



Time-domain boundary conditions in atmospheric acoustics

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Outline



- 1. Introduction.**
- 2. Time-domain boundary conditions (TDBC)
for the modified Zwikker-Kosten (ZK)
impedance model.**
- 3. Causal TDBC for any impedance model.**
- 4. Conclusions.**

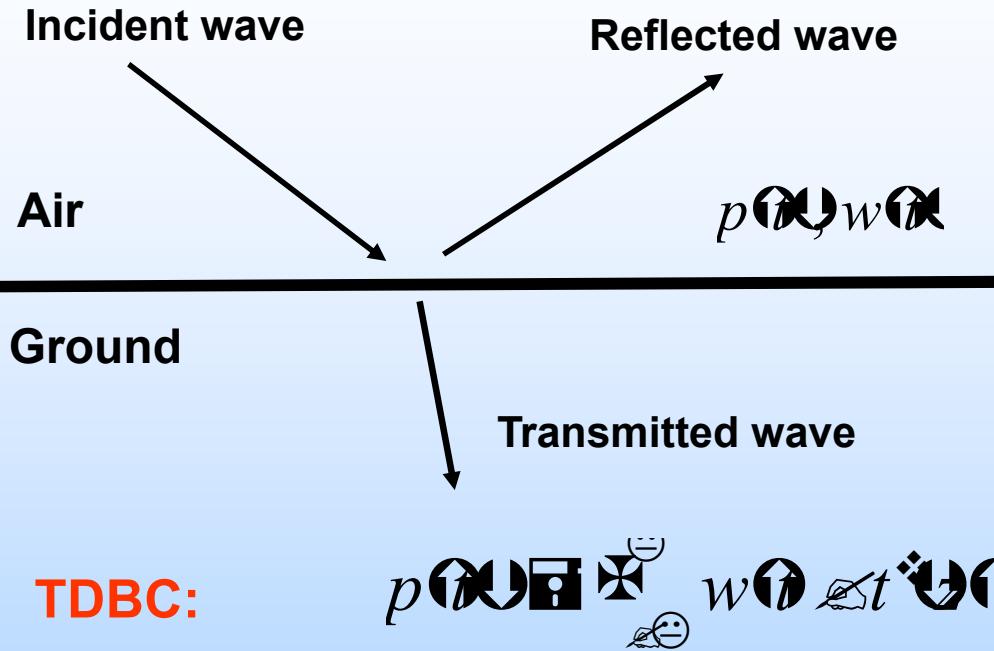


1. Introduction



- **FDTD simulations of outdoor sound propagation is a very promising technique.**
- **A challenging problem in FDTD is formulation of TDBC at the ground surface.**
- **The goal of this paper: Development of numerically efficient and causal TDBC.**

2. TDBC for modified ZK model



BC for a locally reacting surface:

$$P(t, w, \alpha) \otimes Z(t, w, \alpha)$$

Fourier transform:

$$Z(t, w, \alpha) \otimes \frac{1}{2} \gamma \otimes e^{i \gamma_0 t} Z(t, w, \alpha)$$

- Convolution complicates TDBC.
- Some TDBC are noncausal (e.g. Delany and Bazley model).
- The goal of the paper is to make TDBC numerically efficient and causal.

2. TDBC for modified ZK model

ZK impedance model:

$$Z_{\text{ZK}} = Z_{\odot} \sqrt{\frac{1 + \eta_{\odot}}{\eta_{\odot}}}$$

Two parameters: Z_{\odot} and η_{\odot}

Modified ZK impedance model:

$$Z_{\odot} = \frac{q}{\eta_{\odot}}, \quad \eta_{\odot} = \frac{q^2 \phi}{\theta}$$

Here, tortuosity q , porosity ϕ , flow resistivity θ , etc.

The modified ZK impedance model is almost indistinguishable from more realistic models characterized by more parameters. This comes with a price: Inside the ground the modified ZK model does not work.

