

# **Microstructure Construction of Polycrystal Materials for Crystal Plasticity Simulations**

**Presenter: Joel Stinson**

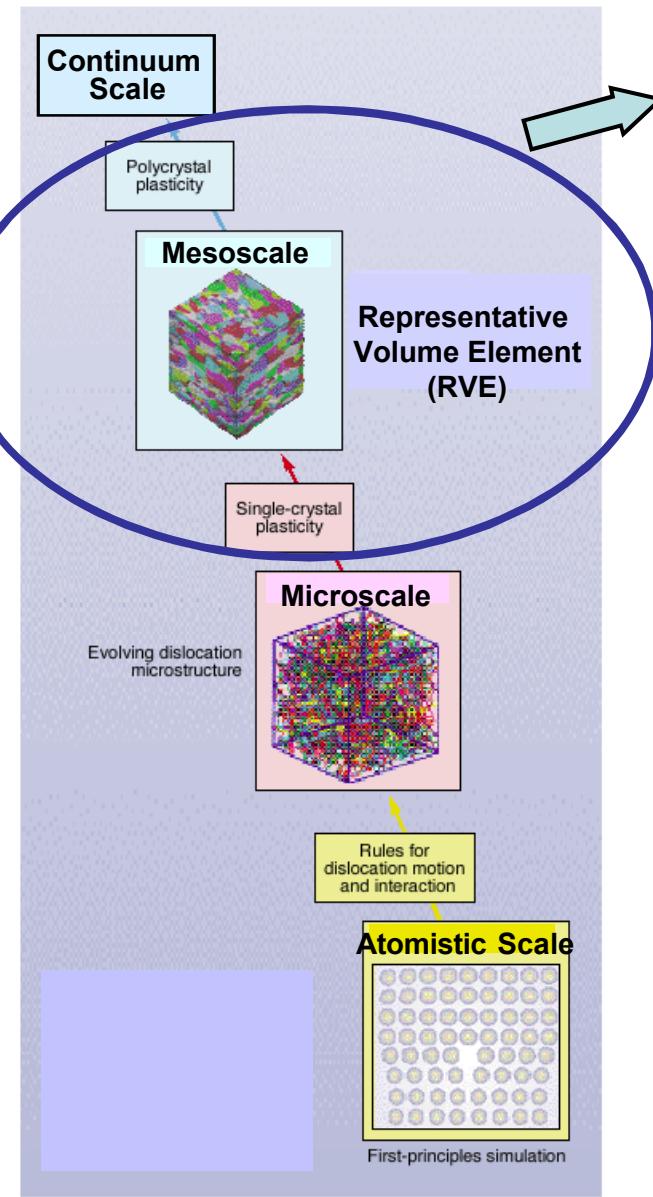
**Mentors: Esteban Marin**

**Doug Bammann**

# Outline

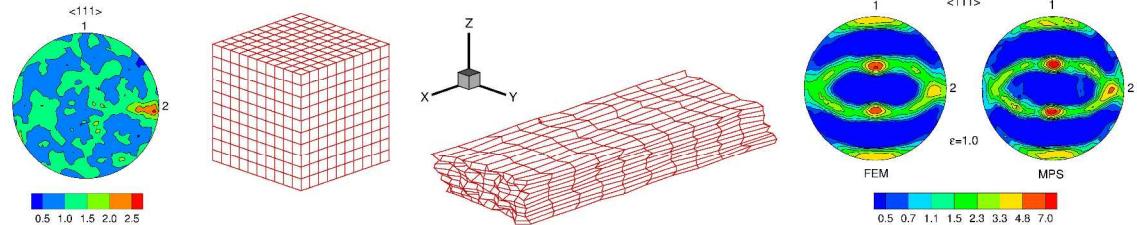
- Motivation
- Methods to construct digital microstructures
- Crystal plasticity model
- Some simulation results using digital microstructures
- Summary

# The Multiscale Approach to Materials Modeling



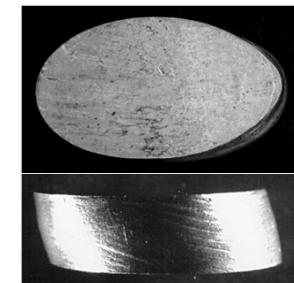
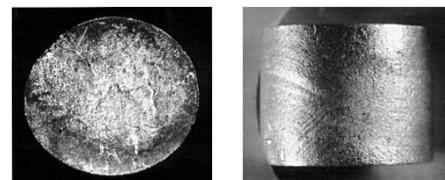
## Some mesoscale simulations using Crystal Plasticity Theory

