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# The Peridynamic Theory of Solid Mechanics for Modeling Material Failure and Fracture

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# Peridynamic Theory of Solid Mechanics

## WHAT IS PERIDYNAMICS?

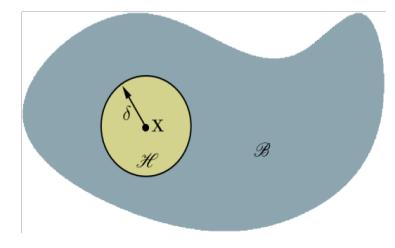
Peridynamics is a mathematical theory that unifies the mechanics of continuous media, cracks, and discrete particles

## HOW DOES IT WORK?

- Peridynamics is a *nonlocal* extension of continuum mechanics
- Remains valid in presence of discontinuities, including cracks
- Balance of linear momentum is based on an *integral equation*:

$$\rho(\mathbf{x})\ddot{\mathbf{u}}(\mathbf{x}, t) = \underbrace{\int_{\mathcal{B}} \left\{ \underline{\mathbf{T}}[\mathbf{x}, t] \langle \mathbf{x}' - \mathbf{x} \rangle - \underline{\mathbf{T}}'[\mathbf{x}', t] \langle \mathbf{x} - \mathbf{x}' \rangle \right\} dV_{\mathbf{x}'} + \mathbf{b}(\mathbf{x}, t)}_{\text{Divergence of stress replaced with integral of nonlocal forces.}}$$

The point  $\mathbf{x}$  interacts directly with all points within its horizon



S.A. Silling. Reformulation of elasticity theory for discontinuities and long-range forces. *Journal of the Mechanics and Physics of Solids*, 48:175-209, 2000.

Silling, S.A. and Lehoucq, R. B. Peridynamic Theory of Solid Mechanics. *Advances in Applied Mechanics* 44:73-168, 2010.

# Peridynamic Theory of Solid Mechanics

## CONSTITUTIVE LAWS IN PERIDYNAMICS

- Peridynamic *bonds* connect any two material points that interact directly
- Peridynamic forces are determined by *force states* acting on bonds

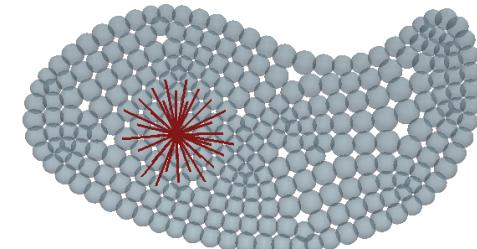
$$\underbrace{\mathbf{T}[\mathbf{x}, t]}_{\text{Force State}} \underbrace{\langle \mathbf{x}'_i - \mathbf{x} \rangle}_{\text{Bond}}$$

- Force states are determined by constitutive laws and are functions of the deformations of all points within a neighborhood
- *Material failure* is modeled through the breaking of peridynamic bonds
  - Example: critical stretch bond breaking law

## DISCRETIZATION OF A PERIDYNAMIC BODY

Direct discretization of the strong form of the balance of linear momentum <sup>1</sup>

$$\rho(\mathbf{x}) \ddot{\mathbf{u}}_h(\mathbf{x}, t) = \sum_{i=0}^N \left\{ \mathbf{T}[\mathbf{x}, t] \langle \mathbf{x}'_i - \mathbf{x} \rangle - \mathbf{T}'[\mathbf{x}'_i, t] \langle \mathbf{x} - \mathbf{x}'_i \rangle \right\} \Delta V_{\mathbf{x}'_i} + \mathbf{b}(\mathbf{x}, t)$$



<sup>1</sup> S.A. Silling and E. Askari. A meshfree method based on the peridynamic model of solid mechanics. *Computers and Structures*, 83:1526-1535, 2005.

# Constitutive Models for Peridynamics

## PERIDYNAMIC FORCE STATES MAP BONDS TO PAIRWISE FORCE DENSITIES

- Peridynamic constitutive laws can be grouped into two categories
  - *Bond-based*: bond forces depend only on a single pair of material points
  - *State-based*: bond forces depend on deformations of all neighboring material points

### Microelastic Material <sup>1</sup>

- Bond-based constitutive model
- Pairwise forces are a function of bond stretch

$$s = \frac{y - x}{x}$$

- Magnitude of pairwise force density given by

$$\underline{t} = \frac{18k}{\pi\delta^4} s$$

### Linear Peridynamic Solid <sup>2</sup>

- State-based constitutive model
- Deformation decomposed into deviatoric and dilatational components

$$\theta = \frac{3}{m} \int_{\mathcal{H}} (\underline{\omega} \underline{x}) \cdot \underline{e} dV \quad \underline{e}^d = \underline{e} - \frac{\theta \underline{x}}{3}$$

- Magnitude of pairwise force density given by

$$\underline{t} = \frac{3k\theta}{m} \underline{\omega} \underline{x} + \frac{15\mu}{m} \underline{\omega} \underline{e}^d$$

### Definitions

$\underline{x}$	bond vector
$x$	initial bond length
$y$	deformed bond length
$s$	bond stretch
$\underline{e}$	bond extension
$\underline{e}^d$	deviatoric bond extension
$\underline{\omega}$	influence function
$V$	volume
$\mathcal{H}$	neighborhood
$m$	weighted volume
$\theta$	dilatation
$\delta$	horizon
$k$	bulk modulus
$\mu$	shear modulus
$\underline{t}$	pairwise force density

1. S.A. Silling. Reformulation of elasticity theory for discontinuities and long-range forces. *Journal of the Mechanics and Physics of Solids*, 48:175-209, 2000.
2. S.A. Silling, M. Epton, O. Weckner, J. Xu, and E. Askari, Peridynamic states and constitutive modeling, *Journal of Elasticity*, 88, 2007.

# Classical Material Models Can be Applied in Peridynamics



## NON-ORDINARY STATE-BASED APPROACH <sup>1</sup>

1. Compute an approximate deformation gradient based on the initial and current locations of material points in nonlocal neighborhood

Approximate Deformation Gradient

$$\bar{\mathbf{F}} = \left( \sum_{i=0}^N \underline{\omega}_i \underline{\mathbf{Y}}_i \otimes \underline{\mathbf{X}}_i \Delta V_{\mathbf{x}_i} \right) \mathbf{K}^{-1}$$

Shape Tensor

$$\mathbf{K} = \sum_{i=0}^N \underline{\omega}_i \underline{\mathbf{X}}_i \otimes \underline{\mathbf{X}}_i \Delta V_{\mathbf{x}_i}$$

2. Kinematic data passed to classical material model
3. Classical material model computes stress
4. Stress converted to pairwise forces

$$\underline{\mathbf{T}} \langle \mathbf{x}' - \mathbf{x} \rangle = \underline{\omega} \sigma \mathbf{K}^{-1} \langle \mathbf{x}' - \mathbf{x} \rangle$$

5. Apply stabilization term to suppress low-energy modes (optional)

<sup>1</sup> S. Silling, M. Epton, O. Weckner, J. Xu, and E. Askari. Peridynamic states and constitutive modeling. *Journal of Elasticity*, 88:151-184, 2007.

# Material Failure Is Controlled by a Bond-Failure Law

*THE CRITICAL-STRETCH MODEL IS THE SIMPLEST BOND-FAILURE LAW<sup>1</sup>*

- A bonds fails when its extension exceeds a critical value
- Bond failure is irreversible

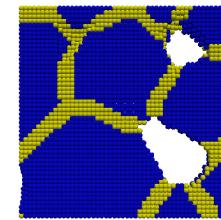
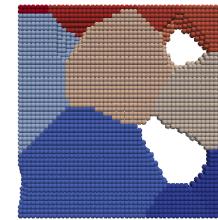
$$s_{\max} = \frac{\|\underline{e}\|_{\max}}{\|\underline{x}\|}$$

$$\phi = \begin{cases} 0 & \text{if } s_{\max} < s_{\text{crit}} \\ 1 & \text{if } s_{\max} \geq s_{\text{crit}} \end{cases}$$

- Damage results from the accumulation of broken bonds
- Critical stretch parameter is tied to the energy release rate (experimentally measureable)

*Example: Modified critical-stretch law for polycrystalline materials<sup>2</sup>*

- Modified critical-stretch law for failure of polycrystalline material



- Bond failure law favors material damage along grain boundaries
- Contact algorithm controls material interactions after bonds are broken

1. Silling, S.A. and Askari, E. A meshfree method based on the peridynamic model of solid mechanics. *Computers and Structures* 83:1526-1535, 2005.

