

# How Robust Are Graph Neural Networks to Structural Noise?

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## Introduction

GNNs are popular models for learning on graph-structure data, but their robustness is not well-understood. We study robustness in context of node structural identity predictions and explore augmented training for improving robustness.

### Key points:

- ◎ GNNs can perfectly distinguish structural identity (without noise)
- ◎ GNN accuracy sharply declines with structural noise (random edge additions)
- ◎ Augmented training with generated noisy samples can improve GNN robustness

## Generated Graphs

Graphs are generated from structural motifs according to [1]. Node labels are from well-defined structural role.

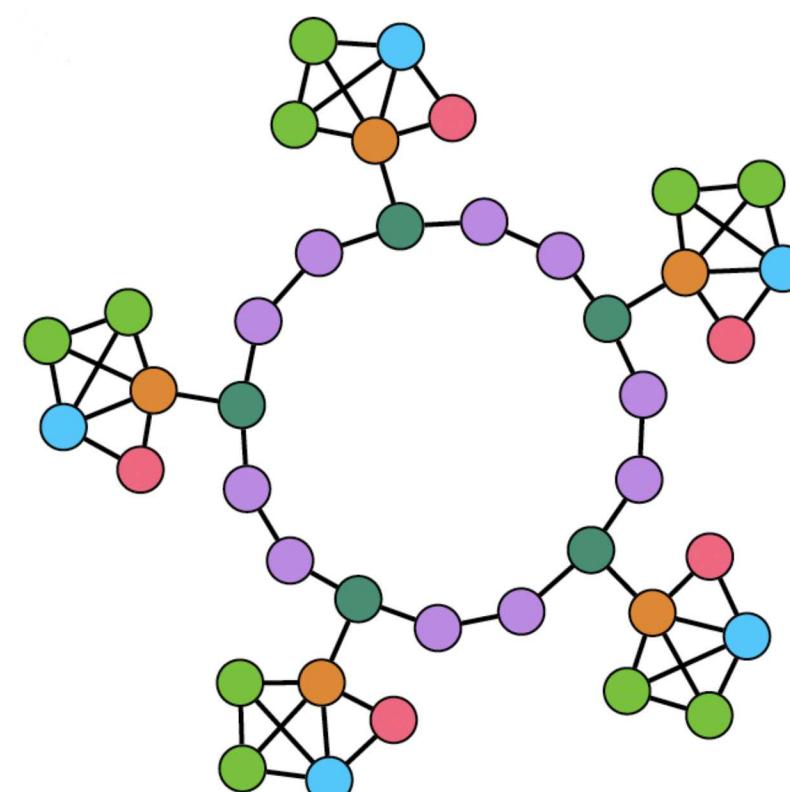


Figure: "Ring of houses" graph. Image from [1].

Size of base graphs used.  $G'$  is downsized version of  $G$ .  $G$  is ring-of-houses in all experiments.

Name	Nodes	Edges	Classes
Ring of houses $G$	2664	3996	6
Ring of houses $G'$	264	396	6

## Structural Noise

We introduce structural noise in the form of random edge additions, but keep original node labels. Labels no longer neatly match structural identity.

### Noise model parameters

- ◎ Noise ratio  $p$ : how many edge additions as ratio of original edges
- ◎ Distance  $k$ : can only form new edges from nodes within  $k$  hops.

New edge pairs are sampled uniformly at random, under  $k$ -hop constraint.

## Augmented Robustness Training

Graph training samples is often limited. Can we augment training with generated noisy samples to improve robustness?

### Noisy Augmentation Method

- ◎ Generating from same distribution:  $G_p^{(j)}$  is  $j$ -th noisy graph generated from  $G$  (of same size). We use 1 in practice to augment training.
- ◎ Generating from similar distribution:  $G_p'^{(j)}$  is  $j$ -th noisy graph generated from  $G'$  (smaller version of  $G$ ). We use 10 such graphs to augment.

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## References

- [1] C. Donnat, M. Zitnik, D. Hallac, and J. Leskovec. Learning structural node embeddings via diffusion wavelets. In *Proceedings of the 24th ACM SIGKDD International Conference on Knowledge Discovery & Data Mining*, pages 1320–1329. ACM, 2018.
- [2] M. Fey and J. E. Lenssen. Fast graph representation learning with pytorch geometric, 2019.
- [3] K. Xu, W. Hu, J. Leskovec, and S. Jegelka. How powerful are graph neural networks? *arXiv preprint arXiv:1810.00826*, 2018.

