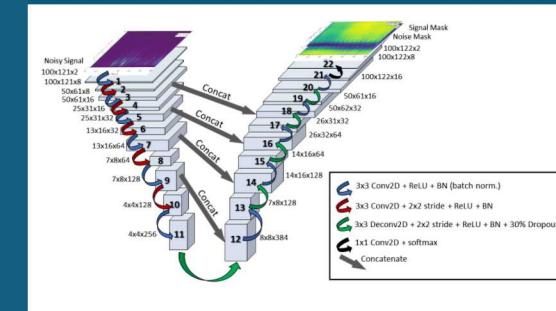
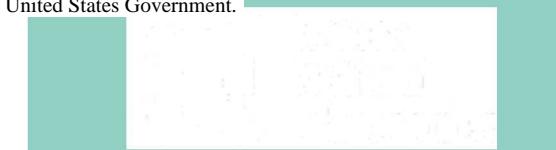
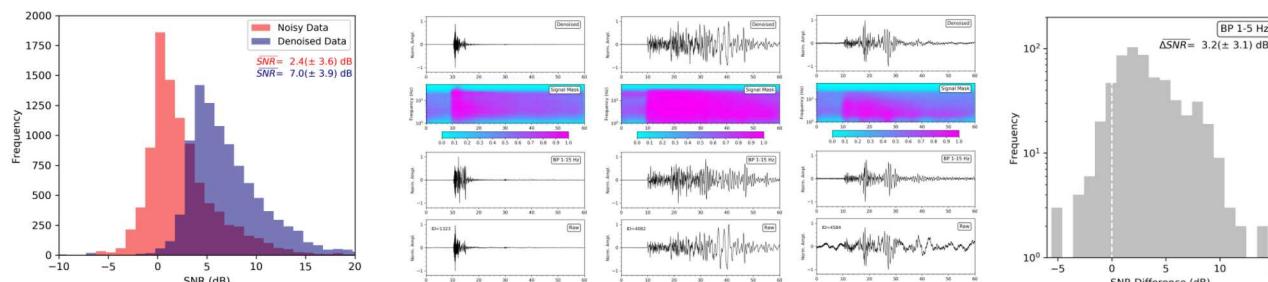


Deep Learning Denoising Applied to the University of Utah Seismic Station Network Data



PRESENTED BY

Rigobert Tibi¹

CO-AUTHORS: Patrick Hammond¹, Ronald Brogan²,
Christopher Young¹, and Keith Koper³

¹Sandia National Laboratories; ²ENSCO, Inc; ³Department of Geology and Geophysics, University of Utah



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- Noise affects our ability to monitor low-magnitude events.
- Frequency filtering commonly used for noise suppression is ineffective when signal and noise share the same frequency range.
- Frequency filtering is known to distort the signal, in some cases, making phase onsets and polarities difficult to determine.
- This work was inspired by Greg Beroza's (Stanford University) presentation at 2018 AGU Meeting (Zhu et al., 2019).

Background

Deep learning denoising widely used in the field of Music Information Retrieval for music source separation (e.g., separation of singing voices from music accompaniment)

SINGLE CHANNEL AUDIO SOURCE SEPARATION USING CONVOLUTIONAL DENOISING AUTOENCODERS

Emad M. Grais and Mark D. Plumley

Centre for Vision, Speech and Signal Processing, University of Surrey, Guildford, UK.

ABSTRACT

Deep learning techniques have been used recently to tackle the audio source separation problem. In this work, we propose to use deep fully convolutional denoising autoencoders (CDAEs) for monaural audio source separation. We use as many CDAEs as the number of sources to be separated from the mixed signal. Each CDAE is trained to separate one source and treats the other sources as background noise. The main idea is to allow each CDAE to learn suitable spectral-temporal filters and features to its corresponding source. Our experimental results show that CDAEs perform source separation slightly better than the deep feedforward neural networks (FNNs) even with fewer parameters than FNNs.

lutional denoising autoencoders, where all the layers of the CDAEs are composed of convolutional units, for single channel source separation (SCSS). The main idea in this paper is to train a CDAE to extract one target source from the mixture and treats the other sources as background noise that needs to be suppressed. This means we need as many CDAEs as the number of sources that need to be separated from the mixed signal. This is a very challenging task because each CDAE has to deal with highly nonstationary background signals/noise. Each CDAE sees the magnitude spectrograms as 2D segments which helps in learning the spectral and temporal information for the audio signals. From the ability of CDAEs in learning noise robust features, in this work, we train each CDAE to learn unique spectral-temporal patterns for its corresponding target source. Each

Deep Karaoke: Extracting Vocals from Musical Mixtures Using a Convolutional Deep Neural Network

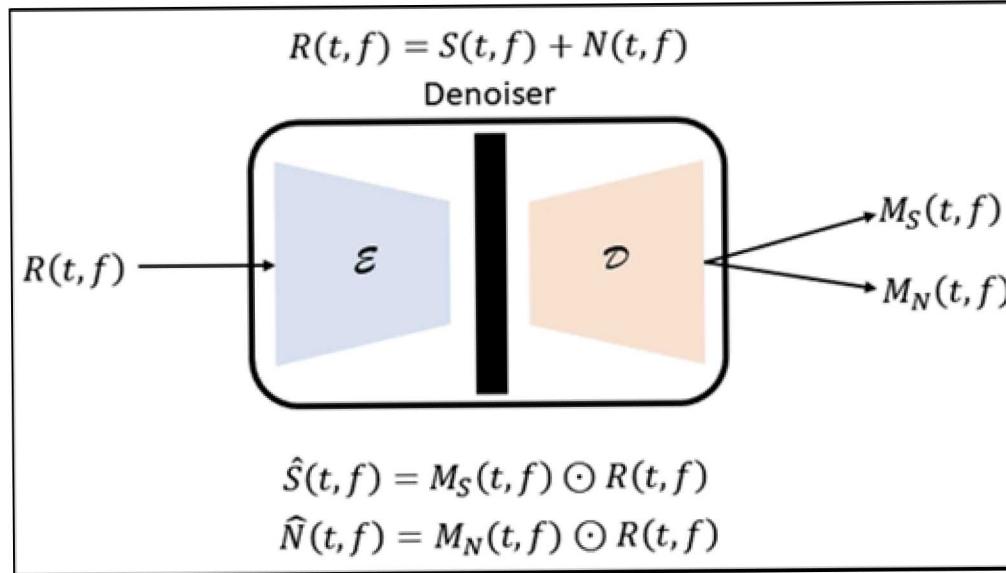
Andrew J.R. Simpson^{#1}, Gerard Roma^{#2}, Mark D. Plumley^{#3}
[#]Centre for Vision, Speech and Signal Processing, University of Surrey
 Guildford, UK
¹andrew.simpson@surrey.ac.uk
²g.roma@surrey.ac.uk
³m.plumley@surrey.ac.uk

Abstract—Identification and extraction of singing voice from musical mixtures is a key challenge in source separation and machine audition. Recently, deep neural networks (DNN) have been used to estimate ‘ideal’ binary masks for carefully controlled cocktail party speech separation problems. However, it is not yet known whether these methods are capable of generalizing to the discrimination of voice and non-voice in the context of musical mixtures. Here, we trained a convolutional DNN (of around a billion parameters) to provide probabilistic estimates of the ideal binary mask for separation of vocal sounds from real-world musical mixtures. We contrast our DNN results with more traditional linear methods. Our approach may be useful for automatic removal of vocal sounds from musical mixtures for ‘karaoke’-type applications.

mask was used to train a deep neural network (DNN) to directly estimate binary masks for new mixtures [6]. However, this approach was limited to a single context of two known speakers and a sample rate of only 4 kHz. Therefore, it is not yet known whether the approach is capable of generalizing to less well controlled scenarios featuring unknown voices and unknown background sounds. In particular, it is not known whether such a DNN architecture is capable of generalizing to the more demanding task of extracting unknown vocal sounds from within unknown music [7]–[9].

