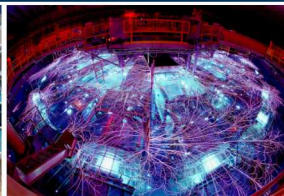


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Compressive sensing for hyperspectral imaging

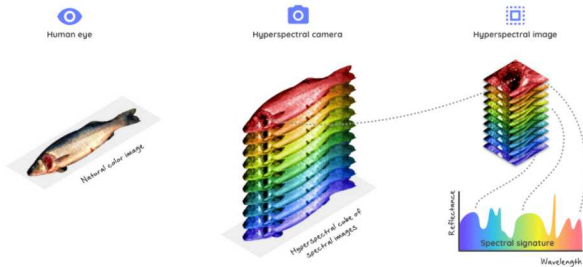
Dennis Lee

February 19, 2020

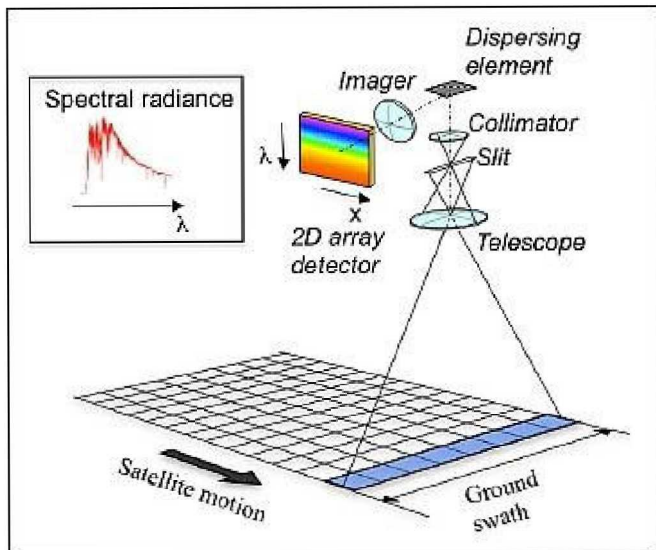


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Hyperspectral imaging



Traditional sensors for HSI

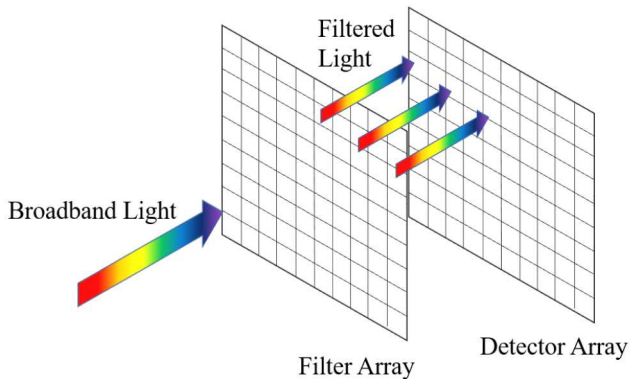


Compressive sensing recovers sparse signals

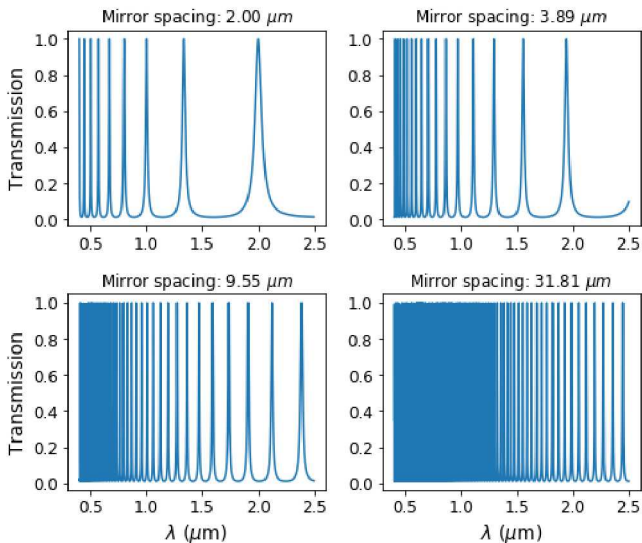
$$\begin{array}{c}
 M \times 1 \\
 \text{measurements}
 \end{array}
 \begin{array}{c}
 y \\
 \begin{array}{|c|} \hline \text{colored bar} \\ \hline \end{array}
 \end{array}
 =
 \begin{array}{c}
 \Phi \\
 \begin{array}{|c|} \hline \text{colored grid} \\ \hline \end{array} \\
 M \times N
 \end{array}
 \begin{array}{c}
 x \\
 \begin{array}{|c|} \hline \text{blue and white bar} \\ \hline \end{array} \\
 N \times 1 \\
 \text{sparse signal} \\
 K \\
 \text{nonzero entries}
 \end{array}$$