### Plane Strain Compression of RVE:

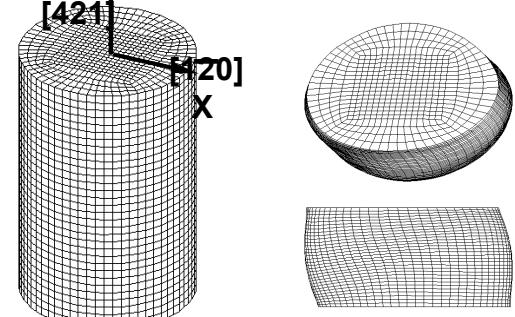


### Single Crystal Uniaxial Compression Tests:

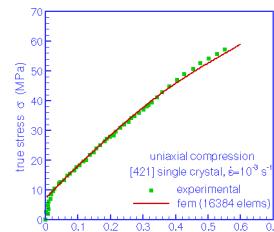
#### Experiments



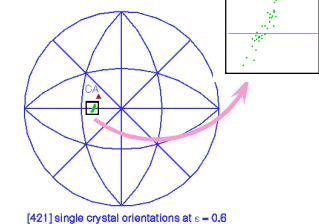
#### Simulations



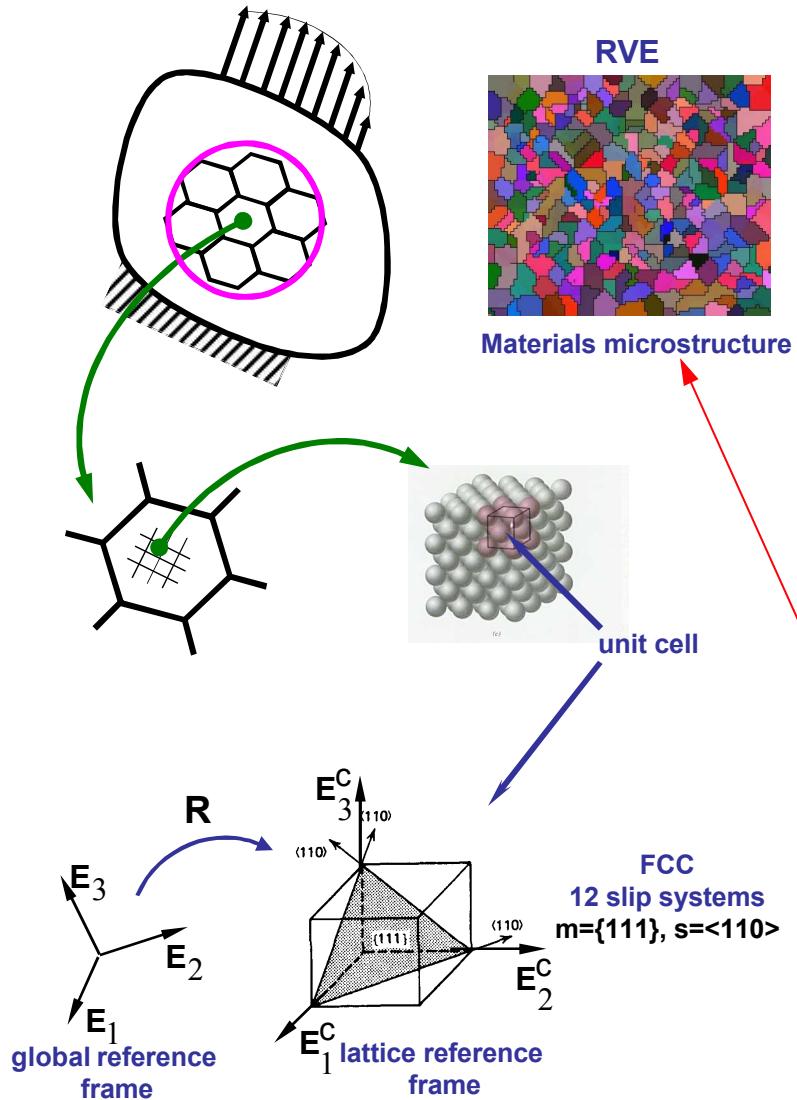
#### Stress Response



#### Crystal Orientations



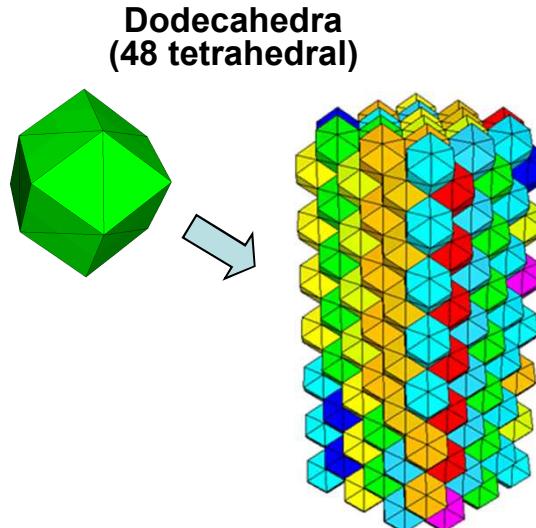
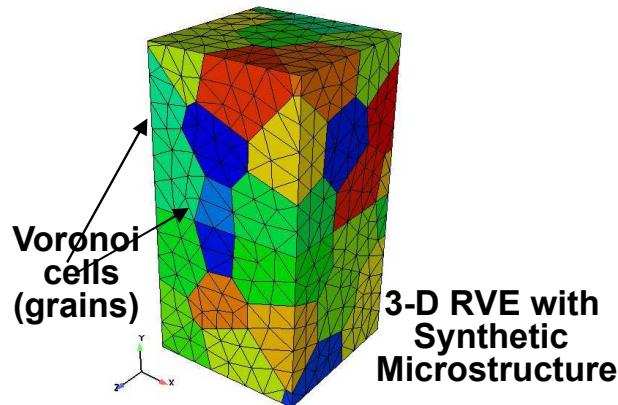
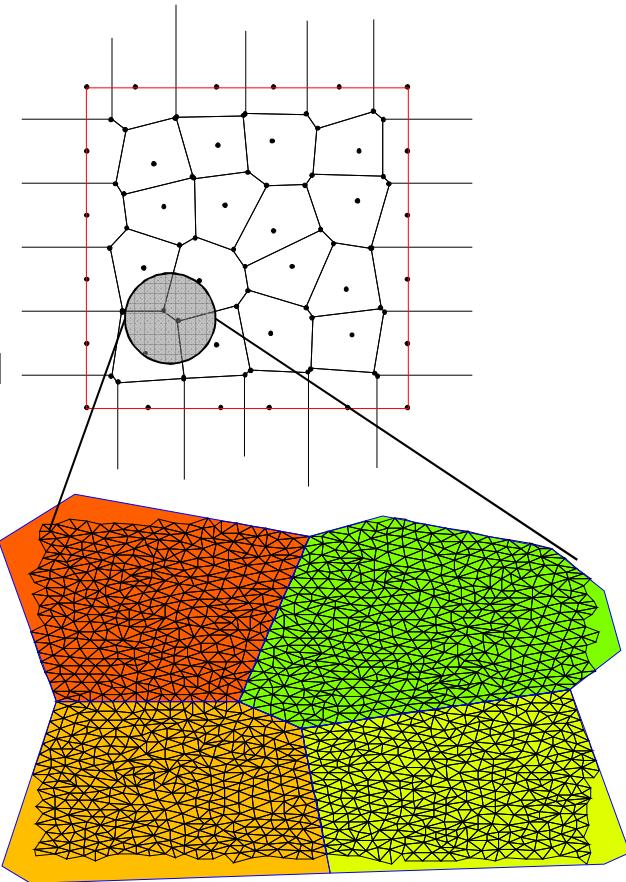
# Main Features of Crystal Plasticity as a Mesoscale Approach to Materials Modeling



