



Gemma

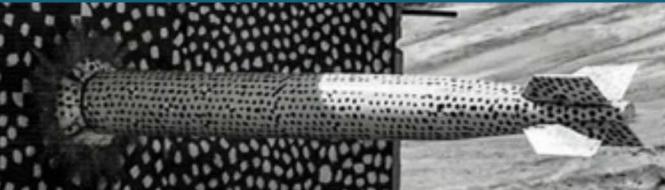
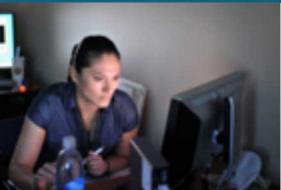
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SAND2020-1403C

A Sandia National Laboratories Electromagnetic Code for Heterogeneous Computer Architectures



BY

Brian Zinser, Samuel Blake, Robert Pfeiffer, Andy Huang, John Himbele, Brian Freno, Vinh Dang, Joseph Kotulski, Sivasankaran Rajamanickam, William Johnson, Salvatore Campione, and William Langston



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Capability and Performance on Next-Generation Hardware



- MPI inter- and intranode parallelism
- High processor clock speed
- High memory per processor

- MPI internode parallelism
- Threading intranode parallelism
- Low processor clock speed
- Low memory per processor

Ideal Development:

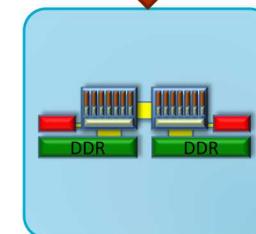
- Writing architecture independent source code
- Using multicore technology efficiently

Applications
Gemma

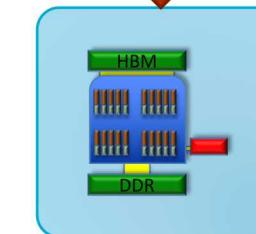
Libraries
Trilinos



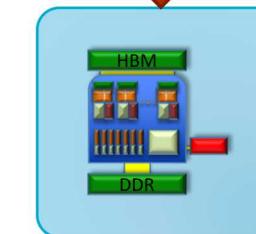
Kokkos abstraction layer



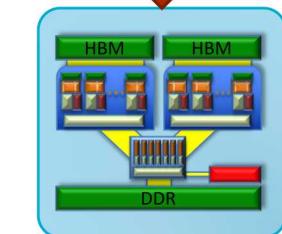
Multi-Core



Many-Core



APU



CPU+GPU



- Overview of Method of Moments
- Radar cross section use case and how it relates to our work
- Field levels near an object and some complications
- Primary use case: Coupling into high quality factor cavities



Method of Moments



Method of Moments (MoM) brief overview



Through the equivalence principle, we consider the current on an objects boundary instead of the field around and inside the object. For electric field \mathbf{E} , magnetic field \mathbf{H} , electric current \mathbf{J} , and magnetic current \mathbf{M} ,

$$\mathbf{E} = -i\omega\mu(\mathcal{L}\mathbf{J}) - (\mathcal{K}\mathbf{M})$$

$$\mathbf{H} = -i\omega\epsilon(\mathcal{L}\mathbf{M}) - (\mathcal{K}\mathbf{J})$$

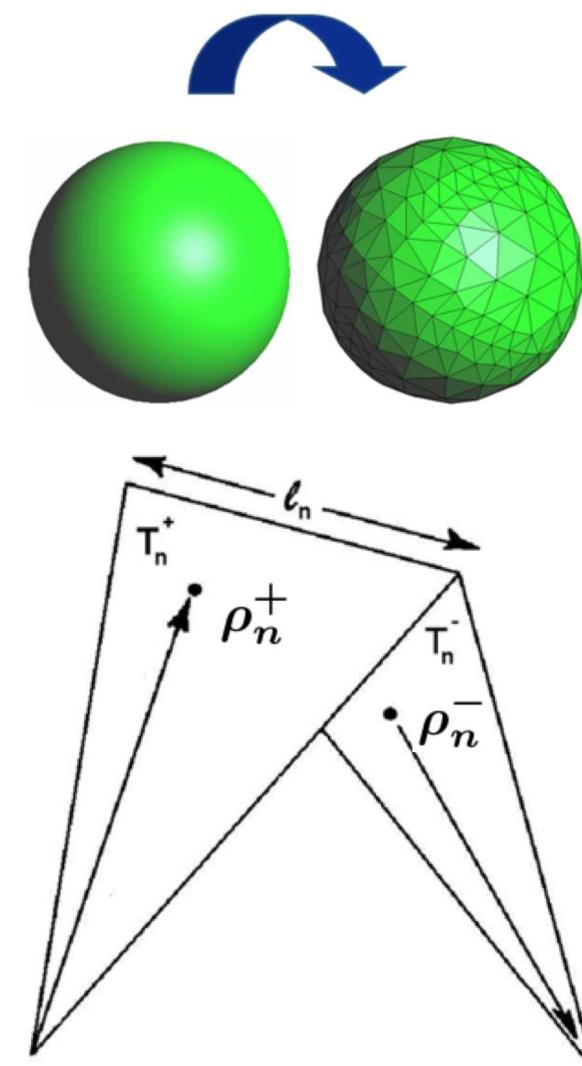
$$\mathcal{L}\mathbf{X} = [1 + \frac{1}{k^2} \nabla\nabla \cdot] \int G(\mathbf{r}, \mathbf{r}') \mathbf{X}(\mathbf{r}') d\mathbf{r}'$$

$$\mathcal{K}\mathbf{X} = \nabla \times \int G(\mathbf{r}, \mathbf{r}') \mathbf{X}(\mathbf{r}') d\mathbf{r}'$$

$$G(r) = \frac{e^{-ikr}}{4\pi r}, \mathbf{r} = |\mathbf{r} - \mathbf{r}'|$$

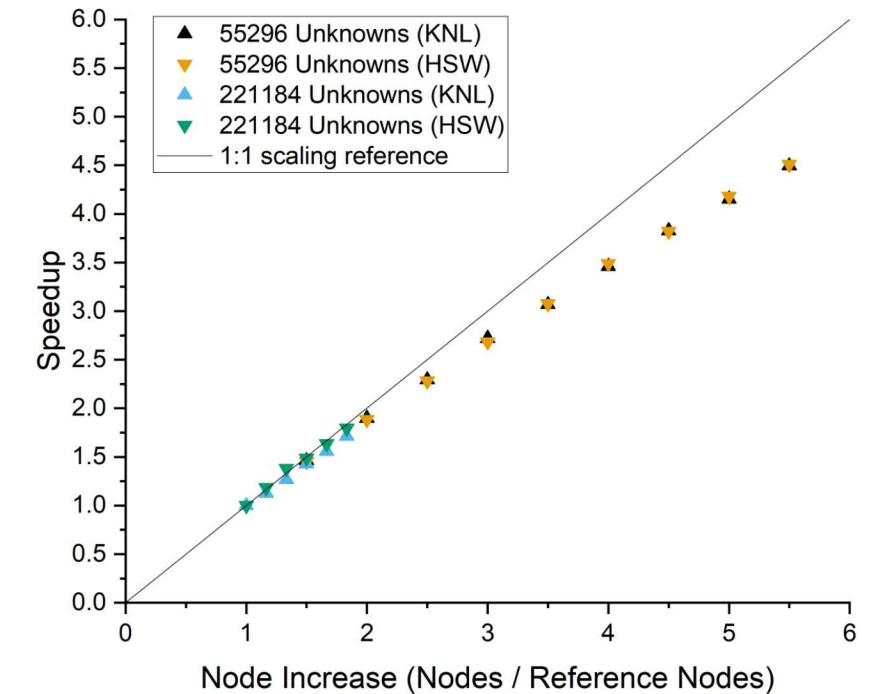
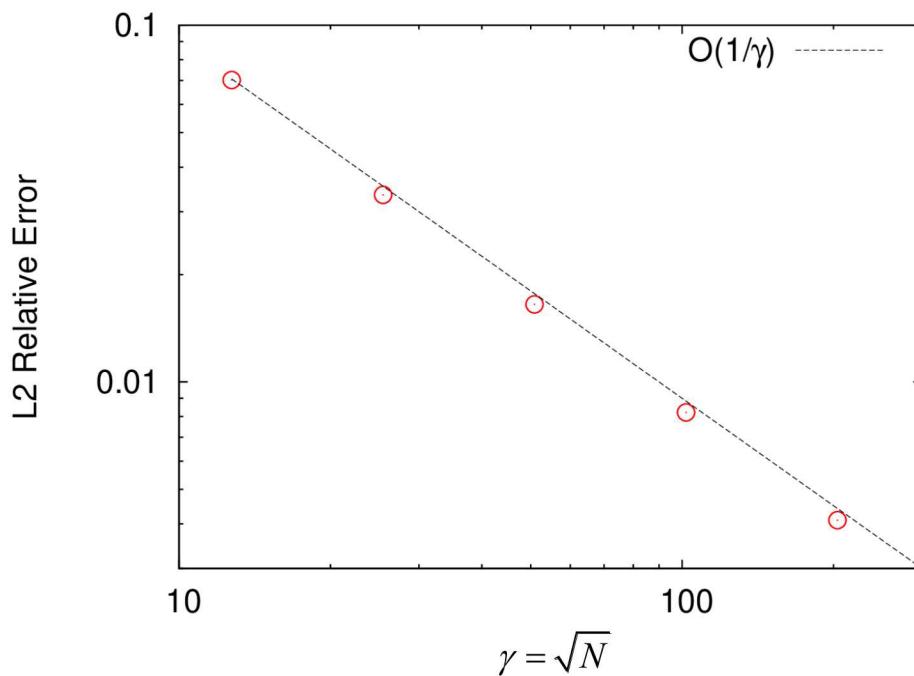
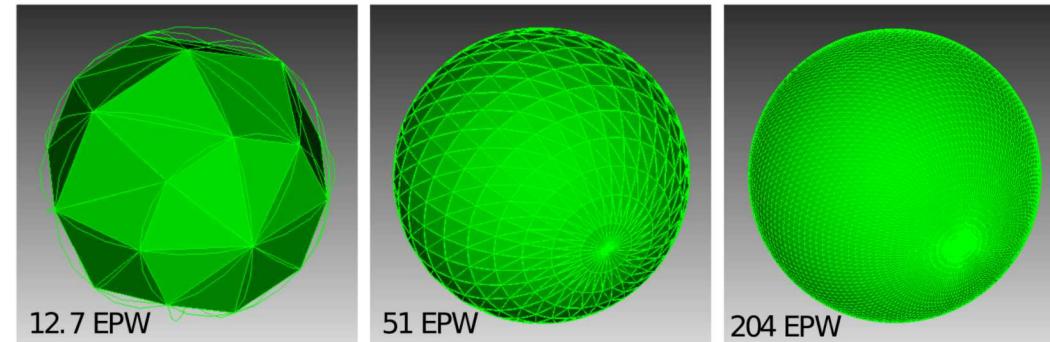
Taking the first equation, but leaving off \mathbf{M} , gives the electric field integral equation (EFIE). Representing \mathbf{J} with a basis \mathbf{f}_n , testing with a function \mathbf{f}_m from the set of basis functions, and moving the derivatives off G , its discrete form Z is

$$Z_{m,n} = \int_{f_m} \int_{f_n} \left[i\omega\mu_l \mathbf{f}_m \cdot \mathbf{f}_n - \frac{i}{\omega\epsilon_l} \nabla \cdot \mathbf{f}_m \nabla' \cdot \mathbf{f}_n \right] \frac{e^{-ikr}}{4\pi r}$$



$$\mathbf{f}_n(\mathbf{r}) = \begin{cases} \frac{\ell_n}{2A_n^+} \rho_n^+ & \mathbf{r} \in T_n^+ \\ \frac{\ell_n}{2A_n^-} \rho_n^- & \mathbf{r} \in T_n^- \\ \mathbf{0} & \text{otherwise} \end{cases}$$

Convergence and scaling for a sphere



Analytic reference solution for surface current given by Mie scattering solution to Maxwell's equations.

Matrix requires $O(N^2)$ memory to store, calculating its entries is memory bound at the cache level, and $O(N^3)$ computation to solve via LU factorization.



Radar cross section



What is radar cross section?

