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Bayesian inversion and optimization of geothermal reservoirs using multivariate adaptive regression spline

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1 **An efficient Bayesian inversion of a geothermal
2 prospect using a multivariate adaptive regression
3 spline method**

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23 **Abstract**

24 In this study, an efficient Bayesian framework equipped with a Multivariate
25 Adaptive Regression Spline (MARS) technique is developed to alleviate computational
26 burdens encountered in a conventional Bayesian inversion of a geothermal prospect. Fast
27 MARS models are developed from training dataset generated by CPU-intensive
28 hydrothermal models and used as surrogate of high-fidelity physical models in Markov
29 Chain Monte Carlo (MCMC) sampling. This Bayesian inference with MARS-enabled
30 MCMC method is used to reduce prior estimates of uncertainty in structural or
31 characteristic hydrothermal flow parameters of the model to posterior distributions. A
32 geothermal prospect near Superstition Mountain in Imperial County of California in USA
33 is used to illustrate the proposed framework and demonstrate the computational
34 efficiency of MARS-based Bayesian inversion. The developed MARS models are also
35 used to efficiently drive calculation of Sobol' total sensitivity indices. Only top sensitive
36 parameters are included in Bayesian inference to further improve the computational
37 efficiency of inversion. Sensitivity analysis also confirms that water circulation through
38 high permeable structures, rather than heat conduction through impermeable granite, is
39 the primary heat transfer method. The presented framework is demonstrated an efficient
40 tool to update knowledge of geothermal prospects by inverting field data. Although only
41 thermal data is used in this study, other type of data, such as flow and transport
42 observations, can be jointly used in this method for underground hydrocarbon reservoirs.

43

44 *Keywords:* Geothermal prospect; inversion; surrogate; uncertainty; sensitivity

45

46 **1. Introduction**

47 Quantitative, model-based prediction of geothermal reservoir behavior requires
48 knowledge of both structural and parametric hydrothermal characteristics of the reservoir
49 system. These include the location, size, and shape of important hydrogeologic flow units
50 and faults, their associated permeability and thermal conductivity, as well as bounding
51 temperature and fluid pressure and saturation conditions. These elements are difficult to
52 fully characterize in the subsurface prior to reservoir development and are, at best, not
53 completely known. This uncertainty will limit the accuracy of reservoir model predictions
54 and reduce the reliability of any type of geothermal production or design that is based
55 upon such predictive capabilities. Inverse methods are often utilized to better identify and
56 estimate uncertain flow properties or system characteristics by matching field
57 observations to corresponding predictive model simulations (Carrera et al., 2005; Hill and
58 Tiedeman, 2007; Tompson et al., 2013; Tonkin and Doherty, 2009), yielding a model
59 with improved accuracy and reduced uncertainties. Depending on the specific techniques
60 used, inverse modeling may be subject to mathematical limitations or require a large
61 number of intensive forward model simulations in order to be successful.

62 It is widely recognized that incomplete knowledge of the underground fluid reservoir
63 may introduce considerable uncertainty into modeling analyses of such systems and can
64 typically lead to ill-posed nonlinear inverse problems with multiple solutions (Carrera,
65 1988; de Marsily et al, 1999; Oliver et al., 2008). The idea of “Bayesian inference” has
66 been demonstrated to provide an effective inverse framework which addresses the issues
67 of ill-posedness and non-uniqueness by incorporating prior information and presenting
68 the inversed solution in terms of probability distribution (e.g., Cui et al., 2011; Fu and

69 Gomez-Hernandez, 2009; Oliver et al., 1997; Tarantola, 2004). In most cases, the
70 posterior densities are difficult to sample directly from the analytical forms of distribution.
71 Markov Chain Monte Carlo (MCMC) approaches provide a more practical simulation
72 method for sampling from target distributions as a means to approximating posterior
73 distributions for parameters or quantities of interest (e.g., Efendiev et al., 2005). However,
74 for many types of large-scale modeling problems, including geothermal prospect
75 characterization, MCMC simulations may become computationally prohibitive because
76 of the large number of uncertain parameters that need to be considered (curse of
77 dimensionality), the absolute size and discretization of the modeling domain of interest,
78 and/or the complexity of the flow physics involved in each forward calculation (Smith
79 and Marshall, 2008; Tompson et al., 2013). Although significant advancements in
80 MCMC sampling efficiency have been made recently (Liu et al., 2000; Mariethoz et al.,
81 2010; Vrugt et al., 2009), the computational burden may still be unaffordable for large-
82 scale high-resolution numerical simulation problems.

83 Two promising ways to address this challenge include (1) the use of up-front
84 parameter sensitivity analyses to identify the most important parameters pertinent to an
85 analysis of interest, prior to any formal inversion effort, and (2) the development of
86 cheaper “surrogate” forward models for application in the MCMC sampling. Surrogate
87 models attempt to replicate the behavior of complex models with simpler models using
88 fewer but sensitive parameters. Sensitivity is a measure of the contribution of an input
89 variable to the total variances of an output variable. In this study, the sensitivity analysis
90 is used as a “screening” analysis to help focus the stochastic inversion work on

91 parameters, properties, or characteristics that would appear to be most important, thus
92 focusing computational efforts where they will be most beneficial.

93 A surrogate model is meant to provide a fast approximation of a high-fidelity physical
94 model calculation. Applications of surrogate modeling techniques in hydrology have
95 been extensively studied in recent years (Razavi et al., 2012). A variety of approximation
96 techniques have been tried, such as polynomials (e.g., Fen et al., 2009), radial basis
97 functions (RBFs) (e.g., Regis and Shoemaker, 2007), kriging (e.g., Simpson and Mistree,
98 2001), support vector machines (SVMs) (Zhang et al., 2009), artificial neural networks
99 (ANNs) (Behzadian et al., 2009; Dowla and Rogers, 2003), and sparse grid interpolation
100 (Zeng et al., 2012). However, few studies have applied the multivariate adaptive
101 regression spline (MARS) technique, a non-parametric approximation method developed
102 by Friedman (1991). In a thorough review of surrogate modeling applications in water
103 resources, none of 48 applications reviewed by Razavi (2012) has used the MARS
104 technique. In a recent application of surrogates in optimizing the process of hydraulic
105 fracturing, Chen et al. (2013) compared MARS to a suite of polynomial models including
106 different number of input parameters and in various orders, and surrogate model
107 approximated by MARS was demonstrated to have the best predictive performance.
108 Motivated by this successful application of MARS in optimization, this study employs
109 this function approximation technique to construct a surrogate of hydrothermal flow
110 model for use in applying a Bayesian inversion algorithm to a geothermal prospect.