$K < M \ll N$

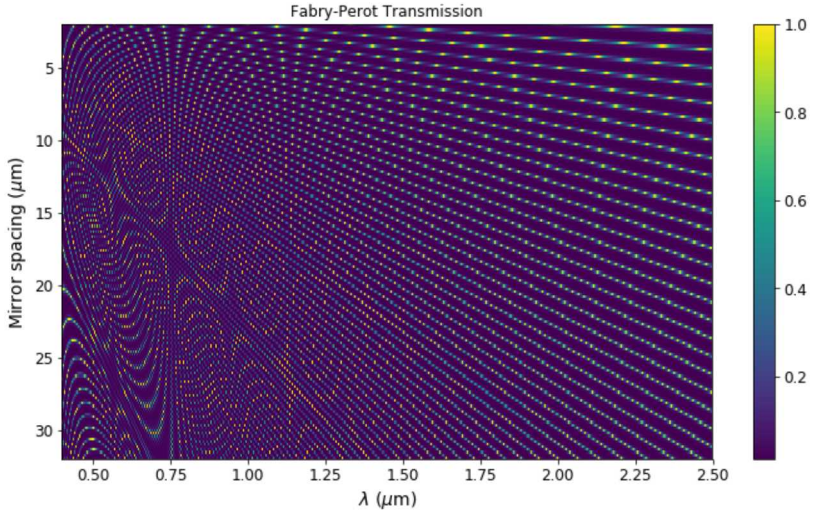
Snapshot hyperspectral imager



Fabry-Perot resonators

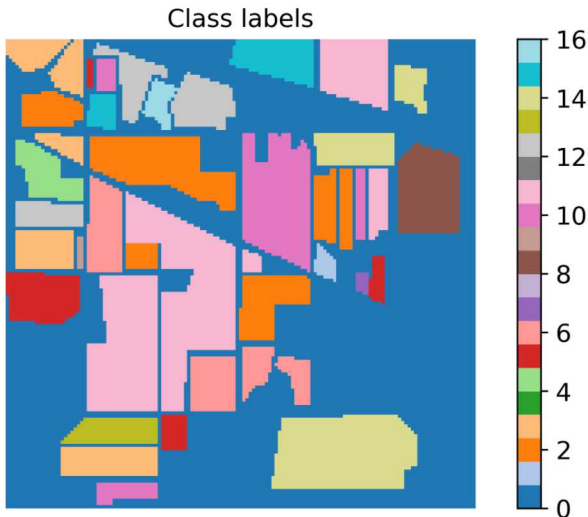


Mirror spacing vs. wavelength



Hyperspectral dataset

- The data cube has size $145 \times 145 \times 220$.
- The measured data cube has size $145 \times 145 \times 160$ with noise added.



Hyperspectral image reconstruction

- $\mathbf{A}$ is the transmission matrix.
- For each pixel, solve a penalized likelihood problem:

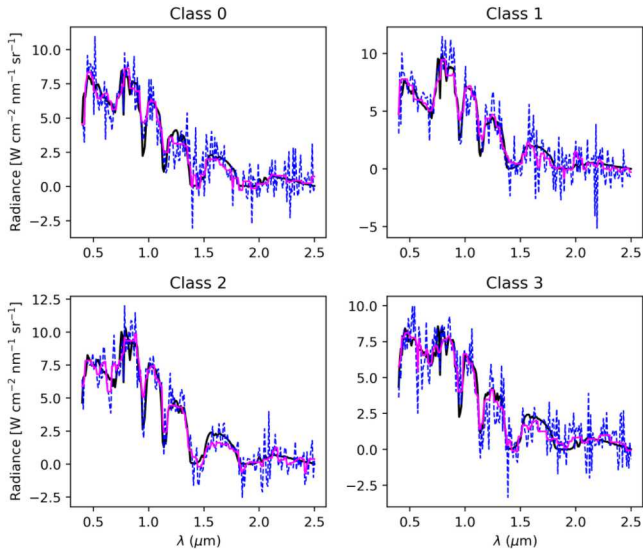
$$\begin{aligned} & \underset{\hat{\mathbf{x}}, \mathbf{x}}{\text{minimize}} && \frac{1}{2} \sum_{i=1}^X \sum_{j=1}^Y \|\mathbf{A} \hat{\mathbf{x}}_{i,j} - \mathbf{y}_{i,j}\|_2^2 + \beta \|\hat{\mathbf{x}}_{i,j}\|_1 + \text{TV}(\mathbf{x}, \alpha) \\ & \text{subject to} && \mathbf{x}_{i,j} = \mathbf{W} \hat{\mathbf{x}}_{i,j}, \quad 1 \leq i \leq X, \quad 1 \leq j \leq Y \end{aligned}$$

Optimization procedure

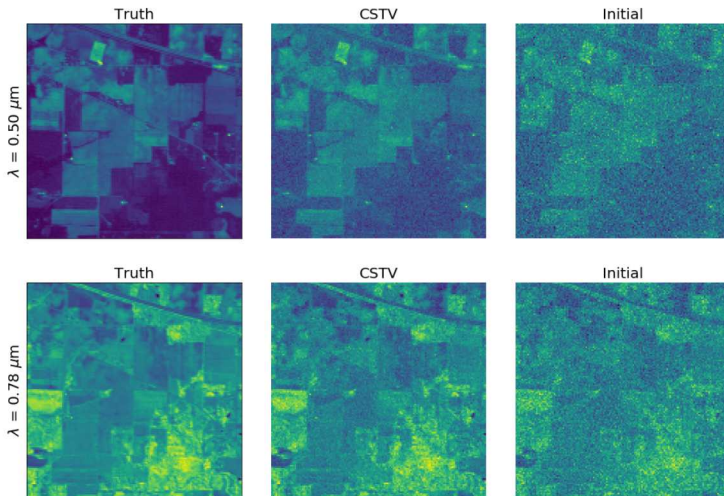
- Update $\hat{\mathbf{x}}$, $\mathbf{x}$, and $\mathbf{p}$ sequentially:

$$\begin{aligned}
 L_{\eta}(\{\hat{\mathbf{x}}_{i,j}\}, \{\mathbf{x}_{i,j}\}, \{\mathbf{p}_{i,j}\}) = & \frac{1}{2} \sum_{i=1}^X \sum_{j=1}^Y \|\mathbf{A}\hat{\mathbf{x}}_{i,j} - \mathbf{y}_{i,j}\|^2 + \beta \|\hat{\mathbf{x}}_{i,j}\|_1 \\
 & + \langle \mathbf{p}_{i,j}, \mathbf{x}_{i,j} - \mathbf{W}\hat{\mathbf{x}}_{i,j} \rangle + \frac{\eta}{2} \|\mathbf{x}_{i,j} - \mathbf{W}\hat{\mathbf{x}}_{i,j}\|^2 \\
 & + \text{TV}(\mathbf{x}, \alpha)
 \end{aligned}$$