2. TDBC for modified ZK model

Causal TDBC:

$$p(t) = Z \left[w(t) - \frac{1}{2} \int_0^t w(t') dt' \right]$$

Here, the response function

$$f(t) = \frac{\exp(\Omega t/2)}{2} \int_0^t \int_0^{t'} dt''$$

Slowly decaying function: $f(t) \propto t^{-1/2}$ for $t \gg 1$

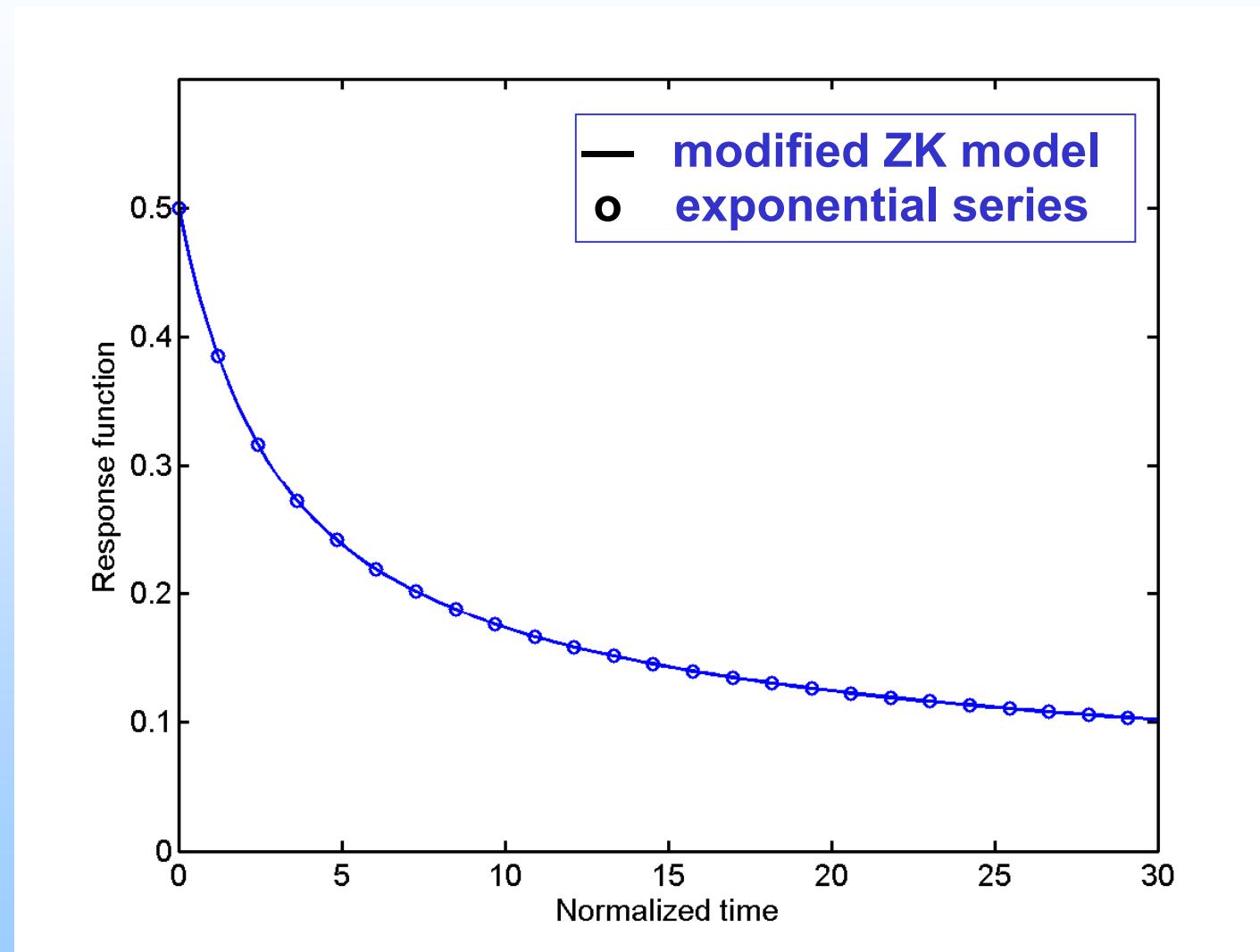
Hundreds of time steps need to be retained.

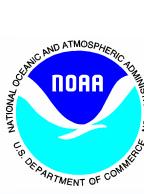
Approximation of $f(t)$ with an exponential series:

$$f(t) \approx \sum_{k=0}^K a_k e^{-\Omega_k t}$$

k	a_k, ZK	Ω_k, ZK
1	0.55590	0.57559
2	0.13751	0.01157
3	0.48279	0.63507
4	0.14898	0.11357
5	0.28696	0.41958
6	0.00037	2.63762

2. TDBC for modified ZK model





2. TDBC for modified ZK model



TDYC:

$$p \otimes Z \otimes \left[w \otimes \begin{matrix} K \\ k \end{matrix} \otimes \begin{matrix} \oplus \\ 0 \end{matrix} w \otimes t \otimes a_k e^{\otimes k t \otimes \partial \frac{dt}{\partial t}} \right]$$

Discrete time steps $t \in t_n \in \mathbb{N} \setminus t, \quad n \in \{1, 2, \dots\}.$

The auxiliary variable \mathfrak{p}_k^n is the value of the integral.

