



Implementing a projection-based reformulation and decomposition algorithm for global optimization of a class of mixed integer bilevel linear programs

Introduction

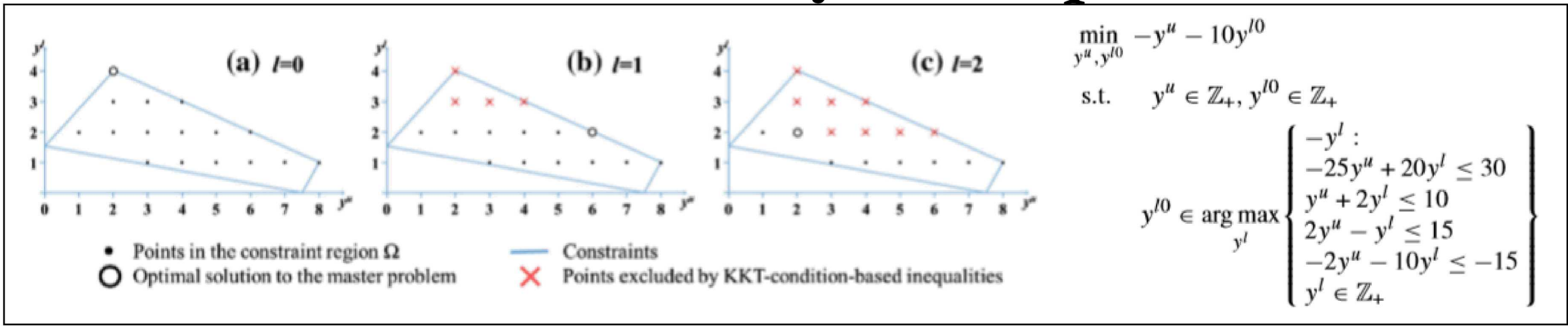
- Bilevel programs are mathematical programs with optimization problems in their constraint.
- Bilevel programs are used in cybersecurity modeling
- A general bilevel mixed integer linear program:
(P0)
$$\begin{aligned} \min_{x^u, y^u, x^{l0}, y^{l0}} \quad & c_R^l x^u + c_Z^l y^u + d_R^l x^{l0} + d_Z^l y^{l0} \\ \text{s.t.} \quad & A_R x^u + A_Z y^u + B_R x^{l0} + B_Z y^{l0} \leq r \\ & x^u \in \mathbb{R}_+^{m_R}, y^u \in \mathbb{Z}_+^{m_Z}, x^{l0} \in \mathbb{R}_+^{n_R}, y^{l0} \in \mathbb{Z}_+^{n_Z} \\ & (x^{l0}, y^{l0}) \in \operatorname{argmax}_{(x^l, y^l)} \{ w_R^l x^l + w_Z^l y^l : \\ & \quad P_R x^l + P_Z y^l \leq s - Q_R x^u - Q_Z y^u \\ & \quad x^l \in \mathbb{R}_+^{n_R}, y^l \in \mathbb{Z}_+^{n_Z} \} \end{aligned}$$

Algorithm

Algorithm. Projection-based reformulation and decomposition through CCG method	
1	Step 1 (Initialization)
2	Set $LB = -\infty$, $UB = +\infty$, $\xi = 0$, $k = 0$, and $\underline{Y}_0^L \leftarrow \emptyset$.
3	Step 2 (Lower Bounding)
4	Solve problem (P5).
5	Denote the optimal solution as $(x_k^{u*}, y_k^{u*}, x_k^{l0*}, y_k^{l0*})$.
6	Set LB to the optimal objective value Θ_k^* .
7	Step 3 (Termination)
8	if $UB - LB < \xi$, then Terminate and return optimal solution.
9	Step 4 (Subproblem 1)
10	Solve problem (P6) at (x_k^{u*}, y_k^{u*}) .
11	Denote the optimal solution as $(\hat{x}_k^l, \hat{y}_k^l)$ and optimal objective value as $\theta_k(x_k^{u*}, y_k^{u*})$.
12	Step 5 (Subproblem 2)
13	Solve problem (P7) at (x_k^{u*}, y_k^{u*}) and $\theta_k(x_k^{u*}, y_k^{u*})$
14	if Feasible then
15	Denote the optimal solution as (x_k^{l*}, y_k^{l*})
16	Set $UB = \min\{UB, c_R^l x_k^{l*} + c_Z^l y_k^{l*} + \Theta_{\alpha,k}(x_k^{u*}, y_k^{u*})\}$.
17	Set $\bar{y}_k^l = y_k^{l*}$.
18	else (Infeasible Problem)
19	Set $\bar{y}_k^l = \hat{y}_k^l$.
20	end
21	Step 6 (Tightening the Master Problem)
22	Create new variables $(x^{l,j}, \pi^j)$ and constraint (54) corresponding to $y^{l,j} = \bar{y}_k^l$.
23	Set $\underline{Y}_{k+1}^L = \underline{Y}_k^L \cup \{y_k^{l,j}\}$ and $k = k + 1$.
24	Step 7 (Loop)
25	if $UB - LB < \xi$, then
26	Terminate and return the optimal solution.
27	else
28	Go to step 2.
29	end

