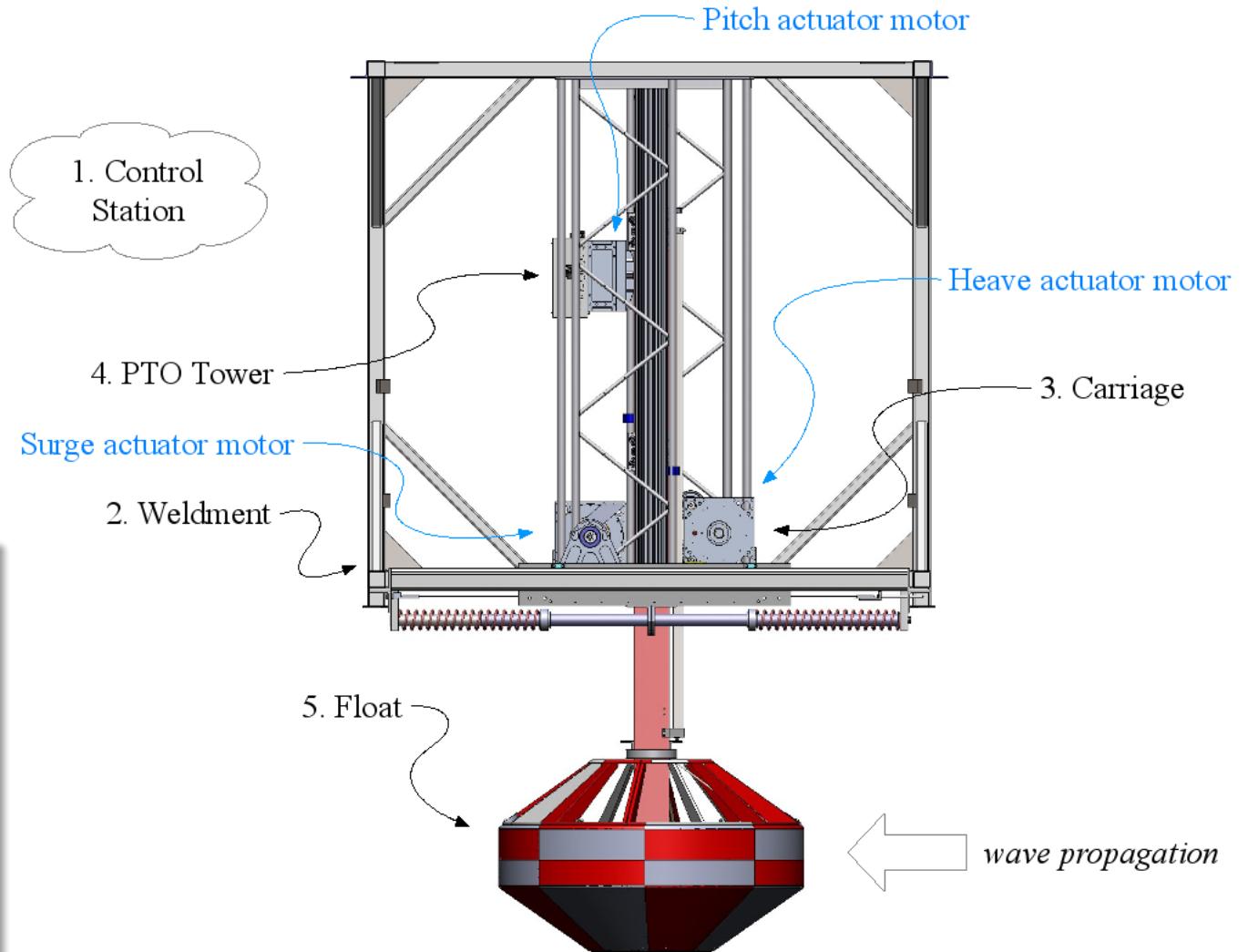
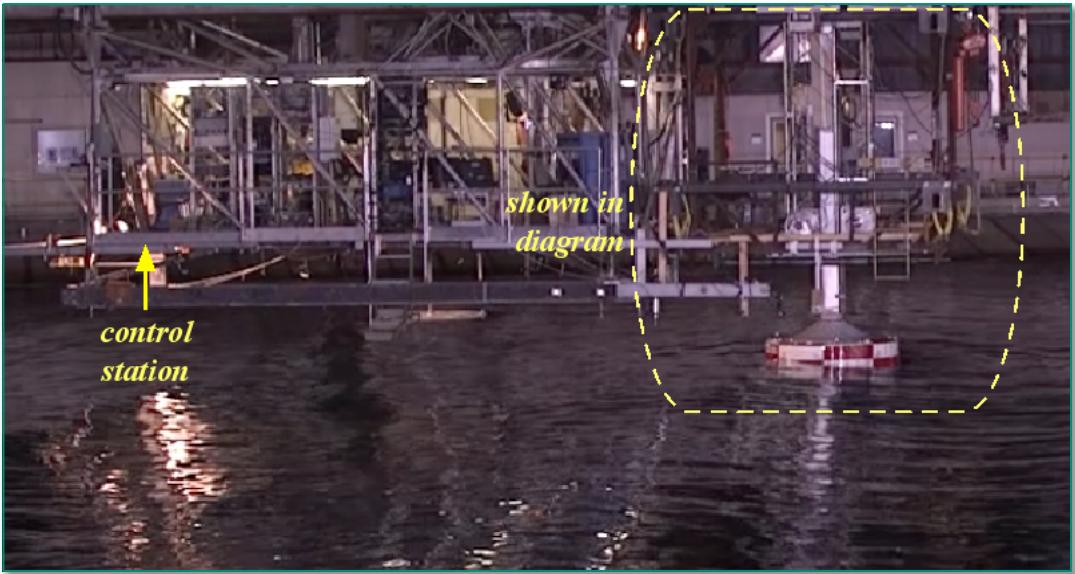
Study device – the “WaveBot”



Parameter	Value
Displaced volume, ∇ [m ³]	0.858
Water density, ρ [kg/m ³]	1000
Inertia, heave [kg]	858
Inertia, surge [kg]	1420
Inertia, pitch [kg m ²]	84



Study device – the “WaveBot” (cont.)

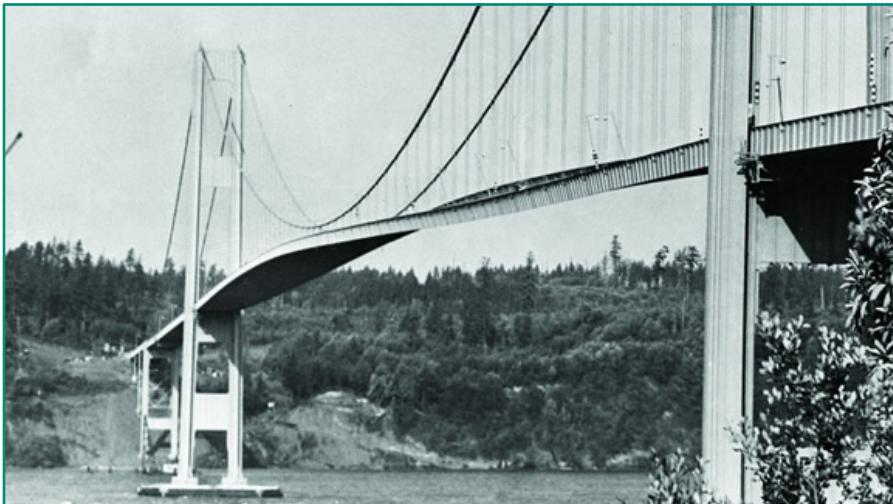




Modeling a WEC



Resonance



Resonance is often something engineers try to avoid



Resonance



*Resonance is often something
engineers try to avoid*

... but not always





Two key aspects:

1. *Frequency* $f = f_n$

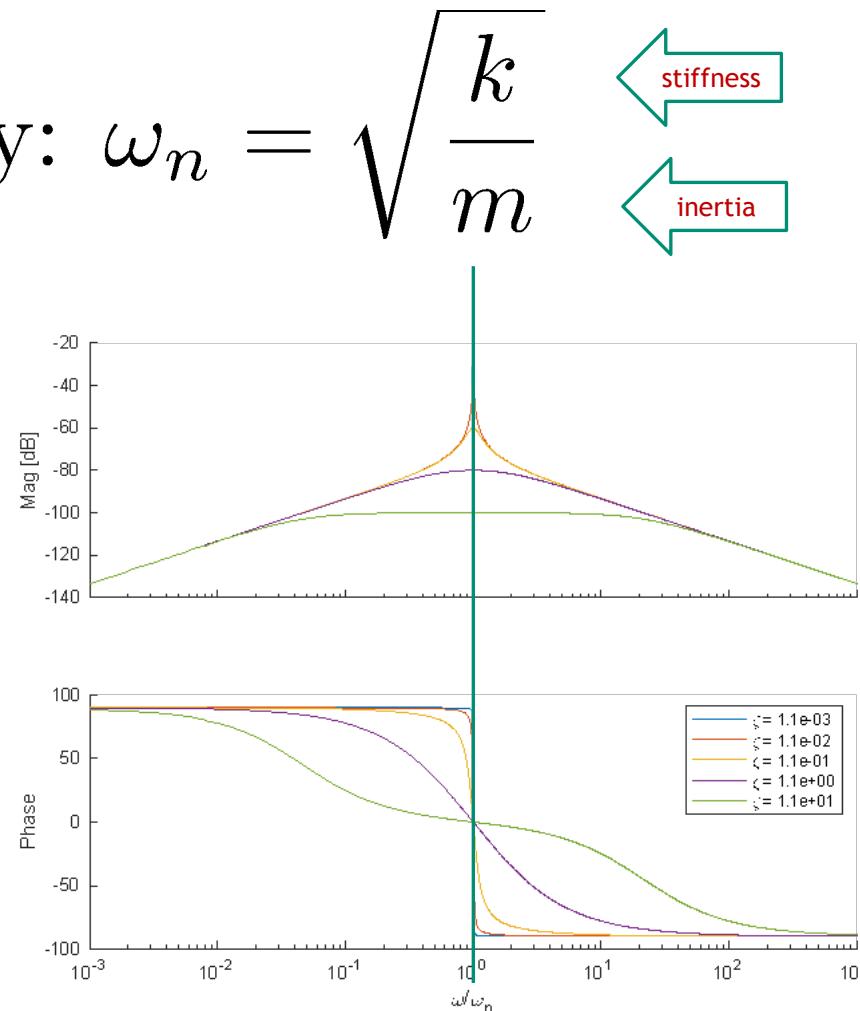
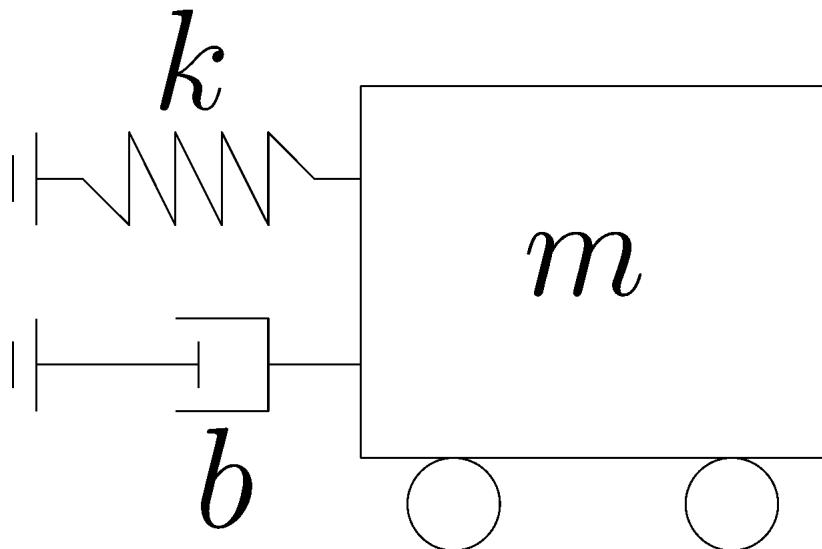
2. *Phase* $\angle \left\{ \frac{U}{F} \right\} = 0$