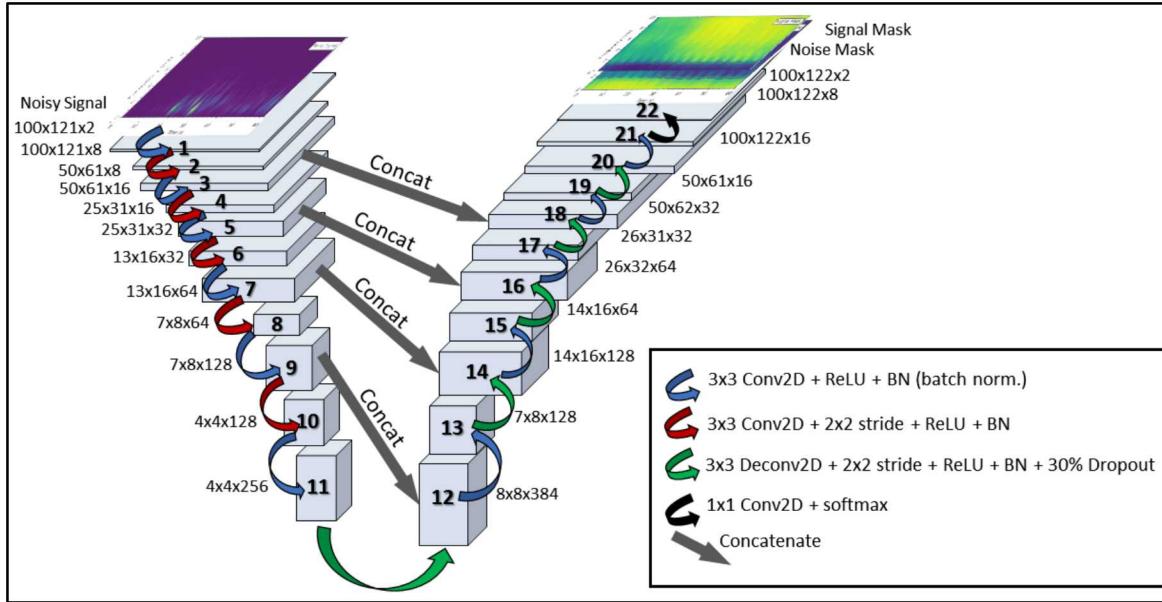
In this paper, we employed a diverse collection of real-world musical multi-track data produced and labelled (on a song-by-song basis) by music producers. We used 63 typical

Approach



- The network consists of an encoder and a decoder.
- For an input $R(t, f)$, the network provides a signal mask ($M_S(t, f)$) and a noise mask ($M_N(t, f)$).
- The estimated 'clean' signal ($\hat{S}(t, f)$) is obtained by multiplying $M_S(t, f)$ with $R(t, f)$; and the estimated noise ($\hat{N}(t, f)$) is obtained by multiplying $M_N(t, f)$ with $R(t, f)$.

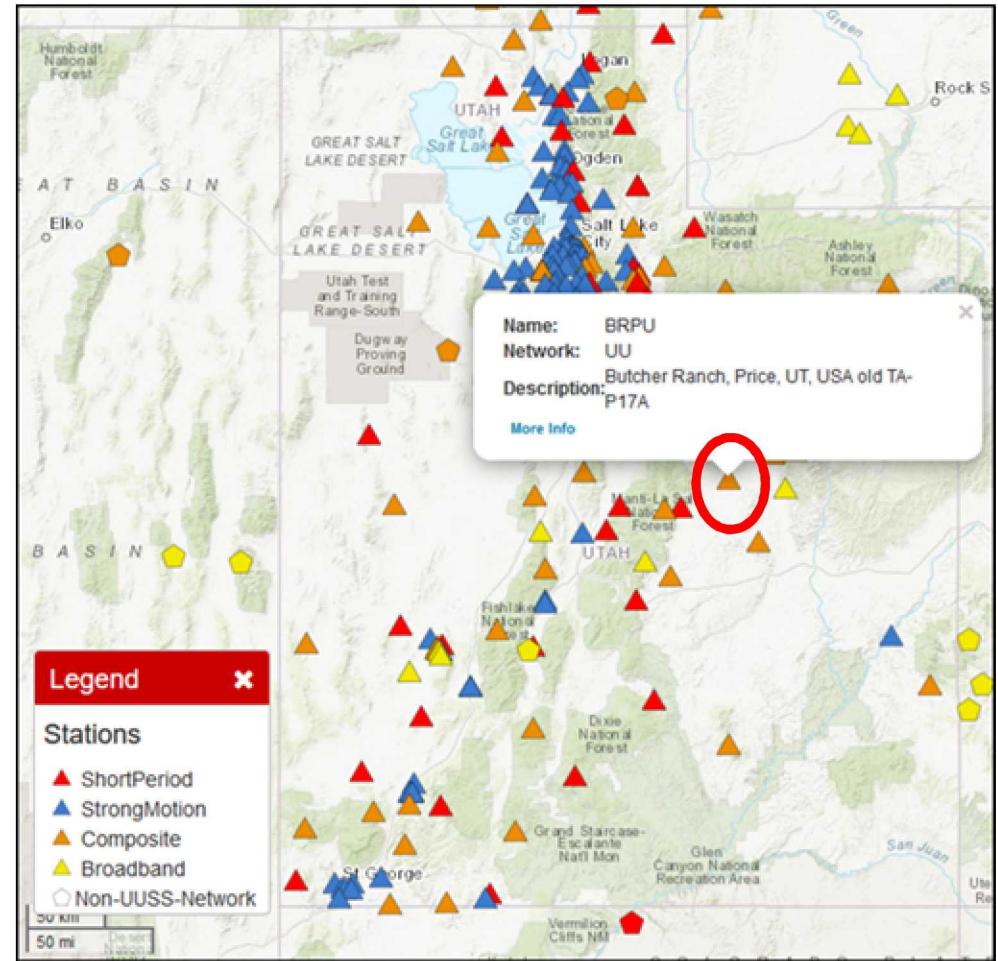
Network Architecture



- The network consists of 20 hidden layers.
- Half of the layers makes up the encoder, and the other half the decoder.
- Implemented using Keras on top of TensorFlow
- ~2.4 million trainable parameters
- ~3K non-trainable parameters

Data

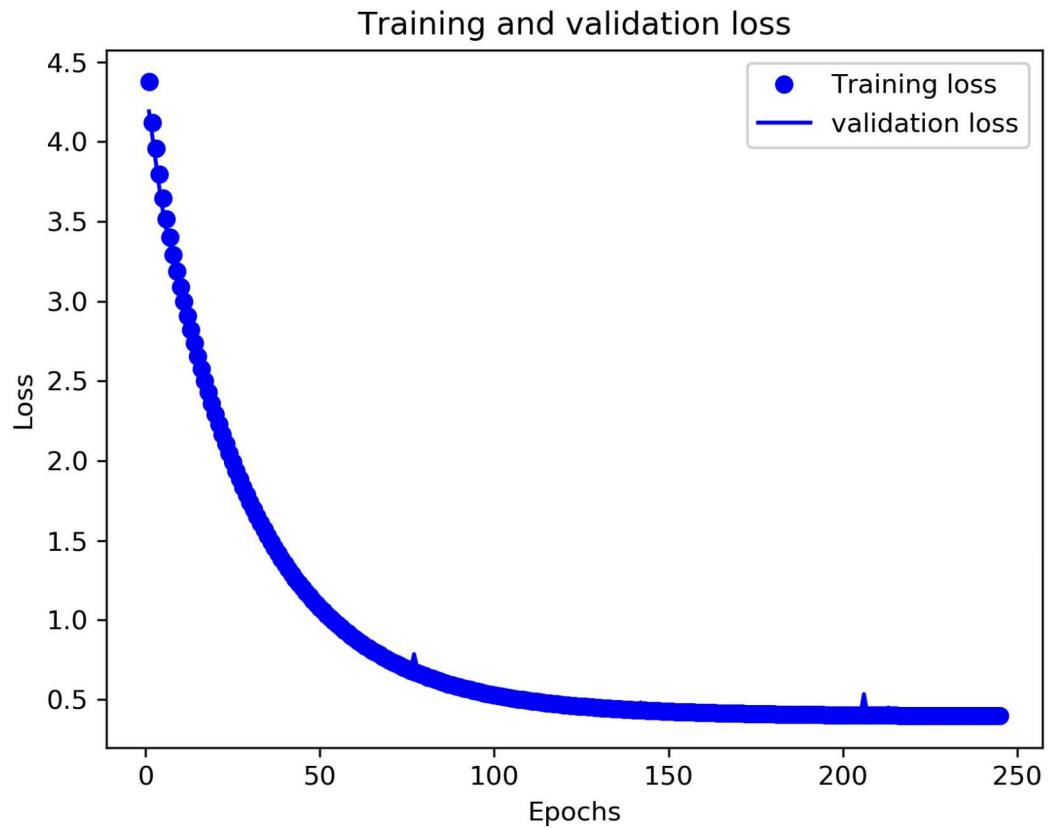
- The ‘clean’ signal dataset consists of 3,188 high-SNR Z-comp waveforms (60-sec long and filtered with BP 1–20 Hz) recorded at **BRPU** from local and near-regional earthquakes.
- The noise dataset contains 15,426 waveforms from various noise sources and various stations.
- The 2 datasets randomly divided into training, validation, and test sets using the ‘70-15-15’ rule.