# Some Methods To Create Digital Microstructures with Embedded Mesh

## Voronoi Tessellation

- Point set + **boundary** = grain structure
- Point set may be modified to produce microstructures with desired grain size and/or orientation distribution
- Each point produces a grain that can be assigned material properties and meshed to the desired resolution using existing meshing tools (e.g. Cubit)
- Robust enough for 2-D and 3-D microstructures

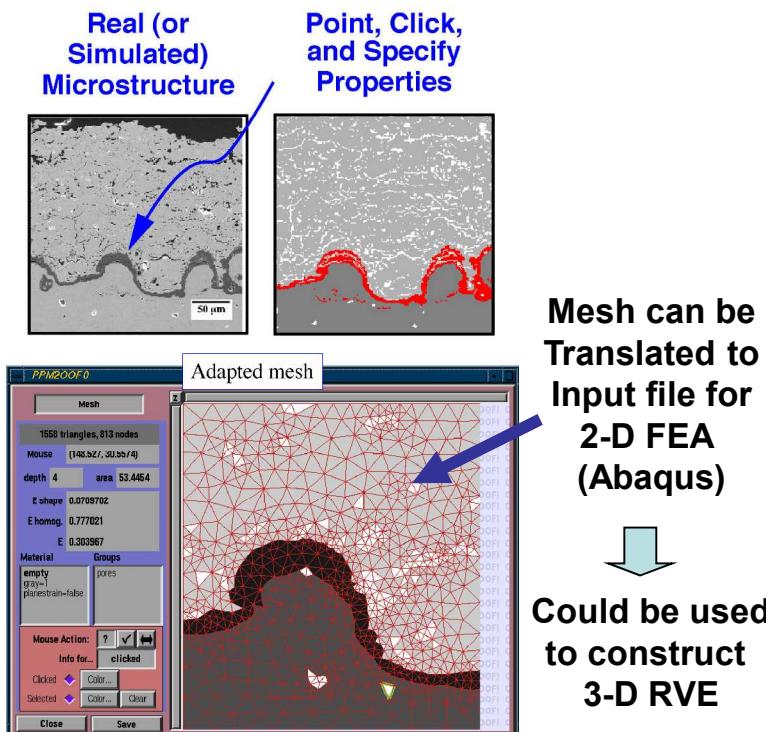
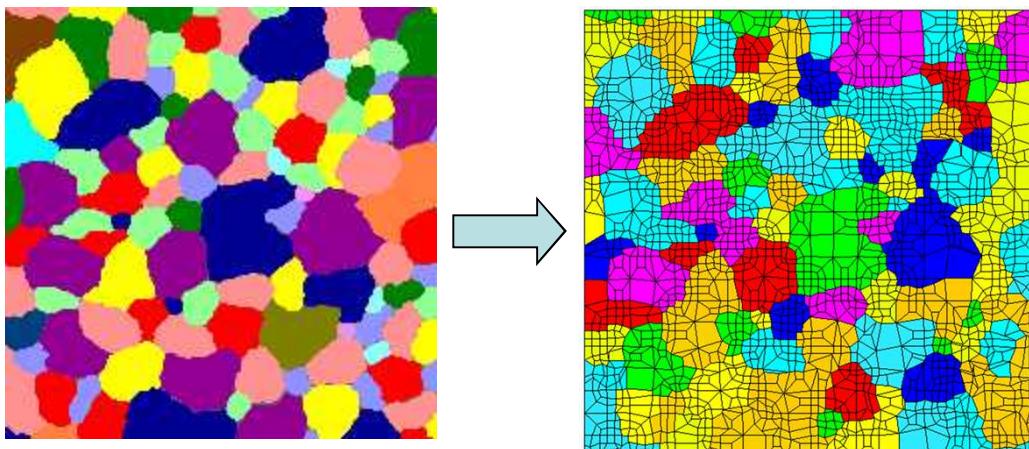