How do we define it?

Natural frequency:

$$\omega_n = \sqrt{\frac{k}{m}}$$

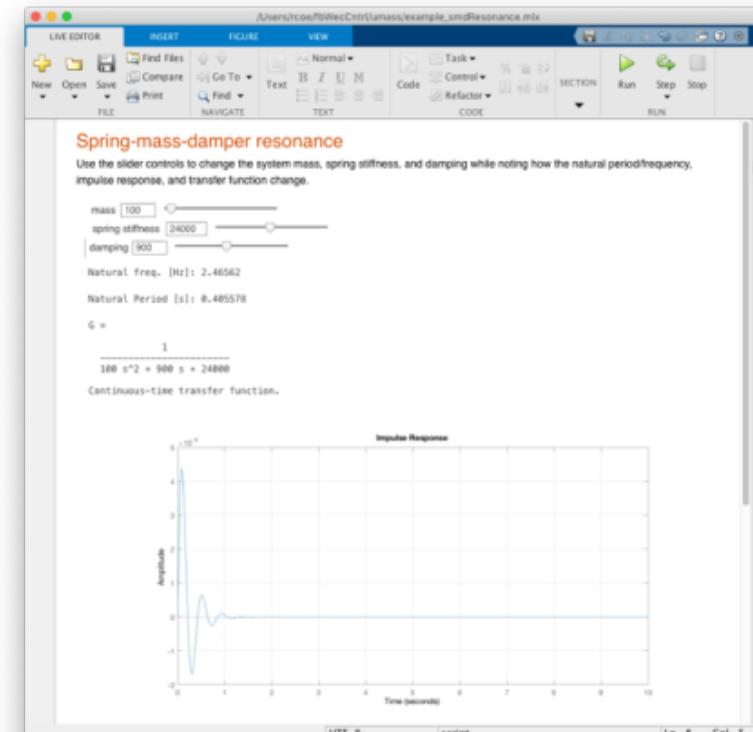
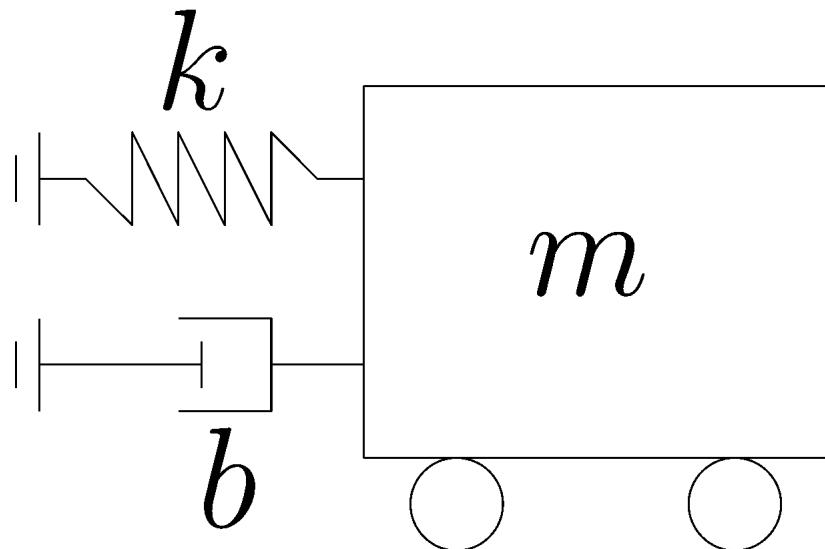


Resonance



How do we define it?

$$\text{Natural frequency: } \omega_n = \sqrt{\frac{k}{m}}$$



example_smdResonance.mlx



What is impedance?

$$F(\omega) = Z(\omega)v(\omega)$$

Tells us: "How does a structure respond to a force?"

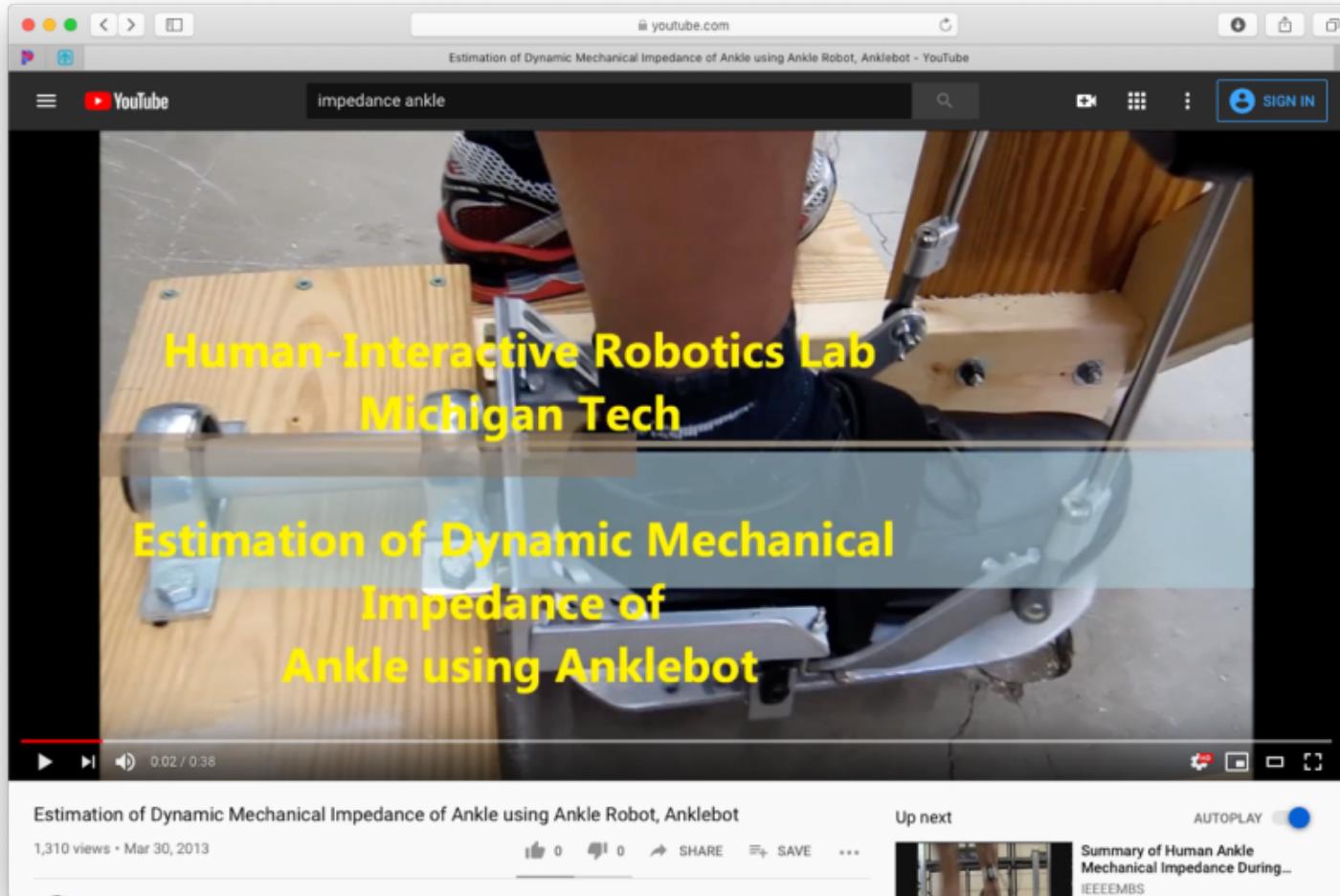
Units?

$$Z = \frac{\text{"potential"}}{\text{"flow"}} \quad \text{e.g., } \left[\frac{N}{m/s} \right] \text{ or } \left[\frac{V}{A} \right]$$

Impedance



Isn't this just for electrical engineers?