- Noisy waveforms constructed by summing each ‘clean’ signal waveform and a randomly selected noise waveform. This was repeated 20 times for each set resulting in:
 - **44,620** waveforms for the training set,
 - **9,580** waveforms for the validation set, and
 - **9,560** waveforms for the test set.
- The validation set is used in tuning the network hyperparameters, while the test set is used to assess network performance.

Network Training

- Input for the network are both the real and imaginary part of the STFT of the noisy ‘constructed’ waveforms.
- We used:
 - A SGD optimizer and a learning rate of 5×10^{-4}
 - An L2 regularization (penalty for larger weights)
 - Training carried out for 225 epochs



- Correlation Coefficient (CC)
 - Measures the similarity between the recovered waveform and the ground truth (GT)

- Signal-to-Noise Ratio (SNR in dB)
 - Using 9-sec window for both signal and noise

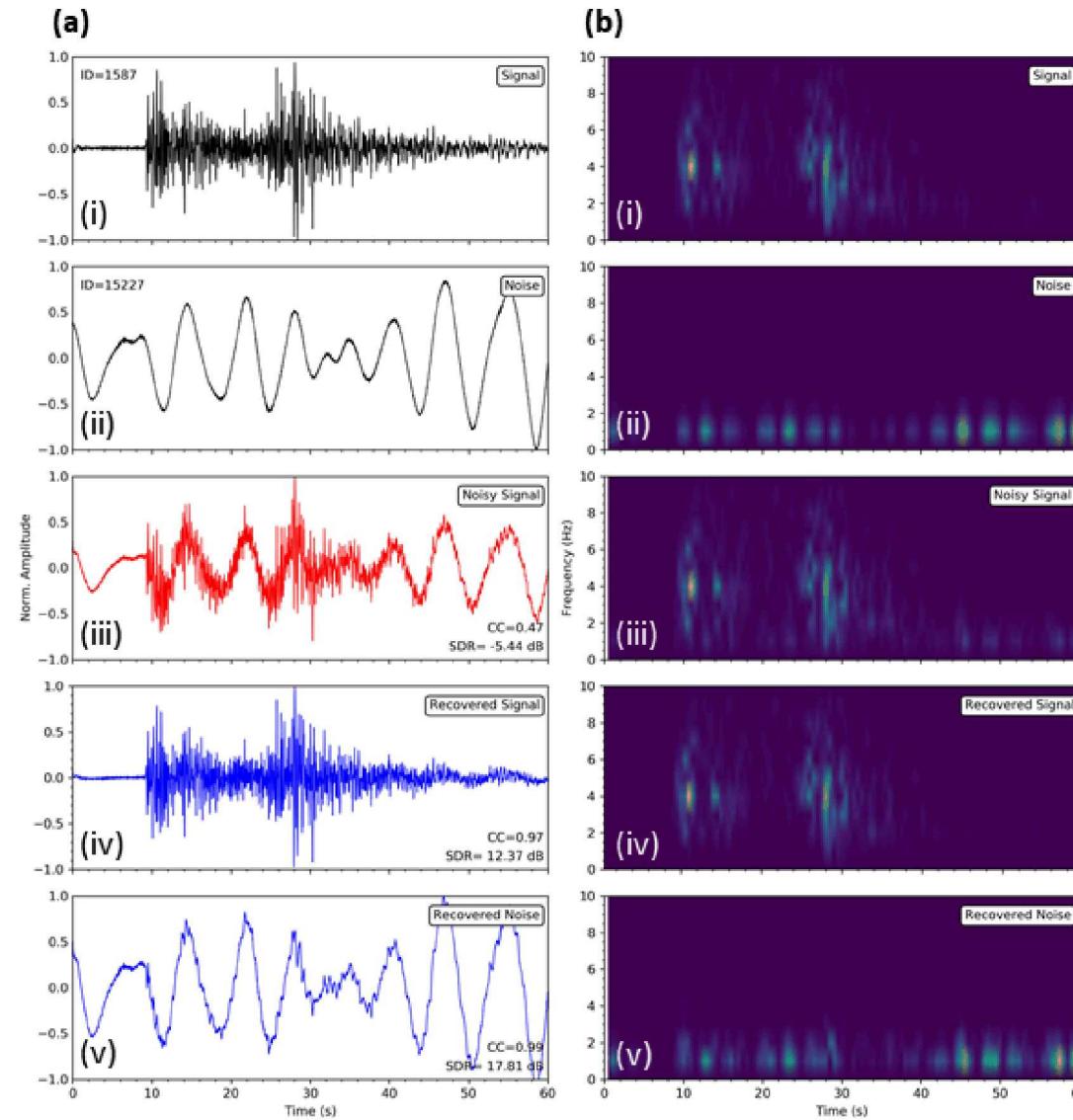
$$SNR = 10 \log_{10} \frac{A_S}{A_N}$$

- Signal-to-Distortion Ratio (SDR in dB)
 - Measures the amplitude distortion with respect to GT

$$SDR = 10 \log_{10} \frac{\|W_{GT}\|^2}{\|\hat{W} - W_{GT}\|^2}$$

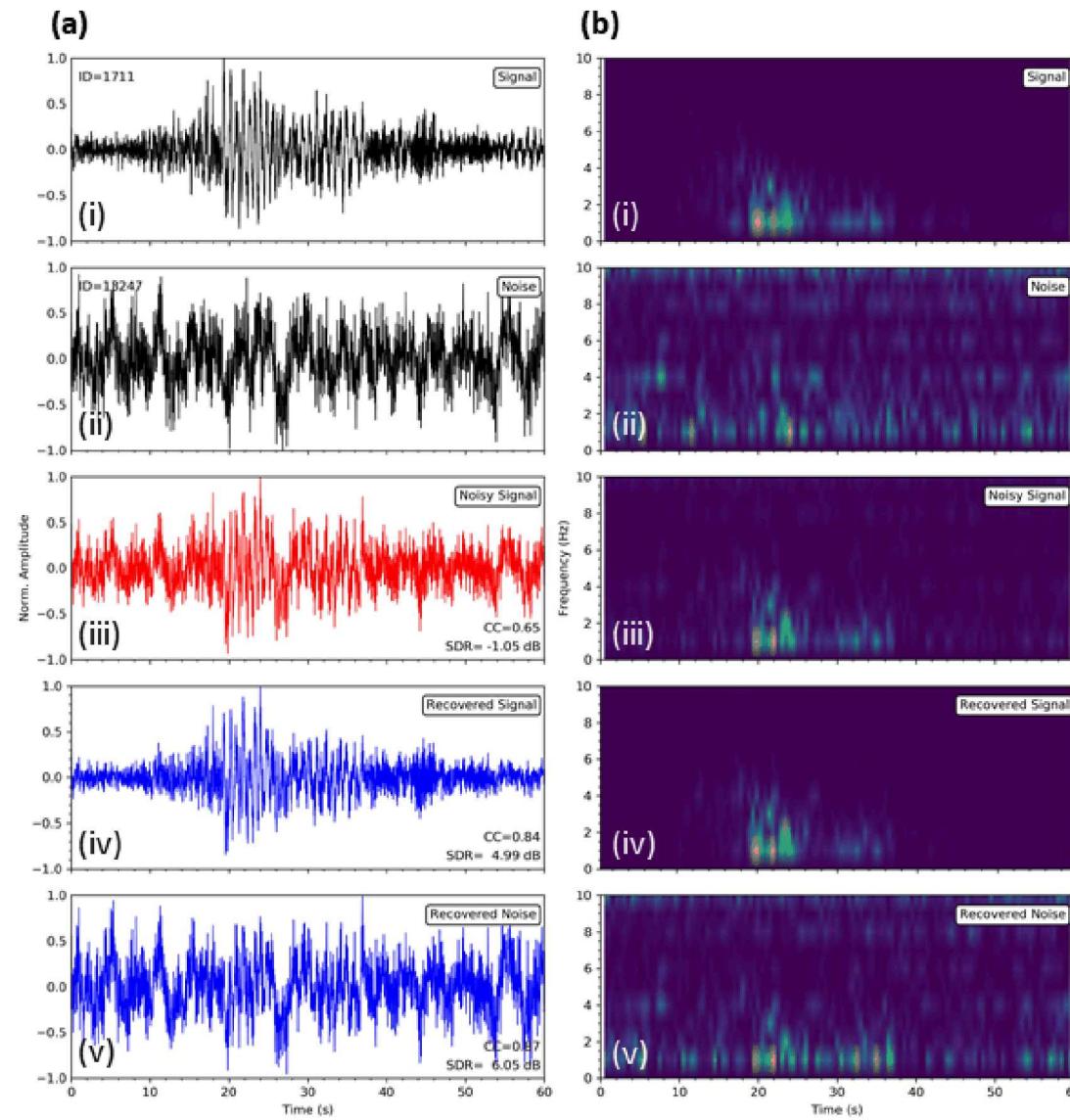
W_{GT} - Ground truth waveform; \hat{W} - Recovered waveform

