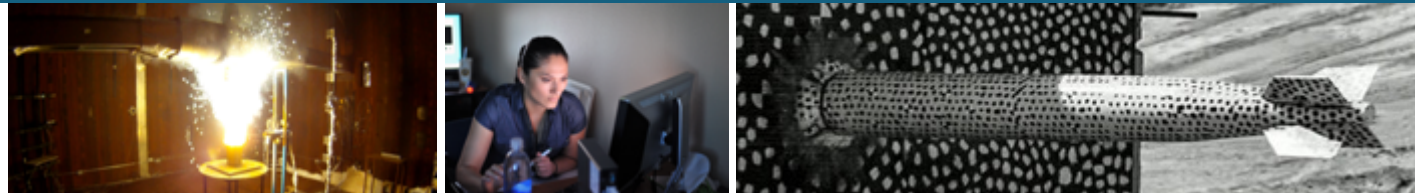


Applied WEC modeling and control design

Oct. 29 2020, UMass-Amherst



Presented by

Ryan Coe, rcoe@sandia.gov

Slides based on combined work of the author, Giorgio Bacelli, Dominic Forbush, Steven Spencer, and others



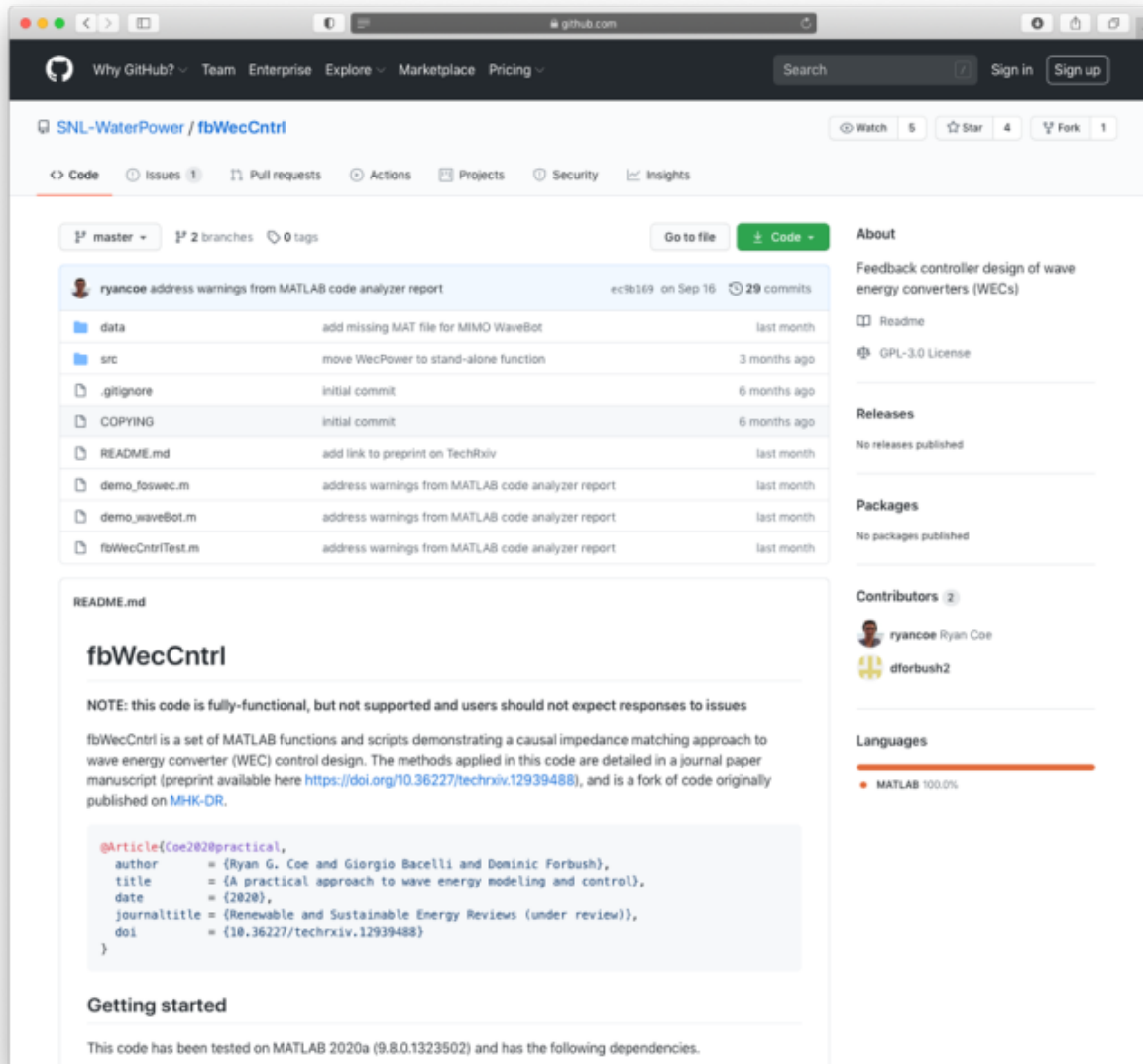
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Class agenda



- I. About me
- II. Wave energy background
- III. Case-study (with examples in MATLAB)
 - I. Modeling a WEC
 - II. Controlling a WEC

3 MATLAB examples



1. Go to the fbWecCntrl repository:
<https://github.com/SNL-WaterPower/fbWecCntrl>
 2. [Download](#) or clone the repository (clone preferred to allow for easier updates)
 3. Follow instructions installing*:
<https://github.com/SNL-WaterPower/fbWecCntrl#getting-started>
 4. The material for the lecture is located in the [seminar examples](#) directory
- * Note that WAFO (<https://github.com/wafo-project/wafo>) is used to generate JONSWAP wave spectra - you will need this too to run some of the examples



About me



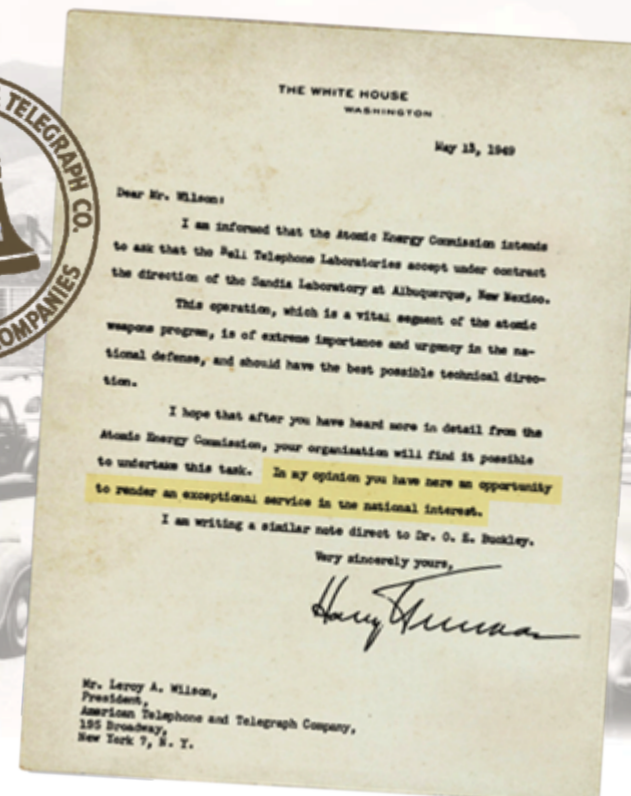
Sandia National Labs



Exceptional service in the national interest

- July 1945: Los Alamos creates Z Division
- Nonnuclear component engineering
- November 1, 1949: Sandia Laboratory established

to undertake this task. In my opinion you have here an opportunity to render an exceptional service in the national interest.



Albuquerque, NM





BS and PhD from Virginia Tech (Go Hokies!)

Sandia researcher for ~7 years

Hobbies: fly fishing, rock climbing, linear algebra

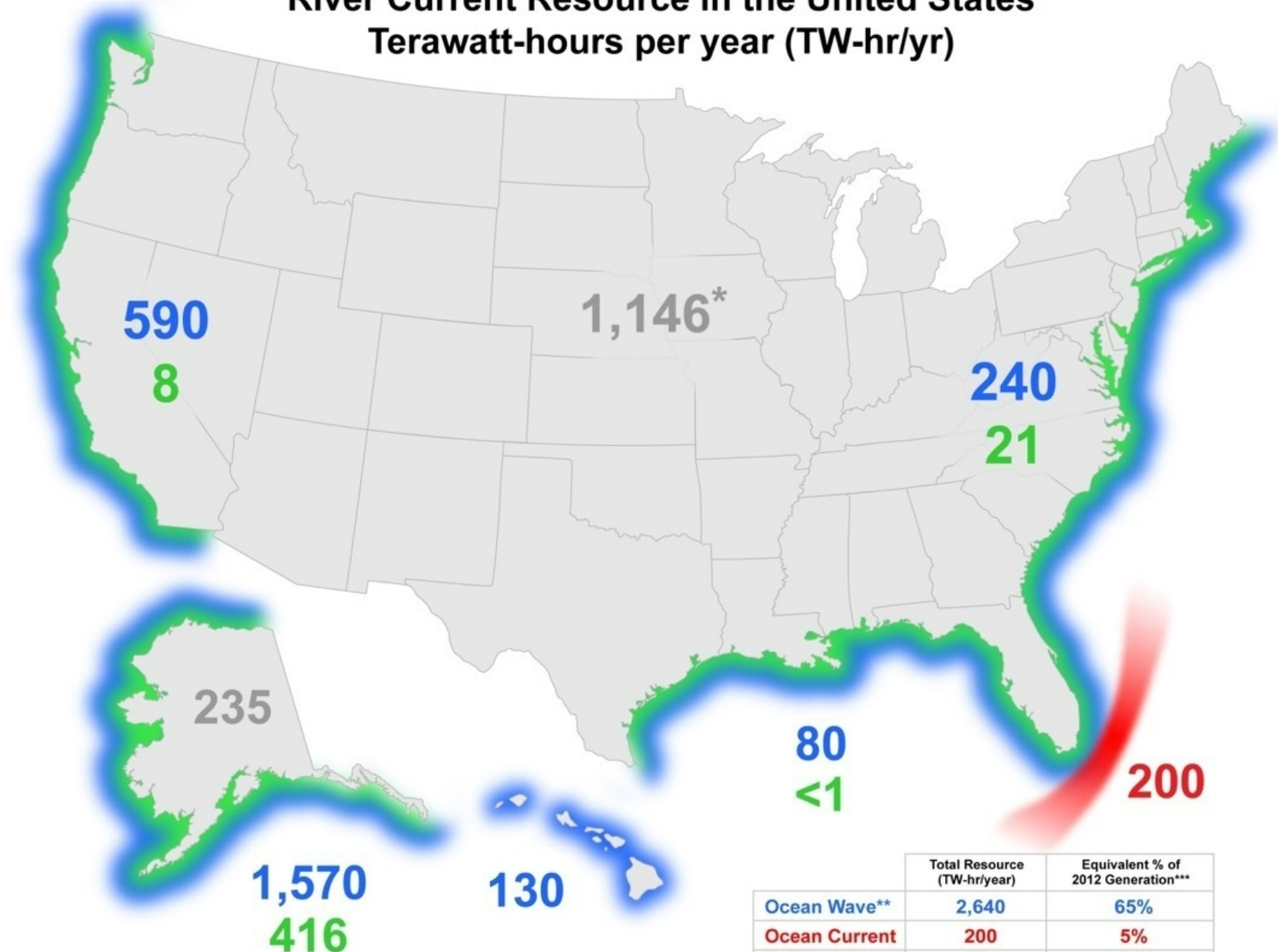




Background



The Ocean Wave, Ocean Current, Tidal Current, and River Current Resource in the United States Terawatt-hours per year (TW-hr/yr)



	Total Resource (TW-hr/year)	Equivalent % of 2012 Generation***
Ocean Wave**	2,640	65%
Ocean Current	200	5%
Tidal Current	445	11%
River Current	1,381	34%

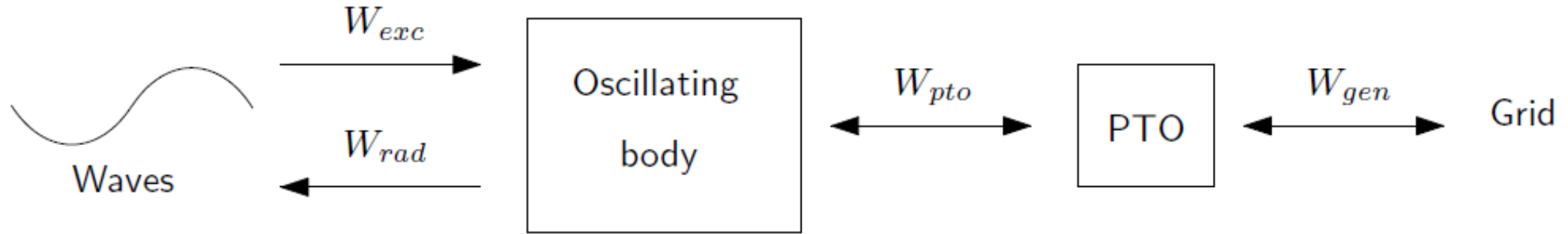
Ocean Wave: P. Jacobson, G. Hagerman, and G. Scott, "Mapping and Assessment of the United States Ocean Wave Energy Resource," Electric Power Research Institute, Report Number 1024637, 2011.
Ocean Current: K. Haas, H. Fritz, S. French, and V. Neary, "Assessment of Energy Production Potential from Ocean Currents Along the United States Coastlines," Georgia Tech Research Corporation, 2013.
Tidal Current: K. Haas, H. Fritz, S. French, S. Smith, and V. Neary, "Assessment of Energy Production Potential from Tidal Streams in the United States," Georgia Tech Research Corporation, 2011.
River Current: T. Ravens, K. Cunningham, and G. Scott, "Assessment and Mapping of the Riverine Hydrokinetic Resource in the Continental United States," Electric Power Research Institute, Report Number 1026880, 2012.

**Resource distributed throughout the river systems in the United States.

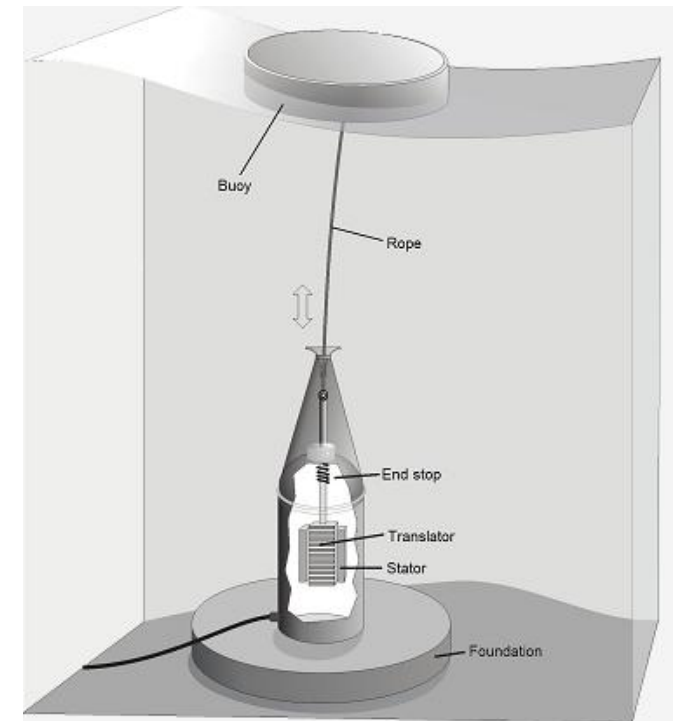
***Resource data for the 200-m depth contour.

***The size of the resource with respect to total U.S. electricity generation in 2012, which was 4,654 TW-hr (U.S. Energy Information Administration, "Electric Power Monthly," May 2013).

What is a Wave Energy Converter?



