

Time-domain boundary conditions in atmospheric acoustics

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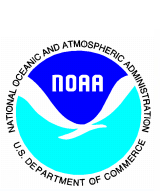
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Outline



1. Introduction.
2. Time-domain boundary conditions (TDBC) for the modified Zwikker-Kosten (ZK) impedance model.
3. Causal TDBC for any impedance model.
4. Conclusions.

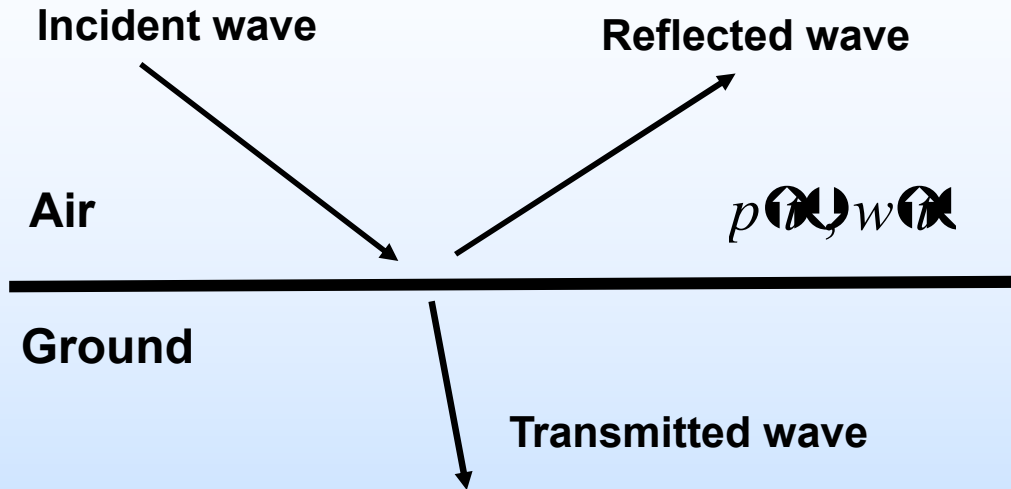


1. Introduction



- **FDTD simulations of outdoor sound propagation is a very promising technique.**
- **A challenging problem in FDTD is formulation of TDBC at the ground surface.**
- **The goal of this paper: Development of numerically efficient and causal TDBC.**

2. TDBC for modified ZK model



BC for a locally reacting surface:

$$P(\mathbf{r}, \omega) = Z(\mathbf{r}, \omega) W(\mathbf{r}, \omega)$$

Fourier transform:

$$Z(\mathbf{r}, \omega) = \frac{1}{2\gamma} \left(\frac{\partial p}{\partial z} \right)_{z=0} e^{-i\mathbf{r} \cdot \nabla} Z(\mathbf{r}, \omega)$$

TDBC:

$$p(\mathbf{r}, t) = \int_{-\infty}^{\infty} \tilde{p}(\mathbf{r}, \omega) e^{-i\omega t} d\omega$$

- Convolution complicates TDBC.
- Some TDBC are noncausal (e.g. Delany and Bazley model).
- The goal of the paper is to make TDBC numerically efficient and causal.

2. TDBC for modified ZK model

ZK impedance model: $Z_{\text{ZK}} = Z_0 \sqrt{\frac{1 + i\omega\tau}{1 - i\omega\tau}}$

Two parameters: Z_0 and τ

Modified ZK impedance model:

$$Z_{\text{mod}} = \frac{Z_0 q}{\phi}, \quad \tau = \frac{q^2 \tau_0}{\phi}$$

Here, tortuosity q , porosity ϕ , flow resistivity τ_0 , etc.

The modified ZK impedance model is almost indistinguishable from more realistic models characterized by more parameters. This comes with a price: Inside the ground the modified ZK model does not work.