Evaluation Based on Constructed Data of the Test Set



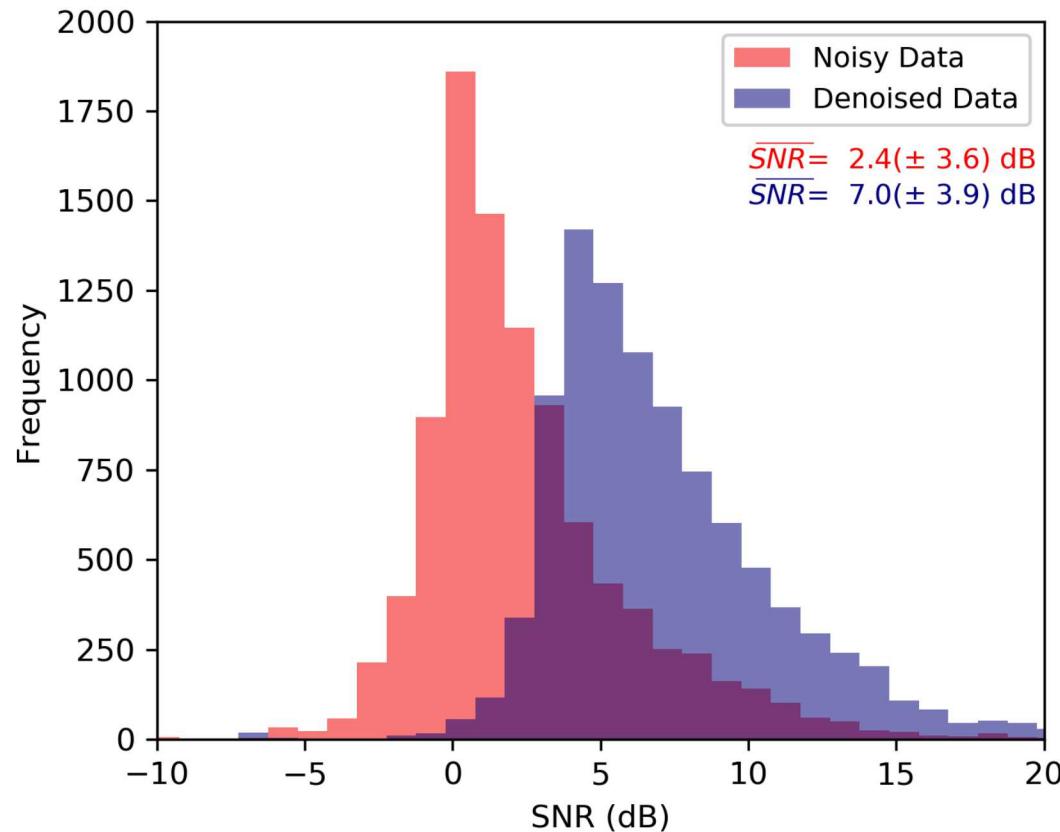
- Recovered waveforms are very similar to the corresponding GTs (CC of 0.97–0.99).
- Recovered seismograms show little distortion with respect to the GTs (SDR of 12.37–17.81 dB).

Evaluation Based on Constructed Data of the Test Set



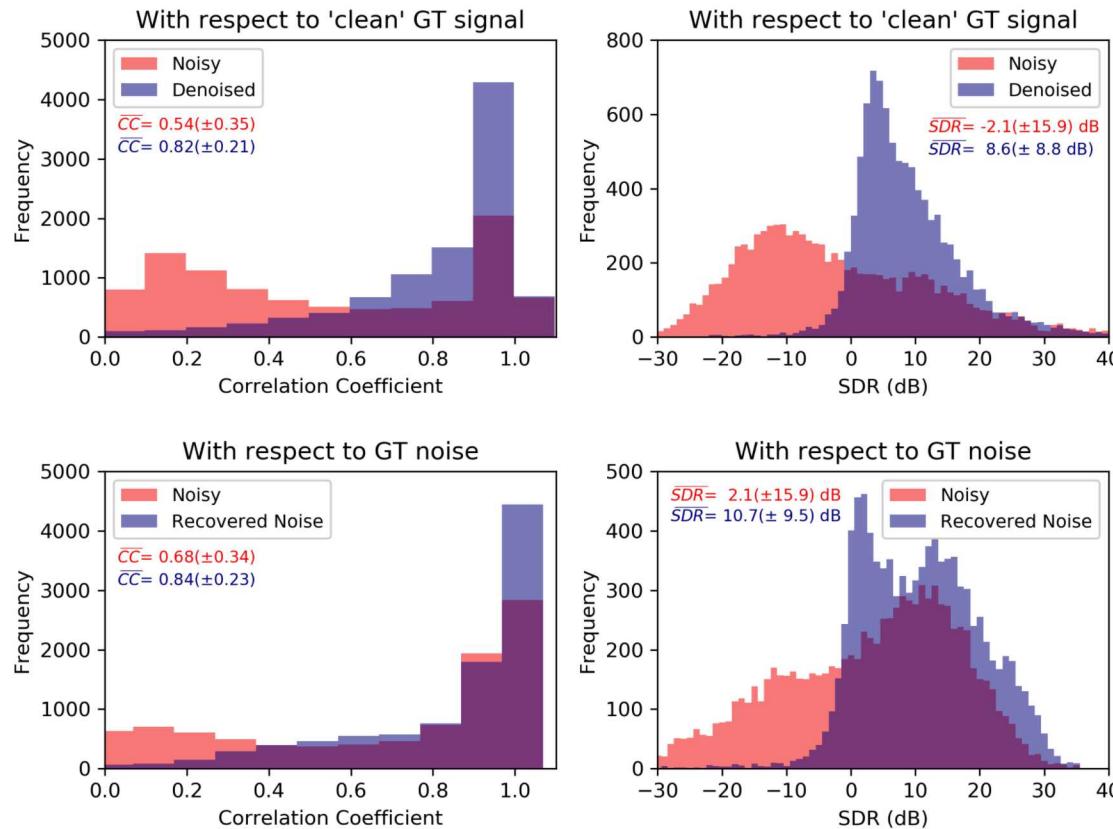
- Again, the recovered waveforms show high degrees of fidelity to the GTs.

Evaluation Based on Constructed Data of the Test Set



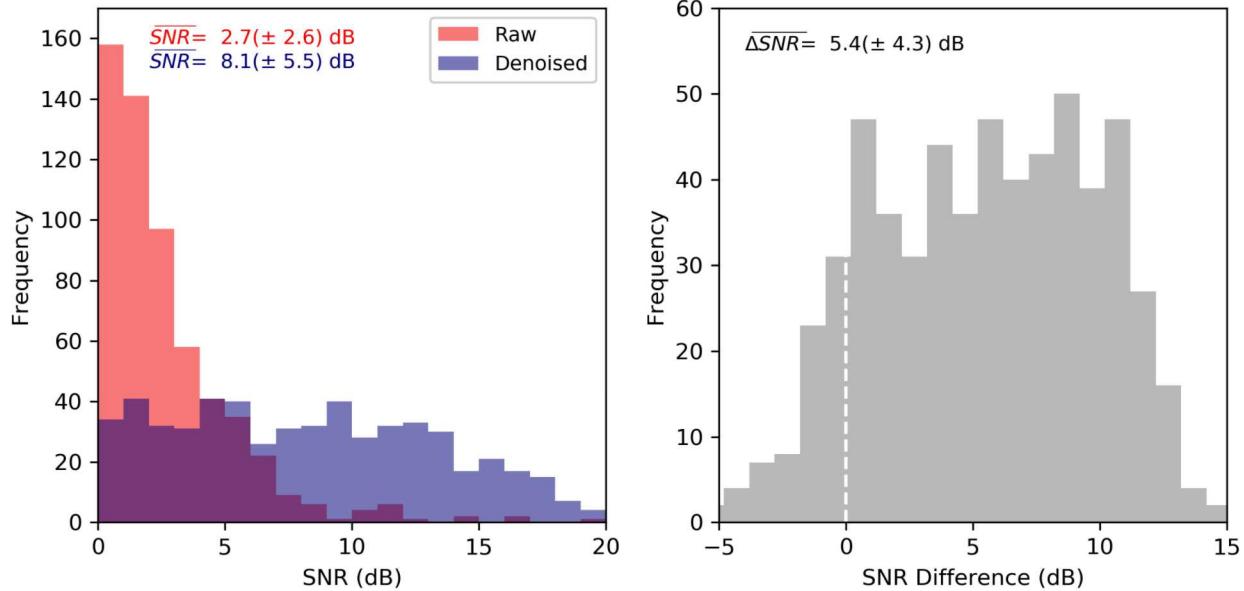
- 9,560 constructed noisy waveforms of the test set
- The denoiser achieves an average improvement in SNR of ~ 5 dB.