Example reconstructions

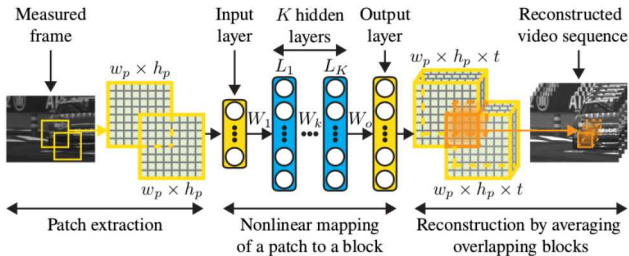


Example images



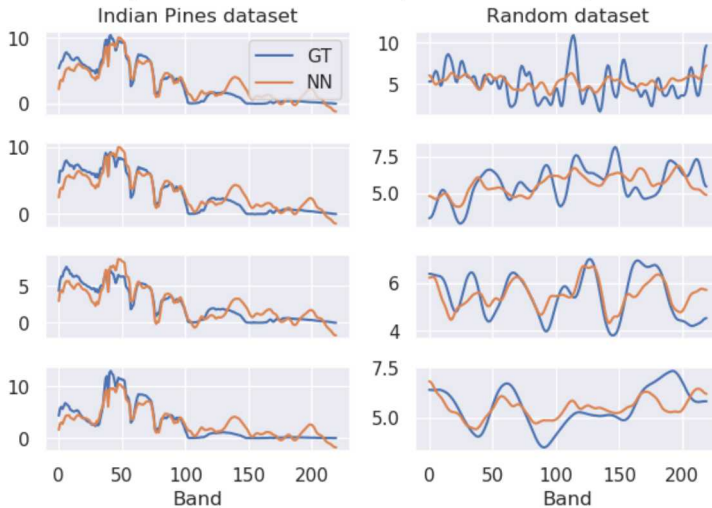
Multi-layer perceptrons for reconstruction

- The dataset contains 21025 spectra (145×145). We reserve 60% for training, 20% for validation, and 20% for testing.
- The number of layers varies as $K = 1, 2, 4, 7, 14$.

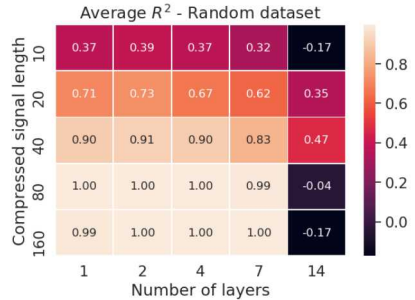
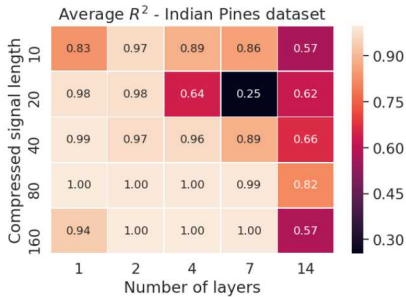


Results from multi-layer perception

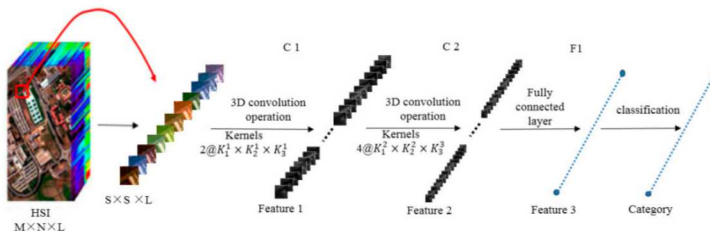
Example Reconstructions, Input size: 10, Layers: 1



Performance with varying layers

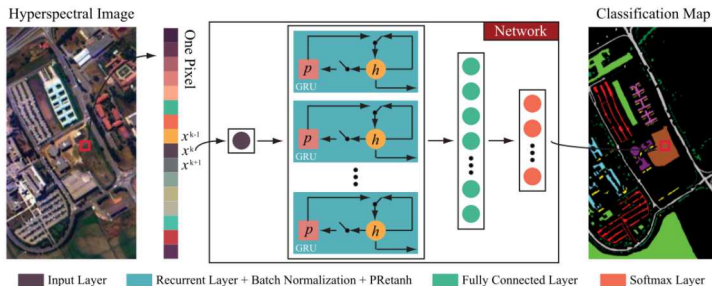


3D convolutions extract spatial and spectral features



Y. Li, et. al., "Spectral-spatial classification of hyperspectral imagery with 3D convolutional neural network" *Remote Sens.* (2017).

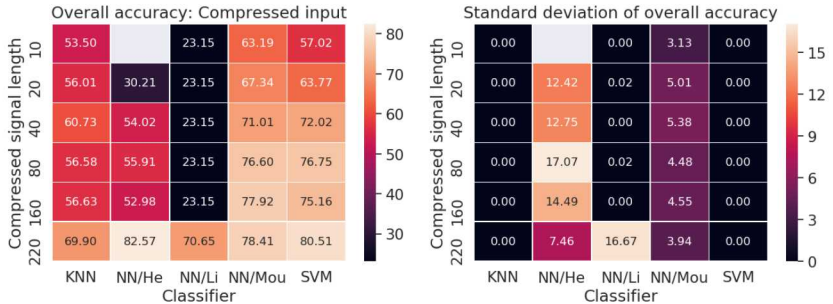
Recurrent networks characterize spectral correlation



L. Mou, et. al., "Deep recurrent neural networks for hyperspectral image classification" *IEEE Trans. Geoscience and Remote Sens.* (2017).