2. TDBC for modified ZK model

Causal TDBC:

$$p(t) = Z \left[w(t) \otimes \frac{1}{\sigma} \int_0^t w(\tau) f(\tau) d\tau \right]$$

Here, the response function $f(t) = \frac{\exp(-t/2)}{2} \mathcal{H}(t)$

Slowly decaying function: $f(t) \propto t^{-1/2}$ for $t \gg 1$

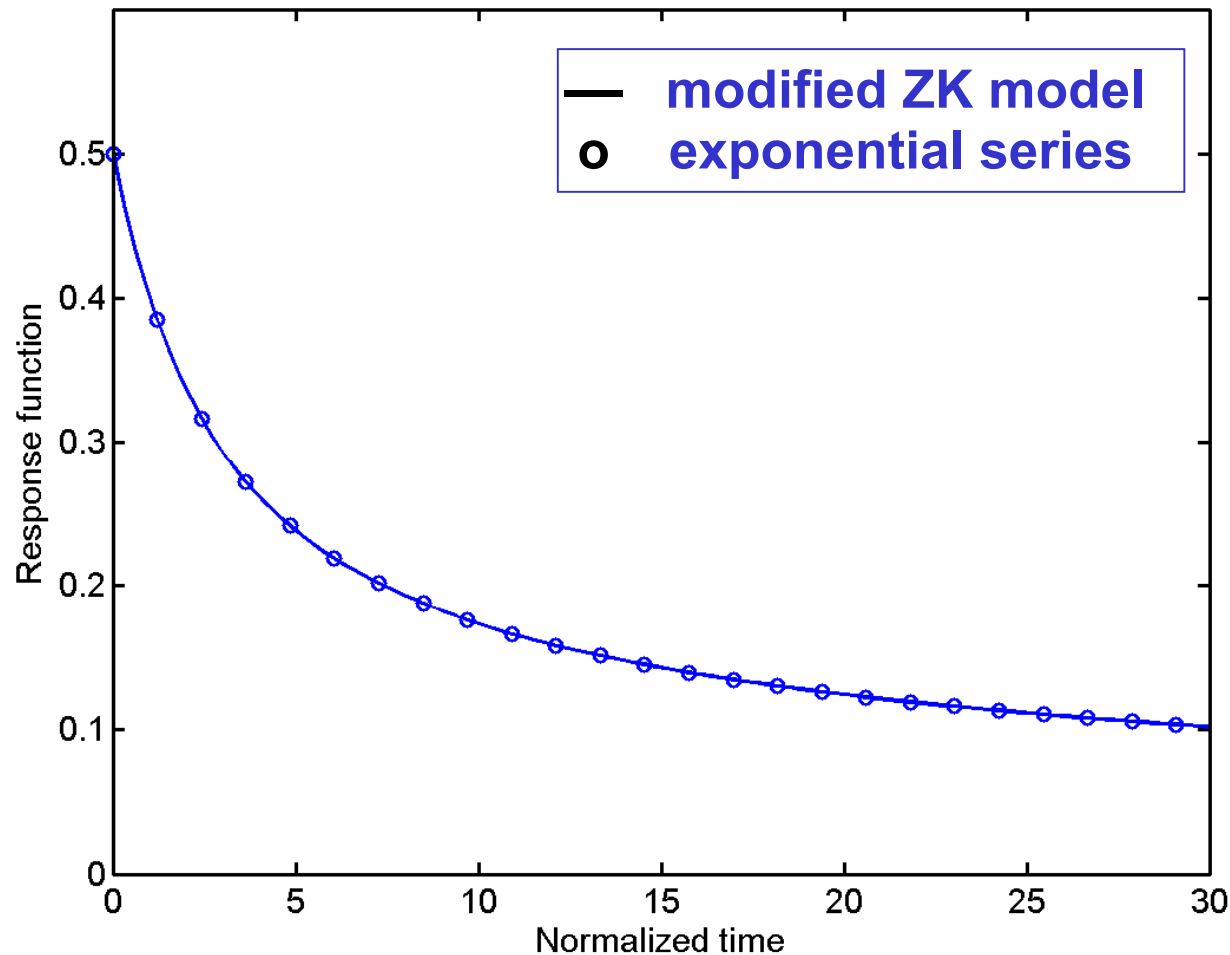
Hundreds of time steps need to be retained.