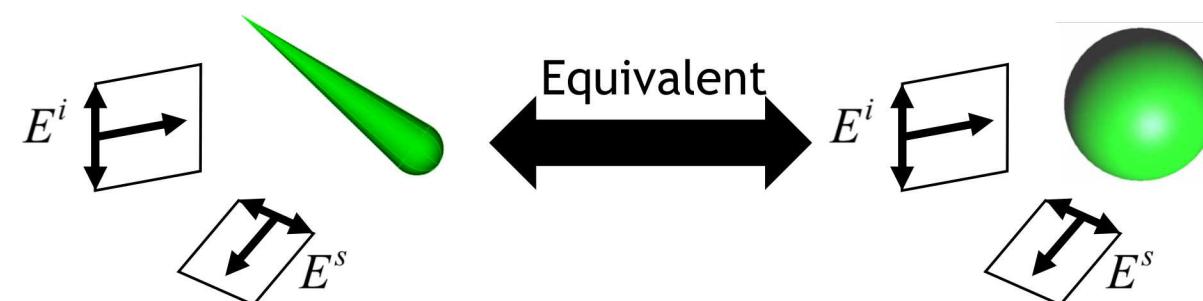
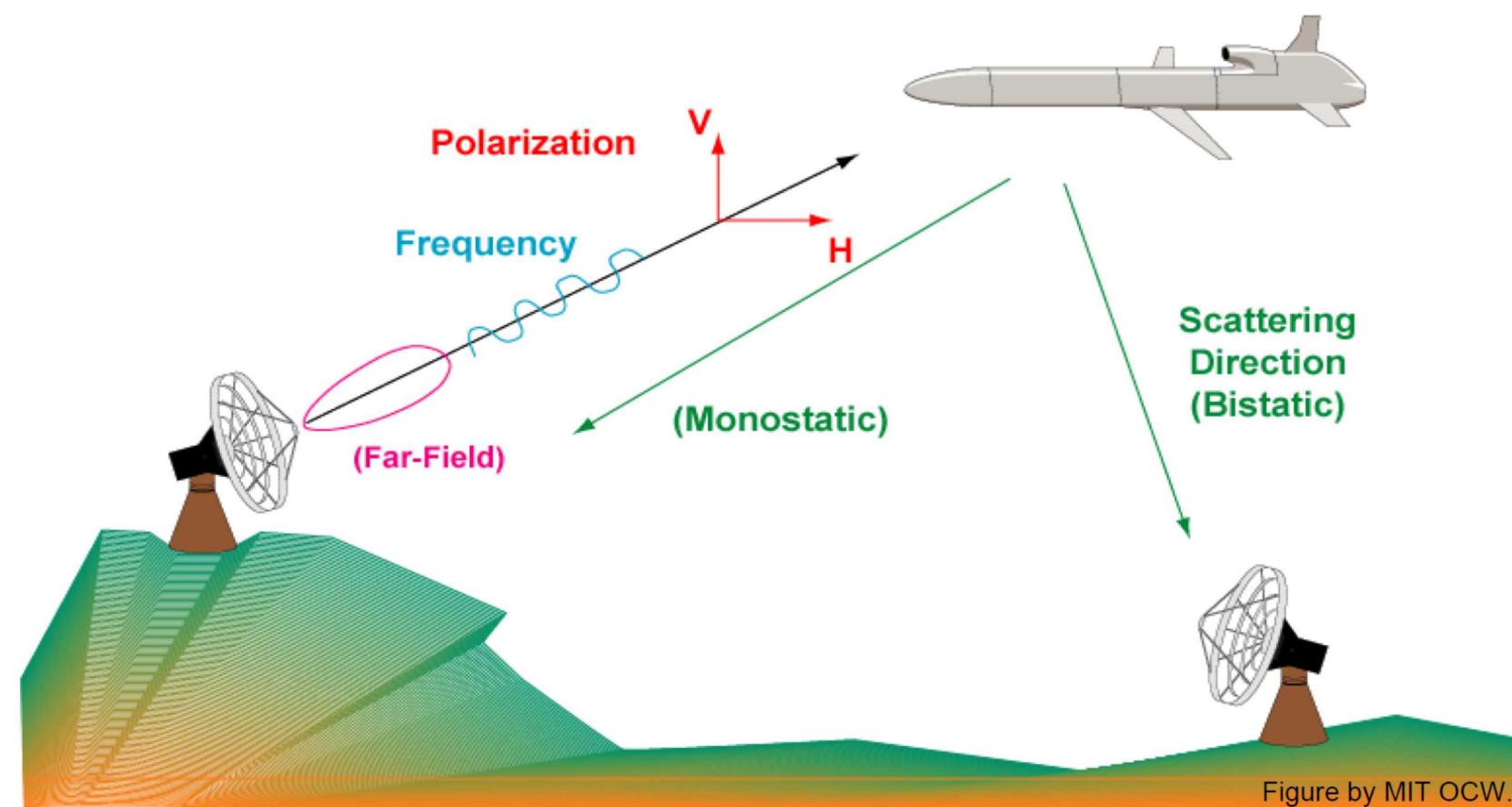
Target, size, shape, material, orientation

The radar cross section (RCS) of an object is

$$\sigma = \lim_{R \rightarrow \infty} 4\pi R^2 \left| \frac{E^s}{E^i} \right|^2$$

where E^i and E^s are the incident and scattered electric fields, respectively.

Less formally, the RCS is $\sigma = \pi a^2$ where a is the radius of the sphere with the same RCS.

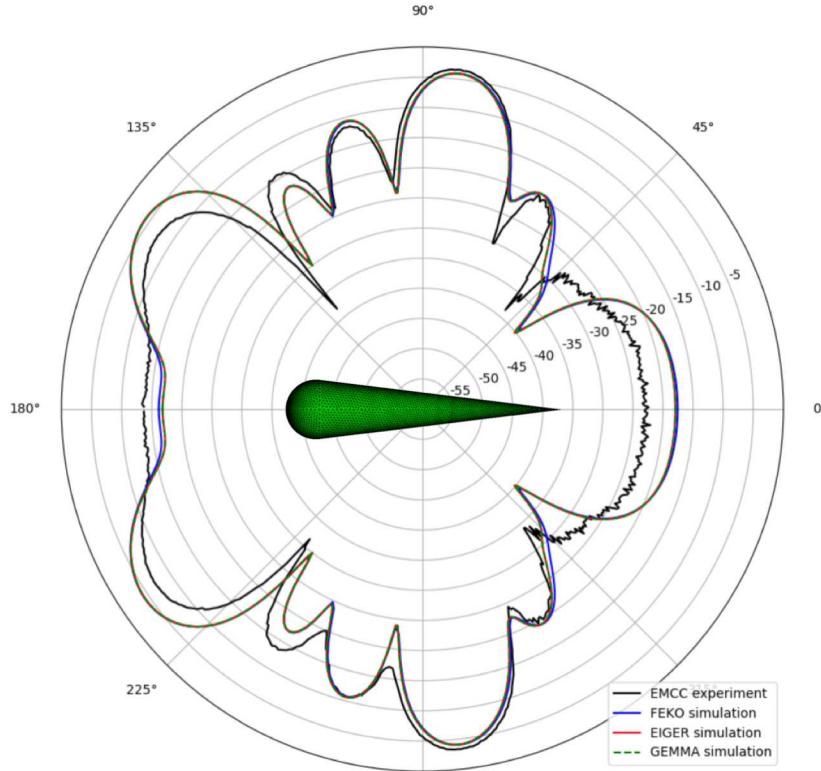


Monostatic RCS for the cone-sphere EMCC object

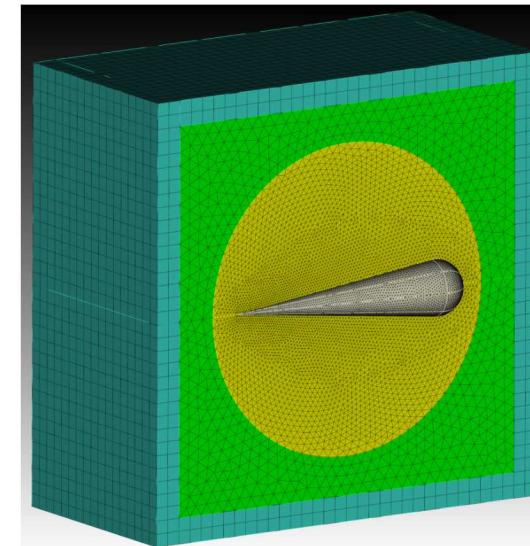


Electromagnetic Code Consortium (EMCC) data are a standard way to compare. However,

- The data lack information on the experiment setup to reproduce all results nicely, i.e., one can get agreement with the cone-sphere's 9 GHz data, but not the 869 MHz data (below).



- The data lack error bars associated with taking data from experiment so that the data can be compared with error bars due to running a simulation.
- We need our own experiment data for our use case of interest



Aside: Performing this simulation with a finite element method (FEM) program required many more elements, but provides many frequencies via a Fourier transform and has a sparse matrix; whether superior to MoM is case dependent.



Near field



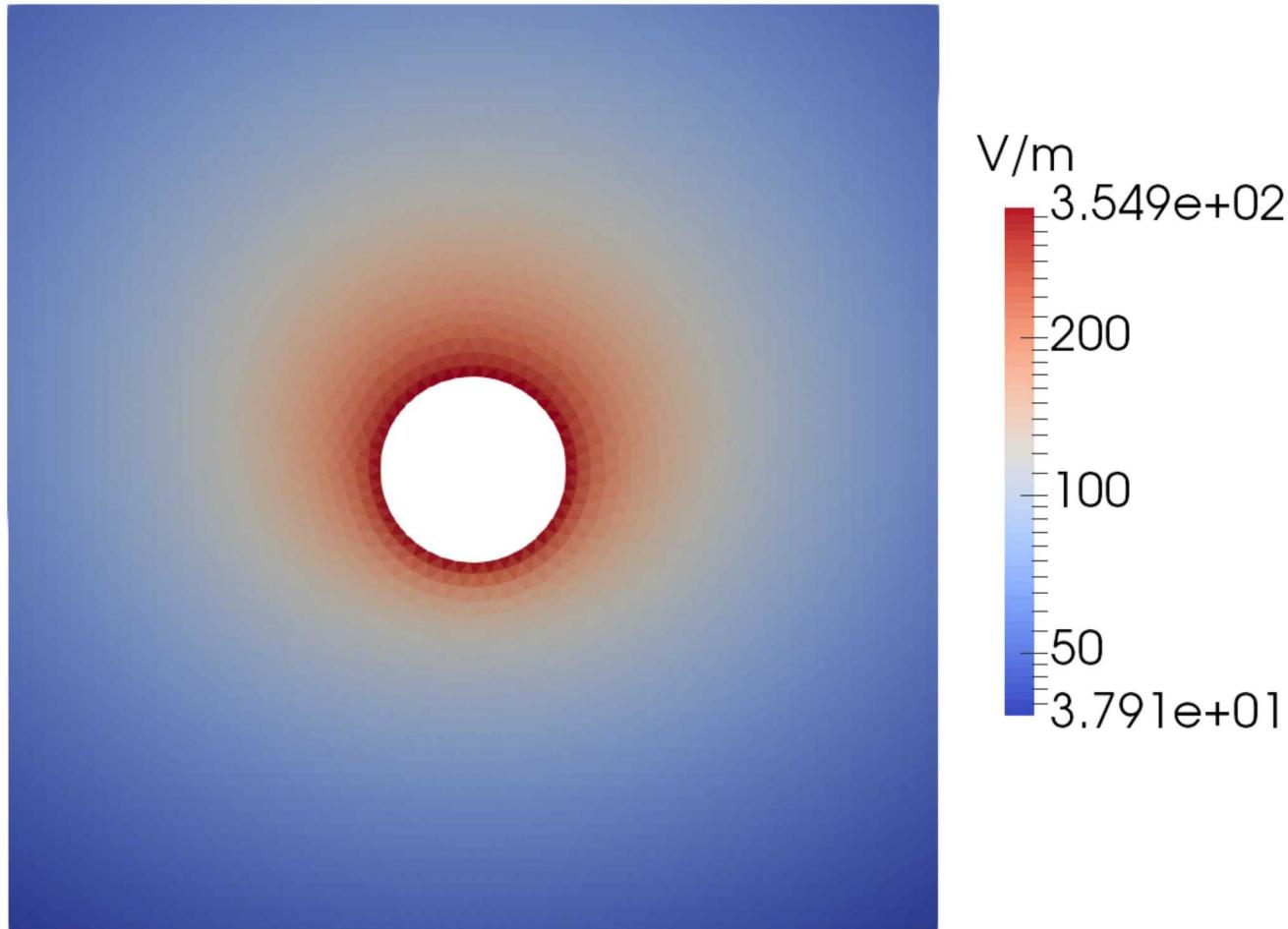
For the EFIE, the near field is computed without the test integral:

$$E^{total} = E^{inc} + E^{scattered}$$

where

$$E^{scattered}(\mathbf{r}) = \sum_n \int_{f_n} \left[i\omega\mu_l \mathbf{f}_n(\mathbf{r}') - \frac{i}{\omega\epsilon_l} \nabla' \cdot \mathbf{f}_n(\mathbf{r}') \right] \frac{e^{-ik|\mathbf{r}-\mathbf{r}'|}}{4\pi|\mathbf{r}-\mathbf{r}'|}$$

For a 1 m PEC sphere illuminated by a 377 V/m excitation at 4.77 MHz from above, the scattered near field is given on the right.