<https://www.youtube.com/watch?v=pgrCjdSYBjM>

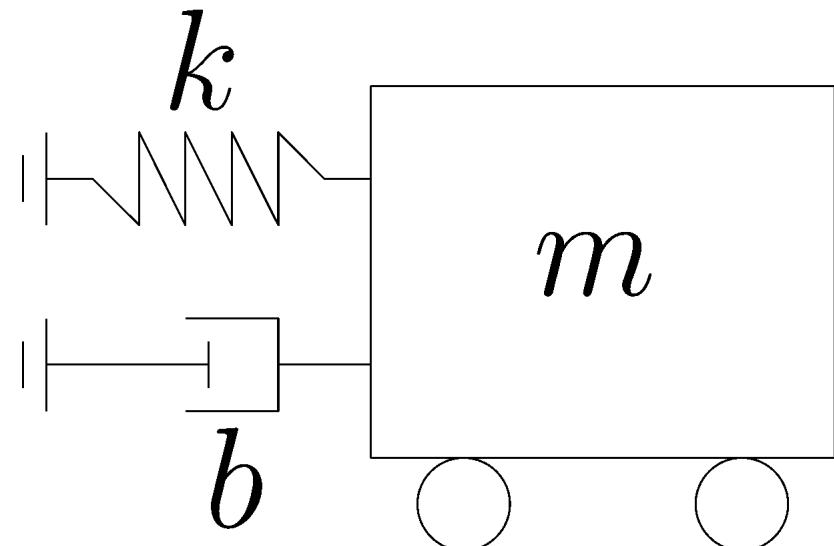
Spring-mass-damper



$$m\ddot{x} + b\dot{x} + kx = F_e$$

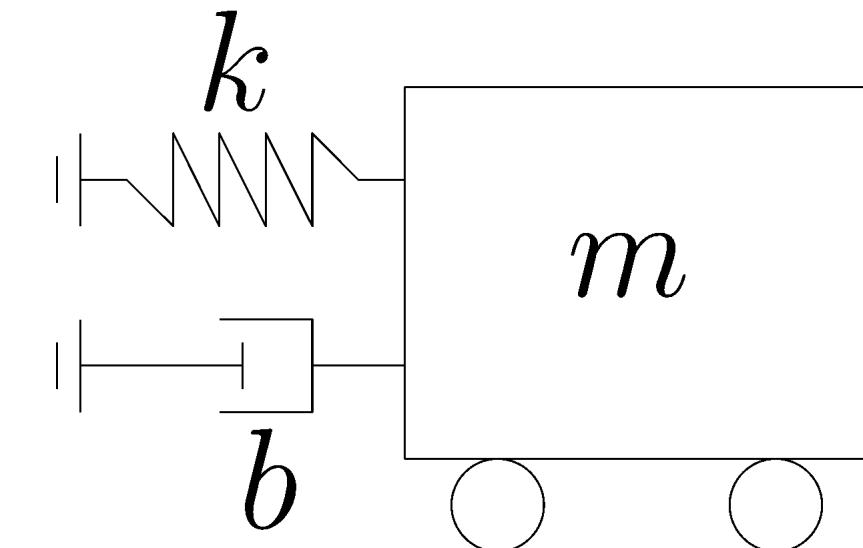
$$x(t) = \mathcal{R} \{ \hat{x} e^{i\omega t} \}$$

$$Z = b + i \left(\omega m - \frac{k}{\omega} \right)$$

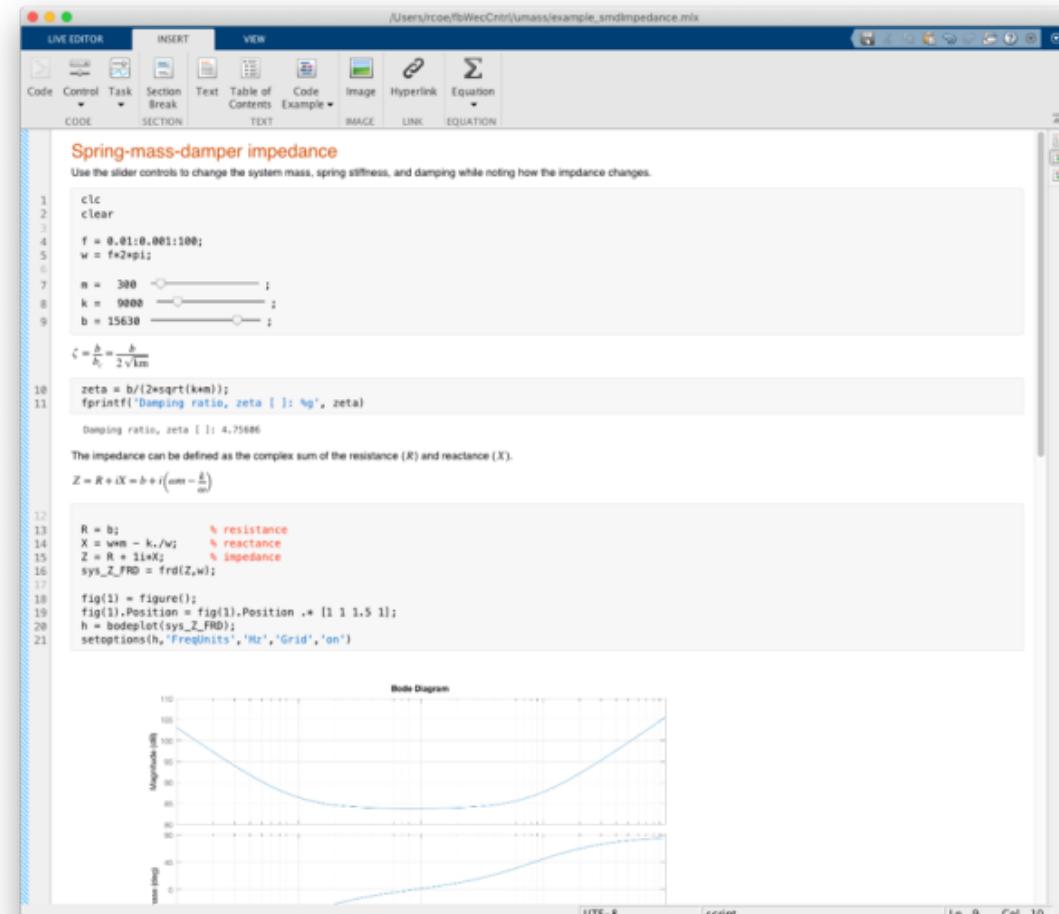


$$\hat{u} = \frac{\hat{F}_e}{Z}$$

Spring-mass-damper (cont.)



$$Z = b + i \left(\omega m - \frac{k}{\omega} \right)$$



example_smdImpedance mlx

How do we define resonance?

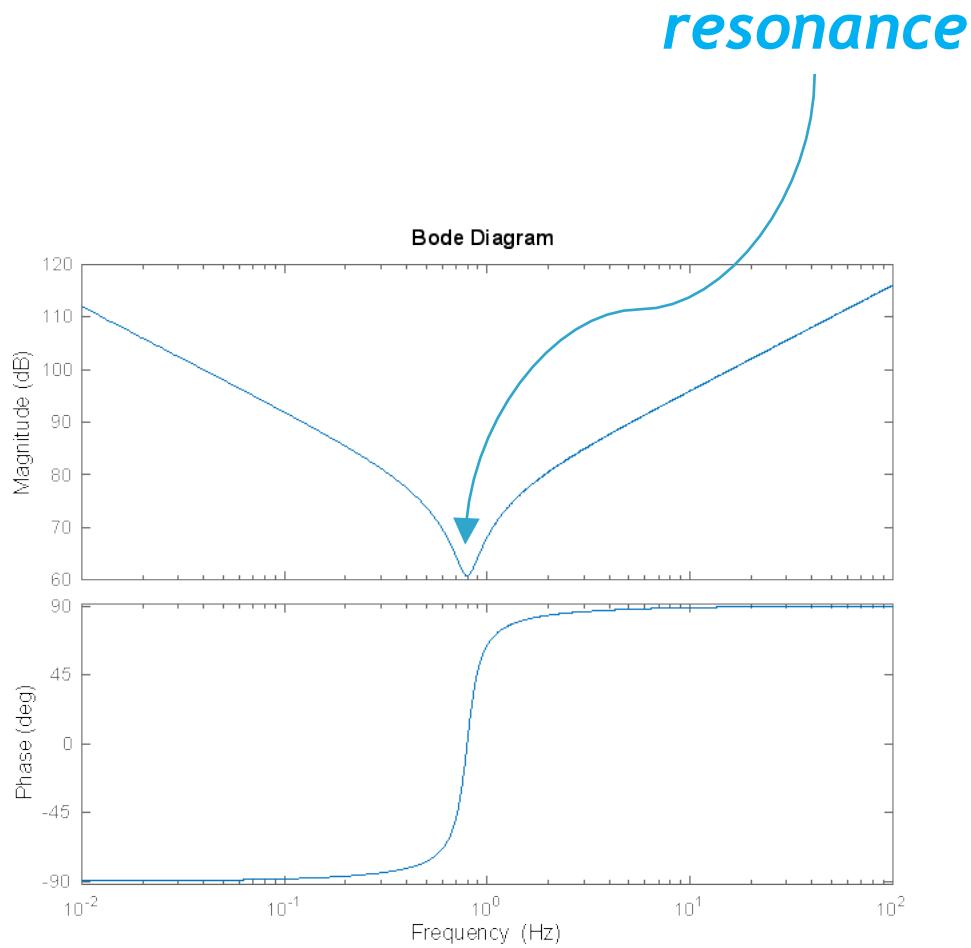
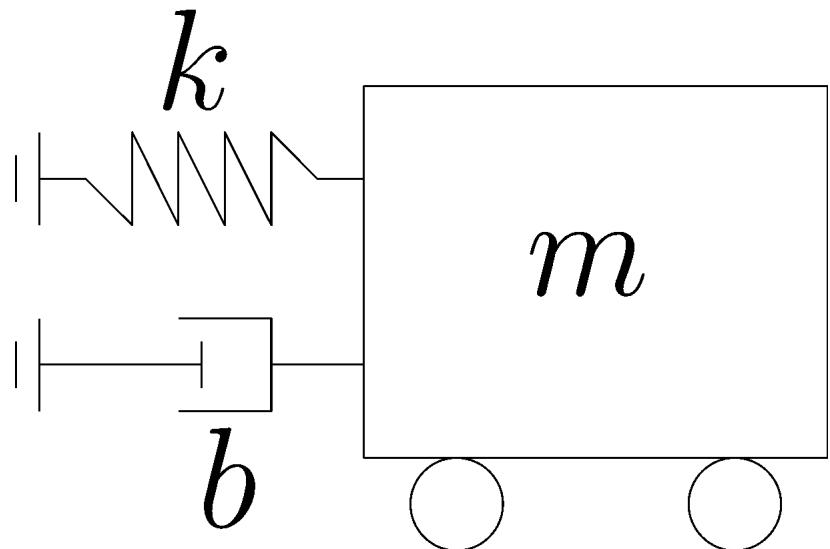