111 **2. Methodology**

112 The proposed methodology involves identification of important, yet uncertain
113 parameters for the problem of interest, sampling in high-dimensional parameter space,

114 development of numerical hydrothermal flow models, evaluation of response functions,
115 construction and validation of MARS models, performing global sensitivity analyses, and
116 coupled execution of Bayesian inference with MARS models.

117 2.1. Inversion framework

118 As illustrated in Figure 1, the inversion proceeds as follows:

- 119 1. A set of M design variables pertinent to the problem are identified and associated with
120 statistical distributions descriptive of their priori uncertainty. In this case, these
121 variables pertain to a series of parametric and structural characteristics of the
122 hydrothermal flow Case Study described below. Their uncertainty, as indicated by
123 their distributions and ranges, are representative of prior knowledge about the target
124 geothermal field and formation.
- 125 2. Each of these variables are sampled N times from their probability distributions using
126 a Latin Hypercube (LH) method (McKay et al., 1979). These N data realizations are
127 used to drive N hydrothermal flow model realizations to (in our case below) a natural
128 steady state and their corresponding responses (in our case below, temperatures at a
129 finite set of observation locations) are evaluated from the simulated results.
- 130 3. The N design variable-response pairs (shaded in Figure 1) are then used as a training
131 and validation dataset to construct a surrogate MARS model. To make best use of
132 limited dataset, leave-one-out cross validation (LOOCV) method is applied to
133 validate the fitted MARS model (Picard and Cook, 1984). Given N input samples, a
134 surrogate MARS model is constructed N times, each time leaving out one of the input
135 sample from training, and using the omitted sample to test the model.

136 4. The importance of the design variables in the hydrothermal model system are ranked
137 according to Sobol' total sensitivity indices (Sobol', 1993, 2003), obtained from a
138 global sensitivity analysis of response surface to input design variables. The Sobol'
139 method computes and decomposes the variances of response into fractions attributed
140 to each input (first-order indices) variable and their interactions (second- or higher-
141 order indices), and hence the fractions (sensitivity indices) measure contribution of
142 each input variable to variances of response variable (Chen et al., 2013). Only
143 sensitive variables are included in Bayesian inference.

144 5. The surrogate model is utilized in place of the hydrothermal flow model within a
145 Bayesian inversion scheme (Tompson et al., 2013), from which posterior distributions
146 of the sensitive variables are inferred from comparisons with observed temperature
147 data. The posterior data distributions represent a subset of the prior data that lead to
148 solutions most consistent with the observed temperature data.

149 2.2. Hydrothermal model

150 The mass balance equation for transient hydrothermal water flow in saturated porous
151 media is considered in this study can be written as:

152
$$\partial(\phi\rho)/\partial t = -\nabla \cdot (\phi\rho\mathbf{v}) + Q, \quad (1)$$

153 where Q is the source/sink term, ϕ is the porosity, ρ is the fluid density, and \mathbf{v} is the
154 velocity, which can be computed from Darcy's law: $\phi\mathbf{v} = -\mathbf{k}(\nabla P + \rho g \nabla z)/\mu$, where \mathbf{k}
155 is the permeability tensor, P is the fluid pressure, μ is the fluid viscosity, g is the
156 gravitational constant, and z is an elevation above some datum. In the current
157 implementation, the principal axes of the permeability tensor are assumed to be aligned
158 with the xyz coordinate system so that \mathbf{k} is diagonal (k_x, k_y, k_z). Permeability of each

159 geological unit is assumed isotropic ($k_x = k_y = k_z$) so we use K instead of \mathbf{k} to represent
160 permeability below this point. Note that the density and viscosity will, in general, be
161 temperature (T) and pressure (P) dependent.

162 In addition to the mass balance equation, the energy balance equation governing heat
163 transfer can be expressed as:

164
$$\partial[\phi\rho u + (1 - \phi)\rho_s C_{ps}(T - T_r)]/\partial t = \nabla \cdot [\phi\rho HK\nabla P/\mu + K_T \cdot \nabla T] + Q_T, \quad (2)$$

165 where ϕ is the rock porosity, u is the water internal energy, ρ_s is the rock density, C_{ps} is
166 the rock heat capacity, T_r is a reference temperature, H is the water enthalpy, K_T is the
167 averaged thermal conductivity of both water and rock, and Q_T is the heat source/sink term.

168 The above mass and energy balance partial differential equations are discretized and
169 solved numerically in NUFT (Nonisothermal Unsaturated-saturated Flow and Transport),
170 a code developed in Lawrence Livermore National Laboratory and applied successfully
171 in many models simulating mass and heat transfer (Nitao, 1998). NUFT is used to build
172 hydrothermal models in this study. Fault size, temperature T at reservoir bottom boundary,
173 rock permeability K and thermal conductivity K_T of each geologic unit are assumed key
174 uncertain reservoir properties for heat transfer, and hence selected as design variables for
175 inversion stage. All the hydrothermal model simulations run to steady state under natural
176 condition.

177 2.3. Multivariate adaptive regression spline (MARS)

178 Multivariate adaptive regression spline represents a nonparametric technique which
179 adaptively develops local models in local regions for flexible regression modeling of high
180 dimensional data. A MARS model can be expressed as

181
$$\hat{f}(\mathbf{x}) = \sum_{i=1}^k a_i B_i(\mathbf{x}), \quad (3)$$

182 where $\mathbf{x} \in \mathcal{R}^m$, and \mathcal{R}^m is the m -dimensional domain of interest. k and a_i are the number
183 and coefficients of associated basis functions $B_i(\mathbf{x})$ given by

184
$$B_i(\mathbf{x}) = \begin{cases} 1, & i = 1 \\ \prod_{j=1}^{J_i} [S_{ji} \cdot (x_{v(j,i)} - t_{ji})]_+, & i = 2, 3, \dots \end{cases} \quad (4)$$

185 where $(\cdot)_+ = \max(0, \cdot)$, J_i is the interaction order of basis B_i , that is, the number of
186 variables included in the basis function, $S_{ji} = \pm 1$ is the sign indicators, $v(j,i)$ is the index
187 of the design variable x which is split on knots t_{ji} . For example, suppose a basis function
188 is given by $B_i = (x_3 + 2.5)_+[-(x_5 - 3.3)]_+$. Apparently, the interaction order is 2, so
189 $J_i = 2$. The sign indicators $S_{1i} = 1, S_{2i} = -1$. The index for the design variable are
190 $v(1, i) = 3, v(2, i) = 5$, and the knots are given by $t_{1i} = -2.5, t_{2i} = 3.3$.