Evaluation Based on Constructed Data of the Test Set



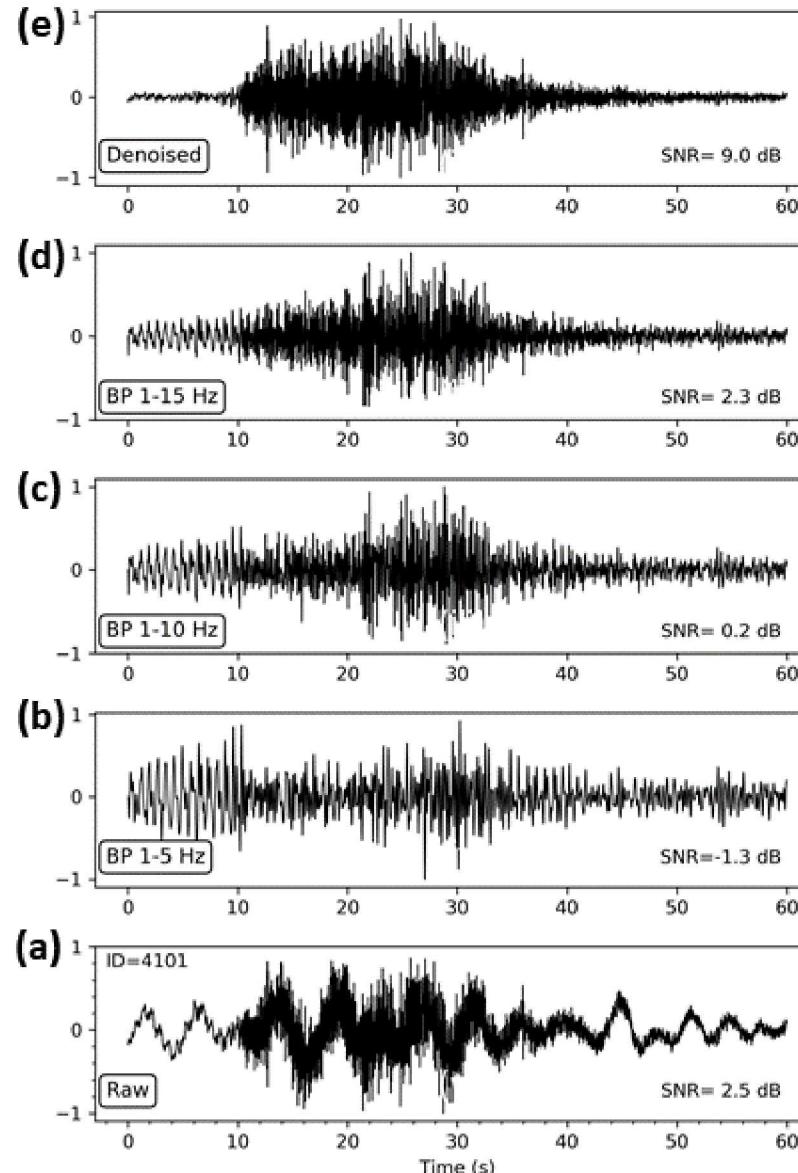
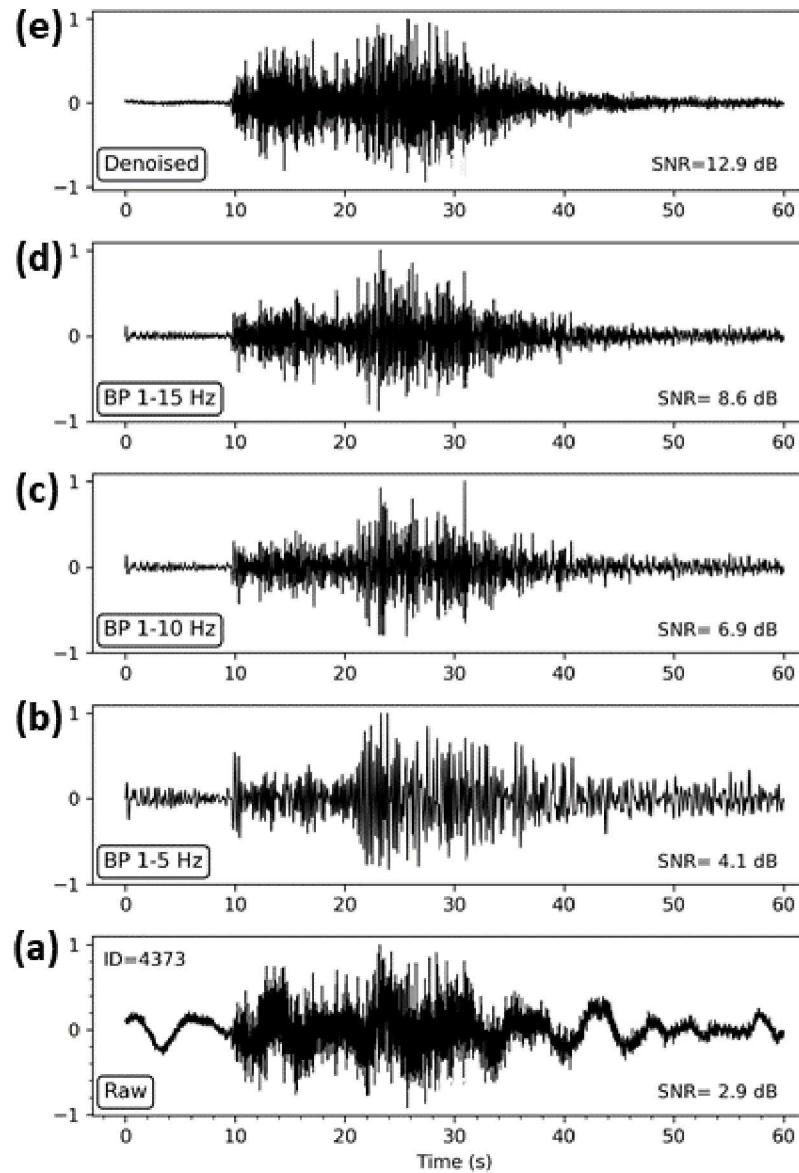
- High average cross correlation values ($CC=0.82-0.84$) for both the signal and noise.
- This suggests that most of the 9,560 waveforms recovered by the network are very similar to their respective GT.
- As implied by the high average SDRs, most of the recovered waveforms suffer little amplitude distortion.

Evaluation Based on Real Data – Denoised vs. Raw



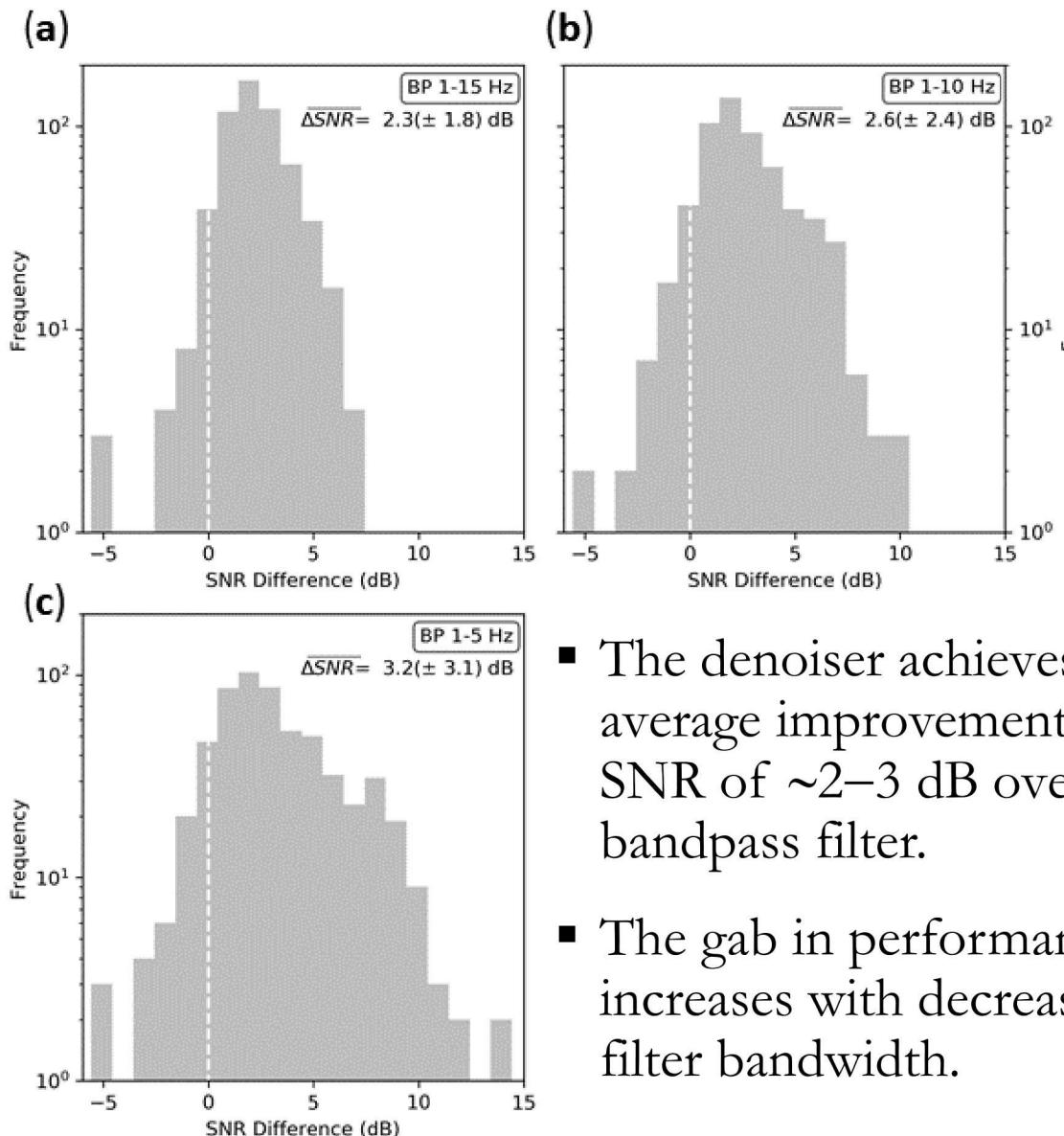
- 584 ‘real’ waveforms from events with M_C from less than -0.1 to 4.5
- The denoiser achieves an average improvement in SNR of ~5 dB over raw data.