2. D. Littlewood, V. Tikare, and J. Bignell. Informing Macroscale Constitutive Laws through Modeling of Grain-Scale Mechanisms in Plutonium Oxide. Workshop on Nonlocal Damage and Failure: Peridynamics and Other Nonlocal Models, San Antonio, Texas, March 11-12 2013.

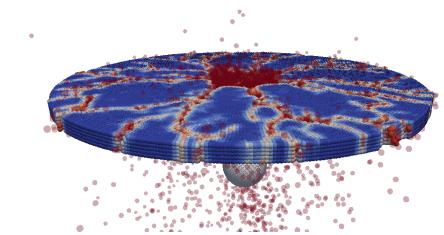
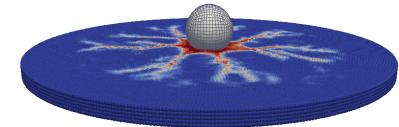
# Contact in Peridynamic Simulations

- A *short-range force* approach has been used in the majority of peridynamic simulations to date <sup>1</sup>

- Spring-like repulsive force
- Active when relative distance,  $r$ , is below contact radius,  $r_c$

$$f_c = \begin{cases} C(r_c - r) \Delta V_1 \Delta V_2 & \text{if } r \leq r_c \\ 0 & \text{if } r > r_c \end{cases}$$

- Does not require explicit definition of contact surfaces
- Friction may be incorporated by decomposing relative motion into normal and tangential components
- More sophisticated contact models are possible
  - Example: iterative penalty enforcement to drive the contact gap to zero <sup>2</sup>



Simulation of brittle fracture

1. Silling, S.A. and Askari, E. A meshfree method based on the peridynamic model of solid mechanics. *Computers and Structures* 83:1526-1535, 2005.
2. SIERRA Solid Mechanics Team, Sierra/SolidMechanics 4.22 user's guide, SAND Report 2011-7597, Sandia National Laboratories, Albuquerque, NM and Livermore, CA, 2011.

# Relationship between Classical and Peridynamic Theories



*PERIDYNAMIC OPERATORS ARE ANALOGUES OF THE CLASSICAL THEORY*

Relation	Peridynamic Theory	Standard Theory
Kinematics	$\underline{\mathbf{Y}} \langle \mathbf{x}' - \mathbf{x} \rangle = \mathbf{y}(\mathbf{x}') - \mathbf{y}(\mathbf{x})$	$\mathbf{F} = \frac{\partial \mathbf{y}}{\partial \mathbf{x}}(\mathbf{x})$
Linear Momentum Balance	$\rho \ddot{\mathbf{u}}(\mathbf{x}) = \int_{\mathcal{H}_{\mathbf{x}}} \{ \underline{\mathbf{T}}[\mathbf{x}, t] \langle \mathbf{x}' - \mathbf{x} \rangle - \underline{\mathbf{T}}[\mathbf{x}', t] \langle \mathbf{x} - \mathbf{x}' \rangle \} dV_{\mathbf{x}'} + \mathbf{b}(\mathbf{x})$	$\rho \ddot{\mathbf{u}}(\mathbf{x}) = \nabla \cdot \boldsymbol{\sigma}(\mathbf{x}) + \mathbf{b}(\mathbf{x})$
Constitutive Model	$\underline{\mathbf{T}} = \widehat{\mathbf{T}}(\underline{\mathbf{Y}})$	$\boldsymbol{\sigma} = \widehat{\boldsymbol{\sigma}}(\mathbf{F})$
Angular Momentum Balance	$\int_{\mathcal{H}_{\mathbf{x}}} \{ \underline{\mathbf{Y}} \langle \mathbf{x}' - \mathbf{x} \rangle \times \underline{\mathbf{T}} \langle \mathbf{x}' - \mathbf{x} \rangle \} dV_{\mathbf{x}'} = 0$	$\boldsymbol{\sigma} = \boldsymbol{\sigma}^T$

# Peridynamic Codes



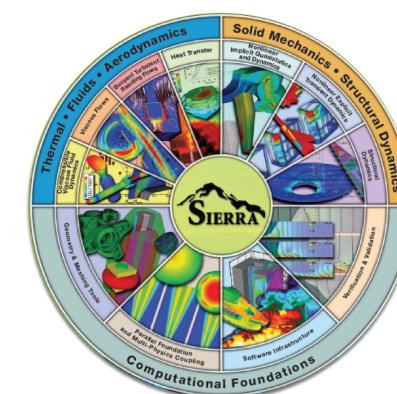
# PERIDIGM

- Computing Research Center's open-source computational peridynamics code
- Built on *Trilinos* software toolset



## SIERRA/SOLIDMECHANICS

- Engineering mechanics simulation code suite supporting the nation's nuclear weapons mission as well as other customers
- Advanced Simulation and Computing (ASC) code



## OTHERS

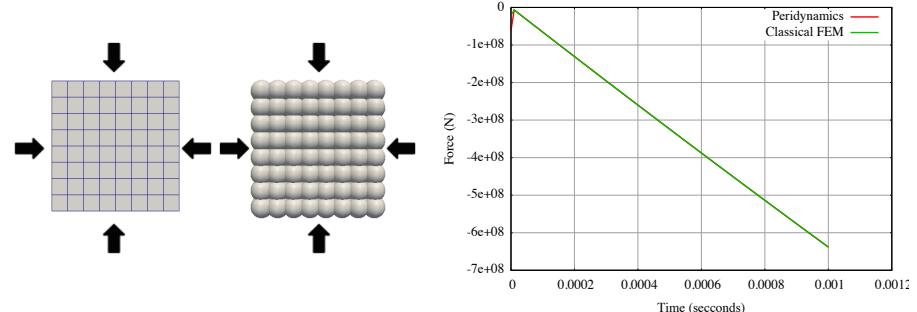
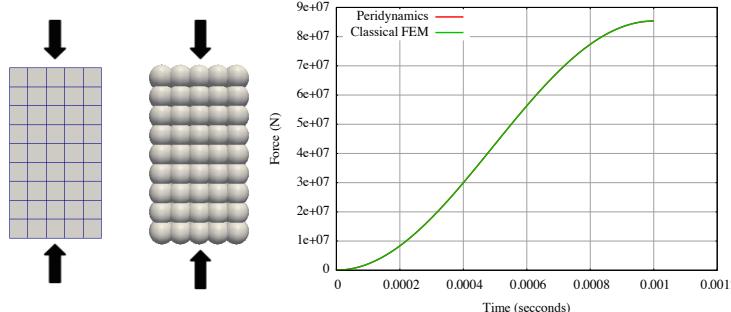
## ■ EMU, LAMMPS

1. Parks, M.L., Littlewood, D.J., Mitchell, J.A., and Silling, S.A. Peridigm users' guide v1.0.0. Sandia Report SAND-2012-7800, 2012.
2. SIERRA Solid Mechanics Team. Sierra/SolidMechanics 4.32 user's guide, 2014.

# Examples of Simple Test Problems

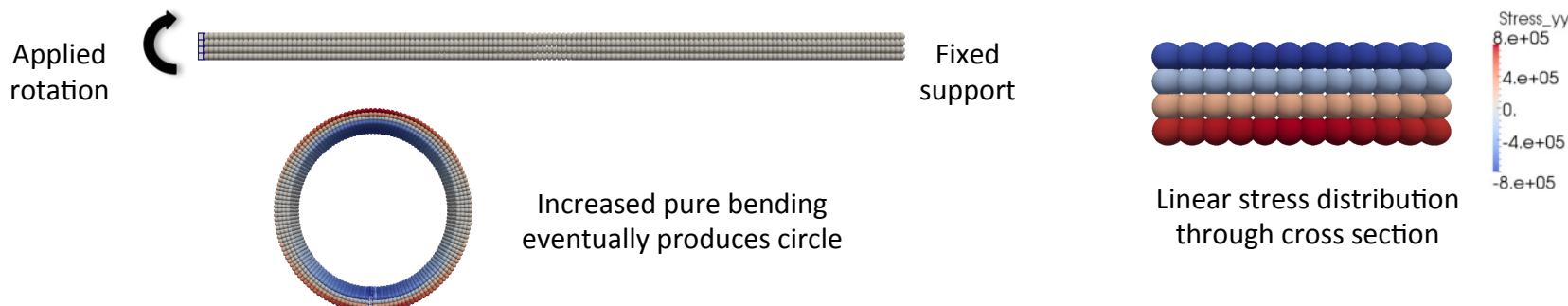
## Uniaxial and hydrostatic compression

- Tests constructed such that peridynamics and classical FEM should yield same result
- Simulation results verified for numerous material models



