

# Introduction to Multigrid Methods

Chris Siefert

Computational and Shock Multiphysics Group (1431)

Sandia National Laboratories



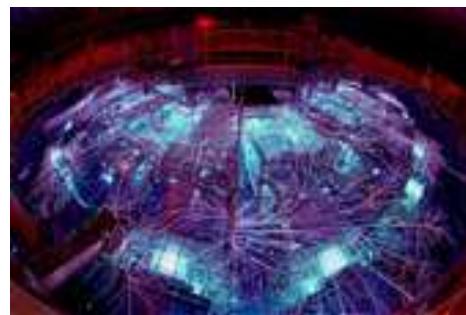
# Outline

- **Background.**
- Solving Linear Systems with Iterative Methods.
- Introduction to Multilevel Methods.
- Introduction to Algebraic Multigrid.
- Open Questions in Multilevel Methods.



# What is Computational Science?

- What do we think of when we think of computational science?
  - Usually “big” things...
  - Airplanes, cars, rockets, etc.



# What is Computational Science?

- What do we think of when we think of computational science?
  - Usually “big” things...
  - Airplanes, cars, rockets, etc.
- **BUT** computational science touches everyday things as well!





# Key Computational Kernels

- What are the important kernels for computational science?



# Key Computational Kernels

- What are the important kernels for computational science?
  - Time integration (time-dependent problems).
  - Force calculations (particle methods).
  - Solving linear systems (implicit methods, static problems).
  - Interface tracking (shock problems).
  - Load balancing, graph algorithms (parallel problems, direct solvers).
  - Optimization (inverse problems).
  - Eigenvalues (structures problems).
  - ... and more.



# Key Computational Kernels

- What are the important kernels for computational science?
  - Time integration (time-dependent problems).
  - Force calculations (particle methods).
  - Solving linear systems (implicit methods, static problems).
  - Interface tracking (shock problems).
  - Load balancing, graph algorithms (parallel problems, direct solvers).
  - Optimization (inverse problems).
  - Eigenvalues (structures problems).
  - ... and more.



# Outline

- Background.
- Solving Linear Systems with Iterative Methods.
- Introduction to Multilevel Methods.
- Introduction to Algebraic Multigrid.
- Open Questions in Multilevel Methods.



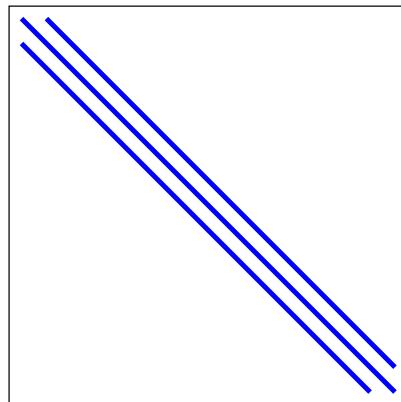
# Importance of Linear Algebra

- Solving linear systems was critical to the example  
⇒ One linear solve per time step!
- This is true of many simulations.
- We can do this w/ Gaussian elimination (GE).
- But is it fast enough?

# Is GE Good Enough?

A sparse matrix is “any matrix with enough zeros that it pays to take advantage of them.” — J. Wilkinson

- For dense problems (almost all entries non-zero), yes.
- But what about sparse problems?
- Example: 1D Heat equation has 3 non-zeros per row.



1D Heat Equation Sparsity



# Introducing Iterative Methods

$$Ax = b$$

- Idea: Sparse matrix-vector products are cheap  
cost = # non-zeros.
- Let  $D = \text{diag}(A)$  contain “a lot” of the matrix. Then,

$$\begin{aligned}(D + (A - D))x &= b \\ Dx &= b - (A - D)x \\ x &= D^{-1}(b - (A - D)x)\end{aligned}$$

- Jacobi’s method:

$$x_{i+1} = x_i + D^{-1}(b - Ax_i)$$

- Total Operations  $\approx \text{nnz.}$



# Speed of Various Methods

Consider a model Laplace problem of size:  $n = k^d$ , where  $d = 2, 3$ .

Method	2D	3D
Dense GE	$k^6$	$k^9$
Sparse GE	$k^3$	$k^6$
Jacobi	$k^4 \log k$	$k^5 \log k$

Table from:

*Scientific Computing: An Introductory Survey*, 2nd ed. by M.T. Heath



# Speed of Various Methods

Consider a model Laplace problem of size:  $n = k^d$ , where  $d = 2, 3$ .

Method	2D	3D
Dense GE	$k^6$	$k^9$
Sparse GE	$k^3$	$k^6$
Jacobi	$k^4 \log k$	$k^5 \log k$
Multigrid	$k^2$	$k^3$

Table from:

*Scientific Computing: An Introductory Survey*, 2nd ed. by M.T. Heath

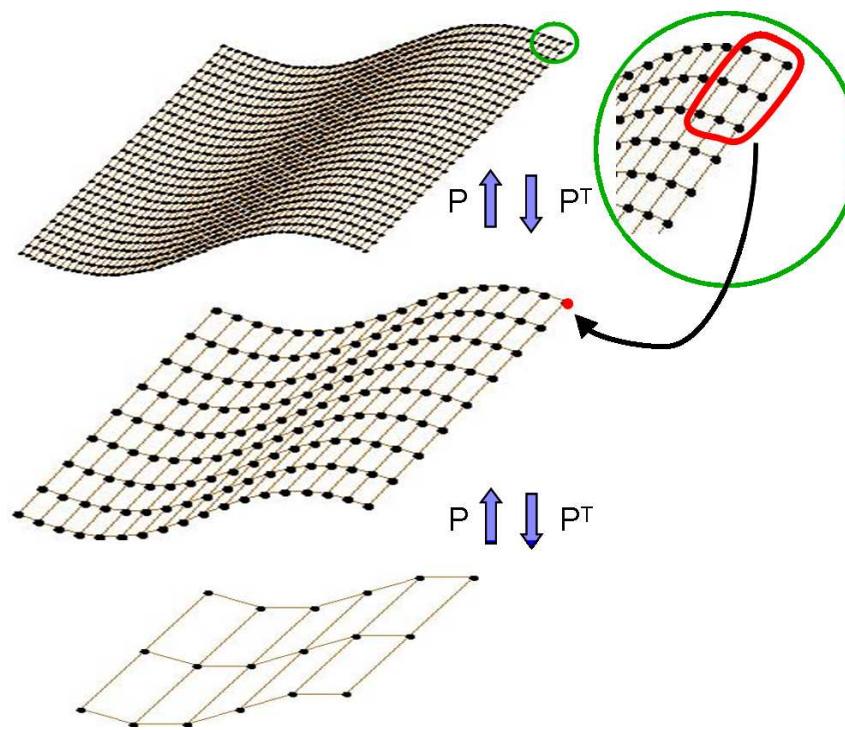


# Outline

- Background.
- Solving Linear Systems with Iterative Methods.
- **Introduction Multilevel Methods.**
- Introduction to Algebraic Multigrid.
- Open Questions in Multilevel Methods.

# Introducing Multilevel Methods

- Goal: Solve problem with specified mesh spacing,  $h$ .
- Idea: Approximate problem w/ coarse mesh  $H$ .



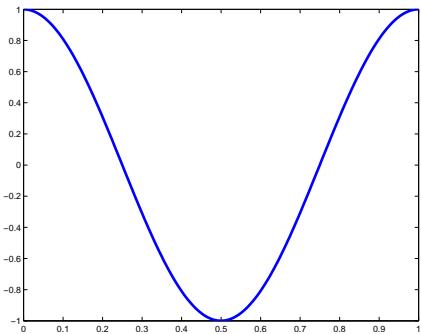
- Big Question: Will this work?

# Fourier Series

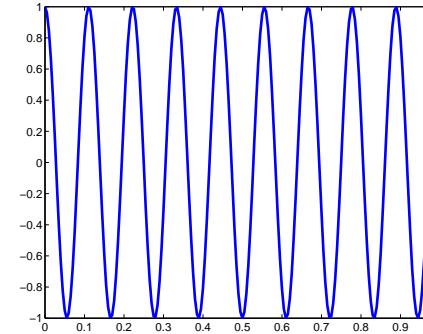
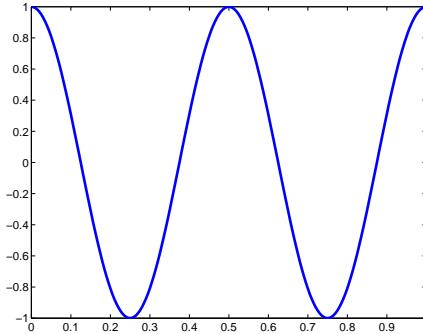
- Consider a (real) Fourier series

$$f(x) = \frac{a_0}{2} + \sum_{i=1}^{\infty} \alpha_i \cos(2\pi x i)$$

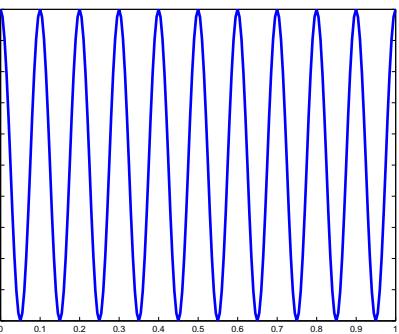
- What do these functions look like?



Smooth

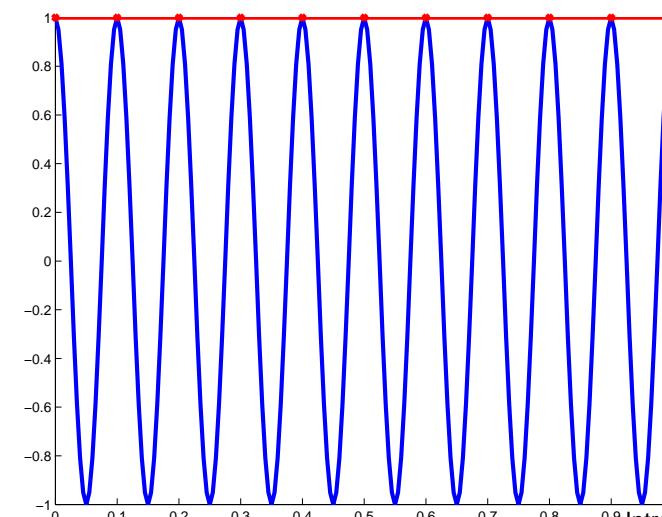
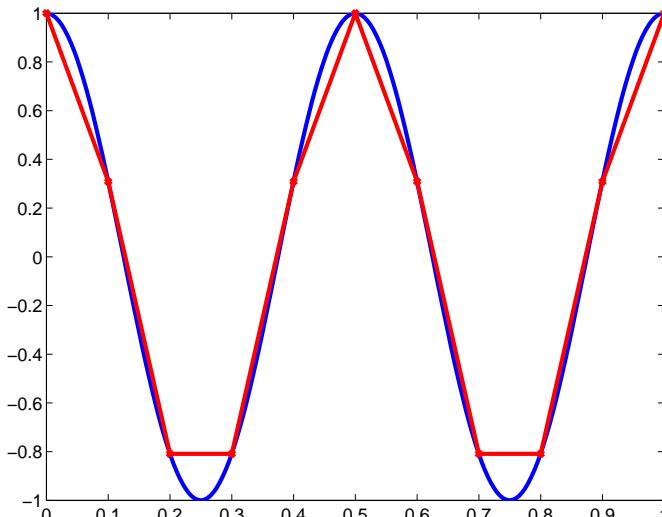
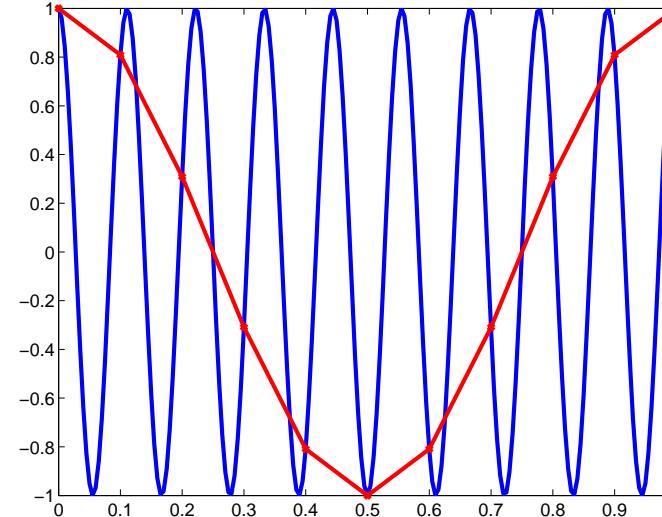
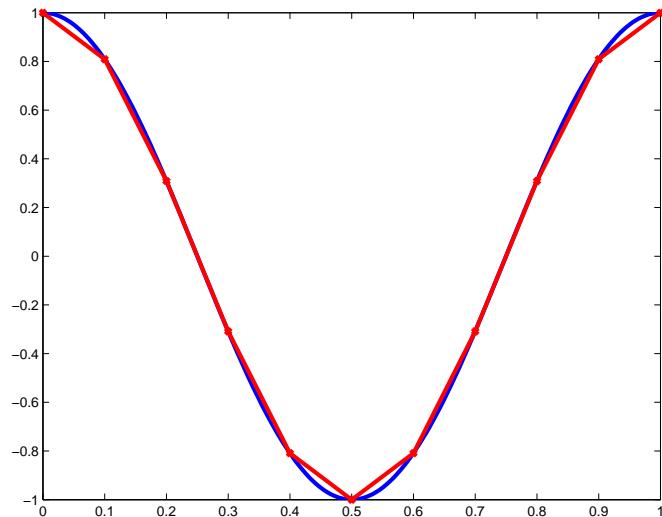