$\mathbf{p}_k \mathbf{n}_k \mathbf{I}_k e^{\mathbf{i} \omega_k \mathbf{v} t / \delta_k} \mathbf{n}_k \mathbf{I}_k \mathbf{a}_k w \mathbf{I}_n \mathbf{v} t / \delta$

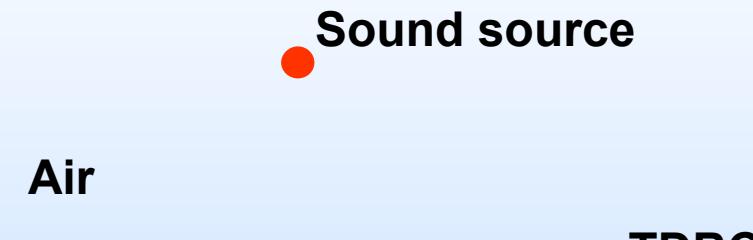
Final TDBC:

$$w \mathbf{1}_{t_n} \mathbf{0} \frac{1}{\frac{1}{\mathbf{1} \otimes \mathbf{1}} \frac{K}{a_k \sqrt{t}} \left[\frac{p \mathbf{1}_{t_n} \mathbf{0}}{Z \otimes} \mathbf{1} \otimes \mathbf{1}^K k \mathbf{0} e^{\mathbf{1} \otimes \mathbf{1} \otimes \sqrt{t} \mathbf{1} \otimes \mathbf{1}^K} \right]}.$$

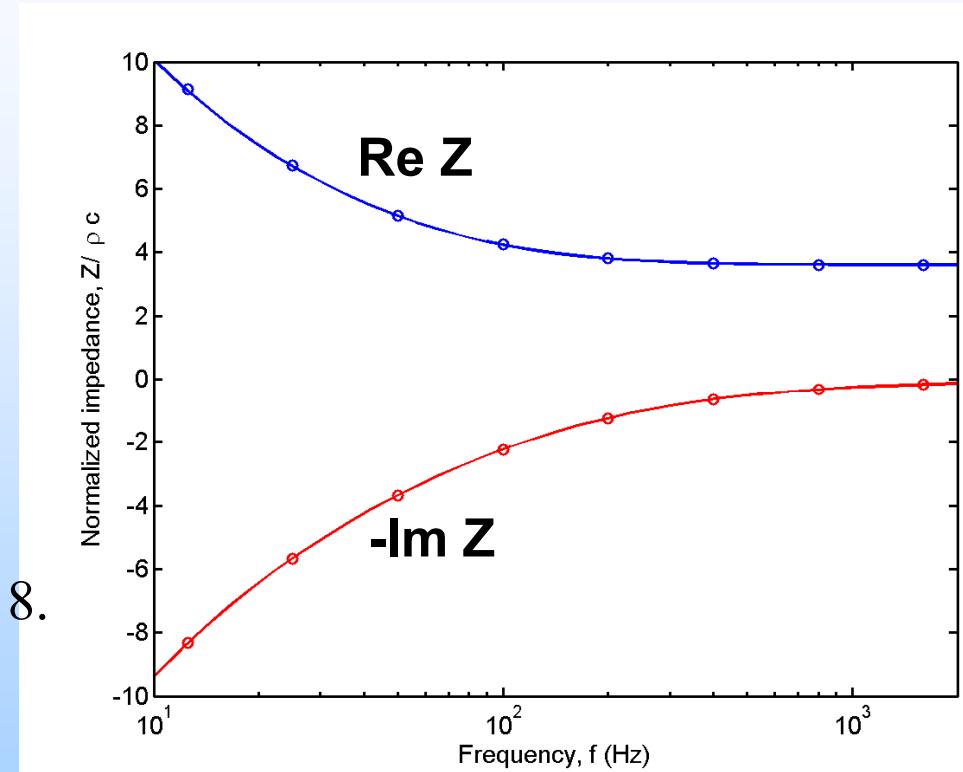
Only one time step need to be retained where 6 values of $\frac{n}{k}$ are updated.