## Beam bending

- Test peridynamics with neo-Hookean material model against classical beam bending theory
- Simulation gives expected bending response and stress distribution

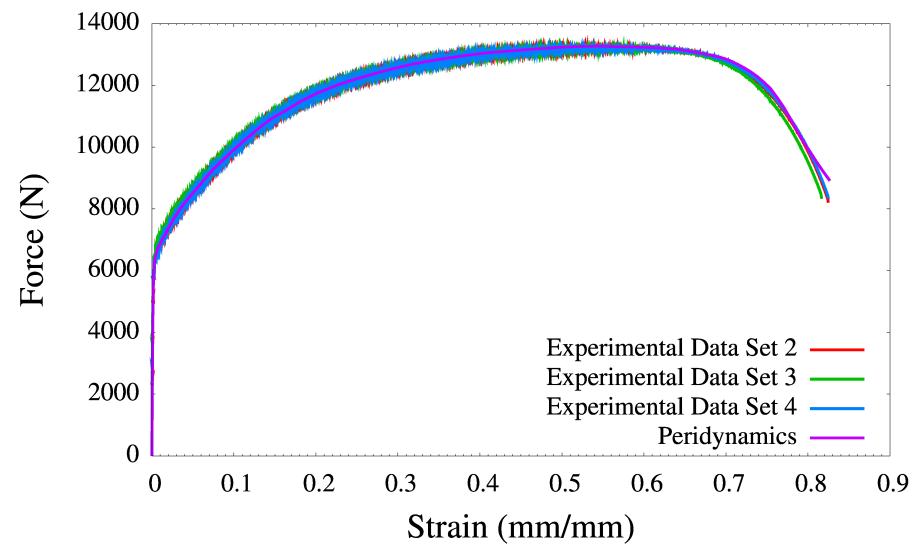
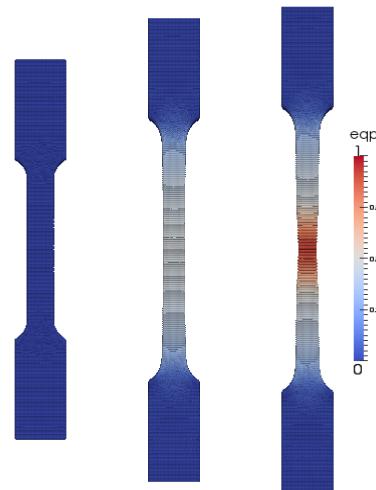


# Dogbone Tensile Test

## CONSTITUTIVE MODEL CALIBRATION AGAINST EXPERIMENTAL DATA

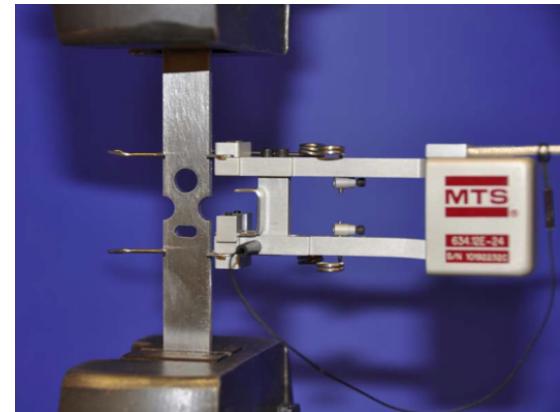
- Dogbone specimen
  - 304L stainless steel (very ductile)
  - Quasi-static loading conditions
- Peridynamic model
  - Non-ordinary state-based peridynamic
  - Elastic-plastic material constitutive model

Young's Modulus	199.95e3 MPa
Poisson's Ratio	0.285
Yield Stress	220.0 MPa
Piecewise linear hardening curve	

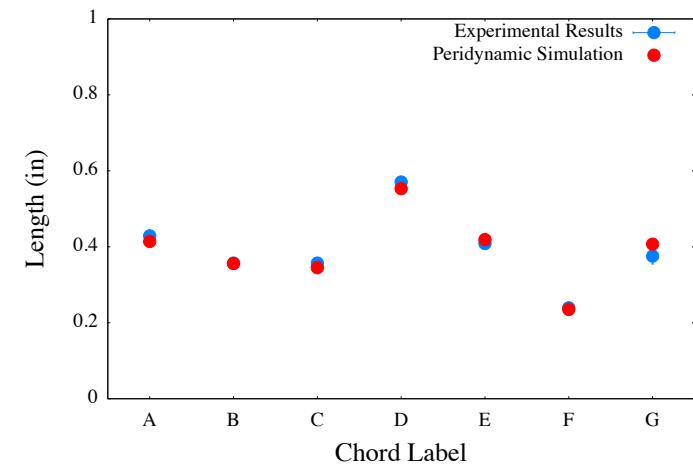
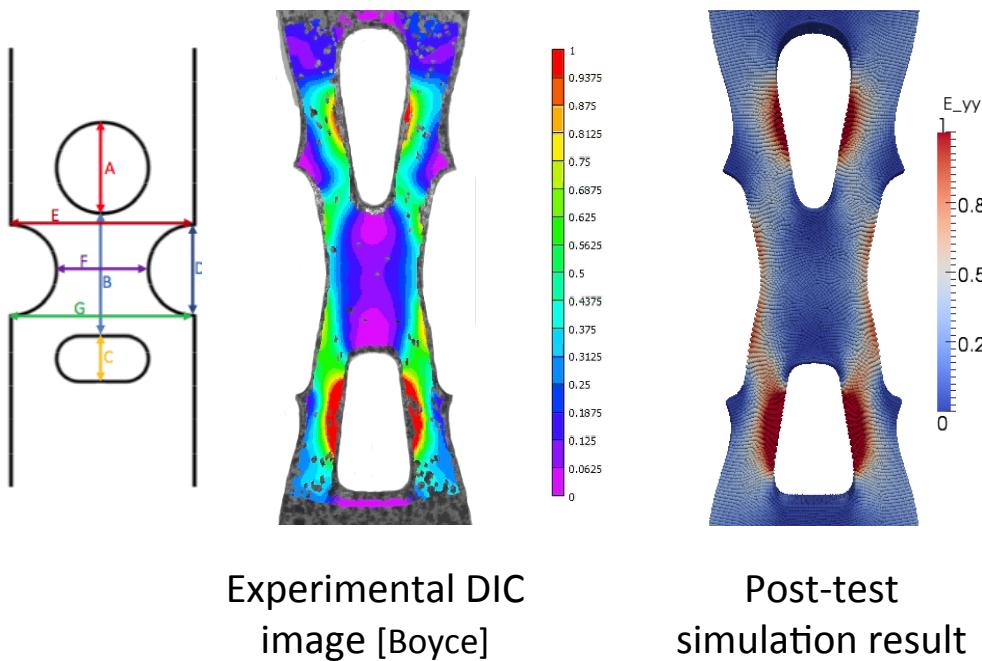


# Necking Experiment

- Modified dogbone specimen
  - 304L stainless steel (very ductile)
  - Quasi-static loading conditions
- Peridynamic model
  - Non-ordinary state-based peridynamic
  - Elastic-plastic material constitutive model

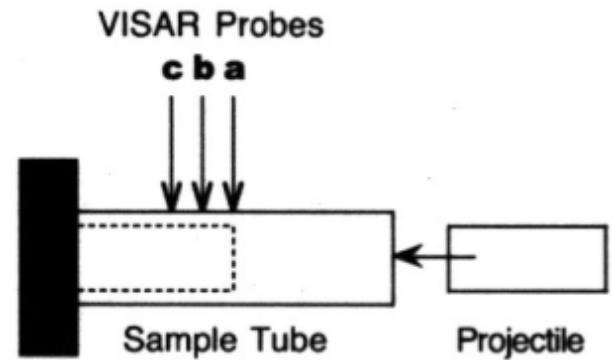


[Boyce]



# Expanding Tube Experiment

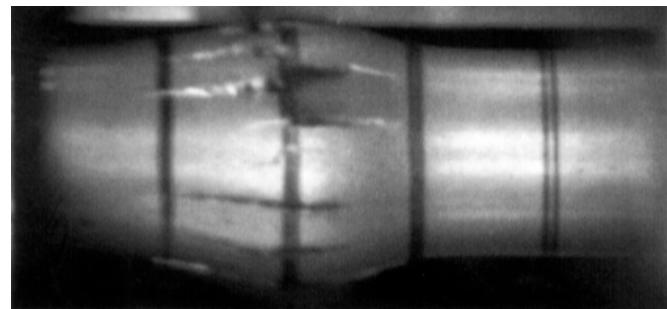
- Experimental setup:
  - Tube expansion via collision of Lexan projectile and plug within AerMet tube
  - Accurate recording of velocity and displacement on tube surface
  