191 The first and second derivatives are enforced to match on the boundaries of adjacent
192 regions to ensure continuity between local models. Once the number of locations of knots
193 (points at the boundaries) is adaptively chosen based on the response function changes,
194 the coefficients a_i and basis functions $B_i(\mathbf{x})$ can be examined and determined.
195 Comprehensive illustration of the MARS algorithm can be found in Friedman (1991).
196 Compared to other popular techniques, the use of MARS is limited to automatic
197 engineering design applications (e.g., Sudjianto et al., 1998) and has seldom been
198 reported in hydrothermal literature. The superiority of MARS over other high
199 dimensional regression methods appears to be accuracy and reduction in computational
200 cost of fitting process (Chen et al., 2013; Jin et al., 2001).

201 2.4. MARS-enabled Bayesian inference

202 The purpose of Bayesian inference is to update the beliefs about uncertain parameters
203 by combining information from the prior distribution and the measurements through the
204 calculation of the posterior distribution. Assuming \mathbf{x} is the vector formed by design
205 variables to be inverted, \mathbf{y} is the measurements, Bayes' theorem relates the posterior
206 distribution $p(\mathbf{x}|\mathbf{y})$ to the product of the conditional probability of the measurements
207 $p(\mathbf{y}|\mathbf{x})$ and the prior probability $p(\mathbf{x})$ of design variables as follows:

208
$$p(\mathbf{x}|\mathbf{y}) = p(\mathbf{y}|\mathbf{x})p(\mathbf{x})/p(\mathbf{y}), \quad (5)$$

209 where marginal distribution $p(\mathbf{y}) = \int p(\mathbf{x})p(\mathbf{y}|\mathbf{x})d\mathbf{x}$ is an integral, which doesn't
210 provide any additional information about posterior distribution and can be seen as a
211 normalized constant. $p(\mathbf{x})$ represents uncertainty prior to any knowledge of
212 measurements, and is assumed uniformly distributed within an appropriate range in this
213 study. Hence, the posterior $p(\mathbf{x}|\mathbf{y})$ is proportional only to $p(\mathbf{y}|\mathbf{x})$.

214 $p(\mathbf{y}|\mathbf{x})$ is also called likelihood function, which quantifies the degree of fit between
215 predictions and measurements. The likelihood can be calculated by forwarding
216 hydrothermal models with the given design variables to steady state, at which the errors
217 between predicted and measured temperatures at observed locations can be included

218
$$\boldsymbol{\epsilon} = \mathbf{y} - f(\mathbf{x}), \quad (6)$$

219 where $\boldsymbol{\epsilon}$ is the errors, $f(\mathbf{x})$ is the predictions from NUFT models. The smaller the errors
220 are, the higher the likelihood is. By assuming $\boldsymbol{\epsilon}$ follows multiple dimensional Gaussian
221 distribution with zero mean and known covariance matrix \mathbf{C} , the likelihood can be
222 expressed as (Zeng et al., 2012):

223
$$p(\mathbf{y}|\mathbf{x}) = \exp(-\boldsymbol{\epsilon}^T \mathbf{C}^{-1} \boldsymbol{\epsilon}/2)/[(2\pi)^{n/2} |\mathbf{C}|^{1/2}], \quad (7)$$

224 where n is the number of measurements, $|\mathbf{C}|$ is the determinant of \mathbf{C} . In the study, MARS
225 model $\hat{f}(\mathbf{x})$ is used as surrogate of NUFT hydrothermal model $f(\mathbf{x})$ in calculating this
226 Gaussian likelihood function. In this way, the posterior can be obtained without running
227 expensive NUFT models during MCMC sampling, thus accelerating Bayesian inversion
228 significantly.

229 **2.5. Implementation**

230 The proposed framework is written in Python by incorporating hydrothermal NUFT
231 models and various numerical codes from PSUADE suite (Tong, 2009), including LH
232 sampling, MARS approximation, Sobol' method, and MCMC algorithm.

233 **3. Case studies and discussions**

234 To illustrate and demonstrate the proposed approach, a geothermal prospect at
235 Superstition Mountain in California is chosen as the example study owing to its data
236 availability of geological stratigraphy and borehole temperature logs from Navy
237 geothermal program (Figure 2) (Bjornstad et al., 2006; Tiedeman et al., 2011).

238 **3.1. Three-dimensional model development for Superstition Mountain**

239 A three-dimensional geologic model built with digital elevation and layer horizon
240 data in Tompson et al. (2008) are used to conceptualize the geologic structure of
241 Superstition Mountain (Figure 2c). Geophysical and drilling logs from the three
242 boreholes near Superstition Mountain provide additional information to refine the model
243 (Figure 2b). The prospect is bounded on the southwest by granite basement and
244 sedimentary layers to the northeast. A major active fault, the Superstition Mountain fault
245 (SMF), lies near the prospect. The study by Layman Energy Associates (2012) supported

246 a hypothesis that one or more of the high-permeable principal or cross faults serve as the
247 vertical pathways for hot water flow from deep zones to shallow aquifers through low
248 permeable granite zone. This water circulation is believed to be the cause of elevated
249 temperatures observed in three NAFEC boreholes and nearby shallow temperature
250 surveys. A recent hydrothermal model developed using NUFT for the prospect (Mellors
251 et al., 2013; Tompson et al., 2013), which contained a vertical conjugate fault (CF)
252 transverse to SMF and extending to northeast through NAFEC-3, predicted temperature
253 profiles closely matching temperature logs of three NAFEC boreholes.

254 This NUFT model domain is adapted in our model as the core region enclosed by a
255 larger far field domain (Figure 3a). The X direction in the core domain is parallel with the
256 CF, while the Y direction is parallel with the SMF. The core model domain used here
257 extends along the X axis 6.5 km to the northeast of the SMF and is restricted to a 1.5 km
258 width in the Y direction, with the center of the left boundary intersecting CF at right
259 angle (Figure 2b). The core domain extends vertically downwards 3.2 km from the
260 ground surface and is discretized into 100 m cubic grid blocks. The current system is
261 considered to be fully saturated throughout the domain. In the future it will be upgraded
262 to more representative partially saturation conditions in the shallower sediments. The
263 larger far-field domain incorporates reduced grid resolution beyond its core as a means to
264 control computational costs. Representation of geological structures in the model grid is
265 simplified from the geologic model. As shown in vertical X-Z section crossing the center
266 of left boundary, where CF is located, the five geologic units crossing the core domain
267 section are sequenced from the bottom as a fractured, low permeability Granite, a
268 permeable sandstone layer Ti, and alluvial sediment layers Tp2, Tp1, Qb, along a

269 downward slope in X direction (Figure 3b). The left boundary is consistent with SMF at
270 X=0 m, and the 100-m thick permeable vertical CF is normal to the left boundary with
271 uncertain length and height (Figure 3c). Pressure and temperature are specified at the top
272 boundaries to represent the average atmospheric conditions. High temperature is fixed at
273 the bottom boundary to mimic the geothermal heat source, with a lower fixed temperature
274 at the ground surface. Groundwater is allowed to flow from the left (X = 0) to the right
275 (X = 6.5km) sides of the as a result of specified pressure conditions that reproduce a
276 small hydraulic gradient in this area, and is also allowed to enter the bottom of the
277 domain as a result of another fixed pressure condition. Depending on permeability
278 conditions, such inflows may support the generation of hydrothermal inflows that may
279 circulate and exit the right side of the boundary. No flow conditions are maintained along
280 the Y faces of the domain.