Evaluation Based on Real Data – Denoised vs. Frequency Filtering



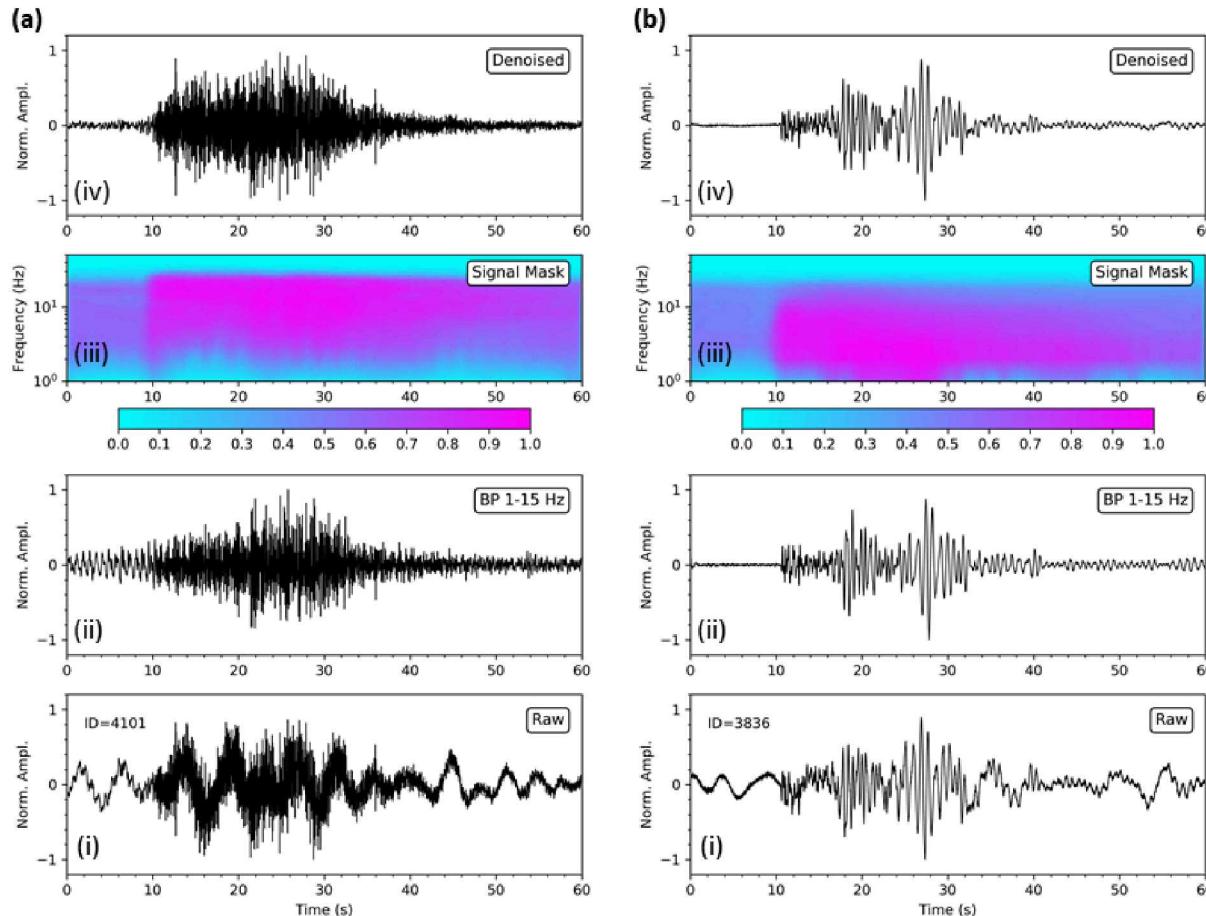
- Compared with both the raw and filtered data, the denoised seismograms show reduced pre-*P* noise and enhanced *P* amplitudes,
- Resulting in improved SNRs.

Evaluation Based on Real Data – Denoised vs. Frequency Filtering



- The denoiser achieves an average improvement in SNR of $\sim 2\text{--}3$ dB over bandpass filter.
- The gap in performance increases with decreasing filter bandwidth.

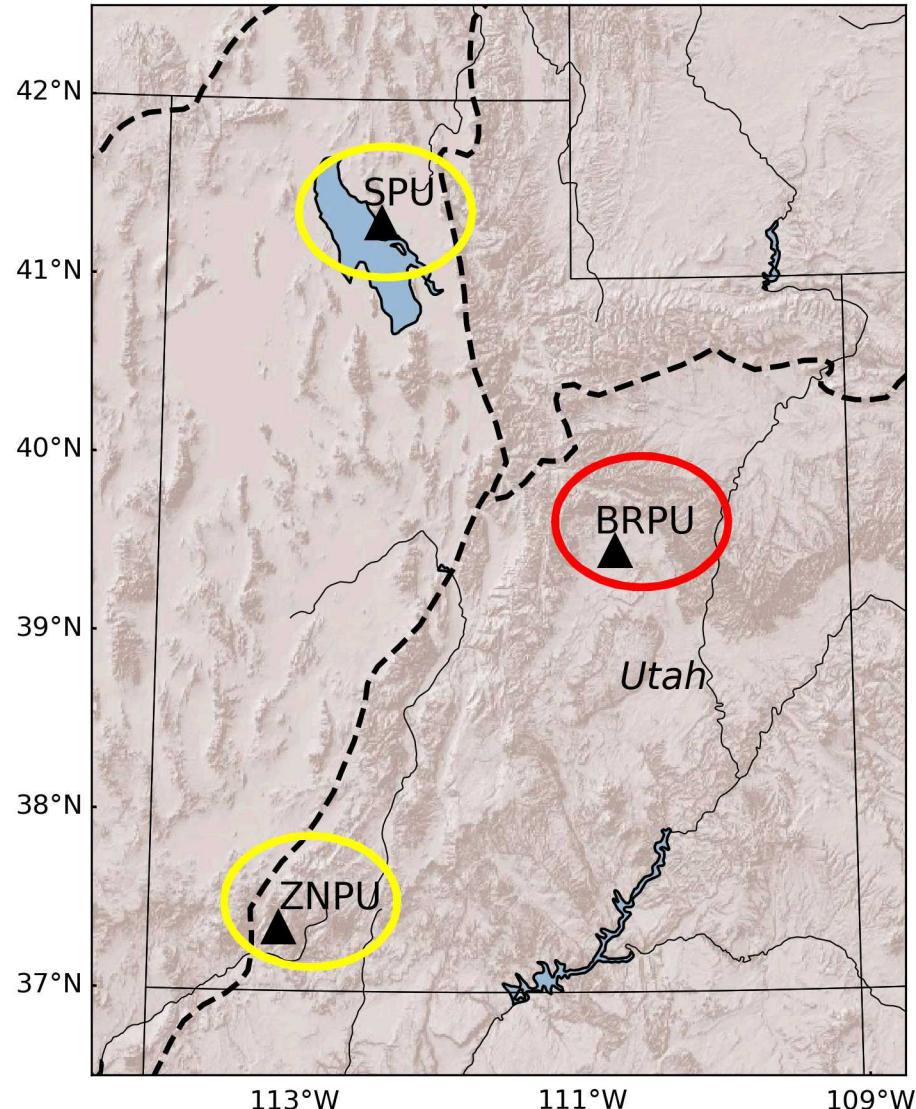
Why Does Denoising Outperform Frequency Filtering?