Energy transfer through an oscillating body wave energy converter



Most of the energy within a wave is contained near the surface.



wave energy devices are designed to stay near the water surface to maximize the energy available for capture

Mean surface level

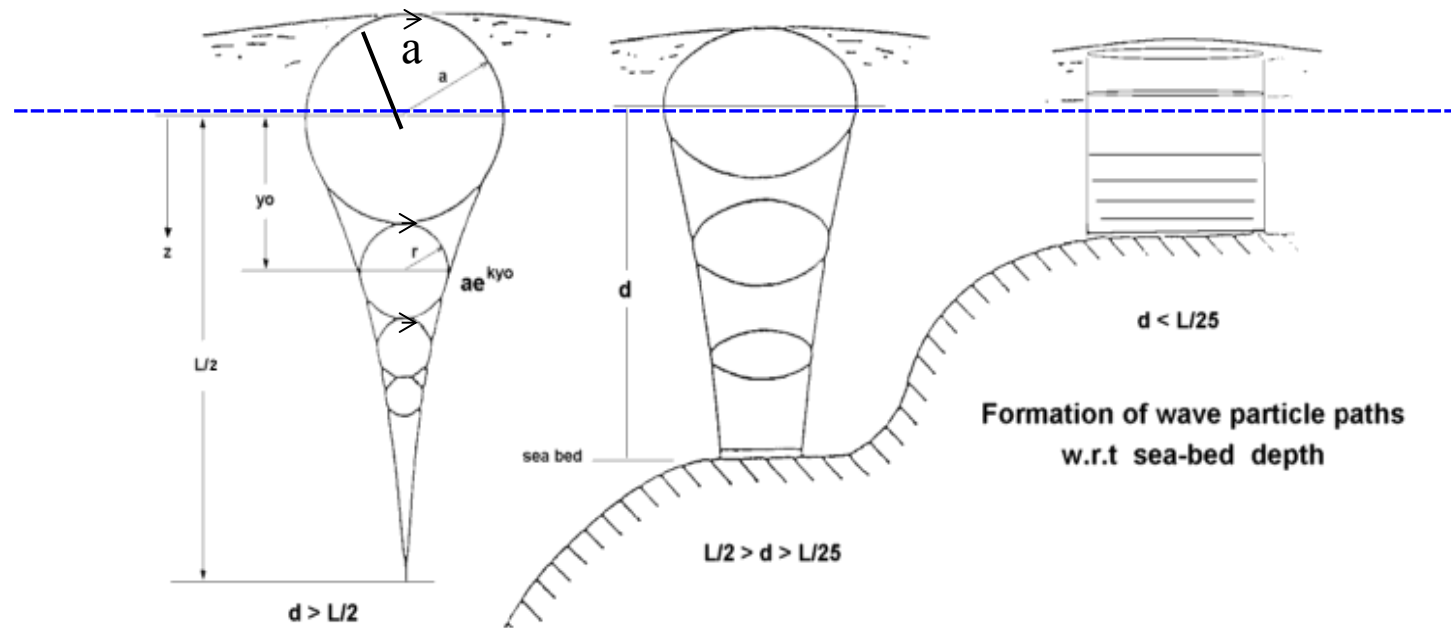
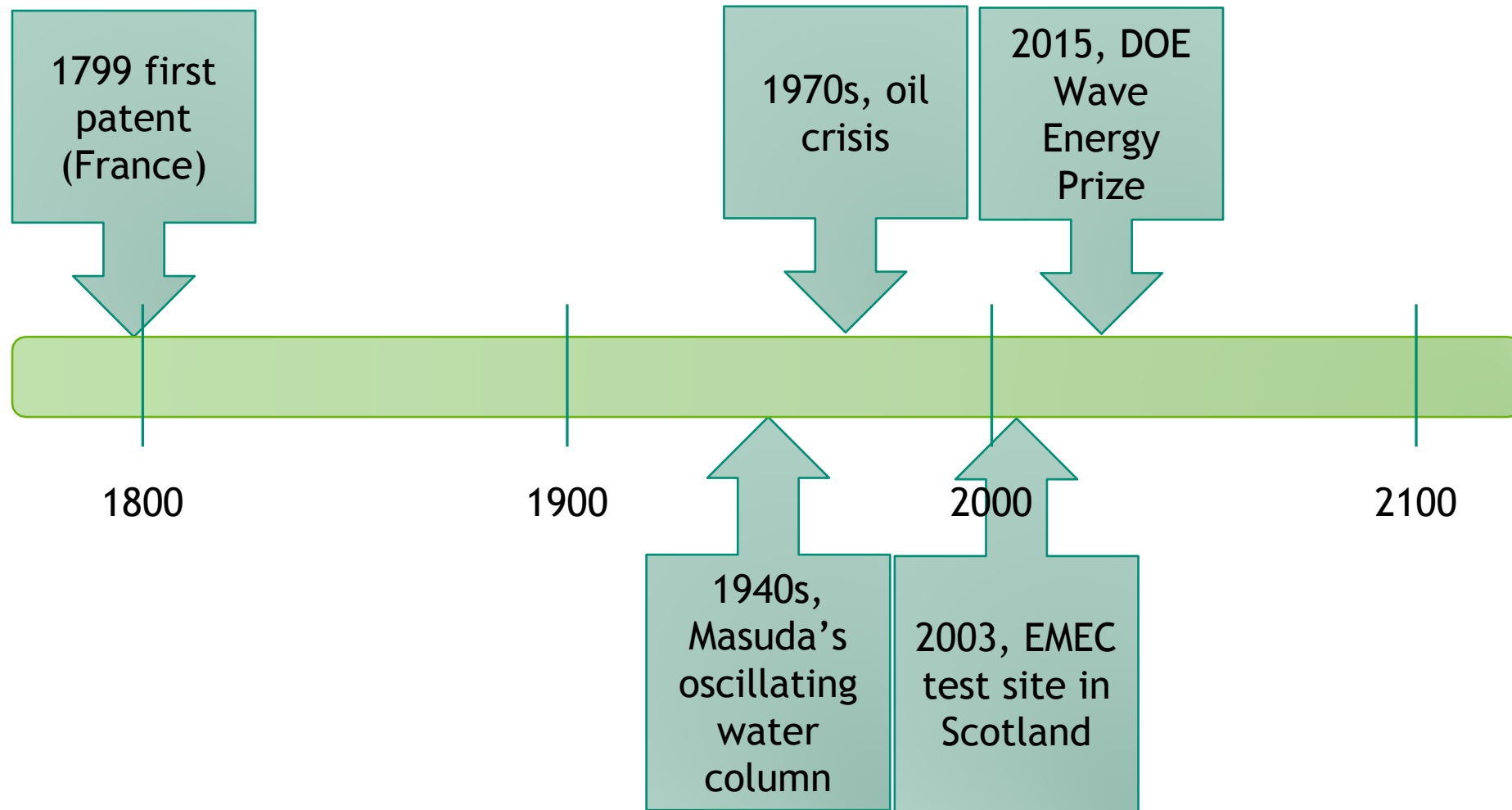
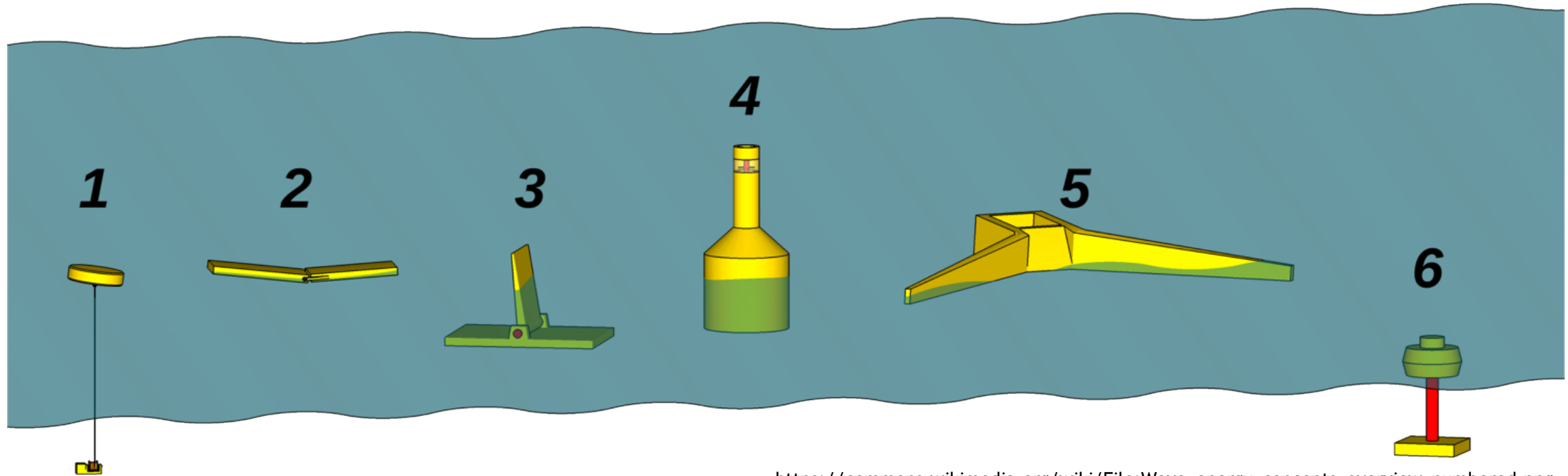


Fig. orbital motion of the water particles

Wave energy, a (brief) history

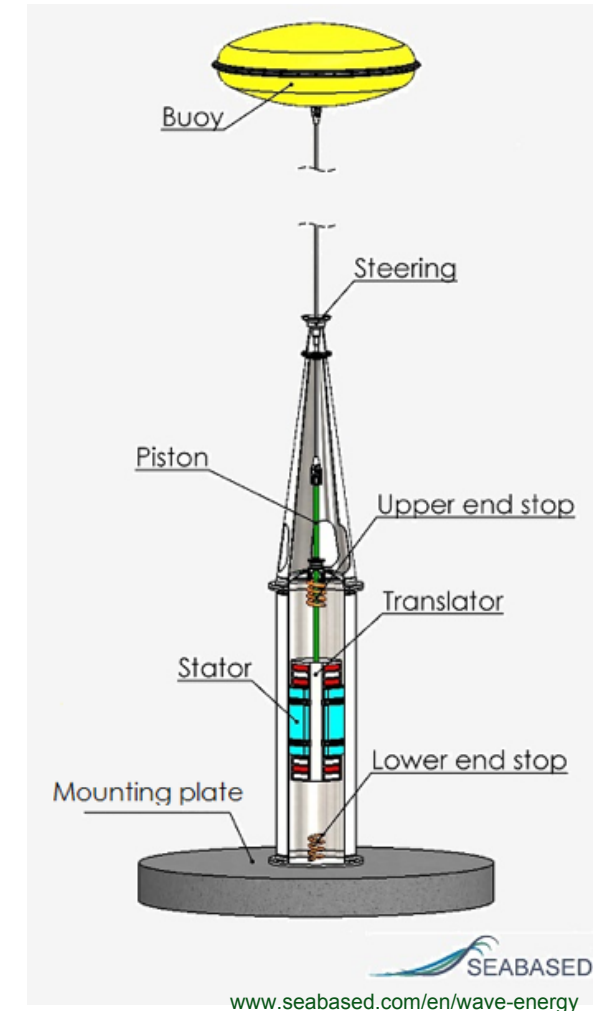
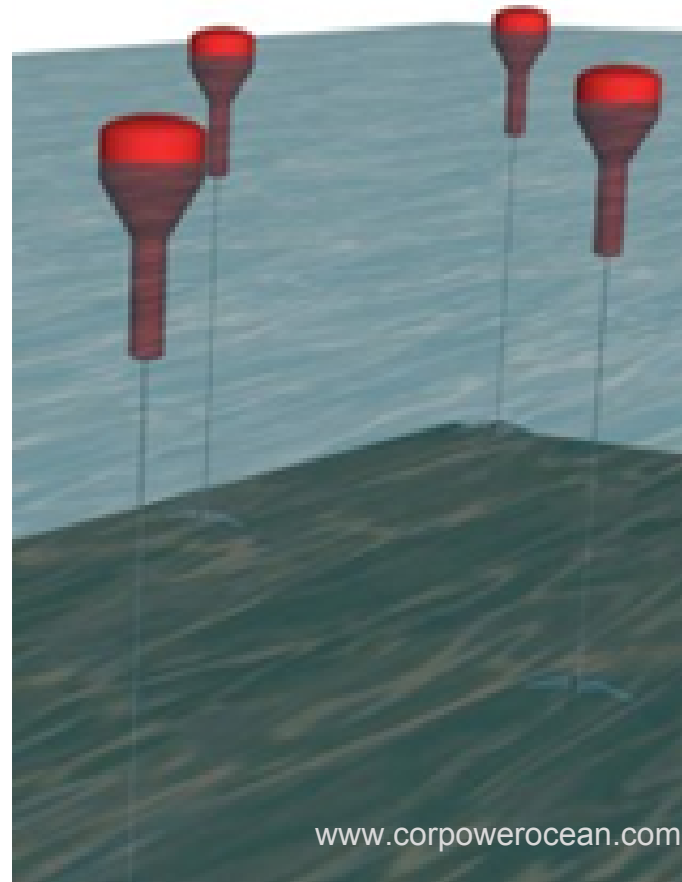
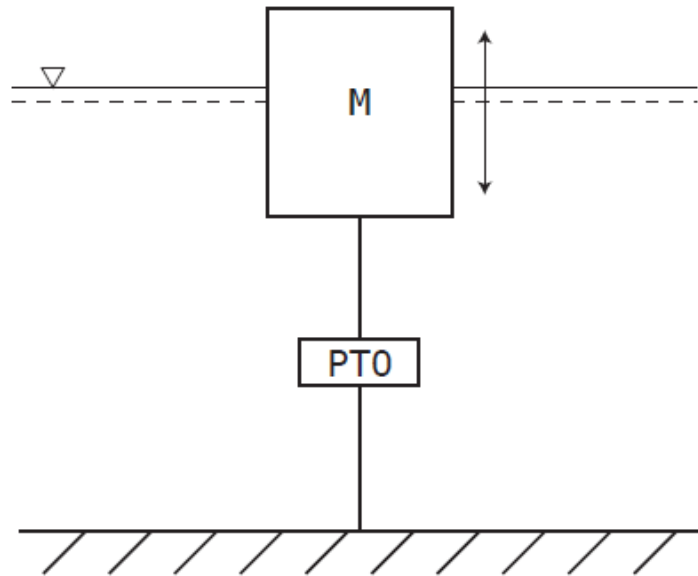


Wave energy concepts

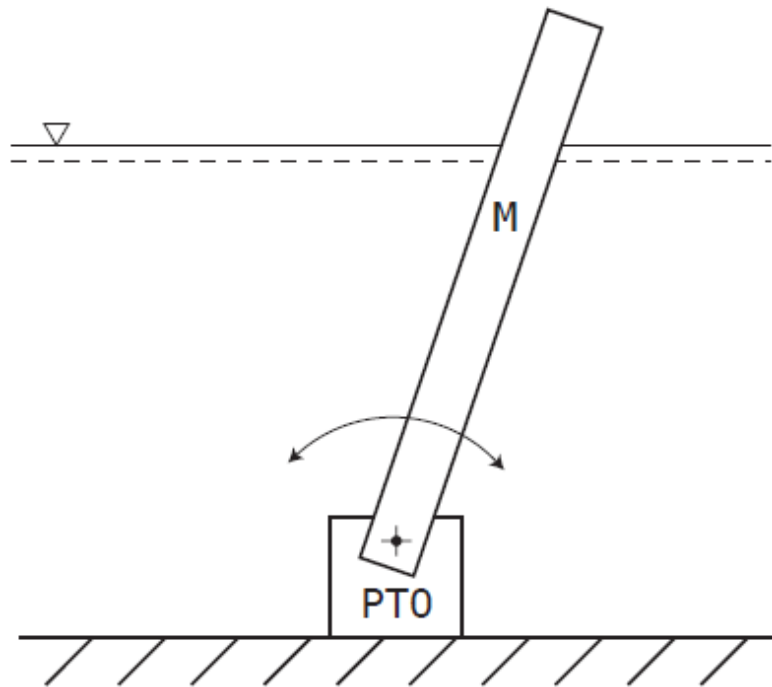


https://commons.wikimedia.org/wiki/File:Wave_energy_concepts_overview_numbered.png

