



Estimating Predictive Uncertainty in Machine Learning Models

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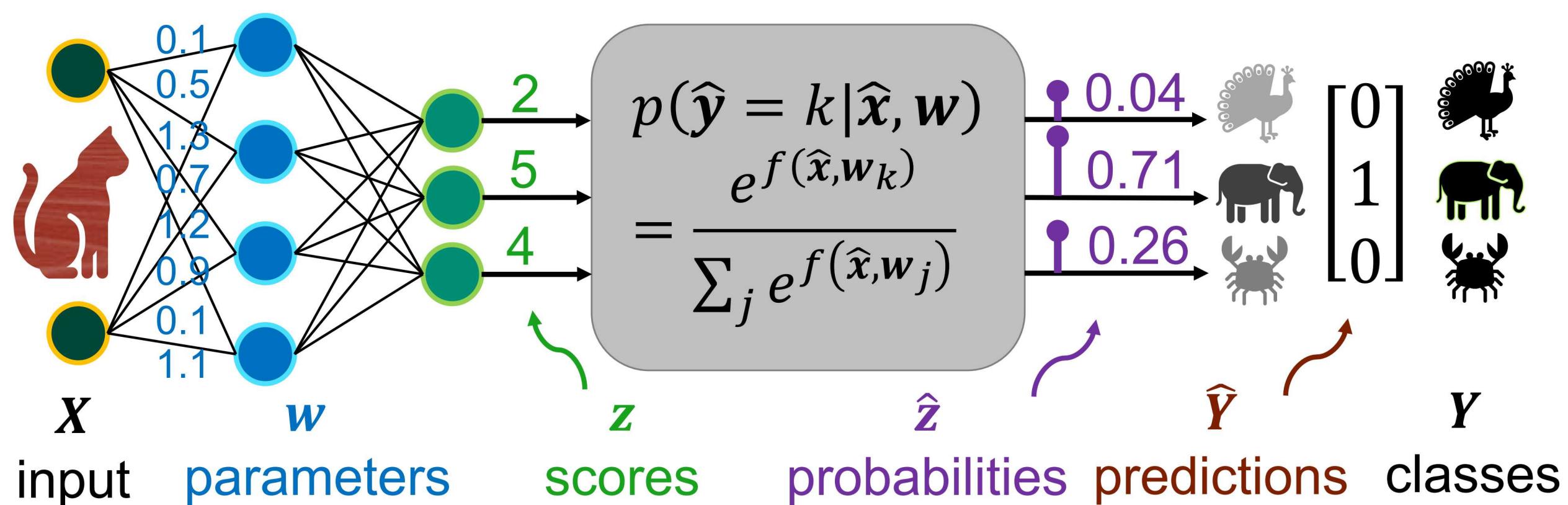
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Goal: Estimate the predictive uncertainty in machine learning models
from point-estimates to approximate probability distributions

"Predictions without UQ are neither predictions nor actionable."
Begoli E, bhattacharya T, kusnezov D., Nature Machine Intelligence 2019

Problem

In ML/DL classification, an e^x **softmax** layer assigns single-point probabilities to each class



Point Estimates of Neural Networks

tend to be **overconfident** causing unintended and harmful behavior, e.g., when training and test distributions differ, class imbalance, etc.

Input and Model to Output Uncertainties

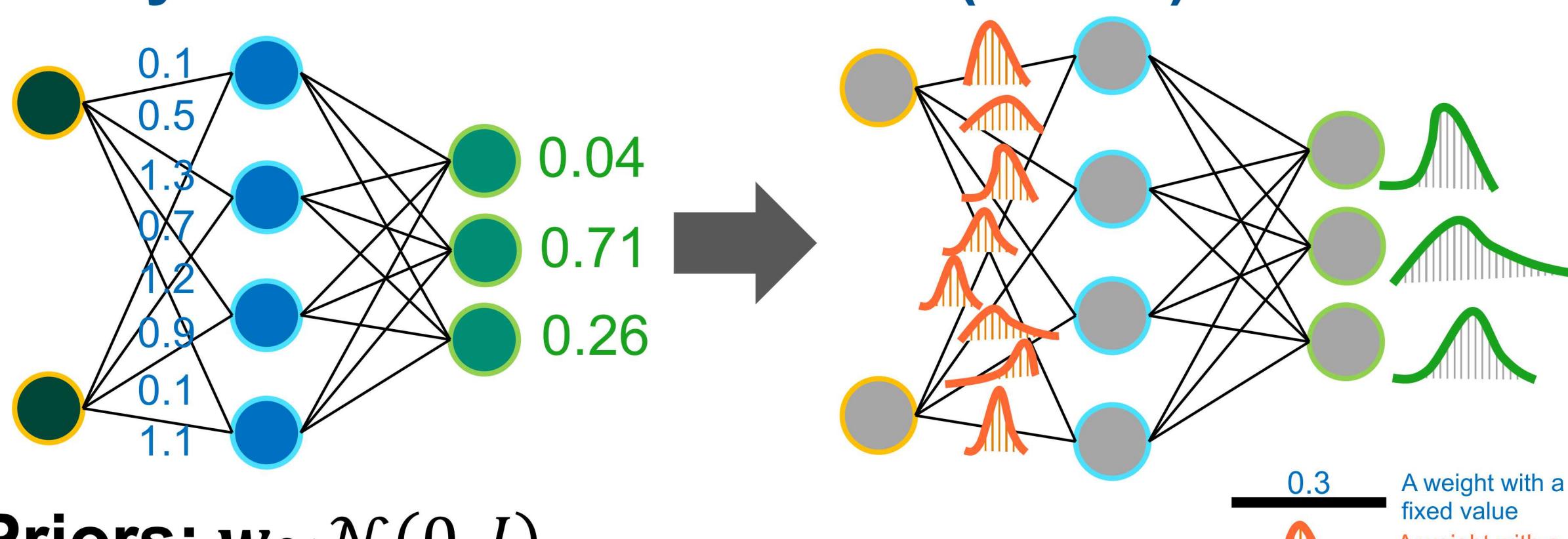
are not properly characterized/decomposed into:

- 1) **Aleatoric** (irreducible, e.g., measurement noise)
- 2) **Epistemic** (reducible, e.g., model parameters)

$$\begin{aligned} \mathbf{w}^{\text{MLE}} &= \arg \max_{\mathbf{w}} \log p(\mathcal{D}|\mathbf{w}) && \text{Maximum Likelihood Estimation} \\ &= \arg \max_{\mathbf{w}} \sum_i \log p(Y_i|X_i, \mathbf{w}) \\ &\text{achieved by gradient descent, e.g., back-propagation} \end{aligned}$$

Approach

Bayesian Neural Networks (BNNs)



Priors: $\mathbf{w} \sim \mathcal{N}(0, I)$

$$\text{Posterior: } p(\mathbf{w}|\mathcal{D}) = \frac{p(\mathcal{Y}|\mathbf{X}, \mathbf{w})p(\mathbf{w})}{p(\mathcal{Y}|\mathbf{X})}$$

$$\begin{aligned} \mathbf{w}^{\text{MAP}} &= \arg \max_{\mathbf{w}} \log p(\mathbf{w}|\mathcal{D}) && \text{Maximum a posteriori (MAP)} \\ &= \arg \max_{\mathbf{w}} \log p(\mathcal{D}|\mathbf{w}) + \log p(\mathbf{w}) \end{aligned}$$

Gaussian prior: **L2 regularization** (weight decay)

Laplace prior: **L1 regularization**

$$p(\hat{\mathbf{y}}|\hat{\mathbf{x}}, \mathbf{X}, \mathbf{Y}) = \int p(\hat{\mathbf{y}}|\hat{\mathbf{x}}, \mathbf{w})p(\mathbf{w}|\mathbf{X}, \mathbf{Y})d\mathbf{w}$$

Exact inference on \mathbf{w} is intractable, **approximation needed**

Results

Variational Inference (VI) Approximation

using a variational distribution $q_{\theta}(\mathbf{w})$, minimizing the Kullback-Leibler divergence $\mathcal{KL}_{VI}(q_{\theta}(\mathbf{w})||p(\mathbf{w}|\mathbf{X}, \mathbf{Y}))$

$$\theta^* = \arg \min_{\theta} \mathcal{KL}(q_{\theta}(\mathbf{w})||p(\mathbf{w}|\mathbf{X}, \mathbf{Y})) \quad \text{integration to optimization}$$