- The values of the elements of the mask operator vary with both time & frequency in the range of 0–1.
- The operator for a bandpass filter would appear as a streak of 1s within the passband.
- The mask operator adapts to the changing characteristics of the input signal.

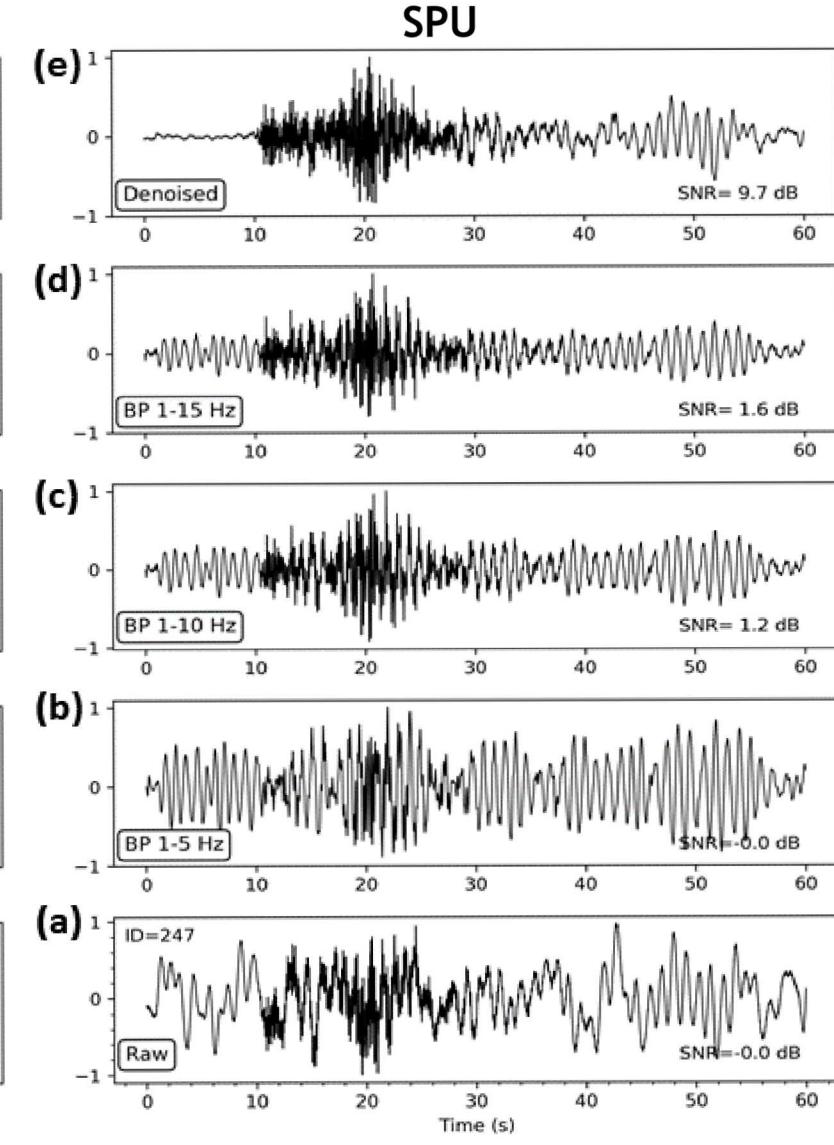
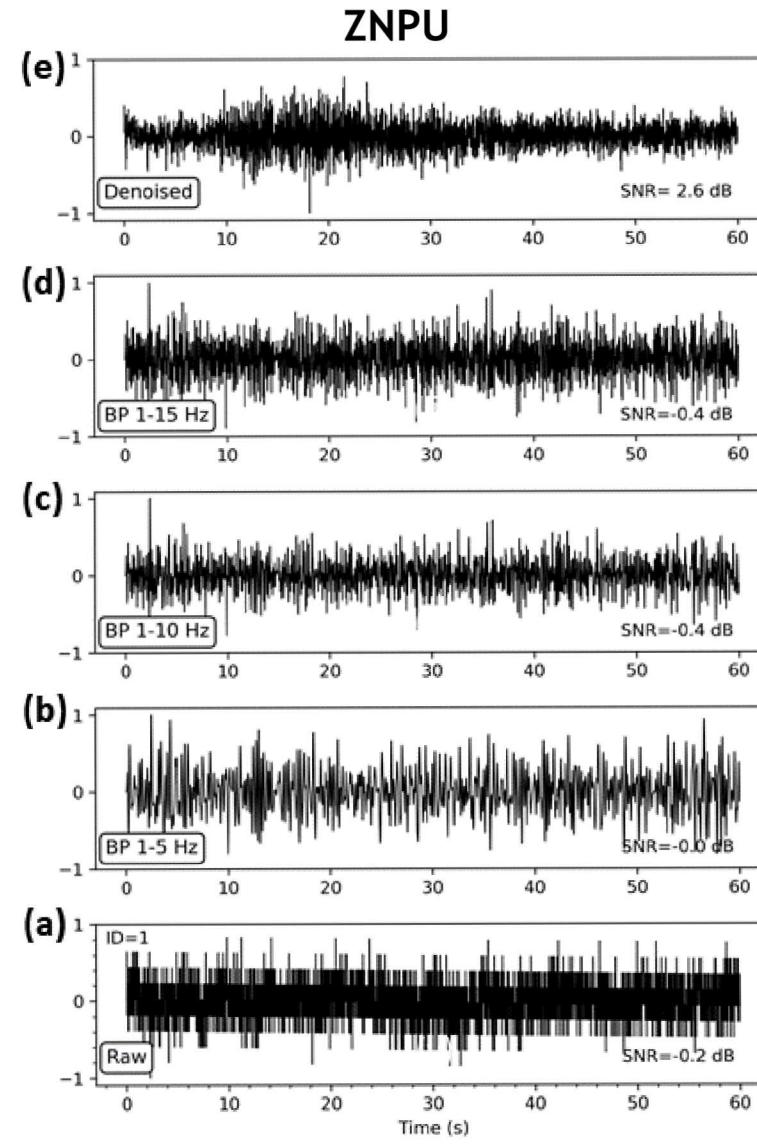
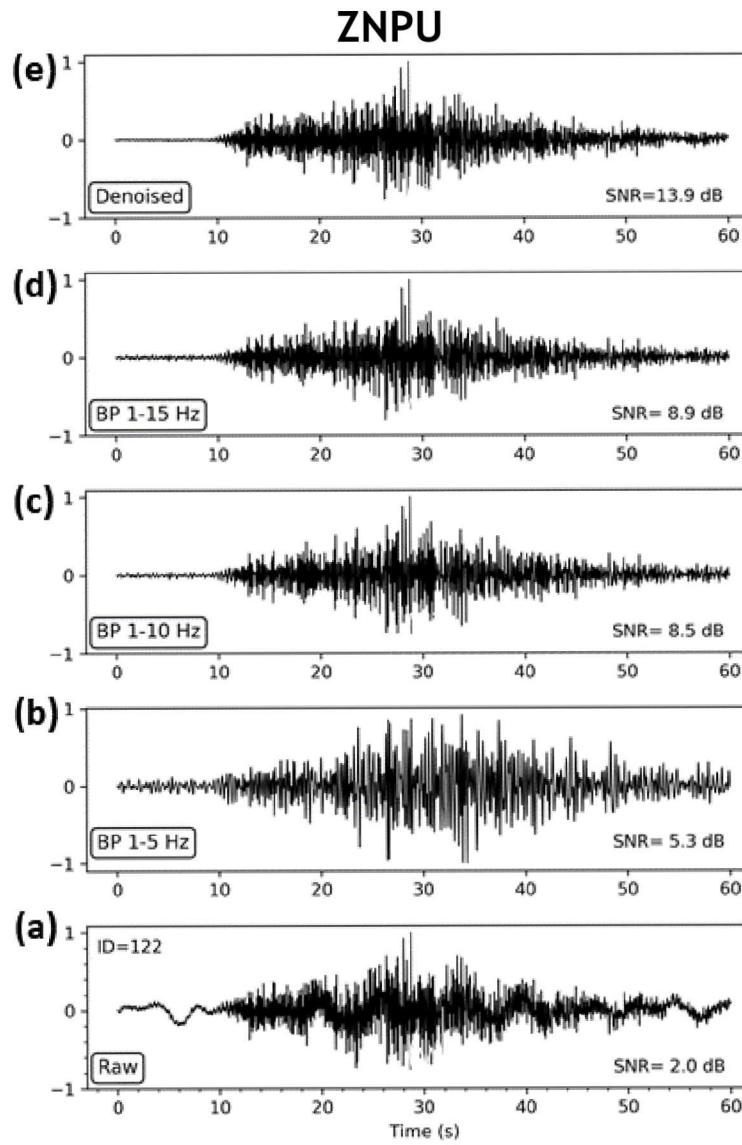
18 Model Transportability