- Modeling approach:
  - AerMet tube modeled with peridynamics, elastic-plastic material model with linear hardening
  - Lexan plugs modeled with traditional FEM, EOS-enabled Johnson-Cook material model



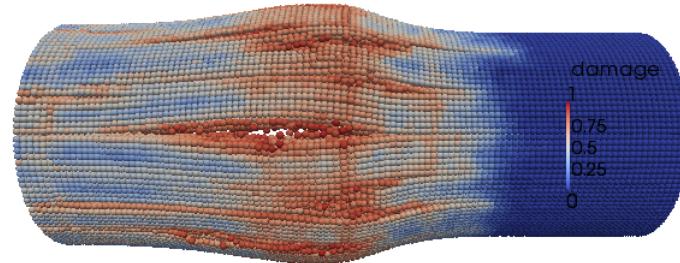
[Vogler et. al]

Vogler, T.J., Thornhill, T.F., Reinhart, W.D., Chhabidas, L.C., Grady, D.E., Wilson, L.T., Hurricane, O.A., and Sunwoo, A. Fragmentation of materials in expanding tube experiments. *International Journal of Impact Engineering*, 29:735-746, 2003.

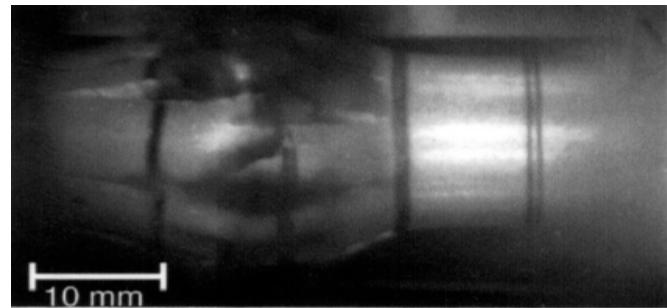
# Expanding Tube Experiment



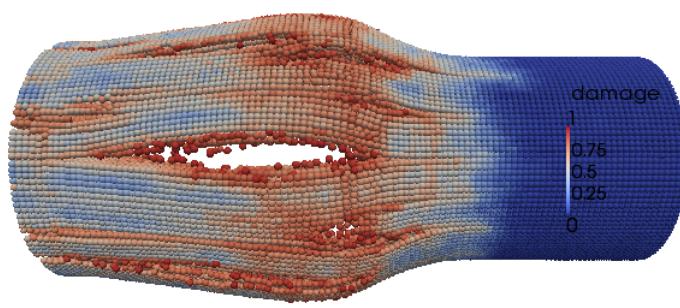
Experimental image at 15.4 microseconds [Vogler et. al]



Simulation at 15.4 microseconds



Experimental image at 23.4 microseconds [Vogler et. al]

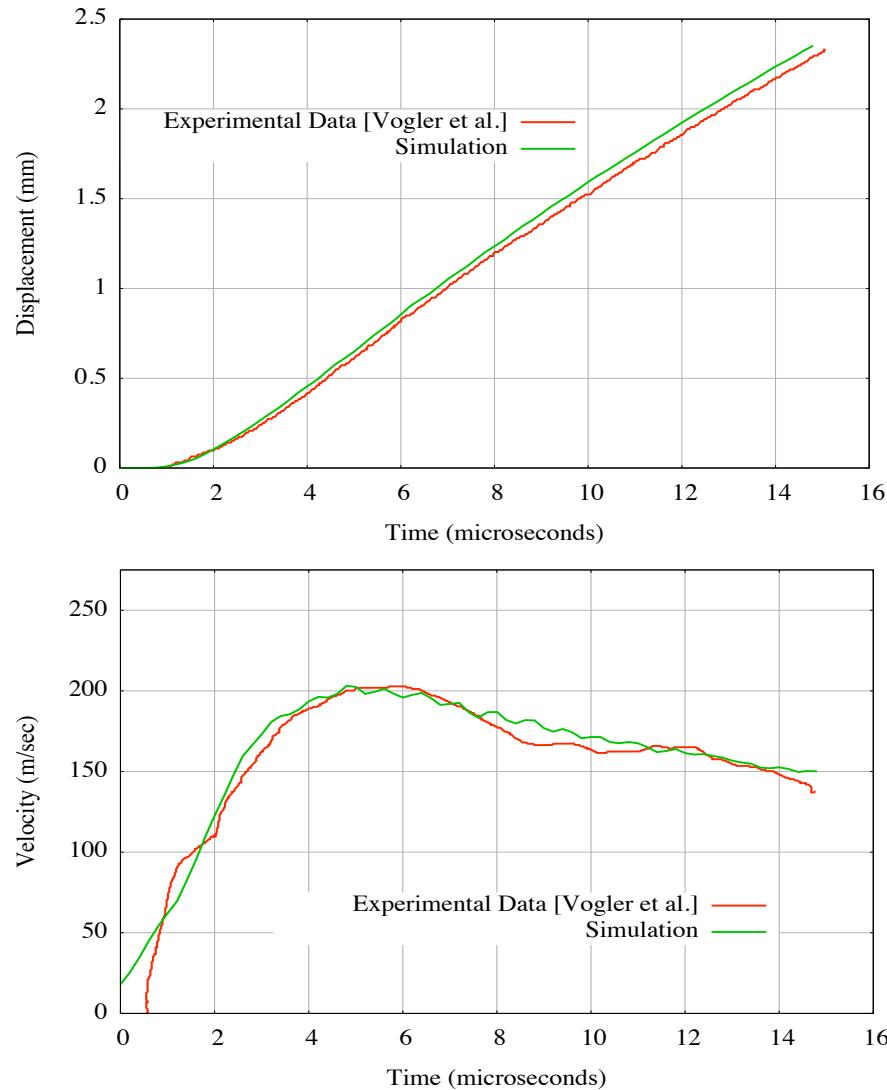
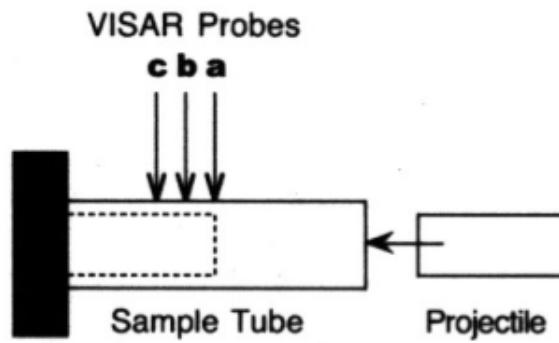


Simulation at 23.4 microseconds

# Predicted Displacement and Velocity on Tube Surface



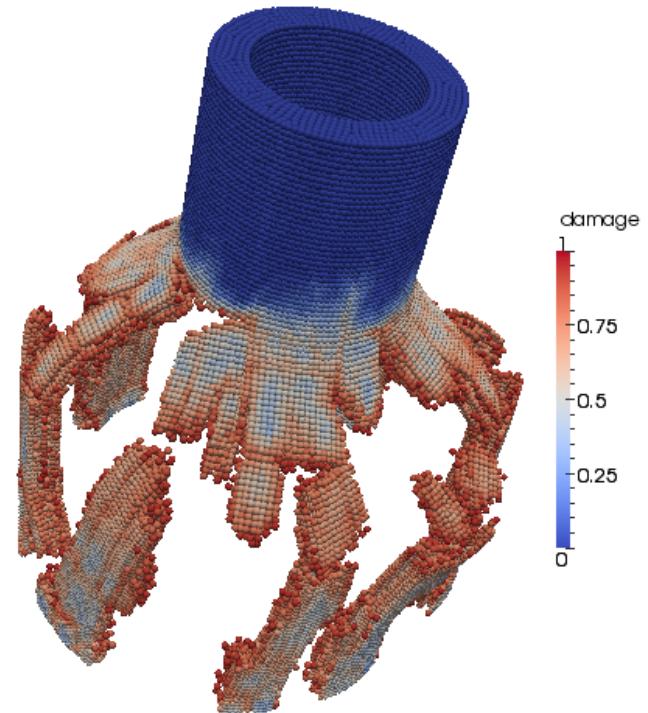
Displacement and velocity  
on tube surface  
at probe position A