Oscillatory



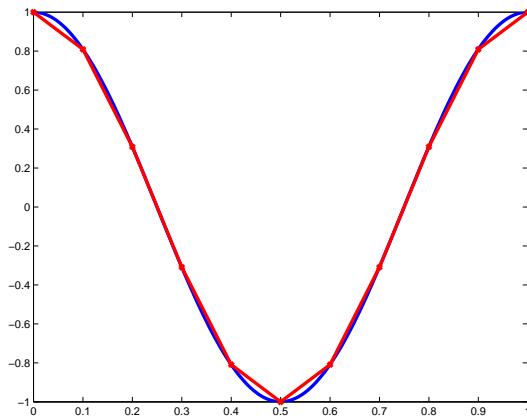
# Sampling Fourier Modes

- What modes can a discretization sample?

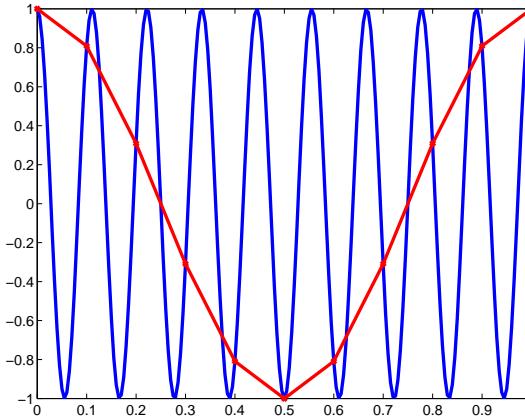


# Multigrid & Fourier Modes

- Question: What does this have to do with multigrid?
- Coarse grids can only resolve smooth modes.
- Coarse grids cannot resolve oscillatory modes (aliasing).
- Next question: What about oscillatory modes?