# Some Methods To Create Digital Microstructures with Embedded Mesh

## Digitizing Real Microstructures

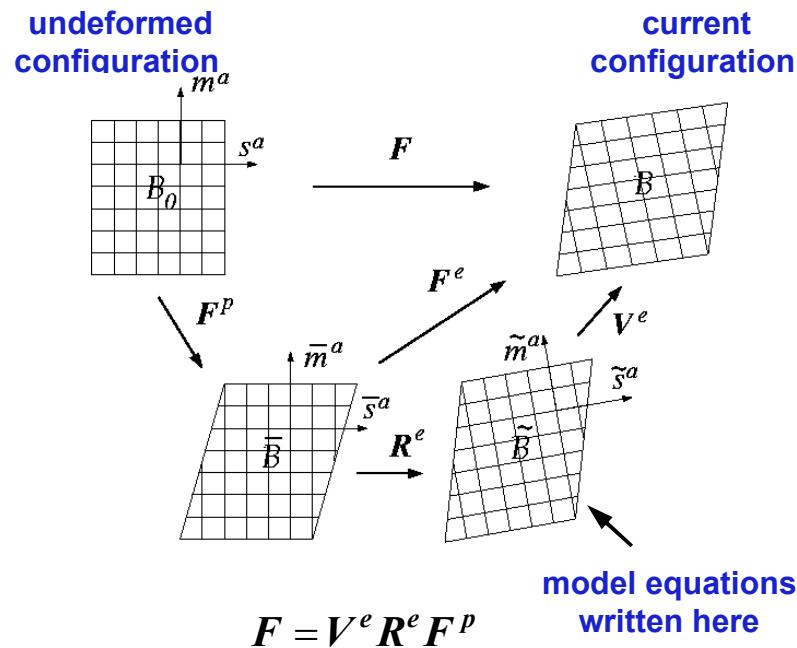
- Realistic microstructures can be produced using digitized images of the micrographs of real polycrystalline materials.
- **OOF2** : Object-Oriented Finite element analysis of **real** material microstructures:

Converts an image of a heterogeneous material into a **2-D finite element mesh** with **constitutive properties** specified by the user (2-D RVE).



(<http://www.ctcms.nist.gov/oof/>)

# Crystal Plasticity Model



Small elastic strains:

$$\tilde{\mathbf{E}}^e = \frac{1}{2} (V^{eT} V^e - I), \quad V^e = \mathbf{I} + \boldsymbol{\varepsilon}^e, \quad \|\boldsymbol{\varepsilon}^e\| \ll 1$$

Free Energy:

$$\tilde{\Psi} = \hat{\tilde{\Psi}}(\tilde{\mathbf{E}}^e, \boldsymbol{\varepsilon}_s^\alpha) = \frac{1}{2} \tilde{\mathbf{E}}^e : \tilde{\mathbf{C}}^e : \tilde{\mathbf{E}}^e + \frac{1}{2} \sum_{\alpha=1}^M \mu_{ef} c_\kappa \boldsymbol{\varepsilon}_s^\alpha \boldsymbol{\varepsilon}_s^\alpha$$

Kinematics:

$$\mathbf{d} = \boldsymbol{\varepsilon}^e + \tilde{\mathbf{D}}^p, \quad \overset{\nabla}{\boldsymbol{\varepsilon}^e} = \mathbf{\dot{\varepsilon}} + \boldsymbol{\varepsilon}^e \tilde{\boldsymbol{\Omega}}^e - \tilde{\boldsymbol{\Omega}}^e \boldsymbol{\varepsilon}^e$$

$$\mathbf{w} = -\text{skw}(\mathbf{\dot{\varepsilon}} \boldsymbol{\varepsilon}^e) + \tilde{\boldsymbol{\Omega}}^e + \tilde{\mathbf{W}}^p$$

Elasticity:

$$\boldsymbol{\tau} = \tilde{\mathbf{C}}^e : \boldsymbol{\varepsilon}^e \rightarrow \begin{cases} \text{dev} \boldsymbol{\tau} = \tilde{\mathbf{C}}_d^e : \text{dev} \boldsymbol{\varepsilon}^e + \tilde{\mathbf{H}}_{dv}^e \boldsymbol{\varepsilon}_{kk}^e \\ p_\tau = \tilde{\mathbf{H}}_{dv}^e : \text{dev} \boldsymbol{\varepsilon}^e + M_v^e \boldsymbol{\varepsilon}_{kk}^e \end{cases}$$

Plasticity:

$$\tilde{\mathbf{D}}^p = \sum_{\alpha=1}^M \mathbf{\dot{\varepsilon}}^\alpha \text{sym}(\tilde{\mathbf{Z}}^\alpha)$$

$$\tilde{\mathbf{W}}^p = \sum_{\alpha=1}^M \mathbf{\dot{\varepsilon}}^\alpha \text{skw}(\tilde{\mathbf{Z}}^\alpha)$$

$$\mathbf{\dot{\varepsilon}}^\alpha = \Phi(\boldsymbol{\tau}^\alpha, \boldsymbol{\kappa}_s^\alpha)$$