High accuracy integration via a radial angular transformation



The EFIE's \mathcal{L} operator has a weak $O(1/r)$ singularity while the MFIE's \mathcal{K} operator has a strong $O(1/r^2)$ singularity.

$$\mathcal{L}\mathbf{X} = [1 + \frac{1}{k^2} \nabla \nabla \cdot] \int G(\mathbf{r}, \mathbf{r}') \mathbf{X}(\mathbf{r}') d\mathbf{r}'$$

$$\mathcal{K}\mathbf{X} = \nabla \times \int G(\mathbf{r}, \mathbf{r}') \mathbf{X}(\mathbf{r}') d\mathbf{r}'$$

$$G(r) = \frac{e^{-ikr}}{4\pi r}, \mathbf{r} = |\mathbf{r} - \mathbf{r}'|$$

For \mathcal{L} , we use a radial angular transformation where the source triangle variables of integration become similar to polar coordinates (ρ, ϕ) :

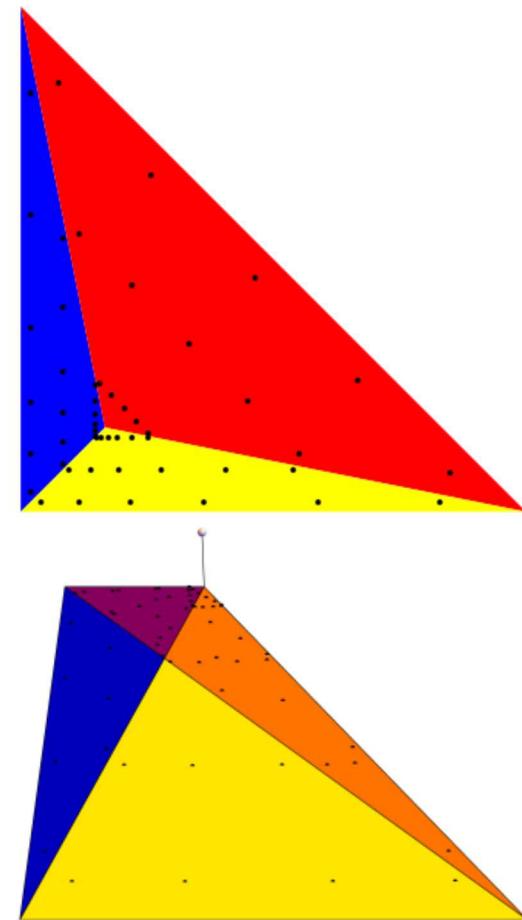
$$\int G(\mathbf{r}, \mathbf{r}') \mathbf{X}(\mathbf{r}') d\mathbf{r}' = \int \frac{e^{-ikr}}{4\pi r} \mathbf{X}(r, u) \frac{r}{\cosh u} dr du,$$

$$u = \ln \tan^{-1}(\phi/2)$$

For \mathcal{K} , in addition to a radial angular transformation, we subtract the first term of the integrand's Taylor series. This is similar to

$$\int \frac{e^r}{r} dr = \int \frac{e^{r-1}}{r} dr - \int \frac{1}{r} dr \text{ where}$$

$$\frac{e^r - 1}{r} = \frac{(1 + r + r^2 + \dots) - 1}{r} = \frac{r + r^2 + \dots}{r}$$



The 3 subtriangles used in the radial angular transformation when the singularity is interior and exterior to the triangle.

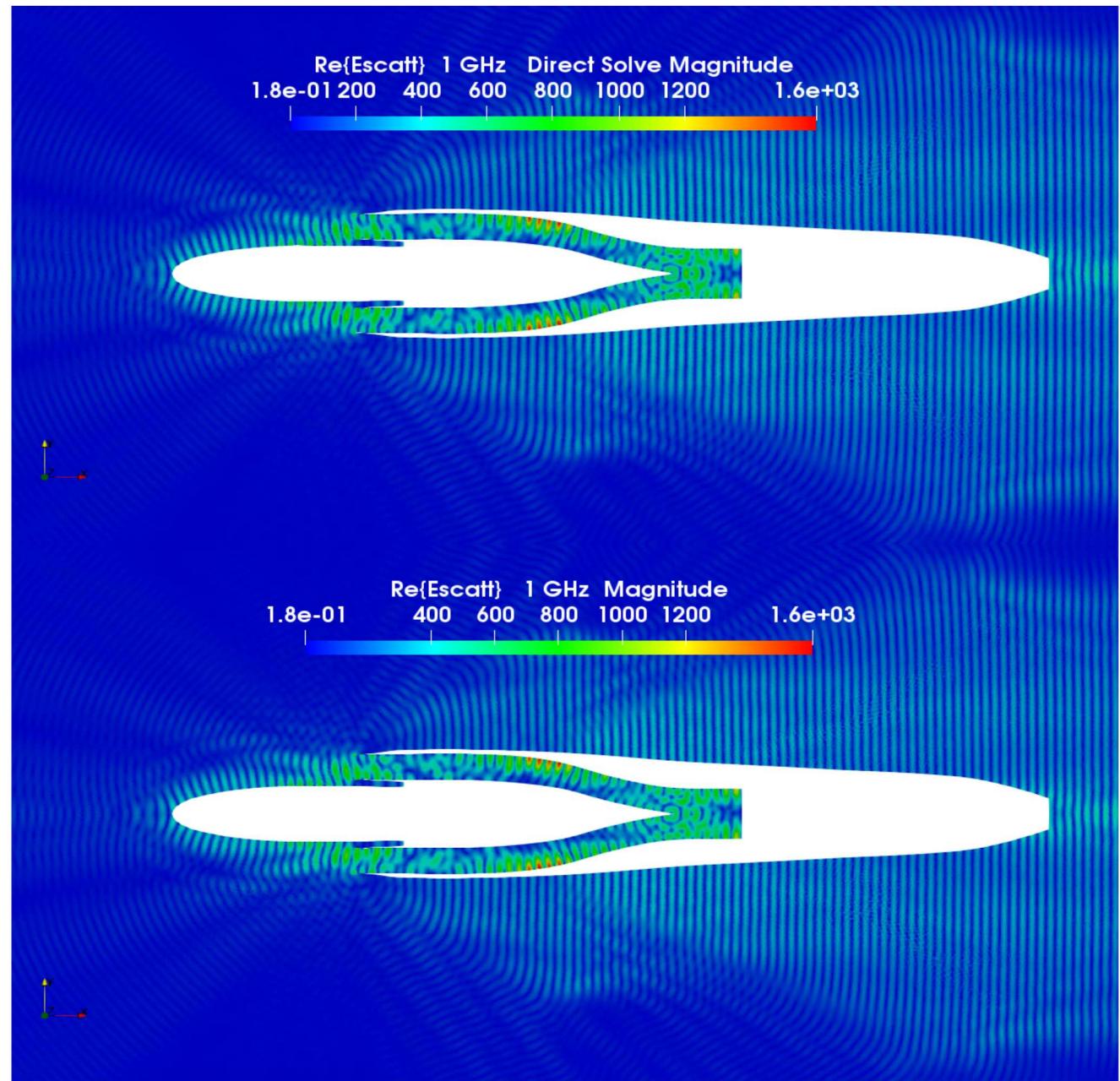
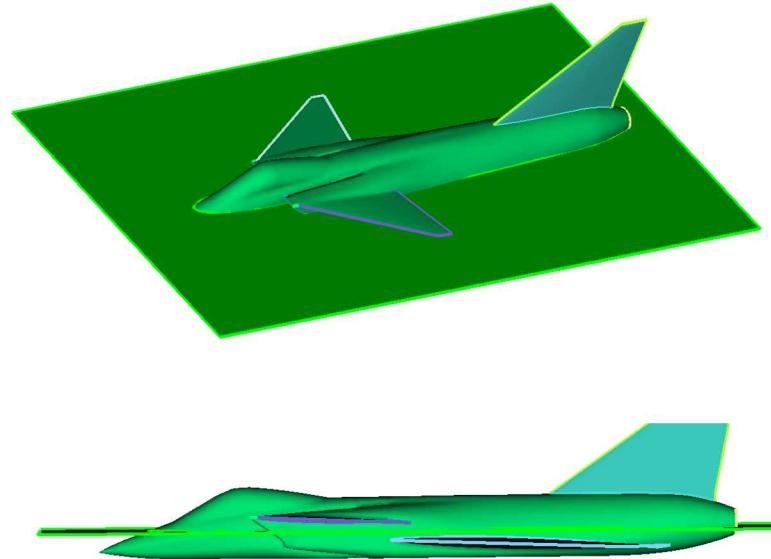
Near field for airplane intakes



Top right: Direct solve by LU factorization.

Bottom right: Solve by adaptive cross approximation (ACA).

While intake fields are much higher than incident fields, fast methods can often obtain qualitatively good results for this near field calculation.





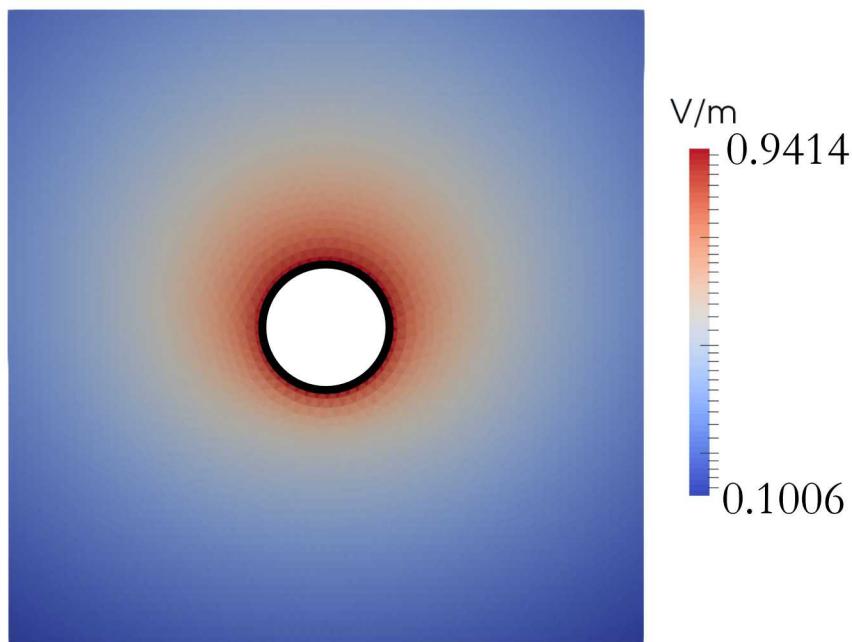
Cavity problem



Thin PEC hollow sphere at a higher frequency than the PEC sphere

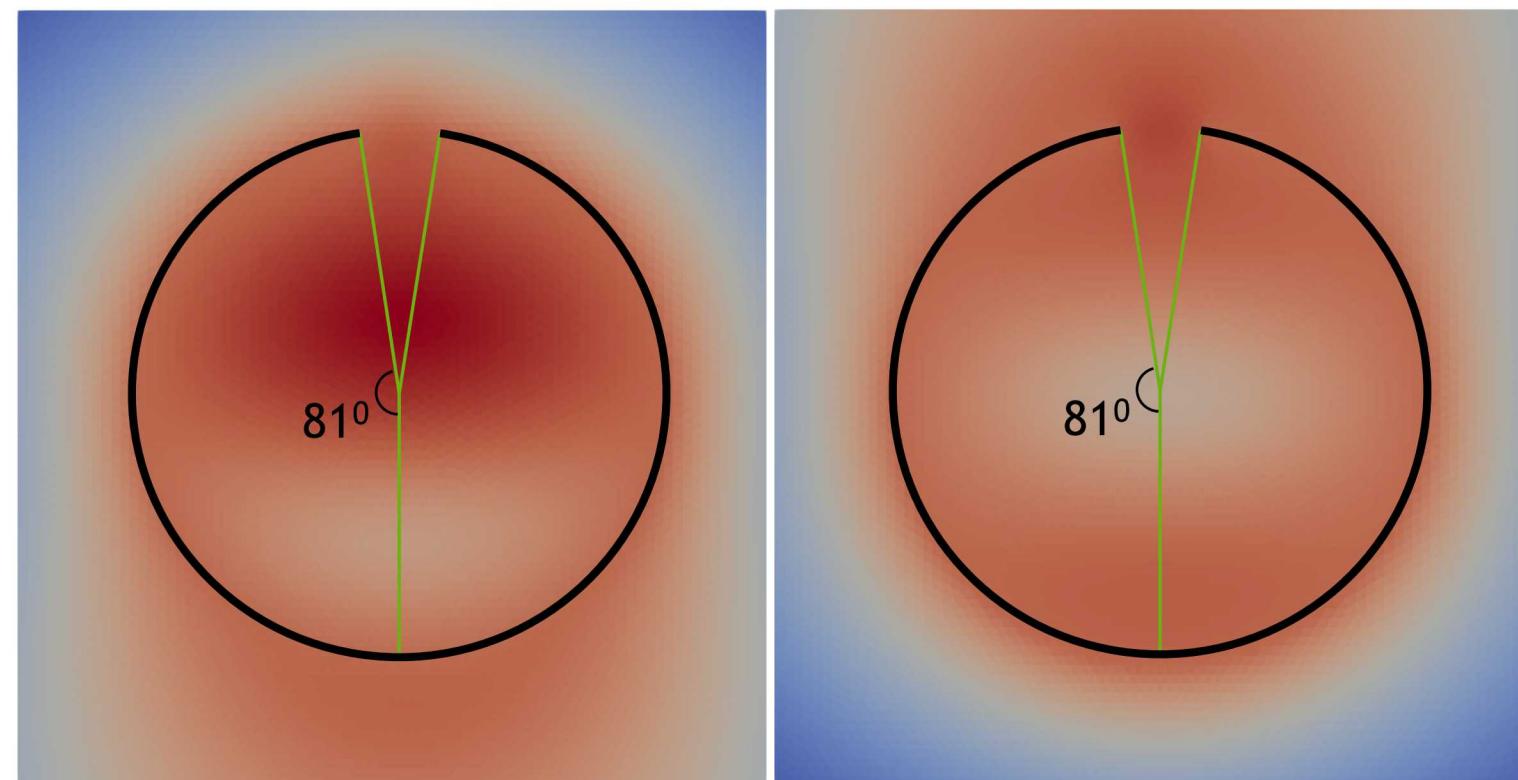
Top:

- Solid sphere
- 4.77 MHz excitation from above, magnitude 1 V/m



Bottom left:

- Hollow sphere
- 130 MHz excitation from above, magnitude 1 V/m

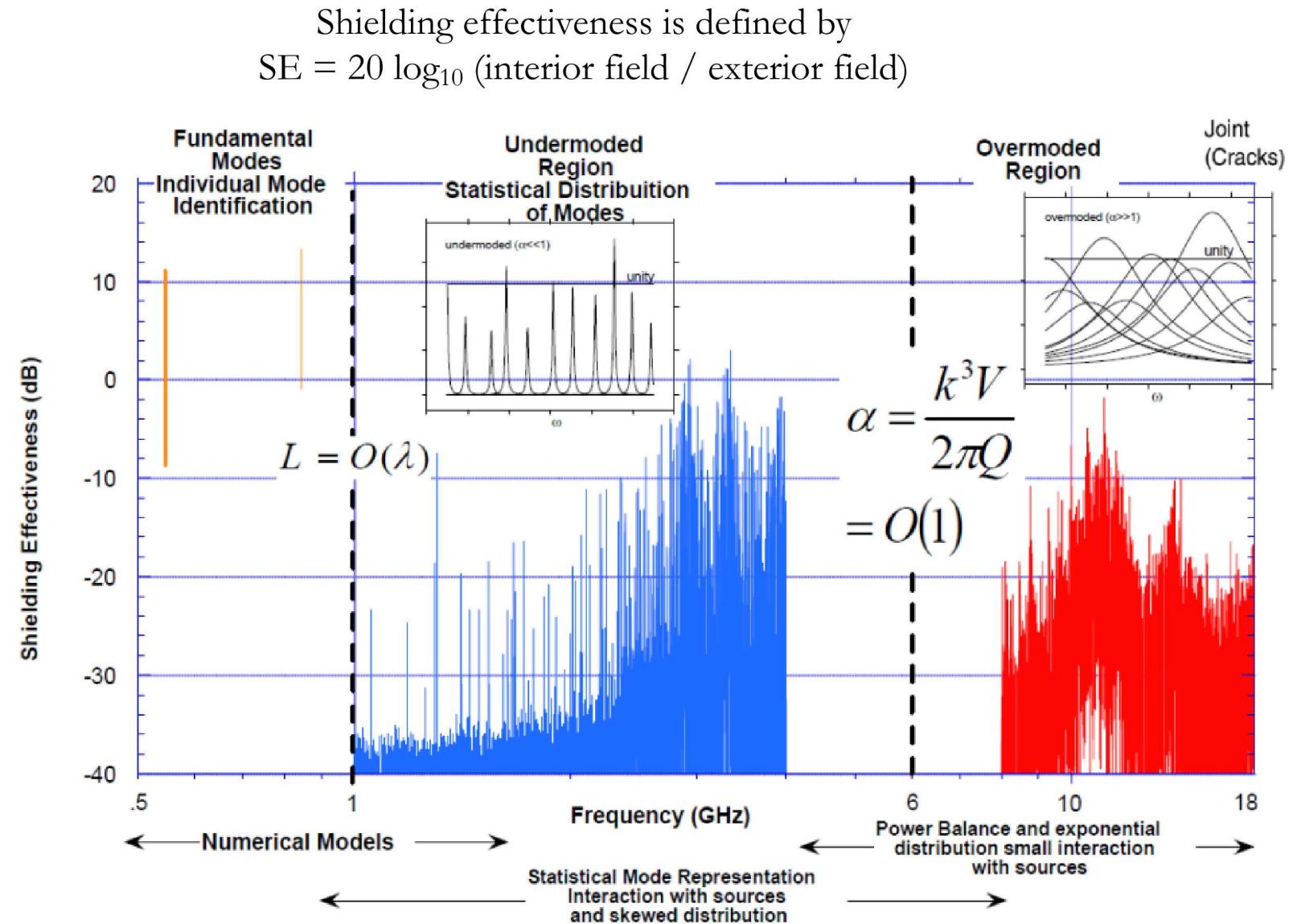
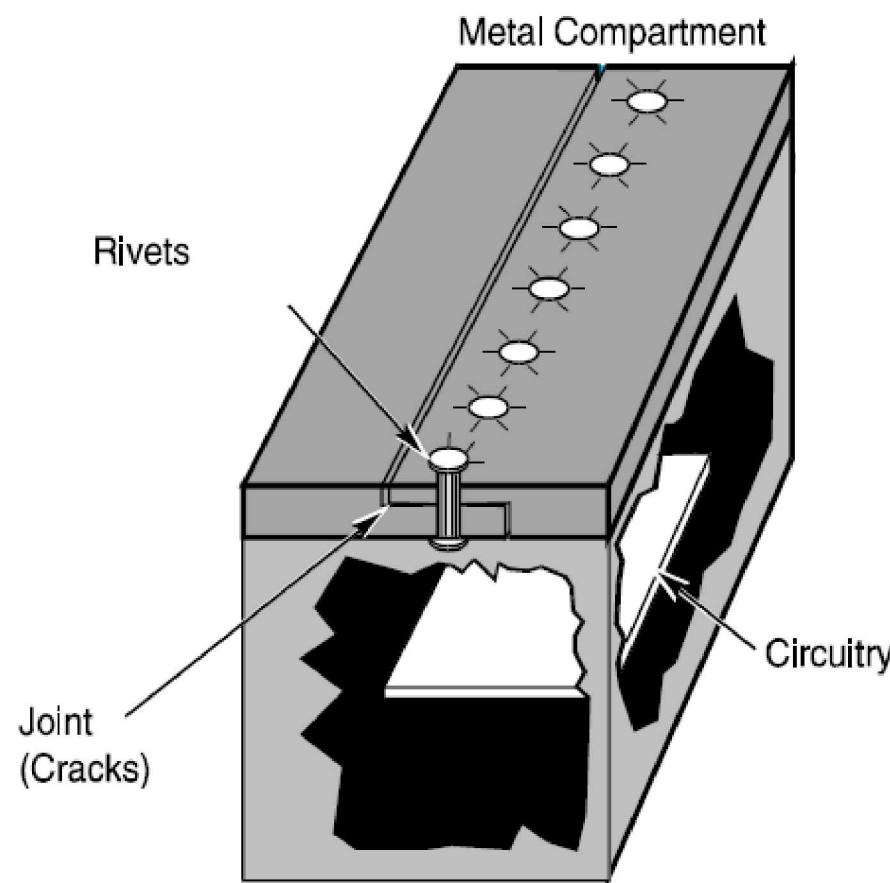


Bottom right:

- Hollow sphere
- 130 MHz excitation from below, magnitude 1 V/m

Electromagnetic radiation (EMR) coupling to high Q cavities

$$Q = \omega \frac{\text{energy stored}}{\text{average power dissipated}}$$



Slot subcell model for capturing coupling into a cavity accurately



In free space, the thin slot equation is:

$$H_z^>(a, z) + \frac{1}{4} \left(\Delta Y_C \frac{d^2}{dz^2} I_m - \Delta Y_L I_m \right) = -H_z^{inc}(z), I_m = -2V$$