281 Because this is considered a “natural” flow system, the hydrothermal models are used
282 to develop a steady-state flow and temperature solution by running them in a transient
283 mode from provisional initial conditions for one million years. The predicted
284 temperatures at steady state time are compared to measurements at observing locations
285 along three NAFEC boreholes during Bayesian inversion.

286 3.2. MARS models construction

287 Following the procedure outlined in Figure 1 and Section 2.1, the inversion starts
288 with the identification of a set of parameters to be treated uncertain (design variables).
289 The differential equation governing geothermal heat transfer (Eq. 2) indicates formation
290 permeability K and thermal conductivity K_T will be crucial properties controlling hot
291 groundwater circulation and heat conduction respectively. Thus the two properties for

292 faults, Granite and four sediment formations, totally 12 variables, are included as design
293 variables. The values of temperature fixed at the bottom boundary, which represent the
294 strength of heat source, are partially unknown (certainly warmer than the surface
295 temperature) but may affect steady state temperature distribution across the model
296 domain, and hence are included as design variables too. In addition, the length and height
297 of CF, which is anchored at the SMF at low left corner, are also considered random. The
298 CF unit is considered to be a more permeable feature able to support geothermal
299 circulation into shallower zones if sufficient flow connectivity exists. These 15 design
300 variables, along with their lower and upper bounds, are listed in Table 1. The log-
301 transformed permeabilities and all the other variables are assumed to follow uniformly
302 random distribution across their indicated ranges. A total of 1500 input samples are
303 drawn from the 15-dimensional parameter space using the LH method, with each sample
304 vector containing, as components, 15 values of the design variables. The 15 component
305 values of each sample vector, together with other fixed parameters, are written into the
306 input file of NUFT model for simulation. The temperatures at 23 observation locations
307 (red circles in Figure 4) along the three NAFEC boreholes, obtained from the output of
308 the NUFT model, are used as the response values. The 1500 NUFT model simulations,
309 specifically the 1500 sets of input vectors and 1500 sets of output response values, are
310 used as both a training and a validation dataset to construct the MARS models. Each
311 MARS model $\hat{f}(\mathbf{x})$ consists of 100 basis functions $B_i(\mathbf{x})$, each with 10 orders of
312 interactions J_i (10 design variables x). It should be noted that a well-fitted MARS model
313 does not necessarily mean that it will have good performance for prediction due to over-
314 fitting issue, and hence it has to be validated before the use for prediction. The predictive

315 performance of MARS models in this study is measured by LOOCV method (Chen et al.,
316 2013; Picard and Cook, 1984). The quality of the MARS models can be illustrated by
317 scatter plot comparing the response values simulated by the surrogate model versus those
318 simulated by the physical NUFT model, based upon the 1500 samples. As shown in
319 Figure 5, the *R*-squared values obtained for the scatter plots in both the fitting and
320 validation steps of the MARS model (with mean response values) are 0.979 and 0.959
321 respectively, suggesting a good predictive ability of the well-fitted MARS model.

322 3.3. Global sensitivity analysis

323 Sensitivity of model responses to the design variables values can be efficiently
324 calculated using MARS models. The Sobol' total sensitivity indices (SI) for 15 variables
325 are listed in Table 1 and visualized in Figure 6 (Sobol' 2003). As expected, the
326 dimensional characteristics of CF, i.e., height and length, rank as the top two (1 and 2)
327 sensitive variables for defining the temperature distribution in the aquifer where NAFEC
328 boreholes are located (depth < 1000 m), while the permeability of the CF and Ti units,
329 which represent primary groundwater circulation pathways, are moderately sensitive (SI >
330 0.1). The low sensitivity (SI < 0.05) of the specified temperature at bottom boundary
331 (heat source of the model) indicates that its variations between 125 °C and 225°C lead to
332 little change of the temperature values in shallow aquifers. This finding demonstrates that
333 the efficiency of heat transfer is more important than heat storage for a geothermal field.
334 Low SIs (< 0.05) associated with the thermal conductivity of both granite and the Ti units
335 reveal that the heat conduction is a minor mechanism of heat transfer, compared to
336 groundwater convection, through these two formations in the Superstition Mountain
337 geothermal prospect. It is not surprising that the granite permeability is insensitive (SI <

338 0.01), given that its value ranges between 10^{-19} and 10^{-17} m², which can be considered
339 effectively impermeable, as compared to the crossing CF permeability ($10^{-14} - 10^{-12}$ m²).
340 Neither the permeability nor the thermal conductivity of the upper sediment aquifers (Tp2,
341 Tp1, and Qb) is sensitive for temperature around NAFEC boreholes, which could be
342 considered a potential geothermal production area. It is reasonable since these formations
343 are not the primary groundwater circulation pathways. Overall, the sensitivity
344 quantification and associated ranking for the hydrothermal model system of the
345 geothermal prospect demonstrates that groundwater circulation is the primary mechanism
346 of heat transfer in the field, consistent with previous studies for this area. Reducing the
347 uncertainty of those most sensitive properties, which is critical for potential geothermal
348 reservoir development and management, is a critical priority of exploration investment.
349 In addition to those expensive geophysical surveying approaches, Bayesian inversion
350 equipped with fast MARS models is applied to achieve better knowledge of these
351 important properties from the temperature observations shown as red circles in Figure 4.

352 3.4. Bayesian inversion with MARS-enabled MCMC

353 The MARS surrogate model was used to enable a MCMC-based Bayesian inversion
354 process using the prior probability density functions (PDFs) shown in Table 1 for the six
355 top sensitive design variables identified in Figure 6. The MCMC procedure starts with
356 a burn-in phase in which 10,000 MARS model simulations are employed. During the
357 following phase of creating posteriors, the chain converges after MARS model calls
358 amount to three sequential sample increments, with each 10,000 in size for convergence
359 check. The total MARS model runs for the complete MCMC, therefore, is 40,000 in this
360 case of Bayesian inversion, which cost about 5 minutes of computing time, while an

361 equivalent NUFT model simulation on a scalar machine take around 10 minutes
362 averagely. Compared to NUFT-based inversion, the MARS-based approach is projected
363 to improve the inversing efficiency by $10/5*40,000 = 80,000$ times. Although NUFT
364 model simulations were, in fact, used to support the inversions described in Tompson et
365 al (2013) on a similar model domain as the core domain in this study, they were
366 accomplished using a parallel implementation of NUFT and exploited the naturally
367 parallel benefits of conducting multiple MCMC simulation chains. That said, the power
368 of the MARS method can be most effectively exploited when, for example, a larger scale
369 and higher resolution model grid is used for more realistic, variably-saturated
370 hydrothermal flow simulations, a configuration that the NUFT-only platform cannot
371 currently address in an efficient, cost effective manner.