2. TDBC for modified ZK model

Numerical experiment:



The porous material parameters:
 $\rho = 10^4 \text{ Pa s m}^{-2}$, $\beta = 0.5$, $q = 1.8$.
The source frequency:
 $12.5 \text{ Hz} \leq f \leq 8000 \text{ Hz}$.
 $0.086 \leq \eta \leq 11$



— modified ZK model
○ numerical calculations



3. Causal and numerically efficient TDBC for any impedance



The main idea: Using a Pade approximation of the impedance in the frequency domain and fractional derivatives, a causal TDBC is derived.

First example: The modified ZK impedance model.

Let $x = \sqrt{\omega/\omega_0}$. Then using a Pade approximation:

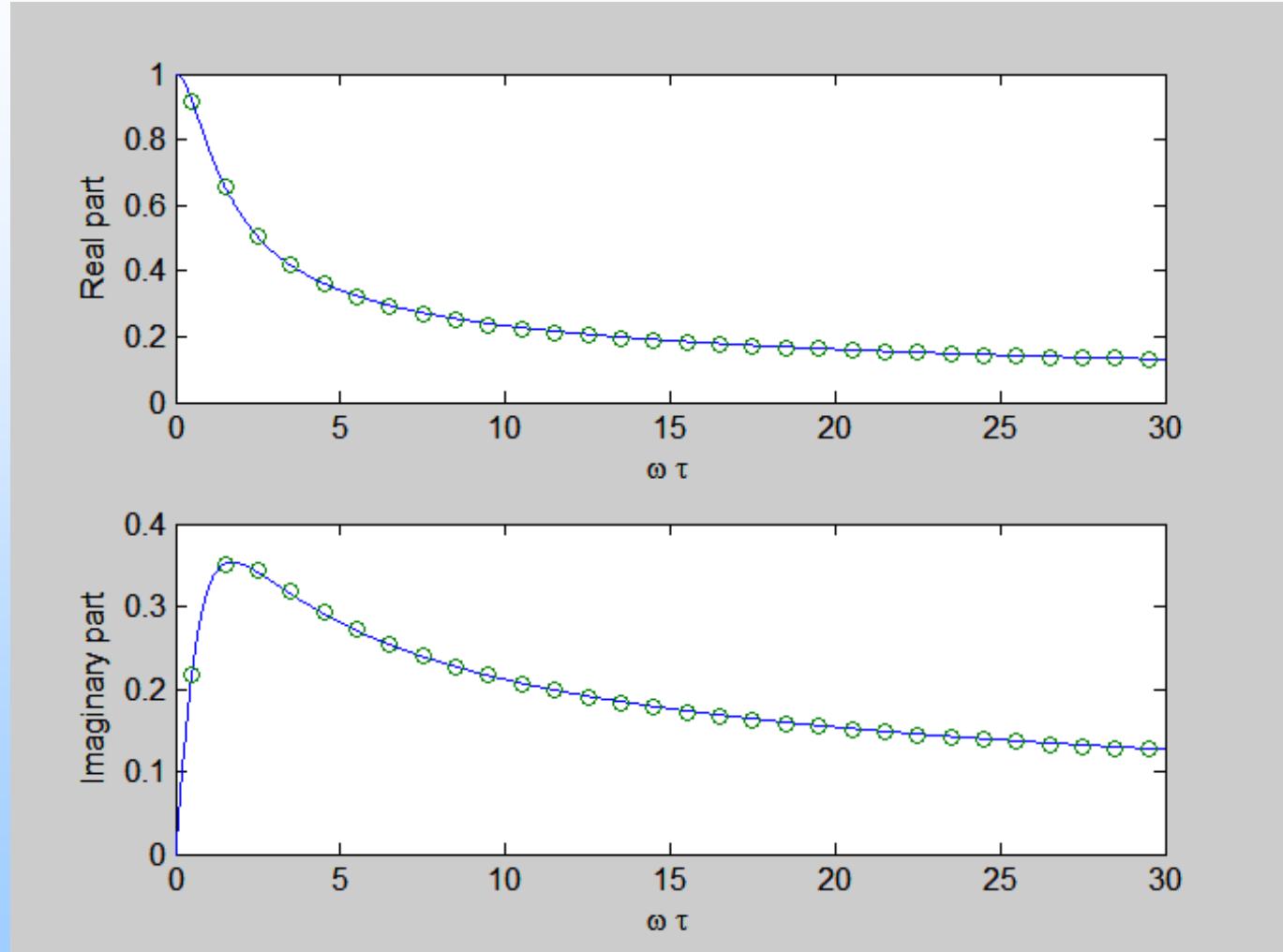
$$\frac{1}{Z} = \frac{x}{Z_0} \frac{1}{\sqrt{1-x^2}} \quad \diamond \quad \frac{x}{Z_0} \frac{1-a_2x-a_3x^2}{1-b_1x-b_2x^2-b_3x^3}.$$