# Fragmentation Pattern

## QUALITATIVE COMPARISON OF FRAGMENTATION RESULTS

- Vogler et. al reported significant uncertainty in results at late time
- Approximately half the tube remained intact
- Vogler et. al recovered 14 fragments with mass greater than one gram



Simulation at 84.8 microseconds

# Ongoing R&D Efforts in Peridynamics

- ★ Local-nonlocal coupling for integrated fracture modeling
  - Peridynamic partial stress formulation to enable a variable horizon
  - Blending-based coupling approaches
- Position-aware constitutive laws
  - Address behavior of a class of peridynamic constitutive laws at free surfaces
- Improvements to meshfree discretization
- Coarse graining approaches for multiscale modeling
- Multi-physics models
  - Mechanics, thermal, fluid flow, etc.
- Validation of peridynamics for specific Sandia applications
  - Problems of direct relevance to national security
  - Comparison against experimental data

# Local-Nonlocal Coupling

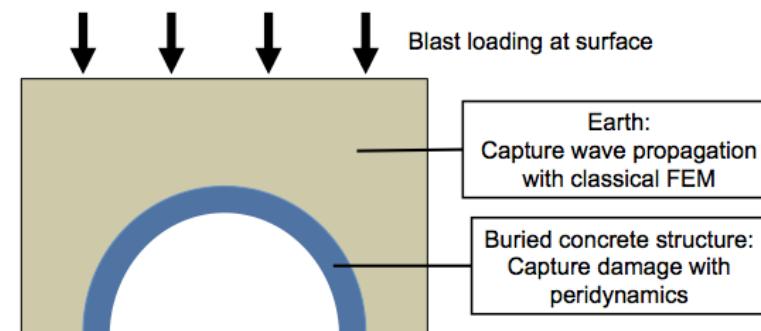
## APPLICATION OF PERIDYNAMICS TO SANDIA MISSIONS REQUIRES INTEGRATION WITH CLASSICAL MODELS

- Standard finite element codes based on classical continuum mechanics provide a robust and mature technology for a broad set of applications
- Peridynamics offers a framework for modeling material failure
- Goal: Unify the strengths of peridynamics and classical continuum mechanics

## KEY CHALLENGES

- The nonlocal governing equations of peridynamics differ inherently from those in the classical (local) theory
- Coupling strategies must avoid nonphysical artifacts at the interface of local and nonlocal models

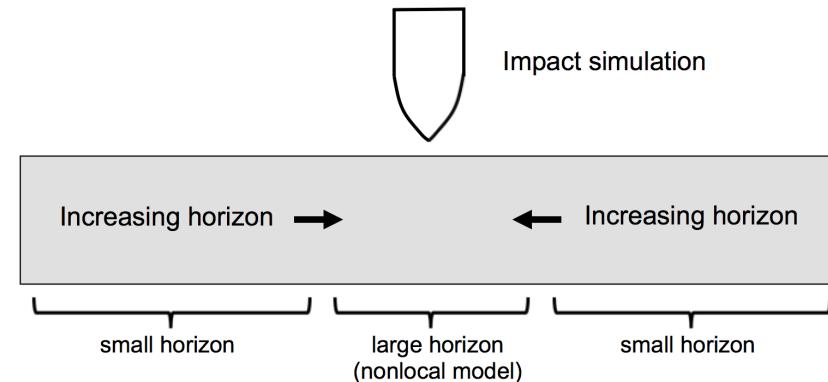
Vision  
*Apply peridynamics only  
in regions susceptible to  
material failure*



# New Research Focus: Variable Nonlocal Length Scale



A variable nonlocal length scale facilitates transitions between peridynamics and classical continuum mechanics



## *EXISTING FORMULATIONS MUST BE EXPANDED TO SUPPORT A VARIABLE HORIZON*

- Current peridynamic constitutive models do not support a variable horizon
- Goal: develop an alternative formulation that mitigates spurious artifacts in the presence of a variable nonlocal length scale
- Approach: target one-dimensional patch tests (expose spurious artifacts, if any)
  - Linear displacement field must be equilibrated
  - Quadratic displacement field must produce constant acceleration

## Proposed Solution

### *PARTIAL STRESS FORMULATION FOR PERIDYNAMIC CONSTITUTIVE LAWS<sup>1</sup>*

$$\nu_o(\mathbf{x}) := \int_{\mathcal{H}} \underline{\mathbf{T}}[\mathbf{x}] \langle \xi \rangle \otimes \xi \, dV_{\mathbf{x}'}$$

- Guaranteed to pass the linear patch test (even with a varying horizon)
- Partial stress and full peridynamic stress<sup>2</sup> are equal if the force state  $\mathbf{T}[\mathbf{x}]$  is independent of  $\mathbf{x}$ 
  - Example: homogeneous body under homogeneous deformation
  - Result suggests that partial stress is a good approximation of the full peridynamic stress under smooth deformation
- Partial stress formulation is not a good candidate for modeling material failure
- Provides a natural transition between the full peridynamic formulation and a classical stress-strain formulation (hybrid approach)

<sup>1</sup> Silling, S., and Seleson, P., Variable Length Scale in a Peridynamic Body, SIAM Conference on Mathematical Aspects of Materials Science, Philadelphia, PA, June 12, 2013.

<sup>2</sup> Lehoucq, R.B., and Silling, S.A. Force flux and the peridynamic stress tensor, Journal of the Mechanics and Physics of Solids, 56:1566-1577, 2008.

# Application of Partial Stress within Peridynamics Framework

## INTERNAL FORCE CALCULATION REQUIRES DIVERGENCE OPERATOR

- Internal force evaluated as divergence of partial stress

$$\mathbf{L}(\mathbf{x}) = \nabla \cdot \nu(\mathbf{x}) = \text{Tr}(\nabla \nu(\mathbf{x}))$$

$$\nabla \nu(\mathbf{x}) = \int_{\mathcal{H}} \underline{\omega} \langle \xi \rangle \{ \nu(\mathbf{x}') - \nu(\mathbf{x}) \} \otimes \xi \, dV_{\mathbf{x}'} \, \mathbf{K}^{-1}$$

- The partial stress can be applied within the meshless approach of Silling and Askari <sup>1</sup>

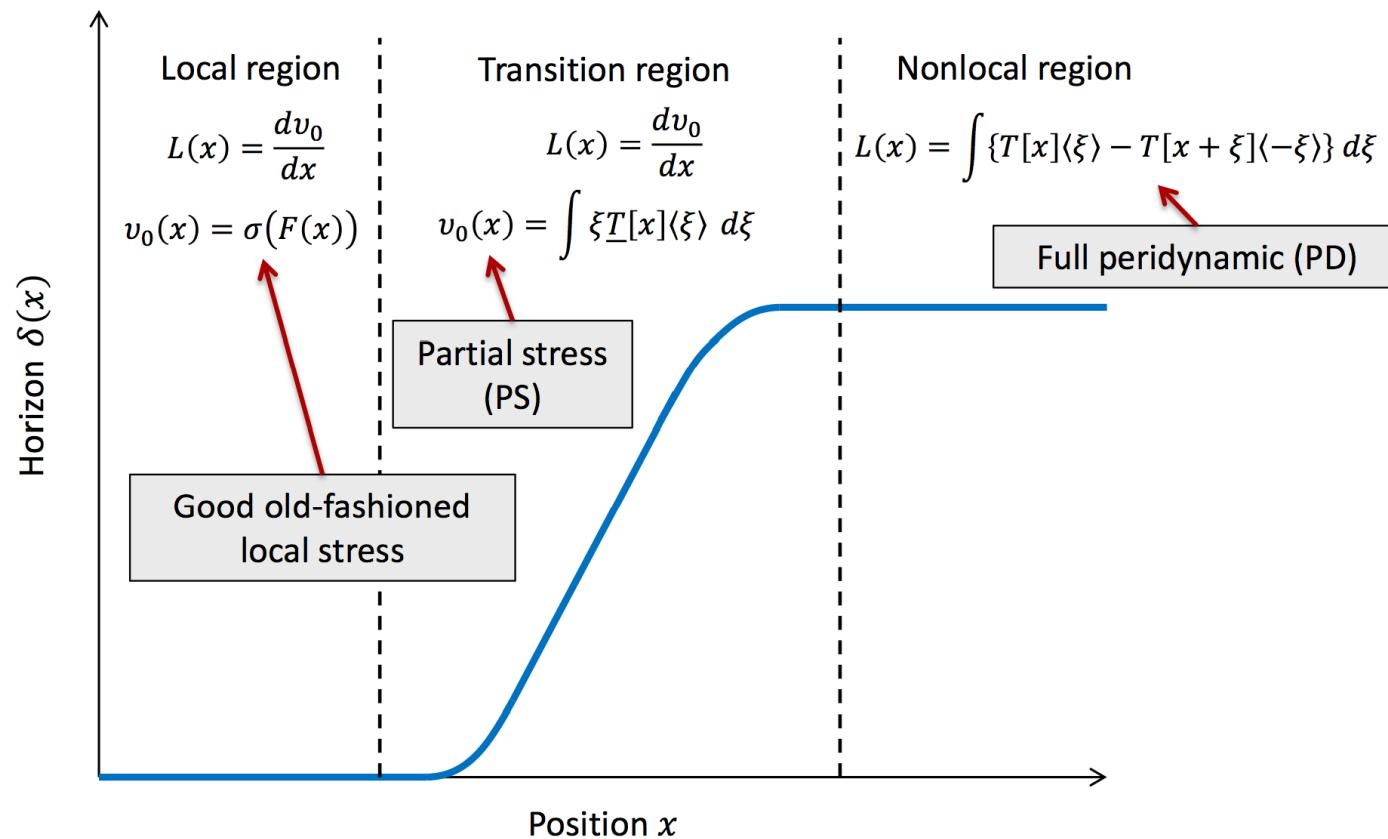
$$\nabla \cdot \nu(\mathbf{x}) = \text{Tr} \left( \left( \sum_{n=1}^N \underline{\omega} \langle \xi^n \rangle \{ \nu(\mathbf{x}^n) - \nu(\mathbf{x}) \} \otimes \xi^n \Delta V^n \right) \mathbf{K}^{-1} \right)$$