$$Z = b + i \left(\omega m - \frac{k}{\omega} \right)$$

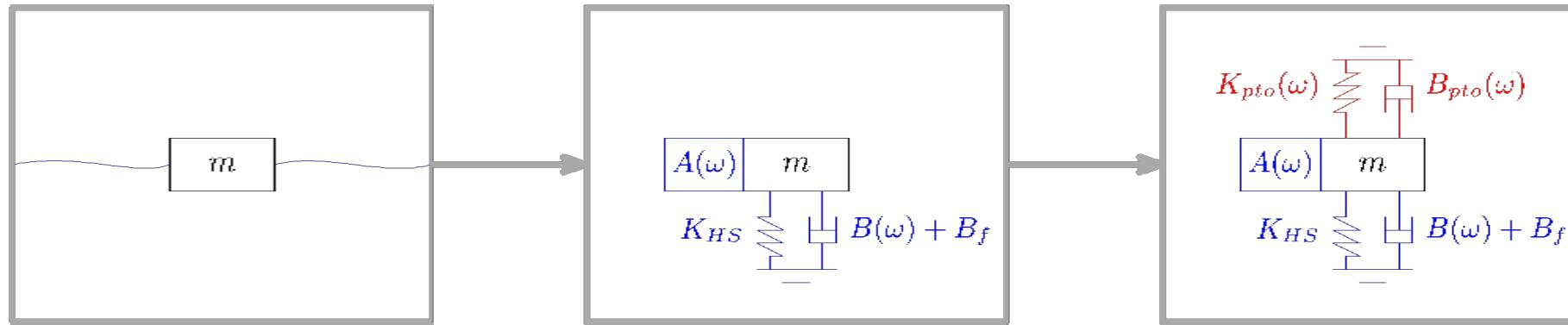
$$\angle \left[\frac{F}{u} \right] = 0$$

$$\angle [Z] = 0$$

$$\Im \{Z\} = 0$$



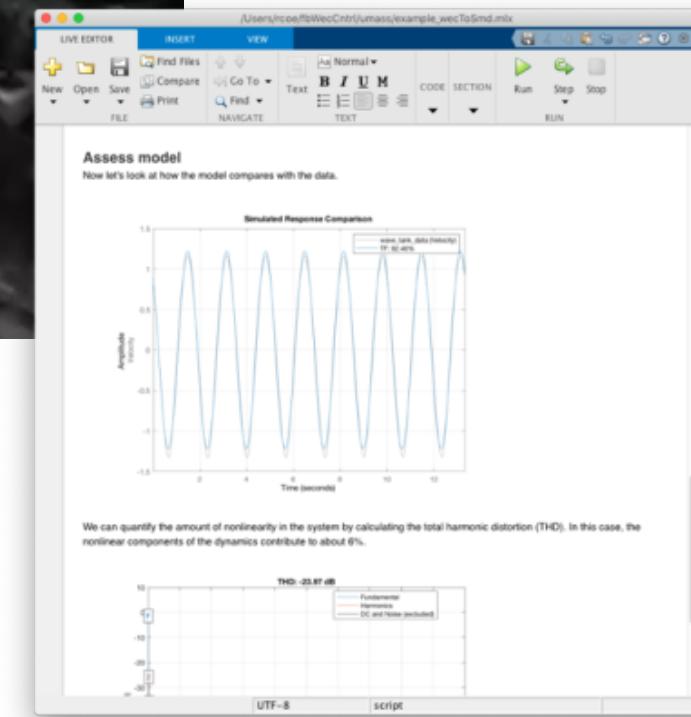
This framework is powerful, practical, and realistic



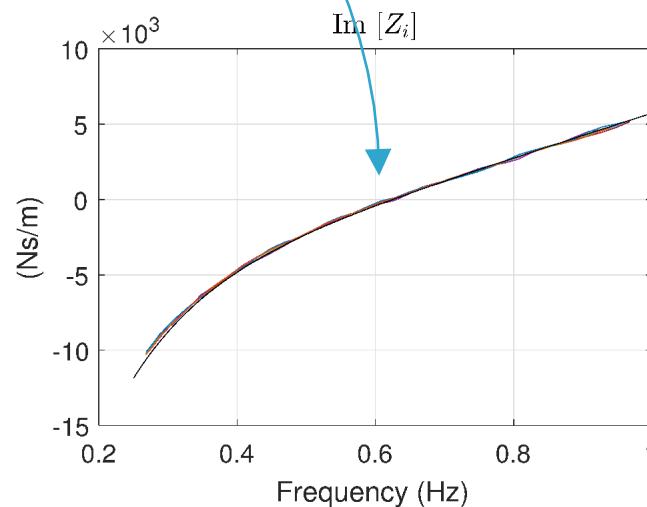
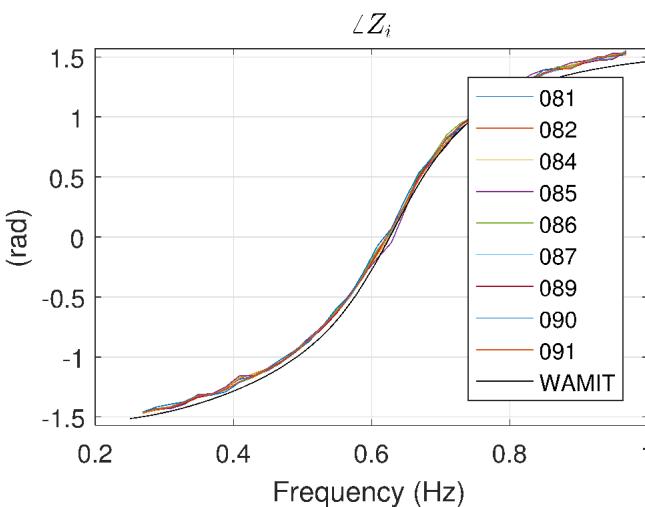
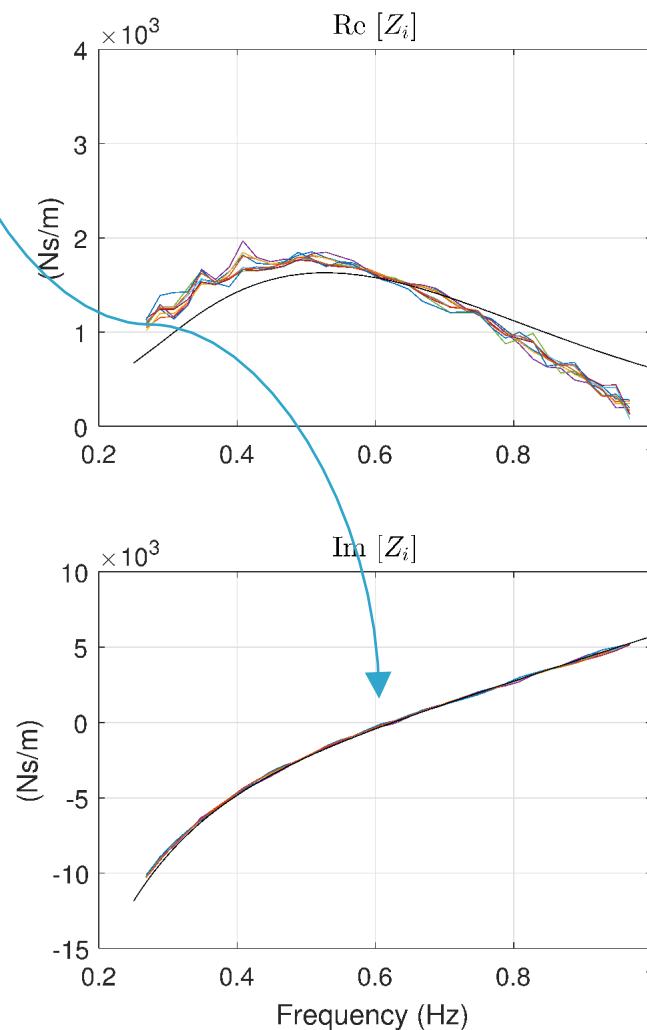
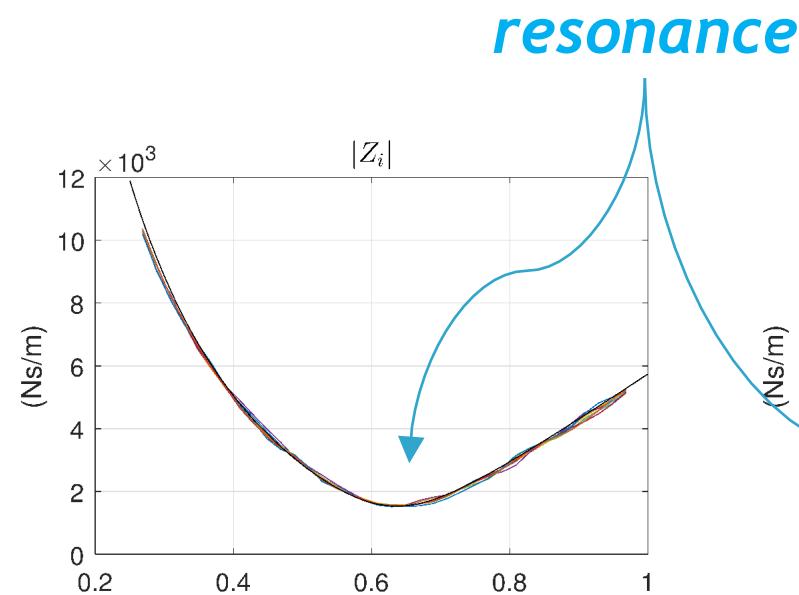
WEC to spring-mass-damper