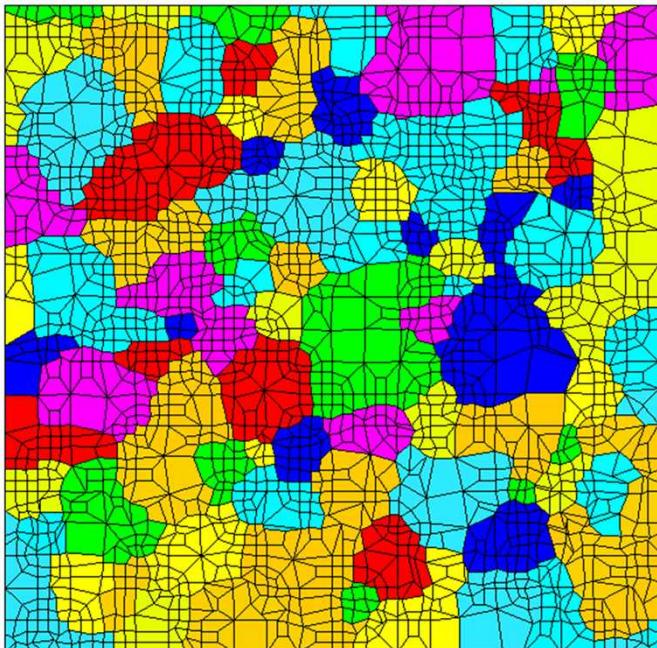
$$\boldsymbol{\tau}^\alpha = \boldsymbol{\tau} : \text{sym}(\tilde{\mathbf{Z}}^\alpha) = \boldsymbol{\tau} : \tilde{\mathbf{Z}}^\alpha$$

$$\mathbf{\dot{\varepsilon}}_s^\alpha = \Theta(\mathbf{\dot{\varepsilon}}^\alpha, \boldsymbol{\varepsilon}_s^\alpha), \quad \boldsymbol{\kappa}_s^\alpha = \mu_{ef} c_\kappa \boldsymbol{\varepsilon}_s^\alpha$$

where:

$$\tilde{\boldsymbol{\Omega}}^e = \mathbf{\dot{\varepsilon}}^e \mathbf{R}^{eT} \quad \tilde{\mathbf{D}}^p = \mathbf{R}^e \tilde{\mathbf{D}}^p \mathbf{R}^{eT} \quad \tilde{\mathbf{W}}^p = \mathbf{R}^e \tilde{\mathbf{W}}^p \mathbf{R}^{eT}$$

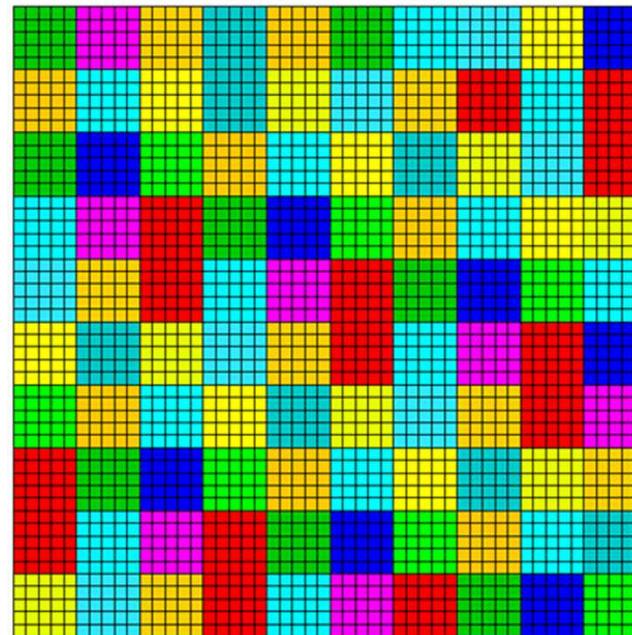
# 2-D Microstructures



**115 grains**

**2486 mesh elements**

**Constructed from an actual microstructure  
using OOF2 software**



**100 grains**

**2500 mesh elements**

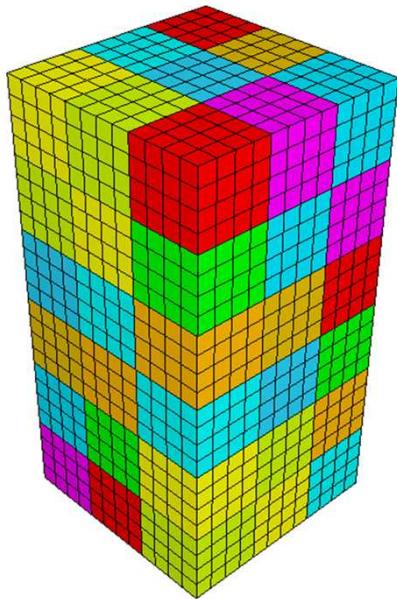
**Constructed using Abaqus CAE**

## 2-D Microstructures - Comparison

This slide will contain deformed meshes and stress strain curves (similar to slides 10-12) for the 2-D meshes if these results are obtained.