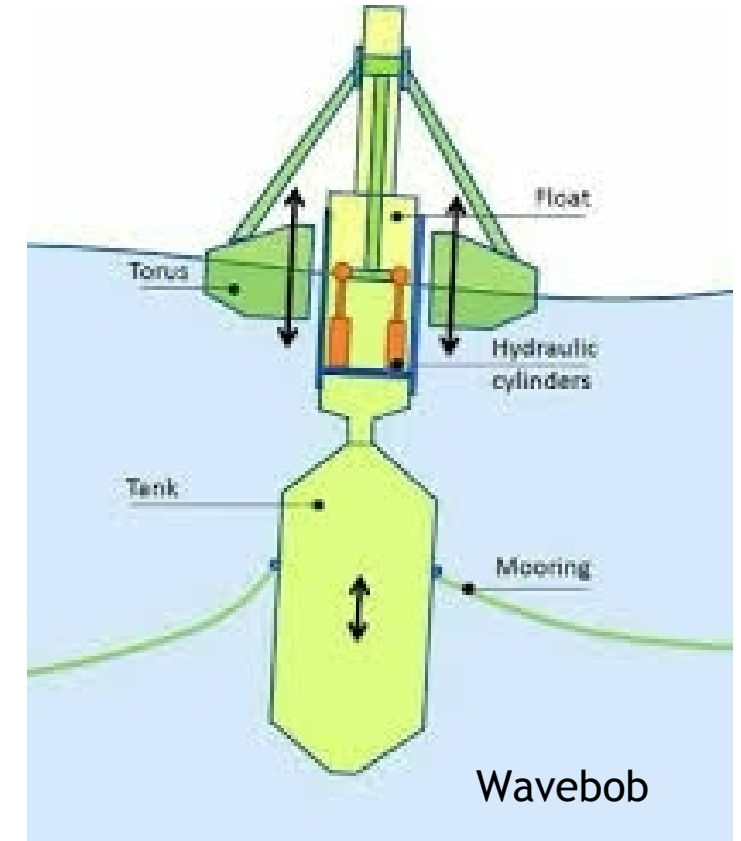
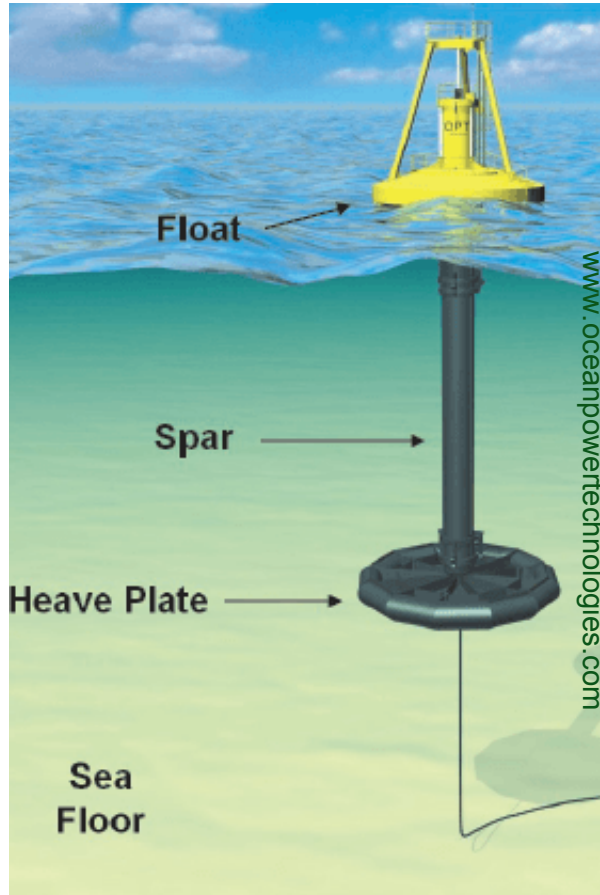
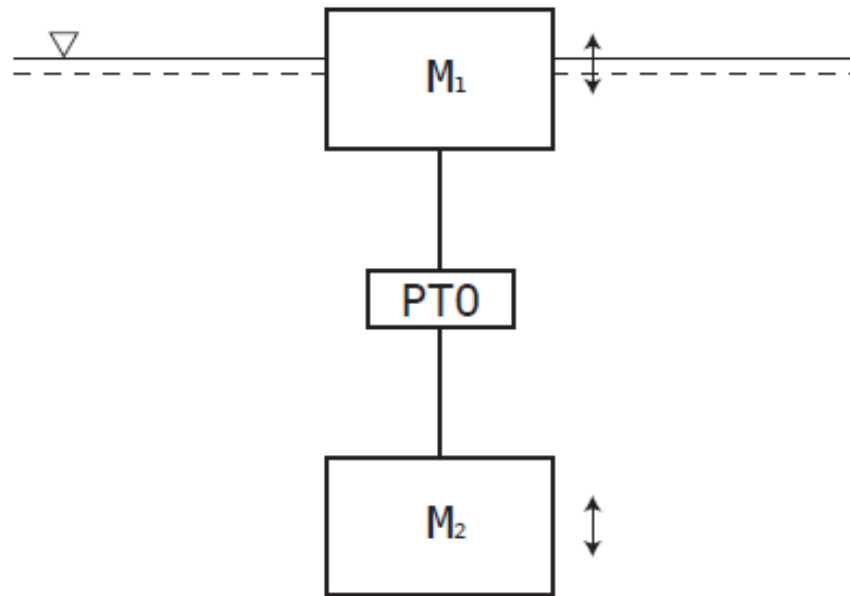
Wave energy concepts – heaving point absorber



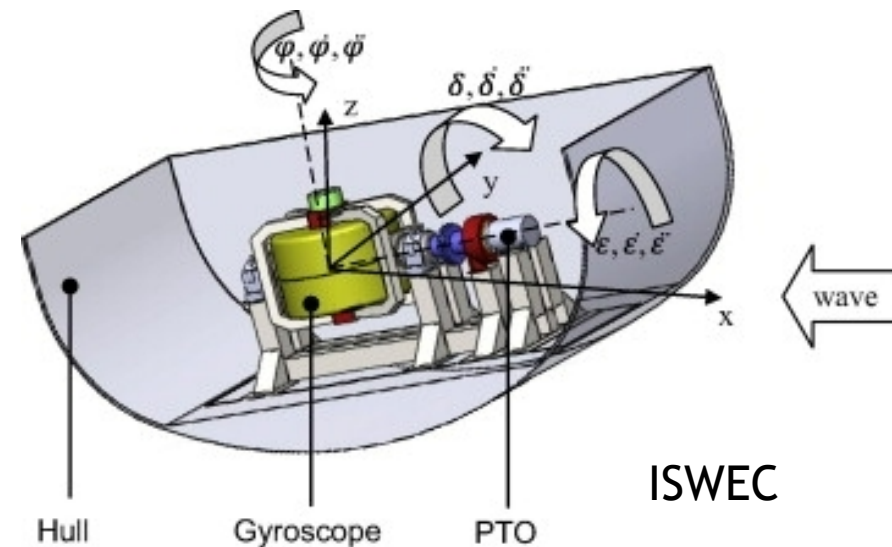
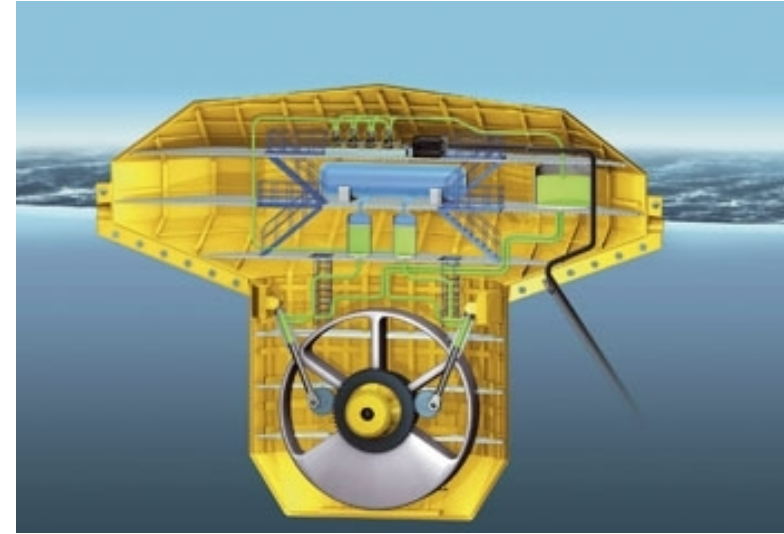
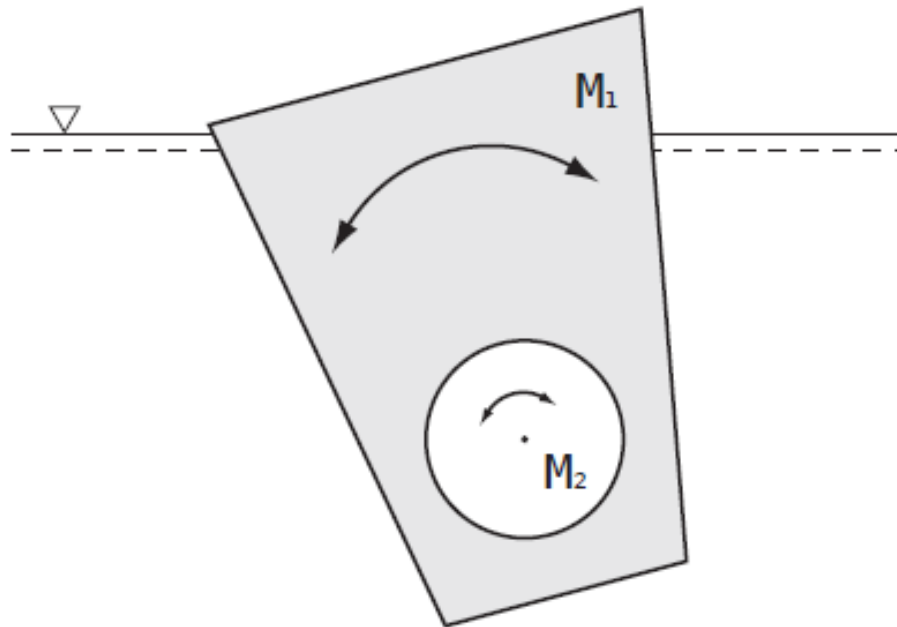
Wave energy concepts – pitching (flapping) device



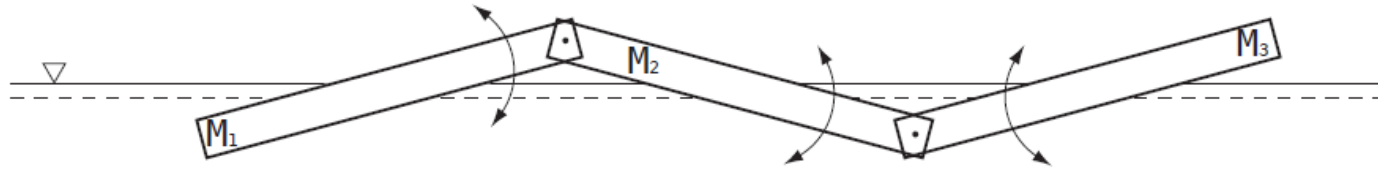
Wave energy concepts - Self-reacting point absorber



Wave energy concepts - Self-reacting wave energy converter with internal mass

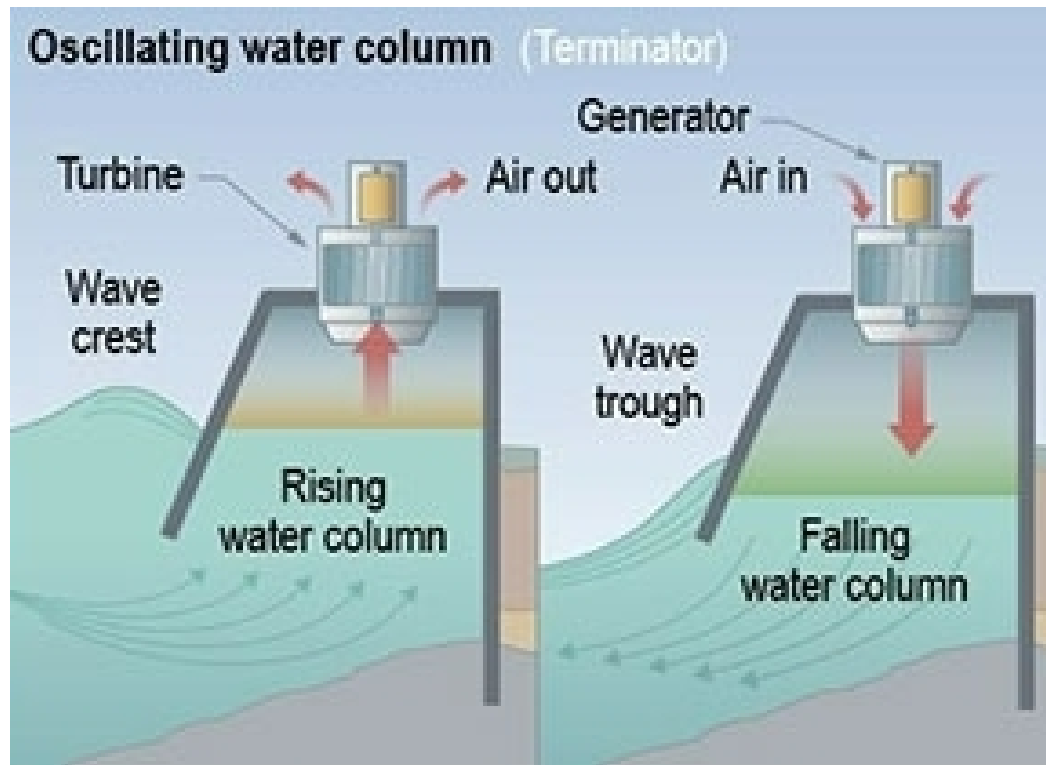


Wave energy concepts - attenuators



Pelamis wave energy

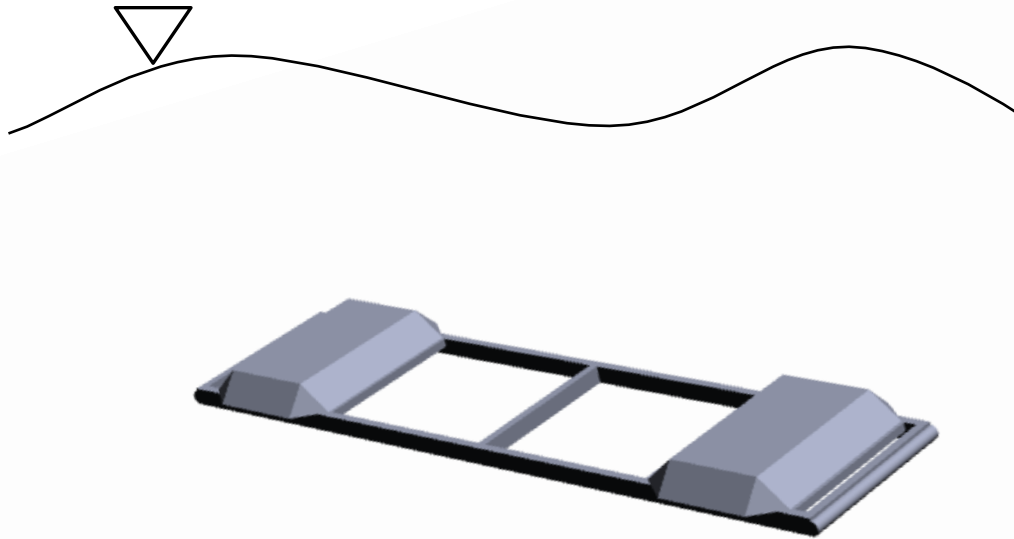
Wave energy concepts – oscillating water column (OWC)