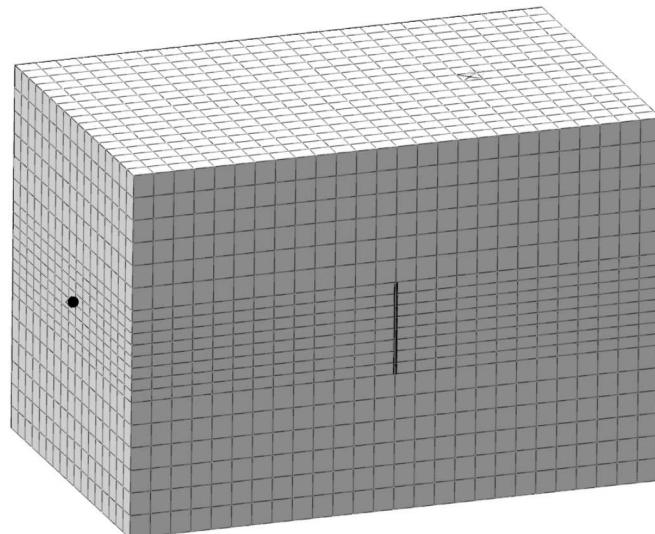
H_z = magnetic field

I_m = current

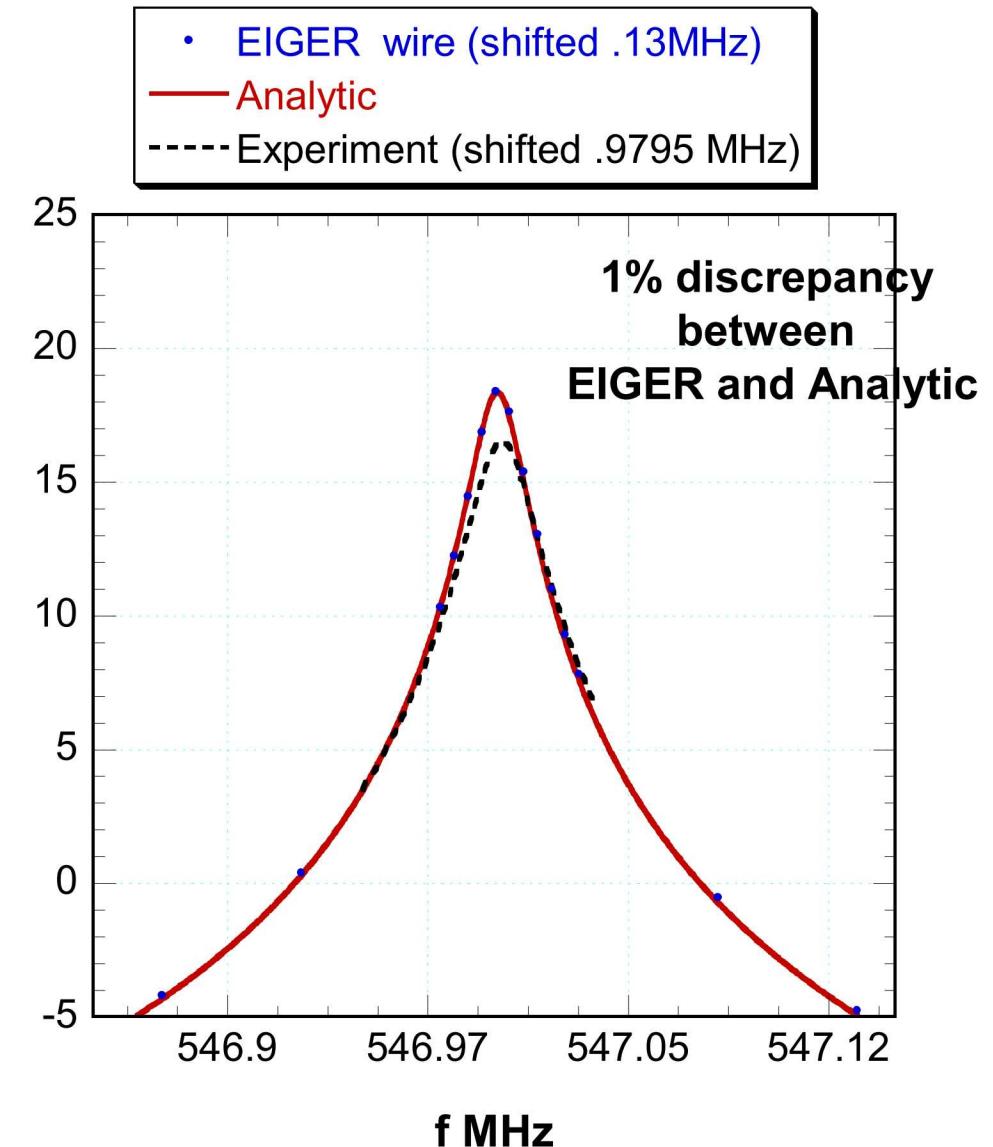
V = voltage

a = equivalent radius

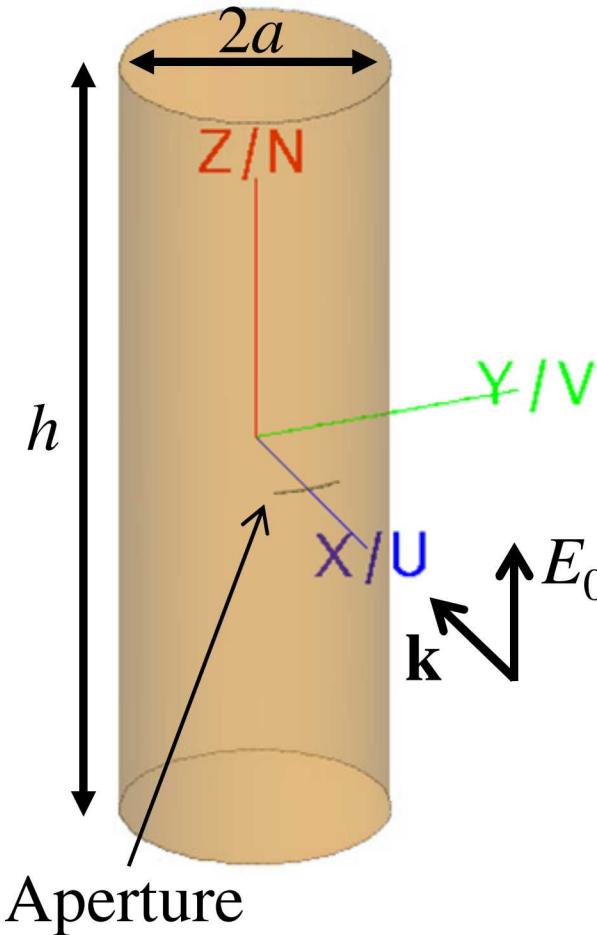
Y_C, Y_L capture gaskets and wall loss



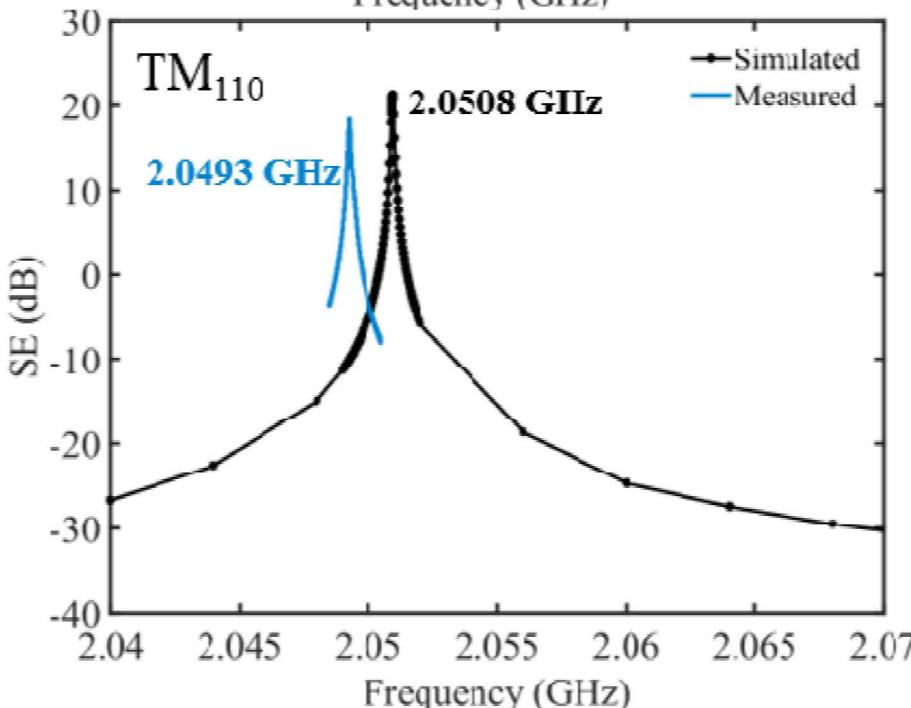
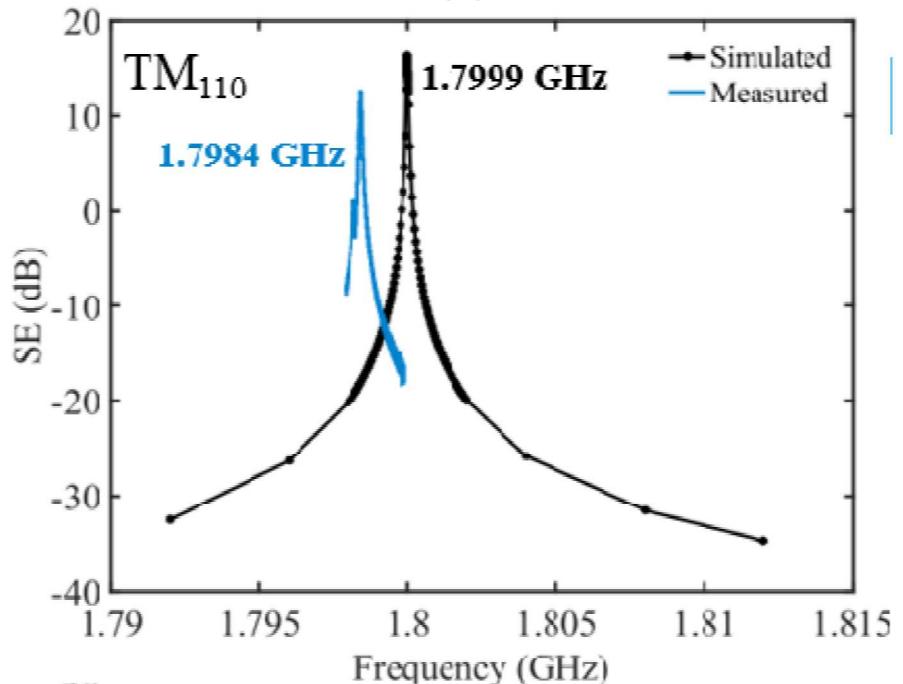
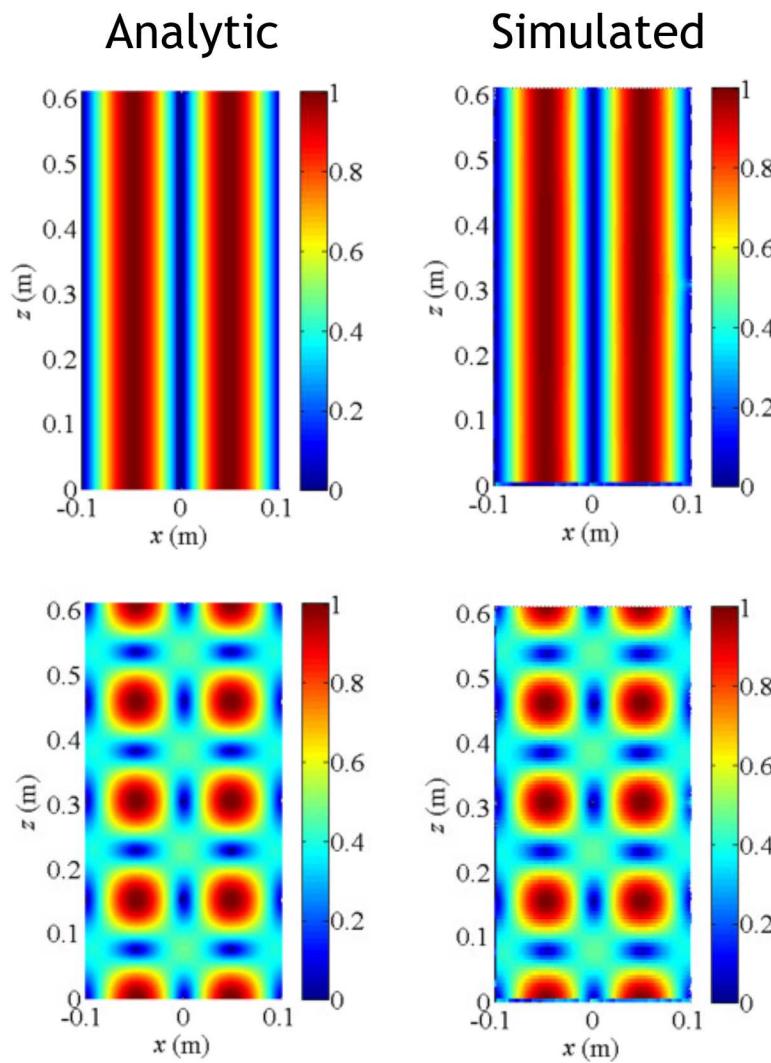
Shielding effectiveness dB



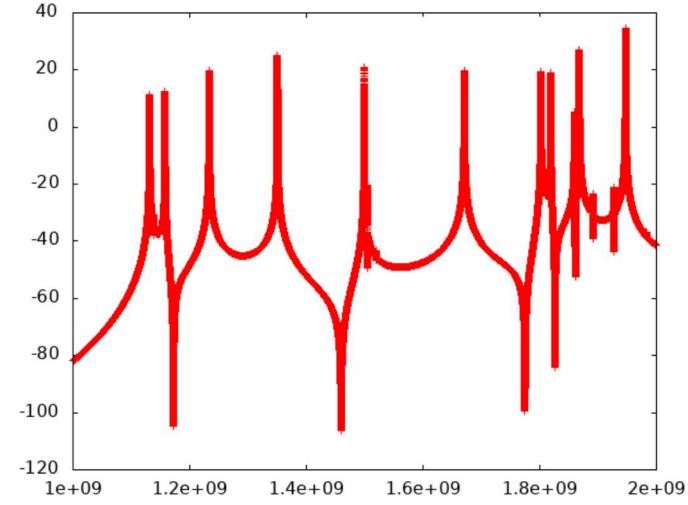
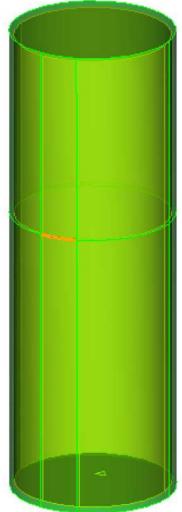
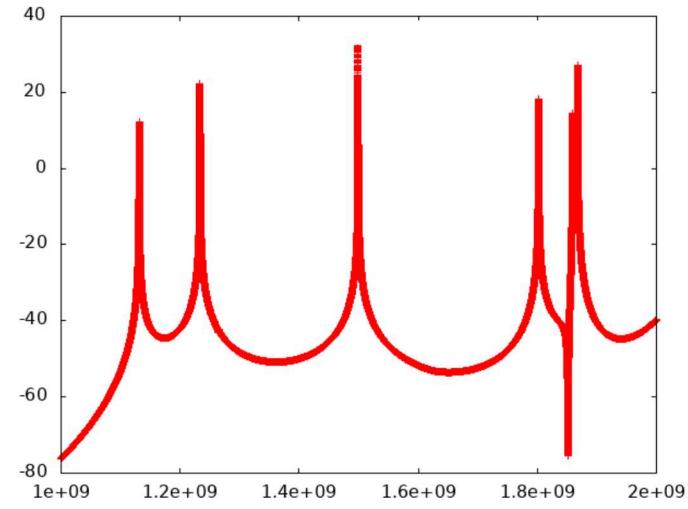
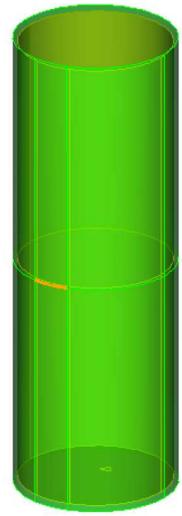
Cavity comparison with analytic and experiment



1.8 GHz

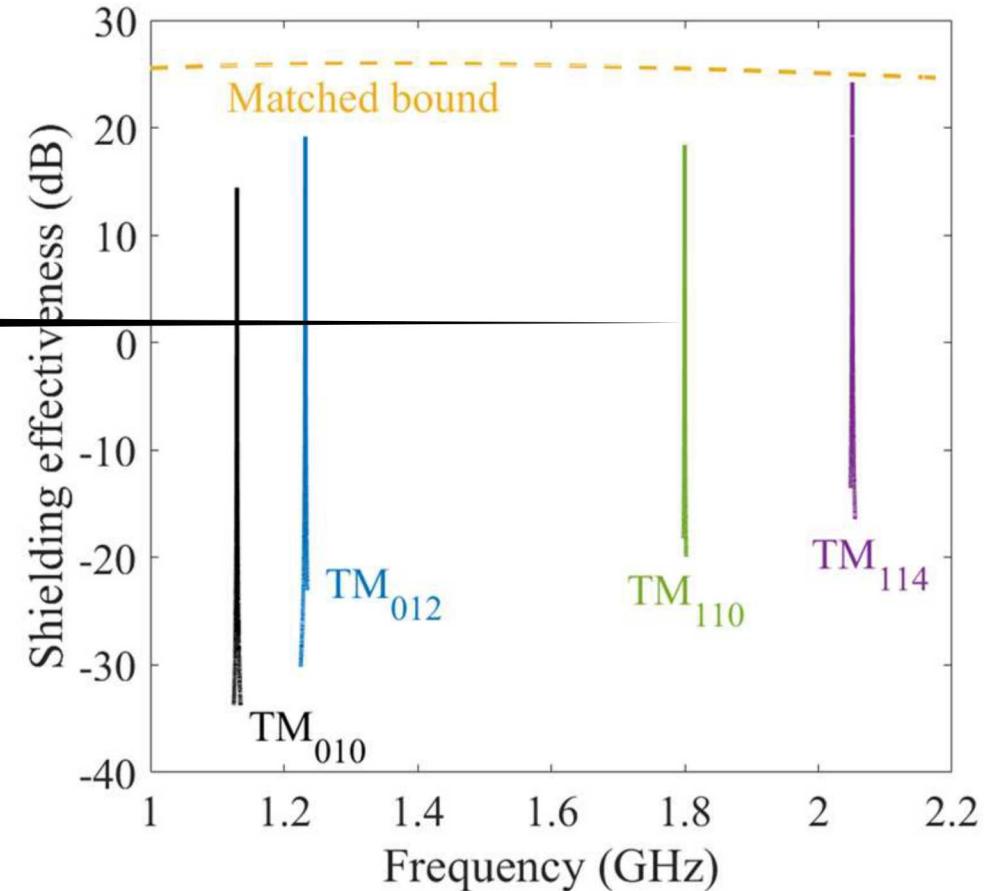


Response for centered slot vs slightly off-center slot



Power balance can be used to obtain an unmatched bound on the SE by equating the power received with the power lost due to the interior cavity wall, interior antennas, energy escaping out the slot, and other causes:

$$P_{rec} = P_{wall} + P_{ant} + P_{out} + \dots$$



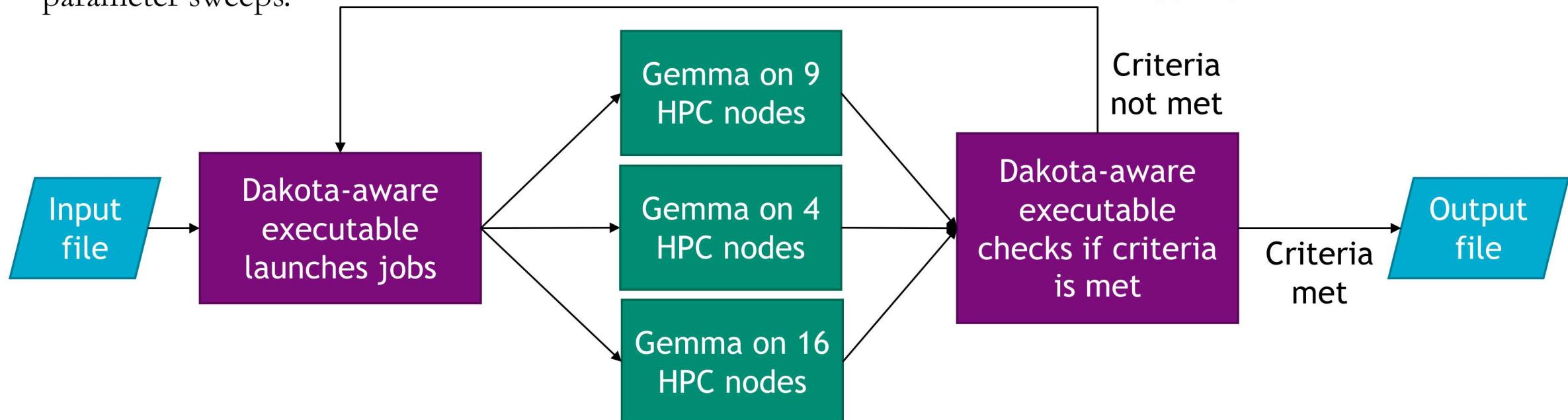
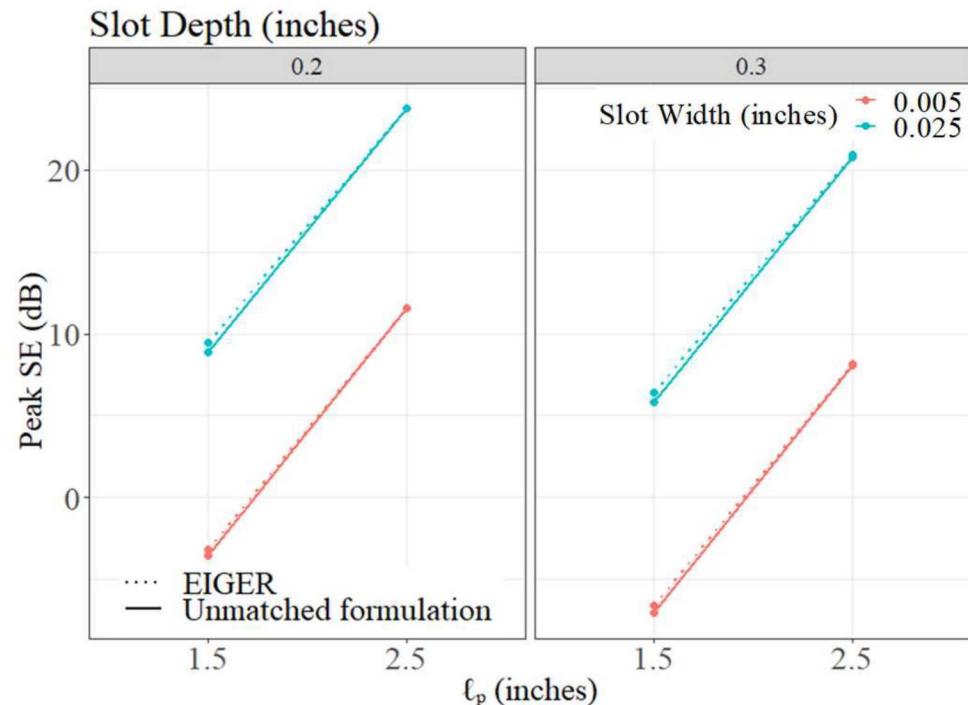
Dealing with uncertainties



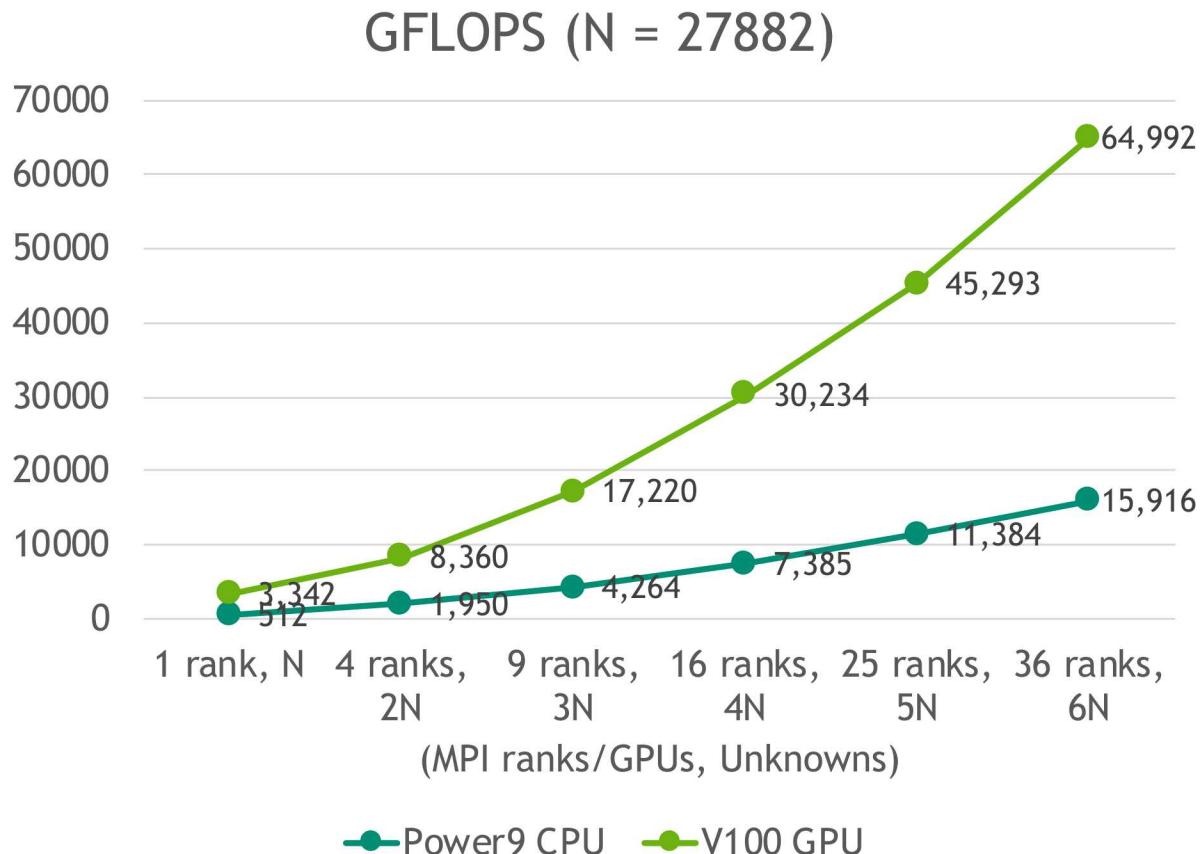
Dakota is a Sandia code that facilitates the exploration of parameter spaces for uncertainty quantification, optimization, and other purposes.

Right: Slot parameter sweeps using EIGER and the unmatched formulation.

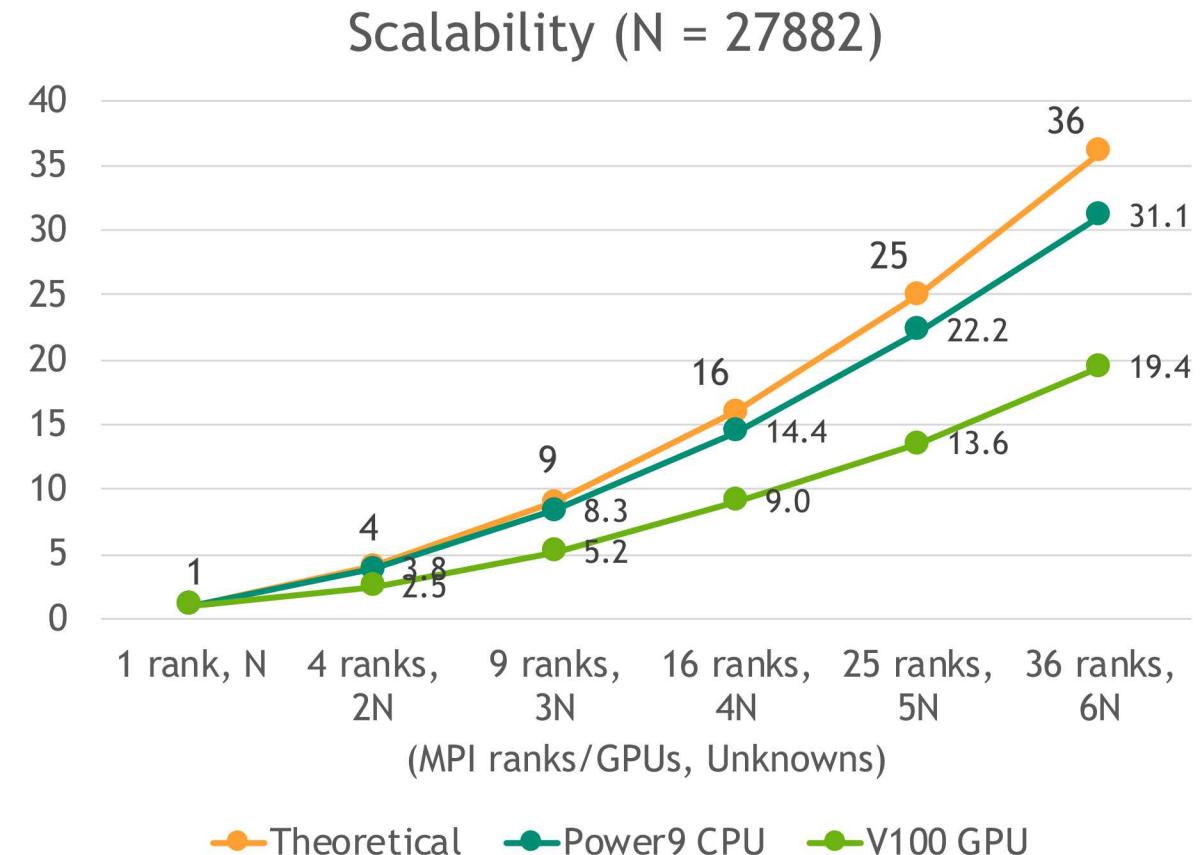
Below: Future automated runs using Gemma with parameter sweeps.