372 Among the six posterior PDFs are shown in Figure 7, the two least sensitive variables,
373 bottom temperature and granite thermal conductivity, are almost equally likely in their
374 ranges, suggesting that little additional knowledge is gained from prior information by
375 Bayesian inference due to their low identifiability. Among the other four variables, CF
376 height is identified as 3200 m at its upper bound that results in best matches with
377 observation data with a highest probability of 0.45, more than twice the magnitude of the
378 second highest probability. This result strongly suggests CF fault penetrates the entire
379 granite zone vertically. Figure 7b indicates that CF length should be 1100m in order to
380 best match the data, with the highest probability of 0.33. The probabilities of lengths
381 larger than 1100 m are much higher than those for smaller values, indicating CF should
382 be long enough in order to maintain contact with (and support fluid flows into) the
383 shallower and permeable Ti formation (Figure 3b). This finding makes sense since a

384 contiguous connection through a permeable CF and Ti supports a viable groundwater
385 circulation pathway to convective heat transfer to the observation wells. The log-
386 transformed permeabilities of the CF and Ti units have highest probability of 0.138,
387 0.146 at values of -13.16 and -13.44 m² respectively. While the possible CF permeability
388 clusters in the mean value of its range, Ti permeability is prone to higher values within
389 the range. The comparison between simulated results by NUFT model using the
390 parameter set with highest probability and measured temperatures along three NAFEC
391 boreholes shows a good match in Figure 4. The corresponding temperature distributions
392 on vertical slice consistent with CF, and horizontal slice at depth of 800 m, are contoured
393 in Figure 3b and 3c, respectively.

394 **4. Conclusions**

395 In this study, an efficient Bayesian inference framework equipped with multivariate
396 adaptive regression spline (MARS) method has been used to reduce geological
397 uncertainties associated with evaluation of a geothermal prospect. Fast surrogate models
398 for hydrothermal flow were constructed by a MARS-based approach for use in a
399 Bayesian MCMC inversion procedure. Computational efficiencies gained in this process
400 (over traditional high-fidelity hydrothermal simulation codes) suggest that more complex
401 aspects of the system can be ultimately addressed, certainly when the costs of physical
402 models becomes too unwieldy. In addition, Sobol' total sensitivity indices for each design
403 variable can also be efficiently calculated using a MARS model instead of a higher-
404 fidelity code. In sensitive variables were screened out of inverse process, enabling
405 Bayesian inference to be conducted that much more efficiently. Owing to the data
406 availability, a geothermal prospect near Superstition Mountain was chosen as the pilot

407 site to test the efficiency and validity of this method. It was demonstrated that MARS-
408 enable Bayesian inference entailing 40 thousands model runs can be accomplished in 5
409 minutes, while an individual high-fidelity model (NUFT) run can cost around 10 minutes.

410 Future work will be focused on adapting the MARS technique to more realistic
411 problems that incorporate larger and higher-resolution domains, or variably saturated
412 flow conditions, aspects that could not have been effectively addressed with high-fidelity
413 hydrothermal models. In addition, the MARS technique can be further utilized in
414 subsequent optimization calculations that may be associated with the design and
415 engineering of a geothermal production operation. In this case, an optimization phase
416 involving hundreds or even thousands of objective function evaluations of reservoir
417 performance under various design configurations could be more readily conducted using
418 a MARS-based simulation approach. Higher-fidelity hydrothermal models incorporating
419 transient source/sink term will cost much more computational time than those in natural
420 condition in this work. This type of operation will also be better constrained, of course,
421 once a viable hydrothermal model of an undisturbed prospect is achieved from an
422 inversion process as described above. Preliminary numerical experiments show that a
423 single geothermal production model simulating up to 1000 years of operation lasts about
424 5 hours. While only temperature data are used in study to demonstrate the developed
425 method, various data sources are possible to be jointly inverted by extending the current
426 Bayesian framework.

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533 Tables and Figures

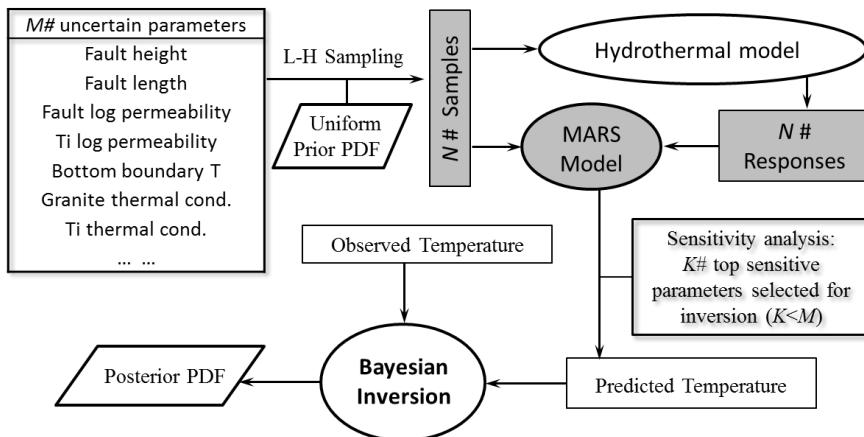
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535 Table 1. Ranges of input design variables in constructing MARS models. The importance
 536 of inputs are ranked according to Sobol' total sensitivity indices for average temperatures
 537 along the three NAFEC boreholes

Input parameter set	Min	Max	Indices	Rank
Fault height (m)	100	3200	0.712	1
Fault length (m)	100	3200	0.406	2
Fault log permeability (m^2)	-14	-12	0.119	3
Ti log permeability (m^2)	-15	-13	0.107	4
Bottom boundary temperature ($^{\circ}\text{C}$)	125	225	0.0378	5
Granite thermal conductivity (W/m-C)	0.1	4.0	0.0286	6
Ti thermal conductivity (W/m-C)	0.1	4.0	0.0139	7
Granite log permeability (m^2)	-19	-17	0.007	8
Fault thermal conductivity (W/m-C)	0.1	4.0	0.0037	7
Tp1 thermal conductivity (W/m-C)	0.1	4.0	0.0033	10
Tp2 log permeability (m^2)	-15	-13	0.0	11
Tp2 thermal conductivity (W/m-C)	0.1	4.0	0.0	12
Tp1 log permeability (m^2)	-15	-13	0.0	13
Qb thermal conductivity (W/m-C)	0.1	4.0	0.0	14
Qb log permeability (m^2)	-15	-13	0.0	15