# 3-D Microstructures

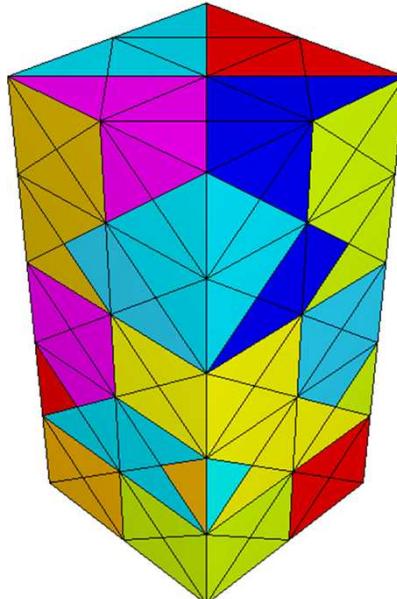
Brick Mesh



54 grains

3456 mesh elements

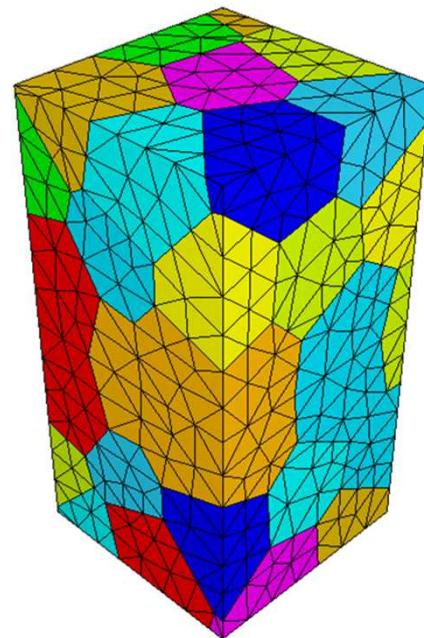
Dodecahedra Mesh



47 grains

480 mesh elements

Voronoi Mesh



44 grains

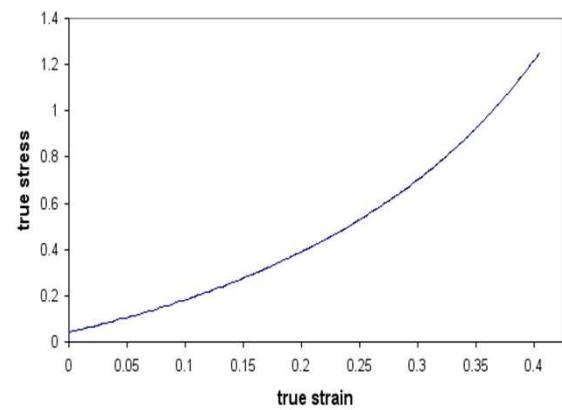
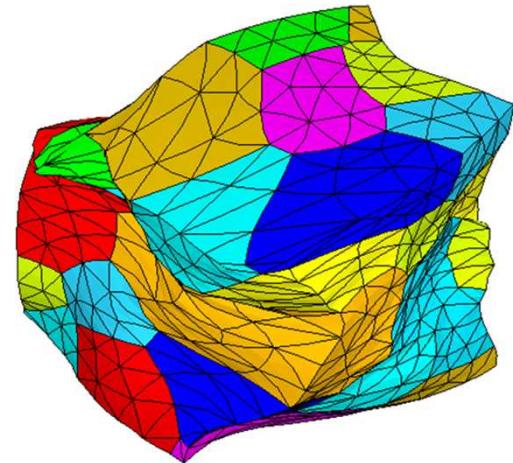
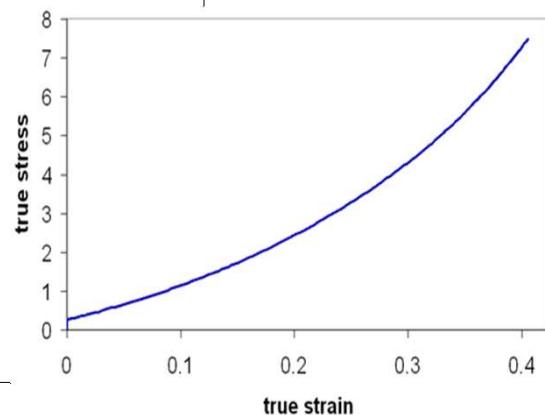
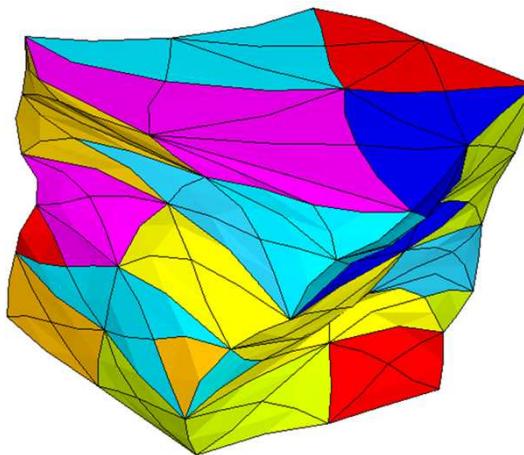
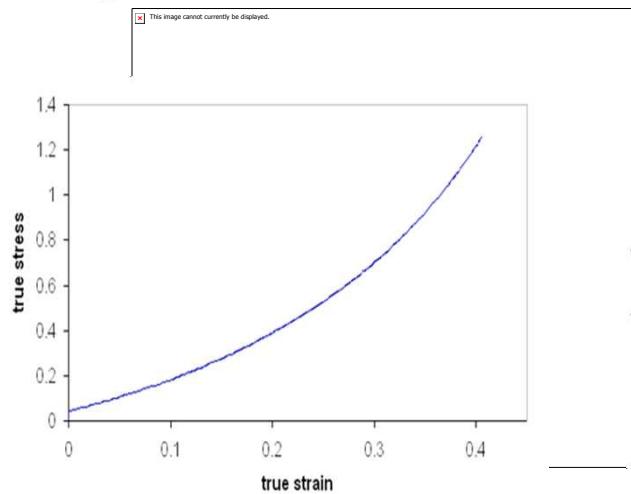
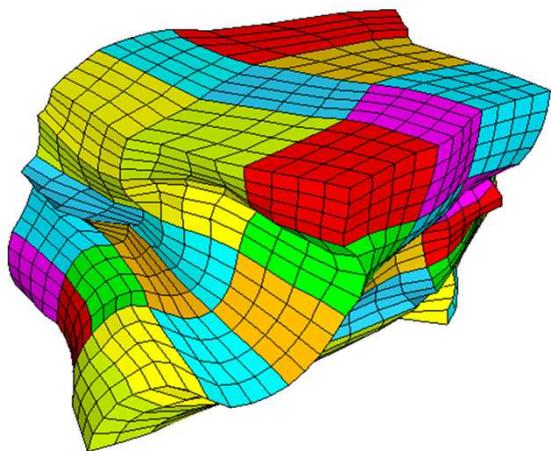
4500 mesh elements