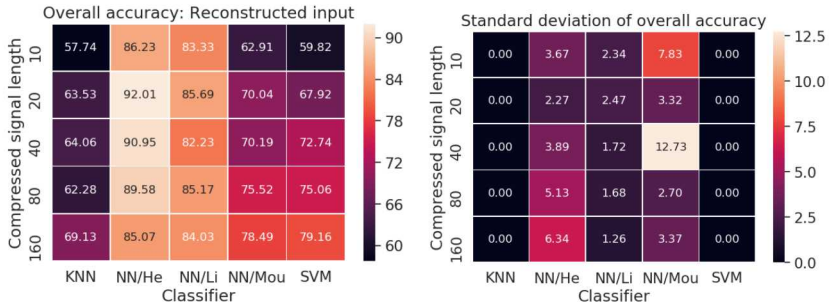
Performance as input size varies

- RNNs (NN/Mou) perform best as input size varies.



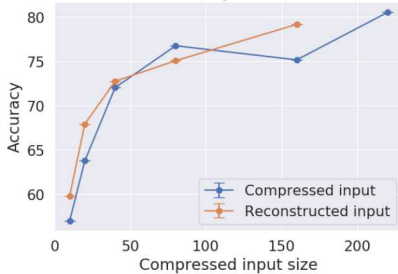
Performance on reconstructed inputs

- 3D CNNs (NN/He) perform best as input size varies.

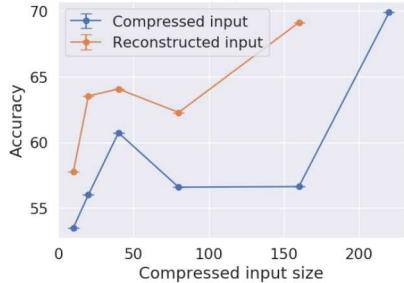


Accuracy improves on reconstructed inputs

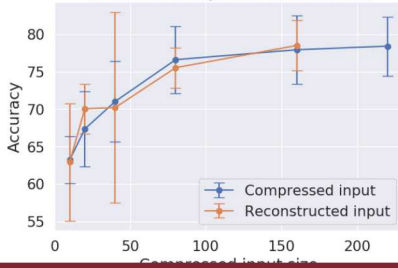
Overall accuracy, Classifier: SVM



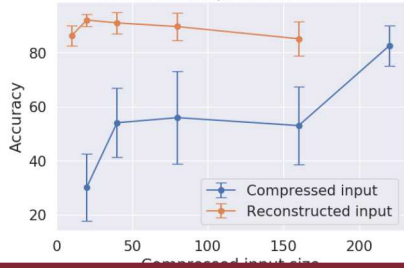
Overall accuracy, Classifier: KNN



Overall accuracy, Classifier: NN/Mou

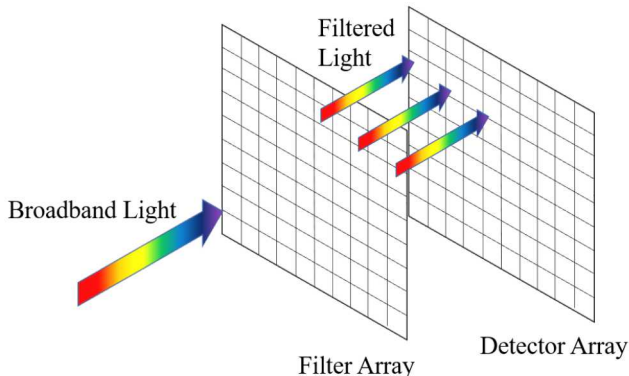


Overall accuracy, Classifier: NN/He



Summary

- A novel hyperspectral imager has been proposed based on the theory of compressive sensing.
- Reconstruction algorithms and machine learning approaches have been developed to process the hyperspectral data.



- D. J. Lee and E. A. Shields, “Compressive hyperspectral imaging using total variation minimization,” Proc. SPIE 10768, 1076804 (2018).
- D. J. Lee, “Deep neural networks for compressive hyperspectral imaging,” Proc. SPIE 11130, 1113006 (2019).