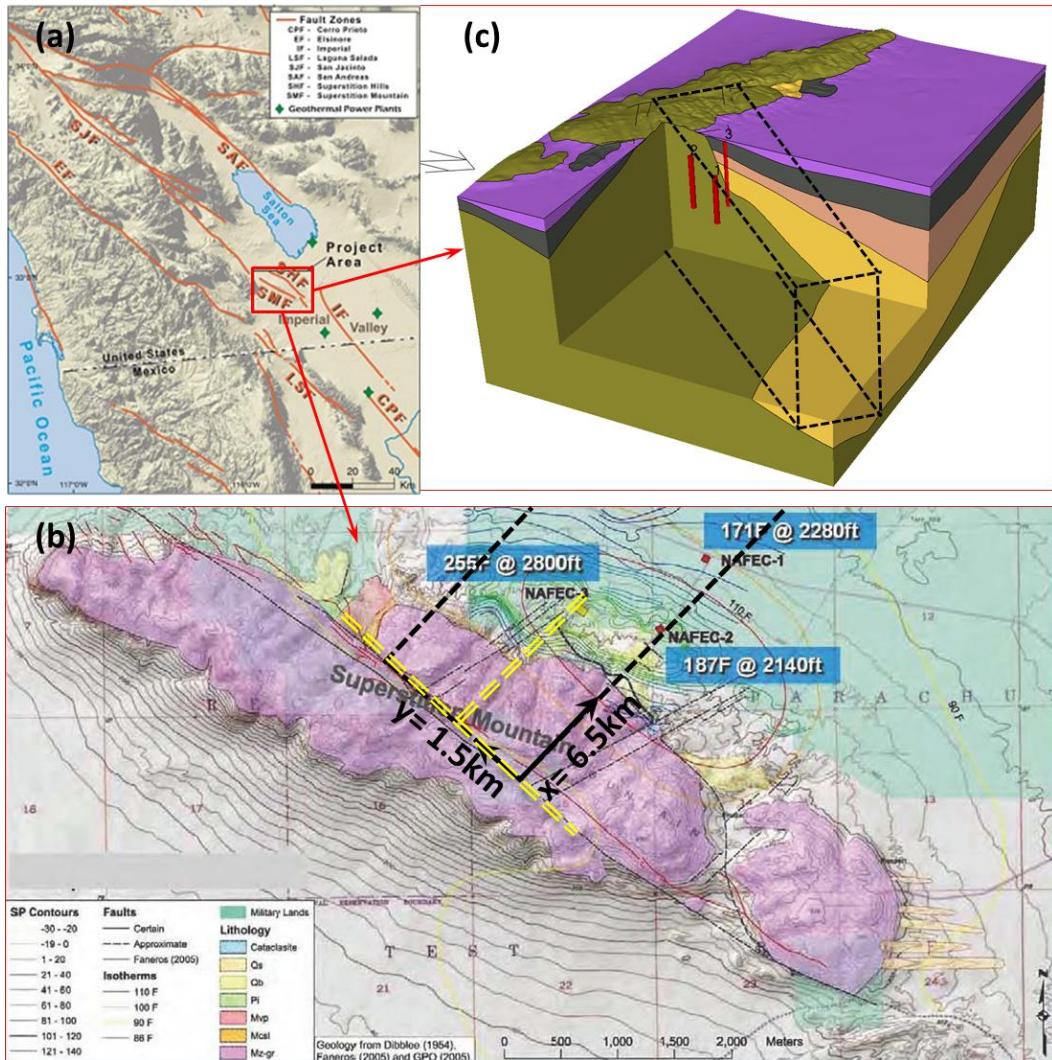
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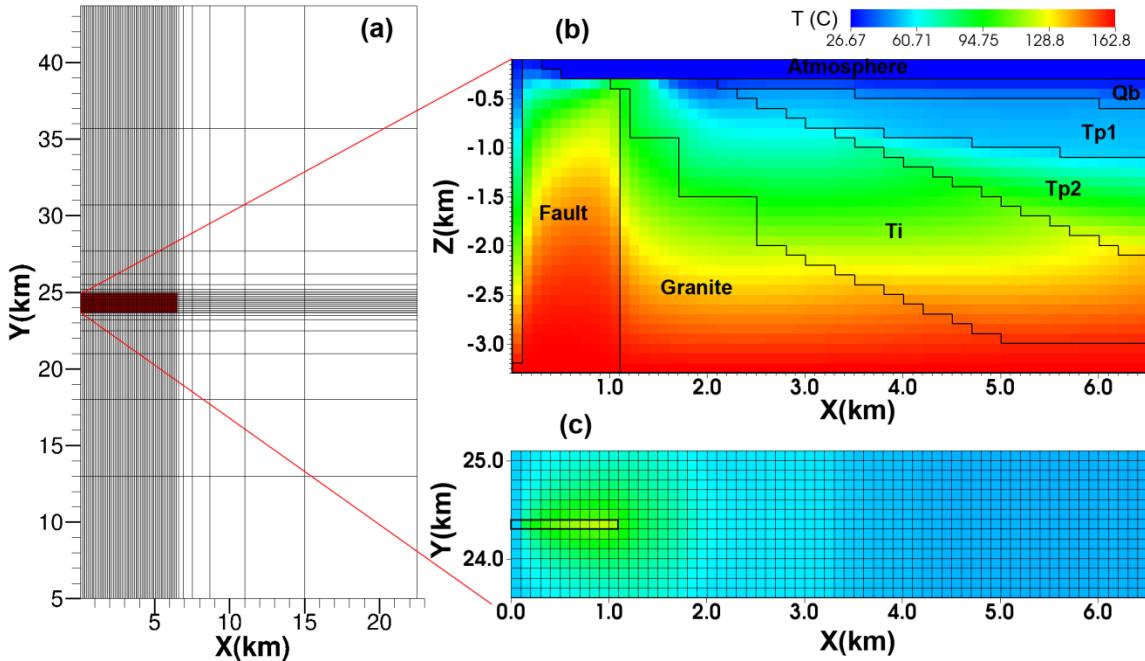