*How realistic can a
spring-mass-damper
model be?*

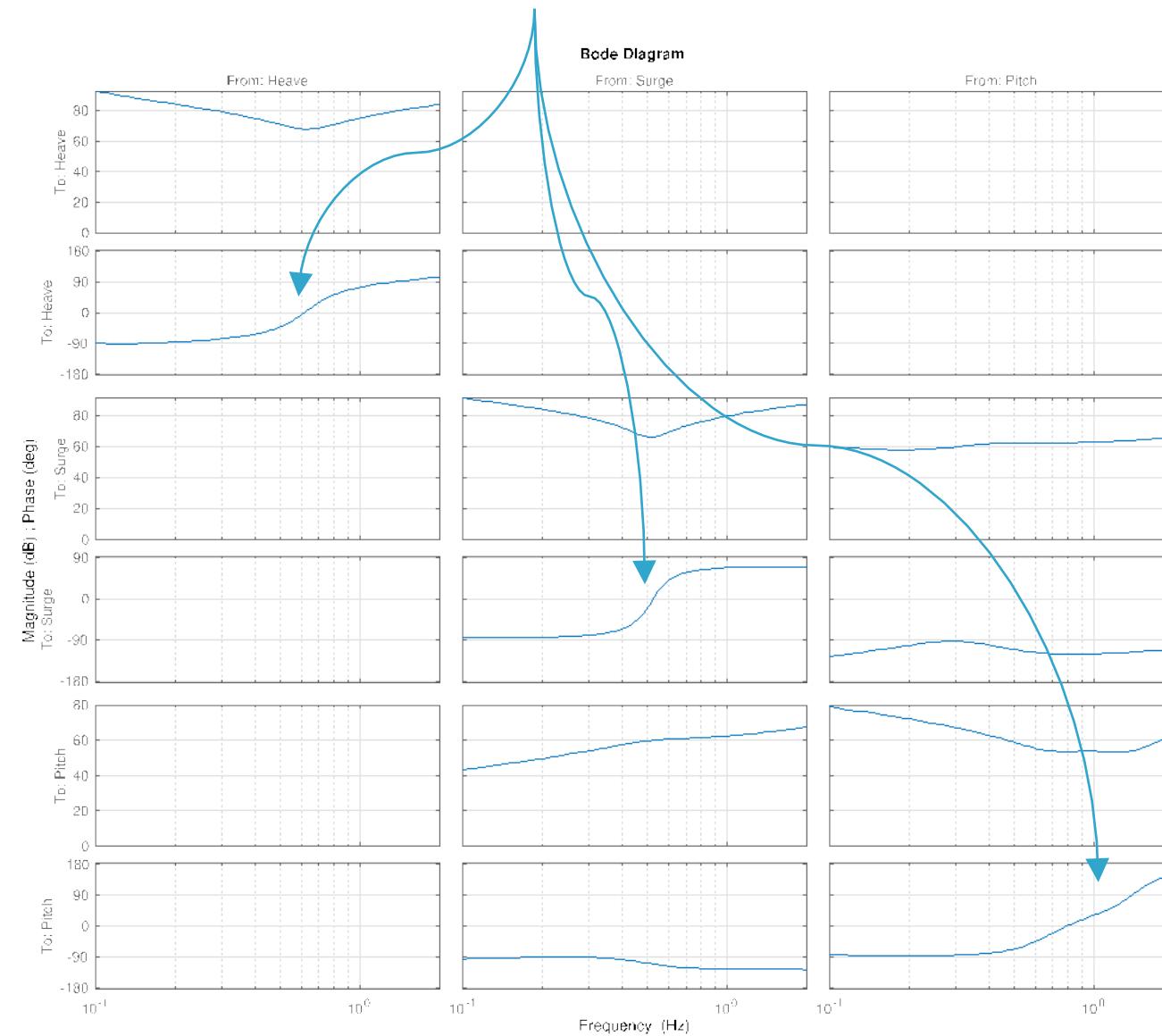


What does an impedance look like?

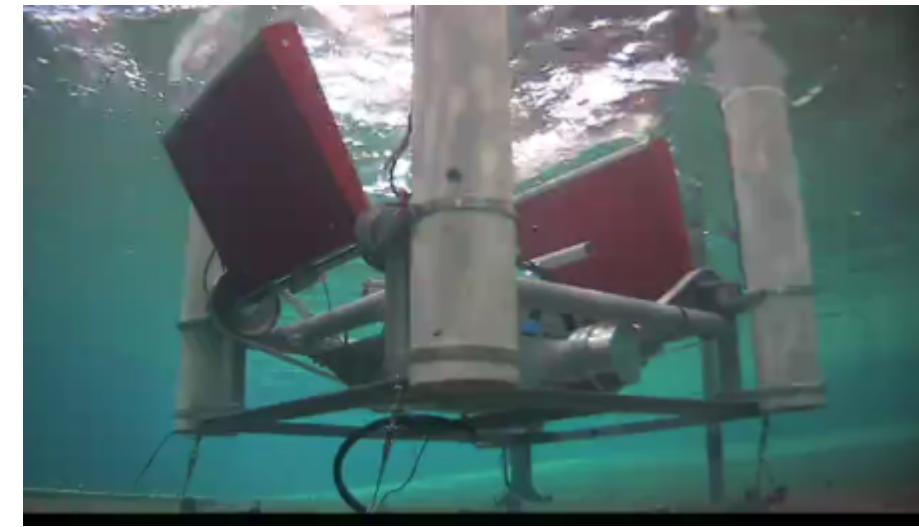
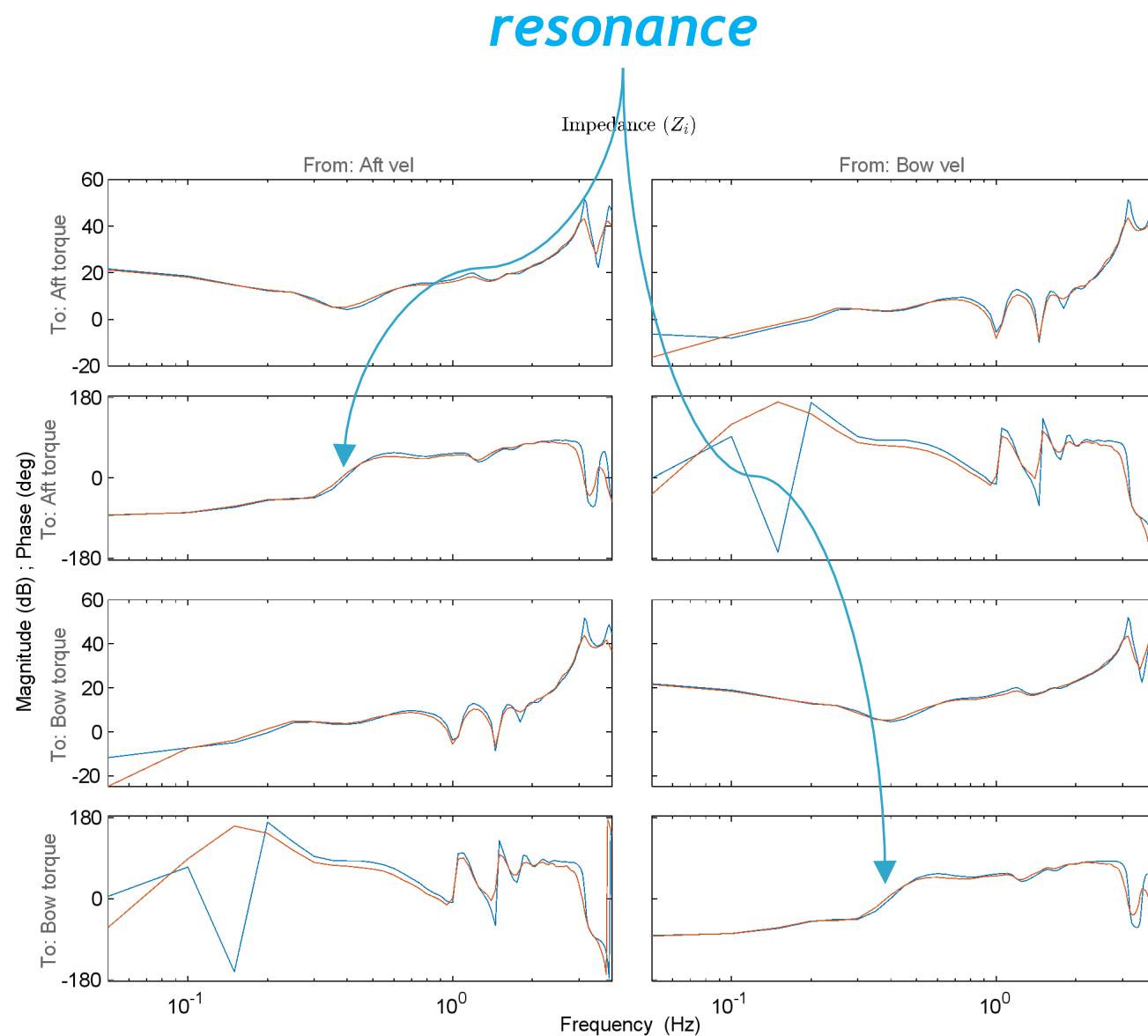


What does an impedance look like?

resonance



What does an impedance look like?

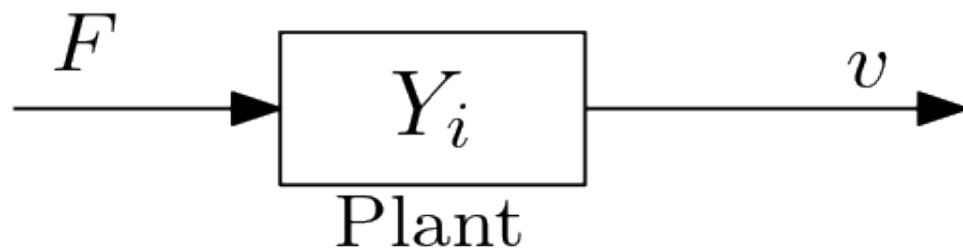




What is admittance?