Two stations (ZNPU & SPU) not involved in model training



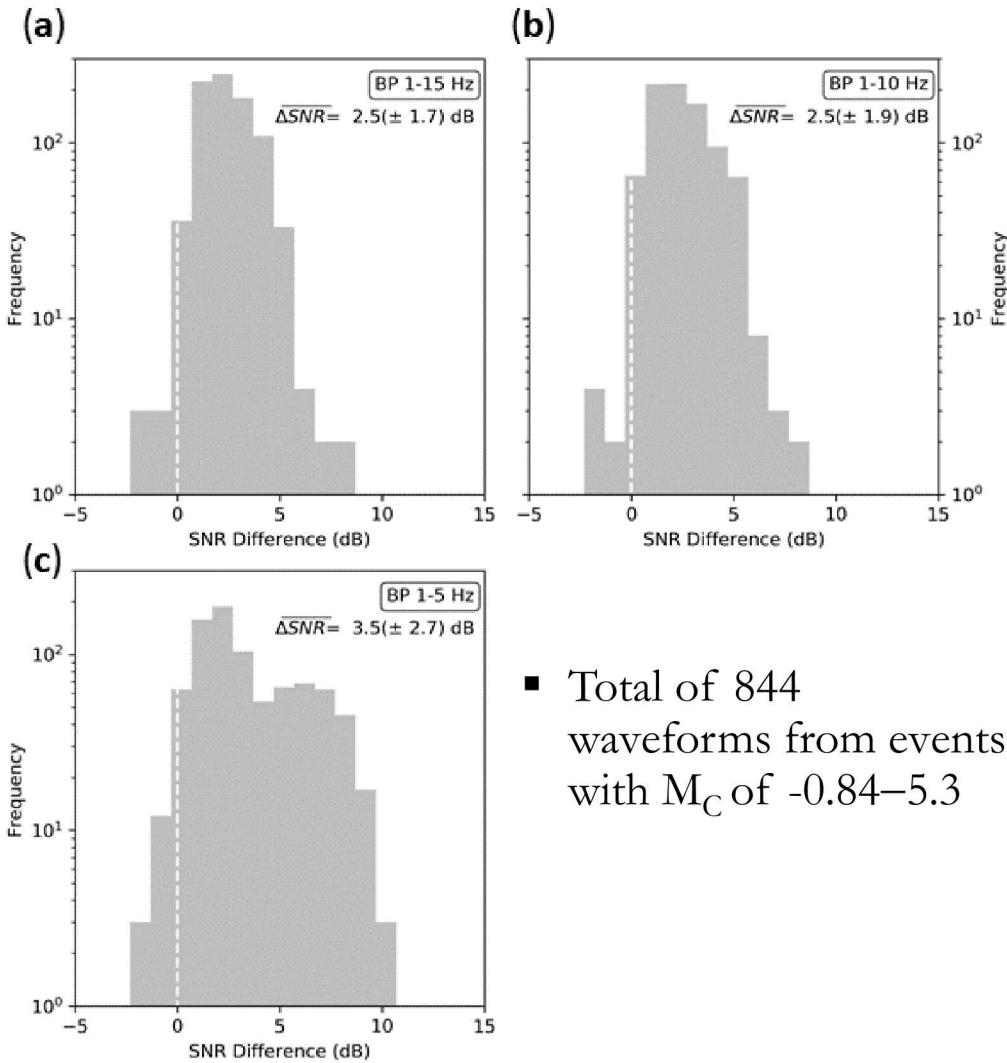
- Large geographical separations insure that variabilities (in terms of propagation effects & background noise) are sufficiently captured.

19 Model Transportability



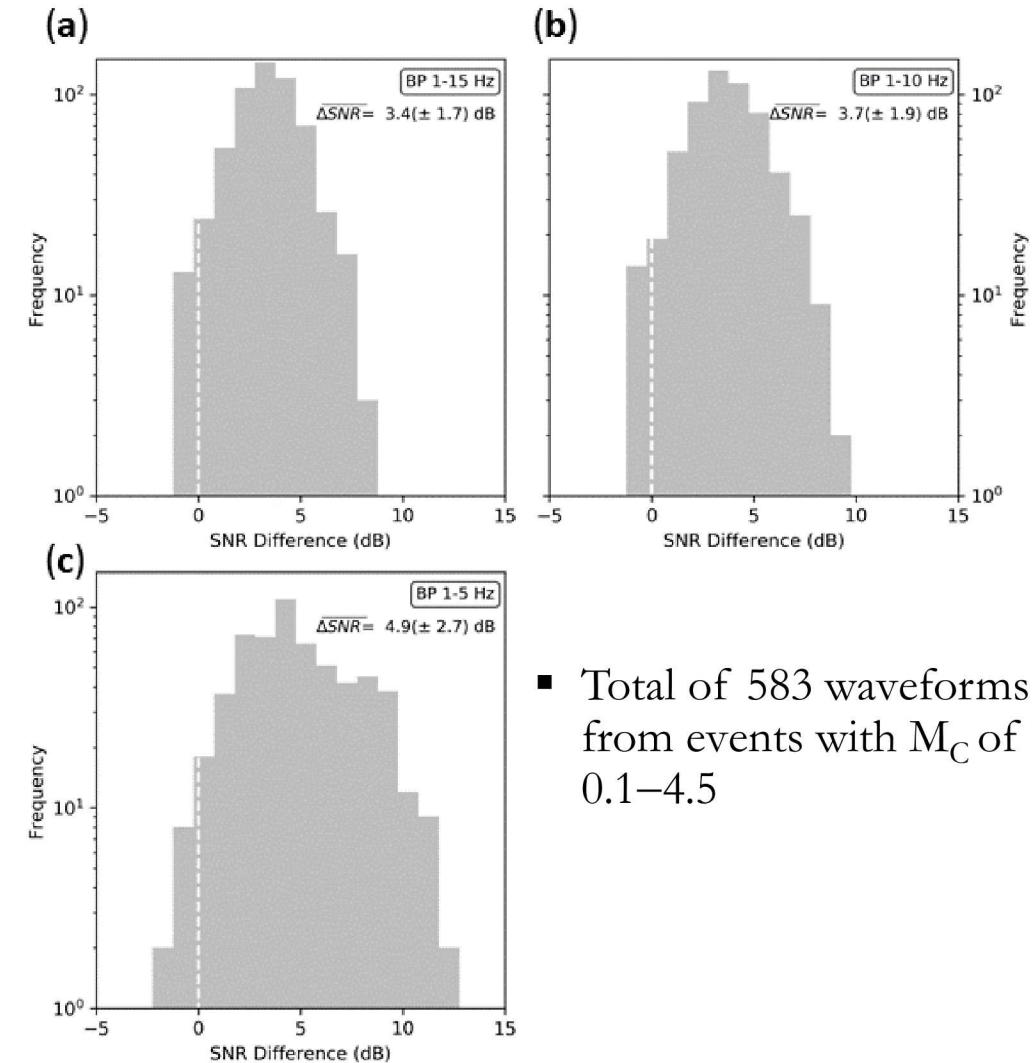
Model Transportability

ZNPU



- Total of 844 waveforms from events with M_C of $-0.84\text{--}5.3$

SPU



- Total of 583 waveforms from events with M_C of $0.1\text{--}4.5$

- For these stations, denoising achieved an average improvement of $\sim 3\text{--}5$ dB over bandpass filtering.

Conclusions

- We implemented a seismic denoising method that uses a trained deep CNN model to decompose an input waveform into a signal of interest and noise.
- Test results based on more than 9,000 constructed waveform data suggest that most of the waveforms recovered by the trained deep convolutional network show high degree of fidelity to their respective GTs, in terms of both waveform similarity and amplitudes.
- Processing of real seismograms suggests that the denoiser achieves an average improvement in SNR of \sim 5 dB and \sim 2–5 dB over the raw and bandpass filtered data, respectively.
- The CNN model also works well for UUSS stations not involved in model training, suggesting that it is transportable around Utah, and possibly also to neighboring regions with similar wave propagation characteristics and background noise.



THANK YOU FOR YOUR ATTENTION

Target (Mask) Calculations

- Signal Mask

$$M_S(t, f) = \frac{|S(t, f)|}{|S(t, f)| + |N(t, f)|}$$

- Noise Mask

$$M_N(t, f) = \frac{|N(t, f)|}{|S(t, f)| + |N(t, f)|}$$