Coefficients:

$$a_2 = b_1 = 0.992, \quad a_3 = b_3 = 0.566, \quad b_2 = 1.066.$$

3. Causal TDBC for any impedance

— $\frac{1}{\sqrt{1 - \frac{1}{\omega^2 \tau^2}}}$
o Pade approximation



3. Causal TDBC for any impedance

BC in frequency domain: $P \propto Z^{-1/2}$

Causal TDBC:

$$\frac{1}{Z} \left[1 - a_3 \frac{d}{dt} - a_2 \frac{d^{1/2}}{dt} D^{1/2} \right] p(t) \\ = \left[b_1 - b_3 \frac{d}{dt} - \left(\frac{d^{1/2}}{dt} - b_2 \frac{d^{1/2}}{dt} \right) D^{1/2} \right] w(t)$$

Fractional derivative: $D^{\alpha} p(t) = \frac{1}{\Gamma(1-\alpha)} \int_0^t \frac{p(t-\tau)}{\tau^{\alpha}} d\tau$

Grunwald formula: $D^{\alpha/2} p(t) = \lim_{m \rightarrow 0} \frac{(-1)^{m/2}}{m!} \frac{\Gamma(m+1)}{\Gamma(m+1-\alpha/2)} p(t-m)$

For $m \geq 1$, $\frac{(-1)^{m/2}}{m!} \frac{\Gamma(m+1)}{\Gamma(m+1-\alpha/2)} \propto m^{\alpha/2}$ (parallels to $f(t) \propto m^{\alpha/2}$).

3. Causal TDBC for any impedance

Liebler et al. (2004):

$$\frac{\zeta_m \mathbb{E}^{\pm} / 2 \mathbf{U}}{\zeta_m \mathbb{E}^{\pm} \mathbf{U}} \quad \blacklozenge \bigcirc \sum_{k=1}^K b_k e^{\zeta \mathbf{t}_k m}.$$

Following the same procedure as earlier we define the auxiliary variable:

$$\star_k^n \bigg| \mathbb{E}^{\pm} \bigg| \mathbb{E}^{\pm} \bigg| b_k e^{\zeta \mathbf{t}_k m} w \mathbf{U} \mathbf{t} \mathbf{U} \mathbf{m} \mathbf{t} \mathbf{U} \sqrt{\mathbf{t} / \delta_t}$$

It can be shown that $\star_k^n \bigg| \mathbb{E}^{\pm} b_k w \mathbf{U} \mathbf{t} \mathbf{U} \sqrt{\mathbf{t} / \delta_t} \mathbf{U} \mathbf{t} \mathbf{U} e^{\zeta \mathbf{t}_k} \star_k^n \bigg| \mathbb{E}^{\pm}$.

TDBC: $w \mathbf{U} \mathbf{t}_n \mathbf{U} \mathbf{t} \mathbf{U} F \leftarrow \mathbf{U} \mathbf{t}_n \mathbf{U} \mathbf{t} \mathbf{U} \star_k^n \mathbf{U} \mathbf{t} \mathbf{U} \rightarrow$

Thus, only K auxiliary functions \star_k^n must be stored and updated at every time step.

3. Causal TDBC for any impedance

Second example: The Attenborough impedance model.

Let $x = \sqrt{\omega_0}$. Then using a Pade approximation:

Chandler-Wilde, Horoshenkov, JASA (1995):

$$\frac{1}{Z} = \frac{x}{Z_0} \frac{1 - a_2 x - a_3 x^2 - a_4 x^3}{1 - b_1 x - b_2 x^2 - b_3 x^3 - b_4 x^4}$$

Causal TDBC:

$$\frac{1}{Z_0} \left[1 - a_3 \frac{d}{dt} - \left(a_2 \frac{d^2}{dt^2} + a_4 \frac{d^3}{dt^3} \right) D^{1/2} \right] p(t)$$

$$= \left[b_1 - b_3 \frac{d}{dt} - \left(D^{1/2} - b_2 \frac{d}{dt} - b_4 \frac{d^2}{dt^2} \right) D^{1/2} \right] w(t)$$



4. Conclusions



1. For the modified ZK impedance model, a numerically efficient algorithm for implementing TDBC is developed.
2. For any impedance model, using a Pade approximation of the impedance in the frequency domain, a causal TDBC can be derived. An efficient algorithm for numerical implementation of TDBC is then developed.