- All meshes simulate materials with FCC crystal structure

- Brick mesh constructed in Abaqus CAE. Dodecahedra and Voronoi meshes were constructed using software from Cornell University.

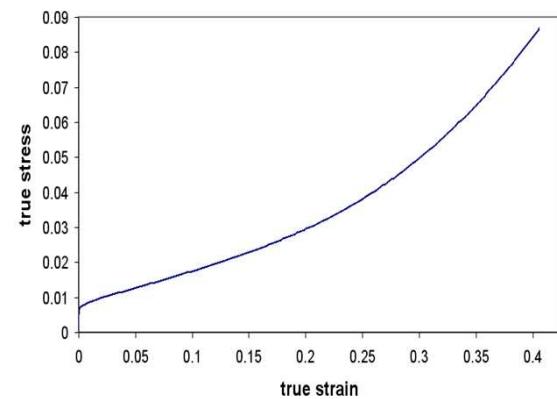
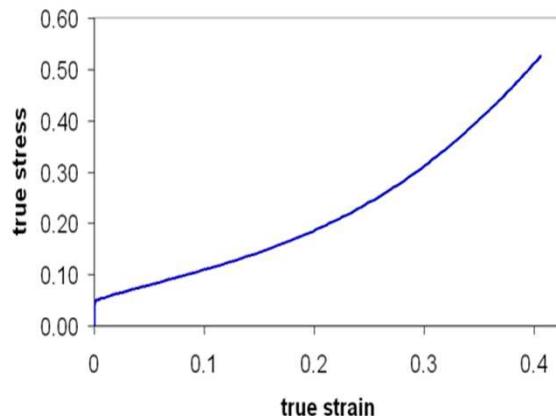
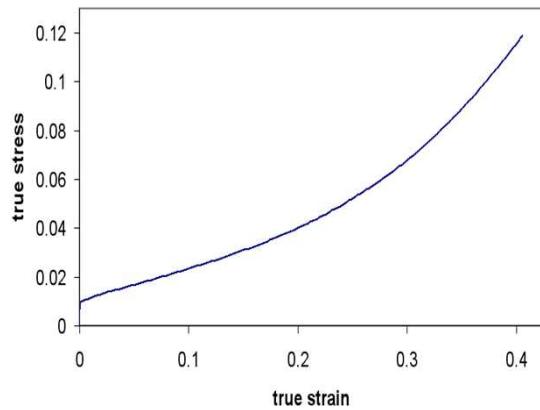
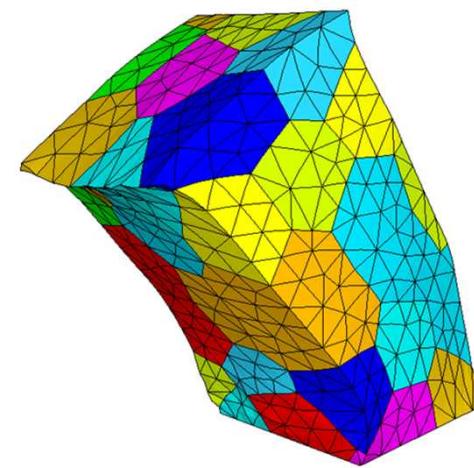
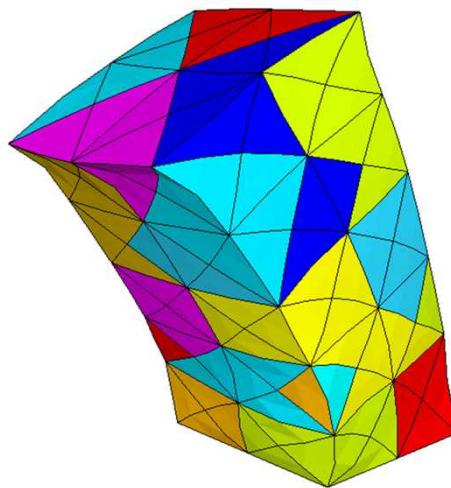
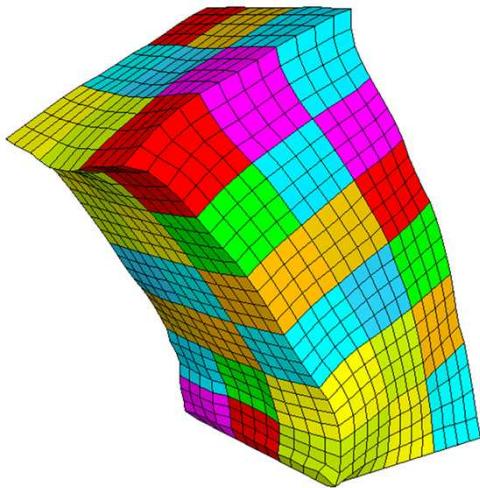
# 3-D Microstructures - Comparison