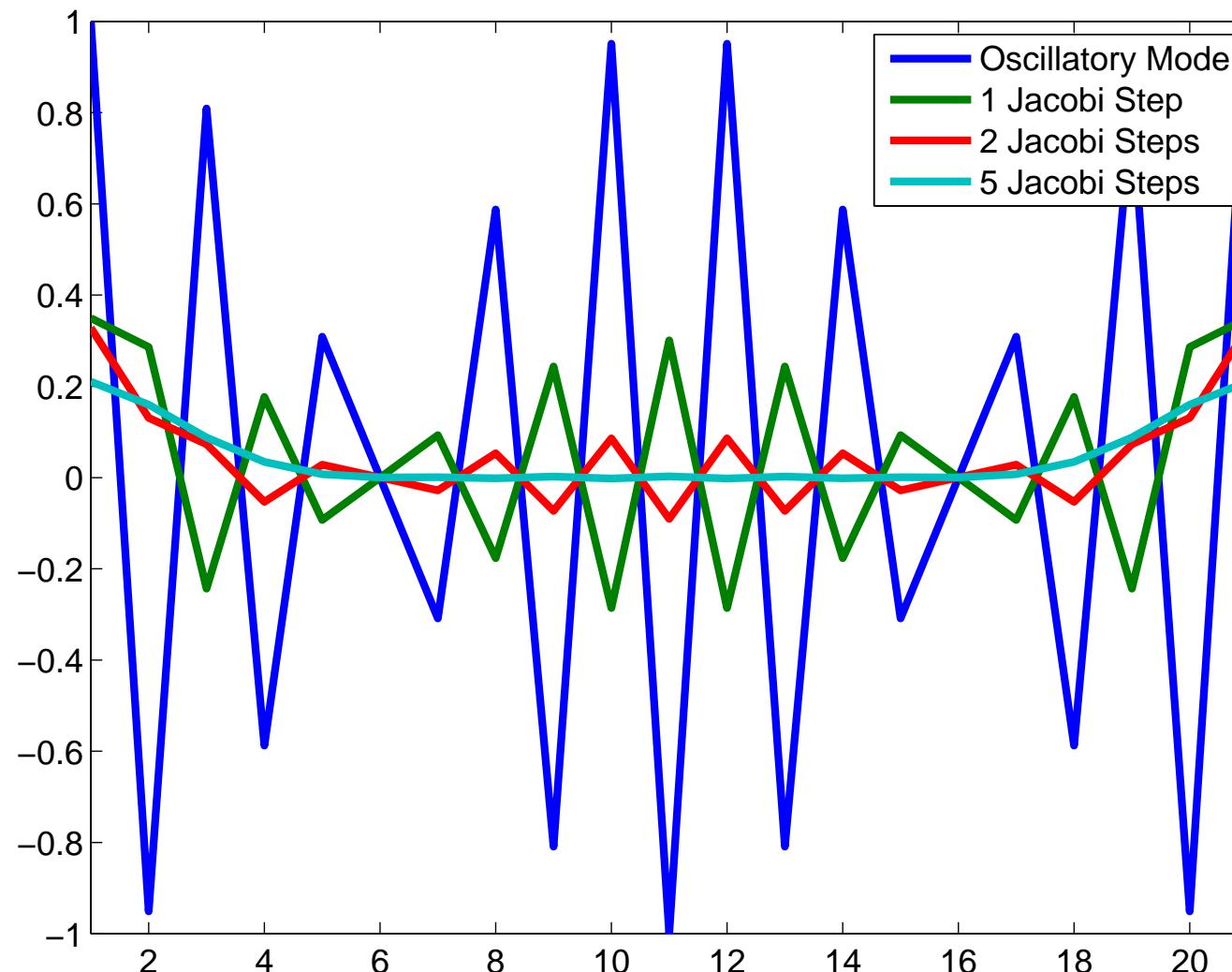
Coarse Grid **OK.**

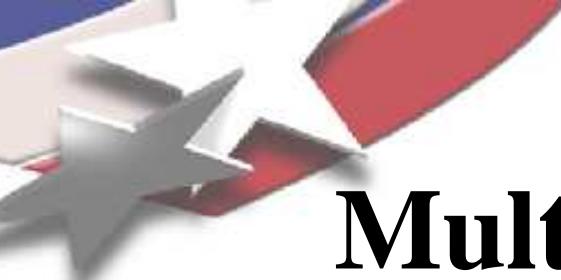


Coarse Grid **no help.**

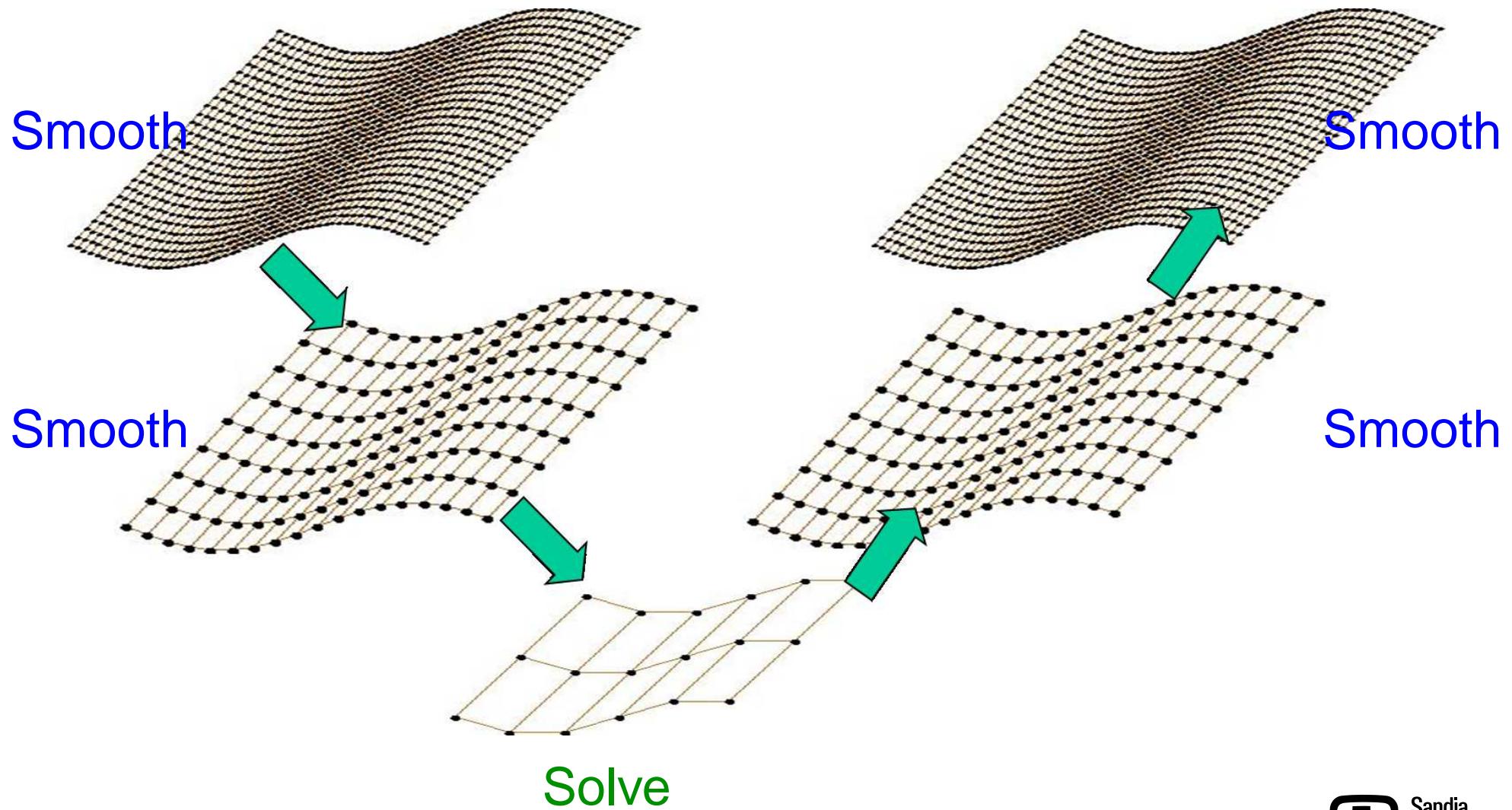


# Jacobi to the Rescue





# Multigrid by Picture





# Multigrid Method for $A_h x = b$

Loop until convergence...