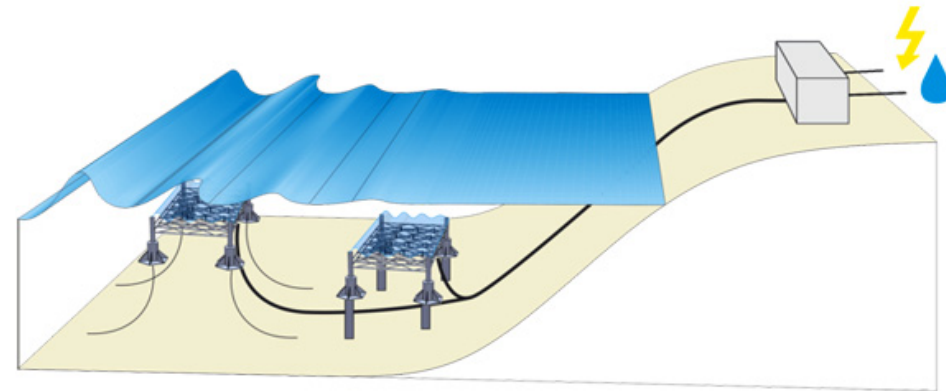
Wave energy concepts



Pressure differential devices



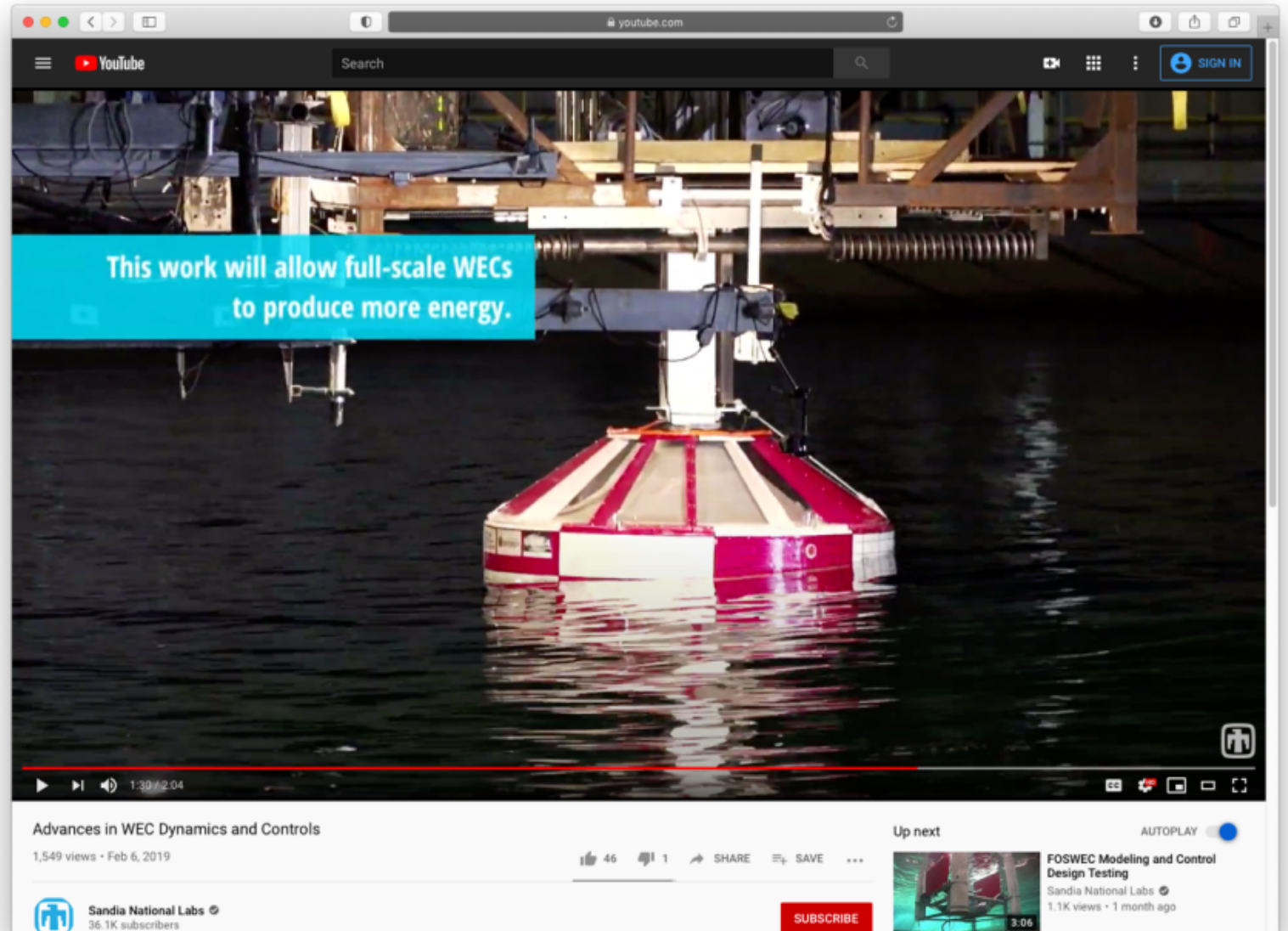
<https://www.m3wave.com>



<http://calwave.org>

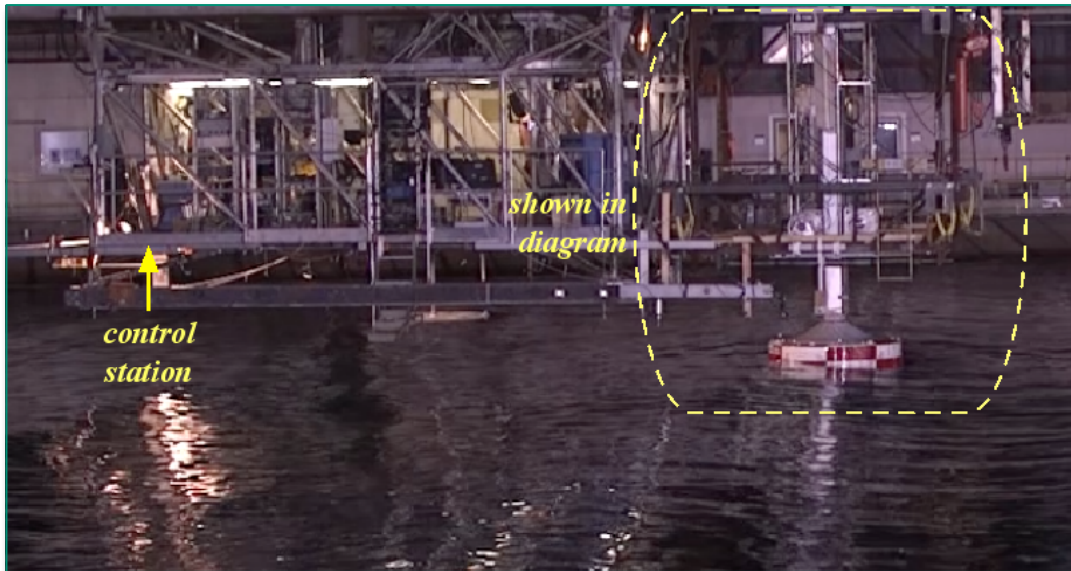
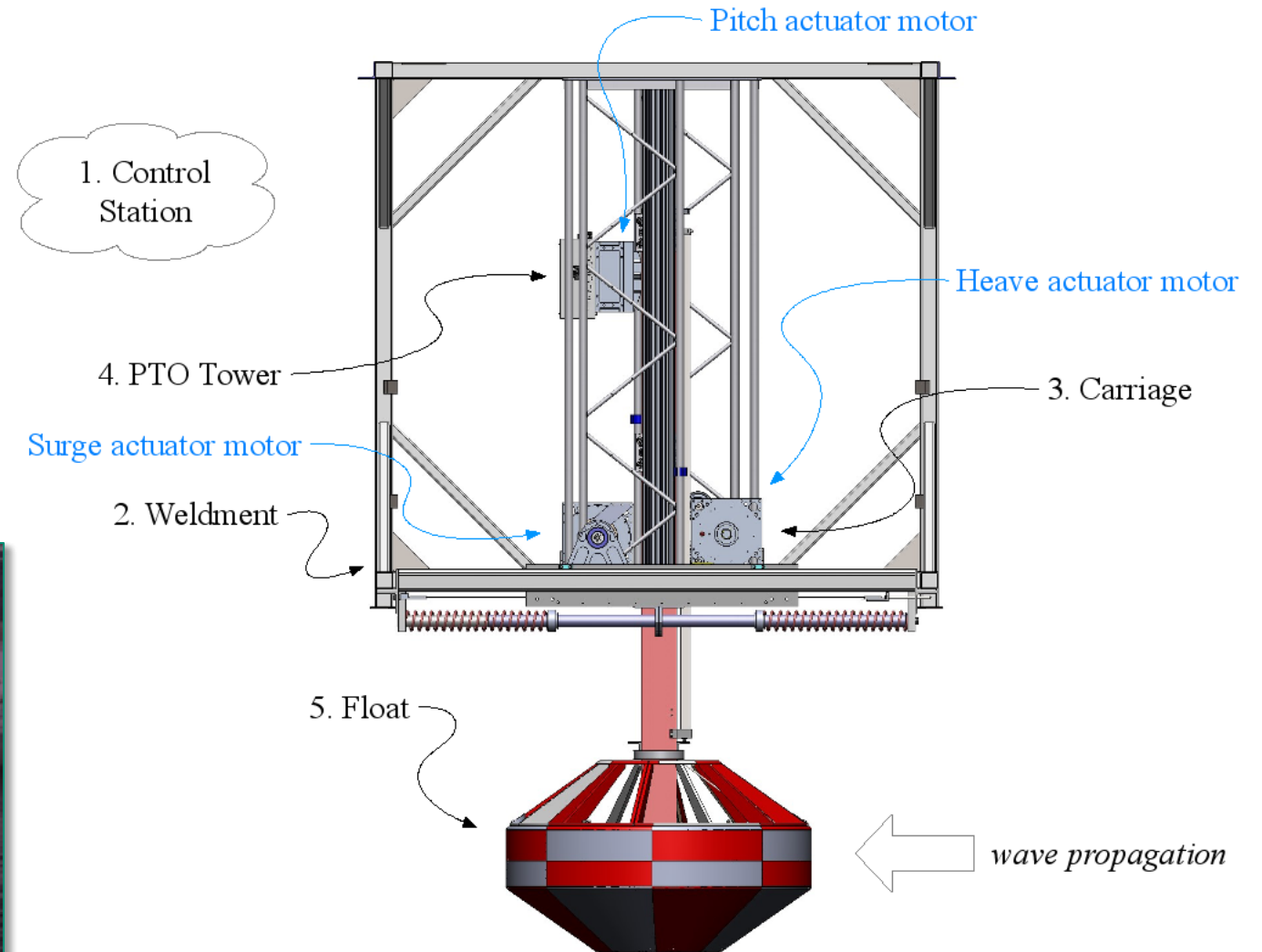
Study device – *the “WaveBot”*

Parameter	Value
Displaced volume, \forall [m ³]	0.858
Water density, ρ [kg/m ³]	1000
Inertia, heave [kg]	858
Inertia, surge [kg]	1420
Inertia, pitch [kg m ²]	84



https://youtu.be/c4npWk_-Pjk

Study device – the “WaveBot” (cont.)





Modeling a WEC





Resonance is often something engineers try to avoid





*Resonance is often something
engineers try to avoid*

... but not always



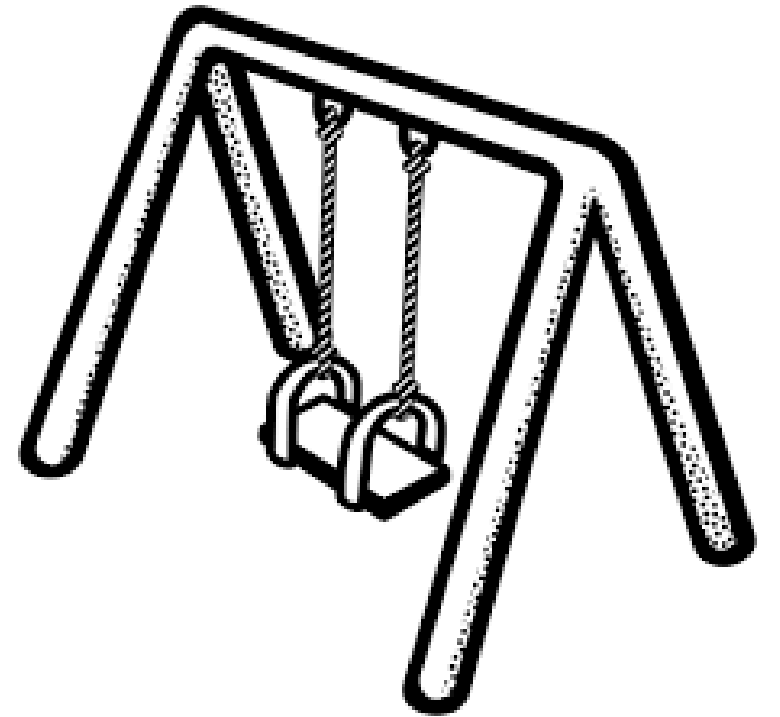
How to make a swing resonate



Two key aspects:

1. *Frequency* $f = f_n$

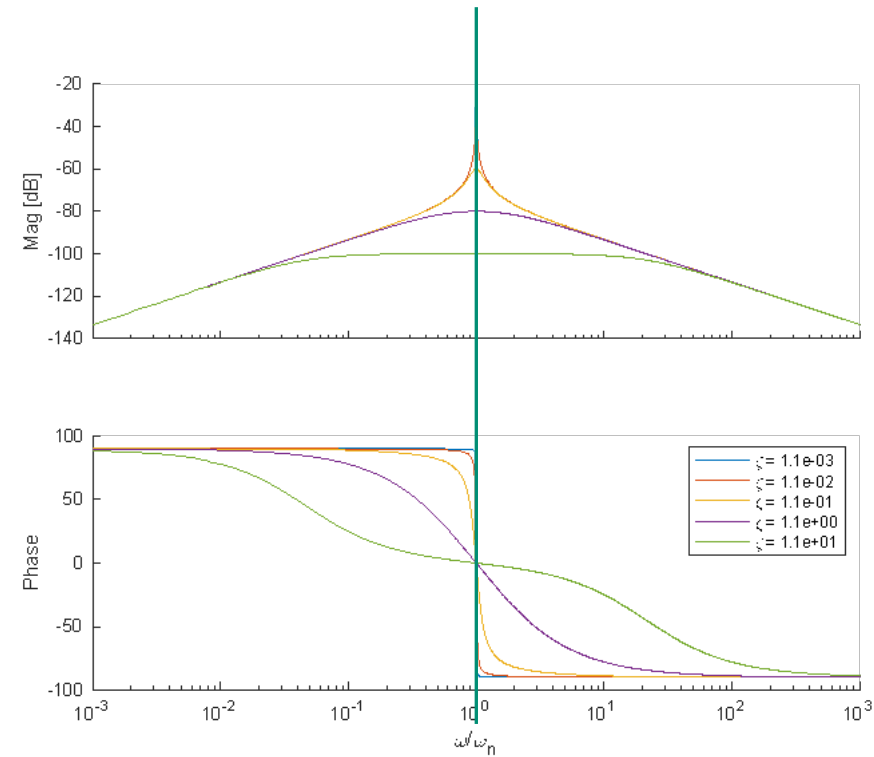
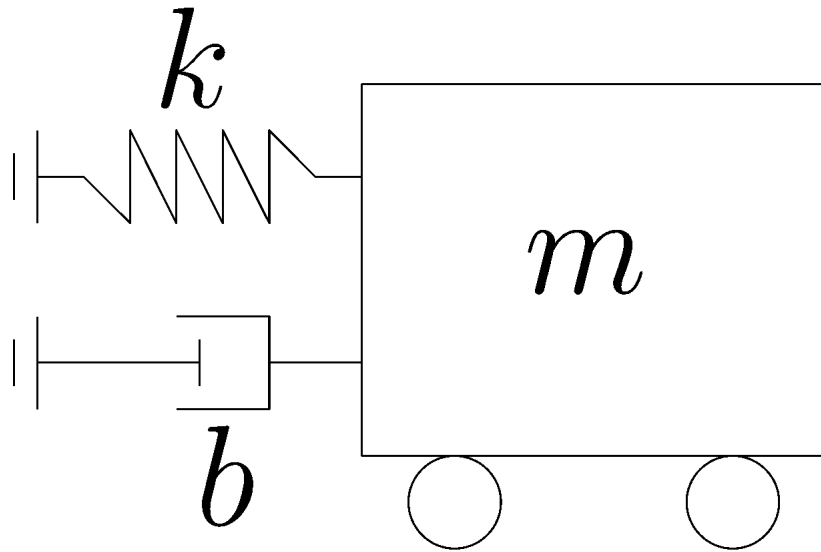
2. *Phase* $\angle \left\{ \frac{U}{F} \right\} = 0$



How do we define it?