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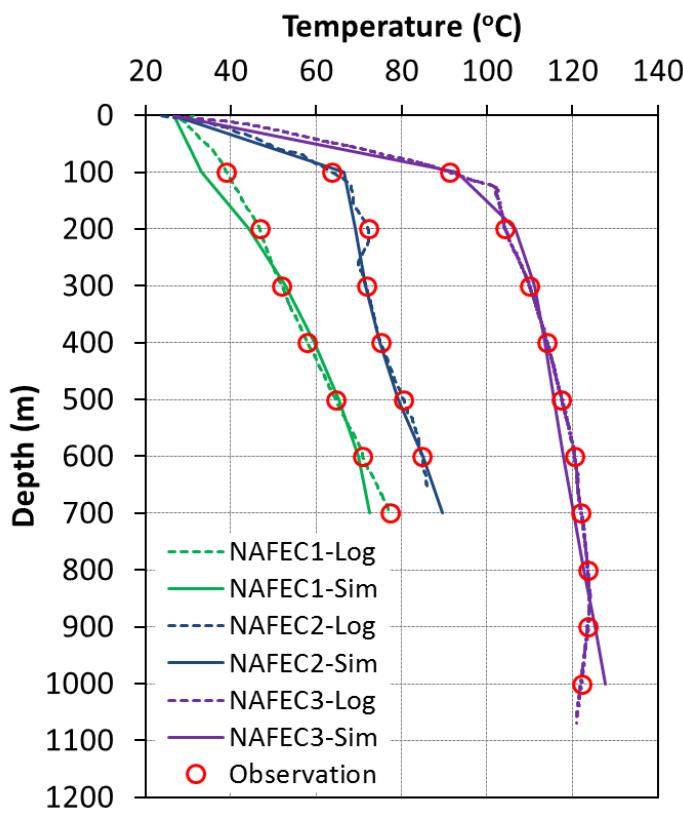
541 Figure 1. Schematic diagram of the MARS-based Bayesian inversion framework. The
 542 gray-shaded boxes indicate the construction of the training dataset used to develop the
 543 MARS surrogate model. The full list of design variables is shown in Table 1. The
 544 Bayesian Inversion within the oval is conducted with MCMC simulation using the
 545 MARS surrogate model.



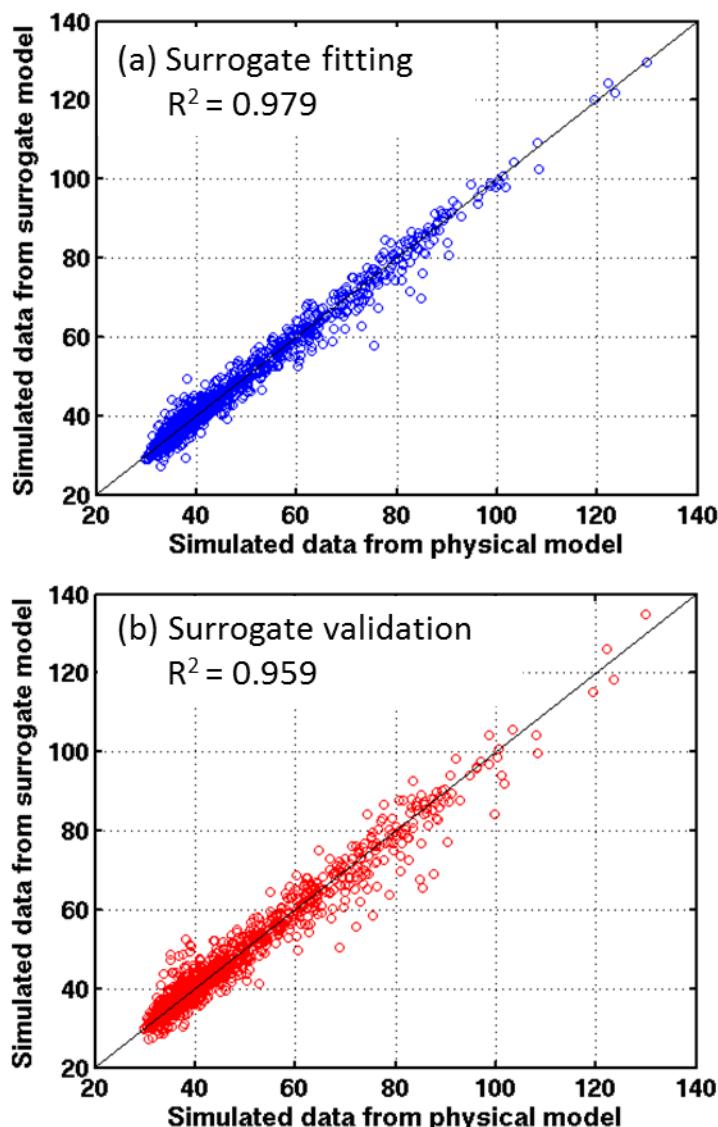
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547 Figure 2. Superstition mountain geothermal prospect. (a) Location in Imperial County,
548 California, USA (Bjornastad et al., 2006); (b) Surface geology and three NAFEC
549 boreholes. Black and yellow dashed lines show the areal projection of the core domain
550 and faults of hydrothermal models (Figure 3). Adapted from Tiedeman et al. (2011); (c)
551 Geological model looking from the Northeast, and showing (from bottom) the granite
552 basement, sandstone Ti, and sedimentary layers Tp2, Tp1, Qb (Figure3b). Dashed box
553 outlines the 3D core domain. The three boreholes are illustrated with red tubes.
554