- Master Problem is initially the high point problem (does not ensure optimality of the lower level problem) and adds constraints through column generation
- Subproblem 1 is the lower level problem given the optimal upper level solution from the previously solved Master Problem
- Subproblem 2 either selects the most optimistic lower level solution of solutions found in Subproblem 1 or indicates that the lower level solution found in Subproblem 1 is infeasible for the Master Problem

A Classic Toy Example



Implementation

- (P9)
$$\begin{aligned} \min_{x^{l,j}, t^j} \quad & e^l t^j \\ \text{s.t.} \quad & P_R x^{l,j} - t^j \leq s - Q_R x^u - Q_Z y^u - P_Z y^{l,j} \\ & x^{l,j} \in \mathbb{R}_+^{n_R}, t^j \in \mathbb{R}_+^{n_L} \end{aligned} \tag{78}$$
- $$[e^l t^j = 0] \Rightarrow \left[\begin{aligned} & w_R^l x^{l0} + w_Z^l y^{l0} \geq w_R^l x^{l,j} + w_Z^l y^{l,j} \\ & P_R x^{l,j} \leq s - Q_R x^u - Q_Z y^u - P_Z y^{l,j} \\ & P_R \pi^j \geq w_R^l x^{l,j} \perp (P_R \pi^j - w_R^l) \\ & \pi^j \perp (s - Q_R x^u - Q_Z y^u - P_R x^{l,j} - P_Z y^{l,j}) \\ & x^{l,j} \in \mathbb{R}_+^{n_R}, \pi^j \in \mathbb{R}_+^{n_L} \end{aligned} \right], \forall y^{l,j} \in \underline{Y}_k^L \subseteq Y^L \tag{82}$$
- $$P_R \lambda^j \geq 0, x^{l,j} \perp P_R \lambda^j, \forall y^{l,j} \in \underline{Y}_k^L \subseteq Y^L \tag{83}$$
- $$e - \lambda^j \geq 0, t^j \perp (e - \lambda^j), \forall y^{l,j} \in \underline{Y}_k^L \subseteq Y^L \tag{84}$$
- $$\lambda^j \perp (s - Q_R x^u - Q_Z y^u - P_Z y^{l,j} - P_R x^{l,j} + t^j), \forall y^{l,j} \in \underline{Y}_k^L \subseteq Y^L \tag{85}$$
- The algorithm is implemented in Pyomo making use of Pyomo's packages mpec (mathematical programs with equilibrium constraints) and GDP (generalized disjunctive programming)
- The logical implication constraint required an approximate implementation:

$$e^l t^j \geq \epsilon \cap \text{CONSTRAINT BLOCK}$$

Exact Reformulation

- Goal: formulate without epsilon approximate disjunction
- Reformulate the “in-the-projection-set” LP as a feasibility problem
- The LP is infeasible iff dual is unbounded or infeasible
- Use disjunction:
$$\left(\begin{aligned} & P_R x^{l,j} \leq s - Q_R x^u - Q_Z y^u - P_Z y^{l,j} \\ & x^{l,j} \geq 0 \\ & \text{CONSTRAINT BLOCK} \end{aligned} \right) \cap \left(\begin{aligned} & d \geq 0 \\ & P_R^T d \geq 0 \\ & d^T (s - Q_R x^u - Q_Z y^u - P_Z y^{l,j}) \leq -1 \end{aligned} \right)$$
- Introduce new variables to represent quadratic terms and linearize with McCormick inequalities
- Requires bounded variables

Future Work

- Test the algorithm against toy examples with known solutions on each iteration
- Optimize the algorithm
- Continue to test reformulations of the approximation
- Compare and benchmark with two other recent bilevel solvers: Fischetti and Ralphs
- Apply to DCOPT model for power supply cybersecurity



She'ifa Punla-Green

(with thanks to Anya Castillo, Emma Johnson, Bryan Arguello and William Hart)