- The partial stress can also be applied within a standard finite-element scheme

<sup>1</sup> S.A. Silling and E. Askari. A meshfree method based on the peridynamic model of solid mechanics. *Computers and Structures*, 83:1526-1535, 2005.

# Utilize the Partial Stress Formulation in a Transition Region

*ALTER THE PERIDYNAMIC HORIZON WITHIN A BODY TO APPLY NONLOCALITY ONLY WHERE NEEDED*



[Stewart Silling]

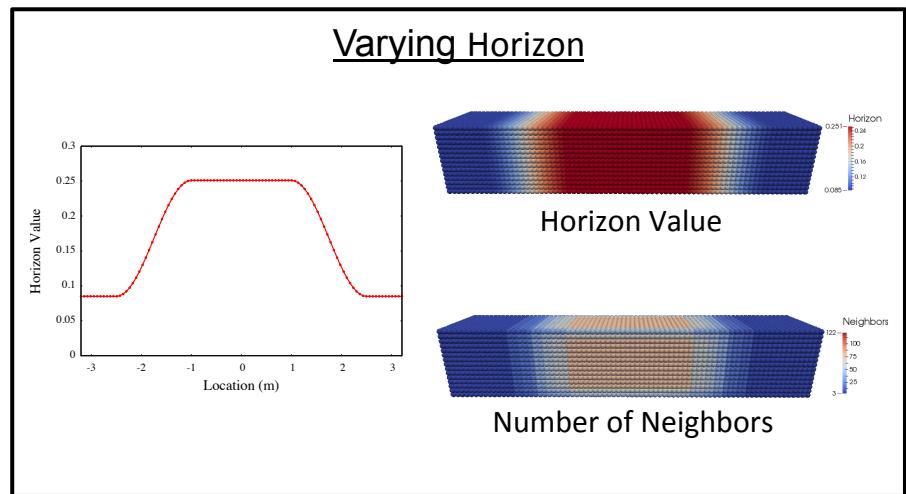
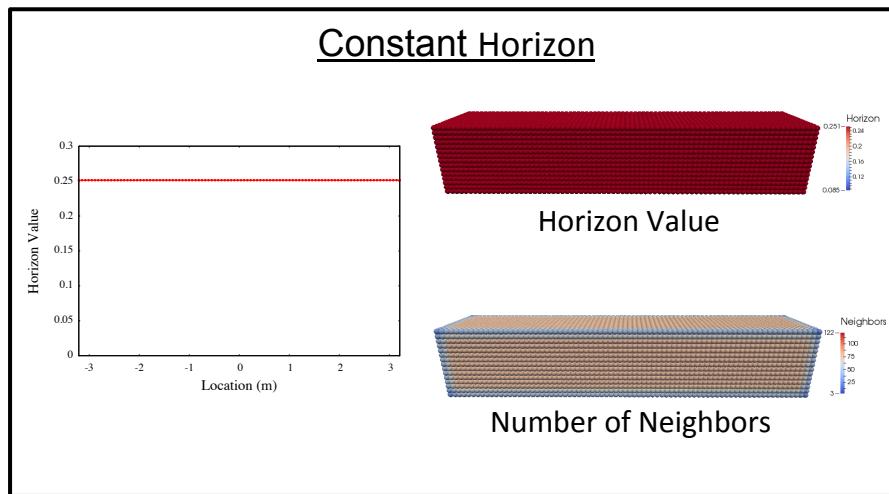
# Patch Tests for Partial Stress Formulation

## *SUBJECT RECTANGULAR BAR TO PRESCRIBED DISPLACEMENT FIELDS*

- Examine response under linear and quadratic displacement fields
- Investigate standard formulation with both constant and varying peridynamic horizon
- Investigate partial stress formulation with both constant and varying peridynamic horizon

Elastic Correspondence  
Material Model

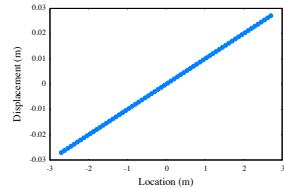
Density	7.8 g/cm <sup>3</sup>
Young's Modulus	200.0 GPa
Poisson's Ratio	0.0
Stability Coefficient	0.0



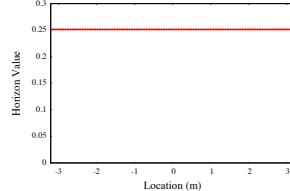
# Patch Test: Prescribed Linear Displacement

## Test set-up

Prescribe linear displacement field



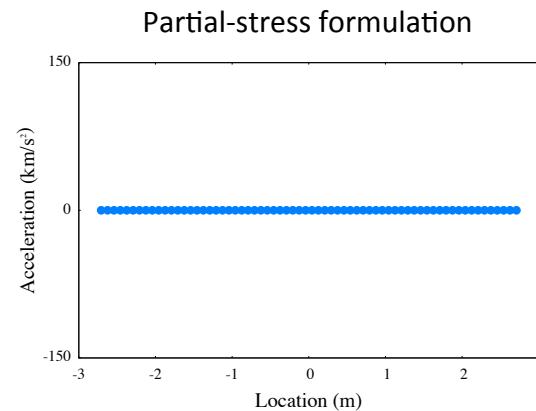
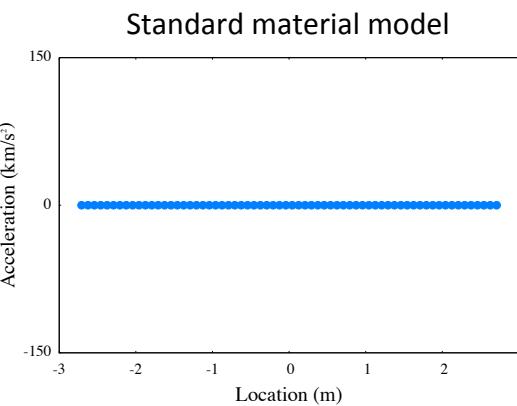
Constant horizon throughout bar



Can the standard model and the partial-stress model recover the expected zero acceleration?