## Model

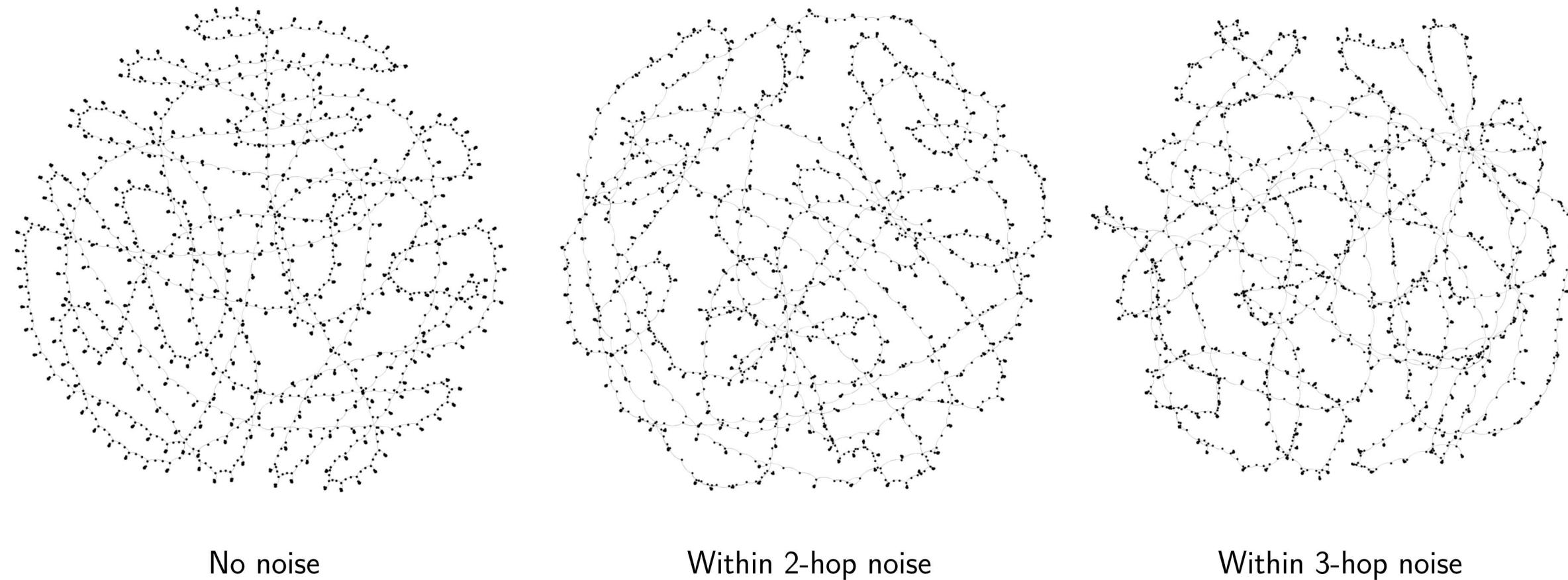
We use Graph Isomorphism Network (GIN) [3] as the GNN. Implemented using PyTorch Geometric [2].

- ◎ Architecture: 3 GIN layers, followed by two fully-connected (FC) layers
- ◎ Each GIN layer is also composed of two FC layers. Batchnorm applied follows each GIN layer. ReLU activation after linear transformations.
- ◎ Only feature is node degree (normalized)