Natural frequency: $\omega_n = \sqrt{\frac{k}{m}}$

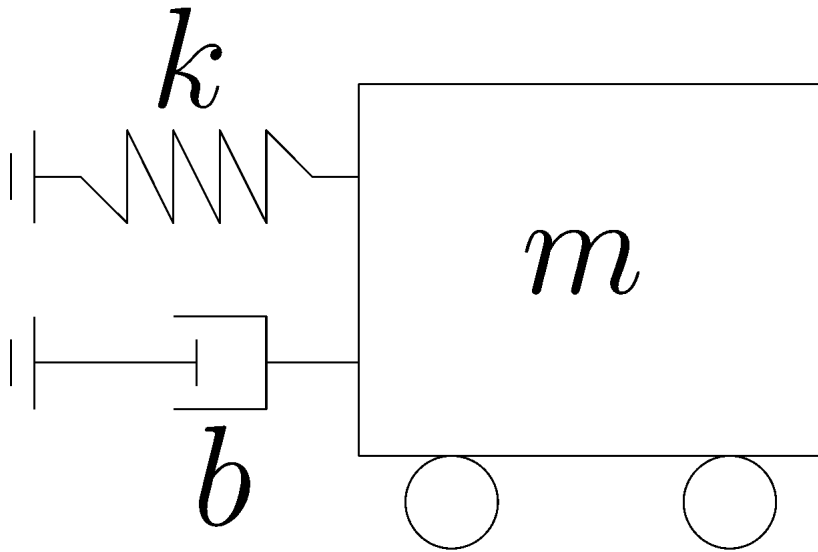
← stiffness
← inertia





How do we define it?

Natural frequency: $\omega_n = \sqrt{\frac{k}{m}}$



example_smdResonance.mlx



What is impedance?

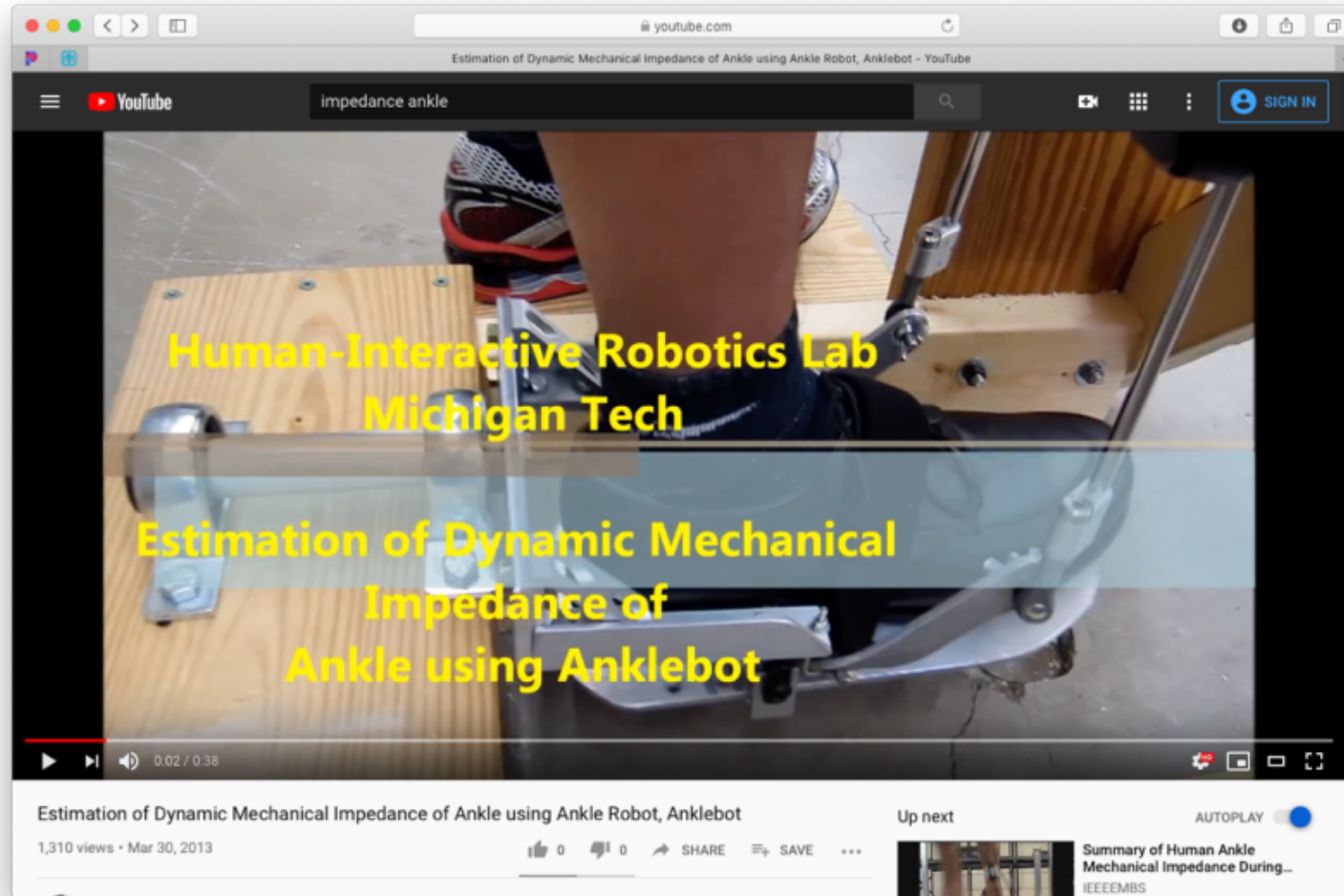
$$F(\omega) = Z(\omega)v(\omega)$$

Tells us: “How does a structure respond to a force?”

Units?

$$Z = \frac{\text{“potential”}}{\text{“flow”}} \quad \text{e.g.,} \quad \left[\frac{N}{m/s} \right] \quad \text{or} \quad \left[\frac{V}{A} \right]$$

Isn't this just for electrical engineers?



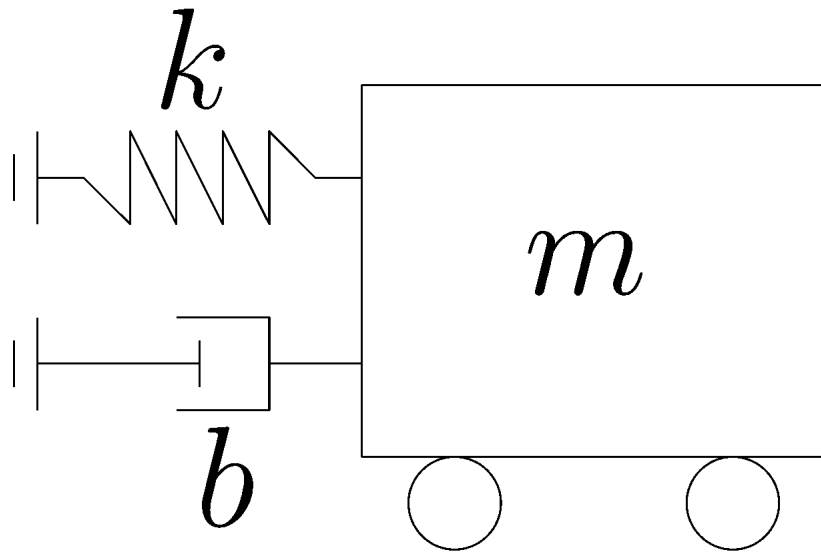
<https://www.youtube.com/watch?v=pgrCjdSYBjM>

$$m\ddot{x} + b\dot{x} + kx = F_e$$

$$x(t) = \mathcal{R} \{ \hat{x} e^{i\omega t} \}$$

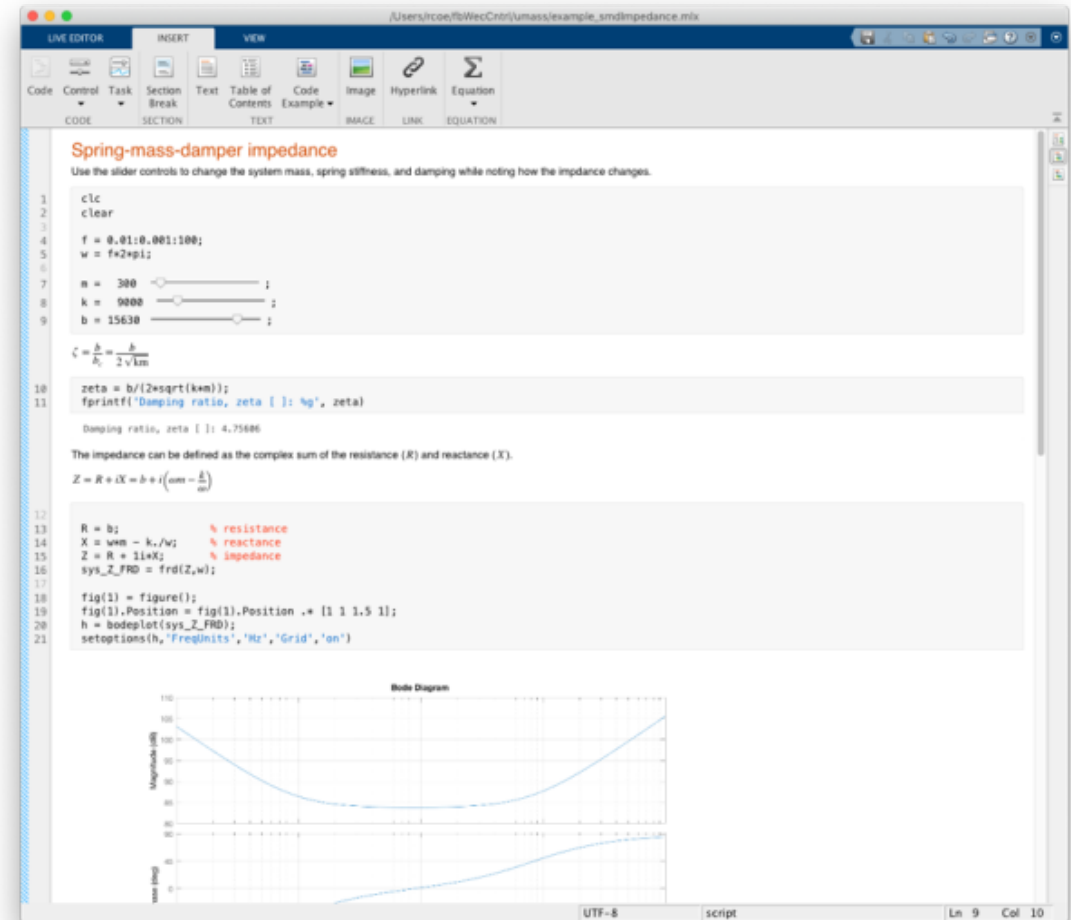
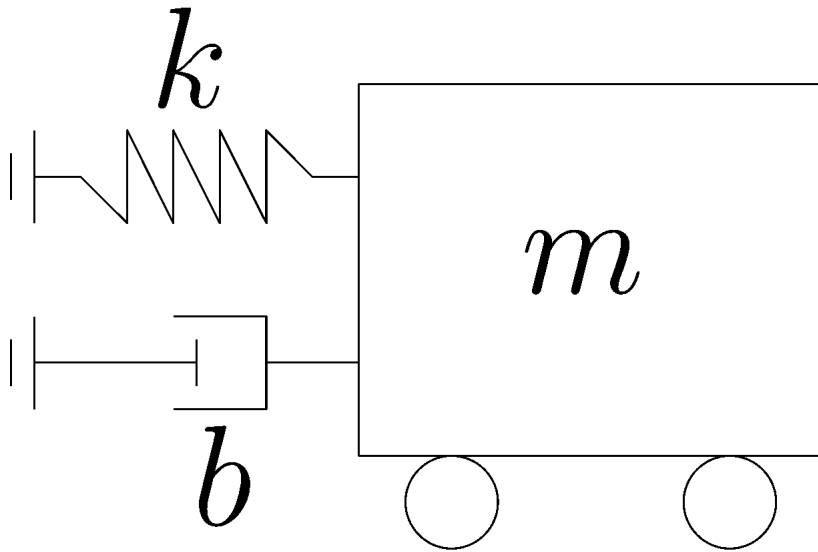
$$Z = b + i \left(\omega m - \frac{k}{\omega} \right)$$

$$\hat{u} = \frac{\hat{F}_e}{Z}$$



Spring-mass-damper (cont.)