1. Smooth on fine grid.

$$\text{jacobi}(A_h, x, b).$$

2. Transfer residual  $(b - A_h x)$  to coarse grid (restriction).

$$r_c = P^T(b - A_h x).$$

3. Solve on coarse grid.

$$x_c = A_H^{-1} r_c.$$

4. Transfer solution to fine grid (prolongation).

$$x = x + P x_c$$

5. Smooth on fine grid.

$$\text{jacobi}(A, x, b).$$

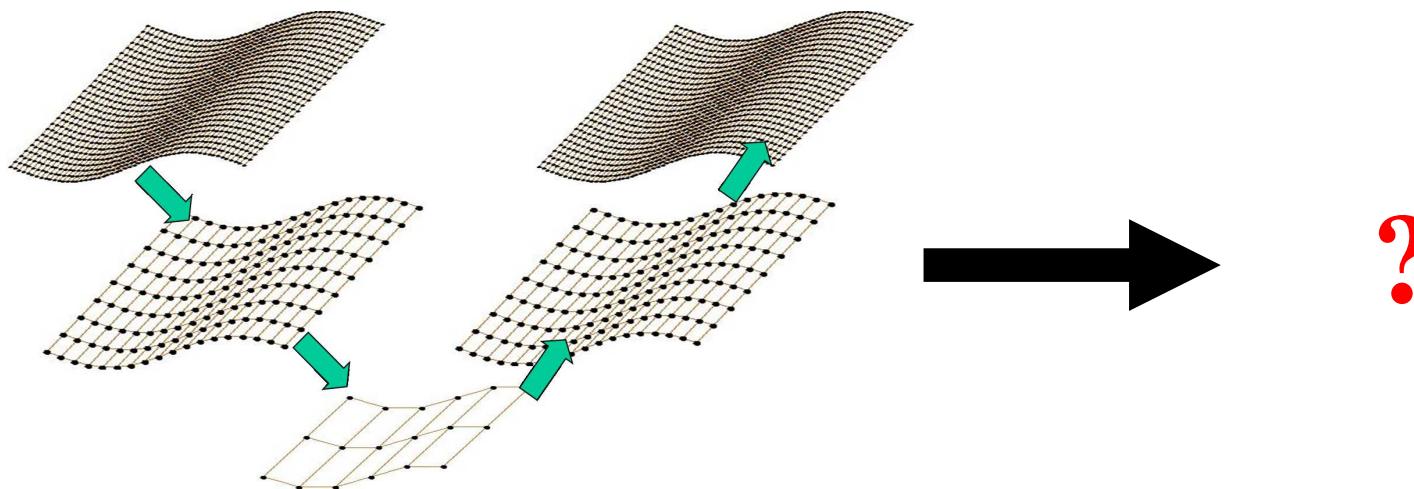


# Outline

- Background.
- Solving Linear Systems with Iterative Methods.
- Introduction to Multilevel Methods.
- **Introduction to Algebraic Multigrid.**
- Open Questions in Multilevel Methods.

# Multigrid without a Grid

- Multigrid requires a hierarchy of grids  
⇒ inconvenient for the user.
- Can we automatically build the hierarchy?
- Yes! This is called algebraic multigrid (AMG).
- Question: Does the smooth/oscillatory distinction make sense?





# The Logic of AMG

- Start by choosing a smoother.
- If the smoother damps the error...  
it is *algebraically* smooth.
- If the smoother doesn't damp the error ...  
choose the grids so that it is smooth somewhere.
- Note: Contrast this with geometric MG where you pick the grid hierarchy first.



# The Two Schools of AMG

- Classical AMG (Ruge-Stüben)
  - Choose subset of nodes for the coarse mesh (C-points).
  - Fine-only nodes (F-points) interpolate off of neighboring C-points.
- Smoothed Aggregation (SA)
  - Group or “aggregate” unknowns together to form coarse unknowns.
  - Interpolate based on grouping plus smoothing.



# Smoothed Aggregation AMG

Near Nullspace

---



- Define the near null space.
  - Often a null space for an unconstrained problem.
  - Example: Constant vector for heat equation.
  - Example: Rigid body modes for structural mechanics.



# Smoothed Aggregation AMG

Near Nullspace

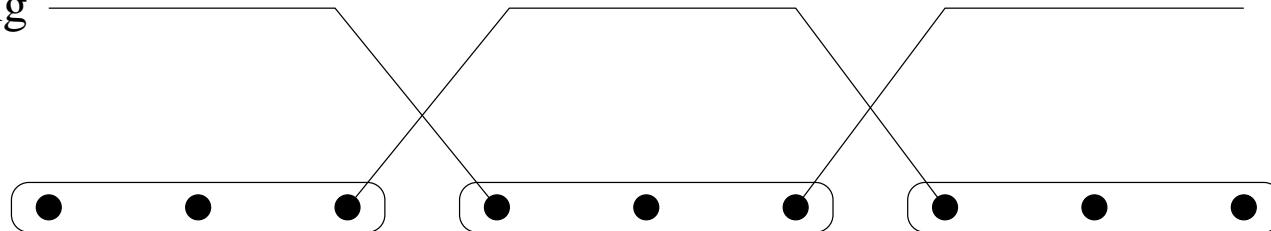
---



- Define the near null space.
- Aggregate unknowns.