Approximation of $f(t)$ with an exponential series:

$$f(t) \approx \sum_{k=1}^K a_k e^{-\lambda_k t}$$

k	a_k, ZK	λ_k, ZK
1	0.55590	0.57559
2	0.13751	0.01157
3	0.48279	0.63507
4	0.14898	0.11357
5	0.28696	0.41958
6	0.00037	2.63762

2. TDBC for modified ZK model



2. TDBC for modified ZK model

TDBC:

$$p(t) = Z \left[w_k^K \otimes_0^{\infty} w(t) a_k e^{-\int_0^t \frac{dt}{\tau}} \right]$$

Discrete time steps $t = t_n = n\tau$, $n = 1, 2, \dots$.

The auxiliary variable I_k^n is the value of the integral.

$$I_k^n = e^{-\tau/\tau} I_k^{n-1} + \tau a_k w(t_n)$$

Final TDBC:

$$w(t_n) = \frac{1}{1 + \sum_{k=1}^K a_k \tau} \left[\frac{p(t_n)}{Z} \otimes_{k=1}^K e^{-\tau/\tau} I_k^{n-1} \right].$$

Only one time step need to be retained where 6 values of I_k^n are updated.

2. TDBC for modified ZK model

Numerical experiment:

● Sound source

Air

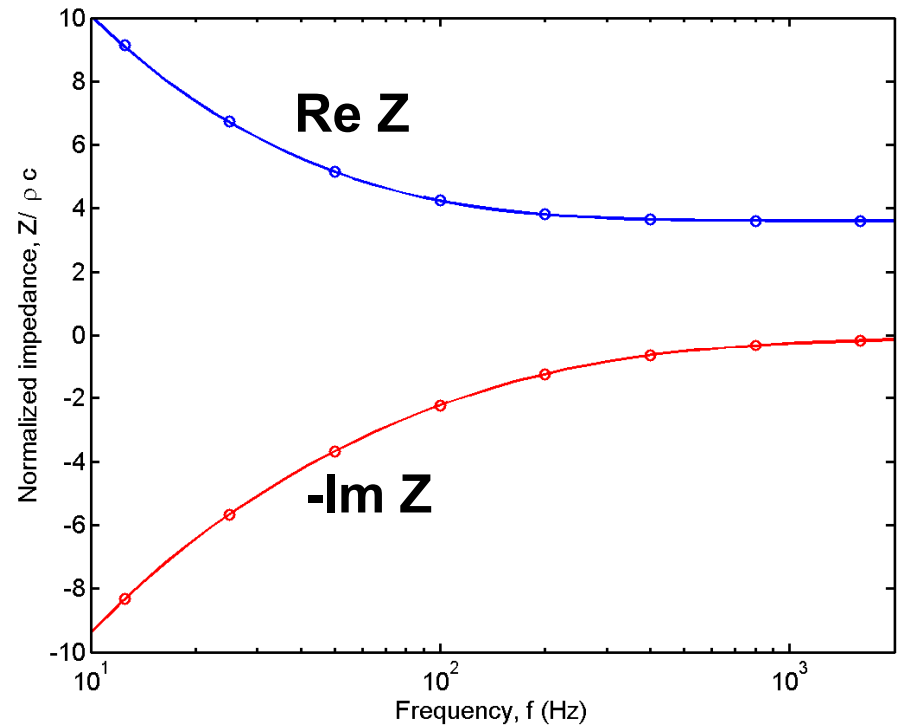
TDBC

Ground

The porous material parameters:
 $\rho_0 = 10^4 \text{ Pa s m}^{-2}$, $\sigma = 0.5$, $q = 1.8$.

The source frequency:
 $12.5 \text{ Hz} \leq f \leq 8000 \text{ Hz}$.