$$Z = b + i \left(\omega m - \frac{k}{\omega} \right)$$



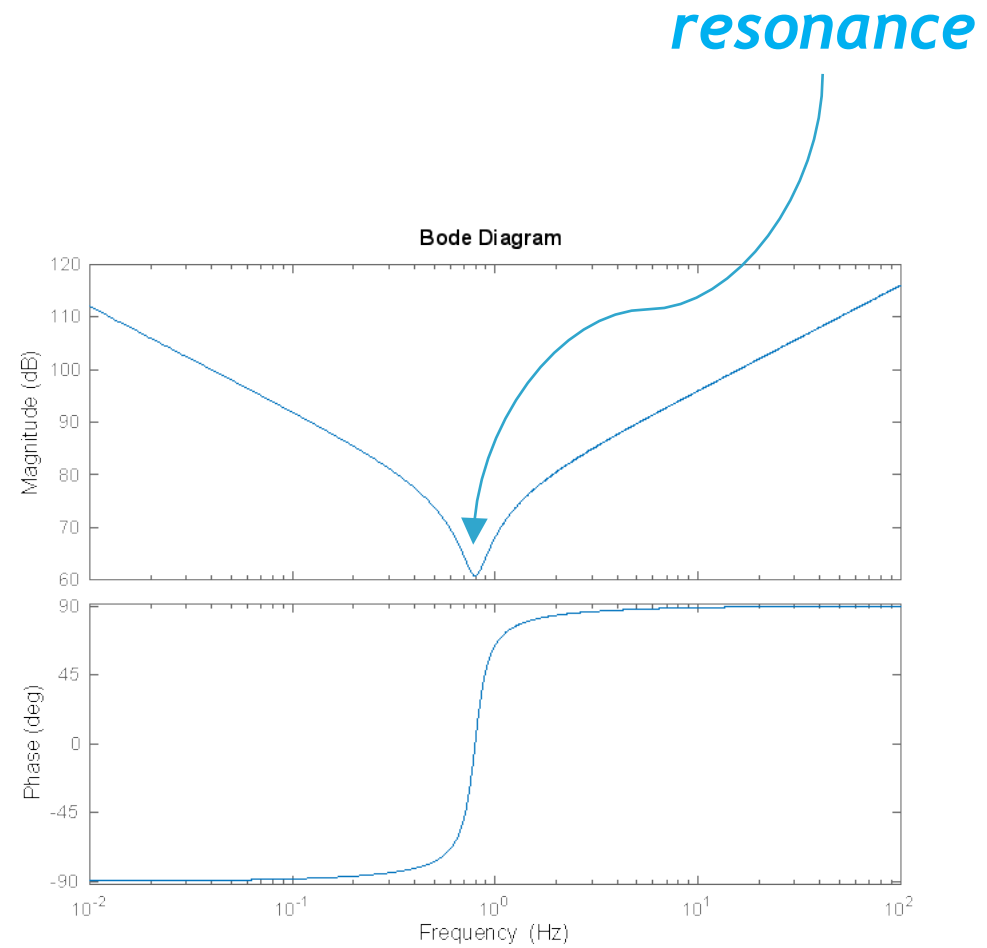
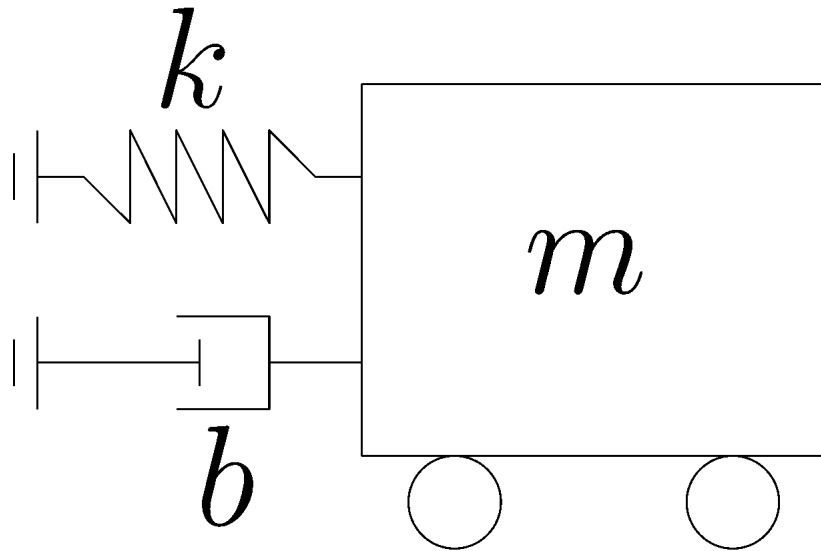
How do we define resonance?

$$Z = b + i \left(\omega m - \frac{k}{\omega} \right)$$

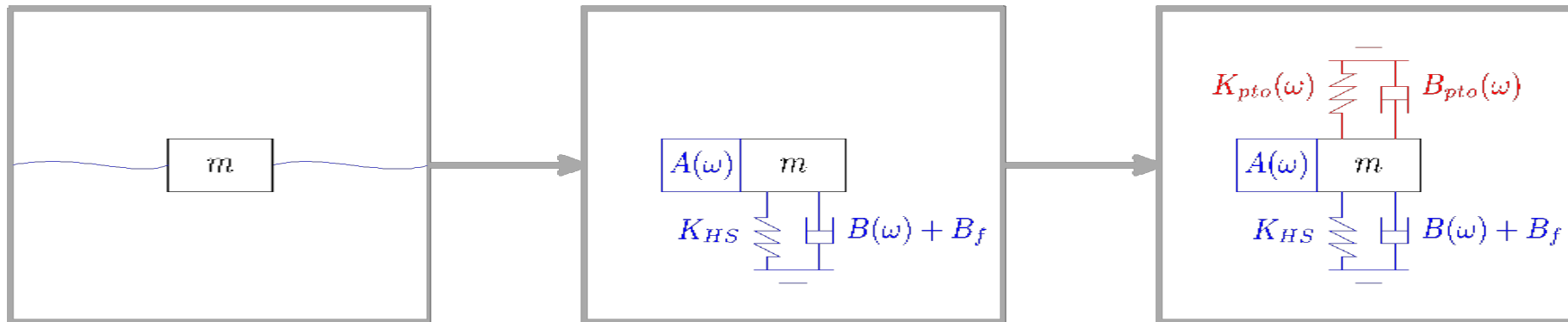
$$\angle \left[\frac{F}{u} \right] = 0$$

$$\angle [Z] = 0$$

$$\Im \{ Z \} = 0$$



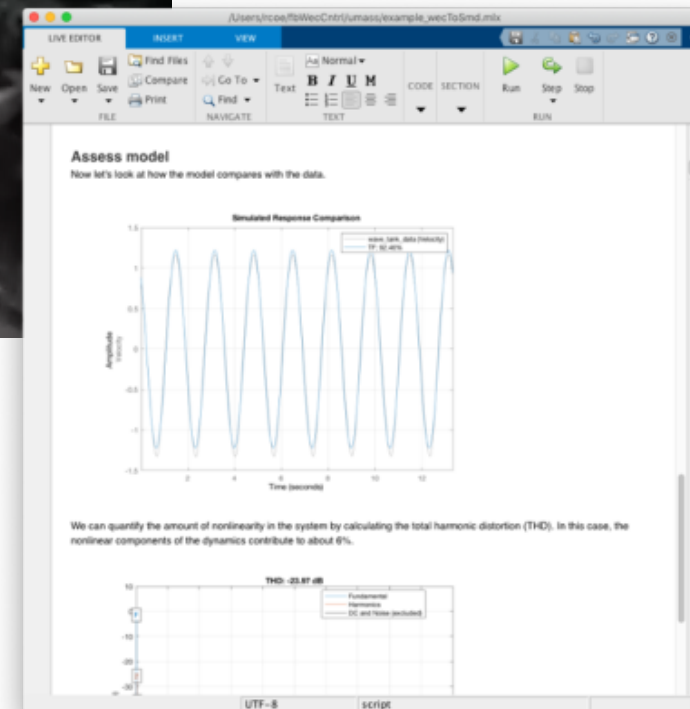
This framework is powerful, practical, and realistic



WEC to spring-mass-damper



How realistic can a spring-mass-damper model be?

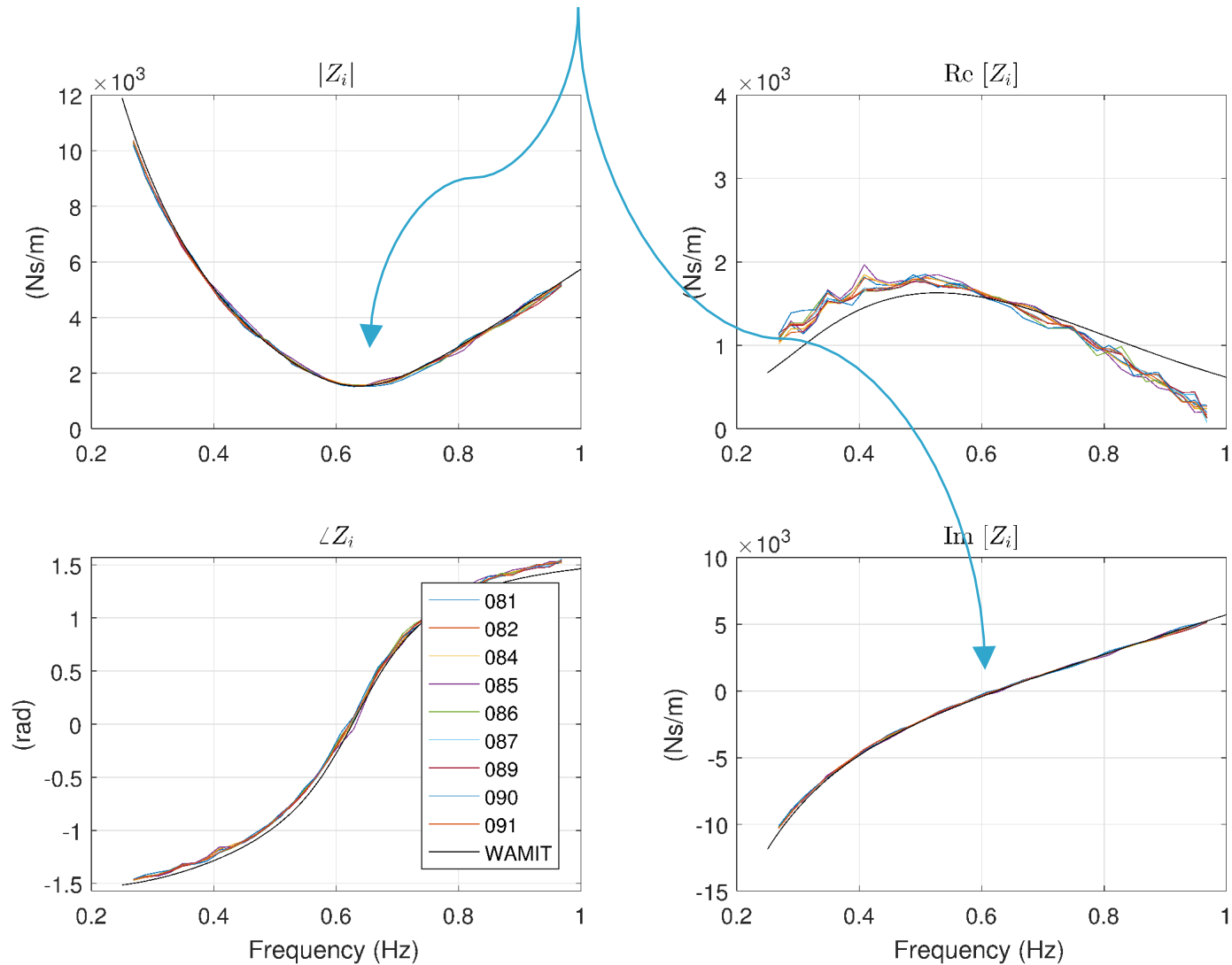


example_wecToSmd.mlx

What does an impedance look like?

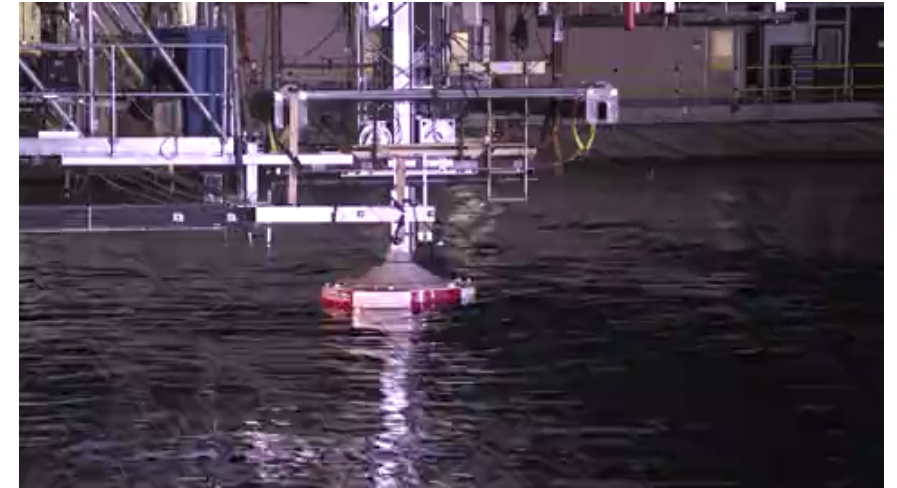
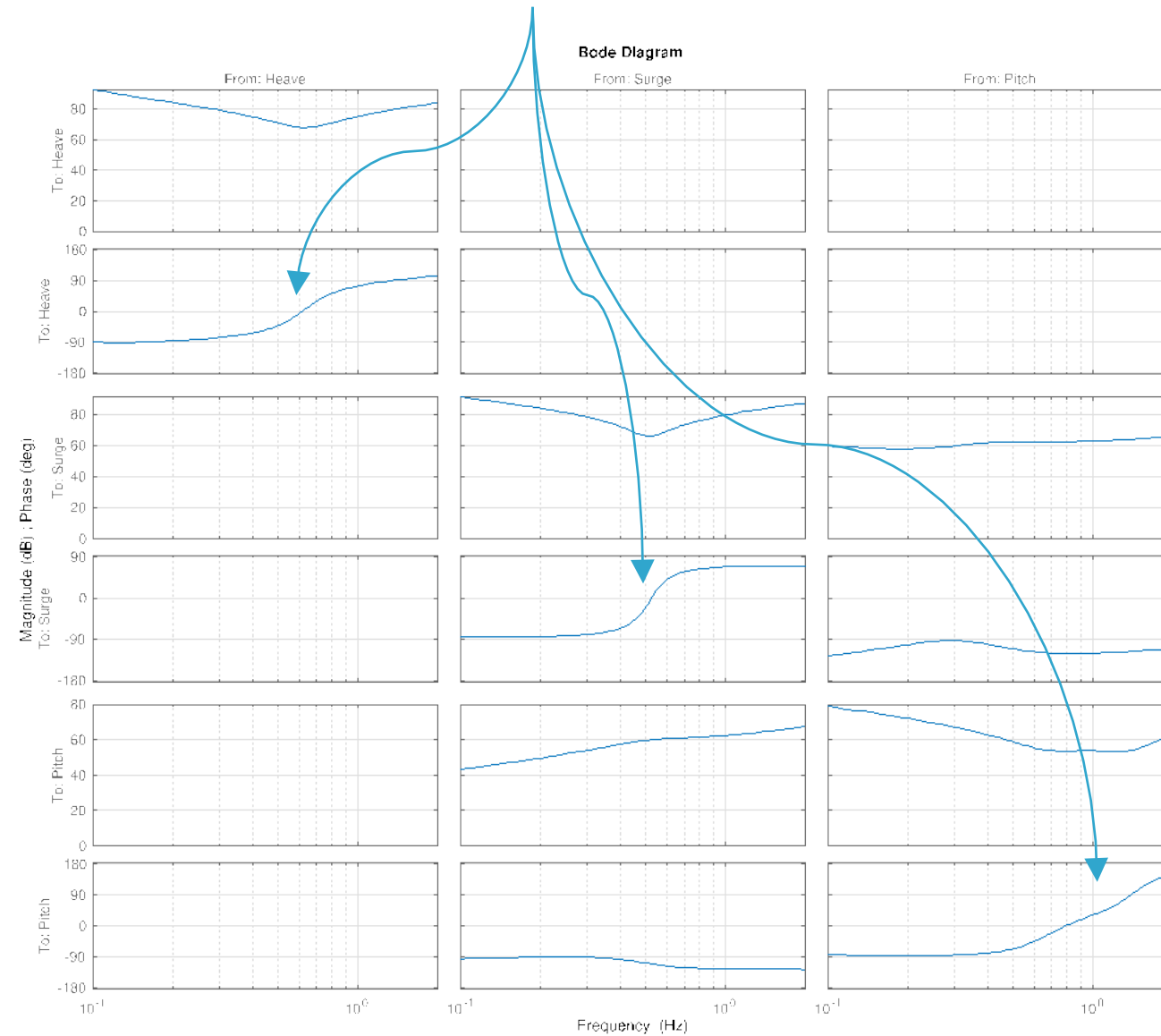


resonance



What does an impedance look like?