**Both** models produce the expected result when the horizon is **constant**

## Test Results: Acceleration over the length of the bar

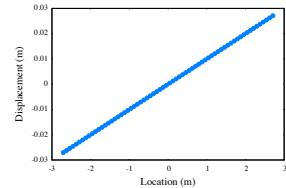


Note: nodes near ends of bar excluded from plots

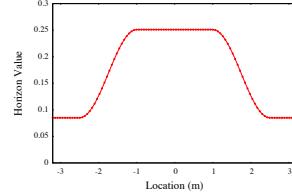
# Patch Test: Prescribed Linear Displacement

## Test set-up

Prescribe linear displacement field



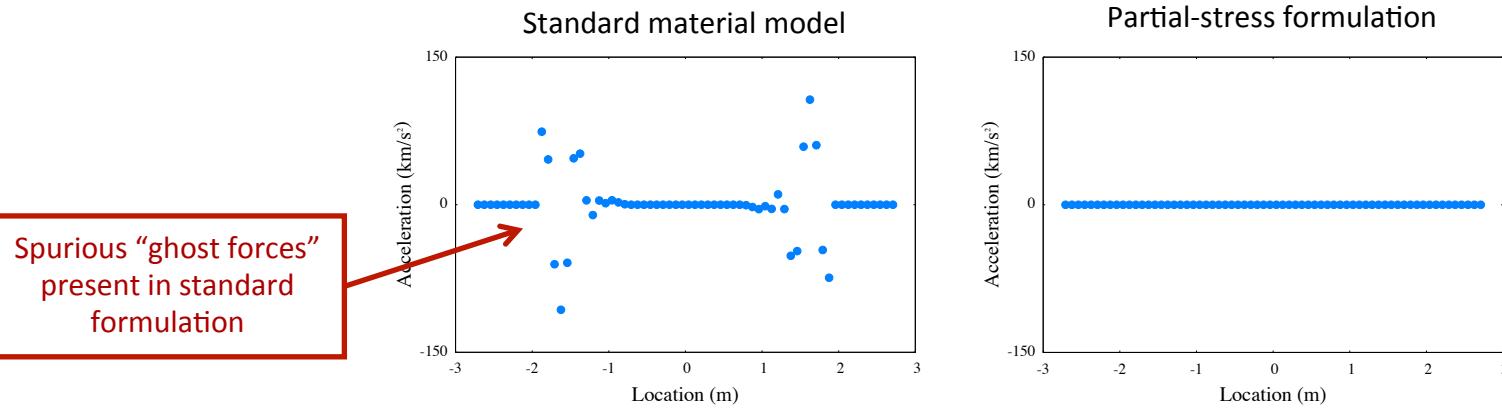
Variable horizon



Can the standard model and the partial-stress model recover the expected zero acceleration?

Only the **partial stress** formulation produce the expected result when the horizon is **varying**

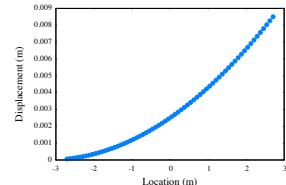
## Test Results: Acceleration over the length of the bar



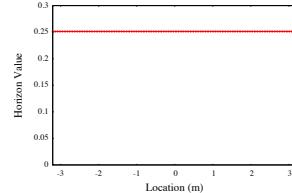
# Patch Test: Prescribed Quadratic Displacement

## Test set-up

Prescribe quadratic displacement field



Constant horizon throughout bar

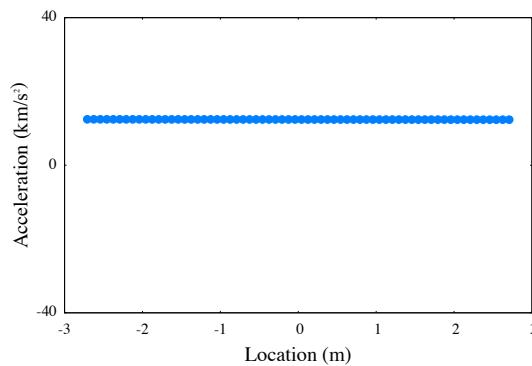


Can the standard model and the partial-stress model recover the expected constant acceleration profile?

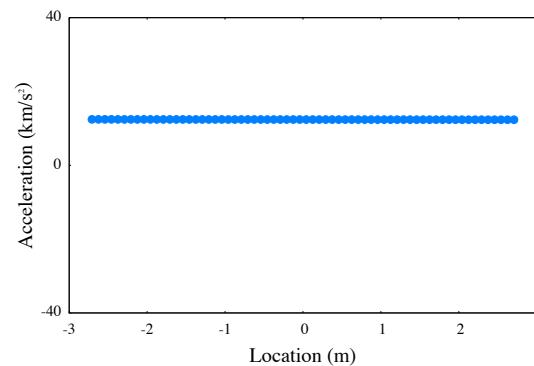
**Both** models produce the expected result when the horizon is **constant**

## Test Results: Acceleration over the length of the bar

Standard material model



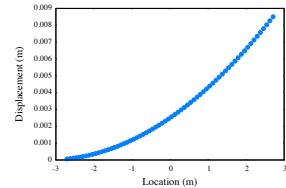
Partial-stress formulation



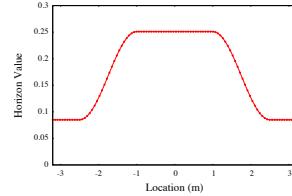
# Patch Test: Prescribed Quadratic Displacement

## Test set-up

Prescribe quadratic displacement field



Variable horizon

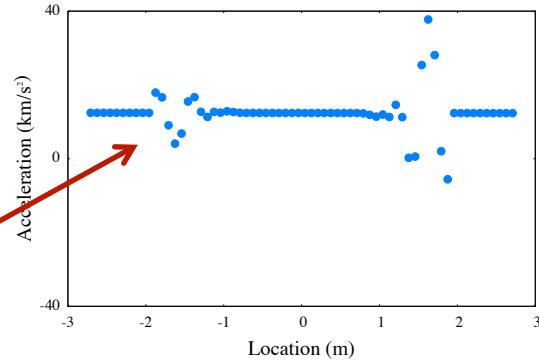


Can the standard model and the partial-stress model recover the expected constant acceleration?

Only the **partial stress** formulation produce the expected result when the horizon is **varying**

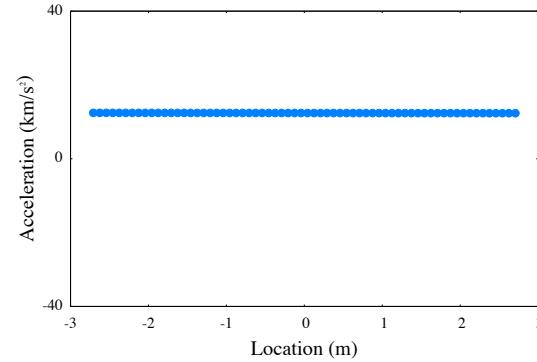
## Test Results: Acceleration over the length of the bar