Decomposed predictive uncertainty

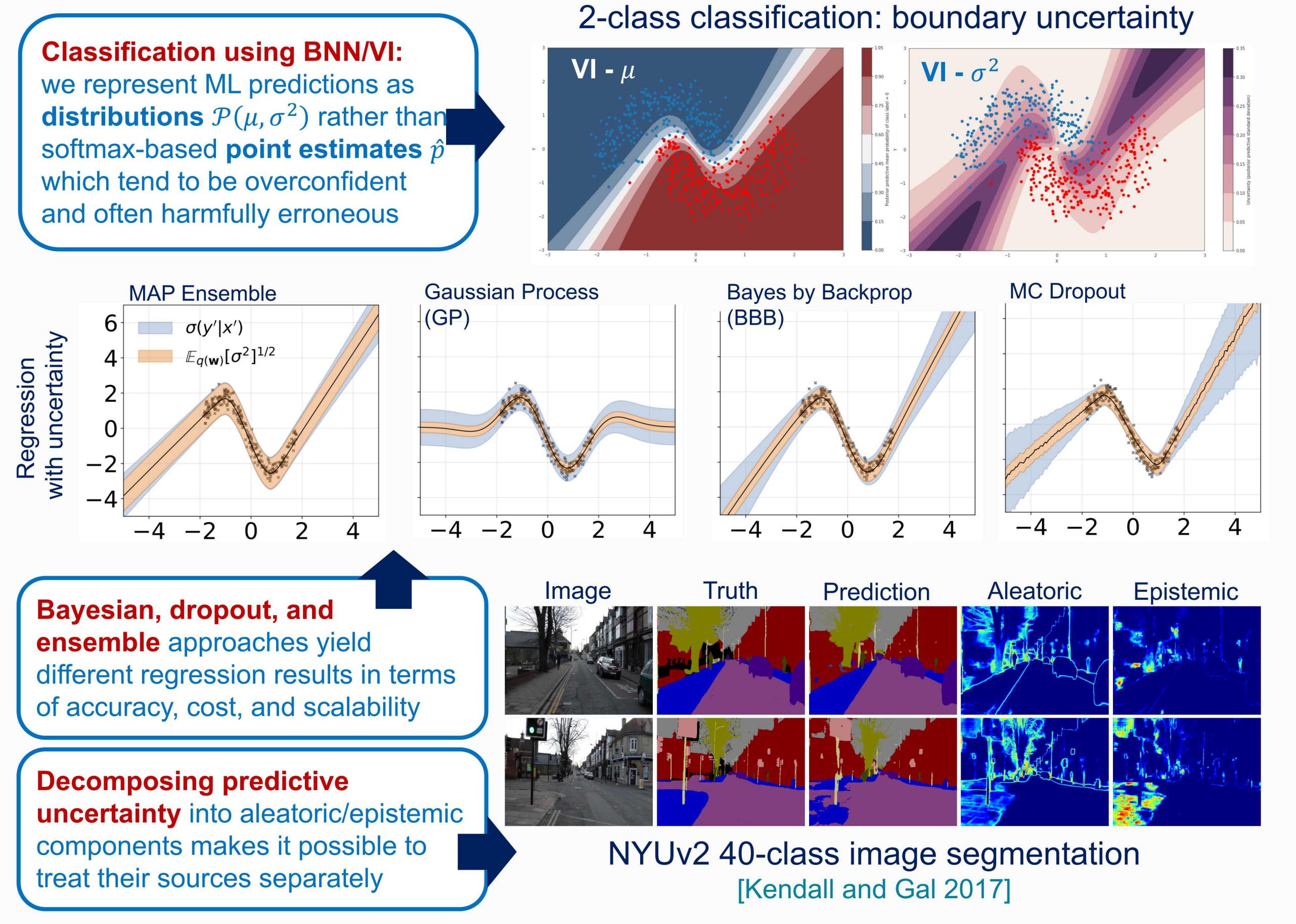
$$\text{Mean } \mathbb{E}_q\{p(\hat{\mathbf{y}}|\hat{\mathbf{x}})\} \approx \frac{1}{T} \sum_{t=1}^T p(\hat{\mathbf{y}}|\hat{\mathbf{x}}, \theta_t^*)$$

$$\text{Variance } \sigma_q^2\{p(\hat{\mathbf{y}}|\hat{\mathbf{x}})\} \approx$$

$$\frac{1}{T} \sum_{t=1}^T \text{diag}(\hat{p}_t) - \hat{p}_t \hat{p}_t^T + \frac{1}{T} \sum_{t=1}^T (\hat{p}_t - \bar{p})(\hat{p}_t - \bar{p})^T$$

Aleatoric (irreducible)

Epistemic (reducible)



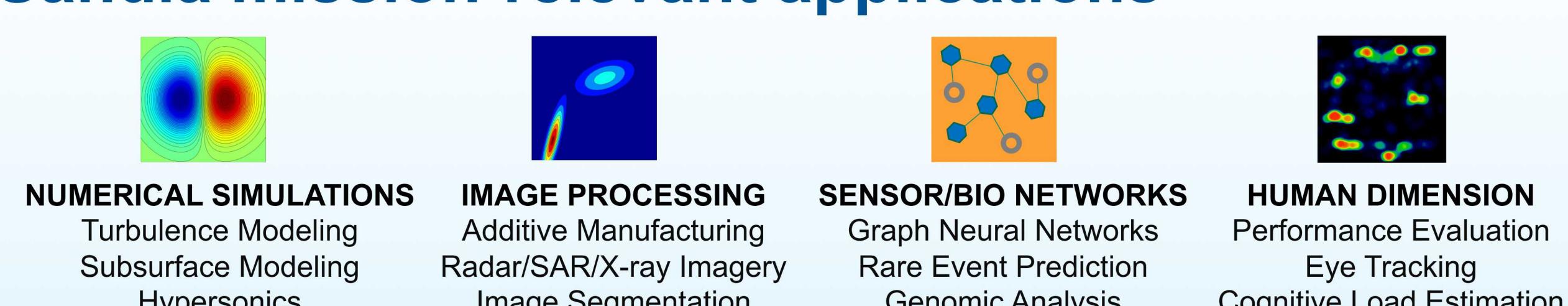
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Next: Multi-fidelity deep ensembles, Sandia applications, and scalability/quality comparisons

Significance

- Enable probabilistic decision making in **high-stakes** and **cost-sensitive** national security, when mistakes cannot be afforded or tolerated
- Evaluate model **trust**, **reliability**, and **risk** factors, guide **adaptive sampling** for model improvement

Sandia mission-relevant applications



Funding

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