$$Y(\omega) = \frac{1}{Z(\omega)}$$

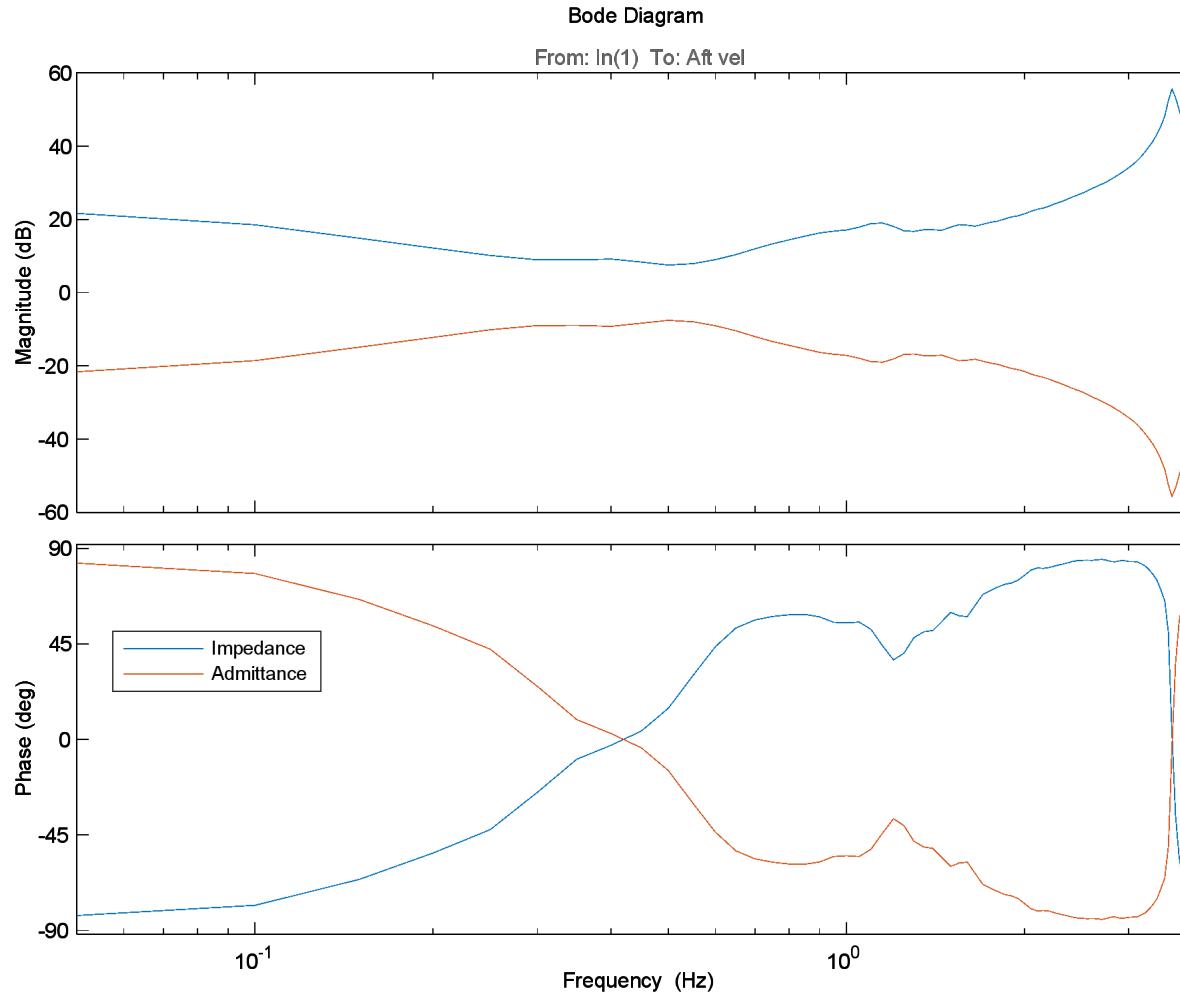
$$v(\omega) = \frac{F(\omega)}{Z(\omega)} = F(\omega)Y(\omega)$$



Admittance



What does it look like?



$$Y(\omega) = \frac{1}{Z(\omega)}$$

$$Z(\omega) = \frac{F(\omega)}{u(\omega)}$$

$$Y(\omega) = \frac{u(\omega)}{F(\omega)}$$

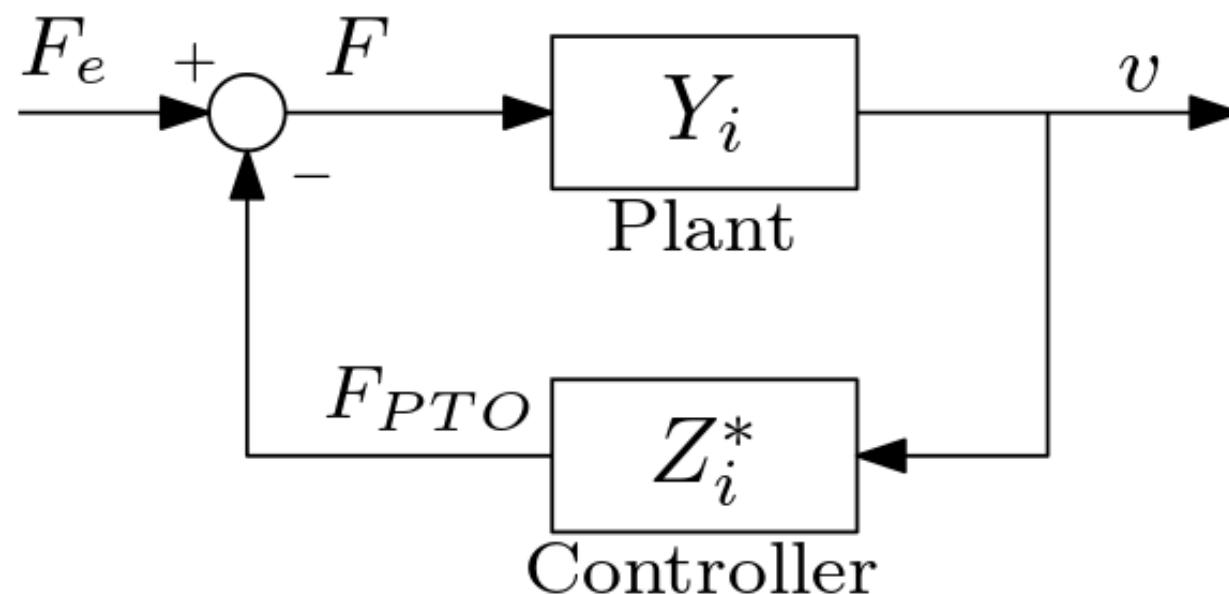
Impedance

and control



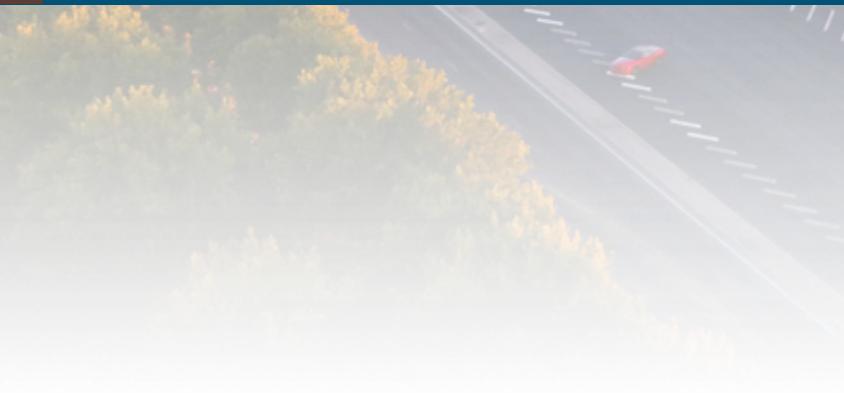
We can use the impedance (or admittance) to cleanly model a WEC

$$Z_i(\omega) = \underbrace{i\omega(M + m(\omega))}_{\text{mass}} + \underbrace{B_v + R(\omega)}_{\text{damping}} + \underbrace{\frac{S}{i\omega}}_{\text{stiffness}}$$





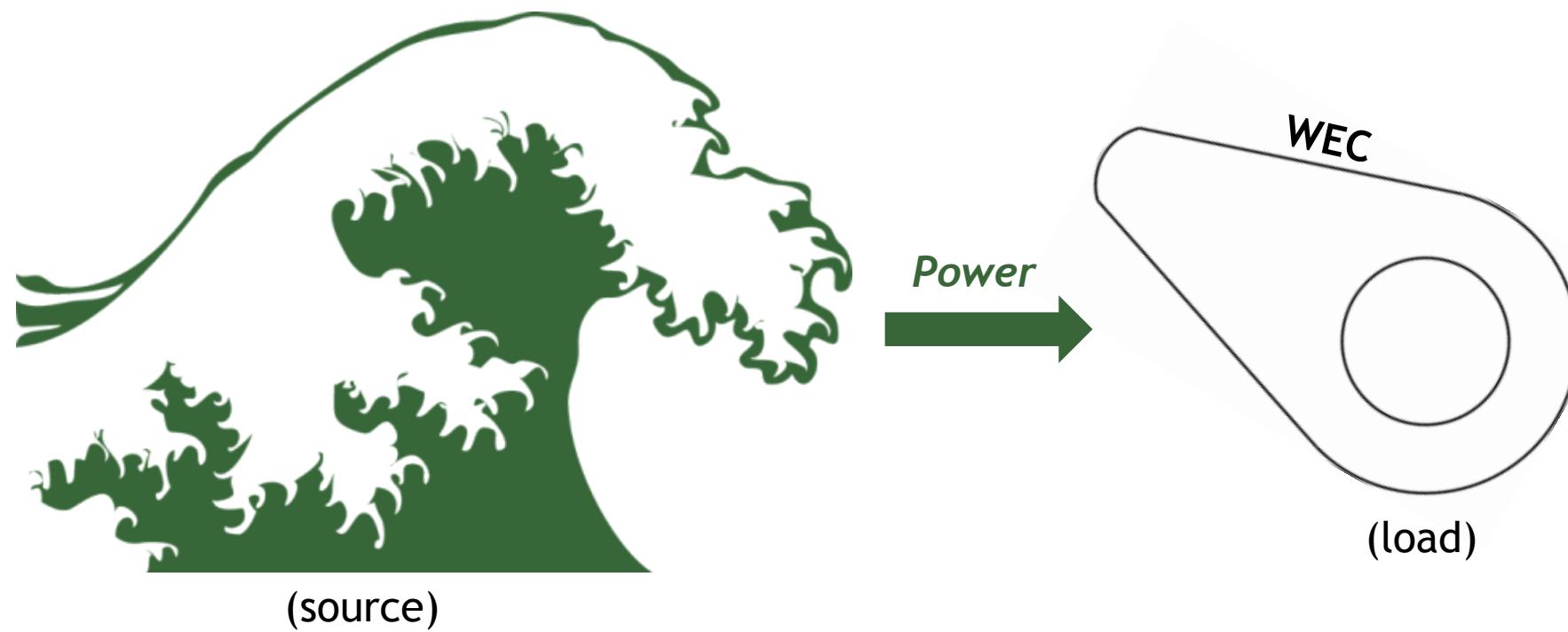
Controlling a WEC





Maximum power transfer (from waves to PTO)