$0.086 \leq \theta \leq 11$



— modified ZK model
 o numerical calculations

3. Causal and numerically efficient TDBC for any impedance

The main idea: Using a Pade approximation of the impedance in the frequency domain and fractional derivatives, a causal TDBC is derived.

First example: The modified ZK impedance model.

Let $x = \sqrt{Z_0} \frac{d}{dt} \psi$. Then using a Pade approximation:

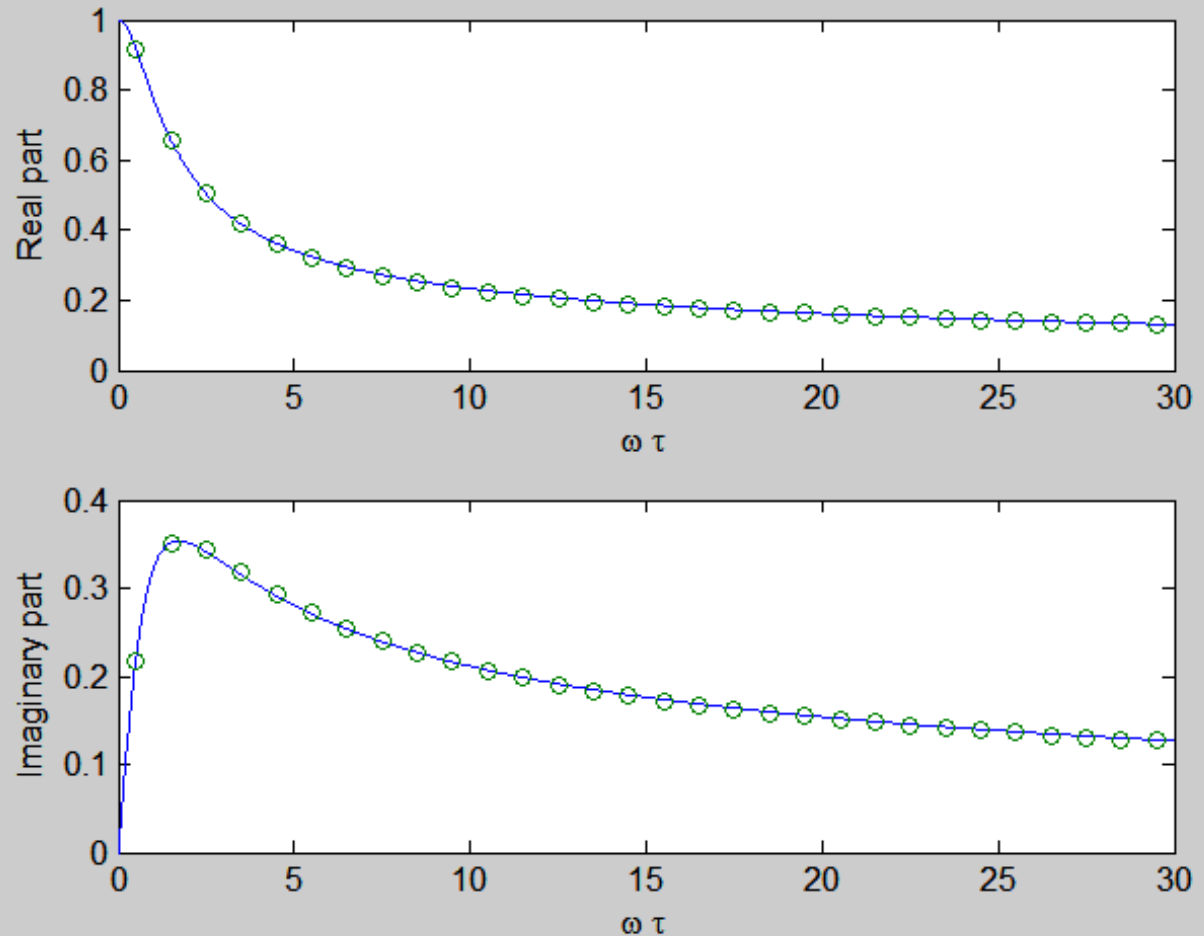
$$\frac{1}{Z} \approx \frac{x}{Z_0} \frac{1}{\sqrt{1 - x^2}} \approx \frac{x}{Z_0} \frac{1 - a_2 x^2 + a_3 x^4}{1 - b_1 x^2 + b_2 x^4 - b_3 x^6}.$$