## Experiment Setup

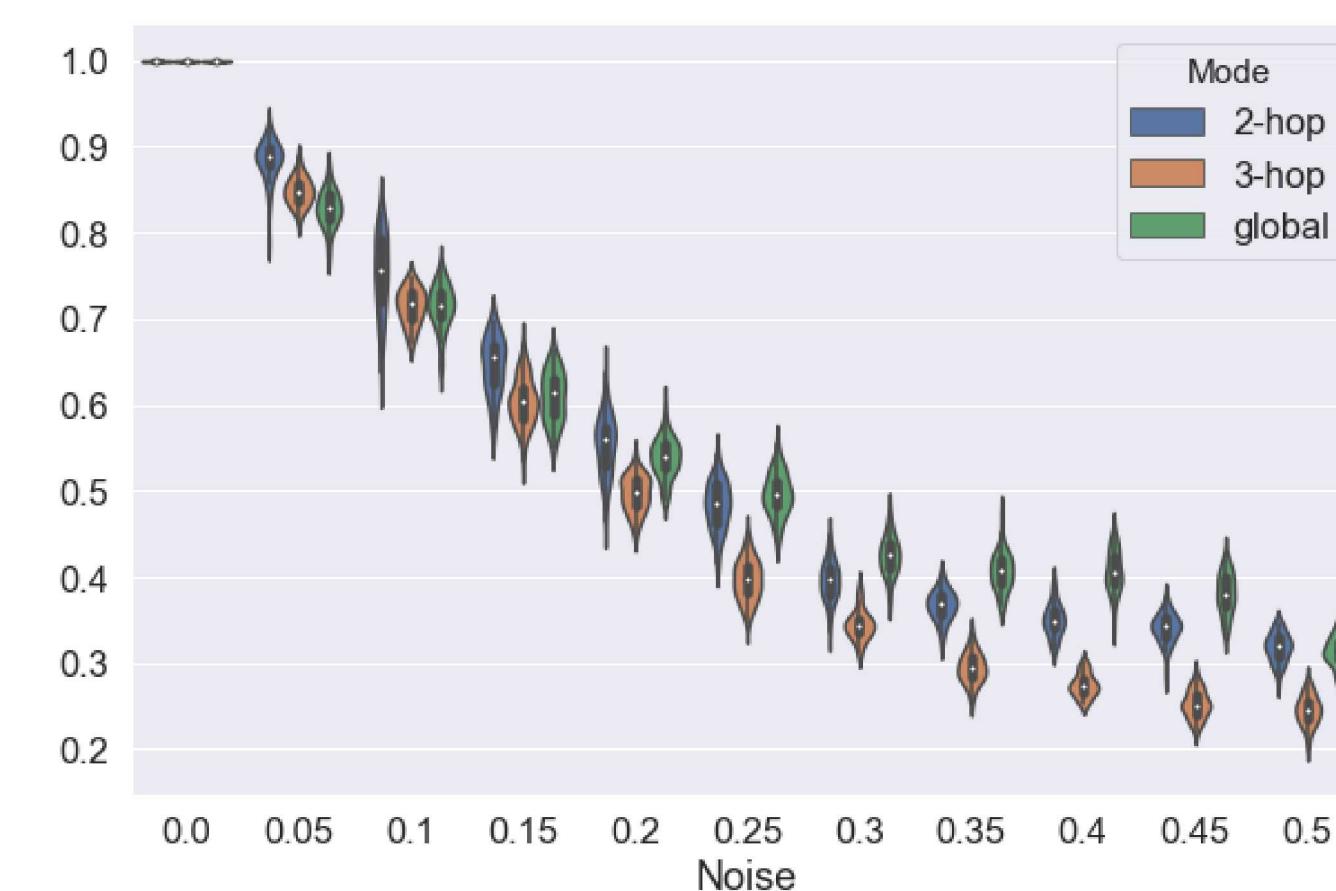
- ◎ Results from 50 independent trials
- ◎ Training set: 20 node labels per class from  $G_p$
- ◎ Validation set: 200 node labels
- ◎ Test set: 1000 nodes
- ◎ Test score ( $F_1$ -macro) is from evaluating model achieving best validation score after training for 200 epochs

## Experiments and Results



### GNN performance vs. structural noise

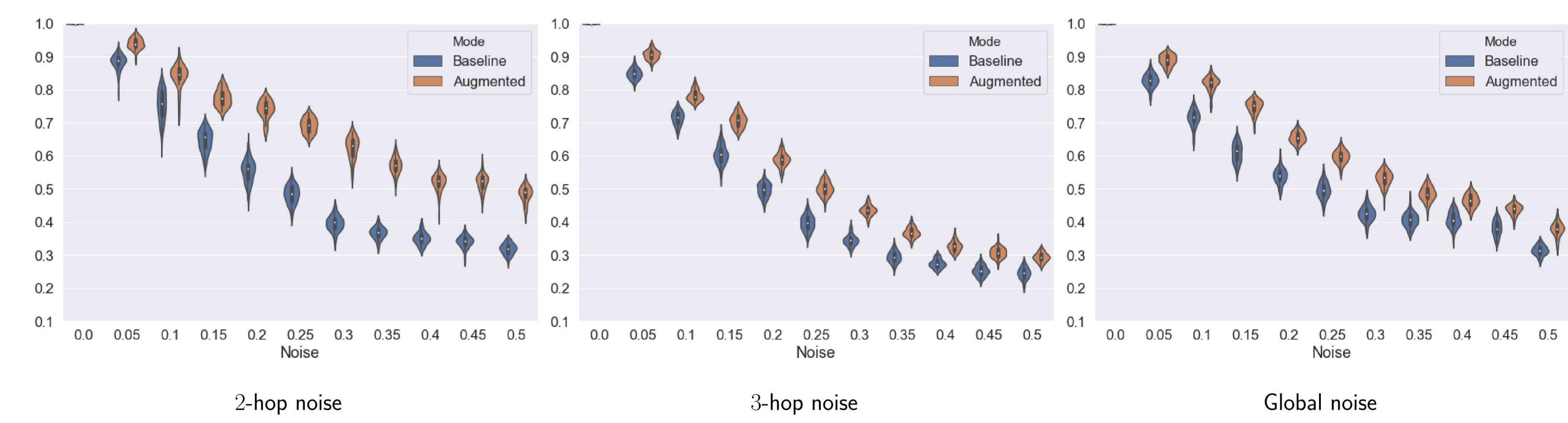
We vary the ratio  $p$  of noisy edges added to  $G$  in increments of 0.05, and evaluate performance trained on each version of  $G_p$ . We evaluate for 3 different modes of noise: 2-hop, 3-hop, or unconstrained (global).