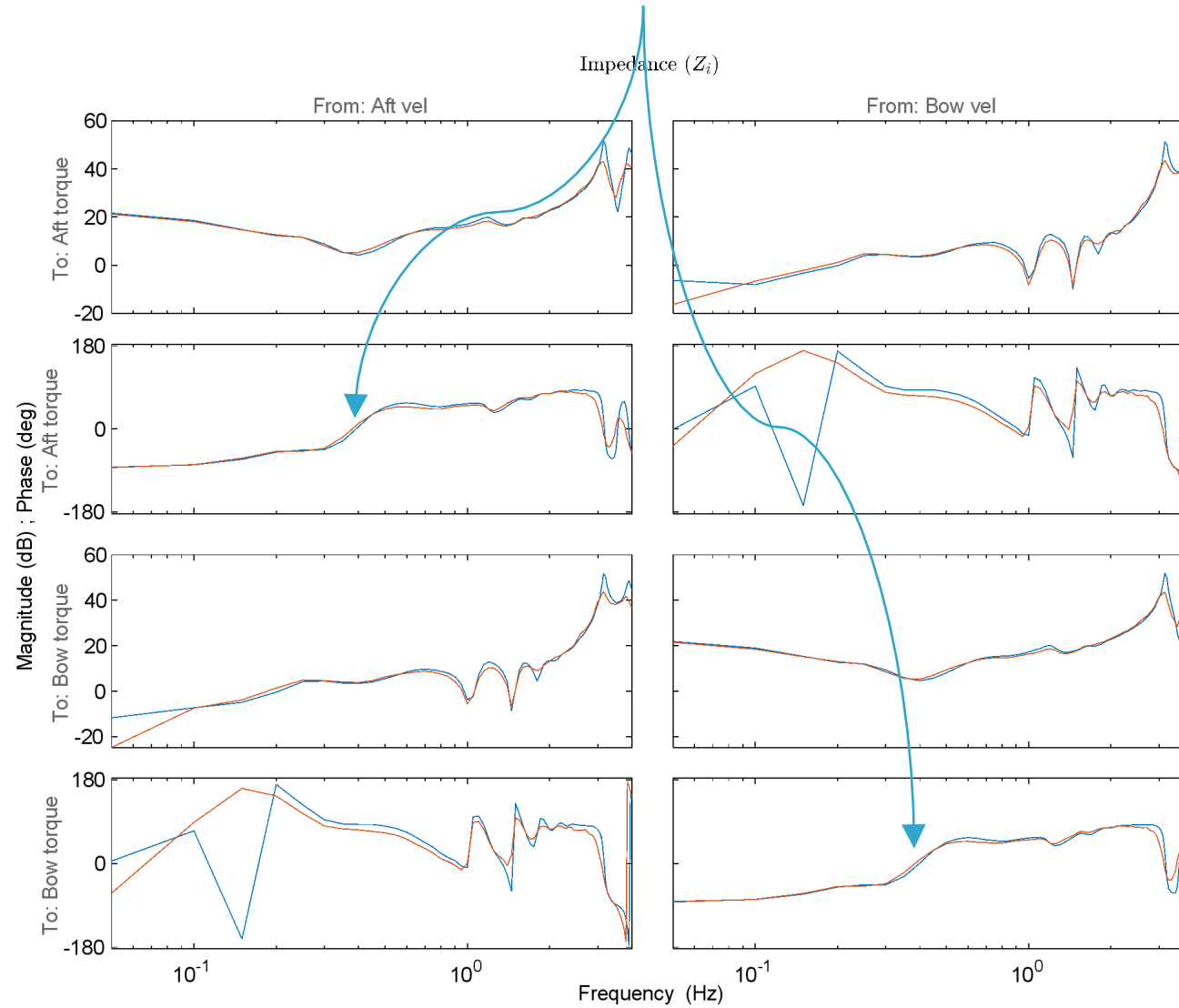
resonance



What does an impedance look like?



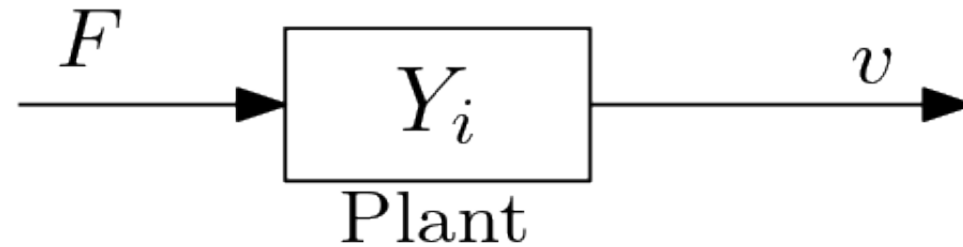
resonance



What is admittance?

$$Y(\omega) = \frac{1}{Z(\omega)}$$

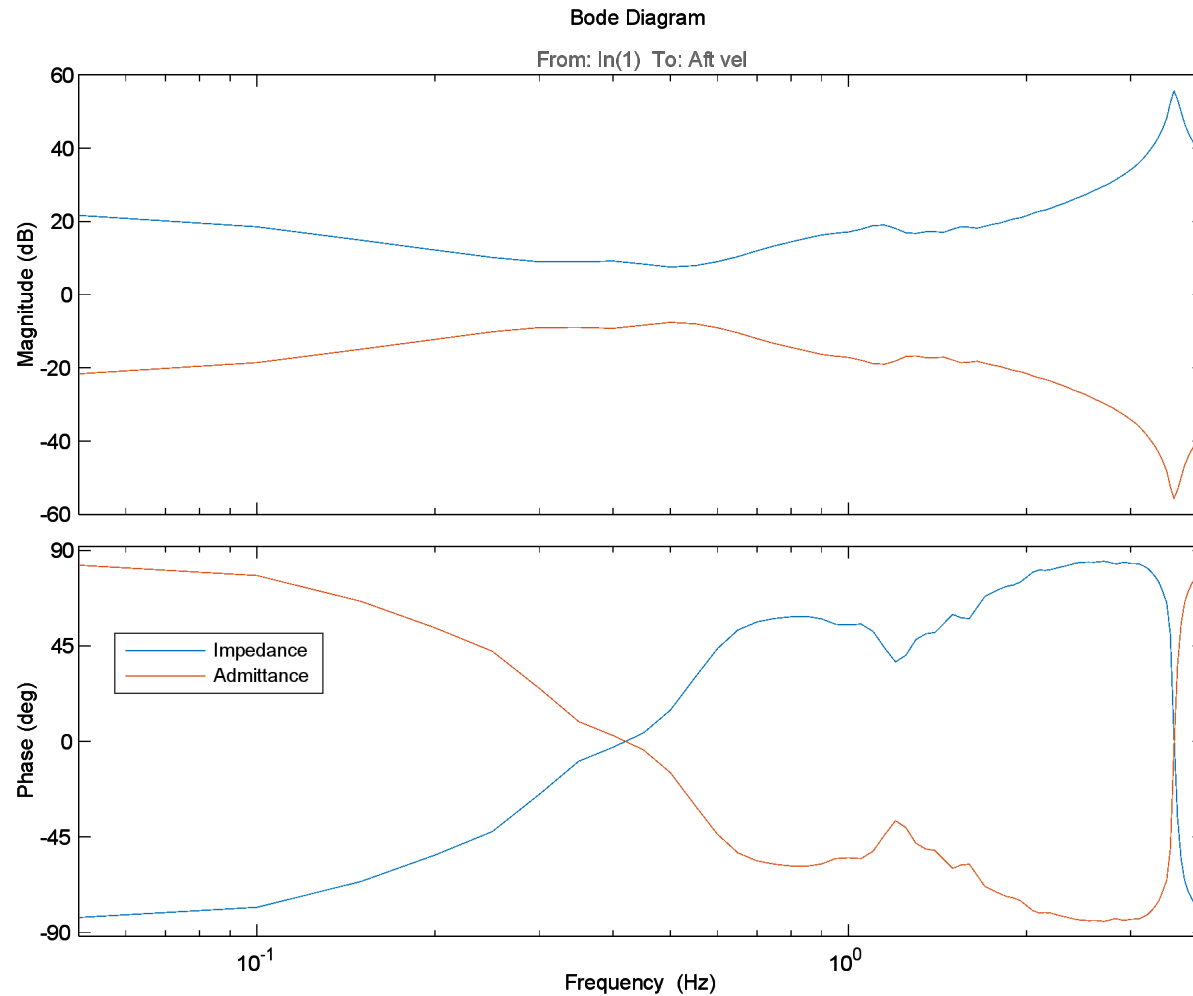
$$v(\omega) = \frac{F(\omega)}{Z(\omega)} = F(\omega)Y(\omega)$$





What does it look like?

$$Y(\omega) = \frac{1}{Z(\omega)}$$



$$Z(\omega) = \frac{F(\omega)}{u(\omega)}$$

$$Y(\omega) = \frac{u(\omega)}{F(\omega)}$$

Impedance

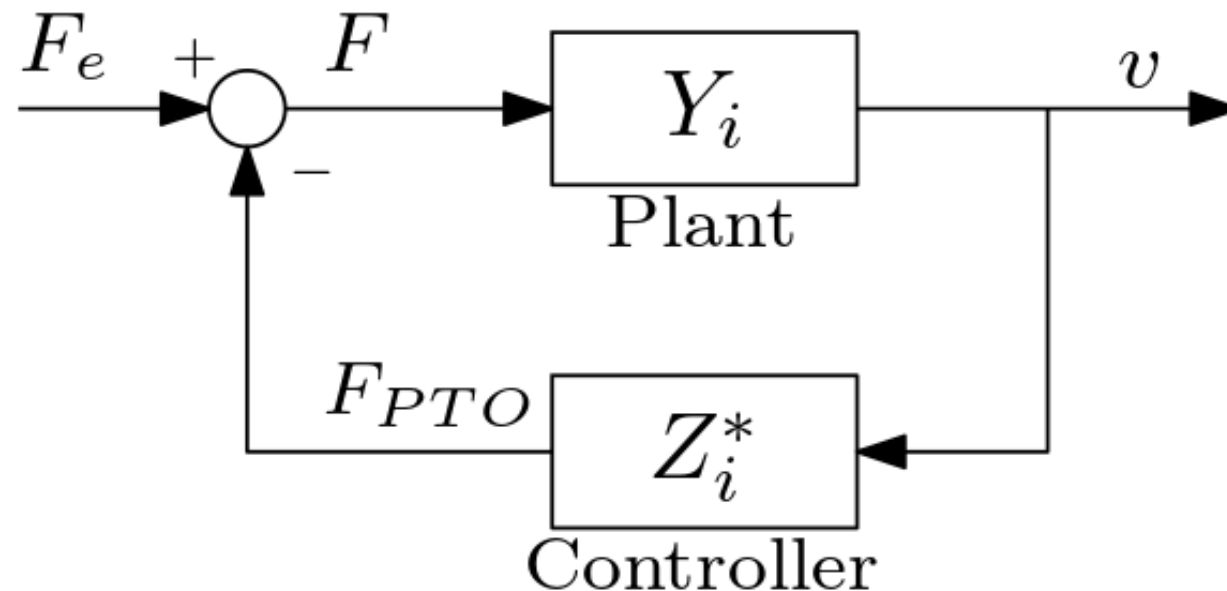


and control



We can use the impedance (or admittance) to cleanly model a WEC

$$Z_i(\omega) = i\omega \underbrace{(M + m(\omega))}_{\text{mass}} + \underbrace{B_v + R(\omega)}_{\text{damping}} + \underbrace{\frac{S}{i\omega}}_{\text{stiffness}}$$



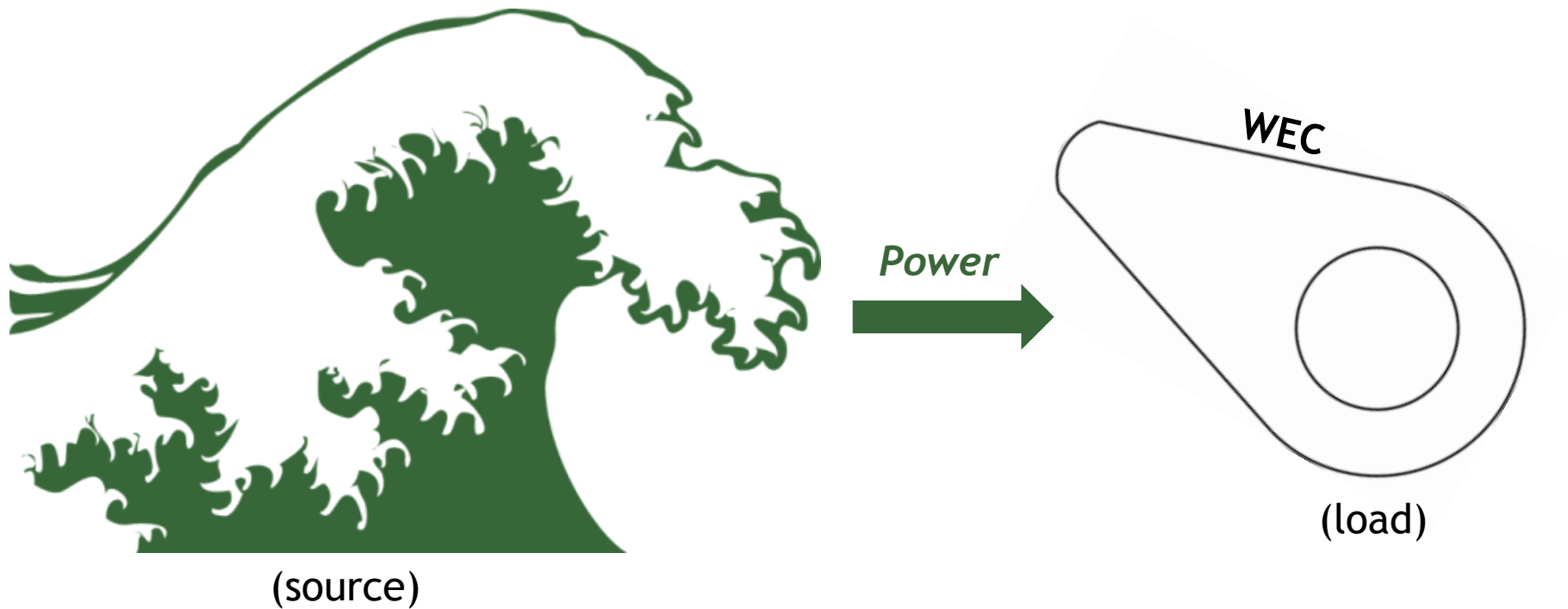


Controlling a WEC



Maximum power transfer (from waves to PTO)

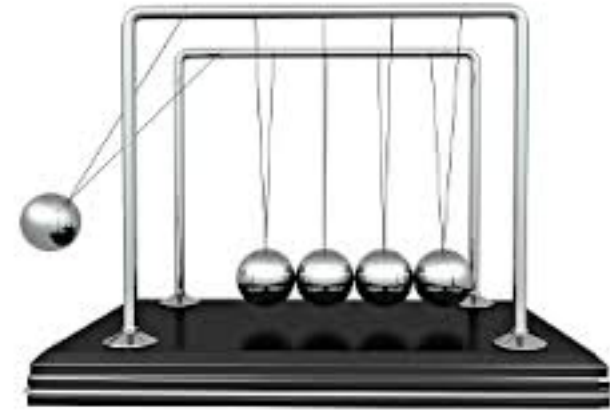
$$Z_{source} = Z_{load}^*$$



Impedance matching



Where else is this used?