Coefficients:

$$a_2 \approx b_1 \approx 0.992, \quad a_3 \approx b_3 \approx 0.566, \quad b_2 \approx 1.066.$$

3. Causal TDBC for any impedance

$\frac{1}{\sqrt{1+x^2}}$
 o Pade approximation



3. Causal TDBC for any impedance

BC in frequency domain: $P(\omega) = Z(\omega)W(\omega)$

Causal TDBC:

$$\frac{1}{Z(s)} \left[1 - a_3 \frac{d}{dt} - a_2 \frac{d^2}{dt^2} - a_1 \frac{d^3}{dt^3} \right] p(t) = \left[b_1 - b_3 \frac{d}{dt} - \left(\frac{d^{1/2}}{dt^{1/2}} - b_2 \frac{d}{dt} \right) \frac{d^{1/2}}{dt^{1/2}} \right] w(t)$$

Fractional derivative: $D^{\alpha} p(t) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dt} \int_0^t \frac{p(\tau)}{(t-\tau)^{\alpha}} d\tau$

Grunwald formula: $D^{\alpha} p(t) = \lim_{m \rightarrow \infty} \frac{(-1)^m}{\Gamma(-\alpha)} \frac{d^m}{dt^m} \frac{t^{\alpha-1}}{m^{\alpha-1}} p(t - \frac{t}{m})$

For $m \rightarrow \infty$, $\frac{d^m}{dt^m} \frac{t^{\alpha-1}}{m^{\alpha-1}} \approx m^{\alpha-1} t^{\alpha-1}$ (parallels to $f(t) \approx m^{\alpha-1}$).

3. Causal TDBC for any impedance

Liebler et al. (2004):

$$\frac{m(t)/2}{m(t)} \diamond \left(\frac{K}{k} \right) b_k e^{i\omega_k t}.$$

Following the same procedure as earlier we define the auxiliary variable:

$$w_k^n(t) = b_k e^{i\omega_k t} w(t) \sqrt{t/\delta t}$$

It can be shown that

$$w_k^n(t) = b_k w(t) \sqrt{t/\delta t} e^{i\omega_k t}.$$

TDBC:

$$w(t_n) = F_F(t_n) w_k^n(t_n) \rightarrow$$

Thus, only K auxiliary functions w_k^n must be stored and updated at every time step.

3. Causal TDBC for any impedance

Second example: The Attenborough impedance model.

Let $x = \sqrt{\frac{Z}{Z_0}}$. Then using a Pade approximation:

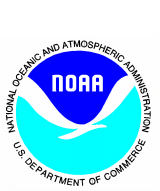
Chandler-Wilde, Horoshenkov, JASA (1995):

$$\frac{1}{Z} = \frac{x}{Z_0} \frac{1 - a_2 x^2 - a_3 x^3 - a_4 x^4}{1 - b_1 x - b_2 x^2 - b_3 x^3 - b_4 x^4}$$

Causal TDBC:

$$\frac{1}{Z_0} \left[1 - a_3 \frac{d}{dt} - \left(a_2 \frac{d}{dt} - a_4 \frac{d^2}{dt^2} \right) D^{-1/2} \right] p$$

$$= \left[b_1 - b_3 \frac{d}{dt} - \left(D^{1/2} - b_2 \frac{d}{dt} - b_4 \frac{d^2}{dt^2} \right) D^{-1/2} \right] w$$



4. Conclusions



1. For the modified ZK impedance model, a numerically efficient algorithm for implementing TDBC is developed.
2. For any impedance model, using a Pade approximation of the impedance in the frequency domain, a causal TDBC can be derived. An efficient algorithm for numerical implementation of TDBC is then developed.