**Findings:** With no noise ( $p = 0$ ), the GIN learns to classify nodes near perfectly.  $F_1$ -score declines sharply with increasing  $p$  (randomly added edges)—median performance is below 50% at 25% noise, and below 35% at 50% noise, across all modes.

### Augmented training from same distribution

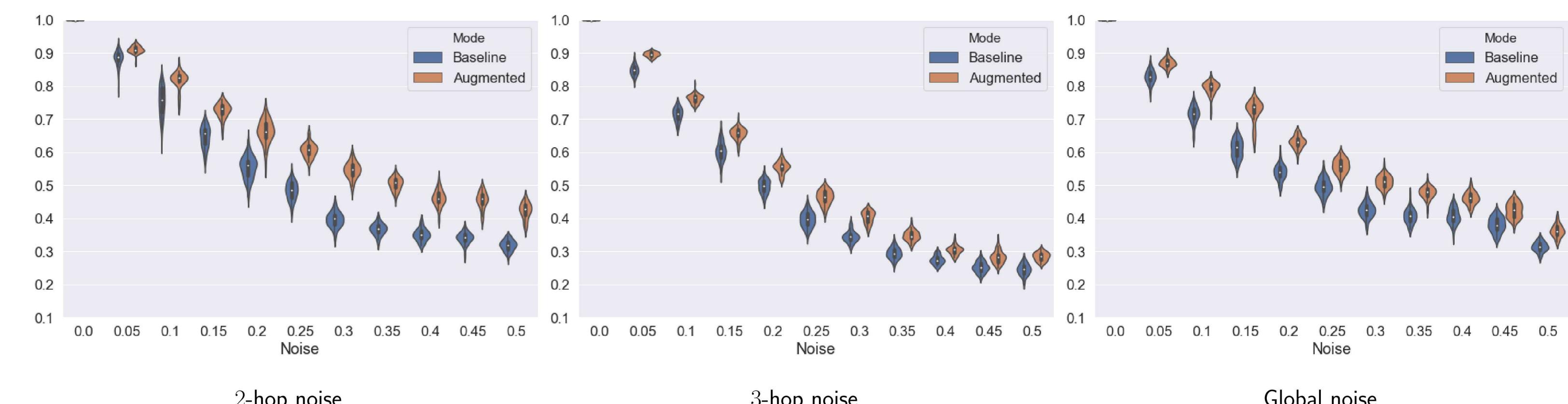
We compare performance from augmented training vs. non-augmented training (baseline) on  $G_p$ . The augmenting graph  $G_p^{(1)}$  is from same distribution as  $G_p$ . All of  $G_p^{(1)}$ 's node labels are used to augment training.



**Findings:** Training augmentation with graph drawn from the same noise distribution gives relative improvement of median F1 score up to 59%, 26%, and 26% for 2-hop, 3-hop, and global noise modes.

### Augmented training with smaller graphs

Here we use a sequence of 10 smaller generated graphs to augment training, where  $G_p^{(j)}$  is drawn from  $G'$ .



**Findings:** Augmented training is beneficial even when the smaller graphs are not of exactly same distribution as  $G_p$ . Relative improvements (of median) are 38%, 18%, and 20% for 2-hop, 3-hop, and global noise modes.