Standard material model



Spurious “ghost forces” present in standard formulation

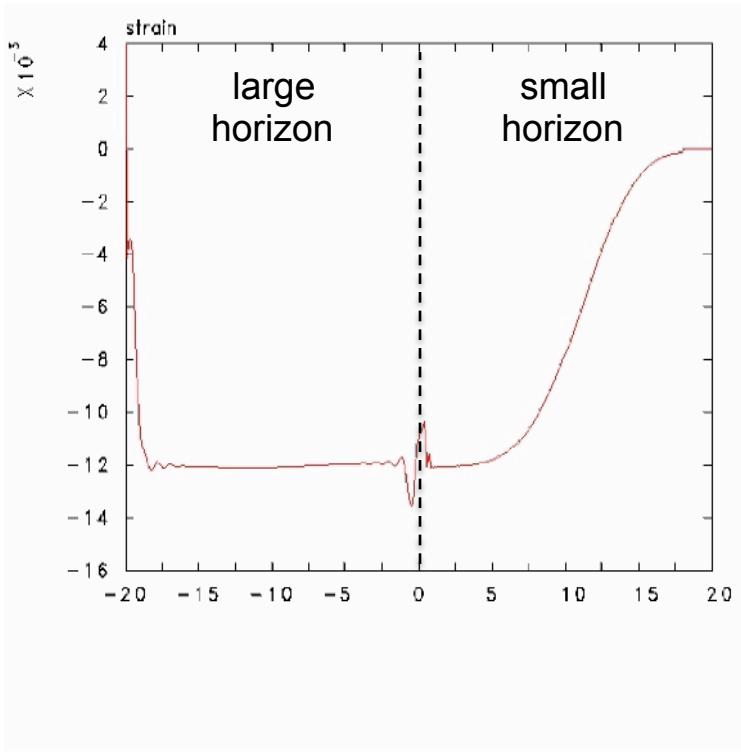
Partial-stress formulation



# Wave Propagation through Region of Varying Horizon

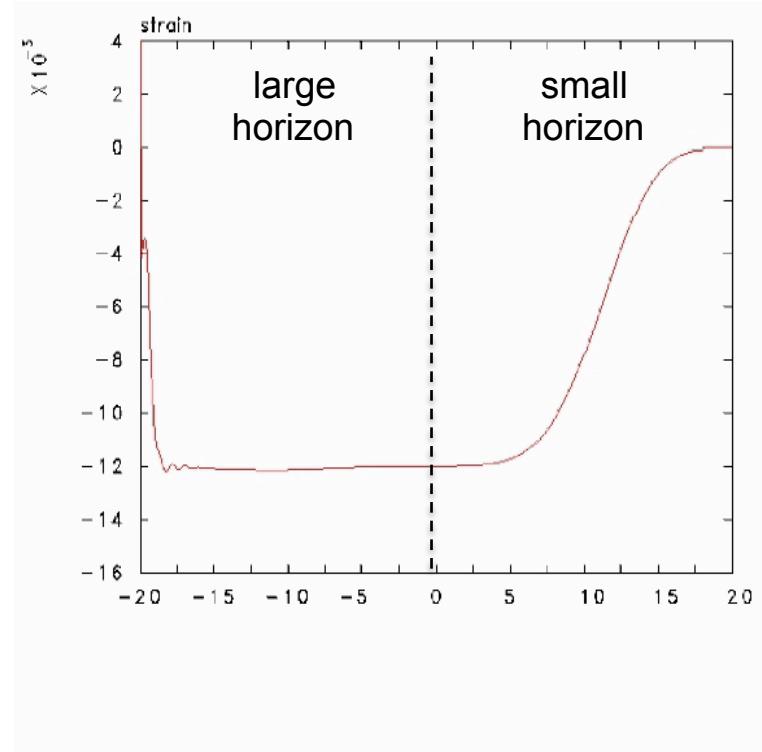
## Standard peridynamic model

Numerical artifacts present at transition from large horizon to small horizon



## Partial-stress approach

Greatly reduces artifacts, enables smooth transition between large and small horizons



<sup>1</sup>Silling, S., and Seleson, P., Variable Length Scale in a Peridynamic Body, SIAM Conference on Mathematical Aspects of Materials Science, Philadelphia, PA, June 12, 2013.

# What about Performance?

## USE OF A VARIABLE HORIZON IMPACTS PERFORMANCE IN SEVERAL WAYS

- Use of a variable horizon can reduce neighborhood size
  - Less computational cost per internal force evaluation
  - Reduces number of unknowns in stiffness matrix for implicit time integration
- Use of a variable horizon can reduce the critical time step
  - Critical time step is strongly dependent on the horizon <sup>1, 2</sup>
  - Smaller time step results in more total steps to solution for explicit transient dynamic simulations
  - Important note: the critical time step for analyses combining peridynamics and classical finite analysis is generally determined by the classical finite elements

**Total Number of Bonds**  
(equal to number of nonzeros in stiffness matrix)

Constant Horizon	92.6 million
Varying Horizon	46.5 million

**Stable Time Step** <sup>1, 2</sup>  
(explicit transient dynamics)

Constant Horizon	2.03e-5 sec.
Varying Horizon	7.15e-6 sec.

<sup>1</sup> S.A. Silling and E. Askari. A meshfree method based on the peridynamic model of solid mechanics. *Computers and Structures*, 83:1526-1535, 2005.

<sup>2</sup> Littlewood, D.J., Thomas, J.D., and Shelton, T.R. Estimation of the Critical Time Step for Peridynamic Models. SIAM Conference on the Mathematical Aspects of Material Science, Philadelphia, Pennsylvania, June 9-12, 2013.

# Questions?

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Multiscale Science (Org. 1444)

# Back-Up Slides

# Suppression of Low-Energy Modes

Penalize deformation that deviates from regularized deformation gradient <sup>1</sup>

Predicted location of neighbor

$$\mathbf{x}_n'^* = \mathbf{x}_n + \bar{\mathbf{F}}_n (\mathbf{x}'_o - \mathbf{x}_o)$$

Hourglass vector

$$\boldsymbol{\Gamma}_{hg} = \mathbf{x}_n'^* - \mathbf{x}'_n$$

Hourglass vector projected onto bond

$$\gamma_{hg} = \boldsymbol{\Gamma}_{hg} \cdot (\mathbf{x}'_n - \mathbf{x}_n)$$

Stabilization force

$$\rightarrow \mathbf{f}_{hg} = -C_{hg} \underbrace{\left( \frac{18k}{\pi\delta^4} \right)}_{\text{micro-modulus}} \underbrace{\frac{\gamma_{hg}}{\|\mathbf{x}'_o - \mathbf{x}_o\|}}_{\text{hourglass stretch}} \underbrace{\frac{\mathbf{x}'_n - \mathbf{x}_n}{\|\mathbf{x}'_n - \mathbf{x}_n\|}}_{\text{bond unit vector}} \Delta V_x \Delta V_{x'}$$

<sup>1</sup> D. Littlewood, K. Mish, and K. Pierson. Peridynamic simulation of damage evolution for structural health monitoring. Proceedings of ASME 2012 International Mechanical Engineering Congress and Exposition (IMECE2012), Houston, TX, November 9-15, 2012.

# Combined Peridynamics / Classical FEM Model

- Lexan projectile and plug
  - Modeled with classical FEM
  - Johnson-Cook constitutive model
- AerMet tube
  - Modeled with peridynamics
  - Elastic-plastic constitutive model

Parameter	Value
Density	1.19 g/cm <sup>3</sup>
Young's Modulus	2.54 GPa
Poisson's Ratio	0.344
Yield Stress	75.8 MPa
Hardening Constant <i>B</i>	68.9 MPa
Rate Constant <i>C</i>	0.0
Hardening Exponent <i>N</i>	1.0
Thermal Exponent <i>M</i>	1.85
Reference Temperature	70.0 °F
Melting Temperature	500.0 °F

Parameter	Value
Density	7.87 g/cm <sup>3</sup>
Young's Modulus	194.4 GPa
Poisson's Ratio	0.3
Yield Stress	1.72 GPa
Hardening Modulus	1.94 GPa
Critical Stretch	0.02



Model Discretization

# Peridynamics and Higher-Order Gradient Methods

- Local models contain no length scale

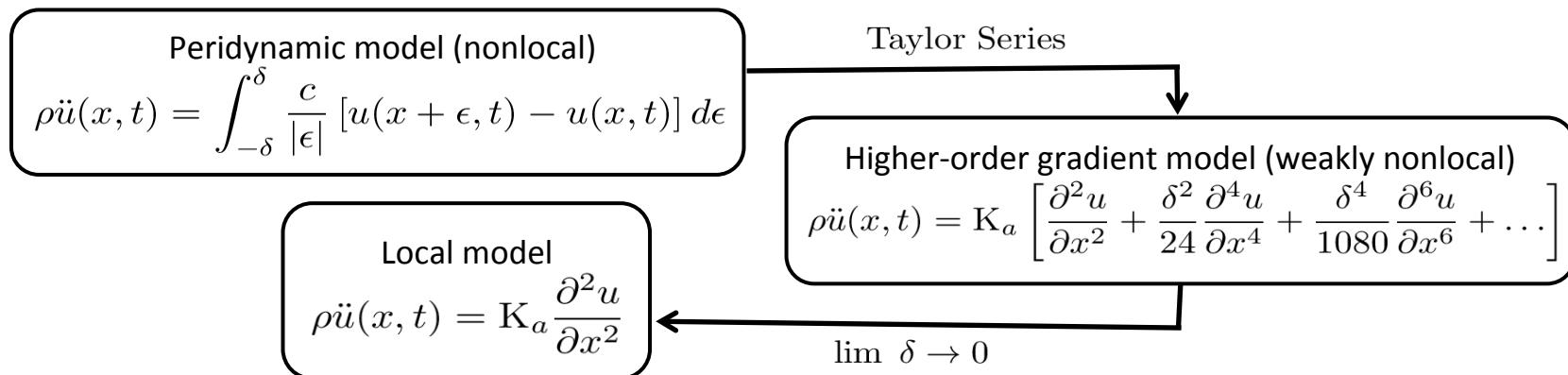
$$\ddot{u}(x) = a u''(x)$$

- Higher-order gradients introduce length scale in a weak sense

$$\ddot{u}(x) = a u''(x) + b u''''(x)$$

→ Dimensional analysis shows that  $\sqrt{b/a}$  has units of length

- Peridynamics is a (strongly) nonlocal model



S.A. Silling and R.B. Lehoucq, Convergence of peridynamics to classical elasticity theory, *Journal of Elasticity*, 93(1), 2008.

Pablo Seleson, Michael L. Parks, Max Gunzburger, and Richard B. Lehoucq. Peridynamics as an upscaling of molecular dynamics. *Multiscale Modeling and Simulation*, 8(1), 2009.