# Smoothed Aggregation AMG

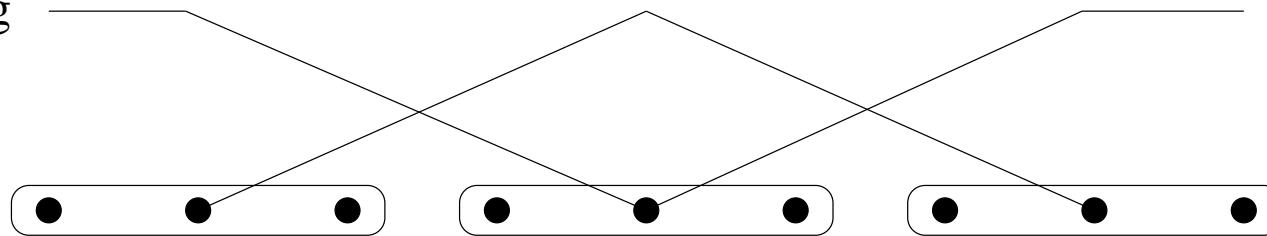
After Partitioning



- Define the near null space.
- Aggregate unknowns.
- Partition near null space between aggregates.
  - Preserves near null space on coarse grids.

# Smoothed Aggregation AMG

After Smoothing



- Define the near null space.
- Aggregate unknowns.
- Partition near null space between aggregates.
- Smooth the prolongator using a step of Jacobi.
  - Preserves null space.
  - Improved interpolation.

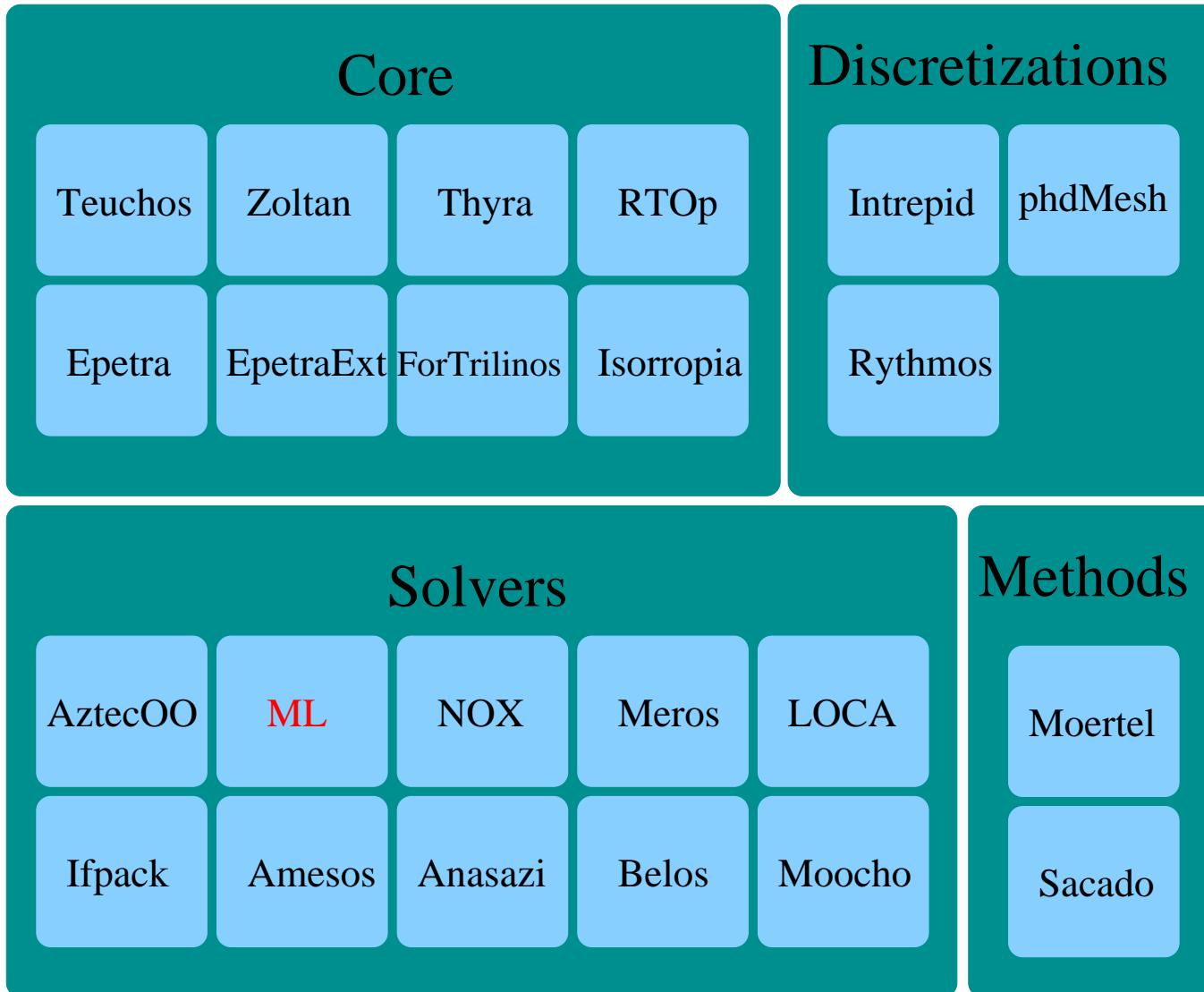


# Multigrid at Sandia

- ML is Sandia's AMG package.
- It provides scalable multilevel/multigrid preconditioners.
- Method types
  - Smoothed Aggregation (SA) - symmetric or nearly symmetric problems.
  - Non-symmetric SA - non-symmetric problems.
  - MatrixFree - matrix-free SA.
  - DD / DD-ML - domain decomposition.
  - Maxwell / RefMaxwell - Maxwell's equations.