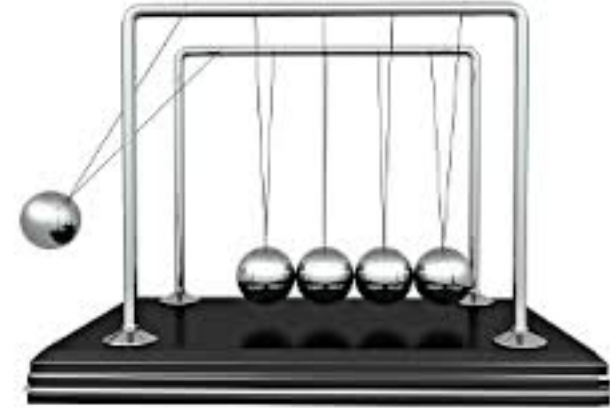


Impedance matching



●	●●
●	●●
●	●●
●	●●
●	●●
●	●●
●	●●
●	●●

<http://www.lockhaven.edu/~dsimanek>



Describing a WEC controller



$$Z_i(\omega) = i\omega \underbrace{(M + m(\omega))}_{\text{mass}} + \underbrace{B_v + R(\omega)}_{\text{damping}} + \underbrace{\frac{S}{i\omega}}_{\text{stiffness}}$$

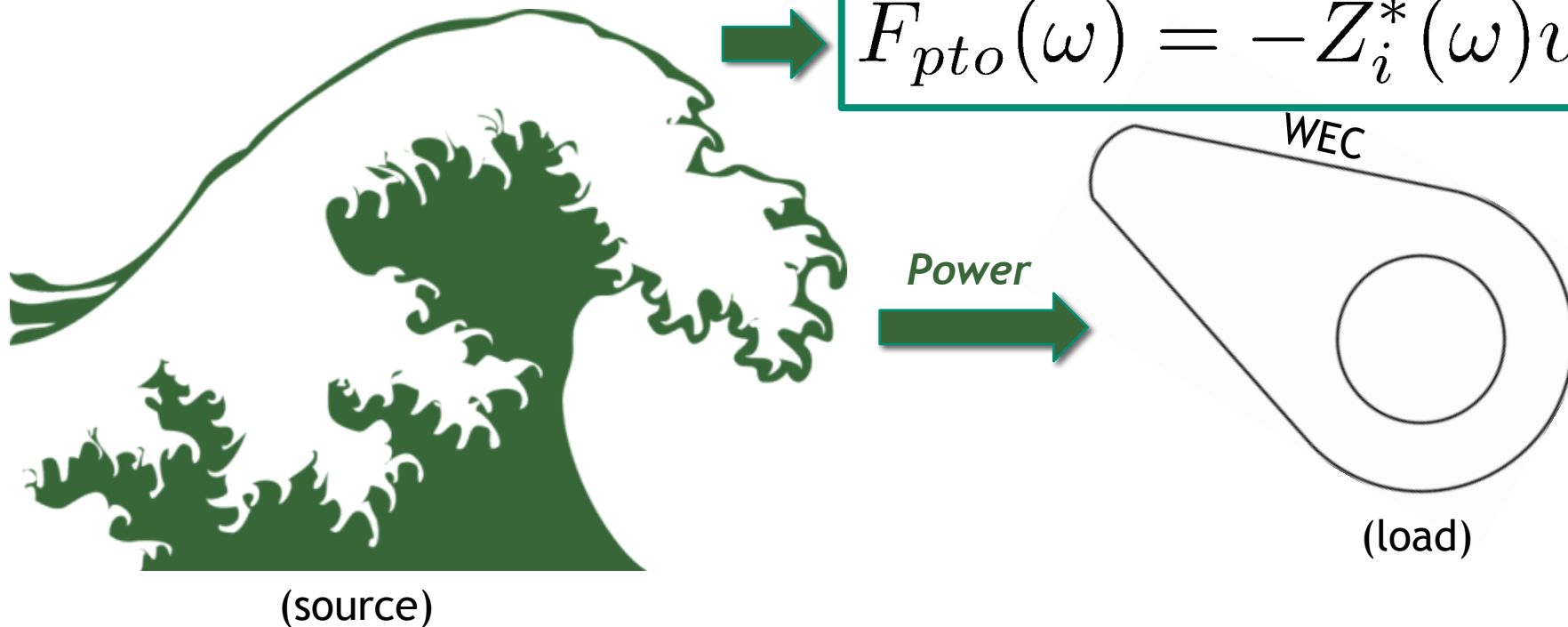
$$\begin{aligned} F_u(\omega) &= f(v(\omega)) \\ &= -Z_u(\omega)v(\omega) \end{aligned}$$

Maximum power transfer (from waves to PTO)

$$Z_{source} = Z_{load}^*$$

$$Z_i = Z_u^* \rightarrow (Z_i^* = Z_u)$$

$$F_{pto}(\omega) = -Z_i^*(\omega)v(\omega)$$



Impedance matching (cont.)

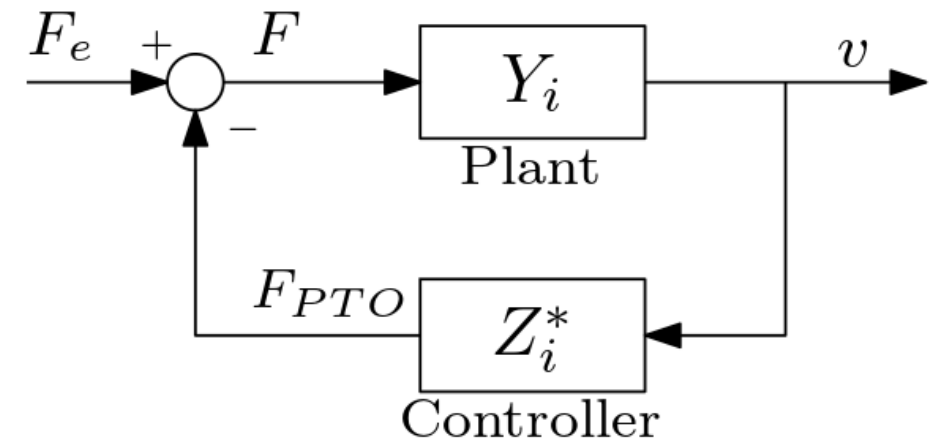
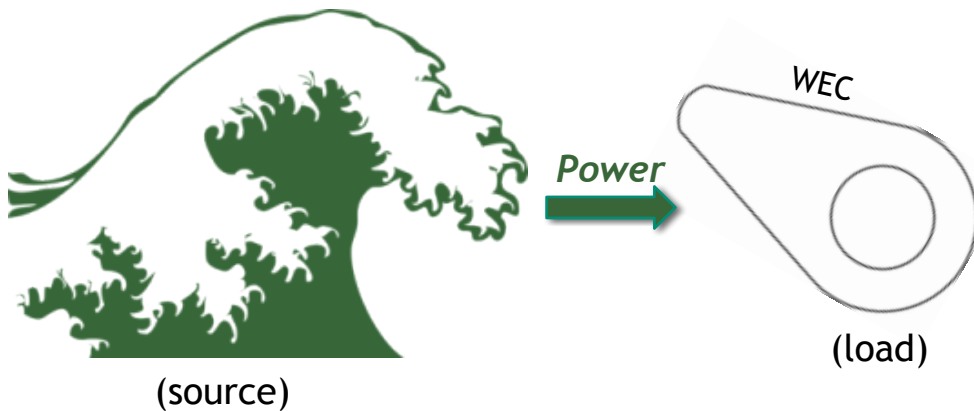


Maximum power transfer (from waves to PTO)

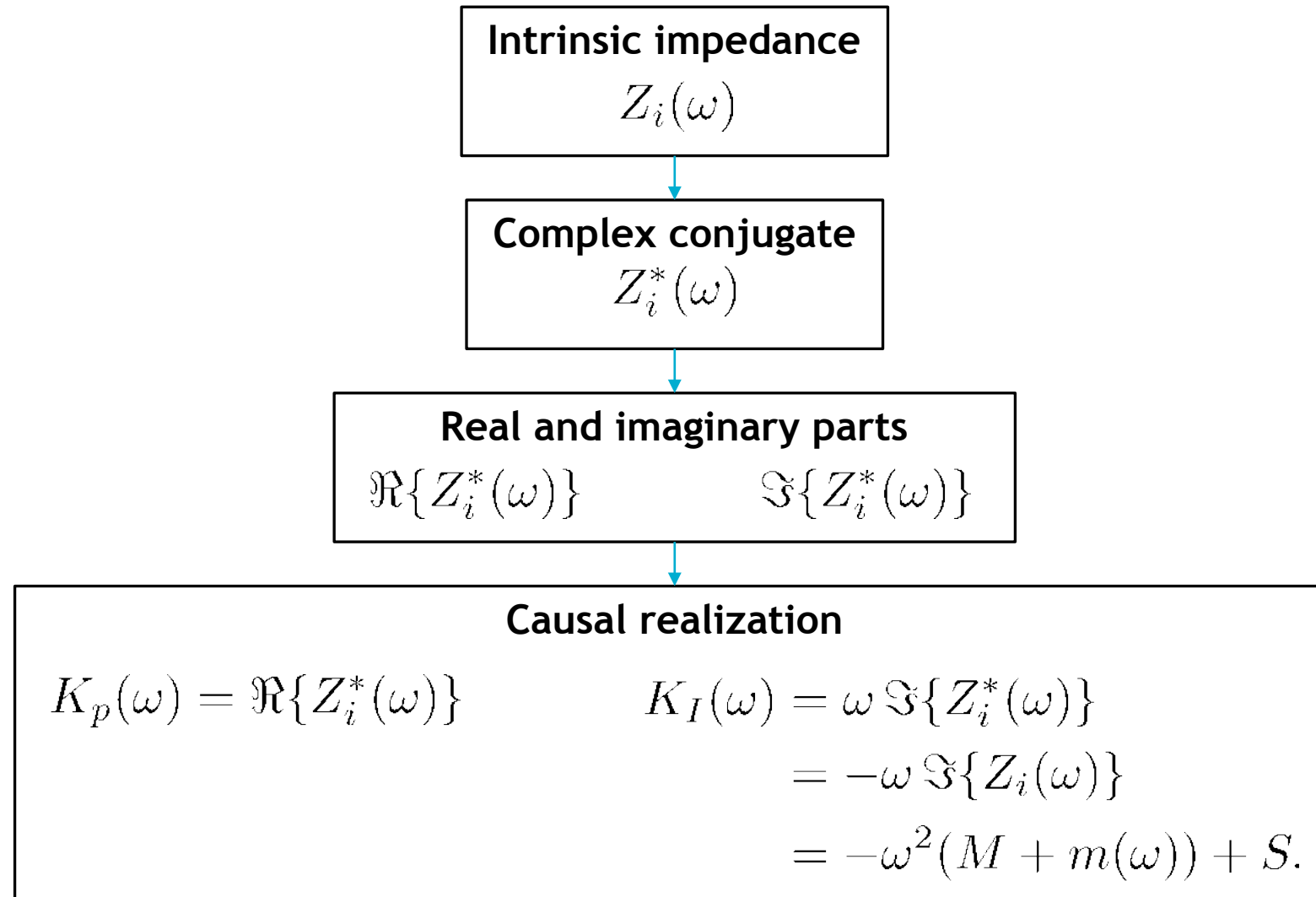
$$Z_{source} = Z_{load}^*$$

$$Z_i = Z_u^* \rightarrow (Z_i^* = Z_u)$$

$$\Rightarrow F_{pto}(\omega) = -Z_i^*(\omega)v(\omega)$$



"WEC control hierarchy"





*While perfectly
implementing impedance
matching in a causal
controllers is not
possible, we can come
quite close*

$$C_{PID}(s) = \frac{K_D s^2 + K_P s + K_I}{s} \frac{1}{s + p}$$

derivative gain proportional gain integral gain

high frequency pole

*most of us learn about “PID” in the context of error minimization, this is not really the intent here

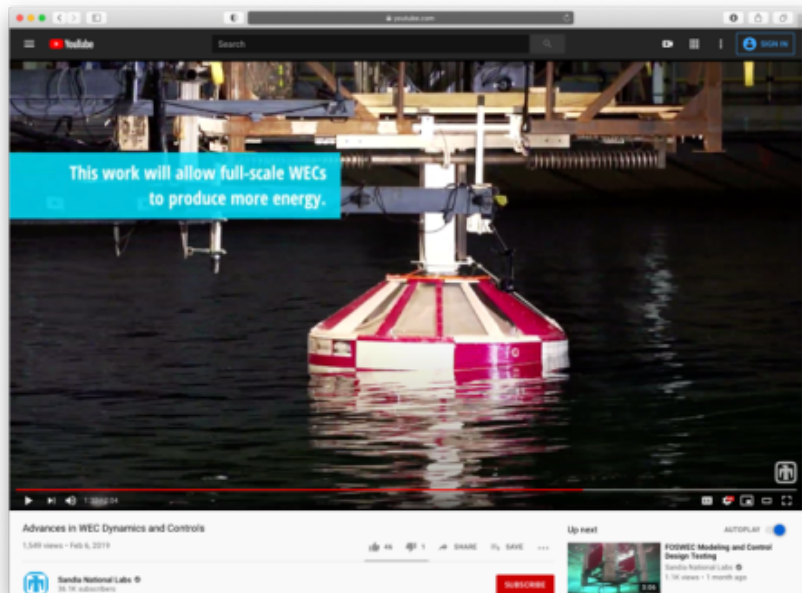
Example: Designing P and PI controllers for a WEC



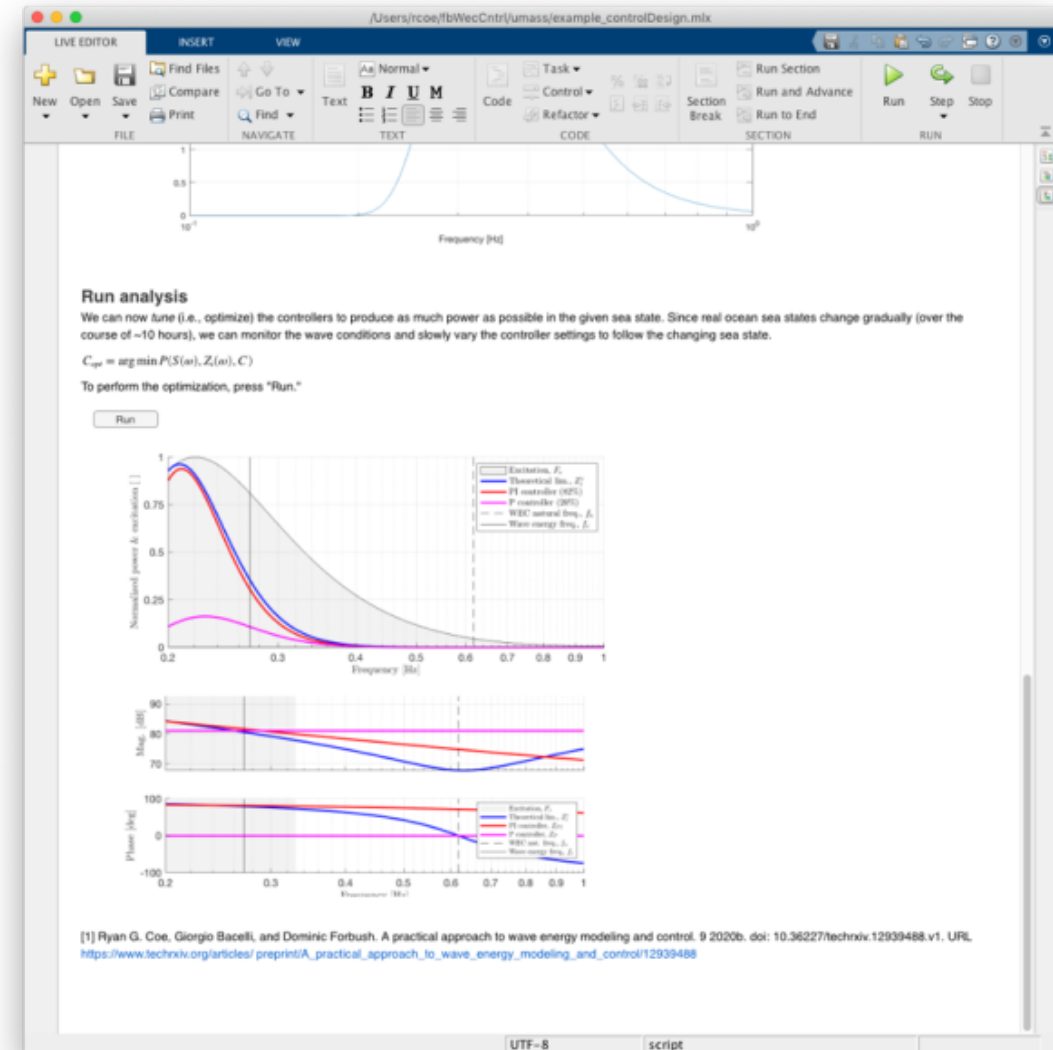
$$C_{opt} = \arg \min P(S(\omega), Z_i(\omega), C)$$



Vary controller to maximize power



https://youtu.be/c4npWk_-Pjk



example_controlDesign.mlx