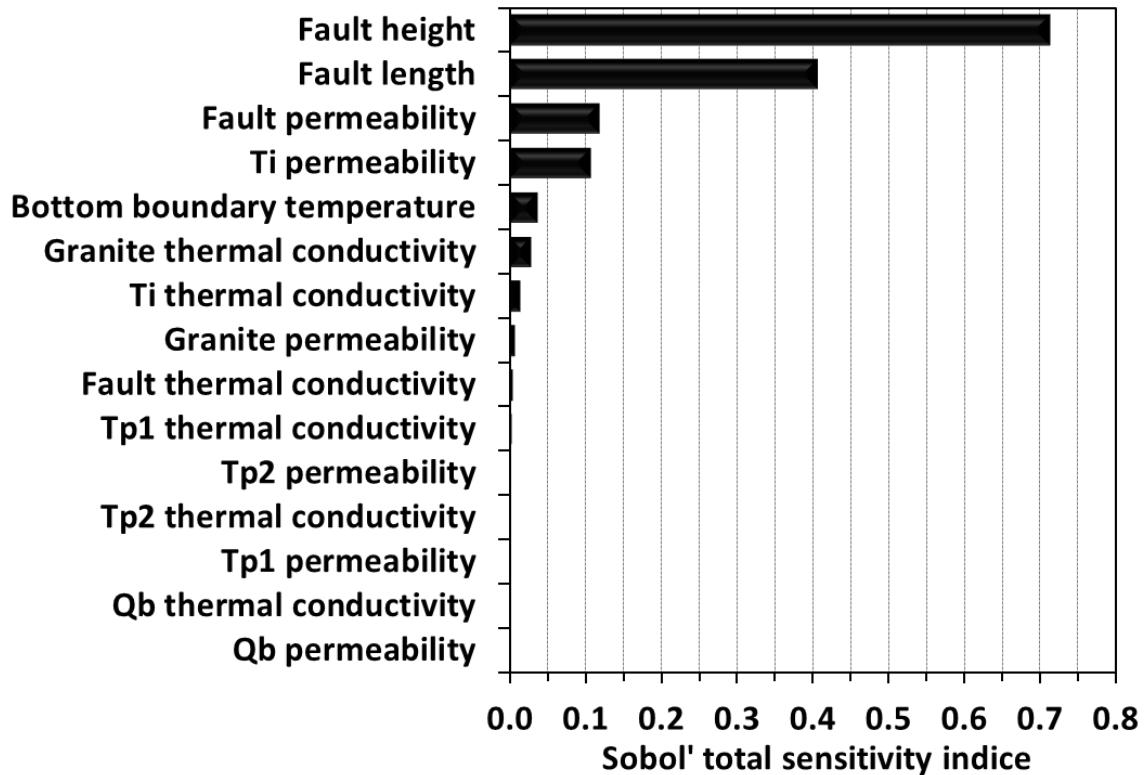
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556 Figure 3. Hydrothermal model domain showing (a) Far field and core area plan view (red
557 shaded area); (b) Vertical slice of the core model domain at $Y=28\text{ km}$, where conjugate
558 fault is located. The fault height and length, and the temperature distribution are
559 corresponding to the input parameter set with the highest probability inferred from
560 Bayesian inversion (Figure 7); (c) Horizontal slice of the core model domain at $Z = 800\text{ m}$.
561



563 Figure 4. Measured and simulated temperature profiles along the three “NAFEC”
564 boreholes (Tiedeman et al., 2001). The parameter set obtained from inversion with
565 highest probability is used in simulation. The red circle marks indicate the discrete
566 locations along the measured data curves used as observations in the stochastic inversion
567 process.
568



569 Figure 5. Scatter plots of mean temperature in the three observation wells obtained from
570 1500 surrogate and physical model simulations. Plot (a) corresponds to the surrogate
571 model fitting step, while plot (b) corresponds to the surrogate model -cross-validation
572 step.
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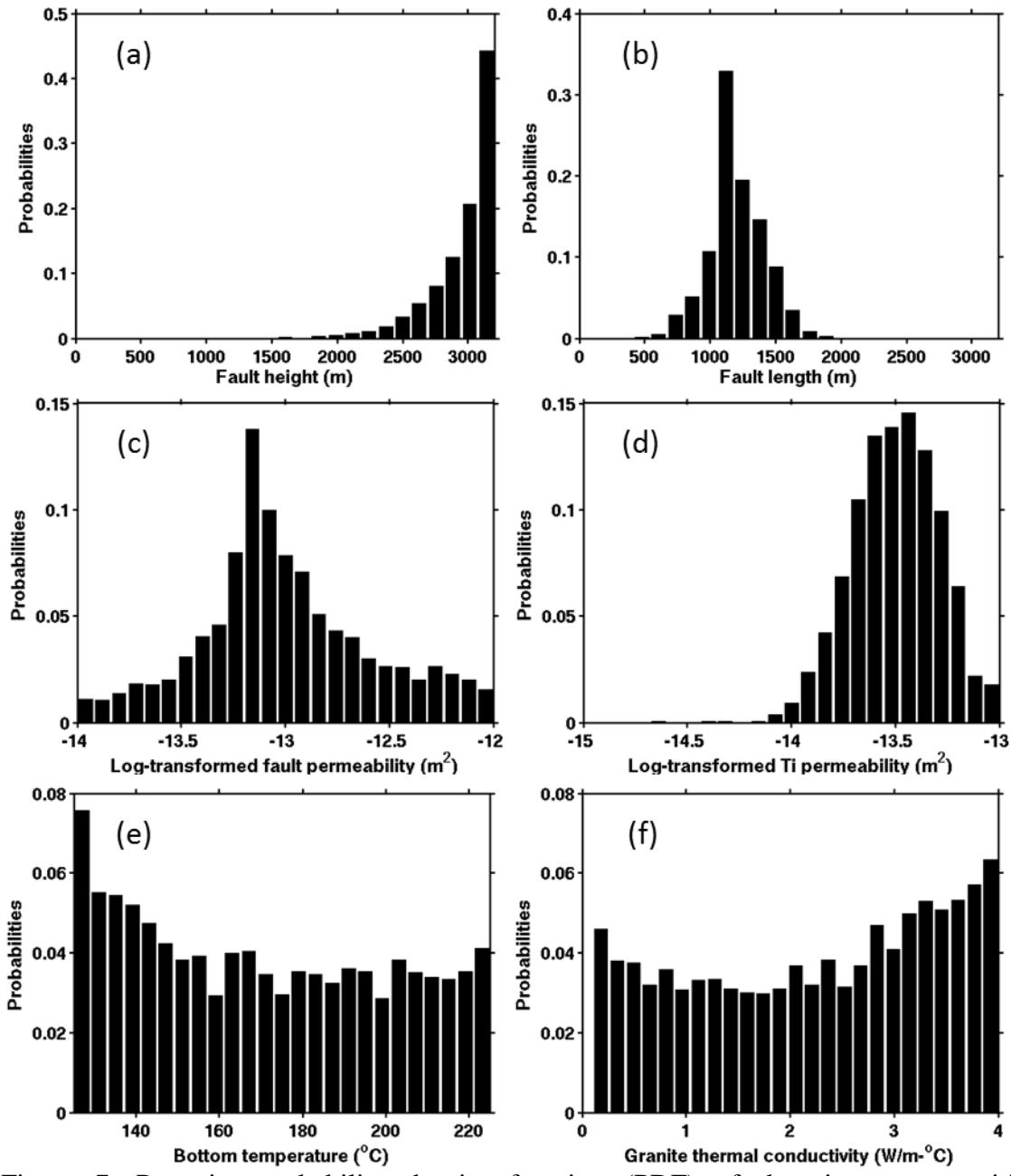
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577 Figure 6. Parameters ranking according to the sensitivity of mean temperature along three

578 boreholes to the 15 hydrothermal parameters (Table 1). The sensitivity is measured by

579 Sobol' total indice.

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Figure 7. Posterior probability density function (PDF) of the six most sensitive parameters: (a) fault height, (b) fault length, (c) fault permeability, (d) Ti permeability, (e) bottom boundary temperature, and (f) granite thermal conductivity. Note the prior probability of each parameter is uniformly distributed within its range.