# Trilinos Summary





# Outline

- Background.
- Solving Linear Systems with Iterative Methods.
- Introduction to Multilevel Methods.
- Introduction to Algebraic Multigrid.
- Open Questions in Multilevel Methods.



# Open Questions in Multigrid

- MG is designed for Laplace/Heat problems
- On other problems additional issues arise.
- Mathematical issues: anisotropy, systems, variable materials.
- Computer science issues: parallelism, scalability.



# Math Issue #1: Anisotropy

$$\frac{\partial^2 u}{\partial x^2} + \epsilon \frac{\partial^2 u}{\partial y^2} = f$$

- Anisotropic operators have direction-dependent behavior.
- Example: Heat diffuses “faster” in  $y$  direction ( $\epsilon$  small).
- Tests varying  $\epsilon$  w/ 10,000 unknowns.

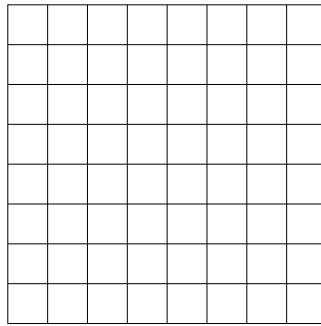
	$\epsilon = 1$	$\epsilon = 10^{-1}$	$\epsilon = 10^{-2}$	$\epsilon = 10^{-3}$	$\epsilon = 10^{-4}$
Iterations	14	20	53	129	189

- This is **BAD!**

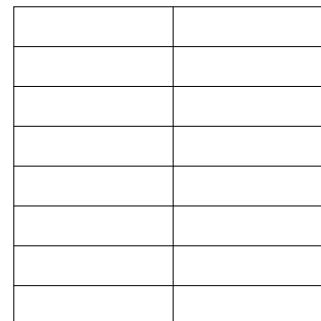


# Reacting to Anisotropy

- Better meshes fix some problems.



Isotropic Mesh



Anisotropic Mesh

- Meshes alone cannot solve hard problems.
- Research problem: Robust detection of anisotropy.
- Research problem: Non-axial anisotropy.

# Math Issue #2: PDE Systems

- PDE systems multiple different types of variables (e.g. displacement, velocity, pressure, temperature, etc.).
- Example: Linear elasticity.
- One solution: Smoothed aggregation — explicitly preserve null space on coarse levels.
- Research problem: Fluid problems (e.g. Navier-Stokes).

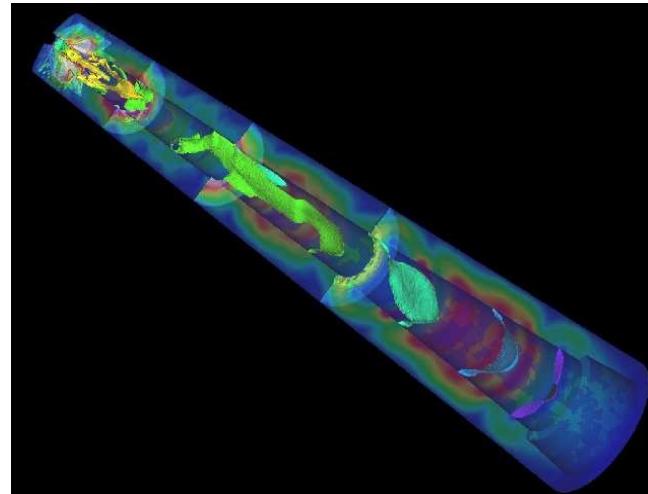
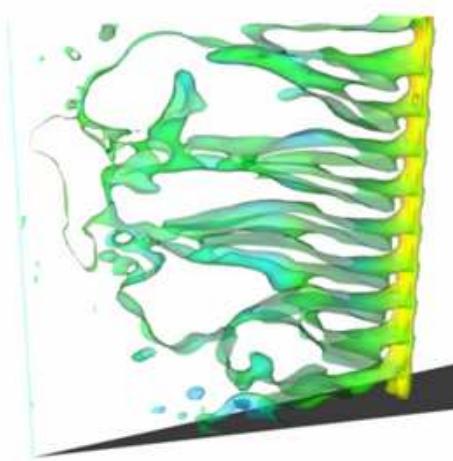


Image courtesy of the CSAR/UIUC  
<http://www.csar.uiuc.edu>

# Math Issue #3: Multimaterial

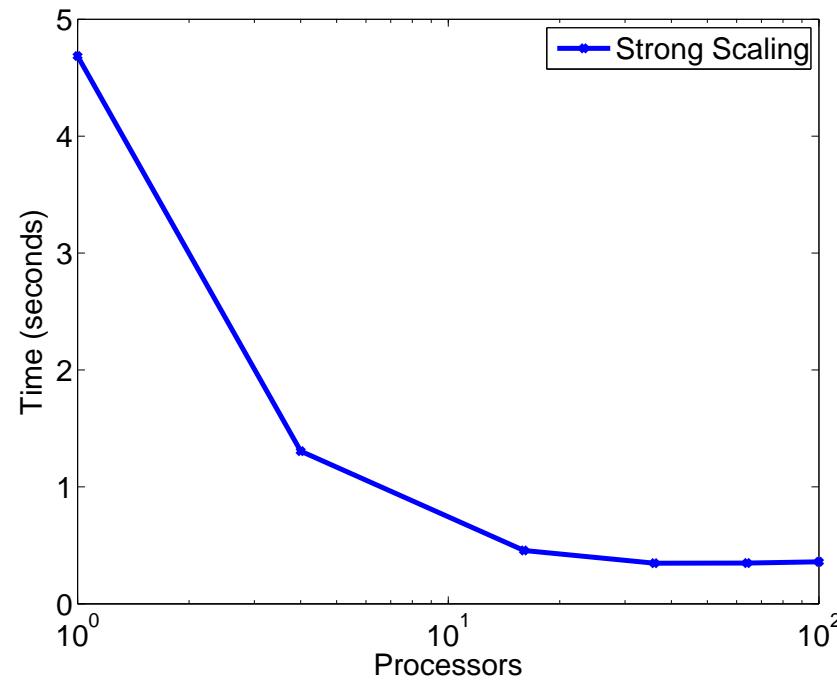
- Material interfaces can be sites of discontinuities  
⇒ oscillatory modes at boundaries.
- Features can be hard to resolve on coarse grid.