Compression Test at constant strain rate = -1



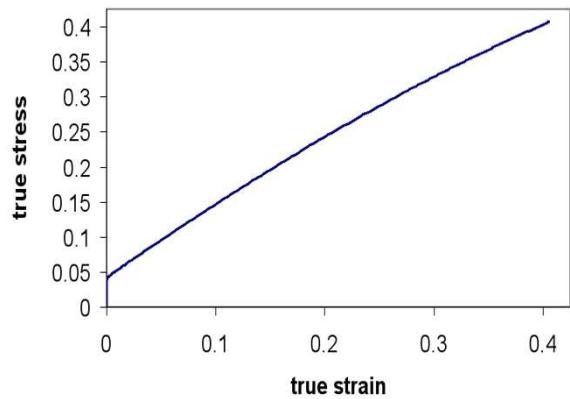
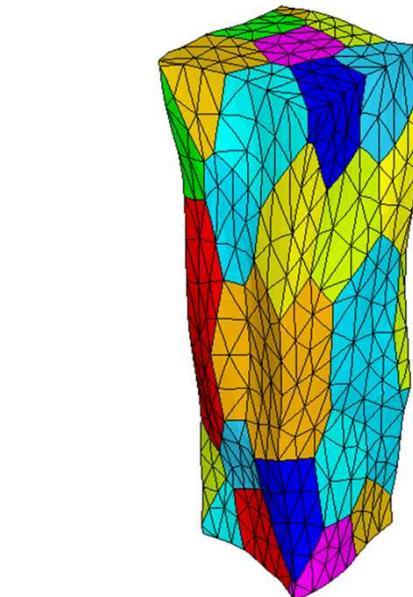
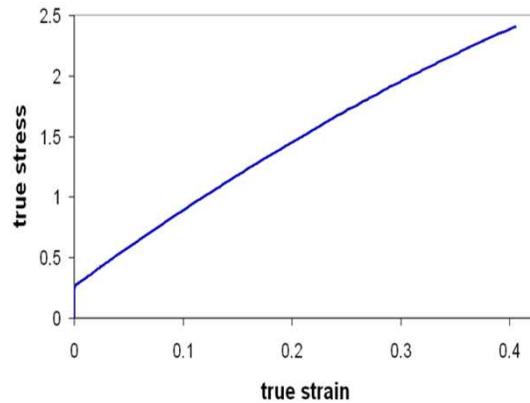
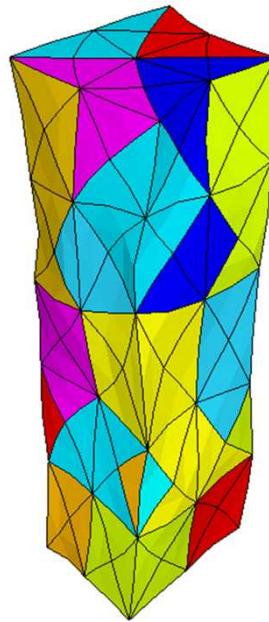
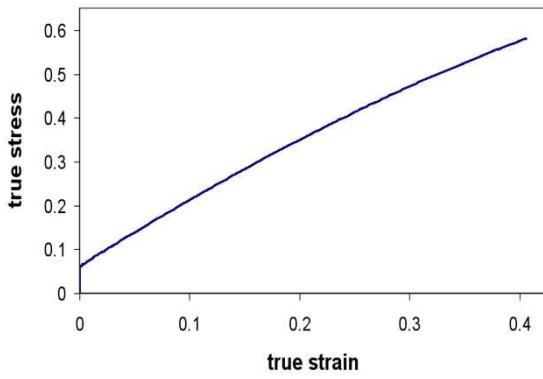
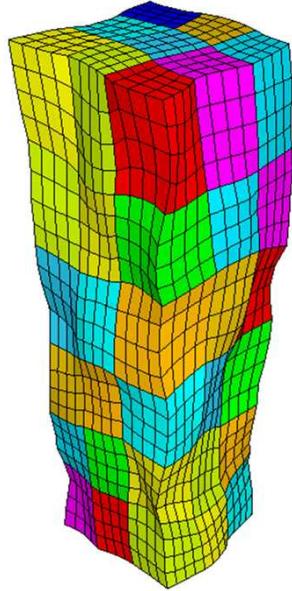
# 3-D Microstructures - Comparison

Shear loading test



# 3-D Microstructures - Comparison

Tensile load at constant strain rate = 1



# 3-D Microstructures - Results

This slide will contain a basic analysis of the deformed meshes and the stress strain curves presented in the previous slides.

# Summary

- **Microstructure** plays an important role in determining various properties in materials made of aggregates of crystalline grains. In particular, materials are intrinsically inhomogeneous on mesoscopic and microscopic scales due to the presence of grain boundaries.
- **Crystal plasticity theories** form the basis of grain-level (mesoscale) approaches to materials modeling using multi-scale strategies.
- The numerical simulation and modeling of polycrystalline materials using these theories will be more predictive if the initial microstructure configuration used resembles realistic grain structures.
- This work is the initial step towards the use of available geometric tools to generate and use **digital microstructures** in our crystal plasticity simulations.