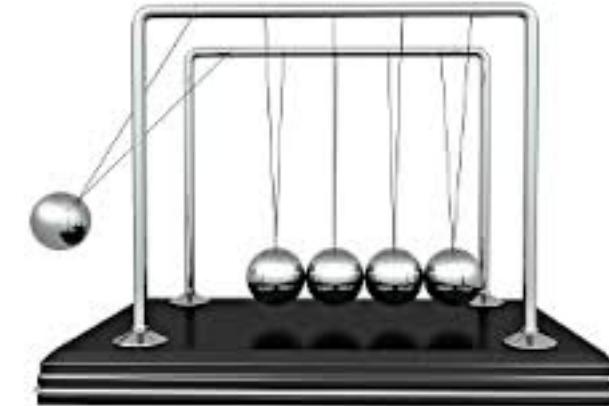
$$Z_{source} = Z_{load}^*$$



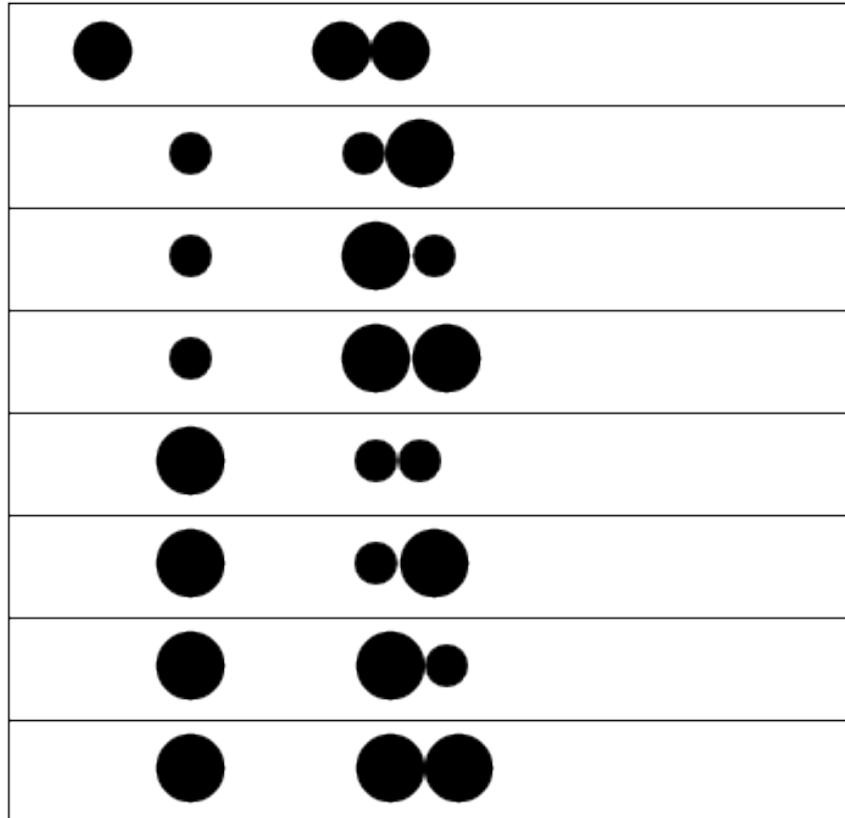
Impedance matching



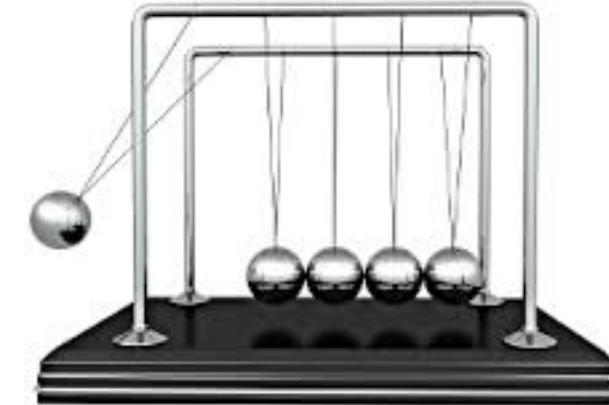
Where else is this used?



Impedance matching



<http://www.lockhaven.edu/~dsimanek>



Describing a WEC controller



$$Z_i(\omega) = i\omega \underbrace{(M + m(\omega))}_{\text{mass}} + \underbrace{B_v + R(\omega)}_{\text{damping}} + \underbrace{\frac{S}{i\omega}}_{\text{stiffness}}$$

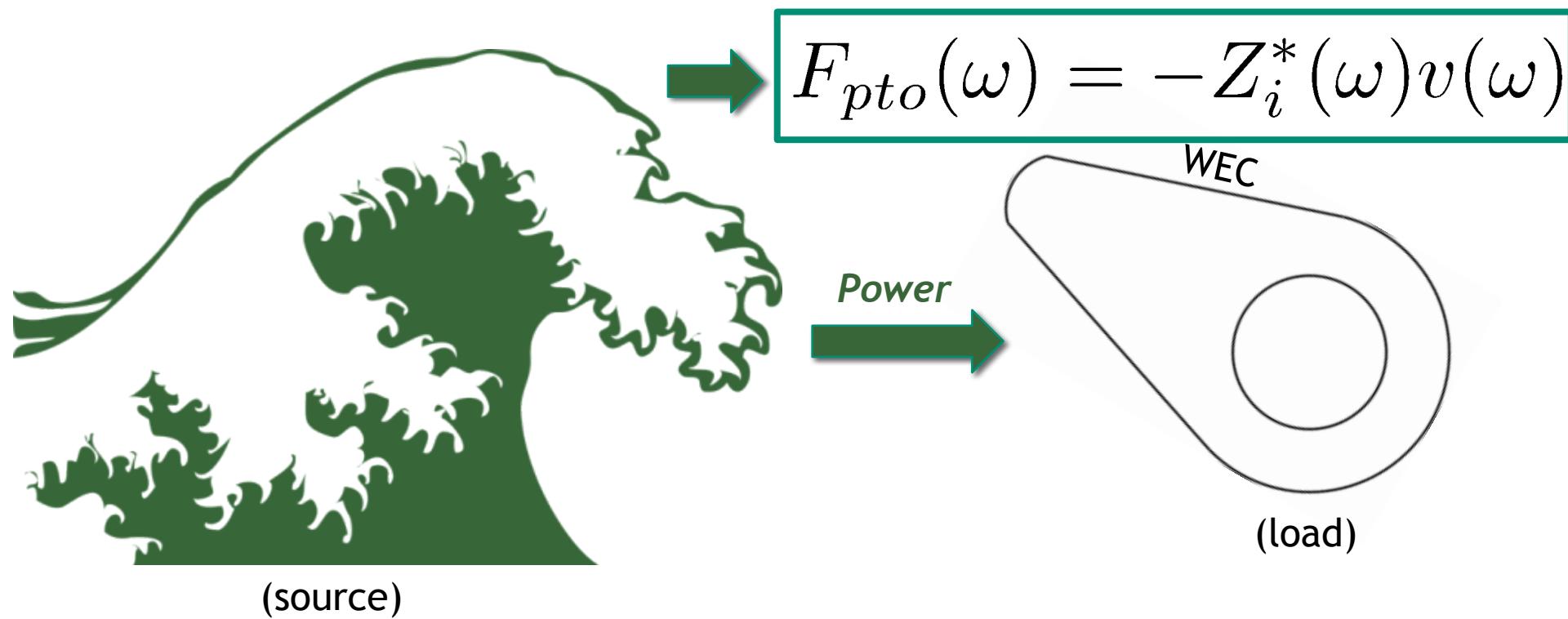
$$\begin{aligned} F_u(\omega) &= f(v(\omega)) \\ &= -Z_u(\omega)v(\omega) \end{aligned}$$



Maximum power transfer (from waves to PTO)

$$Z_{source} = Z_{load}^*$$

$$Z_i = Z_u^* \rightarrow (Z_i^* = Z_u)$$



Impedance matching (cont.)

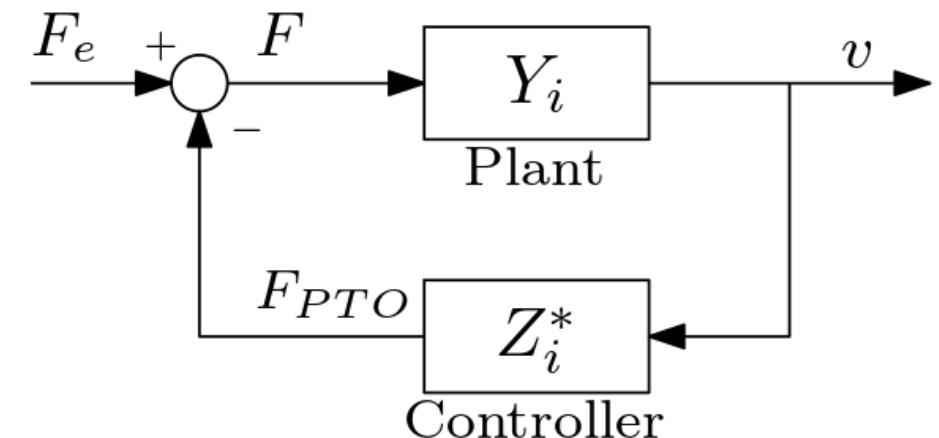
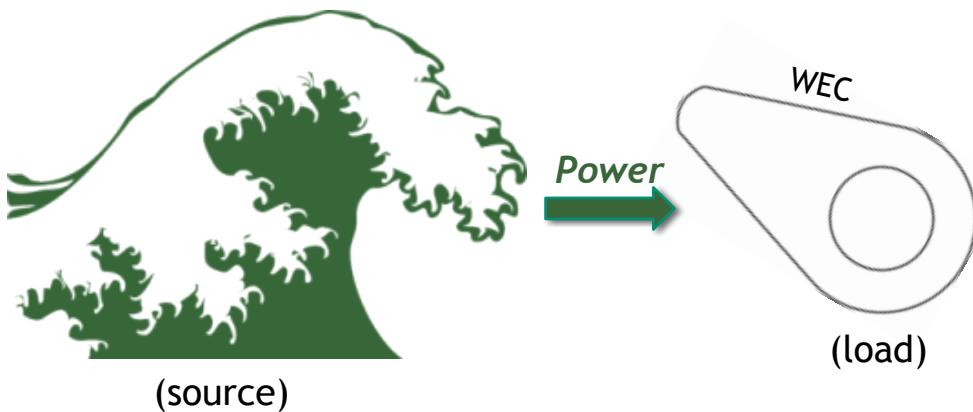