Weak scalability for Adelus, A Dense LU Solver Package



$$S = \frac{\text{GFLOPS}(\text{ranks/GPUs, unknowns})}{\text{GFLOPS}(1,1N)}$$



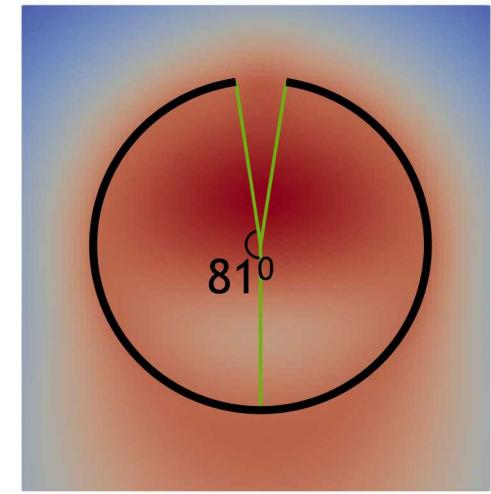
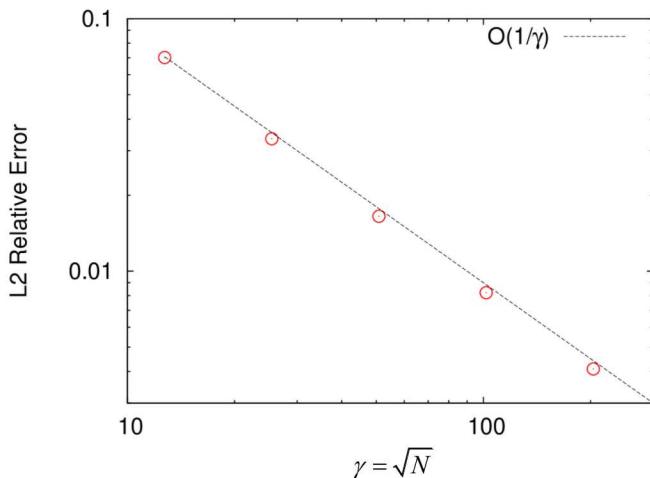
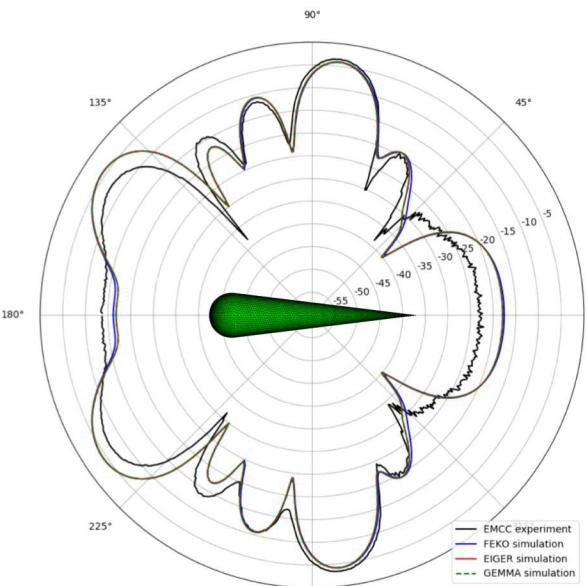
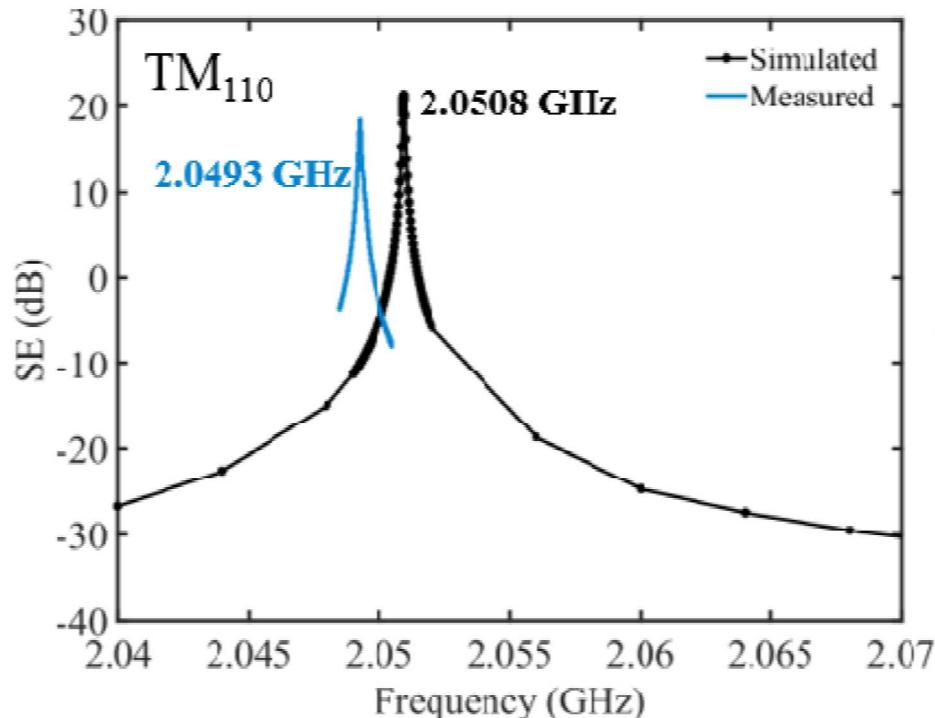
where ranks/GPUs = 1, 4, 9, 16, 25, 36
and unknowns = 1N, 2N, 3N, 4N, 5N, 6N

How to guarantee these capabilities after each source code change?

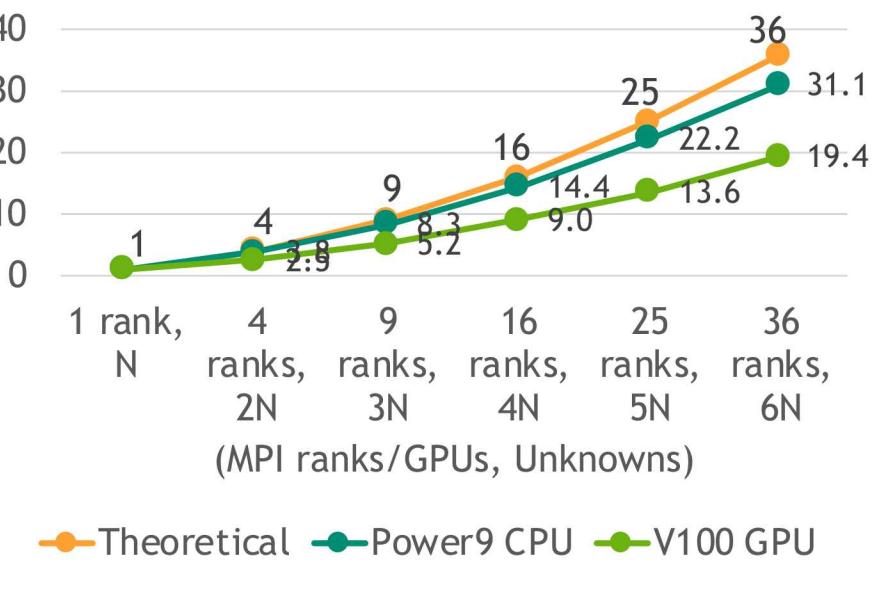


Nightly, weekly, or even monthly testing of problems on local and HPC resources for each use case.

VVtest is a Sandia-developed set of scripts that automate the testing of complex simulation runs, like those required for verification, validation, and uncertainty quantification.



Scalability (N = 27882)



Thank you!

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MIT OCW

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Additional slides



Depiction of surface current on a boundary between regions

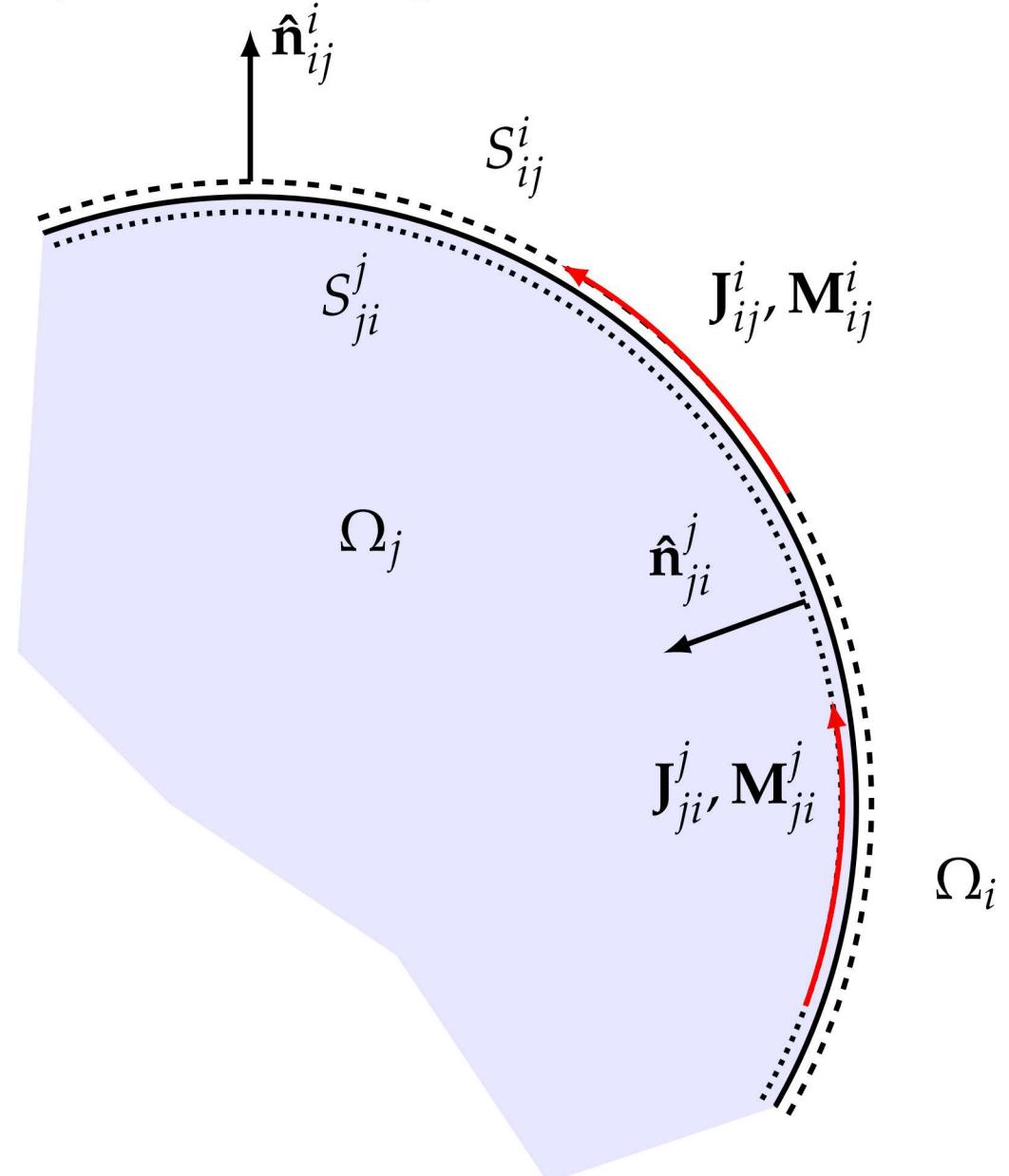
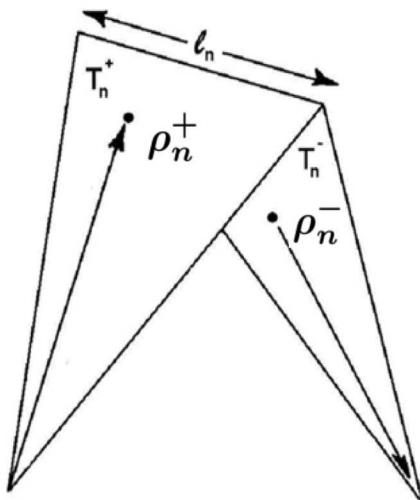


Recall that the EFIE is

$$Z_{m,n} = \int_{f_m} \int_{f_n} \left[i\omega\mu_l \mathbf{f}_m \cdot \mathbf{f}_n - \frac{i}{\omega\epsilon_l} \nabla \cdot \mathbf{f}_m \nabla' \cdot \mathbf{f}_n \right] \frac{e^{-ikr}}{4\pi r}$$

with basis functions

$$\mathbf{f}_n(\mathbf{r}) = \begin{cases} \frac{\ell_n}{2A_n^+} \boldsymbol{\rho}_n^+ & \mathbf{r} \in T_n^+ \\ \frac{\ell_n}{2A_n^-} \boldsymbol{\rho}_n^- & \mathbf{r} \in T_n^- \\ \mathbf{0} & \text{otherwise} \end{cases}$$



Maxwell's Equations in the Frequency Domain

Faraday : $\nabla \times \mathbf{E} = -j\omega \mathbf{B}$

Ampere - Maxwell : $\nabla \times \mathbf{H} = \mathbf{J} + j\omega \mathbf{D}$

Electric Gauss : $\nabla \cdot \mathbf{D} = \rho$

Magnetic Gauss : $\nabla \cdot \mathbf{B} = 0$

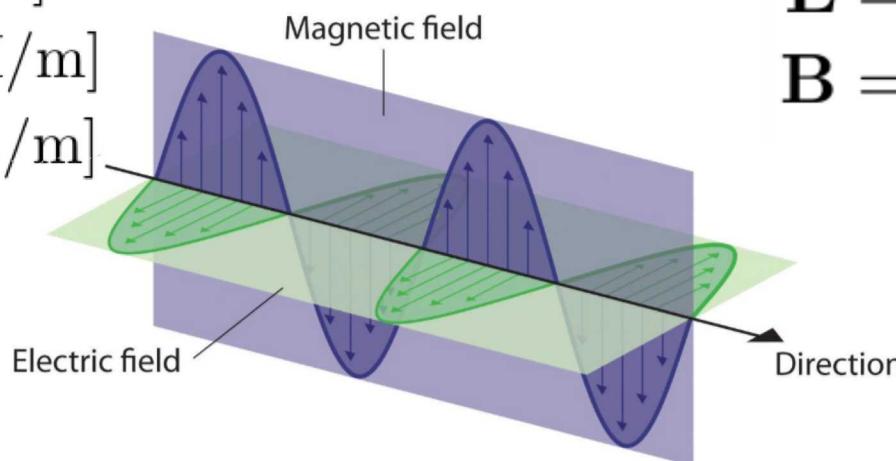
 \mathbf{E} : electric field [V/m] \mathbf{H} : magnetic field [A/m] \mathbf{D} : electric flux density [C/m²] \mathbf{B} : magnetic flux density [T = Wb/m²] \mathbf{J} : electric current density [A/m²] ρ : volume charge density [C/m³]

Constitutive relations:

$\mathbf{D} = \epsilon \mathbf{E}$ ϵ : permittivity [F/m]

$\mathbf{B} = \mu \mathbf{H}$ μ : permeability [H/m]

$\mathbf{J} = \sigma \mathbf{E}$ σ : conductivity [S/m]



Vector & Scalar Potentials:

$\mathbf{E} = -j\omega \mathbf{A} - \nabla \Phi$

$\mathbf{B} = \nabla \times \mathbf{A}$

Lorentz Gauge:

$\nabla \cdot \mathbf{A} = -j\omega \epsilon \mu \Phi$



Wave Equations:

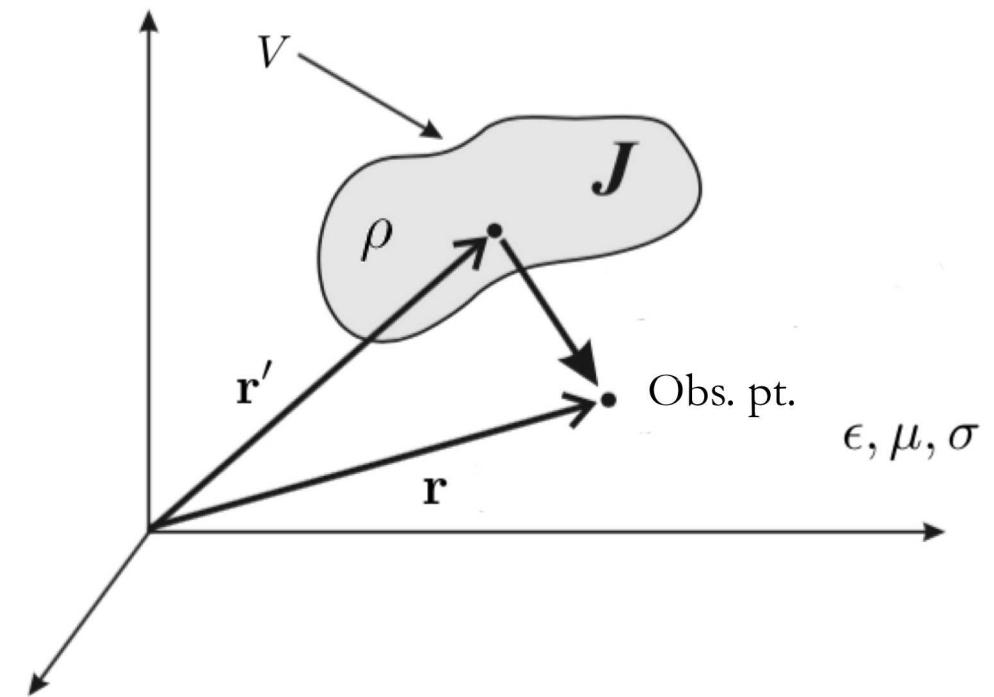
$$\nabla^2 \mathbf{A} + \omega^2 \mu \epsilon \mathbf{A} = -\mu \mathbf{J}$$

$$\nabla^2 \Phi + \omega^2 \mu \epsilon \Phi = \rho / \epsilon$$

For a linear homogeneous, unbounded medium:

$$\mathbf{A} = \int_V \mu \mathbf{J}(\mathbf{r}') g(\mathbf{r} | \mathbf{r}') d\mathbf{v}'$$

$$\Phi = - \int_V \frac{\rho(\mathbf{r}')}{\epsilon} g(\mathbf{r} | \mathbf{r}') d\mathbf{v}'$$



Free-Space Green's Function:

$$g(\mathbf{r} | \mathbf{r}') = \frac{e^{-jk|\mathbf{r} - \mathbf{r}'|}}{4\pi|\mathbf{r} - \mathbf{r}'|}$$

Radiation condition enforced

Integral Equations (Boundary Element Method – BEM)



Example of an electric field integral equation (EFIE) for metallic scatterer:

Enforcing the boundary condition at the surface:

$$\hat{\mathbf{n}} \times (\mathbf{E}_{\text{inc}} + \mathbf{E}_{\text{scat}}) = \mathbf{0}$$

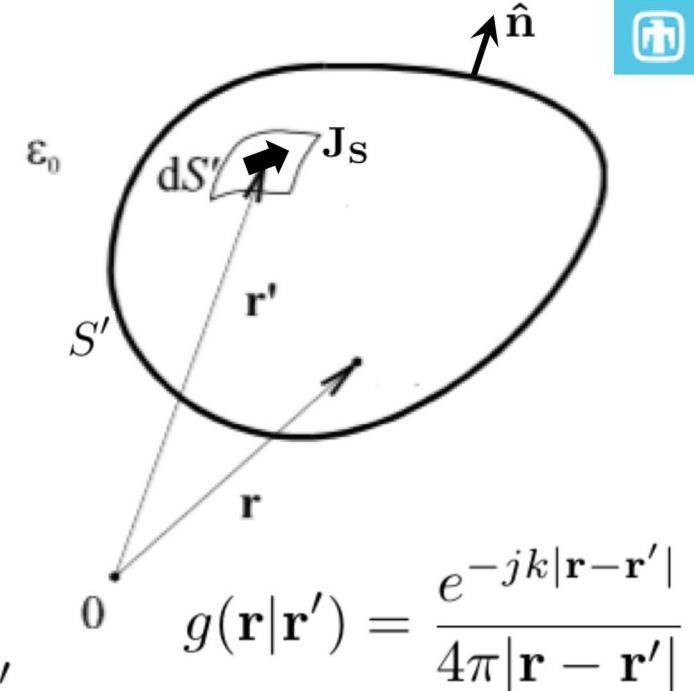
where,

$$\mathbf{E}_{\text{scat}} = -j\omega\mu \int_{S'} \left(\mathbf{J}_S(\mathbf{r}') g(\mathbf{r}|\mathbf{r}') + \frac{1}{\omega^2\mu\epsilon} \nabla' \cdot \mathbf{J}_S(\mathbf{r}') \nabla g(\mathbf{r}|\mathbf{r}') \right) dS'$$

results in the following integral equation:

$$\int_{S'} \hat{\mathbf{n}} \times \left(\mathbf{J}_S(\mathbf{r}') g(\mathbf{r}|\mathbf{r}') + \frac{1}{\omega^2\mu\epsilon} \nabla' \cdot \mathbf{J}_S(\mathbf{r}') \nabla g(\mathbf{r}|\mathbf{r}') \right) dS' = \frac{1}{j\omega\mu} \hat{\mathbf{n}} \times \mathbf{E}_{\text{inc}}$$

$$L \{ \mathbf{J}_S \} = \frac{1}{j\omega\mu} \hat{\mathbf{n}} \times \mathbf{E}_{\text{inc}}$$



$$g(\mathbf{r}|\mathbf{r}') = \frac{e^{-jk|\mathbf{r}-\mathbf{r}'|}}{4\pi|\mathbf{r}-\mathbf{r}'|}$$

Method of Moments (MoM)



Numerical solution of integral equation:

$$L \{ \mathbf{J}_S \} = \frac{1}{j\omega\mu} \hat{\mathbf{n}} \times \mathbf{E}_{\text{inc}}$$

Discretize the scatterer

Expand unknown in a set of basis functions.

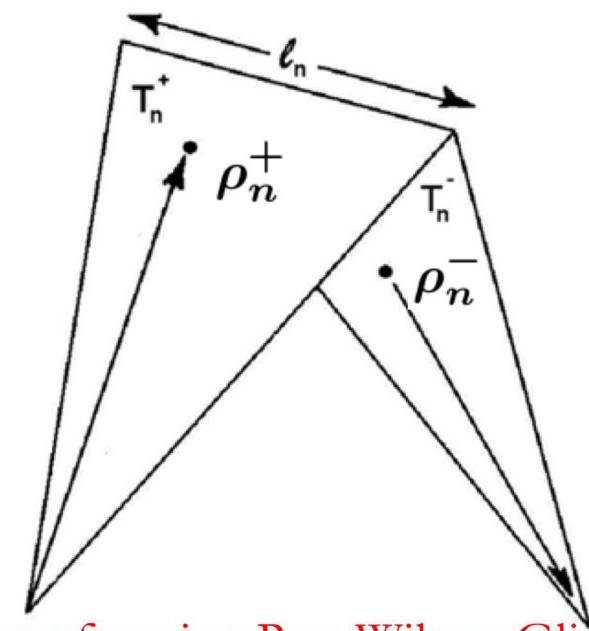
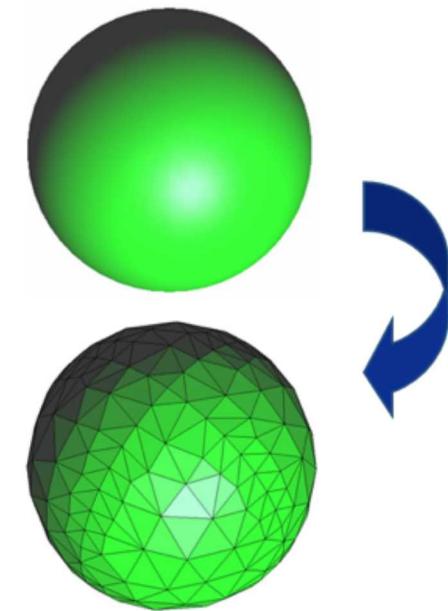
$$\mathbf{J}_S(\mathbf{r}) \approx \sum_n I_n \mathbf{f}_n(\mathbf{r})$$

$$\mathbf{f}_n(\mathbf{r}) = \begin{cases} \frac{\ell_n}{2A_n^+} \rho_n^+ & \mathbf{r} \in T_n^+ \\ \frac{\ell_n}{2A_n^-} \rho_n^- & \mathbf{r} \in T_n^- \\ 0 & \text{otherwise} \end{cases}$$

Test integral equation with basis functions.

$$\int_S \mathbf{f}_m \cdot L \{ \mathbf{J}_S \} ds = \frac{1}{j\omega\mu} \int_S \mathbf{f}_m \cdot (\hat{\mathbf{n}} \times \mathbf{E}_{\text{inc}}) ds$$

$$\bar{\mathbf{Z}} \mathbf{I} = \mathbf{V}$$



Divergence-conforming Rao-Wilton-Glisson (RWG) basis functions

Test with basis functions (Galerkin method)

Integral equation becomes a matrix equation:



$$Z_{N \times N} I_{N \times M} = V_{N \times M}$$

N is the total number of current unknowns

M is the number of independent excitations

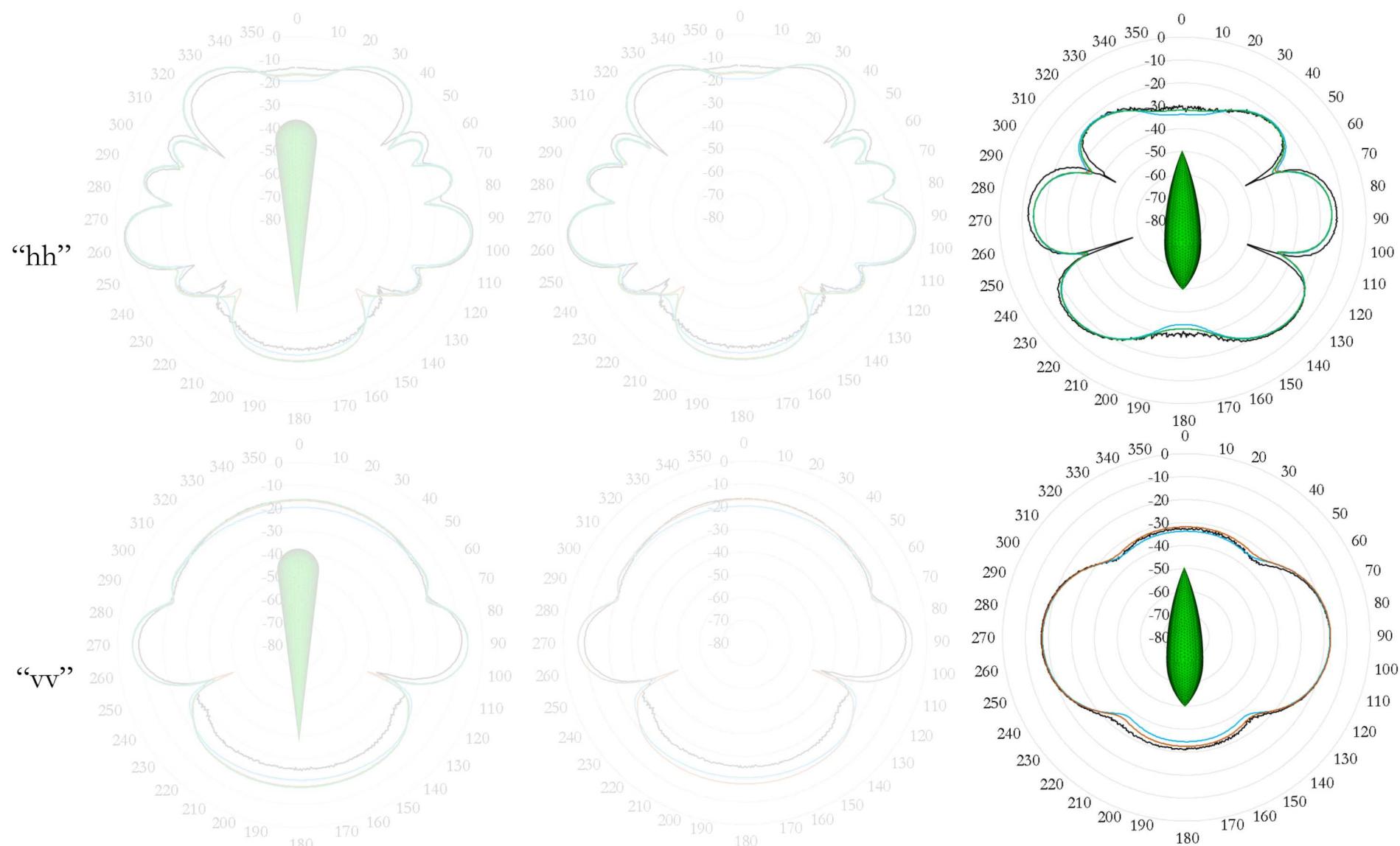
Note that the matrix Z is, in general, **dense** and **complex** valued.

- N^2 double complex matrix entries

Monostatic RCS results (1.57 GHz)



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Machine	Waterman
Platform	GPU
EMCC analysis	Gemma
Nodes	
Threads	

Machine	Mutrino
Platform	MIC
EMCC analysis	Gemma
Nodes	1
Threads	

Machine	Mutrino
Platform	CPU
EMCC analysis	Gemma
Nodes	
Threads	