- Research problem: Detecting material interfaces.
- Research problem: Handling disappearing features.

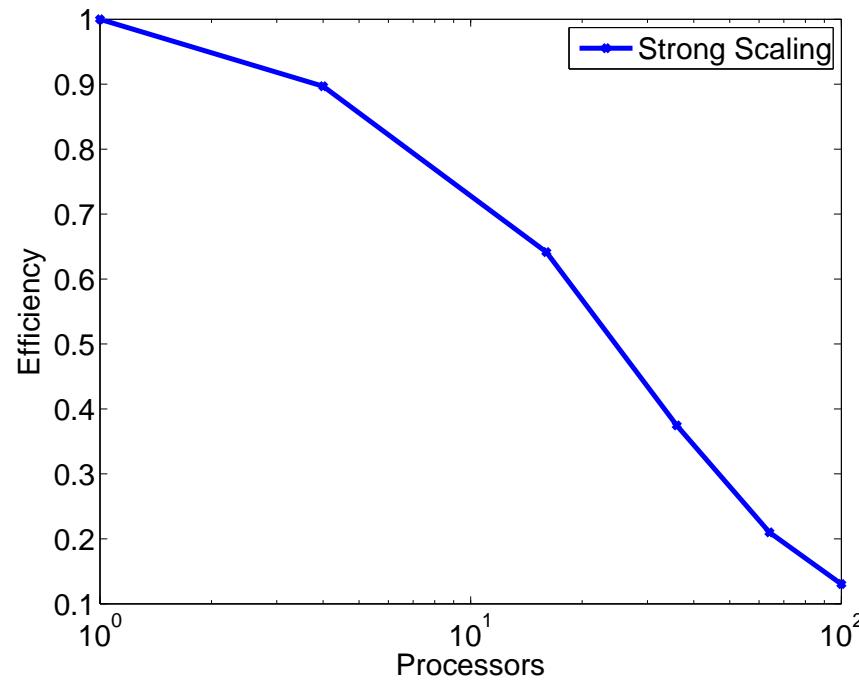
# CS Issues: Parallelism

- More processors *should* lead to faster solutions.
- Strong scaling — fix work, increase processors.
- Example: 2,000 steps of Jacobi.



# CS Issues: Parallelism

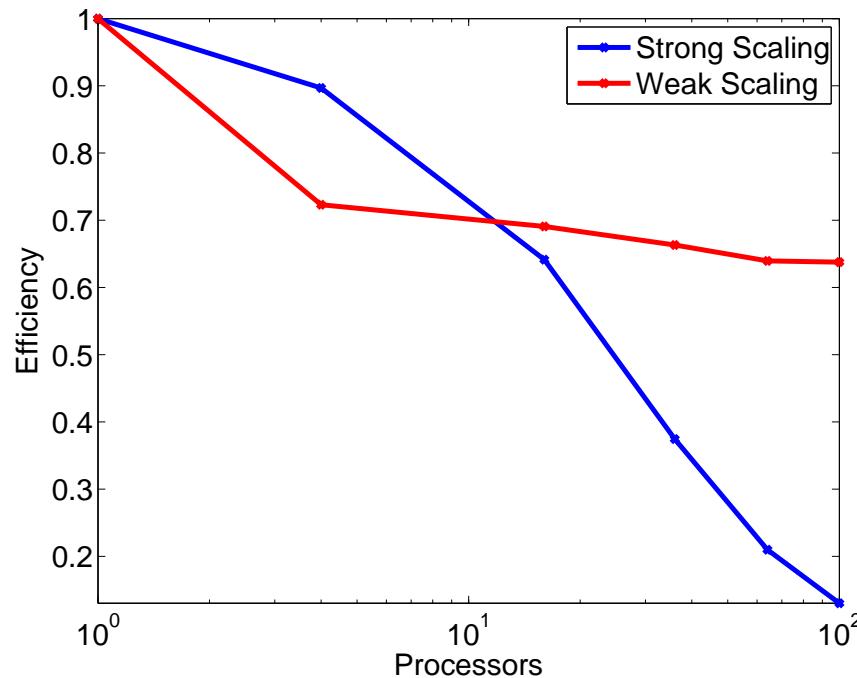
- More processors *should* lead to faster solutions.
- Strong scaling — fix work, increase processors.
- Example: 2,000 steps of Jacobi.



- Question: What causes the loss in efficiency?

# Understanding Efficiency

- Answer: Computation to communication ratio.
- Weak scaling — fix work per processor.



- Message: What works on a small # of procs, might not work on a large #.

# CS Issue #1: Scalability

- Coarse grids  $\Rightarrow$  less work per proc  $\Rightarrow$  poor performance.
- One solution: Move data to leave some procs idle.
- Research problem: What is the best way to repartition?
- Research problem: How to address poor performance on really big (terascale) computers.



Red Storm(SNL) 26,569 procs



Jaguar(ORNL) 23,016 procs



# Take Home

“I would rather have today’s algorithms on yesterday’s computers than vice versa.” - Reported by P. Toint

- Importance of good algorithms.
- Rationale behind multilevel algorithms.
- Nature of the “big questions” in multilevel algorithm research.
  - Math: Anisotropy, multimaterial, PDE systems.
  - CS: parallelism, scalability.
- My web site: <http://www.sandia.gov/~csiefer>
- Trilinos project: <http://trilinos.sandia.gov>