Maximum power transfer (from waves to PTO)

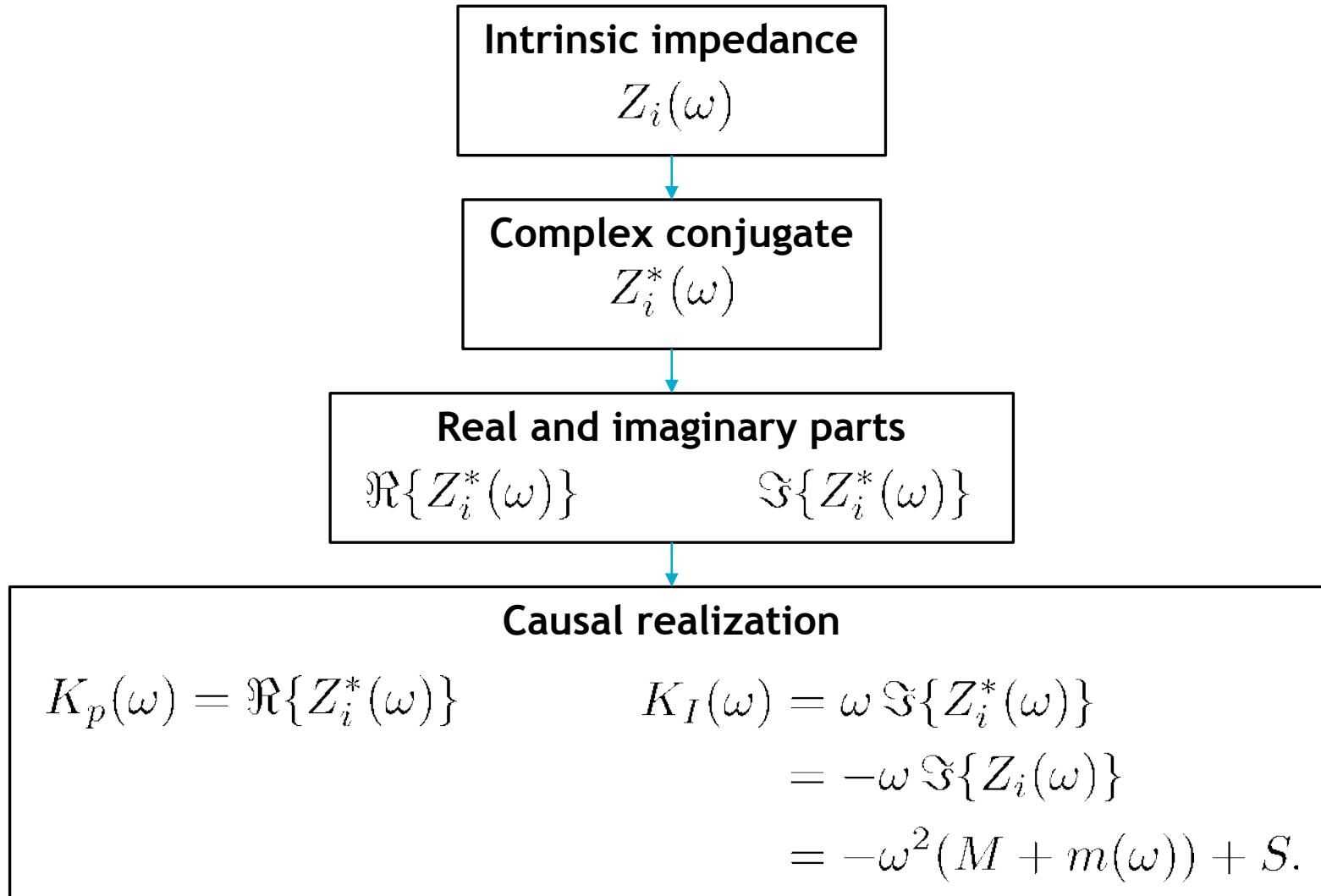
$$Z_{source} = Z_{load}^*$$

$$Z_i = Z_u^* \rightarrow (Z_i^* = Z_u)$$

→ $F_{pto}(\omega) = -Z_i^*(\omega)v(\omega)$



“WEC control hierarchy”





While perfectly implementing impedance matching in a causal controllers is not possible, we can come quite close

$$C_{PID}(s) = \frac{K_D s^2 + K_P s + K_I}{s} \frac{1}{s + p}$$

derivative gain proportional gain integral gain

*most of us learn about “PID” in the context of error minimization, this is not really the intent here

high frequency pole

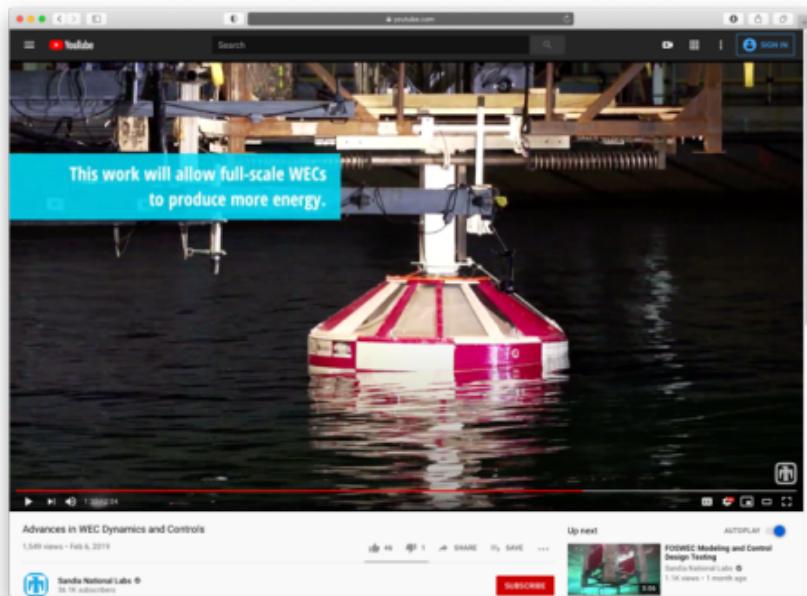
Example: Designing P and PI controllers for a WEC



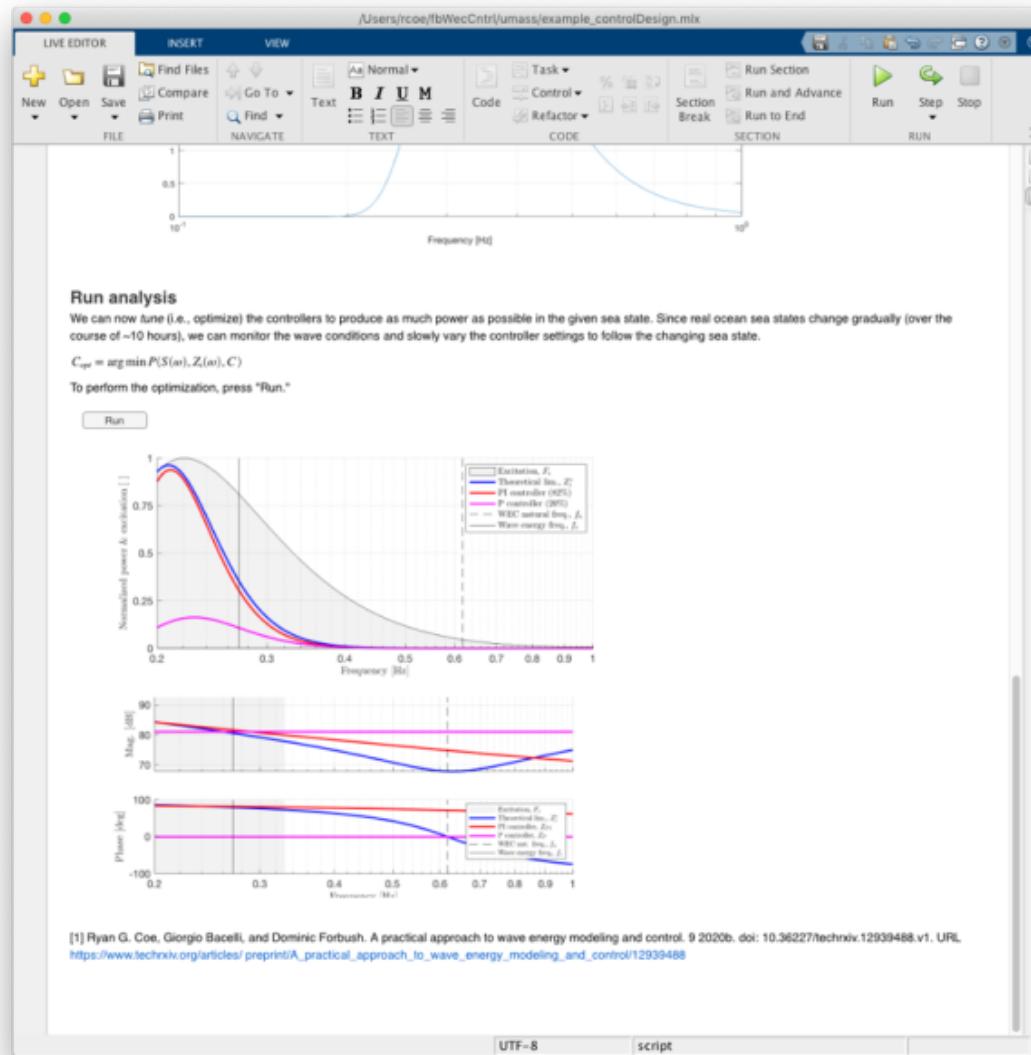
$$C_{opt} = \arg \min P(S(\omega), Z_i(\omega), C)$$



Vary controller to maximize power



https://youtu.be/c4npWk_-Pjk



example_controlDesign.mlx